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Block Elimination Distance¹

Öznur Yaşar Diner^{2,3} — Archontia C. Giannopoulou⁴ — Giannos Stamoulis^{4,5}

Dimitrios M. Thilikos⁶

Abstract

We introduce the parameter of block elimination distance as a measure of how close a graph is to some particular graph class. Formally, given a graph class \mathcal{G} , the class $\mathcal{B}(\mathcal{G})$ contains all graphs whose blocks belong to \mathcal{G} and the class $\mathcal{A}(\mathcal{G})$ contains all graphs where the removal of a vertex creates a graph in \mathcal{G} . Given a hereditary graph class \mathcal{G} , we recursively define $\mathcal{G}^{(k)}$ so that $\mathcal{G}^{(0)} = \mathcal{B}(\mathcal{G})$ and, if $k \geq 1$, $\mathcal{G}^{(k)} = \mathcal{B}(\mathcal{A}(\mathcal{G}^{(k-1)}))$. The block elimination distance of a graph G to a graph class \mathcal{G} is the minimum k such that $G \in \mathcal{G}^{(k)}$ and can be seen as an analog of the elimination distance parameter, defined in [J. Bulian and A. Dawar. Algorithmica, 75(2):363–382, 2016, with the difference that connectivity is now replaced by biconnectivity. We show that, for every non-trivial hereditary class \mathcal{G} , the problem of deciding whether $G \in \mathcal{G}^{(k)}$ is NP-complete. We focus on the case where \mathcal{G} is minor-closed and we study the minor obstruction set of $\mathcal{G}^{(k)}$ i.e., the minor-minimal graphs not in $\mathcal{G}^{(k)}$. We prove that the size of the obstructions of $\mathcal{G}^{(k)}$ is upper bounded by some explicit function of k and the maximum size of a minor obstruction of \mathcal{G} . This implies that the problem of deciding whether $G \in \mathcal{G}^{(k)}$ is constructively fixed parameter tractable, when parameterized by k. Our results are based on a structural characterization of the obstructions of $\mathcal{B}(\mathcal{G})$, relatively to the obstructions of \mathcal{G} . Finally, we give two graph operations that generate members of $\mathcal{G}^{(k)}$ from members of $\mathcal{G}^{(k-1)}$ and we prove that this set of operations is complete for the class \mathcal{O} of outerplanar graphs. This yields the identification of all members $\mathcal{O} \cap \mathcal{G}^{(k)}$, for every $k \in \mathbb{N}$ and every non-trivial minor-closed graph class \mathcal{G} .

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1 Introduction

Graph distance parameters are typically introduced as measures of "how close" is a graph G to some given graph class \mathcal{G} . One of the main motivating factors behind introducing such distance parameters is the following. Let \mathcal{G} be a graph class on which a computational problem Π is tractable and let $\mathcal{G}^{(k)}$ be the class of graphs with distance at most k from \mathcal{G} , for some notion of distance. Our aim is to exploit the "small" distance of the graphs in $\mathcal{G}^{(k)}$ from \mathcal{G} in order to extend the tractability of Π in the graph class $\mathcal{G}^{(k)}$. This approach on dealing with computational problems is known as parameterization by distance from triviality [12]. Usually, a graph distance measure is defined by minimizing the number of modification operations that can transform a graph G to a graph in \mathcal{G} .

The most classic modification operation is the apex extension of a graph class \mathcal{G} , defined as $\mathcal{A}(\mathcal{G}) = \{G \mid \exists v \in V(G) \mid G \setminus v \in \mathcal{G}\}$ and the associated parameter, the vertex-deletion distance of G to \mathcal{G} , is defined as $\min\{k \mid G \in \mathcal{A}^k(\mathcal{G})\}$. The vertex-deletion distance has been extensively studied. Other, popular variants of modification operations involve edge removals/additions/contractions or combinations of them [4,9,11].

Elimination distance. Bulian and Dawar in [5,6], introduced the *elimination distance* of G to a class \mathcal{G} as follows:

$$\mathsf{ed}_{\mathcal{G}}(G) = \begin{cases} 0 & G \in \mathcal{G} \\ \max\{\mathsf{ed}_{\mathcal{G}}(C) \mid C \in \mathsf{cc}(G)\} & \text{if } G \not\in \mathcal{G} \text{ and } G \text{ is not connected }, \\ 1 + \min\{\mathsf{ed}_{\mathcal{G}}(G \setminus v) \mid v \in V(G)\} & \text{if } G \not\in \mathcal{G} \text{ and } G \text{ is connected} \end{cases},$$

where by cc(G) we denote the connected components of G. Notice that the definition ed_{G} , apart from vertex deletions, also involves the connected closure operation, defined as $\mathcal{C}(\mathcal{G}) = \{G \mid \forall C \in \mathcal{G}\}$ $cc(G), C \in \mathcal{G}$. Observe that $ed_{\mathcal{G}}(G) = 0$ iff $G \in \mathcal{G} \cup \mathcal{C}(\mathcal{G})$, while, for k > 0, $ed_{\mathcal{G}}(G) \leq k$ iff $G \in \mathcal{G}' \cup \mathcal{C}(\mathcal{G}')$, where $\mathcal{G}' = \mathcal{A}(\{G \mid \operatorname{\sf ed}_G(G) \leq k-1\})$. Therefore, $\operatorname{\sf ed}_G$ can be seen as a nondeterministic counterpart of the vertex-deletion operation where the operation \mathcal{C} acts as the source of non-determinism, that is, in each level of the recursion, the vertex deletion operation is applied to each of the connected components of the current graph. A motivation of Bulian and Dawar in [5] for introducing ed_G was the study of the GRAPH ISOMORPHISM Problem. Indeed, it is easy to see that there are constants c_{α} and c_{κ} such that if Graph Isomorphism can be solved in $O(n^c)$ time in some graph class \mathcal{G} , then it can be solved in time $O(n^{c+c_{\alpha}})$ (resp. $O(n^{c+c_{\kappa}})$) in the graph class $\mathcal{A}(\mathcal{G})$ (resp. $\mathcal{C}(\mathcal{G})$) (see [8,13,14]). This implies that GRAPH ISOMORPHISM can be solved in $n^{O(k)}$ steps in the class of graphs where ed_G is bounded by k. In [5], Bulian and Dawar improved this implication for the class \mathcal{G}_d of graphs of width at most d and proved that Graph Isomorphism can be solved in $f(k) \cdot n^{c_d}$ time in the class $\{G \mid \mathsf{ed}_{\mathcal{G}_d}(G) \leq k\}$ (here c_d is a constant depending on d). In other words, for every d, GRAPH ISOMORPHISM is fixed parameter tractable (in short FPT), when parameterized by $ed_{\mathcal{G}_d}$.

Computing the elimination distance. Typically, the algorithmic results on $\operatorname{\sf ed}_{\mathcal{G}}$ apply for instantiations of \mathcal{G} that are hereditary, i.e., the removal of a vertex of a graph in \mathcal{G} results to a graph that is again in \mathcal{G} . Bulian and Dawar in [6] examined the case where \mathcal{G} is minor-closed. One may observe that containment in \mathcal{G} is equivalent to the exclusion of the graphs in the minor-obstruction set of \mathcal{G} , that is the set $\operatorname{\sf obs}(\mathcal{G})$ of the minor-minimal graphs not in \mathcal{G} . Also the minor-closed property

is invariant under the operations \mathcal{A} and \mathcal{C} , therefore the class $\{G \mid \mathsf{ed}_{\mathcal{C}}(G) \leq k\}$ is also minor-closed. From the Robertson and Seymour theorem, $obs(\{G \mid ed_G(G) \le k\})$ is finite, and this implies, using the algorithmic results of [16,19], that for every minor-closed class \mathcal{G} , deciding whether $\operatorname{ed}_{\mathcal{G}}(G) \leq k$ is FPT (parameterized by k) by an algorithm that runs in $f(k) \cdot n^2$ time. While this approach is not constructive in general, Bulian and Dawar in [6] proved that there is an algorithm that, with input $obs(\mathcal{G})$ and k, outputs the set $obs(\{G \mid ed_{\mathcal{G}}(G) \leq k\})$. This makes the aforementioned $f(k) \cdot n^2$ -time algorithm constructive in the sense that the function f is computable. An explicit estimation of this function f can be derived from the recent results in [20–22]. The computational complexity of $ed_{\mathcal{G}}$ was also studied for different instantiations of \mathcal{G} . In [18] Lindermayr, Siebertz, and Vigny considered the class \mathcal{G}_d of graphs of degree at most d. They proved that, given k, d, and a planar graph G, deciding whether $ed_{G_d}(G) \leq k$ is FPT (parameterized by k and d) by designing an $f(k,d) \cdot n^{O(1)}$ time algorithm. Also, in [2] the same result was proved without the planarity restriction. Moreover, in [2], more general hereditary classes where considered: let \mathcal{F} be some finite set of graphs and let $\mathcal{G}_{\mathcal{F}}$ be the class of graphs excluding all graphs in \mathcal{F} as induced subgraphs. It was proved in [2] that for every such \mathcal{F} the problem that, given some graph G and k, deciding whether $\operatorname{ed}_{\mathcal{G}_{\mathcal{F}}}(G) \leq k$ is FPT (parameterized by k) by designing an $f(k) \cdot n^{c_d}$ time algorithm, where c_d is a constant depending on d (see also [3] for earlier results).

Block elimination distance. We introduce a more general version of elimination distance where the source of non-determinism is *biconnectivity* instead of connectivity. The recursive application of the vertex deletion operation is now done on the *blocks* of the current graph instead of its components. That way, the *block elimination distance* of a graph G to a graph class G is defined as

$$\mathsf{bed}_{\mathcal{G}}(G) = \begin{cases} 0 & G \in \mathcal{G} \\ \max\{\mathsf{bed}_{\mathcal{G}}(B) \mid B \in \mathsf{bc}(G)\} & \text{if } G \not\in \mathcal{G} \text{ and } G \text{ is not biconnected }, \\ 1 + \min\{\mathsf{bed}_{\mathcal{G}}(G \setminus v) \mid v \in V(G)\} & \text{if } G \not\in \mathcal{G} \text{ and } G \text{ is biconnected} \end{cases},$$

where by bc(G) we denote the blocks of the graph G. We stress that the "source of non-determinism" in the above definition is the *biconnected closure* operation, defined as $\mathcal{B}(\mathcal{G}) = \{G \mid \forall B \in bc(G), B \in \mathcal{G}\}$.

Notice that the above parameter is more general than $\operatorname{ed}_{\mathcal{G}}$ in the sense that it upper bounds $\operatorname{ed}_{\mathcal{G}}$ but it is not upper bounded by any function of $\operatorname{ed}_{\mathcal{G}}$: for instance, if G is a connected graph whose blocks belong to \mathcal{G} , it follows that $\operatorname{bed}_{\mathcal{G}}(G)=0$, while $\operatorname{ed}_{\mathcal{G}}(G)$ can be arbitrarily big.¹ Moreover, $\operatorname{bed}_{\mathcal{G}}$, can also serve as a measure for the distance to triviality in the same way as $\operatorname{ed}_{\mathcal{G}}$. For instance, there is a constant c_{β} such that if Graph Isomorphism can be solved in $O(n^c)$ time in some graph class \mathcal{G} , then it can be solved in time $O(n^{c+c_{\beta}})$ in the graph class $\mathcal{B}(\mathcal{G})$ (using standard techniques, see e.g., [8,13,14]). This implies that Graph Isomorphism can be solved in $n^{O(k)}$ steps in the class of graphs where $\operatorname{bed}_{\mathcal{G}}$ is bounded by k. Clearly, all the problems studied so far on the elimination distance have their counterpart for the block elimination distance and this is a relevant line of research, as the new parameter is more general than its connected counterpart.

Our results. As a first step, we prove that if \mathcal{G} is a non-trivial² and hereditary class, then deciding whether $\mathsf{bed}_{\mathcal{G}}(G) \leq k$ is an NP-complete problem (Section 3). For our proof we certify

¹It is easy to see that $ed_{\mathcal{G}}(G)$ is logarithmically lower-bounded by the maximum number of cut-vertices in a path of G.

²A class is *non-trivial* if it contains at least one non-empty graph and is not the class of all graphs.

yes-instances by using an alternative definition of $bed_{\mathcal{G}}$ that is based on an (multi)-embedding of G in a rooted forest (Section 2).

We next focus our study on the case where \mathcal{G} is minor-closed (and non-trivial). As the operation \mathcal{B} maintains minor-closedness, it follows that the class $\mathcal{G}^{(k)} := \{G \mid \mathsf{bed}_{\mathcal{G}}(G) \leq k\}$ is minor-closed for every k, therefore for every minor-closed \mathcal{G} , deciding whether $G \in \mathcal{G}^{(k)}$ is FPT (parameterized by k). Following the research line of [6], we make this result constructive by proving that it is possible to bound the size of the obstructions of $\mathcal{G}^{(k)}$ by some explicit function of k and the maximum size of the obstructions of \mathcal{G} . This bound is based on the results of [1,21] (Section 4) and a structural characterization of $\mathsf{obs}(\mathcal{B}(G))$, in terms of $\mathsf{obs}(\mathcal{G})$, implying that no obstruction of $\mathcal{B}(G)$ has size that is more than twice the maximum size of an obstruction of \mathcal{G} (Section 5).

