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Mouna Sabrine Mayouf, Florence Dupin de Saint-Cyr

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On Data-Preparation Efficiency
Application on Breast Cancer Classification

Mona Mayouf *IRIT*
Université Paul Sabatier
Toulouse, France
0000-0001-8714-0038

Florence Dupin de Saint-Cyr *IRIT*
Université Paul Sabatier
Toulouse, France
000-0001-7891-9920

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Abstract

Quantifying the informative state of a dataset for a classification task is an important question. In this paper, we try to circumscribe this notion by introducing some new measures and enunciating some principles about data preparation. We experiment the interest of these measures and the validity of these principles by introducing several protocols designed for comparing different ways to prepare the data. We conclude by relating the efficiency of the data preparation and its theoretical diversity.

keywords: deep learning, convolutional neural networks, data preparation, information metrics, Breakhis

1 Introduction

Affecting one in eight women in the world, breast cancer is one of the most common cancer type among women, with one of the highest mortality rate [14]. In this context, convolutional neural networks (CNNs) have demonstrated remarkable accuracy and competitive reliability over traditional methods. However, according to [4], CNN approaches require that the network is trained on a huge amount of data. A main issue is that this amount is not always available: public datasets for a targeted task are not always available or does not have sufficient data. Besides, obtaining real data may be very expensive. Data-augmentation has been introduced to address this problem and has become one of the best-practices which improves the CNN results.

We should notice that the contribution of the artificial generation of data on the learning process is still poorly understood. Indeed, due to the CNN black-box aspect, it is difficult to identify how the data structure is guiding learning.

Is data augmentation successful just because it gives a redundancy which helps the learning? Is it necessary to provide fresh data or is it sufficient to generate data from old one? How can we quantify the information contained in a dataset for a given classification task? How the augmentation technique impacts the training process?

There has been an assumption that data augmentation is a mandatory standard step of data preparation. Traditional data-augmentation is based on basic image transformations that generate images extremely close to the initial data distribution space [17]. Other transformations (such as cut-out, Gaussian noising, Mix-up, overlapping) have been useful for some classification tasks [2] [3], [9]. With the success of generative adversarial networks (GANs), artificial fake images are generated [4]. However in critical fields such as health, where the information label must be conserved, there is a lot of restrictions on the possible transformations. Moreover, the lack of data which makes the learning process unsuccessful can be associated with an imbalanced dataset, in which there is a glaring difference in the number of samples for a category compared to another. Depending on the classification task, this imbalanced rate may create a marginalised category during the training phase [13].

Through this article, we study how to quantify the amount of information in a dataset by first proposing several new measures, second enunciating a set of principles that should govern data-preparation (and help to answer some of the questions introduced abode), third designing several experimental protocols in order to check the validity of our set of principles, fourth experimenting them on BreakHis dataset (histopathological breast cancer images classified into benign and malignant).

2 Background

2.1 Classical information metrics

In this section, we first recall some metrics present in the literature. For this purpose, we consider a dataset D composed of n items, $D = \{s_1, \ldots, s_n\}$, each item s being associated with a unique class c which is called the label of s and denoted by $s.label = c$. The set of possible classes is denoted $\mathcal{C}$. Classically, the *abundance* $a_D(c)$ of a class c given a dataset D is the number of items of this class according to D, and the *proportional abundance* of a class c, $P_D(c)$, is the percentage of representation of a class among all the classes:

$$a_D(c) = |\{s \in D : s.label = c\}|$$
$$p_D(c) = \frac{a_D(c)}{n}$$

According to [6], there are three indicators that have been defined in the literature for estimating the *diversity* of a dataset, namely, the *variety*, the *balance* and the *disparity*. Here we expose some metrics aiming at capturing these indicators:

- *Variety:* The richness $\mathcal{R}$ is a metric related to the *variety* and represents the number of classes effectively considered for the classification task [5, 15]:

$$\mathcal{R}(D) = |\{c \in C : p_D(c) > 0\}|$$

- *Balance:* The imbalance ratio $\mathcal{IR}$ is the ratio of a majority over the minority classes in a binary classification [7]:

$$\mathcal{IR}(D) = \frac{a_D(\text{Majority class})}{a_D(\text{minority class})}$$

  According to [8], the dataset is little imbalanced when $1.5 < \mathcal{IR} < 3$, medium imbalanced for $3 < \mathcal{IR} < 9$ and very imbalanced when $\mathcal{IR} > 9$. Note that in the case of a binary classification, $\mathcal{IR}(D) = \frac{1}{p_D(\text{minority class})} - 1$. There are several other measures that capture the distribution of the data. However since they are all based on the proportional abundance p it means that they only take into account the number of items per class without considering the different natures of these items[1].

