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## Experimental insights on the propagation of fine-grained geophysical flows entering water

### Alexis Bougouin<sup>1</sup>, Olivier Roche<sup>1</sup>, Raphaël Paris<sup>1</sup> and Herbert E. Huppert<sup>2</sup>

<sup>1</sup>Université Clermont Auvergne, CNRS, IRD, OPGC, Laboratoire Magmas et Volcans, F-63000
 <sup>2</sup>Institute of Theoretical Geophysics, King's College, University of Cambridge, CB2 1ST,
 United Kingdom

### Key Points:

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9	•	Gas-fluidized granular flows down an inclined plane entering water are investigated
10		experimentally and compared to those propagating in air
11	•	The presence of the water body promotes the generation of a granular jet above
12		the free surface and a particle-driven gravity current underwater
13	•	The granular jet and the current are well described by ballistic motion theory and
14		the physics of gravity currents, respectively

Corresponding author: A. Bougouin, alexis.bougouin@univ-lehavre.fr

#### 15 Abstract

Granular flows that propagate down a mountainside, then reach the sea, a lake or a river 16 and finally, travel underwater, is a common event on the Earth's surface. To help the 17 description of such events, laboratory experiments on gas-fluidized granular flows enter-18 ing water are performed, analyzed, and compared to those propagating in air. The orig-19 inality of this study lies in the fluidization process, which improves the laboratory mod-20 elling of geophysical flows by taking their high mobility into account. Qualitatively, the 21 presence of the water body promotes the generation of a granular jet over the water sur-22 face, a leading and largest wave, and a particle-driven gravity current underwater. Hy-23 drodynamic forces mainly play a dissipative role by slowing and reducing the spreading 24 of the granular mass underwater, but a low amount of grains are still transported by the 25 turbulent fluid as a gravity current far away. The temporal evolution of the granular jet 26 and the particle-driven gravity current are well described by ballistic motion theory and 27 scaling laws of homogeneous gravity currents, respectively. Most currents propagate with 28 a constant flow-front velocity along the horizontal bottom, which is controlled by the flow 29 height depending on the water depth. In constrast, the bulk volume concentration of par-30 ticles in the current is estimated to be nearly constant, interpreted as a critical concen-31 tration above which the excess of particles cannot be maintained by the turbulent fluid. 32 This experimental study highlights the complexity of the dynamics and deposits of gran-33 ular masses when they encounter a water body. 34

#### <sup>35</sup> Plain Language Summary

Geophysical granular flows driven by gravity occur frequently on the Earth's sur-36 face, as a result of climatic, tectonic or volcanic events. When they occur near the sea, 37 a lake or a river, the granular flows may enter water, generate tsunamis, and propagate 38 underwater. This study presents laboratory experiments on gas-fluidized granular flows 39 entering water, which are performed in a 7 m-long channel and recorded by high-speed 40 cameras. The fluidization process ensures dynamic similarity for modelling of highly mo-41 bile geophysical flows composed of fine materials, which are predisposed to reach the coast 42 and generate turbidity currents underwater. The main contributions of this study are 43 summarized as follows: (i) we show that fine-grained flows entering a water body gen-44 erate both a granular jet over the water surface and a particle-driven gravity current un-45 derwater; (ii) we highlight the dissipative role of water in slowing and reducing the spread-46 ing of the granular mass underwater, while a low amount of grains is still transported 47 as a gravity current far away; and (iii) we describe the dynamics of the granular jet and 48 gravity current using simple theoretical models including major physical processes. 49

Keywords: laboratory experiments, granular media, fluidization process, geophys ical flows, gravity currents, tsunamis.

#### 52 1 Introduction

Geophysical granular flows driven by gravity occur frequently on the Earth's sur-53 face, as a result of climatic, tectonic, or volcanic events (Delannay et al., 2017). Gran-54 ular flows contribute significantly to the global sediment cycle and the shape of landscapes. 55 When they occur near the sea, a lake or a river, these solid-fluid mixtures may enter wa-56 ter, generate tsunamis, and propagate underwater (Løvholt et al., 2015). The subaque-57 ous flows are known to be more highly mobile compared to subaerial flows and they may 58 cause severe damage to submarine facilities (De Blasio et al., 2006). To predict their po-59 tential impact offshore, it is essential to understand the flow dynamics of subaerially-initiated 60 granular flows after impacting water. 61

Many field observations reported the situation of submarine landslides evolving to
 turbidity currents (e.g., Heezen & Ewing, 1952, 1955; Mulder et al., 1997; Talling et al.,

2007; Hsu et al., 2008). There are different ways to define these currents, but they broadly 64 consist of very dilute particle-laden flows in which grains are mainly suspended by the 65 turbulent water (Kneller & Buckee, 2000). In some cases, the dilute clouds can overlay 66 dense near-bed layers, as recently shown by field measurements (Paull et al., 2018; Sim-67 mons et al., 2020; Wang et al., 2020). It is more difficult to find such reports about the 68 transformation of a subaerial granular mass after entering water, because interest has 69 mainly focused on the wave generation (e.g., Weiss et al., 2009). However, it is expected 70 that granular flows composed of fine materials (e.g., fine-grained landslides, ash-rich py-71 roclastic flows) are particularly predisposed to generate subaqueous turbidity currents 72 when they enter water because particles have low settling velocity and they can be eas-73 ily suspended by the turbulent water. To the best of our knowledge, such an event has 74 never been observed and only field works on volcaniclastic deposits have discussed tur-75 bidity currents formed by pyroclastic flows entering water. During the 12-13 July 2003 76 paroxysmal dome collapse of Soufrière Hills volcano, more than  $200 \times 10^6$  m<sup>3</sup> of hot py-77 roclastic material entered the ocean. Phreatic explosions were observed and a cloud surge, 78 decoupled from the main flow, travelled 2 to 3 km over the water surface (Edmonds & 79 Herd, 2005). This phreatic activity promoted the ingestion of sea water by the pyroclas-80 tic flow that evolved as a cool and dense water-saturated granular flow underwater (Trofimovs 81 et al., 2008). Additionally, a grain-size sorting process occurred within the subaqueous 82 83 flow, which led to a fine-particle overload in the upper part and the formation of distal turbidity currents that propagated for more than 30 km on gentle slopes of the sea floor 84 (Trofimovs et al., 2006, 2008). Similar transformation of a subaerially-initiated pyroclas-85 tic flow into a subaqueous turbidity current was proposed by Whitham (1989) for ex-86 plaining Roseau Ash submarine deposits (Dominica Island, Lesser Antilles). The volcani-87 clastic turbidite deposit was found up to 250 km from the source, at 3000 m water depth. 88 Cas and Wright (1991) reported the possible scenarios when hot pyroclastic flows inter-89 act with the sea, and most of them highlight the formation of turbidity currents. 90

Most experimental studies on granular masses entering water considered dry, heavy, 91 and coarse grains leading to dense granular flows depositing rapidly underwater (e.g., 92 Fritz et al., 2003b; Viroulet et al., 2014; Miller et al., 2017). The generation of particle-93 driven gravity currents by initially-subaerial fine-grained flows has therefore been poorly 94 investigated. Mcleod et al. (1999) first considered different grain-fluid mixtures, initially 95 maintained above the free-surface and released over an inclined plane, which entered fresh 96 water. They concluded that both negatively and positively buoyant gravity currents can 97 be obtained separately or together, by varying the grain and fluid densities of the mix-98 ture. These different flow dynamics have also been reported for homogeneous gravity cur-99 rents released into a two-fluid layer (Monaghan et al., 1999; Legros & Druitt, 2000; Mon-100 aghan, 2007; Wells & Wettlaufer, 2007; Cortés et al., 2014). Freundt (2003) focused on 101 the thermal effects of volcanic ash heated up to 400°C, entering water at ambient tem-102 perature. Steam explosions and major ash-cloud surges propagating above the water sur-103 face were obtained with increasing temperature. By contrast, the dynamics of particle-104 driven gravity currents was mainly controlled by the mass flux of the granular flow and 105 the water depth, while it was not significantly affected by the temperature. In fact, heat 106 transfers mainly modified the early stages of the gravity currents, which propagated dom-107 inantly along the water surface at high temperature. Despite these studies, there is still 108 a lack on the description of the granular dynamics after such flows enter water, which 109 is the focus of the present study. 110