In Section 6 we take a closer look of the obstructions of $\mathcal{G}^{(k)}$. We give two graph operations, called parallel join and triangular gluing, that generate members of $\mathcal{G}^{(k)}$ from members of $\mathcal{G}^{(k-1)}$. This yields that the number of obstructions of $\mathcal{G}^{(k)}$ is at least doubly exponential on k. Moreover, we prove that this set of operations is complete for the class \mathcal{O} of outerplanar graphs. This implies the complete identification of $\mathcal{O} \cap \mathcal{G}^{(k)}$, for every $k \in \mathbb{N}$ and every non-trivial minor-closed graph class \mathcal{G} . This yields that the number of obstructions of $\mathcal{G}^{(k)}$ is at least doubly exponential on k.

The paper concludes in Section 7 with some further observations and open problems.

2 Definitions and preliminary results

Sets and integers. We denote by \mathbb{N} the set of non-negative integers. Given two integers p and q, the set [p,q] refers to the set of every integer r such that $p \leq r \leq q$. For an integer $p \geq 1$, we set [p] = [1,p] and $\mathbb{N}_{\geq p} = \mathbb{N} \setminus [0,p-1]$. For a set S, we denote by S the set of all subsets of S and, given an integer $r \in [|S|]$, we denote by S the set of all subsets of S of size S. Given two sets S and a function S is a collection of objects where the operation S is defined, then we denote S is S is a collection and a function S is S in S is a collection of objects where the operation S is defined, then we denote S is S is a collection of objects where the operation S is defined, then we denote S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is a collection of objects where S is S is S is a collection of objects where S is S is S is a collection of objects where S is S is a collection of objects where S is S is S is a collection of objects where S is S is S is a collection of S is S in S is S in S is S in S in S is S in S in S in S is S in S in S in S in S is S in S in S in S in S is S in S in S in S in S in S in S is S in S i

Basic concepts on graphs. All graphs considered in this paper are undirected, finite, and without loops or multiple edges. We use V(G) and E(G) for the sets of vertices and edges of G, respectively. For simplicity, an edge $\{x,y\}$ of G is denoted by xy or yx. We say that H is a subgraph of G if $V(H) \subseteq V(G)$ and $E(H) \subseteq E(G)$. For a set of vertices $S \subseteq V(G)$, we denote by $G[S] = (S, E(G) \cap {S \choose 2})$ the subgraph of G induced by the vertices from S. We also define $G \setminus S = G[V(G) \setminus S]$; we write $G \setminus v$ instead of $G \setminus \{v\}$ for a single vertex set. We say that the graph H is an induced subgraph of a graph G if H = G[S] for some $S \subseteq V(G)$. Given $e \in E(G)$, we also denote $G \setminus e = (V(G), E(G) \setminus \{e\})$. For a vertex v, we define the set of its neighbors in G by $N_G(v) = \{u \mid vu \in E(G)\}$ and $\deg_G(v) = |N_G(v)|$ denotes the degree of v in G. A vertex v of G is called isolated if $\deg_G(v) = 0$. Given two graphs G_1 and G_2 we denote their disjoint union by $G_1 + G_2$. A graph G is connected if for every two vertices u and v, G contains a path whose end-vertices are u and v and it is biconnected if for every two vertices u and v, G contains a cycle containing the vertices u and v. A (bi)connected component of G is a subgraph of G that is maximally (bi)connected. We denote by cc(G) the set of all connected components of G. A cut-vertex of a graph G is a vertex $x \in V(G)$ such that $|cc(G)| < |cc(G \setminus v)|$. A bridge of a graph G is a connected subgraph on two vertices x, y and the edge e = xy such that $|cc(G)| < |cc(G \setminus e)|$. A block of a graph is either an isolated vertex, or a bridge of G, or a biconnected component of G. We also denote by bc(G) the set of all blocks of G and we say that a graph G is a block-graph if $bc(G) = \{G\}$.

We use the term $graph\ class$ (or simply class) for any set of graphs (this set might be finite or infinite). We say that a graph class is non-trivial if it contains at least one non-empty graph and does not contain all graphs. We say that a class \mathcal{G} is hereditary if every induced subgraph of a graph in \mathcal{G} belongs also to \mathcal{G} . Notice that both operations \mathcal{A} and \mathcal{B} maintain the property of being non-trivial and hereditary. We denote by \mathcal{E} the class of the edgeless graphs.

Some observations. In this paper we consider only classes that are non-trivial and hereditary. This implies that $\mathcal{G} \subseteq \mathcal{A}(\mathcal{G})$. Notice that this assumption is necessary as $\{K_1\} \not\subseteq \mathcal{A}(\{K_1\}) = \{K_2\} \ (\{K_1\} \text{ is non-hereditary})$ and $\{K_0\} \not\subseteq \mathcal{A}(\{K_0\}) = \{K_1\} \ (\{K_0\} \text{ is not non-trivial}).$ Also the hereditarity of \mathcal{G} implies that $\mathcal{G} \subseteq \mathcal{B}(\mathcal{G})$ and hereditarity is necessary for this as, for example, $\{P_3\} \not\subseteq \mathcal{B}(\{P_3\}) = \{K_0\}.$ However, $\mathcal{G} \subseteq \mathcal{B}(\mathcal{G})$ also holds for the two finite classes that are not non-trivial, i.e., $\mathcal{B}(\{\}) = \{K_0\}$ and $\mathcal{B}(\{K_0\}) = \{K_0\}.$ We also exclude the class of all graphs as, in this case, \mathcal{A} and \mathcal{B} do not generate new classes.

Given a $k \in \mathbb{N}$, we define $\mathcal{G}^{(k)} = \{G \mid \mathsf{bed}_{\mathcal{G}}(G) \leq k\}$. Observe that, according to the definition of $\mathsf{bed}_{\mathcal{G}}$, $\mathcal{G}^{(0)} = \mathcal{G} \cup \mathcal{B}(\mathcal{G})$ while, for k > 0, $\mathcal{G}^{(k)} = \mathcal{A}(\mathcal{G}^{(k-1)}) \cup \mathcal{B}(\mathcal{A}(\mathcal{G}^{(k-1)}))$. This, together with the fact that $\mathcal{G} \subseteq \mathcal{B}(\mathcal{G})$ implies that

$$\mathcal{G}^{(k)} = \overbrace{\mathcal{B}(\mathcal{A}(\cdots \mathcal{B}(\mathcal{A}(\mathcal{B}(\mathcal{G})))\cdots))}^{k \text{ times}}.$$
 (1)

Observe also that for every non-trivial and hereditary class \mathcal{G} , $\mathcal{B}(\mathcal{G}) = \mathcal{B}(\mathcal{B}(\mathcal{G}))$. This implies that bed_{\mathcal{G}} and bed_{$\mathcal{B}(\mathcal{G})$} are the same parameter.

An alternative definition. A rooted forest is a pair (F,R) where F is an acyclic graph and $R \subseteq V(F)$ such that each connected component of F contains exactly one vertex of R, its root. A vertex $t \in V(F)$ is a leaf of F if either $t \in R$ and $\deg_F(t) = 0$ or $t \notin R$ and $\deg_F(t) = 1$. We use L(F,R) in order to denote the leaves of (F,R). Given $t,t' \in V(F)$ we say that $t \leq_{F,R} t'$ if there is a path from t' to some root in R that contains t. If neither $t \leq_{F,R} t'$ nor $t' \leq_{F,R} t$ then we say that t and t' are incomparable in (F,R). A (F,R)-antichain is a non-empty set C of pairwise incomparable vertices of F. An (F,R)-antichain is non-trivial if it contains at least two elements.

Given a vertex $t \in V(F)$, we define its descendants in (F,R) as the set $d_{F,R}(t) = \{t' \in V(F) \mid t \leq_{F,R} t'\}$. The children of a vertex $q \in V(F)$ in (F,R) are the descendants of q in (F,R) that are adjacent to q in F. The depth of a rooted forest (F,R) is the maximum number of vertices in a path between a leaf and the root of the connected component of F where this leaf belongs.

Let \mathcal{G} be a non-trivial hereditary class and let G be a graph. Let (F, R, τ) be a triple consisting of a rooted forest F whose root set is R and a function $\tau: V(G) \to 2^{V(F)}$. Given a vertex set $S \subseteq V(F)$, we set $\tau^{-1}(S) = \{v \in V(G) \mid \tau(v) \cap S \neq \emptyset\}$. Also, for every $t \in V(F)$, we define $G_t = G[\tau^{-1}(\mathsf{d}_{F,R}(t))]$.

We say that a triple (F, R, τ) is a \mathcal{G} -block tree layout of G if the following hold:

- (1) for every $v \in V(G)$, $\tau(v)$ is an (F, R)-antichain,
- (2) for every $t \in V(T)$, G_t is a block-graph,
- (3) if $t \notin L(F, R)$, then $|\tau^{-1}(\{t\})| = 1$ and $G_t \notin \mathcal{G}$ or,

- (4) if $t \in L(F, R)$, then $G_t \in \mathcal{G}$ and
- (5) for every non-trivial (F, R)-antichain C, the graph $\bigcup \{G_t \mid t \in C\}$ is not biconnected.

The depth of the \mathcal{G} -block tree layout (F, R, τ) is equal to the depth of the rooted forest (F, R).

Lemma 1 (*). Let \mathcal{G} be a non-trivial hereditary class and let G be a graph. Then the minimum depth of a \mathcal{G} -block tree layout of G is equal to $\operatorname{bed}_{\mathcal{G}}(G) - 1$.

Proof. Assume that (F, R, τ) is a \mathcal{G} -block tree of depth $k+1 \geq 1$. We use induction on k. Notice first that if k=0, then V(F)=L(F,R)=R. From (2) and (5), $bc(G)=\{G_r \mid r \in R\}$. From (4), for every $r \in R$, $G_r \in \mathcal{G}$, therefore $G \in \mathcal{B}(\mathcal{G})=\mathcal{G}^{(0)}$.

Suppose now that $k \geq 1$ and consider some $r \in R$. If $r \in L(F,R)$, then, because of (4), $G_r \in \mathcal{G} \subseteq \mathcal{G}^{(k-1)} \subseteq \mathcal{A}(\mathcal{G}^{(k-1)})$. Suppose now that $r \notin L(F,R)$. Then, from (3), $|\tau^{-1}(\{r\})| = 1$ and we define v_r so that $\tau^{-1}(\{r\}) = \{v_r\}$. We also set $G_r^- = G_r \setminus v_r$. Let $F_r = F[\mathsf{d}_{F,R}(r)] \setminus r$, $R_r = N_F(r)$, and $\tau_r = \{(v,\tau(v) \cap V(F_r)) \mid v \in V(G_r^-)\}$ and observe that (F_r,R_r,τ_r) is a \mathcal{G} -block tree layout of G_r^- of depth k-1. By the induction hypothesis $G_r^- \in \mathcal{G}^{(k-1)}$, therefore $G_r \in \mathcal{A}(G^{(k-1)})$. Recall now that R is an (F,R)-antichain, therefore from (2) and (5), we have that $\mathsf{bc}(G) = \{G_r \mid r \in R\}$. This together with the fact that for all $r \in R$, $G_r^- \in \mathcal{G}^{(k-1)}$ imply that $G \in \mathcal{B}(\mathcal{A}(\mathcal{G}^{(k-1)}))$, therefore, $G \in \mathcal{G}^{(k)}$.

Suppose now that $G \in \mathcal{G}^{(k)}$ for some $k \geq 0$. Again we use induction on k. In case k = 0, observe that $G \in \mathcal{B}(G)$, therefore every block of G belongs to \mathcal{G} . We consider a rooted forest (F, R) consisting of isolated vertices, one, say R_B , for each block B of G. We also set up a function $\tau: V(G) \to 2^{V(F)}$ such that, for each vertex v of G, $\tau(v) = \{R_B \mid v \in V(B)\}$. Observe that (F, R, τ) is a \mathcal{G} -block tree layout of \mathcal{G} of depth 1.

Suppose now that $k \geq 1$ and let $B \in bc(G)$. As $G \in \mathcal{G}^{(k)}$, it follows that $B \in \mathcal{A}(\mathcal{G}^{(k-1)})$, therefore B contains a vertex a_B such that $B^- = B \setminus a_B \in \mathcal{G}^{(k-1)}$. From the induction hypothesis, B^- has a \mathcal{G} -block tree layout $(F_{B^-}, R_{B^-}, \tau_{B^-})$ of depth k. We use $(F_{B^-}, R_{B^-}, \tau_{B^-})$ for all $B \in bc(G)$ in order to construct a \mathcal{G} -block tree layout (F, R, τ) of G as follows. F is constructed by first taking the disjoint union of all forests in $\{F_{B^-} \mid B \in bc(G)\}$ then adding one new root vertex r_B for each $B \in bc(G)$ and, finally, making r_B adjacent with all the vertices of R_{B^-} . We also set $R = \{r_B \mid B \in bc(G)\}$. For the construction of τ , if $v \in \{B^- \mid B \in bc(G)\}$, then $\tau(v) = \bigcup \{\tau_{B^-}(v) \mid B \in bc(G)\}$ and if $v \in \{a_B \mid B \in bc(G)\}$, then $\tau(v) = \{R_{B^-} \mid v \in B\}$. The result follows, as (F, R, τ) has depth k+1.

