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Indentation of glasses

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ABSTRACT

Indentation, owing to its ability to induce permanent deformation in a controlled manner even in highly brittle materials that are otherwise not amenable to critical mechanical testing experiments, is widely used for studying the mechanical behavior of amorphous solids. In this paper, an overview of the current understanding on the indentation response of inorganic glasses - both metallic and nonmetallic – is presented. The stresses underneath a sharp indenter, such as the Vickers indenter that is most commonly used to evaluate hardness of glasses, can be substantial, which, in turn, can induce densification, plastic deformation, viscous flow, and cracking, depending on a number of material and experimental variables. In this paper, the physics and mechanics of these processes, the interplay between them, and their effect on hardness of glasses are reviewed. The effect of composition in various glass systems such as chalcogenides, phosphates, silicates, and silicon oxynitrides, on hardness are discussed. Different microcrack patterns that occur during indentation and fracture resistance of glasses are summarized. The effects of extrinsic parameters such as time, temperature, and pressure on the deformation behavior of glasses are highlighted. The use of the bonded-interface and nanoindentation techniques for studying incipient as well as the localized nature of plastic flow and its pressure sensitivity, and hardness in metallic glasses is summarized. A review of the nanoindentation's contribution for investigating the strain rate, ion irradiation, and environmental effects is provided. Finally, possible future avenues for further exploration of indentation of glasses are discussed.

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Α	Alkaline
AE	Alkaline-earth
a-SiO ₂	Amorphous (vitreous) silica
BMG	Bulk metallic glass
BMGC	Bulk metallic glass composite
ECR	Electrical contact resistance
FBG	Fiber Bragg gratings
FE	Finite element
FEM	Finite element method
IP	Intermediate phase
ISE	Indentation size effect
KDE	Kernel density estimate
LJ	Lennard–Jones
MD	Molecular dynamics
MG	Metallic glass
PSR	Proportional specimen resistance
RT	Room temperature
SRO	Short-range ordering
SRS	Strain-rate sensitivity
STZ	Shear transformation zone
UV	Ultraviolet
a	Radius of the circular imprint associated with the equivalent conical indenter
B	Brittleness index
C_{α}	Atomic packing density
C_{v}	A constant connecting τ_{max} and τ_{y}
Ē	Elastic modulus
E_{eff}	Effective modulus
f	Cumulative probability
Н	Hardness
H_{el}	Equilibrium mean contact pressure (referred to as 'elastic hardness')
h	Depth of penetration in indentation test
$h_{\rm max}$	Maximum depth of penetration
K _{Ic}	Plane strain (mode I) fracture toughness
m_i	The molar mass of the <i>i</i> th element
Ni	Shear band number density around spherical indentations
N _n	Shear band number density ahead of a notch tip
P	Applied load in indentation test
<i>₽</i>	Loading rate
R^2	<i>R</i> -squared, a statistical measure representing proportion of the variance in
	the dependent variable that is predictable from the independent variable(s)
R_i	Indenter tip radius
r	Distance to the initial point of indentation contact
<r></r>	Average coordination number
r _i	Ionic radii
Τ	Absolute temperature
T_g	Glass transition temperature
t	Time
V^*	Activation volume
$\overline{V_0}$	Corresponding effective volume of glass

	Actual volume occupied by the constituent elements
x_i	The atomic fraction of the <i>i</i> th element
Y	Constrained factor
α	friction coefficient
Ė	Indentation strain rate
ϕ	Half apical angle of an equivalent conical indenter
η	Shear viscosity coefficient
μ	Shear modulus
ν	Poisson's ratio
θ	Angle to the loading axis, in spherical coordinates with origin on the surface
	at contact point
ρ	Density of material
$\sigma_{\!u}$	Ultimate tensile strength
σ_{y}	Yield strength
σ_{rr}	Stress component along <i>r</i> direction in spherical coordinates
$\sigma_{\scriptscriptstyle \phi \phi}$	Stress component normal to <i>r</i> direction in spherical coordinates
τ_{max}	Maximum shear stress underneath the indenter
$ au_v$	Shear yield strength for the onset of plasticity

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I. INTRODUCTION

The three key attributes that define the quasi-static mechanical behavior of a material at low temperature are its stiffness, strength, and toughness. They reflect the resistance offered by the material to elastic and plastic deformations, and to cracking, respectively, and are quantified through the properties: elastic modulus, *E*, yield strength, σ_y (or tensile strength, σ_u), and fracture toughness, $K_{\rm lc}$. The first property, *E* is often expressed in units of Pa and is the rate of change in the volume density of energy (that is stored in the material by virtue of the elastic deformation) with strain. Since the onset of plastic (or permanent) deformation occurs when the stored energy reaches a critical value (according to the widely used von Mises yield criterion), σ_y is also expressed in units of Pa. The direct measurement of σ_y requires some sophisticated instrumentation and specimen preparation; therefore, hardness, *H*, a measure of the mean contact stress required for the formation of a permanent indentation imprint, is often used as a simple and cost-effective alternative to estimate the plastic flow ability especially for quality control in manufacturing industries that deal with metals and alloys. Like σ_y , *H* is also expressed in Pa and is defined as the ratio between the normal load applied on the indenter and the projected area (cross-section) of the impression made by it on the material being probed.

As soon as humans started using materials for cutting, shaping, or working matter in general, they imagined ways to compare their H, especially when relatively hard materials such as metals, ceramics and glasses became available. With the advent of industrialization, it has become the property that is routinely evaluated due to the relative ease with which it can be measured. Over the past century, various kinds of hardness measures that use different indenter tip geometries (such as Vickers, Brinell, Knoop, Rockwell) were proposed and widely adapted. Nevertheless, H is a somewhat composite property, which reflects different elementary deformation processes that often occur concomitantly. Thus, hardness embodies the resistance offered by the material to both elastic and isochoric plastic deformations, as well as densification – in the case of glasses in which the atomic packing is inefficient or porous materials, as we shall see later – and micro-scale damage [1]. Moreover, the material deformation characteristics under contact loading, which results in severe gradients in stress and strain fields, are embodied in the hardness measure. Therefore, different deformation processes involving intrinsic as well as extrinsic properties may result in the same area of contact for a given load. All these factors can lead to considerable complexity in connecting H to the underlying material physics.

A relatively more recent development in the field of hardness measurements is nanoindentation, in which the applied load, P, is continuously measured as a function of the depth of penetration, h, of the indenter into the material that is being probed [2]. Nanoindentation falls into the broad class of techniques known as 'instrumented indentation', through which P-h data is acquired.

The generated data can be analyzed not only to obtain *H*, but also to extract the effective elastic modulus of the specimen, E_{eff} (= $E/(1-v^2)$), where v is Poisson's ratio). In some specific instances, the shear viscosity coefficient, η , in the 10⁹ to 10¹⁴ Pa·s range (i.e., through the glass transition) can also be estimated using this technique. Since *P* and *h* can be measured with high resolutions (μ N for *P* and nm for *h*) and with high accuracy, nanoindentation is particularly suited – and hence widely exploited – for probing materials that are only available in small volumes such as thin films and coatings [3]. It is also useful for measuring site-specific properties of surfaces, with high spatial and temporal resolutions.

Indentation technique can also be used for measuring the fracture resistance of a material. However, a necessary condition that needs to be fulfilled for measuring the toughness is that the indented material should crack in a controlled and well-defined manner [3–5]. Thus, all the three key mechanical attributes of a material can be measured, in principle, using indentation.

Indentation – whether it is for the simple measurement of H or the more sophisticated nanoindentation – is the commonly used method for exploring the mechanical behavior of glasses, a class of materials of rapidly growing importance that are used extensively for both structural and functional purposes. Glasses at room temperature (RT) are generally brittle and hence tend to fail catastrophically under tension, i.e., they deform in a purely elastic manner before failing, and are highly sensitive to defects. It is possible, however, to induce a permanent deformation in them in a controlled manner via indentation and hence study their mechanical behavior.

The stress state underneath the indenter is complex, especially when a sharp indenter – such as Vickers indenter, which is the most common one for studying glasses – is used, and the deformation occurs with both reversible (elastic) and irreversible contributions; the latter stems either from shear plasticity, densification, or viscous flow, and is responsible for the permanent residual imprint from which *H* is deduced [3,6]. With the nanoindentation technique, initiation of the incipient plasticity and the localized nature of plastic flow can be carefully monitored in quasi-brittle materials such as metallic glasses (MGs) [7]. The analysis of such features allows for a better understanding of the physics of deformation and fracture of glasses. In this paper, the indentation responses of inorganic glasses – both metallic and non-metallic – are reviewed, with emphasis on recent insights gained on the processes that glasses undergo during indentation. The behavior of non-metallic glasses during indentation are discussed first, which is followed by that on MGs.

2. INORGANIC AND NON-METALLIC GLASSES

In the absence of dislocation mediated plasticity, which is the main mechanism for permanent deformation in crystalline metals and alloys, two deformation processes were identified to occur during indentation of inorganic and non-metallic glasses, which are the following. (i) Densification

[8,9], which is dominant in glasses with a relatively low atomic packing density, C_g , which is defined as the ratio of V_a to V_0 , where V_a is the actual volume occupied by the constituent elements (= $\sum_{i=1}^{4} \pi x_i r_i^3$, , as estimated from the ionic radii, r_i , [10] and the atomic fraction x_i of the *i*th element) and V_0 is the corresponding effective volume of glass (= $1/\rho \sum_i x_i m_i$, where m_i is the molar mass of the *i*th element); (ii) Volume conserving (isochoric) shear flow [11,12] in those glasses with a high C_g , and/or when His measured at temperatures, T, approaching the glass transition temperature, T_g [13] It is important to recognize here that a major difference between the indentation of crystalline and amorphous materials is that plasticity in the former is volume conserving, whereas the volume of the material being deformed does not necessarily remain constant in glasses.

Non-metallic inorganic glasses such as the silicate glasses are brittle. Therefore, when the indentation load is sufficiently large, some microcracking events occur both on loading and on unloading [14,15], which weaken the glass by leaving easy crack initiation sites at the surface.

The extent of the deformation, the physics behind it, and the microcracking patterns during indentation of glasses depend much on the composition, and more particularly on the atomic and molecular organizations (short to medium range order). In the context of glasses, H is mostly found to correlate with the elastic moduli – especially the shear modulus, μ [1,16] – and is related to the average bond strength, the volume density of the bonds – and thus the free volume content – and the bond characteristics (especially directionality). Since composition and T can independently influence H, it may be difficult to decouple the chemical and thermal effects. In other words, glasses with relatively low T_g are likely to exhibit similar indentation features to the more refractory ones indented at higher T. Regardless of the specific chemical system, the general tendency is that H scales with T_g . This is not surprising since T_g is the boundary between the liquid state (above) and the supercooled liquid or glassy state (below), and since H scales with the melting point for most materials.

The importance of the glass composition and atomic organization on the indentation deformation will be discussed in subsection §2.1, in light of the major mechanisms evidenced in noncrystalline materials, and of known features of the atomic structure. A quantitative analysis of the irreversible deformation process allows for an estimation of the driving force for indentation cracking, as well as for the crack pattern (morphology). This paves the way to the understanding of the contact damage behavior of glasses from different chemical systems and to the design of damage-resistant glasses, as discussed in subsection §2.2.

2.1. Hardness and indentation plasticity

2.1.1. Physics and mechanics of the deformation process

It is noteworthy that in the case of glasses with a large free volume content, such as vitreous silica (a-SiO₂), *H* is predominantly controlled by the volume density of atomic bonds, regardless of the interatomic bond energy. This is the reason behind a-SiO₂ (H = 8.7 GPa) being considerably softer than its crystalline counterpart, quartz (H = 10-12 GPa), or than its high-density variant, stishovite (33 GPa) [17]. With an increase in the packing density, the bond strength becomes more dominant than the packing density itself, and *H* is governed by the resistance offered by the glass to the shear flow. This is why MGs, which have a relatively high C_g of ~0.6–0.8 [18] that is reflected in their *v* values being typically larger than 0.3, can be stiffer and harder than oxide glasses, despite a much weaker interatomic bonding. The absence of dislocations in MGs, however, makes them considerably harder than their crystalline counterparts. Consequently, σ_y and *H* of MGs reflect the ease with which localized flow units and bands form, with transient local expansions, as will be further discussed in subsection §3.

Typical *H* values for inorganic, non-metallic glasses range between 1 (chalcogenides) and 12 (silicon-oxynitrides) GPa. These are much larger than the stresses that glasses can withstand during classical mechanical testing (such as uniaxial tension or compression tests) and are sufficient to generate some densification in the process zone beneath the indenter imprint. Densification at the indentation sites was inferred from the refractive index measurements made optical interferometry [8,9], as well as by Raman spectroscopy [19,20]. A general property of glasses, densification could occur in a volume that is several times the indentation size and manifests through a persistent change of the atomic network structure¹. Being displacive in nature, it results in packing of matter into a relatively-more close packed structure. The extent to which a glass can densify during indentation depends on its C_g ; a smaller C_g results in a larger shrinkage volume [20,21] Densification accounts for 80 % of the indentation volume in a-SiO₂ [13,20]. In contrast, it contributes to less than 10% of the deformed volume of a Zr-based MG due to the random close packed structure in it [20].

