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# EXTRINSIC EIGENVALUES UPPER BOUNDS FOR SUBMANIFOLDS IN WEIGHTED MANIFOLDS 

FERNANDO MANFIO, JULIEN ROTH, AND ABHITOSH UPADHYAY


#### Abstract

We prove Reilly-type upper bounds for divergence-type operators of the second order as well as for Steklov problems on submanifolds of Riemannian manifolds of bounded sectional curvature endowed with a weighted measure.


MSC 2010: $53 \mathrm{C} 24,53 \mathrm{C} 42,58 \mathrm{~J} 50$.
Key words: Submanifolds, Reilly-type upper bounds, eigenvalues estimates, divergencetype operators, Steklov problems.

## 1. Introduction

Let $\left(M^{n}, g\right)$ be an $n$-dimensional compact, connected, oriented manifold without boundary, and consider an isometric immersion $X: M^{n} \rightarrow \mathbb{R}^{n+1}$ in the Euclidean space. The spectrum of Laplacian of $(M, g)$ is an increasing sequence of real numbers

$$
0=\lambda_{0}(\Delta)<\lambda_{1}(\Delta) \leqslant \lambda_{2}(\Delta) \leqslant \cdots \leqslant \lambda_{k}(\Delta) \leqslant \cdots \longrightarrow+\infty
$$

The eigenvalue 0 (corresponding to constant functions) is simple and $\lambda_{1}(\Delta)$ is the first positive eigenvalue. In [12], Reilly proved the following well-known upper bound for $\lambda_{1}(\Delta)$

$$
\begin{equation*}
\lambda_{1}(\Delta) \leqslant \frac{n}{\mathrm{~V}(M)} \int_{M} H^{2} d v_{g} \tag{1}
\end{equation*}
$$

where $H$ is the mean curvature of the immersion. He also proved an analogous inequality involving the higher order mean curvatures. Namely, for $r \in\{1, \cdots, n\}$

$$
\begin{equation*}
\lambda_{1}(\Delta)\left(\int_{M} H_{r-1} d v_{g}\right)^{2} \leqslant \mathrm{~V}(M) \int_{M} H_{r}^{2} d v_{g} \tag{2}
\end{equation*}
$$

where $H_{r}$ is the $r$-th mean curvature, defined by the $r$-th symmetric polynomial of the principal curvatures. Moreover, Reilly studied the equality cases and proved that equality in (1) or (2) is attained if and only if $X(M)$ is a geodesic sphere.

In the case of higher codimension, Reilly also proved that

$$
\begin{equation*}
\lambda_{1}(\Delta) \leqslant \frac{n}{\mathrm{~V}(M)} \int_{M}\|\mathbf{H}\|^{2} d v_{g} \tag{3}
\end{equation*}
$$

where $\mathbf{H}$ is here the mean curvature vector, with equality if and only if $M$ is minimally immersed in a geodesic sphere.

[^0]The Reilly inequality can be easily extended to submanifolds of the sphere $\mathbb{S}^{n}$ using the canonical embedding of $\mathbb{S}^{n}$ into $\mathbb{R}^{n+1}$ :

$$
\begin{equation*}
\lambda_{1}(\Delta) \leqslant \frac{n}{\mathrm{~V}(M)} \int_{M}\left(\|\mathbf{H}\|^{2}+1\right) d v_{g} \tag{4}
\end{equation*}
$$

Moreover, El Soufi and Ilias [7] proved an analogue for submanifold of the hyperbolic space as

$$
\begin{equation*}
\lambda_{1}(\Delta) \leqslant \frac{n}{\mathrm{~V}(M)} \int_{M}\left(\|\mathbf{H}\|^{2}-1\right) d v_{g} \tag{5}
\end{equation*}
$$

In case the ambient space has non-constant sectional curvature, Heintze 10] proved the following weaker inequality

$$
\begin{equation*}
\lambda_{1}(\Delta) \leqslant n\left(\|\mathbf{H}\|^{2}+\delta\right) \tag{6}
\end{equation*}
$$

where the ambient sectional curvature is bounded above by $\delta$.
On the other hand, more recently, in [14], the second author prove the following general inequality

$$
\begin{equation*}
\lambda_{1}\left(L_{T, f}\right)\left(\int_{M} \operatorname{tr}(S) \mu_{f}\right)^{2} \leqslant\left(\int_{M} \operatorname{tr}(T) \mu_{f}\right) \int_{M}\left(\left\|H_{S}\right\|^{2}+\|S \nabla f\|^{2}\right) \mu_{f} \tag{7}
\end{equation*}
$$

where $\mu_{f}=e^{-f} d v_{g}$ is the weighted measure of $(M, g)$ endowed with the density $e^{-f}, T, S$ are two symmetric, free-divergence $(1,1)$-tensors with $T$ positive definite, and $L_{T, f}$ is the second order differential operator defined for any smooth function $u$ on $M$ by

$$
L_{T, f}=-\operatorname{div}(T \nabla u)+\langle\nabla f, T \nabla u\rangle .
$$

When $f=0$ and the tensor $S$ and $T$ are associated with higher order mean curvatures $H_{s}$ and $H_{r}$, we recover the inequality of Alias and Malacarné [2] and, in particular, Reilly's inequality (2) if $r=0$.

The first result of this paper gives upper bounds for the first eigenvalue of the operator $L_{T, f}$ for submanifolds of Riemannian manifolds with sectional curvature bounded by above which generalizes inequality (7) in the non-constant curvature case. Namely, we prove the following.

Theorem 1.1. Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature sect $\bar{M} \leqslant \delta$ and $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $(M, g)$ be a closed Riemannian manifold isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $X$. We endow $M$ with the weighted measure $\mu_{f}=e^{-f} d v_{g}$. Let $T$ be a positive definite $(1,1)$-tensor on $M$ and denote by $\lambda_{1}$ the first positive eigenvalue of the operator $L_{T, f}$.
(1) If $\delta \leqslant 0$, then

$$
\lambda_{1} \leqslant \sup _{M}\left[\delta \operatorname{tr}(T)+\sup _{M}\left(\frac{\left\|H_{T}-T \nabla f\right\|}{\operatorname{tr}(S)}\right)\left\|H_{S}-S \nabla f\right\|\right] .
$$

(2) If $\delta>0$ and $X(M)$ is contained in a geodesic ball of radius $\frac{\pi}{4 \sqrt{\delta}}$,

$$
\lambda_{1} \leqslant \frac{\left(\int_{M} \operatorname{tr}(T) \mu_{f}\right)}{V_{f}(M)}\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right)
$$

