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## EXTRINSIC EIGENVALUES UPPER BOUNDS FOR SUBMANIFOLDS IN WEIGHTED MANIFOLDS

FERNANDO MANFIO, JULIEN ROTH, AND ABHITOSH UPADHYAY

ABSTRACT. We prove Reilly-type upper bounds for divergence-type operators of the second order as well as for Steklov problems on submanifolds of Riemannian manifolds of bounded sectional curvature endowed with a weighted measure.

MSC 2010: 53C24, 53C42, 58J50.

**Key words:** Submanifolds, Reilly-type upper bounds, eigenvalues estimates, divergence-type operators, Steklov problems.

#### 1. Introduction

Let  $(M^n, g)$  be an n-dimensional compact, connected, oriented manifold without boundary, and consider an isometric immersion  $X: M^n \to \mathbb{R}^{n+1}$  in the Euclidean space. The spectrum of Laplacian of (M, g) is an increasing sequence of real numbers

$$0 = \lambda_0(\Delta) < \lambda_1(\Delta) \leqslant \lambda_2(\Delta) \leqslant \cdots \leqslant \lambda_k(\Delta) \leqslant \cdots \longrightarrow +\infty.$$

The eigenvalue 0 (corresponding to constant functions) is simple and  $\lambda_1(\Delta)$  is the first positive eigenvalue. In [12], Reilly proved the following well-known upper bound for  $\lambda_1(\Delta)$ 

(1) 
$$\lambda_1(\Delta) \leqslant \frac{n}{V(M)} \int_M H^2 dv_g,$$

where H is the mean curvature of the immersion. He also proved an analogous inequality involving the higher order mean curvatures. Namely, for  $r \in \{1, \dots, n\}$ 

(2) 
$$\lambda_1(\Delta) \left( \int_M H_{r-1} dv_g \right)^2 \leqslant V(M) \int_M H_r^2 dv_g,$$

where  $H_r$  is the r-th mean curvature, defined by the r-th symmetric polynomial of the principal curvatures. Moreover, Reilly studied the equality cases and proved that equality in (1) or (2) is attained if and only if X(M) is a geodesic sphere.

In the case of higher codimension, Reilly also proved that

(3) 
$$\lambda_1(\Delta) \leqslant \frac{n}{V(M)} \int_M \|\mathbf{H}\|^2 dv_g,$$

where  $\mathbf{H}$  is here the mean curvature vector, with equality if and only if M is minimally immersed in a geodesic sphere.

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The Reilly inequality can be easily extended to submanifolds of the sphere  $\mathbb{S}^n$  using the canonical embedding of  $\mathbb{S}^n$  into  $\mathbb{R}^{n+1}$ :

(4) 
$$\lambda_1(\Delta) \leqslant \frac{n}{V(M)} \int_M (\|\mathbf{H}\|^2 + 1) dv_g.$$

Moreover, El Soufi and Ilias [7] proved an analogue for submanifold of the hyperbolic space as

(5) 
$$\lambda_1(\Delta) \leqslant \frac{n}{V(M)} \int_M (\|\mathbf{H}\|^2 - 1) dv_g.$$

In case the ambient space has non-constant sectional curvature, Heintze [10] proved the following weaker inequality

(6) 
$$\lambda_1(\Delta) \leqslant n(\|\mathbf{H}\|^2 + \delta),$$

where the ambient sectional curvature is bounded above by  $\delta$ .

On the other hand, more recently, in [14], the second author prove the following general inequality

(7) 
$$\lambda_1(L_{T,f}) \left( \int_M \operatorname{tr}(S) \mu_f \right)^2 \leqslant \left( \int_M \operatorname{tr}(T) \mu_f \right) \int_M \left( \|H_S\|^2 + \|S\nabla f\|^2 \right) \mu_f,$$

where  $\mu_f = e^{-f} dv_g$  is the weighted measure of (M, g) endowed with the density  $e^{-f}$ , T, S are two symmetric, free-divergence (1, 1)-tensors with T positive definite, and  $L_{T,f}$  is the second order differential operator defined for any smooth function u on M by

$$L_{T,f} = -\text{div}(T\nabla u) + \langle \nabla f, T\nabla u \rangle.$$

When f = 0 and the tensor S and T are associated with higher order mean curvatures  $H_s$  and  $H_r$ , we recover the inequality of Alias and Malacarné [2] and, in particular, Reilly's inequality (2) if r = 0.

The first result of this paper gives upper bounds for the first eigenvalue of the operator  $L_{T,f}$  for submanifolds of Riemannian manifolds with sectional curvature bounded by above which generalizes inequality (7) in the non-constant curvature case. Namely, we prove the following.

**Theorem 1.1.** Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $\operatorname{sect}_{\bar{M}} \leq \delta$  and  $\bar{\mu}_f = e^{-f} dv_{\bar{g}}$ . Let (M,g) be a closed Riemannian manifold isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$  by X. We endow M with the weighted measure  $\mu_f = e^{-f} dv_g$ . Let T be a positive definite (1,1)-tensor on M and denote by  $\lambda_1$  the first positive eigenvalue of the operator  $L_{T,f}$ .

(1) If  $\delta \leq 0$ , then

$$\lambda_{1} \leqslant \sup_{M} \left[ \delta \operatorname{tr} \left( T \right) + \sup_{M} \left( \frac{\|H_{T} - T \nabla f\|}{\operatorname{tr} \left( S \right)} \right) \|H_{S} - S \nabla f\| \right].$$

(2) If  $\delta > 0$  and X(M) is contained in a geodesic ball of radius  $\frac{\pi}{4\sqrt{\delta}}$ ,

$$\lambda_1 \leqslant \frac{\left(\int_M \operatorname{tr}(T)\mu_f\right)}{V_f(M)} \left(\delta + \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{V_f(M) \inf\left(\operatorname{tr}(S)^2\right)}\right).$$

The second eigenvalue problem that we consider in this paper is the Steklov problem associated with the operator  $L_{T,f}$  on a submanifold  $\Omega$  with non-empty boundary  $\partial\Omega=M$  of a Riemannian manifold with sectional curvature bounded by above. We can consider the following generalized weighted Steklov problem

(8) 
$$\begin{cases} L_{T,f}u = 0 & \text{on } \Omega, \\ \frac{\partial u}{\partial \nu_T} = \sigma u & \text{on } M = \partial \Omega, \end{cases}$$

where  $\frac{\partial u}{\partial \nu_T} = \langle T(\widetilde{\nabla} u), \nu \rangle$ . In the case where f is constant, the operator  $L_{T,f}$  is of particular interest for the study of r-stability when  $T = T_r$  is the tensor associated with r-th mean curvature (see [1] for instance). More precisely, from [3], we know that this problem (8) has a discrete nonnegative spectrum and we denote by  $\sigma_1$  its first eigenvalue. In [13], the second author has obtained upper bounds for this problem for domains of a manifold lying in a Euclidean space. Namely, he has proved

$$\sigma_1 \left( \int_M \operatorname{tr}(S) \widetilde{\mu}_f \right)^2 \leqslant \left( \int_{\Omega} \operatorname{tr}(T) \mu_f \right) \int_M \left( ||H_S||^2 + ||S\nabla f||^2 \right) \widetilde{\mu}_f,$$

where  $\mu_f = e^{-f} dv_g$  and  $\widetilde{\mu}_f = e^{-f} dv_{\widetilde{g}}$  are respectively, the weighted measures of  $(\Omega, g)$  and  $(M, \widetilde{g})$  endowed with the density  $e^{-f}$  and where T and S are two symmetric, free-divergence (1, 1)-tensors with T positive definite. Note that without density and for  $T = \mathrm{Id}$ , this inequality has been proven by Ilias and Makhoul [11].