Most works on the propagation of particle-driven gravity currents considered simple configurations using laboratory experiments, numerical simulations and theoretical descriptions. One of the most famous configurations corresponds to the propagation of a fixed volume of a heavy fluid released into a lighter fluid on a horizontal plane, the socalled lock-exchange problem (e.g., Huppert & Simpson, 1980; Huppert, 1982; Rottman & Simpson, 1983). In this case, the motion of homogeneous gravity currents is driven by the density difference between the current and the surrounding fluid. Depending on

the dominant forces, the flow dynamics of the current in the two-dimensional configu-118 ration is usually described in three distinct stages, well predicted by shallow laver/lubrication 119 models: (i) a slumping regime dominated by inertia during which the flow-front veloc-120 ity remains constant; (ii) an inertial self-similar regime characterized by a buoyancy/inertia 121 balance for which the front position scales with time as  $x_f \propto t^{2/3}$ ; and (iii) a viscous 122 regime controlled by a balance between buoyancy and viscous dissipation in which the 123 front evolves as  $x_f \propto t^{1/5}$  (Huppert & Simpson, 1980; Huppert, 1982; Rottman & Simp-124 son, 1983). This configuration has been extended to gravity currents propagating down 125 an inclined plane, for which the gravity current is described by an acceleration phase fol-126 lowed by a deceleration phase (e.g., Beghin et al., 1981; Monaghan et al., 1999; Dai & 127 Garcia, 2010; Dai, 2013, 2014). When the current decelerates, the front position scales 128 as  $x_f \propto t^{2/3}$  or  $x_f \propto t^{1/2}$  according to the preponderance of inertia or viscous effects, 129 respectively (Dai, 2014). The motion of these gravity currents is also well predicted by 130 the thermal theory based on the mass and momentum conservation by considering the 131 entrainment of the ambient fluid (Beghin et al., 1981). Finally, for gravity currents down 132 an inclined plane produced by a continuous inflow, the currents evolve with a constant 133 front velocity depending mainly on the buoyancy flux, while the effect of the slope an-134 gle is unsignificant (e.g., Britter & Linden, 1980; Baines, 2001, 2005). We recall that other 135 simple configurations have also been considered, in which the above-mentioned stages 136 137 were observed despite a modification of the scaling laws (e.g., Huppert, 1982; Zgheib et al., 2015; Zhu et al., 2017). The particle-driven gravity currents are fundamentally grav-138 ity currents whose density is greater than that of the surrounding fluid because of their 139 suspended grains (Meiburg & Kneller, 2010; Wells & Dorell, 2020). However, the flow 140 dynamics of these currents are more complex than those of homogeneous gravity cur-141 rents, i.e. the intrusion of a pure fluid into another fluid, because the particle concen-142 tration evolves with time and position due to the erosion/deposition of grains (e.g., Bon-143 necaze et al., 1993, 1995). 144



Figure 1. Oblique view of a particle-driven gravity current, generated by a gas-fluidized granular flow down an inclined plane entering water. The dashed line indicates the bottom of the inclined plane above the level of the undisturbed water surface. On the left, the subaerial granular flow is relatively thin, dense and rapid before evolving to a thick and dilute particle-driven gravity current underwater. An impulse wave is also generated on the water surface, which has already been studied in Bougouin et al. (2020).

In the present work, laboratory experiments on gas-fluidized granular flows entering a body of water are performed to understand better the dynamics of geophysical flows after they reach the sea, a lake or a river. More specifically, it focuses on granular flows composed of fine materials, which are predisposed to generate particle-driven gravity cur-

rents underwater, as illustrated by the oblique view of Figure 1. The questions raised 149 in the present contribution are the following. What is the effect of a water body on the 150 propagation of subaerially-initiated fine-grained flows along an inclined plane? Does the 151 water body play a dissipative or a driven role on the granular material? Can the gen-152 eral evolution of the granular material be described using simple theoretical models? In 153 order to provide some answers, the paper is organized as follows. In Sec. 2, the exper-154 imental setup and materials used are presented. Sec. 3 highlights the influence of the 155 presence of a water body on the granular dynamics through qualitative observations and 156 a comparison between gas-fluidized granular flows propagating only in air and entering 157 water. Finally, the evolution of the granular material, i.e. the initial granular jet above 158 the water surface and the particle-driven gravity current underwater, is described using 159 theoretical models (Secs. 4 and 5). 160

#### <sup>161</sup> 2 Experimental setup

#### 162 2.1 Apparatus

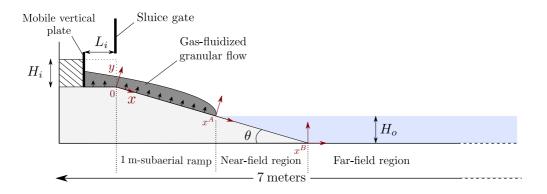


Figure 2. Sketch of the experimental setup with the initial parameters (the height  $H_i$  and the length  $L_i$  defining the initial dimensions of the granular column, the slope angle  $\theta$  of the inclined plane, and the water depth  $H_o$ ). Black arrows represent the air flux through the 12  $\mu$ m-porous bottom plane for the fluidization process. The streamwise coordinates  $x^A$  and  $x^B$  indicate the transition from the 1 m-subaerial ramp to the immersed ramp, and the end of the inclined plane that connects to the horizontal bottom, respectively. The zones containing the immersed inclined plane and the horizontal bottom are referred to as the near- and far-field regions, respectively.

Laboratory experiments are conducted in a horizontal transparent channel of rect-163 angular cross-section with dimensions of  $7 \times 0.8 \times 0.2$  m<sup>3</sup> in the longitudinal, vertical 164 and spanwise directions, respectively. A sketch of the experimental setup is given in Fig-165 ure 2. One side of the channel is equipped with a reservoir delimited by a sluice gate and 166 a mobile vertical plate to vary the initial length  $L_i$  of the granular column. In this study, 167 the length and the height of the initial granular column are varied in the range  $L_i$  = 168  $[9:34] \pm 0.5$  cm and  $H_i = [10:42] \pm 0.5$  cm, respectively. The reservoir is connected 169 to an inclined plane composed of a 1 m-subaerial ramp and an immersed ramp. Both 170 the bottom of the reservoir and of the 1 m-subaerial ramp are equipped with a 12  $\mu$ m-171 porous plate to fluidize the granular flow by a vertical air flux before entering water (see 172 black arrows, in Figure 2). Here, the granular material is fluidized with an air velocity 173 of  $U_f \sim 4.7 \pm 0.1 \text{ mm.s}^{-1}$ , larger than the minimum fluidization velocity  $U_{mf} \sim 3.8 \pm$ 174  $0.1 \text{ mm.s}^{-1}$ , which ensures that the granular flow is fully fluidized when it impacts wa-175 ter. The minimum fluidization velocity  $U_{mf}$  is estimated prior the experiments as the 176 minimum velocity for which the gas pore pressure counterbalances the pressure of a static 177

granular column. The length of the immersed ramp varies as  $H_o/\sin\theta$ , where the slope angle is set to  $\theta = 5^{\circ}$ ,  $10^{\circ}$ ,  $15^{\circ}$ ,  $20^{\circ}$ , and  $30^{\circ}$  and the water depth is varied up to  $H_o =$  $38.5 \pm 0.1$  cm. In the following, the zones containing the immersed ramp and the horizontal bottom are referred to as the near- and far-field regions, respectively. On the opposite side of the channel, a wave breaker is used to limit the reflected waves, which could affect the granular flow dynamics underwater. Indeed, the wave velocity is still much larger than that of the particle-driven gravity current.

As discussed by Bougouin et al. (2020), the initial conditions of the experiment con-185 trol the flow parameters, namely the volume, the velocity, and the height of the gran-186 ular flow. The volume per unit width is estimated as  $v = (H_i - h_r)L_i$ , where  $h_r$  is the 187 residual height of grains in the reservoir at the end of the experiment. The height pro-188 file of the granular flow is non-uniform along the inclined plane, and the front-height  $h_f$ 189 at the impact is therefore chosen as the flow height at 10 cm behind the front (more in-190 formation is provided in the Bougouin et al. (2020)'s Supporting Information). The con-191 stant front velocity  $u_f$  of fluidized granular flows is estimated at the impact, from the 192 slope of the linear trend between the front position and time. Finally, as both  $h_f$  and 193  $u_f$  vary together with  $H_i$ , the flow rate per unit width  $q = h_f u_f$  is also defined. In this 194 study, the control parameters are varied in the range  $v = [1.5:13.2] \pm 0.1 \text{ dm}^2$  (with 195  $1 \text{ dm}^2 = 10^{-2} \text{ m}^2$ ,  $h_f = [0.9 : 2.8] \pm 0.4 \text{ cm}, u_f = [2 : 3.7] \pm 0.1 \text{ m.s}^{-1}$ , and  $q = [1.8 : 10^{-2} \text{ m}^2]$ 196  $8.5] \pm 1 \text{ dm}^2 \text{.s}^{-1}$ , respectively. 197

At the initial time t = 0, the sluice gate is rapidly and entirely removed with a 198 velocity of about  $2 \text{ m.s}^{-1}$  by releasing a suspended weight, which triggers the collapse 199 of the granular column on the inclined plane. The flow dynamics of the granular mate-200 rial is recorded using a classical shadow graph method with two Photron Fastcam  $1024 \times$ 201 1024 pixel cameras and LED panels on the back side of the channel. This optical method 202 allows vizualization of the interface between fluids due to different light absorptions. Here, 203 the granular material, the water layer, and the ambient air are represented in black, gray 204 and white, respectively (see Figure 3, for instance). The first camera records a large view 205 of the experiment, while the second camera focuses on the flow dynamics of currents in 206 the far-field region. The resolution obtained is 4 mm/pixel and 0.8 mm/pixel, respec-207 tively, and the acquisition rate is 250 Hz. Finally, the extraction process is performed 208 using a Matlab routine based on a threshold method. 209

#### 210 2.2 Materials

The granular material used corresponds to quasi-monodisperse spherical glass beads 211 manufactured by Wheelabrator, with a diameter of  $d = 65 \pm 10 \ \mu \text{m}$  and a density of 212  $\rho_p = 2550 \pm 50 \text{ kg.m}^{-3}$ , respectively. Before each experiment, the grains are weighted, 213 poured into the reservoir, fluidized and then the height of the initial column is measured. 214 The particle concentration of the initial granular column is  $\phi_i = V_{grains}/V_{column} \sim$ 215  $0.56 \pm 0.01$ , where  $V_{grains}$  and  $V_{column}$  denote the volume of grains and the total vol-216 ume of the initial column, respectively. This corresponds to an initial bulk density of  $\rho = \phi_i \rho_p + (1-\phi_i)\rho_a \sim 1400 \text{ kg.m}^{-3}$ , where  $\rho_a \sim 1.2 \text{ kg.m}^{-3}$  is the density of ambient air. 217 218 Both the particle concentration and the density are expected to remain constant in the 219 reservoir and during the flow propagation on the 1 m-subaerial ramp because of the sus-220 tained gas flow from the bottom. 221

