



# Factors of acceptability, acceptance and usage for non-rail autonomous public transport vehicles: A systematic literature review

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Title: Factors of acceptability, acceptance and usage for non-rail autonomous public transport vehicles: a systematic literature review

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Transportation Research – Part F: Traffic, Psychology and Behaviour

Abstract:

Non-rail autonomous public transport vehicles have emerged over the last few years. Technical progress in automation has resulted in a growing number of autonomous shuttle pilot experiments. Although these systems are technologically feasible, determining the extent to which they correspond to users' needs and expectations remains a major issue. In order to answer that question, we conducted a systematic review which synthesizes the literature regarding the acceptability and willingness to use this type of autonomous public transport. This literature review allowed us to identify 39 documents addressing 70 factors of acceptability, acceptance and usage of non-rail autonomous public transport vehicles. The most cited factors in the literature concern service characteristics (times, schedules, fares) and safety issues (road-safety, on-board security). Factors related to automation level, comfort and access to the vehicle feature appear to a lesser extent. Acceptance is also related to personal factors, such as socio-demographics, travel habits, and personality. This review could be of interest to designers and manufacturers of non-rail autonomous public transport vehicles, as well as policy makers, and assist with the successful implementation of autonomous public transport services which are better adapted and meet the needs of all potential users.

Keywords: autonomous vehicle; autonomous shuttle; public transit; willingness to use; user needs

## 1 Introduction

The development of autonomous vehicles is currently booming and has been the subject of a growing number of scientific publications over the last fifteen years (Gandia et al., 2019). However, non-rail autonomous public transport vehicles (APTV) have received less interest than the autonomous personal automobile (Azad et al., 2019). Excessive use of autonomous personal automobiles may increase traffic congestion and greenhouse gas emissions (Harb et al., 2018). APTVs are seen as a more appropriate response to the challenges of global warming. They could improve mobility services, and in doing so, lead to an increase in the use of public transport, and therefore decrease reliance on personal automobiles (Millonig & Froehlich, 2018). In this paper, as it is the case in the reviewed literature, the term autonomous is used to refer to completely autonomous vehicles as well as systems which are supervised.

However, if APTVs are to be implemented on a large scale and adopted for future use in daily travel, people need to have a positive attitude towards them. Attitude can be defined as a mental state of readiness, positively or negatively associated with a particular object. It is acquired through experience and is a precursor of behaviour related to the object. Two concepts, "acceptability" and "acceptance", are commonly used to study the general attitude towards a new technology. In the literature, the distinction between these two notions is not always done. In this article we refer **acceptability** to the prospective judgment of potential users towards a technology to be introduced in the future (here the APTV). This implies that the potential users have not yet experienced this new technology (Schade & Schlag, 2003). **Acceptance** corresponds to judgements, attitudes and behavioural reactions of potential users towards a product after they have tried it (Schade & Schlag, 2003, Schuitema, Steg & Forward, 2010). Potential users have experience of the technological object

in an experimental context, but have not used it regularly or spontaneously. The *usage* of a technology refers to the appropriation of this technology by users after its introduction into their daily life. In that case, the technology is available and people opt to use it.

In a recent review (Nordhoff, Kyriakidis, et al., 2019), acceptance of autonomous vehicles was found to be the result of four decision-making steps: exposure to an automated vehicle, formation of a positive attitude towards it, a decision to adopt it and actual use of it. These authors found that acceptance was determined by 28 factors, including socio-demographic characteristics, experience of autonomous vehicles and personality. Other factors, related to personal perception of autonomous vehicles, such as performance expectancy, effort expectancy or social influence, were found to influence acceptance.

Performance expectancy, or perceived usefulness, can be defined as an individual's personal perception that using an innovation would improve his/her performance (Davis, 1989). Effort expectancy, or perceived ease of use, can be described as the degree to which people think that a technology can be used without effort (Davis, 1989). Social influence, also known as the subjective social norm, can be defined as the perception that other significant relatives or influencers have a positive or a negative attitude towards the new technology (Fishbein & Ajzen, 1977).

Most of the articles emerging from our review focused on autonomous vehicles in general, or on private autonomous vehicles. The main aim of the present paper is to present how users and potential users accept autonomous vehicles in the specific context of public transport. In particular, our aim was to identify within the literature the APTV characteristics which users and potential users need or require, and which therefore increase acceptability and acceptance, and encourage their use. In documenting users' needs and requirements for APTVs, we hope that our findings will provide insight for APTV designers, manufacturers and policy makers, and will help to improve APTV design and in doing so meet the needs of all potential users.

This article focuses on non-rail vehicles, which can operate in automated mode on limited sections of road (level 4 according to the classification of the Society of Automotive Engineers; SAE International, 2018) or which can operate in automated mode on all publicly accessible roadways (SAE level 5).

## 2 Material and methods

### 2.1 Search strategy and databases

The literature search was conducted in April 2019 and updated in January 2020 for studies published between 1999 and 2019. A request relating to APTVs and acceptance, in both English and French was submitted with the search field *title* for the Web of Science, Scopus and PsychInfo databases, and with the search fields *title* and *keywords* for Transport Research International Documentation (TRID). The request was: ((Driverless OR "Self-driv\*" OR "Self driv\*" OR Automated OR Autonomous OR Intelligent) AND (Shuttle\* OR Minibus\* OR "Bus" OR "Buses" OR "Busses" OR Autobus\* OR Transit\* OR Vehicule\* OR "Public transport\*")) AND (Accept\* OR Willing\* OR Preference\* OR Perception\* OR Need\* OR Expectation\* OR Attitude\* OR Adoption OR Readiness OR Interest\* OR Opinion\* OR Usefulness OR trust ((Decision OR Intention\*) AND Use)). Additional searches were performed using Pubmed, Springerlink and Sage for documents containing the same terms in the search field *abstract* or *all*, and using Taylor & Francis Online content platform for terms relating to autonomous vehicles in the search field *keywords*. CAIRN and Revue.org were also used, but no results relating to autonomous vehicles were found. In order to retrieve the maximum number of relevant documents, we used backward snowballing to investigate the reference lists of the studies we included, and

forward snowballing on articles citing these studies. This search, carried out in March 2020, yielded additional documents.

## 2.2 Document selection and data extraction

We retrieved journal publications, conference proceedings, theses, reports and books or book chapters. 133 records from database research were reviewed for eligibility (Figure 1). Exclusion criteria were as follows: unrelated to APTV or user perspectives, not in English or French, non-scientific documents, related to on-track-vehicles or only on-demand services, no acceptability, acceptance or use factors identified, data gathering method not sufficiently explicit, full-text unavailable, reviews or meta-analyses. Thirty-six duplicate records were removed, and, based on title and abstract, 61 documents did not fulfil the search criteria, resulting in 36 initially reviewed documents. The three authors of the present paper participated in the screening process, and each document was independently screened by two of them. The independent reviewers initially agreed on 92/97 documents (95%; Cohen's kappa coefficient of 0.89) and then met to reach agreement on the remaining five documents. Fifty-eight additional documents were reviewed with backward and forward snowballing, leading to a total of 94 documents retrieved. Finally, after the removal of 49 documents which did not fulfil the inclusion criteria and 5 documents for which the full text was not available, 39 studies were retained.

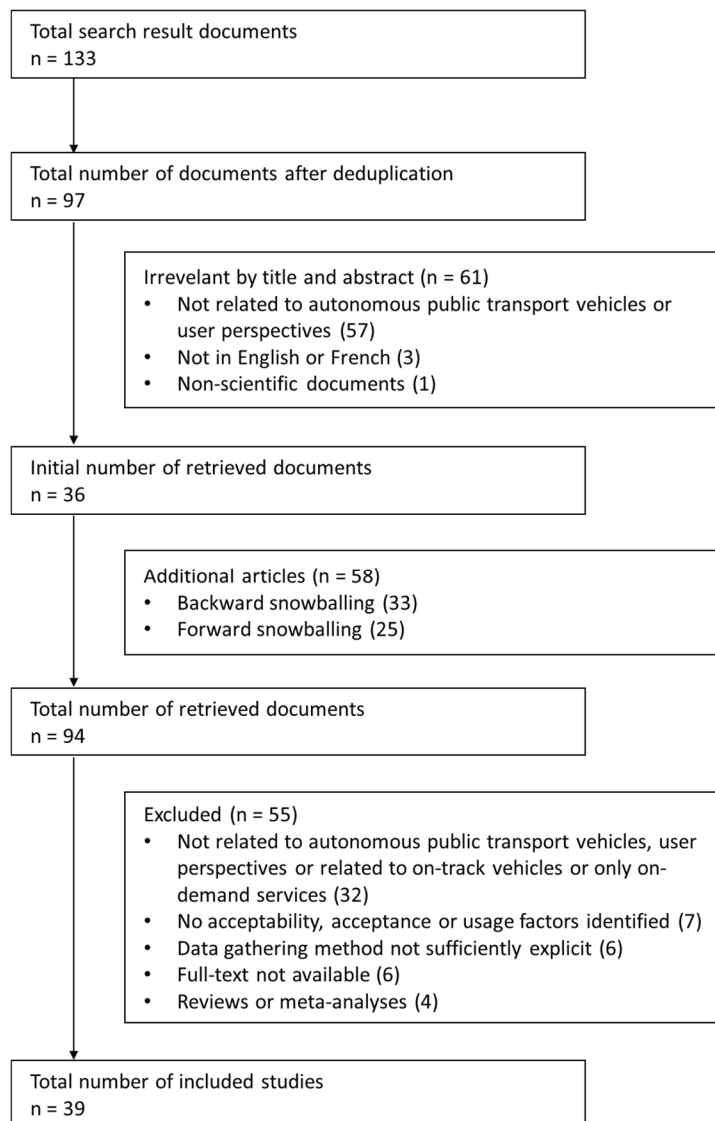


Figure 1. Review procedure flowchart

## 2.3 Analysis

Firstly, the 39 studies included in this review were described according to their type (journal publications, conference proceedings, reports, theses, books or book chapters), the kind of vehicle involved (autonomous shuttle, bus shuttle or APTV in general), the methods used (quantitative, qualitative or mixed) and their focus (acceptability, acceptance or usage). Secondly, all acceptability, acceptance or usage factors investigated in these studies were extracted and categorized. The factor extraction was performed by one author, and a second author independently checked the data extraction forms for accuracy in a sample of the documents.