- *Disparity:* The Disparity $\mathcal{D}$ quantifies the variety of the data based on a pairwise distance d between classes.

$$\mathcal{D} = \sum_{c \in C} \sum_{c' \in C} d(c, c')$$

  However providing the distance d between two classes requires additional knowledge (e.g. coming from the context of the classification task).

Since Variety and Balance are only defined on the abundance of each class with respect to each other, the associated metrics will not help us very much in characterizing the quantity of information contained in the dataset. This is why in Section 4, we propose to introduce several new metrics based on Disparity or on the diameter of the dataset, that incorporates a distance d more appropriate for images.

2.2 BreakHis Dataset

"BreakHis" (which stands for "Breast Cancer Histopathological Database") is a public dataset composed of 7909 histopathological biopsy images observed by four microscopic magnifications: 40X, 100X, 200X and 400X, collected from 82 patients by P&D Laboratory in Brazil on 2014 [14]. Among the labels that

[1] Three other measures could be considered, namely, Shannon entropy [12] $\mathcal{H}$, Herfindahl-Hirschman [11] $\mathcal{HHI}$ and Berger-Parker indexes $\mathcal{BPI}$, which capture respectively the uncertainty in predicting the type of an item taken at random, the probability of two random items to belong to the same class and the maximal proportional abundance:

$$\mathcal{H}(D) = -\sum_{c \in C} p_D(c) \times \log(p_D(c)) \quad \mathcal{HHI}(D) = \sum_{c \in C} p_D(c)^2$$
$$\mathcal{BPI}(D) = \max(p_D(c))$$

characterize the images, we focus on the tumor type which is either benign or malignant. This dataset is imbalanced with $\mathcal{IR} = 2.19$ (see Table 1). Indeed, there are 2480 benign samples representing the minority, versus 5428 malignant ones, representing the majority category yielding a total amount of 7908 (only 5271 (i.e. 2/3) are used for the training phase, as explained in Section 7). In order to deal with this imbalanced dataset, we are going to propose several data-augmentation techniques and compare their impact on the learning process.

3 Formalisation and Protocols for BreakHis data preparation

Data preparation consists in transforming the initial dataset in order to better train the network. Among the classical transformation, the more used are balancing and augmentation. Note that according to [13], there are three ways to rebalance the dataset : 1) *over-sampling the minor class* which amounts to augment the size of the minority class; 2) *under-sampling the major class* which consists in removing items from the majority class; 3) *bagging the training phase* which raises the probability to select an item in a marginalized category. The latter way to balance the data is out of the scope of this paper which focuses on data preparation techniques rather than training techniques.

This section first presents a list of principles that should hold when performing any data preparation, then we introduce the formalism adopted and the signature of the transformation functions that we are going to use for data augmentation. In order to validate the principles that we are introducing here, in Section 3.4 we have designed a discriminating set of experimental protocols whose results allow to confirm or deny these hypotheses.

3.1 General Principles for efficient data preparation

During data preparation, it is often the case that researchers use balancing techniques, or merely augment the data by doing some transformations on the samples. The best practices are guided by the results obtained, some practices are known to work better than others, however the hypothesis underlying the practices are not always made explicit. Moreover it is not clear if some practice are good or not, for instance sometimes augmentation creates duplicate of some samples, is it efficient to do so? Below, we enunciate a list of hypothetical principles that are inspired from the best practices in order to give more awareness about what should be a "rational data preparation". Note that some of these principles are well known, and seem obvious and are still too fuzzy, however by writing them we show that more experiments are required for precising them. It also underlines the need for metrics that could characterize better the datasets, hence, justifying the work done in section 4. We can enunciate six principles that may improve the training:

- *Balanced Dataset (BD)*

- *Sufficient Dataset Size (SDS)*
- *No Duplication of Items (NDI)*
- *Well Chosen Transformation Operators (WCTO)*
- *Variety of Transformation Operators (VTO)*
- *Fresh External Data (FED)*

Indeed, our experiments presented in Section 5 will confirm these rational principles. More precisely, (BD) stipulates that a balanced dataset behaves better than an unbalanced one for a classification task. (SDS) implies that a too small dataset may have a high negative impact (inefficiency and slow convergence) on the training process, even when the data is balanced. Moreover, by (NDI), we assume that duplication does not compensate the smallness of the dataset (it does not improve efficiency nor convergence). Furthermore, using data augmentation with no "fresh" data but with transformed items has often a positive impact on the training process, especially when the transformation is "label conservative", this is the meaning of (WCTO). (WCTO) is also useful for balancing a dataset of sufficient size since by adding well transformed items to the minority class we can obtain a positive impact on training. Indeed we will see that some transformation perform better than others, obviously, label-conservative ones are mandatory. (VTO) expresses that using several diversified transformation operators has a positive impact. Finaly, adding fresh external real data perform better than adding generated data but may require more training time.

3.2 BreakHis transformation operators

In addition to the identity operator denoted *Id*, the data augmentation process is based on two types of *elementary* operators that are label-conservative (see [1] for the geometric operators and [16] for the color ones):

- *Geometric operators* Due to the fact that BreakHis images are rectangles of 460x700, any non-mirror geometric operation would yield a different shape which would need to be reshaped or cropped in order to feed the CNN. To avoid this post-operation that may decrease the precision, we opt for the only two operators that preserve the same shape: the horizontal and vertical flips. These two operators are denoted respectively **H** and **V**.
- *Color operators* In order to increase the number of images, we consider also the possibility to play on colors. We use two operators: a RGB color inversion and a transformation of the RGB encoding of the image into the HSV color encoding. They are denoted respectively **c** and **C**.

In order to perform more than four distinct data augmentation, it is necessary to combine elementary operators by applying them successively. However, some combinations could create duplicated instances of the same images (e.g.

HV=VH, Hc=cH, ...). In summary, due to symmetries, only 15 distinct combinations are possible, namely: H, V, c, C, HV, Hc, HC, Vc, VC, cC, HVc, HVC, HcC, VcC, HVcC.

3.3 Signature of even split data-transformation

In this section, we introduce the signature of a particular kind of data transformations with even distribution, i.e., the data is split into equal parts of samples where the same transformation is applied to all elements of the same part.

Definition 1 (Signature)**.** *The signature of a even-split dataset transformation denoted* $tr(D, ops, ratio)$*, is a function of the following parameters:*

- D*: the dataset to transform*
- *ops: the list of operators to apply to the different parts*
- r*: the division rate (in percentage) for splitting the dataset into parts (on which the operator(s) will apply)*

where $tr(D, (op_1, \dots op_p), r) = (op_1(D_1), \dots, op_p(D_p))$ *is a partition of the dataset* D *into* $D_1, \dots D_p$ *(where* $p = 100/r$*) on which the operators* $(op_1, \dots op_p)$ *are applied respectively and* $op(D)$ *is an abbreviation for:* $op(D) = \{op(s) | s \in D\}$

For instance we can consider the augmentation done by applying one elementary operation among (H, V, c, C) to each 25% of the dataset D: this augmentation has the signature $tr(D, (H, V, c, C), 25)$. It consists in partitioning D into four parts (D_1, D_2, D_3, D_4) and apply H to D_1, V to D_2, c to D_3 and C to D_4 yielding a new dataset $D' = tr(D, (H, V, c, C), 25) = (H(D_1), V(D_2), c(D_3), C(D_4))$.

Note that an augmentation that applies the same operator op to the whole dataset D has the following signature $tr(D, (op), 100)$.

3.4 Experimental Protocols

In this section, we propose 13 different data preparation protocols for BreakHis dataset, designed with the purpose of enabling us to validate the General Principles enunciated above. D denotes the part of BreakHis dataset items assigned for training (we took 2/3 of the initial dataset) and D_i denotes the new training dataset after preparation with the protocol P_i. In the following, all the samples s' of D_i are such that $s'.label = s.label$ where s is the original sample in D which yields s' in D_i (by a transformation in $\{Id, H, V, C, c, HC, Vc, CV, cH\}$). In other words the protocols are creating new samples that are labelled accordingly to their initial label in the original dataset.