Some experiments of dense liquid flows entering water are also performed to compare the propagation of homogeneous gravity currents with that of particle-driven gravity currents. Sodium Chloride (NaCl) is therefore added to dyed water with a concentration of 325g/kg of water, leading to a dense saline liquid of  $\rho \sim 1200$  kg.m<sup>-3</sup> measured by a DMA 35 Anton Paar electronic densimeter. In Sec. 5, we will show that the density of homogeneous gravity currents is roughly similar to that of particle-driven gravity currents, and their dynamics can therefore be compared together depending on the

flow conditions at the impact. It should be remembered that no gravity currents would 229 be generated by the entrance of a fluid into another fluid of the same density (Bullard 230 et al., 2019; Clous et al., 2019), while reversing buoyancy of currents would be observed 231 with a lighter fluid into a heavy fluid (Monaghan et al., 1999; Monaghan, 2007). For dense 232 liquid flows, the initial parameters are  $H_i = [16 : 40]$  cm,  $L_i = 34$  cm,  $H_o = 26.4$ 233 cm and  $\theta = 15^{\circ}$ , while the flow parameters at the impact are found in the range v =234  $[5.2 : 12.5] \text{ dm}^2$ ,  $u_f = [2.4 : 3.2] \text{ m.s}^{-1}$ ,  $h_f = [0.9 : 2.5] \text{ cm}$ , and q = [2.2 : 8.0]235  $dm^2.s^{-1}.$ 236

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#### 2.3 Scaling issues of geophysical granular flows

In this section, we propose to discuss the relevance and limitations of the experiments, which aim to help the understanding of fine-grained geophysical flows propagating down a mountainside, entering the sea, a lake or a river, and then propagating underwater far away.

The novelty of this study lies in the consideration of gas-fluidized granular flows, 242 which ensures a more suitable modelling of geophysical flows taking their high mobil-243 ity into account. Indeed, natural granular flows are known to exhibit energy dissipation 244 lower than at the laboratory scale, for which several physical mechanisms have been pro-245 posed, i.e. basal lubrication (e.g., Bowden & Hughes, 1939; Shreve, 1968; Goren & A., 246 2007), acoustic or mechanical fluidization (e.g., Melosh, 1979; T. R. H. Davies, 1982; Collins 247 & Melosh, 2003), high gas pore pressure (e.g., Major & Iverson, 1999; Sparks, 1976), dy-248 namic fragmentation (e.g., T. R. Davies & McSaveney, 2009), and material entrainment 249 (e.g., Hungr & Evans, 2004; Sovilla et al., 2006), among others. At the laboratory scale, 250 a granular flow fluidized at the source propagates faster and farther than a non-fluidized 251 granular flow with the same initial conditions (Roche et al., 2008). In case of fluidiza-252 tion along the flow path and for gentle slopes, the fluidization process also prevents the 253 deposition of grains along the bottom plane, and the entire volume of the granular flow 254 thus enters water (Bougouin et al., 2019). This behavior is attributed to the high gas 255 pore pressure generated by the fluidization process, which reduces the internal friction 256 within granular flows and therefore promotes the high mobility. The dynamics of exper-257 imental and natural granular flows can be compared through the Froude number Fr =258  $u_f/(gh_f)^{1/2}$ , which is found in the range Fr = [6:9] corresponding to the upper range 259 of natural flows (Delannay et al., 2017). Moreover, the bulk flow to water density ratio 260 is about  $\rho/\rho_f \sim 1.4$  which is consistent with that of most natural flows (Delannay et 261 al., 2017), even if ash-rich pyroclastic flows and dry snow avalanches may be less dense 262 than water. This experimental configuration seems therefore to be a relevant modelling 263 for investigating most geophysical granular flows entering water, despite some limitations. 264

In the present configuration, the fluidization process is facilitated using fine, spher-265 ical, and monodisperse beads, which is a crude assumption about natural flows usually 266 composed of different grain sizes, densities, and shapes. In this way, some physical mech-267 anisms such as the grain-size sorting process in or out of the water, the reversing buoy-268 ancy and the coarse grain spreading underwater cannot be reproduced here. The grain 269 size to flow length ratio of natural flows cannot also be maintained at the laboratory scale, 270 because the grain size used in the experiments is usually similar to those found in the 271 field. Moreover, natural pyroclastic flows can have high temperatures up to  $500-600^{\circ}$ 272 when they enter the sea. Freundt (2003) concluded that the main consequence of high 273 temperature was the generation of phreatic explosions and major ash-cloud surges prop-274 agating over the water surface, while particle-driven gravity currents were slightly affected 275 close to the shoreline. However, an open question still remains about the formation of 276 welded deposits, which could not be addressed here (Sparks et al., 1980; Cas & Wright, 277 1991; Kokelaar & Busby, 1992). In summary, the present setup ensures a suitable mod-278 elling of dense, cold or moderate-heated, fine particle-rich geophysical flows entering wa-279 ter. 280

#### <sup>281</sup> 3 Gas-fluidized granular flows entering water

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#### 3.1 Preliminary observations: Role of the water body

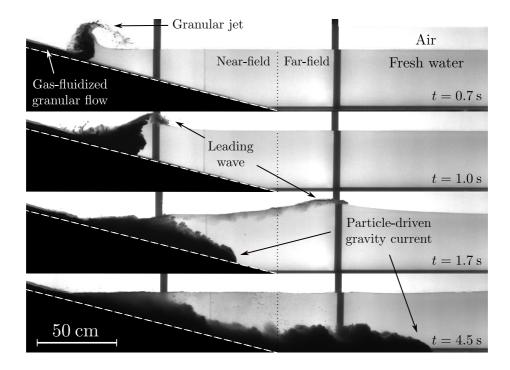


Figure 3. Snapshots of the entrance of a gas-fluidized granular flow into water, for  $H_i = 22$  cm,  $L_i = 34$  cm,  $H_o = 38.5$  cm, and  $\theta = 15^{\circ}$ , at four different times from the opening of the sluice gate. A movie of the same experiment and a compilation of experimental movies from different camera viewpoints are also available in the Supporting Information.

At the initial time t = 0, the initial column of grains is released, collapses and forms 283 a gas-fluidized granular flow on the subaerial inclined plane until reaching water. The impact between the granular flow and the water body generates (i) an initial granular 285 jet corresponding to grains ejected above the water surface, (ii) a leading and largest wave, 286 and (iii) a turbulent mixing zone from which a particle-driven gravity current is spon-287 taneously formed (Figure 3). These observations are direct consequences of the presence 288 of a water body, which have already been observed for fine particle-fluid mixtures en-289 tering water (Mcleod et al., 1999; Freundt, 2003; Allen et al., 2012; Bougouin et al., 2020). 290 By contrast, both the granular jet and the gravity current have never been reported in 291 the literature for coarse granular materials [i.e.,  $d > \mathcal{O}(10^{-3})$  m] under similar flow con-292 ditions (e.g., Fritz et al., 2003a; Heller et al., 2008; Viroulet et al., 2014; Zitti et al., 2016; 293 Miller et al., 2017). It suggests therefore that both the granular jet and the particle-driven 294 gravity current are mainly controlled by the grain-fluid interaction. In fact, the flow dy-295 namics of particle-driven gravity currents along the bottom plane looks more like that 296 of homogeneous gravity currents penetrating a two-fluid layer (Monaghan et al., 1999; 297 Legros & Druitt, 2000; Monaghan, 2007; Wells & Wettlaufer, 2007; Cortés et al., 2014). 298 In this configuration, a splitting of the homogeneous gravity current can even be obtained, which could be related to the formation of the granular jet above the water surface and 300 of the particle-driven gravity current underwater. However, some caution has to be ex-301 ercised here because the splitting of homogeneous gravity currents was attributed to lighter 302 fluid incorporated into the current by turbulent entrainment (Wells & Wettlaufer, 2007; 303

Cortés et al., 2014), which is not expected to occur for gas-fluidized granular flows propagating in air.

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#### 3.2 Comparison with gas-fluidized granular flows in air

In this section, we highlight the effect of a water body on the granular dynamics and the associated deposits by comparison of gas-fluidized granular flows propagating only in air and entering water, under the same initial conditions.

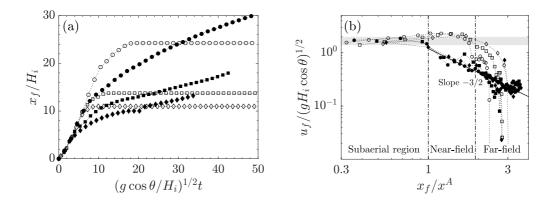


Figure 4. (a) Front position  $x_f/H_i$  as a function of normalized time  $(g \cos \theta/H_i)^{1/2} t$  for gasfluidized granular flows propagating in air (opened symbols) and entering water (closed symbols), with  $H_i = 10 \text{ cm}$  (diamonds),  $H_i = 22 \text{ cm}$  (squares) and  $H_i = 30 \text{ cm}$  (circles). The other initial parameters are set to  $L_i = 34 \text{ cm}$ ,  $\theta = 15^\circ$ , and  $H_o = 26.6 \text{ cm}$  (in the presence of water). (b) Front-velocity  $u_f/(gH_i \cos \theta)^{1/2}$  as a function of the front position  $x_f/x^A$ , where  $x^A$  is the streamwise coordinate of the shoreline. The gray area corresponds to  $u_f/(gH_i \cos \theta)^{1/2} = [1.4:2]$ ; the solid line is a slope -3/2; and the dotted-dashed lines delimit the subaerial, near- and farfield regions.