## 3 Results

### 3.1 Description of included studies

The 39 documents included 19 journal publications, 16 conference proceedings, two master's theses, one doctoral thesis and one report. Thirty studies focused on autonomous shuttles, 4 on buses (including one on school buses) and 5 on APTVs in general. There were 27 quantitative studies and 8

qualitative studies, including 5 with individual interviews, 3 with collective interviews or focus groups and 1 study involving individual and collective interviews. Three studies combined several methods: 1 study used surveys and qualitative interviews, 2 studies combined surveys, focus groups and observations.

### 3.2 Factors described in the literature

Several studies pointed out that a multitude of combined factors play a crucial role in the process of acceptability, acceptance or usage of APTVs.

The model proposed by Acheampong & Cugurullo (2019), based on confirmatory factor analyses indicates that attitude towards public transport (environmental benefits and their effectiveness) is a relevant predictor of intention to use APTVs. The authors also found that other factors, such as attitudes to ecology and technology, behavioural control, social influence and the image associated with using an autonomous car, concerns about autonomous vehicles, perceived benefits, effort expectancy, age, gender and education level, were all also predictors of intention to use APTVs.

In their initial study based on the UTAUT model (Unified Theory of Acceptance and Use of technology of Venkatesh et al., 2003), Madigan et al. (2016) looked at whether the variables performance expectancy, social influence and effort expectancy predict the intention to use an autonomous shuttle. These factors accounted for 22% of the variance, suggesting that they were predictors of intention to use, but that other variables also have an influence. Age, gender and exposure to technology were not found to be moderating variables of intention to use.

In a subsequent study, Madigan et al. (2017) found that perceived pleasure, usefulness, social influence and facilitating conditions (i.e. having the resources and knowledge to use the shuttle) were predictors of intention to use an autonomous bus, and accounted for 58.6% of the variance. Effort expectancy did not predict intention to use, nor did age, gender or the number of times the autonomous shuttle was used.

Motak et al. (2017) found that 55% of the variance of intention to use an autonomous shuttle was accounted for by perceived usefulness, social influence, perceived pleasure, and prior experience.

Our objective of reviewing all the factors influencing acceptability, acceptance and usage of APTVs, leads us to extract 70 different factors from the 39 studies included in the present literature review. The 70 factors found were classified on the basis of the taxonomy proposed by Nordhoff et al. 2019 in their Multi-level model on Automated Vehicle Acceptance (MAVA) resulting from their literature review. The MAVA model, built on Unified Theory of Acceptance and Use of Technology (UTAUT3, Venkatesh et al., 2016) and the Car Technology Acceptance Model (CTAM, Osswald et al., 2012), include a four-stage decision-making process. This process ranges from the exposure of the individual to automated vehicles (AVs) in Stage 1, the formation of favourable or unfavourable attitudes towards AVs in Stage 2, making the decision to adopt or reject AVs in Stage 3, to the implementation of AVs into practice in Stage 4. According to the authors, MAVA incorporates acceptance factors distributed in two levels: the meso-level, composed of the exposure of individuals to autonomous vehicles, instrumental domain-specific, symbolic-affective and moral-normative factors, and the micro-level, composed of individual difference factors (sociodemographics, personality and travel behaviour). In the present study, in contrast to the choice of Nordhoff et al. 2019, factors were retained even though they had only been found in a few studies.

### 3.2.1 Factors at the meso-level

Each of the factors presented at the meso level are summarized in Table 1.

#### 3.2.1.1 Exposure to autonomous vehicles

Level of knowledge and experience of autonomous vehicles can have an impact on acceptance of APTVs. For example, **previous experience** of autonomous vehicles raised willingness to use APTVs in the future (Pakusch & Bossauer, 2017), enhanced the feeling that autonomous shuttles are safe (Salonen & Haavisto, 2019) and increased the likelihood of choosing an autonomous shuttle over several other means of transport (Wicki et al., 2019). Previous experience of APTVs, even on guided tracks, can have a positive impact on feelings of safety prior to traveling by autonomous shuttle (Eden et al., 2017). One study indicated that frequent users of autonomous shuttles have a more positive attitude towards autonomous vehicles than non-users. They also have a greater preference for full automation, and are more likely to think that autonomous shuttles are safer than manually-operated vehicles than non-users (Portouli et al., 2017). Perception of ease of use of autonomous shuttles was greater in participants who had previous experience of this mode of transport than in non-users (Dekker, 2017), and their intention to use an autonomous shuttle was greater (Motak et al., 2017). One study showed that traveling on an autonomous shuttle improved perceived ease of use, confidence in, and attitude towards the vehicle, but did not modify its perceived usefulness or intention to use (Wintersberger et al., 2018). However, in another study (Monéger, 2018), willingness to use APTVs, perception of control and of the usefulness of the vehicle increased after traveling on an autonomous shuttle. When people were offered the opportunity of trying an APTV, acceptance and use were both seen to rise (Nordhoff, de Winter, et al., 2019). However, the number of times participants used or interacted with autonomous shuttles was not seen to have any effect on their degree of willingness to use this type of vehicle (Madigan et al., 2017, 2016). Prior **knowledge of autonomous vehicles** also increases the probability of being willing to use an autonomous bus (Dong et al., 2017; Kistorz et al., 2019). People who had never heard of autonomous shuttles were more concerned about the interaction of these vehicles with other road-users, and perceived APTVs as being more difficult to understand, than people with previous experience (ranging from one trial to regular weekly use) of an autonomous shuttle (Dekker, 2017). However, in the same study, exposure was not seen to have any significant effect on performance, security (in terms of data-hacking and fears about other passengers), trust in APTVs or preference for this means of transport over another. **Knowing that an autonomous shuttle had caused an accident** prior to trying an APTV has a negative impact on willingness to use this type of vehicle (Salonen & Haavisto, 2019) and raises concerns about safety (Eden et al., 2017). **Media coverage** of autonomous vehicles can improve familiarity and consequently, feelings of confidence (Salonen & Haavisto, 2019). However, it can also give rise to unrealistic expectations, therefore decreasing positive perception of an autonomous shuttle tried subsequently (Nordhoff, de Winter, et al., 2019).

Exposure does therefore have an effect on acceptance, and it depends on whether the knowledge of, and the experience in relation to the APTV was positive or negative.

#### 3.2.1.2 Domain specific system evaluation

##### 3.2.1.2.1 Performance and effort expectancies

**Performance expectancy** of APTVs is an important factor in their acceptance. Nordhoff et al. (2017) revealed that both performance expectancy of an autonomous shuttle and the fact that autonomous shuttles constitute an important part of the public transport system foster intention to use APTVs for daily travel. Performance expectancy has also been found to be associated with positive attitudes

towards APTVs (Chen, 2019; Herrenkind et al., 2019) and intention to use this type of vehicle (Acheampong & Cugurullo, 2019; Monéger, 2018; Motak et al., 2017). The perception that autonomous shuttles are useful and more efficient than current transport modes also increases intention to use them (Madigan et al., 2017, 2016). Attitudes towards autonomous shuttles and their perceived utility depend on the perception that they have more advantages than other modes of transport (Herrenkind et al., 2019; Nordhoff, de Winter, et al., 2019). Participants in the study by Nordhoff, de Winter, et al. (2019) indicated that outwith the context of the experiment (in normal circumstances), they would have made the journey on foot. This decreased acceptance and lowered their intention to use the shuttle.

**Effort expectancy** has been found to be an acceptance factor in several studies. When expectancy that the effort involved in using an autonomous shuttle is low, positive attitude towards this means of transport increases, as does its perceived usefulness (Chen, 2019). Herrenkind et al. (2019) also observed that effort expectancy had an effect on attitude towards using APTVs. This was, however, less pronounced than the effect of performance expectancy. An association has been demonstrated between APTV effort expectancy, attitude, performance expectancy and intention to use APTVs (Acheampong & Cugurullo, 2019). Low effort expectancy (Kostorz et al., 2019; Monéger, 2018) and ease of learning how to use an autonomous shuttle (Madigan et al., 2016) have been associated with a greater intention to use APTVs. When effort expectancy for using an autonomous shuttle is lower than for other current means of transport, willingness to use APTVs for everyday journeys increases (Nordhoff et al., 2017). However, Madigan et al. (2017) did not find any significant effect of low effort expectancy (described by the authors as human-machine interfaces which are clear and easily-understandable on the shuttle), perceived ease of use, and ease of learning how to use an autonomous shuttle) on intention to use the shuttle.

#### 3.2.1.2.2 Safety

**Safety** factors discussed here relate to safety issues, and to concerns about traffic safety, difficulties introduced by the absence of a driver, fear of assault, incivilities or invasion of data privacy. In this section, we present vehicle characteristics related to these themes, as well as suggested preventive counter-measures.

Fears and **concerns** about automation have been found to negatively influence attitude towards APTVs, although they do not modify their perceived benefits (Acheampong & Cugurullo, 2019). Concerns about the **safety of the vehicle** and **incivilities** decrease willingness to use an autonomous bus (Dong et al., 2017; Monéger, 2018). Before and after trying an autonomous shuttle, participants reported that fear of a **technology failure** resulted in a negative opinion about autonomous vehicles (Fernández Medina & Jenkins, 2017). Potential users require **personal data protection** (Stark et al., 2019), and concerns about this have been found to negatively impact the perceived usefulness of autonomous shuttles, but not attitude towards them (Herrenkind et al., 2019).