The second result of the present paper gives a generalization of this estimate when the manifold with boundary (M,g) is immersed into an ambient Riemannian manifold of sectional curvature bounded by above. Namely, we prove the following.

**Theorem 1.2.** Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $\operatorname{sect}_{\bar{M}} \leq \delta$  and  $\bar{\mu}_f = e^{-f} dv_{\bar{g}}$ . Let  $(\Omega, g)$  be a compact Riemannian manifold with non-empty boundary M isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$  by X. We endow  $\Omega$  and M, respectively with the weighted measure  $\mu_f = e^{-f} dv_g$  and  $\tilde{\mu}_f = e^{-f} dv_{\bar{g}}$ , where  $\tilde{g}$  is the induced metric on M. Let T, S be a symmetric, divergence-free and positive definite (1,1)-tensors on  $\Omega$  and M, respectively, and denote by  $\sigma_1$  the first eigenvalue of the Steklov problem (8).

(1) If  $\delta \leq 0$  and  $X(\Omega)$  is contained in the geodesic ball B(p,R) or radius R, where p is the center of mass of M for the measure  $\widetilde{\mu}_f$ , then

$$\sigma_{1} \leqslant \sup_{\Omega} \left[ \delta \operatorname{tr} \left( T \right) + \sup_{\Omega} \left( \frac{\|H_{T} - T(\overline{\nabla}f)\|}{\operatorname{tr} \left( T \right)} \right) \|H_{T} - T(\overline{\nabla}f)\| \right]$$

$$\times \left[ \delta + \frac{\sup_{M} \|H_{S} - S(\nabla f)\|^{2}}{\inf_{M} \left( \operatorname{tr} \left( S \right) \right)^{2}} \right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R).$$

(2) If  $\delta > 0$  and  $X(\Omega)$  is contained in a geodesic ball of radius  $\frac{\pi}{4\sqrt{\delta}}$ , then

$$\sigma_1 \leqslant \frac{\int_{\Omega} \operatorname{tr}(T)\mu_f}{V_f(M)} \left( \delta + \frac{\int_{M} \|H_S - S(\nabla f)\|^2 \widetilde{\mu}_f}{V_f(M) \inf \left(\operatorname{tr}(S)^2\right)} \right).$$

Finally, we will consider the so-called eigenvalue problem for Wentzell boundary conditions

(SW) 
$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ -b\widetilde{\Delta}u - \frac{\partial u}{\partial \nu} = \alpha u & \text{on } M \end{cases},$$

where b is a given positive constant,  $\Omega$  is a submanifold with non-empty boundary  $\partial\Omega=M$  of a Riemannian manifold M with sectional curvature bounded by above, and  $\Delta$ ,  $\widetilde{\Delta}$  denote the Laplacians on  $\Omega$  and M, respectively. It is clear that if b=0, then we recover the classical Steklov problem. The spectrum of this problem is an increasing sequence (see [5]) with 0 as first eigenvalue which is simple and the corresponding eigenfunctions are the constant ones. We denote by  $\alpha_1$  the first positive eigenvalue. In [14], the second author proved the following estimate when  $\Omega$  is a submanifold of the Euclidean space  $\mathbb{R}^n$ 

$$\alpha_1 \left( \int_{\partial M} \operatorname{tr}(S) dv_g \right)^2 \leq \left( nV(M) + b(n-1)V(\partial M) \right) \left( \int_{\partial M} \|H_S\|^2 dv_g \right).$$

In the following theorem, we obtain a comparable estimate when the ambient space is of bounded sectional curvature. Namely, we prove

**Theorem 1.3.** Let  $(\bar{M}^{n+p}, \bar{g})$  be a Riemannian manifold with sectional curvature  $sect_{\bar{M}} \leq \delta$ . Let  $(\Omega, g)$  be a compact Riemannian manifold with non-empty boundary M isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$  by X. We denote by  $\tilde{g}$  the induced metric on M. Let S be a symmetric, divergence-free and positive definite (1,1)-tensor on M and denote by  $\alpha_1$  the first eigenvalue of the Steklov-Wentzell problem (SW).

(1) If  $\delta \leq 0$  and  $X(\Omega)$  is contained in the geodesic ball B(p,R) or radius R, where p is the center of mass of  $\overline{M}$ , then

$$\alpha_1 \leqslant \left[ n \frac{V(\Omega)}{V(M)} + b(n-1) - \delta s_{\delta}^2(R) \left( \frac{V(\Omega)}{V(M)} + b \right) \right] \left( \delta + \frac{\sup_M \|H_S\|^2}{\inf_M (\operatorname{tr}(S))^2} \right).$$

(2) If  $\delta > 0$  and so  $X(\Omega)$  is contained in a geodesic ball of radius  $\frac{\pi}{4\sqrt{\delta}}$ , then

$$\alpha_1 \le \left(n \frac{V(\Omega)}{V(M)} + b(n-1)\right) \left(\delta + \frac{\int_M \|H_S\|^2 dv_{\widetilde{g}}}{V(M)\inf(\operatorname{tr}(S)^2)}\right).$$

#### 2. Preliminaries

Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $sect_{\bar{M}} \leq \delta$  and weighted measure  $\bar{\mu}_f = e^{-f} dv_{\bar{g}}$ . Let p a fixed point in  $\bar{M}$ , we denote by r(x) the geodesic distance between x and p. Moreover, we define the vector field X by  $X(x) := s_{\delta}(r(x))(\bar{\nabla}r)(x)$ ,  $s_{\delta}$  is the function defined by

$$s_{\delta}(r) = \begin{cases} \frac{1}{\sqrt{\delta}} \sin(\sqrt{\delta}r) & \text{if } \delta > 0\\ r & \text{if } \delta = 0\\ \frac{1}{\sqrt{|\delta|}} \sinh(\sqrt{|\delta|}r) & \text{if } \delta < 0. \end{cases}$$

We also define

$$c_{\delta}(r) = \begin{cases} \cos(\sqrt{\delta}r) & \text{if } \delta > 0\\ 1 & \text{if } \delta = 0\\ \cosh(\sqrt{|\delta|}r) & \text{if } \delta < 0. \end{cases}$$

Hence, we have

$$c_{\delta}^2 + \delta s_{\delta}^2 = 1$$
,  $s_{\delta}' = c_{\delta}$  and  $c_{\delta}' = -\delta s_{\delta}$ .

