

MS130: Derivative-Free Optimization Methods for Solving Expensive Global Black-Box Problems

Enhanced Kriging models within a Bayesian optimization framework to handle both continuous and categorical inputs

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Context

New aircraft configurations = Unknown behaviors

A. Lambe and J. R. R. A. Martins. "Extensions to the design structure matrix for the description of multidisciplinary design, analysis, and optimization processes". Structural and Multidisciplinary Optimization 46 (2012), pages 273-284.

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New aircraft configurations = Unknown behaviors

→ built as a **black box** (derivative-free & expensive-to-evaluate)

Bayesian optimization (efficient global optimization) can solve efficiently an expensive black box problem.

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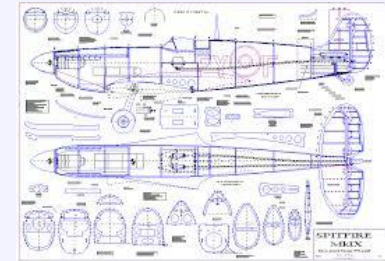
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- a large number of design variables

High-dimension



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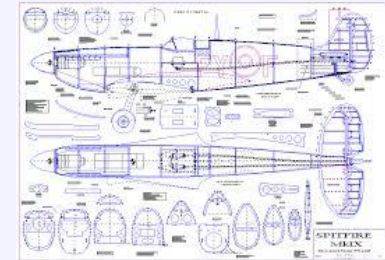
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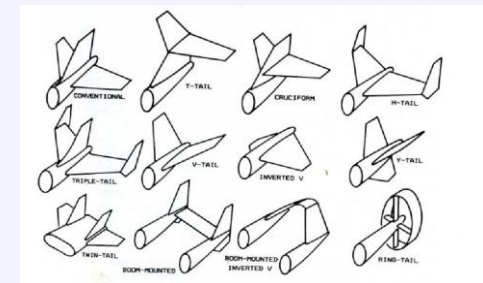
Aircraft design developments required:

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- mixed integer variables

High-dimension



Discrete variables



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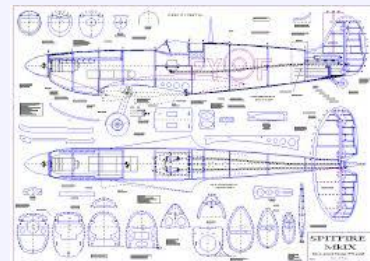
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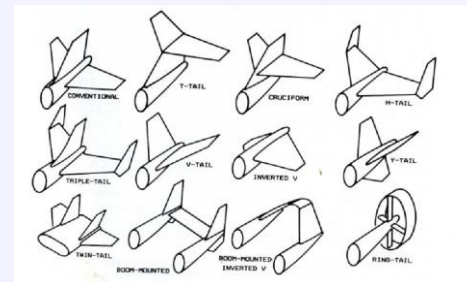
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- multimodal constraints (convex or non-convex, equality or inequality,...)

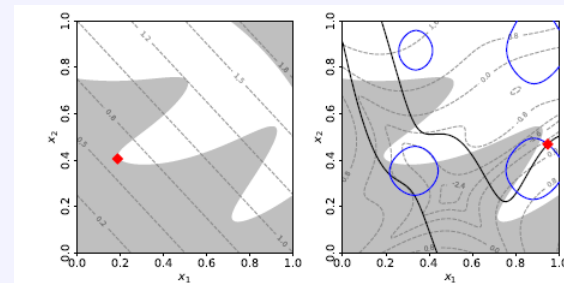
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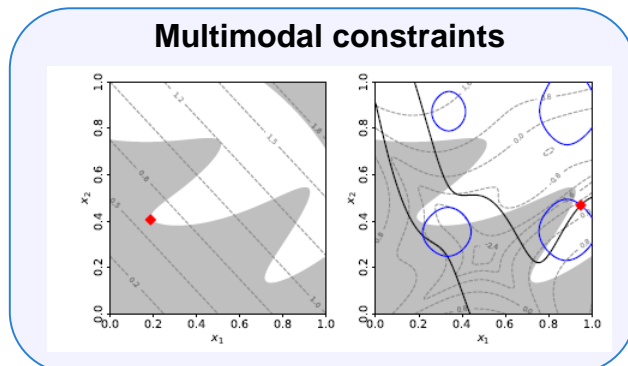
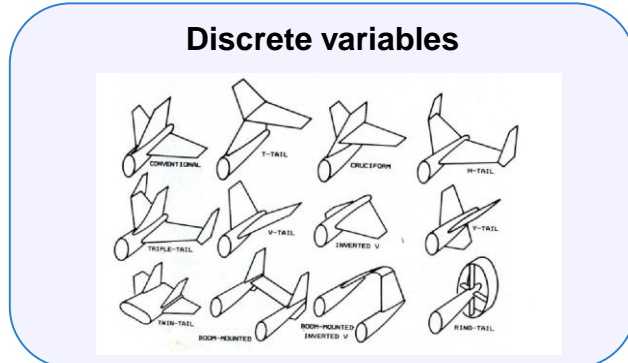
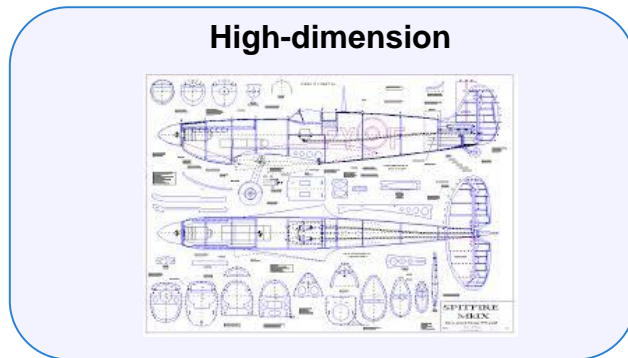
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→ Our objective is to solve **high dimensional mixed integer constrained optimization problems using Bayesian optimization.**

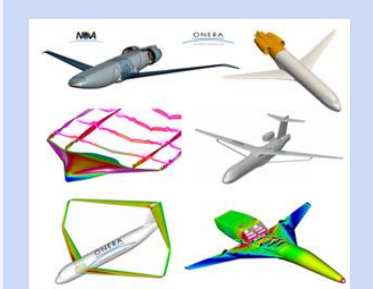


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Bayesian optimization applied to aircraft design

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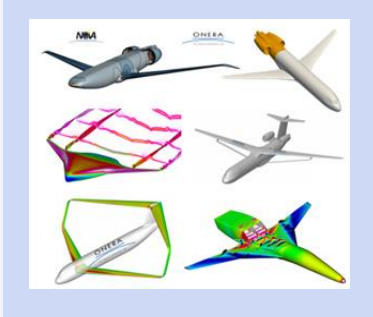
New concepts



Ω

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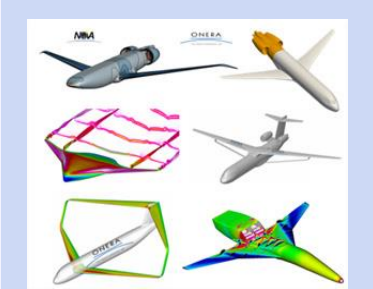
New concepts



Analyze
→

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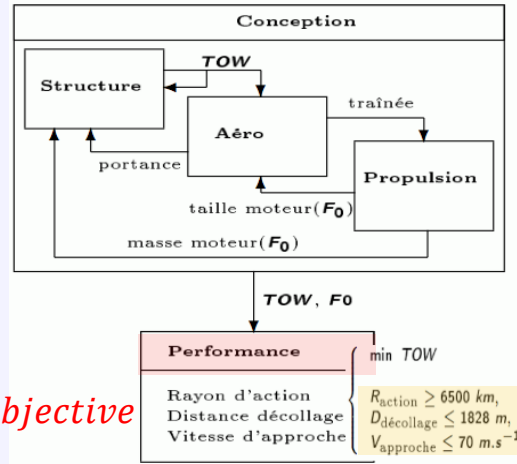
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Analyze

Multidisciplinary Design Analysis

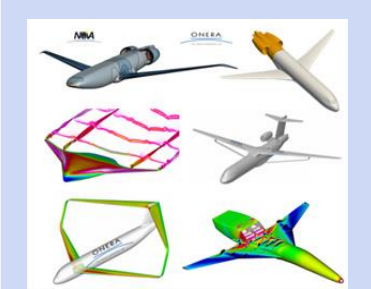


objective

constraints

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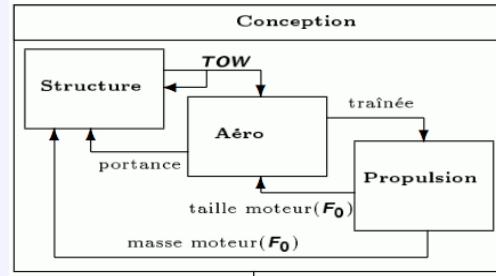
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Improvements

