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# Analysis of Energy-Delay-Product of a 3D Vertical Nanowire FET Technology

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**Abstract**— To sustain transistor scaling beyond lateral 7nm devices, gate-all-around (GAA) junction-less vertical nanowire field effect transistors (VNWFEET) are a promising alternative. This work analyses the energy-delay-product (EDP) for a junction-less 3D vertical gate-all-around nanowire FET technology, with a physical channel length of 14nm. Comparisons with the EDP of a baseline 7nm FinFET technology are carried out. The analysis motivates a new 3D neural network compute cube (N<sup>2</sup>C<sup>2</sup>) concept. Our results show that a 10x gain in EDP can be achieved for a physical VNWFEET gate length of 14nm.

**Keywords**—Vertical junctionless NWFET, logic circuit simulation.

## I. INTRODUCTION

Emerging computing paradigms for the Internet of Things (IoT), in particular edge computing and edge artificial intelligence (AI), target real-time operations including data creation, decision, and action where milliseconds matter. Existing solutions are computation-intensive and energy-hungry requiring server-based implementations, which introduce latency and jitter, as well as raising data protection and privacy concerns. Deterministic, secure, and real-time operation is important for self-driving cars, robotics, industry 4.0, augmented reality, and many other areas. However, despite recent improvements in algorithm efficiency, energy-efficiency of the hardware has become a challenge. Embedded lightweight energy-efficient hardware remains elusive.

Today's 2D electronic architectures suffer from "unscalable" interconnects and are thus still far from being able to compete with biological neural systems in terms of real-time information-processing capabilities with comparable energy consumption. Recent advances in materials science, device technology, and synaptic architectures have the potential to fill this gap with novel disruptive technologies that go beyond conventional technology. A promising solution comes from vertical nanowire field-effect transistors (VNWFEETs) [1-2] that unlock the full potential of truly unconventional 3D networks through a unique integration approach [1] termed Logic Element Gate Overstacking (LEGO). This technology has motivated the concept of a flexible 3D neural network compute cube (N<sup>2</sup>C<sup>2</sup>) with high integration density and performance. While significant gains in silicon area and energy-efficiency are expected through the combination of extremely small elementary device footprint and intrinsically

3D device and circuit functionality, this work is the first attempt to quantify the gains in terms of energy-efficiency of 3D logic blocks based on VNWFEET devices.

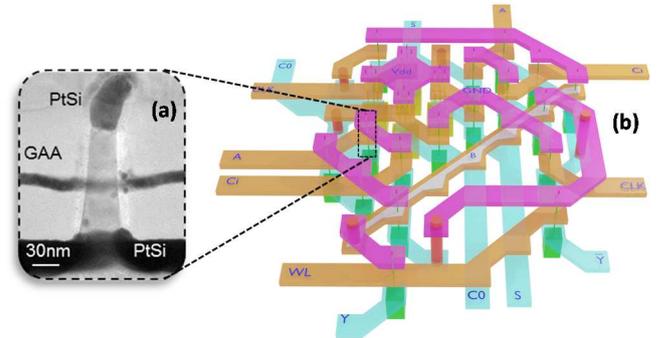


Fig 1: (a) STEM image showing the cross section of a junctionless vertical nanowire transistor, reproduced from [1], (b) 3D logic cell schematic of a 1-bit full adder using vertically stacked VNWFEETs.

The rest of this paper is organized as follows: section II recalls the energy-delay product (EDP) metric and develops analytical equations for on-current and load capacitance based on geometrical and material parameters to compare EDP gains between VNWFEETs and FinFETs. Section III applies this equation to explore EDP gains for both technologies and finally, Section IV concludes the work.

## II. ANALYSIS OF EDP IMPROVEMENT

The VNWFEET technology under study [3, 4] is composed of a homogenous highly doped nanowire channel, patterned into boron doped ( $2 \times 10^{19} \text{cm}^{-3}$ ) Si-substrate, working as a junction-less device [5]. The current between the silicided source/drain contacts is controlled by a gate-all-around structure having a physical channel length of 14nm (Fig. 1 (a)). Leveraging vertical integration of stacked VNWFEETs, much higher compactness and flexibility of vertical device dimensions can be achieved (Fig. 1 (b)) and a significant area gain compared to a 7nm FinFET technology can be expected.

