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Evolution of a structured cell population endowed with plasticity of traits under constraints on and between the traits

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Abstract Confronted with the biological problem of managing plasticity in cell populations, which is in particular responsible for transient and reversible drug resistance in cancer, we propose a rationale consisting of an integro-differential and a reaction-advection-diffusion equation, the properties of which are studied theoretically and numerically. By using a constructive finite volume method, we show the existence and uniqueness of a weak solution and illustrate by numerical approximations and their simulations the capacity of the model to exhibit divergence of traits. This feature may be theoretically interpreted as describing a physiological step towards multicellularity in animal evolution and, closer to present-day clinical challenges in oncology, as a possible representation of bet hedging in cancer cell populations.

Keywords Structured population · Plasticity · Dimorphism · Finite Volume Method

1 Introduction: biological background

One of the main theories explaining the origins of cancer states that the hallmark capabilities of cancer are based on latent functions already existing in the genome of normal human cells, and that cancer represents a reversion

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to a less differentiated and less cooperative cellular behavior. This theory is usually called the atavistic model of cancer [5]. It is opposed to the more commonly admitted somatic mutation theory [10], that states that cancer originated in a single cell, following a catastrophic sequence of stochastic tumorigenic mutations, and from which Darwinian selection produced by divisions from this unicellular basis a more or less organised society of cheating cells, more and more escaping controls by the host organism, i.e., a cancer. In the atavistic theory, accompanied or induced by blockade of differentiation or reverse differentiation of normally maturing cells, societies of cells in a multicellular organism (cancer is always a disease of multicellular organisms) somehow, in some location of the organism, escape the fine control under which they are normally placed and revert to a previous, coarse and disorganised state of multicellularity [5]. This may be understood as a process of “deDarwinization”, through which cancer cells gain a state of *plasticity* [3, 20] representative of a former state in the evolution of multicellularity.

The atavistic theory has thus deep connections with the theory of evolution to multicellularity. The passage from unicellular organisms to multicellular ones led to the regulation of capabilities, resulting in controlled proliferation and differentiation of cells leading to specialisation and cooperation between specialised cells. The role of environment-driven cellular stress in this process of specialisation has recently been stressed by various authors [15, 21]. The new genes responsible for these regulations became tumour suppressors. The atavistic theory states that if these new suppressors become damaged for some reason, then latent genes, associated with functions from unicellular organisms, will reappear and dominate the scenery, thus resulting in the unconstrained proliferation and the lack of cooperation with the other cells of the host organism, as actually found in tumours.

Understanding how evolution led to the emergence of multicellularity then becomes a problem closely related to that of understanding cancer. Firstly because unravelling in detail what is lost (cohesion) and what is gained (plasticity) in this reverse evolutionary process may help understand the nature of cancer from a functional point of view. Secondly because it is reasonable to assume that Darwinian selection in tumors starts from a primitive state of multicellularity in which cells are very plastic with respect to their phenotypes, which sends us back to states in evolution close to the emergence of multicellularity. The division of work through cell differentiation achieved by coherent multicellularity (i.e., designing a stable, cohesive multicellular organism) [14] was of vital importance in order to evolve into more complex and more functionally efficient organisms. In a first stage, this differentiation was very likely reversible, due to the high plasticity that cells were endowed with in a primitive state of multicellularity. Under these conditions, one can reasonably assume that these primitive organisms adopted bet hedging strategies, i.e., common risk-diversifying strategies in unpredictably changing and often aggressive environments, in order to

maximise their phenotypic fitness [17, 19].

In more detail, bet hedging in cell populations may be defined as a diversification of phenotypes in a cohesive (or at least bound by a common fate community, usually of genetic nature) cell population to optimise its fitness, in particular *a minima* to ensure its survival in a life-threatening environment, in other words to design a fail-safe strategy for the preservation of a propagating element; one cell may be enough to achieve this goal. Enhancing the ability to (quickly) diversify phenotypes by changing differentiation paths (by reversal, i.e., vertical de-differentiation, or by horizontal transdifferentiation in a differentiation tree) may in particular be achieved at the chromatin level by means of epigenetic enzymes, molecular instances of cell plasticity at work [20].

Among such commonly described strategies of living organisms (unicellular or multicellular) meant to ensure survival in changing environments have been classically described fright, fight and flight. Fright (or freeze) is not likely to induce phenotype evolution. Fight (establishing barriers, secreting poisons, gathering in colonies) and flight (motility to escape unbeatable predators) can. Differentiation between somatic and germinal cells is also a major step in evolution. Bet hedging strategies were not only present at elementary stages of evolution. They are a common adaptive tool that can still be found in nature at different levels of complexity, from prokaryotic organisms to vertebrate ones. In between, tumour cells, thanks to their high plasticity, in the presence of an aggressive environment provided by immune response of the host body or of any anti-cancer treatment, may adopt bet hedging as a strategy to guarantee a prolonged survival of their colony. The wide presence of bet hedging in nature as an evolutionary mechanism, and its many links to the development of cancer is what motivates us in the present attempt towards a mathematical model representing some of the factors that influence this phenomenon (natural selection, epimutations and environmental stress).

In our modelling choices, we have privileged, for the sake of biological interpretation, as in [2], two phenotypes that are often identified as such in theoretical ecology: viability (potential to resist a deadly insult: the elephant strategy) and fecundity (potential to proliferate, or in a way, surviving by numbers, even under hard environmental conditions: the rat strategy). They may influence cell behaviour in opposed directions, as two different choices, incompatible for the same cell, in the same way as fecundity and motility are notably incompatible (cells that divide do not move, and vice versa). To take into account the faculty of rapidly changing phenotypes in case of a life-threatening insult, a capacity reported about many cancer cells (e.g., epithelial to mesenchymal transition or drug-induced drug persistence) [20], here we have added plasticity as a complementary structuring phenotype (or trait) of cells. Among questions at stake we will in particular deal with is the optimisation of fitness strategy by concentration of phenotypes, either in two or more ranges surrounding fixed points (multimodality of traits, i.e., bet

hedging) or around a central optimal point (unimodality of trait, i.e. no bet hedging when it is not favourable).

2 The model

We consider a population (not necessarily of tumour cells) in which each individual has three defining traits: viability associated with the variable $x \in [0, 1]$ which reflects the potential to resist deadly insults, fecundity associated with the variable $y \in [0, 1]$ representing the potential to proliferate and plasticity associated with the variable $\theta \in [0, 1]$ which represents the potential to continue to differentiate within a differentiation tree. We assume furthermore that for a certain regular function $C : \mathbb{R}^2 \rightarrow \mathbb{R}$ and a positive constant K , $(x, y) \in \Omega := \{C(x, y) \leq K\}$, so $z = (x, y, \theta)$ ranges over the set $D := \{\Omega \times [0, 1]\}$. We then consider the evolution problem (2.1), (2.2), (2.3) on the density of population $n = n(t, z) \geq 0$.

$$\partial_t n + \nabla \cdot (Vn - A(\theta)\nabla n) = (r(z) - d(z)\rho(t))n, \quad (2.1)$$

$$(Vn - A(\theta)\nabla n) \cdot \mathbf{n} = 0, \text{ for all } z \in \partial D, \quad (2.2)$$

$$n(0, z) = n_0(z), \text{ for all } z \in D. \quad (2.3)$$

In the above equation, the matrix

$$A(\theta) = \begin{pmatrix} \alpha(\theta) & 0 & 0 \\ 0 & \beta(\theta) & 0 \\ 0 & 0 & \gamma \end{pmatrix}$$

gives the speed at which non-genetic epimutations occur, the function

$$V(t, z) = (V_1(t, z), V_2(t, z), V_3(t, z))$$

represents the sensitivity of the population to abrupt changes in the environment and

$$\rho(t) = \int_D n(t, z) dz$$

stands for the total amount of individuals in the population at time t .

Throughout our work we assume

- (H1) For some $p > 2$, the initial population density $n_0(z)$ belongs to $L^p(D)$.
- (H2) The intrinsic growth rate in absence of competition $r(z)$ and the death rate $d(z)$ due to competition for individuals with treat z are positive bounded functions that satisfy $0 < r^- \leq r(z) \leq r^+$ and $0 < d^- \leq d(z) \leq d^+$.
- (H3) The diffusion parameters $\alpha(\theta)$, $\beta(\theta)$ and γ are strictly positive, with $\alpha(\theta)$ and $\beta(\theta)$ being non decreasing with respect to θ . Hence, the matrix $A(\theta)$ is elliptic for all values of θ .
- (H4) The function $V(t, z)$ is continuously differentiable for all values of $t > 0$ and $z \in D$.

Under these hypotheses we are able to prove the existence and uniqueness of a solution for the problem (2.1)-(2.3) using the Finite Volume method in order to obtain a convergent semi-discrete scheme.

The problem (2.1)-(2.3) underlying hypotheses $(H1)$ to $(H4)$ sets a structured population model of evolution that, as mentioned before, takes into account some of the factors that might lead to the occurrence of “bet hedging”. Amongst the first works in this topic, we can find [4], where is studied the fraction of seeds that germinate and the fraction that remains dormant, in order to maximise the long term expectation of growth. In the same work, the similarities of this phenomenon with economic decision making under risk (so-called “fail-safe strategies”) are noted. Other early works on the subject are [17] and [19]. The reaction term in (2.1) is a simple way of modelling the selection principle. This term and more general ones are used in [16] in order to study some basic properties of structured populations undergoing this type of behaviour. The same reaction term is also used in [18], where are analysed the global asymptotic stability properties for integro-differential systems of N species structured by different sets of traits. A similar competition term is used in [6] to provide results about the long time behaviour of such reaction models. The diffusion term here models non-genetic instabilities (also known as epimutations), which constitute the drift of phenotype without alteration of the genotype. In [16] an integral operator in order to model mutations arising during reproduction is used, and something similar could be done for the epimutations. The second order operator used in (2.1) can be obtained then after re-scaling the time variable. The effect of this phenomenon in cancer development is discussed in [9] from a biological point of view. Epimutations can also occur because of external stress, and this is represented in (2.1) by means of the advection terms. A biological example for a population changing phenotype due to external stress can be found in [12], where the effect of physical stress on the shape and the cell wall thickness of E.coli bacterias is discussed. Two different models are used in [2] to conclude that the three mechanisms described above might reversibly push an actively-proliferating, and drug-sensitive, cell population to transition into a weakly-proliferative and drug-tolerant state, which will eventually facilitate the emergence of more potent, proliferating and drug-tolerant cells. One of such models is an integro-differential model very similar to (2.1)-(2.3), but without including the effect of plasticity on the evolution of the population and without assuming the existence of a constraint between the traits x and y .

The main results of this paper involve the variational formulation of (2.1)-(2.3), which we now introduce. Denote $H = L^2(D)$, with $(\cdot, \cdot)_H$ the usual scalar product in that space, and $\mathcal{V} = H^1(D)$ with $\langle \cdot, \cdot \rangle = \langle \cdot, \cdot \rangle_{\mathcal{V}' \times \mathcal{V}}$ being the duality product in \mathcal{V} .

For any given $n_0 \in H$, $T > 0$, we say that

$$n := n(t) \in X_T := C([0, T], H) \cap L^2((0, T), \mathcal{V}) \cap H^1([0, T], \mathcal{V}'),$$

is a variational solution of the problem (2.1)-(2.3) if it is a solution in the following weak sense

$$(n(t), \varphi(t))_H = (n_0, \varphi(0))_H + \int_0^t \left(\langle Q[n](s), \varphi(s) \rangle + \langle \varphi'(s), n(s) \rangle \right) ds, \quad (2.4)$$

where

$$\langle Q[n], \varphi \rangle = \int_D \left(-A \nabla n \nabla \varphi + V n \nabla \varphi + (r(z) - \rho d(z)) n \varphi \right) dz,$$

for any $\varphi \in X_T$. We say that n is a global solution if it is a solution on $[0, T]$ for any $T > 0$.

Theorem 1 *For all non-negative $n_0 \in L^p(D)$, $p > 2$, there exists a unique global non-negative weak solution for problem c in the sense of (2.4).*

We focus on giving a proof for this theorem using a discretised version of problem (2.1)-(2.3) after applying the Finite Volume Method to it. For this purpose, we define a subset $D_h \subset D$, that can be covered by the union of N disjoint cubic cells, denoted as D_j , of side length h and after integrating the equation (2.1) over each of the cells D_j we derive the system of first-order differential equations

$$\frac{d}{dt} \nu_j(t) = M_j(t, \nu(t)) \nu_j(t) + \sum_{l \in N_j} B_{jl}(t) \nu_l(t), \quad (2.5)$$

$$\nu_j(0) = \frac{1}{h^3} \int_{D_j} n_0(z) dz, \quad (2.6)$$

where the coefficients M_j and B_{jl} are functions of $V(t, z)$, $A(\theta)$, $r(z)$ and $d(z)$. We can then introduce the following result involving the solution for this system:

Theorem 2 *For all non-negative $n_0 \in L^p(D)$, $p > 2$, there exists a unique non-negative solution for problem (2.5)-(2.6). Furthermore, the function $\tilde{n}_h(t, z)$ defined by*

$$\tilde{n}_h(t, z) = \sum_j \nu_j(t) \mathbb{1}_{D_j \cap D},$$

converges in $L^2(D_T)$ to the unique non-negative weak solution of (2.1)-(2.3) as h goes to zero.

The existence and non-negativity of the solution for (2.5)-(2.6) results from the Cauchy-Lipschitz theorem, while the convergence of $\tilde{n}_h(t, z)$ is the consequence of the compactness of the sequence.

