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Hydrochemical interactions of phoretic particles: a regularized multipole framework

³ Francisco Rojas-Pérez^{1 2}, Blaise Delmotte¹ and Sébastien Michelin¹[†]

4 ¹LadHyX, CNRS, Ecole Polytechnique, Institut Polytechnique de Paris, 91120 Palaiseau, France

5 ²Departamento de Física, Instituto Tecnológico de Costa Rica, Cartago, Costa Rica

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Chemically-active colloids modify the concentration of chemical solutes surrounding them in 7 order to self-propel. In doing so, they generate long-ranged hydrodynamic flows and chemical 8 gradients that modify the trajectories of other particles. As a result, the dynamics of reactive 9 suspensions is fundamentally governed by hydro-chemical interactions. A full solution of 10 the detailed hydro-chemical problem with many particles is challenging and computationally 11 expensive. Most current methods rely on the Green's functions of the Laplace and Stokes 12 operators to approximate the particle signatures in the far-field, which is only valid in the very 13 dilute limit in simple geometries. To overcome these limitations, we propose a regularized 14 mutipole framework, directly inspired by the Force Coupling Method (FCM), to model 15 phoretic suspensions. Our approach, called Diffusio-phoretic FCM (DFCM), relies on grid-16 based volume averages of the concentration field to compute the particle surface concentration 17 moments. These moments define the chemical multipoles of the diffusion (Laplace) problem 18 and provide the swimming forcing of the Stokes equations. Unlike far-field models based on 19 singularity superposition, DFCM accounts for mutually-induced dipoles. The accuracy of the 20 method is evaluated against exact and accurate numerical solutions for a few canonical cases. 21 We also quantify its improvements over far-field approximations for a wide range of inter-22 particle distances. The resulting framework can readily be implemented into efficient CFD 23 solvers, allowing for large scale simulations of semi-dilute diffusio-phoretic suspensions. 24

25 1. Introduction

Many microscopic organisms and colloidal particles swim by exerting active stresses on the 26 surrounding fluid in order to overcome its viscous resistance. In doing so, they set their fluid 27 environment into motion and modify the dynamics of their neighbours (Lauga & Powers 28 2009; Elgeti, Winkler & Gompper 2015). Large scale collective behaviour can emerge from 29 the resulting long-ranged interactions between individual agents (Pedley & Kessler 1992; 30 Zöttl & Stark 2016), but also profound modifications of the effective macroscopic rheological 31 and transport properties of such active suspensions (Saintillan & Shelley 2013; Saintillan 32 2018). These have recently become a major focus to study a broader class of systems 33 that are fundamentally out of thermodynamic equilibrium, broadly referred to as active 34 matter systems, which comprise large assemblies of individually-active agents that convert 35

† Email address for correspondence: sebastien.michelin@ladhyx.polytechnique.fr

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locally-stored energy into mechanical actuation resulting in non-trivial effective macroscopic
 properties (Marchetti *et al.* 2013; Bechinger *et al.* 2016).

Most biological swimmers apply such active stresses on the fluid through sequences of 38 shape changes, or swimming strokes, commonly through the flapping of slender flexible 39 appendages such as flagella or cilia (Lauga & Powers 2009; Brennen & Winet 1977; Lauga 40 2016). Such cell motility in viscous fluids plays a critical role in a diversity of biological 41 42 processes including mammal fertility (Fauci & Dillon 2006) or the balance of marine life ecosystems (Guasto, Rusconi & Stocker 2012). Inspired by these biological examples and 43 many promising applications in such various fields as biomedicine or biochemical reactors, 44 researchers and engineers across disciplines have focused on the design of microscopic self-45 propelled systems (Ebbens & Howse 2010). Many earlier designs were directly inspired 46 47 by the rotation of the helical flagella of bacteria or the flapping of flexible cilia (Dreyfus et al. 2005; Zhang et al. 2009; Babataheri et al. 2011), but rely on complex miniaturization 48 processes of moving parts or a macroscopic actuation (e.g. magnetic fields). 49

A fundamentally-different route, explored more recently, exploits interfacial processes 50 to generate fluid flow from local physico-chemical gradients (e.g. temperature, chemical 51 potential, electric potential or solute concentration), resulting directly from a chemical 52 activity of the particle surface itself (e.g. catalytic reactions) (Yadav et al. 2015; Moran 53 & Posner 2017). The most famous and commonly-used design is that of Janus nano- or 54 micro-particles with two different catalytic or physical properties (Paxton et al. 2004; Perro 55 et al. 2005). In dilute suspensions, these colloids exhibit short-term ballistic behaviour 56 (with velocities reaching a few $\mu m.s^{-1}$) but their long-time dynamics is more diffusive 57 as the result of thermal fluctuations (Howse et al. 2007). In contrast, complex collective 58 behaviour is observed in denser suspensions with the coexistence of cluster and gas-59 like phases (Theurkauff et al. 2012; Ginot et al. 2018). Understanding the emergence of 60 such phase-separation is currently a leading challenge in active matter physics (Cates & 61 Tailleur 2015). Beyond their fundamental interest and the puzzling details of their individual 62 and collective self-propulsions, these active colloids are already considered for various 63 engineering or biomedical applications, including drug delivery (Kagan et al. 2010), micro-64 surgery (Shao et al. 2018), intelligent cargo delivery (Sundararajan et al. 2008), self-healing 65 microchips (Li et al. 2015), chemical analysis (Duan et al. 2015) or sensing (Yi et al. 2016). 66 To generate autonomous propulsion, chemically-active colloids exploit a combination of 67 68 two different physico-chemical properties (Golestanian, Liverpool & Ajdari 2007; Moran & Posner 2017). The first one is a *phoretic mobility*, namely the ability to generate slip flow 69 along the boundary of a colloidal particle in response to gradients of a solute (diffusiophore-70 sis), temperature (thermophoresis) or electric potential (electrophoresis) (Anderson 1989), 71 resulting in a net drift of this particle. The second one is the ability of the particle itself 72 to generate the local gradients through a *surface activity*, e.g. surface-catalysis of chemical 73 reactions (Wang et al. 2006) or heat release (Bregulla & Cichos 2015). The combination 74 of these two generic properties, or *self-phoresis*, provides the colloid with the ability to 75 swim (Golestanian et al. 2007). Other self-propulsion mechanisms also share important 76 similarities with self-phoresis, including the propulsion of active droplets (Maass et al. 2016) 77 or of light-illuminated colloids in binary mixtures (Buttinoni et al. 2012). For simplicity, we 78 79 focus on self-diffusiophoresis of particles absorbing or releasing neutral chemical solutes (Córdova-Figueroa & Brady 2008; Popescu, Uspal & Dietrich 2016), keeping in mind that 80 the approach and framework presented here can be applied or generalised to account for more 81 generic self-phoretic systems (Moran & Posner 2011; Yariv 2011; Ibrahim, Golestanian & 82 Liverpool 2017). 83

84 Symmetry-breaking is an intrinsic requirement for directed motion in viscous flows; for 85 self-phoretic colloids, this requires to create or sustain a chemical surface polarity. As a result,

strictly isotropic colloids can not self-propel individually, although they may do so by self-86 87 assembling into geometrically- or chemically-asymmetric structures (Soto & Golestanian 2014, 2015; Varma et al. 2018; Schmidt et al. 2019). In practice, most chemically-active 88 colloids thus exhibit an intrinsic chemical asymmetry, where the two sides of a Janus colloid 89 capture or release solutes of different natures or at different rates (Moran & Posner 2017). 90 Geometrically-asymmetric colloids also break the symmetry of their chemical environment 91 92 and may thus self-propel (Kümmel et al. 2013; Shklyaev et al. 2014; Michelin & Lauga 2015). A third route to symmetry-breaking, based on an instability, arises for isotropic 93 colloids when the chemical solutes diffuse sufficiently slowly for the nonlinear convective 94 coupling of phoretic flows and chemical transport to become significant (Michelin et al. 95 2013; Izri et al. 2014; Hu et al. 2019). 96

Like all microswimmers, Janus phoretic particles self-propel by stirring the fluid around 97 them and thus modify the trajectory and speed of their neighbours. Due to their chemical 98 activity, they also alter their chemical environment and thus also drive an additional phoretic 99 motion of the surrounding particles. In most experiments on chemically-active particles, 100 the diffusing solutes are small (e.g. dissolved gas) and chemical transport is dominated by 101 diffusion. Such micron-size colloids typically propel with velocities $U \approx 1-10 \mu \text{m.s}^{-1}$ and 102 consume or release solutes of diffusivity $D \approx 10^3 \mu m^2 \, s^{-1}$, so that the relevant Péclet number 103 Pe is always small (Pe $\approx 10^{-3}$ -10⁻²) (Paxton *et al.* 2004; Howse *et al.* 2007; Theurkauff 104 et al. 2012; Brown & Poon 2014). Then, obtaining the swimming velocity of phoretic 105 Janus particles therefore requires solving two different problems sequentially, namely (i) 106 a diffusion (Laplace) problem for the solute concentration around the colloids and (ii) a 107 hydrodynamic (Stokes) problem for the fluid flow around them. Analytical solution is in 108 general amenable only for single particles (Golestanian et al. 2007), although determining the 109 coupled motion of two Janus colloids is also possible semi-analytically (Varma & Michelin 110 2019; Nasouri & Golestanian 2020a; Sharifi-Mood et al. 2016). For more than two particles, 111 a complete description of the phoretic motion requires numerical treatment (Montenegro-112 Johnson, Michelin & Lauga 2015) but with a computational cost that increases rapidly with 113 the number of particles, motivating the use for reduced models for the particles' interactions. 114 In dilute suspensions, i.e. when particles are far apart from each other, their hydro-chemical 115 interactions can be accounted for through the slowest-decaying chemical and hydrodynamic 116 signatures of individual particles and their effect on their neighbours (Saha et al. 2014; 117 118 Varma & Michelin 2019). Due to their simplicity, small computational cost for large number 119 of particles and their ability to handle the effect of confinements through image systems, far-field models have been extensively used to analyse the motion of active suspensions (see 120 e.g. Ibrahim & Liverpool 2016; Thutupalli et al. 2018; Kanso & Michelin 2019; Liebchen 121 & Löwen 2019). An alternative mean-field approach describes the particles' motion in the 122 ambient chemical and hydrodynamic fields generated by the superposition of their individual 123 far-field signatures (Liebchen et al. 2015; Traverso & Michelin 2020). 124 125 For more concentrated suspensions, i.e. when the inter-particle distances is reduced, far-

field models are not accurate as finite-size effects of the particles are no longer negligible. 126 Although it is possible to include higher order corrections using the Method of Reflec-127 tions (Varma & Michelin 2019), more complex numerical models are in general required to 128 129 solve the dual hydro-chemical problem accurately within not-so-dilute suspensions. Due to the mathematical similarities between Laplace and Stokes problems, it is possible to draw 130 inspiration from and build upon a large variety of methods already used in recent years for the 131 132 numerical modelling of passive and active suspensions. A popular example is the Stokesian dynamics and its more recent extensions (Brady & Bossis 1988; Swan et al. 2011; Sierou & 133 134 Brady 2001; Fiore & Swan 2019), from which an analogous approach was proposed to solve for diffusion problems (Yan & Brady 2016). A similar approach relies on a truncated spectral 135

