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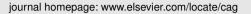
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The Effects of VR in Training Simulators: Exploring Perception and Knowledge Gain

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ABSTRACT

Although immersive virtual environments have been used for years for training and learning purposes (e.g., flight and surgery simulators), the effects of using VR devices on simulation sessions are yet to be understood. In this work, we explore the effects of different VR devices on virtual environments developed for training, focusing on perception and knowledge gain aspects. We performed two user studies to investigate the influence of these devices on users' workload, motion sickness, and performance in the domain of work safety training. The first experiment includes 61 participants and seeks to understand whether and how VR displays providing different fields of view affects the users' ability to search for risks in an office-like virtual environment (i.e. focus on user perception). Subsequently, we conducted a second experiment involving 46 subjects, where we assess whether and how interaction techniques providing different degreesof-freedom influence users' ability to learn procedural tasks (i.e. focus on knowledge gain). From our results, we learned that users' knowledge on the simulation's topic (i.e. work safety) and gaming experience play an important role in VR simulations, and that cybersickness symptoms such as disorientation are likely caused by unawareness of one's surroundings instead of VR content.

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1. Introduction

The low-cost and danger-free aspects of virtual reality (VR) technology enable the design of immersive simulations with game aspects (i.e. gameplay, challenge, interaction, and objective) for training people in diverse application domains. There are numerous successful examples on the literature on how immersive VR can improve user performance and game effectiveness. Chitarro et al. [1] proposed an immersive simulator for educating passengers on aviation safety through experiencing a serious aircraft emergency situation using a Head-Mounted Display (HMD). In fire service, Backlund et al. [2] present a simulator to train firefighter's skills using a Cave Automatic Virtual Environment (CAVE) based system and allowing free 13 interaction through motion tracking. In health-care, Pedraza-14 Hueso et al. [3] propose a simulator that allows the user to carry 15 out physical and cognitive rehabilitation therapies using a nat-16 ural user interface based on motion tracking. Cecil et al. [4] 17 proposed a VR simulator to facilitate and supplement the train-18 ing opportunities provided to orthopedic residents. Mobach [5] 19 showed that VR simulations can incite users to actively engage 20 in architectural and organizational participatory design, while 21 improving staff satisfaction and reducing costs. Jiang et al. [6] 22 proposed an immersive serious game delivered via an HMD for 23 teaching users the sequence of operations necessary to launch 24 a lifeboat and on handling the potential risks of such a task. Furthermore, the analysis of the usage of VR technology in 26 immersive simulations presented by Menin et al. [7] showed 27 that VR enables users to save money and perform safe training, 28

while supporting knowledge gain as efficiently as conventional methods. Further, VR training simulations improve knowledge retention and increase users' engagement, which, consequently, з enable situational awareness and improve the understanding of training procedures [7]. 5

It is well-known that effective learning occurs when the body 6 senses are stimulated, particularly the visual one [8]. Nonethe-7 less, motion sickness is a common side-effect of using VR due 8 to standing still while the surrounding environment is moving, disturbing the brain's equilibrium and causing nausea. Thus, 10 in this paper, we investigate the effects of different VR display 11 devices and interaction techniques on perceptual learning and 12 knowledge retention. We performed two user-based evalua-13 tions with two realistic immersive simulations designed to teach 14 and train people on work safety. We considered aspects of user 15 experience (i.e. workload and cybersickness) and user perfor-16 mance (i.e. error rate, simulation time) to understand how VR 17 technology stimulates the body's senses and how it reacts. The 18 contributions of this work are summarized as follows: 19

• A user study involving 107 unpaid persons divided into 20 two groups to assess the effects of: three different display 21 devices (from conventional desktop displays to VR head-22 sets) on perceptual learning, and four different interaction 23 techniques (from traditional game like interaction to VR 24 techniques, such as walking-in-place) on perception and 25 knowledge retention. The studies also assessed user expe-26 rience in two immersive simulations designed for training 27 purposes; and 28

· A set of lessons learned, which can lead to research ques-29 tions and help developers on choosing the VR setup for 30 new training simulations. 31

The remainder of this paper is organized as follows. Sec-32 tion 2 presents the related work. Section 3 explains our de-33 sign rationale, and presents the description of the serious games 34 developed. Section 4 presents the protocol used for both user 35 studies, while Sections 5 and 6 present the two experiments, the 36 methodology employed, the results achieved and the hypothe-37 ses assessment. Section 7 discusses our findings, presents the 38 lessons learned from this study, and the limitations of our stud-39 ies. Finally, we conclude in Section 8. 40

2. Related Work 41

Studies preceding ours have already investigated the impacts 42 of VR technology on user experience (UX), which we present 43 hereafter. Mania et al. [9] have studied the effects of differ-44 ent levels of immersion (real-world, desktop, audio-only, and 45 head-mounted display - HMD) on sense of presence and mem-46 orization in a seminar-like presentation. Predictably, users re-47 ported the highest sense of presence and performance when 48 they were in a real-world seminar room. In terms of fidelity 49 aspects (i.e. the objective degree of exactness with which real-50 world sensory stimuli is reproduced [10]), Mania et al. [9] re-51 sults suggest that low interaction/display fidelity may improve 52 memorization due to the higher attention demand imposed to 53

the cognitive system. These findings were later contradicted by 54 Bowman et al. [11], who showed that a higher level of visual fidelity provides better performance in procedure memorization 56 tasks. They also showed that high display fidelity improves spatial knowledge and allows users to use spatial strategies on procedure memorization, leading to better target detection. More recently, Kwon [12] showed that high fidelity VR setups help 60 users to recognize a virtual experience as the actual experience, 61 while improving their ability to analyze, evaluate, and create 62 questions based on the subject learned during the simulation.

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Ragan et al. [13] showed that the use of auxiliary spatial information affects mental strategies and improves user performance in terms of cognitive processing and learning-based activities. Moreover, stereoscopic vision has been shown to improve memory recall when objects are consistent with the environmental context [14]. In another study, Roman et al. [15] showed that a three-monitor CAVE is more engaging with a 3D first-person shooter game than a single monitor.

Napieralski et al. [16] showed that users can locate themselves easier inside a VR environment when the realism of graphics is higher. Furthermore, Ragan et al. [17] showed that high visual realism improves strategy transfer, but worsen user performance in scanning tasks probably due to the extra information that exists on VR environments simulating real-world scenarios (e.g., trees, people, buildings), which can distract the user from their main task. They also demonstrated that training with higher FOVs lead to better object detection in a serious game using scanning tasks to train military personnel. Although, they did not find any correlation between the user performance on the VR environment and the real-world, their findings suggest that a higher FOV do not improve the real-world task performance more than training with a lower FOV.