In addition, let  $(M^n,g)$  be a closed Riemannian manifold isometrically immersed into  $(\bar{M}^{n+p},\bar{g})$  by  $\phi$ . If  $\delta>0$ , then we assume that  $\phi(M)$  is contained in a geodesic ball of radius  $\frac{\pi}{2\sqrt{\delta}}$ . We endow M with the weighted measure  $\mu_f=e^{-f}dv_g$ . We can define on M a divergence associated with the volume form  $\mu_f=e^{-f}dv_g$  by

$$\operatorname{div}_{f} Y = \operatorname{div} Y - \langle \nabla f, Y \rangle$$

or, equivalently,

$$d(\iota_Y \mu_f) = \operatorname{div}_f(Y) \mu_f,$$

where  $\nabla$  is the gradient on  $\Sigma$ , that is, the projection on  $T\Sigma$  of the gradient  $\bar{\nabla}$  on  $\bar{M}$ . We call it the f-divergence. We recall briefly some basic facts about the f-divergence. In the case where  $\Sigma$  is closed, we first have the weighted version of the divergence theorem:

(9) 
$$\int_{\Sigma} \operatorname{div}_{f} Y \ \mu_{f} = 0,$$

for any vector field Y on  $\Sigma$ . From this, we deduce easily the integration by parts formula

(10) 
$$\int_{\Sigma} u \operatorname{div}_{f} Y \ \mu_{f} = -\int_{\Sigma} \langle \nabla u, Y \rangle \ \mu_{f},$$

for any smooth function u and any vector field Y on  $\Sigma$ . First, we prove the following elementary lemma which generalize in non constant curvature the classical Hsiung-Minkowski formula (see [8, 13] for instance).

**Lemma 2.1.** Let T be a symmetric divergence-free positive (1,1)-tensor on M. Then the following hold

(1) 
$$\operatorname{div}_f(TX^\top) \geqslant \operatorname{tr}(T)c_\delta + \langle X, H_T - T(\nabla f) \rangle.$$

(2) 
$$\int_{M} \operatorname{tr}(T) c_{\delta} \mu_{f} \leqslant -\int_{M} \langle X, H_{T} - T(\nabla f) \rangle \mu_{f}.$$

(3) 
$$\delta \int_{M} \langle TX^{\top}, X^{\top} \rangle \mu_{f} \geqslant \int_{M} \operatorname{tr}(T) c_{\delta}^{2} \mu_{f} - \int_{M} \|H_{T} - T(\nabla f)\| s_{\delta} c_{\delta} \mu_{f}.$$

*Proof.* The proof is a straightforward consequence of the analogue non-weighted result proven by Grosjean. Namely, in [8], the author has shown that

$$\operatorname{div}_{M}(TX^{\top}) \geqslant \operatorname{tr}(T)c_{\delta}(r) + \langle X, H_{T} \rangle.$$

Hence, from the definition of the f-divergence, we have

$$\operatorname{div}_{f}(TX^{\top}) = \operatorname{div}(TX^{\top}) - \langle \nabla f, TX^{\top} \rangle$$
  
 
$$\geqslant \operatorname{tr}(T)c_{\delta}(r) + \langle X, H_{T} - T(\nabla f) \rangle,$$

and this proves part (1). For the second part, we integrate the last inequality with respect to the measure  $\mu_f$  and we get immediately

$$\int_{M} \operatorname{tr}(T) c_{\delta} \mu_{f} \leqslant -\int_{M} \langle X, H_{T} - T(\nabla f) \rangle \mu_{f},$$

since

$$\int_{M} \operatorname{div}_{f}(TX^{\top}) \mu_{f} = 0.$$

Finally, for the last part, if  $\delta = 0$ , then  $c_{\delta} = 1$  and we get directly the conclusion from the second one by using

$$|\langle X, H_T - T(\nabla f) \rangle| \leqslant ||X|| \cdot ||H_T - T(\nabla f)|| = s_\delta ||H_T - T(\nabla f)||.$$

If  $\delta \neq 0$ , since  $X^{\top} = s_{\delta}(r)\nabla r = -\delta \nabla c_{\delta}(r)$ , then we have

$$\begin{split} \delta \int_{M} \langle TX^{\top}, X^{\top} \rangle \mu_{f} &= \frac{1}{\delta} \int_{M} \langle T(\nabla c_{\delta}, \nabla c_{\delta}) \mu_{f} \\ &= -\frac{1}{\delta} \int_{M} \operatorname{div}_{f} (T \nabla c_{\delta}) c_{\delta} \mu_{f} \\ &= \int_{M} \operatorname{div}_{f} (X^{\top}) c_{\delta} \mu_{f} \\ &\geqslant \int_{M} \operatorname{tr} (T) c_{\delta}^{2} \mu_{f} - \int_{M} \|H_{T} - T(\nabla f)\| s_{\delta} c_{\delta} \mu_{f}, \end{split}$$

where we have used the first part of the lemma and the well-known Cuachy-Schwarz inequality.  $\hfill\Box$ 

#### 3. Two key lemma

In this section we will prove two basic key lemma that will be used throughout the paper.

**Lemma 3.1.** Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $\operatorname{sect}_{\bar{M}} \leq \delta \leq 0$ , and  $\bar{\mu}_f = e^{-f} dv_{\bar{g}}$ . Let (M,g) be a closed Riemannian manifold isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$ , and we endow M with the weighted measure  $\mu_f = e^{-f} dv_g$ . Let S be a symmetric, divergence-free and positive definite (1,1)-tensor on M. Then, we have

$$\frac{\int_{M} ||X||^{2} \mu_{f}}{V_{f}(M)} \geqslant \frac{1}{\delta + \frac{||H_{S} - S(\nabla f)||_{\infty}^{2}}{\inf(\operatorname{tr}(S))^{2}}}.$$

*Proof.* We have

$$\begin{split} &\int_{M} \left( \operatorname{tr}\left( S \right) - \delta \langle SX^{\top}, X^{\top} \rangle \right) \mu_{f} = \int_{M} \left( \operatorname{tr}\left( S \right) - \operatorname{div}(SX^{\top}) c_{\delta}(r) \right) \mu_{f} \\ &\leqslant \int_{M} \left( \operatorname{tr}\left( S \right) - \operatorname{tr}\left( S \right) c_{\delta}^{2}(r) - \langle H_{S} - S(\nabla f), X \rangle c_{\delta}(r) \right) \mu_{f} \\ &\leqslant \int_{M} \left( \delta \operatorname{tr}\left( S \right) s_{\delta}^{2}(r) - \langle H_{S} - S(\nabla f), X \rangle c_{\delta}(r) \right) \mu_{f} \\ &\leqslant \int_{M} \left( \delta \operatorname{tr}\left( S \right) s_{\delta}^{2}(r) + \frac{\|H_{S} - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}\left( S \right))} \int_{M} \operatorname{tr}\left( S \right) s_{\delta}(r) c_{\delta}(r) \right) \mu_{f} \\ &\leqslant \frac{\|H_{S} - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}\left( S \right))} \int_{M} \left( s_{\delta}(r) \operatorname{div}(SX^{\top}) - s_{\delta}(r) \langle H_{S} - S(\nabla f), X \rangle \right) \mu_{f} \\ &+ \delta \inf(\operatorname{tr}\left( S \right)) \int_{M} s_{\delta}^{2}(r) \mu_{f} \\ &\leqslant - \frac{\|H_{S} - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}\left( S \right))} \int_{M} \left( c_{\delta}(r) s_{\delta}(r) \langle S\nabla^{M} r, \nabla^{M} r \rangle + s_{\delta}^{2}(r) \langle H_{S} - S(\nabla f), \nabla^{M} r \rangle \right) \mu_{f} \\ &+ \delta \inf(\operatorname{tr}\left( S \right)) \int_{M} s_{\delta}^{2}(r) \mu_{f} \end{split}$$

$$\leq \left( \delta \inf(\operatorname{tr}(S)) + \frac{\|H_S - S(\nabla f)\|_{\infty}^2}{\inf(\operatorname{tr}(S))} \right) \int_M s_{\delta}^2(r) \mu_f$$

$$- \frac{\|H_S - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}(S))} \int_M c_{\delta}(r) s_{\delta}(r) \langle S \nabla^M r, \nabla^M r \rangle \mu_f.$$