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136 expansion of the integral formulation of the Laplace and Stokes equations with tensorial spherical harmonics on the particle's surface (Singh et al. 2019; Singh & Adhikari 2019). 137 But the possible routes also include Boundary Element Methods (Ishikawa et al. 2006; Uspal 138 et al. 2015; Montenegro-Johnson et al. 2015), Immersed Boundary Methods (Lushi & Peskin 139 140 2013; Lambert et al. 2013; Bhalla et al. 2013), Lattice-Boltzmann approaches (Alarcón & Pagonabarraga 2013; Ladd & Verberg 2001), Multi-Particle Collision Dynamics (Zöttl & 141 142 Stark 2014; Yang, Wysocki & Ripoll 2014; Colberg & Kapral 2017; Zöttl & Stark 2018), and the Force Coupling Method (Maxey & Patel 2001; Delmotte et al. 2015). 143

The objective of the present work is to extend the fundamental idea and framework of 144 the latter to establish and validate a unified method that accounts for both chemical and 145 hydrodynamic interactions between phoretic particles. The Force Coupling Method (FCM) 146 used to solve for the hydrodynamic interactions of particles in a fluid relies on the classical 147 multipolar expansion of the solution for Stokes' equation (Saffman 1973), but proposes 148 a regularised alternative to singular Green's function in the form of smoothed Gaussian 149 kernels. Beyond the obvious numerical advantage of such a regularization, it also provides 150 an indirect route to account for the finite size of the particles through the finite support of 151 152 these kernels. The FCM framework was initially proposed twenty years ago by Maxey and coworkers (Maxey & Patel 2001; Lomholt & Maxey 2003) to analyse the joint dynamics of 153 154 passive spherical particles sedimenting in a viscous fluid. It has since then been extended to account for finite inertia (Xu, Maxey & Karniadakis 2002), lubrication effects (Dance 155 & Maxey 2003) and non-sphericity of the particles (Liu et al. 2009) leading to a powerful 156 method to study the hydrodynamic interactions of large suspensions. More recently, FCM 157 was also adapted to account for the activity of the colloids and enabled the analysis of 158 microswimmer suspensions (Delmotte et al. 2015). 159

In this work, an FCM-based method is presented to solve the Laplace problem for the 160 concentration field in phoretic suspensions of spherical Janus particles, using a regularized 161 162 multipole representation of the concentration based on smoothed kernels instead of the classical singular monopole and dipole singularities. This provides the phoretic forcing 163 introduced by the local inhomogeneity of the concentration field on each particle, from 164 which the hydrodynamic problem can be solved using the existing FCM approach for active 165 suspensions (Delmotte et al. 2015). Taken together, this provides an integrated framework to 166 solve for the complete diffusiophoretic problem, or Diffusiophoretic Force Coupling Method 167 whose fundamental justification and validation is the main objective of the present work. 168

The rest of the paper is organized as follows. The governing equations for the collective 169 motion of phoretic particles are first reminded in Section 2. The Diffusiophoretic Force 170 Coupling Method (DFCM) is then presented in detail in Section 3. More specifically, the 171 172 new solution framework for the Laplace problem is first presented in Section 3.1. Section 3.2 summarizes the main elements of the classical hydrodynamic FCM method and its extension 173 to active particles, and Section 3.3 finally presents how the two steps are conveniently 174 coupled to solve successively the chemical and hydrodynamic problem. In order to validate 175 the approach and compare its accuracy to existing methods, Section 4 considers a series 176 of canonical configurations for pairwise interactions of two Janus particles, for which an 177 analytical or numerical solution of the full problem is available for any inter-particle distance. 178 The results of DFCM are compared to this benchmark but also to the far-field estimation 179 of the particles' velocities. This provides further insight on the improvement brought by 180 this approach and its range of validity, which will be a critical information for future use 181 in larger suspension simulations. Finally, Section 5 summarizes the findings of the paper, 182 183 the constraints and advantages of the method and discusses some perspectives for its future implementation in studying large phoretic suspensions. 184

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185 2. Modelling reactive suspensions

186 Reactive suspensions consist of large sets of micro-particles that are able to self-propel in a viscous fluid by exploiting the chemical activity of their surface and its ability to generate 187 an effective hydrodynamic slip in response to gradients of the solute species they produce or 188 consume. As a result, these particles react to the chemical and hydrodynamic forcing exerted 189 by their neighbours, introducing a coupling that may lead to modified effective properties at 190 the scale of the suspensions. For purely diffusive solute species, determining their individual 191 dynamics requires solving successively for two different problems, namely a Laplace problem 192 for the solute concentration distribution, followed by a Stokes problem for the hydrodynamic 193 194 fields and particle velocities (translation and rotation) in response to the solute gradients at their surface (Golestanian et al. 2007). The corresponding equations of motion are reminded 195 196 in detail below.

2.1. Governing equations for self-diffusiophoresis of N micro-particles

The coupled motion of N identical and spherical phoretic particles of equal radius a is considered within a viscous fluid of density ρ and viscosity μ . Particle n occupies a volume V_n bounded by its surface S_n and centred at $Y_n(t)$, and has orientation p_n ; U_n and Ω_n are its translation and rotation velocities. The fluid domain is noted V_f and may be bounded or unbounded (figure 1a).

Each particle emits a chemical solute of diffusivity D on the catalytic parts of its surface with a fixed spatially-dependent rate, of characteristic magnitude α_0 , and is able to generate a slip flow in response to a surface concentration gradient, with a characteristic phoretic mobility M_0 . In the following, all variables and equations are made dimensionless using a, $U_0 = \alpha_0 M_0/D$ and $a\alpha_0/D$ as characteristic length, velocity and concentration scales.

As a result of its surface activity, the dimensionless relative concentration c (with respect to its background value far from the particles) satisfies the following Neumann condition on the surface of particle n:

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$$-\boldsymbol{n}\cdot\nabla\boldsymbol{c} = \alpha_n(\mathbf{n}) \qquad \text{on } S_n, \tag{2.1}$$

where $\alpha_n(\mathbf{n})$ is the dimensionless activity distribution (i.e. emission rate) and \mathbf{n} is the outward normal unit vector on S_n . For sufficiently small particles, the solute's dynamic is purely diffusive, i.e. the relevant Péclet number $Pe = aU_0/D \ll 1$, so that *c* obeys Laplace's equation outside the particles,

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$$\nabla^2 c = 0 \qquad \text{in } V_f \,. \tag{2.2}$$

Together with an appropriate boundary conditions at the external boundary of V_f (e.g. $c \to 0$ for $|\mathbf{r}| \to \infty$ in unbounded domains), these equations form a well-posed problem for the distribution of solute in the fluid domain V_f .

In response to non-uniform solute distribution at the particles' surface, a phoretic slip flow u_n^s develops outside a thin interaction layer (Anderson 1989) so that effectively, the hydrodynamic boundary condition on S_n becomes

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$$\boldsymbol{u} = \boldsymbol{U}_n + \boldsymbol{\Omega}_n \times \boldsymbol{r}_n + \boldsymbol{u}_n^s, \quad \text{with } \boldsymbol{u}_n^s = M_n(\mathbf{n}) \nabla_{||} c \quad \text{on } S_n.$$
(2.3)

In the previous equation, $\nabla_{||} = (l - nn) \cdot \nabla$ is the tangential gradient on the particle's surface, $r_n = r - Y_n$ is the generic position relative to the *n* particle's centre, and $M_n(n)$ denotes the dimensionless and spatially-dependent phoretic mobility of the surface of particle *n*. For small particles, inertial effects are negligible (i.e. $Re = \rho U_0 a/\mu \ll 1$), and the dimensionless fluid's velocity and pressure (u, p) satisfy Stokes' equations:



Figure 1: (a) Geometric description and parameter definition for (a) a reactive suspension system and (b) an individual active particle including the fluid domain V_f , as well the phoretic particles' position Y_n and orientation p_n , their radius *a*. The particle's orientation p_n , allows for the definition of its front caps (noted *F* and *B* respectively). The different colours of the caps (white or grey) illustrate their different chemical activity, while their pattern (striped and solid) illustrate their different mobilities.

- with appropriate condition at the outer boundary of V_f (e.g. $\boldsymbol{u} \to 0$ for $|\boldsymbol{r}| \to \infty$). Neglecting
- any outer forcing such as gravity, each particle is hydrodynamically force- and torque-free
- 232 (Popescu et al. 2016) at all times,

233
$$\boldsymbol{F}_n = \int_{S_n} \boldsymbol{\sigma} \cdot \boldsymbol{n} \, \mathrm{d}S = \boldsymbol{0}, \qquad \boldsymbol{T}_n = \int_{S_n} \boldsymbol{r}_n \times (\boldsymbol{\sigma} \cdot \boldsymbol{n}) \, \mathrm{d}S = \boldsymbol{0}, \qquad (2.5)$$

with $\sigma = -p\mathbf{I} + (\nabla \mathbf{u} + \nabla \mathbf{u}^T)$ the dimensionless Newtonian stress tensor, and their dominant hydrodynamic signature is therefore that of a force dipole or stresslet S_n (Batchelor 1970). For a given concentration distribution *c*, Equations (2.3)–(2.5) form a well-posed problem for the fluid velocity and pressure, and particle velocities, so that at a given time *t*, and for given particle positions and orientations, $Y_n(t)$ and $p_n(t)$, the successive Laplace and Stokes problems presented above uniquely determine the instantaneous particle velocities $U_n(t)$ and $\Omega_n(t)$, from which the motion of the particles is obtained:

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$$\frac{\mathrm{d}\boldsymbol{Y}_n}{\mathrm{d}t} = \boldsymbol{U}_n, \qquad \frac{\mathrm{d}\boldsymbol{p}_n}{\mathrm{d}t} = \boldsymbol{\Omega}_n \times \boldsymbol{p}_n. \tag{2.6}$$

For a single isolated particle, the Lorentz Reciprocal Theorem to Stokes flows provides the particle's translation and rotation velocities directly in terms of the phoretic slip (Stone & Samuel 1996):

245
$$U = -\langle u^s \rangle, \qquad \Omega = -\frac{3}{2a} \langle n \times u^s \rangle, \qquad (2.7)$$

where $\langle \cdot \rangle$ is the spatial average over the particle's surface. Similarly, the stresslet **S** of the particle is obtained as (Lauga & Michelin 2016),

248
$$\mathbf{S} = -10\pi a^2 \langle \mathbf{n} \mathbf{u}^s + \mathbf{u}^s \mathbf{n} \rangle. \tag{2.8}$$

2.2. Hemispheric Janus phoretic particles

Most phoretic particles have a Janus-type surface consisting of two different materials 250 251 or surface coatings with distinct physico-chemical properties (e.g. a catalytic side and a passive one) (Paxton et al. 2004; Howse et al. 2007; Theurkauff et al. 2012). These 252 provide the particles with a built-in chemical asymmetry that triggers the inhomogeneity 253 of the concentration distribution at their surface at the heart of their self-propulsion. In 254 the following, we thus consider such hemispheric Janus particles with uniform but distinct mobilities (M_n^F, M_n^B) and activities (α_n^F, α_n^B) on their front (F) and back (B) hemispheres, as defined with respect to their orientation p_n (figure 1b), e.g. the surface mobility of particle 255 256 257 n writes 258

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$$M_n(\boldsymbol{n}) = M_n + M_n^* \operatorname{sign}(\boldsymbol{p}_n \cdot \boldsymbol{n}), \qquad (2.9)$$

with $\overline{M}_n = (M_n^F + M_n^B)/2$ and $M_n^* = (M_n^F - M_n^B)/2$ the mean mobility and mobility contrast, and a similar definition for the spatially-dependent activity $\alpha_n(n)$ at the particle's surface. The special case of a particle with uniform mobility thus corresponds to $\overline{M}_n = M_n^0$ and $M_n^* = 0$.