Bowman and McMahan [18] also showed that using wide FOV and high resolution provides a less cluttered and more comprehensible VE. McMahan et al. [10] showed that high display and interaction fidelity affect strategy and user performance in a first-person shooter game in a way that, with high interaction fidelity users took less damage and were less accurate then with low interaction fidelity. The authors showed that users' familiarity with the technology improves user performance, which could explain the high accuracy when interacting with conventional mouse and keyboard devices. In terms of user experience (UX), the authors observed that high display/interaction fidelity increases the users' sense of presence, engagement and the simulator's assessed usability.

Krokos et al. [19] showed that using virtual memory palaces 99 (i.e. placing pieces of information within palace and medieval 100 town environments, and associating them to salient features of 101 the environment) as a spatial mnemonic to support informa-102 tion recall are more effective when delivered via HMDs than 103 desktop displays. Nabioyuni and Bowman [20] investigated the 104 effects of hyper-natural transfer and biomechanical techniques 105 for navigating inside a VR environment. Their findings suggest 106 that well-designed hyper-natural navigation techniques can be 107 understood and adapted by users, resulting in more speed per-108 formance. However, these techniques may still be more diffi-109 cult to control than real walking when performing complicated, 110

more precise movements. Further, hyper-natural biomechanical techniques do not improve locomotion performance in VR, but instead reduce accuracy and users' comfort [20].

Kakoschke et al. [21] investigated the effects of Approach-Avoidance Training (AAT) delivered via three interfaces (computer, smartphone, and VR) on user experience (flow, immer-6 sion, engagement) and performance (accuracy, approach bias). Their results showed that VR was a more effective way to deliver the training by providing higher engagement, flow, and immersion than the AAT delivered via a computer or smartphone 10 application, while reducing errors. 11

Albus et al. [22] used signals in the form of textual annota-12 tions to support learning in VR simulations. They also inves-13 tigated its effects on different learning outcomes and cognitive 14 load. Results showed that annotations in VR can help users to 15 process and recall the information, but have no effects in terms 16 of reducing distractions. Gupta et al. [23] used a VR simulator 17 for condylar plating surgery to show that VR based environ-18 ments can serve both as skills training and learning tools. 19

Di Mascio et al. [24] evaluated the acceptability, usability, 20 and engagement of two HMDs (i.e. Oculus Rift and Hololens) 21 as tools to provide VR and AR-based treatment for people with 22 Autism Spectrum Disorder (ASD). For both devices, results 23 suggest that initial training is necessary, as well as long-term 24 usage to provide users with freedom to virtually and physi-25 cally move around the environment. The study showed yet that 26 familiarity with objects in an IVE's (Immersive Virtual Envi-27 ronments) had a higher impact on emotional participation than 28 photo-realism. 29

Hasanzadeh et al. [25] investigated the feasibility and useful-30 ness of providing passive haptics in a mixed-reality (MR) envi-31 ronment to capture the risk-taking behavior of workers. Results 32 showed that MR helps to raise users' sense of presence and to 33 capture their realistic response to safety features for both re-34 search and training purposes. Additionally, the study showed 35 that extroverts workers could place themselves more readily 36 within this mental representation and experience higher levels 37 of involvement, higher degrees of presence, and stronger sense 38 of being there. 39

Recently, due to the constraints imposed by the COVID-19 40 pandemics, the use of VR for training and learning has receiv-41 ing more attention and the influence of aspects such as users' 42 visual attention and behavior are being explored. Simeone et 43 al. [26] found that the presence of a virtual instructor increases 44 the engagement and accelerate the progress of the user during 45 a learning experience. Bozkir et al. [27] focused in three differ-46 ent objects-of-interest for measuring attention: peer-learners, 47 instructor, and lecture material. More specifically, they var-48 ied sitting positions of students, visualization styles of virtual 49 avatars (realistic or cartoon-like), and hand-raising percentages 50 of peer-learners. Results showed that such manipulations play 51 an important role in students' attention. 52

These user studies illustrate the interest and benefits of using 53 VR technologies to provide the user with high fidelity setups to 54 support training procedures through low-cost and danger-free 55 alternatives. A high fidelity VR setup would be built with tech-56 nologies that provide the closest experience as one would have 57

in the real-world, which means peripheral vision and natural interaction techniques, such as through mid-air gestures and real walking. Nonetheless, we could see that, depending on the target tasks, low interaction fidelity provides better user performance than high fidelity due to the users' familiarity with devices such as game controllers and mouse devices. The study 63 reported by McMahan et al. [10] is the closest to the one we present in this paper in terms of comparing different combina-65 tions of low and high interaction/display fidelity devices, which considers for instance the joint use of CAVEs and mouse devices or display-walls and pointing devices. However, the disparity in terms of fidelity between one display and interaction devices are quite large.

In this paper, we extend the understanding of the effects of low/intermediate/high fidelity in user perception and knowledge retention. We considered different VR devices, interaction and navigation techniques on the outcomes of training simulations. Few previous studies have considered the effects of motion sickness, even though it is known to be a side-effect of VR, or the quantity of work necessary to achieve the task using high fidelity interaction tools, which are quite new to the users. Therefore, we measure motion sickness and workload and evaluate their impact on user engagement, sense of presence and immersion.

3. Design Rationale

Perception and learning are intrinsically connected: in training tasks, one cannot learn a new procedure without the ability of perceiving one's surroundings. Thus, this study focuses on investigating the effects of different VR technologies on perception and learning aspects of VR simulations. To reduce cognitive load possibly engendered by the combination of all these technologies, we separated the study in two user experiments: (i) user perception (Section 5) comparing three display devices, and (ii) knowledge gain (Section 6) comparing four combinations of semi- and non-natural interaction and locomotion techniques.

First and foremost, the purpose of a training simulation is to prepare the user for the real-world situation, which has naturally high visual complexity. Thus, the simulators where build on the basis of realistic scenarios, supporting the transfer of what has been learned during the simulation to the real-world situation. We used a simulator for risk perception assessment (Fig. 1a), which purpose is to train workers on detecting potential risk elements in a normal workplace environment [28], and a sim-101 ulator for lightning rod replacement (Fig. 1b), which intend 102 to train apprentices on basic safety procedures for electrical in-103 stallations on public utility poles.