BreakHis training Dataset D is composed of two classes, the marginal class called m, it is the benign category: $m = \{s \in D | s.label = benign\}$. The majority class denoted M is the malignant category: $M = \{s \in D | s.label = malignant\}$. Hence $D = M \cup m$. Note that m has a size equal to half the size of

the majority class M, the protocols are using this characteristics for balancing the data.

1. Protocols 1 (no data creation): P_{1a} is a control protocol where no balancing nor augmentation are processed to the dataset. $D_{1a} = D$; P_{1b} is a second control protocol where only an augmentation is done without bringing "new" information: mere identical duplication of the items of the already majority class $D_{1b} = D \cup tr(M, (Id), 100)$; P_{1c} is a third control protocol which does not bring any "new" information but increases the size by simple duplication of the items in order to balance and augment the data $D_{1c} = D \cup m \cup tr(D \cup m, (Id), 100)$.

2. Protocols 2 (balanced data) : double the size of the minority class with only one operator. P_{2a} uses a geometrical operator: $D_{2a} = D \cup tr(m, (H), 100)$; P_{2b} uses a color operator : $D_{2b} = D \cup tr(m, (C), 100)$; P_{2c}: balance by under-sampling. $D_{2c} = m \cup Sample(M, |m|)$ where $Sample(X, n)$ is a function that randomly selects n elements among the set X;

3. Protocols P_3 (augmented unbalanced data) uses a color operator to augment the size of the majority class : $D_3 = D \cup tr(M/2, (C), 100)$.

4. Protocols 4 (balanced and augmented data): with two single successive operators. P_{4a} uses the geometrical operators H and V: $m' = m \cup tr(m, (H), 100)$ (double the size of the minority), $D_{4a} = M \cup m' \cup tr(M \cup m', (V), 100)$ (augment the whole dataset); P_{4b} is similar to P_{4a} but uses the color operators C and c; P_{4c} uses the operators H and C; P_{4d} uses the operators V and c. P_{4e} uses the four operators applied on different parts of the dataset: $m' = m \cup tr(m, (H, V, C, c), 25)$ (double the size of minority), $D_{4e} = M \cup m' \cup tr(M \cup m', (C, c, V, H), 25)$ (augment[2] the whole dataset). P_{4f} supply the lack of data by adding samples from another dataset[3]: $D_{4f} = M \cup m \cup m\_extra \cup M\_extra$ where m_extra (resp. M_extra) is a set of $3|m|$ (resp.$|M|$) minority (resp. majority) category images of the other dataset.

4 Diversity measures

According to the definitions recalled in Section 2, in order to compute the *disparity* $\mathcal{D}$ of a dataset, we should be able to provide a way to compute the distance between the different classes. We propose to define the distance between two classes by introducing first the distance between two images. Then we base the distance between two classes on the distance between the means of each classes. There are several ways to compute the distance between two images, for instance the Euclidean distance is based on a point-to-point comparison of the pixels of

[2]More precisely, $D_{4e} = M \cup m \cup tr(m, (H, V, C, c), 25) \cup tr(M, (C, c, V, H), 25) \cup tr(m, (C, c, V, H), 25) \cup tr(m, (HC, Vc, CV, cH), 25)$

[3]`https://iciar2018-challenge.grand-challenge.org/Dataset/`

each image (it is the norm of the matrix difference). Another idea is to take into account extra information in order to integrate into the distance the fact that horizontal and vertical symmetries should not increase the distance between images, because for a classification task these symmetries do not matter. This is why we choose to use a standard measure called SSIM (structural similarity index measure) [18] which estimates the similarity of two images based on a kind of contraction of the images according to their luminance, contrast and structure.