Dong et al. (2017) found that the **absence of a driver** leads to concerns about assistance to people with disabilities and access to information. These concerns negatively impact willingness to use autonomous buses. The absence of a driver also raises questions about the resolution of technical problems, the provision of information to passengers, the prevention of incivilities and supervision of compliance with regulations (López-Lambas & Alonso, 2019). It also emerged that public transport drivers carry out tasks unrelated to driving, such as providing information, ensuring passenger safety and handling unexpected situations (Fernández Medina & Jenkins, 2017). Fears associated with **the night service** is another issue (Piao et al., 2016), and this seems to affect women more than men (Stark et al., 2019). Women are also more worried than men about traffic safety, incivilities, assault,



terrorism and personal data protection (Roche-Cerasi, 2019). Concerns about the **decision-making algorithm**, in situations where a collision is unavoidable have also been voiced (Salonen & Haavisto, 2019).

In response to these concerns, and to improve safety, countermeasures have been proposed. The presence of **seat belts** (Eden et al., 2017; Vöge & McDonald, 2003) and **child safety seats** (Stark et al., 2019), and **the prohibition of standing** inside the vehicle (Vöge & McDonald, 2003) have all been cited as ways of preventing falls during braking. Divergences were found on passenger **registration** and **video and audio surveillance** to prevent incivilities and assaults, because they raised concerns about personal data protection (Stark et al. 2019). Certain studies have identified the need for a **stop button** (Nordhoff, de Winter, et al., 2019) or **a means of communication** in case of emergency, vehicle dysfunction or incivility, in the form of an on-vehicle system application (Vöge & McDonald, 2003). **Autonomous medical emergency management** has also been proposed (Vöge & McDonald, 2003). More globally, the need to **respect current security standards** was expressed in a study by Stark et al. (2019).

#### 3.2.1.2.3 Service characteristics

Mobility service characteristics have been assessed in a number of APTV studies. **High frequency** services and short **waiting times** emerge as positive factors for APTVs acceptability or acceptance (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2014; Dekker, 2017; Papadima et al., 2020; Ramseyer et al., 2018; Salonen & Haavisto, 2019; Stark et al., 2019; Vöge & McDonald, 2003; Wicki et al., 2019). A median waiting time of 10 minutes was defined as acceptable in the study conducted by Hinderer et al. (2018), and an average of 6.4 minutes for flexible services and 5.4 for fixed routes in the study by Földes et al. (2018). A lengthy **travel time** on an autonomous shuttle results in a negative assessment (Dekker, 2017). When travel time is shorter, an autonomous shuttle is more likely to be chosen over an equivalent manual vehicle (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2014), or over another means of transport (Wicki et al., 2019; Wintersberger et al., 2018). Similarly, long travel time seems to be less acceptable for an autonomous shuttle than for a regular bus, but a long waiting time has been found to be more acceptable for an autonomous shuttle than for a regular bus (Wien, 2019; K. Winter et al., 2019). In terms of **service schedules**, the participants in a study in which an autonomous shuttle operated from 1:00 to 6:00 p.m. found that the service needed to be extended (Eden et al., 2017), and another study suggested that autonomous mobility services should operate 24 hours a day (Salonen & Haavisto, 2019).

Studies indicated that attractiveness of APTVs can be improved when **fares are** lower than for other means of transport (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2014; Dekker, 2017; Herrenkind et al., 2019; Papadima et al., 2020; Piao et al., 2016; Stark et al., 2019; Wicki et al., 2019) or when the service is free of charge (Hinderer et al., 2018; Vöge & McDonald, 2003). However, 54% of respondents in another study were willing to pay the same price for an autonomous bus as for a conventional bus, and 21.5% of respondents were prepared to pay 0.50 € more (Portouli et al., 2017). Fares can also be customized in line with the service provided (Stark et al., 2019). Some studies have addressed the importance of the **integration of autonomous vehicles into the traditional public transport offer**, and **intramodality with other means of transport** (Madigan et al., 2017; Stark et al., 2019; Vöge & McDonald, 2003). People are willing to pay higher fares for flexible services than for fixed routes, in peak hours, and if they can select fellow passengers; they expect to pay lower fares for a flexible service ordered 30 minutes in advance and for daily use (Földes et al., 2018). People are also willing to pay higher fares on an autonomous shuttle when it reduces on-vehicle time (Wien, 2019; K. Winter et al., 2019).

**Travel information**, for example about routes and connections (Földes et al., 2018; Nordhoff, de Winter, et al., 2019), and about vehicle speed and congestion is seen to be important for potential APTV users (Fröhlich et al., 2019), and its provision in real time on smartphone applications has been promoted (Papadima et al., 2020; Stark et al., 2019). Provision of on-board information about the current position of the vehicle is also necessary (Vöge & McDonald, 2003). Another study found that information should be easily visible for passengers, and therefore two screens are preferable when seating is bi-directional. These should not, however, obstruct passengers' view from the vehicle (Fröhlich et al., 2019). **Reliability** of service and information provided is also a requirement of users and potential users (Nordhoff, de Winter, et al., 2019; Stark et al., 2019).

With regards to the vehicle **location context**, several studies (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini, Delle Site, Stam, et al., 2016; Alessandrini et al., 2015, 2014) found that preference for autonomous shuttles over traditional shuttles was greater in major facility infrastructures (technological park, university campus), than in city centers, at transport public nodes or in residential areas. In one survey, 28.8 % of respondents stated that autonomous shuttles would be useful between residential areas and public transport connections, while 12.3 % replied in favour of autonomous shuttles between workplaces and public transport connections (Roche-Cerasi, 2019). Other studies report that a service on a dedicated line (Dekker, 2017; Vöge & McDonald, 2003) and in a context of calm traffic is preferred (Salonen & Haavisto, 2019). However, pedestrian areas are not seen as a suitable context for autonomous shuttles, while autonomous shuttles for connections to places such as railway stations or airports are perceived as being more useful (Eden et al., 2017). Autonomous shuttle services in locations which currently have insufficient public transport links, for example rural areas, have been promoted in several studies (Hinderer et al., 2018; Nordhoff, de Winter, et al., 2019; Stark et al., 2019). The itinerary of the autonomous vehicle must meet the needs of users (Salonen & Haavisto, 2019).

**Flexibility** of service has been identified as a positive factor of intention to use an autonomous shuttle (Nordhoff, de Winter, et al., 2019; Salonen & Haavisto, 2019; Vöge & McDonald, 2003). However, there is also a certain reluctance to use this type of service, because it involves actively ordering a vehicle, and can therefore be perceived as being less spontaneous and independent than just going to a stop and waiting for a vehicle (Stark et al., 2019; Wien, 2019; K. Winter et al., 2019).

#### 3.2.1.2.4 Vehicle characteristics

The issue of **vehicle speed** leads to contrasting appreciations, depending on whether safety or efficiency is the priority. Low speed has been associated with a negative appreciation of autonomous vehicles in a number of studies (Fernández Medina & Jenkins, 2017; Nordhoff, de Winter, et al., 2019; Nordhoff et al., 2018; Ramseyer et al., 2018; Wintersberger et al., 2018), and has been both positively and negatively assessed in others (Eden et al., 2017; Salonen & Haavisto, 2019; Vöge & McDonald, 2003). Abrupt and frequent **braking** was assessed negatively in some studies (Eden et al., 2017; Fernández Medina & Jenkins, 2017; Nordhoff, de Winter, et al., 2019; Ramseyer et al., 2018). However, participants' opinion of autonomous shuttles improved after they experienced that vehicle stopped when pedestrians or cyclists came too close to it (Fernández Medina & Jenkins, 2017).

Comfort factors, which refer to the physical and aesthetic characteristics of a vehicle, and options aimed at improving passenger satisfaction, have been mentioned in several studies. Good **visibility of the exterior**, via large windows is important for users (Eden et al., 2017; Ramseyer et al., 2018), as are road-facing seats (Fernández Medina & Jenkins, 2017; Nordhoff, de Winter, et al., 2019). **Free internet access** on the vehicle was perceived positively in three studies (Földes et al., 2018; Nordhoff, de Winter, et al., 2019; Vöge & McDonald, 2003). Other studies have addressed the question of

1 **seats**, which have to be comfortable (Eden et al., 2017; Nordhoff, de Winter, et al., 2019) and in a  
2 configuration which facilitates discussion between passengers (Ramseyer et al., 2018). A low **noise**  
3 **level** inside the vehicle has also been requested: the hydraulic compressor noise of a shuttle (Eden et  
4 al., 2017) and an audible warning device used to warn other road users of the electric vehicle's  
5 presence (Fernández Medina & Jenkins, 2017) were found by participants to be irritating. Shuttle  
6 **appearance** has also been studied. Potential users require an attractive interior (Nordhoff, de  
7 Winter, et al., 2019), and an external appearance similar to that of a traditional shuttle (Vöge &  
8 McDonald, 2003). Vehicle **cleanliness** is also a requirement (Vöge & McDonald, 2003). Users and  
9 potential users have also suggested that **air-conditioning** should be a feature of the vehicle  
10 (Nordhoff, de Winter, et al., 2019). Finally, for participants who tried an autonomous shuttle, the  
11 presence of an **humanoid voice** decreased their willingness to use the vehicle, its perceived  
12 usefulness, its social influence and their perceived pleasure (Monéger, 2018).

