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# Riemann theta functions, Fredholm and wronskian representations of the solutions to the KdV equation 

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#### Abstract

We degenerate the finite gap solutions of the KdV equation from the general formulation given in terms of abelian functions when the gaps tends to points, to get solutions to the KdV equation given in terms of Fredholm determinants and wronskians. For this we establish a link between Riemann theta functions, Fredholm determinants and wronskians. This gives the bridge between the algebro-geometric approach and the Darboux dressing method.


## 1 Introduction

We consider the KdV equation in the following normalization

$$
\begin{equation*}
u_{t}=6 u u_{x}-u_{x x x} \tag{1}
\end{equation*}
$$

where the subscripts $x$ and $t$ as usual denote partial derivatives.
This equation (1) was introduced for the first time in 1895 by Korteweg and de Vries [56]. This equation appears in a wide range of physical problems and describes the propagation of waves with weak dispersion in various nonlinear media.
A method of resolution was given in 1967 by Gardner et al. [52]. It was proven that this equation is a complete integrable system by Zakharov and Faddeev in 1971 [76].
Solutions were constructed by Hirota in 1971 by using the bilinear method [53]. Its and Matveev present solutions in terms of Riemann theta functions [54] in 1975. Lax gives in the same year the expressions of periodic and almost periodic solutions [59]. A lot of works have been realized in the following years. We can mention for example Airault et al. in 1977 [3], Adler and Moser in 1978 [2], Ablowitz and Cornille in 1979 [1], Freeman and Nimmo in 1984 [5], Matveev in 1992 [64], Ma in 2004 [60], Kovalyov in 2005 [58] and more recently Ma in 2015 [61].

In the following, we are interested in the algebro-geometric approach given by Its and Matveev in 1975. We degenerate the solutions to the KdV equation given in terms of Riemann theta functions to get solutions in terms of Fredholm determinants. Then we give a representation in terms of wronskians. This gives the correspondence between the algebro-geometric approach and the Darboux dressing method.

## 2 The KdV equation and its solutions in terms of theta functions

We consider the Riemann surface $\Gamma$ of the algebraic curve defined by

$$
\omega^{2}=\prod_{j=1}^{2 g+1}\left(z-E_{j}\right)
$$

with $E_{j} \neq E_{k}, j \neq k$. Let $D$ be some divisor $D=\sum_{j=1}^{g} P_{j}, P_{j} \in \Gamma$. The so-called finite gap solution of the KdV equation

$$
\begin{equation*}
u_{t}=6 u u_{x}-u_{x x x} \tag{2}
\end{equation*}
$$

can be expressed in the form [54]

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2}[\ln \theta(x g+t v+l)]+C . \tag{3}
\end{equation*}
$$

We recall briefly, the notations. In (3), $\theta$ is the Riemann function defined by

$$
\begin{equation*}
\theta(z)=\sum_{k \in \mathbf{Z}^{g}} \exp \{\pi i(B k \mid k)+2 \pi i(k \mid z)\} \tag{4}
\end{equation*}
$$

constructed from the matrix of the B-periods of the surface $\Gamma$, and the vectors $g, v, l$ are defined by

$$
\begin{gather*}
g_{j}=2 i c_{j 1}  \tag{5}\\
v_{j}=8 i\left(\frac{c_{j 1}}{2} \sum_{k=1}^{2 g+1} E_{k}+c_{j 2}\right)  \tag{6}\\
l_{j}=-\sum_{k=1}^{g} \int_{\infty}^{P_{k}} d U_{j}+\frac{j}{2}-\frac{1}{2} \sum_{k=1}^{g} B_{k j}  \tag{7}\\
C=\sum_{k=1}^{2 g+1} E_{k}-2 \sum_{k=1}^{g} \int_{a_{k}} z d U_{k} \tag{8}
\end{gather*}
$$

the coefficients $c_{j k}$ being relating with abelian differential $d U_{j}$ by

$$
\begin{equation*}
d U_{j}=\frac{\sum_{k=1}^{g} c_{j k} z^{g-k}}{\sqrt{\prod_{k=1}^{2 g+1}\left(z-E_{k}\right)}} d z \tag{9}
\end{equation*}
$$

and coefficients $c_{j k}$ can be obtained by solving the system of linear equations

$$
\int_{a_{k}} d U_{j}=\delta_{j k}, \quad 1 \leq j \leq g, \quad 1 \leq k \leq g
$$

## 3 Degeneracy of solutions

We suppose that $E_{j}$ are real, $E_{m}<E_{j}$ if $m<j$ and try to evaluate the limits of all objects in formula (3) when $E_{2 m}, E_{2 m+1}$ tends to $-\alpha_{m},-\alpha_{m}=-\kappa_{m}^{2}$, $\kappa_{m}>0$, for $1 \leq m \leq g$, and $E_{1}$ tends to 0 (these ideas were first presented by A. Its and V.B. Matveev, exposed for example in [4]).