Shear flow, which is reconstructive in nature², operates almost concomitantly to densification [13]. It results in the piling-up of matter around the indent edges while densification leaves a well-defined indent surrounded by a marginally distorted surface. A remarkable correlation was found

¹ Densification was demonstrated both by light scattering spectroscopy (Raman in particular) and by specific annealing treatments below T_g that would 'recover' the densified zone. An axisymmetric boundary of the densified area exists, even if a sharp indenter is used, because the St-Venant principle is valid at a depth of about the indentation size [22].

² Densification becomes increasingly difficult with an increasing amount of the modifying cations in the glass. Both C_g and v increase with this amount. Still, densification occurs, especially at SiO₄ tetrahedral sites, but to a lesser extent. Details on the mechanistic variations upon densification in different glass chemical systems can be found in [21].

between the v and the amount of densification or shear flow, which involve large strains³ [22]. This is because glasses with relatively open structures, such as those of amorphous silica and germania, are based on corner-sharing tetrahedra and usually come with a high degree of cross-linking. Hence, they offer a strong resistance to contraction in the transverse direction to tensile axis and have a low v (0.15 and 0.19 respectively). On the contrary, amorphous structures that are more efficiently packed are mostly associated with a smaller degree of atomic cross-linking (it is easier to pack rod- or sheetlike units than tetrahedra) so that local shear becomes easier and v increases. In the extreme case of MGs with precious metal host elements v reaches values as large as 0.45 [23]. In contrast to MGs, where significant progress toward the understanding of plastic flow was achieved thanks to the huge research efforts made during the last three decades, detailed understanding of the shear deformation mechanism of silicate glasses is still elusive. The observations of shear bands were reported in silicate glasses some decades ago [11,24,25]. However, it was not clear whether those were slip bands or shear microcracks. What we know is that shear flow in amorphous materials, which do not work harden, results in the pile-up of matter as a result of the volume conservative nature of it. The occurrence of both pile-up and sink-in crystalline metals and alloys, depending on their work hardening characteristics, has been extensively reported for crystals [26]. Shear flow occurs in a localized process zone beneath the indenter, and is more sensitive to T than densification, with approximately an order of magnitude difference in their activation energies. As a matter of fact, shear flow takes over densification at T from near – and above – T_g but is much reduced at low T [27,28]. Having relatively low T_g , chalcogenide and phosphate glasses experience significant shear flow at RT. Shear-thinning is favored in weakly polymerized network structures⁴; indeed both viscosity measurements and numerical simulation provide evidence for a sharp viscosity reduction at high stresses or strain- rates [29,30]. Hence, it is anticipated that for shear stresses of the order of GPa (comparable to *H* values) viscosity may drop of orders of magnitude, so that viscous flow is plausible.

³ The permanent deformation in glasses is reflected in v, and interestingly, this is consistent with the finding (phenomenological) that sink-in or pile-up is correlated to H/E. As the shear deformation becomes easier relative to the volume change, H decreases while E/μ and K/μ increase (K/μ is better for a sound comparison of shear and volumetric deformations). Since both E/μ and K/μ scale with v, it turns out that examining E/H or v to anticipate sink-in or pile-up is about the same thing. Note that ductile materials, which show extensive pile-up, are comparatively soft and exhibit large v values. ⁴ In network glasses, the tetrahedra (or the basic units of the structure) form a mostly percolating network. The cross-linking decreases with an increasing content of alkaline or alkaline-earth cations in silicates, or chalcogen elements in chalcogenide glasses. This is often referred as a decrease in the polymerization degree.



Fig. 1. Schematic drawings of different indentation deformation stages. The dashed lines indicate the indentation profile after unloading. Arrows indicate matter displacement. Hardness, *H*, is the mean contact pressure. (Reprinted with permission from Januchta and Smedskjaer [31]. Copyright (2019) Elsevier)

Deformation during indentation could involve three different processes, namely elastic deformation, densification, and shear flow (Fig. 1) [31]. If linear elasticity was to be the sole deformation mechanism, the equilibrium mean contact pressure (referred to as 'elastic hardness'), H_{el} , for a rigid conical indenter of apical angle 2ϕ would be [32]:

$$H_{\rm el} = \mu / [(1 - \nu) \tan \phi].$$
 (1)

For a Vickers indenter, which is the most widely used for measuring H of glasses, $\phi = 70.3^{\circ}$ such that the equivalent cone indenter produces the same projected area for a given penetration depth. Substituting typical values of μ and ν in Eq. (1), shows that H_{el} is about 2 to 3 times larger than Hmeasured on the same solid, which means that matter will tend to relax such highly constrained localized stress by means of densification and shear flow. If these mechanisms are not sufficiently active, microcracking damage occurs. Densification is supposed to occur first because it requires small local displacements in which the interatomic bond distances remain nearly unchanged, while inter-units (tetrahedra) angles are affected, which results in a change in the refractive index. Indeed, the refractive index of the pristine silica glass immediately surrounding the indentation was found to be different from that of the bulk [33]. Even in the cases where volume conserving flow is dominant, the pile-up volume remains considerably smaller than the indentation volume. For example, it is 34%, 61%, and 75% of the total imprint volume for a $Zr_{55}Cu_{30}Ni_{10}Al_5$ MG, GeSe₄ glass, and pure crystalline platinum, respectively [13]. The latter case of Pt demonstrates that even for a dense material, whose indentation behavior is essentially isochoric (plastic), the pile-up volume is significantly less than the imprint one. This is because a significant fraction of material moves downwards into the bulk, inducing post-unloading residual stresses. Such a stress field prevents complete recovery of the elastic strains induced during the loading stage and is responsible for the radial-median cracks observed at higher loads in brittle solids (see subsection §2.3).

2.1.2. Effect of composition

Composition affects glass H in several different ways. Neither simple relationships nor efficient tools are available to predict H of glasses from the stoichiometric formulae. At the local atomic scale of the short-range ordering (SRO), the cationic field strength, which accounts for both the valency and the ionic radius, and the bonding energy are important parameters. At the medium-range order scale, H depends on $C_{\rm g}$, on the fraction of non-bridging anions, which can be viewed as 'loose ends', and possibly on the formation of weak channels within the network structures providing pathways for easy shear. These parameters are mostly coupled, making the understanding and prediction of Hcomplex. For example, as T_g is raised, C_g is usually found to decrease, which results in a decrease of H despite an increase of the molar dissociation energy, which scales with T_g . Conversely, upon annealing in the T_g range, the fictive temperature (see reference [34] for a detailed description of this parameter) decreases whilst C_{g} increases as well as the density, so that H increases upon structural relaxation. It is noteworthy that C_g is of primary importance in H changes. Besides, phase separation is often reported (in barium silicates and in borates, for example) and makes the interpretation difficult. Mixed alkali effects, i.e., H goes through an extremum as one alkali is substituted for another, are also reported in different chemical systems (in mixed alkali silicates and germanates for example [35–37]). Then, one must keep in mind that most compositional changes alter T_g the same way changing T affects the glass structure (as depolymerization occurs, especially above T_g , H drops rapidly, and v increases). Therefore, both chemical and T effects need to be considered simultaneously in rationalizing the variation in H.



Fig. 2. Vickers hardness of glass as a function of the glass transition temperature. Background grey marks were extracted from the SciGlass database [38]. Data on chalcogenide and on halide glasses are from [39–43] and [44] respectively. Data for phosphate glasses are from [45] and [46]. Hardness values for silicon oxynitride are from [47–51] and those for silicon oxycarbide glasses are from [52]. Data for silicon-oxycarbonitride and -oxyfluoronitride materials are from [47] and [50] respectively. The germano-aluminate data are from [36].

The hardness of glasses from different chemical systems as a function of T_g is plotted in Fig. 2, using the SciGlass database (background grey marks) [38]. Some peculiar series of glasses are highlighted with colored marks for discussion. Note in this diagram that H is expected to drop to nearly zero at $T > T_g$, so that the data points are intersecting the x axis at the ambient temperature in Fig. 2. A general observation from this representation is that as glasses become more refractory, they also become harder, and unfortunately more brittle. Nevertheless, there are several anomalies to these trends, where the chemical system providing the softest glasses is also the one resulting in the most brittle materials. For example, H of chalcogen-rich chalcogenide glasses is mostly below 2 GPa while their toughness is typically smaller than 0.3 MPa \sqrt{m} , and the most refractory glasses such as amorphous silica and silicon oxycarbides (with $T_g > 1300$ °C) are not as hard as the hardest oxynitride glasses, exhibiting T_g ranging between 900–1000 °C. This is where interesting fundamental aspects come into play.

H depends much on the glass composition, and more specifically on the atomic scale organization. Following the description of the physics of deformation that occurs during indentation deformation, it is anticipated that the sensitivity to densification will play a key role on *H* in the case of glasses with low C_g , whereas the ease for shear will be predominant in glasses with high C_g . Indeed, *H* is the result of a competition between the bond strength and C_g . On the one side, C_g depends very much on the relative size of the constituent elements – and thus on the valency – as well as on the average coordination and electronegativity difference. On the other side, an overall analysis of many chemical systems including metallic ones, shows that the average interatomic bonding energy scales with T_g [18]. This is where the atomic bonding energy comes into consideration. We briefly discuss the key features of specific glass systems below.

- Chalcogenide glasses [39–43]: Despite the covalent nature of the interatomic bonding between adjacent chalcogen elements (Se, S, Te), *H* of these glasses is relatively small (bottom left in Fig. 2) because they mainly consist of chain-like structural units, which are prone to relative sliding, owing to the weak inter-chain van der Waals interactions. In these systems, *H* can be improved by replacing sulfur by selenium [20], which is more refractory, or more significantly by increasing the average coordination number, *<r>*. (For instance, in the Ge-Se system, *<r>* for the Ge_xSe_(1-x) composition is expressed as 4x+2(1-x) = 2(x+1)), by incorporating 3-fold coordinated pnictogen elements such as As or Sb, or even tetra-coordinated ones such as Ge or Si [40,41]. A linear correlation is often reported between *H* and *<r>* up to a maximum amount of 3-fold or 4-fold coordinated elements, beyond which some demixing occurs (formation of As-As cycling groups or Ge-rich clusters above 40 mol.% As or Ge for example). Barium fluorozirconate glasses exhibit *H* values in the 2 to 2.5 GPa range [44]. A major issue with these low *T_g* glasses, especially on approaching the chalcogen rich or halide rich side of the chemical system is that *H* becomes loading-time and rate dependent, as viscoelasticity becomes significant.
- *Phosphate glasses* [45,46,53–55]: These glasses exhibit *H* and T_g values in-between those of the chalco-halide and silicate glasses [45]. In regard of the low T_g of pure P₂O₅ glass (~377 °C), the incorporation of rare-earth elements or tetrahedrally coordinated glass forming cations such as Si and Al leads to a pronounced increase of *H*, as well as the substitution of divalent oxide (CaO or ZnO) for monovalent ones [46,53,54]. The addition of CaO or the substitution of P₂O₅ for B₂O₃ is also found to increase both *H* and T_g in the series presented in Fig. 2 [45,55].
- *Silicate glasses* [36,56–59]: In view of the impressive quantity of data reported in the literature on these glasses (light grey marks in Fig. 2), largely due to the ease in performing Vickers indentation tests on them, we restrict our discussion to some particular cases, which bring to light the great diversity of the situations, to show that there is mostly no straightforward relationship between *H* and the chemical composition in this glass system. Starting with alkaline (A) and alkaline-earth

(AE) silicate glasses, it was noticed by Hand and Tadjiev [36] that as Na₂O is replaced by K₂O, a bell curve is observed for both T_g and H, with a maximum of H at about K₂O/(ΣA) ≈ 0.5 (where ΣA is the sum of the alkaline oxide constituents). This is the so-called 'mixed alkali effect'. Replacing larger AE ions (Ca or Ba) by smaller Mg ions does not result in an improvement of H, T_g and C_g , whilst MgO is more refractory than CaO and BaO. Within the composition range studied in [36], H of mixed A and AE oxides silicate glasses can be ranked as following: H(Na,Ca,Ba) >H(K,Ca,Mg) > H(K,Ba,Mg). Large ions such as K and Ba are found to make the glass softer even though the silica content is slightly increased. The same tendency was reported by Hermansen et al. [56], who concluded that H(Na,Ca) > H(K,Ca) > H(Na,Ba) > H(K,Ba) for (A,AE) silicate glasses containing 75 % SiO₂. Besides, an increase of H was observed when up to 25 % of SiO₂ was replaced by a mixture of AE oxides, although the Si-O bond energy is much larger than the Ca-O and the Ba-O ones. This is because the corresponding increase of the atomic packing efficiency in comparison to a-SiO₂ ($C_g \sim 0.45$) compensates for the decrease of the mean dissociation energy, which clearly reflects in the decrease of T_g . Hence, a horizontal line can be drawn in Fig. 2 through the point associated with a-SiO₂ that intersects with many equally hard glasses containing A and AE oxides, and thus exhibiting much lower T_g values. Focusing on A and AE silicates, Smedskjaer et al. [57] observed that replacing the A element by a smaller one $(Na \rightarrow K \rightarrow Rb \rightarrow Cs)$ does not induce the same H change as the substitution of the AE element by a smaller one (Mg \rightarrow Ca \rightarrow Sr \rightarrow Ba). Whilst both cases correspond to an increase of the cationic field strength, the A substitution leads to softening whereas the AE one results in hardening. It was suggested by the authors that large A cations, being weakly bonded to the silicate tetrahedra, promote a stronger atomic network skeleton (SiO₄ tetrahedra for example). In contrast, in the cases of cations with larger valency such as AE (+2) or Rare-earth (+3), the cationic field strength is directly affecting H, and thus a decrease of the ionic radius induces an increase of H. The presence of elements with multiple coordination numbers such as Al (4,5,6), Ge (4,5), B (3,4), which enhance the atomic packing in comparison to tetrahedrally coordinated glass forming elements such as Si, results in an increase of H. As was discussed by Morin et al. [58], in simple silicate glasses, where network-forming cation coordination is fixed, the fraction of non-bridging oxygens (NBO) per network cation is also fixed and thus structure-property effects are limited to structural details of network connectivity and bond strengths (other than network speciation). On the contrary, this constraint is relaxed in aluminoborosilicates in which B and Al coordination vary significantly.