One of the relevant macroscopic analyses to compare the dynamics of granular flows 310 is the tracking of the front position  $x_f$  and the front-velocity  $u_f$  with time and position 311 (Figure 4). The presence of a water body significantly affects the temporal evolution of 312 the flow front beyond the initial height  $H_i$ , the latter being already reported for water 313 dam-break flows (e.g., Ritter, 1892; Laubert & Hager, 1998; Ancey et al., 2008) and sub-314 aerial granular flows (e.g., Roche et al., 2008; Mangeney et al., 2010; Farin et al., 2014; 315 Bougouin et al., 2020). At early times, all curves collapse together corresponding to the 316 propagation of granular flows down the subaerial inclined plane. During this stage, the 317 flow front slightly accelerates along the plane, as predicted by the theory for a friction-318 less fluid flow down an inclined plane (Ancey et al., 2008). We recall that the acceler-319 ation phase of channeled granular flows is expected to end when the gravity is balanced 320 by sidewall friction (Brodu et al., 2015). For the sake of simplicity, the averaged front 321 velocity can also be defined in the range  $u_f/(gH_i\cos\theta)^{1/2} = [1.4 : 2]$  [gray area, in 322 Figure 4(b)], in agreement with values found in the case of dam-break flows on a hor-323 izontal plane (Dressler, 1954; Jánosi et al., 2004; Leal et al., 2006; Roche et al., 2008; Bonometti 324 et al., 2008; Bougouin et al., 2017). During the second phase, gas-fluidized granular flows 325 either enter water and then propagate in the form of subaqueous particle-driven grav-326 ity currents, or they continue to flow down the subaerial inclined plane without the sus-327 tained gas flow from the bottom. The main consequence of the water body is to slow down 328 the spreading of the granular material. A gross estimate of the normalized front veloc-329 ity with the normalized front position gives  $u_f/(gH_i\cos\theta)^{1/2} \propto (x_f/x^A)^{-3/2}$  [solid line, 330

in Figure 4(b)]. However, the flow dynamics of the currents will be more fully investi-

gated in Sec. 5. Finally, the gas-fluidized granular flows in air stop rapidly on the hor-

izontal bottom, while the gravity currents continue slowly to propagate underwater [Far-

field region, in Figure 4(b)].

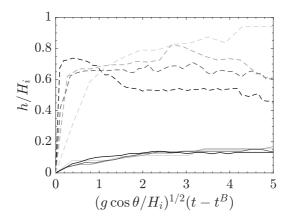


Figure 5. Temporal evolution of the flow height  $h/H_i$  at the slope break  $x - x^B = 0$ , for gasfluidized granular flows propagating in air (—) and entering water (- - -), with  $H_i = 10, 22, 30$ and 42 cm (from light to dark gray). The other initial parameters are set to  $L_i = 34$  cm,  $\theta = 15^{\circ}$ , and  $H_o = 26.6$  cm (in the presence of water).

The morphology of the granular flow can also be investigated here, because it is particularly modified by the presence of the water body (Figure 5). More specifically, the major effect of water is to generate thick and dilute particle-driven gravity currents underwater compared to dense and thin gas-fluidized granular flows in air. Moreover, the inertial dimensionless form used here allows the collapse of the height profile of gasfluidized granular flows obtained for different  $H_i$ , which does not hold true for subaqueous particle-driven gravity currents.

Finally, at sufficiently long times (i.e., from a few seconds to tens of seconds), the 342 granular material stops forming a final deposit along the bottom surface (Figure 6). Again, 343 the morphology of the granular deposit strongly differs for gas-fluidized granular flows 344 propagating in air and those entering water. The presence of the water body leads to 345 a thick and voluminous granular mass along the inclined plane probably due to a dense 346 granular flow, while a thin layer of grains, initially suspended in the gravity current, is 347 deposited on the horizontal bottom. By contrast, the subaerial granular flows form only 348 a massive deposit at the end of the inclined plane. The inset of Figure 6 shows that the 349 presence of water reduces significantly the runout of granular flows, as already reported 350 for coarse grains falling into water (Mazzanti & De Blasio, 2011; Viroulet et al., 2014; 351 Miller et al., 2017). The runout is defined here as  $h(x - x^B = R_f) = H_i/10$  to be free 352 of the thin and very elongated granular layer deposited by the current. Overall, the pres-353 ence of the water body therefore plays a dissipative role by slowing and reducing the spread-354 ing of the granular material, even if a low amount of grains are still transported by the 355 turbulent fluid far away. 356

#### 357 **3.3 Discussion of results**

Our laboratory experiments on fine-grained granular flows entering a water body have revealed the following results. Overall, the presence of water promoted the formation of a granular jet, corresponding to grains ejected above the water surface and then

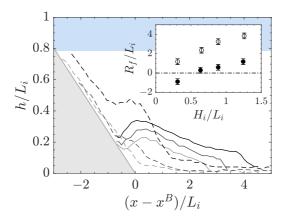


Figure 6. Morphology of granular deposits along the bottom surface, for gas-fluidized granular flows propagating in air (—, opened circles) and entering water (- - -, closed circles), with  $H_i = 22, 30$  and 42 cm (from light to dark gray). The other initial parameters are set to  $L_i = 34$  cm,  $\theta = 15^\circ$ , and  $H_o = 26.6$  cm (in the presence of water). Inset: Runout  $R_f/L_i$ , defined as  $h(x - x^B = R_f) = H_i/10$ , as a function of the aspect ratio  $a = H_i/L_i$  of the initial column.

falling onto it, and a particle-driven gravity current underwater. Moreover, hydrodynamics forces mainly played a dissipative role by slowing and reducing the spreading of the granular mass underwater, even if a low amount of grains were still transported by the turbulent fluid as a gravity current far away. These observations highlight the complexity of granular flows impacting water, with in particular, a splitting of granular masses. These results are now discussed to help the interpretation of some submarine deposits in the natural environment.

In the field, both the morphology and the internal structure of deposited material 368 represent a suitable marker of the dynamics of granular flows. In the case of fine-grained 369 geophysical flows entering water, it is expected from our experiments to obtain distinct 370 submarine deposits, recording successively gravity currents, dense basal flows, and gran-371 ular jets. The 1995-2010 eruption of Soufrière Hills volcano represents an invaluable case 372 study of pyroclastic flows entering the sea with volcanic activity having been intensively 373 documented (e.g., Young et al., 1998; Trofimovs et al., 2006, 2008; Le Friant et al., 2009, 374 2010; Trofimovs et al., 2012; Wadge et al., 2014, among others). A large part of volcani-375 clastic materials was transported into the sea, and associated submarine deposits have 376 been particularly well described through bathymetric survey data and core samples. Over-377 all, massive coarse-grained deposits were observed close to the slope break, which was 378 interpreted as the sign of dense granular flows propagating slowly underwater (Le Fri-379 ant et al., 2009, 2010; Trofimovs et al., 2012). A grain-size sorting process also promoted 380 the formation of dilute turbidity currents composed of fine materials, which deposited 381 as thin and elongated masses far away from the shoreline (Trofimovs et al., 2006, 2008, 382 2012). Our experimental observations of submarine gravity currents and deposit mor-383 phologies are consistent with those reported from the field. Additionally, they highlight 384 that grain-size sorting processes are not needed to form both proximal massive deposits 385 and distal turbidites. Finally, deposits of granular jets have never been mentioned in the 386 literature, suggested that they were probably hardly recognized. 387

### <sup>388</sup> 4 Spatio-temporal evolution of the granular jet

The entrance of a gas-fluidized granular flow into a water body generates first a 389 granular jet above the water surface, before falling onto it. Here, we propose to describe 390 the spatio-temporal evolution of the position of the jet crest  $(X_c, Y_c)$  considering a bal-391 listic trajectory. A sketch of this issue is shown in Figure 7(a), with the flow parame-392 ters before entering water (upper) and the granular jet after the impact (bottom). It can 393 already be anticipated that both the initial length  $L_i$ , which only controls the volume 394 of the granular flow, and the water depth  $H_o$  could be disregarded here, as the granular jet is rapidly generated near the shoreline. The control parameters for this problem 396 are therefore the slope angle  $\theta$  of the inclined plane and the front velocity  $u_f$ , the lat-397 ter being controlled by the initial height  $H_i$  of the column and the slope angle  $\theta$ . Fig-398 ure 7(b) shows snapshots of the typical evolution of a granular jet over the free-surface 399 at different times from the impact. Note that the granular jet could also contain some 400 water, but the proportion is expected to be low compared to those of grains and the am-401 bient air. 402

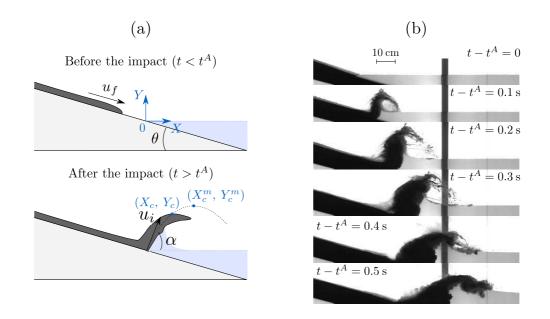


Figure 7. (a) Sketch of a gas-fluidized granular flow before (upper) and after (bottom) the impact with water. The trajectory of the granular jet is characterized by the crest position  $(X_c, Y_c)$  reaching a maximum height at the position  $(X_c^m, Y_c^m)$  and the time  $T^m$ , and described by ballistic motion theory considering an initial velocity  $u_i$  and an initial angle  $\alpha$ . (b) Snapshots of the typical evolution of a granular jet for  $u_f = 3.0 \text{ m.s}^{-1}$  and  $\theta = 15^{\circ}$ , at different times from the impact.