The second eigenvalue problem that we consider in this paper is the Steklov problem associated with the operator $L_{T, f}$ on a submanifold $\Omega$ with non-empty boundary $\partial \Omega=M$ of a Riemannian manifold with sectional curvature bounded by above. We can consider the following generalized weighted Steklov problem

$$
\left\{\begin{array}{l}
L_{T, f} u=0 \quad \text { on } \Omega  \tag{8}\\
\frac{\partial u}{\partial \nu_{T}}=\sigma u \quad \text { on } M=\partial \Omega
\end{array}\right.
$$

where $\frac{\partial u}{\partial \nu_{T}}=\langle T(\widetilde{\nabla} u), \nu\rangle$. In the case where $f$ is constant, the operator $L_{T, f}$ is of particular interest for the study of $r$-stability when $T=T_{r}$ is the tensor associated with $r$-th mean curvature (see [1] for instance). More precisely, from [3], we know that this problem (8) has a discrete nonnegative spectrum and we denote by $\sigma_{1}$ its first eigenvalue. In [13], the second author has obtained upper bounds for this problem for domains of a manifold lying in a Euclidean space. Namely, he has proved

$$
\sigma_{1}\left(\int_{M} \operatorname{tr}(S) \widetilde{\mu}_{f}\right)^{2} \leqslant\left(\int_{\Omega} \operatorname{tr}(T) \mu_{f}\right) \int_{M}\left(\left\|H_{S}\right\|^{2}+\|S \nabla f\|^{2}\right) \widetilde{\mu}_{f}
$$

where $\mu_{f}=e^{-f} d v_{g}$ and $\widetilde{\mu}_{f}=e^{-f} d v_{\widetilde{g}}$ are respectively, the weighted measures of $(\Omega, g)$ and $(M, \widetilde{g})$ endowed with the density $e^{-f}$ and where $T$ and $S$ are two symmetric, free-divergence (1,1)-tensors with $T$ positive definite. Note that without density and for $T=\mathrm{Id}$, this inequality has been proven by Ilias and Makhoul [11].

The second result of the present paper gives a generalization of this estimate when the manifold with boundary $(M, g)$ is immersed into an ambient Riemannian manifold of sectional curvature bounded by above. Namely, we prove the following.

Theorem 1.2. Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature $\operatorname{sect}_{\bar{M}} \leqslant \delta$ and $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $(\Omega, g)$ be a compact Riemannian manifold with non-empty boundary $M$ isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $X$. We endow $\Omega$ and $M$, respectively with the weighted measure $\mu_{f}=e^{-f} d v_{g}$ and $\tilde{\mu}_{f}=e^{-f} d v_{\tilde{g}}$, where $\tilde{g}$ is the induced metric on $M$. Let $T, S$ be a symmetric, divergence-free and positive definite $(1,1)$-tensors on $\Omega$ and $M$, respectively, and denote by $\sigma_{1}$ the first eigenvalue of the Steklov problem (8).
(1) If $\delta \leqslant 0$ and $X(\Omega)$ is contained in the geodesic ball $B(p, R)$ or radius $R$, where $p$ is the center of mass of $M$ for the measure $\widetilde{\mu}_{f}$, then

$$
\begin{aligned}
& \sigma_{1} \leqslant \sup _{\Omega}\left[\delta \operatorname{tr}(T)+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\bar{\nabla} f)\right\|}{\operatorname{tr}(T)}\right)\left\|H_{T}-T(\bar{\nabla} f)\right\|\right] \\
& \times\left[\delta+\frac{\sup _{M}\left\|H_{S}-S(\nabla f)\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}\right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R)
\end{aligned}
$$

(2) If $\delta>0$ and $X(\Omega)$ is contained in a geodesic ball of radius $\frac{\pi}{4 \sqrt{\delta}}$, then

$$
\sigma_{1} \leqslant \frac{\int_{\Omega} \operatorname{tr}(T) \mu_{f}}{V_{f}(M)}\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \widetilde{\mu}_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right)
$$

Finally, we will consider the so-called eigenvalue problem for Wentzell boundary conditions

$$
\left\{\begin{array}{rlll}
\Delta u & =0 & \text { in } \Omega  \tag{SW}\\
-b \widetilde{\Delta} u-\frac{\partial u}{\partial \nu} & =\alpha u & & \text { on } M
\end{array}\right.
$$

where $b$ is a given positive constant, $\Omega$ is a submanifold with non-empty boundary $\partial \Omega=M$ of a Riemannian manifold $M$ with sectional curvature bounded by above, and $\Delta, \widetilde{\Delta}$ denote the Laplacians on $\Omega$ and $M$, respectively. It is clear that if $b=0$, then we recover the classical Steklov problem. The spectrum of this problem is an increasing sequence (see [5]) with 0 as first eigenvalue which is simple and the corresponding eigenfunctions are the constant ones. We denote by $\alpha_{1}$ the first positive eigenvalue. In [14, the second author proved the following estimate when $\Omega$ is a submanifold of the Euclidean space $\mathbb{R}^{n}$

$$
\alpha_{1}\left(\int_{\partial M} \operatorname{tr}(S) d v_{g}\right)^{2} \leqslant(n V(M)+b(n-1) V(\partial M))\left(\int_{\partial M}\left\|H_{S}\right\|^{2} d v_{g}\right)
$$

In the following theorem, we obtain a comparable estimate when the ambient space is of bounded sectional curvature. Namely, we prove
Theorem 1.3. Let $\left(\bar{M}^{n+p}, \bar{g}\right)$ be a Riemannian manifold with sectional curvature sect $_{\bar{M}} \leqslant \delta$. Let $(\Omega, g)$ be a compact Riemannian manifold with non-empty boundary $M$ isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $X$. We denote by $\widetilde{g}$ the induced metric on $M$. Let $S$ be a symmetric, divergence-free and positive definite (1,1)-tensor on $M$ and denote by $\alpha_{1}$ the first eigenvalue of the Steklov-Wentzell problem SW.
(1) If $\delta \leqslant 0$ and $X(\Omega)$ is contained in the geodesic ball $B(p, R)$ or radius $R$, where $p$ is the center of mass of $\bar{M}$, then

$$
\alpha_{1} \leqslant\left[n \frac{V(\Omega)}{V(M)}+b(n-1)-\delta s_{\delta}^{2}(R)\left(\frac{V(\Omega)}{V(M)}+b\right)\right]\left(\delta+\frac{\sup _{M}\left\|H_{S}\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}\right)
$$

(2) If $\delta>0$ and so $X(\Omega)$ is contained in a geodesic ball of radius $\frac{\pi}{4 \sqrt{\delta}}$, then

$$
\alpha_{1} \leqslant\left(n \frac{V(\Omega)}{V(M)}+b(n-1)\right)\left(\delta+\frac{\int_{M}\left\|H_{S}\right\|^{2} d v_{\widetilde{g}}}{V(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right)
$$

## 2. Preliminaries

Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature $\operatorname{sect}_{\bar{M}} \leqslant \delta$ and weighted measure $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $p$ a fixed point in $\bar{M}$, we denote by $r(x)$ the geodesic distance between $x$ and $p$. Moreover, we define the vector field $X$ by $X(x):=s_{\delta}(r(x))(\bar{\nabla} r)(x), s_{\delta}$ is the function defined by

$$
s_{\delta}(r)= \begin{cases}\frac{1}{\sqrt{\delta}} \sin (\sqrt{\delta} r) & \text { if } \delta>0 \\ r & \text { if } \delta=0 \\ \frac{1}{\sqrt{|\delta|}} \sinh (\sqrt{|\delta|} r) & \text { if } \delta<0\end{cases}
$$

We also define

$$
c_{\delta}(r)= \begin{cases}\cos (\sqrt{\delta} r) & \text { if } \delta>0 \\ 1 & \text { if } \delta=0 \\ \cosh (\sqrt{|\delta|} r) & \text { if } \delta<0\end{cases}
$$