Furthermore, when cations with the same valences and coordination numbers are present, smaller ionic radii lead to large cationic field strength – given by the valency of the cation divided by the square of its distance to a neighboring oxygen atom – and thus to a more efficient packing.

For example, *H* is significantly increased (from ~6 to 9 GPa) as La is replaced by Y, or further by Lu and Sc in rare-earth aluminosilicate glasses with fixed Al_2O_3 and SiO_2 contents [59]. A similar trend was observed (*H* increases from 5.6 to 6 GPa) in a series of phosphate glasses as La was substituted for Nd, Sm, Gd, and finally Y [46].

In the sodium titanium silicate system [60], ν increases monotonically with the sodium and with the titanium contents, from 0.182 for the Na₂O(10)-TiO₂(4)-SiO₂(86) composition to 0.245 for the Na₂O(25)-TiO₂(7)-SiO₂(65) (numbers in brackets express the composition in mol. %). Commensurately, the deformation mechanism evolves toward more volume conservative shear flow and less densification, as evidenced by the relative contribution of both processes to the indentation volume [61]. The transition in the deformation mechanism coincides with a significant change in the structure with the formation of (Ti, Na) rich clusters inducing local increases of C_g and of the number of non-bridging oxygen atoms as well, in favor to shear flow, which becomes pronounced in glasses with more than 25 mol.% Na₂O and 10 mol.% TiO₂ (ν >0.23). It is noteworthy that although T_g increases, from 510 to 600 °C, and v decreases as the amounts of TiO₂ and Na₂O decrease to the benefit of the SiO₂ content, *H* remains nearly invariant. *H* is about 4.7 and 4.6 GPa (10 N Vickers indentation load) for the Na₂O(10)-TiO₂(7)-SiO₂(83) and Na₂O(25)-TiO₂(10)-SiO₂(65) grades respectively, having ν values of 0.183 and 0.237. But for the Na₂O(15)-TiO₂(10)-SiO₂(75) intermediate case, *H*=5.4 GPa and the smallest resistance to indentation cracking is recorded.

• Silicon oxynitride glasses [47–51]: These glasses are mostly obtained by conventional melting in either argon or nitrogen atmosphere, typically up to 1750 °C, adding some nitrided powders such as AlN and Si₃N₄ in the powder mixture. Nitrogen is found to substitute for oxygen in the glass network leading to the formation of Si-(O,N)₄ tetrahedral units, where it is mostly connected to three Si-(O,N)₄ tetrahedra. A significant improvement of the cross-linking degree is achieved, which results in better mechanical properties in general. As some oxygen is replaced by nitrogen, the dissociation energy is not affected in a significant manner, but the C_g is much larger (from ~0.5 for most A and AE-silicate glasses to ~0.55–0.6 for silicon oxynitride). Consequently siliconoxynitride glasses, and especially those containing rare-earth oxides, are among the hardest inorganic – and non-metallic – glasses. The substitution of some oxygen by tetrahedrally coordinated carbon to form silicon oxycarbide glasses results in an increase of the dissociation energy and thus in T_g up to ~1300 °C for the SiOC grade (as compared to about 1070-1200 °C for a-SiO₂) [52]. However, these glasses suffer from a relatively open structure, with an C_g in the range of 0.41-0.43 [62]. Consequently, the permanent deformation in them stems essentially from densification and *H* is not as large as the one reported for silicon oxynitride glasses.

2.2. Indentation cracking

2.2.1. Driving force and crack morphology

As already mentioned, the indentation volume after complete unloading is still larger than the sum of the densification and the pile-up volumes: a significant amount of matter is radially displaced permanently during loading and is responsible for the development of the residual stresses. The stress field associated with the loading stage as well as the residual stress field give raise to a complicated microcracking pattern in the vicinity of the imprint. The way glass deforms beneath the sharp contact loading governs the microcracking features. It was long recognized [63,64] that different crack morphologies occur depending on the glass composition and indenter geometry. For instance, surface ring cracks (corresponding to the Hertzian cone cracks that develop under the surface) are predominantly observed in amorphous silica and silica-rich glasses (as well as borates to a lesser extent), whereas radial (radial/median semi-elliptical under the surface) cracks are seen to extend from the indentation corners in the case of soda-lime-silica glasses (such as ordinary window and crown glasses) [65]. A binary classification was first proposed, where glasses exhibiting radialmedian cracking were considered as 'normal', as opposed to abnormal ones (exemplified by a-SiO₂). The ring crack formation at the surface of amorphous silica and silica-rich glasses (low C_g glasses), and its development toward a cone crack with a steep angle was described in the pioneering work of Knight et al. [66]. It was proposed by them that the shear induced compaction of the region beneath a conical indenter extends to the contact area so that the propagation of ring cracks that nucleate in the contact zone occurs along shear stress trajectories. The truth is that all glasses are partially normal and abnormal, depending on the extent to which they densify during indentation. From residual-stress observations, it was noticed by Arora et al. [12] that reconstructive flow takes precedence over densification as the glass atomic structure becomes less and less open, or more closely packed. A mechanics analysis of this problem shows that v, E, and H play key roles in this process. In particular, a large variation in v, when glasses from different chemical systems are compared, from 0.1 (SiOC and silica-rich glasses) to above 0.28 (oxynitride glasses), is primarily responsible for the dramatic changes in the indentation pattern, from ring/cone cracking at low v to fully developed radial-median cracks at large v, until ductility shows up typically for v > 0.4, where stress relaxation via plasticity or viscous flow becomes sufficient to suppress microcracking (for Pd based MGs for example, or as T gets close to T_g [64,65]. The dependence of the stress field at the periphery of the imprint on E, H and v is illustrated in Fig. 3 (see [6,64] for details regarding the calculations), in the case of the normal component σ_{rr} (in spherical coordinates, with origin on the surface at contact point, θ being the angle to the loading axis, and a the radius of the circular imprint associated with the equivalent conical indenter). This stress component is the driving force for the ring/cone cracking at $\theta = \pi/2$ and for the subsurface lateral cracking (eventually resulting in chipping) at $\theta = 0$. For $\nu < 0.18$, σ_{rr} ($\theta = \pi/2$) is

positive on loading, irrespective of the E/H ratio⁵. This means that ring/cone cracks are likely to form on loading in this range of v, which corresponds to silica-rich glasses for example. An examination of σ_{rr} (θ =0), shows that it is negative on loading for v < 0.2, but becomes positive on unloading at higher v, with an intensity that goes up rapidly with the E/H ratio, especially for v between 0.25 and 0.35. In this latter case, lateral cracking can be expected upon unloading and more particularly for glasses with $v \sim 0.3$, such as silicon oxynitride ones.



Fig. 3. Driving force for ring/cone cracking, $\sigma_r(r=a, \theta=\pi/2)$, where *a* is the radius of the equivalent cone, and subsurface lateral cracking, $\sigma_r(r=a, \theta=0)$) for different *E/H* ratios as a function of the Poisson's ratio, *v*. (Reprinted with permission from Rouxel *et al.* [6]. Copyright (2019) Elsevier)

The (*E/H*, *v*) regimes where radial/median cracks, which are governed by the $\sigma_{\phi\phi}(\theta=\pi/2)$ stress component, and the ring/cone cracks are favored are illustrated in Figs. 4 (a) and (b), respectively, for different glass forming systems. In these figures, the thick red line shows the isostress contour where $\sigma_{\phi\phi}(\theta=\pi/2)$ vanishes, i.e., where the driving force for cracking reaches its minimum. It is noteworthy that the 'less brittle' glass developed by Sehgal and Ito [67], with *E/H* = 14.7 and $\nu = 0.18$ stands precisely in the red contour for $\sigma_{rr}(\theta=\pi/2)$ and in the compressive side for $\sigma_{\phi\phi}(\theta=\pi/2)$. It is important to note, however, that the analysis of the driving force for indentation

⁵ Whether cracks will actually show up in the glass under indentation does not solely depend on this driving force, but also on the fracture toughness of the glass, which ultimately controls the onset for crack initiation.

cracking presented in Figs. 3 and 4 does not allow to conclude whether cracks will form or not; the occurrence of cracks is ultimately controlled by the fracture toughness of the material.



Fig. 4. Driving force for two common indentation cracking patterns, namely a) the radial-median crack system, as illustrated by $\sigma_{\phi\phi}$ at the surface (q=p/2) (left), and b) the ring-cone crack system occurring in loose packed atomic structures (silica-rich glasses for example) as given by σ_{rr} . The isostress contours were drawn by means of the expression of the stress components at the vicinity of the imprint provided in [6,64]. The thick red line corresponds to zero stress and separate domains where cracks are either unlikely to show up (negative stress) or favored (positive stress).

The Vickers indentation responses of different glasses, or of a given glass at different *T*, are illustrated in Fig. 5. As anticipated from the driving force, a-SiO₂ and borosilicate glasses are prone to cone cracking, whereas soda-lime-silicates and fluorite glasses exhibit the radial-median crack system, with some visible subsurface cracking when v > 0.24, and even the formation of chips at v > 0.26. Nevertheless, some critical load needs to be reached for the microcracking pattern to fully develop (this will be discussed in the next subsection), as illustrated for the case of a borosilicate indented at 1 and 98.07 N (Figs. 5 (g) and (h)). As *T* is increased, both *E/H* and *v* change. Since *H* decreases faster than *E* [68,69], *E/H* increases, as well as *v*, especially in the case of 'fragile' glasses [52] (per Angell's concept). Consequently, in the case of an ordinary window glass, damage is more pronounced as *T* is increased up to about 400 °C [70]. At higher *T*, the behavior becomes viscoelastic and a brittle to ductile transition occurs, such that cracking disappears at 480 °C [71].



Fig. 5. Optical micrographs of different indentation cracking patterns produced by Vickers indentation. a) to f): Indentation load of 9.81 N for 15 s for oxide glasses with different Poisson's ratio, from left to right: 0.15 (a-SiO2), 0.195 (borosilicate), 0.227 (soda-lime-silica: SLS), 0.248 (SLS), 0.264 (SLS), and 0.298 (fluorite) (after [64]). g) and h): borosilicate for 1 N and 98.07 N indentation load. i) to l): SLS glass for 49 N load at 20, 200, 450 and 480 °C (after [70]).

2.2.2. Crack initiation and cracking resistance



Fig. 6. The probability of crack initiation, determined as the average number of radial cracks per corner out of a series of indents performed at a given load (typically over 10), as a function of the indentation load, P. The crack resistance is the load at which the probability of crack initiation is equal to 50 % (i.e., on average two corners out of four will contain cracks). Insets on the left show typical indentation cracking patterns corresponding to 0, 2, 3 and 4 well developed radial cracks. All results were obtained in ambient conditions, i.e., in humid air. Unfortunately, the accurate value of the water content in the air was not specified by most authors.