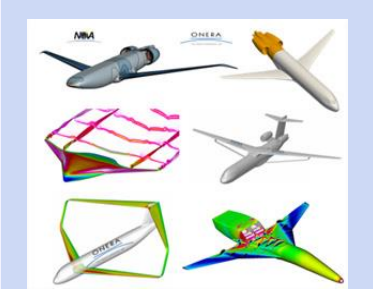
objective

constraints

Performance		min TOW
Rayon d'action		$R_{\text{action}} \geq 6500 \text{ km}$,
Distance décollage		$D_{\text{décollage}} \leq 1828 \text{ m}$,
Vitesse d'approche		$V_{\text{approche}} \leq 70 \text{ m.s}^{-1}$

Bayesian optimization applied to aircraft design

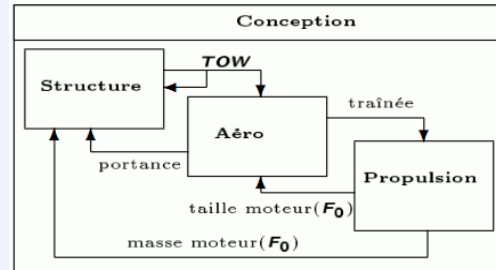
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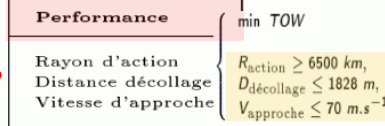
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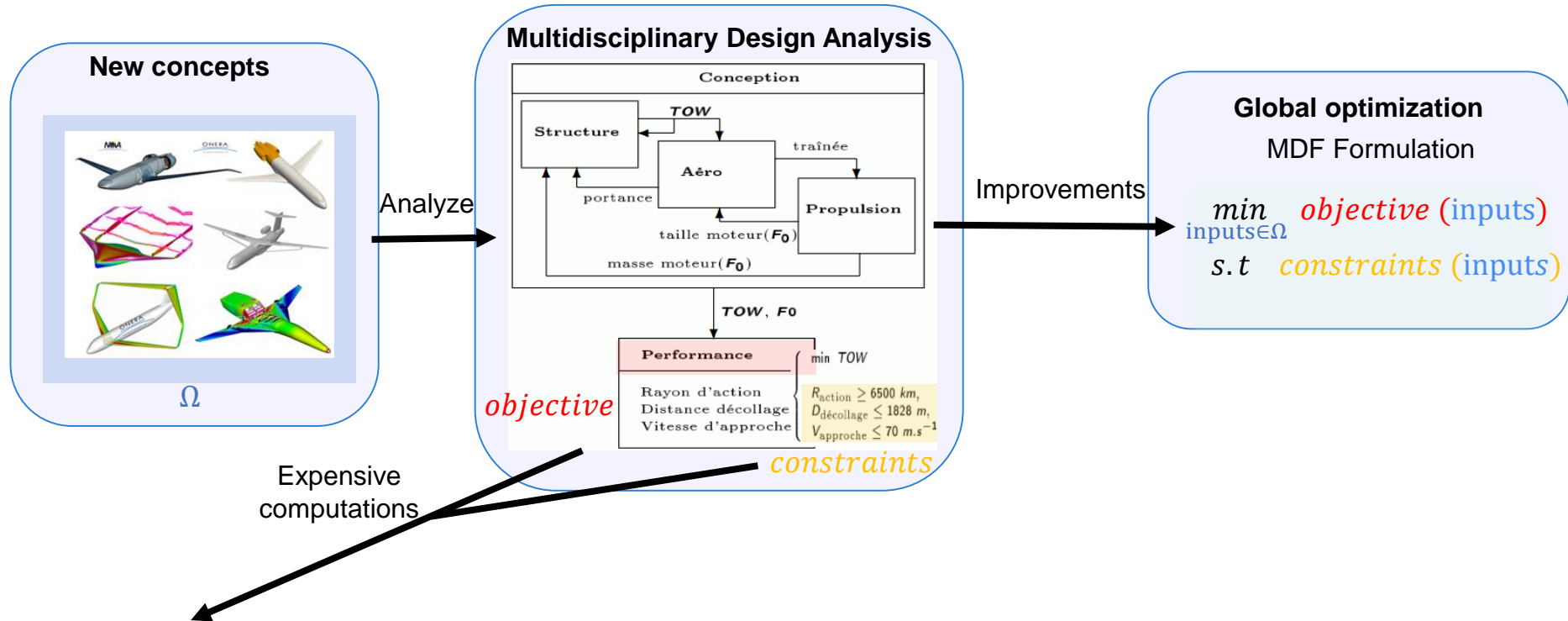
Improvements

Global optimization

MDF Formulation

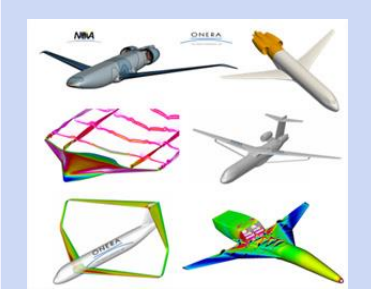
$$\begin{aligned} \min_{\text{inputs} \in \Omega} & \text{objective (inputs)} \\ \text{s.t.} & \text{constraints (inputs)} \end{aligned}$$

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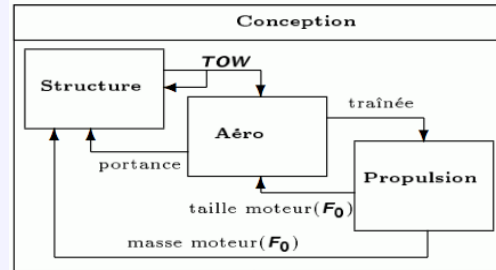
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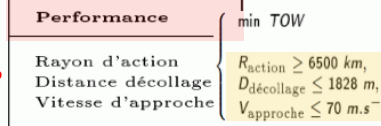
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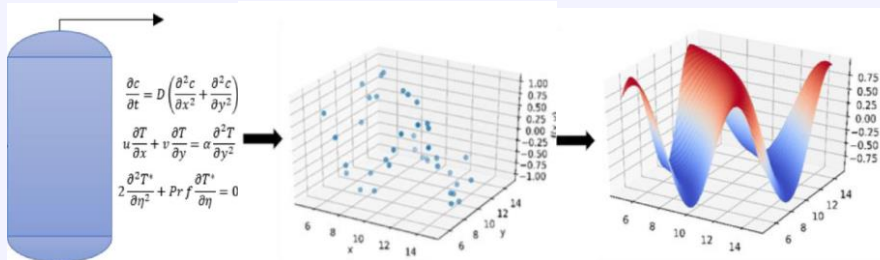
MDF Formulation

$$\min_{\text{inputs} \in \Omega} \text{objective}(\text{inputs})$$

$$\text{s.t. constraints}(\text{inputs})$$

Expensive computations

Surrogate model



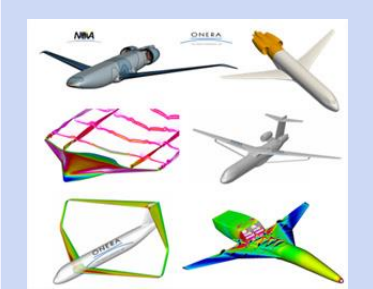
Expensive black-box

Design of Experiments

Gaussian processes

Bayesian optimization applied to aircraft design

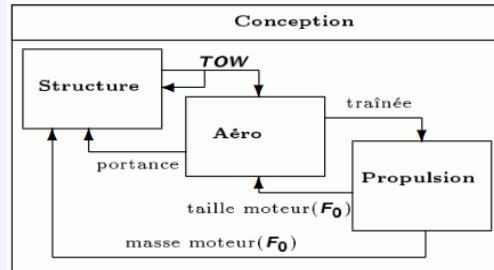
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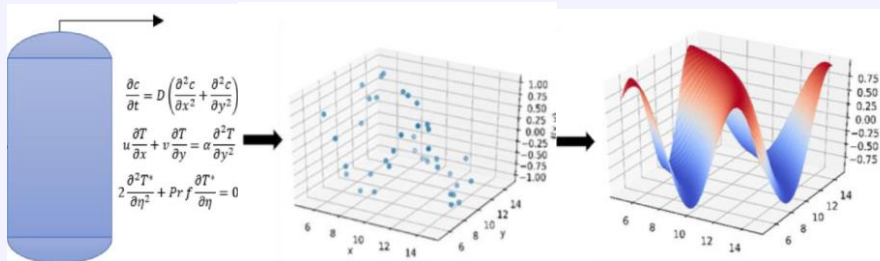
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Expensive computations

Expensive black-box optimization

Surrogate model

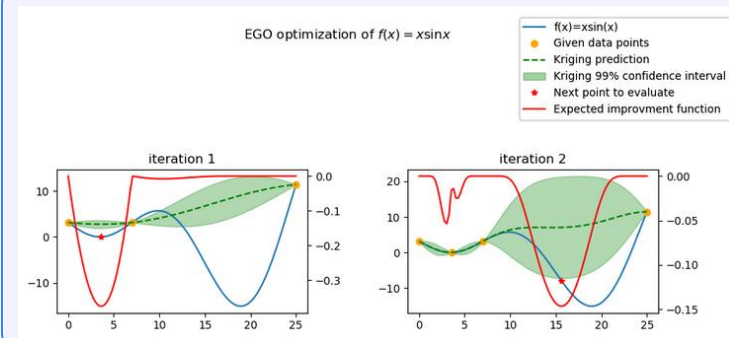


Expensive black-box

Design of Experiments

Gaussian processes

Efficient Global Optimization



State-of-the-art

Baseline method \Rightarrow Super Efficient Global Optimizer (SEGO)

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Constraints 😊
High-Dimension 😊
Mixed integer 😞

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CAT-EGO

Mixed integer kernels coupled with adapted Mesh Adaptive Direct Search

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Garrido-Merchán and Hernández-Lobato

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The proposed approach:

- **Continuous relaxation** to tackle **mixed integer** but increase the number of dimensions.
- **Kriging with Partial Least Squares (KPLS)** to tackle **high-dimension**.
- **SEGO** to tackle **constrained optimization**.

