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# **General Interest**

# Digital Twins: Properties, Software Frameworks, and Application Scenarios

5 Roberto Minerva and Noël Crespi

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- 7 Abstract—The Digital Twin (DT) is an emerging approach that promises to change the way
- 8 products and systems are made and used. The DT is attracting increasing interest in the
- 9 Internet of Things community for its potential applications. Despite the hype, this
- 10 approach requires a more precise definition and characterization in terms of its properties
- ${\scriptstyle 11}$   ${\scriptstyle \ }$  in relationship to software architectures and their platform implementations, as well as a
- 12 deeper analysis of its potential applications and actual feasibility in several industries.
- ${\scriptstyle 13}$   $\,$  This paper investigates the basic properties that hold for a DT, sketches a software
- ${}^{14}$   $\,$  framework and presents two application scenarios. The paper also addresses the
- 15 business impact of DT by discussing servitization capabilities.

**THE DIGITAL TWIN** (DT) was conceived to 16 design, prototype, and operate a virtual copy 17 of a product.<sup>1</sup> It promotes the softwarization of 18 physical objects (POs), into logical compo-19 nents and the development of applications 20 that exploit programmability of the software 21 representation. Originally used by NASA,<sup>2</sup> it has 22 gained interest in manufacturing.<sup>3</sup> Because of 23 its ability to describe POs by means of logical 24 models and actual data, it is increasingly used 25 in the Internet of Things and cyber-physical 26

systems.<sup>4</sup> To fully master its potential, there is a need to understand what a DT is from a software perspective, how to support and implement it, how to manage the physical and logical counterparts, and what constraints are implied by the relationship between them. This article addresses the current DT definition, and identifies a set of characterizing properties. Next, a software framework is sketched out to illustrate two application scenarios that highlight technical possibilities and challenges. An analysis of some business benefits is provided. Conclusions summarize challenges and risks of this approach.

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# General Interest

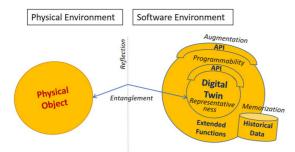


Figure 1. DT representation.

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# DIGITAL TWIN (DT) AND ITS PROPERTIES

DTs embody software capabilities to describe or simulate relevant features and behavior of POs from design to end-of-life phases.<sup>5</sup> A DT is a software actionable representation of a PO (or aggregated objects) in a specific environment. Some PO's features could be unrelated to the goals of the software representation. Products or complex objects are the main targets, because mapping one to one atomic objects may be unpractical or useless. DTs in a cyber-physical systems (CPS) domain are characterized<sup>6</sup> by events they are capable of managing, methods and functionalities they offer, storage capabilities to maintain a historical log of status changes, ability to serve as functional interfaces to applications through application programming interfaces (APIs) and ability to send/receive information. The definition of basic DT properties (see Figure 1) is instrumental to determine requirements and constraints posed to software platforms. The key properties of a DT are given as follows.

- Representativeness and contextualization. A
  DT represents the PO in a specific context,
  i.e., a DT is a software implementation of a
  model representing the PO in a specific environment. Feature simplifications or generalizations are possible when they do not affect
  the behavior in the specific context.
- *Reflection*. A DT mirrors the behavior and the status of the PO. Each change in status, each event faced by the PO is reflected by the DT. Changes that occur to the DT should be reproduced in the PO.
- *Entanglement*. A DT and its PO must be constantly "connected" to instantaneously (i.e., in a time period consistent with requirements

of applications) register any change in status. 79 Entanglement requires an effective, reliable 80 communication between the PO and the DT 81 suitable to the rate of changes. 82

- Persistency. A DT is always available. Its avail- 83
  ability exceeds the actual existence of the 84
  PO. A DT could be available before the 85
  "creation," during malfunctioning and 86
  crashes, and after the end of life of the PO. 87
- *Memorization.* A DT stores all the status <sup>88</sup> changes and events occurred to the PO. A DT <sup>89</sup> represents the status of the PO over time <sup>90</sup> and space. <sup>91</sup>
- Augmentation. A DT can extend the PO func- 92 tions and offer them by means of APIs. Aug- 93 mentation can add new functionalities that 94 the PO does not support or provide access 95 to data in particular formats. 96
- *Composability.* Physical systems are aggrega- 97 tions of subsystems and components, a DT 98 must support the correlation of different ele- 99 mentary DTs into complex organizations and 100 provide views on the aggregated DT and indi- 101 vidual components. 102
- *Replication*. A DT can be replicated to serve 103 the needs of different applications. Replicas 104 of the same PO must behave consistently, 105 i.e., they cannot have a different status and 106 they cannot exhibit different behaviors. 107
- Accountability/Manageability. Each DT must 108
   be manageable; it is possible to determine its 109
   status and activities and to optimize its exe- 110
   cution in the framework in which it is operat- 111
   ing. It must provide information about the 112
   usage of the PO by the applications associ- 113
   ated with it. Self-management of DTs is a 114
   desirable property for large systems. 115
- Servitization. A DT enables the transformation 116

   of a product/artifact into a set of functionali- 117
   ties offered to users. This capability trans- 118
   forms products into software-controlled and 119
   connected entities accessible "on-demand" 120
   by users.
   121
- Predictability. A DT has the ability to simulate its 122
  behavior over time. Specific instances of DTs 123
  can simulate the behavior of PO in a context at 124
  a specific time (in the past or in the future). 125

