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### Advanced data pre−processing for Comprehensive two−dimensional Gas Chromatography with Vacuum Ultraviolet Spectroscopy detection

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#### **Abstract**

Comprehensive two−dimensional Gas Chromatography with Vacuum Ultraviolet detection  $(GC \times GC / VUV)$  results in sizable data for which noise and baseline drift ought to be corrected. As GC×GC/VUV signal is acquired from multiple channels, these pre−processing steps have to be applied to data from all channels while being robust and rather fast with respect to significant size of the GC×GC/VUV data. In this study, we describe advanced GC×GC/VUV data pre−processing techniques for noise and baseline correction that are not available in commercial softwares. Noise reduction was performed on both the spectral and the time dimension. For baseline correction, a morphological approach based on iterated convolutions and rectifier operations is proposed. On the spectral dimension, much less noisy and reliable spectra are obtained. From a quantitative point of view, mentioned pre−processing steps significantly improve signal to noise ratio for analyte detection and hence improve their limit of detection (circa 6 times in this study). These pre−processing methods were integrated into plug im! platform [\(https://www.plugim.fr/\).](https://www.plugim.fr/plugin/107)

*Key words*: comprehensive two−dimensional gas chromatography, vacuum ultraviolet detection, data pre-processing, baseline correction, noise reduction

## **1 Introduction**

Analysis of multidimensional chromatography data can be extremely complex, hence strategies and approaches for data analysis must be carefully devised in order to obtain the most from the available information. Before applying intricate data analysis techniques, comprehensive two−dimensional gas chromatography (GC×GC) data must be subjected to pre−processing. Pre−processing techniques are applied with a goal of eliminating irrelevant chemical variations and often include noise reduction procedures, baseline correction, normalization, and retention time alignment [1, 2]. After data pre−processing, the challenge is usually to identify compounds peaks and perform quantification [2].

Vacuum ultraviolet detector (VUV) has been recently successfully hyphenated with  $GCxGC$ analysis [3–5]. This analysis technique has a lot of potential for analysis of complex samples, particularly in the field of fuel analysis. Although  $GC \times GC/VUV$  data processing is specific to chosen application, it generally begins with integrating an interval of a spectral band. This operation is called 'spectral filtering'. Further processing procedure can be reduced in a rather classic way to the following sequence of steps: baseline correction, detection of peaks corresponding to compounds of interest and peak integration [1, 6]. Concerning softwares for processing and analysis of  $GC \times GC/VUV$  data, previous studies mainly rely on homemade Matlab software [4, 5] and GC Image [7] which is as far as our knowledge the only commercial software supporting direct import of the  $GC \times GC/VUV$  data.

In this work, we propose a strategy for advanced pre−processing of GC×GC/VUV data. Adaptive noise reduction and robust and fast baseline correction methods are described. For baseline correction, a morphological approach based on iterated convolutions and rectifier operations is proposed. VUV detector blank signal subtraction was also performed. This data pre−processing approach was evaluated regarding enhancement of the detection limits in  $GC \times GC/VUV$  analysis as well as improvement of quality of data obtained for real complex samples.

### **2 Data processing methods**

### **2.1 Noise reduction**

 $GC \times GC/VUV$  data can be quite noisy, owing to high acquisition frequencies which are necessary for  $GC \times GC$  analysis. As VUV detector possesses moderate sensitivity, in the case of  $GC \times GC/VUV$ analysis it is important to apply noise reduction as this can help to significantly improve obtained signal to noise (S/N) ratio [8].

Our approach for noise reduction uses a wide range of noise reduction filters whose parameterization, linked to the size of the calculation neighbourhood, adapts automatically and locally to the signal. Classical linear filtering techniques express the smoothed value at one point as a linear combination of the values of the samples located in the interval around the considered point. This filtering can be interpreted in terms of a scale corresponding intuitively to the length and the weighting applied. The choice of the right filtering scale is crucial in order to preserve as much as possible the local properties of the signal we wish to analyse. However, this good scale (unknown a priori) can vary from one point to another, and most of the time leads the user to choose filtering parameters allowing a compromise on the whole signal.