13 Several factors relating to physical access to the vehicle were found to influence APTVs acceptability.  
14 Firstly, **vehicles need to be sufficiently large in size**, with enough seats for users (Stark et al., 2019)  
15 and with room for wheelchairs, strollers and luggage (Eden et al., 2017; Nordhoff, de Winter, et al.,  
16 2019; Nordhoff et al., 2018; Vöge & McDonald, 2003). Secondly, **access with no physical obstacles**,  
17 (for example with low floors, large sliding doors and access ramps) has been found to influence  
18 APTVs acceptability, in particular for users with disabilities (Nordhoff, de Winter, et al., 2019; Stark et  
19 al., 2019; Vöge & McDonald, 2003). A high vehicle **occupancy rate** decreases willingness to use an  
20 autonomous shuttle (Wicki et al., 2019). Proposals aimed at **preventing overloading** of the vehicle  
21 via an access control system have been put forward (Vöge & McDonald, 2003). Finally, participants  
22 have stated that **access to the vehicle with a bicycle or a dog** should also be possible (Hinderer et al.,  
23 2018). **Access to shuttle stops and their characteristics** have also been considered. Stops with a  
24 shelter, lighting and seats are preferred to stops without these facilities. A short walking distance to  
25 and from a bus stop (<200 m) was also declared to be an important attribute (Papadima et al., 2020).

26 Some factors found in the present literature review relate to automation characteristics, i.e. vehicle  
27 behaviour and capabilities. These include supervision of the vehicle, presence of a means of manual  
28 control, automation level and information provided to users about automated driving. Inconsistent  
29 results were found regarding vehicle **supervision**. Some studies reveal a preference for an on-board  
30 supervisor (Dong et al., 2017; López-Lambas & Alonso, 2019; Piao et al., 2016; Salonen & Haavisto,  
31 2019). External supervision was preferred in others (Dekker, 2017; Nordhoff et al., 2018) and no  
32 supervision in other studies (Papadima et al., 2020). The same discrepancies can also be found within  
33 a single study. In several studies, some of the participants appreciated the presence of a supervisor  
34 on the shuttle, while others would have preferred not to have a supervisor on board (Ramseyer et  
35 al., 2018; Wien, 2019; K. Winter et al., 2019). The need for supervision (via an external or an on-  
36 board supervisor) was expressed by 20 % of the sample in the study by Nordhoff, de Winter, et al.  
37 (2019), and a lack of supervision was perceived as being a barrier to autonomous shuttle use by 18 %  
38 of participants in Monéger's study (2018). Finally, preference for an on-board supervisor on shuttles  
39 was found to be more important for non-users than for regular users of an autonomous shuttle  
40 (Portouli et al., 2017). Four studies have highlighted the interest for users of having a means of  
41 **manual control** over the vehicle. This should take the form of an emergency stop button (Nordhoff,  
42 de Winter, et al., 2019), which also opens the doors when pressed (Vöge & McDonald, 2003), or of a  
43 joystick which allows the supervisor to take control of the vehicle (Ramseyer et al., 2018). However, a  
44 user-operated horn to warn other road users of the approach of the autonomous shuttle was rated  
45 less well than an autonomous horn (Monéger, 2018). The importance of providing passengers with  
46 **information about the autonomous functioning of the shuttle** has been pointed out, in particular in  
47 relation to the vehicle's 'awareness' of its surroundings (obstacles) and its 'intentions' (turning,  
48 braking, avoiding obstacles). This information could be relayed by an auditory warning signal (Vöge &

McDonald, 2003), or displayed at eye-level on the windscreen (Fröhlich et al., 2019). However, it has not been clearly demonstrated if visually-displayed information should contain text, icons or come in an augmented reality format, although a combination of these formats might be more comprehensible (Fröhlich et al., 2019). Concerning the **automation level**, participants in one study preferred traditional buses, or buses with a low level of autonomy to fully-autonomous buses (Roche-Cerasi, 2019). In other research, after trying an autonomous shuttle, participants negatively assessed both the shuttle's inability to automatically bypass obstacles, and manual interventions by a supervisor (Nordhoff, de Winter, et al., 2019).

### 3.2.1.3 Symbolic-affective system evaluation

Social influence and perceived pleasure are symbolic-affective factors which can play a role in the acceptance of autonomous vehicles. Studies on **social influence** have indicated that an individual's intention to use an autonomous shuttle is affected by the opinion of significant relatives (Madigan et al., 2017, 2016), or of people living in the same region (Motak et al., 2017). Intention to use an APTV is also associated with significant others adopting the same behaviour (Acheampong & Cugurullo, 2019). In this context, a study conducted by Herrenkind et al. (2019) indicates that the reputation of autonomous shuttles has an impact on their perceived utility, and that social influence is associated with the perceived utility of the shuttles, attitude towards them and intention to use them. Nordhoff et al. (2017) showed that use of an autonomous shuttle by significant relatives had an effect on willingness to use shuttles in a rural context, but not in an urban context. **Perceived pleasure**, also referred to as hedonic motivation, was positively associated with the intention to use an autonomous shuttle (Madigan et al., 2017; Motak et al., 2017), with perception of usefulness and a positive attitude to autonomous shuttles (Herrenkind et al., 2019), and with positive attitude to autonomous shuttles and the intention to use them (Chen, 2019).

*Table 1. Factors of acceptability, acceptance or usage related to the meso-level and number of studies that investigated them (n)*

Themes	Factors	n
Exposure to autonomous vehicles	Previous experience	Acceptance studies: 8 Acceptability/acceptance studies: 3 Acceptability/usage studies: 1
	Previous knowledge	Acceptability studies: 2 Acceptance studies: 1
	Awareness of an accident	Acceptance studies: 2
	Media coverage	Acceptance studies: 2
- Domain specific system evaluation	Performance expectancy	Acceptability studies: 1 Acceptance studies: 8
	Effort expectancy	Acceptability studies: 2 Acceptance studies: 6
	Safety <ul style="list-style-type: none"> <li>- concerns: road-safety of the vehicle, incivilities, technology failures, personal data protection, absence of a driver, night services, decision-making algorithm</li> </ul>	Acceptability studies: 5 Acceptance studies: 4 Acceptability/acceptance studies: 1
	- Countermeasures: seat belts, child safety seats, prohibition of standing,	Acceptability studies: 2 Acceptance studies: 2

	<p>registration of passengers and audio and video surveillance, emergency stop button, communication means, medical emergency management, respect of current security standards</p>	
	<p>Mobility service characteristics</p> <ul style="list-style-type: none"> <li>- Times and schedules: frequency/waiting time, travel time, schedules</li> </ul>	<p>Acceptability studies: 8 Acceptance studies: 4 Acceptability/acceptance studies: 2 Acceptability/acceptance/usage studies: 1</p>
	<ul style="list-style-type: none"> <li>- Fares, integration with public transport and intramodality</li> </ul>	<p>Acceptability studies: 8 Acceptance studies: 2 Acceptability/acceptance studies: 3 Acceptability/usage studies: 1 Acceptability/acceptance/usage studies: 1</p>
	<ul style="list-style-type: none"> <li>- Location context</li> </ul>	<p>Acceptability studies: 8 Acceptance studies: 3 Acceptability/acceptance studies: 1</p>
	<ul style="list-style-type: none"> <li>- Travel information and reliability</li> </ul>	<p>Acceptability studies: 4 Acceptance studies: 3 Acceptability/acceptance/usage studies: 1</p>
	<ul style="list-style-type: none"> <li>- Flexibility</li> </ul>	<p>Acceptability studies: 3 Acceptance studies: 2 Acceptability/acceptance studies: 1</p>
	<p>Vehicle characteristics</p> <ul style="list-style-type: none"> <li>- Vehicle speed</li> </ul>	<p>Acceptability studies: 2 Acceptance studies: 6</p>
	<ul style="list-style-type: none"> <li>- Braking behaviour</li> </ul>	<p>Acceptance studies: 4</p>
	<ul style="list-style-type: none"> <li>- Automation factors: supervision, manual control means, automation level, information about autonomous functioning</li> </ul>	<p>Acceptability studies: 8 Acceptance studies: 5 Acceptability/acceptance studies: 2 Acceptability/usage studies: 1 Acceptability/acceptance/usage studies: 1</p>
	<ul style="list-style-type: none"> <li>- Comfort : visibility of the outside, Free internet access, seats (comfortable and with a configuration facilitating discussion), noise, internal and external appearance, air-conditioning, cleanliness, humanoid voice</li> </ul>	<p>Acceptability studies: 2 Acceptance studies: 4</p>
	<ul style="list-style-type: none"> <li>- Access to the vehicle: vehicle size, obstacle-free access, occupancy rate and overloading prevention,</li> </ul>	<p>Acceptability studies: 3 Acceptance studies: 3 Acceptability/acceptance studies: 1 Acceptability/acceptance/usage studies:</p>

	access to the vehicle with a bicycle or a dog, access and characteristics of stops	1
Symbolic-affective system evaluation	Social influence	Acceptability studies: 5 Acceptance studies: 1
	Perceived pleasure	Acceptance studies: 4

### 3.2.2 Factors at the micro-level

Factors at the micro-level can be classified into three categories: socio-demographics, travel behaviour, and personality. They will be presented below and summarized in Table 2.

#### 3.2.2.1 Socio-demographic factors

Several studies have measured the effects of socio-demographic variables such as age, gender, education level and income, on acceptance of APTVs.