Definition 2 (SSI [18])**.** *Let s_1, s_2 be two samples,*

$$SSI(s_1, s_2) = \frac{(2\mu_1\mu_2 + \alpha_1)(2\sigma_{12} + \alpha_2)}{(\mu_1^2 + \mu_2^2 + \alpha_1)(\sigma_1^2 + \sigma_2^2 + \alpha_2)}$$

where μ_1, μ_2, σ_1^2, σ_2^2, σ_{12}, α_1, α_2 are the means and variance of $s_1.image$ and $s_2.image$, the co-variance of $s_1.image$ and $s_2.image$, and two small constants respectively.[4]*.*

Note that this similarity measure is invariant to the vertical and horizontal flip, since an image and its flipped version have the same average and variance. However this does not hold for color operation. We propose a *SSI* variant, called *SSIC* that is label-conservative for all operations introduced in Section 2.2, i.e., which is invariant to color operations **c** and **C**.

Definition 3. *Let s_1, s_2 be two samples,*

$$SSIC(s_1, s_2) = \min_{op \in \{Id, c, C\}} SSI(s_1, op^{-1}(s_2))$$

Example 1. *for instance if s is a sample to be compared to its transformed sample by RGB color inversion $c(s)$, the distance $SSIC(s, c(s))$ is 0 since $c^{-1}(c(s))$ $= s$*

Proposition 1. *For any combination cop of the elementary operators $\{Id$, H, V, C, $c\}$, it holds that for all sample s, $SSIC(s, cop(s)) = 0$*

Proof. The proof concerning the geometric operators is due to the definition of *SSI* and is already explained in the Note below Definition 2. *SSIC* being built on *SSI* to ignore color transformations hence the result. □

We are now in position to define the best representative sample among a set X, called $\mu_I(X)$. It is the sample which is the most similar to the other samples of X:

$$\mu_I(X) = \text{argmax}_{x \in X} \sum_{y \in X \setminus \{x\}} SSIC(x, y)$$

We propose to evaluate the diversity of a dataset D by its disparity and diameter. The disparity has already been recalled above and is related to the

[4]These constants were introduced by [19] for avoiding unstability when the denominator is close to 0 by setting $\alpha_1 = 0.01 \times L$ and $\alpha_2 = 0.03 \times L$ where L is the dynamic range of the pixel values. For BreakHis dataset, with 8 bits/pixel images, $L = 255$.

distinction between the different classes. The diameter is a general measure of the scope of the whole dataset independently of the classes, it is the maximum distance between any two images of the dataset. These two measures can be defined either on the Euclidean distance d, or on the more informed similarity measure *SSIC* yielding four measures *diam*, *disp*, $diam_I$ and $disp_I$ where I stands for "informed measure". We normalize the Euclidean distance by the the greatest possible distance matrix denoted $|im255|$, i.e., the image composed of 255 on the three channels RGB (since the images are 460×700 then $|im_{255}| = \sqrt{460 \times 700 \times 3 \times 255^2} = 250627.5125$).

Definition 4. *Given a dataset D, with two classes D_1 and D_2 ($D = D_1 \cup D_2$),*

- $diam(D) = \frac{\max_{s_1,s_2 \in D} d(s_1.image, s_2.image)}{|im_{255}|}$
- $disp(D) = \frac{d(\mu(D_1),\mu(D_2))}{|im_{255}|}$
- $diam_I(D) = \max_{s_1,s_2 \in D}(1 - SSIC(s_1.image, s_2.image))$
- $disp_I(D) = (1 - SSIC(\mu_I(D_1), \mu_I(D_2))$

Note that concerning disparities, the definitions are given for a binary classification ($|\mathcal{C}| = 2$) where D_1 is the part of the set D containing the first class and D_2 is the part of the set containing the second class.[5]

The following proposition shows that all the protocols that we provide except P_{4f} does not bring any "new" information to the dataset.

Proposition 2. *for all the datasets D_{ij} obtained by the protocols except D_{4f}*

$$diam_I(D_{ij}) = diam_I(D_{1a}) \text{ and } disp_I(D_{ij}) = disp_I(D_{1a})$$

Proof. The proof is based on the invariance of *SSIC* wrt color and geometric operators. □

5 Results and discussion

In this part, we try to estimate the amount of information that is contained in the different datasets obtained by the previous protocols. As said in Section 2, the variety and balance can be respectively estimated through the richness measure $\mathcal{R}$ and the imbalance ratio $\mathcal{IR}$. This section evaluates the different protocols on two aspects, first the quantity of information present in the dataset produced by the protocol, second the classification efficiency given by a CNN trained on these datasets. Table 1 gives the different sizes D_{ij} of the datasets obtained by the different protocols P_{ij}. Note that the *richness* of the dataset obtained with any of the protocols remains the same since the number of classes remains constant: $\mathcal{R}(D_{ij}) = 2$ for all the datasets. Concerning the *balance*, the