3 NP-completeness

We consider the following family of problems, each defined by some non-trivial and hereditary graph class \mathcal{G} . We say that a class \mathcal{G} is *polynomially decidable* if there exists an algorithm that, given an n-vertex graph G, decides whether $G \in \mathcal{G}$ in polynomial, on n, time.

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BLOCK ELIMINATION DISTANCE TO \mathcal{G} (\mathcal{G}-BED)

Instance: A graph G and a non-negative integer k.

Question: Is the block elimination distance of G to \mathcal{G} at most k?
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Lemma 2 (*). For every polynomially decidable, non-trivial, and hereditary graph class \mathcal{G} , the problem $\mathcal{G}\text{-BED}$ is NP-complete.

Proof. Given a graph G and a non-negative integer k and using Lemma 1, we certify that $\mathbf{bed}_{\mathcal{G}}(G) \leq k$ by a \mathcal{G} -block tree layout (F, R, τ) of G of depth at most k+1. This, together with the fact that \mathcal{G} is polynomially decidable, implies that \mathcal{G} -BED belongs to NP.

We next prove that $\mathcal{G}\text{-BED}$ is NP-hard. Our first step is to prove that $\mathcal{E}\text{-BED}$ is NP-hard. Notice that, in this case, conditions (2) and (4) of the definition of a $\mathcal{E}\text{-block}$ tree layout imply that if $t \in L(F, R)$ then $G_t = K_1$. This, in turn, implies that $\{\tau(v) \mid v \in V(G)\}$ is a partition of V(F).

We present a reduction to \mathcal{E} -BED from the following NP-hard problem:

BALANCED COMPLETE BIPARTITE SUBGRAPH (BCBS)

Instance: A bipartite graph G with partition V_1, V_2 and a positive integer k. Question: Are there $W_i \subseteq V_i, i \in [2]$, such that $G[W_1 \cup W_2]$ is a complete

bipartite graph and $|W_1| = |W_2| = k$?

Let G be a bipartite graph with partition V_1, V_2 . Let n = |V(G)|, $\xi = 2n - 4k$, and $k' = 2n + \xi - 2k$. Also keep in mind that $2\xi + 2k + 1 = k' + 1$. For each vertex $v \in V(G)$, we consider a new vertex v' and we denote by V' this set of n new vertices (i.e., $V' = \{v' \mid v \in V(G)\}$). We consider the graph

$$G^{\bullet} = (V(G) \cup V', E(G) \cup \bigcup_{\{u,v\} \in E(G)} (\{u,v'\} \cup \{u',v\} \cup \{u',v'\})).$$

Then, we consider the graph G^* obtained by $\overline{G^{\bullet}}$ after adding a set \hat{V} of $\xi+1$ new vertices and make them adjacent with all the vertices in $V(G^{\bullet})$. We set $n^* = |V(G^*)|$ and we observe that $n^* = 2n + \xi + 1$. Also, for each $i \in [2]$, we set $V'_i = \{v' \in V' \mid v \in V_i\}$ and $V_i^* = V_i \cup V'_i$. In what follows, we prove that (G, k) is a yes-instance of BCBS iff (G^*, k') is a yes-instance of \mathcal{E} -BED. We begin by proving that if (G, k) is a yes-instance of BCBS, then (G^*, k') is a yes-instance of \mathcal{E} -BED.

Suppose that (G, k) is a yes-instance of BCBS. Therefore, there exist $W_i \subseteq V_i, i \in [2]$ such that $G[W_1 \cup W_2]$ is a complete bipartite graph and $|W_i| = k, i \in [2]$. For each $i \in [2]$, we set $W_i' = \{v' \in V' \mid v \in W_i\}$ and $W_i^* = W_i \cup W_i'$ and we observe that the graph $G^{\bullet}[W_1^* \cup W_2^*]$ is a complete bipartite graph whose parts are W_1^* and W_2^* , each of size 2k. We now aim to define a triple (F, R, τ) that certifies that $\mathbf{bed}_{\mathcal{E}}(G^*) \leq k'$. To define F, let P be an (r, q)-path of $2\xi + 1$ vertices and P_1 (resp. P_2) be an (a_1, ℓ_1) -path (resp. (a_2, ℓ_2) -path) of 2k vertices such that P, P_1 , and P_2 are pairwise vertex-disjoint. We set F to be the graph obtained from $P \cup P_1 \cup P_2$ by adding the edges qa_1 and qa_2 and observe that F is a tree of depth $2\xi + 2k + 1 = k' + 1$. We now consider the triple (F, R, τ) , where $R = \{r\}$ and τ is a function mapping each vertex of $\hat{V} \cup (V_1^* \setminus W_1^*) \cup (V_2^* \setminus W_2^*)$ to a unique vertex of P and each vertex of P and each vertex of P and each vertex of P and therefore, since P and epith P and P and therefore, since P and epith P and P and the definition of P block tree layout, where P and therefore, since P has depth P and the definition of P block tree layout, where P and P and therefore, since P has depth P and the definition of P block tree layout, where P and therefore, since P has depth P because P because P because P and P and P because P because

What remains now is to prove that if $\mathbf{bed}_{\mathcal{E}}(G^*) \leq k'$, then (G, k) is a yes-instance of BCBS. Towards this, we argue that the following holds.

Claim: There are sets $B_i \subseteq V_i^*$ such that $|B_i| \ge 2k-1, i \in [2]$, and there is no edge between vertices of B_1 and B_2 in G^* .

Proof of Claim: Assume that the \mathcal{E} -block tree layout (T, R, τ) certifies that $\mathbf{bed}_{\mathcal{E}}(G^*) \leq k'$. Observe that, since G^* is connected, T is connected and R is a singleton. Let $r \in V(T)$ such that $R = \{r\}$.

Keep in mind that T has depth at most k'+1. Let P be the (r,q)-path in T where only q has degree more than two in T. Let $C = \tau^{-1}(V(P)) \cap (V_1^* \cup V_2^*)$ and $A_i = V_i^* \setminus C$, $i \in [2]$. Notice that $|A_1| + |A_2| = n^* - \xi - |C| - 1$, which implies that

$$|A_1| + |A_2| = 2n - |C|. (2)$$

We set H to be the graph $G^* \setminus \tau^{-1}(V(P))$ and keep in mind that $V(H) = A_1 \cup A_2 \cup (\hat{V} \setminus \tau^{-1}(V(P)))$ and $H[A_i], i \in [2]$ is a complete graph.

The fact that q has at least two children in (T, r) implies that H contains a cut-vertex. Moreover, there exist $H_1, H_2 \in \mathsf{bc}(H)$ such that for each $i \in [2]$, H_i contains the complete graph $H[A_i]$ as a subgraph. For each $i \in [2]$, let T_i be the subtree of T induced by the vertices of $\tau(V(H_i))$ and q_i be the depth of T_i . Since H_i contains the complete graph $H[A_i]$ as a subgraph, we have that $|A_i| \leq q_i$. Moreover, the fact that T has depth at most k' + 1 implies that $q_i \leq k' + 1 - |V(P)|, i \in [2]$. Therefore, for each $i \in [2]$,

$$|A_i| \le k' + 1 - |V(P)|. \tag{3}$$

Also, the fact that H contains a cut-vertex implies that there is at most one vertex of \hat{V} in V(H). Thus, $|\tau^{-1}(V(P)) \cap \hat{V}| \geq \xi$. We now distinguish two cases, depending whether $\hat{V} \setminus \tau^{-1}(V(P)) \neq \emptyset$, or not.

Case 1: $\hat{V} \setminus \tau^{-1}(V(P)) \neq \emptyset$. In this case, we have that $|V(P)| = |C| + \xi$ and therefore, by (3), $|A_i| \leq 2n - |C| - 2k + 1, i \in [2]$. This, together with (2), implies that $|A_i| \geq 2k - 1, i \in [2]$. Let w be the (unique) vertex in $\hat{V} \setminus \tau^{-1}(V(P))$ and observe that, since w is adjacent to every vertex in $A_1 \cup A_2$, w is a cut-vertex of H. This, in turn, implies that there is no edge in G^* between vertices of A_1 and A_2 . Thus, in this case, the claim holds for $B_i = A_i, i \in [2]$.

Case 2: $\hat{V} \setminus \tau^{-1}(V(P)) = \emptyset$. Notice that the fact that $\hat{V} \setminus \tau^{-1}(V(P)) = \emptyset$ implies that $|V(P)| = |C| + \xi + 1$. Therefore, by (3), $|A_i| \leq 2n - |C| - 2k, i \in [2]$. This together with (2) imply that $|A_i| \geq 2k, i \in [2]$. Let z be a cut-vertex of H and suppose that $z \in A_1$. The fact that z is a cut-vertex of H implies that $A_1 \setminus z$ and A_2 are two subsets of V_1^* and V_2^* respectively such that there is no edge, in G^* , between the vertices of $A_1 \setminus z$ and A_2 . Thus, since $|A_1 \setminus \{z\}| \geq 2k - 1$ and $|A_2| \geq 2k$, in this case, the claim holds for $B_1 = A_1 \setminus \{z\}$ and $B_2 = A_2$.

Following the Claim, there are sets $B_i \subseteq V_i^*$ such that $|B_i| \ge 2k-1, i \in [2]$ and there is no edge between the vertices of B_1 and B_2 in G^* . For every $i \in [2]$, since $|B_i| \ge 2k-1$, there is a set Q_i of at least k vertices such that $Q_i \subseteq V(G)$ or $Q_i \subseteq V'$. In the former case, we set $W_i = Q_i$, while, in the latter case, we set $W_i = \{v \in V(G) \mid v' \in Q_i\}$. Therefore, $W_i, i \in [2]$, is a subset of V(G) of size at least k. Since $Q_i \subseteq B_i, i \in [2]$, the fact that there is no edge between the vertices of B_1 and B_2 in G^* implies that there is no edge edge between the vertices in Q_1 and Q_2 . This, in turn, implies that there is no edge in G^* between W_1 and W_2 , since otherwise, an edge $uv \in E(G^*)$ between W_1 and W_2 would imply the existence of the edges uv', u'v, and u'v' in G^* , and at least one of them should be between vertices of Q_1 and Q_2 , a contradiction. Thus, since there is no edge in G^* between W_1 and W_2 , W_i , $i \in [2]$ induces a complete graph in Q^* , and $G^* = \overline{G^{\bullet}}$, it holds that $G[W_1 \cup W_2]$ is a complete bipartite graph. Hence, (W_1, W_2) certifies that (G, k) is a yes-instance of BCBS.

We just proved that \mathcal{E} -BED is NP-hard. Our next step is to reduce \mathcal{E} -BED to \mathcal{G} -BED for every non-trivial hereditary class \mathcal{G} . For this consider an instance (G, k) of \mathcal{E} -BED and a graph Z as in

Lemma 3. We construct the graph G^* by considering |E(G)| copies of Z and identify each edge of G with some edge of one of these copies. Notice that if there is a \mathcal{G} -block tree layout (F, R, τ) of G^* of depth at most k+1, then there is also one where all vertices of Z' that have not been identified with vertices of G are mapped via τ to subsets of L(F,R). This implies that (G,k) is a yes-instance of \mathcal{E} -BED iff (G^*,k) is a yes-instance of \mathcal{G} -BED, as required.

Notice that the proof of the above theorem is a (multi) reduction from the problem Balanced Complete Bipartite Subgraph (BCBS). It is based on the alternative definition of block elimination distance (Lemma 1) and has two parts. The first proves the NP-hardness of \mathcal{E} -BED. The second is a multi-reduction from \mathcal{E} -BED to \mathcal{G} -BED where the existence of the main gadget is based on the following lemma.

Lemma 3 (*). Let \mathcal{G} be a non-trivial hereditary class. Then there exists a graph Z with the following properties: (1) Z is a block graph, (2) $Z \notin \mathcal{B}(\mathcal{G})$ and, (3) $\forall v \in V(Z), Z \setminus v \in \mathcal{B}(\mathcal{G})$.