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Lawn et al. [72] suggested that the widely-used expanding cavity models for describing the deformation fields underneath indenter are then no longer valid when a material undergoes densification by compaction within the immediate contact zone of a sharp indenter. (This is also true when phase transformations occur underneath the indenter [73,74].) This is because of the intense hydrostatic compressive stresses that render the volume of the indentation to be more readily accommodated within the compaction zone, diminishing the intensity of any residual stresses. High pressure investigations conducted in the past twenty years on series of glasses from different chemical systems, either by isostatic loading or by sharp contact loading, uniformly concluded that densification contributes to over 40 % of the indentation deformation [15,20,22,31,56,60,75-78]. Therefore, and in view of (i) the wide diversity in the glass deformation responses, and (ii) the lack of relevant universal constitutive law, methods based on the measurement of the indentation crack length are not recommended for the estimation of fracture toughness [5,79]. Nevertheless, sharp contact loading experiments, by means of cube-corner, Vickers, Knoop or Berkovich indenters, are still remarkably useful to characterize the onset for crack initiation, with the aim to reproduce what may happen in service conditions when the surface of a glass part is damaged by impacts, scratches, indents, etc. The crack resistance of a glass can be assessed by means of Vickers indentation tests, by indenting stepwise at increasing loads, and counting the number of radial cracks emanating from the corners of the residual imprints [80]. The probability of crack initiation is then defined as the ratio between the number of corners where a radial crack was formed and the total number of corners (4 for a Vickers test). When the occurrence of two radial cracks (optical microscope resolution) from two opposite corners of a Vickers indent (four cracks are observed when the indentation cracking pattern is fully developed) is considered as a criterion for the onset of indentation cracking, values of ~0.3, 0.7, 1, and 10 N are obtained for the critical indentation load for lead glasses, window glasses, E-glass (a low alkali boro-aluminosilicate glass) and the mother Vycor glass (silica-rich (96 mol.%)) borosilicate glass) respectively (Fig. 6). The so-called 'less brittle' glass (79 mol.% SiO2 with alkaline and alkaline-earth) with a critical indentation load for crack initiation larger than 10 N was also proposed in the late 1990s, which represents a more than one order of magnitude improvement, in comparison to an ordinary window glass [80]. Nevertheless, there is no one to one relation between the onset load for crack initiation and mechanical properties such as H, K_{Ic} , elastic moduli, strength, or any simple combination of those such as the brittleness index $(B=H/K_{Ic})$ [5,22,75,81]. In an extensive comparison of German medieval and ancient Turkish glasses, Hasdemir et al. [81] reported a much better crack resistance for an ancient Turkish glass with 70.5 mol.% SiO₂ ($C_g \sim 49.5$) than for a medieval glass with 46.2 mol. % SiO₂ (C_{g} ~53.6). The general trend, again confirming the crucial role of C_g , is that glasses with relatively open atomic structures, such as a-SiO₂, are more resistant

toward crack initiation than glasses with large C_g , such as lead-borate glasses for example [80], and indeed an increase in the critical crack initiation load with the densification contribution to the formation of the imprint (and thus with the decrease of the intensity of the residual stress field) was found (Fig. 7) [22,75,76,80,81]. It is interesting to note here that although silicate glasses are based on the same SiO₄ tetrahedral units, the secondary cationic species, mostly alkaline and alkaline-earth ones, play a key role in determining the critical load for indentation cracking. The overall trend is that the more efficiently the atomic network space is filled, the smaller the critical load becomes. In general, enhanced levels of nano-porosity and free volume content are beneficial to the indentation cracking resistance.



Fig. 7. The critical crack initiation load (associated with the formation of two corner radial cracks) as a function of the atomic packing density. The inset is reprinted with permission from Yoshida [15]. Copyright (2019) Elsevier.

2.3. Effects of time, temperature, and pressure

The indentation response of glasses is affected by time in several different ways. First, due to the exceptional stress intensity (GPa order) at the indentation site, creep cannot be excluded even at RT. Besides, time, especially during annealing at T close to T_g , allows for the structural relaxation of the material, i.e., for a reduction of the free volume content, so that the indentation behavior slightly evolves toward a relatively lower contribution of densification and a larger amount of pile-up around the indent. The rate at which the glass is loaded is also, obviously, of paramount importance. Unlike

densification, shear flow is not kinematically bounded. Consequently, its relative contribution can increase sharply with the loading time and with T. For glasses with different T_g values, it tends to decrease with rising T_g . As a consequence of shear-thinning, which is favored in weakly polymerized network structures, viscosity may drop by orders of magnitude due to the fact that shear stresses are in the order of GPa in the regions that are immediately beneath the indenter. In addition, because of the large stress and strain rate levels at indentation site, the thermodynamics of the processes at play during sharp contact loading tend to be singular in character, and involves heat fluxes as well as entropy changes, and consequently local variations of the physical properties of the material. Nevertheless, considering a simple linear Maxwell model for the creep function, the following straightforward expression for the time-dependence of H is obtained [82]:

$$H(t) = \frac{2\eta\mu}{(\mu t + \eta) \cdot \tan\phi}$$
(2)

where the η/μ ratio gives the characteristic relaxation time, and ϕ is the apical angle of the axisymmetric indenter (equivalent cone for a Vickers indenter). In the case of a purely elastic materials ($\eta \rightarrow \infty$), this expression reduces to the classical elasticity solution (Eq. 1).

Most glasses experience a decrease of their *H* with increasing *T*. As discussed in subsection §2.2, this decrease is more dramatic than the corresponding decrease of the elastic moduli. Consequently, an increase of the intensity of the residual stress field, which is governed by the *E/H* ratio, and thus the driving force for cracking, is expected. The increase of the *E/H* ratio is particularly large when stiffening of the glass with increasing *T* occurs (this is the so-called 'elastic anomaly' observed for a-SiO₂). Consequently, the formation of radial/median cracks, as opposed to the ring/cone cracking, becomes favored as *T* increases from below T_g , at least based on a simple elastic approach of the far field stress. This was experimentally verified in a few cases, mostly for a-SiO₂ and soda-lime-silicate glasses [68–70]. As the Vickers indentation testing *T* is raised from ambient to 400 °C, the ring/cone cracking system observed in a-SiO₂ disappears to the benefit of the radial/median system. Conversely, as the testing *T* is decreased from the RT, *E/H* as well as *v* decrease and shear flow becomes less and less significant and eventually disappears at –196 °C (liquid nitrogen) as observed by Kurkjian *et al.* [27] in the case of a-SiO₂ and a soda-lime-silica glass, for which the *E/H* ratio decreases from 8 and 10 at RT to 3 and 6.3, respectively at –196 °C.

Pressure, *P*, and *T* have strong effects on the atomic network structure. In general, the C_g increases with *P* while *T* tends to de-structure or depolymerize the network. In both the cases, a rise of *v* is noticed. High pressure experiments lead to denser materials (even after unloading), to an extent that was found to scale with *v* of the glass because of the intimate relationship that exists between *v* and the C_g [65,83]. Hence, there is less room for further indentation densification after a high-pressure

treatment. Both experiments [13] and molecular dynamics (MD) simulations [84] point to a shift to more pile-up of matter at the vicinity of the imprint and thus shear flow after high pressure treatments and, as a matter of fact, *v* is mostly larger in the treated glass than in the pristine sample.

2.4. Nanoindentation studies

Most of the indentation studies performed on glasses up to the 1980s were conducted with conventional hardness tests in which the impression area is measured after the indenter is removed. Since this is an *ex-situ* measurement process, loss of some crucial information, which could otherwise be obtained from the real-time indentation response measurements (such as time- and load-dependent parameters), was a distinct possibility. The advent of the nanoindentation technique in the 1980s and the widespread adaption of it for measuring mechanical properties (especially of 'small volume materials') made it possible to extract additional information during indentation, since the small-load instrumented test can provide real-time record of indentation responses obtained under precisely controlled conditions. Consequently, instrumented indentation in general, and nanoindentation in particular, is extensively employed to study a wide variety of physical phenomena in inorganic glasses. In this section, we briefly review some of them while nanoindentation studies on MGs are summarized in subsection §3.

2.4.1. Densification behaviour

The nanoindentation technique was utilized to gain intricate insights into the permeant deformation characteristics of various glasses. The fact that the areas under the loading and unloading parts of the *P*-*h* curves give the work done during indentation and elastic recovery, respectively, was exploited by Suzuki et al. [85] to examine the energy spent for permanently indenting fused silica glass at RT with a Vickers tip for different maximum depths of penetration, h_{max} . On the basis that the energy spent indenting the glass was similar to the reported activation energy required for the recovery of densification in it, they conclude that the main mechanism of permanent deformation during indentation is densification. Lee et al. [86] examined the effect of different indentation strains, varied by using different sharp-tipped indenters, on commercial window glass. By comparing the atomic force microscopy images of the indents before and after annealing (and through the process evaluating the volume of the recovery due to annealing), they revealed that the relative contribution of the shear flow to the total permanent deformation becomes larger with the indentation strain. They then employed a spherical indentation tip with which the indentation strain can be varied by changing h_{max} and concluded that the plastic deformation at the early stage of indentation is dominated by densification, and that the contribution of shear flow increases with strain. Their strain rate-based analysis shows that the latter's mechanism is shear transformation zone (STZ) mediated one.

Niu *et al.* [87] employed nanoindentation to introduce surface defects in a controlled manner and then study the effect of such defects on the chemical dissolution rates of silica and soda-lime silicate glass surfaces through atomic force microscopy characterization. Their experimental results show indentation leads to enhanced dissolution rate, which was attributed to densification of the glass that occurs underneath the indenter. Such an enhancement completely 'disappears' upon postindentation annealing, proving that pressure-induced structural modifications are reversible. On this basis, they propose the study of dissolution rate can be utilized to probe the structural changes in glasses during indentation at the nanometer scale.

2.4.2. Rates effects on hardness

Due to the ready availability of polished disc samples, fused silica, i.e., $a-SiO_2$, is commonly used as a reference material (or 'standard' sample) for the calibrations and verification of nanoindentation equipment and indenter tip. However, it is often overlooked that fused silica exhibits time-dependent plastic deformation during indentation, and creep can affect the unloading curve and should be minimized by a load-hold at the peak load [88]. While this serves as an example for highlighting the necessity of examining the time-dependent nanoindentation responses of glasses, the number of studies performed on this topic thus far are not many. The adopted approaches in these studies can be categorized into the following two groups: (1) directly examining the effect of the indentation rate (either loading rate or indentation strain rate) on the measured H and (2) indirectly estimating the creep behavior.

The effect of the loading rate ($\dot{P} \sim dP/dt$ where *P* is the load and *t* is the time) on *H* of sodalime-silica glass was investigated over a wide range of \dot{P} [89–91]. A two-stage behavior can be seen from it; *H* increases rapidly for up to some critical rate, whereafter the enhancement with \dot{P} occurs less steeply (Fig. 8). In contrast, 'micro-indentation' experiments are inconclusive; the *H* is increased [92], is decreased [93] or is almost rate-independent [94].



Fig. 8. Nanoindentation hardness variation as a function of loading rate performed on raw and ionexchanged (for different periods of time) aluminosilicate glasses. (Reprinted with permission from Li *et al.* [95]. Copyright (2018) Elsevier)

Studies on the influence of indentation strain rate ($\dot{\epsilon} \sim h^{-1}(dh/dt)$) on *H* can lead to an estimation of the strain-rate sensitivity (SRS), $\frac{\partial H}{\partial \dot{\epsilon}}$, which is often accomplished by conducting strain-rate jump tests. The SRS values of a wide variety of non-metallic glasses over a broad range of compositions including covalent, ionic, and superionic (typically containing Li, Na, S, Ag or I, with ionic conductivities better than $10^{-3} \text{ S} \cdot \text{cm}^{-1}$) glasses are investigated by Limbach *et al.* [96], who attempted to correlate them with the thermo-physical and structural properties such as reduced glass transition temperature (T/T_g), C_g , average single bond strength, and ν (Fig. 9). As seen, SRS in glasses is relatively small (the maximum value is less than 0.1). While broad correlation could be found (for example, SRS increases with T/T_g , especially for $T/T_g \ge 0.6$), the trends are somewhat scattered.



Fig. 9. Strain rate sensitivity data obtained using the nanoindentation tests on various glasses plotted as a function of (a) the reduced temperature, and (b) the atomic packing density. (Reprinted with permission from Limbach *et al.* [96]. Copyright (2014) Elsevier)

Early studies on the nanoindentation creep of non-metallic glasses were focused on a specific topic: the effect of water (H₂O) on the degradation of the glass. Han and Tomozawa [97], who performed 'instrumented' micro-indentation, and Keulen [98] explored the influence of the water content in glass on the indentation creep. They found that water enhances the creep rate by promoting viscous flow [99]. To date, limited studies have been carried out on the nanoindentation creep behavior of non-metallic glasses (for instance, see [100]). However, detailed mechanisms that can explain how and why the nanoindentation parameters (including the peak load, \dot{P} , indenter type, and holding time) affect the indentation creep behavior of non-metallic glasses are not fully understood yet and hence require further exploration. Here, it is important to note that decoupling the creep effects from those of machine drift during nanoindentation, which could be substantial for some instruments, at various loading rates or hold times could pose a significant challenge.

2.4.3. Indentation size effect



Fig. 10. Correlation between nanoindentation displacement and hardness for fused silica. (Reprinted with permission from Suzuki *et al.* [85]. Copyright (2004) John Wiley and Sons)

An interesting phenomenon that was confirmed using the nanoindentation on glasses is the indentation size effect (ISE), which manifests through a significant increase in H upon decreasing the indentation load, that is with the reduction in the probed volume. As an example, data obtained on fused silica (with a density of 2.2 g/cm³) is shown in Fig. 10⁶ [85]. ISE is widely reported in crystalline metals and alloys and is rationalized by recourse to the strain gradient plasticity models that postulate the necessity of certain density of dislocations to accommodate the imposed plastic strains purely from the geometrical considerations [101]. Hence, the observation of ISE in glasses is surprising, given that they lack long-range periodicity (and hence dislocations) [85,89,102,103]. There have been attempts to explain the origin of the ISE in non-metallic glasses such as the empirical model based on Meyer's law [102], the minimum specimen resistance model (Hays–Kendall model) [104], the proportional specimen resistance (PSR) model [105], and the modified PSR model [102]. All these approaches are focused on how to describe the experimental data of ISE by correlating H, peak load, and contact depth. An alternate explanation for ISE in ceramics, which is based on fracture mechanics, was given by Swain and Wittling [99]. Although the connection between ISE and the fundamental mechanisms of glass deformation (such as densification and shear flow) has not been established yet, some plausible explanation was proposed by Li et al. [105,106], based on the increase of the indentation surface to imprint volume ratio. With a reduction in the load both the contact area and the indentation volume decrease. Since the former scales with a^2 , the latter with a^3 (where a is

⁶ The universal hardness displayed in this figure was estimated by the authors using the maximum applied load (146 mN) and the penetration depth at the peak load.

half the diagonal length of the projected imprint for the Vickers case), the surface to volume ratio increases with decreasing P. On this basis, Li et al. conclude that friction at the indenter-material interface is a major contributor to the observation of ISE. The role of friction in the load-independent high-load regime becomes negligible.