Hence, we have

$$
c_{\delta}^{2}+\delta s_{\delta}^{2}=1, \quad s_{\delta}^{\prime}=c_{\delta} \quad \text { and } \quad c_{\delta}^{\prime}=-\delta s_{\delta}
$$

In addition, let $\left(M^{n}, g\right)$ be a closed Riemannian manifold isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $\phi$. If $\delta>0$, then we assume that $\phi(M)$ is contained in a geodesic ball of radius $\frac{\pi}{2 \sqrt{\delta}}$. We endow $M$ with the weighted measure $\mu_{f}=e^{-f} d v_{g}$. We can define on $M$ a divergence associated with the volume form $\mu_{f}=e^{-f} d v_{g}$ by

$$
\operatorname{div}_{f} Y=\operatorname{div} Y-\langle\nabla f, Y\rangle
$$

or, equivalently,

$$
d\left(\iota_{Y} \mu_{f}\right)=\operatorname{div}_{f}(Y) \mu_{f}
$$

where $\nabla$ is the gradient on $\Sigma$, that is, the projection on $T \Sigma$ of the gradient $\bar{\nabla}$ on $\bar{M}$. We call it the $f$-divergence. We recall briefly some basic facts about the $f$-divergence. In the case where $\Sigma$ is closed, we first have the weighted version of the divergence theorem:

$$
\begin{equation*}
\int_{\Sigma} \operatorname{div}_{f} Y \mu_{f}=0 \tag{9}
\end{equation*}
$$

for any vector field $Y$ on $\Sigma$. From this, we deduce easily the integration by parts formula

$$
\begin{equation*}
\int_{\Sigma} u \operatorname{div}_{f} Y \mu_{f}=-\int_{\Sigma}\langle\nabla u, Y\rangle \mu_{f} \tag{10}
\end{equation*}
$$

for any smooth function $u$ and any vector field $Y$ on $\Sigma$. First, we prove the following elementary lemma which generalize in non constant curvature the classical HsiungMinkowski formula (see [8, 13] for instance).

Lemma 2.1. Let $T$ be a symmetric divergence-free positive (1,1)-tensor on $M$. Then the following hold
(1) $\operatorname{div}_{f}\left(T X^{\top}\right) \geqslant \operatorname{tr}(T) c_{\delta}+\left\langle X, H_{T}-T(\nabla f)\right\rangle$.
(2) $\int_{M} \operatorname{tr}(T) c_{\delta} \mu_{f} \leqslant-\int_{M}\left\langle X, H_{T}-T(\nabla f)\right\rangle \mu_{f}$.
(3) $\delta \int_{M}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f} \geqslant \int_{M} \operatorname{tr}(T) c_{\delta}^{2} \mu_{f}-\int_{M}\left\|H_{T}-T(\nabla f)\right\| s_{\delta} c_{\delta} \mu_{f}$.

Proof. The proof is a straightforward consequence of the analogue non-weighted result proven by Grosjean. Namely, in [8], the author has shown that

$$
\operatorname{div}_{M}\left(T X^{\top}\right) \geqslant \operatorname{tr}(T) c_{\delta}(r)+\left\langle X, H_{T}\right\rangle
$$

Hence, from the definition of the $f$-divergence, we have

$$
\begin{aligned}
\operatorname{div}_{f}\left(T X^{\top}\right) & =\operatorname{div}\left(T X^{\top}\right)-\left\langle\nabla f, T X^{\top}\right\rangle \\
& \geqslant \operatorname{tr}(T) c_{\delta}(r)+\left\langle X, H_{T}-T(\nabla f)\right\rangle
\end{aligned}
$$

and this proves part (1). For the second part, we integrate the last inequality with respect to the measure $\mu_{f}$ and we get immediately

$$
\int_{M} \operatorname{tr}(T) c_{\delta} \mu_{f} \leqslant-\int_{M}\left\langle X, H_{T}-T(\nabla f)\right\rangle \mu_{f}
$$

since

$$
\int_{M} \operatorname{div}_{f}\left(T X^{\top}\right) \mu_{f}=0
$$

Finally, for the last part, if $\delta=0$, then $c_{\delta}=1$ and we get directly the conclusion from the second one by using

$$
\left|\left\langle X, H_{T}-T(\nabla f)\right\rangle\right| \leqslant\|X\| \cdot\left\|H_{T}-T(\nabla f)\right\|=s_{\delta}\left\|H_{T}-T(\nabla f)\right\|
$$

If $\delta \neq 0$, since $X^{\top}=s_{\delta}(r) \nabla r=-\delta \nabla c_{\delta}(r)$, then we have

$$
\begin{aligned}
\delta \int_{M}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f} & =\frac{1}{\delta} \int_{M}\left\langle T\left(\nabla c_{\delta}, \nabla c_{\delta}\right) \mu_{f}\right. \\
& =-\frac{1}{\delta} \int_{M} \operatorname{div}_{f}\left(T \nabla c_{\delta}\right) c_{\delta} \mu_{f} \\
& =\int_{M} \operatorname{div}_{f}\left(X^{\top}\right) c_{\delta} \mu_{f} \\
& \geqslant \int_{M} \operatorname{tr}(T) c_{\delta}^{2} \mu_{f}-\int_{M}\left\|H_{T}-T(\nabla f)\right\| s_{\delta} c_{\delta} \mu_{f}
\end{aligned}
$$

where we have used the first part of the lemma and the well-known Cuachy-Schwarz inequality.

## 3. Two key lemma

In this section we will prove two basic key lemma that will be used throughout the paper.

Lemma 3.1. Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature sect $_{\bar{M}} \leqslant \delta \leqslant 0$, and $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $(M, g)$ be a closed Riemannian manifold isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$, and we endow $M$ with the weighted measure $\mu_{f}=e^{-f} d v_{g}$. Let $S$ be a symmetric, divergence-free and positive definite $(1,1)$-tensor on $M$. Then, we have

$$
\frac{\int_{M}\|X\|^{2} \mu_{f}}{V_{f}(M)} \geqslant \frac{1}{\delta+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}^{2}}{\inf (\operatorname{tr}(S))^{2}}}
$$

Proof. We have

$$
\begin{aligned}
& \int_{M}\left(\operatorname{tr}(S)-\delta\left\langle S X^{\top}, X^{\top}\right\rangle\right) \mu_{f}=\int_{M}\left(\operatorname{tr}(S)-\operatorname{div}\left(S X^{\top}\right) c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \int_{M}\left(\operatorname{tr}(S)-\operatorname{tr}(S) c_{\delta}^{2}(r)-\left\langle H_{S}-S(\nabla f), X\right\rangle c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \int_{M}\left(\delta \operatorname{tr}(S) s_{\delta}^{2}(r)-\left\langle H_{S}-S(\nabla f), X\right\rangle c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \int_{M}\left(\delta \operatorname{tr}(S) s_{\delta}^{2}(r)+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))} \int_{M} \operatorname{tr}(S) s_{\delta}(r) c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \\
& \frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))} \int_{M}\left(s_{\delta}(r) \operatorname{div}\left(S X^{\top}\right)-s_{\delta}(r)\left\langle H_{S}-S(\nabla f), X\right\rangle\right) \mu_{f} \\
& \quad+\delta \inf (\operatorname{tr}(S)) \int_{M} s_{\delta}^{2}(r) \mu_{f} \\
& \leqslant-\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))} \int_{M}\left(c_{\delta}(r) s_{\delta}(r)\left\langle S \nabla^{M} r, \nabla^{M} r\right\rangle+s_{\delta}^{2}(r)\left\langle H_{S}-S(\nabla f), \nabla^{M} r\right\rangle\right) \mu_{f} \\
& \quad+\delta \inf (\operatorname{tr}(S)) \int_{M} s_{\delta}^{2}(r) \mu_{f}
\end{aligned}
$$

$$
\begin{aligned}
& \leqslant\left(\delta \inf (\operatorname{tr}(S))+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}^{2}}{\inf (\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r) \mu_{f} \\
& \quad-\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))} \int_{M} c_{\delta}(r) s_{\delta}(r)\left\langle S \nabla^{M} r, \nabla^{M} r\right\rangle \mu_{f}
\end{aligned}
$$