The risk perception assessment simulator reinforces users' 105 perception through their ability to see, hear, or become aware 106 of something through the senses to apprehend their surround-107 ings, detecting and avoiding risk hazards. Thus, the simulator 108 train users through perceptual learning, which comprises the 109 ability to detect pieces of information (i.e. events, distinctive 110 features, and affordances) offered by the environment [29]. Ra-111 gan et al. [17] had previously evaluated the effects of different 112

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Fig. 1: Virtual environments used in the Experiment I - risk perception assessment (a) and Experiment II - lighting rod replacement(b).

levels of FOV (in an HMD device) on a scanning task using
 realistic scenarios, which shown no significant effect on target
 detection or assessment strategy usage. In order to extend the
 understanding of VR impact on perceptual learning, we investi gate how different display devices providing different FOVs and
 different usage settings (more or less comfortable to the user),
 could impact user experience and performance.

Further to acquire information, the user should be able to re-8 tain the information obtained through training simulations in 9 order to transfer it into the real-world situation. Recalling infor-10 mation is also known as knowledge and can be classified into 11 different categories such as factual, conceptual, procedural and 12 meta-cognitive [30]. Both simulators require the user to recog-13 nize specific details or elements (i.e. factual knowledge). In 14 this paper, we explore knowledge retention through the light-15 ing rod replacement simulator, where we investigate the effects 16 of different navigation and interaction techniques for grabbing 17 and manipulation, which are fundamental in numerous training 18 simulators (e.g., firefighting, military training, etc). In terms of 19 interaction, we use motion tracking to map knowledge retention 20 21 to the real-world by providing high fidelity experiences to the user. 22

In terms of navigation, we considered the use of motion 23 tracking, but the solutions found to track the large physical 24 spaces required for both simulations (Fig. 1) were too expen-25 sive [31]. Hyper-natural navigation techniques such as Seven 26 League Boots [32] could improve speed performance, but they 27 might be difficult to control when precision is needed [20]. 28 Thus, we focus in less natural navigation techniques such as 29 walking-in-place (WIP) and joystick navigation. Particularly, 30 the Wii balance board has been largely used by researchers to 31 provide low-cost WIP techniques, showing positive effects on 32 user performance in human-scale spaces and spatial orientation, 33 while providing high sense of presence [33]. 34

In terms of grabbing and manipulating objects, motion tracking can also enable natural interaction through mid-air gestures [34], which has shown to offer less precise control and require more physical work on the part of the user [35]. Furthermore, Mine et al. [36] showed that having a physical reference helps the user to be more precise on memory recall. Thus, we combine physical objects and body movement by using the Razer Hydra controllers, and compare it to conventional game controllers, since users are familiar with these devices.

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The first experiment focuses on perception, using a VE that requires walking around while observing and perceiving hazardous features in different rooms. In this task, the display device impacts the performance more than the interaction technique, so we compared three different display devices. The second experiment focused on investigating the effects of interaction and locomotion techniques on learning. Although it uses a different simulator, the perception skills are as important, since the user should be aware of their surroundings to judge the best way of securing the workplace. Therefore, we chose the display device that has shown the best effects on the first trial, ensuring that the display was not a bias, while showing positive effects in terms of perception.

Particularly, as shown by previous works (see Section 2), VR 57 devices providing highly immersive and natural experiences 58 can improve user performance. Therefore, we selected a set of 59 VR devices that provide proper levels of immersion (i.e. HMD 60 and display-wall) and naturalness (i.e. Razer Hydra and Wii 61 Balance Boards) while comparing them with traditional and 62 familiar devices (i.e. PC monitor and game controllers), en-63 abling us to investigate their effects the outcomes of the train-64 ing simulations. Furthermore, the selected devices are cheap 65 and therefore accessible to the companies interested on using 66 these types of simulators, thus easing their dissemination since 67 these are intended for use in large-scale training sessions within 68 companies [28]. Hereafter, we first describe the shared exper-69 iment protocol, measures, and statistical analysis process, then 70 we present both user experiments and their results. 71

4. Shared Protocol Between Experiments and Measures

Since we focus on learning, we assumed that using a withinsubjects design could influence the results by allowing users to recycle the information they learned while using a particular display/interaction technique. Thus, we used a betweensubjects design in both experiments, where participants were randomly assigned to each experimental condition.

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In both experiments, the experimental sessions were individual, accompanied by an experimenter who guided the participant through five steps of a standard protocol consisting of: 3 (1) a Term and Conditions Agreement, where the user is informed about the risks and benefits of participating in the experiment, and through which they consent their participation allowing us to anonymously use their data for research purposes; (2) a socio-demographic questionnaire, where we gather standard profiling information (e.g., age, sex, profession), data regarding their experience with the technologies used (e.g., expe-10 rience with VR, 3D games) and the subject being addressed in 11 each simulation (e.g., work safety); (3) a learning phase, where 12 users were given time to get familiar with the VR setup; (4) 13 a trial phase, where the user carry out the required tasks; and 14 (5) a post-test phase, where we apply a questionnaire gathering 15 users' self-reported engagement, cybersickness, and workload, 16 as well as information specific to each experiment. 17

Particularly, to measure the impact of the VR devices on cy-18 bersickness (i.e. visually induced motion sickness) we admin-19 istered the Simulator Sickness Questionnaire (SSQ) [37]. The 20 questionnaire allows the user to assess the severity with which 21 they experienced sixteen sickness symptoms in a 4-point scale 22 (i.e. from low to high), which allows to determine the user's 23 24 level of sickness regarding four scales: nausea (N), oculomotor (O), disorientation (D), and total severity (TS). The highest 25 scores possible are 124 for nausea, 90.9 for oculomotor, 97.4 for 26 disorientation, and 108.6 for total severity. As common prac-27 tice [38], we administrated the SSQ before and after the trial in 28 both experiments to obtain baseline and completion measure-29 ments. This way, we can ensure that the results are not biased 30 by the condition of the participant before the trial, who could 31 be stressed, anxious, or nauseous for unrelated reasons. 32