A. M. Bouhlel, N. Bartoli, A. Otsmane, and J. Morlier. "Improving kriging surrogates of high-dimensional design models by Partial Least Squares dimension reduction". Structural and Multidisciplinary Optimization 53 (2016), pages 935-952

Proposed approach: the surrogate model (1/2)

- i. Relax continuously integer/categorical input variables

if integer

|relax continuously within the bounds

if categorical

|Add a dimension by level with bounds [0,1]

D. R. Jones, M. Schonlau, and W. J. Welch. "Efficient Global Optimization of Expensive Black-Box Functions". Journal of Global Optimization, vol. 13 (1998), pages 455–492.

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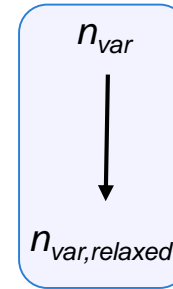
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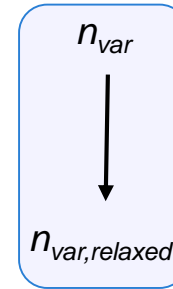
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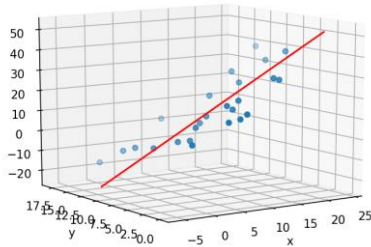
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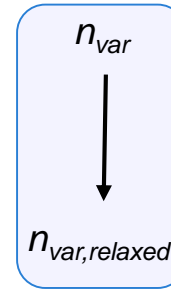
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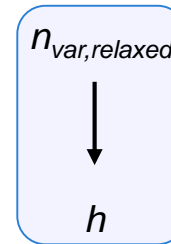
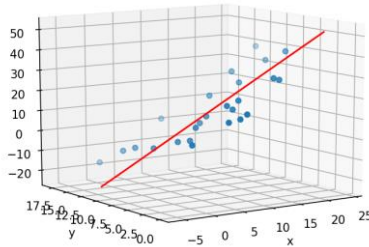
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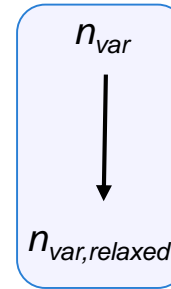
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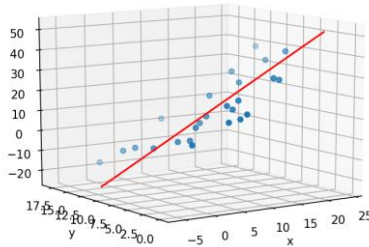
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iii. Fit the continuous Gaussian process metamodel on h dimensions

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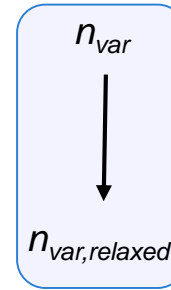
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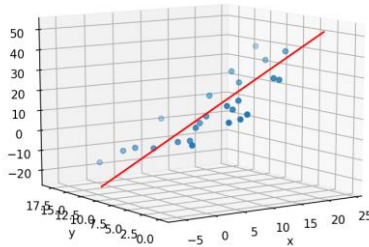
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iii. Fit the continuous Gaussian process metamodel on h dimensions

$$\text{Initial DoE} \begin{cases} x_{DoE} = (x_{s,0}, \dots, x_{n,0}) & y_{pred}(x_{DoE}) = y_s \\ y_{DoE} = (y_{s,0}, \dots, y_{n,0}) & y_{pred}(x) = \hat{y} + \varepsilon(x) \end{cases}$$

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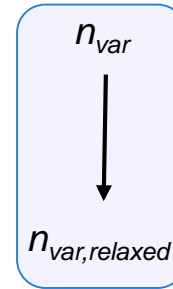
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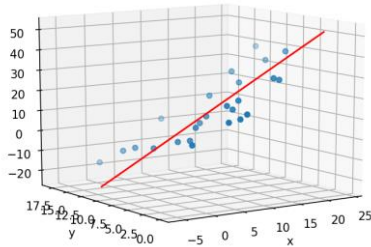
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iii. Fit the continuous Gaussian process metamodel on h dimensions

$$\text{Initial DoE} \begin{cases} x_{DoE} = (x_{s,0}, \dots, x_{n,0}) \\ y_{DoE} = (y_{s,0}, \dots, y_{n,0}) \end{cases} \quad \begin{cases} y_{pred}(x_{DoE}) = y_s \\ y_{pred}(x) = \hat{y} + \varepsilon(x) \end{cases} \rightarrow \begin{cases} \varepsilon(x) \sim N(0, \sigma^2) \\ \text{Corr}(\varepsilon(x), \varepsilon(x')) = k(x^i - x^j, \theta) \end{cases}$$

D. R. Jones, M. Schonlau, and W. J. Welch. "Efficient Global Optimization of Expensive Black-Box Functions". Journal of Global Optimization, vol. 13 (1998), pages 455–492.

C. E. Rasmussen, and J. Quiñonero-Candela, "A Unifying View of Sparse Approximate Gaussian Process Regression". Journal of Machine Learning Research, vol. 6 (2005), pages 1939–1959.

Proposed approach: the surrogate model (1/2)

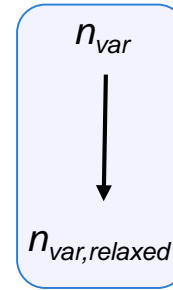
i. Relax continuously integer/categorical input variables

if integer

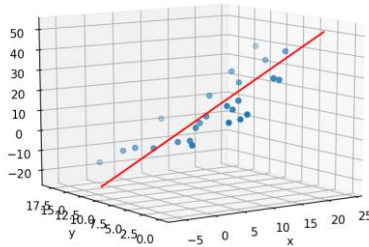
|relax continuously within the bounds

if categorical

|Add a dimension by level with bounds [0,1]



ii. Use PLS to reduce the dimension $n_{var,relaxed}$ to h principal components ($h \ll n_{var,relaxed}$)



iii. Fit the continuous Gaussian process metamodel on h dimensions

$$\text{Initial DoE} \begin{cases} x_{DoE} = (x_{s,0}, \dots, x_{n,0}) \\ y_{DoE} = (y_{s,0}, \dots, y_{n,0}) \end{cases} \quad \begin{cases} y_{pred}(x_{DoE}) = y_s \\ y_{pred}(x) = \hat{y} + \varepsilon(x) \end{cases} \rightarrow \begin{cases} \varepsilon(x) \sim N(0, \sigma^2) \\ \text{Corr}(\varepsilon(x), \varepsilon(x')) = k(x^i - x^j, \theta) \end{cases}$$

The *hyperparameters* of the model are fit to data by maximum likelihood estimation.

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Proposed approach: the surrogate model (1/2)

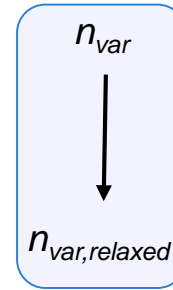
i. Relax continuously integer/categorical input variables

if integer

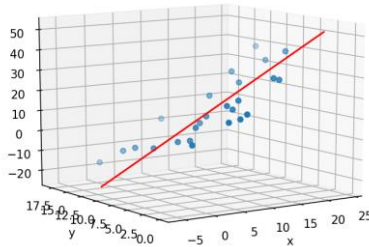
|relax continuously within the bounds

if categorical

|Add a dimension by level with bounds [0,1]



ii. Use PLS to reduce the dimension $n_{var,relaxed}$ to h principal components ($h \ll n_{var,relaxed}$)



iii. Fit the continuous Gaussian process metamodel on h dimensions

$$\text{Initial DoE} \begin{cases} x_{DoE} = (x_{s,0}, \dots, x_{n,0}) \\ y_{DoE} = (y_{s,0}, \dots, y_{n,0}) \end{cases} \quad \begin{cases} y_{pred}(x_{DoE}) = y_s \\ y_{pred}(x) = \hat{y} + \varepsilon(x) \end{cases} \rightarrow \begin{cases} \varepsilon(x) \sim N(0, \sigma^2) \\ \text{Corr}(\varepsilon(x), \varepsilon(x')) = k(x^i - x^j, \theta) \end{cases}$$

The *hyperparameters* of the model are fit to data by maximum likelihood estimation.

iv. Project back to respect the type of the variables

D. R. Jones, M. Schonlau, and W. J. Welch. "Efficient Global Optimization of Expensive Black-Box Functions". Journal of Global Optimization, vol. 13 (1998), pages 455–492.