The existence result in Theorem 1 will be treated in Section 3, but the uniqueness can be directly obtained from the variational formulation with the help of some *a posteriori* estimates. Let us proceed then to prove the

uniqueness before addressing the existence. Assume that there exists a non-negative weak solution n for (2.1)-(2.3) and take $\varphi \equiv 1$ on the variational formulation. This leads to the equality

$$\rho(t) = \rho(0) + \int_D (r(z) - d(z)\rho(t))n(t, z)dz,$$

where $\rho(t) = \int_D n(t, z)dz$ is a continuous function due to the fact that $n(t, z) \in \mathcal{C}([0, T], H)$. From this it is simple to deduce that

$$\min\{\rho(0), \frac{r^-}{d^+}\} \leq \rho(t) \leq \max\{\rho(0), \frac{r^+}{d^-}\}$$

for all values of t . Taking now $\varphi = n$ on the variational formulation, using standard arguments to bound the linear terms from $Q[n]$ and the previous result for the non-linear part together with the Gronwall Lemma, we obtain the relation

$$\frac{1}{2}\|n(t)\|_H^2 \leq \frac{1}{2}\|n(0)\|_H^2 + a \int_0^t \frac{1}{2}\|n(s)\|_H^2 ds,$$

for some real positive number a . Using Gronwall's lemma, this relation implies that

$$\|n(t)\|_H^2 \leq \|n_0\|_H^2 e^{2at},$$

for all values of t . Finally assume the existence of two non-negative weak solutions n_1 and n_2 for the same initial data n_0 . Taking the difference between their respective variational formulations, choosing $\varphi = n_1 - n_2$ and using again the Gronwall lemma, we get the equality

$$\frac{1}{2}\|n_1 - n_2\|_H^2 = \int_0^t \langle Q[n_1] - Q[n_2], n_1 - n_2 \rangle ds.$$

Once again, the linear part of $Q[n_1] - Q[n_2]$ can be easily bounded using standard methods, leading to

$$\begin{aligned} \frac{1}{2}\|n_1 - n_2\|_H^2 &\leq a \int_0^t \|n_1 - n_2\|_H^2 ds - \int_0^t \rho_1(s) \int_D d(z)(n_1 - n_2)^2 dz ds \\ &\quad - \int_0^t (\rho_1(t) - \rho_2(t)) \int_D n_2 d(z)(n_1 - n_2) dz ds \\ &\leq \int_0^t (a + d^+ \|n_0\|_H \sqrt{s} e^{as}) \|n_1 - n_2\|_H^2 ds \end{aligned}$$

Consequently, thanks to Gronwall's lemma, $\|n_1 - n_2\|_H^2 = 0$ for all t , therefore, the solution is unique.

As stated before, the proof of existence of a weak solution will be carried on in Section 3. Following the ideas from [1], the semi-discrete numerical scheme (2.5)-(2.6) is developed and the convergence of its solution to the solution of (2.1)-(2.3) is demonstrated. A fully discrete numerical scheme is obtained starting from the semi-discrete one and its convergence is also proved. Section 4 is devoted to the numerical simulations, starting with some numerical computations of the approximation error by comparing the results with an exact solution. Finally, the solutions of some examples with biological meaning is presented.

3 Existence of a weak solution and numerical approximation

We aim to use the Finite Volume method in order to find a sequence of problems whose solutions converge to the solution of (2.4).

3.1 Preliminaries on the finite volume method

Consider $h = 1/M$ where M is a natural number and define the mesh

$$C_{ijk} = [\frac{i}{M}, \frac{i+1}{M}] \times [\frac{j}{M}, \frac{j+1}{M}] \times [\frac{k}{M}, \frac{k+1}{M}],$$

with $i, j, k = 0, \dots, M-1$, such that $\bigcup_{i,j,k} C_{ijk} = [0, 1]^3$.

Now introduce the sets

$$\mathcal{M} = \{C_{ijk} : C_{ijk} \cap D \neq \emptyset\}$$

and

$$D_h = \bigcup_{\mathcal{M}} C_{ijk}.$$

For simplicity, enumerate each element of \mathcal{M} as D_j , for $j = 1, \dots, N = |\mathcal{M}|$, and for each D_j , denote its centre of mass as $\mathbf{z}_j := (x_j, y_j, \theta_j)$. For each j , define N_j as the set of indexes l such that D_l and D_j share a common boundary. Denote such common boundary as Γ_{jl} , its centre of mass as \mathbf{z}_{jl} and \mathbf{n}_{jl} the outer normal vector of D_j , in the direction of D_l . The distance between the centres of two neighbouring cells D_j and D_l will be denoted as d_{jl} . Having cubes as the mesh cells guarantees that the condition

$$\mathbf{n}_{jl} = \frac{\mathbf{z}_l - \mathbf{z}_j}{d_{jl}}, \quad (3.1)$$

is fulfilled.

It is important to remark that if D has a regular enough boundary (for example: smooth or polygonal), then $|D_h \setminus D|$ will converge to zero as h vanishes. The approximated problem (2.1)-(2.3) is then given by

$$\partial_t \tilde{n}_h + \nabla \cdot (V \tilde{n}_h - A(\theta) \nabla \tilde{n}_h) = (r(z) - d(z) \tilde{\rho}_h(t)) \tilde{n}_h, \text{ in } D_h \quad (3.2)$$

$$(V \tilde{n}_h - A(\theta) \nabla \tilde{n}_h) \cdot \mathbf{n} = 0, \text{ for all } z \in \partial D_h, \quad (3.3)$$

$$\tilde{n}_h(0, z) = n_0(z), \text{ for all } z \in D_h, \quad (3.4)$$

where $\tilde{\rho}_h(t) = \int_{D_h} \tilde{n}_h(t, z) dz$. We propose a classical finite volume method based on local averages of the unknown density over cell grids defined by

$$\nu_j(t) := \frac{1}{h^3} \int_{D_j} \tilde{n}_h(t, z) dz = n(t, \mathbf{z}_j) + \mathcal{O}(h^2). \quad (3.5)$$

Assume that the coefficients and the solution from equation (3.2) are smooth. Then, integrating it over a cell D_j yields the equality

$$\frac{d}{dt} \int_{D_j} \tilde{n}_h dz = - \int_{D_j} \nabla \cdot (V \tilde{n}_h - A \nabla \tilde{n}_h) dz + \int_{D_j} r(z) \tilde{n}_h dz - \tilde{\rho}_h(t) \int_{D_j} d(z) \tilde{n}_h dz.$$

After integrating by parts and using the boundary conditions (3.3), we get

$$- \int_{D_j} \nabla \cdot (V \tilde{n}_h - A \nabla \tilde{n}_h) dz = - \sum_{l \in N_j} \int_{\Gamma_{jl}} (V \tilde{n}_h - A \nabla \tilde{n}_h) \cdot \mathbf{n}_{jl} dS.$$

For a real function $f(t)$, define the positive and negative part of f as

$$f^+(t) = \begin{cases} f(t), & \text{if } f(t) \geq 0, \\ 0, & \text{if } f(t) < 0, \end{cases}$$

and

$$f^-(t) = \begin{cases} 0, & \text{if } f(t) \geq 0, \\ f(t), & \text{if } f(t) < 0, \end{cases}$$

respectively. Using an upwind approximation technique for the advection term, we conclude

$$\int_{\Gamma_{jl}} V \tilde{n}_h \cdot \mathbf{n}_{jl} dS = |\Gamma_{jl}| \left(\nu_j(t) u_{jl}^+(t) + \nu_l(t) u_{jl}^-(t) \right) + \mathcal{O}(h^2), \quad (3.6)$$

where $u_{jl}(t) = V(t, \mathbf{z}_{jl}) \cdot \vec{\mathbf{n}}_{jl}$. On the other hand, we have

$$- \int_{\Gamma_{jl}} (A \nabla \tilde{n}_h) \cdot \mathbf{n}_{jl} dS = - |\Gamma_{jl}| \left(A(\theta_{jl}) \nabla \tilde{n}_h(\mathbf{z}_{jl}) \right) \cdot \mathbf{n}_{jl} = - |\Gamma_{jl}| \nabla \tilde{n}_h(\mathbf{z}_{jl}) \cdot A(\theta_{jl}) \mathbf{n}_{jl}.$$

As $A(\theta)$ is a diagonal matrix and \mathbf{n}_{jl} is either one of the vectors from the euclidean canonical base, or one of their opposites, we have the relation

$$A(\theta_{jl})\mathbf{n}_{jl} = A_{jl}\mathbf{n}_{jl},$$

where $A_{jl} = (A(\theta_{jl})\mathbf{n}_{jl} \cdot \mathbf{n}_{jl})$. Notice that, thanks to hypothesis $(H3)$, there exists $\alpha > 0$ such that $A_{jl} \geq \alpha$, for all j and l . So that, together with the expression of the normal vectors, (3.1) this implies

$$-\int_{\Gamma_{jl}} (A\nabla \tilde{n}_h) \cdot \mathbf{n}_{jl} dS = -\frac{A_{jl}|\Gamma_{jl}|}{d_{jl}} (\nabla \tilde{n}_h(\mathbf{z}_{jl})) \cdot (\mathbf{z}_1 - \mathbf{z}_j).$$

Due to the approximation of the gradient

$$(\nabla \tilde{n}_h(\mathbf{z}_{jl})) \cdot (\mathbf{z}_j - \mathbf{z}_1) = \tilde{n}_h(\mathbf{z}_1) - \tilde{n}_h(\mathbf{z}_j) + \mathcal{O}(h^2),$$

we can finally write

$$\begin{aligned} -\int_{\Gamma_{jl}} (A\nabla \tilde{n}_h) \cdot \mathbf{n}_{jl} dS &= -\frac{A_{jl}|\Gamma_{jl}|}{d_{jl}} (\tilde{n}_h(\mathbf{z}_j) - \tilde{n}_h(\mathbf{z}_1)) + \mathcal{O}(h^2) \\ &= -\frac{A_{jl}|\Gamma_{jl}|}{d_{jl}} (\nu_l(t) - \nu_j(t)) + \mathcal{O}(h^2). \end{aligned} \quad (3.7)$$

Taking into account that

$$\rho_h(t) = \int_{D_h} \tilde{n}_h(t, z) dz = \sum_l \int_{D_l} \tilde{n}_h(t, z) dz = \sum_l h^3 \nu_l(t),$$

the reaction terms can be easily approximated

$$\begin{aligned} \int_{D_j} r(z) \tilde{n}_h dz - \tilde{\rho}_h(t) \int_{D_j} d(z) \tilde{n}_h dz &= h^3 (r(\mathbf{z}_j) - \rho_h(t) d(\mathbf{z}_j)) \tilde{n}_h(t, \mathbf{z}_j) + \mathcal{O}(h^5) \\ &= h^3 (r_j - \tilde{\rho}_h(t) d_j) \nu_j(t) + \mathcal{O}(h^5) \\ &= h^3 \left(r_j - d_j \sum_l h^3 \nu_l(t) \right) \nu_j(t) + \mathcal{O}(h^5). \end{aligned} \quad (3.8)$$

Finally, using again (3.5), we get

$$\frac{d}{dt} \int_{D_j} \tilde{n}_h(z) dz = h^3 \nu'_j(t).$$

Consequently, collecting (3.6), (3.7) and (3.8), and getting rid of the approximation orders we obtain the semi-discrete scheme

$$\frac{d}{dt} \nu_j(t) = M_j(t, \tilde{\rho}_h(t)) \nu_j(t) + \sum_{l \in N_j} B_{jl}(t) \nu_l(t), \quad (3.9)$$

where

$$M_j(t, \tilde{\rho}_h(t)) = - \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{h^3} \left(u_{jl}^+(t) + \frac{A_{jl}}{d_{jl}} \right) + \left(r_j - d_j \tilde{\rho}_h(t) \right),$$

$$B_{jl} = \frac{|\Gamma_{jl}|}{h^3} \left(-u_{jl}^-(t) + \frac{A_{jl}}{d_{jl}} \right).$$

This system of equations can be complemented with the set of initial data

$$\nu_j(0) = \nu_j^0 := \frac{1}{h^3} \int_{D_j} \bar{n}_0(z) dz, \quad (3.10)$$

where $\bar{n}_0(z)$ is the extension by 0 of $n_0(z)$ to all of \mathbb{R}^3 .

3.2 Global existence, uniqueness, positivity and boundedness of the solution for the semi-discrete scheme

We prove the local existence and uniqueness of the solution for the problem (3.9)-(3.10), by using the Cauchy-Lipschitz theorem. Then, such solution is proved to be non-negative and, as a consequence, bounded independently of t . Finally the boundedness property is used to prove the global existence of the solution.

Proposition 1 (Local existence of solution) *For all sets of initial data $\{\nu_j^0\}$, there exists $0 < T^* < \infty$ such that the problem (3.9)-(3.10) has an unique solution over $[0, T^*)$. Furthermore, if $\nu_j^0 \geq 0$ for all j , then $\nu_j(t) \geq 0$ for all time $t \in [0, T^*)$ and all j .*

Proof. The RHS term in (3.9) is Lipschitz continuous for all values of t and ν_j , therefore the existence and uniqueness of solution over a certain interval $[0, T^*)$ is a direct consequence of the Cauchy-Lipschitz theorem.

On the other hand, consider a strictly positive set of initial values ν_j^0 and define the continuous function $f(t) = \min_j \nu_j(t)$. If $f(t) \geq 0$ for all $t < T^*$, then the solution remains positive at all times. If $f(t) < 0$ for some $t \in (0, T^*)$, then there exists $t_0 > 0$ such that $f(t_0) = 0$ and $f(t) \geq 0$ for $t < t_0$. This implies the existence of j_0 such that $\nu_{j_0}(t_0) = 0$ with $\nu'_{j_0}(t_0) \leq 0$. If $\nu_l(t_0) > 0$ for some $l \in N_{j_0}$, then, thanks to (3.9) we have

$$\begin{aligned} \nu'_{j_0}(t_0) &= \sum_{l \in N_{j_0}} B_{jl}(t_0) \nu_l(t_0) \\ &= \sum_{l \in N_{j_0}} \frac{|\Gamma_{jl}|}{h^3} \left(-u_{jl}^-(t_0) + \frac{A_{jl}}{d_{jl}} \right) \nu_l(t_0) > 0, \end{aligned}$$

which is a contradiction with the previously established fact that $\nu'_{j_0}(t_0) \leq 0$. Consequently $\nu_l(t_0) = 0$ for all $l \in N_{j_0}$. Furthermore, from the definitions of $f(t)$ and t_0 , we also have that $\nu'_l(t_0) \leq 0$ for all $l \in N_{j_0}$. We can iterate the

previous argument in order to obtain that $\nu_j(t_0) = 0$ for all j and consequently, thanks to the uniqueness of the solution, $\nu_j(t) \equiv 0$ for all j and all t . This is a contradiction with the assumption that $f(t)$ is negative for some value of t and consequently $f(t) \geq 0$ for all t .