Regarding statistical analysis, we set the significance level 33 to p = 0.05 to analyze the empirical data. We submitted the 34 data to a mixed design, where the between-subjects variables 35 are the experimental conditions and the user profile, while the 36 within-subjects variables are the simulator sickness scores (ob-37 tained before and after the trial) and other measures specific to each experiment, such as the sense of presence scores (ob-39 tained per room in the VE), and the self-reported workload 40 scores (obtained before and after the trial). We performed a 41 Shapiro-Wilk Normality test of the null hypothesis that the data 42 come from a normal distribution, and a Fligner-Killeen test of 43 the null hypothesis that the variances in each group are the 44 same. If the data passes both tests (p < 0.5) we performed 45 a One-Way ANOVA test. Otherwise, the data was submit-46 ted to non-parametric tests, namely Friedman for paired and 47 Kruskal-Wallis for unpaired groups. In tests involving more 48 than two groups, with statistical significance, we ran post-hoc 49 tests: Tukey's range test [39] for One-Way ANOVA, and Ne-50 menyi test [40] for the remaining. We report statistical signifi-51 cance in the difference of means for two or more groups through 52 codes on the charts, if any, as follows: '***' 0.001, '**' 0.01, 53 '*' 0.05, and '.' 0.1. 54

5. Experiment I: User Perception

This experiment aims to understand whether different VR 56 display devices influence the user perception in a simulation de-57 signed to train workers of an electricity distribution company on 58 detecting risks elements in their work environment. This exper-59 iment requires users to leverage their perception skills to detect potential hazards in the virtual environment. Based on previous 61 studies' findings (see Section 2), we believe that the higher the 62 feeling of being "there" in the VE, the better the user can per-63 form the tasks and recall the information acquired during the 64 simulation. Particularly, a high immersive setup would enable 65 them to completely focus on the elements of the virtual world 66 without being distracted by the real-world objects surrounding 67 them. Thus, we hypothesized that (H1) display devices pro-68 ducing higher self-reported sense of presence improve the user 69 performance. Moreover, the existing immersive training simu-70 lators have shown overall positive outcomes [7], which lead us 71 to hypothesize that (H2) simulator sickness will not worsen the 72 user performance. 73

5.1. Virtual Environment

This simulation was designed for assessing the ability of workers to detect potential risk elements in a normal workplace environment. The VE contains a building with a reception room, a parking lot, an office, and a kitchen. Further to the normal objects of an office environment, the scenario has 53 objects defined as potential hazards which can be simple or composite. The former refers to imminent risk items (e.g., wet floor, blocked fire extinguisher), while the latter refers to objects which hazard is triggered by an external situation (e.g., flashing lamp, alarm off). These require higher cognitive effort from the user to be detected.

5.2. Experimental Conditions

We compared three VR display devices: (A) a 23-inch LCD 87 screen with a 120Hz refresh rate and 1920×1080 pixels resolu-88 tion desktop display, which we used as our baseline condition, 89 since games and current non-immersive simulations are usually 90 ran on PC desktops; (B) a 3200×1800 pixels resolution dis-91 play wall built up from a set of twelve 22-inch LCD screens, 92 with a total dimension of 244×108 centimeters (Fig. 2b). This 93 display intends to immerse the user on the simulation while 94 allowing them to be aware of their surroundings; and (C) an 95 HMD device, since it is widely used in VR and provides high 96 self-reported sense of presence, allowing the user to focus on 97 the simulation while avoiding distractions issued from their sur-98 roundings. We used the Oculus Rift DK2 device, which has a 99 960×1080 pixels resolution per eye and a refresh rate of 75Hz. 100

5.3. Participants

Sixty-one volunteers (15 female) took part in this experiment. They were students, mostly from Computer Science, and University personnel, aged between 19 and 63 years old (M=28.67, SD=10.12). They were all beginners in terms of work safety and VR, and 42% reported to be experienced on 3D video games. All the participants reported normal or correctedto-normal vision.



(a) Desktop

(b) Display-Wall

(c) HMD

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Fig. 2: Experimental conditions for the first experiment (user perception).

5.4. Task

The users were assigned with two tasks: (1) to follow the in-2 structions (e.g. "Inside of this building has a kitchen. Go there 3 and get a coffee.") given by a storyteller, while (2) scanning the environment for potential risks objects. The guidance en-5 abled users to go through every room in the building. In each 6 room, they were instructed to reach a target object (flashing in 7 red) by moving back and forward using the game controller's 8 joystick. Users would turn their heads to set the movement di-9 rection when using the HMD and the display wall, and use the 10 joystick when using the desktop display. After reaching the tar-11 get, the system triggers the next instruction, except in the case 12 of two special instructions, when the user should stand in a lo-13 cation and scan the room for potential risks for as long as they 14 would like. These tasks were included as a strategy to reduce 15 the difference among the experimental conditions, demanding 16 users to perform the same movements by either turning their 17 heads with the HMD or using the game controller. Further, it 18 serves also to verify whether users would simply follow what 19 the narrator was telling them to do or they were also attentive 20 to the scanning task. Such as in the real world, the detection of 21 risky situations should be a background task. 22

5.5. Measures 23

We measured the users' subjective sense of presence us-24 ing the SUS (Slater-Usoh-Steed) presence questionnaire [41], 25 which consists of six statements rated in a 7-point Likert scale 26 used to assess the sense of presence in each room of the VE. 27 Further, we asked users to respond the question "how much im-28 mersed did you feel?" in a 10-point scale, in order to assess 29 their sense of immersion. Regarding user experience, we asked 30 users to rate in a 5-point Likert scale the following statements: 31 "I believe the simulation achieve the purpose of assessing the 32 user's aptitude on detecting risk hazards in the work environ-33 ment", "I could perform the simulation easily"; "I enjoyed us-34 ing the simulator". Finally, we measured user performance by 35 combining three factors: task completion time (the lower the 36 better), traveled distance in the VE (the less the better), and the 37 number of detected risks (the more the better). 38

5.6. Results 39

The virtual path which users were supposed to follow was 40 determined by the audio instructions, which send them to the 41

car at the parking lot, the coffee maker at the kitchen, the desk at the office, and, finally, to meet their co-workers outside the 43 office. Although, we did not observe major differences among the experimental conditions, users wearing the HMD followed 45 a path slightly more straight than the ones in Display-Wall and 46 Desktop conditions.

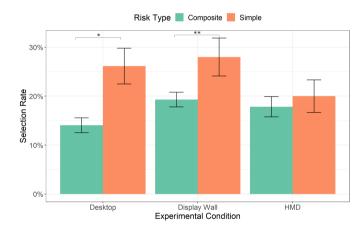


Fig. 3: Mean selection rates per type of risk in each experimental condition of experiment I.