Proof. Notice that every graph can be seen as an induced subgraph of a block-graph (just add two new universal vertices). This, along with the hereditarity and the non-triviality of \mathcal{G} implies that there exists a block graph H that does not belong to \mathcal{G} and, thus, neither belongs to $\mathcal{B}(\mathcal{G})$. Among all induced subgraphs of H that are block graphs and not belonging to $\mathcal{B}(\mathcal{G})$, let Z be one with minimum number of vertices. Clearly, Z satisfies the two first properties. Assume towards a contradiction that there is some $v \in V(Z)$ such that $Z \setminus v$ is not biconnected and, moreover, $Z \setminus v \notin \mathcal{B}(\mathcal{G})$. It follows that at least one, say B, of the blocks of $Z \setminus v$ are not in \mathcal{G} , and thus also not in $\mathcal{B}(\mathcal{G})$. Notice that B is a proper induced subgraph of Z (and thus of H as well) that is a block graph and does not belong to $\mathcal{B}(\mathcal{G})$, a contradiction to the minimality of the choice of Z. \square

We stress that the proof of the above lemma is not constructive in the sense that it does not give any way to construct Z. However, if the non-trivial and hereditary class \mathcal{G} is decidable, then Z is effectively computable and this makes the proof of Lemma 2 constructive.

4 Elimination distance to minor-free graph classes

Minors and obstructions. The result of the contraction of an edge e = xy in a graph G is the graph obtained from G after contracting e, that is the graph obtained from $G \setminus \{x,y\}$ after introducing a new vertex v_{xy} and edges between v_{xy} and $N_G(\{x,y\}) \setminus \{x,y\}$. It is denoted by G/e. If H can be obtained from some subgraph of G after contracting edges, we say that H is a minor of G and we denote it by $H \leq G$. Given a set G of graphs, we denote by G/e the class of all graphs excluding every graph in G as a minor and by G/e the class of all minor-minimal graphs that do not belong to G/e. Clearly, for every class G/e excl(obs(G/e)). Also, according to Roberson and Seymour theorem, for every minor-closed class G/e, obs(G/e) is finite. We call a class essential if it is a finite minor-antichain that is non-empty and does not contain the graph G/e0 or the graph G/e1. Notice that G/e2 is trivial iff obs(G/e2) is essential. We call an essential class G/e2 biconnected if all graphs in obs(G/e2) are block-graphs. Given that G/e2 is an essential graph class, we define G/e3.

It is easy to verify that the property of being non-trivial and minor-closed is invariant under both operations \mathcal{A} and \mathcal{B} . The most simple example of a non-trivial minor-closed class is $\mathcal{E}' = \{K_0, K_1\}$ where $\mathsf{obs}(\mathcal{E}') = \{K_1 + K_1\}$. Another simple example is the class of edgeless graphs \mathcal{E} , where $\mathsf{obs}(\mathcal{E}) = \{K_2\}$. Notice that $\mathcal{B}(\mathcal{E}') = \mathcal{E} \neq \mathcal{E}'$ while $\mathcal{B}(\mathcal{E}) = \mathcal{E}$. In this example $\mathcal{B}(\mathcal{E}') \neq \mathcal{E}'$. The

following easy observation clarifies which classes are invariants under the operation \mathcal{B} and follows from the fact that for every non-block graph G, all graphs in bc(G) are proper minors of G.

Observation 4. For every non-trivial minor-closed class \mathcal{G} , $\mathcal{B}(\mathcal{G}) = \mathcal{G}$ iff $\mathsf{obs}(\mathcal{G})$ is biconnected.

Lemma 5 (*). For every non-trivial minor-closed class \mathcal{G} and every $k \in \mathbb{N}$, if $Z \in \mathsf{obs}(\mathcal{G}^{(k)})$, then (1) Z is biconnected and (2) every vertex of degree 2 in Z has adjacent neighbors.

Proof. (1) follows directly from Observation 4, Equation 1, and the fact that $\mathcal{B}(\mathcal{G}) = \mathcal{B}(\mathcal{B}(\mathcal{G}))$. For (2), we consider a biconnected graph G with an edge e = xy and the graph G^+ obtained if we remove e from G and add a new vertex v adjacent to x and y.

We claim that if G has a \mathcal{G} -block tree layout of depth k, then the same holds for G^+ as well. As G is biconnected, we may assume that $(T,\{r\},\tau)$ is a \mathcal{G} -block tree layout where T is a tree rooted on r. We use the notation $G_t := G[\tau^{-1}(\mathsf{d}_{T,\{r\}}(t))]$, $t \in V(T)$. Let $t \in V(T)$ such that $G_t := G[\tau^{-1}(\mathsf{d}_{T,\{r\}}(t))]$ contains the edge e = xy and e is not contained in $G_{t'}$ for some $t' \in \mathsf{d}_{T,\{r\}}(t) \setminus \{t\}$ (in case t is not a leaf of T). Vertex t is unique due to condition (2) of \mathcal{G} -block tree layout and because of the fact that an edge cannot belong to two blocks of a graph. We update the \mathcal{G} -block tree layout $(T,\{r\},\tau)$ by distinguishing three cases. If t is a leaf of T and G_t is biconnected, then we define $\tau' = \tau \cup \{(v,t)\}$ and T' = T. If t is a leaf of T and G_t is not biconnected, then $G_t = (\{x,y\},\{xy\})$ and, in this case we define T' by adding a new vertex t' in T and we set $\tau' = \tau \setminus \{(t,\{x,y\})\} \cup \{(t,\{x,v\}),(t',\{x,v\})\}$. In case t is not a leaf of T, then one of the endpoints, say x, of e should be mapped, via τ , to t. Then we define T' by adding a new vertex t' in T adjacent to t and we set $\tau' = \tau \cup \{(t',\{y,v\})\}$. In any of the above cases $(T',\{r\},\tau')$ is a \mathcal{G} -block tree layout of G^+ of depth k. This completes the proof of claim.

Suppose now that there is an obstruction Z of $\mathcal{G}^{(k)}$ that contains some vertex v with two non-adjacent neighbors x, y. As Z is an obstruction, is should be biconnected (by (1)), therefore, from the above claim and Lemma 1, it follows that the graph Z' obtained by G after contracting the edge vx also belongs to $\mathcal{G}^{(k)}$, a contradiction to the fact that Z is an obstruction.

The next lemma is a direct corollary of Lemma 9. This lemma specifies the structure of the obstructions of the block closure of every non-trivial minor-closed class and the proof is postponed to Section 5.

Lemma 6. For every essential class \mathcal{Z} , it holds that $s(\mathsf{obs}(\mathcal{B}(\mathsf{excl}(\mathcal{Z})))) \leq 2s - 1$, where s is the maximum number of vertices of a graph in \mathcal{Z} .

An interesting algorithmic consequence of Lemma 6 is the following. The proof is tedious as it recycles standard techniques.

Lemma 7 (*). There is an explicit function $f: \mathbb{N} \to \mathbb{N}$ and an algorithm that, given a finite class \mathbb{Z} , where $s = s(\mathbb{Z})$, a n-vertex graph G, and an integer k, outputs whether $\mathsf{bed}_{\mathsf{excl}(\mathbb{Z})}(G) \leq k$ in $O(f(s,k) \cdot n^2)$ time. Moreover, if \mathbb{Z} contains some planar graph, then the dependence of the running time on n is linear.

Proof. Let $s = s(\mathcal{Z})$, $\mathcal{G} = \text{excl}(\mathcal{Z})$, and $\mathcal{Z}^{(k)} = \text{obs}(\mathcal{G}^{(k)})$, for $k \in \mathbb{N}$. According to the resent result in [21] there is an explicit function $f_1 : \mathbb{N} \to \mathbb{N}$ such that $s(\text{obs}(\mathcal{A}(\mathcal{G}))) \leq f_1(k,s)$. This, together with Lemma 6 and Equation 1, means that there is an explicit function $f_2 : \mathbb{N}^2 \to \mathbb{N}$ such that $s(\text{obs}(\mathcal{G}^{(k)})) \leq f_2(k,s)$. The function f_2 along with the fact that the problem $\Pi_{\mathcal{G}} = \{(G,k) \mid G \in \mathcal{G}^{(k)}\}$

 $\mathcal{G}^{(k)}$ } is decidable (actually, as observed in Lemma 2, it is in NP), implies that the class $\mathcal{Z}^{(k)}$ can be constructed by an algorithm whose running time is some explicit function, say $f_3: \mathbb{N}^2 \to \mathbb{N}$, of k and s. Recall now that $G \in \mathcal{G}^{(k)}$ iff $\forall Z \in \mathcal{Z}^{(k)}, Z \nleq G$. Also because of the algorithmic results in [16,19], deciding whether a z-vertex graph Z is a minor of a n-vertex graph G can be done in $O(f_4(z) \cdot n^2)$ time where $f_4: \mathbb{N} \to \mathbb{N}$ is some explicit function (here f_4 is enormous, however, it is indeed explicit — see [17,19]). This means that, after the construction of $\mathcal{Z}^{(k)}$ one may check whether $G \in \mathcal{G}^{(k)}$ in $O(f_3(k,s) + f_4(f_2(k,s)) \cdot n^2)$ time.

Suppose now that \mathcal{Z} contains a planar graph. This, according to [7], implies that $\operatorname{tw}(\mathcal{G}) = s^{O(1)}$; we use $\operatorname{tw}(\mathcal{G})$ for the maximum treewidth of a graph in \mathcal{G} (here such a bound will always exist). It is also easy to see that the treewidth of a non-empty graph is equal to the maximum treewidth of its blocks. This implies that $\operatorname{tw}(\mathcal{B}(\mathcal{G})) = \operatorname{tw}(\mathcal{G})$. Also, the addition of a vertex does not increase the treewidth of a graph by more than one. This implies that $\operatorname{tw}(\mathcal{A}(\mathcal{G})) \leq \operatorname{tw}(\mathcal{G}) + 1$. Given these two observations, and Equation 1, we obtain that $\operatorname{tw}(\mathcal{G}^{(k)}) = s^{O(1)} + k$. As deciding whether $\operatorname{tw}(G) \leq q$ can be done in $O(f_5(q) \cdot n)$ steps for some (explicit) function $f_5 : \mathbb{N} \to \mathbb{N}$ we may assume that $\operatorname{tw}(G) = s^{O(1)} + k$. Recall that, according to Courcelle's theorem, if \mathcal{Q} is a class for which there is a formula φ in monadic second order logic where $G \in \mathcal{Q}$ iff $G \models \varphi$ then there is an explicit function $f_6 : \mathbb{N}^2 \to \mathbb{N}$ and an algorithm that, given a graph G, can check whether $G \in \mathcal{G}$ in $O(f_6(|\varphi|,\operatorname{tw}(G)) \cdot n)$ time. Therefore, the second statement of the lemma follows if we give a formula φ_k such that $G \in \mathcal{G}^{(k)}$ iff $G \models \varphi_k$. This follows from the known fact that for every graph Z there is a formula φ_Z such that $Z \leq G$ iff $G \models \varphi_Z$, therefore, $G \in \mathcal{G}^{(k)}$ iff $\forall Z \in \mathcal{Z}^{(k)}$, $\neg (G \models \varphi_Z)$. \square

The next lemma permits us to assume that, in the definition of $\mathsf{bed}_{\mathcal{G}}$, the class \mathcal{G} can be chosen so that $\mathsf{obs}(\mathcal{G})$ is biconnected and, moreover, such a \mathcal{G} has an explicit obstruction characterization.

Lemma 8 (*). For every essential class \mathcal{Z} there is a biconnected essential class, in particular the class $\mathcal{Z}' = \mathsf{obs}(\mathcal{B}(\mathsf{excl}(\mathcal{Z})))$, such that $\mathsf{bed}_{\mathsf{excl}(\mathcal{Z})}$ and $\mathsf{bed}_{\mathsf{excl}(\mathcal{Z}')}$ are the same parameter and, moreover, there is an explicit function f_7 such that $\mathsf{s}(\mathcal{Z}') \leq f_7(\mathsf{s}(\mathcal{Z}))$.

Proof. Let $\mathcal{G} = \text{excl}(\mathcal{Z})$. From Observation 4 and the fact that $\mathcal{B}(\mathcal{G}) = \mathcal{B}(\mathcal{B}(\mathcal{G}))$, $\text{obs}(\mathcal{B}(\mathcal{G}))$ is biconnected. The same fact, together with (1), imply that the parameter $\text{bed}_{\mathcal{G}}$ is the same as $\text{bed}_{\mathcal{B}(\mathcal{G})}$. The bound holds because of Lemma 6.

5 Structure of the obstructions for the biconnected closure

Minors. We start with an alternative definition of the minor relation. Let G and H be graphs and let $\rho: V(G) \to V(H)$ be a surjective mapping such that:

- 1. for every vertex $v \in V(H)$, its codomain $\rho^{-1}(v)$ induces a connected graph $G[\rho^{-1}(v)]$,
- 2. for every edge $\{u,v\} \in E(H)$, the graph $G[\rho^{-1}(u) \cup \rho^{-1}(v)]$ is connected, and
- 3. for every edge $\{u,v\} \in E(G)$, either $\rho(u) = \rho(v)$ or $\{\rho(u),\rho(v)\} \in E(H)$.