2.4.4. Effect of irradiation on the mechanical properties

The structure of the glasses is highly susceptible for change upon exposure to photonic and ionic irradiation and a detailed understanding of the effect of such changes on the properties are of paramount importance in a wide variety of contexts that range from nuclear waste disposal to optical communication technology. Since the irradiation effect is often confined to a thin surface layer (in the order of microns) of the material, nanoindentation is particularly useful to probe the properties of irradiated glasses and hence widely used. We summarize some such studies below.

Laser irradiation is frequently utilized for the scribing and welding of various glasses. For example, fiber Bragg gratings (FBG) in optical fibers, whose refractive index can vary markedly under exposure to ultraviolet (UV) radiation, are fabricated by modulating the refractive index via exposure to a patterned UV radiation. The mechanism of photosensitivity in the glasses used for optical fibers and the variation of it with UV exposure are rationalized by recourse to either the electronic models that rely on irradiation-induced defects affecting the electronic states, or the structural models that postulate changes to the intrinsic structure of the glass. The compactiondensification model, which belongs to the latter category, hypothesizes that the laser-irradiation induces compaction of the glass through internal structural rearrangements, and the resulting densification alters the index of refraction [107]. Aashia et al. [108] employed the nanoindentation technique to examine this, by studying germanosilicate preforms that were exposed to varying levels of UV irradiation. Their results show that while H remains invariant with the exposure time, the E increases first, indicating densification, before sharply decreasing due to internal dilation and damage accumulation that occurs in the glass, which is in accordance with the compaction-densification model. Likewise, Bellouard et al. [109] reported an increase in E in the laser-affected zone of silica that was irradiated with low-energy femtosecond pulses, whereas high-energy pulses led to a reduction in both E and H. The softening behavior in the latter was attributed to nonbridging oxygen hole centers formed in the regions exposed to femtosecond laser irradiation, especially in high pulse energy regime, which cause lower connectivity [110]. In addition, by measuring the radial crack lengths initiated from nanoindentation, Kongsuwan et al. [110] found out that the fracture toughness also decreases slightly (<10%), which can be minimized by lowering the laser pulse energy or increasing the laser scanning speed. Sabapathy et al. [111] extended this work to GeGaS and GeGaSSb chalcogenide glasses whereas Ayiriveetil et al. [112,113] studied Er₂O₃-doped GeGaS and

 GeS_2 glasses, wherein they examined the structural and mechanical characteristics of the glasses subjected to waveguide inscription using ultrafast lasers. The nanoindentation data reveled that the top region of the waveguide is considerably compliant and softer as compared to the other regions in the waveguide or the bulk. Micro-focus Raman spectroscopic studies that were performed in conjunction confirmed the existence of such distinct regions and support the notion of laser irradiation-induced structural modifications to the glass atomic network.

Borosilicate glasses are potential candidates for underground disposal of high-level radioactive waste owing to its radiation durability [114,115]. Nanoindentation has been widely used to investigate their ion or electron irradiation sensitivity. In general, ion irradiation causes a reduction in both E and H, as compared to pristine glasses. Abbas *et al.* [116], who conducted nanoindentation experiments with complementary MD simulations on aluminoborosilicate glasses irradiated with He and Kr ions, attribute such property changes to an increase in the polymerization of the network structure due to irradiation. Peuget *et al.* [117] tried to decouple the relative influences of electronic and nuclear deposition energies from ion irradiation and suggested that the latter is predominant in the irradiation-induced softening. By comparing nanoindentation H variations of borosilicate glasses irradiated with different ions, later studies also confirmed the dominated effect of nuclear energy in causing the ion irradiation induced variations in H and E [118–123] as well as unchanged or even reduced polymerization of the glass network [118,124].

Alternatively, external irradiation means to simulate natural radioactivity and accelerate radiation experiments, were utilized and the resulting irradiated surface layers were evaluated using nanoindentation [125–127]. Yang *et al.* [125] reported that the *H* reduction induced by He ion irradiation (~14%) is larger than the one by electron irradiation (~4%). It was suggested that the extended incubation dose and slower decreasing rate in the latter may be related to the survival and accumulation of point defects, since ionization and electronic excitation are the dominant mechanisms during electron irradiation. In addition, negligible compositional dependence was found in the Au ion irradiation induced variations in both *H* and *E* [127] whereas the changes by electron irradiation shows a certain level of dependence on the chemical compositions [128], which was attributed to the combination of several factors (transition of [BO₄] to [BO₃], the modification in polymerization, volume compaction, reduce in average ring size and point defects).

While a majority of the nanoindentation studies on ion/electron irradiated glasses are performed on borosilicates, a few investigations on other types of glasses that show distinct behavior are available. For example, Guan *et al.* [22], who compared the Xe ion irradiation susceptibility of borosilicate glass and a-SiO₂, found that *H* of silica decreases (only marginally) while *E* increases upon irradiation. On this basis and some MD simulation results [23-26], it was suggested that the irradiation-induced softening of sodium borosilicate is not due to breaking of silicate network but to

the breaking of boron-related network [124,129]. Interestingly, a binary potassium-silicate glass, which also does not contain boron like silica, was found to show a behavior similar to the one of a borosilicate glasses, that is both H and E decrease as the electron dose is increased [130]. Systematic nanoindentation studies on various types of glasses are required to further reveal the underlying reasons for the irradiation-induced mechanical property changes.

2.4.5. Topological constraints in chalcogenide glasses

As already mentioned in subsection §2.1.2, chalcogenide glasses are the softest and most brittle amongst all the inorganic and non-metallic amorphous materials. They consist of covalently bonded networks of chalcogen atoms (S, Se, Te) connected to fourfold coordinated atoms such as Ge and Si. The degree of network connectivity in these glasses, which depends on the mean coordination number <*r*>, can be varied by changing the composition [131]. At low connectivity, the number of degrees of freedom is more than the number of constraints, which leads to the glass being 'floppy'. When the number of constraints is larger than the degrees of freedom, the structure is 'rigid'. Thus, an increase in <r> can induce a floppy to a rigid transition [132–134] at the rigidity percolation threshold that refers to the critical average coordination number $\langle r_c \rangle$ at which the number of constraints is equal to number of degrees of freedom. For random covalent networks, $\langle r_c \rangle = 2.4$. Various property anomalies that are observed at the rigidity percolation threshold of chalcogenide glasses are rationalized by recourse to the mean field constraint theory [132,133,135]. The floppy to rigid transition is usually not sharp and Boolchand et al. [136] proposed that the range of <r> over which it occurs (for some chalcogenides and oxide glasses as well) is associated with a so-called intermediate phase (IP) whose boundaries are labeled as rigidity and stress transitions. Over the IP region, the glass network is rigid but is unstressed due to optimum space filling [137,138]. Chalcogenide glasses with the compositions corresponding to this region are known to exhibit remarkable electrical, thermal, structural, and optical properties [136,139–141]. Since the mechanical behavior of glasses is sensitive to the atomic scale organization in them, the extended IP region should also get reflected in the mechanical properties, especially on the elastic modulus since it is a physical property that is highly sensitive to the connectivity and rigidity of the networks within the glass, which can be evaluated using nanoindentation. Das et al. [140] examined the variation of E in bulk GeTeSi glasses and report a plateau in for $2 \le x \le 6$ in Ge₁₅Te_{85-x}Si_x glasses, for which <r> range between 2.34 and 2.42, see Fig. 11. In an earlier study on the same glass system, Anbarasu et al. [142], who examined the composition dependence of enthalpy change during glass transition obtained from non-reversing heat flow-a key attribute of IP that should have near-zero values-show a broad through in the same composition range, and hence identified it as IP formation range. A subsequent

study by Varma *et al.* [137] on Ge-Te-In glass system also showed that the IP region can be identified with the aid of nanoindentation.



Fig. 11. Variation of *E* in $Ge_{15}Te_{85-x}Si_x$ glasses with composition. (Reprinted with permission from Das *et al.* [140]. Copyright (2012) Elsevier)

2.5. Modeling and simulation of the indentation process

Although many attempts to model the indentation behavior of non-metallic inorganic glasses were reported in scientific journals, several (very) serious problems remain. The elastic behavior can be modeled by means of approaches inspired by Boussinesq [143] (contact point loading) or Hertz (no deformation at the surface) [144], and then in the case of axisymmetric indenters, some solutions were provided by Sneddon [32] and Johnson [145]. Accounting for the irreversible deformation component is complicated; in particular, the force distribution along the contact area is usually not known, and so is the actual mechanical behavior of the material under such an intense stress field (stress is of the order of H), especially in the region close to the indenter and in the early stage of the imprint formation. Then time and temperature come into play. The slip-line field method [146] was applied to analyze the two-dimensional plane strain indentation of a rigid plastic material by an axisymmetric indenter [11,145]. In most of the approaches, a plastic zone is considered to develop beneath the indenter and to be confined by the surrounding elastic matrix. This zone expands and may eventually reach the surface on the sides of the indenter, allowing for matter to pile-up. This cavity expansion model is derived from Hill's spherical cavity solution [24]. As the core expands, due to the increasing indentation load, the stress increase in proportion to $\ln(r)$ in the cavity, and as $1/r^3$ in the surrounding half-infinite elastic medium, where r is the distance to the initial point of contact. A limitation of this model is that it does not consider the hoop stresses on the free surface of both half

spaces. Besides, an exact analytical solution for this problem is out of reach inasmuch as the plastic yield stress of a glass is an unknown quantity, and how pressure contributes to the process. A field referred to as 'blister' field [14,147] was introduced to better describe the residual stress field that develops at the indentation site, especially on unloading, and is responsible for the microcracking events that occur during unloading in brittle materials such as silicate glasses and ceramics. By superposing the Boussinesq's stress field originating from a point-load normal to the surface of a semi-infinite elastic body and a blister field stemming from a strain nucleus built on three double forces of same intensity, Yoffe [147] proposed a field having the remarkable ability to provide an accurate description of the various indentation cracking features, especially in the case of materials experiencing densification (such as silicate glasses). This approach remains micro-mechanical and semi-empirical though. The strength of the blister fields is usually not known. Nevertheless, attempts to correlate the intensity of the blister field to the C_{g} , and to the sensitivity of the glass to densification, were quite successful in the case of silicate glasses [64,148]. Another approach consists in implementing a yield criterion accounting independently for both shear and pressure effects (such as in the Drucker-Prager constitutive law) in a finite element (FE) analysis code, and further introducing some hardening to account for the fact that as densification proceeds, permanent deformation becomes more difficult [149,150].

In the case of time- or rate-dependent materials, and especially for indentation experiment conducted from 0.9 T_g and to higher T where creep and viscoelasticity become significant, the exact elasticity solutions provided by Sneddon were successfully extrapolated to the case of linear viscoelasticity [151,152] using the Boltzmann's superposition principle. Using the finite element method (FEM) and remeshing techniques [153], discrete element method [154] or an X-FEM method [155], the geometrical characteristics of the Hertzian cone cracks observed in brittle materials could be reproduced well.

Recently, Luo et al. [156,157] conducted molecular dynamics (MD) simulations to gain a detailed understanding of the stress evolution and crack nucleation during indentation of oxide glasses. Their work revealed that the MD simulations can be a helpful tool for better understanding the underlying criteria for indentation cracking and its resistance of oxide glasses by providing the detailed information about principal stress fields and deformation morphology.

3. METALLIC GLASSES

In most common solidification conditions, metals and alloys crystallize upon cooling from the liquid state. However, it is possible to circumvent crystallization and obtain amorphous alloys by rapidly quenching the molten alloys of some specific compositions. Sixty years back, Klement *et al.* [158] first reported the synthesis of MGs (1960), which were achieved by imposing very high cooling rates

 $(> 10^{6}$ K/s) that allow the melt to bypass crystallization. Since this discovery, there has been extensive research into the structure and properties of MGs [23,159–163]. The critical requirement of high cooling rates for obtaining MGs in most alloy systems meant that they could only be produced in thin ribbon or powder forms, which limited their application potential. The discovery of bulk metallic glass (BMG) forming compositions, which do not crystallize even when cooled relatively slowly, in the 1990s [164,165], made these materials candidates for advanced structural applications in view of their extraordinary properties. Consequently, considerable research was conducted to understand their mechanical behavior, which is of interest from both technological and scientific viewpoints [23,160–163].