Finally, for non-negative initial values ν_j^0 and ε small enough, we define ν_j^ε as

$$\nu_j^\varepsilon = \begin{cases} \nu_j^0 & \text{if } \nu_j^0 > 0, \\ \varepsilon & \text{if } \nu_j^0 = 0. \end{cases}$$

Thanks to the previous step, the solution of (3.9) associated to ν_j^ε remains non-negative for all t and all ε . Hence, thanks to the continuous dependence of the solution of a system with respect to its initial data, we conclude that $\nu_j^0 \geq 0$ implies $\nu_j(t) \geq 0$ for all $t \in [0, T^*)$. \square

Proposition 2 (Discrete L^1 bound) *The L^1 norm $\tilde{\rho}_h(t) := \sum_l h^3 \nu_l(t)$ satisfies the bounds*

$$\underline{\rho} := \min\{\tilde{\rho}_h(0), \frac{r^-}{d^+}\} \leq \tilde{\rho}_h(t) \leq \max\{\tilde{\rho}_h(0), \frac{r^+}{d^-}\} =: \bar{\rho}, \quad \forall t \geq 0, \quad (3.11)$$

where r^- , r^+ , d^- and d^+ are the bounds given in (H1) for $r(z)$ and $d(z)$ respectively.

Proof. Multiplying (3.9) by h^3 for each j , adding up all the equations, recalling that $|\Gamma_{jl}| = |\Gamma_{lj}|$, $u_{jl}^+ = -u_{lj}^-$, $A_{jl} = A_{lj}$ and $d_{jl} = d_{lj}$ we obtain that

$$\tilde{\rho}_h'(t) = \sum_j \left(r_j - d_j \tilde{\rho}_h(t) \right) h^3 \nu_j(t).$$

The non-negativity of the solution implies then

$$\left(r^- - d^+ \tilde{\rho}_h(t) \right) \tilde{\rho}_h(t) \leq \tilde{\rho}_h'(t) \leq \left(r^+ - d^- \tilde{\rho}_h(t) \right) \tilde{\rho}_h(t).$$

These differential inequalities directly imply the bounds over $\tilde{\rho}_h(t)$. \square

Notice that the L^1 bounds are independent of t . Additionally, the upper bound also implies that

$$h^3 \nu_j(t) \leq \tilde{\rho}_h(t) \leq \bar{\rho}, \quad \text{for all } t \in [0, T^*), \quad \text{for all } j,$$

So that in general $\nu_j(t) \leq \frac{\bar{\rho}}{h^3}$, which is the key estimate in order to prove global existence of solution for (3.9)-(3.10).

Proposition 3 (Global existence of solution) *For all sets of initial data $\{\nu_j^0\}$, there exists a unique solution of problem (3.9)-(3.10) for all $t > 0$. Such solution is non-negative and satisfies the estimate (3.11).*

Proof. For each h , assume that there exists a finite maximal time of existence T_h . However, the previous estimate for $\tilde{\rho}_h(t)$ implies that for all j , $\nu_j(T_h) \leq \frac{\bar{\rho}}{h^3} < \infty$, which, thanks to the Lipschitz continuity of the right hand side of (3.9) allows to extend to solution to a certain interval $[T_h, T_h^*)$, contradicting this way the maximality of T_h . \square

3.3 Discrete gradient, L^2 norm estimate and compactness result

In this section we introduce some piece-wise constant functions depending on the solution of (3.9)-(3.10) together with some estimates related to such functions. Then, some compactness properties will be proved in order to ensure that such functions converge to some function that will be proved to be a weak solution of (2.1)-(2.2), and their derivatives, respectively.

We first introduce $n_h(t, z)$ defined as

$$n_h(t, z) = \sum_j \nu_j(t) \mathbb{1}_{D_j}(z).$$

Notice that $\|n_h\|_{L^1} = \tilde{\rho}_h(t)$. Now, for each $l \in N_j$, define the polygonal subsets of D_j , denoted D_{jl} , having Γ_{jl} as the common side and \mathbf{z}_j as a vertex. The subsets D_{jl} are pyramids of area $s_{jl} = \frac{|\Gamma_{jl}|d(\mathbf{z}_j, \Gamma_{jl})}{3} = \frac{h^3}{6}$. Let us define the piece-wise constant function

$$v_h(t, z) = \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} \left((\mathbf{z}_{jl} - \mathbf{z}_j) \frac{\nu_l(t) - \nu_j(t)}{s_{jl}} \mathbb{1}_{D_{jl}}(z) \right).$$

This function can be regarded as a discrete gradient for $n_h(t)$.

Proposition 4 (L^2 bound) *For each value of h , define the space $H_h := L^2(D_h)$. Then, there exists positive constants a and b , independent of h , such that the functions $n_h(t, z)$ and $v_h(t, z)$ satisfy the following estimate*

$$\|n_h\|_{H_h}^2 + a \int_0^T \|v_h\|_{H_h}^2 \leq e^{bT} \|n_0\|_{H_h}^2, \text{ for all } T > 0. \quad (3.12)$$

Proof. Multiplying equation (3.9) by $h^3 \nu_j(t)$ for each j , and adding them up, we obtain the relation

$$\sum_j h^3 \nu_j(t) \nu_j'(t) = A(t) + D(t) + R(t), \quad (3.13)$$

where

$$\begin{aligned} A(t) &= - \sum_j \nu_j(t) \sum_{l \in N_j} |\Gamma_{jl}| \left(\nu_j(t) u_{jl}^+(t) + \nu_l(t) u_{jl}^-(t) \right), \\ D(t) &= \sum_j \nu_j(t) \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right), \\ R(t) &= \sum_j h^3 \left(r_j - d_j \sum_l h^3 \nu_l(t) \right) \nu_j^2(t). \end{aligned}$$

Let us proceed to estimate each of these terms. In order to simplify the notation, we define

$$\mu_{jl}(t) = |\Gamma_{jl}|(\nu_j(t)u_{jl}^+(t) + \nu_l(t)u_{jl}^-(t)),$$

and write

$$A(t) = -\frac{1}{2} \sum_j \sum_{l \in N_j} \left(\nu_j(t)\mu_{jl}(t) + \nu_l(t)\mu_{lj}(t) \right).$$

Consequently, knowing that $-u_{jl}^+ = u_{lj}^- \leq 0$, we have

$$\begin{aligned} A(t) &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\nu_l(t) - \nu_j(t) \right) \left(u_{jl}^+(t)\nu_j(t) + u_{jl}^-(t)\nu_l(t) \right) \\ &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\nu_l(t) - \nu_j(t) \right) \left(u_{jl}(t)\nu_j(t) + u_{jl}^-(t)(\nu_l(t) - \nu_j(t)) \right) \\ &\leq \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\nu_l(t) - \nu_j(t) \right) \left(u_{jl}(t)\nu_j(t) \right) \\ &= \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} |\mathbf{z}_{jl} - \mathbf{z}_j| \left(\nu_l(t) - \nu_j(t) \right) \left(u_{jl}(t)\nu_j(t) \right), \end{aligned}$$

where we used that $d_{jl} = 2|\mathbf{z}_{jl} - \mathbf{z}_j|$. From the definition of u_{jl} , we conclude that

$$|u_{jl}| \leq |V(t, \mathbf{z}_{jl}) \cdot \bar{\mathbf{n}}_{jl}| \leq \bar{V},$$

where $\bar{V} := \max_{z,t} |V(t, z)|$. This implies

$$\begin{aligned} |A(t)| &\leq \bar{V} \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} |\mathbf{z}_{jl} - \mathbf{z}_j| \left(|\nu_l(t) - \nu_j(t)| \right) \nu_j(t) \\ &= \bar{V} \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} |\mathbf{z}_{jl} - \mathbf{z}_j| \frac{\left(|\nu_l(t) - \nu_j(t)| \right)}{s_{jl}} \nu_j(t) s_{jl} \\ &= \bar{V} \int_D |v_h(t, z)| |n_h(t, z)| dz. \end{aligned}$$

Then, for all $\varepsilon > 0$, Young's inequality implies

$$|A(t)| \leq \bar{V} \left(\frac{\varepsilon}{2} \|v_h\|_{H_h}^2 + 2\varepsilon^{-1} \|n_h\|_{H_h}^2 \right). \quad (3.14)$$

On the other hand

$$\begin{aligned}
D(t) &= \frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_j(t) (\nu_l(t) - \nu_j(t)) + \nu_l(t) (\nu_j(t) - \nu_l(t)) \right) \\
&= -\frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right)^2 \\
&= -\frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} s_{jl} d_{jl}}{|\Gamma_{jl}| |\mathbf{z}_{jl} - \mathbf{z}_j|^2} \frac{|\Gamma_{jl}|^2 |\mathbf{z}_{jl} - \mathbf{z}_j|^2}{d_{jl}^2} \frac{\left(\nu_l(t) - \nu_j(t) \right)^2}{s_{jl}^2} s_{jl}.
\end{aligned}$$

The ellipticity and boundedness of the matrix $A(\theta)$ imply that there exist positive constants $\underline{\alpha}$, $\bar{\alpha}$ such that $\underline{\alpha} \leq A_{jl} \leq \bar{\alpha}$ for all j and l . From this and the value of s_{jl} we deduce that

$$\frac{A_{jl} s_{jl} d_{jl}}{|\Gamma_{jl}| |\mathbf{z}_{jl} - \mathbf{z}_j|^2} = \frac{4A_{jl} h^4}{6h^4} \geq \frac{2\underline{\alpha}}{3},$$

and consequently

$$\begin{aligned}
D(t) &\leq -\frac{\underline{\alpha}}{3} \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|^2 |\mathbf{z}_{jl} - \mathbf{z}_j|^2}{d_{jl}^2} \frac{\left(\nu_l(t) - \nu_j(t) \right)^2}{s_{jl}^2} s_{jl} \\
&= -\frac{\underline{\alpha}}{3} \|v_h\|_{H_h}^2,
\end{aligned} \tag{3.15}$$

notice that the last identity is true since v_h is a piece-wise constant function. Using the L^1 bound from Proposition 3, it is possible to establish

$$R(t) \leq (\bar{r} - \underline{d\rho}) \sum_j h^3 \nu_j^2(t) = (\bar{r} - \underline{d\rho}) \|n_h\|_{H_h}^2. \tag{3.16}$$

Using (3.14), (3.15) and (3.16) in (3.13), with the relation

$$\sum_j h^3 \nu_j(t) \nu_j'(t) = \frac{1}{2} \left(\sum_j h^3 \nu_j^2(t) \right)' = \frac{1}{2} \left(\|n_h\|_{H_h}^2 \right)',$$

yields the differential inequality

$$\frac{1}{2} \left(\|n_h\|_{H_h}^2 \right)' + \left(\frac{\underline{\alpha}}{3} - \frac{\varepsilon \bar{V}}{2} \right) \|v_h\|_{H_h}^2 \leq \left(\frac{\varepsilon^{-1} \bar{V}}{2} + \bar{r} - \underline{d\rho} \right) \|n_h\|_{H_h}^2, \tag{3.17}$$

which, after taking $\varepsilon = \frac{\underline{\alpha}}{3\bar{V}}$ and using Gronwall's lemma, leads to the estimate (3.12). \square

The result of Proposition 4 can be easily generalised if instead of multiplying each equation (3.9) by $h^3 \nu_j(t)$, we multiply by $h^3 \nu_j^{p-1}(t)$, for any $p > 1$, which would lead to the following uniform L^p bound:

Proposition 5 (*L^p bound*) *There exists positive constants a_p and b_p , independent of h , such that the functions $n_h^p(t, z)$ and $v_h^p(t, z)$ defined as*

$$n_h^p(t, z) = \sum_j \nu_j^{p/2}(t) \mathbb{1}_{D_j}(z)$$

$$v_h^p(t, z) = \sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} \left((\mathbf{z}_{jl} - \mathbf{z}_j) \frac{\nu_l^{p/2}(t) - \nu_j^{p/2}(t)}{s_{jl}} \mathbb{1}_{D_{jl}}(z) \right).$$

satisfy the following estimate

$$\|n_h^p\|_{H_h}^2 + a_p \int_0^T \|v_h^p\|_{H_h}^2 \leq e^{b_p T} \|n_0\|_{L^p(D)}^2, \text{ for all } T > 0. \quad (3.18)$$

Before stating the compactness result that will allow us to extract a convergent subsequence from n_h we give two important results that are a consequence from estimate (3.12).

Proposition 6 *For all vectors $\eta \in \mathbb{R}^3$ define the translation operator $\pi_\eta : L^2(\mathbb{R}^3) \rightarrow L^2(\mathbb{R}^3)$ as $\pi_\eta(u)(z) = u(z + \eta)$. Then*

$$\lim_{\eta \rightarrow 0} \|\pi_\eta \bar{n}_h - \bar{n}_h\|_{L^2(\mathbb{R}^3 \times (0, T))} = 0,$$

uniformly in h , where \bar{n}_h represents the extension by 0 of n_h to all of \mathbb{R}^3 .

Proof. The proof of this proposition follows the same steps as Lemma 18.3 and Remark 18.8 in [8]. In particular, thanks to the discrete trace inequality given in the Lemma 10.5 within the same reference, we can prove the existence of a constant C , independent of h and η , such that

$$\|\pi_\eta \bar{n}_h - \bar{n}_h\|_{L^2(\mathbb{R}^3 \times (0, T))}^2 \leq |\eta| C \left(\int_0^T (\|v_h\|_{H_h}^2 + \|n_h\|_{H_h}^2) dt \right),$$

and we get the result from Proposition 6 thanks to (3.12). \square

From now on we introduce the notation $D_T := (0, T) \times D$.