Hence, we get

$$\int_{M} \operatorname{tr}(S)\mu_{f} \leq \left(\delta \inf(\operatorname{tr}(S)) + \frac{\|H_{S} - S(\nabla f)\|_{\infty}^{2}}{\inf(\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r)\mu_{f} 
- \frac{\|H_{S} - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}(S))} \int_{M} c_{\delta}(r)s_{\delta}(r)\langle S\nabla^{M}r, \nabla^{M}r\rangle\mu_{f} 
+ \delta \int_{M} s_{\delta}^{2}(r)\langle S\nabla^{M}r, \nabla^{M}r\rangle\mu_{f} 
\leq \left(\delta \inf(\operatorname{tr}(S)) + \frac{\|H_{S} - S(\nabla f)\|_{\infty}^{2}}{\inf(\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r)\mu_{f} 
+ \int_{M} \left(\delta s_{\delta}^{2}(r) - c_{\delta}(r)s_{\delta}(r) \frac{\|H_{S} - S(\nabla f)\|_{\infty}}{\inf(\operatorname{tr}(S))}\right) \langle S\nabla^{M}r, \nabla^{M}r\rangle\mu_{f}.$$

Since  $\delta \leq 0$ , the second term of the right hand side is nonpositive, and thus we get

$$\inf(\operatorname{tr}(S))V_{f}(M) \leq \int_{M} \operatorname{tr}(S)\mu_{f}$$

$$\leq \left(\delta \inf(\operatorname{tr}(S)) + \frac{\|H_{S} - S(\nabla f)\|_{\infty}^{2}}{\inf(\operatorname{tr}(S))}\right) \int_{M} s_{\delta}^{2}(r)\mu_{f},$$

which gives immediately the result since  $||X|| = s_{\delta}(r)$ .

**Lemma 3.2.** Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $sect_{\bar{M}} \leq \delta$ , with  $\delta > 0$ , and  $\bar{\mu}_f = e^{-f}dv_{\bar{g}}$ . Let (M,g) be a closed Riemannian manifold isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$  by X so that X(M) is contained in a geodesic ball of radius  $\frac{\pi}{2\sqrt{\delta}}$ . We endow M with the weighted measure  $\mu_f = e^{-f}dv_g$ . Let S be a symmetric, divergence-free and positive definite (1,1)-tensor on M. Then, we have

$$1 - \left(\frac{\int_{M} c_{\delta}(r)\mu_{f}}{V_{f}(M)}\right)^{2} \geqslant \frac{1}{1 + \frac{\int_{M} ||H_{S} - S(\nabla f)||^{2}\mu_{f}}{\delta \inf(\operatorname{tr}(S))^{2}V_{f}(M)}}.$$

*Proof.* For a sake of compactness, we will write

$$\alpha = \frac{\int_{M} c_{\delta}(r)\mu_{f}}{V_{f}(M)} \quad \text{and} \quad \beta = 1 + \frac{\int_{M} \|H_{S} - S(\nabla f)\|^{2} \mu_{f}}{\delta \inf(\operatorname{tr}(S))^{2} V_{f}(M)}.$$

We thus have to show that  $(1 - \alpha^2)\beta \ge 1$ . We have

$$\begin{split} (1-\alpha^2)\beta &= \beta - \left(\frac{\int_M c_\delta(r)\mu_f}{V_f(M)}\right)^2 - \left(\frac{\int_M c_\delta(r)\mu_f}{V_f(M)}\right)^2 \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)} \\ &\geqslant \beta - \left(\frac{\int_M \operatorname{tr}(S)c_\delta(r)\mu_f}{\inf(\operatorname{tr}(S))V_f(M)}\right)^2 - \left(\frac{\int_M c_\delta(r)^2 \mu_f}{V_f(M)}\right) \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)} \\ &\geqslant \beta - \left(\frac{\int_M s_\delta(r)\|H_S - S(\nabla f)\|\mu_f}{\inf(\operatorname{tr}(S))V_f(M)}\right)^2 - \left(\frac{\int_M c_\delta(r)^2 \mu_f}{V_f(M)}\right) \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)} \\ &\geqslant \beta - \frac{\left(\int_M s_\delta^2(r)\mu_f\right) \left(\int_M \|H_S - S(\nabla f)\|^2 \mu_f\right)}{\inf(\operatorname{tr}(S))^2 V_f(M)^2} \\ &- \left(\frac{\int_M c_\delta(r)^2 \mu_f}{V_f(M)}\right) \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)} \\ &\geqslant \beta - \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)^2} \left(\int_M (s_\delta^2(r) + \delta^2 c_\delta^2(r)) \mu_f\right) \\ &= \beta - \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{\delta \inf(\operatorname{tr}(S))^2 V_f(M)} \\ &= 1, \end{split}$$

and this concludes the proof.

#### 4. Proofs of the Theorems

Proof of Theorem 1.1. Case  $\delta \leq 0$ . Let  $p \in \overline{M}$  be a fixed point and let  $\{x_1, \dots, x_N\}$  be the normal coordinates of  $\overline{M}$  centered at p. For any  $x \in \overline{M}$ , r(x) is the geodesic distance between p and x over  $\overline{M}$ . We want to use as test functions the functions

$$\frac{s_{\delta}(r)}{r}x_{i},$$

for  $1 \le i \le N$ . For this purpose, we will choose p as the center of mass of M with respect for the measure  $\mu_f$ , that is, p is the only point in M so that

$$\int_{M} \frac{s_{\delta}(r)}{r} x_{i} \mu_{f} = 0,$$

for any  $i\in\{1,\cdots,N\}$ . Note at that point that we assume that M is contained in a ball of radius  $\frac{\pi}{4\sqrt{\delta}}$  when  $\delta$  is positive allows us to ensure that M is contained in a ball of radius  $\frac{\pi}{4\sqrt{\delta}}$  centered at p. This holds also for Theorems 1.2 and 1.3. These

functions are candidates for test functions since they are  $L^2(\mu_f)$ -orthogonal to the constant functions which are the eigenfunctions for the first eigenvalue  $\lambda_0 = 0$ . Thus, we have

(11) 
$$\lambda_1 \int_M \sum_{i=1}^N \frac{s_{\delta}^2(r)}{r^2} x_i^2 \mu_f \leqslant \int_M \sum_{i=1}^N \left\langle T \nabla \left( \frac{s_{\delta}(r)}{r} x_i \right), \nabla \left( \frac{s_{\delta}(r)}{r} x_i \right) \right\rangle \mu_f.$$

We recall that Grosjean proved in [8, Lemma 2.1] that

(12) 
$$\sum_{i=1}^{N} \left\langle T \nabla \left( \frac{s_{\delta}(r)}{r} x_{i} \right), \nabla \left( \frac{s_{\delta}(r)}{r} x_{i} \right) \right\rangle \leqslant \operatorname{tr}(T) - \delta \left\langle T X^{\top}, X^{\top} \right\rangle.$$