C. E. Rasmussen, and J. Quiñero-Candela, "A Unifying View of Sparse Approximate Gaussian Process Regression". Journal of Machine Learning Research, vol. 6 (2005), pages 1939–1959.

Proposed approach: the surrogate model (2/2)

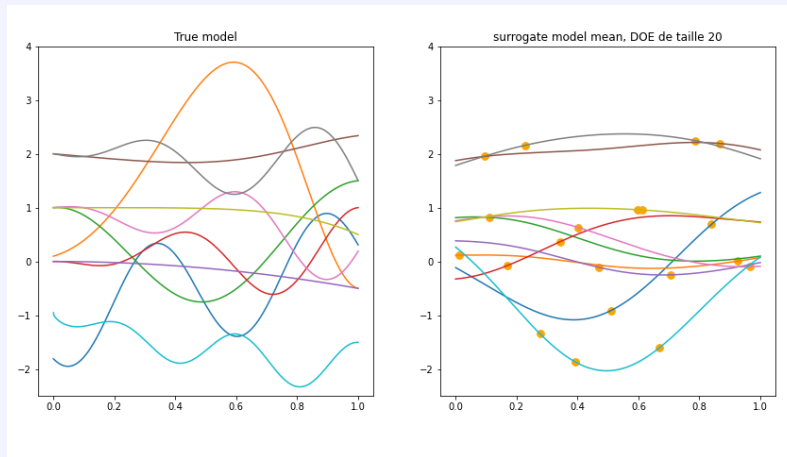
D. R. Jones, M. Schonlau, and W. J. Welch. "Efficient Global Optimization of Expensive Black-Box Functions". Journal of Global Optimization, vol. 13 (1998), pages 455–492.

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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

- Variable types: continuous and categorical with 10 levels. $n_{var,relaxed} = 11$



Toy case

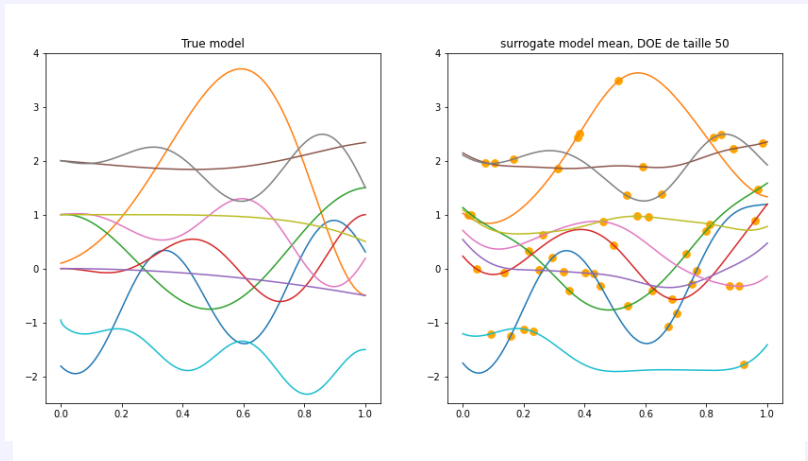
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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

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Toy case

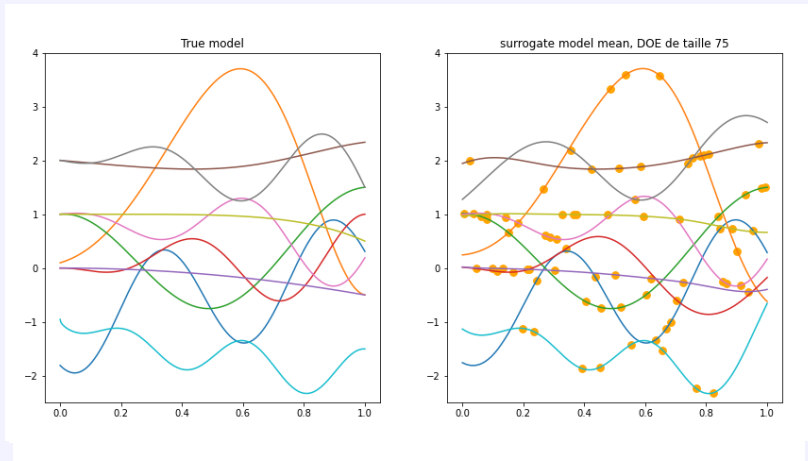
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Toy case

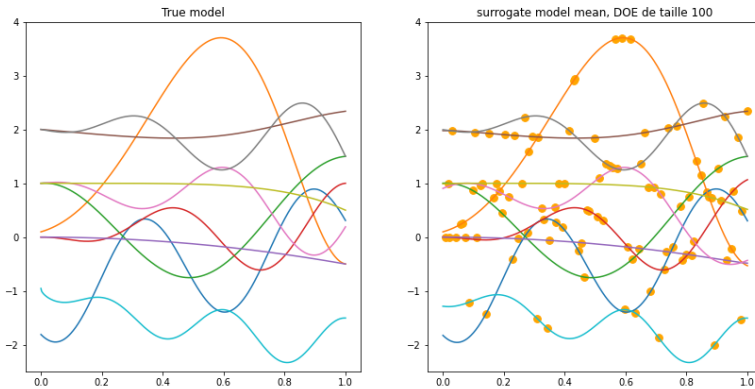
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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

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Toy case

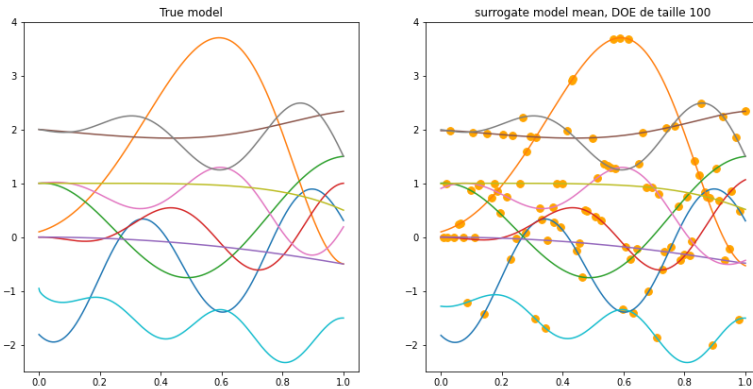
D. R. Jones, M. Schonlau, and W. J. Welch. "Efficient Global Optimization of Expensive Black-Box Functions". Journal of Global Optimization, vol. 13 (1998), pages 455–492.

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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

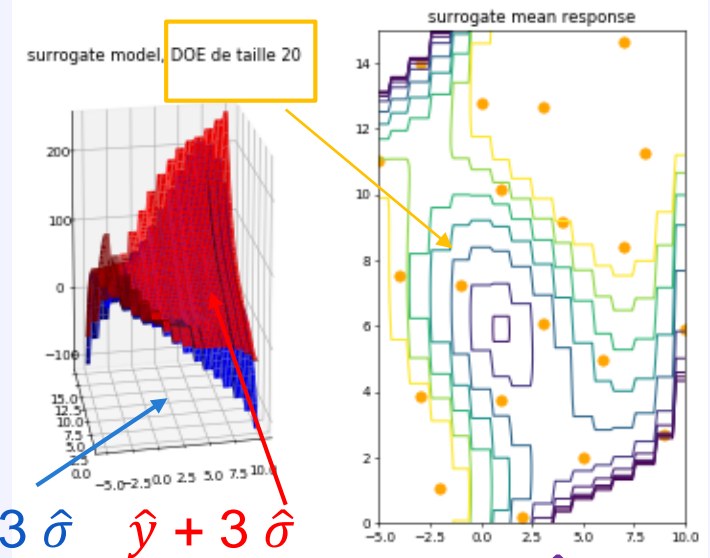
- Variable types: continuous and categorical with 10 levels. $n_{var,relaxed} = 11$



Toy case

Validation problem $n_{var} = 2$

- Variable types: continuous and integer



Integer Branin

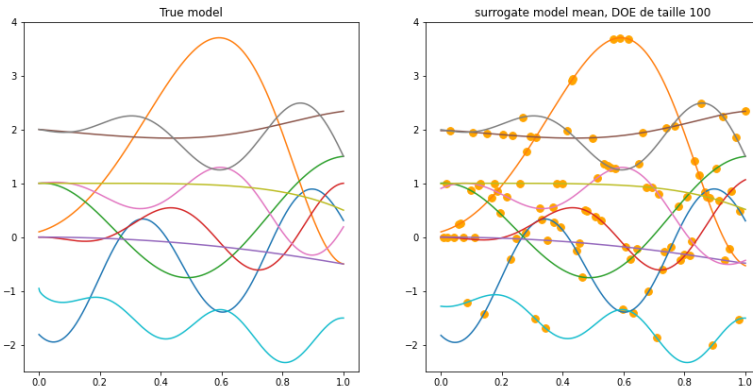
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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