[5] If there were more than two classes, the disparity would be $\frac{2\sum_{c \in C}\sum_{c' \in C \setminus \{c\}} d(\mu(D_c),\mu(D_{c'}))}{|C| \times (|C|-1) \times |im_{255}|}$

imbalance ratio $\mathcal{IR}$ of the datasets D_{ij} obtained by the different protocols is always 1 (due to the doubling of the size of the minority class that has a size equal to half the one of the majority class), for any protocol P_{ij} except P_{1a}, P_{1b} and P_3. Note that due to Proposition 2, the informed disparities and diameters are the same for all the datasets except D_{4f}.

P	$\lvert D_{ij}\rvert$	$\mathcal{R}$	$\mathcal{IR}$	$disp$	$diam$	$disp_I$	$diam_I$
1a	5271	2	2,19	0.0254	0.1299	0.0975	0.0157
1b	8785	2	4,38	0.0254	0.1299	0.0975	0.0157
1c	14056	2	1	0.0254	0.1299	0.0975	0.0157
2a	7028	2	1	0.0528	0.1299	0.0975	0.0157
2b	7028	2	1	0.0826	0.2453	0.0975	0.0157
2c	3514	2	1	0.0265	0.1045	0.0975	0.0157
3	7028	2	3,28	0.0654	0.4213	0.0975	0.0157
4a	14056	2	1	0.038	0.1465	0.0975	0.0157
4b	14056	2	1	0.1168	0.5812	0.0975	0.0157
4c	14056	2	1	0.2051	0.3489	0.0975	0.0157
4d	14056	2	1	0.1030	0.4731	0.0975	0.0157
4e	14056	2	1	0.4361	0.8312	0.0975	0.0157
4f	14056	2	1	0.4673	0.4369	0.1385	0.2413

Table 1: Metrics Results obtained on BreakHis

Table 2 describes the results obtained by the network trained on the datasets produced by the different protocols. *Acc* represents the accuracy, Acc is the rate of correctly classified samples among all the samples $Acc = \frac{TM+TB}{TM+TB+FM+FB}$ with TB (respectively TM, FB, FM) denotes the number of samples correctly assigned to the benign (resp. correctly to the malignant, wrongly labeled benign, wrongly labeled malignant) class. *Prec* is the precision, it indicates the portion of correctly assigned elements among the ones that are predicted malignant $Prec = \frac{TM}{TM+FM}$. *Rec* is the recall, it indicates the portion of samples correctly affected to the malignant class among all the samples that are malignant in the ground truth $Rec = \frac{TM}{TM+FB}$. We also give an indication of the training behavior by mentioning the stabilization's epoch *StbE* which is computed thanks to the early-stopping regularization technique [10]. It is the epoch from which the training loss is nearly steady. Table 3 shows the principles that seem to support the protocol performance, for WCTO and VTO we precise respectively the list of transformation operators and the number of distinct operators used.

In Table 2, the bad results of P_{1a} and P_{2c} underlines that *a too small dataset has a high negative impact on the training process, even when the data is balanced* confirming the principle (SDS). Also, these two datasets had the smallest disparity and diameters (absolute and informed). Having a small disparity translates that the images of the two classes are near to each other making harder the discrimination task.

Duplication does not compensate the smallness of the dataset. Also, compensating the lack of data by duplicating identically the same images makes

P	StbE	Acc (%)	Prec (%)	Rec (%)
1a	inf	47.23	53.22	48.59
1b	inf	49.08	46.59	49.03
1c	inf	50.01	48.23	47.71
2a	1966	64.12	65.27	67.02
2b	2133	69.43	66.15	68.13
2c	inf	50.03	46.02	49.93
3	inf	55.79	52.03	56.46
4a	2146	88.63	75.10	70.02
4b	2369	85.36	71.36	69.04
4c	1967	90.02	85.03	88.52
4d	2513	84.29	72.13	78.96
4e	2719	95.63	78.49	75.16
4f	2861	96.03	89.46	91.75