### 3.1 Degeneracy of the components of the solution

3.1.1 Limit of $P(z)=\prod_{j=1}^{2 g+1}\left(z-E_{j}\right)$

The limit of $P(z)=\prod_{j=1}^{2 g+1}\left(z-E_{j}\right)$ is evidently equal to $\tilde{P}(z)=z \prod_{j=1}^{g}\left(z+\alpha_{j}\right)^{2}$
3.1.2 Limit of $d U_{m}=\frac{\sum_{k=1}^{g} c_{m k} z^{g-k}}{\sqrt{\prod_{k=1}^{2 g+1}\left(z-E_{k}\right)}} d z$

The limit of $d U_{m}$ is equal to $d \tilde{U}_{m}=\frac{\varphi_{m}(z)}{\sqrt{z} \prod_{j=1}^{g}\left(z+\alpha_{j}\right)} d z$, where $\varphi_{m}(z)=$ $\sum_{k=1}^{g} \tilde{c}_{m k} z^{g-k}$. The normalization condition takes the form in the limit

$$
\begin{equation*}
\int_{a_{k}} d U_{j} \rightarrow \frac{2 \pi i \varphi_{j}\left(-\alpha_{k}\right)}{-i \kappa_{k} \prod_{m \neq k}\left(-\alpha_{k}+\alpha_{m}\right)}=\delta_{k j} \tag{10}
\end{equation*}
$$

which proves that the numbers $-\alpha_{m}, m \neq k$ are the zeros of the polynomials $\varphi_{k}(z)$, and so $\varphi_{k}(z)$ can be written as $\varphi_{k}(z)=\tilde{c}_{k 1} \prod_{m \neq k}\left(z+\alpha_{m}\right)$. By (10), we get in the limit

$$
\tilde{c}_{k 1}=-\frac{\kappa_{k}}{2 \pi i} .
$$

So

$$
d \tilde{U}_{k}=-\frac{\kappa_{k}}{2 \pi i \sqrt{z}\left(z+\alpha_{k}\right)} d z
$$

### 3.1.3 Limit of $v_{k}$ and $g_{k}$

By identification of the powers of $z^{g-2}$ in (11)

$$
\begin{equation*}
\tilde{\varphi_{k}}(z)=\tilde{c_{k} 1} \prod_{l \neq k}\left(z+\alpha_{l}\right)=\sum_{j=1}^{g} \tilde{c_{k j}} z^{g-j} \tag{11}
\end{equation*}
$$

we get in the limit

$$
\tilde{c}_{k 1} \sum_{l=1}^{g} \alpha_{l}=\tilde{c}_{k 2}
$$

So we have the limit values of $v_{k}$ and $g_{k}$ :

$$
\tilde{v}_{k}=\frac{4 i \kappa_{k}^{3}}{\pi}
$$

and

$$
\tilde{g}_{k}=\frac{-i \kappa_{k}}{\pi} .
$$

### 3.1.4 Limit of $U_{k}(P)$ and $B_{m k}$

For $\lambda_{0}=-\alpha_{m}=-\kappa_{m}^{2}, I=\int_{\lambda_{0}}^{0} d U_{k} \rightarrow \frac{1}{2} \tilde{B}_{m k}$. The integral $I$ can be easily evaluate along the real axis on the upper sheet of surface $\Gamma$ and we get

$$
I \rightarrow \frac{i}{2 \pi} \ln \left|\frac{\kappa_{m}+\kappa_{k}}{\kappa_{m}-\kappa_{k}}\right|
$$

So we have the limit values of matrix $B$ :

$$
\tilde{B}_{m k}=\frac{i}{\pi} \ln \left|\frac{\kappa_{m}+\kappa_{k}}{\kappa_{m}-\kappa_{k}}\right| .
$$