Some DT properties need contextualization: 126 replicas are used for tracking POs or for simulate 127

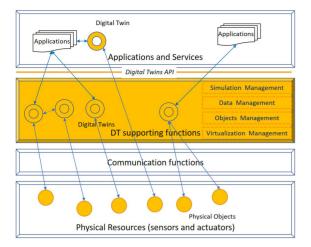


Figure 2. General framework for digital twins.

their behavior. All the replicas of a DT tracking the actual status of a PO should have the same status at the same time t (with time limitations explained for entanglement), DTs used for simulations can diverge depending on the simulation conditions.

# 134 TOWARDS A GENERAL SOFTWARE135 FRAMEWORK

A software framework for DTs implements 136 numerous functionalities, e.g., orchestration of 137 objects, cognition for intelligent optimization, 138 self-management to minimize human interven-139 tion. Different software architectures may be 140 applicable.<sup>7,8</sup> Some adopt layering principles for 141 organizing functionalities.<sup>9</sup> These architectures 142 must be evaluated to determine how properly 143 they support the DT requirements. Figure 2 rep-144 resents a generic framework organized in four 145 functional segments. This structure is chosen to 146 illustrate the separation of concerns. IoT devices, 147 communications means (protocols and net-148 works), DT tools and functions will quickly 149 150 evolve. Layering may prove useful: it is simple enough to be practically used and can allow 151 independent evolution of the different techno-152 logical layers. Finally, layering is aligned with 153 efforts in standardizing IoT architectures. AIOTI<sup>10</sup> 154 describes an IoT layered architecture that could 155 support the DT approach. However, modulariza-156 tion and linkage of functionalities can prove as 157 practical as layered architectures. Physical 158 resources are devices producing information or 159

acting on the environment (sensors and actuators). The information (commands, events, requests, and status notifications) exchanged between devices and components of the framework is transported by means of communications functions. The DT supporting functions segment represents the execution environment of DTs and the set of intelligent functionalities that DT instances use for orchestrating their interactions and lifecycles (e.g., instantiation, replication, identification, access control, and self-management), managing collected data, and simulation capabilities. This segment mediates the interaction between applications and physical devices. New functions, mechanisms and tools may be progressively designed and added to better meet DTs requirements. The application and services segment supports the applications that use the DTs interfaces and functions. For customization and execution purposes, DT replicas may be locally executed in this environment.

The actual exploitation of the DT as a generalpurpose approach occurs if some conditions are met: the availability of a software framework capable of fulfilling the properties of DTs; the ability to create new applications with better functionalities for the user; and the ability to introduce new business models or to improve existing ones. These issues are analyzed in the following sections.

# **APPLICATION SCENARIOS**

DT can be used to implement several scenarios. In this article, two application scenarios, based on properties of DTs and software framework, illustrate possibilities and issues.

Scenario 1: Virtual Object

This example describes how to create the DT of an object. A sensor is chosen, but different (aggregations of) objects may be considered. The needed design tasks are given as follows.

*Physical object model*: An abstract computable description of the data and behavior of the PO that the DT implements. The sensor status and the measurements it takes in the environment are relevant aspects to consider and to model.

*API definition*: an interface for requesting the functionalities offered by the DT. Applications use it to get data or to give commands. Data formats and interaction mechanisms should be defined.

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*Entanglement model*: a model governing how PO and DT exchange data and status updates. The framework must offer mechanisms and protocols to support communication. Often the data flow is unidirectional from PO to DT, while it is bidirectional between the DT and applications (data, events, and commands). Commands from the applications to DT are used to govern the DT behavior.

A single PO can be replicated by several DTs. This occurrence accommodates specific requirements of applications: providing special functions, or permit access to the data with different rates, or segmenting and securing the computational space. Replicas can be instantiated in the framework and others in the application space. This option offers flexibility in deployment. Replication of DTs poses interesting issues. When the status of the PO changes, all the replicas need to change status. The propagation of information can be achieved with different mechanisms; PubSub is used in IoT implementations<sup>11</sup> and it suits the case of unidirectional communication (where the PO is a publisher and the replicas are subscribers). If PO status can be modified or it can be instructed (an actuator), the problem of synchronization and consistency of information between the PO and different replicas emerges. This issue can be solved by introducing transaction management functions into the framework.