Proposition 7 *There exists a constant C_1 , independent of h , such that for all $\psi \in \mathcal{D}(D_T)$,*

$$\left| \int_0^T \left\langle \frac{d\bar{n}_h}{dt}, \psi \right\rangle_{H^{-3} \times H^3} dt \right| \leq C_1 \sum_{|k| \leq 3} \|\partial_z^k \psi\|_{L^2(D_T)}.$$

Proof. Using the scheme (3.9), we have that, for all $\psi \in \mathcal{D}(D)$

$$\begin{aligned} \left\langle \frac{d\bar{n}_h}{dt}, \psi \right\rangle_{H^{-3} \times H^3} &= \sum_j \frac{d\nu_j(t)}{dt} \int_{D_j} \psi dz \\ &= \sum_j h^3 \left(M_j(t, \tilde{\rho}_h(t)) \nu_j(t) + \sum_{l \in N_j} B_{jl}(t) \nu_l(t) \right) \psi_j, \end{aligned}$$

where $\psi_j = h^{-3} \int_{D_j} \psi dz$ is the mean value of ψ over D_j . Reordering the terms in this equality we have

$$\begin{aligned} \left\langle \frac{d\bar{n}_h}{dt}, \psi \right\rangle_{H^{-3} \times H^3} &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\psi_l - \psi_j \right) \left(u_{jl}^+(t) \nu_j(t) + u_{jl}^-(t) \nu_l(t) \right) \\ &\quad - \frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right) \left(\psi_l - \psi_j \right) \\ &\quad + \sum_j h^3 \left(r_j - d_j \tilde{\rho}_h(t) \right) \nu_j \psi_j \end{aligned}$$

The boundedness of the coefficients A_{jl} , u_{jl} , r_j and d_j , together with the regularity of ψ imply the existence of a constant C independent of h , such that

$$\left| \left\langle \frac{d\bar{n}_h}{dt}, \psi \right\rangle_{H^{-3} \times H^3} \right| \leq C \|\psi\|_{C^1(D)} \left(\|n\|_{H_h} + \|v_h\|_{H_h} \right), \text{ for all } t \in (0, T).$$

Finally, using the inclusions $H^3(D) \subset \mathcal{C}^{1, \frac{1}{2}}(D) \subset \mathcal{C}^1(D)$ that hold true in any open subset of \mathbb{R}^3 with smooth enough boundary thanks to the Sobolev inequalities, integrating over $(0, T)$, using the Cauchy-Schwartz inequality and estimate (3.12), we get to the result stated in the proposition. \square

Proposition 8 *If $n_0 \in L^p(D)$ for some $p > 2$, then there exists a function $n \in L^2(0, T; \mathcal{V})$ such that, up to the extraction of a subsequence, the sequence of functions n_h strongly converges to n in $L^2(D_T)$ and v_h weakly converges to ∇n in $L^2(D_T)$.*

Proof. Propositions 6 and 7 give all the necessary tools in order to ensure the relative compactness of the set of functions $\{n_h\}_h$ in $L^2(D_T)$. In order to prove that such set is indeed compact, we will use a variant adapted to our purposes of the proof of [13, Theorem 3] to show that $\{n_h\}_h$ is a Cauchy sequence in $L^2(D_T)$. We consider a sequence of mollifiers $\Phi_\varepsilon(z) = \varepsilon^{-3} \Phi(\varepsilon^{-1} z)$ for a positive, symmetric function $\Phi \in \mathcal{D}(B(0, 1))$ satisfying $\int_{\mathbb{R}^3} \Phi(z) dz = 1$.

Step 1: We claim that

$$\lim_{\varepsilon \rightarrow 0} \|\Phi_\varepsilon * \bar{n}_h - \bar{n}_h\|_{L^2((0, T) \times \mathbb{R}^3)} = 0,$$

uniformly on h .

We have

$$\begin{aligned} |\Phi_\varepsilon * \bar{n}_h(z) - \bar{n}_h(z)| &\leq \int_{\mathbb{R}^3} |\bar{n}_h(z-y) - \bar{n}_h(z)| \Phi_\varepsilon(y) dy \\ &\leq \int_{\mathbb{R}^3} |\bar{n}_h(z-y) - \bar{n}_h(z)|^2 \Phi_\varepsilon(y) dy, \end{aligned}$$

thanks to the Cauchy-Schwartz inequality. Consequently

$$\begin{aligned} \|\Phi_\varepsilon * \bar{n}_h - \bar{n}_h\|_{L^2((0,T) \times \mathbb{R}^3)} &\leq \int_0^T \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} |\bar{n}_h(z-y) - \bar{n}_h(z)|^2 \Phi_\varepsilon(y) dy dz dt \\ &= \int_{B(0,\varepsilon)} \Phi_\varepsilon(y) \|\pi_{-y} \bar{n}_h - \bar{n}_h\|_{L^2((0,T) \times \mathbb{R}^3)}^2 dy, \end{aligned}$$

and due to Proposition 6, we obtain the strong convergence of $\Phi_\varepsilon * \bar{n}_h$ to \bar{n}_h in $L^2((0,T) \times \mathbb{R}^3)$, uniformly in h .

Step 2: We prove that for every fixed ε and any compact $\omega \subset D$, the sequence $\Phi_\varepsilon * \bar{n}_h$ is uniformly bounded in $H^1((0,T) \times \omega)$.

Thanks to Young's inequality, for a fixed ε ,

$$\|\nabla(\Phi_\varepsilon * \bar{n}_h)\|_{L^2(D_T)} \leq \|\nabla \Phi_\varepsilon\|_{L^2(D)} \|\bar{n}_h\|_{L^1(D_T)} \leq C_\varepsilon \bar{\rho} T.$$

Furthermore, for any compact $\omega \subset D$, $\psi \in \mathcal{D}((0,T) \times \omega)$ and ε small enough, we have $\Phi_\varepsilon * \psi \in \mathcal{D}(D_T)$ and consequently, using Proposition 7 and Young's inequality for the convolution product, we get

$$\begin{aligned} \left| \int_0^T \left\langle \frac{d}{dt} \Phi_\varepsilon * \bar{n}_h, \psi \right\rangle dt \right| &\leq \int_0^T \left| \left\langle \frac{d\bar{n}_h}{dt}, \Phi_\varepsilon * \psi \right\rangle \right| dt \\ &\leq C \sum_{|k| \leq 3} \|\partial_z^k \Phi_\varepsilon * \psi\|_{L^2(D_T)} \\ &\leq C_\varepsilon \|\psi\|_{L^1(D_T)}. \end{aligned}$$

Then, by duality, for a fixed ε , $\frac{d}{dt} \Phi_\varepsilon * \bar{n}_h$ is uniformly bounded in $L^\infty((0,T) \times \omega)$ and we conclude that for each fixed ε , $\Phi_\varepsilon * \bar{n}_h$ is uniformly bounded in $H^1((0,T) \times \omega)$.

Step 3: We claim that, for all compacts $\omega \subset D$, the sequence \bar{n}_h is a Cauchy sequence in $L^2((0,T) \times \omega)$.

Write

$$\bar{n}_{h_1} - \bar{n}_{h_2} = (\bar{n}_{h_1} - \Phi_\varepsilon * \bar{n}_{h_1}) + (\Phi_\varepsilon * \bar{n}_{h_1} - \Phi_\varepsilon * \bar{n}_{h_2}) + (\Phi_\varepsilon * \bar{n}_{h_2} - \bar{n}_{h_2}).$$

Thanks to *Step 1*, for all $\eta > 0$, we can fix ε in such a way that

$$\begin{aligned}\|\bar{n}_{h_1} - \Phi_\varepsilon * \bar{n}_{h_1}\|_{L^2((0,T) \times \omega)} &< \eta/3, \\ \|\Phi_\varepsilon * \bar{n}_{h_2} - \bar{n}_{h_2}\|_{L^2((0,T) \times \omega)} &< \eta/3.\end{aligned}$$

Thanks to *Step 2* and Rellich-Kondrachov's theorem, we know that for a fixed ε , $\Phi_\varepsilon * \bar{n}_h$ is a Cauchy sequence in $L^2((0,T) \times \omega)$, hence, for h_1 and h_2 close enough

$$\|\Phi_\varepsilon * \bar{n}_{h_1} - \Phi_\varepsilon * \bar{n}_{h_2}\|_{L^2((0,T) \times \omega)} < \eta/3$$

Consequently, for all positive $\eta > 0$, there exists h_1 and h_2 such that

$$\|\bar{n}_{h_1} - \bar{n}_{h_2}\|_{L^2((0,T) \times \omega)} < \eta,$$

which proves that \bar{n}_h is a Cauchy sequence.

Step 4: The sequence \bar{n}_h is a Cauchy sequence in $L^2(D_T)$.

Fix a natural number m , define $\omega_m := \{z \in D : d(z, \partial D) \geq 1/m\}$, $\omega_m^T := (0, T) \times \omega_m$ and write

$$\begin{aligned}\|\bar{n}_{h_1} - \bar{n}_{h_2}\|_{L^2(D_T)} &= \|\bar{n}_{h_1} - \bar{n}_{h_2}\|_{L^2(\omega_m^T)} + \|\bar{n}_{h_1} - \bar{n}_{h_2}\|_{L^2((0,T) \times (D \setminus \omega_m))} \\ &\leq \|\bar{n}_{h_1} - \bar{n}_{h_2}\|_{L^2(\omega_m^T)} + 2 \sup_h \|n_h\|_{L^2((0,T) \times (D \setminus \omega_m))} \quad (3.19)\end{aligned}$$

Taking $q > 1$ and using Hölder's inequality we have

$$\begin{aligned}\|n_h\|_{L^2((0,T) \times (D \setminus \omega_m))}^2 &= \int_0^T \int_{D \setminus \omega_m} n_h^2 dz dt \\ &\leq \int_0^T \|(n_h)^q\|_{L^2(D)} dt |D \setminus \omega_m|^{1/q^*}.\end{aligned}$$

Hence, for $q = p/2$, thanks to (3.18), we can conclude that $\sup_h \|n_h\|_{L^2((0,T) \times (D \setminus \omega_m))}$ goes to 0 when m goes to infinity. Consequently, for all $\eta > 0$, we can fix m big enough so that the second term in (3.19) is smaller than $\eta/2$ and then, thanks to *Step 3*, we can choose h_1 and h_2 in such a way that the first term is also smaller than $\eta/2$, which proves that $\{n_h\}_h$ is a Cauchy sequence in $L^2(D_T)$.

Step 5: Let n be the limit of a suitable subsequence of n_h and v the weak limit of v_h (such limit exists due to the fact that v_h is bounded in $L^2(D_T)$). We claim that $n \in L^2(0, T; \mathcal{V})$ and $v = \nabla n$.

For all $\phi(t, z) \in \mathcal{C}([0, T]; \mathcal{D}(D))$, the convergence of n_h to n implies that

$$\int_0^T \int_D n(t, z) \partial_i \phi(t, z) dz dt = \lim_{h \rightarrow 0} \int_0^T \int_D n_h(t, z) \partial_i \phi(t, z) dz dt, \quad (3.20)$$

where $\partial_1\phi(z) = \partial_x\phi(z)$, $\partial_2\phi(z) = \partial_y\phi(z)$ and $\partial_3\phi(z) = \partial_\theta\phi(z)$. Writing $\partial_i\phi(z) = \nabla \cdot (\phi(t, z)\mathbf{e}_i)$, where $\{\mathbf{e}_i\}$ is the euclidian canonical basis, we have that

$$\begin{aligned} \int_D n_h(t, z) \partial_i \phi(t, z) dz &= \sum_j \nu_j(t) \int_{D_j} \nabla \cdot (\phi(t, z) \mathbf{e}_i) dz \\ &= \sum_j \nu_j(t) \sum_{l \in N_j} \int_{\Gamma_{jl}} \phi(t, z) \mathbf{e}_i \cdot \mathbf{n}_{jl} dS \\ &= \sum_j \sum_{l \in N_j} \nu_j(t) \int_{\Gamma_{jl}} \phi(t, z) n_{jl}^i dS. \end{aligned}$$

Therefore, we obtain

$$\int_D n_h(t, z) \nabla \phi(t, z) dz = \sum_j \sum_{l \in N_j} \nu_j(t) \int_{\Gamma_{jl}} \phi(t, z) \mathbf{n}_{jl} dS.$$

Using an estimate similar to (3.5) for the integral over Γ_{jl} , and using the fact that $|\Gamma_{jl}| = \mathcal{O}(h^2)$ and the amount of cells on the mesh is $\mathcal{O}(h^{-3})$, we have

$$\int_D n_h(t, z) \nabla \phi(t, z) dz = \sum_j \sum_{l \in N_j} \nu_j(t) |\Gamma_{jl}| \phi(t, \mathbf{z}_{jl}) \mathbf{n}_{jl} + \mathcal{O}(h). \quad (3.21)$$

Reordering the terms of this last sum, we have

$$\begin{aligned} \sum_j \sum_{l \in N_j} \nu_j(t) |\Gamma_{jl}| \phi(t, \mathbf{z}_{jl}) \mathbf{n}_{jl} &= \frac{1}{2} \sum_j \sum_{l \in N_j} \left(\nu_j(t) |\Gamma_{jl}| \phi(t, \mathbf{z}_{jl}) \mathbf{n}_{jl} + \nu_l(t) |\Gamma_{lj}| \phi(t, \mathbf{z}_{lj}) \mathbf{n}_{lj} \right) \\ &= -\frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \mathbf{n}_{jl} \left(\nu_l(t) - \nu_j(t) \right) \phi(t, \mathbf{z}_{jl}) \\ &= -\sum_j \sum_{l \in N_j} \frac{|\Gamma_{jl}|}{d_{jl}} (\mathbf{z}_{jl} - \mathbf{z}_j) \frac{(\nu_l(t) - \nu_j(t))}{s_{jl}} \phi(t, \mathbf{z}_{jl}) s_{jl} \\ &= -\int_D v_h(z) \phi_h(t, z) dz, \end{aligned} \quad (3.22)$$

where

$$\phi_h(t, z) = \sum_j \sum_{l \in N_j} \phi(t, \mathbf{z}_{jl}) \mathbb{1}_{D_{jl}}(z).$$

This function strongly converges in $L^2(D_T)$ to ϕ . Substituting (3.22) in (3.21) and then in (3.20), and using the weak convergence of v_h to v , we obtain that, for all $\phi \in \mathcal{C}([0, T]; \mathcal{D}(D))$

$$\int_0^T \int_D n(t, z) \partial_i \phi(t, z) dz dt = - \int_0^T \int_D v^i(t, z) \phi(t, z) dz dt.$$

Taking $\phi(t, z) = \varphi(z)\chi(t)$, with $\varphi \in \mathcal{D}(D)$ and $\chi(t) \in \mathcal{C}([0, T])$, this last equality becomes

$$\int_0^T \int_D n(t, z) \partial_i \varphi(z) dz \chi(t) dt = - \int_0^T \int_D v^i(t, z) \varphi(z) dz \chi(t) dt,$$

for all $\varphi \in \mathcal{D}(D)$ and $\chi(t) \in \mathcal{C}([0, T])$, which implies that for each $\varphi \in \mathcal{D}(D)$

$$\int_D n(t, z) \partial_i \varphi(z) dz = - \int_D v^i(t, z) \varphi(z) dz, \text{ a.e. } [0, T].$$

The separability of $\mathcal{D}(D)$ finally implies that

$$\int_D n(t, z) \partial_i \varphi(z) dz = - \int_D v^i(t, z) \varphi(z) dz, \quad \forall \varphi \in \mathcal{D}(D), \text{ a.e. } [0, T].$$

As $v(t, z) \in L^2(D)$ for almost all $t \in [0, T]$, $n(t, z)$ belongs to \mathcal{V} for almost all $t \in [0, T]$, which proves the statements of the Proposition. \square

An immediate consequence of Proposition 8, together with estimate (3.12) is that

$$\|n\|_H^2 + a \int_0^T \|v\|_H^2 \leq e^{bT} \|n_0\|_H^2, \text{ for all } T > 0. \quad (3.23)$$

We can also deduce from Proposition 8 that the sequence of functions $\rho_h(t)$ strongly converges to $\rho(t) := \int_D n(t, z) dz$ in $L^2((0, T))$.