Hence, we get

$$
\begin{aligned}
\int_{M} \operatorname{tr}(S) \mu_{f} \leqslant & \left(\delta \inf (\operatorname{tr}(S))+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}^{2}}{\inf (\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r) \mu_{f} \\
& -\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))} \int_{M} c_{\delta}(r) s_{\delta}(r)\left\langle S \nabla^{M} r, \nabla^{M} r\right\rangle \mu_{f} \\
& +\delta \int_{M} s_{\delta}^{2}(r)\left\langle S \nabla^{M} r, \nabla^{M} r\right\rangle \mu_{f} \\
\leqslant & \left(\delta \inf (\operatorname{tr}(S))+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}^{2}}{\inf (\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r) \mu_{f} \\
& +\int_{M}\left(\delta s_{\delta}^{2}(r)-c_{\delta}(r) s_{\delta}(r) \frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}}{\inf (\operatorname{tr}(S))}\right)\left\langle S \nabla^{M} r, \nabla^{M} r\right\rangle \mu_{f}
\end{aligned}
$$

Since $\delta \leqslant 0$, the second term of the right hand side is nonpositive, and thus we get

$$
\begin{aligned}
\inf (\operatorname{tr}(S)) V_{f}(M) & \leqslant \int_{M} \operatorname{tr}(S) \mu_{f} \\
& \leqslant\left(\delta \inf (\operatorname{tr}(S))+\frac{\left\|H_{S}-S(\nabla f)\right\|_{\infty}^{2}}{\inf (\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r) \mu_{f}
\end{aligned}
$$

which gives immediately the result since $\|X\|=s_{\delta}(r)$.

Lemma 3.2. Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature $\operatorname{sect}_{\bar{M}} \leqslant \delta$, with $\delta>0$, and $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $(M, g)$ be a closed Riemannian manifold isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $X$ so that $X(M)$ is contained in a geodesic ball of radius $\frac{\pi}{2 \sqrt{\delta}}$. We endow $M$ with the weighted measure $\mu_{f}=e^{-f} d v_{g}$. Let $S$ be a symmetric, divergence-free and positive definite (1,1)-tensor on $M$. Then, we have

$$
1-\left(\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)}\right)^{2} \geqslant \frac{1}{1+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)}}
$$

Proof. For a sake of compactness, we will write

$$
\alpha=\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)} \quad \text { and } \quad \beta=1+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)}
$$

We thus have to show that $\left(1-\alpha^{2}\right) \beta \geqslant 1$. We have

$$
\begin{aligned}
\left(1-\alpha^{2}\right) \beta= & \beta-\left(\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)}\right)^{2}-\left(\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)}\right)^{2} \frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)} \\
\geqslant & \beta-\left(\frac{\int_{M} \operatorname{tr}(S) c_{\delta}(r) \mu_{f}}{\inf (\operatorname{tr}(S)) V_{f}(M)}\right)^{2}-\left(\frac{\int_{M} c_{\delta}(r)^{2} \mu_{f}}{V_{f}(M)}\right) \frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)} \\
\geqslant & \beta-\left(\frac{\int_{M} s_{\delta}(r)\left\|H_{S}-S(\nabla f)\right\| \mu_{f}}{\inf (\operatorname{tr}(S)) V_{f}(M)}\right)^{2}-\left(\frac{\int_{M} c_{\delta}(r)^{2} \mu_{f}}{V_{f}(M)}\right) \frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)} \\
\geqslant & \beta-\frac{\left(\int_{M} s_{\delta}^{2}(r) \mu_{f}\right)\left(\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}\right)}{\inf (\operatorname{tr}(S))^{2} V_{f}(M)^{2}} \\
& -\left(\frac{\int_{M} c_{\delta}(r)^{2} \mu_{f}}{V_{f}(M)}\right) \frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)} \\
\geqslant & \beta-\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)^{2}}\left(\int_{M}\left(s_{\delta}^{2}(r)+\delta^{2} c_{\delta}^{2}(r)\right) \mu_{f}\right) \\
= & \beta-\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)} \\
= & 1,
\end{aligned}
$$

and this concludes the proof.

## 4. Proofs of the Theorems

Proof of Theorem 1.1. Case $\delta \leqslant 0$. Let $p \in \bar{M}$ be a fixed point and let $\left\{x_{1}, \cdots, x_{N}\right\}$ be the normal coordinates of $\bar{M}$ centered at $p$. For any $x \in \bar{M}, r(x)$ is the geodesic distance between $p$ and $x$ over $\bar{M}$. We want to use as test functions the functions

$$
\frac{s_{\delta}(r)}{r} x_{i},
$$

for $1 \leqslant i \leqslant N$. For this purpose, we will choose $p$ as the center of mass of $M$ with respect for the measure $\mu_{f}$, that is, $p$ is the only point in $M$ so that

$$
\int_{M} \frac{s_{\delta}(r)}{r} x_{i} \mu_{f}=0
$$

for any $i \in\{1, \cdots, N\}$. Note at that point that we assume that $M$ is contained in a ball of radius $\frac{\pi}{4 \sqrt{\delta}}$ when $\delta$ is positive allows us to ensure that $M$ is contained in a ball of radius $\frac{\pi}{4 \sqrt{\delta}}$ centered at $p$. This holds also for Theorems 1.2 and 1.3 . These
functions are candidates for test functions since they are $L^{2}\left(\mu_{f}\right)$-orthogonal to the constant functions which are the eigenfunctions for the first eigenvalue $\lambda_{0}=0$. Thus, we have

$$
\begin{equation*}
\lambda_{1} \int_{M} \sum_{i=1}^{N} \frac{s_{\delta}^{2}(r)}{r^{2}} x_{i}^{2} \mu_{f} \leqslant \int_{M} \sum_{i=1}^{N}\left\langle T \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right), \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right)\right\rangle \mu_{f} \tag{11}
\end{equation*}
$$

We recall that Grosjean proved in [8, Lemma 2.1] that

$$
\begin{equation*}
\sum_{i=1}^{N}\left\langle T \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right), \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right)\right\rangle \leqslant \operatorname{tr}(T)-\delta\left\langle T X^{\top}, X^{\top}\right\rangle . \tag{12}
\end{equation*}
$$