### Scenario 2: Digital Twins in Smart City

Cities are complex systems<sup>12</sup> difficult to control and program. A prerequisite for a smart city is having "measurable" attributes. Sensors and actuators are deployed to capture data that describe its processes. This make a city quantifiable and assessable. Once reliable data are available, artificial intelligence and machine learning, AI/ML, techniques determine patterns and behavioral models of urban systems.<sup>13</sup> The city becomes "understandable," i.e., it is possible to predict events and their associated causes by means of data analysis. DTs are a step toward the programmability of a city: the digital representation of resources makes it possible to design applications that, by interacting with DTs, can affect the behavior of "things" and optimize city resources and their behavior. Several experiences introduce the DT concept in smart

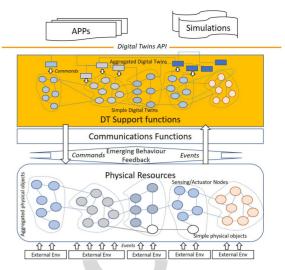


Figure 3. Programmability of complex systems with digital twins.

cities.<sup>14,15</sup> The DT application introduces new 259 capabilities and has an impact on how to govern 260 the complexity of urban systems. For exam- 261 ple, the adoption of the DT approach is improv- 262 ing the usage of building information modeling, 263 e.g., such as given by Delbrügger *et al.*<sup>16</sup> 264

DTs are programmable objects that can 265 orchestrate, on request of applications, POs like 266 actuators toward the desired behavior. DTs can 267 detect malfunctioning in POs and minimize their 268 impact on other resources. DTs, exploiting 269 advancement in storage technology, can store 270 large datasets and hence supporting the continu- 271 ous "learning" of city behavior. They offer the 272 possibility to evaluate new policies by simulat- 273 ing future situations. DTs could be utilized to 274 solve a common issue of smart cities: the siloing 275 of application domains (e.g., transportation, 276 energy, and so on). DTs offer interfaces through 277 which different applications can access data, 278 behavior, and status corresponding to specific 279 resources. DT composability enables the crea- 280 tion of object aggregations that support abstract 281 views of larger phenomena. The framework must 282 scale up from few resources to a multitude. 283 Figure 3 represents a DT platform able to cap- 284 ture the behavior of a complex system. Some 285 applications are designed to monitor the situa- 286 tion for applying policies on specific issues (traf- 287 fic, transportation, etc.). When issues arise, 288 these applications implement mechanisms to 289 minimize impacts on users and optimize 290

resource usage. Other applications are simula-291 tions executed to understand how the "smart 292 city" could react to changes in policies of 293 resources' usage. Benefits of applying the DT 294 concept to the "smart city" are many. These 295 advantages depend upon the introduction of 296 higher programmability levels, a strong integra-297 tion with AI/ML capabilities, the elimination of 298 silo constraints, and the possibility to simulate 299 300 the functioning of a city.

### 301 BUSINESS AS USUAL?

302 The DT concept has business implications. It changes the nature of POs and products. DT 303 properties facilitate the adoption of servitiza-304 tion, i.e., the ability to transform a physical prod-305 uct into a set of services offered to the user.<sup>17,18</sup> 306 Servitization nurtures customization of function-307 alities, making products more aligned to the life-308 styles and needs of people and it introduces 309 additional innovations in the service area.<sup>19</sup> 310 Products could even be modified, improved, and 311 customized by the user. New functions can be 312 added to products if users' needs change. The 313 customer relationship process could be trans-314 formed.<sup>20</sup> Customers are "entangled" with prod-315 ucts. If malfunctions emerge in a product, they 316 can be predicted before they actually occur and 317 the impact on users could be mitigated. Mainte-318 nance can be improved by focusing more on pre-319 venting problems than on solving them. The 320 products' value chain could be largely modified. 321 As the mobile phone industry showed, a rich 322 application layer has a tremendous impact on 323 products and it can determine success in a 324 global market. Customization, and the actors 325 supporting it, could become an important com-326 ponent of the entire value chain of new digital 327 markets. 328

### 329 CONCLUSIONS

The DT approach promises to have impact. It 330 may provide solutions in different sectors (smart 331 cities, e-health, e.g., virtual patient, automotive, 332 cultural heritage), supporting the provision of 333 servitized products, and programmability of 334 complex systems. It fosters new ways of doing 335 business by transforming products into sets of 336 customizable services (an autonomous car and a 337

smart building). A precise definition of the DT can help in better understanding requirements and impacts on IoT software platforms. DTs should be evaluated for their ability to support and deliver the expected benefits. Further investigation on how DTs can enable an ecosystem of applications that are feasible, marketable, and sustainable by the industry is needed. There are two major concerns: feasibility, i.e., the complexity and technical challenges associated with the creation of scalable, secure DT frameworks are such that the construction of a viable platform remains to be proven in-the-large: and user ownership, i.e., the possibility to frame users into a system of products and applications that limit privacy. The DT approach needs validation before it will be widely accepted and used. It already is a powerful means to control, govern, and program the lifecycle of objects, physical resources, and products, for providing better services to end-users. It is a challenge to academia and industry to find relevant applications for it.

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