#### 4.1 Frictionless ballistic motion theory

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For the purpose of describing the trajectory of the granular jet crest, let us first consider a single grain ejected with an initial velocity  $u_i$  and an initial angle  $\alpha$  (with respect to the horizontal plane), i.e.  $(X_c, Y_c) = (0, 0)$  and  $t - t^A = 0$  with  $t^A$  the time at the impact [see Figure 7(a)]. To first order, the drag force of the ambient air on the grain motion can be neglected. Hence, the single grain is only subject to its own weight and momentum conservation reduces to  $(d^2X_c/dt^2, d^2Y_c/dt^2) = (0, -g)$  in the horizontal and vertical directions, respectively. Then one can simply obtain the temporal evo lution of the horizontal and vertical positions of the grain as

$$X_c = u_i \cos \alpha (t - t^A),\tag{1}$$

$$Y_c = -\frac{g}{2}(t - t^A)^2 + u_i \sin \alpha (t - t^A).$$
(2)

Additionally, the spatial evolution can also be expressed by combining equations (1) and (2), which leads to

$$Y_c = -\frac{g}{2u_i^2 \cos^2 \alpha} X_c^2 + \tan \alpha X_c.$$
(3)

<sup>414</sup> It can also be useful to predict the position  $(X_c^m, Y_c^m)$  and the time  $T^m$  at which <sup>415</sup> the maximum height is reached as discussed later in Sec. 4.3. This is obtained when  $dY_c/dt =$ <sup>416</sup>  $dY_c/dX_j = 0$ , at  $t = T^m$  and  $X_c = X_c^m$ . Using equations (1), (2) and (3), we obtain

$$X_c^m = \frac{\cos\alpha \sin\alpha}{g} u_i^2, \qquad Y_c^m = \frac{\sin^2\alpha}{2g} u_i^2, \qquad T^m = \frac{\sin\alpha}{g} u_i. \tag{4}$$

It should be noted that each quantity depends only on the initial conditions of the 417 ballistic trajectory, i.e. the initial velocity  $u_i$  and the initial angle  $\alpha$ . Now, we assume 418 that the grain motion of the jet crest can be related to that of a single grain with a bal-419 listic trajectory, which can be anticipated to be a crude assumption in view of dense gran-420 ular flows impacting the water body. In fact, this suggests that grain-grain interaction 421 can be neglected, at least in the upper region of the granular jet. In the following, it will 422 be shown that this model captures most of the physical mechanisms, giving a fairly good 423 description of the spatio-temporal evolution of the granular jet. 424

#### 4.2 Application to the experiments

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The validity of the predictive model is now assessed from experimental data. Fig-426 ure 8 shows a fairly good collapse of the spatio-temporal evolution of the granular jet 427 crest, using  $(X_c^m, Y_c^m)$  and  $T^m$  as length and time scales. The duration of the jet is (t-428  $t^A)/T^m \sim 1.5$  here, from which the jet falls down the generated leading wave. More-429 over,  $X_c/X_c^m$  and  $Y_c/Y_c^m$  have a quasi-linear and a 2-polynomial trend with the time 430  $(t-t^A)/T^m$  [solid lines, in Figs. 8(a)-(b)], which is consistent with the form of the the-431 oretical predictions given by equations (1) and (2), respectively. Similar conclusions can 432 also be drawn from the spatial evolution of the granular jet [Figure 8(c)] in comparison 433 with equation (3). This supports the idea that the trajectory of the jet crest could be 434 simply described from a frictionless ballistic trajectory of grains. Finally, the insets of 435 Figure 8 show the spatio-temporal evolution of the jet crest generated by dense liquid 436 flows impacting a water body (salt water into fresh water, here). In this case, the jet cor-437 responds to a volume of dense liquid ejected above the water surface. The dynamics of 438 liquid jets is equivalent to that of granular jets, as shown by the collapse of the exper-439 imental data and the solid lines. In the present configuration, the jet dynamics is there-440 fore mainly dependent on the flow conditions (e.g., flow velocity, slope angle), regard-441 less of the rheology of the flowing material (e.g., Newtonian fluid, granular material). 442

In order to describe the spatio-temporal evolution of the granular jet, the initial parameters  $(u_i, \alpha)$  of the model have to be quantified from the flow conditions. The temporal evolution of the horizontal and vertical positions of the granular jet crest, i.e.  $X_c(t)$ and  $Y_c(t)$ , are fitted by equations (1) and (2), respectively, for which  $u_i$  and  $\alpha$  can be

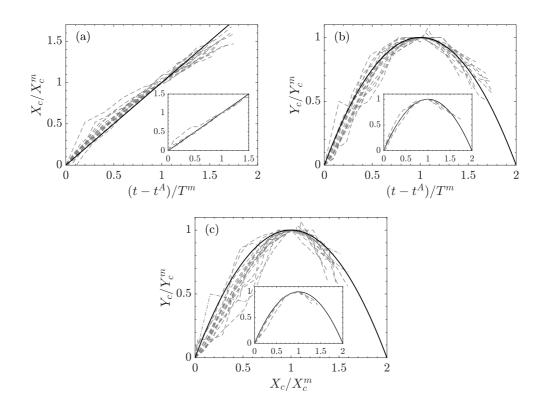


Figure 8. Evolution of (a) the horizontal position  $X_c/X_c^m$  and (b)-(c) the vertical position  $Y_c/Y_c^m$  of the jet crest generated by gas-fluidized granular flows (insets: dense liquid flows) impacting a water body, as a function of (a)-(b) the time  $(t - t^A)/T^m$  and (c) the horizontal position  $X_c/X_c^m$ , where  $(X_c^m, Y_c^m)$  and  $T^m$  are the position and the time at which the maximum height of the jet crest is reached. The solid lines correspond to (a)  $X_c/X_c^m = (t - t^A)/T^m$ , (b)  $Y_c/Y_c^m = -[(t - t^A)/T^m]^2 + 2(t - t^A)/T^m$ , and (c)  $Y_c/Y_c^m = -(X_c/X_c^m)^2 + 2X_c/X_c^m$ , respectively.

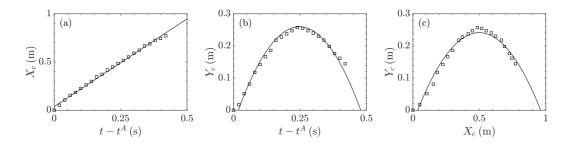


Figure 9. Spatio-temporal evolution of the granular jet crest, with  $u_f = 3.0 \text{ m.s}^{-1}$  and  $\theta = 15^{\circ}$ . Squares and solid lines correspond to the experimental data and the theoretical predictions [equations (1), (2) and (3)] with (a)-(b)  $u_i \sim 3.0 \text{ m.s}^{-1}$  and  $\alpha \sim 53^{\circ}$ , and (c)  $u_i \sim 3.1 \text{ m.s}^{-1}$  and  $\alpha \sim 48^{\circ}$ , respectively. To overcome the problem of time and space offsets, the fitted relations are not set to  $(X_c, Y_c) = (0, 0)$ , at  $t - t^A = 0$ .

adjusted. To overcome the problem of time and space offsets, the fitted relations are not set to  $(X_c, Y_c) = (0, 0)$ , at  $t - t^A = 0$ . A similar method is also realized with the spatial evolution of the granular jet crest, i.e.  $Y_c(X_c)$ , using equation (3). Figure 9 shows an example of the good agreement between the experimental data and the fitted theoretical predictions. Here, the initial parameters of the model are equal to (a) and (b)  $u_i \sim$  $3.0 \text{ m.s}^{-1}$  and  $\alpha \sim 53^{\circ}$  and (c)  $u_i \sim 3.1 \text{ m.s}^{-1}$ , and  $\alpha \sim 48^{\circ}$ , respectively. As two different values of  $u_i$  and  $\alpha$  are obtained by the extracted method, the values and errorbars used in the following correspond to the averaged value and the standard deviation, respectively.