Moreover, by Lemma 2.1, item (3), we have

$$
\delta \int_{M}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f} \geqslant \int_{M} \operatorname{tr}(T) c_{\delta}^{2}(r) \mu_{f}-\int_{M}\left\|H_{T}-T(\nabla f)\right\| s_{\delta}(r) c_{\delta}(r) \mu_{f}
$$

which together with 11 and 12 gives

$$
\begin{aligned}
\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} & \leqslant \int_{M}\left(\operatorname{tr}(T)-c_{\delta}^{2}(r) \operatorname{tr}(T)+\left\|H_{T}-T(\nabla f)\right\| s_{\delta}(r) c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \delta \int_{M} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f}+\int_{M}\left\|H_{T}-T(\nabla f)\right\| s_{\delta}(r) c_{\delta}(r) \mu_{f}
\end{aligned}
$$

where we have used $c_{\delta}^{2}+\delta s_{\delta}^{2}=1$. Hence, we obtain

$$
\begin{align*}
\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} \leqslant & \delta \int_{M} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f}  \tag{13}\\
& +\sup _{M}\left(\frac{\left\|H_{T}-T(\nabla f)\right\|}{\operatorname{tr}(S)}\right) \int_{M} \operatorname{tr}(S) s_{\delta}(r) c_{\delta}(r) \mu_{f}
\end{align*}
$$

Now, we claim the following
Lemma 4.1. We have

$$
\int_{M} \operatorname{tr}(S) s_{\delta}(r) c_{\delta}(r) \mu_{f} \leqslant \int_{M}\left\|H_{S}-S(\nabla f)\right\| s_{\delta}^{2}(r) \mu_{f}
$$

Reporting this into (13), we get

$$
\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} \leqslant \int_{M}\left[\delta \operatorname{tr}(T)+\sup _{M}\left(\frac{\left\|H_{T}-T(\nabla f)\right\|}{\operatorname{tr}(S)}\right)\left\|H_{S}-S(\nabla f)\right\|\right] s_{\delta}^{2}(r) \mu_{f}
$$

which gives immediately the desired estimate

$$
\lambda_{1} \leqslant \sup _{M}\left[\delta \operatorname{tr}(T)+\sup _{M}\left(\frac{\left\|H_{T}-T \nabla f\right\|}{\operatorname{tr}(S)}\right)\left\|H_{S}-S \nabla f\right\|\right] .
$$

This concludes the proof for the case $\delta<0$, up to the proof of the lemma that we give now.

Proof of Lemma 4.1. Multiplying the first part of Lemma 2.1 for the tensor $S$ by $s_{\delta}(r)$, we get

$$
\operatorname{div}_{f}\left(S X^{\top}\right) s_{\delta}(r) \geqslant \operatorname{tr}(S) c_{\delta}(r) s_{\delta}(r)-\left\langle X, H_{S}-S(\nabla f)\right\rangle
$$

and thus, by the Cauchy-Schwarz inequality, we have

$$
\operatorname{div}_{f}\left(S X^{\top}\right) s_{\delta}(r) \geqslant \operatorname{tr}(S) c_{\delta}(r) s_{\delta}(r)-\left\|H_{S}-S(\nabla f)\right\| s_{\delta}(r)
$$

Now, integrating this relation and using the integration by parts in the formula (10), we get

$$
\begin{aligned}
\int_{M} \operatorname{tr}(S) c_{\delta}(r) s_{\delta}(r) \mu_{f}-\int_{M}\left\|H_{S}-S(\nabla f)\right\| s_{\delta}(r) \mu_{f} & \leqslant-\int_{M}\left\langle\nabla s_{\delta}(r), S X^{\top}\right\rangle \mu_{f} \\
& \leqslant-\int_{M} c_{\delta}(r) s_{\delta}(r)\langle\nabla r, S \nabla\rangle \\
& \leqslant 0
\end{aligned}
$$

since $S$ is positive. This concludes the proof of Lemma 4.1
Case $\delta>0$. Like in the case $\delta<0$, we use $\frac{s_{\delta}(r)}{r} x_{i}, 1 \leqslant i \leqslant N$, as test functions. Using (12) again, we get

$$
\begin{equation*}
\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} \leqslant \int_{M}\left(\operatorname{tr}(T)-\delta\left\langle T X^{\top}, X^{\top}\right\rangle\right) \mu_{f} \tag{14}
\end{equation*}
$$

On the other, we use another test function in this case, namely $c_{\delta}(r)-\overline{c_{\delta}}$ where for more convenience, we have denoted by $\overline{c_{\delta}}$ the mean value of $c_{\delta}(r)$, that is $\overline{c_{\delta}}=\frac{1}{V_{f}(M)} \int_{M} c_{\delta}(r) \mu_{f}$. Here again, this function is $L^{2}\left(\mu_{f}\right)$-orthogonal to the constant functions, so it is a candidate for being a test function. Hence, we have

$$
\begin{aligned}
\lambda_{1} \int_{M}\left(c_{\delta}(r)-\overline{c_{\delta}}\right)^{2} \mu_{f} & \leqslant \int_{M}\left\langle T \nabla\left(c_{\delta}(r)-\overline{c_{\delta}}\right), \nabla\left(c_{\delta}(r)-\overline{c_{\delta}}\right)\right\rangle \mu_{f} \\
& \leqslant \int_{M}\left\langle T \nabla c_{\delta}(r), \nabla c_{\delta}(r)\right\rangle \mu_{f} \\
& \leqslant \delta^{2} \int_{M} s_{\delta}^{2}(r)\langle T \nabla r, \nabla r\rangle \mu_{f} \\
& \leqslant \delta^{2} \int_{M}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f}
\end{aligned}
$$

From this, we deduce immediately that

$$
\begin{equation*}
\lambda_{1} \int_{M} c_{\delta}^{2}(r) \mu_{f} \leqslant \delta^{2} \int_{M}\left\langle T X^{\top}, X^{\top}\right\rangle+\frac{\lambda_{1}}{V_{f}(M)}\left(\int_{M} c_{\delta}(r) \mu_{f}\right)^{2} \tag{15}
\end{equation*}
$$

Now, using the fact that $c_{\delta}^{2}+\delta s_{\delta}^{2}=1,(15)$ plus $\delta$ times (14) gives

$$
\lambda_{1} V_{f}(M) \leqslant \delta \int_{M} \operatorname{tr}(T) \mu_{f}+\left(\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)}\right)^{2}
$$

and thus

$$
\lambda_{1} V_{f}(M)\left(1-\left(\frac{\int_{M} c_{\delta}(r) \mu_{f}}{V_{f}(M)}\right)^{2}\right) \leqslant \delta \int_{M} \operatorname{tr}(T) \mu_{f}
$$

Now, we conclude by using Lemma 3.2 to get the desired upper bound

$$
\lambda_{1} \leqslant \frac{\left(\int_{M} \operatorname{tr}(T) \mu_{f}\right)}{V_{f}(M)}\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \mu_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right)
$$

and this concludes the proof of Theorem 1.1.