Overall, users took between 5 and 15 minutes to complete 48 the simulation regardless the display device. We observed sig-49 nificant difference in the mean completion times for the dis-50 play wall and the remaining devices, suggesting that partici-51 pants using the display wall took longer to finish the simu-52 lation (M=12.4, p<0.001). In terms of risk selection, users 53 were able to identify about 21% of potential risk objects in 54 the VE (Fig. 3). The mean scores show that users found 55 more risk objects using the desktop display than with the re-56 maining, but no statistical difference was observed. Nonethe-57 less, when analyzing the type of risk objects users found, 58 we observed that they detected more simple than composite 59 risks using the display wall (p < 0.001) and the desktop display 60 (p < 0.05), while there was no significant difference under the 61 HMD condition. We observed that completion time and risk se-62 lection is positively correlated when using the desktop (p < 0.02, 63 R=0.5) and HMD (p<0.03, R=0.48) display devices. 64

In order to determine whether the devices inflicted cybersickness on users, we compared the SSQ scores measured before and after the trial. We observed statistical difference be-

tween mean scores for symptoms of nausea (p < 0.01), disorientation (p < 0.001), and total severity (p < 0.01) of users using the HMD. The desktop display reduced users' perceived severity of 3 symptoms, where we observed statistical difference in the mean scores of oculomotor and total severity (p < 0.02). No statistical 5 difference was observed for the display wall device.

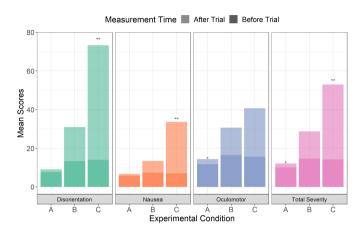


Fig. 4: Mean scores per SSQ scale before and after the trial in each experimental condition of Experiment I. A, B and C are the experimental conditions, see section 5.2

We did not observe statistical differences in the mean SSQ scores for users using the desktop display and the display wall. However, the users of the HMD appear to perceive the severity of symptoms of nausea, disorientation, and the total sever-10 ity significantly higher than the users of other devices (p < 0.01)11 (Fig. 4). We have also observed statistical differences in the 12 mean scores of the oculomotor scale between the HMD and 13 the desktop display devices (p < 0.05), while no statistical differ-14 ences were observed in regard to the display wall. The highest 15 SSQ score was 45.4 points (SD=53.7) regarding disorientation 16 symptoms while using the HMD device, which is a high score 17 compared to the maximum score of 97.4 points. 18

In terms of immersion, mean scores suggest that participants 19 using the HMD device (M=7.96, SD=1.68) perceived them-20 selves more immersed in the simulation than the users of the 21 display wall (M=5.8, SD=2.63, p<0.001) and the desktop dis-22 play (M=5.45, SD=1.77, p<0.01). Regarding the users' sense 23 of presence, we observed statistical significance in the SUS 24 scores for the HMD and the desktop display (p < 0.05), indicat-25 ing that users could feel more present when using the HMD 26 device. No statistical difference was observed in the scores for 27 the display wall and the remaining devices. 28

Overall, users reported to be satisfied with the experience 29 and, particularly the users who experienced it through the HMD 30 and display wall, reported to have felt "really" there. A few 31 participants mentioned that having to only walk towards what 32 they are seeing did not felt natural. However, we believe that, 33 differently from the real world, looking towards one direction 34 and walking towards another can increase disorientation. Users 35 have also appreciated the short duration of the experiment and 36 agreed that the simulation meets its goals. 37

5.6.1. Hypotheses Assessment.

Although the assessed sense of presence of users using the 39 HMD was higher than the other devices, the participants' risk 40 selection rate and completion time were similar among devices, 41 which means that we cannot accept H1. Nonetheless, we ob-42 served that the mean number of risk selection was quite low, 43 which is most likely a consequence of the users' overall lack 44 of expertise on work safety. The users with the HMD device 45 reported more severe sickness symptoms than the users of dis-46 play wall and desktop display devices, which latter appear to 47 have reduced the severity of symptoms. Nonetheless, comple-48 tion time and risk selection rate did not present any difference 49 among users of different display devices. Moreover, we did not 50 observe correlation between SSQ scores and completion time 51 or risk selection rate, which allows us to accept H2. Although 52 the participants did not present high performance, their varied perception of sickness symptoms severity did not impacted the 54 user performance among the different display devices.

6. Experiment II: Knowledge Gain

This experiment intends to explore the effects of two different interaction and two locomotion techniques on user experience and knowledge gain in a simulator designed for teaching apprentices the work safety procedures of a lightning rod replacement task. Overall, we believe the devices enabling movements closer to natural ones would improve user experience and, consequently, increase the knowledge gain from the simulation. Therefore, we hypothesized that (H1) the closest the movement is to the natural one, the better will be the user performance; (H2) the devices enabling arms and legs movements will not inflict severe motion sickness; and (H3) high workload inducing techniques will worsen user performance.

6.1. Virtual Environment

This simulation was designed for training apprentices on ba-70 sic safety procedures for electrical installations on public utility 71 poles. The VE consists of a town street where a lightning rod is 72 being replaced (Fig. 1b). A storyteller guides the user through 73 audio instructions (e.g. "The workers need to be equipped with 74 scrap gloves, safety belt, and helmet, while carrying the service 75 order. Please, select the objects representing this equipment. They are flashing in red. When you have finished, activate the 77 next instruction."), while teaching them the steps needed to se-78 cure the job site for workers and pedestrians. The simulation 79 has three phases: a learning phase, where the user learn the 80 proper placement of safety items, which is indicated via glow-81 ing objects and arrows; and two application phases, where the 82 user is asked to perform the safety task using the information 83 they just learned. In the learning phase, users can only grab objects that have been mentioned by the storyteller, which should 85 reinforce their focus on the task. In the application phases, users 86 can grab whichever items they like and follow their own strat-87 egy to place them in the scene. We change the initial placement 88 of objects between one phase and another to reduce the bias of 89 already knowing where to start. 90

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The users were asked to perform a set of five tasks: (1) to ensure that the truck is parked correctly and stuck with shims at 2 the wheels; (2) to equip workers with scrap gloves, safety belt, 3 helmet, and the service order; (3) to place the materials on the 4 protection canvas; (4) to signal the workplace using signposts; 5 and (5) to isolate the workplace, including the vehicle, using 6 cones and ropes. The tasks should be performed according to 7 the users' interpretation. In the assignment to arrange the cones 8 around the workplace, the users had eight available cones to be a arranged along a square illustrated by four arrows, so they could 10 either place one cone by each arrow or distribute a number of 11 cones they found necessary in the provided space. Later, they 12 were requested to tie the ropes between the cones previously 13 placed. In this case, there were seven ropes available and they 14 could choose a number of ropes they found necessary to isolate 15 the place. A barrier prevented users from crossing through the 16 rope after it has been tied between two cones, which served to 17 remind them of leaving an opening in the isolated area to allow 18 workers to transit. 19