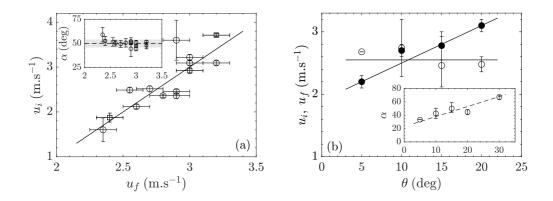


Figure 10. (a) Initial velocity  $u_i$  (inset: initial angle  $\alpha$ ) as a function of the front-velocity  $u_f$  of gas-fluidized granular flows (circles) and dense liquid flows (squares) at the impact with water, with  $\theta = 15^{\circ}$ . The solid line is  $u_i = 2u_f - 3$ , and the dashed line and gray area correspond to  $\alpha = 50 \pm 4^{\circ}$ . (b) Initial velocity  $u_i$  (opened circles) and front-velocity  $u_f$  (closed circles) as a function of the slope angle  $\theta$  of the inclined plane, with  $H_i \sim 22$  cm. The solid lines are  $u_i = 2.55 \text{ m.s}^{-1}$  and  $u_f = 0.06\theta + 1.9$ , respectively. Inset:  $\alpha$  as a function of  $\theta$ , with  $\alpha = 1.5\theta + 23$  (dashed line).

The estimated parameters of the model, i.e. the initial velocity  $u_i$  and the initial 456 angle  $\alpha$ , are plotted as a function of the relevant parameters of the problem, i.e. the flow-457 front velocity  $u_f$  before entering water and the slope angle  $\theta$  of the inclined plane [Fig-458 ure 10]. As expected, the initial velocity  $u_i$  is related to the flow-front velocity  $u_f$  be-459 ing the relevant velocity scale of the problem [Figure 10(a)]. By constrast, the initial an-460 gle  $\alpha$  is not affected by  $u_f$ , which is found equal to  $\alpha = 50 \pm 4^\circ$ , for a given slope an-461 gle of  $\theta = 15^{\circ}$  [dashed line and gray area, in the inset of Figure 10(a)]. Additionally, 462 Figure 10(b) shows the effect of  $\theta$  on the initial parameters  $(u_i, \alpha)$  of the model. Sur-463 prisingly,  $u_i$  remains broadly constant, while  $u_f$  increases for increasing  $\theta$  (opened vs. 464 closed symbols). Here, the variation of  $u_f$  is only attributed to the slope angle  $\theta$ , as the 465 initial height of the column is kept constant. This observation seems to be inconsistent 466 with the conclusions drawn from Figure 10(a), for which  $u_i$  and  $u_f$  increase together. 467 In fact, this could suggest that the driving effect of  $u_f$  on the initial velocity  $u_i$  is here 468 counterbalanced by a dissipative effect of  $\theta$ . In the inset of Figure 10(b), it is shown that 469  $\alpha$  increases with  $\theta$ . This means that grains substain a change of their direction more abrupt 470 at larger  $\theta$  (i.e., from  $\alpha + \theta \sim 40^{\circ}$  to  $\alpha + \theta \sim 100^{\circ}$  with  $\theta = [5 : 30]^{\circ}$ ) which could 471 strongly promote dissipation in the system. 472

#### 473 4.3 Discussion of results

474 Experiments showed that the spatio-temporal evolution of the position of the gran-475 ular jet crest above the water surface can be well described using the theoretical predic-476 tion of a frictionless ballistic motion. This simple model requires only two parameters, 477 i.e. the initial velocity  $u_i$  and the initial angle  $\alpha$  of the ballistic trajectory, which are directly related to the flow-front velocity  $u_f$  and the slope angle  $\theta$  of the inclined plane. In the following, the predictive model is applied to a recent natural event to assess its accuracy for geophysical applications.

Stromboli volcano (Italy) has persistent explosive activity with several hundreds 481 of moderate-intensity events per day, and some notable paroxysmal phases. The 03 July 482 and 28 August 2019 paroxysmal explosions produced eruptive columns of more than 5 483 km height, whose collapse generated pyroclastic density currents travelling rapidly along 181 the northern flank of the volcano and entering the Mediterranean Sea (Giudicepietro et 485 al., 2020). Recorded images of the impact of pyroclastic density currents into water showed 486 the generation of volcaniclastic jets above the sea level, from which the maximum height 487 of a granular jet crest could be approximately estimated as  $Y_c^m \sim 200$  m. In the present 488 case, equation (4) can therefore be reversed to provide an estimate of the impact veloc-489 ity of the pyroclastic flow, knowing that the values of both  $u_f \sim 70 \text{ m.s}^{-1}$  and  $\alpha \sim$ 490  $50^{\circ}$  are also extracted from videos of LBZ webcam of Laboratorio Geofisica Sperimen-491 tale (lgs.geo.unifi.it). The predictive model gives an impact velocity of  $u_i \sim 68 \,\mathrm{m.s^{-1}}$ , 492 with  $Y_c^m = 200$  m and  $\alpha = 50^\circ$ , which is in excellent agreement with the direct measurement of the flow velocity  $u_f \sim 70 \text{ m.s}^{-1}$ . It should be mentioned, however, that recorded images suggest a lower streamwise position  $X_c^m$  of the maximum crest height 495 compared to the vertical position  $Y_c^m$ , unlike the prediction of the model, but the esti-496 mate of  $X_c^m$  is poorly constrained. In any case, this result suggests that the theoretical 497 prediction of a frictionless balistic motion could be successfully used for granular jets gen-498 erated by fine-grained geophysical flows entering water to provide an estimate of their 499 impact velocity, which is unvaluable for the hazard assessment of tsunami generation. 500

#### <sup>501</sup> 5 Flow dynamics of the particle-driven gravity current

In this section, we focus on the propagation of particle-driven gravity currents along 502 the inclined plane and the horizontal bottom underwater, referred to as the near- and 503 far-field regions, respectively (Figure 11). The current is characterized by the height pro-504 file h(x, t), the front position  $x_f$ , and the bulk volume concentration of particles  $\phi$  as 505 a function of the flow rate per unit width q and the volume per unit width v of the gran-506 ular flow, the slope angle  $\theta$  and the water depth  $H_o$ . It should be remembered that the 507 gas-fluidized granular flow enters the water body at  $x_f = x^A$  and  $t = t^A$ , and then 508 the current reaches the slope break at  $x_f = x^B$  and  $t = t^B$ . 509

510

#### 5.1 Near-field region: gravity current over an inclined plane

The first stage of the flow dynamics of particle-driven gravity currents underwater corresponds to the flow propagation along the inclined plane in the near-field region. It can already be anticipated that the water depth  $H_o$  could be disregarded here, being sufficiently far from the inclined plane. This is supported by results (Figure S1, in the Supporting Information) and the present configuration is therefore reduced to three control parameters here, i.e. q, v and  $\theta$ .

Figure 12 shows the temporal evolution of the front position  $x_f - x^A$  varying (a) 517 the flow rate per unit width  $q_{i}$  (b) the volume per unit width  $v_{i}$  and (c) the slope an-518 gle  $\theta$  of the inclined plane. In the first two cases, other control parameters are strictly 519 kept constant while, in the latter case, the flow-front velocity  $u_f$ , and therefore the flow 520 rate q, varies with the slope angle  $\theta$  of the inclined plane. First, it can be clearly observed 521 that both q and v affect the propagation of the front position, while  $\theta$  can be disregarded 522 here. More specifically, q modifies the whole propagation of the current, with in partic-523 ular, a front propagation slower at lower q than at larger q [from light to dark gray, in 524 Figure 12(a)]. By contrast, the influence of v is only clear for  $t \gtrsim 0.5$  s, from which all 525 data deviate from the master curve. In this case, the flow front of currents propagates 526 slower at lower v than at larger v [from light to dark gray, in Figure 12(b)]. This tran-527

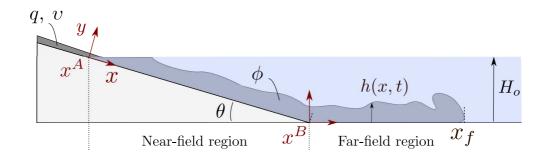


Figure 11. Sketch of the propagation of a particle-driven gravity current along a bottom plane with its macroscopic quantities [height profile h(x, t), front position  $x_f$  and bulk volume concentration of particles  $\phi$ ], and the control parameters (flow rate per unit width q and volume per unit width v of the granular flow, slope angle  $\theta$ , and water depth  $H_o$ ) of the problem. The streamwise coordinates  $x^A$  and  $x^B$  indicate the transition from the 1 m-subaerial ramp to the immersed ramp, and the end of the inclined plane that connects to the horizontal bottom, respectively. The zones containing the immersed inclined plane and the horizontal bottom are referred to as the near- and far-field regions, respectively.

sient behavior can probably be attributed to the end of the granular inflow. Finally, the influence of q and v is hardly observed from the height profile of currents (insets of Figure 12), which supports the idea that the front position evolution is more relevant to quantify the flow dynamics of currents in the near-field region.