3.4 Existence of weak solution

This section is devoted to prove that the function n is a weak solution of problem (2.1)-(2.2).

Proposition 9 *The function n satisfies*

$$-\langle n_0, \varphi(0) \rangle = \int_0^T \langle Q[n], \varphi \rangle + \langle \varphi'(t), n \rangle dt, \quad (3.24)$$

for all $\varphi \in \mathcal{C}_c^1([0, T], \mathcal{V})$.

Proof. First consider $\varphi \in \mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3))$, and for each j , multiply equation (3.9) by $h^3 \varphi_j(t) := h^3 \varphi(t, \mathbf{z}_j)$, and add them up for all j , obtaining the relation

$$\sum_j h^3 \nu_j'(t) \varphi_j(t) = A_\varphi(t) + D_\varphi(t) + R_\varphi(t),$$

where

$$\begin{aligned} A_\varphi(t) &= - \sum_j \varphi_j(t) \sum_{l \in N_j} |\Gamma_{jl}| \left(\nu_j(t) u_{jl}^+(t) + \nu_l(t) u_{jl}^-(t) \right), \\ D_\varphi(t) &= \sum_j \varphi_j(t) \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right), \\ R_\varphi(t) &= \sum_j h^3 \left(r_j - d_j \sum_l h^3 \nu_l(t) \right) \nu_j(t) \varphi_j(t). \end{aligned}$$

Reordering the terms from $A_\varphi(t)$, we get

$$\begin{aligned} A_\varphi(t) &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\varphi_l(t) - \varphi_j(t) \right) \left(u_{jl}^+(t) \nu_j(t) + u_{jl}^-(t) \nu_l(t) \right) \\ &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\varphi_l(t) - \varphi_j(t) \right) \left(u_{jl}(t) \nu_j(t) + u_{jl}^-(t) (\nu_l(t) - \nu_j(t)) \right) \\ &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\varphi_l(t) - \varphi_j(t) \right) u_{jl}(t) \nu_j(t) + A_\varphi^1(t), \end{aligned} \quad (3.25)$$

where

$$A_\varphi^1(t) = \frac{1}{2} \sum_j \sum_{l \in N_j} u_{jl}^-(t) |\Gamma_{jl}| \left(\varphi_l(t) - \varphi_j(t) \right) \left(\nu_l(t) - \nu_j(t) \right).$$

Thanks to the boundedness of u_{jl} and the regularity of φ , this term satisfies

$$\begin{aligned} |A_\varphi^1(t)| &\leq \frac{\bar{V}}{2} \|\nabla_z \varphi\|_{L^\infty(\mathbb{R}^3)} h \sum_j \sum_{l \in N_j} |\Gamma_{jl}| |\nu_l(t) - \nu_j(t)| \\ &= h \bar{V} \|\nabla_z \varphi\|_{L^\infty(\mathbb{R}^3)} \|v_h\|_{L^1(D_h)} \\ &\leq h |D_h|^{1/2} \bar{V} \|\nabla_z \varphi\|_{L^\infty(\mathbb{R}^3)} \|v_h\|_{L^2(D_h)}. \end{aligned} \quad (3.26)$$

Recalling the definition of u_{jl} and the property (3.1), we get from (3.25)

$$\begin{aligned} A_\varphi(t) &= \frac{1}{2} \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \frac{(\varphi_l(t) - \varphi_j(t))}{d_{jl}} V_{jl}(t) \cdot (\mathbf{z}_l - \mathbf{z}_j) \nu_j(t) + A_\varphi^1(t), \\ &= \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \frac{(\varphi_l(t) - \varphi_j(t))}{d_{jl}} V_{jl}(t) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t) + A_\varphi^1(t), \end{aligned}$$

Defining $V_j(t) := V(t, \mathbf{z}_j)$ allows us to write

$$A_\varphi(t) = \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \frac{(\varphi_l(t) - \varphi_j(t))}{d_{jl}} V_j(t) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t) + A_\varphi^1 + A_\varphi^2(t),$$

with

$$A_\varphi^2(t) = \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \frac{(\varphi_l(t) - \varphi_j(t))}{d_{jl}} (V_{jl}(t) - V_j(t)) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t).$$

Thanks to the regularity of φ and V , we have

$$\begin{aligned} |A_\varphi^2(t)| &\leq \frac{h}{4} \|\nabla_z \varphi\|_{L^\infty(\mathbb{R}^3)} \|\nabla_z V\|_{L^\infty(\mathbb{R}^3)} \sum_j \sum_{l \in N_j} h^3 \nu_j(t) \\ &\leq \frac{h}{4} |D_h|^{1/2} \|\nabla_z \varphi\|_{L^\infty(\mathbb{R}^3)} \|\nabla_z V\|_{L^\infty(\mathbb{R}^3)} \|n_h\|_{L^2(D_h)}. \end{aligned} \quad (3.27)$$

Finally, we write

$$\begin{aligned} A_\varphi(t) &= \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\nabla \varphi(\mathbf{z}_j) \cdot \mathbf{n}_{jl} \right) V_j(t) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t) \\ &\quad + A_\varphi^1(t) + A_\varphi^2(t) + A_\varphi^3(t) \\ &:= A_\varphi^0(t) + A_\varphi^1(t) + A_\varphi^2(t) + A_\varphi^3(t), \end{aligned}$$

where

$$A_\varphi^3(t) = \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\frac{(\varphi_l(t) - \varphi_j(t))}{d_{jl}} - \nabla \varphi(\mathbf{z}_j) \cdot \mathbf{n}_{jl} \right) V_j(t) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t).$$

Again, the regularity of φ and the boundedness of V imply

$$|A_\varphi^3| \leq \frac{h}{4} \bar{V} |D_h|^{1/2} \|\nabla_z^2 \varphi\|_{L^\infty(\mathbb{R}^3)} \|n_h\|_{L^2(D_h)}.$$

And this together with (3.26), (3.27) and estimate (3.12) ensures that there exists a constant C_A independent of h such that

$$\int_0^T |A_\varphi^1(t) + A_\varphi^2(t) + A_\varphi^3(t)| dt \leq C_A h.$$

On the other hand, we can rewrite the remaining term as

$$\begin{aligned} A_\varphi^0(t) &= \sum_j \sum_{l \in N_j} |\Gamma_{jl}| \left(\nabla \varphi(\mathbf{z}_j) \cdot \mathbf{n}_{jl} \right) V_j(t) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \nu_j(t) \\ &= \sum_j \nu_j(t) V_j(t) \cdot \sum_{l \in N_j} |\Gamma_{jl}| \left(\nabla \varphi(\mathbf{z}_j) \cdot \mathbf{n}_{jl} \right) (\mathbf{z}_{jl} - \mathbf{z}_j). \end{aligned}$$

In [7], it was proven that

$$\sum_{l \in N_j} |\Gamma_{jl}| \left(\nabla \varphi(\mathbf{z}_j) \cdot \mathbf{n}_{jl} \right) (\mathbf{z}_{jl} - \mathbf{z}_j) = h^3 \nabla \varphi(\mathbf{z}_j),$$

consequently

$$A_\varphi^0(t) = \sum_j \nu_j(t) V_j(t) \cdot \nabla \varphi(\mathbf{z}_j) h^3 = \int_D n_h(t) \left(V \cdot \nabla \varphi \right)_h(t),$$

where

$$\left(V \cdot \nabla \varphi \right)_h(t) := \sum_j V_j(t) \cdot \nabla \varphi(\mathbf{z}_j) \mathbb{1}_{D_j}(z).$$

Moreover, the sequence $\left(V \cdot \nabla \varphi \right)_h(t)$ strongly converges to $V \cdot \nabla \varphi$ in $L^2(D_T)$, which implies that

$$\int_0^T A_\varphi(t) dt \longrightarrow \int_0^T \int_D n V \cdot \nabla \varphi dz dt, \text{ for all } \varphi \in \mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3)). \quad (3.28)$$

Reordering as well the terms from D_φ , we get

$$\begin{aligned} D_\varphi(t) &= -\frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right) \left(\varphi_l(t) - \varphi_j(t) \right) \\ &= -\frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right) \left(\nabla \varphi(\mathbf{z}_{jl}) \cdot (\mathbf{z}_l - \mathbf{z}_j) \right) + D_\varphi^1(t) \\ &= -\sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right) \left(\nabla \varphi(\mathbf{z}_{jl}) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \right) + D_\varphi^1(t) \end{aligned}$$

where

$$D_\varphi^1(t) = -\frac{1}{2} \sum_j \sum_{l \in N_j} \frac{A_{jl} |\Gamma_{jl}|}{d_{jl}} \left(\nu_l(t) - \nu_j(t) \right) \left(\varphi_l(t) - \varphi_j(t) - \nabla \varphi(\mathbf{z}_{jl}) \cdot (\mathbf{z}_l - \mathbf{z}_j) \right).$$

Thanks to the boundedness of the coefficients A_{jl} and the regularity of φ we get

$$|D_\varphi^1| \leq h |D_h|^{1/2} \frac{\bar{\alpha}}{4} \|\nabla_z^2 \varphi\|_{L^\infty(\mathbb{R}^3)} \|v_h\|_{L^2(D_h)}. \quad (3.29)$$

Recalling the definition of A_{jl} , the fact that $A(\theta)$ is a diagonal matrix and the normal vectors to the boundary of D_j are elements of the canonical euclidean basis or their opposites, we have that, for all j and l

$$A_{jl} \left(\nabla \varphi(\mathbf{z}_{jl}) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j) \right) = \left(A(\theta_{jl}) \nabla \varphi(\mathbf{z}_{jl}) \right) \cdot (\mathbf{z}_{jl} - \mathbf{z}_j).$$

Consequently, we infer that

$$D_\varphi(t) = - \int_D v_h \cdot \left(A(\theta) \nabla \varphi(z) \right)_h dz + D_\varphi^1(t),$$

where

$$\left(A(\theta) \nabla \varphi(z) \right)_h(t) := \sum_j \sum_{l \in N_j} A(\theta_{jl}) \nabla \varphi(\mathbf{z}_{jl}) \mathbb{1}_{D_{jl}}(z)$$

strongly converges to $A(\theta) \nabla \varphi(z)$ in $\left(L^2(D_T) \right)^3$. The regularity of φ , the boundedness of v_h in $L^2(D_T)$ and (3.29) guarantee the existence of C_D such that

$$\int_0^T |D_\varphi^1(t)| dt \leq C_D h,$$

so that, consequently,

$$\int_0^T D(t) dt \longrightarrow \int_0^T \int_D A(\theta) \nabla n \nabla \varphi dz dt, \text{ for all } \varphi \in \mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3)). \quad (3.30)$$

The sequence of functions

$$R_h(t, z) = \sum_j \left(r_j - d_j \rho_h(t) \right) \mathbb{1}_{D_j}(z),$$

belongs to $L^\infty(D_T)$ and strongly converges in $L^2(D_T)$ to $r(z) - d(z) \rho(t)$, which implies that

$$\int_0^T R_\varphi(t) dt \longrightarrow \int_0^T \int_D \left(r(z) - d(z) \rho(t) \right) n \varphi dt, \text{ for all } \varphi \in \mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3)). \quad (3.31)$$

Finally, we conclude that

$$\begin{aligned} \int_0^T \sum_j h^3 \nu_j'(t) \varphi_j(t) dt &= \sum_j h^3 \int_0^T \nu_j'(t) \varphi_j(t) dt \\ &= - \sum_j h^3 \left(\nu_j(0) \varphi_j(0) + \int_0^T \nu_j(t) \varphi_j'(t) dt \right), \end{aligned}$$

which converges to

$$- \int_D n_0 \varphi(0) dz - \int_0^T \int_D n(t, z) \varphi'(t, z) dz dt.$$

Putting this result together with (3.28), (3.30) and (3.31), we get that, for all $\varphi \in \mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3))$

$$-\langle n_0, \varphi(0) \rangle = \int_0^T \langle Q[n], \varphi \rangle + \langle \varphi'(t), n \rangle dt. \quad (3.32)$$

As $\mathcal{C}_c^1([0, T], \mathcal{C}_c^\infty(\mathbb{R}^3))$ is dense in $\mathcal{C}_c^1([0, T], H^1(\omega))$ for all compacts $\omega \subset D$, and the functions n and ∇n belong to $L^2(D_T)$, (3.32) also holds for all $\varphi \in \mathcal{C}_c^1([0, T], \mathcal{V})$. \square

Proposition 10 *The function n belongs to $H^1((0, T); \mathcal{V}')$.*

Proof: Taking $\varphi := \chi(t)\psi(z)$ with $\chi \in \mathcal{D}((0, T))$ and $\psi \in \mathcal{V}$ in equation (3.24), we get

$$\left\langle \int_0^T n \chi' dt, \psi \right\rangle = \int_0^T \langle \psi \chi', n \rangle dt = - \int_0^T \langle Q[n], \varphi \rangle dt = - \left\langle \int_0^T Q[n] \chi dt, \psi \right\rangle.$$

As this holds true for all $\psi \in \mathcal{V}$, this equation is equivalent with

$$\int_0^T n \chi' dt = - \int_0^T Q[n] \chi dt \text{ in } \mathcal{V}' \text{ for any } \chi \in \mathcal{D}((0, T)).$$

or in other words

$$\partial_t n = Q[n] \text{ in the sense of distributions in } \mathcal{V}'.$$

The estimate (3.23) implies that $Q[n] \in L^2((0, T); \mathcal{V}')$, consequently, n belongs to $H^1((0, T); \mathcal{V}')$. \square