We say that H is a contraction of G (via ρ) and for a vertex $v \in V(H)$ we call the codomain $\rho^{-1}(v)$ the model of v in G. A graph H is a minor of G if there exists a subgraph M of G and a surjective function $\rho: V(M) \to V(H)$ such that H is a contraction of M, via ρ .

In this section we prove our next result, which can be seen as the biconnected analog of [6, Lemma 5] where the structure of $obs(\mathcal{C}(excl(\mathcal{Z})))$ is studied. The connected closure operation in [6]

allows for a shorter less complicated proof, since also the structure of graphs in $obs(\mathcal{C}(excl(\mathcal{Z})))$ is simpler. However, in our results, where the deal with the biconnected closure, richer structural properties are revealed, resulting also in a more technical proof.

Lemma 9 (*). Let \mathcal{Z} be a finite graph class. For every graph $G \in \mathsf{obs}(\mathcal{B}(\mathsf{excl}(\mathcal{Z})))$ there is a graph $H \in \mathcal{Z}$ such that G can be transformed to H after a sequence of at most $|\mathsf{bc}(H)| - 1$ edge deletions and $|\mathsf{bc}(H)| - 1$ edge contractions.

Proof. Let $G \in \mathsf{obs}(\mathcal{B}(\mathsf{excl}(\mathcal{Z})))$. We assume that $|V(G)| \geq 4$, since otherwise the lemma holds trivially. Since $G \in \mathsf{obs}(\mathcal{B}(\mathsf{excl}(\mathcal{Z})))$, G is biconnected and also, the fact that $G \notin \mathcal{B}(\mathsf{excl}(\mathcal{Z}))$ implies that there exists a graph $H \in \mathcal{Z}$ that is a minor of G. Moreover, since G is a minor-minimal biconnected graph with the latter property, it holds that

no proper minor of
$$G$$
 is biconnected and contains H as a minor. (\star)

Let M be a (vertex-minimal and, subject to this, edge-minimal) subgraph of G such that there exists a surjective function $\rho: V(M) \to V(H)$ such that H is a contraction of M via ρ . As H is a minor of G, we know that a pair (M, ρ) as above exists. We begin with the following claim.

Claim 1: G can be transformed to M after a sequence of at most |bc(H)| - 1 edge removals.

Proof of Claim 1: We will prove that V(M) = V(G) and $|E(G) \setminus E(M)| \le |\operatorname{bc}(M)| - 1$. This, together with the fact that $|\operatorname{bc}(M)| \le |\operatorname{bc}(H)|$, will imply Claim 1. To prove that V(M) = V(G) observe that the existence of a vertex $v \in V(G) \setminus V(M)$ implies that an edge $e \in E(G)$ incident to v can be either contracted or removed from G while maintaining biconnectivity and the fact that it contains H as a minor, a contradiction to (\star) . We now set $E := E(G) \setminus E(M)$ and we prove that $|E| \le |\operatorname{bc}(M)| - 1$ by induction on the number of blocks of M. First, notice that (\star) implies that every edge in E is between vertices of different blocks of M. This proves the base case where $|\operatorname{bc}(M)| = 1$. Suppose that $|\operatorname{bc}(M)| \ge 2$ and let B be a block of M that contains at most one cut-vertex. By induction hypothesis, the edges in $\tilde{E} := E \cap E(\bigcup(\operatorname{bc}(G) \setminus \{B\}))$ are at most $|\operatorname{bc}(M)| - 2$ and by (\star) , there is at most one edge between the vertices of B and $\bigcup(\operatorname{bc}(G) \setminus \{B\})$. Therefore, there is at most one edge in $E \setminus \tilde{E}$, which implies that $E \le |\operatorname{bc}(M)| - 1$. Hence, Claim 1 follows.

We now prove the following. This, combined with Claim 1, completes the proof of the lemma.

Claim 2: M can be transformed to H after a sequence of at most |bc(H)| - 1 edge contractions.

Proof of Claim 2: For every $v \in V(H)$, we set $X_v = \rho^{-1}(v)$. We will prove that $\sum_{v \in V(H)} |E(G[X_v])| \leq |\mathsf{bc}(H)| - 1$, which implies the above Claim. We start with a series of observations.

Observation 1: For every vertex $v \in V(H)$, the graph $G[X_v]$ is a tree. Indeed, notice that edgeminimality of M implies that $M[X_v]$ is a tree and (\star) implies that $E(G[X_v]) \subseteq E(M[X_v])$.

Observation 2: For every vertex $v \in V(H)$ and for every edge $xy \in E(G[X_v])$, $G \setminus \{x,y\}$ is disconnected. Indeed, if there was an edge $e = xy \in E(G[X_v])$ such that $G \setminus \{x,y\}$ is connected, then G/e would be biconnected, a contradiction to (\star) .

We now prove that for every vertex $v \in V(H)$ that is not a cut-vertex of H, it holds that $|X_v| = 1$. Suppose towards a contradiction that $|X_v| \ge 2$. By Observation 1, $G[X_v]$ is a tree and

therefore, since $|X_v| \geq 2$, there exists an edge $e = xy \in E(G[X_v])$. The fact that $H \setminus v$ is connected implies that $M \setminus X_v$ and, thus, $G \setminus X_v$ are also connected. Moreover, due to (\star) , every leaf of $G[X_v]$ is adjacent to a vertex of $G \setminus X_v$, which implies that $G \setminus \{x,y\}$ is connected, a contradiction to Observation 2.

Next, we argue that the following holds.

Subclaim: For every cut-vertex v of H it holds that $|E(G[X_v])| \leq |\operatorname{cc}(G \setminus X_v)| - 1$.

Proof of Subclaim: Let v be a cut-vertex of H and let $\mathcal{Q} = \{Q_1, \ldots, Q_w\}$ be the set $\operatorname{cc}(G \setminus X_v)$. By Observation 1, $G[X_v]$ is a tree. For simplicity, we denote by T the graph $G[X_v]$. For every $i \in [w]$, we set T_i to be the maximum size subtree of T whose leaves are vertices of $N_G(Q_i)$. We say that an edge $e = \{x, y\} \in E(T)$ is small if there is an $i \in [w]$ such that $V(T_i) = \{x, y\}$. Also, given a tree T, the internal edges of T are the ones that are not adjacent to one of its leaves. We observe that

- 1. for every $e_1, e_2 \in E(T)$, where $|e_1 \cap e_2| = 1$, there is an $i \in [w]$ such that $e_1, e_2 \in E(T_i)$,
- 2. for every edge $e \in E(T)$, there are $i, j \in [w]$, where $i \neq j$, such that $e \in E(T_i) \cap E(T_j)$, and
- 3. every edge of T that is either incident to a leaf of T or an internal edge of some T_i , is small.

The fact that G is biconnected implies (1) and (2). To see why (3) holds, let e = xy be an edge of T such that either one of x, y is a leaf of T or e is an internal edge of some T_i , $i \in [w]$ and suppose, towards a contradiction, that e is not small, or, equivalently, for every $j \in [w]$, $|V(T_j)| \geq 3$. Then, for every vertex w in $V(G) \setminus X_v$ there is a path connecting w with a vertex of $T \setminus \{x, y\}$. If e is an internal edge of some T_i , every pair of vertices in $T \setminus \{x, y\}$ is connected by a path in $G \setminus \{x, y\}$, while if e is incident to a leaf x of T, we distinguish two cases: if y has degree two then $T \setminus \{x, y\}$ is connected, while if y has degree at least three, then, by (1), for every pair e_1, e_2 of edges of T incident to y, there is an $i \in [w]$ such that $e_1, e_2 \in E(T_i)$ and therefore every two vertices in $T \setminus \{x, y\}$ are connected by a path in $G \setminus \{x, y\}$. Therefore, in all cases, it holds that $G \setminus \{x, y\}$ is connected, a contradiction to Observation 2.

We assume that there is a non-leaf vertex $r \in V(T)$, since otherwise, Subclaim is directly derived from (2). We consider the rooted tree (T,r). For every $x \in V(T)$, we consider the subtree $T_x = T[\mathsf{d}_{T,r}(x)]$ of T and we set $\mathsf{tc}(x) = |\{i \in [w] \mid T_i \subseteq T_x \text{ and } x \text{ is a leaf of } T_i\}|$. Observe that $|E(T)| = |E(T_r)|$ and $\mathsf{tc}(r) \le w - 1$, since, by (1), there is an $i \in [w]$ such that r is an internal vertex of T_i . To conclude the proof of the Subclaim, we prove, by induction on the depth of T, that for every $x \in V(T)$, $|E(T_x)| \le \mathsf{tc}(x)$. Due to (3), for every vertex $x \in V(T)$ that is incident to a leaf of T, $|E(T_x)| \le \mathsf{tc}(x)$. Let T_x be a minimum subtree of T whose number of edges is more than $\mathsf{tc}(x)$ and let $\{y_1, \ldots, y_m\}, m \ge 1$ be the children of x in (T,r). Since T_x is minimal, for every $i \in [m]$, $|E(T_{y_i})| \le \mathsf{tc}(y_i)$. Let $i \in [m]$ such that $y_i x$ is not small. Due to (1), there is a $j_i \in [w]$ such that y_i is an internal vertex of T_{j_i} and, due to (3), $y_i x$ is not an internal edge of T_{j_i} , i.e., $T_{j_i} \subseteq T_x$ and x is a leaf of T_{j_i} . Thus, for every $i \in [m]$, either $y_i x$ is small, or there is a $j_i \in [w]$ such that $T_{j_i} \subseteq T_x$ and x is a leaf of T_{j_i} . Moreover, for every $i, i' \in [m]$, if $i \ne i'$, then $j_i \ne j_{i'}$. This implies that $\mathsf{tc}(x) - \sum_{i \in [m]} \mathsf{tc}(y_i) \ge m$. Thus, $|E(T_x)| = m + \sum_{i \in [m]} |E(T_{y_i})| \le m + \sum_{i \in [m]} \mathsf{tc}(y_i) \le \mathsf{tc}(x)$, a contradiction to our initial assumption that $|E(T_x)| > \mathsf{tc}(x)$. Subclaim follows.

To conclude the proof of Claim 2, for every cut-vertex v of H, we set $\mathsf{blocks}(H,v)$ to be the blocks of H that contain v. Observe that $|\mathsf{cc}(G \setminus X_v)| \leq |\mathsf{blocks}(H,v)|$. We set $\mathsf{cv}(H)$ to be the set of cut-vertices of H and we notice that $\sum_{v \in \mathsf{cv}(H)} |E(G[X_v])| \leq \sum_{v \in \mathsf{cv}(H)} (|\mathsf{cc}(G \setminus X_v)| - 1) \leq$

 $\sum_{v \in \mathsf{cv}(H)} (|\mathsf{blocks}(H, v)| - 1)$. The fact that $\sum_{v \in \mathsf{cv}(H)} (|\mathsf{blocks}(H, v)| - 1) \le |\mathsf{bc}(H)| - 1$ implies that $\sum_{v \in \mathsf{cv}(H)} |E(G[X_v])| \le |\mathsf{bc}(H)| - 1$. The latter together with the fact that for every vertex $v \in V(H)$ that is not a cut-vertex of H, it holds that $|X_v| = 1$ completes the proof of Claim 2. \diamond

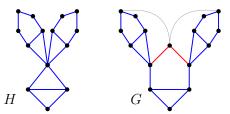


Figure 1: Example of a graph H (on the left) and a graph $G \in \mathsf{obs}(\mathcal{B}(\mathsf{excl}(H)))$ (on the right) such that G can be transformed to H after exactly $|\mathsf{bc}(H)| - 1$ edge deletions and $|\mathsf{bc}(H)| - 1$ edge contractions.

We stress that the bounds on the number of operations in Lemma 9 are tight in the sense that, given a graph H, there is a graph $G \in \mathsf{obs}(\mathcal{B}(\mathsf{excl}(\{H\})))$ such that G can be transformed to H after exactly $|\mathsf{bc}(H)| - 1$ edge deletions and $|\mathsf{bc}(H)| - 1$ edge contractions. For example, in Figure 1, the graph H on the left has three blocks (i.e., $|\mathsf{bc}(H)| = 3$), the graph G on the right is a graph in $\mathsf{obs}(\mathcal{B}(\mathsf{excl}(\{H\})))$, and to transform G to H one has to remove the two grey edges and contract the two red ones.

6 Outerplanar obstructions for block elimination distance

In this section we study the set $obs(\mathcal{G}^{(k)})$ for distinct instantiations of k and \mathcal{G} . As a warm up, we prove the following lemma.

Lemma 10
$$(\star)$$
. obs $(\mathcal{E}^{(1)}) = \{K_3\}$ and obs $(\mathcal{E}^{(2)})$ consists of the graphs \bullet .