Moreover, by Lemma 2.1, item (3), we have

$$\delta \int_{M} \langle TX^{\top}, X^{\top} \rangle \mu_{f} \geqslant \int_{M} \operatorname{tr}(T) c_{\delta}^{2}(r) \mu_{f} - \int_{M} \|H_{T} - T(\nabla f)\| s_{\delta}(r) c_{\delta}(r) \mu_{f}$$

which together with (11) and (12) gives

$$\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} \leq \int_{M} \left( \operatorname{tr}(T) - c_{\delta}^{2}(r) \operatorname{tr}(T) + \|H_{T} - T(\nabla f)\| s_{\delta}(r) c_{\delta}(r) \right) \mu_{f}$$

$$\leq \delta \int_{M} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f} + \int_{M} \|H_{T} - T(\nabla f)\| s_{\delta}(r) c_{\delta}(r) \mu_{f},$$

where we have used  $c_{\delta}^2 + \delta s_{\delta}^2 = 1$ . Hence, we obtain

(13) 
$$\lambda_{1} \int_{M} s_{\delta}^{2}(r) \mu_{f} \leq \delta \int_{M} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f} + \sup_{M} \left( \frac{\|H_{T} - T(\nabla f)\|}{\operatorname{tr}(S)} \right) \int_{M} \operatorname{tr}(S) s_{\delta}(r) c_{\delta}(r) \mu_{f}.$$

Now, we claim the following

Lemma 4.1. We have

$$\int_{M} \operatorname{tr}(S) s_{\delta}(r) c_{\delta}(r) \mu_{f} \leqslant \int_{M} \|H_{S} - S(\nabla f)\| s_{\delta}^{2}(r) \mu_{f}.$$

Reporting this into (13), we get

$$\lambda_1 \int_M s_{\delta}^2(r) \mu_f \leqslant \int_M \left[ \delta \operatorname{tr}(T) + \sup_M \left( \frac{\|H_T - T(\nabla f)\|}{\operatorname{tr}(S)} \right) \|H_S - S(\nabla f)\| \right] s_{\delta}^2(r) \mu_f.$$

which gives immediately the desired estimate

$$\lambda_{1} \leqslant \sup_{M} \left[ \delta \operatorname{tr} \left( T \right) + \sup_{M} \left( \frac{\|H_{T} - T\nabla f\|}{\operatorname{tr} \left( S \right)} \right) \|H_{S} - S\nabla f\| \right].$$

This concludes the proof for the case  $\delta < 0$ , up to the proof of the lemma that we give now.

Proof of Lemma 4.1. Multiplying the first part of Lemma 2.1 for the tensor S by  $s_{\delta}(r)$ , we get

$$\operatorname{div}_f(SX^\top)s_\delta(r) \geqslant \operatorname{tr}(S)c_\delta(r)s_\delta(r) - \langle X, H_S - S(\nabla f) \rangle,$$

and thus, by the Cauchy-Schwarz inequality, we have

$$\operatorname{div}_f(SX^\top)s_{\delta}(r) \geqslant \operatorname{tr}(S)c_{\delta}(r)s_{\delta}(r) - \|H_S - S(\nabla f)\|s_{\delta}(r).$$

Now, integrating this relation and using the integration by parts in the formula (10), we get

$$\int_{M} \operatorname{tr}(S) c_{\delta}(r) s_{\delta}(r) \mu_{f} - \int_{M} \|H_{S} - S(\nabla f)\| s_{\delta}(r) \mu_{f} \leq - \int_{M} \langle \nabla s_{\delta}(r), SX^{\top} \rangle \mu_{f} 
\leq - \int_{M} c_{\delta}(r) s_{\delta}(r) \langle \nabla r, S\nabla \rangle 
\leq 0,$$

since S is positive. This concludes the proof of Lemma 4.1.

Case  $\delta > 0$ . Like in the case  $\delta < 0$ , we use  $\frac{s_{\delta}(r)}{r}x_i$ ,  $1 \leq i \leq N$ , as test functions. Using (12) again, we get

(14) 
$$\lambda_1 \int_M s_{\delta}^2(r) \mu_f \leqslant \int_M \left( \operatorname{tr}(T) - \delta \left\langle T X^{\top}, X^{\top} \right\rangle \right) \mu_f.$$

On the other, we use another test function in this case, namely  $c_{\delta}(r) - \overline{c_{\delta}}$  where for more convenience, we have denoted by  $\overline{c_{\delta}}$  the mean value of  $c_{\delta}(r)$ , that is  $\overline{c_{\delta}} = \frac{1}{V_f(M)} \int_M c_{\delta}(r) \mu_f$ . Here again, this function is  $L^2(\mu_f)$ -orthogonal to the constant functions, so it is a candidate for being a test function. Hence, we have

$$\begin{split} \lambda_1 \int_M \left( c_\delta(r) - \overline{c_\delta} \right)^2 \mu_f & \leqslant & \int_M \left\langle T \nabla \left( c_\delta(r) - \overline{c_\delta} \right), \nabla \left( c_\delta(r) - \overline{c_\delta} \right) \right\rangle \mu_f \\ & \leqslant & \int_M \left\langle T \nabla c_\delta(r), \nabla c_\delta(r) \right\rangle \mu_f \\ & \leqslant & \delta^2 \int_M s_\delta^2(r) \left\langle T \nabla r, \nabla r \right\rangle \mu_f \\ & \leqslant & \delta^2 \int_M \left\langle T X^\top, X^\top \right\rangle \mu_f. \end{split}$$

From this, we deduce immediately that

(15) 
$$\lambda_1 \int_M c_\delta^2(r) \mu_f \leqslant \delta^2 \int_M \langle TX^\top, X^\top \rangle + \frac{\lambda_1}{V_f(M)} \left( \int_M c_\delta(r) \mu_f \right)^2.$$

Now, using the fact that  $c_{\delta}^2 + \delta s_{\delta}^2 = 1$ , (15) plus  $\delta$  times (14) gives

$$\lambda_1 V_f(M) \leqslant \delta \int_M \operatorname{tr}(T) \mu_f + \left( \frac{\int_M c_\delta(r) \mu_f}{V_f(M)} \right)^2$$

and thus

$$\lambda_1 V_f(M) \left( 1 - \left( \frac{\int_M c_\delta(r) \mu_f}{V_f(M)} \right)^2 \right) \leqslant \delta \int_M \operatorname{tr}(T) \mu_f.$$

Now, we conclude by using Lemma 3.2 to get the desired upper bound

$$\lambda_1 \leqslant \frac{\left(\int_M \operatorname{tr}(T)\mu_f\right)}{V_f(M)} \left(\delta + \frac{\int_M \|H_S - S(\nabla f)\|^2 \mu_f}{V_f(M)\inf\left(\operatorname{tr}(S)^2\right)}\right),$$

and this concludes the proof of Theorem 1.1.