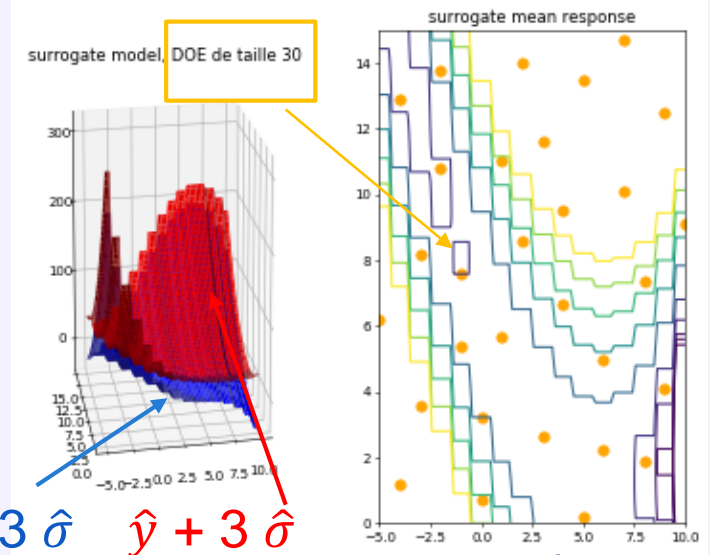
- Variable types: continuous and categorical with 10 levels. $n_{var,relaxed} = 11$



Toy case

Validation problem $n_{var} = 2$

- Variable types: continuous and integer



$$\hat{y} - 3 \hat{\sigma} \quad \hat{y} + 3 \hat{\sigma}$$

Integer Branin

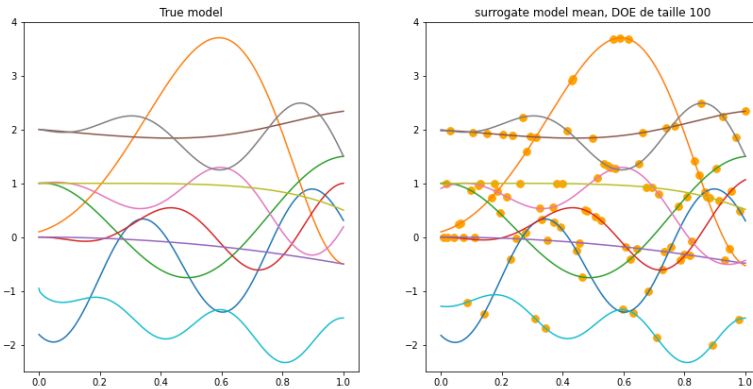
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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

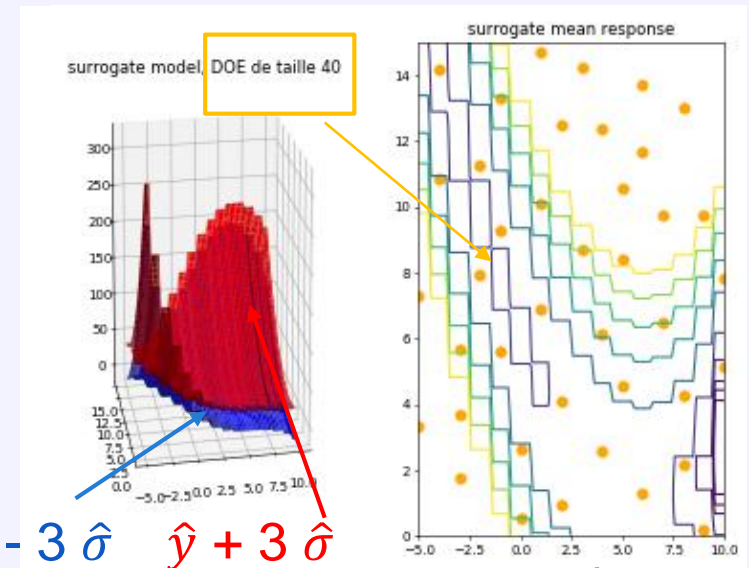
- Variable types: continuous and categorical with 10 levels. $n_{var,relaxed} = 11$



Toy case

Validation problem $n_{var} = 2$

- Variable types: continuous and integer



Integer Branin

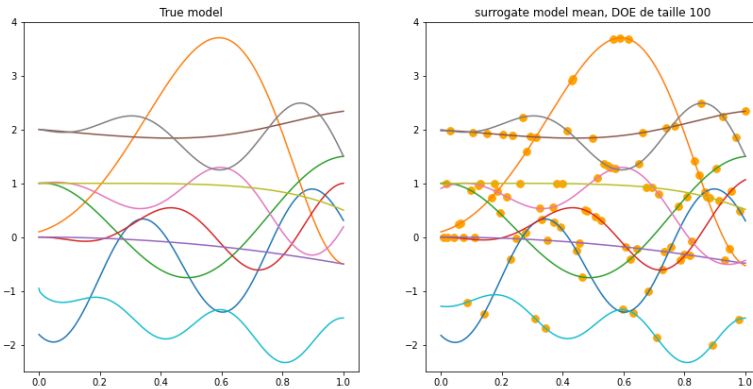
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Proposed approach: the surrogate model (2/2)

Validation problem $n_{var} = 2$

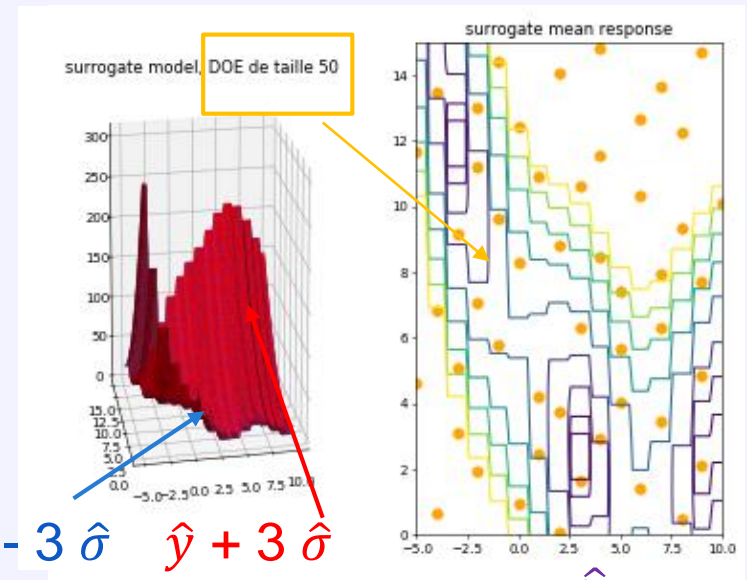
- Variable types: continuous and categorical with 10 levels. $n_{var,relaxed} = 11$



Toy case

Validation problem $n_{var} = 2$

- Variable types: continuous and integer



Integer Branin

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Proposed approach: The optimization process

- i. Build the surrogate model of the objective $(\hat{y}(x), \hat{\sigma}(x))$

R. Priem, N. Bartoli, Y. Diouane, A. Sgueglia. "Upper Trust Bound Feasibility Criterion for Mixed Constrained Bayesian Optimization with Application to Aircraft Design". Aerospace Science and Technology

Proposed approach: The optimization process

- i. Build the surrogate model of the objective $(\hat{y}(x), \hat{\sigma}(x))$
- ii. Build the surrogate model for each constraint $(\hat{c}_i(x), \hat{\sigma}_i(x))$ and compute $\Omega_f = \{x \in \Omega : \hat{c}_i(x) - 3\hat{\sigma}_i(x) \leq 0\}$

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- iii. Compute the infill criterion $WB2s(x) = -\hat{y}(x) + s \cdot EI(x)$, with $EI(x) = \mathbb{E}[\max\{f_{\min} - y(x), 0\}]$ for an optimal scaling factor s . This measure consists in an **optimal trade-off** between the unknown zones to **explore** and the best zones to **exploit**.

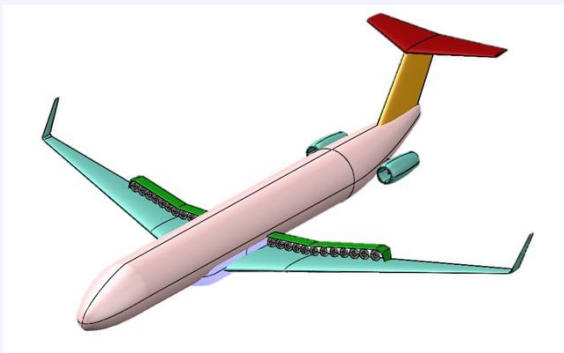
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- iv. Compute $y_{new} = f\left(\arg \max_{x \in \Omega_f} WB2s(x)\right)$.