Therefore $i B_{k k}$ tends to $-\infty$. As previously, we have

$$
\begin{equation*}
\int_{\infty}^{P} d U_{j} \rightarrow-\frac{i}{2 \pi} \ln \left|\frac{\kappa_{j}-\sqrt{z_{P}}}{\kappa_{j}+\sqrt{z_{P}}}\right| \tag{12}
\end{equation*}
$$

### 3.1.5 Limit of argument of exponential in $\theta(p)$

Let us denote $A_{0}$ the argument of exponential in $\theta(p)=\sum_{k \in \mathbf{Z}^{g}} \exp \{\pi i(B k \mid k)+$ $2 \pi i(k \mid p)\}$.
$A_{0}$ can be rewritten in the form

$$
\begin{equation*}
A_{0}=\pi i \sum_{j=1}^{g} B_{j j} k_{j}\left(k_{j}-1\right)+2 \pi i \sum_{j>m} B_{m j} k_{m} k_{j}+\sum_{j=1}^{g} \pi i\left(2 p_{j}+B_{j j}\right) k_{j} \tag{13}
\end{equation*}
$$

Using the inequality $k_{j}\left(k_{j}-1\right) \geq 0$ for all $k \in \mathbf{Z}^{g}$ and the fact that $i B_{k k}$ tends to $-\infty$, we can reduce the limit $\tilde{\theta}$ of $\theta(p)$ to a finite sum taken over vectors $k \in \mathbf{Z}^{g}$ such that each $k_{j}$ must be equal to 0 or 1 .
So, if we denote $A$ the argument of $\theta(x g+t v+l)$, it can be written in the form

$$
\begin{gathered}
A=\pi i \sum_{j=1}^{g} B_{j j} k_{j}\left(k_{j}-1\right)+2 \pi i \sum_{j>m} B_{m j} k_{m} k_{j}+\sum_{j=1}^{g} k_{j}\left[2 \pi i\left(g_{j} x+v_{j} t\right)\right. \\
\left.-\pi i\left(-j+2 \sum_{k=1}^{g} \int_{\infty}^{P_{k}} d U_{j}+\sum_{m \neq j} B_{m j}\right)\right] .
\end{gathered}
$$

In other words

$$
A=\pi i \sum_{j=1}^{g} B_{j j} k_{j}\left(k_{j}-1\right)+2 \pi i \sum_{j>m} B_{m j} k_{m} k_{j}+\sum_{j=1}^{g} k_{j} Q_{j},
$$

with

$$
Q_{j}=2 \pi i\left(g_{j} x+v_{j} t\right)+\beta_{j}
$$

and

$$
\beta_{j}=-\pi i\left(-j+2 \sum_{k=1}^{g} \int_{\infty}^{P_{k}} d U_{j}+\sum_{m \neq j} B_{m j}\right)
$$

The quantity $\beta_{j}$ has a finite limit value $\tilde{\beta}_{j}$ independent from $x$ and $t$.

### 3.1.6 Limit of $\theta(x g+v t+l)$

By means of the inequality $k_{j}\left(k_{j}-1\right) \geq 0$ for all $k \in \mathbf{Z}^{\mathbf{g}}$ and the previous relation $i B_{k k}$ tends to $-\infty$, it turns out that the limit $\tilde{\theta}$ of $\theta(x g+t v+l)$ reduce to a finite sum taken over vectors $k \in \mathbf{Z}^{\mathbf{g}}$ with the property that each $k_{j}$ must be equal to 0 or 1 .

$$
\tilde{\theta}=\sum_{k \in \mathbf{Z}^{g}, k_{j}=0 \text { or } 1} \exp \left\{\sum_{m>j} 2 \ln \left|\frac{\kappa_{m}-\kappa_{j}}{\kappa_{m}+\kappa_{j}}\right| k_{m} k_{j}+\left(\sum_{j=1}^{g} 2 \kappa_{j} x-8 \kappa_{j}^{3} t+2 \kappa_{j} x_{j}+\pi j i+\sum_{m \neq j} \ln \left|\frac{\kappa_{m}+\kappa_{j}}{\kappa_{m}-\kappa_{j}}\right|\right) k_{j}\right\}
$$

with

$$
x_{j}=\frac{1}{2 \kappa_{j}} \sum_{k=1}^{g} \ln \left|\frac{\sqrt{z_{k}}-i \kappa_{j}}{\sqrt{z_{k}}+i \kappa_{j}}\right| .
$$