Proposition 11 *The function n belongs to $\mathcal{C}([0, T], L^2(D))$.*

Proof. From Proposition 6 we have that $n \in L^2((0, T), \mathcal{V})$. Define $\bar{n}(t, z) = n(t, z) \mathbb{1}_{[0, T]}(t)$ and the approximation to the identity sequence

$$\Phi_\varepsilon(t) := \varepsilon^{-1} \Phi(\varepsilon^{-1} t),$$

where $\Phi(t)$ is a mollifier with compact support included in $(-1, -1/2)$. The sequence $n_\varepsilon(t) := n * \Phi_\varepsilon$ belongs to $\mathcal{C}^1(\mathbb{R}, \mathcal{V})$, $n_\varepsilon \rightarrow n$ a.e. on $[0, T]$ and in $L^2((0, T), \mathcal{V})$. For a fixed $\tau \in (0, T)$ and for any $t \in (0, \tau)$ and any $0 < \varepsilon < T - \tau$, we have $s \rightarrow \Phi_\varepsilon(t - s) \in \mathcal{D}(0, T)$, since $\text{supp} \Phi_\varepsilon(t - \cdot) \subset [t + \varepsilon/2, t + \varepsilon] \subset [\varepsilon/2, \tau + \varepsilon]$. Therefore, we get

$$\begin{aligned} n'_\varepsilon &= \int_{\mathbb{R}} \partial_t \Phi_\varepsilon(t - s) \bar{n}(s) ds \\ &= - \int_0^T \partial_s \Phi_\varepsilon(t - s) n(s) ds = \int_0^T \Phi_\varepsilon(t - s) n'(s) ds = \Phi_\varepsilon * \bar{n}'. \end{aligned}$$

As a consequence $n'_\varepsilon \rightarrow n'$ a.e. and in $L^2((0, \tau), \mathcal{V}')$. Now fix $\tau \in (0, T)$ and $\varepsilon, \varepsilon' \in (0, T - \tau)$, and compute

$$\frac{d}{dt} \|n_\varepsilon(t) - n_{\varepsilon'}(t)\|_H^2 = 2 \langle n'_\varepsilon - n'_{\varepsilon'}, n_\varepsilon - n_{\varepsilon'} \rangle_{\mathcal{V}' \times \mathcal{V}},$$

so that for any $t_1, t_2 \in [0, \tau]$

$$\|n_\varepsilon(t_2) - n_{\varepsilon'}(t_1)\|_H^2 = \|n_\varepsilon(t_1) - n_{\varepsilon'}(t_1)\|_H^2 + 2 \int_{t_1}^{t_2} \langle n'_\varepsilon - n'_{\varepsilon'}, n_\varepsilon - n_{\varepsilon'} \rangle dt.$$

Since $n_\varepsilon \rightarrow n$ a.e. in $[0, \tau]$ in V , fix t_1 such that $n_\varepsilon(t_1) \rightarrow n(t_1)$ in V , so as a consequence of $n_\varepsilon \rightarrow n$ in $L^2((0, T), \mathcal{V})$ and $n'_\varepsilon \rightarrow n'$ in $L^2((0, \tau), \mathcal{V}')$ we have

$$\limsup_{\varepsilon, \varepsilon' \rightarrow 0} \sup_{[0, \tau]} \|n_\varepsilon - n_{\varepsilon'}\|_H^2 \leq \lim_{\varepsilon, \varepsilon' \rightarrow 0} \int_0^\tau \|n'_\varepsilon - n'_{\varepsilon'}\|_{\mathcal{V}'} \|n_\varepsilon - n_{\varepsilon'}\|_{\mathcal{V}} ddt = 0.$$

So that n_ε is a Cauchy sequence in $\mathcal{C}([0, \tau], L^2(D))$, and then n_ε converges in $\mathcal{C}([0, \tau], L^2(D))$ to a limit $\tilde{n} \in \mathcal{C}([0, \tau], L^2(D))$. That proves $n = \tilde{n}$ a.e. and $n \in \mathcal{C}([0, \tau], L^2(D))$. Similarly can be proven that $n \in \mathcal{C}([\tau, T], L^2(D))$, and consequently $n \in \mathcal{C}([0, T], L^2(D))$. \square

Proposition 12 *The function n is a weak solution of problem (2.1)-(2.2).*

Proof. Assume first $\varphi \in \mathcal{C}_c([0, T], H) \cap L^2((0, T), \mathcal{V}) \cap H^1([0, T], \mathcal{V}')$. We define $\varphi_\varepsilon(t) = \varphi *_t \Phi_\varepsilon$ for a mollifier Φ_ε with compact support included in $(0, \infty)$ so that $\varphi_\varepsilon \in \mathcal{C}_c^1([0, T]; \mathcal{V})$ for any $\varepsilon > 0$ small enough and

$$\varphi_\varepsilon \rightarrow \varphi \text{ in } \mathcal{C}([0, T], H) \cap L^2((0, T), \mathcal{V}) \cap H^1([0, T], \mathcal{V}').$$

Writing the equation (3.24) for φ_ε and passing to the limit $\varepsilon \rightarrow 0$ we get that (3.24) also holds true for φ .

Assume now $\varphi \in X_T = \mathcal{C}([0, T], H) \cap L^2((0, T), \mathcal{V}) \cap H^1([0, T], \mathcal{V}')$. Fix $\chi \in \mathcal{C}^1(\mathbb{R})$, such that $\text{supp } \chi \subset (-\infty, 0)$, $\chi' \leq 0$, $\chi' \in \mathcal{C}_c((-1, 0))$, and such that the integral of χ' is -1 . For example, fix $\delta < 1/2$ and define

$$\chi(s) = \begin{cases} 1 & \text{if } s \leq -1 + \delta \\ \frac{1}{2}(1 + \cos(\frac{\pi(t+1-\delta)}{1-2\delta})) & \text{if } -1 + \delta \leq s \leq -\delta \\ 0 & \text{if } s \geq -\delta \end{cases}$$

Now define $\chi_\varepsilon^t = \chi(\frac{s-t}{\varepsilon})$, so that $\varphi_\varepsilon := \varphi \chi_\varepsilon^t \in \mathcal{C}_c([0, T]; H)$ and $\chi_\varepsilon^t \rightarrow \mathbf{1}_{[0, t]}$, $(\chi_\varepsilon^t)' \rightarrow -\delta_t$ as $\varepsilon \rightarrow 0$. Equation (3.24) for the function φ_ε writes

$$-(n_0, \varphi(0)) - \int_0^T (n, \varphi(s)) (\chi_\varepsilon^t)' ds = \int_0^T \chi_\varepsilon^t \left(\langle Q[n](s), \varphi(s) \rangle + \langle \varphi'(s), n \rangle \right) ds.$$

Passing to the limit when ε goes to 0 we obtain that n is a solution for the variational formulation. \square

3.5 A discrete implicit scheme

Once we have established the proof of existence of a solution for problem (3.9)-(3.10), together with the obtention of a semi-discrete scheme in order to approximate such solution, we proceed to derive an implicit discrete scheme starting from problem (3.9)-(3.10), and to prove its convergence.

Consider a natural number K and define $\Delta t = \frac{T}{K}$ and $t_k = k\Delta t$, $\nu_j^k := \nu_j(t_k)$, $k = 1, \dots, K$. Using a forward difference approximation for the time derivative in (3.9) we get the implicit scheme

$$\frac{\nu_j^{k+1} - \nu_j^k}{\Delta t} = M_j^{k+1} \nu_j^{k+1} + \sum_{l \in N_j} B_{jl}^{k+1} \nu_l^{k+1}, \quad (3.33)$$

where

$$M_j^{k+1} := M_j(t_{k+1}) = -\frac{|G_{jl}|}{h^3} \sum_{l \in N_j} \left(u_{jl}^+(t_{k+1}) + \frac{A_{jl}}{d_{jl}} \right) + \left(r_j - d_j \sum_l h^3 \nu_l^{k+1} \right),$$

$$B_{jl}^{k+1} := B_{jl}(t_{k+1}) = \frac{|G_{jl}|}{h^3} \left(-u_{jl}^-(t_{k+1}) + \frac{A_{jl}}{d_{jl}} \right).$$

Theorem 3 *Let ν_j^0 be non-negative initial data with mass $\rho_0 = \sum_j h^3 \nu_j^0$ and assume that*

$$\Delta t(r^+ + d^+ \bar{\rho}) < \frac{1}{4},$$

then there exists a unique non-negative solution ν_j^k , $k = 1, \dots, N$ to scheme (3.33). Furthermore, for each h , the sequence of piecewise constant functions

$$\nu_{\Delta t}^j(t) = \sum_{k=0}^K \nu_j^k \mathbb{1}_{(t_k, t_{k+1})},$$

strongly converges to the solution of (3.9)-(3.10) in $(L^2((0, T)))^N$ when Δt goes to 0.

Proof. As $\Delta t(r^+ + d^+ \bar{\rho}) < \frac{1}{4}$, there exists a positive constant $\lambda < 1$ such that

$$\Delta t < \frac{\lambda}{r^+ + d^+ \bar{\rho}_\lambda}, \quad (3.34)$$

where $\bar{\rho}_\lambda = \frac{\bar{\rho}}{1-\lambda}$. Consider the set

$$\mathcal{X} = \{\eta \in \mathbb{R}^M : \eta_j \geq 0 \forall j, \|\eta\|_1 = \sum_j h^3 \eta_j \leq \bar{\rho}_\lambda\},$$

and assume $\nu^k \in \mathbb{R}^M$ to be the solution of (3.33) for a previous iteration, having all non-negative components and satisfying $\sum_j h^3 \nu_j^k \leq \bar{\rho}$. Define the

operator $\nu = F(\eta) : \mathcal{X} \rightarrow \mathbb{R}^M$ as the solution of the linear system

$$M(\eta)\nu = \nu^k, \quad (3.35)$$

where the components of matrix $M(\eta)$ are defined as

$$M_{jl}(\eta) = \begin{cases} -\Delta t B_{jl}^{n+1}, & \text{if } l \in N_j, \\ 1 + \Delta t \left(\frac{|I_{jl}|}{h^3} \sum_{l \in N_j} \left(u_{jl}^+(t_{n+1}) + \frac{A_{jl}}{d_{jl}} \right) - (r_j - d_j \|\eta\|_1) \right) & \text{if } j = l. \end{cases}$$

From the definition of \mathcal{X} and the choice of Δt we have that $M_{jl}(\eta)$ is positive for all η if $j = l$, and non-positive if $j \neq l$. Furthermore $M(\eta)$ is a column-dominant matrix, so that we may conclude that $M(\eta)$ is an M -matrix, which implies that its inverse exists and has only non-negative entries. As ν^k has all non-negative components, then $\nu = F(\eta)$ also has non-negative components for all $\eta \in \mathcal{X}$. Multiplying system (3.35) by h^3 and adding up all equations, thanks to (3.34) we obtain

$$\begin{aligned} \sum_j h^3 \nu_j &= \sum_j h^3 \nu_j^k + \Delta t \sum_j h^3 (r_j - d_j \|\eta\|_1) \nu_j \\ &\leq \bar{\rho} + \Delta t (r^+ + d^+ \bar{\rho}_\lambda) \sum_j h^3 \nu_j \\ &< \bar{\rho} + \lambda \sum_j h^3 \nu_j. \end{aligned}$$

This implies that $\sum_j h^3 \nu_j < \bar{\rho}_\lambda$ and consequently, $F(\eta)$ is a continuous application going from \mathcal{X} to itself, and thanks to Brouwer's fixed point theorem, $F(\eta)$ has at least a fixed point on \mathcal{X} . Furthermore, a fixed point of $F(\eta)$ will satisfy

$$\sum_j h^3 \nu_j = \sum_j h^3 \nu_j^k + \Delta t \sum_j h^3 (r_j - d_j \|\nu\|_1) \nu_j$$

which in turn implies $\|\nu\|_1 \leq \bar{\rho}$. As a consequence, the implicit Euler scheme satisfies

$$\|\nu^k\|_1 \leq \bar{\rho} \quad \text{for all } k. \quad (3.36)$$

For the uniqueness, assume there exists two different solutions ν and μ to scheme (3.33). Let us denote the sign of $\beta \in \mathbb{R}$ as $\text{sign}(\beta)$. Taking the difference for each equation, multiplying by $h^3 \text{sign}(\nu_j - \mu_j)$, adding up all the equations and recalling that

$$\sum_{l \in N_j} B_{jl}^{n+1} = \frac{|I_{jl}|}{h^3} \sum_{l \in N_j} \left(u_{jl}^+(t_{n+1}) + \frac{A_{jl}}{d_{jl}} \right),$$

we obtain that

$$\begin{aligned} \sum_j h^3 |\nu_j - \mu_j| &= \Delta t \sum_j h^3 \left((r_j - d_j \|\nu\|_1) |\nu_j - \mu_j| \right. \\ &\quad \left. + d_j \operatorname{sign}(\nu_j - \mu_j) (\|\nu\|_1 - \|\mu\|_1) \mu_j \right) \\ &\leq \Delta t (r^+ + d^+ \bar{\rho}) \sum_j h^3 |\nu_j - \mu_j|. \end{aligned}$$

The condition over Δt then implies that $\|\nu - \mu\|_1 = 0$ and consequently $\nu = \mu$. To prove the convergence of $\nu_{\Delta t}^j$ to ν_j , we define the sequences of continuous functions

$$\mu_{\Delta t}^j(t) = \sum_{k=1}^K \frac{(t - t_k) \nu_j^{k+1} + (t_{k+1} - t) \nu_j^k}{\Delta t} \mathbb{1}_{(t_k, t_{k+1})}.$$

These sequences are in $\mathcal{C}([0, T])$ and are uniformly bounded because for all values of j and k , $\nu_j^k \leq \frac{\bar{\rho}}{h^3}$ due to (3.36). Furthermore, thanks to (3.33)

$$|\mu_{\Delta t}^j - \nu_{\Delta t}^j| \leq \max_k |\nu_j^{k+1} - \nu_j^k| = \Delta t \max_k |M_j^{k+1} \nu_j^{k+1} + \sum_{l \in N_j} B_{jl}^{k+1} \nu_l^{k+1}| \leq C \Delta t,$$

where C is independent of Δt . Consequently, for each j , when Δt goes to 0 both sequences $\nu_{\Delta t}^j$ and $\mu_{\Delta t}^j$ strongly converge in $L^2((0, T))$ to a certain continuous functions $\nu_j^*(t)$.