Table 2: Accuracy Results obtained on BreakHis

P	BD	SDS	NDI	WCTO (ops)	VTO (nb ops)	FED
1a	no	no	yes	no	0	no
1b	no	no	no	no	0	no
1c	yes	yes	no	no	0	no
2a	yes	no	yes	H	1	no
2b	yes	no	yes	C	1	no
2c	yes	no	yes	no	0	no
3	no	no	yes	C	1	no
4a	yes	yes	yes	V + VH	2	no
4b	yes	yes	yes	c + cC	2	no
4c	yes	yes	yes	C + CH	2	no
4d	yes	yes	yes	c + cV	2	no
4e	yes	yes	yes	C + c + V + H + CH + cV + VC + Hc	8	no
4f	yes	yes	yes	no	0	yes

Table 3: Principles satisfied by the protocols

the training even more difficult and yields the CNN into over-fitting (P_{1b} and P_{1c}), because for these latter protocols the CNN is unstable and blocked in a transitory regime with a bad accuracy under 50%, confirming the (NDI) principle. *Using data augmentation with no "fresh" data but with transformed items has a positive impact on the training process* (since P_{4a} gives better results than P_{1c} and P_{2b} being better than P_{2c}) this confirms both (WCTO) and (BD) principles. Moreover, the reader can check that *augmenting a balanced dataset increases the performances*, (see $P_4abcdef$ wrt P_{2abc}) which supports again the (SDS) and (BD) principles. Note that *the color transformations have better impact than the geometric ones* (P_{2b} being better than P_{2a} and P_{4c} than P_{4a}), consolidating the (WCTO) principle. In parallel, we observe that both the dis-

parity and the diameter are augmented by adding transformed samples relating these measure to the (WCTO) and (VTO) principles. In addition, we conclude *that varying the operators by using them on different parts of the dataset, increases the accuracy*: the best accuracy 95.63% is obtained in that case (P_{4e}) with the use of 8 different operators demonstrating the importance of (VTO) principle which is again correlated with a high disparity and diameter. Lastly, we see that P_{4f} has the best performances with the addition of fresh external data (FED) but this protocol needs more training time. Obviously having the possibility to add fresh external data is ideal, however, it is not always possible to find more real data, this is why we can consider that P_{4e} and P_{4c} are the best data preparations. Contrarily to what was expected, several dataset that have equal values with $disp_I$ and $diam_I$ may have very different efficiency. These measures are capturing a kind of brute richness similar to the one that a human expert could have given by understanding the equivalences between samples. It seems that the network is benefiting from the creation of equivalent samples which do not increase what we call "informed" disparity and diameter but increase the non informed disparity and diameter.

6 Conclusion

This article studies the data preparation process through the idea that there is a need for evaluating the quantity of information present in a dataset in terms of efficiency for a classification task. For this purpose, we define four new metrics to evaluate the dataset diversity and we formalize six rational principles for data preparation. Then, we experiment 13 data-preparation protocols and identified among them the most suitable ones for BreakHis images classification. As a perspective of this work we propose to use the saliency maps technique to visualize what the CNN is considering from a transformed data and to define another family of informativeness metrics.

7 Ethical Issues and Computational Details

This research study was conducted retrospectively using human subject data made available in open access and ethically approved by (`https://www.kaggle.com/ambarish/breakhis`).

We used the pre-trained "VGG19" convolutional neural network model as a classifier to compare the different dapa-preparation protocols. In order to optimize the network training, we used the the several regularization techniques such as the L2 regularization with α set to 0.01, the early stopping and the dropout techniques are also used. We trained our model for 3000 epochs with a batch size of 64. We opted for Adam-optimiser for a learning rate fixed initially at 0.0001. The initial breakHis dataset was split into 2/3 for the training set D_{1a}, 1/6 for validation and 1/6 for the test. $|D_{1a}| = 5271, p(M) = 2/3, p(B) = 1/3$

8 Acknowledgments and Ethical Issues

This research study was conducted retrospectively using human subject data made available in open access and ethically approved by (`https://www.kaggle.com/ambarish/breakhis`). The authors have non-financial interests to disclose. Experiments presented in this paper were carried out using the OSIRIM platform that is administered by IRIT and supported by CNRS, the Région Midi-Pyrénées, the French Government, ERDF (see `https://osirim.irit.fr/site/en`).

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