Proof. The fact that $\operatorname{obs}(\mathcal{E}^{(1)}) = \{K_3\}$ follows because each block of an acyclic graph is a K_2 . Let us name by Z_1, Z_2 , and Z_3 the three graphs in second part of the statement from left to right. It is easy to verify, by inspection, that $\{Z_1, Z_2, Z_3\} \subseteq \operatorname{obs}(\mathcal{E}^{(2)})$. We assume, towards a contradiction, that $G \in \operatorname{obs}(\mathcal{E}^{(2)}) \setminus \{Z_1, Z_2, Z_3\}$. Since G is biconnected (Lemma 5.(1)) and $Z_2 = K_4 \nleq G$, then by Dirac's Theorem [10], there exist at least two non-adjacent vertices x and y of degree two in G. From Lemma 5.(2), each of x and y should belong to a triangle, say T_x and T_y , and T_x , T_y cannot be disjoint as, otherwise, because of its biconnectivity, G would contain Z_3 as a minor. Let w be a common neighbor of x and y. If $G \setminus w$ contains a cycle C, then C should intersect both T_x and T_y , otherwise, again by the biconnectivity, this would imply that $Z_3 \subseteq G$. But then $T_1 \cup T_2 \cup C$ contains Z_1 as a minor, a contradiction. We conclude that $G \setminus w$ is acyclic, therefore it belongs to $\mathcal{E}^{(2)}$, again a contradiction to the fact that $G \in \operatorname{obs}(\mathcal{E}^{(2)}) \setminus \{Z_1, Z_2, Z_3\}$.

Our objective is to generate obstructions of $\mathcal{G}^{(k+1)}$ using obstructions of $\mathcal{G}^{(k)}$. For this, we define the following two operations. (See also Figure 2.)

- Parallel join: Let G_1 and G_2 be graphs and let $v_1^i, v_2^i \in V(G_i)$, $i \in [2]$. We denote by $||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)$ the graph obtained from the disjoint union of G_1 and G_2 after we add the edges $\{v_i^1, v_i^2\}$, $i \in [2]$ and we call it the parallel join of G_1 and G_2 on (v_1^1, v_2^1) and (v_1^2, v_2^2) .
- Triangular gluing: Let G_1, G_2 , and G_3 be graphs and let $v_1^i, v_2^i \in V(G_i)$, $i \in [3]$. We denote by $\triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_3, v_1^3, v_2^3)$ the graph obtained from the disjoint union of G_1, G_2 , and G_3 after we identify the pairs v_2^1 and v_1^2 , v_2^2 and v_1^3 , and v_2^3 and v_1^4 . We call this graph the triangular gluing of G_1, G_2 , and G_3 on $(v_1^1, v_2^1), (v_1^2, v_2^2)$, and (v_1^3, v_2^3) .

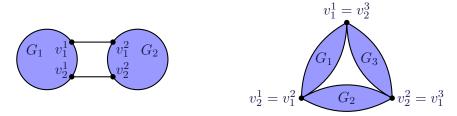


Figure 2: On the left side we see the graph resulting from the parallel join of the graphs G_1 and G_2 on (v_1^1, v_2^1) and (v_1^2, v_2^2) . On the right side we see the graph resulting from the triangular gluing of the graphs G_1 , G_2 , and G_3 on (v_1^1, v_2^1) , (v_1^2, v_2^2) , and (v_1^3, v_2^3) .

By the above constructions we can make the following observation.

Observation 11. Let G_1 , G_2 , and G_3 be graphs and $v_1^i, v_2^i \in V(G_i)$, $i \in [3]$. If G_1 , G_2 , and G_3 are biconnected then so are the graphs $||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)|$ and $\triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_3, v_1^3, v_2^3)$.

Lemma 12 (*). Let \mathcal{G} be a non-trivial and minor-closed class and $k \in \mathbb{N}$. If $\operatorname{bed}_{\mathcal{G}}(G_i) \geq k+1$, $i \in [2]$, $v_1^i, v_2^i \in V(G_i), i \in [2]$, and the graph $G = ||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)|$ is biconnected, then $\operatorname{bed}_{\mathcal{G}}(G) \geq k+2$. Moreover, under the assumption that either $\mathcal{G} \neq \mathcal{E}$ or $k \geq 1$, the following holds: if $G_1, G_2 \in \operatorname{obs}(\mathcal{G}^{(k)})$ and $v_1^i, v_2^i \in V(G_i), i \in [2]$, then $G \in \operatorname{obs}(\mathcal{G}^{(k+1)})$.

Proof of Lemma 12. Let G_1 and G_2 be two graphs such that $\operatorname{bed}_{\mathcal{G}}(G_i) \geq k+1$, $i \in [2]$, and $v_1^i, v_2^i \in V(G_i), i \in [2]$. We denote by G the graph $||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)|$. First, we prove that $\operatorname{bed}_{\mathcal{G}}(G) \geq k+2$. Indeed, assume to the contrary, that $\operatorname{bed}_{\mathcal{G}}(G) \leq k+1$. Hence, there exists a vertex $v \in V(G)$ such that $k+1 \geq 1 + \operatorname{bed}_{\mathcal{G}}(G \setminus v)$ and therefore $\operatorname{bed}_{\mathcal{G}}(G \setminus v) \leq k$. Notice that v is either a vertex of $V(G_1)$ or a vertex of $V(G_2)$. Without loss of generality, let $v \in V(G_2)$. Then $G_1 \subseteq G \setminus v$ and thus, $\operatorname{bed}_{\mathcal{G}}(G_1) \leq \operatorname{bed}_{\mathcal{G}}(G \setminus v) \leq k$. A contradiction to the hypothesis that $\operatorname{bed}_{\mathcal{G}}(G_1) \geq k+1$.

We now prove that, if $G_1, G_2 \in \operatorname{obs}(\mathcal{G}^{(k)})$ then $G \in \operatorname{obs}(\mathcal{G}^{(k+1)})$. From Lemma 5.(1) and the first part of the lemma it follows that $\operatorname{bed}_{\mathcal{G}}(G) \geq k+2$. Therefore, in order to prove that $G \in \operatorname{obs}(\mathcal{G}^{(k+1)})$ it is enough to prove that, any vertex/edge deletion or edge contraction on G decreases the parameter by 1. In particular, notice that it suffices to show that any edge deletion or edge contraction decreases the parameter by 1. Let $e \in E(G)$. Then either $e \in E(G_1)$ or $e \in E(G_2)$ or $e = \{v_i^1, v_i^2\}$ for some $i \in [2]$. Let us first consider the case where $e \in E(G_1)$ (the case where $e \in E(G_2)$ is symmetrical). We will prove that $\operatorname{bed}_{\mathcal{G}}(G \setminus e) \leq k+1$ and $\operatorname{bed}_{\mathcal{G}}(G/e) \leq k+1$. Let $G' = G \setminus e$ and let $v = v_1^2 \in V(G_2)$. Then $\operatorname{bed}_{\mathcal{G}}(G') \leq 1 + \operatorname{bed}_{\mathcal{G}}(G' \setminus v)$. Let H be a biconnected component of $G' \setminus v$. Notice that either $H \subseteq G_2 \setminus v$ or $H \subseteq G_1 \setminus e$. Since G_1 and G_2 belong to $\operatorname{obs}(\mathcal{G}^{(k)})$, $\operatorname{bed}_{\mathcal{G}}(G_1 \setminus e) \leq k$ and $\operatorname{bed}_{\mathcal{G}}(G_2 \setminus v) \leq k$. Therefore $\operatorname{bed}_{\mathcal{G}}(H) \leq k$. This implies that

 $\operatorname{bed}_{\mathcal{G}}(G' \setminus v) \leq k$ and thus $\operatorname{bed}_{\mathcal{G}}(G') \leq k+1$. Let now G' = G/e and observe that the proof above also argues that $\operatorname{bed}_{\mathcal{G}}(G') \leq k+1$, after replacing $G_1 \setminus e$ by G_1/e .

Finally, we consider the case where $e = v_1^1 v_1^2$ (the case where $e = v_2^1 v_2^2$ is symmetrical). Let $G' = G \setminus e$. Notice that G' is not biconnected and, moreover, its blocks are the graphs G_1 and G_2 , and the bridge B consisting of the edge $v_1^1 v_1^2$. Recall that $G_1, G_2 \in \mathsf{obs}(\mathcal{G}^{(k)})$ and thus $\mathsf{bed}_{\mathcal{G}}(G_i) = k+1$, $i \in [2]$. Therefore, $\mathsf{bed}_{\mathcal{G}}(G') = \max\{\mathsf{bed}_{\mathcal{G}}(G_1), \mathsf{bed}_{\mathcal{G}}(G_2), \mathsf{bed}_{\mathcal{G}}(B)\} = k+1$. Let now G' = G/e and let $v = v_2^1$. As before, notice that the graph $G' \setminus v$ is not biconnected. Moreover, if H is a block of $G' \setminus v$ then either $H = G_2$ or $H \subseteq G_1 \setminus v_2^1$. Again, we obtain that $\mathsf{bed}_{\mathcal{G}}(H) \le k+1$. This concludes the proof of the lemma.

Lemma 13 (*). Let \mathcal{G} be a non-trivial and minor-closed class and $k \in \mathbb{N}$. If $\operatorname{bed}_{\mathcal{G}}(G_i) \geq k+1$, $i \in [3], v_1^i, v_2^i \in V(G_i), i \in [3]$, and the graph $G = \triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_3, v_1^3, v_2^3)$ is biconnected, then $\operatorname{bed}_{\mathcal{G}}(G) \geq k+2$. Moreover, if $G_1, G_2, G_3 \in \operatorname{obs}(\mathcal{G}^{(k)})$ and $v_1^i, v_2^i \in V(G_i), i \in [3]$, then $G \in \operatorname{obs}(\mathcal{G}^{(k+1)})$.

Proof of Lemma 13. Let G_1 , G_2 , and G_3 be three graphs such that $\operatorname{bed}_{\mathcal{G}}(G_i) \geq k+1$, $i \in [3]$. We denote by G the graph $\triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_3, v_1^3, v_2^3)$ and prove that $\operatorname{bed}_{\mathcal{G}}(G) \geq k+2$. Indeed, assume to the contrary, that $\operatorname{bed}_{\mathcal{G}}(G) \leq k+1$. Hence, there exists a vertex $v \in V(G)$ such that $k+1 \geq 1 + \operatorname{bed}_{\mathcal{G}}(G \setminus v)$ and therefore $\operatorname{bed}_{\mathcal{G}}(G \setminus v) \leq k$. Notice that there exists $i \in [3]$ such that $v \notin V(G_i)$. Without loss of generality, let $v \notin V(G_2)$. Then $G_1 \subseteq G \setminus v$ and thus, $\operatorname{bed}_{\mathcal{G}}(G_1) \leq \operatorname{bed}_{\mathcal{G}}(G \setminus v) \leq k$. A contradiction to the hypothesis that $\operatorname{bed}_{\mathcal{G}}(G_1) \geq k+1$.

We now prove that if $G_1, G_2, G_3 \in \mathsf{obs}(\mathcal{G}^{(k)})$ then $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$. The first part of the lemma, combined with Lemma 5.(1), proves that $\mathsf{bed}_{\mathcal{G}}(G) \geq k+2$. Hence, it is enough to prove that any vertex/edge deletion or edge contraction on G decreases the parameter by 1. In particular, notice that it suffices to show that any edge deletion or edge contraction decreases the parameter by 1. Let $e \in E(G)$. Then $e \in E(G_i)$ for some $i \in [3]$. Without loss of generality, we assume that $e \in E(G_3)$. Recall that the vertices $v_2^1 \in V(G_1)$ and $v_1^2 \in V(G_2)$ have been identified in G. We denote them by v.

Let $G' = G \setminus e$. We will prove that $\operatorname{bed}_{\mathcal{G}}(G') \leq k+1$. We distinguish two cases according to whether G' is biconnected. Let us first assume that G' is not biconnected. It follows that if H is a block of G' then either $H \subseteq G_i$ for some $i \in [2]$, or $H \subseteq G_3 \setminus e \subseteq G_3$. Since $G_i \in \operatorname{obs}(\mathcal{G}^{(k)}), i \in [3]$, it holds that $\operatorname{bed}_{\mathcal{G}}(G_i) = k+1$ and hence $\operatorname{bed}_{\mathcal{G}}(H) \leq k+1$, for every block H of G'. Moreover, from the definition, $\operatorname{bed}_{\mathcal{G}}(G') = \max\{\operatorname{bed}_{\mathcal{G}}(H) \mid H \text{ is a block of } G'\}$. Thus, $\operatorname{bed}_{\mathcal{G}}(G') \leq k+1$.

Let us now assume that G' is biconnected. Then, $\operatorname{bed}_{\mathcal{G}}(G') \leq 1 + \operatorname{bed}_{\mathcal{G}}(G' \setminus v)$. Observe that $G' \setminus v$ is not biconnected. Moreover, if H is a block of $G' \setminus v$ then either $H \subseteq G_i \setminus v$, for some $i \in [2]$, or $H \subseteq G_3 \setminus e$. Observe that since $G_i \in \operatorname{obs}(\mathcal{G}^{(k)})$, $i \in [3]$ it holds that $\operatorname{bed}_{\mathcal{G}}(G_i \setminus v) \leq k$, $i \in [2]$, and $\operatorname{bed}_{\mathcal{G}}(G_3 \setminus e) \leq k$. Thus, $\operatorname{bed}_{\mathcal{G}}(H) \leq k$, for any block H of $G' \setminus v$. Therefore, $\operatorname{bed}_{\mathcal{G}}(G') \leq 1 + \operatorname{bed}_{\mathcal{G}}(G' \setminus v) \leq 1 + \max\{\operatorname{bed}_{\mathcal{G}}(H) \mid H \text{ is a block of } G' \setminus v\} \leq 1 + k$. This concludes the proof that the removal of any edge from G decreases the parameter by 1.