Energy-Delay Product (EDP) is a useful metric to compare the speed of energy-efficient circuits. While the Power-Delay Product (PDP), or the switching energy, measures the energy per function, it does not satisfactorily capture the speed. In a classical CMOS circuit, considering the PDP for a 0-to-1-to-0 computation cycle, the EDP can be written as

$$EDP = PDP * t_p = C_L V_{DD}^2 * t_p = \frac{C_L^2 V_{DD}^3}{I_{sat}} \quad (1)$$

where  $t_p$  represents the propagation time,  $C_L$  represents the load capacitance on the gate output,  $V_{DD}$  represents the supply voltage and  $I_{sat}$  represents the saturation current of the transistor through which the current is drawn from the voltage supply or sunk to the ground to change the output voltage state (we assume that the transistor through which the current is flowing is primarily in the saturation region).

The ratio between the EDP of the FinFET technology and the VNWFET technology can therefore be expressed as:

$$G_{Evf} = \frac{EDP_f}{EDP_v} = \frac{C_{L_f}^2 V_{DDf}^3}{I_{satf}} \frac{I_{satv}}{C_{L_v}^2 V_{DDv}^3} \approx \frac{C_{L_f}^2 I_{satv}}{C_{L_v}^2 I_{satf}} \quad (2)$$

where the subscripts  $f$  and  $v$  stand for the FinFET and VNWFET, respectively. We assume that supply voltage values for both technologies are identical (i.e.  $V_{DDf} = V_{DDv}$ ). Hence, for a given value  $n$  of  $G_{Evf}$ , the EDP of the VNWFET technology is  $n$  times lower than that of the FinFET technology.

### A. On-current ( $I_{sat}$ ) considerations

We also assume that material current density and carrier mobility are close enough for both technologies such that their influence can be ignored in this comparison. This then implies that the transistor saturation current can be approximated as

$$I_{sat} = \kappa \frac{W_g}{L_g} \quad (3)$$

where  $\kappa$  is a constant incorporating technology parameters and operating conditions,  $W_g$  represents the effective width of the transistor channel under the gate orthogonal to current flow, and  $L_g$  represents the length of the channel under the gate, i.e. the distance between source and drain. This also assumes that the transistor channel occupies all the space available in the given geometry – this implies that the channel is fully depleted in the FinFET and the radius of the nanowire is sufficiently small in the VNWFET to allow junctionless transport.

We can calculate  $W_g$  according to the geometry of both FinFET and VNWFET devices:

$$\left. \begin{aligned} W_{gf} &= 2(h_f + w_f) \\ W_{gv} &= 2\pi r_v \end{aligned} \right\} \quad (4)$$

where  $W_{gf}$  and  $W_{gv}$  represent the effective widths of the FinFET and VNWFET channels, respectively;  $h_f$  and  $w_f$  represent the height and width of a fin in the FinFET device; and  $r_v$  represents the radius of the VNWFET nanowire channel. The geometries and parameters of both devices are shown in Figs. 2 (FinFET) and 3 (VNWFET). Thus, the ratio between the saturation currents of both devices can be written as:

$$\frac{I_{satv}}{I_{satf}} = \frac{W_{gv} L_{gf}}{L_{gv} W_{gf}} = \frac{\pi r_v L_{gf}}{(h_f + w_f) L_{gv}} \quad (5)$$

In nanowire-based devices, the ratio of channel length  $L_{gv}$  to channel diameter  $2r_v$  should be kept constant at 2:1 to preserve desirable behavior in the off state [6]. It is also important to avoid degradation of both ballistic and dissipative currents, which occurs with decreasing device size. In fact, ballisticity (i.e. the ratio of dissipative to ballistic current) also degrades for very small devices, with channel lengths below around 10nm. Both constraints can be combined resulting in:

$$L_{gv} \geq 10nm, r_v = \frac{L_{gv}}{4} \text{ subject to } r_v \geq 2.5nm \quad (6)$$

### B. Load capacitance ( $C_L$ ) considerations

In terms of capacitance, we will, in a first approach, consider that load capacitance is composed of the input gate capacitance  $C_{in}$  of  $F$  (fanout) logic gates on the output node, as well as interconnect capacitance  $C_w$ . Hence,