The basic mechanisms by which plastic deformation takes place in MGs are distinctly different from those in crystalline metals and alloys in which the character and mobility of lattice line defects (namely dislocations) dictates plasticity. After extensive research over the past two decades, it is now widely accepted that the fundamental unit processes of plastic deformation in glasses occurs via the collective shuffling of clusters of atoms to accommodate the applied shear strain; these are termed as shear transformation zones (STZs). At the more macroscopic scale and when the applied stresses are sufficiently high, plastic deformation of MGs at low T occurs inhomogeneously through localization of flow into narrow bands with typical thickness of ~10 nm [160,166]. Since amorphous alloys lack long range atomic order, they offer a relatively weak resistance to the propagation of these 'shear bands'. This is because the atomic network consists of relatively stiff clusters embedded in a softer and weaker matrix (per the random modified network proposed by Greaves [167]). After propagating a characteristic distance, the shear bands become shear cracks and, in turn, lead to failure of the MG. Consequently, negligible plasticity beyond the elastic limit is often noted when MGs are tested in tension. Therefore, indentation techniques are widely employed to understand the mechanical behavior of MGs [168–170]. Since many reviews on this topic are already available in literature [7,171,172], only the aspects that are not covered hitherto, are briefly reviewed below. Before doing so, it is worth reiterating that the indentation plasticity in MGs is almost exclusively isochoric, just as in crystalline metals and alloys, and densification during indentation of MGs is negligible due to the random close packing in these 'atomic glasses'. Therefore, the following summary of indentation behavior of MGs will exclusively be in terms of shear flow in them.

3.1. Indentation-induced plasticity

3.1.1. Correlation between hardness and elastic properties

While the packing density is a key factor for understanding the elastic moduli and *H* of oxide glasses, the bond energy and character predominate in the case of MGs due to the high $C_{\rm g}$. A direct consequence of the near-ideal close random packing efficiency in MGs is that there is little room for

densification during indentation and the formation of an indentation imprint is almost solely due to shear flow. The macroscopic stress-strain response remains elastic and yield occurs at a considerably large strain, and the RT H of MGs is almost linearly correlated to the shear modulus (Fig. 12), with $H = 0.151 \mu$ [173]. A similar expression relating H with the E, H = E/20, was proposed, despite the relatively wide range of v of MGs [174]. The presence of light elements in the glass composition results in strong directional bonds, but to the detriment of the packing, and to the ease for isochoric shear. In contrast, heavy elements improve the atomic packing of the MG but lead to weaker bonds and thus to softer glasses. Non-transition metal host elements such as Ce, Ca, and Mg, impart more directional bonding through better localized 'f' (for Ce) and 'sp' (Ca,Mg) electrons giving rise to a relatively inefficient packing (and low v). As a consequence, rare-earth-based MGs as well as Caand Mg-based ones are relatively soft, although they behave in a more brittle manner than harder glasses such as the Zr-based ones for example. So soft does not mean ductile in the context of MGs, and the same holds for chalcogenide glasses, which are very soft (pure Se glass can be even deformed by hand at RT), but are extremely brittle (K_{lc} is less than 0.3 MPa· \sqrt{m}). MGs based on precious metal elements such as Pt, Au or Pd also exhibit relatively small H values because of the ease for shear deformation in such glasses thanks to the large atomic number and weak interatomic bonding directionality. The addition of Cr or Mo to Fe-based glasses containing metalloid elements such as carbon and boron provide metal-metalloid bonds, which are stronger than the Fe-(Cr,Mo) bonds, while the packing density is almost unchanged. In such a situation, H is increased. The highest Hreported so far for BMGs are those reported on Co-based glasses, and in particular for the $Co_{43}Fe_{20}Ta_{5.5}B_{31.5}$ (H=14.5 GPa) [175] and for the $(Co_{0.535}Fe_{0.1}Ta_{0.055}B_{0.31})_{98}Mo_2$ (H=16.6 GPa) [176] compositions and approaches the value for a $W_{46}Ru_{37}B_{17}$ ribbon (H=16.8 GPa) reported by Ohtsuki et al. [177]. Replacing Fe with Ni, or (Cr, Mo) by Ti reduces the bond strength and makes the glass softer. Ni-based amorphous alloys have about the same H as α -SiO₂, despite much smaller interatomic bonding energies. This example illustrates that efficient packing can easily compensate for the weaker interatomic bonding. Of course, the formation of clusters and of chemical heterogeneities in BMGs prevents a detailed case by case discussion at this stage, but the general trend is illustrated in Fig. 12. Most MGs, which include Cu-, Zr-, Ti-, and Fe-based ones, exhibit similar values, much larger than those reported for oxide glasses. The fact that the efficient atomic packing in MGs leaves little room for volume change in comparison with oxide glasses, and is conducive to isochoric shear flow, gives a great importance to the bond character. The volume density of energy (reflected in the elastic moduli) then almost scales with the dissociation energy, or with $T_{\rm g}$ (as the melting *T* is an ill-defined concept for a glass).



Fig. 12. Hardness, *H*, plotted as a function of the shear modulus, μ , illustrating the influence of the chemical system.

3.1.2. Discrete deformation during nanoindentation

Unlike the conventional hardness tests, the nanoindentation testing technique makes it possible to explore the mechanical response during the entire loading and unloading sequence. The P-hresponses measured on MGs using sharp indenters often exhibit small and discrete displacement bursts at constant loads (when the tests are performed under load control) that are often referred to as 'pop-ins', which are attributed to the shear band nucleation, propagation, and arrest in a 'stick-slip' manner [160,166]. Such a serrated flow, which is more clearly observed when a sharper tip like the cube-corner indenter is used, is known to be affected by various factors. Schuh and Nieh [178] asserted that the nature of pop-ins depends not only on the composition of the MG being tested but also on the \dot{P} ; the servations on the *P*-*h* curves are more pronounced at lower \dot{P} and gradually disappear with increasing rate. Since then, there have been extensive studies investigating the 'apparent' rate dependency of the inhomogeneous-to-homogeneous transition (e.g., see [179–182]). The following are the two major hypotheses offered for this transition. First (and mostly accepted) hypothesis is that the absence of pop-in events in 'fast' indentation was caused by kinetic limitations on the nucleation of shear bands. In the low-rate regime, a single shear band operates in isolation leading to a large pop-in. At high rates of loading, simultaneous nucleation of multiple shear bands causes each one to propagate only shorter distances, making it appear as if the flow is homogeneous overall. The second hypothesis is that the apparent absence of serrations at high indentation rate is just an artifact due to the lack of instrumental resolution including the limited data acquisition rate as well as the limited response time of the indentation equipment.

Temperature is another factor that affects the serrated flow behavior in a marked manner, which was revealed through high temperature nanoindentation experiments. For example, Schuh *et al.* [183] showed that increasing *T* leads to the gradual emergence of homogeneous flow, as thermal relaxations allow dissipation of strain localization into general viscous flow. Another critical factor is the indenter angle [184]; as shown in Fig. 13, sharper the indenter, more pronounced are the pop-in events. Additionally, factors like sub- T_g annealing [185], shot peening [186] and residual stress [187] may also affect the serrated flow of MGs.



Fig. 13. Representative examples of the nanoindentation load-displacement responses illustrating different extents of serrated flow obtained with (a) Berkovich and (b) cube-corner indenters at different loading rates. (Reprinted with permission from Yoo *et al.* [184]. Copyright (2007) The Japan Institute of Metals and Materials)

Recently, coupling of nanoindentation with electrical contact resistance (ECR) measurement such that both electrical and mechanical responses can be measured simultaneously became possible [188–190]. Yang *et al.* [191] performed nanoindentation in elastic regime on a Zr-based MG and revealed what triggers local inelastic atomic shuffling using ECR. It was inferred from the results obtained that deformation events take place cooperatively and exhibit a self-organized behavior. Singh *et al.* [192] investigated further the relationship between plastic deformation and current output in a Pd-based MG using ECR, and reported that the pop-in behavior in the P-h curve can be directly linked to the discrete surges in current measurement, implying the current excursions may be attributed to the formation of shear band offsets.

3.1.3. Plasticity evolution and pressure sensitivity

It is relatively straightforward to find the evidence that 'shear banding' is responsible for the serrations in the loading segments of the P-h responses. For example, shear bands can be observed on the surface around hardness impression, which is clearer when indentations are made with a sharper indenter [181]. However, imaging the entire shape of shear bands development, to develop 'structureproperty' correlations, is difficult since most of the shear bands usually form underneath the indenter and do not manifest often on to the free surface [184]. To overcome this, the 'bonded interface' technique, which was pioneered by Mulhearn and Van Der Zwaag et al. for metals and brittle materials, respectively [193,194], was utilized to study the subsurface deformation characteristics (especially, the shear band patterns) in a plane along the indentation axis [195-203]. In it, macroscopic indentation imprint is made on the bonded interface such that a well-defined plastic flow zone is generated on a cross-section underneath the indenter, which can later be probed for deformation morphology as well as for performing nanoindentation tests on the shear bands. Although the flow constraint is somewhat relaxed in the interface-bonded samples, and hence the stress and strain fields differ from those during indentation on samples without interface, it provides a rather unique opportunity to gain insights into the governing deformation mechanism during indentation, especially in the case of opaque materials [195].

One of the important features that have been successfully captured through interface-bonded technique and which was investigated by means of nanoindentation experiments on the shear banded region, is the strain softening behavior of MGs. Such softening is a consequence of the large local and transient dilatation of the surrounding matrix (required for the activation of STZs), which, in turn, enhances the structural disorder within the amorphous packing and, consequently, makes the structure more readily amenable for subsequent plastic flow [160]. This was demonstrated by Bhowmick *et al.* [198], who employed the bonded interface technique to generate a large and well-defined plastic zone decorated with profuse shear bands, as shown in Fig. 14(a), which was subsequently probed by nanoindentation. Analyses of the nanohardness data obtained from an extensively deformed regions [185], as illustrated in Fig. 14(b), showed that the deformed region is always softer than the undeformed region.



Fig. 14. Indentation-induced subsurface deformation of BMGs. (a) The subsurface deformation morphology of $Zr_{41}Cu_{14}Ti_{12}Ni_{10}Be_{23}$ BMG under a spherical indenter with the inset showing elastic zone immediately beneath the indenter (Reprinted with permission from Bhowmick *et al.* [198]. Copyright (2006) Elsevier): (b) The hardness distribution underneath a spherical indenter made on $Zr_{52.5}Cu_{17.9}Ni_{14.6}Al_{10}Ti_5$ BMG. (Reprinted with permission from Yoo *et al.* [202]. Copyright (2008) IOP)

Although plasticity in MGs is volume conserving at the macroscopic scale, the yield condition was found to be sensitive to the normal stress or pressure [183,186,204]. This sensitivity stems from the requirement of dilatation associated with STZ activation [205]. To account for this, instead of Tresca or Von Mises yield criteria that are routinely used for describing the yield loci in crystalline alloys, pressure-modified criteria such as Mohr–Coulomb [205,206], Drucker–Prager [207–209], modified Tresca [210], and a cooperative-shear process based shear plane criteria [211] have been proposed in the literature and have been validated to varying extent. Indentation can be also used to examine the pressure sensitivity of plastic flow in MGs. Vaidyanathan *et al.* [206], who employed both Berkovich nanoindentation experiments and their 3-dimensional FE simulations, reported that the experimental P–h curves are consistent with FE simulations when the Mohr–Coulomb criterion (instead of von Mises criterion) was used, and that the shear band traces around the hardness impression follow the contours of effective Mohr–Coulomb stress (as illustrated in Fig. 15).



Fig. 15. Plain view of contours indicating the Mises equivalent stress (top left) and the Mohr-Coulomb effective stress where the part with dark orange represents the areas of greatest stress, obtained from the finite element analyses using two different constitutive responses. An experimentally obtained image of the Berkovich indent made on a Zr-based BMG, scaled to the size of the simulation, is shown below; it agrees well with the simulated result obtained with the Mohr-Coulomb yield criterion, implying pressure sensitivity of plastic flow. (Reprinted with permission from Vaidyanathan *et al.* [206]. Copyright (2001) Elsevier)

The shear bands emanating from the edge of the spherical indentation impression resemble the slip lines around circular holes under pressure. The intersection angle between the shear bands can be utilized to infer the friction angle associated with the Mohr–Coulomb yield condition and hence examine the pressure sensitivity of plastic flow [186,207,212]. An included angle of 90° means the flow is pressure-insensitive; a deviation from it implies pressure-sensitivity. For example, Dubach *et al.* [186] examined the effect of structural state, and in turn, the free volume content in the MG on the pressure sensitivity of plastic flow in MGs through experiments on a $Zr_{41.2}Ti_{13.8}Cu_{12.5}Ni_{10}Be_{22.5}$ (composition in at.%) MG in the as-cast, shot-peened and structurally relaxed conditions. Their results show *H* to be highly sensitive to the structural state whereas the uniaxial compressive σ_y remains invariant. Significant variations in the shear band morphology around the indenter impressions was noted as well (see the left panel on Fig. 16). The observed variations in the intersection angles of the slip lines emanating from the periphery of the conical indents (right panel on Fig. 16) indicate that while structural relaxation, which reduces the free volume content in the glass, leads to a marginal reduction in the friction angle (compared with the as-cast state) and hence an enhanced pressure sensitivity. In comparison, prior-plastic deformation via shot peening makes the MG pressure-insensitive.