20 6.2. Experimental Conditions and Apparatus

In this experiment we compared two interaction and two lo-21 comotion techniques. For grabbing and manipulating objects, 22 we use (1) a ray-casting technique based on the Razer Hydra 23 controllers used as pointing devices controlled by the user arms' 24 movements. When the object is within view, the user holds the 25 controller's button to grab and drag it, and drop it by releasing 26 27 the button; and (2) a head orientation technique, which uses the user's head orientation to point out to objects and one of the 28 Hydra's controllers to manipulate them using a button. In terms 29 of locomotion techniques, we use (1) the joystick of a Hydra's 30 controller for moving forward, backward, left, and right in the 31 environment; and (2) a WIP technique supported by a set of 32 four Wii balance boards, which gives the user a 0.80×1.2 me-33 ters platform to "walk". The experimental conditions for this 34 experiment are then resulting from the combination of these 35 techniques: (A) ray-casting and WIP, (B) ray-casting and joy-36 stick, (C) head orientation and WIP, and (D) head orientation 37 and joystick. 38

The equipment worn by the participants consisted of an Ocu-39 lus Rift DK2 device, a headphone, and a Sixense Razer Hydra. 40 To ensure a certain homogeneity among the conditions, users 41 went through the simulation on top of the Wii Balance Boards 42 platform and used the Razer Hydra controllers, regardless of the 43 enabled interaction/locomotion techniques (Fig. 5). The Razer 44 Hydra device contains a base station with a low-power mag-45 netic field that gets the controller's position and orientation. Al-46 though it does not require a line of sight to the controllers, the 47 range area is quite small, introducing noise to the tracking when 48 the user turns its back to the base station. Therefore, we used 49 a band to hold the base station on the user's body (Fig. 5b). In 50 between, we placed a smartphone to capture the orientation of 51 the user's torso, allowing this way to properly place the virtual 52 hands according to the user's rotational movements. Finally, to 53 provide users with confidence and control when using the WIP 54 technique, we added an EVA mat over the platform with EVA 55 borders around 7.5 centimeters high so the user could sense it, 56 being aware of the platform limits. 57

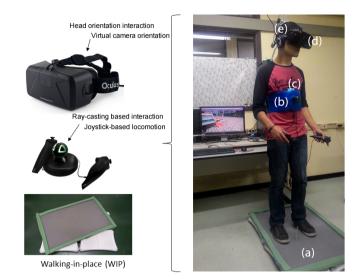


Fig. 5: Technical apparatus of experiment II: (a) WIP platform; (b) band to hold the Razer Hydra base station on the user's body; (c) a smartphone to get the user's orientation; (d) Oculus Rift device; (e) headphones.

6.3. Participants

Sixty volunteers took part in this experiment. They were all students recruited in the context of a Human-Computer Interaction course. Thirteen participants abandoned the simulation due to sever cybersickness symptoms, and we have lost the log files of one participant. Thus, we conducted the experiment with a sample of 46 participants (4 female), aged between 18 and 33 years old (M=23.21, SD=3.42). They reported to have great experience with 3D video games, but little with VR. They all had normal or corrected-to-normal vision (self-reported).

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6.4. Measures

Prior to the trial, we established the baseline for cybersickness and users' knowledge regarding safety procedures. We also assessed users' subjective memory complaints through a 10-item memory questionnaire [42], which information could support knowledge outcomes. To assess knowledge (before and after the trial), we prepared a 7-question test on the safety procedures addressed in the simulation. These were essay questions, presented one by one to the user and defined as follows: *What do you do to secure a job site for workers and pedestrians?*; *What do you do after arriving at the site and parking the vehicle?*; *What safety equipment do you wear to perform the task?*; *What extra item(s) do you need?*; *Where and how do you place the working tools?*; *What do you do first to secure the site for pedestrians?*; *How do you isolate the job site?*.

We applied the NASA Task Load Index (TLX) [43] questionnaire to assess workload for using the different navigation and interaction techniques. The questionnaire provides an overall workload score based on a weighted average of ratings on six workload factors (scales): Mental Demand (MD), Physical Demand (PD), Temporal Demand (TD), Own Performance (OP), Effort (EF), and Frustration (FR). Additionally, we assess user engagement's factors such as immersion, presence, flow, and physiological absorption through the Game Engagement Ques tionnaire (GEQ) [10]. The GEQ consists of 15 statements de scribing different feelings, which the user must rate in a 5-point
 Likert scale to indicate the intensity with which they experi enced that feeling during the simulation. Finally, we measure
 user performance by combining three information: task com pletion time, accuracy of objects' placement according to the
 instructions given in the learning phase, and knowledge gain.

9 6.5. Results

Fig. 6 presents the mean scores per SSO scale and experi-10 mental condition. Although we have found statistical difference 11 in the mean scores of certain scales before and after the trial in 12 every experimental condition, suggesting that they inflict cy-13 bersickness to users, we did not observe statistical difference 14 in the mean scores among the experimental conditions, nei-15 ther before nor after the trial. Particularly, every experimental 16 condition has engendered disorientation, which highest scores 17 (M=56.84) were reported by users of condition C (head orien-18 tation and WIP). Surprisingly, we found a 82% correlation be-19 tween disorientation and knowledge gain in condition A (ray-20 casting and WIP) with p < 0.01. Although no statistical differ-21 ence was observed, the users in this group reported the lowest 22 disorientation scores and the highest experience scores in 3D 23 games (M=4.25 in a 5-point scale, SD=1.03), suggesting that 24 disorientation probably did not affect their performance. 25

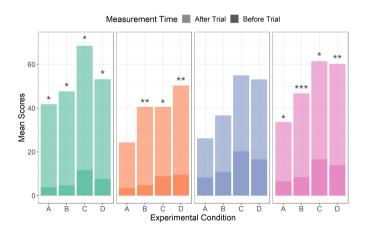


Fig. 6: Mean scores per SSQ scale before and after the trial in each experimental condition of Experiment II. A, B, C and D are the experimental conditions, see section 6.2