• *Noise reduction on the spectral dimension:*

The most important strategy to reduce noise for VUV data is based on the observation that any VUV spectrum inherently possesses monotonous nature, without high frequency variations. Thus, VUV spectrum at every point of the  $G C \times G C$  chromatogram can be smoothed efficiently by choosing a number of points in the averaging window, calculating the mean value in the window and repeating this operation until the entire observed spectral range is covered.

• *Noise reduction on the time dimension:*

Above mentioned approach ensures the majority of the  $GcxGC/VUV$  data noise smoothing effect, however an additional smoothing can be applied on the chromatographic dimension (for all wavelength channels). This approach was already published in [9] and can be described as follows. Let *s*(*x*) be a signal with noise to correct and composed by a set of peaks. Let us agree on the terms, "smoothing the noise" in our context, means eliminating peaks of the signal *s* corresponding to noise while modifying as little as possible the other peaks of *s* corresponding to useful information. It is assumed that noise peaks correspond to peaks of lower intensity and width than peaks containing useful information. The elimination of a peak is equivalent to transforming *s* locally for this peak into a slowly varying function passing through this peak at best. On the other hand, *s* must be modified as little as possible (or not at all) for peaks containing information (see Figure 1). Let  $f_\alpha$  be a smoothing function parameterized by the variable  $\alpha$ . The higher the  $\alpha$  is, the more important the smoothing is. Such a function can be a Gaussian kernel. Let *M* be the maximum value that parameter *α* can reach. All peaks of *s* with width greater than *M* are considered relevant information. Finally, let *m* be an incremental step for parameter *α*. For each point *x*, a parameter *α*

is calculated to adapt the smoothing function locally. The optimal parameters  $\alpha_*(x)$  are obtained for the minimum residue between two consecutive smoothed functions:

$$
\alpha_{*}\left(x\right) = \alpha \bigg|_{\alpha \in [m,M]} \min\left| s * f_{\alpha}\left(x\right) - s * f_{\alpha-m}\left(x\right)\right| \tag{1}
$$

The corrected noise signal is then obtained by convolution with  $f_{\alpha_*(\chi)}$ :

$$
s * f_{\alpha_*(x)} \tag{2}
$$

It should be noted that Equation (1) can be seen in a continuous framework as the search for each *x* of the parameter *α* allowing to obtain in *x* the minimum of the derivative with respect to *α* from *s* convolved with *f*.



Figure 1: Principle of the action of the filter: filter minimally modifies the peaks containing information (peaks of high intensity and rather isolated), and smooths strongly the peaks corresponding to noise (peaks of low intensity and spaced close together).

#### **2.2 Baseline correction**

Observed detector signal in general can be defined as a sum of useful information, high frequency perturbation i.e. noise (no information) and low frequency trend i.e. baseline (no information). Baseline drift is a common problem in chromatographic studies. Baseline drift in the case of GC×GC/VUV analysis can occur due to column stationary phase bleed and/or low−frequency variations in the detector and/or instrument parameters (e.g. flow). Baseline correction is performed with a goal to improve analytes detection and quantification which otherwise may be affected by baseline interference. Baseline correction methods ought to be carefully administered in order to preserve relevant information (even broadened coeluting peaks which might be incorrectly attributed to low frequency baseline variations) but also overfitting ought to be avoided. In the case of multichannel detectors (which is the case of VUV), baseline correction ought to be applied for all channels, after what baseline noise ought to be centred on zero for the entire length of the chromatographic separation.

Baseline correction can be based on physical or mathematical approaches. Physical approaches usually require changes in the instrumental set−up. These are for example wavelength−shifted excitation [10–12] and time gating techniques [13–15]. Mathematical approaches mainly include polynomial fitting based methods, penalized least square based methods, first derivative based methods, peak detection and interpolation methods, peak detection and interpolation, wavelet transform based methods and morphology based methods [16, 17].