To conclude, observe that the above arguments hold for the case that we consider edge contractions instead of deletions, if we replace $G' \setminus e$ by G'/e and $G_3 \setminus e$ by G_3/e .

Lemma 12 and Lemma 13 imply that the set $\bigcup_{i\geq 0} \mathsf{obs}(\mathcal{G}^{(i)})$ is closed under the parallel join and the triangular gluing operations.

The following is also a consequence of Lemma 12 and Lemma 13.

Lemma 14. Let \mathcal{G} be a non-trivial and minor-closed graph class and $k \in \mathbb{N}$. Let also G, G_1 , G_2 , and G_3 be graphs and $v_1^i, v_2^i \in V(G_i)$, $i \in [3]$. If $G = \triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_3, v_1^3, v_2^3)$ (or $G = ||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)|$) and $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$ then $G_i \in \mathsf{obs}(\mathcal{G}^{(k)})$ for all $i \in [3]$ (or $i \in [2]$).

We denote by \mathcal{O} the class of all outerplanar graphs. We claim that $\mathcal{O} \cap \bigcup_{i \geq 1} \mathsf{obs}(\mathcal{G}^{(i)})$ is complete under these two operations. In particular we prove the following:

Lemma 15 (*). Let \mathcal{G} be a non-trivial and minor-closed class. For every $k \in \mathbb{N}_{\geq 1}$ and for every graph $G \in \mathsf{obs}(\mathcal{G}^{(k+1)}) \cap \mathcal{O}$, there are

- either two graphs G_1 and G_2 of $obs(\mathcal{G}^{(k)}) \cap \mathcal{O}$ and $v_1^i, v_2^i \in V(G_i), i \in [2]$, such that $G = ||(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2)||$ or
- three graphs G_1, G_2 and G_3 of $obs(\mathcal{G}^{(k)}) \cap \mathcal{O}$ and $v_1^i, v_2^i \in V(G_i), i \in [3]$, such that $G = \triangle(G_1, v_1^1, v_2^1, G_2, v_1^2, v_2^2, G_2, v_1^3, v_2^3)$.

Before we begin the proof of Lemma 15 we need a series of definitions.

Let A be a subset of the plane \mathbb{R}^2 . We define $\operatorname{int}(A)$ to be the interior of A, $\operatorname{cl}(A)$ its closure and $\operatorname{bd}(A) = \operatorname{cl}(A) \setminus \operatorname{int}(A)$ its border. Given a plane graph Γ (that is a graph embedded in \mathbb{R}^2), we denote its faces by $F(\Gamma)$, that is, $F(\Gamma)$ is the set of the connected components of $\mathbb{R}^2 \setminus \Gamma$ (in the operation $\mathbb{R}^2 \setminus \Gamma$ we treat Γ as the set of points of \mathbb{R}^2 corresponding to its vertices and its edges). Observe that $\mathbb{R}^2 \setminus \Gamma$ contains exactly one unbounded face, which we call outer face and denote it by f_o . All other faces are called inner faces. For every $f \in F(\Gamma)$ we denote by $B_{\Gamma}(f)$ the graph induced by the vertices and edges of Γ whose embeddings are subsets of $\operatorname{bd}(f)$ and we call it the boundary of f.

Let Γ be a fixed outerplanar embedding of an outerplanar graph G. Thus, all vertices of G belong to $B_{\Gamma}(f_o)$. Let Γ^* be the graph obtained from Γ in the following way. Its vertex set is the set

$$V(\Gamma^*) = \{ v_f \mid f \in F(\Gamma) \setminus f_o \} \cup \{ v_e \mid e \in E(B_{\Gamma}(f_o)) \}.$$

That is, Γ^* contains a vertex for every inner face of Γ and a vertex for every edge of Γ that belongs to the graph induced by the boundary of its outer face. Moreover, its edge set is

$$E(\Gamma^*) = \{ v_{f_1} v_{f_2} \mid f_1 \neq f_2 \text{ and } E(B_{\Gamma}(f_1)) \cap E(B_{\Gamma}(f_2)) \neq \emptyset \} \cup \{ v_f v_e \mid e \in E(B_{\Gamma}(f)) \},$$

that is, two vertices are connected by an edge if one of the two following holds: Either both vertices correspond to distinct inner faces whose boundary graphs share an edge or one of the vertices corresponds to an inner face that shares an edge with the outer face and the other vertex corresponds to that edge. We call an edge of Γ^* that contains a vertex v_e , for some $e \in E(\Gamma)$ (and in particular $e \in B_{\Gamma}(f_o)$), marginal. Otherwise, we call it internal. Finally, we call Γ^* the weak dual of Γ . The parameter bed_G on embedded graphs Γ is defined as the parameter bed_G on the underlying combinatorial graph G.

The following observation is folklore and we skip its proof.

Observation 16. If Γ is an outerplanar embedding of a graph then Γ^* is a tree. Moreover, all of its leaves belong to marginal edges and each marginal edge contains a leaf of T.

Let $e = v_{f_1}v_{f_2}$ be an internal edge of Γ^* . Let e_{f_1,f_2} denote the edge in $E(B_{\Gamma}(f_1)) \cap E(B_{\Gamma}(f_2))$. By construction, $e_{f_1,f_2} \notin E(B_{\Gamma}(f_o))$. This implies that the endpoints of e_{f_1,f_2} form a separator of Γ . Let $\Gamma'_{e,f_1}, \Gamma'_{e,f_2}$ be the connected components of $\Gamma \setminus e_{f_1,f_2}$ such that $\Gamma'_{e,f_1} \cap B_{\Gamma}(f_i) \neq \emptyset$ (here, we interpret e_{f_1,f_2} as the vertex set containing the endpoints of the edge e_{f_1,f_2}). We denote by Γ_{e,f_i} the embedded graph induced by $V(\Gamma'_{f_i}) \cup e_{f_1,f_2}$ (where, again, we interpret e_{f_1,f_2} as the vertex set containing the endpoints of the edge e_{f_1,f_2}).

We now proceed with the proof of Lemma 15.

Proof of Lemma 15. Let G be an outerplanar graph such that $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$. Since $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$, from Lemma 5.(1), G is biconnected and thus has a unique outerplanar embedding on the plane. We denote its unique embedding by Γ . Let Γ^* be the weak dual of Γ . From Observation 16, Γ^* is a tree. We orient the edges of Γ^* in the following way. The marginal edges are oriented away from their incident leaf. Let $e = v_{f_1}v_{f_2}$ be an internal edge of Γ^* . If $\mathsf{bed}_{\mathcal{G}}(\Gamma_{f_1}) > \mathsf{bed}_{\mathcal{G}}(\Gamma_{f_2})$, we orient the edge towards v_{f_1} . Symmetrically, if $\mathsf{bed}_{\mathcal{G}}(\Gamma_{f_2}) > \mathsf{bed}_{\mathcal{G}}(\Gamma_{f_1})$, we orient the edge towards v_{f_2} . We call these edges unidirectional. Otherwise, we orient the edge in both directions and call it bidirectional.

We will use the oriented tree to prove that G can be decomposed in one of the two ways stated in the lemma. Towards this, we prove the following claims.

Claim 1: For every internal edge $e = v_{f_1}v_{f_2}$, it holds that $\mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_i}) \leq k+1$, $i \in [2]$. Moreover, if e is bidirectional then $\mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_1}) = \mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_2}) = k+1$ and if e is unidirectional oriented from v_{f_1} to v_{f_2} then $\mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_1}) \leq k$.

Proof of Claim 1: Indeed, both statements follow from the facts that Γ_{f_i} is a proper subgraph of G and $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$. The first statement is straightforward. For the second statement, let us assume first that $\mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_1}) = \mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_2}) \leq k$. Let also uv be the common edge of the graphs Γ_{e,f_1} and Γ_{e,f_2} . Observe then that if H is a block of the graph $G \setminus u$ then H is a subgraph of one of the two graphs $\Gamma_{e,f_i} \setminus u$, $i \in [2]$. This implies that $\mathsf{bed}_{\mathcal{G}}(H) \leq \mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_i} \setminus u) \leq \mathsf{bed}_{\mathcal{G}}(\Gamma_{e,f_i}) \leq k$, for some $i \in [2]$. Hence, by definition, we get that $\mathsf{bed}_{\mathcal{G}}(G) \leq k+1$, a contradiction to the hypothesis that $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$.

Claim 2: There does not exists a vertex of Γ^* incident to two distinct edges, such that both of them are oriented away from it and at least one of them is unidirectional.

Proof of Claim 2: Indeed, let us assume that such a vertex exists and let e_1 and e_2 be two edges oriented away from it and without loss of generality let e_1 be the edge that is unidirectional. Notice that the assumed vertex is an internal vertex of the tree Γ^* . We will denote it by v_f . Moreover, by definition of the orientations, the two distinct endpoints of e_1 and e_2 are also internal vertices of the tree. We denote them by v_{f_1} and v_{f_2} , respectively. Notice that Γ_{e_2,f_2} is a subgraph of $\Gamma_{e_1,f}$ and that Γ_{e_1,f_1} is a subgraph of $\Gamma_{e_2,f}$. Therefore, $\operatorname{bed}_{\mathcal{G}}(\Gamma_{e_2,f_2}) \leq \operatorname{bed}_{\mathcal{G}}(\Gamma_{e_1,f})$ and $\operatorname{bed}_{\mathcal{G}}(\Gamma_{e_1,f_1}) \leq \operatorname{bed}_{\mathcal{G}}(\Gamma_{e_2,f})$. Moreover, $\operatorname{bed}_{\mathcal{G}}(\Gamma_{e_1,f_1})$, since e_1 is uniquely oriented towards f_1 . This implies that $\operatorname{bed}_{\mathcal{G}}(\Gamma_{e_2,f_2}) < \operatorname{bed}_{\mathcal{G}}(\Gamma_{e_2,f})$, a contradiction to the assumption that e_2 is oriented towards f_2 . This completes the proof of the claim.

Claim 3: There exists a bidirectional edge in Γ^* (by construction, this edge is internal).

Proof of Claim 3: Assume, towards a contradiction, that all edges of Γ^* have a unique direction. Then Claim 2 implies that there exists a unique vertex in Γ^* that is a sink, that is, all edges are oriented towards it. It follows that this vertex is internal. Let us denote it by v_f . Let us denote by e_i denote the internal edges incident to v_f and v_{f_i} denote their other endpoints, $i \in [x]$, where by x we denote the number of internal edges incident to v_f . Finally, let $u \in B_{\Gamma^*}(f)$, and notice that if H is a block of $\Gamma^* \setminus u$ then $H \subseteq \Gamma_{e_i,f_i} \setminus u \subseteq \Gamma_{e_i,f_i}$ for some $i \in [x]$. From Claim 1, we obtain

that $\mathsf{bed}_{\mathcal{G}}(H) \leq \mathsf{bed}_{\mathcal{G}}(\Gamma_{e_i,f_i}) \leq k$, for some $i \in [x]$. From the definition of $\mathsf{bed}_{\mathcal{G}}$ we obtain that $\mathsf{bed}_{\mathcal{G}}(\Gamma) \leq k+1$, a contradiction to the hypothesis that $G \in \mathsf{obs}(\mathcal{G}^{(k+1)})$.

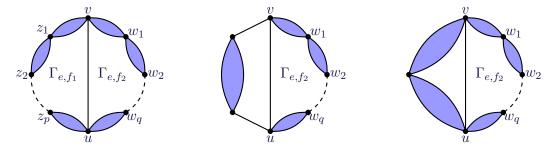


Figure 3: In the left figure, the edge $e' = \{u, v\}$, the subgraphs Γ_{e, f_1} and Γ_{e, f_2} and the cut-vertices are depicted. In the central figure we see the form of the obstruction in Claims 5 and 6. In the right figure we see the form of the obstruction in Claim 7.