Proof of Theorem 1.2. Case $\delta \leqslant 0$. Like in the proof of Theorem 1.1, we will consider $p \in \bar{M}$ as the center of mass of $\Omega,\left\{x_{1}, \ldots, x_{N}\right\}$ the normal coordinates of $\bar{M}$ centered at $p$ and by $r(x)$ the geodesic distance (on $\bar{M}$ ) between $x$ and $p$, for any $x \in \bar{M}$. By the choice of $p$, we have

$$
\int_{M} \frac{s_{\delta}(r)}{r} x_{i} \tilde{\mu}_{f}=0
$$

for any $i \in\{1, \ldots, N\}$, and we can use the functions $\frac{s_{\delta}(r)}{r} x_{i}$ as test functions in the variational characterization of $\sigma_{1}$. Thus, we have

$$
\begin{align*}
\sigma_{1} \int_{M} \sum_{i=1}^{N} \frac{s_{\delta}^{2}(r)}{r^{2}} x_{i}^{2} \widetilde{\mu}_{f} & \leqslant \int_{\Omega} \sum_{i=1}^{N}\left\langle T \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right), \nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right)\right\rangle \mu_{f}  \tag{16}\\
& \leqslant \int_{\Omega}\left(\operatorname{tr}(T)-\delta\left\langle T X^{\top}, X^{\top}\right\rangle\right) \mu_{f}
\end{align*}
$$

where we have used inequality $(12)$ to get the second line. Here, $X=s_{\delta}(r) \bar{\nabla} r$ and $X^{\top}=s_{\delta}(r) \nabla r$ is the tangent component of $X$ to $\Omega$. On the other hand, by item (3) of Lemma 2.1 applied to $\bar{M}$, we have

$$
\delta \int_{\Omega}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f} \geqslant \int_{\Omega} \operatorname{tr}(T) c_{\delta}^{2} \mu_{f}-\int_{\Omega}\left\|H_{T}-T(\nabla f)\right\| s_{\delta} c_{\delta} \mu_{f} .
$$

Reporting into (16), we have

$$
\begin{aligned}
\sigma_{1} \int_{M} s_{\delta}^{2}(r) \widetilde{\mu}_{f} & \leqslant \int_{\Omega}\left(\operatorname{tr}(T)-c_{\delta}^{2}(r) \operatorname{tr}(T)+\left\|H_{T}-T(\nabla f)\right\| s_{\delta}(r) c_{\delta}(r)\right) \mu_{f} \\
& \leqslant \delta \int_{\Omega} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f}+\int_{\Omega}\left\|H_{T}-T(\bar{\nabla} f)\right\| s_{\delta}(r) c_{\delta}(r) \mu_{f} \\
& \leqslant \delta \int_{\Omega} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f}+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\bar{\nabla} f)\right\|}{\operatorname{tr}(T)}\right) \int_{\Omega} \operatorname{tr}(T) s_{\delta}(r) c_{\delta}(r) \mu_{f}
\end{aligned}
$$

From Lemma 4.1 applied on $\Omega$ for the tensor $T$, we have

$$
\int_{\Omega} \operatorname{tr}(T) s_{\delta}(r) c_{\delta}(r) \mu_{f} \leqslant \int_{\Omega}\left\|H_{T}-T(\nabla f)\right\| s_{\delta}^{2}(r) \mu_{f}
$$

which yields to
$\sigma_{1} \int_{M} s_{\delta}^{2}(r) \widetilde{\mu}_{f} \leqslant \int_{\Omega} s_{\delta}^{2}(r)\left[\delta \operatorname{tr}(T)+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\nabla f)\right\|}{\operatorname{tr}(T)}\right)\left\|H_{T}-T(\nabla f)\right\|\right] \mu_{f}$.
Moreover, from the assumption that $\Omega$ is contained in the ball of radius $B(p, R)$, we get that $s_{\delta}(r) \leqslant s_{\delta}(R)$ and thus
$\sigma_{1} \int_{M} s_{\delta}^{2}(r) \widetilde{\mu}_{f} \leqslant s_{\delta}^{2}(R) V_{f}(\Omega) \sup _{\Omega}\left[\delta \operatorname{tr}(T)+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\nabla f)\right\|}{\operatorname{tr}(T)}\right) t\left\|H_{T}-T(\nabla f)\right\|\right]$.
Finally, by Lemma 3.2, we have

$$
\frac{\int_{M} s_{\delta}(r)^{2} \widetilde{\mu}_{f}}{V_{f}(M)} \geqslant \frac{1}{\delta+\frac{\sup _{M}\left\|H_{S}-S(\widetilde{\nabla} f)\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}}
$$

which give the desired estimate when $\delta \leqslant 0$ :

$$
\begin{aligned}
\sigma_{1} \leqslant \sup _{\Omega}[\delta \operatorname{tr}(T) & \left.+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\nabla f)\right\|}{\operatorname{tr}(T)}\right)\left\|H_{T}-T(\bar{\nabla} f)\right\|\right] \\
& \times\left[\delta+\frac{\sup _{M}\left\|H_{S}-S(\widetilde{\nabla} f)\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}\right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R)
\end{aligned}
$$

Case $\delta>0$. Like in the case $\delta \leqslant 0$, we have

$$
\begin{equation*}
\sigma_{1} \int_{M} s_{\delta}^{2}(r) \widetilde{\mu}_{f} \leqslant \int_{\Omega}\left(\operatorname{tr}(T)-\delta\left\langle T X^{\top}, X^{\top}\right\rangle\right) \mu_{f} \tag{17}
\end{equation*}
$$

by using $\frac{s_{\delta}(r)}{r} x_{i}, 1 \leqslant i \leqslant N$ as test functions. In addition, we also use another test function, $c_{\delta}(r)-\widetilde{c_{\delta}}$, with $\widetilde{c_{\delta}}=\frac{1}{V_{f}(M)} \int_{M} c_{\delta}(r) \widetilde{\mu}_{f}$. By a computation analogue to the proof of Theorem 1.1. we have

$$
\begin{aligned}
\sigma_{1} \int_{M}\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right)^{2} \widetilde{\mu}_{f} & \leqslant \int_{\Omega}\left\langle T \nabla\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right), \nabla\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right)\right\rangle \mu_{f} \\
& \leqslant \int_{\Omega}\left\langle T \nabla c_{\delta}(r), \nabla c_{\delta}(r)\right\rangle \bar{\mu}_{f} \\
& \leqslant \delta^{2} \int_{\Omega} s_{\delta}^{2}(r)\langle T \nabla r, \nabla r\rangle \mu_{f} \\
& \leqslant \delta^{2} \int_{\Omega}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f}
\end{aligned}
$$

From this, we deduce

$$
\begin{equation*}
\sigma_{1} \int_{M} c_{\delta}^{2}(r) \widetilde{\mu}_{f} \leqslant \delta^{2} \int_{\Omega}\left\langle T X^{\top}, X^{\top}\right\rangle \mu_{f}+\frac{\sigma_{1}}{V_{f}(M)}\left(\int_{M} c_{\delta}(r) \widetilde{\mu}_{f}\right)^{2} \tag{18}
\end{equation*}
$$

Now, using the fact that $c_{\delta}^{2}+\delta s_{\delta}^{2}=1$, (18) plus $\delta$ times (17) gives

$$
\sigma_{1} V_{f}(M) \leqslant \delta \int_{\Omega} \operatorname{tr}(T) \mu_{f}+\left(\frac{\int_{M} c_{\delta}(r) \widetilde{\mu}_{f}}{V_{f}(M)}\right)^{2}
$$

and so

$$
\sigma_{1} V_{f}(M)\left(1-\left(\frac{\int_{M} c_{\delta}(r) \widetilde{\mu}_{f}}{V_{f}(M)}\right)^{2}\right) \leqslant \delta \int_{\Omega} \operatorname{tr}(T) \mu_{f}
$$