Proposed approach: The optimization process

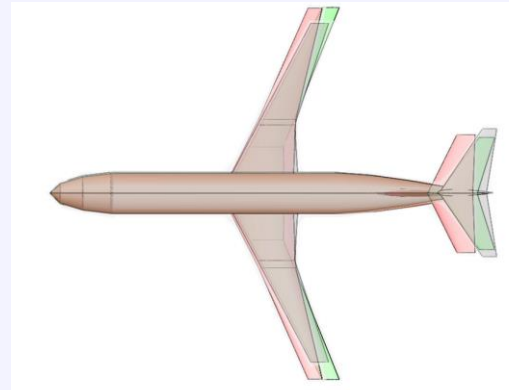
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Hybrid aircraft concept with distributed propulsion



Validation problem $n_{var} = 12$

- 8 inequality constraints and 3 equality constraints.
- Total energy consumption.



R. Priem, N. Bartoli, Y. Diouane, A. Sgueglia. "Upper Trust Bound Feasibility Criterion for Mixed Constrained Bayesian Optimization with Application to Aircraft Design". Aerospace Science and Technology

Optimization problems and options

Optimization problems and options

Optimizers

- Unconstrained cases: Bandit-BO
- No parallelization, batch = 1

D. Nguyen, S. Gupta, S. Rana, A. Shilto, and S. Venkatesh, "Bayesian Optimization for Categorical and Category-Specific Continuous Inputs". In: AAAI Conference on Artificial Intelligence. 2020.

- Constrained cases: genetic algorithm NSGA2 (1 objective)
- Probability of crossover = 1, eta = 3 from the Open-Source Pymoo toolbox <https://pymoo.org/>

J. Blank and K. Deb, "Pymoo: Multi-Objective Optimization in Python," in IEEE Access, vol. 8, pp. 89497-89509, 2020.

- SEGO coupled with the Open-Source SMT toolbox <https://smt.readthedocs.io/>
- WB2s maximized with SNOPT <https://web.stanford.edu/group/SOL/snopt.htm>
- With and without Partial Least Squares.

M. A. Bouhlef, J. T. Hwang, N. Bartoli, R. Lafage, J. Morlier, and J. R. R. A. Martins. "A Python surrogate modeling framework with derivatives". Advances in Engineering Software 135 (2019).
P. E. Gill, W. Murray, and M. A. Saunders. "SNOPT: An SQP Algorithm for Large-Scale Constrained Optimization". SIAM Review 47.1 (2005), pages 99–131.

Optimization problems and options

Optimizers

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P. E. Gill, W. Murray, and M. A. Saunders. "SNOPT: An SQP Algorithm for Large-Scale Constrained Optimization". SIAM Review 47.1 (2005), pages 99–131.

Test cases

- Validation on analytical test cases, with and without constraints (20 runs)
 - For SEGO & Bandit-BO: 50 iterations
 - For NSGA2: 200 iterations (5 individuals, 40 mutations)
- Validation on an expensive industrial case
 - For SEGO & NSGA2: 20 runs of 50 iterations

Unconstrained Bayesian optimization (1/2)

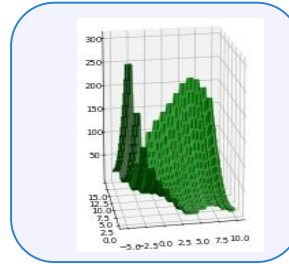
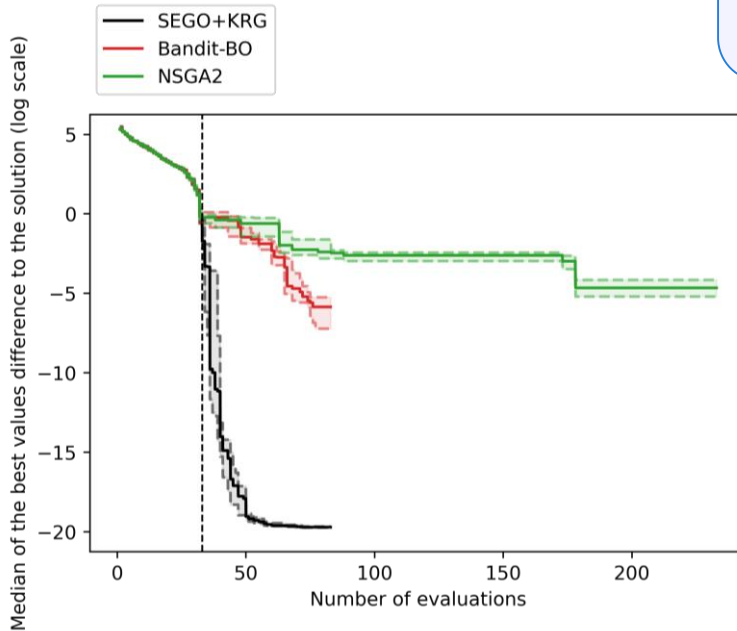
Validation problem $n_{var} = 2$

- Variable types: integer (1) and continuous (1).

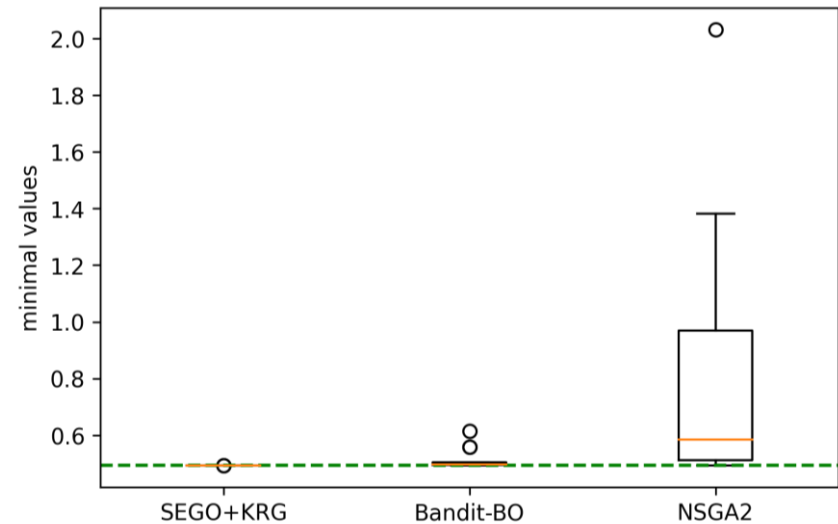
Options for Bandit-BO

16 arms, minimal DoE of 32 points

Convergence plots for the integer Branin test case



Boxplots for the 20 optimization results after 50 iterations



S. Roy, W. A. Crossley, B. Stanford, K. T. Moore, and J. S. Gray, "A Mixed Integer Efficient Global Optimization Algorithm with Multiple Infill Strategy - Applied to a Wing Topology Optimization Problem". In: AIAA Scitech 2019 Forum.

Unconstrained Bayesian optimization (2/2)

Validation problem $n_{var} = 2$

- Variable types: continuous (1) and categorical (1 with 10 levels). $n_{var,relaxed} = 11$

Options for Bandit-BO

10 arms, minimal DoE of 20 points

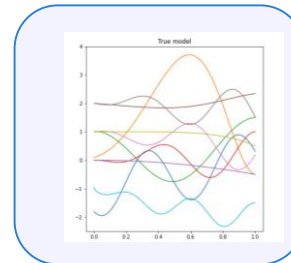
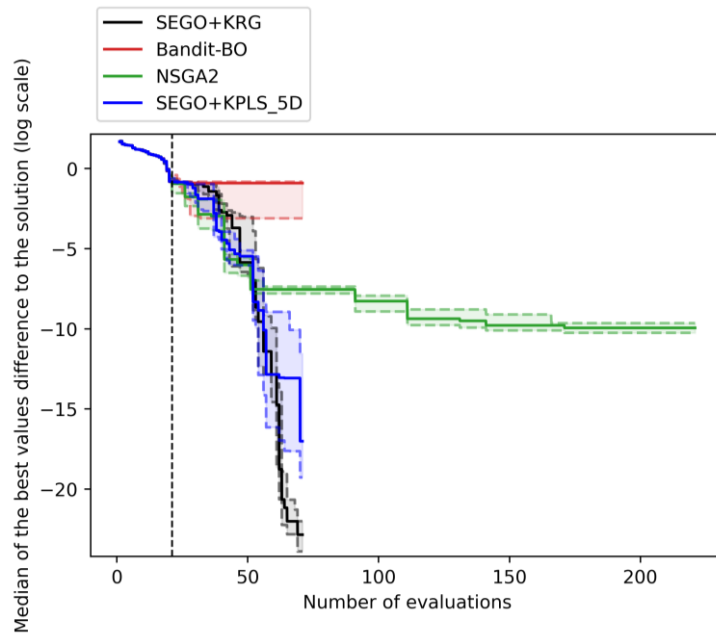
Options for NSGA2