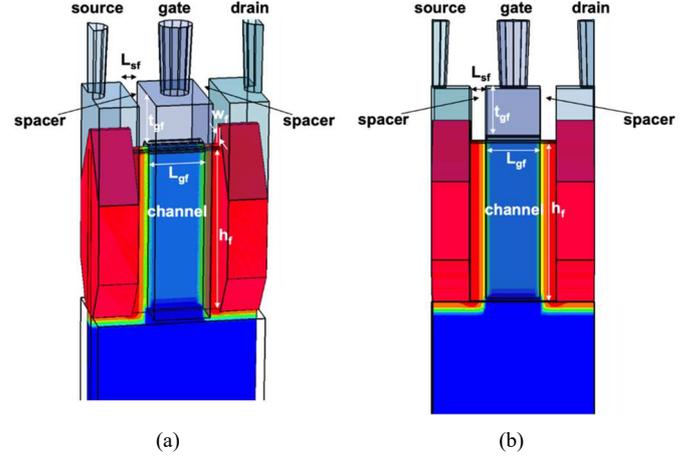


Fig. 2: FinFET geometry (a) 3D view (b) lateral view perpendicular to the gate electrode; color scheme: red (resp. blue) indicates a high (resp. low) electron density for an n-channel device (vice versa for p-channel devices).

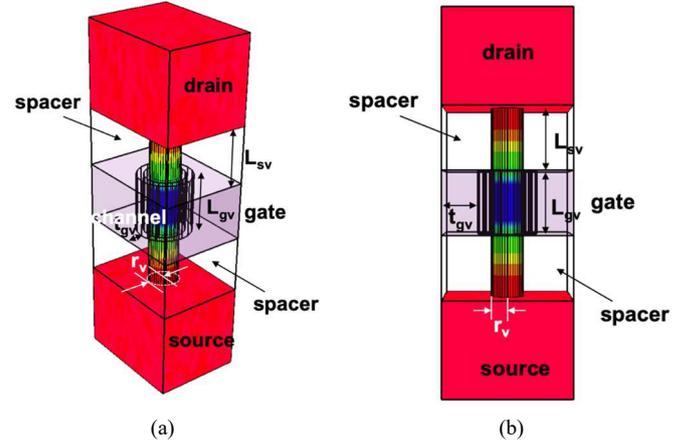


Fig. 3: VNWFET geometry (a) 3D view (b) lateral view; color scheme: red (resp. blue) indicates a high (resp. low) electron density for an n-FET (vice versa for p-FETs).

$$C_L = F(C_{in} + C_w) = F(C_{gc} + C_{gs} + C_w) \quad (7)$$

where the input gate capacitance is composed of the direct gate-channel capacitance  $C_{gc}$  linked to the gate-channel area, and the gate-source capacitance  $C_{gs}$  linked to the spacer geometry.

#### 1) Gate-channel capacitance

The gate-channel capacitance can be expressed in terms of channel geometry for both devices as:

$$\left. \begin{aligned} C_{gcf} &= \frac{\epsilon_{ox} L_{gf} 2(h_f + w_f)}{EOT} \\ C_{gcv} &= \frac{\epsilon_{ox} L_{gv} 2\pi r_v}{EOT} \end{aligned} \right\} \quad (8)$$

Here,  $C_{gcf}$  and  $C_{gcv}$  are the gate-channel capacitance for FinFET and VNWFET devices, respectively;  $\epsilon_{ox}$  and  $EOT$  are the dielectric permittivity for standard  $\text{SiO}_2$  and the equivalent oxide thickness of the gate dielectric material (i.e. converted to the thickness it would have using  $\text{SiO}_2$  as the gate dielectric), respectively. Assuming that the dielectric material is identical for both technologies,  $EOT$  writes:

$$EOT = t_{high-k} \frac{\epsilon_{ox}}{\epsilon_{high-k}} \quad (9)$$

where  $\epsilon_{high-k}$  is the permittivity of the hi-k gate dielectric. A typical value for  $EOT$  is around 0.89nm in current technologies where  $HfO_2$  gate dielectrics are used.