The effect of **age** on acceptance is not consistent across the literature. Several studies found no significant age effect on willingness to use an autonomous shuttle (Kostorz et al., 2019; Madigan et al., 2017, 2016; Motak et al., 2017), or an APTV (Pakusch & Bossauer, 2017), on the probability of choosing an autonomous shuttle over another means of transport (Alessandrini, Delle Site, Gatta, et al., 2016; Wien, 2019), on feelings of safety onboard the vehicle, traffic safety or emergency management (Salonen, 2018) or on trust in autonomous shuttles (Dekker, 2017). Age was not found to have any effect on intention to use public transport more when autonomous shuttles provided mobility services between public transport and car parks, or the workplace and residential areas. Younger people appeared to be more willing to use autonomous buses with high levels of automation (Roche-Cerasi, 2019). Other studies also showed that acceptance was higher in younger people. A negative correlation between age and a positive attitude towards technology, intention to use APTVs and the perceived benefits of APTVs has been demonstrated (Acheampong & Cugurullo, 2019). Participants aged 18-35 were found to be more willing to use an autonomous bus than those aged 45 years or more (Dong et al., 2017). 42% of students surveyed were prepared to use a fee-based APTV service, compared to 20% of retired people surveyed (Hinderer et al., 2018). In addition, regular users of an autonomous shuttle were found to be younger than non-users (Portouli et al., 2017), and perceived ease of use was found to be higher in younger participants than in older ones (Nordhoff et al., 2017). However, in one study, acceptance of an autonomous shuttle was found to be higher in older than in younger participants, although the former viewed the autonomous shuttle as less efficient than their current mode of transport (Nordhoff et al., 2018). Another study showed that social influence was more important for older participants (Nordhoff et al., 2017). Age also has a moderating influence on some factors. The effect of perceived ease of use of an autonomous shuttle on attitude was seen to be greater in participants over 40, whereas the effect of trust on attitude was significant only in participants of 40 and under (Chen, 2019).

The effect of **gender** on acceptability and acceptance is unclear. Several studies have found that men are more willing to use an autonomous bus (Dong et al., 2017; S. R. Winter et al., 2018). They are also seen to be more prepared to use APTVs in general (Acheampong & Cugurullo, 2019), to choose an autonomous shuttle over a traditional vehicle (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2014; Wien, 2019; K. Winter et al., 2019), to use an autonomous bus with a high level of automation (Roche-Cerasi, 2019) and have more trust in autonomous shuttles than women (Dekker, 2017). In addition, while parents are globally unwilling to let their children use a driverless school bus in the United States, mothers are less likely to accept this than fathers (Anania et al.,

2018). Men are also less afraid of other passengers on autonomous vehicles than women, but no significant difference has been found on concerns about traffic safety or managing an emergency (Salonen, 2018). Gender was found to have a moderating role on several factors: the effects of perceived ease of use of an autonomous shuttle on its perceived usefulness were found to be greater for females than for males. The effects of perceived usefulness on attitude were found to be greater for males than for females, and the effects of trust on attitude were found to be significant only for females (Chen, 2019). Women are less likely to think that APTVs are useful, have more concerns about them, and subjective norms and ecological values moderate their intention to use APTVs less (Acheampong & Cugurullo, 2019). Finally, people might be more willing to use an autonomous bus than to let their partner or their child use it, and this applies more to women than to men (S. R. Winter et al., 2018). However, other studies did not find significant differences between men's and women's willingness to use an autonomous shuttle (Madigan et al., 2017; Nordhoff et al., 2018, 2017), or APTVs in general (Pakusch & Bossauer, 2017), and there is also no significant difference between them for performance expectancy, effort expectancy, and social influence (Nordhoff et al., 2017). No gender effect was found on the intention to use public transport more if autonomous shuttles provided mobility services between public transport and car parks, the workplace and residential areas (Roche-Cerasi, 2019).

A high **education level** was associated positively with a preference for autonomous shuttles over traditional ones in three out of twelve cities surveyed (Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2015, 2014). In these three cities, implementation of autonomous shuttles was planned in city centers. An effect of education level was found on willingness to use an autonomous bus (Roche-Cerasi, 2019) on intention to use an APTV, on perceived usefulness of APTVs and perceived ease of use (Acheampong & Cugurullo, 2019). However, no effect of education appeared either on feelings of traffic safety, on-vehicle security and emergency management (Salonen, 2018) or on trust in autonomous shuttles (Dekker, 2017). No effect of education was found between regular users of autonomous shuttles and participants who never used this means of transport (Portouli et al., 2017).

**Income** was not found to have an effect on preference for autonomous shuttles over traditional shuttles (Alessandrini, Delle Site, Gatta, et al., 2016), on the intention to use an autonomous shuttle (Kostorz et al., 2019), on feelings about traffic safety, on-vehicle security and emergency management (Salonen, 2018) or on trust in autonomous shuttles (Dekker, 2017). Another study stated that a higher income increases willingness to use an autonomous bus, but this difference exists only between higher and lower incomes, and only when knowledge about autonomous vehicles is not controlled (Dong et al., 2017).

**Employment** was not found to have an effect on preference for autonomous shuttles over traditional ones (Alessandrini, Delle Site, Gatta, et al., 2016) or on fears about traffic safety and emergency management (Salonen, 2018). However, students were found to be more regular autonomous shuttle users than employees, or unemployed and retired people (Portouli et al., 2017). This can also be attributed to an age effect.

Regarding the **place of residence**, people living in India were more willing to let their children use a driverless school bus than US residents (Anania et al., 2018). There was no difference in willingness to use an autonomous shuttle between residents and visitors to La Rochelle (France) and residents and visitors to Lausanne (Switzerland; Madigan et al., 2016). People living in highly populated areas are more willing to use highly automated buses (Roche-Cerasi, 2019). Intention to use an autonomous shuttle did not differ between Germans living in rural areas and Germans living in urban areas (Kostorz et al., 2019). However, American participants stated that they were more willing to

1 use an autonomous bus in the USA than in Russia, China, India, Nigeria, Indonesia or Brazil (S. R.  
2 Winter et al., 2018). Trust in, and willingness to use, an autonomous shuttle was found to be greater  
3 in participants living in regions where autonomous shuttle services had been implemented than in  
4 regions where no autonomous shuttles were in operation (Dekker, 2017). However, participants  
5 working on a German campus rated an autonomous shuttle as less efficient than their current means  
6 of transport than participants who did not work on the campus (Nordhoff et al., 2018).

#### 7 3.2.2.2 Travel behaviour factors

8 A number of studies have assessed the effects of travel behaviour, such as travel habits, purpose of  
9 travel and weather, mobility difficulties and attitudes towards using public transport.

10 Studies have established that **purpose of travel** and the **weather** have an impact on acceptance.  
11 Autonomous transport with fixed schedules appears to be better accepted for fixed travel purposes  
12 (work, education) than for flexible travel purposes (for example leisure; Földes et al., 2018).  
13 However, in another study, 56% of respondents stated that they were willing to use an autonomous  
14 shuttle for leisure trips, and only 41% for business trips (Kostorz et al., 2019). In conditions of bad  
15 weather, people would be more willing to use an autonomous shuttle rather than to walk or hire a  
16 bicycle (Nordhoff, de Winter, et al., 2019; Wicki et al., 2019).

17 In addition, a positive **attitude towards public transport** was found to be associated with a  
18 willingness to use APTVs (Acheampong & Cugurullo, 2019), in particular, autonomous shuttles  
19 (Kostorz et al., 2019).

20 Regarding **travel habits**, K. Winter et al. (2019) showed that people who use public transport once a  
21 month or more are more willing to use an autonomous shuttle instead of a traditional bus, than  
22 people who use public transport less frequently. Another study states that car users and public  
23 transport users might be more willing to change their travel habits to using autonomous transport  
24 for journeys to work, than pedestrians and bicycle users (Földes et al., 2018). According to a study  
25 conducted by Motak et al. (2017), walking, the belief that public transport comes with too many  
26 constraints and knowing about autonomous technology all tend to explain intention to use an  
27 autonomous shuttle. Kostorz et al. (2019) concluded that bicycle users, public transport users and  
28 people using at least three different means of transport per week were more willing to use an  
29 autonomous shuttle than drivers. They also showed a positive association between feeling at ease in  
30 a car and the intention to use an autonomous shuttle. However, other studies do not reveal any  
31 effect of an individual's current use of a car or public transport on their willingness to use APTVs  
32 (Pakusch & Bossauer, 2017). Nor has any effect of frequency of public transport use (Wien, 2019), or  
33 frequency of bus use been observed on willingness to use APTVs (Dong et al., 2017). In addition, no  
34 association has emerged between public transport use and trust in autonomous shuttles (Dekker,  
35 2017). Moreover, neither possession of a monthly public transport pass nor access to a car had any  
36 effect on preference for autonomous shuttles over manually-operated shuttles (Alessandrini, Delle  
37 Site, Gatta, et al., 2016). Finally, people with the most flexible travel habits (for example car drivers)  
38 preferred on-demand autonomous vehicles to autonomous public transport with fixed schedules  
39 (Földes et al., 2018).

40 The presence or absence of **mobility difficulties** can also have an effect on acceptance. Faced with  
41 the choice of an autonomous shuttle, a rented bicycle or walking, the ability to walk unaided and  
42 without stopping for a distance of 200 m and to use a bicycle, increases the probability of choosing  
43 the most useful means of transport in terms of cost and travel time (Wicki et al., 2019). This study  
44 also showed that the presence of mobility difficulties increases the probability of choosing an  
45 autonomous shuttle out of the same three means of transport. Temporary disability (Nordhoff, de



Winter, et al., 2019), walking problems, the after-effects of surgery and the need to carry luggage (Monéger, 2018) all increased the use of autonomous shuttles in the context of a hospital campus. In addition, people with impaired mobility seem to have a greater preference for an on-board supervisor than people with no disabilities (Földes et al., 2018).

### 3.2.2.3 Personality factors

A high level of **trust in autonomous vehicles** has been found to be a factor in the choice of an autonomous shuttle over a traditional bus (Wien, 2019; K. Winter et al., 2019) or other means of transport (Dekker, 2017). Herrenkind et al. (2019) also revealed a positive association between trust in autonomous shuttles and intention to use this type of vehicle. Attitudes towards technology have been found to be positively associated with the perceived usefulness of APTVs, and perceived behavioural control. These attitudes have been negatively associated with concerns about using APTVs (Acheampong & Cugurullo, 2019). However, Chen's study (2019) indicates that trust in autonomous shuttles positively modifies attitude towards them but does not have a significant direct effect on intention to use this type of transport. A positive **attitude towards autonomous shuttles** is associated with intention to use (Chen, 2019; Kostorz et al., 2019).