Morphological approach to baseline correction consists in defining a baseline as a rigid / deformable element which can be placed under a curve (kind of elastic more or less stretched under a curve). Basic morphological operators include: erosion, dilation, opening and closing. Mathematical morphology is mostly applied in the image processing field. For baseline correction, the application of mathematical morphology is considered mostly for the Raman spectroscopy signal [16, 18–21]. The advantages of mathematical morphology for the baseline correction include possibility of fast, robust and automated methods which can be advantageous for many applications, but also that they are well adapted to analysis of 1D GC and 2D GC data. Early implementation of the approach based on morphology operations was provided in the work by Perez−Pueyo et al.[18] who proposed an automated approach based on changing the size of the structuring elements and calculating the opening of the spectrum until three consecutive equal openings are obtained. Further top−hat transformation (subtraction of an opening operation to the signal) was applied to obtain a baseline free spectrum. Disadvantages of this approach involved possible distortion of Raman peaks and estimation of baseline which does not correspond to the conventional smooth nature of the background signal. Chen and Dai [16] subsequently modified this approach by proposing iteration of morphological operations leading to gradual estimation of the baseline. Koch et al.[21] developed an approach involving iterations of erosion operations which provides estimation of baseline together with mollification which smooths the baseline. Chen et al.[17] proposed automated baseline correction based on alternating sequential filters (iterations of closing and opening operations) and convolutions. Chen and Hsu [22, 23] developed an approach involving iterations of convolutions and erosion operations.

Morphological closing operation, with horizontal segment or disc for example, leads to interesting results. Disadvantages of this approach however include: discrete implementation, high time computation, and standard image processing algorithm are not directly transposable to signal (for point (x,y), x can be discrete but y has real value). Segment with local fitting length can be also employed [2, 24] producing similar result to closing operation.

The approach proposed in this work for  $GC \times GC/VUV$  data baseline estimation is taken from a previous patent [25] and belongs to approaches based on iterations of convolutions and thresholding operations [17, 21, 22]. At each iteration, a baseline passing through the fluctuations of s is obtained from a convolution operation. A rectifier is used to extract the lower part of this curve. The smoothing operation is repeated only on this lower part, thus allowing to gradually constrain the curve to position itself close to the local minima of s. One iteration of this operator is formulated as follows:

$$
F_{\alpha}(s) = s * f_{\alpha} - \text{ReLU}(s - s * f_{\alpha})
$$
\n(3)

$$
ReLU(x) = x^+ = max(0, x)
$$
\n(4)

with f*<sup>α</sup>* a Gaussian kernel with parameter *α*. Baseline is defined as n compositions of F*α*:

$$
\mathbf{b} = (F_{\alpha}(s) \circ F_{\alpha}(s) \circ \ldots \circ F_{\alpha}(s)) * f_{\alpha}
$$
\n(5)

$$
\mathbf{b} = (F_{\alpha}(s))^n * f_a \tag{6}
$$

Illustration of the proposed approach is provided in Figure 2. Figure 3 shows the influence of increasing of the number of iterations.



Figure 2: Illustration of the approach for baseline correction ( $\alpha = 20$ ).



Figure 3: Influence of the number of iterations on baseline estimation ( $\alpha = 20$ ).

The advantages of the proposed approach for baseline correction include: only two parameters, very fast computation with real time preview accessible for  $GC \times GC/VUV$  data (> 1Gb), handling signal with mixtures of low and high peak intensities, no model dependency for baseline. Disadvantages include: non−intuitive settings, i.e. need to make a "trial and error" adjustment.

#### **2.3 Detector spectral blank subtraction**

Inherent to GC×GC/VUV data is also a detector blank signal which is varying depending on the observation wavelength. It can be seen in Figure 4, which shows measured blank detector signal, that noise is more dominant at certain wavelengths, i.e. in the beginning and the end of chromatogram. If detector blank is not subtracted, then VUV spectra extracted from a chromatogram zone may contain a summed contribution of detector blank signal which can distort the spectrum as it is shown in the Results section.

Our approach for subtracting the detector blank consists in estimating a contribution of detector in a  $GC \times GC$  chromatogram zone without analyte signal (see Figure  $S6$  in Supplementary material) and then calculating its average for a single pixel. This detector blank spectrum is then subtracted from spectra at each pixel of the chromatogram.



Figure 4: Measured detector blank spectrum.