The overall workload scores were above average (scores 26 range from 0 to 100), varying from 49.2 in condition A to 62.4 27 in condition B, which difference of means showed statistical 28 significance with p < 0.05. In terms of the different scales mea-29 sured by the NASA TLX questionnaire (Fig. 7), we observed 30 statistical difference in the mean scores of: frustration between 31 conditions A (M=37.27) and D (M=206.36); mental demand 32 between conditions A (M=177.27) and D (M=50); own per-33 formance between conditions B (M=315) and D (M=143.63); 34 and physical demand between conditions C (M=131.66) and 35 D (M=205.45). Furthermore, we observed a 71% correla-36 tion between mental demand and knowledge gain in condition 37 (p < 0.05), suggesting that users had higher knowledge gain 38

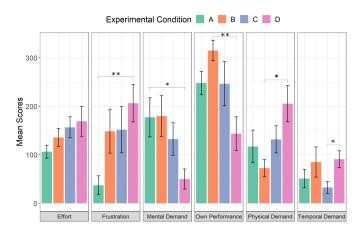


Fig. 7: Reported workload scores for each scale: mental demand (MD), physical demand (PD), temporal demand (TD), own performance (OP), effort (EF) and frustration (FR) for the experimental conditions on Experiment II.

when the task required higher mental effort. For users in condition B, we found a -69% correlation between overall workload scores and knowledge gain (p=0.019), suggesting that when users needed higher loads of work their ability to retain knowledge is reduced.

Figure 8 shows the response accuracy for the knowledge test taken by users before, after, and three weeks after the trial. We observed a statistical difference in the mean accuracy scores for those three measurement times. We did not found statistical difference between scores of tests taken after the trial, which similarity between means suggest that users were capable of recalling the information learned during the simulation. The mean simulation times across conditions varied from 20 minutes in conditions A and B to 32.7 minutes in condition D, which difference of means showed statistical significance (p < 0.001). Overall, the completion time reduced between the simulation's phases, which was expected due to users familiarizing with the navigation/interaction techniques, the VE, and the tasks. Users took around 3.6 minutes less time to finish the first application phase than the learning, and the completion time of the second application phase was yet reduced in around 1.1 minutes (no statistical difference was observed among conditions).

Overall, users could complete the simulation's tasks with 61 95% of accuracy. Particularly, we noticed that 88% of users 62 could correctly recall the instructions given in the learning 63 phase regarding the objects' placement. In terms of isolating 64 the job site, i.e. by forming a fence with cones and a rope 65 around the area containing the canvas with the tools and the 66 truck, while leaving an opening on it to allow workers to tran-67 sit, we observed that the 78% of users placed the cones cor-68 rectly, but only 36% of them left an opening in the fence. We 69 observed statistical difference among conditions in users' accu-70 racy to complete certain tasks. In terms of tools placement on 71 the canvas, participants in condition B performed better than 72 users in condition D (p < 0.038). Participants in condition C 73 and D were more accurate in terms of arranging the signposts 74 than users in condition A (p < 0.05) and B (p < 0.05), respectively. 75 Users in condition C were also more accurate in terms of iso-76 lating the job site than participants in condition D (p < 0.05). 77

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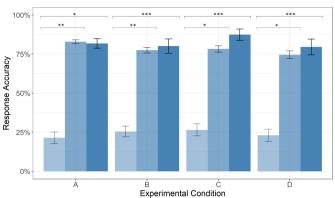
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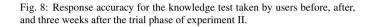
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Measurement Time 📕 Before Trial 📕 After Trial 📕 3 Weeks After Trial



The GEQ mean score was 2.8 across experimental conditions, which differences were not statistical significant. We 2 have found a 45% correlation between mental demand and en-3 gagement (p < 0.01), suggesting that navigation/interaction tech-4 niques demanding higher mental effort also tend to be more en-5 gaging. Overall, users reported to have enjoyed the experience 6 and found it easy to learn and apply the safety procedures. As in the previous experiment, we allow users to walk towards their 8 looking direction to reduce the severity of sickness symptoms. 9 In this matter, two persons have said that they would like to 10 walk backwards. Selecting objects in the scene was reported 11 to be difficult by some users, particularly regarding the cones. 12 Participants suggested the addition of a checklist to allow the 13 user to check tasks as done as they progress in the simulation. 14

15 6.6. Hypotheses Assessment

Due to the lack of statistical significance regarding knowl-16 edge gain, simulation time, and task accuracy across condi-17 tions, we cannot accept not refuse H1. Every experimental 18 condition increased the severity of sickness symptoms in every 19 20 SSQ scale, except oculomotor. Condition A requires the user to move their arms around to select objects and employs the 21 WIP technique for navigating in the VE. Although the mean 22 SSQ scores in condition A are the lowest in every scale, we 23 could not find statistical significance to support the difference 24 25 of means among conditions. In terms of knowledge gain, a negative correlation between overall workload and knowledge 26 gain suggests that high demanding navigation/interaction tech-27 niques could distract users from the task, requiring them to 28 place higher attention on how to use the techniques, decreasing 29 knowledge gain. In condition A, we observed a positive corre-30 lation between mental demand and knowledge gain, suggesting 31 that mentally demanding techniques do not affect knowledge 32 gain. In this condition, we also observed that users appear to 33 be more engaging when mental demand increase. Thus, we be-34 lieve that the freedom provided by more natural movements in 35 condition A allowed users to keep focus on the task, increas-36 ing mental demand and learning. These experiments should be 37 repeated and the sample enlarged to evaluate H2 and H3. How-38 ever, we believe these results favor their acceptance. 39

7. Discussion

In this work, we performed two empirical studies to investigate the impacts of three different VR displays and four interaction techniques on several VR aspects, such as motion sickness, workload, engagement, sense of presence, user performance, and learning outcomes on training simulations.

7.1. Main Findings

Our results showed that participants could perform certain tasks with higher accuracy, such as isolating the job site using the conditions where navigation was supported via the WIP technique, and placing tools over a canvas in conditions where they would grab and manipulate objects using the ray-casting technique. The latter provided a physical reference through a Razer Hydra's controller, which higher accuracy on performing the task suggests that users could better recall the information given during the learning phase, in conformity with previous findings [36]. Although we did not observe statistical difference in knowledge gain among experimental conditions and replication of these experiments may be necessary to evaluate our hypotheses, our results suggest that semi-natural navigation/interaction techniques could improve user performance.