Numerous studies have observed that **interest in technology** is a factor of acceptance. Participants who are more positive about technology are more willing to try an autonomous vehicle (Földes et al., 2018), to choose an autonomous shuttle over a traditional bus (Wien, 2019; K. Winter et al., 2019) or to choose an autonomous shuttle instead of walking or renting a bicycle (Wicki et al., 2019). However, competence in technology or the feeling of having a high level of control over technology (i.e. a person's belief in their own ability to use technology) does not seem to have an effect on the choice between an autonomous shuttle and walking or renting a bicycle (Wicki et al., 2019). Confidence in technology also influences intention to use autonomous shuttles (Motak et al., 2017). Finally, a significant association between attraction to innovation and perceived ease of use of autonomous shuttles has been observed, but this is not the case for perceived utility (Herrenkind et al., 2019).

Perceived **behavioural control**, that is an individual's confidence in his/her own ability to use an autonomous shuttle, is another personality factor which has been shown to have an effect on intention to use (Motak et al., 2017). However, a negative association between the **need to control** and attitudes towards autonomous shuttles has also been observed (Herrenkind et al., 2019).

According to one study (Motak et al., 2017), **ecological values** are not a predictor of intention to use an autonomous shuttle, and they were not significantly associated with perceived usefulness in another (Herrenkind et al., 2019). They were, however, found to be positively associated with the perceived usefulness of APTVs and with intention to use APTVs in a third study (Acheampong & Cugurullo, 2019).

*Table 2. Factors of acceptance, acceptability or usage related to the micro-levelors and the number of studies that investigated them (n)*

Themes	Factors	n
Socio-demographics	Age	Acceptability studies: 6 Acceptance studies: 7 Acceptability/acceptance studies: 2 Acceptability/usage studies: 1
	Gender	Acceptability studies: 9 Acceptance studies: 5 Acceptability/acceptance studies: 2

	Education	Acceptability studies: 6 Acceptance studies: 1 Acceptability/acceptance studies: 1
	Income	Acceptability studies: 3 Acceptance studies: 1 Acceptability/acceptance studies: 1
	Employment	Acceptability studies: 1 Acceptance studies: 1 Acceptability/usage studies: 1
	Place of residence or work place	Acceptability studies: 4 Acceptance studies: 2 Acceptability/acceptance studies: 1
Travel behavior	Travel purpose and weather	Acceptability studies: 2 Acceptance studies: 1 Acceptability/acceptance studies: 1
	Attitude towards public transport	Acceptability studies: 2
	Travel habits	Acceptability studies: 6 Acceptance studies: 1 Acceptability/acceptance studies: 2
	Mobility difficulties	Acceptability studies: 1 Acceptance studies: 2 Acceptability/acceptance studies: 1
Personality	Trust in autonomous vehicles	Acceptability studies: 4 Acceptance studies: 2 Acceptability/acceptance studies: 1
	Technology interest	Acceptability studies: 3 Acceptance studies: 2 Acceptability/acceptance studies: 1
	Control	Acceptance studies: 2
	Ecological values	Acceptability studies: 1 Acceptance studies: 2

Table 3. Overview of the studies selected in the present literature review

Reference	Vehicle	Methods	Participants	Exposure to autonomous vehicle	Factors studied
Acheampong & Cugurullo, 2019	Autonomous vehicles including APTV	Online survey (54 items; Likert scales)	507 adults living in the Greater Dublin Area of the Republic of Ireland	Unspecified	Perceived expectancy Effort expectancy Concerns Subjective Norm Age Gender Education Attitude towards public transport Interest in technology Ecological values
Alessandrini, Delle Site, Stam, et al., 2016; Alessandrini et al., 2015; Alessandrini, Delle Site, Gatta, et al., 2016; Alessandrini et al., 2014	Autonomous shuttle	Stated preference questionnaire (face-to-face, online, or telephone)	3326 potential users of autonomous shuttles in 12 European cities (167-742/city) For the study of Alessandrini, Delle Site, Stam, et al. (2016): sub-sample of 1714 potential users of autonomous shuttles in 4 cities	No exposure (study conducted before implementation of autonomous shuttles)	Waiting time Travel time Location context Fares Age Gender Education Income Employment Travel habits
Anania et al., 2018	Autonomous school bus	Online questionnaire (7 items; Likert scales + an emotion scale in study 2)	Study 1: 50 participants (25 females) living in the United States (within-subjects design); Study 2: 610 participants (274 females) living in the United States or in India (between-subjects	Unspecified (probably no exposure)	Gender Place of residence

			design). Convenience sampling using Amazon's® Mechanical Turk®		
Chen, 2019	Autonomous shuttle	Self-administered questionnaire on paper (21 items in Likert scale + questions about respondent's characteristics)	Random selection of 700 questionnaires /1498 correctly completed / 1658 completed by passengers of an autonomous shuttle. Convenience sampling	Data collection after a trial on an autonomous shuttle in a scooter-dominant urban context	Performance perceived Effort perceived Perceived pleasure Age Gender Trust in autonomous vehicles Attitude towards autonomous shuttles
Dekker, 2017	Autonomous shuttle	Online questionnaire (12 Likert scales items + 6 state preference questions + 9 questions about respondent's characteristics; 5-10 min)	195 correctly completed questionnaires/198 questionnaires completed by participants working in three business areas (including one area served by an autonomous shuttle). Sample quite representative of the Dutch labour force, but with a greater proportion of men and a higher income and educational level	Exposure measured: 13.8% of participants used the autonomous shuttle weekly, 21.5% used it once or several times, 44.6% had seen or read something about it, 20% had no experience of it	Previous experience of autonomous vehicle Waiting time Travel time Fares Location context Flexibility Supervision Age Gender Education Place of residence Income Travel habits Trust in autonomous vehicles
Dong et al., 2017	Autonomous bus	Online state preference questionnaire (Likert scales items + questions explaining	891 correctly completed questionnaires/930 respondents/3350 University of Pennsylvania employees	Effect of prior knowledge of autonomous vehicles measured (sample proportion not indicated)	Prior knowledge of autonomous vehicle Concerns: road-safety, incivilities, absence of driver Supervision

		previous responses + questions about respondent's characteristics)	who participated in a pre-tax transit commuter program contacted. Compared to transit users: under-representation of 18-24-olds and users 65 years and above; and higher income		Age Gender Income Travel habits
Eden et al., 2017	Autonomous shuttle	Collective semi-structured interviews	17 autonomous shuttle passengers in the old town of Sion (Switzerland). Sample characteristics and recruitment methods unspecified	Data collection before and after a trial on an autonomous shuttle	Previous exposure to other APTVs Knowledge of an accident caused by an autonomous vehicle Schedules Location context Seat belt Feeling of safety Vehicle speed Braking behaviour Windows Seat Noise Vehicle size
Fernández Medina & Jenkins, 2017	Autonomous shuttle	Two individual semi-structured interviews (2x60 min)	33 participants recruited from people interested in trying an autonomous shuttle but who had no professional interest in autonomous technology, mainly living, working or commuting through	Data collection before and after a trial on an autonomous shuttle	Concerns: technology failure, absence of driver Vehicle speed Braking behaviour Road-facing seats Noise Supervision

			Greenwich, London. Various ages, genders and driving status		
Földes et al., 2018	Autonomous taxis and shuttles with on-demand and fixed services	Online questionnaire with multiple choice and Likert-scale questions (respondent's characteristics, mobility habits and expectations about autonomous vehicles)	510 Hungarian participants. Sample not representative of the population	Usage cases not available in the region studied; 1/3 of the respondents had heard about autonomous vehicles	Waiting time Fares Travel information Internet access Travel purpose Travel habits Mobility difficulties Interest in technology
Fröhlich et al., 2019	Autonomous shuttle	Study 1: paper questionnaire (illustration of different designs of dynamic information displays, 2 open questions, 2 Likert- scale questions; 10 min). Study 2: questionnaire after a simulated shuttle ride (2 Likert-scale questions; 10 min)	Study 1: 56 participants, without prior experience of a shuttle, aged 15-55. Study 2: 77 participants, aged 17-90. Participants in the 2 studies recruited during a shuttle demonstration on the site of a transport research conference	Study 1: data collection after a shuttle trial Study 2: data collection after simulated shuttle trial	Information about autonomous functioning
Herrenkind et al., 2019	Autonomous shuttle	Study 1: phone individual semi- directed interviews (35 min) Study 2: online and paper survey	Study 1: 15 automotive industry experts (snowball sampling) Study 2: 268 participants recruited in a German city, sample varied in terms of gender, age, income, place of	Study 1: participants with professional experience of at least 3 years in future mobility. Study 2: participants recruited after a shuttle trial	Performance expectancy Effort expectancy Fares Concerns: personal data protection Trust in autonomous vehicle Capacity for personal innovation

			residence, familiarity with public transport (57% used this at least a few times a month)		Control Ecological values Social influence Perceived pleasure
Hinderer et al., 2018	APTV	Paper questionnaire (17 questions): age group (pupil/students, employees, retired people), distance to the nearest bus stop, satisfaction with available mobility service (6 Likert-scale questions), attitudes towards APTV (8 Likert-scale questions), APTV requirements (6 questions) and additional comment sections)	178 participants living in the village of Buechenbronn (suburban area) recruited outside the polling station during a parliamentary election. Sample composed of 2.87% of the village population	Unspecified	Performance expectancy Waiting time Fares Location context Access to the vehicle with a bicycle or a dog Age
Kostorz et al., 2019	Autonomous shuttle	Online questionnaire including Likert-scale questions (15 minutes): respondent's characteristics, mobility habits and attitudes, introduction to autonomous shuttles, attitudes towards autonomous shuttle, usage and attitudes towards	900 correctly completed questionnaires out of 1078 adult Germans surveyed. Representative sample of the German population (age, gender, rural-urban distributions)	Prior knowledge of autonomous vehicles measured. No experience of autonomous shuttles, however, the majority of participants knew of them	Prior knowledge of APTVs Effort expectancy Age Place of residence Income Travel purpose Attitude towards public transport Travel habits Attitude towards autonomous shuttles Interest in technology