It can be rewritten as

$$
\begin{equation*}
\tilde{\theta}=\sum_{J \subset\{1, \ldots, g\}} \prod_{j \in J}(-1)^{j} \prod_{j \in J}\left|\frac{\kappa_{j}+\kappa_{k}}{\kappa_{j}-\kappa_{k}}\right| \exp \sum_{j \in J} 2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right) . \tag{14}
\end{equation*}
$$

### 3.1.7 Limit of the coefficient $C$

The coefficient $C$ is defined in (8) by

$$
C=\sum_{k=1}^{2 g+1} E_{k}-2 \sum_{k=1}^{g} \int_{a_{k}} z d U_{k}=C_{1}+C_{2},
$$

can be evaluated as follows.

$$
\begin{gathered}
C_{2}=-2 \sum_{k=1}^{g} \int_{a_{k}} z d U_{k}=-2 \sum_{k=1}^{g} \int_{a_{k}} \frac{-\kappa_{k} z d z}{2 \pi \sqrt{z}\left(z+\alpha_{k}\right)}=\sum_{k=1}^{g} \frac{\kappa_{k}}{\pi} \int_{a_{k}} \frac{\sqrt{z} d z}{\left(z+\alpha_{k}\right)} \\
=\sum_{k=1}^{g} \frac{\kappa_{k}}{\pi} 2 i \pi\left(-i \kappa_{k}\right)=\sum_{k=1}^{g} 2 \kappa_{k}^{2}=2 \sum_{k=1}^{g} \alpha_{k} .
\end{gathered}
$$

Thus when the gaps tends to points,, the coefficient $C$ tends to $\tilde{C}$ equal to

$$
\tilde{C}=2 \sum_{k=1}^{g}-\alpha_{k}+2 \sum_{k=1}^{g} \alpha_{k}=0
$$

### 3.2 Degenerate solution to the KdV equation

Therefore, we have the following representation of the degenerate solution to the KdV equation

Theorem 3.1 The fonction $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2} \ln \left(\sum_{J \subset\{1, \ldots, g\}} \prod_{j \in J}(-1)^{j} \prod_{j \in J}\left|\frac{\kappa_{j}+\kappa_{k}}{\kappa_{j}-\kappa_{k}}\right| \exp \left(\sum_{j \in J} 2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right)\right) \tag{15}
\end{equation*}
$$

with $\kappa_{j}$, and $x_{j}$ arbitrary real parameters, is a solution to the KdV equation (1).

## 4 From theta function to Fredholm determinant

### 4.1 The link between the degenerate solution and the Fredholm determinant

In a recent paper, Kirillov and Van Diejen [72] have given formulas in terms of determinants for zonal spherical functions on hyperboloids. In particular, they compute $\operatorname{det}(I+A)$, where $I$ is the unit matrix and $A=\left(a_{j k}\right)_{1 \leq j, k \leq m}$ the matrix defined as :

$$
\begin{equation*}
a_{j k}=\frac{2 \epsilon_{j} \kappa_{j}}{\kappa_{j}+\kappa_{k}} \exp \left(-2 \kappa_{j} x\right) \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{j}}{\kappa_{l}-\kappa_{j}}\right| \tag{16}
\end{equation*}
$$

where $\epsilon_{j} \in\{-1 ;+1\}$ and $\kappa_{j}>0$ for $1 \leq j \leq N$.
Then $\operatorname{det}(I+A)$ has the following form

$$
\begin{equation*}
\operatorname{det}(I+A)=\sum_{J \subset\{1, \ldots, N\}} \exp \left(-2 x \sum_{j \in J} \kappa_{j}\right) \prod_{j \in J} \epsilon_{j} \prod_{j \in J}\left|\frac{\kappa_{j}+\kappa_{k}}{\kappa_{j}-\kappa_{k}}\right| \tag{17}
\end{equation*}
$$

Using the same strategy, we can compute $\operatorname{det}(I+A)$ where $A=\left(a_{j k}\right)_{1 \leq j, k \leq m}$ is the matrix defined as :

$$
a_{j k}=\frac{(-1)^{j} 2 \kappa_{j}}{\kappa_{j}+\kappa_{k}} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{j}}{\kappa_{l}-\kappa_{j}}\right|,
$$