Finally, since we have

$$
1-\left(\frac{\int_{M} c_{\delta}(r) \widetilde{\mu}_{f}}{V_{f}(M)}\right)^{2} \geqslant \frac{1}{1+\frac{\int_{M}\left\|H_{S}-S(\widetilde{\nabla} f)\right\|^{2} \widetilde{\mu}_{f}}{\delta \inf (\operatorname{tr}(S))^{2} V_{f}(M)}}
$$

by Lemma 3.2, we get

$$
\sigma_{1} \leqslant \frac{\int_{\Omega} \operatorname{tr}(T) \mu_{f}}{V_{f}(M)}\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\widetilde{\nabla} f)\right\|^{2} \widetilde{\mu}_{f}}{V_{f}(M) \inf (\operatorname{tr}(S))^{2}}\right)
$$

and this concludes the proof.
Proof of Theorem 1.3. Here again we consider differently the two cases. Case $\delta \leqslant 0$. First, we recall the variational characterization of $\alpha_{1}$ (see [5])

$$
\begin{equation*}
\alpha_{1}=\inf \left\{\left.\frac{\int_{\Omega}\|\bar{\nabla} u\|^{2} d v_{\bar{g}}+b \int_{M}\|\nabla u\|^{2} d v_{\widetilde{g}}}{\int_{M} u^{2} d v_{\widetilde{g}}} \right\rvert\, \int_{M} u d v_{\widetilde{g}}=0\right\} . \tag{19}
\end{equation*}
$$

 desic distance to the center of mass $p$ of $\Omega$ and $\left\{x_{1}, \cdots, x_{N}\right\}$ the normal coordinates of $\bar{M}$ centered at $p$. Hence, we have
$\alpha_{1} \int_{M} \sum_{i=1}^{N} \frac{s_{\delta}^{2}(r)}{r^{2}} x_{i}^{2} d v_{\widetilde{g}} \leqslant \int_{\Omega} \sum_{i=1}^{N}\left\|\bar{\nabla}\left(\frac{s_{\delta}(r)}{r} x_{i}\right)\right\| d v_{\bar{g}}+b \int_{M} \sum_{i=1}^{N}\left\|\nabla\left(\frac{s_{\delta}(r)}{r} x_{i}\right)\right\| d v_{\widetilde{g}}$
that is,

$$
\begin{align*}
\alpha_{1} \int_{M} s_{\delta}(r)^{2} d v_{\widetilde{g}} & \leqslant \int_{\Omega}\left(n-\delta\left\|X^{\top}\right\|^{2}\right) d v_{\bar{g}}  \tag{20}\\
& +b \int_{M}\left((n-1)-\delta\left\|X^{\widetilde{\top}}\right\|^{2}\right) d v_{\widetilde{g}}
\end{align*}
$$

where we use use inequality 12 twice, once on $\Omega$ for the first term and once on $M$ for the second term. Moreover we have, $\left\|X^{\widetilde{\top}}\right\| \leqslant\left\|X^{\top}\right\| \leqslant\|X\|=s_{\delta}(r)$ and since $\delta$ is nonpositive, $s_{\delta}$ is an increasing function. So, by the assumption that $\Omega$ is contained in the ball $B(p, R)$, we have
$\left.\underset{(21)}{\alpha_{1}} \int_{M} s_{\delta}^{2}(r) d v_{\widetilde{g}} \leqslant\left(n-\delta s_{\delta}(R)^{2}\right) V(\Omega)+b(n-1)-\delta s_{\delta}(R)\right) V(M)$

$$
\leqslant(n V(\Omega)+b(n-1) V(M))-\delta s_{\delta}(R)^{2}(V(\Omega)+b V(M))
$$

We conclude by applying Lemma 3.2 , which says for $f=0$,

$$
\frac{\int_{M} s_{\delta}(r)^{2} d v_{\widetilde{g}}}{V(M)} \geqslant \frac{1}{\delta+\frac{\sup _{M}\left\|H_{S}\right\|}{\inf _{M}(\operatorname{tr}(S))^{2}}}
$$

to obtain the desired estimate when $\delta \leqslant 0$, that is,

$$
\alpha_{1} \leqslant\left[n \frac{V(\Omega)}{V(M)}+b(n-1)-\delta s_{\delta}^{2}(R)\left(\frac{V(\Omega)}{V(M)}+b\right)\right]\left(\delta+\frac{\sup _{M}\left\|H_{S}\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}\right)
$$

Case $\delta>0$. Like in the cas $\delta \leqslant 0$, using the functions $\frac{s_{\delta}(r)}{r} x_{i}$ as test functions in the variational characterization of $\alpha_{1}$, we get

$$
\begin{equation*}
\alpha_{1} \int_{M} s_{\delta}^{2}(r) d v_{\widetilde{g}} \leqslant \int_{\Omega}\left(n-\delta\left\|X^{\top}\right\|^{2}\right) d v_{\bar{g}}+b \int_{M}\left((n-1)-\delta\left\|X^{\tilde{\top}}\right\|^{2}\right) d v_{\widetilde{g}} \tag{22}
\end{equation*}
$$

Moreover, we use another test function, $c_{\delta}(r)-\widetilde{c_{\delta}}$ with $\widetilde{c_{\delta}}=\frac{1}{V(M)} \int_{M} c_{\delta}(r) d v_{\widetilde{g}}$.

$$
\begin{aligned}
\alpha_{1} \int_{M}\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right)^{2} d v_{\widetilde{g}} \leqslant & \int_{\Omega}\left\langle\nabla\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right), \nabla\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right)\right\rangle d v_{g} \\
& +b \int_{M}\left\langle\widetilde{\nabla}\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right), \widetilde{\nabla}\left(c_{\delta}(r)-\widetilde{c_{\delta}}\right)\right\rangle d v_{\widetilde{g}} \\
\leqslant & \int_{\Omega}\left\langle\nabla c_{\delta}(r), \nabla c_{\delta}(r)\right\rangle d v_{g}+b \int_{M}\left\langle\widetilde{\nabla} c_{\delta}(r), \widetilde{\nabla} c_{\delta}(r)\right\rangle d v_{\widetilde{g}} \\
\leqslant & \delta^{2} \int_{\Omega} s_{\delta}^{2}(r)\langle\nabla r, \nabla r\rangle d v_{g}+b \delta^{2} \int_{M} s_{\delta}^{2}(r)\langle\widetilde{\nabla} r, \widetilde{\nabla} r\rangle d v_{\widetilde{g}} \\
\leqslant & \delta^{2} \int_{\Omega}\left\|X^{\top}\right\|^{2} d v_{g}+b \delta^{2} \int_{M}\left\|X^{\widetilde{\top}}\right\|^{2} d v_{\widetilde{g}}
\end{aligned}
$$

where $X^{\top}=s_{\delta}(r) \nabla r$ is the tangent component of $X$ to $\Omega$ and $X^{\widetilde{\top}}=s_{\delta}(r) \widetilde{\nabla} r$ is the part of $X$ tangent to $M$. From this, we get

$$
\begin{align*}
\alpha_{1} \int_{M} c_{\delta}(r)^{2} d v_{\widetilde{g}} & \leqslant \delta^{2} \int_{\Omega}\left\|X^{\top}\right\|^{2} d v_{g}+b \delta^{2} \int_{M}\left\|X^{\widetilde{\top}}\right\|^{2} d v_{\widetilde{g}} \\
& +\frac{\alpha_{1}}{V(M)}\left(\int_{M} c_{\delta}(r) d v_{\widetilde{g}}\right)^{2} . \tag{23}
\end{align*}
$$