		technology			
López-Lambas & Alonso, 2019	Autonomous vehicles in general and autonomous bus in particular	Two focus groups (1h30-2h)	8 participants per focus group, recruited in Madrid and Malaga. Age and gender diversity	Unspecified	Concerns: incivilities, technology failures, absence of driver Supervision
Madigan et al., 2016	Autonomous shuttle	Questionnaire on tablet (8-10 min), self-administered on site: respondent's characteristics, mobility habits, exposure to autonomous shuttle, attitude towards technology and attitudes towards autonomous shuttles	349 participants residents or visitors of La Rochelle (France) and Lausanne (Switzerland), 61.6% of males	Participants had already interacted with the shuttle	Previous experience Performance expectancy Effort expectancy Social influence Age Gender Place of residence
Madigan et al., 2017	Autonomous shuttle	Questionnaire on tablet (8-10 min), self-administered on site: respondent's characteristics and 20 Likert-scale questions performance expectancy, effort expectancy, social influence, facilitating condition, hedonic motivation and intention to use the	315 participants aged 9-65, recruited in Trikala (Greece), 54.6% of males	Participants who had used a shuttle at least once	Previous experience Performance expectancy Effort expectancy Social influence Pleasure Integration into the public transport offer Age Gender



		autonomous shuttle.			
Motak et al., 2017; Monéger, 2018	Autonomous shuttle	<p>Pilot study: 4 focus groups for the creation of the study questionnaire (1h45). Study 1: questionnaire (25-30 min, around 200 items): personal values, sociodemographic characteristics and mobility habits, introduction to autonomous shuttle, and perception and attitudes towards autonomous shuttle</p> <p>Study 2: on-site questionnaire, abbreviated version from the previous one</p> <p>Additional study from Monéger, 2018: experiment on shuttle: measure of acceptance in different conditions (with and without a manual horn; with or without a humanoid voice)</p>	<p>Pilot study: 23 occasional visitors to a hospital campus aged 19-67.</p> <p>Study 1: 370 students aged 18-25.</p> <p>Study 2: occasional visitors to the hospital campus (108 autonomous shuttle non-users of aged 16-87, and 54 first-time users aged 28-76)</p>	<p>Pilot study and study 1: conducted before the implementation of the autonomous shuttle</p> <p>Study 2: data gathering prior to implementation of the autonomous shuttle for 108 respondents, and after a trial on autonomous shuttle for 54 respondents</p> <p>Additional study: data collection after a trial on autonomous shuttle</p>	<p>Previous experience</p> <p>Performance expectancy</p> <p>Effort expectancy</p> <p>Social influence</p> <p>Perceived pleasure</p> <p>Concerns: road-safety</p> <p>Manual control means</p> <p>Supervision</p> <p>Humanoid voice</p> <p>Age</p> <p>Travel habits</p> <p>Mobility difficulties</p> <p>Technology interest</p> <p>Control</p> <p>Ecological values</p>
Nordhoff et al., 2018	Autonomous shuttle	Online questionnaire (68 items): respondent	384 participants recruited online, 274	Participants had used an autonomous shuttle	<p>Effort expectancy</p> <p>Vehicle speed</p>

		characteristics and impressions about the autonomous shuttle and the services, attitudinal questions and acceptance questions	included in the analyses		Supervision Vehicle size Age Gender Work location
Nordhoff, de Winter, et al., 2019	Autonomous shuttle	Face-to-face or phone (2/30) semi-directed interview (50 min) about acceptance factors of the autonomous shuttle	30 participants recruited from among former participants in previous studies, students or campus employees and people who expressed interest in participating in the study	Participants used the autonomous shuttle just before data collection	Previous experience Vehicle exposure Media coverage Performance expectancy Location context Travel information Flexibility Reliability Vehicle speed Braking behaviour Stop button Supervision Manual control means Automation level Large windows Free internet access Comfortable seats Internal appearance Air conditioning Vehicle size Obstacle-free access Weather Mobility difficulties
Nordhoff et al., 2017	Autonomous shuttle	Self-administered questionnaire on tablet (37 items):	326 participants recruited on an autonomous shuttle	Data collection after a trial on the autonomous shuttle; first ever trial for 95.7% of	Performance expectancy Effort expectancy Social influence

		intention to use an autonomous shuttle, perceived usefulness, ease of use, social influence, trust, ecological norms, pleasure; respondent's characteristics	demonstration site, on a campus (31.9% male, 77.1% campus employees)	participants	Integration into public transport system Age Gender
Pakusch & Bossauer, 2017	APTV	Online questionnaire: presentation of APTV, mobility habits, experience of autonomous vehicles and attitude towards APTV (Likert scales and open questions), respondent's characteristics	201 participants (18-81 years, 49.3% female) recruited online, mainly students)	91% of participants already knew about autonomous vehicles, 37.1% had already tried an autonomous vehicle (train, tram, metro, car or shuttle)	Previous experience Age Gender Travel habits
Papadima et al., 2020	Autonomous shuttle	Study 1: online questionnaire (21 items): respondents characteristics, exposure to autonomous shuttle, impressions of the pilot implantation of autonomous shuttle Study 2: online conjoint analysis; attributes: information provision mode, frequency of service, stop facilities, walking	Trikala citizens recruited online Study 1: 158 participants (48.7% female, 70.3% permanent Trikala citizens) Study 2: 43 participants	Study 1: 78% of participants had never tried an autonomous shuttle; 12% had tried one; 9.5% used one daily.	Frequency Fares Travel information Supervision Access and characteristics of stops

		distance from bus stop, supervision, fares			
Piao et al., 2016	Autonomous vehicles, including autonomous shuttle	Questionnaire administered online and by phone (28 items): knowledge of autonomous vehicles, attractiveness and concerns about autonomous shuttles, taxis and cars, and attitude towards owning and sharing autonomous cars	Online questionnaire: 148 participants living near an autonomous shuttle demonstration. Phone questionnaire: 352 participants living in the La Rochelle area. After resampling to correspond to local demography in terms of age, gender and education: 425 participants (53.6% female)	Participants living, working or studying in a city with an autonomous shuttle demonstration, 87% of them had heard about autonomous vehicles, and a minority (rate unclear) had already tried an autonomous shuttle	Fares Concerns: incivilities, night service Supervision
Portouli et al., 2017	Autonomous shuttle	Study 1: face-to-face questionnaire: respondent's characteristics, previous exposure to the autonomous shuttle, satisfaction with it, usefulness, safety perceived, and willingness to use it and pay for it Study 2: paper questionnaire: attitude towards autonomous vehicles, attractiveness, concerns and	Study 1: 200 autonomous shuttle passengers (105 females) Study 2: 519 Trikala citizens (urban and suburban areas)	Study 1: participants were autonomous users; 40% had used once, 42.5% twice, 17% 3-5 times and 1 person more than 5 times Study 2: participants were aware of an autonomous shuttle demonstration in Trikala; 318 participants had never used the autonomous shuttle, 105 were regular users	Previous experience Fares Supervision Age Education Employment

		preferences			
Ramseyer et al., 2018	Autonomous shuttle	Individual interviews. Before an autonomous ride: concerns, anticipated advantages, and advance description of the ride After the ride: description of the ride, positive and negative impressions, things to be changed, changes in previous concerns and intention to use autonomous vehicles	21 students in risk management from a university in Switzerland	Data collection before and after a trial on an autonomous shuttle (1 <sup>st</sup> exposure to an autonomous vehicle)	Waiting time Vehicle speed Braking behaviour Supervision Manual control means Windows Seating configuration
Roche-Cerasi, 2019	Autonomous shuttle (+ 1 question about autonomous bus)	Online questionnaire (27 questions): mobility habits, transport priorities, autonomous shuttle experience and their usefulness, concerns and trust and respondents' characteristics	1479 members of the car federation of Norway (19-98 years, 80.7% male). Sample unrepresentative of the Norwegian population (in terms of age, gender, income, travel habits).	91.8% of respondents had heard of autonomous shuttles; 1.4% had tried one	Location context Concerns Automation level Age Gender Education Place of residence
Salonen, 2018	Autonomous shuttle	Face-to-face questionnaire: perceptions of traffic safety, on-vehicle security and emergency	197 autonomous shuttle passengers during an important design exhibition in Finland (61.9% female; discretionary sampling)	Data collection after a trial on an autonomous shuttle	Age Gender Education Income Employment

		management on an autonomous shuttle compared to a bus travelling in the same conditions, and respondent's characteristics			
Salonen & Haavisto, 2019	Autonomous shuttle	Semi-structured individual interview (10-15 min): reaction to the autonomous shuttle, attitudes towards it, social factors and passenger's feelings	44 autonomous shuttle passengers on a route between a metro station and a university in Helsinki (45.5% females, 15-64 years, 50% students)	Data collection after a trial in autonomous shuttle	Previous experience Knowledge of an accident Media coverage Frequency and schedules Location context Flexibility Concerns: algorithm of decision-making Vehicle speed Supervision
Stark et al., 2019	Three use cases, including autonomous vehicle on a traditional bus route, and first and last mile service	Workshops including 3 focus groups and individual interviews about the needs, requirements and challenges of APTV	13-16 workshop participants recruited online: public transport users, local authorities and transport operators	Unspecified	Waiting time Fares Integration with other transport means and intramodality Location context Travel information Reliability Flexibility Concerns: personal data protection, night service Vehicle speed Countermeasures: child safety seats, registration of passengers, video and audio surveillance, respect of