Categorical variable treated as integer

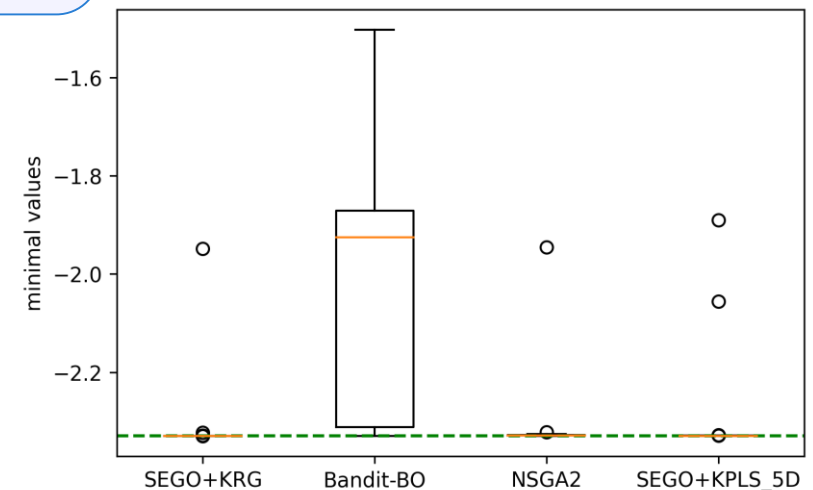
Options for SEGO-KPLS

$n_{var,relaxed} = 11 \rightarrow h = 5$

Convergence plots for the Toy test case



Boxplots for the 20 optimization results after 50 iterations



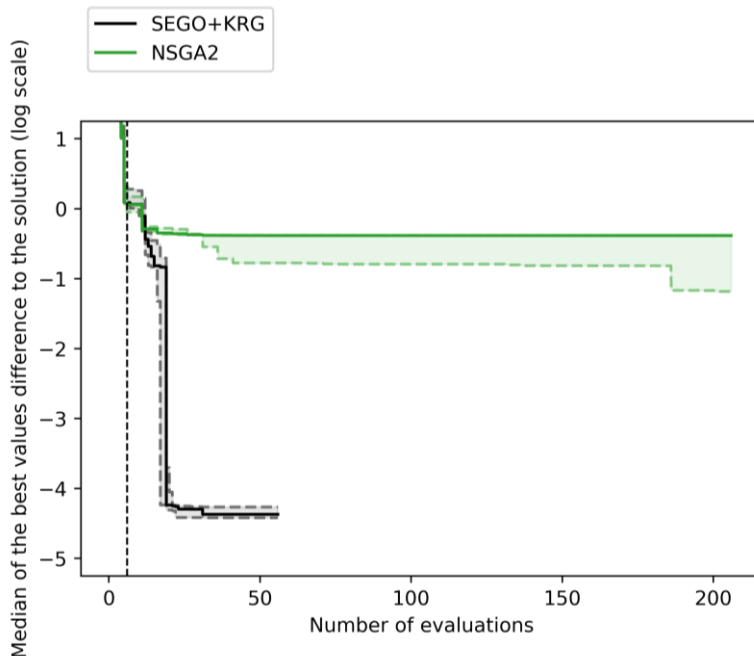
Constrained Bayesian optimization (1/2)

Validation problem $n_{var} = 4$
Variable types: continuous (2) and categorical (2 with 2 levels). $n_{var,relaxed} = 6$

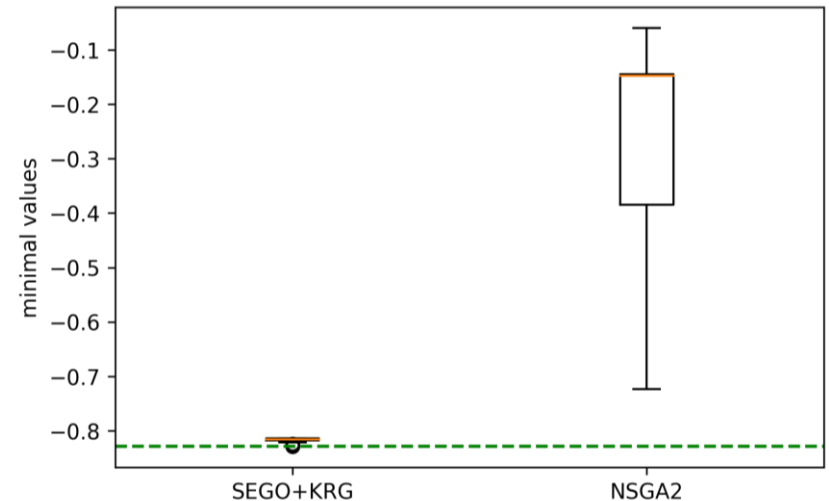
- 1 constraint

Options for NSGA2
Categorical variables treated as integer ones

Convergence plots for the categorical Branin test case



Boxplots for the 20 optimization results after 50 iterations



J. Pelamatti, L. Brevault, M. Balesdent, E.-G Talbi, and Y. Guerin. "Efficient global optimization of constrained mixed variable problems". Journal of Global Optimization 73 (2019), pages 583-613

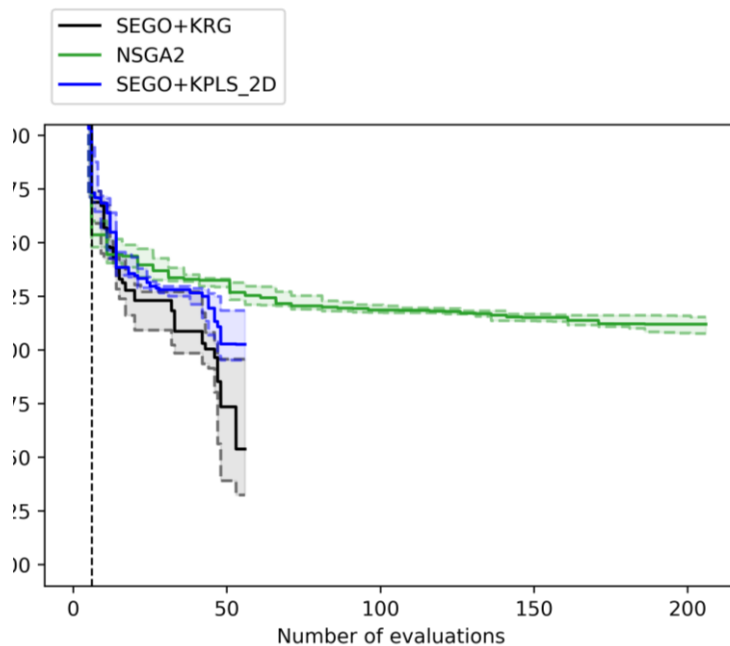
Constrained Bayesian optimization (2/2)

Validation problem $n_{var} = 12$
Variable types: continuous (10) and categorical (2 with 2 levels). $n_{var,relaxed} = 14$

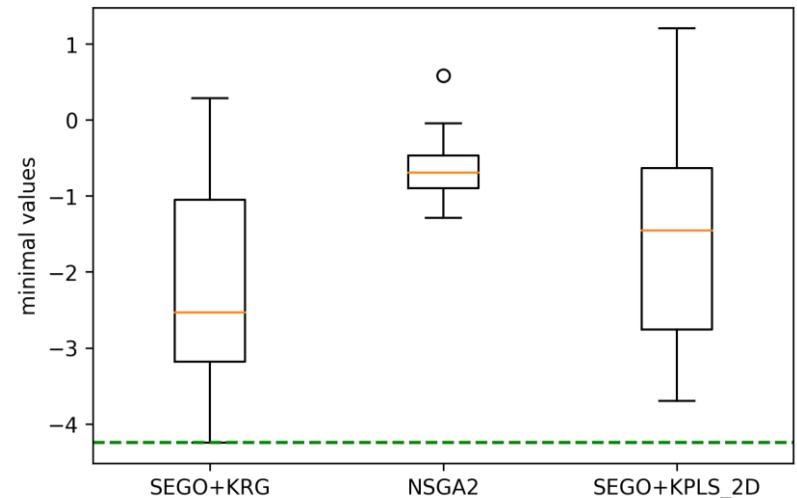
- 1 constraint

Options for NSGA2
Categorical variables treated as integer ones
Options for SEGO-KPLS
 $n_{var,relaxed} = 14 \rightarrow h = 2$

Convergence plots for the augmented categorical Branin test case



Boxplots for the 20 optimization results after 50 iterations



J. Pelamatti, L. Brevault, M. Balesdent, E.-G Talbi, and Y. Guerin. "Efficient global optimization of constrained mixed variable problems". Journal of Global Optimization 73 (2019), pages 583-613

Optimization problem

Short range reference Aircraft CeRAS A320

Future Aircraft Sizing Tool-Overall Aircraft Design

<https://github.com/fast-aircraft-design/FAST-OAD>

Design variables	Nature	Range
Number of engines	discrete	{1,2,3,4}
Engine position	cat	Under wing/rear fuselage
Horizontal tail	cat	Attached fuselage / vertical tail
Mean average chord at 25%	cont	[16.,18.] (m)
Wing Aspect Ratio	cont	[3.,20.]
VT Aspect Ratio	cont	[3.,20.]
HT Aspect Ratio	cont	[1.5, 50.]
Wing taper ratio	cont	[0.,1.]
Angle for swept wing	cont	[20., 48] (°)
Cruise altitude	cont	[5000., 38000.] (feet)



$$n_{var} = 10$$

Variable types: continuous (7), integer (1) and categorical (2 with 2 levels).
each. $n_{var,relaxed} = 14$