Proof of Theorem 1.2. Case  $\delta \leq 0$ . Like in the proof of Theorem 1.1, we will consider  $p \in \overline{M}$  as the center of mass of  $\Omega$ ,  $\{x_1, \ldots, x_N\}$  the normal coordinates of  $\overline{M}$  centered at p and by r(x) the geodesic distance (on  $\overline{M}$ ) between x and p, for any  $x \in \overline{M}$ . By the choice of p, we have

$$\int_{M} \frac{s_{\delta}(r)}{r} x_{i} \widetilde{\mu}_{f} = 0,$$

for any  $i \in \{1, ..., N\}$ , and we can use the functions  $\frac{s_{\delta}(r)}{r}x_i$  as test functions in the variational characterization of  $\sigma_1$ . Thus, we have

(16) 
$$\sigma_{1} \int_{M} \sum_{i=1}^{N} \frac{s_{\delta}^{2}(r)}{r^{2}} x_{i}^{2} \widetilde{\mu}_{f} \leq \int_{\Omega} \sum_{i=1}^{N} \left\langle T \nabla \left( \frac{s_{\delta}(r)}{r} x_{i} \right), \nabla \left( \frac{s_{\delta}(r)}{r} x_{i} \right) \right\rangle \mu_{f}$$
$$\leq \int_{\Omega} \left( \operatorname{tr}\left( T \right) - \delta \left\langle T X^{\top}, X^{\top} \right\rangle \right) \mu_{f},$$

where we have used inequality (12) to get the second line. Here,  $X = s_{\delta}(r)\overline{\nabla}r$  and  $X^{\top} = s_{\delta}(r)\nabla r$  is the tangent component of X to  $\Omega$ . On the other hand, by item (3) of Lemma 2.1 applied to  $\overline{M}$ , we have

$$\delta \int_{\Omega} \langle TX^{\top}, X^{\top} \rangle \mu_f \geqslant \int_{\Omega} \operatorname{tr}(T) c_{\delta}^2 \mu_f - \int_{\Omega} \|H_T - T(\nabla f)\| s_{\delta} c_{\delta} \mu_f.$$

Reporting into (16), we have

$$\sigma_{1} \int_{M} s_{\delta}^{2}(r) \widetilde{\mu}_{f} \leq \int_{\Omega} \left( \operatorname{tr}(T) - c_{\delta}^{2}(r) \operatorname{tr}(T) + \|H_{T} - T(\nabla f)\| s_{\delta}(r) c_{\delta}(r) \right) \mu_{f}$$

$$\leq \delta \int_{\Omega} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f} + \int_{\Omega} \|H_{T} - T(\overline{\nabla}f)\| s_{\delta}(r) c_{\delta}(r) \mu_{f},$$

$$\leq \delta \int_{\Omega} s_{\delta}^{2}(r) \operatorname{tr}(T) \mu_{f} + \sup_{\Omega} \left( \frac{\|H_{T} - T(\overline{\nabla}f)\|}{\operatorname{tr}(T)} \right) \int_{\Omega} \operatorname{tr}(T) s_{\delta}(r) c_{\delta}(r) \mu_{f}.$$

From Lemma 4.1 applied on  $\Omega$  for the tensor T, we have

$$\int_{\Omega} \operatorname{tr}(T) s_{\delta}(r) c_{\delta}(r) \mu_{f} \leqslant \int_{\Omega} \|H_{T} - T(\nabla f)\| s_{\delta}^{2}(r) \mu_{f},$$

which yields to

$$\sigma_1 \int_M s_\delta^2(r) \widetilde{\mu}_f \quad \leqslant \quad \int_\Omega s_\delta^2(r) \left[ \delta \mathrm{tr} \left( T \right) + \sup_\Omega \left( \frac{\|H_T - T(\nabla f)\|}{\mathrm{tr} \left( T \right)} \right) \|H_T - T(\nabla f)\| \right] \mu_f.$$

Moreover, from the assumption that  $\Omega$  is contained in the ball of radius B(p, R), we get that  $s_{\delta}(r) \leq s_{\delta}(R)$  and thus

$$\sigma_1 \int_M s_{\delta}^2(r) \widetilde{\mu}_f \leqslant s_{\delta}^2(R) V_f(\Omega) \sup_{\Omega} \left[ \delta \operatorname{tr}(T) + \sup_{\Omega} \left( \frac{\|H_T - T(\nabla f)\|}{\operatorname{tr}(T)} \right) t \|H_T - T(\nabla f)\| \right].$$

Finally, by Lemma 3.2, we have

$$\frac{\int_{M} s_{\delta}(r)^{2} \widetilde{\mu}_{f}}{V_{f}(M)} \geqslant \frac{1}{\delta + \frac{\sup_{M} \|H_{S} - S(\widetilde{\nabla}f)\|^{2}}{\inf_{M} (\operatorname{tr}(S))^{2}}},$$

which give the desired estimate when  $\delta \leq 0$ :

$$\sigma_{1} \leqslant \sup_{\Omega} \left[ \delta \operatorname{tr} \left( T \right) + \sup_{\Omega} \left( \frac{\|H_{T} - T(\nabla f)\|}{\operatorname{tr} \left( T \right)} \right) \|H_{T} - T(\overline{\nabla} f)\| \right]$$

$$\times \left[ \delta + \frac{\sup_{M} \|H_{S} - S(\widetilde{\nabla} f)\|^{2}}{\inf_{M} (\operatorname{tr} \left( S \right))^{2}} \right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R).$$

Case  $\delta > 0$ . Like in the case  $\delta \leq 0$ , we have

(17) 
$$\sigma_1 \int_M s_{\delta}^2(r) \widetilde{\mu}_f \leqslant \int_{\Omega} \left( \operatorname{tr} \left( T \right) - \delta \left\langle T X^{\top}, X^{\top} \right\rangle \right) \mu_f$$

by using  $\frac{s_{\delta}(r)}{r}x_i$ ,  $1 \leq i \leq N$  as test functions. In addition, we also use another test function,  $c_{\delta}(r) - \widetilde{c_{\delta}}$ , with  $\widetilde{c_{\delta}} = \frac{1}{V_f(M)} \int_M c_{\delta}(r) \widetilde{\mu}_f$ . By a computation analogue to the proof of Theorem 1.1, we have

$$\sigma_{1} \int_{M} \left( c_{\delta}(r) - \widetilde{c_{\delta}} \right)^{2} \widetilde{\mu}_{f} \leq \int_{\Omega} \left\langle T \nabla \left( c_{\delta}(r) - \widetilde{c_{\delta}} \right), \nabla \left( c_{\delta}(r) - \widetilde{c_{\delta}} \right) \right\rangle \mu_{f}$$

$$\leq \int_{\Omega} \left\langle T \nabla c_{\delta}(r), \nabla c_{\delta}(r) \right\rangle \overline{\mu}_{f}$$

$$\leq \delta^{2} \int_{\Omega} s_{\delta}^{2}(r) \left\langle T \nabla r, \nabla r \right\rangle \mu_{f}$$

$$\leq \delta^{2} \int_{\Omega} \left\langle T X^{\top}, X^{\top} \right\rangle \mu_{f}.$$

From this, we deduce

(18) 
$$\sigma_1 \int_M c_\delta^2(r) \widetilde{\mu}_f \leqslant \delta^2 \int_{\Omega} \langle TX^\top, X^\top \rangle \, \mu_f + \frac{\sigma_1}{V_f(M)} \left( \int_M c_\delta(r) \widetilde{\mu}_f \right)^2.$$

Now, using the fact that  $c_{\delta}^2 + \delta s_{\delta}^2 = 1$ , (18) plus  $\delta$  times (17) gives

$$\sigma_1 V_f(M) \leqslant \delta \int_{\Omega} \operatorname{tr}(T) \mu_f + \left( \frac{\int_{M} c_{\delta}(r) \widetilde{\mu}_f}{V_f(M)} \right)^2$$

and so

$$\sigma_1 V_f(M) \left( 1 - \left( \frac{\int_M c_\delta(r) \widetilde{\mu}_f}{V_f(M)} \right)^2 \right) \leqslant \delta \int_{\Omega} \operatorname{tr} \left( T \right) \mu_f.$$