These results show that, as long as the entire granular volume has not yet entered 532 the fluid layer, the flow rate per unit width q mostly controls the front dynamics of the 533 gravity current beneath the free-surface. This observation can be related to a homoge-534 neous gravity current produced by a constant flux over an inclined plane, for which the 535 front position scales as  $x_f \propto (g'Q)^{1/3}t$ , with  $g' = 2g(\rho - \rho_f)/(\rho + \rho_f)$  the reduced 536 gravity,  $\rho$  and  $\rho_f$  the densities of the current and of the surrounding fluid, respectively, 537 and Q the flow rate per unit width (Britter & Linden, 1980). It is difficult to consider 538 this scaling in the present configuration, given that the flow rate per unit width Q be-539 neath the free-surface and the bulk density  $\rho$  of currents are unknown. However, we make 540 the somewhat crude assumptions that the flow rate per unit width q at the impact is re-541 lated to the flow rate per unit width Q beneath the free-surface, and that the bulk vol-542 ume concentration of particles  $\phi$ , and therefore the reduced gravity g', do not vary sig-543 nificantly in the range of parameters considered here. The latter issue will be more fully 544 discussed in Sec. 5.2. Under these assumptions, the front position  $x_f - x^A$  is plotted 545 as a function of  $(qq)^{1/3}(t-t^A)$  in Figure 13, for the same set of experiments shown in 546 Figure 12(a). Surprisingly, a very good collapse of the experimental data is obtained for 547 different flow rates per unit width q, which supports the use of this scaling. More specif-548 ically, it is not necessary to consider the reduced gravity g', which means that the par-549 ticle concentration  $\phi$  of currents is fairly constant here. The inset of Figure 13 shows that 550 all experimental data are included in a low interval delimited by two scaling laws, i.e. 551  $x_f - x^A = \lambda (gq)^{1/3} (t - t^A)$  with  $\lambda = 1.3$  and 2 (gray area). At large times, the front 552 position deviates from the linear trend, which is probably caused by the end of the gran-553 ular inflow. The dynamics could tend towards the power-law evolution  $x_f \propto t^{2/3}$  of a 554 finite volume released over an inclined plane (Dai, 2013, 2014), represented by the dashed 555 line in the inset of Figure 13. However, the inclined plane is not long enough in this study 556 to fully support this interpretation. 557

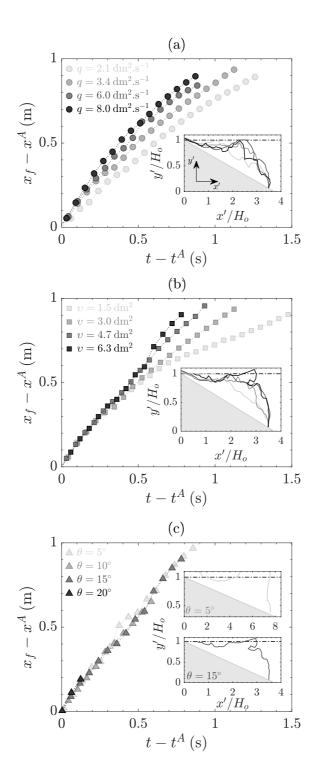


Figure 12. Near-field region: temporal evolution of the front position  $x_f - x^A$  of the particledriven gravity currents by varying (a) the flow rate per unit width q ( $v \sim 3.1 \text{ dm}^2$ ,  $\theta = 15^\circ$ ), (b) the volume per unit width v ( $q \sim 3.3 \text{ dm}^2 \text{.s}^{-1}$ ,  $\theta = 15^\circ$ ), and (c) the slope angle  $\theta$  ( $q = [2.6 : 4.3] \text{ dm}^2 \text{.s}^{-1}$ ,  $v \sim 6.2 \text{ dm}^2$ ). Insets: Height profile of currents along the inclined plane, at  $x_f - x^A \sim 1 \text{ m}$ .

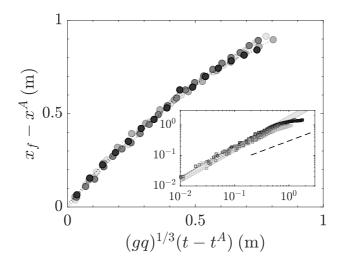


Figure 13. Near-field region: front position  $x_f - x^A$  of the particle-driven gravity currents as a function of  $(gq)^{1/3}(t-t^A)$  [based on Britter and Linden (1980)], for the same set of experiments shown in Figure 12(a) (inset: for the whole set of experiments, in a log-log representation). Gray area:  $x_f - x^A = \lambda (gq)^{1/3}(t-t^A)$  delimited by  $\lambda = 1.3$  and 2; (- - )  $x_f - x^A \propto (t-t^A)^{2/3}$ .

#### 5.2 Far-field region: gravity current over a horizontal bottom

558

The front of the particle-driven gravity current reaches the slope break, at  $x_f$  – 559  $x^B = 0$  and  $t - t^B = 0$ . Then, it propagates on the horizontal bottom until it reaches 560 the end of the channel, referred to as the far-field region. Figure 14 shows  $x_f - x^B$  as 561 a function of  $t-t^B$  for different flow rates per unit width q and volumes per unit width 562 v of the granular flow, while the water depth and the slope angle are set to  $H_o \sim 26.5$ 563 cm and  $\theta = 15^{\circ}$ , respectively. Additionally, the front dynamics of homogeneous gravity currents generated by the impact of dense liquid flows into water is shown, for dif-565 ferent q and v (blue circles, in inset of Figure 14). Note that, at early times of the prop-566 agation, the partial mixing between the dense liquid and water prevents the tracking of 567 the invisible front of the currents. 568

At early times, the front position  $x_f - x^B$  increases faster for larger v (from light 569 to dark gray symbols), due to the flow dynamics of the current in the near-field region. 570 Then, at sufficiently long times, all experimental data collapse on a master curve with 571 a linear trend (dashed line), regardless of q and v. In contrast, at sufficiently low  $v \leq v$ 572  $2.3 \text{ dm}^2$  (cross symbols, in inset of Figure 14), the front position deviates from the lin-573 ear trend and tends towards a slope of 2/3 (solid line). Surprisingly, the constant front-574 velocities of both particle-driven gravity currents (black symbols, in Figure 14) and ho-575 mogeneous gravity currents (blue circles, in inset of Figure 14) are similar for different 576 q and v. More specifically, one obtains  $dx_f/dt \sim 0.35 \text{ m.s}^{-1}$  (dashed lines), which sug-577 gests that both currents have similar densities, and this point will be further discussed 578 in the following. 579

Figure 15(a) shows the temporal evolution of the height h of particle-driven gravity currents at  $x \sim 3.5$  m. The height h increases rapidly at the front and then remains roughly constant over time (dashed lines), despite Kelvin-Helmholtz instabilities at the interface. Moreover, the constant height of the current behind the front, noted  $\langle h \rangle$ , is only dependent on the water depth  $H_o$ , while the flow rate per unit width q, the volume per unit width v, and the slope angle  $\theta$  are varied. In Figure 15(b),  $\langle h \rangle$  increases linearly

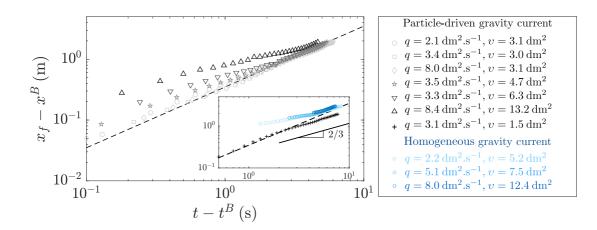


Figure 14. Far-field region: temporal evolution of the front position  $x_f - x^B$  of the particledriven gravity currents (gray symbols) and homogeneous gravity currents (blue circles) as a function of time since arrival at the slope break, for different flow rates q and volumes per unit width v. The water depth and the slope angle are set to  $H_o \sim 26.5$  cm and  $\theta = 15^\circ$ , respectively. The dashed line is  $x_f - x^B = 0.35(t - t^B)$  and the solid line represents a slope of 2/3.

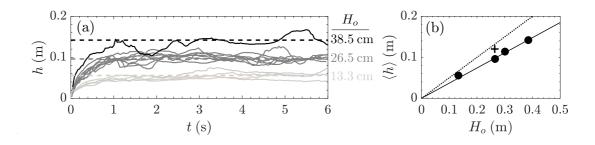


Figure 15. Far-field region: (a) Temporal evolution of the height h of particle-driven gravity currents at  $x \sim 3.5$  m, for different flow rates per unit width q and volumes per unit width vof the granular flow, water depths  $H_o$  and slope angles  $\theta$ . Here, the time t = 0 corresponds to the arrival time of the current front at the given position. The dashed lines indicate the constant height  $\langle h \rangle$  of currents behind the front. (b)  $\langle h \rangle$  as a function of  $H_o$ , for particle-driven gravity currents (full circles) and homogeneous gravity currents (cross). The lines are  $\langle h \rangle = \gamma H_o$ , with the best fit  $\gamma = 0.37$  (solid line) and the theoretical value  $\gamma = 0.5$  (dotted line) for homogeneous gravity currents in the full-depth lock-exchange, respectively.

with  $H_o$ , and in particular, it is found that  $\langle h \rangle \sim 0.37 H_o$  (solid line). Note that  $\langle h \rangle$  is 586 slightly lower for particle-driven gravity currents (full circles) than for homogeneous grav-587 ity currents (cross), which could be attributed to the different mixing efficiencies at the 588 interface. Finally, the dotted line represents the theoretical value  $\langle h \rangle = 0.5 H_o$ , for ho-589 mogeneous gravity currents in the full-depth lock-exchange (Ungarish, 2007; Bonometti 590 & Balachandar, 2010). Experimental data of both particle-driven and homogeneous grav-591 ity currents are lower than the theoretical prediction, which is partly consistent with other 592 experimental studies (Rottman & Simpson, 1983; Lowe et al., 2005). In particular, Lowe 593 et al. (2005) showed that the decrease of the density ratio  $\rho_f/\rho$  between the surround-594 ing fluid and the current could decrease the parameter  $\gamma$  (see their Figure 12), but it can-595 not fully explain the values obtained here. 596