Previous studies suggest that semi-natural interfaces, i.e. interfaces that use real walking and body interaction, could be inefficient since they require the user to operate it differently from what they are used to, which adds workload to the process [44]. However, we observed that users reported higher frustration scores when using the head orientation technique and the joystick to navigate, while they were more engaged with the simulation when moving their arms and legs through the ray-casting and WIP techniques, which were considered high mentally demanding by users. Users also perceived a higher quality on their own performance when using the WIP technique compared to the joystick. Furthermore, we observed a positive correlation between mental demand and knowledge gain in the condition using WIP and ray-casting, which also had the lowest simulator sickness effects. Our results suggest that providing close to natural interaction interfaces can be enjoyable and aid users to transfer the potential mental burden generated from adapting their real-walking expertise to better performance.

7.2. Lessons Learned

Disorientation is probably a consequence of the user un-80 awareness of their surroundings. As we have hypothesized, 81 techniques providing semi-natural interaction did not increase 82 the severity of sickness symptoms, because users could "move" 83 together with the VE. Nonetheless, we observed that disorienta-84 tion would be a constant across the experimental conditions in 85 experiment II, which coincides with the disorientation reported 86 by users of the HMD in experiment I, suggesting that disori-87 entation is only the fact that the user is not aware of their sur-88 roundings, which seems not to be affected by the different inter-89 action/locomotion techniques. Thus, our findings suggest that 90 better VEs would allow the user to be aware of their surround-91 ings, such as through the use of physical interaction devices 92 and more importantly through haptic interaction, allowing the

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user to physically feel what they're virtually experiencing. Such physical approaches have been previously explored to increase awareness in VEs and improve user experience (see [45, 46]).

The use of interaction techniques as natural as possible continue to be the best choice. Simulations designed for VR Б technology aim to provide a real-world-like experience, where high sense of presence, immersion and realism are essential ingredients. Thus, it is important to allow the use of our wellknown movements to navigate and interact with the VE. While much research is still needed to improve this technology, there 10 are several studies [10, 20, 32], including this one, showing the 11 advantages of natural or semi-natural interaction techniques on 12 user performance and experience. Thus, users could leverage of 13 training simulators employing well-drafted (semi-)natural inter-14 action techniques, which provide the sense of naturally navigat-15 ing and grabbing objects in the VE, while providing accuracy 16 for effectively dealing with small objects or performing precise 17 tasks, such as painting. 18

Perception is more likely to be affected by the user ex-10 pertise on the simulator subject than by the technology em-20 ployed. We have observed in experiment I (Section 5) that nei-21 ther the VR display nor the sickness caused by it affected user 22 perception. However, we noticed that users had a rather poor 23 performance on what refers to the risk scanning task. Users 24 were able to select 20% of risks elements (consistently through-25 out the devices), which is a low selection rate, likely explained 26 by users' self-reported very low knowledge on work safety pro-27 cedures. Previous works showed that the familiarity of users 28 with the objects in the environment improves the user expe-29 rience [24, 10]. Similarly, considering that our simulator have 30 been developed to assess the ability of users to detect hazardous 31 objects in the workplace, we suppose that the knowledge on the 32 subject could have strongly impacted user performance, since 33 one should know what is an hazardous element in the real work-34 place to be able to identify it in the simulation. Therefore, fur-35 ther studies using the "risk perception assessment" or similar 36 simulations to investigate user perception should recruit target 37 users of the simulation or to provide a training on work safety 38 to the participants before undertaking the simulation. 39

Gaming experience plays an important role on VR simu-40 lation. We have found a positive correlation between disorien-41 tation and knowledge gain in condition A of experiment II (Sec-42 tion 6), which oddly suggests that users improved their scores 43 despite the severity of disorientation's symptoms. However, we 44 noticed that the users in this group reported to have high experi-45 ence with 3D video games. Thus, we could suppose that users' 46 familiarity with games and the constantly experienced mild cy-47 bersickness due 3D graphics allowed them to keep focused on 48 the simulation despite the disorientation experienced in the VE. 49 Further, while studying the impact of narrative in immersive 50 VR games, Weech et al. [47] also observed differences cyber-51 sickness symptoms reported by gamers and non-gamers. While 52 non-gamers reported higher cybersickness when receiving min-53 imal narrative, regular gamers would present similar levels of 54 cybersickness regardless of the narrative context. 55

Although our case study focuses on work safety training, our 56 results and lessons learned can assist the choice of VR devices 57

to provide a comfortable and efficient virtual training environment in other application domains and, particularly, for simulations requiring the users to leverage their perception skills. For instance, our observations regarding the effects of users' profile on perception and cybersickness could help designers to conceive suitable guidance for simulators based on users' profile (e.g., whether they need more pre-training on the simulator's subject or the usage of devices, etc). Likewise, the usage of high fidelity devices to provide a real-world-like experience is independent of the application domain and can be generalized to any type of training simulator.

7.3. Limitations

Each user experiment tested multiple independent variables by 107 volunteers in total. Nevertheless, we applied between-71 subjects designs in both experiments due to the learning nature 72 of our dependent variables, reducing the groups to 20 and 12 73 persons, respectively. Thus, these experiments should be repli-74 cated using larger groups, and preferably the simulator's target 75 users, to strengthen our findings. The lack of expertise on work 76 safety may have introduced bias to the results. As suggested by 77 Nazir et al. [48], immersive simulators are not effective per se 78 and need guidance of a professional in the field when the task 79 is unfamiliar. We have used VR technology that was available 80 to us at the time of this study. Hence, a new set of experi-81 ments should be performed using novel technology to understand whether these results are technology independent.

8. Conclusion

We conducted two empirical studies to investigate the effects 85 of VR interface on perceptual learning and knowledge reten-86 tion in simulations designed for worker safety training. We 87 measured simulator sickness, self-reported workload, engage-88 ment, presence and performance. Our objective was to better 89 understand the impacts of different display devices and interac-90 tion techniques on user performance and simulation outcomes. 91 Our results strongly suggest that a setup employing interaction 92 and navigation techniques closest to natural movements can im-93 prove user performance. In our experiments, we observed this 94 improvement through accurately placing objects in the VE, giv-95 ing users the feeling of performing better, and having low ef-96 fects on simulator sickness. However, users still had a phys-97 ical reference for moving the hands in the VE and select ob-98 jects, which is supported by previous studies as a mechanism to 99 improve memory recall. Different VR display devices did not 100 influence the user performance in our risk scanning task, but 101 rather their experience on work safety. 102

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