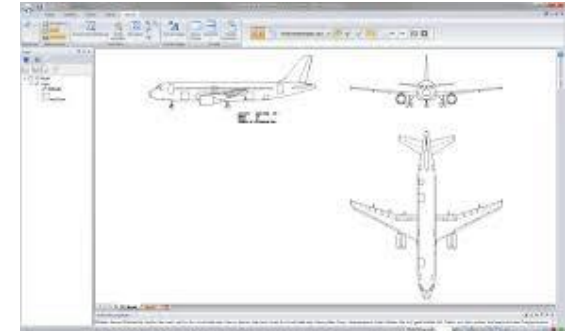
Optimization problem

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HT Aspect Ratio	cont	[1.5, 50.]
Wing taper ratio	cont	[0.,1.]
Angle for swept wing	cont	[20., 48] (°)
Cruise altitude	cont	[5000., 38000.] (feet)



$$n_{var} = 10$$

Variable types: continuous (7), integer (1) and categorical (2 with 2 levels).
each. $n_{var,relaxed} = 14$

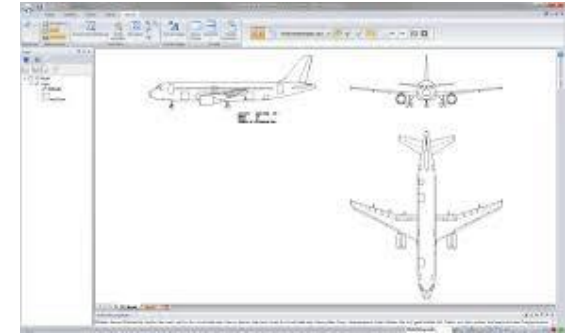
Optimization problem

Short range reference Aircraft CeRAS A320

Future Aircraft Sizing Tool-Overall Aircraft Design

<https://github.com/fast-aircraft-design/FAST-OAD>

Design variables	Nature	Range
Number of engines	discrete	{1,2,3,4}
Engine position	cat	Under wing/rear fuselage
Horizontal tail	cat	Attached fuselage / vertical tail
Mean average chord at 25%	cont	[16.,18.] (m)
Wing Aspect Ratio	cont	[3.,20.]
VT Aspect Ratio	cont	[3.,20.]
HT Aspect Ratio	cont	[1.5, 50.]
Wing taper ratio	cont	[0.,1.]
Angle for swept wing	cont	[20., 48] (°)
Cruise altitude	cont	[5000., 38000.] (feet)



$$n_{var} = 10$$

Variable types: continuous (7), integer (1) and categorical (2 with 2 levels).
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	Name	Lower	Value	Upper	Unit	Description
1	data.handling_qualities:static_margin	0.05	0.049999981508569307	0.1		(X-position of neutral point - X-position of center of gravity) / (mean aerodynamic chord)

	Name	Value	Unit	Description
2	data.mission:sizing:fuel	20564.57070885031	kg	consumed fuel mass during whole mission

S. Delbecq, C. David, S. Defoort, P. Schmollgruber, and E. Benard, V. Pommier-Budinger. " ". In: 10th EASN Virtual International Conference on Innovation in Aviation & Space to the Satisfaction of the European Citizens (2020).

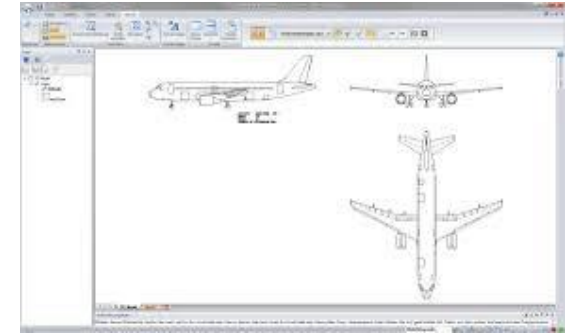
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- 2 inequality constraints
- Fuel-Mission

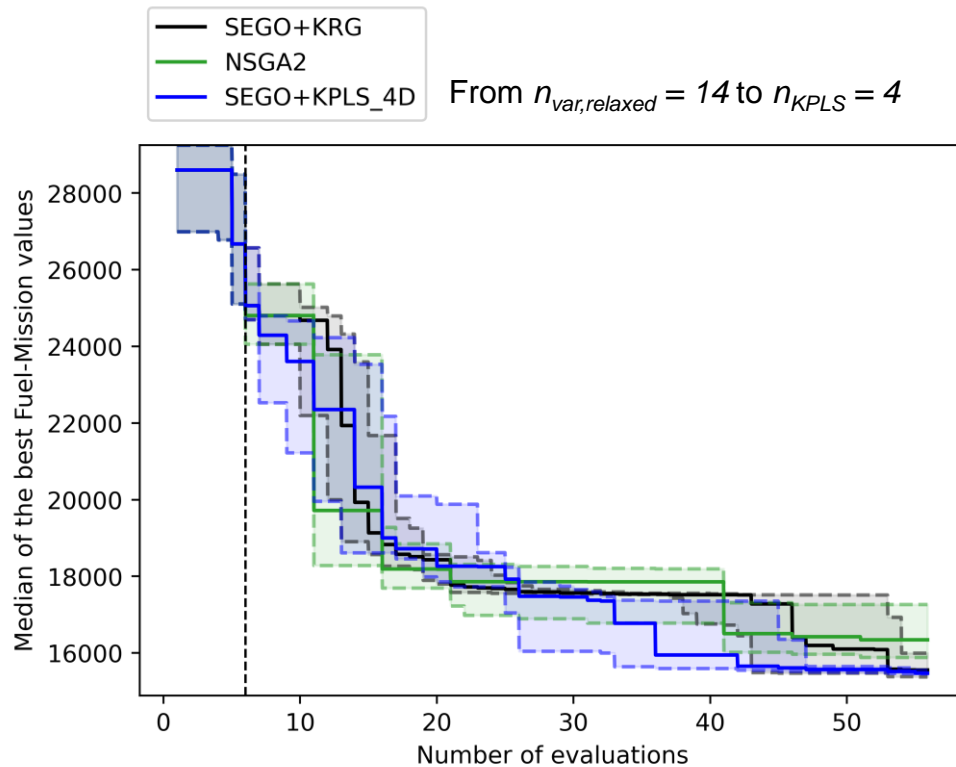
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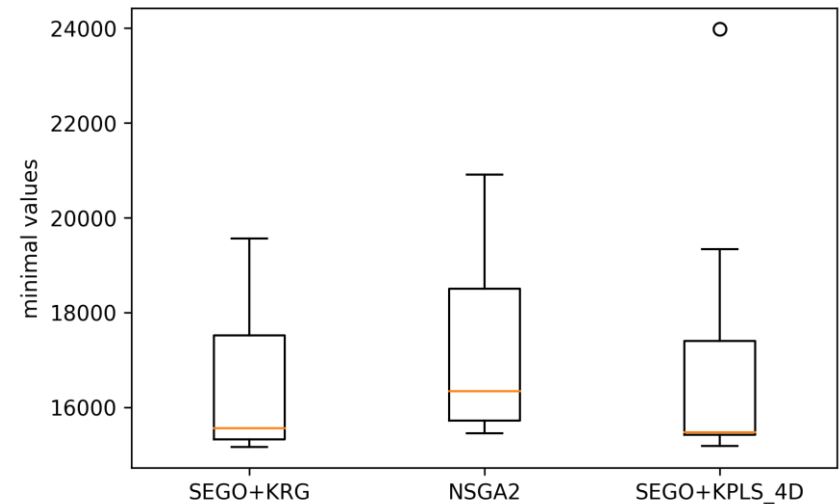
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CeRAS A 320 Optimization results

CeRAS test case in dimension 10



Repartition of 20 best Fuel-Mission values after 50 evaluations



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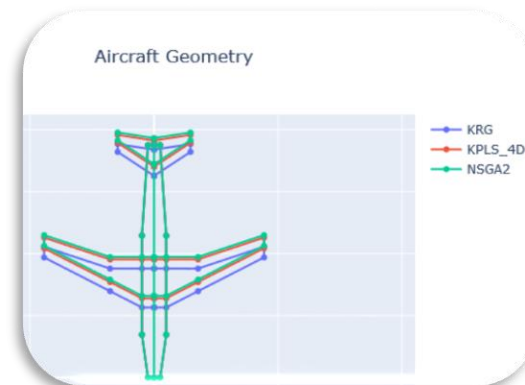
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→ Investigate other mixed optimization heuristics (SO-MI, Bi-level, CAT-EGO,...) for high-dimensional optimization.

J. Mueller, C. Shoemaker, and R. Piché. "SO-MI: A surrogate model algorithm for computationally expensive nonlinear mixed-integer black-box global optimization problems". Computers and Operations Research 40 (2013), pages 1383-1400.

P.J. Barjhoux, Y. Diouane, S. Grihon, D. Bettebghor, J. Morlier. "A bi-level methodology for solving large-scale mixed categorical structural optimization". Struct Multidisc Optim 62 (2020), pages 337–351 .

M. Muniga, and D. Sinoquet. "Global optimization for mixed categorical-continuous variables based on Gaussian process models with a randomized categorical space exploration step". Information Systems and Operational Research, vol. 58 (2020), pages 1–32.

The End

Thank you for your attention !