Finally, since we have

$$1 - \left(\frac{\int_{M} c_{\delta}(r)\widetilde{\mu}_{f}}{V_{f}(M)}\right)^{2} \geqslant \frac{1}{1 + \frac{\int_{M} \|H_{S} - S(\widetilde{\nabla}f)\|^{2}\widetilde{\mu}_{f}}{\delta \inf(\operatorname{tr}(S))^{2}V_{f}(M)}},$$

by Lemma 3.2, we get

$$\sigma_{1} \leqslant \frac{\int_{\Omega} \operatorname{tr}(T)\mu_{f}}{V_{f}(M)} \left( \delta + \frac{\int_{M} \|H_{S} - S(\widetilde{\nabla}f)\|^{2} \widetilde{\mu}_{f}}{V_{f}(M) \inf \left(\operatorname{tr}(S)\right)^{2}} \right),$$

and this concludes the proof.

Proof of Theorem 1.3. Here again we consider differently the two cases. Case  $\delta \leq 0$ . First, we recall the variational characterization of  $\alpha_1$  (see [5])

(19) 
$$\alpha_1 = \inf \left\{ \frac{\int_{\Omega} \|\overline{\nabla}u\|^2 dv_{\overline{g}} + b \int_{M} \|\nabla u\|^2 dv_{\widetilde{g}}}{\int_{M} u^2 dv_{\widetilde{g}}} \left| \int_{M} u dv_{\widetilde{g}} = 0 \right\}.$$

As in the proof of Theorem 1.2, we use  $\frac{s_{\delta}(r)}{r}x_i$  as test functions, where r is the geodesic distance to the center of mass p of  $\Omega$  and  $\{x_1, \dots, x_N\}$  the normal coordinates of  $\overline{M}$  centered at p. Hence, we have

$$\alpha_1 \int_M \sum_{i=1}^N \frac{s_\delta^2(r)}{r^2} x_i^2 dv_{\widetilde{g}} \leqslant \int_\Omega \sum_{i=1}^N \left\| \overline{\nabla} \left( \frac{s_\delta(r)}{r} x_i \right) \right\| dv_{\overline{g}} + b \int_M \sum_{i=1}^N \left\| \nabla \left( \frac{s_\delta(r)}{r} x_i \right) \right\| dv_{\widetilde{g}}$$

that is,

(20) 
$$\alpha_1 \int_M s_{\delta}(r)^2 dv_{\widetilde{g}} \leqslant \int_{\Omega} \left( n - \delta \|X^{\top}\|^2 \right) dv_{\overline{g}} + b \int_M \left( (n-1) - \delta \|X^{\widetilde{\top}}\|^2 \right) dv_{\widetilde{g}},$$

where we use inequality (12) twice, once on  $\Omega$  for the first term and once on M for the second term. Moreover we have,  $\|X^{\widetilde{\top}}\| \leq \|X^{\top}\| \leq \|X\| = s_{\delta}(r)$  and since  $\delta$  is nonpositive,  $s_{\delta}$  is an increasing function. So, by the assumption that  $\Omega$  is contained in the ball B(p, R), we have

$$\alpha_{1} \int_{M} s_{\delta}^{2}(r) dv_{\widetilde{g}} \leq \left(n - \delta s_{\delta}(R)^{2}\right) V(\Omega) + b\left(n - 1\right) - \delta s_{\delta}(R) V(M)$$
$$\leq \left(nV(\Omega) + b(n - 1)V(M)\right) - \delta s_{\delta}(R)^{2} \left(V(\Omega) + bV(M)\right).$$

We conclude by applying Lemma 3.2, which says for f = 0,

$$\frac{\int_{M} s_{\delta}(r)^{2} dv_{\widetilde{g}}}{V(M)} \geqslant \frac{1}{\delta + \frac{\sup_{M} \|H_{S}\|}{\inf_{M} (\operatorname{tr}(S))^{2}}},$$

to obtain the desired estimate when  $\delta \leq 0$ , that is,

$$\alpha_{1} \leqslant \left[ n \frac{V(\Omega)}{V(M)} + b(n-1) - \delta s_{\delta}^{2}(R) \left( \frac{V(\Omega)}{V(M)} + b \right) \right] \left( \delta + \frac{\sup_{M} \|H_{S}\|^{2}}{\inf_{M} (\operatorname{tr}(S))^{2}} \right).$$

Case  $\delta > 0$ . Like in the cas  $\delta \leq 0$ , using the functions  $\frac{s_{\delta}(r)}{r}x_i$  as test functions in the variational characterization of  $\alpha_1$ , we get

$$(22) \quad \alpha_1 \int_M s_{\delta}^2(r) dv_{\widetilde{g}} \leqslant \int_{\Omega} \left( n - \delta \|X^{\top}\|^2 \right) dv_{\overline{g}} + b \int_M \left( (n - 1) - \delta \|X^{\widetilde{\top}}\|^2 \right) dv_{\widetilde{g}}.$$

Moreover, we use another test function,  $c_{\delta}(r) - \widetilde{c_{\delta}}$  with  $\widetilde{c_{\delta}} = \frac{1}{V(M)} \int_{M} c_{\delta}(r) dv_{\widetilde{g}}$ .

$$\begin{split} \alpha_1 \int_M \left( c_\delta(r) - \widetilde{c_\delta} \right)^2 dv_{\widetilde{g}} & \leqslant & \int_\Omega \left\langle \nabla \left( c_\delta(r) - \widetilde{c_\delta} \right), \nabla \left( c_\delta(r) - \widetilde{c_\delta} \right) \right\rangle dv_g \\ & + b \int_M \left\langle \widetilde{\nabla} \left( c_\delta(r) - \widetilde{c_\delta} \right), \widetilde{\nabla} \left( c_\delta(r) - \widetilde{c_\delta} \right) \right\rangle dv_{\widetilde{g}} \\ & \leqslant & \int_\Omega \left\langle \nabla c_\delta(r), \nabla c_\delta(r) \right\rangle dv_g + b \int_M \left\langle \widetilde{\nabla} c_\delta(r), \widetilde{\nabla} c_\delta(r) \right\rangle dv_{\widetilde{g}} \\ & \leqslant & \delta^2 \int_\Omega s_\delta^2(r) \left\langle \nabla r, \nabla r \right\rangle dv_g + b \delta^2 \int_M s_\delta^2(r) \left\langle \widetilde{\nabla} r, \widetilde{\nabla} r \right\rangle dv_{\widetilde{g}} \\ & \leqslant & \delta^2 \int_\Omega \|X^\top\|^2 dv_g + b \delta^2 \int_M \|X^{\widetilde{\top}}\|^2 dv_{\widetilde{g}}, \end{split}$$

where  $X^{\top} = s_{\delta}(r)\nabla r$  is the tangent component of X to  $\Omega$  and  $X^{\widetilde{\top}} = s_{\delta}(r)\widetilde{\nabla}r$  is the part of X tangent to M. From this, we get

