# Explainable Decisions under Incomplete Knowledge with Supports and Weights

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Image: A matrix

#### Introduction

Possibility Theory and Defaults Bipolar Framework with Supports and Weights Interpreting BLFSW in Possibility Theory Conclusion and prospects



- Qualitative and Argumentative decision problem
- Under incomplete knowledge
- Bipolar evaluation
- Bipolar Layered Framework = visual representation
  - Connection between possible knowledge and goals,
  - Explication of a decision choice
- Aim of this proposal:
  - Take into account the notion of support and weight.
  - Make explicit the principles governing decision in possibilistic context

## Possibility Theory

A possibility distribution  $\pi$  :

- $\pi(x) \leq \pi(x')$  : x' is the actual situation is at least as plausible as for x
- $\pi(x) = 0$  : impossibility
- $\pi(x) = 1$  : x is unsurprising or normal

The possibility measure  $\Pi$  of a formula:

•  $\Pi(\varphi) = \max_{\omega \models \varphi} \pi(\omega)$ : how unsurprising the formula is,

• 
$$N(\varphi) = 1 - \Pi(\neg \varphi) = \min_{\omega \models \neg \varphi} (1 - \pi(\omega))$$
 : Dual Necessity Measure



#### Definition

A default rule  $a \rightsquigarrow b = \text{compact way to express a general rule without mentioning its exceptions.}$ 

In Possibility theory  $a \rightsquigarrow b$ : constraint  $\Pi(a \land b) > \Pi(a \land \neg b)$ .

Note:  $\Pi(a \land b) > \Pi(a \land \neg b)$  equivalent to N(b|a) > 0

#### Bipolar Layered Framework with Supports and Weights (BLFSW)

#### Definition (BLFSW)

A Bipolar Layered Framework with Supports and Weights is a tuple  $(\mathcal{P}, \mathcal{I}, \mathcal{S}, pol, \leq, w)$ .

- $\mathcal{P}$ : set of decision principles:  $\mathcal{P} = \{ \varphi \rightsquigarrow g | \varphi \in \mathscr{L}_F, g \in LIT_G \}$
- $\mathcal{I} \subseteq (\mathcal{L}_{F} \times \mathcal{P})$ : set of inhibitors
- $\mathcal{S} \subseteq (\mathcal{L}_F \times \mathcal{P})$ : set of supports
- $pol: \mathcal{V}_G \to \{\oplus, \ominus\}$ : polarity of a goal  $g \in \mathcal{V}_G$ .
- $LIT_G$  is totally ordered by the relation  $\leq$
- $w : \mathcal{I} \cup S \rightarrow ]0, 1]$ : weight function on inhibitors and supports.

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## Example of a BLFSW: Finding an Hotel

An agent wants to find a hotel which is:

- not expensive (e)
- in which she/he can swim (s)
- she/he prefers to avoid crowded hotels (c)

Information about the following attributes:

- "to have a pool" (p)
- "to be a four star hotel" (f)
- "to be in a place where the weather is fine" (w)
- "to propose special offers" (o)

The agent may consider the following principles:

- "a priori when there is a pool the agent can swim"  $(p \rightsquigarrow s)$
- "a priori if the hotel is four star then it is expensive"  $(f \rightsquigarrow e)$
- "if the weather is fine in this area then the hotel is a priori crowded"
  (w → c)

## Example of BLFSW: Find an Hotel

Principles can be supported or inhibited:

- A special offer (o) increases the certainty of w → c : to have a crowded hotel (c) when the weather is fine (w)
- Four star hotels are expensive: f → e but a special offer may inhibit this deduction



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## Reasoning about goal achievements

First: Reasoning about goal achievements:

- a decision is based on the knowledge about the features
- reason wrt the argumentation graph: check the realized goals



#### Definition (K-BLFSW)

Given a consistent base K and a BLFSW  $B = (\mathcal{P}, \mathcal{I}, \mathcal{S}, \text{ pol}, \preceq, w)$ A K-BLFSW associated to B is  $(\mathcal{P}_K, \mathcal{I}_K, \mathcal{S}_K, \text{ pol}, \preceq, w_K)$  where

•  $\mathcal{P}_{K} = \{(\varphi, g) \in \mathcal{P}, \text{ s.t. } K \models \varphi\}$ : set of <u>valid DPs</u> (wrt K)

• 
$$\mathcal{I}_{K} = \{(\varphi, p) \in \mathcal{I}, \text{ s.t. } K \models \varphi \text{ and } p \in \mathcal{P}_{K}\}$$
: set of valid inhibitions

•  $S_{K} = \{(\varphi, p) \in S, s.t. K \models \varphi \text{ and } p \in \mathcal{P}_{K}\}$ : set of valid supports

•  $w_K$ : restriction of w on  $\mathcal{I}_K \cup \mathcal{S}_K$ .

## Realized goals

#### Definition (activation level of a principle)

Given ( $\mathcal{P}_K$ ,  $\mathcal{I}_K$ ,  $\mathcal{S}_K$ , pol,  $\preceq$ ,  $w_K$ ), the activation level of  $p \in \mathcal{P}_K$  is

$$\alpha(p) = \sum_{s \in \mathcal{S}_{\mathcal{K}}(p)} w_{\mathcal{K}}(s, p) - \sum_{i \in \mathcal{I}_{\mathcal{K}}(p)} w_{\mathcal{K}}(i, p)$$

 $\begin{array}{ll} p \text{ is } \underline{inhibited} & iff \ \alpha(p) < 0 & p \text{ is } \underline{supported} \ iff \ \alpha(p) > 0 \\ p \text{ is } \underline{unaffected} & iff \ \alpha(p) = 0 \end{array}$ 

#### Definition (realized goals)

A goal g is <u>realized</u> if there is a principle that concludes g and that is not inhibited.