We consider an internal bidirectional edge, say $e = \{v_{f_1}, v_{f_2}\}$. Let $e' = \{u, v\}$ be the edge in $E(B_{\Gamma}(f_1)) \cap E(B_{\Gamma}(f_2))$. Observe that e' belongs to the outer face of the graph Γ_{e,f_i} and hence, $\Gamma_{e,f_i} \setminus e'$ is not, $i \in [2]$. Recall that Γ_{e,f_1} is outerplanar and let $z_1, z_2, \ldots, z_p, p \geq 1$, denote the cut-vertices of $\Gamma_{e,f_1} \setminus e'$ according to the order they appear on the outer face of $\Gamma_{e,f_1} \setminus e'$ when traversing it from v to u. Let also Γ_i^1 , $i \in [p+1]$, denote the blocks that contain the vertices z_{i-1} and z_i , where $z_0 = v$ and $z_{p+1} = u$. Similarly, let also $w_1, w_2, w_q, q \geq 1$ denote the cut-vertices of $\Gamma_{e,f_2} \setminus e'$ according to the order they appear on the outer face of $\Gamma_{e,f_2} \setminus \{u,v\}$ when traversing it from v to u. Let also Γ_i^2 , $i \in [q+1]$, denote the blocks that contain the vertices w_{i-1} and w_i , where $w_0 = v$ and $w_{p+1} = u$. The blocks Γ_i^1 , Γ_j^2 , $i \in [p+1]$, $j \in [q+1]$ that do not contain v or u are called free. (See Figure 3)

Claim 4: It holds that $\mathsf{bed}_{\mathcal{G}}(H) = k+1$ for some $H \in \{\Gamma^1_i, \Gamma^2_j \mid i \in [p+1], j \in [q+1]\}.$

Proof of Claim 4: Towards a contradiction assume that $\operatorname{bed}_{\mathcal{G}}(H) \leq k$ for every $H \in \{\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]\}$. Notice that every block B of $\Gamma \setminus u$ is a subgraph of some block $\Gamma_i^1, i \in [p+1]$, or $\Gamma_j^2, j \in [q+1]$, and therefore, $\operatorname{bed}_{\mathcal{G}}(B) \leq k$. Then, from the definition of $\operatorname{bed}_{\mathcal{G}}, \operatorname{bed}_{\mathcal{G}}(\Gamma) \leq k+1$, a contradiction to the hypothesis that $\Gamma \in \operatorname{obs}(\mathcal{G}^{(k+1)})$.

Claim 5: If there exists a free block $H \in \{\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]\}$ such that $\mathsf{bed}_{\mathcal{G}}(H) = k+1$ then the Lemma holds.

Proof of Claim 5: Indeed without loss of generality let $H = \Gamma^1_{i_0}$ for some $i_0 \in [p+1]$. Let us consider the graph obtained by contracting all vertices of Γ_{e,f_1} except for $V(\Gamma^1_{i_0})$ and $\{u,v\}$. Observe then that the resulting graph Γ' can be expressed as the parallel join of $\Gamma^1_{i_0}$ and $\mathrm{bed}_{\mathcal{G}}(\Gamma_{e,f_2})$ in the following way: $\Gamma' = ||(\Gamma^1_{i_0}, z_{i_0-1}, z_{i_0}, \Gamma_{e,f_2}, v, u)|$. From Claim 1, since e is bidirectional, we obtain that $\mathrm{bed}_{\mathcal{G}}(\Gamma_{e,f_2}) = k+1$. Moreover, since $\mathrm{bed}_{\mathcal{G}}(\Gamma^1_{i_0}) = k+1$, from Lemma 12, we obtain that $\mathrm{bed}_{\mathcal{G}}(\Gamma') = k+2$. As $\Gamma \in \mathbf{obs}(\mathcal{G}^{(k+1)})$ and Γ' is a minor of Γ , it follows that $\Gamma' = \Gamma$. From Lemma 14, $\Gamma^1_{i_0}$, $\Gamma_{e,f_2} \in \mathbf{obs}(\mathcal{G}^{(k)})$ and this indeed proves the statement of the Lemma. \diamond

Therefore, from now on we will assume that if $H \in \{\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]\}$ and $\mathsf{bed}_{\mathcal{G}}(H) = k+1$ then H is not free, that is, H contains u or v.

Claim 6: If all blocks $H \in {\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]}$ for which $\mathsf{bed}_{\mathcal{G}}(H) = k+1$ contain v,

then the Lemma holds. Symmetrically, if all blocks $H \in \{\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]\}$ for which $bed_{\mathcal{G}}(H) = k+1$ contain u, then the Lemma holds.

Proof of Claim 6: Observe that the only blocks that contain v are Γ_1^1 and Γ_1^2 . Moreover, for any other block B of $\Gamma \setminus u$, it holds that $\operatorname{bed}_{\mathcal{G}}(B) \leq k$. Since $\Gamma \in \operatorname{obs}(\mathcal{G}^{(k+1)})$, it follows that $\operatorname{bed}_{\mathcal{G}}(\Gamma \setminus u) = k+1$. From the above discussion and the definition of $\operatorname{bed}_{\mathcal{G}}$, we obtain that there exists a block D of $\Gamma \setminus u$ for which $\operatorname{bed}_{\mathcal{G}}(D) = k+1$ and $D \subseteq \Gamma_1^1 \setminus v$ or $D \subseteq \Gamma_1^2 \setminus v$. Without loss of generality let us assume that $D \subseteq \Gamma_1^1 \setminus v$. (The case where $D \subseteq \Gamma_1^2 \setminus v$ is symmetrical). Let v_1 denote the neighbor of v in $\Gamma_{e_{f_1}}$ that is also a neighbor of v in the graph $B_{\Gamma}(f_o)$. Observe also that $u \notin V(D)$. Let Γ' be the graph obtained after we contract all blocks of Γ_{e,f_1} except for the block Γ_1^1 to the edge z_1u and remove all edges that contain v in $E(\Gamma_1^1)$ apart from the edge v_1v . Then Γ' can be expressed as the parallel join of the graphs $\Gamma_1^1 \setminus v$ and Γ_{e,f_2} in the following way: $\Gamma' = ||(\Gamma_1^1, v_1, z_1, \Gamma_{e,f_2}, v, u)|$. From Lemma 12, we obtain that $\operatorname{bed}_{\mathcal{G}}(\Gamma') = k+2$. As Γ' is a minor of Γ and $\Gamma \in \operatorname{obs}(\mathcal{G}^{(k+1)})$, it follows that $\Gamma' = \Gamma$. Moreover, from Lemma 14, $\Gamma_1^1 \setminus v$ and Γ_{e,f_2} belong to $\operatorname{obs}(\mathcal{G}^{(k)})$. Then indeed the Lemma holds and this concludes the proof of the claim.

Claim 7: If there exist two blocks $H, H' \in \{\Gamma_i^1, \Gamma_j^2 \mid i \in [p+1], j \in [q+1]\}$ such that H contains v, H' contains u, and $\mathsf{bed}_{\mathcal{G}}(H) = \mathsf{bed}_{\mathcal{G}}(H') = k+1$ then the Lemma holds.

Proof of Claim 7: We first examine the case where $H = \Gamma_1^1$ and $H' = \Gamma_{p+1}^1$. (The case where $H = \Gamma_1^2$ and $H' = \Gamma_{q+1}^2$ is symmetrical.) Let Γ' be the graph obtained from Γ after contracting the vertices of all blocks $\Gamma_2^1, \ldots, \Gamma_p^1$ into a new vertex y. Observe that Γ' can be expressed as triangular gluing of Γ_1^1 , Γ_{p+1}^1 , and Γ_{e,f_2} in the following way: $\Gamma' = \triangle(\Gamma_1^1, v, y, \Gamma_{p+1}^1, y, u, \Gamma_{e,f_2}, u, v)$. From Claim 1, we obtain that $\operatorname{bed}_{\mathcal{G}}(\Gamma_{e,f_2}) = k+1$. Hence, from Lemma 13, it follows that $\operatorname{bed}_{\mathcal{G}}(\Gamma') \geq k+2$. As $\Gamma \in \operatorname{obs}(\mathcal{G}^{(k+1)})$ and Γ' is a minor of Γ , it follows that $\Gamma' = \Gamma$. From Lemma 14, we obtain that the graphs Γ_1^1 , Γ_{p+1}^1 , and Γ_{e,f_2} belong to $\operatorname{obs}(\mathcal{G}^{(k)})$. In this case we have proven the assertion of the Lemma.

We now examine the case where $H = \Gamma_1^1$ and $H' = \Gamma_{q+1}^2$. (The case where $H = \Gamma_1^2$ and $H' = \Gamma_{p+1}^1$ is symmetrical.) Let Γ' be the graph obtained from Γ after contracting the edges of all blocks $\Gamma_2^1, \ldots, \Gamma_{p+1}^1$ into the single edge z_1u and the edges of all blocks $\Gamma_1^2, \ldots, \Gamma_q^1$ except w_qv and finally removing the edge e' = uv. Observe that Γ' can be expressed as the parallel join of Γ_1^1 and Γ_{q+1}^2 in the following way: $\Gamma' = ||(\Gamma_1^1, v, z_1, \Gamma_{q+1}^2, w_q, u)|$. Observe that Γ' is a proper minor of Γ and from Lemma 12, $\operatorname{bed}_{\mathcal{G}}(\Gamma') \geq k+2$. This is a contradiction to the hypothesis that $\Gamma \in \operatorname{obs}(\mathcal{G}^{(k+1)})$. This concludes the proof of the claim.

The above claims complete the proof of the Lemma.

Lemma 12, Lemma 13, and Lemma 15 the following.

Theorem 17. For every non-trivial minor-closed class \mathcal{G} and every $k \in \mathbb{N}$, every outerplanar graph in $\mathsf{obs}(\mathcal{G}^{(k+1)})$ can be generated by applying either the parallel join or the triangular gluing operation to outerplanar graphs of $\mathsf{obs}(\mathcal{G}^{(k)})$ in a way that preserves outerplanarity.

As $\operatorname{obs}(\mathcal{G}^{(0)}) = \operatorname{obs}(\mathcal{B}(\mathcal{G}))$, Lemma 9 and Theorem 17 give a complete characterization of $\mathcal{O} \cap \mathcal{G}^{(k)}$, for every $k \in \mathbb{N}$ and every non-trivial minor-closed graph class \mathcal{G} . It is easy to verify that for every \mathcal{G} , there are at least two obstructions in $\operatorname{obs}(\mathcal{G}^{(3)})$ that are generated by the triangular gluing operation. Moreover, as the operation of trianglular gluing three graphs from a set of q graphs results to $q^2 + \binom{q}{3} \geq q^2$ new graphs, our results imply that, for $k \geq 3$, $|\operatorname{obs}(\mathcal{G}^{(k)})| \geq |\operatorname{obs}(\mathcal{G}^{(k-1)})|^2$. It follows that, for every non-trivial minor-closed class \mathcal{G} , $\operatorname{obs}(\mathcal{G}^{(k)})$ contains doubly exponentially many graphs.

7 A conjecture on the universal obstructions

Recently, Huynh et al. in [15] defined the parameter td₂ as follows. A biconnected centered coloring of a graph G is a vertex coloring of G such that for every connected subgraph H of G that is a block graph, some color is assigned to exactly one vertex of H. Given a non-empty graph G, $\mathsf{td}_2(G)$ is defined as the minimum number of colors in a biconnected centered coloring of G. Using the alternative definition of Section 2, it can easily be verified that, for every non-empty graph G, $\mathsf{td}_2(G) = \mathsf{bed}_{\mathcal{E}}(G) + 1$. We define the t-ladder as the $(2 \times t)$ -grid (i.e., the Cartesian product of K_2 and a path on t-vertices) and we denote it by L_t . It is easy to check that $td_2(L_t) = \Omega(\log(t))$. One of the main results of [15] was that there is a function $f: \mathbb{N} \to \mathbb{N}$ such that every graph excluding a t-ladder belongs to $\mathcal{E}^{(f(t))}$. This implies that the t-ladder L_t is a universal minor obstruction for $bed_{\mathcal{E}}$. This motivates us to make a conjecture on how the results of [15] should be extended for every non-trivial minor-closed class \mathcal{G} : Given a positive t, we define $\mathcal{L}_{\mathcal{G},t}$ as the class containing every graph that can be constructed by first taking the disjoint union of two paths P_i , $i \in [2]$, with vertices v_1^i, \ldots, v_t^i (ordered the way they appear in P_i) and t graphs G_1, \ldots, G_t from $\mathbf{obs}(\mathcal{B}(\mathcal{G}))$ and then, for $i \in [t]$, identify v_i^1 and v_i^2 with two different vertices in G_i . It is easy to check that if $G \in \mathcal{L}_{\mathcal{G},t}$, then $\mathsf{bed}_{\mathcal{G}}(G) = \Omega(\log t)$. We conjecture that $\mathcal{L}_{\mathcal{G},t}$ is a universal minor obstruction for $\mathsf{bed}_{\mathcal{G}}$, i.e., there is a function $f:\mathbb{N}\to\mathbb{N}$ such that every graph excluding all graphs in $\mathcal{L}_{\mathcal{G},t}$ as a minor, has block elimination distance to \mathcal{G} bounded by f(t), i.e., $excl(\mathcal{L}_{\mathcal{G},t}) \subseteq \mathcal{G}^{(f(t))}$. Notice that the two operations of Theorem 17 imply that, when restricted to outerplanar graphs, this conjecture is correct for f(t) = O(t). However we do not believe that the linear upper bound is maintained in the general case.

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