## 2) Gate-source capacitance

The gate-source capacitance can be expressed in terms of spacer geometry for both devices as:

$$\left. \begin{aligned} C_{gsf} &= \frac{\epsilon_s 2t_{gf}(2t_{gf}+h_f+w_f)}{L_{sf}} \\ C_{gsv} &= \frac{\epsilon_s(4(t_{gv}+r_v)^2 - \pi r_v^2)}{L_{sv}} \end{aligned} \right\} \quad (10)$$

where  $C_{gsf}$  and  $C_{gsv}$  represent the gate-source capacitance for FinFET and VNWFET devices, respectively;  $t_{gf}$  and  $t_{gv}$  represent the gate material thickness for FinFET and VNWFET devices, respectively and can be typically assumed to be between 10nm-20nm;  $L_{sf}$  and  $L_{sv}$  represent the spacer length (between gate and source) for FinFET and VNWFET devices, respectively, and can be typically assumed to be around 8nm;  $\epsilon_s$  represents the spacer material dielectric permittivity. We assume that the spacer material (typically  $Si_3N_4$ ) is identical for both technologies and that there are no fabrication issues for different dielectric materials for the gate (high-k) and for the spacer. We also assume that the gate material surrounds the channel with uniform thickness (overlap) equal to  $t_{gf}$  for the FinFET (although the lateral thickness is defined by the FinFET pitch), and is a square centered around the nanowire with minimum overlap equal to  $t_{gv}$  for the VNWFET. Note that this expression does not consider fringing capacitances, which is a reasonable assumption since this is not the dominant component. Hence one can write:

$$\left. \begin{aligned} C_{inf} &= \frac{\epsilon_{ox} L_{gf} 2(h_f+w_f)}{EOT} + \frac{\epsilon_s 2t_{gf}(2t_{gf}+h_f+w_f)}{L_{sf}} \\ C_{inv} &= \frac{\epsilon_{ox} L_{gv} 2\pi r_v}{EOT} + \frac{\epsilon_s(4(t_{gv}+r_v)^2 - \pi r_v^2)}{L_{sv}} \end{aligned} \right\} \quad (11)$$

## 3) Wire capacitance

Wire capacitance is considered for local (gate-to-gate) interconnect, and is expressed as:

$$C_w = \frac{\epsilon_{ox} w_m L_{gg}}{t_{ox}} \quad (12)$$

where  $w_m$  and  $L_{gg}$  represent the width and length of local (gate-to-gate) interconnect respectively; and  $t_{ox}$  represents the metal-substrate oxide thickness for interlayer dielectric  $SiO_2$ .  $L_{gg}$  can be directly linked to circuit compactness since it represents the lateral distance (pitch) between two gates. For a given improvement in compactness  $A_c$  between VNWFET and FinFET (i.e.  $A_c = A_f / A_v$ ),

$$\frac{L_{ggf}}{L_{ggv}} = \sqrt{A_c} \quad (13)$$

Assuming identical values for  $\epsilon_{ox}$ ,  $t_{ox}$  and  $w_m$  between the FinFET and VNWFET technologies, we can also write:

$$\frac{C_{wf}}{C_{wv}} = \sqrt{A_c} \quad (14)$$

## 4) Overall expressions for the load capacitances

Leveraging (14) one can write the expression for the load capacitances in both cases as

$$\left. \begin{aligned} C_{Lf} &= F [C_{gcf} + C_{gsf} + C_{wf}] \\ C_{Lv} &= F \left[ C_{gcv} + C_{gsv} + \frac{C_{wf}}{\sqrt{A_c}} \right] \end{aligned} \right\} \quad (15)$$

where  $C_{Lf}$  and  $C_{Lv}$  represent the load capacitances on FinFET and VNWFET logic gate outputs, respectively.