$x_{j}$ being an arbitrary parameter.
Then $\operatorname{det}(I+A)$ has the following form

$$
\begin{equation*}
\operatorname{det}(I+A)=\sum_{J \subset\{1, \ldots, N\}} \exp \left(\sum_{j \in J} 2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right) \prod_{j \in J}(-1)^{j} \prod_{j \in J k \notin J}\left|\frac{\kappa_{j}+\kappa_{k}}{\kappa_{j}-\kappa_{k}}\right|, \tag{18}
\end{equation*}
$$

By the previous section,
$\tilde{\theta}=\sum_{J \subset\{1, \ldots, g\}} \prod_{j \in J}(-1)^{j} \prod_{j \in J}\left|\frac{\kappa_{j}+\kappa_{k}}{\kappa_{j}-\kappa_{k}}\right| \exp \left(\sum_{j \in J}\left(2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right)\right.$.
If we compare the expression (18) to (19), we have clearly the equality with $g=N$

$$
\begin{equation*}
\tilde{\theta}=\operatorname{det}(I+A) \tag{20}
\end{equation*}
$$

### 4.2 Solution to the KdV equation in terms of Fredholm determinant

So we have the following representation of the solutions to the KdV equation
Theorem 4.1 The fonction $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2} \ln (\operatorname{det}(I+A)) \tag{21}
\end{equation*}
$$

with $A$ the matrix defined by $A=\left(a_{j k}\right)_{1 \leq j, k \leq N}$

$$
\begin{equation*}
a_{j k}=\frac{(-1)^{j} 2 \kappa_{j}}{\kappa_{j}+\kappa_{k}} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{j}}{\kappa_{l}-\kappa_{j}}\right| \tag{22}
\end{equation*}
$$

and $\kappa_{j}, x_{j}$ arbitrary real parameters, is a solution to the KdV equation (1).
If we consider the matrix $B$ defined by

$$
b_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq k}\left|\frac{\kappa_{l}+\kappa_{j}}{\kappa_{l}-\kappa_{k}}\right|
$$

it is easy to verify that $\operatorname{det}(I+A)=\operatorname{det}(I+B)$, and so we can give another representation of the solutions to the KdV equation. We get the following statement :

Theorem 4.2 The fonction $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2} \ln (\operatorname{det}(I+B)) \tag{23}
\end{equation*}
$$

with $B$ the matrix defined by $B=\left(b_{j k}\right)_{1 \leq j, k \leq m}$

$$
\begin{equation*}
b_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq k}\left|\frac{\kappa_{l}+\kappa_{j}}{\kappa_{l}-\kappa_{k}}\right| \tag{24}
\end{equation*}
$$

and $\kappa_{j}, x_{j}$ arbitrary real parameters, is a solution to the KdV equation (1).

We can also consider the matrix $C$ defined by

$$
c_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \frac{\prod_{l \neq k}\left|\kappa_{l}+\kappa_{j}\right|}{\prod_{l \neq j}\left|\kappa_{l}-\kappa_{j}\right|} .
$$

It is easy to check that $\operatorname{det}(I+A)=\operatorname{det}(I+C)$, and so we can give a third representation of the solutions to the KdV equation :

Theorem 4.3 The fonction $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2} \ln (\operatorname{det}(I+C)) \tag{25}
\end{equation*}
$$

with $C$ the matrix defined by $C=\left(c_{j k}\right)_{1 \leq j, k \leq m}$

$$
\begin{equation*}
c_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \frac{\prod_{l \neq k}\left|\kappa_{l}+\kappa_{j}\right|}{\prod_{l \neq j}\left|\kappa_{l}-\kappa_{j}\right|}, \tag{26}
\end{equation*}
$$

and $\kappa_{j}, x_{j}$ arbitrary real parameters, is a solution to the $K d V$ equation (1).
Another possibility is to choose the matrix $D$ defined by

$$
d_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{k}}{\kappa_{l}-\kappa_{j}}\right|
$$

It is also easy to check that $\operatorname{det}(I+A)=\operatorname{det}(I+D)$, and so we can give another representation of the solutions to the KdV equation :

Theorem 4.4 The fonction $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2} \ln (\operatorname{det}(I+D)) \tag{27}
\end{equation*}
$$

with $C$ the matrix defined by $D=\left(d_{j k}\right)_{1 \leq j, k \leq m}$

$$
\begin{equation*}
d_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{k}}{\kappa_{l}-\kappa_{j}}\right|, \tag{28}
\end{equation*}
$$

and $\kappa_{j}, x_{j}$ arbitrary real parameters, is a solution to the KdV equation (1).
It remains to find the link between this Fredholm determinant and a certain wronskian.