264 3. An FCM-based method for phoretic suspensions

In the purely diffusive and viscous limit, solving for the particles' dynamics therefore 265 amounts to solving sequentially two linear problems, namely a Laplace problem for c and 266 a Stokes swimming problem for the hydrodynamic field and particles' velocity. Although 267 the exact solution to this joint problem can be obtained analytically for the single- and two-268 particle cases (Golestanian et al. 2007; Sharifi-Mood et al. 2016; Varma & Michelin 2019), 269 analytical treatment becomes intractable beyond $N \ge 3$ due to the geometric complexity 270 of the fluid domain and despite the problem's linearity. Numerical simulations are therefore 271 critically needed, and several numerical strategies have been proposed recently and briefly 272 reviewed in the introduction. In order to analyse accurately the collective dynamics of in a 273 suspension of Janus phoretic particles, such a method must combine an efficient solution 274 of the Laplace and Stokes problems outside a large number of finite-size objects, while 275 providing accurate representation of the coupling at the surface of each particle between 276 chemical and hydrodynamic fields. 277

278 With that double objective in mind, we propose and present here a novel numerical framework to solve for the reactive suspension problem presented in Section 2, based on 279 the classical Force Coupling Method (FCM) used for pure hydrodynamic simulations of 280 passive particles or microswimmers, thereby generalising its application to the solution of 281 the chemical diffusion problem and its coupling with the already-established hydrodynamic 282 FCM (Maxey & Patel 2001; Lomholt & Maxey 2003; Yeo & Maxey 2010; Delmotte et al. 283 2015). Section 3.1 develops the regularized Laplace problem and associated Reactive FCM, 284 285 while Sec. 3.2 presents a brief review of the existing hydrodynamic FCM, and Sec. 3.3 combines both to obtain a new Diffusio-phoretic Force Coupling Method approach. 286

The fundamental idea of the Force Coupling Method is to replace a solution of the Stokes 287 equations only within the fluid domain V_f outside the forcing particles, by a solution of these 288 equations over the entire domain $V_F = V_f \cup V_1 \cup \ldots \cup V_N$ (i.e. both outside and inside the 289 particles), replacing the surface boundary conditions with a distributed regularised forcing 290 over a compact envelope calibrated so as to reproduce certain physical features of the problem 291 and account for a weak form of the surface boundary conditions (figure 2). Doing so, the 292 costly discrete resolution and time-dependent meshing of the particles is no longer necessary, 293 294 so that efficient (e.g. spectral) Laplace and Stokes solvers on a fixed regular grid may be used at all times, offering significant performance and scalability advantages with respect to other 295



Figure 2: Regularized representation of (a) the reactive suspension system and (b) individual particles in the DFCM framework. The chemical and hydrodynamic fields are now defined over the entire domain with distributed forcings defined relative to each particle's position Y_n and orientation p_n . The boundary S_n of the real particle (dashed) and its radius *a* are plotted only as reference.

approaches (e.g. Boundary Element Methods). More specifically, FCM associates to each
 particle a finite set of regularized hydrodynamic singularities (force monopoles, dipoles and
 so on) chosen so as to satisfy a weak form of the surface boundary conditions.

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3.1. Reactive FCM

We extend here this approach to the solution of the Laplace problem for c in Eqs. (2.1)–(2.2).

Replacing each particle by a distributed forcing modifies Laplace's equations into a Poisson equation over the entire domain V_F (including both fluid and particles),

$$\nabla^2 c = -g(\mathbf{r}, t) \qquad \text{in } V_F, \tag{3.1}$$

where the function $g(\mathbf{r}, t)$ includes the source terms accounting for the presence of each particle.

306 3.1.1. Standard Multipole Expansion for Laplace problem

The exact solution of the Laplace problems can in fact be recovered from Eq. (3.1), when the function $g(\mathbf{r}, t)$ is taken as a (possibly infinite) set of singularities centred on each particle (Saffman 1973),

310
$$g(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[q_n^M \delta(\boldsymbol{r}_n) + \boldsymbol{q}_n^D \cdot \nabla \delta(\boldsymbol{r}_n) + \dots \right], \qquad (3.2)$$

where $\delta(\mathbf{r}_n)$ is the Dirac delta distribution, and $(q_n^M, \mathbf{q}_n^D,...)$ are the intensity of the singularities associated with particle *n*, and are constant tensors of increasing order. This equation can be solved explicitly for the concentration field *c* as a multipole expansion for each particle in terms of source monopoles, dipoles, etc...

315
$$c(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[\boldsymbol{q}_{n}^{M} \boldsymbol{G}^{M}(\boldsymbol{r}_{n}) + \boldsymbol{q}_{n}^{D} \cdot \boldsymbol{G}^{D}(\boldsymbol{r}_{n}) + \dots \right], \qquad (3.3)$$



Figure 3: Singular (dotted lines, Eq. (3.5)) and regularized (solid lines, Eqs. (3.10)–(3.11)) concentration distributions along the axial polar direction associated to the Greens' Functions for the Laplace equation for: a) monopole terms and b) dipole terms. The line r/a = 1 represents the particle surface.

where G^M and G^D are the monopole and dipole Green's functions and satisfy

317
$$\nabla^2 G^M = -\delta(\mathbf{r}_n), \qquad \nabla^2 G^D = -\nabla \delta(\mathbf{r}_n), \tag{3.4}$$

together with appropriate decay or boundary conditions on the domain's outer boundary. For

unbounded domains with decaying conditions in the far-field, the singular monopole and dipole Green's functions are simply

321
$$G^{M}(\boldsymbol{r}_{n}) = \frac{1}{4\pi r_{n}} \quad \text{and} \quad \boldsymbol{G}^{D}(\boldsymbol{r}_{n}) = -\nabla \boldsymbol{G}^{M} = \frac{\boldsymbol{r}_{n}}{4\pi r_{n}^{3}}.$$
 (3.5)

The concentration distributions associated to these singular Green's functions are displayed in figure 3. Higher-order derivatives of $G^M(\mathbf{r})$, Eq. (3.5), are also solutions of Laplace's equation leading to singularities of increasing order (quadrupole, octopole,...).

325 3.1.2. Truncated regularized multipole expansion

The previous approach, based on an infinite set of singular sources, is known as the standard multipole expansion of the Laplace problem. Although satisfying from a theoretical point of view, since it is able to recover an accurate representation of the analytical solution outside the particles for a large enough number of singular monopoles, it is not well-suited for a versatile numerical implementation because of (i) the singular behaviour of the forcing terms in the modified Laplace equation, Eq. (3.1), and (ii) the *a priori* infinite set of singularities required for each particle.

To avoid the latter issue, the infinite expansion is truncated here after the first two terms, thus retaining the monopole and dipole contributions only. Physically, this amounts to retaining the two leading physical effects of the particle on the concentration field, i.e. a net emission with a front-back asymmetric distribution. In order to overcome the former problem, the standard FCM replaces the singular Dirac distributions $\delta(\mathbf{r})$ by regular Gaussian spreading functions $\Delta(\mathbf{r})$:

339
$$\Delta(\mathbf{r}) = (2\pi\sigma^2)^{-3/2} \exp\left(-\frac{r^2}{2\sigma^2}\right),$$
(3.6)

where σ denotes the finite-size support of this envelop and acts as a smoothing parameter of the method, thus eliminating the singular behaviour of the delta distribution $\delta(\mathbf{r})$ near the origin, thereby allowing for a more accurate numerical treatment. The original singular distribution is recovered when $\sigma \ll r$, i.e. the solution of the regularised problem is an accurate representation of the true solution away from the particle. This approach using
regular distributions allows for a more versatile and robust numerical solution of the physical
equations than their singular counterparts (Maxey & Patel 2001; Lomholt & Maxey 2003).

Combining these two approximations, we therefore consider a truncated regularized expansion including only the monopole and the dipole terms as:

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$$g(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[q_n^M \Delta^M(r_n) + \boldsymbol{q}_n^D \cdot \nabla \Delta^D(r_n) \right], \tag{3.7}$$

350 with the Gaussian spreading operators Δ^M and Δ^D defined as:

351
$$\Delta^{M}(r) = (2\pi\sigma_{M}^{2})^{-3/2} \exp\left(-\frac{r^{2}}{2\sigma_{M}^{2}}\right), \qquad \Delta^{D}(r) = (2\pi\sigma_{D}^{2})^{-3/2} \exp\left(-\frac{r^{2}}{2\sigma_{D}^{2}}\right), \qquad (3.8)$$

where *M* and *D* once again denotes monopole and dipole, and σ_M and σ_D are the finite support of each regularized distribution and are free numerical parameters of the method that need to be calibrated. Note that in all generality, these do not need to be identical (Lomholt & Maxey 2003).

The corresponding truncated regularized solution for c is then finally obtained as:

$$c(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[q_n^M G^M(\boldsymbol{r}_n) + \boldsymbol{q}_n^D \cdot \boldsymbol{G}^D(\boldsymbol{r}_n) \right],$$
(3.9)

358 with the regularized monopole and dipole Green's functions

359
$$G^{M}(\mathbf{r}) = \frac{1}{4\pi r} \operatorname{erf}\left(\frac{r}{\sigma_{M}\sqrt{2}}\right), \qquad (3.10)$$

$$\boldsymbol{G}^{D}(\boldsymbol{r}) = \frac{\boldsymbol{r}}{4\pi r^{3}} \left[\operatorname{erf}\left(\frac{r}{\sigma_{D}\sqrt{2}}\right) - \sqrt{\frac{2}{\pi}} \left(\frac{r}{\sigma_{D}}\right) \exp\left(-\frac{r^{2}}{2\sigma_{D}^{2}}\right) \right].$$
(3.11)

360 361

These clearly match the behaviour of their singular counterpart, Eq. (3.5), when *r* is greater than a few σ_M or σ_D , respectively, while still maintaining finite values within the particle (figure 3), e.g. $G^D(r = 0) = 0$.