Thus, the ratio between the load capacitances of both devices can be written as:

$$\frac{C_{Lf}^2}{C_{Lv}^2} = \frac{[C_{gcf} + C_{gsf} + C_{wf}]^2}{\left[ C_{gcv} + C_{gsv} + \frac{C_{wf}}{\sqrt{A_c}} \right]^2} \quad (16)$$

And finally, the ratio between the EDPs can be expressed as,

$$G_{Evf} = \frac{C_{Lf}^2 I_{satv}}{C_{Lv}^2 I_{satf}} = \frac{[C_{gcf} + C_{gsf} + C_{wf}]^2 I_{satv}}{\left[ C_{gcv} + C_{gsv} + \frac{C_{wf}}{\sqrt{A_c}} \right]^2 I_{satf}} \quad (17)$$

Which can be further re-written in terms of geometric parameters as,

$$G_{Evf} = \frac{\left[ \frac{\epsilon_{ox} L_{gf} 2(h_f+w_f)}{EOT} + \frac{\epsilon_s 2t_{gf}(2t_{gf}+h_f+w_f)}{L_{sf}} + C_{wf} \right]^2}{\left[ \frac{\epsilon_{ox} L_{gv} 2\pi r_v}{EOT} + \frac{\epsilon_s(4(t_{gv}+r_v)^2 - \pi r_v^2)}{L_{sv}} + \frac{C_{wf}}{\sqrt{A_c}} \right]^2} \frac{\pi r_v}{(h_f+w_f)} \frac{L_{gf}}{L_{gv}} \quad (18)$$

## 5) Impact on 3D design

For this analysis, we assume that  $A_c$  is a constant and of the order of 5 according to [7], although it is anticipated that it will vary (negatively) with an increasing number of fins per FinFET / nanowires per VNWFET. This hypothesis is explored quantitatively in the next section and will require further analysis once an automated 3D place and route tool is available. This tends also to support the view that

- VNWFET-based design performance improves for lower numbers of nanowires per VNWFET – not only for the pitch overhead but also because the on-current varies sublinearly with the nanowire number per VNWFET.
- Computing should be kept local to enable short interconnects and limit energy consumption in parasitic elements (particularly relevant for mobile low power applications).

The proposed  $N^2C^2$  concept (fig. 4) enabled by the VNWFET technology is exactly this – a regular 3D matrix of individual computing functions where intra-cube interconnect is short due to both the limited complexity of the  $N^2C^2$  circuit and the limited number of targeted nanowires per VNWFET. While the benefit of local computing is known to limit the impact of interconnect delays,  $N^2C^2$  goes beyond the current planar state-of-the-art by extending this principle to 3 dimensions. Fig. 4 illustrates the  $N^2C^2$  concept as a scalable and flexible assembly of high-expressivity logic cells based on VNWFETs. By focusing on commonly used functions in deep learning and convolutional neural network architectures such as Multiply-Accumulate, combined with logic design styles suited to multiple transistors in series such as Pass-Transistor logic, we target compact and low-EDP neural network compute cube hardware capable of interfacing seamlessly with other, identical cubes through a versatile 3D interconnect framework. This will facilitate the development of physically regular and logically flexible 3D matrices for AI accelerators, including levers to explore hardware/software

co-design and approximation techniques to further improve energy-efficiency both at design time and at run-time.

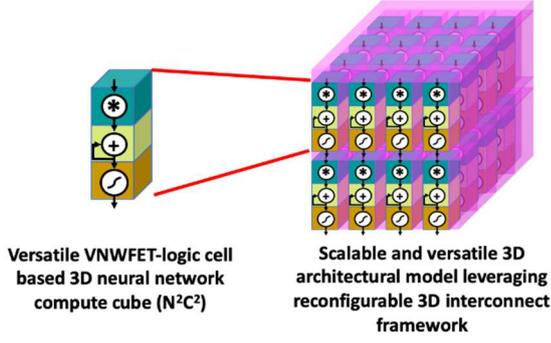


Fig 4: N<sup>2</sup>C<sup>2</sup> concept

### III. EDP GAIN ANALYSIS

For a FinFET aspect ratio ( $h/w_f$ ) value of 60nm/7nm with 20nm physical FinFET gate length  $L_{gf}$ , and by varying the value of physical VNWFET gate length  $L_{gv}$  between 10nm-20nm for varying nanowire radius  $r_v$ , gate material thickness  $t_{gv}$ , spacer length  $L_{sv}$  and compactness  $A_c$ , EDP- and PDP-gain values have been calculated, as shown in Fig. 5.