Hence summing (23) and $\delta$ times (22), using the fact that $c_{\delta}^{2}+\delta s_{\delta}^{2}=1$, gives

$$
\alpha_{1} V(M) \leqslant \delta(n V(\Omega)+b(n-1) V(M))+\frac{\alpha_{1}}{V(M)}\left(\int_{M} c_{\delta}(r) d v_{\widetilde{g}}\right)^{2}
$$

and so

$$
\alpha_{1} V(M)\left(1-\left(\frac{1}{V(M)} \int_{M} c_{\delta}(r) d v_{\widetilde{g}}\right)^{2}\right) \leqslant \delta(n V(\Omega)+b(n-1) V(M))
$$

Moreover, from we have Lemma 3.2 (with $f=0$ ), we have

$$
1-\left(\frac{\int_{M} c_{\delta}(r) d v_{\widetilde{g}}}{V(M)}\right)^{2} \geqslant \frac{1}{1+\frac{\int_{M}\left\|H_{S}\right\|^{2} d v_{\widetilde{g}}}{\delta \inf (\operatorname{tr}(S))^{2} V(M)}}
$$

which gives

$$
\alpha_{1} V(M) \leqslant \delta(n V(\Omega)+b(n-1) V(M))\left(\delta+\frac{\int_{M}\left\|H_{S}\right\|^{2} d v_{\widetilde{g}}}{V(M) \inf (\operatorname{tr}(S))^{2}}\right)
$$

and finally the desired estimate

$$
\alpha_{1} \leqslant\left(n \frac{V(\Omega)}{V(M)}+b(n-1)\right)\left(\delta+\frac{\int_{M}\left\|H_{S}\right\|^{2} d v_{\widetilde{g}}}{V(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right)
$$

This concludes the proof.

## 5. A REmark about the case $\delta>0$

The aim of this section is to compare the estimates in both case $\delta>0$ and $\delta \leqslant 0$. Indeed, in the estimates of Theorems 1.2 the radius $R$ of a ball containing $\Omega$ appears when $\delta \leqslant 0$ but not for the estimates for $\delta>0$. It turns out that when $\delta>0$, we can bound the radius $R$ from above in terms of $H_{T}$ and $\operatorname{tr} T$ and so obtain upper bounds comparable to those obtained for $\delta \leqslant 0$. First, we have the following

Proposition 5.1. Let $\left(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_{f}\right)$ be a weighted Riemannian manifold with sectional curvature sect $\bar{M} \leqslant \delta$, with $\delta>0$, and $\bar{\mu}_{f}=e^{-f} d v_{\bar{g}}$. Let $(\Omega, g)$ be a compact Riemannian manifold with non-empty boundary $M$ isometrically immersed into $\left(\bar{M}^{n+p}, \bar{g}\right)$ by $X$. We endow $\Omega$ with the weighted measure $\mu_{f}=e^{-f} d v_{g}$. Let $T$ be a symmetric, divergence-free and positive definite $(1,1)$-tensor on $\Omega$. If $\Omega$ is contained a ball of radius $R$, then

$$
s_{\delta}^{2}(R)\left(\frac{\left\|H_{T}-T \nabla f\right\|_{\infty}^{2}}{\inf _{\Omega}(\operatorname{tr}(T))^{2}}+\delta\right) \geqslant 1
$$

Proof. From the second part of Lemma 2.1 applied on $\Omega$, we have

$$
\int_{\Omega} c_{\delta}(r) \operatorname{tr}(T) \mu_{f} \leqslant-\int_{\Omega}\left\langle X, H_{T}-T \nabla f\right\rangle \mu_{f}
$$

We recall that $X=s_{\delta}(r) \nabla r$, which gives

$$
\int_{\Omega} c_{\delta}(r) \operatorname{tr}(T) \mu_{f} \leqslant \int_{\Omega}\left\|H_{T}-T \nabla f\right\| s_{\delta}(r) \mu_{f}
$$

We are in the case where $\delta>0$, so $c_{\delta}$ and $s_{\delta}$ are respectively decreasing and increasing on $\left[0, \frac{\pi}{2 \sqrt{\delta}}\right]$. Moreover, $\Omega$ is contained in a ball of radius $R<\frac{\pi}{4 \sqrt{\delta}}$ which implies that $\Omega$ is contained in a ball of radius $\frac{\pi}{2 \sqrt{\delta}}$ centered at $p$. Hence, $r<R$ and so $c d(r) \geqslant c_{\delta}(R)$ and $s_{\delta}(r) \leqslant s_{\delta}(R)$ on $\Omega$. Thus, we get

$$
c_{\delta}(R) \inf _{\Omega}(\operatorname{tr}(T)) \leqslant s_{\delta}(R) \sup _{\Omega}\left\|H_{T}-T \nabla f\right\|
$$

We deduce easily from this and the fact that $c_{\delta}^{2}+\delta s_{\delta}^{2}=1$ that

$$
s_{\delta}^{2}(R)\left(\frac{\left\|H_{T}-T \nabla f\right\|_{\infty}^{2}}{\inf _{\Omega}(\operatorname{tr}(T))^{2}}+\delta\right) \geqslant 1
$$

which concludes the proof of the proposition.
Now, using the above proposition together with the estimate of Theorem 1.2 in the case $\delta>0$, we get the following estimate

$$
\begin{aligned}
\sigma_{1} & \leqslant\left(\frac{\left\|H_{T}-T \nabla f\right\|_{\infty}^{2}}{\inf _{\Omega}(\operatorname{tr}(T))^{2}}+\delta\right)\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \widetilde{\mu}_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right) \frac{\int_{\Omega} \operatorname{tr}(T) \mu_{f}}{V_{f}(M)} s_{\delta}^{2}(R) \\
& \leqslant \sup _{\Omega}(\operatorname{tr}(T))\left(\frac{\left\|H_{T}-T \nabla f\right\|_{\infty}^{2}}{\inf _{\Omega}(\operatorname{tr}(T))^{2}}+\delta\right)\left(\delta+\frac{\int_{M}\left\|H_{S}-S(\nabla f)\right\|^{2} \widetilde{\mu}_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)^{2}\right)}\right) \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R)
\end{aligned}
$$

which is comparable to the estimate for the case $\delta \leqslant 0$ :

$$
\begin{aligned}
\sigma_{1} \leqslant \sup _{\Omega}[\delta \operatorname{tr}(T) & \left.+\sup _{\Omega}\left(\frac{\left\|H_{T}-T(\bar{\nabla} f)\right\|}{\operatorname{tr}(T)}\right)\left\|H_{T}-T(\bar{\nabla} f)\right\|\right] \\
& \times\left[\delta+\frac{\sup _{M}\left\|H_{S}-S(\nabla f)\right\|^{2}}{\inf _{M}(\operatorname{tr}(S))^{2}}\right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R)
\end{aligned}
$$

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