365 3.1.3. Finding the intensity of the singularities

Up to this point, no information was implemented regarding the surface boundary conditions on *c* in Eq. (2.1). We now present how to determine the intensities of the monopole and dipole distributions associated with each particle, q_n^M and q_n^D , so as to satisfy a weak form of the Neuman boundary condition, Eq. (2.1), i.e. its first two moments over the particle's surface. Using the multipole expansion of the fundamental integral representation of the concentration (see Appendix A), the monopole and dipole intensities of particle *n*, q_n^M and q_n^D , are obtained as (Yan & Brady 2016):

373
$$q_n^M = \int_{S_n} \alpha_n \mathrm{d}S, \qquad \boldsymbol{q}_n^D = a \int_{S_n} \alpha_n \mathbf{n} \mathrm{d}S + 4\pi a^2 \langle c \boldsymbol{n} \rangle_n \tag{3.12}$$

where the second term in q_n^D is proportional to the concentration polarity at the surface of particle *n*, i.e. its first moment $\langle cn \rangle_n$, and is defined using the surface average operator $\langle \cdot \rangle_n$ over particle *n*'s surface. Note that the activity distribution at the particle's surface is known, and thus Eq. (2.9) explicitly provides the monopole intensity and the first term in the dipole intensity. The second contribution to the latter requires however knowledge of the solution on the particle's surface – which is not explicitly represented in the present FCM approach.

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This term therefore requires to be solved for as part of the general problem. In the previous equation, it should be noted that the dimensionless particle radius is a = 1, but will be kept in the equations to emphasize the relative scaling of the numerical spreading enveloppes (e.g. σ_M and σ_D) with respect to the particle size.

Here, we use an iterative approach to solve this linear joint problem for the dipole intensity and concentration field, solving alternatively Eqs. (3.7) and (3.12) until convergence is reached, as defined by the following criterion between two successive iterations:

387
$$\left\|\frac{\langle cn\rangle^{k+1} - \langle cn\rangle^{k}}{\langle cn\rangle^{k+1}}\right\|_{\infty} < \epsilon, \qquad (3.13)$$

where $\langle cn \rangle^k$ is the vector collecting the polarities of the *N* particles at iteration *k*. For the results presented in this work, we set the tolerance to $\epsilon = 10^{-10}$ in our calculations.

390 3.1.4. Regularized moments of the concentration distribution

Finding the dipole intensity, q_n^D , requires computing the polarity $\langle cn \rangle_n$ which is in principle defined *at the particle's surface*. To follow the spirit of FCM, and allow for efficient numerical treatment, this surface projection is replaced by a weighted projection over the entire volume V_F :

395
$$\langle c\mathbf{n}\rangle_n = \frac{1}{4\pi a^2} \int_{S_n} c\mathbf{n} dS \longrightarrow \{c\mathbf{n}\}_n = \int_{V_F} c\mathbf{n}_n \Delta^P(\mathbf{r}_n) dV,$$
 (3.14)

396 with n_n now defined as $n_n = r_n/r_n$, and the regular averaging kernel Δ^P for the polarity as:

397
$$\Delta^P(\mathbf{r}) = \frac{r}{8\pi\sigma_P^4} \exp\left(-\frac{r^2}{2\sigma_P^2}\right). \tag{3.15}$$

Beyond its importance for determining the dipole intensity associated to a given particle, we will later show that the polarity of the concentration at particle *n*'s surface is directly related to its self-induced phoretic velocity, Eq. (2.7), and that, similarly, the self-induced hydrodynamic stresslet signature of the particle is in general associated to the first two moments of the surface concentration. Similarly to the polarity, the second surface moment, $\langle c(nn - l/3) \rangle_n$ will be replaced in our implementation by a weighted volume projection $\{c(nn - l/3)\}_n$:

$$\langle c(\boldsymbol{n}\boldsymbol{n}-\boldsymbol{l}/3)\rangle_{n} = \frac{1}{4\pi a^{2}} \int_{S_{n}} c\left(\boldsymbol{n}\boldsymbol{n}-\boldsymbol{l}/3\right) \mathrm{d}S \to \{c(\boldsymbol{n}\boldsymbol{n}-\boldsymbol{l}/3)\}_{n} = \int_{V_{F}} c\left(\boldsymbol{n}_{n}\boldsymbol{n}_{n}-\boldsymbol{l}/3\right) \Delta^{S}(\boldsymbol{r}_{n}) \mathrm{d}V$$
(3.16)

405

406 where the projection kernel for the second moment of concentration, Δ^S , is defined as:

407
$$\Delta^{S}(\mathbf{r}) = \frac{r^{2}}{3(2\pi)^{\frac{3}{2}}\sigma_{S}^{5}} \exp\left(-\frac{r^{2}}{2\sigma_{S}^{2}}\right).$$
(3.17)

The envelopes σ_P and σ_S are free parameters in the method that need to be calibrated. In our 408 reactive FCM formulation, we use modified forms of the Gaussian operator Δ as projection 409 operators, Eqs. (3.15) and (3.17), in order to ensure a fast numerical convergence of the 410 integration for the first and second moments calculation, Eqs. (3.14) and (3.16) respectively. 411 The integrals over the entire volume V_F of these averaging functions is still equal to one, 412 and their weight is shifted from the particle centre and toward the particle surface (figure 4), 413 414 which is both numerically more accurate and more intuitive physically as these operators are used to obtain the properties of the particle on their surface. 415



Figure 4: Averaging envelopes for the first and second moments of concentration, Δ^P (solid, Eq. (3.15)) and Δ^S (dashed, Eq. (3.17)) respectively. The numerical values for σ_P and σ_S are set from Eqs. (3.21) and (3.24).

416 3.1.5. Calibrating the spreading/averaging envelopes.

Our method relies on four numerical parameters (σ_M , σ_D , σ_P , σ_S) that we choose to calibrate so as to ensure that several key results in reference configurations are obtained exactly. In particular, to properly account for the phoretic drift induced by the other particles, we ensure that the polarity $\langle cn \rangle$ of an isolated particle placed in an externally-imposed uniform gradient of concentration can be exactly recovered using the regular representation and averaging operators. A similar approach is then followed for the particle's second moment of concentration $\langle c(nn - l/3) \rangle$ in a quadratic externally-imposed field.

Isolated passive particle in an external linear field – We first consider a single particle placed at the origin in an externally-imposed linear concentration field so that for $r \gg a$, $c \approx c_E$ with

$$c_E = \boldsymbol{L}_E \cdot \boldsymbol{r},\tag{3.18}$$

where L_E is the externally-imposed uniform gradient. For a passive particle (i.e. $\alpha = 0$), satisfying the boundary condition, Eq. (2.1), at the surface of the particle imposes that the exact concentration distribution around the particle is $c = c_E + c_I^o$, with $c_I^o(\mathbf{r}) = a^3 L_E \cdot \mathbf{r}/(2r^3)$ a singular dipole induced field. The polarity of the external and induced parts, c_E and c_I , can be obtained analytically as:

434
$$\langle c_E \boldsymbol{n} \rangle = \frac{a}{3} \boldsymbol{L}_E, \qquad \langle c_I^o \boldsymbol{n} \rangle = \frac{a}{6} \boldsymbol{L}_E.$$
 (3.19)

Following the framework presented above, the regularized solution can be written $c = c_E + c_I^r$ with c_i^r a regularized dipole, and the corresponding regularized-volume moments based on Eq. (3.14) are obtained using Eq. (3.11), as

438
$$\{c_E \boldsymbol{n}\} = \sqrt{\frac{\pi}{8}} \sigma_P \boldsymbol{L}_E, \qquad \{c_I^r \boldsymbol{n}\} = \frac{a^3 \sigma_P}{12(\sigma_D^2 + \sigma_P^2)^{\frac{3}{2}}} \boldsymbol{L}_E. \tag{3.20}$$

Identification of the regularized result (3.20) to the true solution (3.19), determines σ_P and σ_D uniquely as:

441
$$\frac{\sigma_P}{a} = \frac{1}{3}\sqrt{\frac{8}{\pi}} \approx 0.5319, \qquad \frac{\sigma_D}{a} = \sqrt{\left(\frac{\sigma_P}{2a}\right)^{2/3} - \left(\frac{\sigma_P}{a}\right)^2} \approx 0.3614.$$
(3.21)

442 443

Isolated passive particle in an external quadratic field – Similarly, in an external quadratic field c_E of the form:

446

$$c_E(\mathbf{r}) = \mathbf{r} \cdot \mathbf{Q}_E \cdot \mathbf{r}, \qquad (3.22)$$

with Q_E a second-order symmetric and traceless tensor, the concentration distribution around a passive particle ($\alpha = 0$) takes the form $c = c_E + c_I^o$ with $c_I^o(\mathbf{r})$ an induced singular quadrupole. The exact and regularized second moments of the external field c_E at the particle surface is equal to

451
$$\langle c_E(nn - I/3) \rangle = \frac{2a^2}{15} Q_E, \qquad \{c_E(nn - I/3)\} = \frac{2\sigma_S^2}{3} Q_E.$$
 (3.23)

Identifying both results determines the size of the averaging envelope for the second moment uniquely, as

$$\frac{\sigma_S}{a} = \sqrt{\frac{1}{5}} \approx 0.4472. \tag{3.24}$$

Note that we do not enforce here a constraint on the representation of the second moment of the induced field c_I , since the particles' representation do not include a regularized quadrupole in our method.

458

454

The value σ_M remains as a free parameter at this point and cannot be calibrated with a similar approach. In the following, in order to minimize the number of distinct numerical parameters and to minimize the departure of the regularized solution from its singular counterpart, we set its value equal to the smallest envelope size, namely $\sigma_M = \sigma_D$. These specific values of the parameters were used in figures 3 and 4.

464

474

3.2. Hydrodynamic FCM

To compute the hydrodynamic interactions between phoretic particles, we rely on the Force Coupling Method (FCM). This section briefly describes the existing FCM framework developed for the simulation of passive and active suspensions in Stokes flow.

468 3.2.1. FCM for passive suspensions

With hydrodynamic FCM, the effect of the particles on the fluid is accounted for through a forcing term f applied to the dimensionless Stokes equations

471
$$\nabla p - \nabla^2 \boldsymbol{u} = \boldsymbol{f}(\boldsymbol{r}, t) \quad \text{in } V_F. \tag{3.25}$$

472 As for reactive FCM, this forcing arises from a truncated regularized multipolar expansion 473 up to the dipole level

$$\boldsymbol{f}(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[\boldsymbol{F}_{n} \Delta(\boldsymbol{r}_{n}) + \boldsymbol{D}_{n} \cdot \nabla \Delta^{*}(\boldsymbol{r}_{n}) \right], \qquad (3.26)$$

475 where the spreading envelopes are defined by

476
$$\Delta(r) = (2\pi\sigma^2)^{-3/2} \exp\left(-\frac{r^2}{2\sigma^2}\right), \qquad \Delta^*(r) = (2\pi\sigma_*^2)^{-3/2} \exp\left(-\frac{r^2}{2\sigma_*^2}\right). \tag{3.27}$$

477 F_n and D_n are the force monopole and dipole applied to particle *n*. The force dipole can be 478 split into a symmetric part, the stresslet **S**, and an antisymmetric one related to the external 14

479 torque *T*:

480

483

$$\boldsymbol{D}_n = \boldsymbol{S}_n + \frac{1}{2}\boldsymbol{\epsilon} \cdot \boldsymbol{T}_n, \qquad (3.28)$$

with ϵ the third-order permutation tensor. The corresponding regularized solution for the fluid velocity u is then obtained as:

$$\boldsymbol{u} = \boldsymbol{u}(\boldsymbol{r}) = \sum_{n=1}^{N} \left[\boldsymbol{F}_n \cdot \boldsymbol{J}(\boldsymbol{r}_n) + \boldsymbol{D}_n : \boldsymbol{R}^*(\boldsymbol{r}_n) \right].$$
(3.29)

For unbounded domains with vanishing perturbations in the far-field (i.e. $||u|| \to 0$ when $r \to \infty$), the regularized Green's function J(r) reads

486
$$\boldsymbol{J}(\boldsymbol{r}) = \frac{1}{8\pi r} \left(A(r)\boldsymbol{I} + B(r)\frac{\boldsymbol{r}\boldsymbol{r}}{r^2} \right), \qquad (3.30)$$

487 with

$$A(r) = \left(1 + \frac{\sigma^2}{r^2}\right) \operatorname{erf}\left(\frac{r}{\sigma\sqrt{2}}\right) - \frac{\sigma}{r}\sqrt{\frac{2}{\pi}} \exp\left(-\frac{r^2}{2\sigma^2}\right),\tag{3.31}$$

$$B(r) = \left(1 - \frac{3\sigma^2}{r^2}\right) \operatorname{erf}\left(\frac{r}{\sigma\sqrt{2}}\right) + \frac{3\sigma}{r}\sqrt{\frac{2}{\pi}} \exp\left(-\frac{r^2}{2\sigma^2}\right), \quad (3.32)$$

489 490

488

and $\mathbf{R}^* = \nabla \mathbf{J}^*$ is the FCM dipole Green's function evaluated with the parameter σ_* .