Among the chosen radii, the lowest permissible value is 2.5nm (according to (6)) and the highest is 25nm which corresponds to the largest diameter available for the VNWFET technology. For low  $r_v$ , the on-current ratio  $I_{satv}/I_{satf}$  is lower than 1, but is offset significantly by the  $(C_{if}/C_{iv})^2$  ratio; while for high  $r_v$ , the on-current ratio approaches 2,5 while the  $(C_{if}/C_{iv})^2$  ratio tends towards unity. The results show that 10x gain in EDP between VNWFET and 7nm FinFET technology can be achieved for  $L_{gv}=14$ nm and a nanowire radius of 3.5nm. If the smallest fabricated device dimensions are considered, i.e.  $L_{gv}=14$ nm and  $r_v=11$ nm, an EDP gain of 4.3 has been predicted. Considering the worst-case scenario, for the largest already-fabricated devices ( $r_v=25$ nm and  $L_{gv}=14$  nm [4]), a 2x EDP gain can still be observed. This analysis demonstrates that the VNWFET can be designed to be more energy-efficient compared to a 7nm FinFET.

### IV. CONCLUSIONS

It is well known that transistor energy efficiency improves as gate length decreases. This is especially true for GAA NWFETs, among which the disruptive vertical device implementations allow the transition from 2D to truly 3D architectures. In this work, we developed a comparative analysis of logic energy-efficiency through first-order equations for EDP of VNWFET and FinFET technologies. Leveraging a set of realistic geometric and material parameter values, our work shows that a 10x gain in EDP over a baseline 7nm FinFET technology can be achieved for a physical VNWFET gate length of 14nm and even for actual fabricated devices, 4.3x gain in EDP has been predicted. These results pave the way towards 3D neural network compute cube required for dense and energy efficient non Von Neumann computing.

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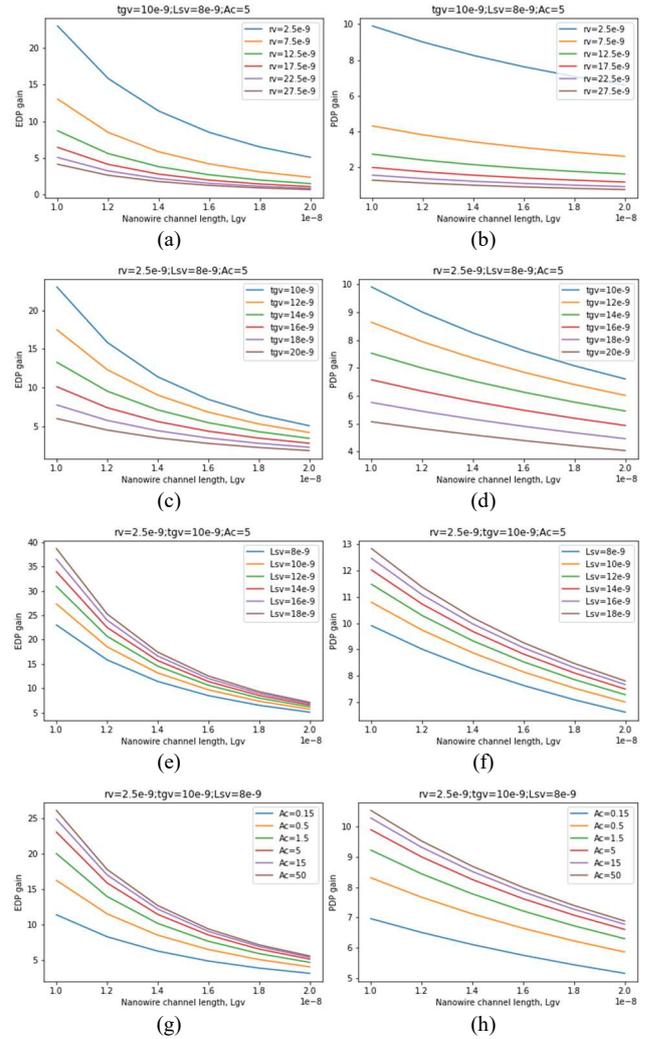


Fig. 5: EDP- and PDP-gain versus VNWFET gate length: a),b) for varying nanowire radius  $r_v$ ; c),d) for varying gate material thickness  $t_{gv}$ ; e),f) for varying spacer length  $L_{sv}$ ; g),h) for varying compactness  $A_c$ .

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