# **3 Materials and methods**

For the investigation of the improvement of detection limits for  $GC \times GC/VUV$  data through application of described pre−processing methods, a standard test mixture was first analysed. It consisted of various hydrocarbons diluted in toluene, all of purity 95% or greater (detailed composition is provided in Supplementary material). Also analysed is a real sample, a gas oil diluted in toluene, provided by IFP Energies Nouvelles (Solaize, France).

For GC×GC/VUV experiments, an Agilent 7890A gas chromatograph under hydrogen as carrier gas equipped with a G3486A CFT forward fill/flush differential flow modulator was employed. A normal configuration column set was chosen: DB−1 column (100% dimethyl polysiloxane; 20 m, 0.1 mm ID, 0.4 *µ*m; Agilent Technologies, Inc.) was used in first dimension whereas BPX−50

(50% Phenyl Polysilphenylene−siloxane, 3.2 m, 0.25 mm ID, 0.25 *µ*m; SGE) was used in second dimension.

*For gasoil analysis:* 1 *µ*L injected, 80:1 split ratio. Flow rates in first and second dimensions were set to 0.15 ml/min and 13 ml/min, respectively. Oven temperature program was 50 ◦C (3 min) to 325 °C at 2.5 °C/min. Modulation period was set to 4.5 s while modulation injection time was set to 0.19 s. Modulation parameters were optimised according to our previous work [26].

*For standard mixture analysis:* Split injections were performed with a temperature programmed MMI Agilent inlet operated in split mode (0.1  $\mu$ L split injections with 50:1 split ratio). Flow rates in first and second dimensions were 0.15 ml/min and 13 ml/min, respectively. Oven temperature program was 50 °C (3 min) to 245 °C at 2.5 °C/min. Modulation period was set to 4.5 s while modulation injection time was set to 0.19 s.

VGA−101 (VUV Analytics, Inc., Austin, TX, United States) detector was employed. VUV conditions were as follows: wavelength range, 125–430 nm; acquisition frequency, 33.33 Hz; flow cell and transfer line temperature 325 ◦C, make−up gas pressure 0.15 psig.

Agilent ChemStation B.04.03−SP1 and VUVisionTM 3.0.1 were used for GC×GC/VUV data acquisition. plug im! software was employed for data pre−processing and extraction of spectra [27]. GC Image 2.7 software was employed for data integration.

# **4 Results and discussion**

## **4.1 Improving spectral data quality with pre-processing**

To illustrate the importance of data pre−processing for GC×GC/VUV data, a gasoil was first analysed, and a summed VUV spectrum was extracted for the zone of chromatogram where alkenes and cycloalkanes typically coelute (Figure 5). As absorbance is additive, having a reliable spectrum from this zone may allow to discern individual quantities of these two groups trough spectral decomposition. Extracted spectrum from the raw data (see Figure 6A trace in black) illustrates the necessity for pre−processing as the spectrum is very noisy and exhibits a shape that is not characteristic of the mixture of the two mentioned groups of compounds (see the VUV library spectra for two representatives of alkenes and cycloalkanes families in Figure 6B).



1D retention time (min)



For noise correction, first VUV spectral filtering (noise reduction on spectral dimension) was applied which ensures majority of the noise smoothing effect. Figure [S1](#page-17-0) in the Supplementary material illustrates the influence of the choice of the averaging window size on the recalculated spectrum. VUV data wavelength step for the used instrument is fixed at 0.2 nm. A window size (M) of 15 points ensures maximum noise reduction without loss of significant spectral features. This value corresponds to half the size of the convolution window (i.e. 31 points are used for averaging that corresponds to a spectral range of 6.2 nm). All points of the spectral dimension are recalculated, the dimensionality of the data is preserved. Satisfactory performance was obtained all over entire  $GC \times GC$  chromatogram as VUV spectra features are in general not very elaborate, and hydrocarbons exhibit broad absorption bands. Subsequently, additional chromatogram smoothing in the time dimension was applied. Figure [S2](#page-17-1) in the Supplementary material shows the influence of the choice of the noise filter value. It can be seen how analyte signal is preserved while noise is significantly reduced when choosing filter value  $M = 5$ , i.e. for each point the averaging is adjusted automatically with a maximum number of 11 points (corresponding to a time window of 0.33 s). These two approaches in conjunction lead to a very good result. After pre−processing, summed spectrum was again extracted from alkenes and cycloalkanes zone (Figure 6A in blue). It can be seen that spectrum is much smoother.