The particle's translational and angular velocities, U_n and Ω_n , are obtained from a volumeweighted average of the local fluid velocity and vorticity

494
$$\boldsymbol{U}_n = \int_{V_F} \boldsymbol{u} \,\Delta(\boldsymbol{r}_n) \mathrm{d}V, \qquad \boldsymbol{\Omega}_n = \frac{1}{2} \int_{V_F} [\nabla \times \boldsymbol{u}] \Delta^*(\boldsymbol{r}_n) \mathrm{d}V. \tag{3.33}$$

The Gaussian parameters, σ and σ^* are calibrated to recover the correct Stokes drag, $F = 6\pi a \mu U$, and viscous torque, $T = 8\pi a^3 \mu \Omega$, of an isolated particle (Maxey & Patel 2001; Lomholt & Maxey 2003), leading to

498
$$\frac{\sigma}{a} = \frac{1}{\sqrt{\pi}} \approx 0.5641, \qquad \frac{\sigma_*}{a} = \frac{1}{(6\sqrt{\pi})^{1/3}} \approx 0.4547.$$
 (3.34)

The rigidity of the particle is similarly weakly enforced by imposing that the volumeaveraged strain rate \boldsymbol{E}_n over the envelope of particle *n* vanishes:

501
$$\boldsymbol{E}_n = \frac{1}{2} \int_{V_F} [\nabla \boldsymbol{u} + (\nabla \boldsymbol{u})^{\mathrm{T}}] \Delta^*(\boldsymbol{r}_n) \mathrm{d} \boldsymbol{V} = \boldsymbol{0}, \qquad (3.35)$$

which determines the stresslet S_n induced by particle *n*. Note that unlike forces and torques which are typically set by external or inter-particle potentials, the stresslets result from the constraint on the flow given by Eq. (3.35) and, consequently, need to be solved for as part of the general flow problem. The resulting linear system for the unknown stresslet coefficients is solved directly or iteratively, with the conjugate gradients method, depending on the number of particles considered (Lomholt & Maxey 2003; Yeo & Maxey 2010). In the following, we consider pairs of particles (see Section 4) and therefore use direct inversion.

Note that the averaging envelopes used to recover the translational and rotational velocities, Δ_n and Δ_n^* , are exactly the same as the spreading operators in (3.26), all of them Gaussian functions. As a result, the spreading and averaging operators are adjoints to one another. Also note that only two envelope lengths are required for the hydrodynamic problem: σ and σ_* . In contrast, the new reactive FCM extension presented in Section 3.1 uses spreading and averaging operators that are not adjoint. To recover the first (3.14) and second (3.16)

moments of concentration we have two non-Gaussian averaging envelopes (Δ^P and Δ^S), that differ from the Gaussian spreading envelopes (Δ^M and Δ^D) in (3.7). While having adjoint

operators is crucial in hydrodynamic FCM to satisfy the fluctuation-dissipation balance, the

518 lack of adjoint properties for the Laplace problem does not raise any issue in the deterministic

519 setting.

520 3.2.2. Active hydrodynamic FCM

In recent years, FCM has been extended to handle suspensions of active particles, such 521 522 as microswimmers. In addition to undergoing rigid body motion in the absence of applied forces or torques, active and self-propelled particles are also characterized by the flows 523 they generate. These flows can be incorporated into FCM by adding an appropriate set of 524 regularized multipoles to the Stokes equations. This problem was solved previously for the 525 classical squirmer model (Delmotte et al. 2015), a spherical self-propelled particle that swims 526 527 using prescribed distortions of its surface. In the most common case where radial distortions are ignored, the squirmer generates a tangential slip velocity on its surface, just like phoretic 528 529 particles, which can be expanded into spherical harmonics mode (Blake 1971; Pak & Lauga 530 2014). Consistently with the phoretic problem presented above, only the first two modes are included in the following. 531

The FCM force distribution produced by *N* microswimmers self-propelling with a surface slip velocity is given by

534
$$f(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[\boldsymbol{S}_{n} \cdot \nabla \Delta^{*}(\boldsymbol{r}_{n}) + \boldsymbol{S}_{n}^{a} \cdot \nabla \Delta(\boldsymbol{r}_{n}) + \boldsymbol{H}_{n}^{a} \nabla^{2} \Delta^{*}(\boldsymbol{r}_{n}) \right], \quad (3.36)$$

where S_n^a is the active stresslet and H_n^a is the active potential dipole associated to the swimming disturbances of swimmer *n*. The latter is defined as

537 $H_n^a = -2\pi a^3 U_n^a,$ (3.37)

where U_n^a is the swimming velocity arising from the slip velocity on the swimmer surface u^s (2.7). Note that the rigidity stresslet S_n is included in (3.36) to enforce the absence of deformation of the swimmers, Eq. (3.35). The resulting velocity field reads

541
$$\boldsymbol{u}(\boldsymbol{r},t) = \sum_{n=1}^{N} \left[\boldsymbol{S}_{n} : \boldsymbol{R}^{*}(\boldsymbol{r}_{n}) + \boldsymbol{S}_{n}^{a} : \boldsymbol{R}(\boldsymbol{r}_{n}) + \boldsymbol{H}_{n}^{a} \cdot \boldsymbol{A}^{*}(\boldsymbol{r}_{n}) \right], \qquad (3.38)$$

where **R** is the FCM dipole Green's function evaluated with the parameter σ instead of σ_* . The second order tensor **A**^{*} is the FCM Green's function for the potential dipole

544
$$\boldsymbol{A}^{*}(\boldsymbol{r}) = \frac{1}{4\pi r^{3}} \left[\boldsymbol{I} - \frac{3\boldsymbol{r}\boldsymbol{r}}{r^{2}} \right] \operatorname{erf}\left(\frac{r}{\sigma_{*}\sqrt{2}}\right) - \frac{1}{\mu} \left[\left(\boldsymbol{I} - \frac{\boldsymbol{r}\boldsymbol{r}}{r^{2}} \right) + \left(\boldsymbol{I} - \frac{3\boldsymbol{r}\boldsymbol{r}}{r^{2}} \right) \left(\frac{\sigma_{*}}{r}\right)^{2} \right] \Delta^{*}(r). \quad (3.39)$$

545 The particles' velocity, angular velocity and mean strain rate are then computed as

546
$$\boldsymbol{U}_n = \boldsymbol{U}_n^a - \boldsymbol{W}_n + \int_{V_F} \boldsymbol{u} \,\Delta(\boldsymbol{r}_n) \mathrm{d}V, \qquad (3.40)$$

547
$$\boldsymbol{\Omega}_n = \boldsymbol{\Omega}_n^a + \frac{1}{2} \int_{V_F} [\nabla \times \boldsymbol{u}] \Delta^*(\boldsymbol{r}_n) \mathrm{d}V, \qquad (3.41)$$

548
549
$$\boldsymbol{E}_n = -\boldsymbol{K}_n + \frac{1}{2} \int_{V_F} [\nabla \boldsymbol{u} + (\nabla \boldsymbol{u})^{\mathrm{T}}] \Delta^*(\boldsymbol{r}_n) \mathrm{d}V = \boldsymbol{0}, \qquad (3.42)$$

where the active swimming velocities U_n^a and rotation rates Ω_n^a correspond to the intrinsic velocities of particle *n*, if it was alone (i.e. in the absence of external flows or other particles), and W_n and K_n are defined as

553
$$\boldsymbol{W}_n = \int_{V_F} (\boldsymbol{H}_n^a \cdot \boldsymbol{A}^*(\boldsymbol{r}_n)) \Delta(\boldsymbol{r}_n) \mathrm{d}V, \qquad (3.43)$$

554
555
$$\boldsymbol{K}_{n} = \frac{1}{2} \int_{V_{F}} [\boldsymbol{S}_{n}^{a} : \nabla \boldsymbol{R}(\boldsymbol{r}_{n}) + (\boldsymbol{S}_{n}^{a} : \nabla \boldsymbol{R}(\boldsymbol{r}_{n}))^{\mathrm{T}}] \Delta^{*}(\boldsymbol{r}_{n}) \mathrm{d}V, \qquad (3.44)$$

and are included to subtract away the spurious self-induced velocities and local rates of strain arising from the integration of the full velocity field \boldsymbol{u} , which already includes the contribution of \boldsymbol{H}_{n}^{a} and \boldsymbol{S}_{n}^{a} (Delmotte *et al.* 2015).

559 3.3. Diffusio-phoretic FCM

At this point, we have described our new reactive FCM framework and have reviewed the 560 key aspects of the existing active hydrodynamic FCM. These two steps provide respectively 561 the solution (i) for the concentration field and its moments at the surface of each particles 562 in terms of their position and orientation, and (ii) the particles' velocity in terms of their 563 active hydrodynamic characteristics, i.e. their intrinsic velocities and stresslet, U_n^a , Ω_n^a and 564 \mathbf{S}_{a}^{a} . To solve for the full diffusio-photetic problem (i.e. obtain the velocity of the particle 565 in terms of their position and orientation), these quantities must be determined from the 566 chemical environment of the particles. The following section details how to obtain these 567 active characteristics from the output of the reactive problem and provides algorithmic 568 details on the numerical implementation. This new diffusio-phoretic framework based on the 569 570 Force Coupling Method is referred to as DFCM hereafter.