## Example of K-BLFSW

The same BLFSW used with 2 Knowledge Bases  $K_1$  and  $K_2$ :



Image: A matrix and a matrix

## Handling preferences

Decide if K is preferred to K': use Bipolar decision rules

#### Definition (BiLexi decision rule)

Given two alternatives K and K' with resp. realized goals R and R': The Bipolar Leximin dominance  $\succeq_{BiLexi}$  (BiLexi-preferred to) is s.t.:

$$\begin{array}{ll} K \succ_{BiLexi} K' & iff & M \text{ exists and} \\ |\mathbb{R}_{M}^{\oplus}| \geq |\mathbb{R}_{M}'^{\oplus}| \text{ and } |\mathbb{R}_{M}^{\ominus}| \leq |\mathbb{R}_{M}'^{\ominus}| \\ K \simeq_{BiLexi} K' & iff & M \text{ does not exist} \end{array}$$

where  $M = \max(\{g \in \mathbb{R} \cup \mathbb{R}' \text{ s.t. } |\mathbb{R}_g^{\oplus}| \neq |\mathbb{R}_g'^{\oplus}| \text{ or } |\mathbb{R}_g^{\ominus}| \neq |\mathbb{R}_g'^{\ominus}|\}, \preceq)$  and  $\mathbb{R}_g^{\oplus} = set \text{ of positive realized goals at same level as } g$ 

## Refining the classical rules using Certainty evaluation

#### Definition (Certainty of a realized goal)

Given a BLFSW  $B = (\mathcal{P}, \mathcal{I}, \mathcal{S}, pol, \preceq, w)$  and an alternative described by K, for all goal g realized in  $B_K$ , the certainty associated to g is:

$$\alpha_{\mathcal{K}}(g) = \max_{\varphi \in \mathscr{L}_{\mathcal{F}}, p = \varphi \rightsquigarrow g \in \mathcal{P}_{\mathcal{K}}} \alpha(p)$$

#### Example

 $K_2 = \{p \land w \land f\}, K_3 = \{p \land \neg w \land f\}$  same realized goals:  $\{e, s\}$ But  $\alpha_{K_2}(s) = 0.6$  and  $\alpha_{K_3}(s) = 0.2$ 

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## Interpreting a BLFSW in Possibility Theory

Given a possibility measure  $\Pi$ ,

Definition  $(\Pi$ -DP)

A  $\Pi$ -DP  $\varphi \rightsquigarrow g$  is s.t.  $N(g|\varphi) > 0$ 

### Definition ( $\Pi$ -Inhibitor)

 $\psi$  is a  $\Pi$ -Inhibitor of  $\varphi \rightsquigarrow g$  if  $N(g|\varphi \land \psi) = 0$ 

#### Definition (Π-Support)

 $\psi$  is a  $\Pi$ -Support of  $\varphi \rightsquigarrow g$  if  $N(g|\varphi \land \psi) > N(g|\varphi)$ 

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## Interpreting a BLFSW in Possibility Theory

#### Given a possibility measure $\Pi$

#### Definition ( $\Pi$ -weight)

w is a  $\Pi$ -weight function iff for all possible K-BLFSW ( $\mathcal{P}_K$ ,  $\mathcal{I}_K$ ,  $\mathcal{S}_K$ , pol,  $\leq$ ,  $w_K$ ) where  $w_K$  is the restriction of w on  $\mathcal{I}_K \cup \mathcal{S}_K$  and for all decision principles  $p = \varphi \rightsquigarrow g$ ,  $p' = \varphi' \rightsquigarrow g' \in \mathcal{P}_K$ 

• 
$$\alpha(p) < 0$$
 iff  $N(g \mid \varphi \bigwedge_{\psi \in \mathcal{I}_{\mathcal{K}}(p) \cup \mathcal{S}_{\mathcal{K}}(p)} \psi) = 0$ 

• 
$$\alpha(p) \geq 0$$
 iff  $N(g \mid \varphi \bigwedge_{\psi \in \mathcal{I}_{\mathcal{K}}(p) \cup \mathcal{S}_{\mathcal{K}}(p)} \psi) > 0$ 

•  $\alpha(p) \ge \alpha(p') \ge 0$  iff  $N(g \mid \varphi \bigwedge_{\psi \in \mathcal{I}_{K}(p) \cup \mathcal{S}_{K}(p)} \psi) \ge N(g' \mid \varphi' \bigwedge_{\psi \in \mathcal{I}_{K}(p') \cup \mathcal{S}_{K}(p')} \psi) > 0$ with  $\alpha(p)$  defined from  $w_{K}$ 

## Interpreting a BLFSW in Possibility Theory

#### Proposition

Given a  $\Pi$ -Bipolar Layered Framework with Supports and Weights B,built on a possibility distribution  $\pi$  and on a utility function u on  $LIT_G$ .

B is s.t. for all consistent knowledge bases K, K' and for any goals g, g':

- g not realized wrt  $B_K$  iff N(g|K) = 0 or u(g) = 0
- if g realized wrt  $B_K$  and g' realized wrt  $B_{K'}$  then  $\alpha_K(g) > \alpha_{K'}(g')$  iff N(g|K) > N(g'|K')



#### Conclusions

- The BLFSW is a visual tool made to help human decision makers in their tasks.
- BLFSW can justify a decision by giving the features that support and attack the goals.
- BLFSW can be built from a possibility distribution (help the decision maker to understand decision situations)



#### Prospects

- Link between other criteria for qualitative decision under uncertainty and BLFSW
- Better understand the relation between polarity and optimism/pessimism of the decision maker.
- Learn a BLFSW from data with knowledge and utility or knowledge and ranking

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