Fig. 16. [Left column] Scanning electron micrographs of the cube corner indents showing the appearance of shear bands in the form of surface steps for the (a) as-cast, (b) structurally relaxed, and (c) shot-peened Zr-based bulk metallic glass. [Right column] Optical micrographs and SEM image, respectively, showing the intersecting slip lines (with the intersection angle a) emanating from the edge of a conical indent, performed on the (d) as-cast and (e) structurally-relaxed material, and (f) on the cross-section of the shot-peened layer. (Reprinted with permission from Dubach *et al.* [186]. Copyright (2011) Materials Research Society)

A major consequence of the pressure sensitivity, in the context of indentation is an enhancement in *H* since the deforming volume of material underneath the indenter experiences a large hydrostatic compression. This is captured through the constraint factor, *Y*, which is given by the ratio of *H* to σ_y , measured in uniaxial compression. The value of *Y* depends on the geometry of the indenter as well as the mechanical properties of the material being indented. Based on the modified of expanding cavity model developed by Narasimhan [213], it was first shown by Patnaik *et al.* [207]

that the pressure sensitivity of plastic flow in MGs leads to high Y, which ranges between 3 and 4.5 in the fully plastic regime of indentation, whereas it is always below 3 for crystalline metals; see Fig. 17(a) [145].

Below T_g , the plastic flow characteristics, in terms of shear band nucleation rate and the amount of strain each of them carries, vary significantly with *T* even though the strength of a MG is only weakly *T* dependent. Through nanoindentation experiments on the Pd₄₀Ni₄₀P₂₀ (in at.%) BMG at 20, 100, and 150 °C coupled with analytical modeling, Schuh *et al.* [183] showed that the pressure sensitivity increases with increasing *T* as diffusive activation of the STZs prevents easy shear localization. Since shear band initiation is relatively more pressure-sensitive, Prasad *et al.* [199] and (then) Keryvin *et al.* [214] have shown that *Y* increases monotonically with *T*, confirming enhanced pressure sensitivity with *T*; see Fig. 17(b). Surprisingly, similar *T* dependence of *Y* was also reported for an amorphous polymer, poly(methyl methacrylate), suggesting an universal trend [215].



Fig. 17. Variation of the constraint factor, given by the ratio of the hardness to the yield strength in compression, in various BMGs (a) as a function of the indentation strain (normalized with the respective yield strains) at room temperature (Reprinted with permission from Schuh *et al.* [160]. Copyright (2007) Elsevier), and (b) as a function of homologous temperature T/T_g (Reprinted with permission from Keryvin *et al.* [214]. Copyright (2008) Taylor & Francis)

3.1.4. Time-dependent deformation

Although localized plastic flow mediated by shear bands dominates the deformation of MGs at relatively low *T* and sufficiently high stresses, it was demonstrated that at sufficiently long loading periods, homogeneous deformation can be observed even when the applied stresses are well below the nominal yield strength at RT [216,217]. While atomistic simulations have suggested that such loads can produce irreversible changes in the glass structure [216], creep-like behavior at RT was experimentally observed through uniaxial elastostatic compression tests in mm-sized MG samples [217,218]. Hence, time-dependent plastic deformation, or creep, at RT in a wide variety of MGs has

been investigated using nanoindentation [219–227]. Results show that creep occurs at RT irrespective of whether T_g is low or high, and the measured response is sensitive to both intrinsic material features such as the chemical composition [228] and the nature of initial structural defects [223,225], as well as external testing conditions such as the \dot{P} [223,226] and imposed strain [224,227]). For example, the influence of structural state on the RT indentation creep of BMG was studied by comparing the nanoindentation responses of the as-cast and annealed BMGs [222,223]. The results show that both anelastic and viscoplastic deformations were much more pronounced in the as-cast sample than in the annealed one [223]; this difference was attributed to the fact that the structurally relaxed glass contained relatively less free volume [229] and hence was more creep resistant.

3.1.5. Indentation plasticity and toughness correlation

Unlike oxide, chalcogenide or fluoride glasses, most MGs are 'ductile' when indented, which implies that they are susceptible to extensive shear band mediated plasticity. Although such shear band activity does not result in any tensile ductility, the fracture initiation toughness of MGs can be considerable. For some BMGs, exceptional values, as high as ~150 MPa√m (for Zr₆₁Ti₂Cu₂₅Al₁₂ BMG [230,231]), of mode I fracture initiation toughness, K_{Ic} , were reported. This is due to the occurrence of extensive plasticity ahead of crack/notch tips during tensile loading of cracked/notched specimens. When indented with sufficiently large loads, distinct shear band morphology forms around indents, but corner cracks are rarely seen (unless otherwise the MG in question is severely embrittled). Narayan et al. [231], who examined the shear band morphology in the plastic zones ahead of notch tips in a number of notched BMGs, found that K_{Ic} is proportional to the square root of the shear band number, N_n ($K_{1c} = 16.95\sqrt{N_n}$), as displayed in Fig. 18(a). By recourse to elasto-plastic fracture mechanics and recognizing that the critical energy release rate is directly proportional to the area of the notch-tip plastic zone (and since shear bands of discretized carriers of plasticity in MGs), Narayan et al. [231] rationalized the observed square root dependency between N_n and K_{Ic} . It is interesting to note here that Shao et al. [232], who examined a broad range of 13 BMGs from different alloy systems, found this exact relation to hold. Narayan et al. [231] also found an excellent correlation between K_{Ic} and N_i , which is the number of shear bands around spherical indentation impressions that are made to predetermined indentation strain of 10%; see Fig. 18(b). (The choice of 10% indentation strain was made on the basis of the 'ductile fracture criterion,' which postulates that fracture initiates upon the attainment of a critical strain over a characteristic length, identified by Tandaiya et al. [233] through their mixed-mode fracture studies.) The critical examination of the possible connection between N_i and N_n performed by Narayan *et al.* [231] suggests that it is possible to use indentation as a quick (and easier way) to estimate the fracture toughness of BMGs.



Fig. 18. Variations in the mode I fracture initiation toughness, K_{Ic} , with the number of shear bands (a) in the notch tip plastic zone, N_n , and (b) around the spherical indents (made with an indentation strain of 10%), N_i , illustrating the power law relationship between K_{Ic} and both N_n and N_i . (Reprinted with permission from Narayan *et al.* [231]. Copyright (2018) Elsevier)

Since BMGs lack tensile ductility, several routes are being investigated to remedy this problem; the most common one being the composites approach. Early efforts in this direction are either to introduce crystalline second phases, either by means of a controlled thermal treatment of the BMG to induce nanocrystalline phases [234] or via infiltration of the MG matrix in a preform of fibers (the most common being tungsten crystalline fibers) [235]. Vickers micro-indentation studies on nanocrystalline BMG composites (BMGCs) by Basu et al. [236] show that the embrittlement associated with the nanocrystallization of the BMG can easily be studied by examining the indents; the very observation of a shear band morphology around the indents made on the BMG in the as-cast state indicates that it is tough. Annealing the alloy first leads to the absence of such shear bands, with further annealing causing corner cracks, which indicates that the BMG became brittle. Recognizing the limitations of such composites, Hofmann et al. [237] have designed BMGCs with crystalline dendritic phases that are ductile, and hence enhance the BMG's fracture toughness significantly. Narayan et al. [238] employed the nanoindentation technique to evaluate the E and H of the constituent phases and Vickers microindentation to examine the shear band interactions between the amorphous matrix and the crystalline dendrites. Their results show that the modulus of the BMGC is in agreement with the 'rule of mixtures' prediction whereas H corresponds to that of the matrix. They rationalized the latter result as due to the constraint imposed by the matrix for the flow of (otherwise) softer second phases. Recently, Gentile et al. [239] have employed the bonded interface technique, which was coupled with the strain-field mapping to examine the yield condition's dependence on the

volume fraction and size of the dendritic phases, to show a cross-over in the mechanism to nearhomogeneous one at about 60 vol.% of the crystalline phase.

3.2. Incipient plasticity

3.2.1. Onset of plasticity and its statistics

It has been widely demonstrated that nanoindentation on well-prepared surface can capture the onset of plasticity in crystalline materials when spherical or blunt indenters are used [240–242]. On the P-hresponse, the transition from elastic to elastoplastic deformation is observed as a sudden displacement burst (or pop-in). The first pop-in for crystalline materials originates from the nucleation or movement of dislocations; for MGs it is generally thought to mark the completion of shear band nucleation and the onset of its propagation [172,243,244]. Fig. 19 shows an example of the pop-in behavior in the loading segment of the P-h curve obtained through nanoindentation with a spherical tip on the Zr_{52.5}Cu_{17.9}Ni_{14.6}Al₁₀Ti₅ BMG. The maximum shear stress underneath the indenter at the first pop-in, $\tau_{\rm max}$, usually represents the shear yield strength for the onset of plasticity, $\tau_{\rm v}$, in the crystalline material. In MGs, however, τ_{max} value may not be the exact τ_y due to pressure sensitivity of plastic flow. Nevertheless, τ_v can always be written in the form $\tau_v = C_v \tau_{max}$, where the constant C_v depends on the yield criterion [211,245], for spherical indentation. Producing large pop-in data sets and statistical analyses of them can provide insights into the physics of deformation. First example is that despite the absence of dislocations, the average value of the first pop-in stress in MGs is dependent on the indenter radius, R_{i} , which was reported for single crystal Ni as a new kind of 'spherical' ISE: the smaller R_{i} , the higher pop-in load/stress [246]. Bei *et al.* [245] reported that the upper bound of the $\tau_{\rm max}$ is almost constant for indenter radii smaller than a critical value (for example, ~90 μ m for a Zrbased MG [246], but the lower bound of this τ_{max} decreases with increasing R_i . They argued that this size effect is probably due to the increased probability of finding defects underneath larger indenters. Packard et al. [247], who made first pop-in statistical measurements on both crystalline metals as well as on MGs, suggest that at the nanoscale, the strength distributions in crystalline metals are governed by thermal fluctuations (and hence are $\dot{\varepsilon}$ and T sensitive) whereas in MGs, the measured variance is due to the intrinsic statistical nature of the atomic packing and is both T and $\dot{\varepsilon}$ insensitive. The nanoscale structural heterogeneity in the disordered atomic structure, which also reflects in significant variability (up to 30%) in the local E values was independently confirmed by atomic force acoustic microscopy measurements [248], dynamic modulus mapping [249] and dynamic force microscopy [250].



Fig. 19. Representative P-h response obtained from spherical nanoindentation (tip radius: 780 nm) on a $Zr_{52.5}Cu_{17.9}Ni_{14.6}Al_{10}Ti_5$ metallic glass sample showing pop-ins and Hertzian contact model fit for the elastic part of the response. (Reprinted with permission from Wang *et al.* [244]. Copyright (2011) Elsevier)

Subsequent to the work of Packard et al., a number of such studies [228,251,252] were performed on a wide variety of MGs. In most of these, the analysis performed by Packard et al. (but for crystalline metals) was used for obtaining activation volume associated with the incipient plasticity. However, neither Packard *et al.* nor those who followed them examined the nature of the statistical distributions of first pop-in strength in detail and routinely used the Gaussian distribution function to describe the dispersions. Perepezko et al. [253], who critically examined such datasets generated on four different MGs, observed that the statistical distribution of τ_v in MGs is bimodal in nature. On this basis, they assert the existence of a bimodal distribution of intrinsic defect sites and justify it as following: (a) The yield event underneath the indenter is triggered by the formation of an incipient shear band. (b) A shear band can be nucleated by activating one of two families of defects, one which operates at a lower load and another at higher load. Such distinct defect morphology results in an overlapping normal distributions of yield events. The above conjecture is supported by the observation of a shoulder at higher loads in the probability density distribution of their τ_v data. This observation also prompted the authors to arbitrarily fit two Gaussian distributions to the kernel density estimates (KDEs) of their data [254], which they validate with an adjusted- R^2 test. Then, using a hazard function to model this distribution, individual shear band nucleation rates were calculated for the families of low load and high load defect sites.

The data sets that Perepezko *et al.* have analyzed were obtained with only one combination of \dot{P} (= 20 µN/s) and R_i (= 5 µm) [253]. Recently, Nag *et al.* [255] performed detailed statistical analyses

on a total of 13 τ_v distributions, each containing at least 100 data points, that are obtained on two different Zr-based MGs with varying structural states and are probed with different combinations of R_i and \dot{P} . By employing the maximum likelihood estimates and the Akaike information criterion, Nag et al. [255] critically examined the suitability of the uni- and bi-modal (or mixture) versions of Gaussian, lognormal, and Weibull statistical models to examine which one of those best describes the experimental data. Results show that the 3-parameter bimodal Weibull distribution best captures the stochastic nature of the incipient plastic strengths in MGs. Interestingly, they noted that the bimodality is significant only when either large indenters or high \dot{P} , or both, were employed; see Fig. 20. Based on the analyses of the stress distributions and their gradients, which shows that the stress required to nucleate a shear band along a particular shear trajectory depends on both R_i and \dot{P} , Nag et al. [255] rationalize the bimodality observed under specific experimental conditions by postulating that the stress required for shear band nucleation must exceed a critical value over a characteristic distance over which the stress gradients are minimum. It is interesting to note that Gao and Perepezko [256] reported a trimodal pop-in strength distribution in a Gd-based MG that was probed with four different *P*. Nevertheless, a comprehensive and detailed understanding on the nature of incipient plasticity in MGs is still elusive.