We consider now a function $\varphi \in \mathcal{C}_0^1((0, T))$ and we define $\varphi_k := \varphi(t_k)$. For all k , multiply (3.33) by $\Delta t \varphi_k$ and add over k in order to obtain

$$\sum_{k=1}^K (\nu_j^k - \nu_j^{k-1}) \varphi_k = \sum_{k=1}^K \Delta t \left(M_j^k \nu_j^k + \sum_{l \in N_j} B_{jl}^k \nu_l^k \right) \varphi_k,$$

or, after reordering the sum on the left side

$$\sum_{k=1}^K \Delta t \nu_j^k \frac{\varphi_k - \varphi_{k-1}}{\Delta t} = \sum_{k=1}^K \Delta t \left(M_j^k \nu_j^k + \sum_{l \in N_j} B_{jl}^k \nu_l^k \right) \varphi_k. \quad (3.37)$$

For all φ in $\mathcal{C}_0^1((0, T))$, the sequence

$$\sum_{k=1}^K \frac{\varphi_k - \varphi_{k-1}}{\Delta t} \mathbb{1}_{(t_k, t_{k+1})},$$

strongly converges in $L^2((0, T))$ to φ' . The boundedness of the coefficients M_j^k and B_{jl}^k together with strong convergence of $\nu_{\Delta t}^j$ imply that

$$\sum_{k=1}^K \left(M_j^k \nu_j^k + \sum_{l \in N_j} B_{jl}^k \nu_l^k \right) \mathbb{1}_{(t_k, t_{k+1})},$$

strongly converges to $M_j(t, \rho_h(t))\nu_j^* + \sum_{l \in N_j} B_{jl}(t)\nu_l^*$, so, taking the limit in (3.37), we get

$$\int_0^T \nu_j^* \varphi'(t) dt = \int_0^T \left(M_j(t, \nu_j^*)\nu_j^* + \sum_{l \in N_j} B_{jl}(t)\nu_l^* \right) \varphi(t) dt,$$

which implies that ν_j^* is in C^1 and is a solution for (3.9). Furthermore, as ν_j^* is the point-wise limit of $\mu_{\Delta t}^j$, it also satisfies the initial conditions (3.10). \square

4 Simulations

The first part of this section is devoted to the numerical analysis of the approximation error. For certain values of the coefficients of problem (2.1)-(2.3), it is possible to obtain an analytical solution, which we will use in order to compare with our numerical approximation.

Assume that $r(x, y, \theta)$ and $d(x, y, \theta)$ are constants, that $V(t, x, y, \theta)$ is independent of t and that exists $W(x, y, \theta)$ such that

$$V(z) = A(\theta) \nabla W(z).$$

Assume as well that

$$n_0(z) = C \frac{e^{W(z)}}{\int_D e^{W(z)} dz}.$$

Then, the solution for problem (2.1)-(2.3) is

$$n(t, z) = \frac{e^{W(z)}}{\int_D e^{W(z)} dz} \frac{r e^{rt}}{d(K + e^{rt})},$$

where

$$K = \frac{r - Cd}{Cd}.$$

The existence of an analytic solution allows us to compare its values with those obtained from solving (3.9) for different values of h , and this way, numerically establish the error order of the method. Choosing

$$D := \{(x, y, \theta) \in [0, 1]^3 : x^2 + y^2 \leq 1\},$$

$$V(t, z) = \begin{pmatrix} -(\theta + 1)x \\ -(\theta + 1)y \\ 1 \end{pmatrix}, \quad A(\theta) = \begin{pmatrix} \theta + 1 & 0 & 0 \\ 0 & \theta + 1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

$r = d = 1$ and $n_0 = \left(\pi(1 - e^{-1/2})(e - 1) \right)^{-1} e^{-\frac{x^2}{2} - \frac{y^2}{2} + \theta}$, the exact solution for (2.1)-(2.3) is

$$n(t, z) = \left(\frac{\pi}{2} (1 - e^{-1/2})(e - 1) \right)^{-1} e^{-\frac{x^2}{2} - \frac{y^2}{2} + \theta} \frac{e^t}{1 + e^t}.$$

For a grid of points $\{(t_k, z_j)\}$ with $t_k = k\Delta t$, $k = 1, \dots, K$, $\Delta t > 0$ and $j = 1, \dots, N$, we define the discrete $L^2(D_T)$ error for the semi-discrete scheme (3.9) as

$$E^1(\Delta t, h) = \left(\sum_{k=1}^K \sum_{j=1}^N (n(t_k, z_j) - \nu_j(t_k))^2 h^3 \Delta t_k \right)^{1/2},$$

where $\nu(t)$ is the solution of the scheme for the functions introduced above. We set $\Delta t = 0.01$ and in Figure 1 we show the dependence in log-log scale of $E_h = E(0.01, h)$ with respect to the inverse of the cell size $M = 1/h$.

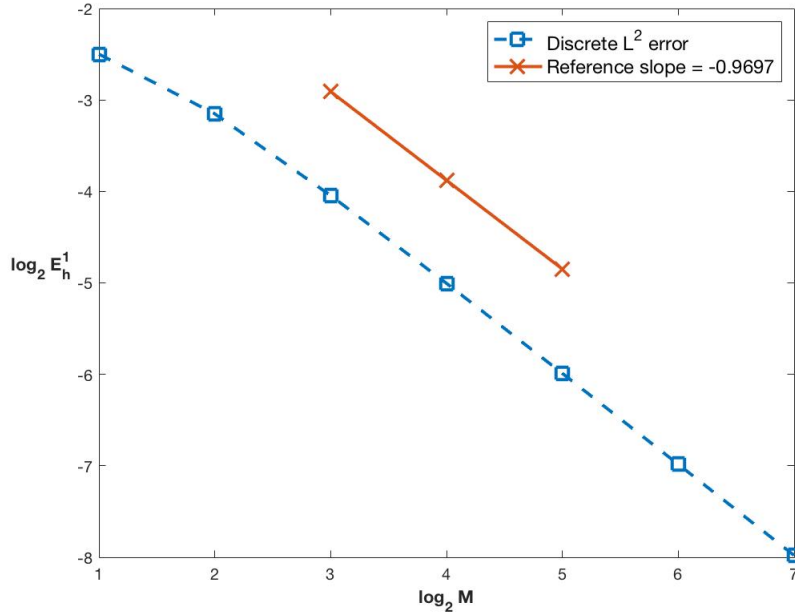


Fig. 1 The discrete $L^2(D_T)$ error for the semi-discrete scheme, for $T = 10$ and M ranging between 2 and 128.

In the same way, we define the discrete $L^2(D_T)$ error for the discrete scheme (3.33) as

$$E^2(\Delta t, h) = \left(\sum_{k=1}^K \sum_{j=1}^N (n(t_k, z_j) - \nu_j^k)^2 h^3 \Delta t_k \right)^{1/2},$$

where ν_j^k is the solution of (3.33). We set $h = 1/50$ and plot the dependence of $E_{\Delta t}^2 := E^2(\Delta t, 0.02)$ with respect to $\Delta t = 1/M_1$, again in log-log scale.

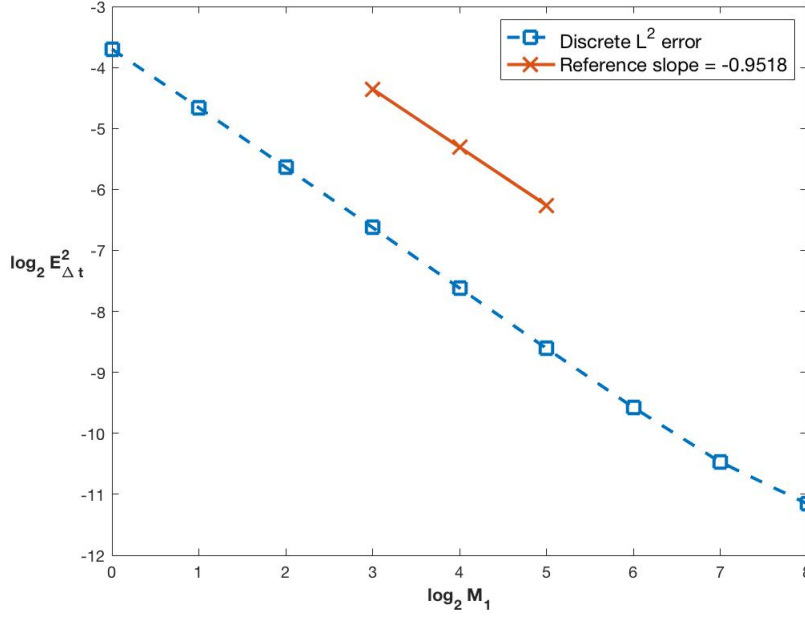


Fig. 2 The discrete $L^2(D_T)$ error for the discrete scheme, for $T = 10$ and M_1 ranging between 2 and 256.

4.1 Phenotypic Dimorphism

We present now several examples illustrating the effect of the environment on a population and how the plasticity trait plays a role in surviving effects.

4.1.1 Monomorphic Population

On the first place, we show the evolution of a population which is under the effects of natural selection and non-genetic epimutations, but without considering plasticity as a trait nor accounting for the environmental pressure. Specifically, we solve the problem (2.1)-(2.2) over the domain

$$\Omega = \{(x, y) \in [0, 1]^2 : (x - 1)^2 + (y - 1)^2 > 1\},$$

while taking the growth rate as $r(x, y) = e^{-(x-0.1)^2 - (y-0.1)^2}$, the death rate as $d(x, y) = 0.5$, the diffusion parameters $\alpha(\theta) = \beta(\theta) = 10^{-6}$, and the drift terms $V(t, x, y) = (0, 0)$. We take an initial condition (2.3) given by the expression

$$n_0(x, y) = a \mathbb{1}_{\{f(x, y) < 1\}} e^{-\frac{1}{1-f(x, y)}},$$

with $f(x, y) = \frac{(x-0.25)^2 + (y-0.25)^2}{(0.025)^2}$. We choose the value of a in such a way that $\rho_0 = \int_{\Omega} n_0(x, y) dx dy = 1$.

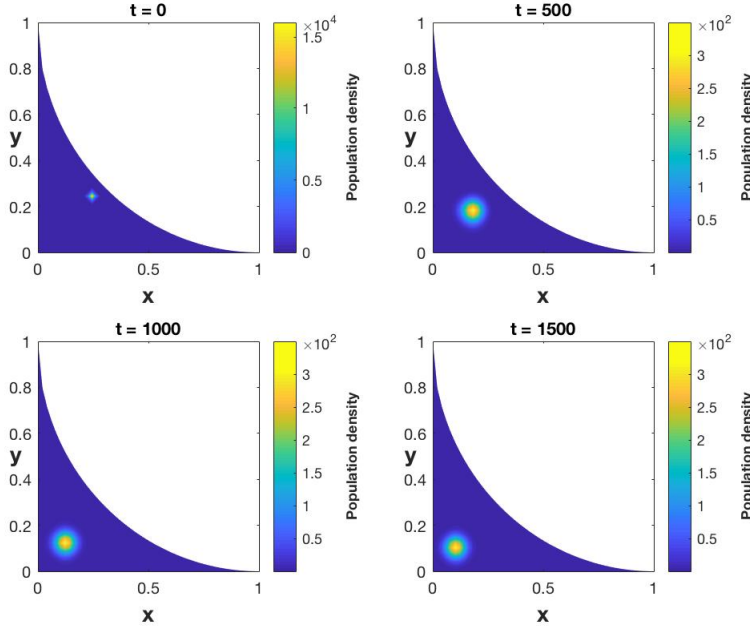


Fig. 3 Evolution of a population only subjected to natural selection and non-genetic epimutations.

We observe in figure 3 that the dominant phenotype slowly converges to the point which maximises the fitness, in this case, the point $(0.1, 0.1)$, which maximises the growth rate $r(x, y)$.

4.1.2 Dimorphism due to the effect of the environment

For a second example we keep the same parameters, but add a drift term accounting for the effect of the environment (biologically, a “cellular stress”). Specifically we choose

$$V(t, x, y) = 10^{-3}(\mathbb{1}_{(y>x)}(-1, 1) + \mathbb{1}_{(y<x)}(1, -1)).$$

Notice that we still are not including plasticity as a trait in our analysis. Also notice that the function $V(t, x, y)$ is not continuous, while the results presented in previous sections needed $V(t, z)$ to be smooth in order to ensure the existence and uniqueness of solution for the problem, as well as the convergence of the finite volume method. This is not a big issue, because the conditions of our problem allow us to use a density argument in order to extend our results to any $V(t, z) \in \mathcal{C}([0, T], L^2(D))$, and in any case all numerical approximations are smoothing approximations of the drift V .

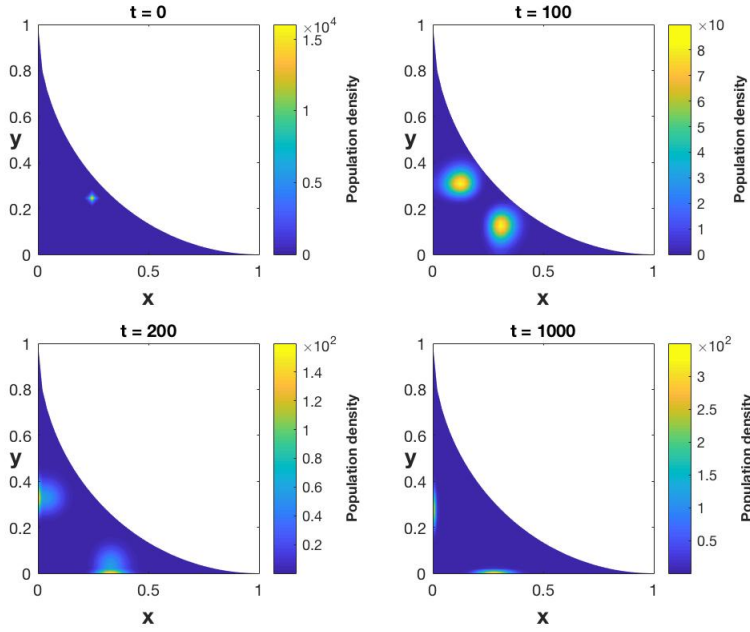


Fig. 4 Evolution of a population under the effect of the environment.

We can appreciate in figure 4 that adding a drift term resulted in the appearance of dimorphism: the final population is concentrated around two different trait configurations. This evolution into dimorphism due the action of environment, contrasts with the results obtained in [11], where it was proved that dimorphism can occur in the absence of a drift term, given that the growth rate $r(x, y)$ has several maximum point satisfying certain conditions.

4.1.3 Plasticity, environmental effect and dimorphism

We will now consider plasticity as a trait and modify the parameters from the previous examples accordingly. We first consider the growth rate as

$$r(x, y, \theta) = e^{-(x-0.1)^2 - (y-0.1)^2} + e^{-(z-0.8)^2},$$

and keep the constant death rate $d(x, y, \theta) = 0.5$. We consider the diffusion matrix

$$A(\theta) = \begin{pmatrix} (\theta + 1)10^{-6} & 0 & 0 \\ 0 & (\theta + 1)10^{-6} & 0 \\ 0 & 0 & 10^{-6} \end{pmatrix},$$

and the drift term

$$V(t, z) = 10^{-3}\theta(-\mathbb{1}_{(y>x)} + \mathbb{1}_{(y<x)}, \mathbb{1}_{(y>x)} - \mathbb{1}_{(y<x)}, -x^2 - y^2).$$

Notice that a higher plasticity increases the effect of non-genetic epimutations (given by the diffusion term) and stress induced mutations (given by the drift term). For the initial data (2.3) we take a function of the form

$$n_0(z) = a \left(\mathbb{1}_{\{f_1(z) < 1\}} e^{-\frac{1}{1-f_1(z)}} + \mathbb{1}_{\{f_2(z) < 1\}} e^{-\frac{1}{1-f_2(z)}} \right),$$

with $f_i(z) = \frac{\|z - z_i\|^2}{(0.025)^2}$, $i = 1, 2$, $z_1 = (0.25, 0.25, 0.25)$ and $z_2 = (0.25, 0.25, 0.75)$. The value of a is again chosen in a way that the total population size over $D = \Omega \times [0, 1]$ is equal 1.