					security standards Vehicle size Obstacle-free access Gender
Vöge & McDonald, 2003	APTV and personal autonomous automobile	23 focus groups and individual interviews	Total N unspecified (>257). Potential users, non-users, public decision makers, public and private operators in seven countries (such as France, Israel). 10-12 participants /focus group; 27 participants for individual interviews	Unspecified	Waiting time Fares Integration with other transport means Location context Travel information Flexibility Vehicle speed Countermeasures: seat belts, prohibition of standing, communication means, autonomous medical emergency management Manual control means Information about autonomous functioning Free internet access Vehicle appearance Cleanliness Vehicle size Obstacle-free access Overloading prevented
Wicki et al., 2019	Autonomous shuttle	Online state preference questionnaire (13 min) with 3 alternatives: autonomous shuttle, walking and rented bike and respondent's	879 respondents out of 1080 adult residents of the Canton of Schaffhausen invited to participate. Analysis on data of the 761 respondents who knew	Respondents already knew about an autonomous shuttle test	Previous experience Waiting time Travel time Fares Occupancy rate Weather Mobility difficulties

		characteristics	about an autonomous shuttle test in the Canton		Interest in technology
Wien, 2019; K. Winter et al., 2019	Autonomous shuttle	Online state preference questionnaire with 3 alternatives: autonomous shuttle and regular bus and an opt-out alternative, respondent's characteristics	282 questionnaires completed out of 305 citizens and employees surveyed in two municipalities (Vaals, Netherlands, and Aachen, Germany) where autonomous shuttles were to be implemented. Respondents used public transport at least yearly (48.9% female). Sample representative of public transport users in the Netherlands	No previous exposure (data collection before implementation of an autonomous shuttle trial)	Waiting time Travel time Fares Flexibility Supervision Age Gender Travel habits Trust in autonomous vehicles Interest in technology
S. R. Winter et al., 2018	Autonomous bus	Online questionnaire with two scenarios: autonomous bus or regular bus and a willingness to ride scale (study 1: within-participants design; study 2: mixed-participants design)	Study 1: 510 American participants (226 females) Study 2: 571 American participants (276 females). Convenience sampling on Amazon Mechanical Turk	Unspecified	Gender Vehicle user (self or family member) Place of residence
Wintersberger et al., 2018	Autonomous shuttle	Face-to-face questionnaire about respondent's characteristics and expectations and	12 participants, aged under 35, recruited on the autonomous shuttle pilot site in a Bavarian city	Participants had no exposure prior to the study; data gathered before and after an autonomous shuttle trip and a trip in a regular taxi	Previous experience Travel duration Vehicle speed



		individual semi- directed interview about opinions			
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## 4 Discussion

The deployment of APTVs is relatively recent, and they exist mainly in the form of autonomous shuttles as part of pilot experiments (The Aspen Institute Center for Urban Innovation, n.d.). The literature review presented in this paper, which aims to contribute to the design and implantation of this new mode of transport, so that it meets the needs of the greatest possible number of potential users, provides a fairly exhaustive review of the factors of acceptability, acceptance and use of APTVs. This literature review offers ways of alleviating concerns and of encouraging the future use of APTVs. It could serve as a guideline for designers, manufacturers and policy makers, and help them to provide autonomous mobility services which correspond to the needs of users and potential users.

As suggested by the MAVIA model (Nordoff et al., 2019), the process of acceptance starts with the exposure of the individual to the autonomous vehicle in a first stage. The exposure can consist of a real usage or simply to some knowledge about the autonomous vehicle. This first stage is crucial because it moves to the formation of either a favorable or unfavorable attitude towards autonomous vehicles (stage 2) which can influence the decision to adopt it (stage 3) and to use it (stage 4). In accordance with the MAVIA model, a negative experience with an autonomous vehicle may affect the future usage of APTVs. As shown in the present literature review, individuals who have experienced negative exposure related to vehicle safety, to on-board security or abrupt braking experience on an autonomous shuttle may have an unfavorable attitude towards this type of vehicle in the future, limiting their intention to use it

At the opposite, many factors may lead to the formation of a favorable attitude increasing willingness to use APTVs. These factors relate mainly to the ways in which APTVs could improve mobility services and were also found by Nordoff et al. (2019) and presented at the domain-specific system evaluation level. Potential users estimate that they would save time and money, be more comfortable on-board and have good visibility from the vehicle. Free internet access, comfortable and well oriented seats are also factors contributing to a positive attitude towards the APTV. Most of the personal factors which are consistently found to be positively associated with willingness to use APTVs can be influenced by the vehicle's characteristics or by the level of mobility service offered. Trust in autonomous vehicles, users' performance expectancy and effort expectancy, social influence and perceived pleasure might therefore be greater when users or potential users interact with APTVs which are secure, reliable, useful, efficient, comfortable, accessible, easy and pleasant to use. In this perspective, positive exposure to an autonomous vehicle (through experience, word-of-mouth or the media) can increase the likelihood of using an APTV.

The literature review of Jing et al. (2020) conducted on any kind of autonomous vehicles also indicated that psychological factors have proven to be predictors of acceptance intention. They reported that the effect of the psychological variables on the acceptance may be direct or indirect. The authors also highlighted that there are complex interactions between variables, the choice to use or not an APTV is thus multifactorial. The presence of interactions between factors may explain that results sometimes appear divergent in the literature. Low vehicle speed, for instance, can be perceived both as a marker of security, and a sign of inefficiency. The presence of supervision, which can be reassuring for some users, can also be perceived as evidence that the vehicle is not entirely reliable by others. Discrepancies surrounding personal factors, in particular socio-demographic characteristics, also exist. Although male and younger users and potential users appear to have a more positive attitude towards APTVs in some studies, not all studies point in the same direction

regarding the effects of gender, age, education level and place of residence. In addition, inconsistencies around ecological values could be related to the fact that autonomous vehicles can be seen as being both ecological (since they are commonly associated with electric vehicles), and as non-ecological (compared to walking or cycling). However, these contradictory results could also be related to differences between studies in terms of methodology (qualitative interview or online survey; involving a shuttle trial or not), nature and size of study samples, usage contexts (campus, city center or rural environment) or vehicle considered (shuttle, buses). In one study, for example, participants indicated that their positive perception of the safety of an autonomous shuttle might change if the vehicle was larger (for example a bus), if there was no supervisor, or if the journey took place on a real road and at normal speed (Eden et al., 2017).

To summarize, the factors of acceptance of APTVs the most cited in the literature relate to the quality of the service on offer, as is the case for every means of public transport. As research has shown, autonomous aspects seem to matter less than the improvement of mobility services (Fernández Medina & Jenkins, 2017; Hinderer et al., 2018). Nevertheless, the autonomous aspect of APTVs and the absence of a driver bring new concerns. These concerns are about the vehicle's total dependency on technology, poor braking behaviour, safety and on-board security. Factors related to comfort and vehicle access appear to be less central, but results on these may be due to the fact that samples studied are not always representative, and do not include the profiles of all potential users. Elderly people and people with disabilities, who are not explicitly included in the studies we reviewed, may have greater needs in terms of accessibility or comfort. In addition, for both safety and acceptability issues, implementation of APTVs which are unreliable and inefficient appears to compromise the future use of these vehicles. While rail-bound autonomous public transport vehicles (subways, trains, trams) are now a full part of the transport supply, and are preferred over non-rail autonomous public transport vehicles (Pakusch & Bossauer, 2017), these new autonomous systems give rise to concerns, and raise questions about their acceptability.

One limitation of the present literature review was that the majority of the studies reviewed here consisted of surveys conducted on respondents who had never used an APTV. Some of the findings are therefore based on the projections of potential users rather than on the actual opinions of real users, limiting their generalization. As it is the case for recent publications (Bernhard et al., 2020; Hilgarter & Granig, 2020), it can be reasonably expected that as more and more APTVs are introduced, future studies will focus more on individuals who have already tried one of these vehicles, or who even use them for day to day travel. Future studies will go on to fine-tune the findings of our present review of the literature.

#### 4.1. Conclusion and recommendations

As highlighted by the present review, it is important not to expose the public to pilot implementations with negative experience, especially those involving bad braking behaviours and which do not meet mobility needs. It is essential to propose secure, useful and comfortable autonomous systems if we wish to encourage more wide-spread adherence to APTVs. To alleviate users' concerns, rules such as the prohibition of standing when the vehicle is in motion could be imposed. Preventive equipment, such as seat belts, child safety seats, video surveillance or a means of dealing with emergencies (for example, a button for emergency stops or to open the doors and a means of communication) could also be made available.

Potential users also require a means of compensating for the absence of a driver - for example, information screens and easy, obstacle-free access to the vehicle. As for the location of APTV implementation, normal urban traffic conditions are seen as less acceptable. Implementation in a more secure context, for example on dedicated routes, on campus, or in areas with no public transport links, such as rural areas, is seen as preferable.

A great deal remains to be done before APTVs, which correspond completely to users' needs can be successfully implemented. Although many pilot experiments with autonomous shuttles have been conducted, they have not yet managed to entirely convince all potential users. The latter continue to express concerns about safety, security, usability, accessibility and comfort. This review of the literature allows us to conclude that in order to improve acceptance of APTVs, users' confidence in them must increase.

Finally, a number of factors cited across studies should be investigated more thoroughly in future research in order to assess their impact on acceptance of APTVs. These factors are the display of information about autonomous functioning, vehicle appearance, air-conditioning, cleanliness, prevention of vehicle overload, vehicle access with a bicycle or a dog, and some stop characteristics. Similarly, relatively little research has been carried out on personal factors, such as attitudes towards public transport, behavioural control and need for control.

Other studies are required to analyze the needs, expectations and concerns of elderly people and people with disabilities in greater detail. Although some of the studies included in the present review evoke the needs and concerns expressed on this subject by respondents, APTV accessibility for people with disabilities and the elderly does not seem to have been studied specifically (Tabattanon et al., 2019).

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