Additional pre−processing was applied in the form of baseline correction. Figure [S3](#page-18-0) and Figure [S4](#page-18-1) illustrate the estimation of baseline based on the choice of the number of iterations and convolution kernel size. As it can be seen a very good estimation is obtained with these parameters set to 15 and 100, respectively. Gaussian kernel size ought to correspond approximately to the width of the widest peak of interest in the chromatogram, as if the length is too short loss of signal for wider peaks will be incurred. Very important is to add that  $GC \times GC/VUV$  data can be very large in size (often >1Gb) which is why very fast computation with real time preview are advantages of our approach.

After applying baseline correction, extracted spectrum (Figure 6A in red) is finally more in line with what can be expected for a mixture of alkenes and cycloalkanes. However, absorbance never reaches zero at wavelengths above 200 nm, what is expected for these species (conjugated diolefins can however demonstrate absorbance up to 240 nm) and is even showing an increasing trend at 240 nm, which on the other hand can be explained only by detector blank signal. To correct for this artificial contribution, detector blank (Figure [S5](#page-19-1) and Figure [S6\)](#page-19-0) was subtracted from spectra at each pixel of the  $GC \times GC$  chromatogram. Finally, real alkenes/cycloalkanes mixture spectra was obtained (Figure 6A in green).



Figure 6: A) Extracted summed VUV spectrum for alkenes/cycloalkanes template zone; B) example of VUV spectrum of a cycloalkane (ethyl cyclohexane) and an alkene (1-tetradecene) from the VUVision® spectral library.

In the final spectrum in green, the expected pi−bond absorption bond of alkenes centred at 180−190 nm is observed. It shows that adequate pre−processing improves the quality of extracted information. In this way, extracted spectra for zones with coeluting species with spectral differences can be further employed to estimate linear contribution of each of the two families to the mixture provided their reference spectra per unit mass are known.

#### **4.2 Improving detection limits with data pre-processing**

In order to investigate the effect of GC×GC/VUV data pre−processing on quantitative performances and detection limits, diluted solutions of a hydrocarbons test mixture were prepared: 2x, 10x, 20x, 50x, 100x, 150x, 200x, 300x and 500x. These solutions contained respectively ca. 5000 ppm, 1000 ppm, 500 ppm, 200 ppm, 100 ppm, 70 ppm, 50 ppm, 30 and 20 ppm of the present analytes, including linear alkanes, alkenes, cycloalkanes and monoaromatics. Test mixture along with all the diluted solutions were analysed with  $GC \times GC/VUV$ . A typical chromatogram of the test mix is presented on Figure 7 for a concentration of ca. 5000 ppm per compound for the 125−240 nm spectral range.



Figure 7:  $GC \times GC / VUV$  chromatogram of a test mixture 2x dilution (125 nm).

First, GC×GC/VUV data integration was performed using GC Image software. Average absorbance in the 125−240 nm spectral range was calculated as no signal was obtained for longer wavelengths, i.e. in the 240−430 nm range. Integration was performed on the data for which baseline correction, the only available pre−processing operation available in GC Image, was applied.

Subsequently, all acquired data were subjected to pre−processing in plug im! software, which involved noise reduction, baseline correction and detector blank subtraction according to the approaches described above. Parameters chosen for the algorithms of the pre−processing steps were kept the same as for the Gas oil data.

Figure 8A illustrates the extracted VUV spectra from the analysis of the 150x diluted test mixture with concentrations around 70 ppm for n−decane, 1−decene and m−xylene before any pre−processing. As observed previously on the gasoil sample, Figure 8B demonstrates much improved spectra after proposed noise, baseline correction and detector blank subtraction are applied. m−xylene spectrum is clearly representative of monoaromatic species, 1−decene demonstrates a characteristic profile for alkenes, while n−decane exhibits monotonous nature characteristic for paraffins.