571 3.3.1. DFCM: coupling Reactive and Hydrodynamic FCM

The active swimming speed U_n^a involved in the potential dipole H_n^a , (3.37), is the phoretic response of particle *n* to the chemical field, if it was hydrodynamically isolated (i.e. neglecting the presence of other particles in solving the swimming problem). It thus includes its selfinduced velocity (i.e. the response to the concentration contrasts induced by its own activity) and the drift velocity induced by the activity of the other particles. The swimming problem for a hydrodynamically-isolated particle in unbounded flows can be solved directly using the reciprocal theorem (Stone & Samuel 1996), and using the definition of the phoretic slip flow

579
$$U_n^a = -\langle \boldsymbol{u}^s \rangle_n = -\langle \boldsymbol{M} \nabla_{\parallel} c \rangle_n. \tag{3.45}$$

After substitution of the mobility distribution at the surface of particle n, Eq. (2.9), using a truncated multipolar expansion of the surface concentration on particle n (up to its secondorder moment) and integration by parts, the intrinsic swimming velocity is obtained in terms of the first two surface concentration moments (see Appendix B for more details)

584
$$\boldsymbol{U}_{n}^{a} = -\frac{2\overline{M}_{n}}{a}\langle c\boldsymbol{n}\rangle_{n} - \frac{15M_{n}^{*}}{8a} \Big[2\langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{I}/3)\rangle_{n} \cdot \boldsymbol{p}_{n} + \big(\langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{I}/3)\rangle_{n} : \boldsymbol{p}_{n}\boldsymbol{p}_{n}\big) \boldsymbol{p}_{n} \Big].$$
(3.46)

585 Similarly, the active stresslet S_n^a , is defined as in Eq. (2.8),

589

$$\mathbf{S}_{87}^{a} = -10\pi a^{2} \langle \boldsymbol{n}\boldsymbol{u}^{s} + \boldsymbol{u}^{s}\boldsymbol{n} \rangle_{n} = -10\pi a^{2} \langle \boldsymbol{M}(\boldsymbol{n}\nabla_{||}\boldsymbol{c} + (\nabla_{||}\boldsymbol{c})\boldsymbol{n}) \rangle_{n}, \qquad (3.47)$$

and rewrites in terms of the moments of concentration (see Appendix B for more details)

$$\boldsymbol{S}_{n}^{a} = -60\pi a \overline{M}_{n} \langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{I}/3) \rangle_{n} + \frac{15\pi a M_{n}^{*}}{2} \Big[(\langle c\boldsymbol{n} \rangle_{n} \cdot \boldsymbol{p}_{n}) (\boldsymbol{I} - \boldsymbol{p}_{n} \boldsymbol{p}_{n}) - \langle c\boldsymbol{n} \rangle_{n} \boldsymbol{p}_{n} - \boldsymbol{p}_{n} \langle c\boldsymbol{n} \rangle_{n} \Big].$$
(3.48)

16

Finally, the active rotation Ω_n^a , Eq. (2.7), is obtained in terms of the moments of concentration and the mobility contrast (see Appendix B)

$$\boldsymbol{\Omega}_{n}^{a} = \frac{9M_{n}^{*}}{4a^{2}} \boldsymbol{p}_{n} \times \langle c\boldsymbol{n} \rangle_{n}.$$
(3.49)

For uniform mobility, the swimming velocity and stresslet are directly related to the first and second of surface concentrations, but non-uniform mobility introduces a coupling of the different concentration moments. Here, the surface concentration is expanded up to its second-order moment only.

In our regularized approach, the surface concentration moments appearing in the previous equations will conveniently be computed as weighted volume averages over the entire domain V_F as detailed in Eqs. (3.14) and (3.16).

600

Computing the second moment of concentration however requires an additional step: as 601 detailed in Section 3.1.5, the second moment of concentration in an external field arises 602 from the second gradient of that external field, and includes both an externally-induced 603 component $\langle c_E(nn - I/3) \rangle_n$ (i.e. the moment of that externally-imposed field) and a self-604 induced component which corresponds to the second moment of the induced field generated 605 by the particle to ensure that the correct flux boundary condition is satisfied at the particles' 606 surface. For a chemically-inert particle ($\alpha = 0$), the self-induced contribution is obtained 607 exactly as $\langle c_I^o(\mathbf{nn} - \mathbf{I}/3) \rangle_n = \frac{2}{3} \langle c_E(\mathbf{nn} - \mathbf{I}/3) \rangle$. 608

Our representation of the particles in the chemical problem is however truncated at the dipole level, Eq. (3.9), and as a result, the quadrupolar response of the particle to the external field can not be accounted for directly. To correct for this shortcoming, we first compute the external second moment produced by the other particles on particle *n* using (3.16) and (3.9), and multiply the resulting value by 5/3 to account for the full second moment induced by the concentration field indirectly.

Finally, the particles are themselves active and may generate an intrinsic quadrupole. Its effect on the second surface concentration moment can be added explicitly in terms of the second activity moment, so that the total second moment on particle n is finally evaluated as

618
$$\langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{l}/3) \rangle_{\boldsymbol{n}} = \frac{5}{3} \{ c_E(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{l}/3) \}_{\boldsymbol{n}} + \frac{a}{D} \langle \alpha(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{l}/3) \rangle_{\boldsymbol{n}}.$$
(3.50)

In summary, at a given time step, the particles' velocities are obtained from their 619 instantaneous position and orientation as follows. The first two surface concentration 620 moments are first obtained using our new reactive FCM framework by solving the Poisson 621 problem, Eq. (3.7). These moments are then used to compute the phoretic intrinsic translation 622 and rotation velocities, Eqs. (3.46) and (3.49), as well as the active stresslets and potential 623 dipoles, Eqs. (3.48) and (3.37). The Stokes equations forced by the swimming singularities 624 Eq. (3.36), and subject to the particle rigidity constraint, Eq. (3.42), are finally solved to 625 obtain the total particle velocities, Eqs. (3.40)–(3.41). 626

627 3.3.2. Numerical details

The volume integrals required to compute the concentration moments and the hydrodynamic quantities are performed with a Riemann sum on cartesian grids centred at each particle position. To ensure a sufficient resolution, the grid size, Δx , is chosen so that the smallest envelope size σ_D satisfies $\sigma_D = 1.5\Delta x = 0.3614a$, which corresponds to roughly 4 grid points per radius.Owing to the fast decay of the envelopes, the integration domain is truncated so that the widest envelope (that with the largest σ) essentially vanishes on the boundary of the domain, $\Delta(r) < \gamma = 10^{-16}$, which, given the grid resolution, requires 39 integration



Figure 5: Validation cases considered: a) Case A: Isotropic particles with uniform mobility, b) Case B: Hemispheric Janus particles with uniform mobility, c) Case C: Hemispheric Janus particles with non-uniform mobility. In each case, both particles have exactly the same orientation and phoretic properties and their dimensionless separation is noted *d*.

points in each direction. Doing so, the numerical integrals yield spectral accuracy. Setting instead $\gamma = \epsilon = 10^{-10}$, where ϵ is the relative tolerance for the polarity in the iterative procedure, Eq. (3.13), reduces that number to 31 integration points along each axis while keeping a spectral convergence.

639 4. Results

In this section, we evaluate the accuracy of the present novel DFCM framework in three different canonical or more generic configurations involving pairs of isotropic and Janus phoretic particles, as shown in figure 5. The particles' motion are restricted to a plane within a three-dimensional unbounded domain for the sake of clarity in visualizing the results.

In this validation process, DFCM is compared with three existing methods providing 644 either a complete or approximate solution of the problem. The simplest one, the Far-645 Field Approximation model (Soto & Golestanian 2014; Varma & Michelin 2019), relies 646 on a multipolar expansion of the reactive and hydrodynamic singularities up to the dipole 647 level generated by each particles, but neglects the finite size of the particles (i.e. without 648 reflections on the polarity and rigidity stresslet). Our results are also compared to the complete 649 (exact) solution of the problem (i.e. solving the complete hydrodynamic and chemical fields 650 regardless of the particles' distance, accounting for their finite size). For axisymmetric 651 problems, this solution is obtained semi-analytically using the Bi-Spherical Coordinates 652 approach (Michelin & Lauga 2015; Reigh & Kapral 2015), whose accuracy is only limited 653 by the number of Legendre modes used to represent the solution. For non-axisymmetric 654 configurations, the complete solution is obtained numerically using the regularized Boundary 655 Element Method (Montenegro-Johnson et al. 2015). These reference solutions are referred 656 to in the following, as FFA, BSC and BEM respectively. 657

658

4.1. Isotropic particles - axisymmetric configuration

The first configuration, Case A (figure 5a), consists of two identical isotropic particles with uniform activity and mobility ($\alpha_n^F = \alpha_n^B = 1$, $M_n^F = M_n^B = 1$) separated by a distance *d* along the *x*-axis (Varma *et al.* 2018; Nasouri & Golestanian 2020*b*). Phoretic particles require an asymmetry in their surface concentration field to self-propel (Golestanian *et al.* 2007), so that an isolated isotropic particle can not swim. In the configuration considered here however,



Figure 6: Case A: a) concentration field for d = 1 (upper half: DFCM, lower half: BSC), b) first moment of concentration $\langle cn \rangle_X$, c) second moment of concentration $\langle c(nn - l/3) \rangle_{xx}$, d) velocity U_x . The black lines (and markers) correspond to particle 1 and the light green ones to particle 2. The triangle markers correspond to DFCM, the solid lines correspond to BSC, while the dashed lines to FFA. The inset shows the absolute values in logarithmic scale and the corresponding decay. The surface averages $\langle ... \rangle$ where used for BSC and FFA, while the volume average $\{...\}$ for DFCM. All the omitted components of $\langle cn \rangle$, $\langle c(nn - l/3) \rangle$, and U are zero.

the concentration gradient produced by a second isotropic particle introduces the required asymmetry to generate motion along the x-axis.

Figure 6(a) shows the concentration field induced by two isotropic particles for d = 1. 666 The DFCM solution (upper panel) is in good agreement with BSC (lower panel), except near 667 the particles' boundaries in the gap, where the low-order multipolar expansion of DFCM 668 and inaccurate resolution of the particle's surface underestimates the concentration field. 669 The increase in concentration between the particles is a direct result of the confinement 670 between their active surfaces. It produces a surface concentration gradient and phoretic slip 671 flow on each particle's boundary that pumps the fluid toward this high concentration zone 672 and thus drives the particles away from each other (figure 6d). This effect is magnified as 673 d is reduced, leading to higher particle velocities and higher moments of concentration for 674 shorter distances. 675

The evolution with interparticle distance of the particles' polarity, a measure of the net concentration gradient over their surface, is shown on figure 6(b) as obtained with the DFCM, BSC and FFA approaches. While both FFA and DFCM are in good agreement with the exact solution (BSC) even for relatively small distances, the DFCM approach provides a

noticeable improvement over the cruder representation of FFA in the near field (d < 1), where 680 the iterative corrections for the mutually-induced polarity (3.13) contribute significantly. The 681 expected decay of the polarity as $1/d^2$ is recovered (figure 6b, inset) in all three cases 682 as the dominant contribution to the polarity is proportional to the gradient of the leading 683 order monopolar concentration field. Similar results are obtained for the second moment of 684 concentration (figure 6c), with an expected $1/d^3$ -decay proportional to the second gradient 685 of the leading order of the concentration field. We note that isotropic particles do not drive 686 any flow when isolated (and therefore do not have any hydrodynamic signature), but acquire 687 a net stresslet as a result of their chemical interactions, behaving as pusher swimmers. 688