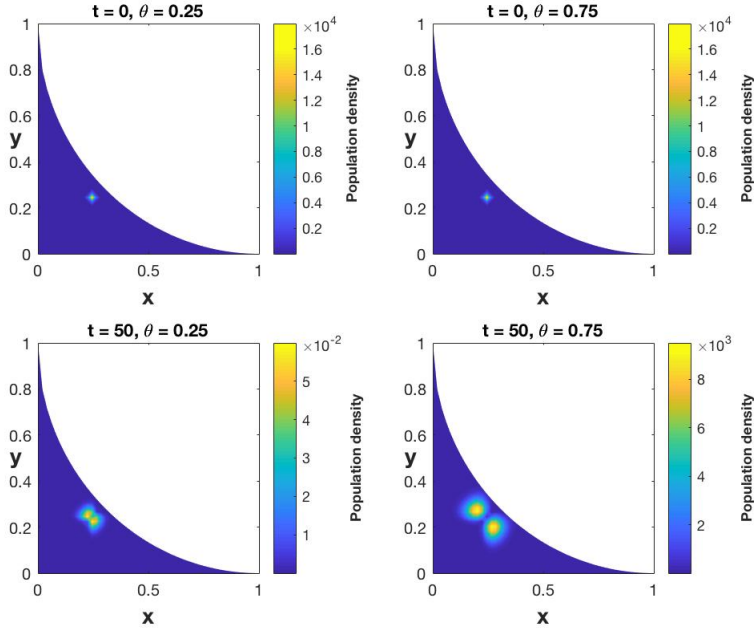


Fig. 5 Evolution of two sub-populations with different levels of plasticity: Initial stages.

We observe in figure 5 that for this set of parameters, the sub-population with the lowest plasticity quickly gets extinct (notice the scale of the density values), while the emergence of dimorphism can be appreciated for the one with higher plasticity.

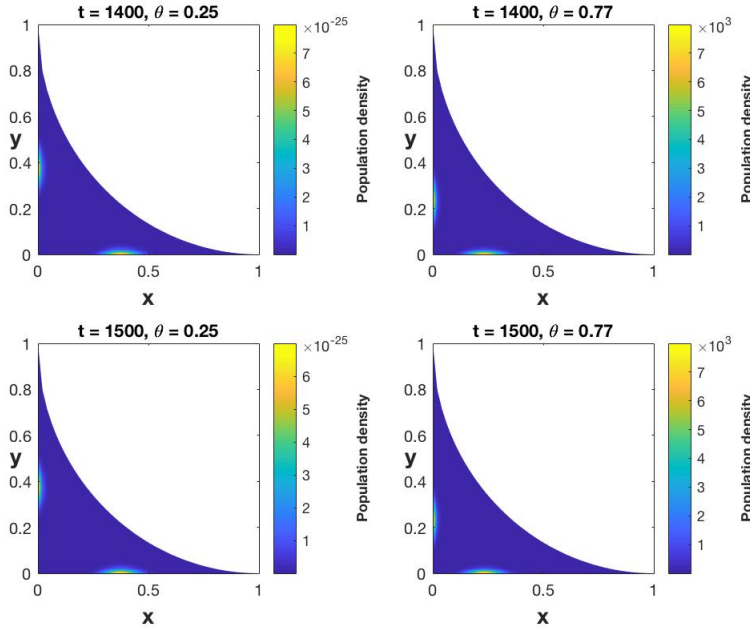


Fig. 6 Evolution of two sub-populations with different levels of plasticity: Final stages.

This kind of behaviour persists up to the final stages of the evolution, when we can observe in Figure 6 that the low plasticity sub-population is completely extinct while the high plasticity one has completed the differentiation process.

4.1.4 Another example of emergence of dimorphism

We present now a different example of emergence of dimorphism, but this time, not as a result of a response to the effect of the environment, but as a consequence of the existence of two maximum points for the growth rate. We will observe how a population initially concentrated around a single phenotype configuration, will evolve with time into a dimorphic population, in which each upcoming sub-population is more specialised and less plastic than in the initial configuration. For this purpose, over the domain $D = \Omega \times [0, 1]$ we consider an initial density given by the expression

$$n_0(z) = a \mathbb{1}_{\{f(z) < 1\}} e^{-\frac{1}{1-f(z)}},$$

with $f(z) = \frac{\|z - z_0\|^2}{(0.025)^2}$, where $z_0 = (0.25, 0.25, 0.5)$ and $\|\cdot\|$ is the euclidean norm. We choose the value of a in such a way that $\rho_0 = \int_D n_0(z) = 1$.

We set the growth rate and the death rate as

$$r(x, y, \theta) = \mathbb{1}_{\{y > x\}} e^{-(0.1-x)^2 - (0.9-y)^2} + \mathbb{1}_{\{x \geq y\}} e^{-(0.1-y)^2 - (0.9-x)^2},$$

$$d(x, y, \theta) = \frac{1}{2}.$$

We choose the diffusion matrix

$$A(\theta) = \begin{pmatrix} (\theta + 1)10^{-6} & 0 & 0 \\ 0 & (\theta + 1)10^{-6} & 0 \\ 0 & 0 & 10^{-6} \end{pmatrix},$$

and finally the drift term

$$V(t, z) = (-\theta y 10^{-3}, -\theta x 10^{-3}, -\theta(x + y) 10^{-3}).$$

The growth rate was chosen in such a way that it satisfies the sufficient conditions given in [11] in order to guarantee the appearance of phenotypic polymorphism.

We show in Figure 7 that initially the population is concentrated around the phenotype $z_0 = (0.25, 0.25, 0.5)$, and gradually evolves into two well differentiated sub-populations.

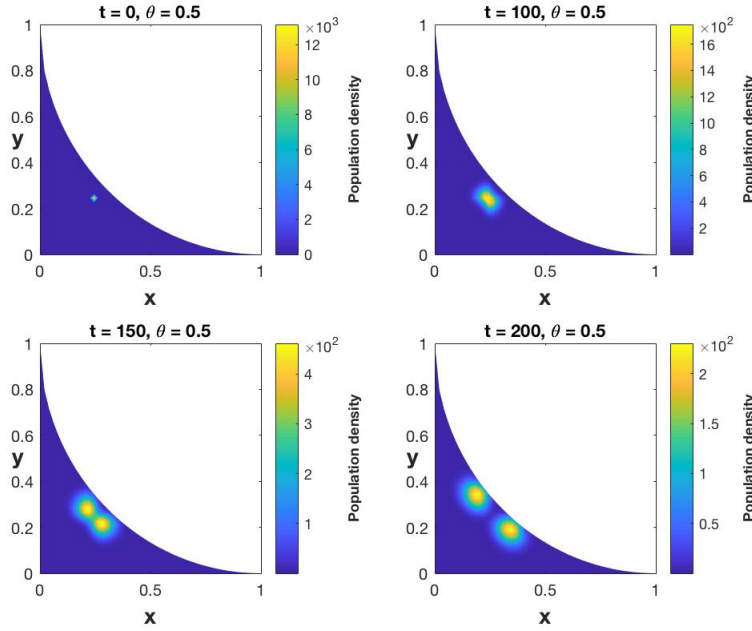


Fig. 7 Initial stages of the population density for $\theta = 0.5$: The differentiation process starts.

As the two new sub-populations become more and more differentiated, a loss in plasticity can be observed, and we see in Figure 8 that most of the mass is migrating to the less plastic state $\theta = 0.25$, while the differentiation process continues.

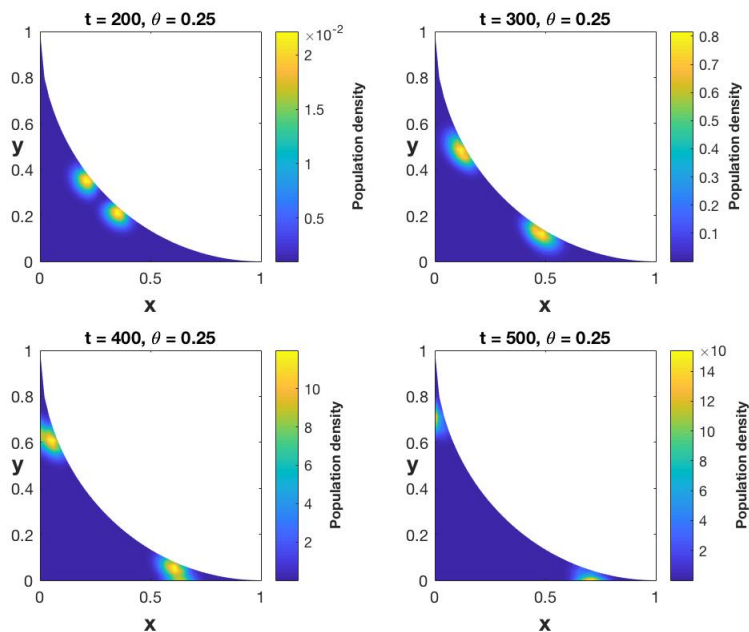


Fig. 8 Intermediate stages of the population density for $\theta = 0.25$: Most of the mass is being concentrated at $\theta = 0.25$ while the differentiation process continues.

Finally we observe in Figure 9 that once the sub-populations are fully specialised, the concentration process continues and at the final stage $t = 1000$ we have a dimorphic population which is more specialised but less plastic than the initial one.

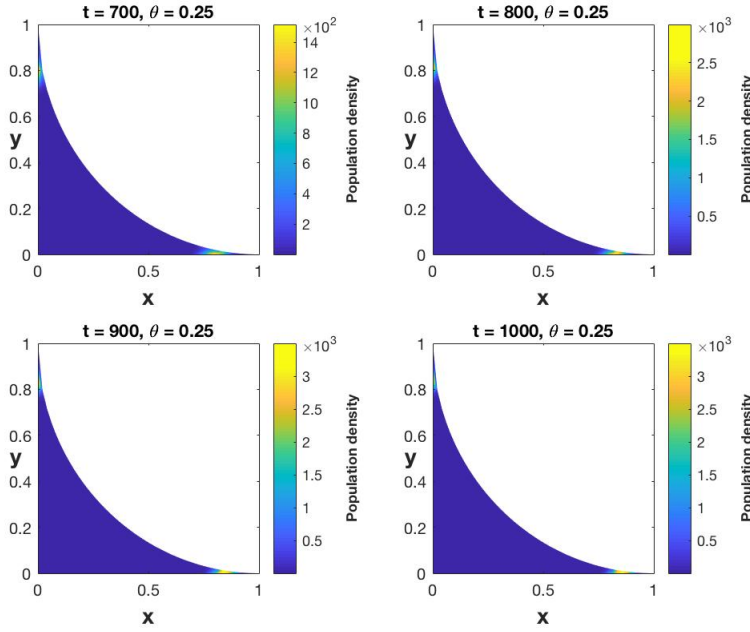


Fig. 9 Final stages of the population density for $\theta = 0.25$: The differentiation process is over, but the mass keeps concentrating on both selected phenotypes.

5 Concluding remarks

The validity of the model we constructed is strengthened by the different evolutionary mechanisms described in [21], where the authors focus their attention on Stress-Induced Evolutionary Innovation, and compare it to plasticity-based models, in particular the Plasticity First Hypothesis. Quoting the authors: “SIEI and PFH are not competing models but explain different kinds of evolutionary processes that are sometimes distinct and sometimes combined over evolutionary time”. Similar mechanisms were taken into consideration in the construction of our model, environmental stress (aka environmental pressure, biologically, at the single-cell level, “cellular stress”) in the form of an advection term and mutations thanks to plasticity in the form of a diffusion term, both accompanied by natural selection in the form of reaction term.

The finite volume method offers a powerful tool in order to numerically approximate the solution of integro-differential or reaction-diffusion equations, such as the one treated in the present paper. The preservation of the structure of the original problem at a semi-discrete level and the excellent approximation for the non-local terms are just two of the reasons why we chose this method. This way, we were able to obtain two numerical schemes in order to

approximate the solution for an evolution problem modelling bet hedging strategies.

We proved the existence and uniqueness of solutions for such schemes, and constructed sequences of functions converging to the solution of the original problem. We approximated the convergence error by establishing a comparison with an exact solution. It is worth mentioning that the constructive character of the proofs may provide new and interesting tools in order to obtain further theoretical results.

After simulating various situations, we observed different ways in which a population can respond to external stress, depending on the plasticity levels of its individuals. A highly plastic sub-population can quickly adapt to its surrounding environment, guaranteeing this way its survival, while a less plastic sub-population might go extinct under the same external factor. Another strategy consists in “trading” some of the plasticity by a higher differentiation level.

Furthermore, the emergence of dimorphism as a consequence of external stress, not only is an interesting alternative to the previously established results from [11], but also shows that bet-hedging strategies are a suitable response to (abrupt) external changes in the environment, and, at the same time, a possible way to survive them. It is fair mentioning that, throughout all the simulations, the symmetry hypothesis required in the reference [11] in order to observe dimorphism were respected. It remains to establish what are the essential conditions that will lead to the appearance of dimorphism when an advection term is present.

We thus provided here a rigorous model for the study of the emergence of dimorphism, an event that is likely to have been at the evolutionary origin of multicellularity by divergence of phenotypes and may thus provide a rationale for a renewed conception of animal evolution towards multicellular organisms, and, more pragmatically and consistently with the atavistic theory of cancer, for a possible origin of phenotype bet hedging in cancer cell populations.

Bet hedging in cancer cell populations is indeed a strategy susceptible to yield maximal probabilities of survival to a plastic cell population exposed to life-threatening insults such as by drugs or other deadly therapies. The modelling setting presented here may thus help in the future to test and optimise combined anticancer therapies involving chemotherapies, targeted therapies, and - what is likely still ahead of us for the present time - possible control of cell plasticity by epigenetic drugs.

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