Fig. 20. Strength distribution represented as KDE of τ_y in different MGs demonstrating the individual effects of (a) loading rate, \dot{P} , and (b) indenter tip radius, R_i . (Reprinted with permission from Nag *et al.* [255]. Copyright (2020) Elsevier)

3.2.2. STZ volume estimation

An important application of nanoindentation studies of MGs is the estimation of STZ volume through a statistical analysis of the first pop-in data [257–260]. According to the cooperative shear model

proposed by Johnson and Samwer [261], yielding is determined by the cooperative shearing of STZs and, hence, intrinsically depends on the activation volume V^* (which generally ranges from ~0.01 to 0.05 nm³ for various MGs [258–260]), whose value can be estimated from ln[ln(1-*f*)⁻¹] versus τ_{max} plots, where *f* is the cumulative probability of the thermally assisted and stress-biased pop-in events, as illustrated in Fig. 21 [262]. The measured STZ volume would be independent of the spherical tip R_i [258] but influenced by $\dot{\varepsilon}$ (see Fig. 21 [257]), *v*, and structural state of MG [258,260]. It should be noted that although τ_{max} was used to denote yielding here, it is possible to use other yield criteria to mark the elastic-plastic transition. However, this does not change the cumulative property of pop-in event, because all the nonzero stresses can be written in terms of the τ_{max} as discussed above [245].



Fig. 21. The distributions of cumulative probability, *f*, of the maximum shear stress, τ_{max} , at various loading rates. Inset shows the linear fits to the ln[ln(1-*f*)-1] vs. τ_{max} data. (Reprinted with permission from Choi *et al.* [257]. Copyright (2012) Elsevier)

The rate-jump method, which is a commonly used method to evaluate SRS and, in turn, estimate the activation volume, was also utilized via nanoindentation to estimate the STZ volume [263]. However, the results obtained based on such tests are valid if and only if the SRS obtained is a positive quantity. Since the strain softening nature of MGs imparts negative SRS to them [264–267], i.e., the flow stress decreases when the strain-rate is increased, rate-jump methods are unlikely to be useful for this purpose. Significant material pile-up around indenter that occurs during nanoindentation of BMGs, can lead to an overestimation of H [184,264,268]. Since pile-up volume would also depend on the rate of loading, a higher rate of deformation can lead to larger pile-up, which, in turn, could lead to a larger divergence between estimated and actual H values.

3.3. Environmental effects

Since MGs have potential for hydrogen storage or hydrogen separation [269,270], understanding the effects of hydrogen on their mechanical behavior is of paramount importance. As already discussed, deformation mechanisms in MGs are much different from those in crystalline alloys. It is thus anticipated that the physics behind the hydrogen effects in BMGs might differ from the one in crystalline metals. By performing nanoindentation on the subsurface region of a macroscopic spherical indentation made on a (Zr_{52.5}Ni_{13.6}Cu₁₈Al_{10.4})Nb₂ BMG, Yoo et al. [271] found that hydrogen charging enhances the nanohardness and decreases both the plastic zone size and the corresponding shear band density. Zhao et al. [259] applied nanoindentation with a spherical tip to investigate the influence of dissolved hydrogen on τ_y and STZ volume of Ni₄₅Nb₃₀Zr₂₅, Ni₃₃Nb₂₂Zr₄₀Co₅, Ni₂₇Nb₁₈Zr₅₀Co₅, and Ni₃₅Nb₃₀Zr₁₅Ti₁₀Fe₅Co₅ MG membranes through pop-in analyses. While no clear trend was seen across all MGs, τ_{max} increases and the STZ volume decreases in the high-Zr alloys (Ni₃₃Nb₂₂Zr₄₀Co₅ and Ni₂₇Nb₁₈Zr₅₀Co₅), whereas opposite effects were observed in the low-Zr alloys (Ni₄₅Nb₃₀Zr₂₅ and Ni₃₅Nb₃₀Zr₁₅Ti₁₀Fe₅Co₅). Similarly, Zhao et al. [272] also observed softening in low-Zr alloys and hardening in high-Zr ones during nanoindentation with a sharp tip as shown in Fig. 22 [272]. These variations were attributed to the mobile-hydrogen-assisted softening and immobile hydrogen trapped inside Zr-rich interstitial sites that results in a densely packed structure, respectively [273,274].



Fig. 22. Variation in hardness with Zr-content and the H-induced hardness change of MGs, ΔH (= $H_{\text{Charged}} - H_{\text{Uncharged}}$). Inset shows representative *P*–*h* responses. (Reprinted with permission from Zhao *et al.* [272]. Copyright (2014) Elsevier)

Irradiation can tailor the amorphous structure, since the bombardment of MGs with energetic particles such as electrons, neutrons, and ions induce structural heterogeneities [275,276]. Irradiation effects on the mechanical behavior of MGs was also examined via nanoindentation [276–278]. Raghavan *et al.* [278] observed an irradiation-induced hardening behavior and a transition from serrated flow in the as-cast region to homogeneous flow in the ion-irradiated regions, which were attributed to the densification of the material (that dilated during irradiation) underneath the indenter in the irradiated regions. Their work clearly demonstrated that irradiation makes MGs more plastic, whereas it hardens and embrittles crystalline metals, due to the increased free volume content in MGs upon ionic irradiation.

3.4. Modeling and simulation of indentation response of MGs

The state of stress underneath the indenter is complex, especially when a sharp tipped indenter is used, with steep gradients in stress, strain, and displacement fields. This invariably makes the deciphering of the experimental results difficult. To overcome this limitation, several studies focused on the inelastic deformation behavior of MGs during indentation by means of numerical simulations. These can be classified into two broad classes: continuum-level FEM and atomic-scale MD simulations. For FEM, the choice of appropriate constitutive laws that reflect the modeled material's intrinsic mechanical response is critical. For MGs, which are pressure sensitive and are prone to discrete plasticity through shear banding, constitutive descriptions that are routinely used for crystalline metals would result in inaccurate simulated results. The first elastic-plastic FE analysis on the indentation of MGs by Vaidyanathan *et al.* [206] revealed that the predicted *P*–*h* curve using Mohr–Coulomb criterion (with friction coefficient α of 0.13 for the examined Zr-based MGs) is in a good agreement with the experimental results whereas the classical von Mises criterion over-predicts *h* at any given *P*.

While the Mohr–Column yield criterion (that is the most widely used for describing plasticity in granular materials in soil mechanics as well as amorphous polymers) was found to be valid for predicting the yield locus of MGs [205], there was no agreement for the elastic-plastic constitutive model for the criterion. In this light, Anand and Gu [279] generalized the existing two-dimensional 'double shearing' model to develop a three dimensional rate-independent elastic-plastic model, and Anand and Su [280] further generalized it to formulate a thermodynamically consistent, finite-deformation macroscopic constitutive model for the rate-dependent elastic-viscoplastic deformation of pressure-sensitive, plastically-dilatant materials. They implemented this constitutive model in a commercial FE software (ABAQUS) to simulate the plane-strain wedge indentation (whose wedge half-angle was chosen to be 68° to approximate a Vickers indenter) of a Zr-based MG. The simulated shear band patterns around indent (i.e., slip steps on the free surface) and the serrations in *P*–*h* curves

were in reasonable agreement with those of the complementary experimental results; see Fig. 23. In a follow-up paper [281], a number of (approximately plane-strain) wedge indentation experiments were performed on a Zr-based MG with a cylindrical indenter tip. By direct comparison of the predicted shear-band pattern and equivalent plastic strain contours from FE simulations with the corresponding experimental data, it was suggested that their constitutive model and simulation procedures are capable of not only quantitatively predicting P-h curves, but also capable of approximately estimating the inelastic strain distribution and its evolution during indentation.



Fig. 23. Simulated P-h response using finite element modeling. Distinct 'load-drops' marked as events *a*, *b*, and *c* on the P-h curve occur when the shear bands (indicated by arrows in the inset figures) initiate. (Reprinted with permission from Anand and Su [280]. Copyright (2005) Elsevier)

In addition to continuum FE simulations, atomistic MD simulations were conducted for analyzing the nanoindentation behavior of MGs. During the MD simulation (where the equation of motion is solved for all the atoms to retrace their trajectories during indentation), P and h are calculated by the sum of the forces acting on the atoms of the indenter and the relative displacement of the indenter tip to the initial surface of the indented material [282].

Atomistic simulation for nanoindentation of MGs is useful for understanding of their atomicscale deformation mechanism but is somewhat challenging. The unique nature of MGs (e.g., the inhomogeneities are frozen into the entire solid and the macroscopic plastic deformation is intensely localized into shear bands) makes it difficult to identify the nanoindentation damage by computational techniques used for a crystalline solid. Early works on atomistic simulation of MG were performed by Lund and Schuh [205]. While they are not on nanoindentation, their molecular static simulations of a Cu-Zr MG showed the asymmetry in the plane-stress yield surface (i.e., uniformly stronger in net compressive stress state than in net tension) and it can be well-described using the Mohr–Coulomb yield criterion, which can be linked to the fundamental criterion for STZ activation.

By performing a series of MD simulations on nanoindentations of three-dimensional binary (i.e., non-specific) MG, Shi and Falk [283] proved the usefulness of the atomistic simulations in exploring the atom-scale subsurface deformation morphology and stress field pattern that can characterize the incipient plasticity of a MG during nanoindentation. From their simulations controlling various parameters (such as quenching rate and $\dot{\varepsilon}$; see Fig. 24), they proposed that the short range ordered (SRO) domains provide a significantly greater signal-to-noise response than the free volume. While the Lennard–Jones (LJ) model system employed by Shi and Falk gives some hints about the deformation in a MG, its description of the atomic interactions may be too simple to realistically describe a 'specific' MG. Thus, MD simulations with many-body potentials instead of LJ potential were performed. For example, Păduraru et al. [284] used the effective medium theory potentials to describe CuZr and Mg₈₅Cu₁₅ MGs, and reported a clear signature of shear band formation under the indenter, though shear bands are less clearly developed in comparison with the LJ-based simulations. To overcome the scale hurdle of each simulation and to capture the actual features of the deformation during indentation of MGs, combined FE and MD simulations, as for crystalline materials, appears promising (e.g., see for example, Ref. [285] for the simulations performed on crystalline Cu).



Fig. 24. Visualization of the magnitude of the net local deviatoric shear strain underneath the indenter at the maximum depth under three indentation rates, obtained using MD simulations. The simulations were performed for the spherical indentations (with tip having the radius of 40 nm) until the maximum displacement reaches 5 nm. (Reprinted with permission from Shi and Falk [283]. Copyright (2007) Elsevier)

4. CLOSING REMARKS

On one hand, *glass* is a generic word which covers a great diversity of materials with stunning mechanical and physical properties. These materials have in common the lack of long range atomic ordering and their complex structures still raise numerous fundamental questions. On the other hand, *indentation* is a unique mechanical testing method, where extraordinary stress levels (order of magnitude of hardness) with steep gradients and spatial variations develop, leading to complicated physical phenomena, such as densification, localized shear flow through shear transformation zone activation, shear band formation, and cracking. Hence, deciphering the experimental data generated through such tests requires cutting edge developments in physics, mechanics and modelling tools even for crystalline materials whose deformation mechanisms are well understood. Therefore, indentation of glasses, while relatively easy to perform and perhaps the most convenient method to probe properties, is considerably more challenging in terms of understanding the results obtained. As this review highlights, considerable progress was made over the years and insights continue to be gained by means of innovative indentation techniques in conjunction with image analysis and

modelling. While indentation remains a useful and suitable tool for the study of glasses⁷ and is increasingly being used, several unsolved issues remain. Especially, direct experiments that would reveal fundamental unit deformation processes and mechanisms of fracture at the nanoscopic length scales would not only advance this field of research further, but also will enable design of stronger and tougher glasses. Further advances in instrumentation complemented with sophisticated theoretical models and simulations are required for such an objective to be accomplished. Towards former, one can expect coupled experiments performed in situ, involving for example indentation and electric conductivity through the contact area, or indentation and optical spectroscopy (Raman, IR), etc. can shed new insights into the extraordinary physics that takes place at the indentation site. That way, indentation can become a more and more as a unique and powerful tool to fill the connection between the nanoscale glass structural scale to its macroscale response. Besides, there are great expectations for a better understanding of environmental effects using indentation investigations, as indentation testing is particularly suitable for environment-controlled set-up.

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⁷ Indentation techniques are also employed to study glassy polymers. However, they were not covered in this review, due in part to the lack of necessary expertise amongst the authors of this paper on that specific area. While the plastic deformation phenomenology in glassy polymers is significantly different from those of the inorganic glasses examined in this review, indentation studies on glassy polymers (which are not many, compared to those on the inorganic glasses) indicate some common features, such as pressure sensitivity of plastic flow [286], indentation size effect [287], strain rate sensitivity [288], etc. Interested reader is referred the papers listed here [289–298].

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