The resulting translational velocities are shown in figure 6(d): again, DFCM performs better 689 than FFA in the range d < 2 since it additionally considers the hydrodynamic interactions 690 of the particles (e.g. the effect of the rigidity constraint through the rigidity stresslet, see 691 Eq. (3.36) in addition to the active flows, while FFA does not. Such discrepancy arises from 692 the accumulated errors in the successive truncated multipolar expansions: using the BSC 693 solution as a reference, we can determine that for near-field interactions of the two particles 694 695 around the 25% - 30% of the DFCM error comes from the Reactive FCM approximation (3.7), while the other 70% - 75% comes from the Hydrodynamical FCM approximation (3.36). 696 As expected, in the far-field limit, the velocity decays as $1/d^2$ since it is proportional to the 697 polarity to leading order and this dominant contribution does not involve any hydrodynamic 698 interactions: these would correspond at leading order to the contribution of the stresslet 699 generated by the presence of the other particles and decay as $1/d^5$ (Varma & Michelin 2019). 700

701

4.2. Janus particles - axisymmetric configuration

Our second configuration of interest, Case B (figure 5b), focuses on Janus particles, which are 702 currently the most commonly-used configuration for self-propelled phoretic particle in both 703 experiments and theoretical models. Their motion stems from the self-induced concentration 704 gradients produced by the difference in activity between their two hemispheres. Here we 705 consider two identical Janus particles with uniform mobility $(M_n^F = M_n^B = 1)$, a passive front cap $(\alpha_n^F = 0)$ and an active back cap $(\alpha_n^B = 1)$, leading to a self-propulsion velocity of $U^{\infty} = \frac{1}{4}e_x$ (Golestanian *et al.* 2007). We further focus here on an axisymmetric setting where 706 707 708 the particles' orientation coincides with the line connecting their centers, for which an exact 709 semi-analytic solution of the complete hydrochemical problem is available using bispherical 710 711 coordinates (BSC) as exploited in several recent studies (Varma & Michelin 2019; Nasouri & Golestanian 2020a). Furthermore, both particles point in the same direction so that, when 712 far enough apart, they swim at the same velocity in the same direction. 713

Figure 7(a) shows the concentration field for d = 1: again, DFCM closely matches the BSC predictions. Here, both particles pump fluid from their front to their active back cap where an excess solute concentration is produced, and therefore move along the $+e_x$ direction. As the interparticle distance shortens, the concentration increases in the gap, leading to enhanced (resp. decreased) surface gradients on the leading (resp. trailing) particle.

This physical intuition is confirmed by the evolution of the concentration polarity with the 719 interparticle distance (figure 7b). The polarity matches that of an isolated particle $\langle cn \rangle^{\infty}$ = 720 $-\frac{1}{2}e_x$ for large distances $d \gg 1$, and is increased in magnitude for particle 1 (leader) while its 721 722 magnitude decreases for particle 2 (follower) as d is reduced. The DFCM solution remains in close agreement with BSC for all distances (even down to a tenth of a radius), in particular 723 capturing the asymmetric effect of the interaction on the two particles. In contrast, FFA 724 predicts a symmetric progression of the polarity, leading to large discrepancies for d < 3. A 725 similar behaviour is observed for the second moment (figure 7c), except for particle 1 which 726 727 is underestimated by DFCM in the near field (d < 1). We note that although isolated Janus particles with uniform mobility behave as neutral swimmers (exerting no force dipole or 728



Figure 7: Case B: a) concentration field for d = 1 (upper half: DFCM, lower half: BSC), b) first moment of concentration $\langle cn \rangle_X$, c) second moment of concentration $\langle c(nn - l/3) \rangle_{XX}$, d) velocity U_X . The black lines (and markers) correspond to particle 1 and the light green ones to particle 2. The triangle markers correspond to DFCM, the solid lines correspond to BSC, while the dashed lines to FFA. The inset shows the absolute values in logarithmic scale and the corresponding decay. The surface averages $\langle ... \rangle$ where used for BSC and FFA, while the volume average $\{...\}$ for DFCM. All the omitted components of $\langle cn \rangle$, $\langle c(nn - l/3) \rangle$, and U are zero.

active stresslet on the fluid), their interaction leads to both of them acting as effective pushers on the fluid (negative stresslet, see Eq. (2.8)).

The velocity matches that of an isolated particle when $d \gg 1$, and the corrections 731 introduced by the particles' interaction scale as $1/d^2$, as a result of the dominant phoretic 732 repulsion (as for case A): all three methods are able to capture that property (see figure 7b,d, 733 inset). Similarly, the second moment of surface concentration decreases as $1/d^3$ (figure 7c). 734 As d is reduced, the combined effects of strong phoretic repulsion and hydrodynamic coupling 735 (including the repulsion by the active stresslet) slow down and may even eventually reverse 736 737 the swimming direction of particle 2 (figure 7d). Both our FCM solution and the FFA prediction show a qualitative agreement with the full solution (BSC) and predict the increase 738 in velocity for the leading particle, while the trailing particle is slowed down. However, they 739 fail to predict the reversal of particle 2's velocity observed in the full solution, although 740 DFCM exhibits an appreciable improvement over FFA in the near field. A possible reason for 741 742 this may be found in a dominant role of the lubrication layer separating the particles which is not well resolved in either approximation. 743



Figure 8: Case C: a) DFCM concentration field for d = 1, b) velocity U_x , c) velocity U_y , d) angular velocity Ω_z . The black lines (and markers) correspond to particle 1 and the light green ones to particle 2. The triangle markers correspond to DFCM, the solid lines correspond to BEM, while the dashed lines to FFA. The inset shows the absolute values in logarithmic scale and the corresponding decay.

744

4.3. Janus particles - asymmetric configuration

Case B was still highly symmetric and further considered only uniform mobility which is 745 known to affect the hydrodynamic signature of the particle significantly (Lauga & Michelin 746 2016). In our third and final configuration, Case C (figure 5c), we consider a more generic interaction of two identical Janus particles with non-uniform mobility ($\alpha_n^F = 0, \alpha_n^B = 1$, $M_n^F = 0, M_n^B = 1$) positioned at an angle $\pi/4$ relative to x axis. Surface mobility results 747 748 749 from the differential short-range interaction of solute and solvent molecules with the particle 750 surface and, as such, is an intrinsic property of the particle's surface coating and may thus 751 differ between the two caps of a Janus particle. For these particles, when isolated, the 752 non-dimensional self-propulsion velocity is given by $U^{\infty} = \frac{1}{8}e_x$ (Golestanian *et al.* 2007). 753 The convenient bispherical coordinate approach is not usable in this non-axisymmetric 754 setting, and although an extension to generic interactions of Janus particles is possible 755 using full bispherical harmonics (Sharifi-Mood et al. 2016), it is sufficiently complex that 756 direct numerical simulations using BEM proves in general more convenient, although the 757 discontinuity of the mobility at the equator may introduce numerical errors, due to the 758 singularity of the surface concentration gradient for a Janus particle (Michelin & Lauga 759 760 2014). In the following, we therefore compare our DFCM predictions with the solution obtained using BEM and the prediction of the far-field analysis (FFA). 761

The asymmetric concentration field obtained with DFCM for that configuration when 762 d = 1 is shown on figure 8(a). Besides their intrinsic self-propulsion along $+e_x$ due to their 763 self-generated surface chemical polarity, the accumulation of solute in the confined space 764 between the particles introduces a phoretic repulsion along their line of centers (as for case 765 B), leading to an enhancement (resp. reduction) of both components of the velocity (U_x and 766 $U_{\rm v}$) for particle 1 (resp. particle 2). This behaviour is well-captured by all three methods 767 (figure 8b-c). Additionnally, in the present configuration (case C), the mobility is non uniform: 768 specifically here, we consider the case where the surface mobility of the front hemisphere is 769 zero, so that only the back hemisphere generates a phoretic slip. As a result of the arrangement 770 of the particles, the dominant slip along the surface of particle 1 (resp. particle 2) is therefore 771 counter-clockwise (resp. clockwise) leading to a negative (resp. positive) rotation velocity 772 Ω_{z} for that particle. This rotation rate is proportional to the polarity, and therefore decays as 773 774 $1/d^2$ in the far field. These intuitive trends are confirmed by the results of all three methods on figure 8(b-d). 775

As for case B, when the interparticle distance d is reduced, these effects become more 776 pronounced and the results obtained with DFCM for the translation velocity are in that regard 777 slightly better than the predictions of FFA. However, FFA predicts a symmetric evolution 778 of Ω_{τ} with distance, while BEM, the most accurate solution, shows that particle 1 rotates 779 slower than particle 2 for d < 10, and changes direction in the near field d < 0.2. DFCM is 780 able to capture this nontrivial and asymmetric evolution of the rotation velocity, but fails to 781 capture the direction reversal of particle 1; as for case B, this may stem from the inability 782 of DFCM to resolve correctly the lubrication flows within the thin fluid gap between the 783 particles. 784

785

Nevertheless, over all three cases considered and in particular in the most generic setting 786 of Janus particles with non-uniform mobility in non-axisymmetric settings, our results 787 show the importance of the proper resolution of higher order hydro-chemical multipolar 788 signatures (e.g. induced polarities and rigidity stresslets) in order to capture accurately 789 non-trivial feature of the hydro-chemical interactions between particles. DFCM may not 790 be able to resolve the details of the chemical and hydrodynamic fields in the gap between 791 the surface of the particles when they are close to each other (e.g. $d \leq 0.5$) as it does 792 not actually represent the exact position of the surface. Yet, this new numerical approach 793 794 offers significant improvements in capturing such complex effects both qualitatively and quantitatively in comparison with simpler analytical or numerical models, while providing a 795 significant reduction in complexity in comparison with detailed numerical simulations such 796 as BEM, opening significant opportunities for the numerical analysis of larger number of 797 particles and suspension dynamics. 798

799 5. Discussion

In this work, we presented a generalization called Diffusiophoretic Force Coupling Method 800 (DFCM) of the approach of the hydrodynamic FCM in order to compute hydro-chemical 801 interactions within reactive suspensions of Janus particles with non-uniform surface activity 802 and mobility. Following the standard hydrodynamic FCM, we rely on a truncated regularized 803 multipolar expansion at the dipole level to solve the Laplace problem for the reactant 804 concentration field, and its moments at the particle surface. While the monopole is directly 805 obtained from the prescribed fluxes on the swimmer surface, the dipole is found iteratively 806 by accounting for the effect of other particles on their polarity. Instead of using surface 807 808 operators, which are difficult to handle on Eulerian grids, our method relies on spectrally convergent weighted volume averages to compute successive concentration moments. Unlike 809

standard FCM, the averaging envelopes are non Gaussian as their weight is shifted toward the 810 particle's surface and thus differ from the Gaussian spreading envelopes associated with each 811 singularity. The first two moments of concentration around the particle are directly related to 812 the intrinsic phoretic velocity and rotation of the particles (i.e. those obtained for an isolated 813 particle experiencing the same hydrodynamic surface slip in an unbounded domain) but 814 also to the singularities characterizing their hydrodynamic signatures, i.e. an intrinsic active 815 816 stresslet and a potential dipole. These multipoles are then used as inputs for the solution of the hydrodynamic (swimming) problem, solved using the existing hydrodynamic FCM 817 framework to obtain the total particle velocities. 818

Even though our approximate method does not resolve the particle surface exactly (and is 819 as such unable to capture lubrication or strong confinement effects), its predictions for the 820 dynamics of two particles compare well with analytical or accurate numerical solutions for 821 distances larger than half a radius ($d \gtrsim 0.5$), which is relevant for dilute and semi-dilute 822 suspensions. Most importantly, in all the results presented above, DFCM provides significant 823 improvements over far-field models that neglect mutually-induced polarities and rigidity 824 stresslets. Our case study has shown the importance of properly resolving these dipolar 825 826 singularities to capture non-trivial hydro-chemical interactions between particles.