(23) 
$$\alpha_{1} \int_{M} c_{\delta}(r)^{2} dv_{\widetilde{g}} \leq \delta^{2} \int_{\Omega} \|X^{\top}\|^{2} dv_{g} + b\delta^{2} \int_{M} \|X^{\widetilde{\top}}\|^{2} dv_{\widetilde{g}} + \frac{\alpha_{1}}{V(M)} \left( \int_{M} c_{\delta}(r) dv_{\widetilde{g}} \right)^{2}.$$

Hence summing (23) and  $\delta$  times (22), using the fact that  $c_{\delta}^2 + \delta s_{\delta}^2 = 1$ , gives

$$\alpha_1 V(M) \le \delta \left( nV(\Omega) + b(n-1)V(M) \right) + \frac{\alpha_1}{V(M)} \left( \int_M c_\delta(r) dv_{\widetilde{g}} \right)^2,$$

and so

$$\alpha_1 V(M) \left( 1 - \left( \frac{1}{V(M)} \int_M c_\delta(r) dv_{\widetilde{g}} \right)^2 \right) \leqslant \delta \Big( n V(\Omega) + b(n-1) V(M) \Big).$$

Moreover, from we have Lemma 3.2 (with f = 0), we have

$$1 - \left(\frac{\int_{M} c_{\delta}(r)dv_{\widetilde{g}}}{V(M)}\right)^{2} \geqslant \frac{1}{1 + \frac{\int_{M} \|H_{S}\|^{2}dv_{\widetilde{g}}}{\delta \inf(\operatorname{tr}(S))^{2}V(M)}}$$

which gives

$$\alpha_1 V(M) \leqslant \delta \left( nV(\Omega) + b(n-1)V(M) \right) \left( \delta + \frac{\int_M \|H_S\|^2 dv_{\widetilde{g}}}{V(M)\inf(\operatorname{tr}(S))^2} \right)$$

and finally the desired estimate

$$\alpha_1 \leqslant \left(n \frac{V(\Omega)}{V(M)} + b(n-1)\right) \left(\delta + \frac{\int_M \|H_S\|^2 dv_{\widetilde{g}}}{V(M)\inf\left(\operatorname{tr}(S)^2\right)}\right).$$

This concludes the proof.

#### 5. A REMARK ABOUT THE CASE $\delta > 0$

The aim of this section is to compare the estimates in both case  $\delta > 0$  and  $\delta \leq 0$ . Indeed, in the estimates of Theorems 1.2, the radius R of a ball containing  $\Omega$  appears when  $\delta \leq 0$  but not for the estimates for  $\delta > 0$ . It turns out that when  $\delta > 0$ , we can bound the radius R from above in terms of  $H_T$  and tr T and so obtain upper bounds comparable to those obtained for  $\delta \leq 0$ . First, we have the following

**Proposition 5.1.** Let  $(\bar{M}^{n+p}, \bar{g}, \bar{\mu}_f)$  be a weighted Riemannian manifold with sectional curvature  $sect_{\bar{M}} \leq \delta$ , with  $\delta > 0$ , and  $\bar{\mu}_f = e^{-f}dv_{\bar{g}}$ . Let  $(\Omega, g)$  be a compact Riemannian manifold with non-empty boundary M isometrically immersed into  $(\bar{M}^{n+p}, \bar{g})$  by X. We endow  $\Omega$  with the weighted measure  $\mu_f = e^{-f}dv_g$ . Let T be a symmetric, divergence-free and positive definite (1,1)-tensor on  $\Omega$ . If  $\Omega$  is contained a ball of radius R, then

$$s_{\delta}^{2}(R) \left( \frac{\|H_{T} - T\nabla f\|_{\infty}^{2}}{\inf_{\Omega} (\operatorname{tr}(T))^{2}} + \delta \right) \geqslant 1.$$

*Proof.* From the second part of Lemma 2.1 applied on  $\Omega$ , we have

$$\int_{\Omega} c_{\delta}(r) \operatorname{tr}(T) \mu_{f} \leqslant -\int_{\Omega} \langle X, H_{T} - T \nabla f \rangle \mu_{f}.$$

We recall that  $X = s_{\delta}(r)\nabla r$ , which gives

$$\int_{\Omega} c_{\delta}(r) \operatorname{tr}(T) \mu_{f} \leqslant \int_{\Omega} \|H_{T} - T \nabla f\| s_{\delta}(r) \mu_{f}.$$

We are in the case where  $\delta>0$ , so  $c_\delta$  and  $s_\delta$  are respectively decreasing and increasing on  $[0,\frac{\pi}{2\sqrt{\delta}}]$ . Moreover,  $\Omega$  is contained in a ball of radius  $R<\frac{\pi}{4\sqrt{\delta}}$  which implies that  $\Omega$  is contained in a ball of radius  $\frac{\pi}{2\sqrt{\delta}}$  centered at p. Hence, r< R and so  $cd(r) \geqslant c_\delta(R)$  and  $s_\delta(r) \leqslant s_\delta(R)$  on  $\Omega$ . Thus, we get

$$c_{\delta}(R) \inf_{\Omega} (\operatorname{tr}(T)) \leqslant s_{\delta}(R) \sup_{\Omega} \|H_T - T\nabla f\|.$$

We deduce easily from this and the fact that  $c_{\delta}^2 + \delta s_{\delta}^2 = 1$  that

$$s_{\delta}^{2}(R)\left(\frac{\|H_{T} - T\nabla f\|_{\infty}^{2}}{\inf_{\Omega}(\operatorname{tr}(T))^{2}} + \delta\right) \geqslant 1,$$

which concludes the proof of the proposition.

Now, using the above proposition together with the estimate of Theorem 1.2 in the case  $\delta > 0$ , we get the following estimate

$$\sigma_{1} \leq \left(\frac{\|H_{T} - T\nabla f\|_{\infty}^{2}}{\inf_{\Omega}(\operatorname{tr}(T))^{2}} + \delta\right) \left(\delta + \frac{\int_{M} \|H_{S} - S(\nabla f)\|^{2} \widetilde{\mu}_{f}}{V_{f}(M)\inf_{\Omega}(\operatorname{tr}(S)^{2})}\right) \frac{\int_{\Omega} \operatorname{tr}(T)\mu_{f}}{V_{f}(M)} s_{\delta}^{2}(R)$$

$$\leq \sup_{\Omega} (\operatorname{tr}(T)) \left(\frac{\|H_{T} - T\nabla f\|_{\infty}^{2}}{\inf_{\Omega}(\operatorname{tr}(T))^{2}} + \delta\right) \left(\delta + \frac{\int_{M} \|H_{S} - S(\nabla f)\|^{2} \widetilde{\mu}_{f}}{V_{f}(M)\inf_{\Omega}(\operatorname{tr}(S)^{2})}\right) \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R)$$

which is comparable to the estimate for the case  $\delta \leq 0$ :

$$\sigma_{1} \leqslant \sup_{\Omega} \left[ \delta \operatorname{tr} \left( T \right) + \sup_{\Omega} \left( \frac{\|H_{T} - T(\overline{\nabla}f)\|}{\operatorname{tr} \left( T \right)} \right) \|H_{T} - T(\overline{\nabla}f)\| \right]$$

$$\times \left[ \delta + \frac{\sup_{M} \|H_{S} - S(\nabla f)\|^{2}}{\inf_{M} (\operatorname{tr} \left( S \right))^{2}} \right] \frac{V_{f}(\Omega)}{V_{f}(M)} s_{\delta}^{2}(R).$$

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