Figure 8: Extracted summed VUV spectrum for n-decane, 1-decene and m-xylene (150x dilution, ca. 70 ppm): A) without pre-processing, B) after noise, baseline correction and detector blank subtraction.

After pre−processing, the corrected data were imported in GC Image for peak integration. For each solution, peak volumes were calculated as well as signal to noise ratio. Detailed results for raw data and pre−processed data are given in Supplementary material and are summarized for 3 selected analytes in Figure 9.



Figure 9: log S/N ratio vs. log Concentration for n-decane, 1-decene and m-xylene for data with baseline correction in GC Image (in red) and with full pre-processing in plug im! software (in blue). S/N ratio was determined with GC Image (ratio of peak value to the estimated peak-to-peak noise).

It can be seen that, for all peaks, ca.  $6\times$  improvement of S/N ratio was obtained when additional pre−processing was applied. As expected for VUV data, S/N ratio is the highest for aromatic species and it decreases with decrease of the degree of unsaturation. Improving S/N ratio naturally helps in improving limit of detection for the species. We have observed that, in  $GC \times GC/VUV$ analysis below ca. 50 ppm, signal to noise ratio for analytes drops quickly and at this stage peaks are difficult to distinguish from noise. This can be seen on the example of m−xylene peak in Figure 10 (concentration ca. 20 ppm). After baseline and noise correction this peak is more easily detected, useful information is preserved while noise is much reduced.



Figure 10: Column II 1D view of the chromatogram (Avg. Abs. 125-240 nm) for the m-xylene peak: A) without preprocessing; B) with baseline, noise correction and detector blank subtraction (the first peak is water peak).

# **5 Conslusions**

In this work, we proposed advanced pre−processing techniques for noise and baseline correction of  $GC \times GC/VUV$  data. For baseline correction, a morphological approach based on iterated convolutions and rectifier operations was presented. Great improvement of spectral information extracted from real samples or model mixtures was shown, opening the possibility of reliable spectral mixtures estimations. Moreover, sensitivity improvements after applying developed noise and baseline correction approaches were demonstrated on the example of model mixture. All these features have been fully integrated in plug im!, a free open−access signal and image processing software [\(\(https://www.plugim.fr/\)\)](https://www.plugim.fr/plugin/107). This software and dedicated modules for  $GC \times GC/VUV$  data processing are available to any user and provide open access capabilities which are complementary to currently existing software solutions.

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### **SUPPLEMENTARY MATERIAL Advanced data pre**−**processing for Comprehensive two**−**dimensional Gas Chromatography with Vacuum Ultraviolet Spectroscopy detection**

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Table S1: Composition of standard mixture in toluene for investigation of the limits of detection of the GC×GC/VUV method.



Table S2: Peak volume and signal to noise ratio for selected peaks, for different dilutions of the test mixture with baseline correction in GC Image. GC Image was used for integration of Avg. 125-240 nm chromatogram.

<span id="page-17-0"></span>

<span id="page-17-1"></span>\* At this level detector saturation could be present.

Table S3: Peak volume and signal to noise ratio for selected peaks, for different dilutions of the test mixture with pre-processing in plug im! software (noise, baseline correction and detector blank subtraction). GC Image was used for integration of Avg. 125-240 nm chromatogram.

<span id="page-18-0"></span>

Figure S1: Spectrum at a chosen chromatogram point (in grey) smoothed by choosing following filter M values (in blue) (A) 5, (B) 15, (C) 20.

<span id="page-18-1"></span>

Figure S2: Illustration of the noise correction: input signal in grey and resultant signal in blue. Noise filter M value (A) 2, (B) 5. One modulation period 125 nm chromatogram is shown.

<span id="page-19-1"></span>

Figure S3: Estimated baseline (in blue) for a VUV signal (in grey) depending on the chosen convolution kernel sizes; (A) 5, (B) 20, (C) 100, number of iterations is 15 (125 nm).

<span id="page-19-0"></span>

Figure S4: Estimated baseline (in blue) for a VUV signal (in grey) depending on the chosen number iterations; (A) 5, (B) 10, (C) 15, convolution kernel size is 100 (125 nm).



Figure S5: Detector blank signal.



Figure S6: Selection of a zone for extracting detector blank signal.