Although the present work purposely focuses on the presentation of the framework 827 and detailed validation on pairwise interactions of phoretic particles, our diffusio-phoretic 828 framework readily generalizes to N particles. A remarkable feature of FCM is that the 829 spreading and averaging operations are volume-based and independent of the Stokes and 830 831 Laplace solvers. Instead of using Green's functions for specific geometries, the reactant concentration c and fluid velocity u can be solved for with any numerical method (e.g. 832 finite volume, spectral methods) on an arbitrary domain where the FCM spreading and 833 averaging operations are performed on the fixed computational grid (Maxey & Patel 2001; 834 Liu et al. 2009; Yeo & Maxey 2010). As shown in previous work (Delmotte et al. 2015), the 835 corresponding cost scales linearly with the particle number O(N), while Green's function-836 based methods, such as Stokesian Dynamics (Brady & Bossis 1988) and the method of 837 838 reflections (Varma & Michelin 2019), are restricted to simple geometries and require sophisticated techniques to achieve similar performances instead of their intrisic quadratic 839 scaling $O(N^2)$ (Liang et al. 2013; Fiore & Swan 2019; Yan & Blackwell 2020). In addition 840 to improving far-field models, our method therefore offers a scalable framework for large 841 scale simulations of reactive particles. We will use these capacities to study their collective 842 motion and characterize their macroscopic rheological response. 843

Despite its specific focus on the modelling of hydrochemical interactions within phoretic 844 suspensions, the present analysis demonstrates how the fundamental idea of the original Force 845 Coupling Method can be extended and applied to other fields of physics. In such an approach 846 the elliptic Stokes equations are solved over the entire domain (instead of the multiply-847 connected fluid domain outside the particles) by introducing regularized forcings whose 848 support is calibrated to account for the particle finite size and whose intensity is determined 849 to account for a weak form of the boundary condition. For the chemical diffusion problem 850 considered here, this amounts to (i) replacing a Laplace problem by a Poisson equation, (ii) 851 852 calibrating the support of the spreading operators to match benchmark properties for a single particle and (iii) determining the forcing intensity by projecting the Neumann-type boundary 853 condition on the particle surface onto a localized support function of appropriate shape (e.g. 854 Gaussian or annular). This approach can readily be adapted for solving diffusion problems 855 with more general (Dirichlet or mixed) boundary conditions, as encountered for more detailed 856 857 chemical activity of reactive particles (Michelin & Lauga 2014; Tatulea-Codrean & Lauga 2018) or in bubble growth/dissolution problems (Michelin et al. 2019), but also to other 858

physical phenomena driven by elliptic equations, such as electromagnetic interactions of particles (Keaveny & Maxey 2008).

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865 Appendix A. Determining the source intensities

We consider here a single active particle bounded by a surface S. The concentration field outside S (in the fluid) satisfies Laplace's equation, and its value anywhere in the fluid domain can therefore be obtained in terms of its value and normal flux on S as

869
$$c(\mathbf{r}) = \frac{1}{4\pi} \int_{S} \left[c(s)\mathbf{n} \cdot \frac{(\mathbf{r} - s)}{|\mathbf{r} - s|^{3}} + \left(-\frac{\partial c(s)}{\partial n} \right) \frac{1}{|\mathbf{r} - s|} \right] \mathrm{d}S. \tag{A1}$$

where s = an, is a vector of the surface of the particle. Far from the particle (i.e. $|r| \gg |s|$), and using the following Taylor expansion for $|r - s|^{-n}$,

872
$$\frac{1}{|\boldsymbol{r}-\boldsymbol{s}|^n} \approx \frac{1}{r^n} \left[1 + n\left(\frac{\boldsymbol{s}\cdot\boldsymbol{r}}{r^2}\right) + n\left(\frac{n}{2}+1\right)\left(\frac{\boldsymbol{s}\cdot\boldsymbol{r}}{r^2}\right)^2 + \dots \right], \tag{A2}$$

the concentration field can be expanded in terms of a series of singular multipoles, namely a monopole of intensity q^M , a dipole of intensity q^D , (and up to the desired order of approximation):

876
$$c(\mathbf{r}) = \frac{q^M}{4\pi r} + \frac{q^D \cdot \mathbf{r}}{4\pi r^3} + \dots$$
(A 3)

877 where the intensities are obtained as:

878
$$q^{M} = \int \left(-\frac{\partial c(s)}{\partial n}\right) \mathrm{d}S,\tag{A4}$$

880
$$\boldsymbol{q}^{D} = a \int \left(-\frac{\partial c(s)}{\partial n}\boldsymbol{n}\right) \mathrm{d}S + \int c(s)\boldsymbol{n} \,\mathrm{d}S. \tag{A5}$$

Substitution of the boundary condition Eq. (2.1) leads to the result in Eq. (3.12).

882 Appendix B. Intrinsic phoretic velocities and stresslet

The intrinsic phoretic velocity of a particle (i.e. its swimming speed in the absence of any hydrodynamic interactions or outer flow) is defined in Eq. (2.7). Using the slip velocity definition in Eq. (2.3) and the mobility distribution as in Eq. (2.9), we obtain:

886
$$\boldsymbol{U}_{n}^{a} = -\langle \boldsymbol{u}_{s} \rangle_{n} = -\overline{M}_{n} \langle \nabla_{\parallel} c \rangle_{n} - M_{n}^{*} \langle \operatorname{sign}(\boldsymbol{p} \cdot \boldsymbol{n}) \nabla_{\parallel} c \rangle_{n}.$$
(B1)

⁸⁸⁷ Integrating by parts the surface averaging operators we arrive to:

888
$$\boldsymbol{U}_{n}^{a} = -\frac{2M_{n}}{a} \langle c\boldsymbol{n} \rangle_{n} + \frac{M_{n}^{*}\boldsymbol{p}_{n}}{a} \langle c \rangle_{n}^{\text{eq}} - \frac{M_{n}^{*}}{a} \Big(\langle c\boldsymbol{n} \rangle_{n}^{+} - \langle c\boldsymbol{n} \rangle_{n}^{-} \Big), \qquad (B 2)$$

where the operators $\langle ... \rangle_n^{\pm}$ refer to the mean value over the front and back caps of particle *n*, respectively, and $\langle ... \rangle_n^{\text{eq}}$ is the line average over the equator of particle *n*. To compute these particular averages, we expand the surface concentration c(n) in terms of its surface moments and truncate the expansion to the first three terms:

893
$$c(\boldsymbol{n}) = \langle c \rangle_n + 3 \langle c\boldsymbol{n} \rangle_n \cdot \boldsymbol{n} + \frac{15}{2} \langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{I}/3) \rangle_n : \boldsymbol{n}\boldsymbol{n}.$$
(B 3)

894 Substitution in Eq. (B 1) then finally provides

895
$$\boldsymbol{U}_{n}^{a} = -\frac{2M_{n}}{a} \langle c\boldsymbol{n} \rangle_{n} - \frac{15M_{n}^{*}}{8a} \langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{l}/3) \rangle_{n} : [\boldsymbol{p}_{n}\boldsymbol{l} + (\boldsymbol{p}_{n}\boldsymbol{l})^{\mathrm{T}_{12}} + \boldsymbol{p}_{n}\boldsymbol{p}_{n}\boldsymbol{p}_{n}], \quad (\mathrm{B}\,4)$$

which can be simplified into Eq. (3.46) using the symmetry and traceless property of nn - 1/3. Following a similar procedure, the intrinsic phoretic angular velocity can be expanded from Eqs. (2.3), (2.7) and (2.9) as

899
$$\mathbf{\Omega}_{n}^{a} = -\frac{3}{2a} \langle \mathbf{n} \times M \nabla_{\parallel} c \rangle_{n} = -\frac{3}{2a} \overline{M}_{n} \langle \mathbf{n} \times \nabla_{\parallel} c \rangle_{n} - \frac{3}{2a} M_{n}^{*} \langle \operatorname{sign}(\mathbf{p} \cdot \mathbf{n}) | \mathbf{n} \times \nabla_{\parallel} c \rangle_{n}, \quad (B 5)$$

and after integration by parts simplifies to:

901
$$\boldsymbol{\Omega}_{n}^{a} = -\frac{3M_{n}^{*}}{2a^{2}} \left(\boldsymbol{p}_{n} \times \langle c\boldsymbol{n} \rangle_{n}^{\mathrm{eq}} \right).$$
(B 6)

902 Substitution of Eq. (B 3) provides the desired expression, Eq. (3.49).

903

The same method can also be applied to determine the intrinsic phoretic stresslet \mathbf{S}_n^a . From its definition in Eq. (2.8) and using Eqs. (2.3) and (2.9), we obtain:

906
$$\boldsymbol{S}_{n}^{a} = -10\pi a^{2} \overline{M}_{n} \langle (\boldsymbol{n} \nabla_{\parallel} c + (\nabla_{\parallel} c) \boldsymbol{n}) \rangle_{n} - 10\pi a^{2} M_{n}^{*} \langle \operatorname{sign}(\boldsymbol{p} \cdot \boldsymbol{n}) (\boldsymbol{n} \nabla_{\parallel} c + (\nabla_{\parallel} c) \boldsymbol{n}) \rangle_{n}$$
(B 7)

907 Integrating by parts the surface averaging operators provides

908
$$\mathbf{S}_{n}^{a} = -60\pi a \overline{M}_{n} \langle c(\mathbf{n}\mathbf{n} - \mathbf{I}/3) \rangle_{n}$$

909
$$+ 10\pi a M_{n}^{*} \Big[\langle c\mathbf{n} \rangle_{n}^{eq} \mathbf{p}_{n} + \mathbf{p}_{n} \langle c\mathbf{n} \rangle_{n}^{eq} - 3 \Big(\langle c(\mathbf{n}\mathbf{n} - \mathbf{I}/3) \rangle_{n}^{+} - \langle c(\mathbf{n}\mathbf{n} - \mathbf{I}/3) \rangle_{n}^{-} \Big) \Big] \quad (B 8)$$

911 Subsitution of Eq. (B 3) provides finally

912
$$\boldsymbol{S}_{n}^{a} = -60\pi a \overline{M}_{n} \langle c(\boldsymbol{n}\boldsymbol{n} - \boldsymbol{I}/3) \rangle_{n} + \frac{15}{2} \pi a M_{n}^{*} \Big[\Big(\langle c\boldsymbol{n} \rangle_{n} \cdot \boldsymbol{p}_{n} \Big) (\boldsymbol{I} - \boldsymbol{p}_{n} \boldsymbol{p}_{n}) - \langle c\boldsymbol{n} \rangle_{n} \boldsymbol{p}_{n} - \boldsymbol{p}_{n} \langle c\boldsymbol{n} \rangle_{n} \Big]$$
913 (B 9)

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