## 5 From Fredholm determinants to wronskians

### 5.1 Link between Fredholm determinants and wronskians

In this section, we consider the following functions

$$
\begin{equation*}
\phi_{j}(x)=\sinh \left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right) \tag{29}
\end{equation*}
$$

where $\kappa_{j}$ are real numbers such that $\kappa_{1} \leq \ldots \leq \kappa_{N}$, and $x_{j}$ an arbitrary constant independent of $x$.
We use the following notations :
$\theta_{j}=\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)$.
$W=W\left(\phi_{j}, \ldots, \phi_{N}\right)$ is the classical Wronskian $W=\operatorname{det}\left[\left(\partial_{x}^{j-1} \phi_{i}\right)_{i, j \in[1, \ldots, N]}\right]$.
We consider the matrix $A=\left(a_{j k}\right)_{j, k \in[1, \ldots, N]}$ defined by

$$
\begin{equation*}
a_{j k}=(-1)^{j} \exp \left[2\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right] \prod_{l \neq j}\left|\frac{\kappa_{l}+\kappa_{k}}{\kappa_{l}-\kappa_{j}}\right| \tag{30}
\end{equation*}
$$

Then we have the following statement
Theorem 5.1

$$
\begin{equation*}
\operatorname{det}(I+A)=\frac{2^{N}(-1)^{\frac{N(N+1)}{2}} \exp \left(\sum_{j=1}^{N} \theta_{j}\right)}{\prod_{j=2}^{N} \prod_{i=1}^{j-1}\left(\kappa_{j}-\kappa_{i}\right)} W\left(\phi_{1}, \ldots, \phi_{N}\right) \tag{31}
\end{equation*}
$$

### 5.2 Solutions to the $K d V$ equation in terms of wronskians

From the previous subsection, we can give the following wronskian representation of the solutions to the KdV equation.

Theorem 5.2 The function $u$ defined by

$$
\begin{equation*}
u(x, t)=-2 \partial_{x}^{2}\left(\ln \left[W\left(\phi_{1}, \ldots, \phi_{N}\right)\right]\right) \tag{32}
\end{equation*}
$$

where $=W\left(\phi_{1}, \ldots, \phi_{N}\right)=\operatorname{det}\left[\left(\partial_{x}^{j-1} \phi_{i}\right)_{i, j \in[1, \ldots, N]}\right]$ is the wronskian of the functions $\phi$ defined by $\phi_{j}(x, t)=\sinh \left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right), \kappa_{j}, x_{j}$ being real numbers, is a solution to the $K d V$ equation (1).

It is relevant to note that we recover the result given by the Darboux dressing [64].
This realize the connection between the algebro-geometric approach and the Darboux dressing method.

Remark 5.1 The choices of functions $\phi_{j}$ are not unique. For example, we can choose:
$\phi_{j}(x)=\cosh \left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)$, or $\phi_{j}(x)=\exp \left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)$, or $\phi_{j}(x)=\exp \left(-\left(\kappa_{j} x-4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right)$ or any combinations of these different last functions.
We can also choose the following functions :
$\phi_{j}(x)=\sin \left(\kappa_{j} x+4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)$, or $\phi_{j}(x)=\cos \left(\kappa_{j} x+4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)$, or $\phi_{j}(x)=$ $\exp \left(i\left(\kappa_{j} x+4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right)$, or $\phi_{j}(x)=\exp \left(-i\left(\kappa_{j} x+4 \kappa_{j}^{3} t+\kappa_{j} x_{j}\right)\right)$ or any combinations of these different last functions.

## 6 Conclusion

In this paper, we succeed to construct different types of representations of the solutions to the KdV equation. First, it was essential to express the degenerate $\theta$ function into an explicit Fredholm determinant. The second step was to get the transformation of the Fredholm determinant into a wronskian.
I have to mention a paper of Whitham [74] in connection with this work, and I would like to thank the referee about this information. The article [74] deals with equations as the KdV equation and the representation of solutions as sum of solitons, and also the relation of these solutions with Riemann theta functions in particular. It can be compared with the solutions given in the present work expressed in terms of Fredholm determinant and wronskians.

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