In view of these results, the motion of particle-driven gravity currents in the far-597 field region can be roughly related to that of homogeneous gravity currents in the full-598 depth lock-exchange, far enough from the shoreline where the propagation in the near-599 field region does not affect yet the front dynamics. In the present work, most of currents exhibit a constant height and velocity of the front similar to the slumping regime while, 601 at low v, the front position evolves as  $x_f \propto t^{2/3}$  according to the inertial self-similar 602 regime. In both regimes, the preponderance of inertia over viscous effects can be quan-603 tified by the Reynolds number  $Re = (\rho \langle h \rangle / \mu) (dx_f/dt)$ , where  $\rho \sim \rho_f$  and  $\mu \sim \mu_f$  are 604 the density and the viscosity of currents estimated as those of water given that the bulk 605 particle concentration remains sufficiently low [see Figure 16(e)], and  $\langle h \rangle$  and  $dx_f/dt$  are 606 the height and the front velocity of currents in the far-field region. The Reynolds number is in the range  $Re = [10^4 : 6 \times 10^4]$ , much larger than one. Now, let us consider that the theoretical relation of the constant flow-front velocity, i.e.  $dx_f/dt = 0.5(g''H_o)^{1/2}$ 609 with  $g'' = g(\rho - \rho_f)/\rho_f$ , can be used here (Ungarish, 2007). It should be remembered 610 that this relation is applicable as long as the settling of grains is sufficiently slow along 611 the time and the particle concentration is not too high, i.e.  $\phi \lesssim 0.3$  (Hallworth & Hup-612 pert, 1998). These assumptions seem to be reasonable here because the constant front 613 velocity of currents is broadly maintained until  $x_f - x^B \sim 2$  m corresponding to the 614 tracked propagation, and the bulk particle concentration of the currents is thereafter es-615 timated of the order of  $\mathcal{O}(0.1)$  [Figure 16(e)]. Now, the above-mentioned equation of the 616 front velocity can be reversed to estimate the bulk concentration of particle-driven grav-617 ity currents because the density and the concentration are related by  $\rho = \phi \rho_p + (1 - 1) \phi \rho_p$ 618  $\phi$ ) $\rho_f$ , where  $\rho_p = 2550 \text{ kg.m}^{-3}$  and  $\rho_f = 1000 \text{ kg.m}^{-3}$  are the densities of grains and 619 water, respectively. Recall that the bulk particle concentration of currents corresponds 620 to  $\phi = V_{grains}/V_{current}$ , where  $V_{grains}$  and  $V_{current}$  denote the volume of grains and the 621 total volume of the current, respectively. In this way, one obtains 622

$$\phi = \frac{4\rho_f}{(\rho_p - \rho_f)gH_o} \left(\frac{dx_f}{dt}\right)^2.$$
(5)

No clear trend is obtained between the bulk volume concentration of particles  $\phi$ 623 and the flow rate per unit width q, the volume per unit width v, and the water depth 624  $H_{a}$ , which suggests its independency on these different parameters [Figure 16(a)-(c)]. By 625 contrast, the slope angle  $\theta$  of the inclined plane seems to affect the concentration of cur-626 rents, in the far-field region [Figure 16(d)]. More specifically, a steeper slope angle  $\theta$  of 627 the inclined plane promotes a larger bulk particle concentration of currents. Now, re-628 gardless of the role of  $\theta$ , the bulk concentration of particle-driven gravity currents is roughly 629 constant in the set of experiments, with an order of magnitude of  $\phi \sim \mathcal{O}(0.1)$  [Figure 630 16(e)]. More precisely, it is found that  $\phi \sim 0.13 \pm 0.035$  (dashed line and gray area), 631 but some caution has to be exercised with the obtained value because some crude as-632 sumptions were made through the model. This result suggests, however, that an increase 633 of the front velocity, the front height, or the volume of the granular flow do not increase 634 the bulk particle concentration  $\phi$  of the currents interpreted as a critical value. This crit-635 ical value of  $\phi$  corresponds to a current density of  $\rho \sim 1.20 \pm 0.09 \text{ g.cm}^{-3}$ , similar to 636 that of homogeneous gravity currents in our experiments. This could explain that the 637 front-velocity of both particle-driven and homogeneous gravity currents is similar in the 638 far-field region (see Figure 14). Moreover, the constant value of  $\phi$  supports the idea that 639 the relative gravity can be disregarded using Britter and Linden's scaling in the near-640 field region (see Figure 13). Finally, Freundt (2003) also estimated the density of particle-641 driven gravity currents generated by experimental volcanic ash flows entering water based 642 on the front dynamics of the currents. He reported a bulk density of currents evolving 643 from  $\rho \sim 1.15 - 1.25$  g.cm<sup>-3</sup> proximally to < 1.01 g.cm<sup>-3</sup> near the tank end, corre-644 sponding to bulk particle concentrations from 0.16 - 0.27 proximally to 0.01 distally. 645 The strong decrease of the particle concentration along the current propagation is at-646

tributed to the high settling velocity of the ash material sieved at 4 mm, which is much smaller in our experiments with glass beads of 65  $\mu$ m. In both cases, the bulk particle concentration of currents proximally is estimated to be of the same order of magnitude, i.e.  $\phi \sim 0.16 - 0.27$  for Freundt (2003)'s experiments and  $\phi \sim 0.13 \pm 0.035$  for our experiments, while quantitative variations can be probably attributed to the different grain properties (e.g., size, density, shape).

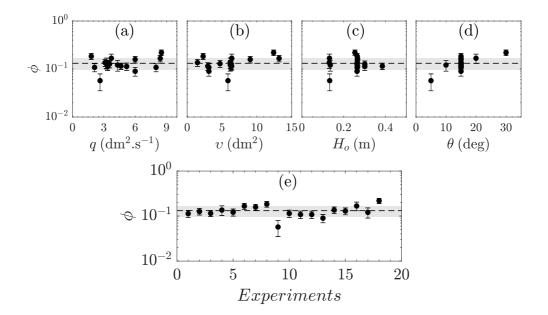


Figure 16. Bulk particle concentration  $\phi$  (in volume) of particle-driven gravity currents estimated by equation (5) in the far-field region, as a function of (a) the flow rate per unit width q, (b) the volume per unit width v, (c) the water depth  $H_o$ , (d) the slope angle  $\theta$  of the inclined plane, and (e) for all experiments of the present study. The dashed line and gray area correspond to the mean value and the standard deviation, i.e.  $\phi \sim 0.13 \pm 0.035$ .

#### 5.3 Discussion of results

In the natural environment, there are few measurements of particle concentration 654 in subaqueous particle-laden flows due to the difficulty of predicting them. For turbid-655 ity currents in which grains are mainly suspended by the turbulent fluid, available field 656 measurements showed that the volume concentration was usually lower than 0.01 (Talling 657 et al., 2013, and references herein). The indirect concentration measurements of subma-658 rine currents caused by the 1929 Grand Banks event, however, give higher values of  $\sim$ 659 0.03 - 0.05 (Stevenson et al., 2018). Moreover, recent works reported that the dilute clouds 660 of such currents can sometimes overlay dense basal layers (Paull et al., 2018; Simmons 661 et al., 2020; Wang et al., 2020). In fact, grains can theoretically be suspended by the fluid turbulence up to a volume concentration of about 0.1, above which grains settle due to 663 the importance of grain-grain interaction (Bagnold, 1962). This threshold is in line with 664 the critical concentration obtained in our experiments, while other experimental stud-665 ies also observed a threshold of the particle concentration in fluid-particle systems. 666

For the purpose of better understanding subaerial dilute pyroclastic density currents, Weit et al. (2018, 2019) performed experiments to study the spatial distribution of solid grains into a gas-particle turbulent system. In a steady vertical flow in which grains were poured gradually, the bulk particle concentration of the dilute gas-particle suspen-

sion increased with the added granular mass before it reached a threshold. Then, the ex-671 cess of grains could not be suspended by the turbulent fluid and clusters were formed 672 and fell forming a basal concentrated granular bed. The coexistence of dilute and dense 673 674 regions controlled by clustering instabilities has also been observed for gas-particle gravitydriven flows, which suggested that the upper dilute part was in its saturated-state (Breard 675 et al., 2016). Although clustering is poorly understood, it is usually attributed to dis-676 sipation of the granular temperature by collisional contacts or to hydrodynamic insta-677 bilities caused by the relative motion between the grains and the surrounding fluid (more 678 details in Fullmer & Hrenya, 2017, and references herein). In both above-mentioned ex-679 periments, the critical volume concentration of the dilute region was a few percent, much 680 lower than in our experiments. Yet, subaerial pyroclastic density currents and subaque-681 ous turbidity currents share common characteristics, such as the turbulent-multiphase 682 nature and the potential formation of dense granular regions (Doronzo & Dellino, 2010). 683 For grains suspended in water by a vertical oscillating grid, the particle concentration 684 also saturated to a critical value depending on the oscillation frequency, but the clus-685 tering instabilities disappeared (Bennett et al., 2013, 2014). 686

In view of these findings, the particle-driven gravity currents in our experiments 687 could be related to physical mechanisms similar to those mentioned above. The impact 688 between the granular flow and water generated a turbulent mixing zone, in which grains 689 were suspended by the turbulent fluid. The bulk volume concentration of particles ex-690 ceeded a critical value, leading to a saturated upper region in which the excess of grains 691 probably fell, forming a basal concentrated region. For all experiments, a thick and vo-692 luminous granular deposit was obtained along the inclined plane, which could be inter-693 preted as the final state of the dense granular flow (see Figure 6). Unfortunately, the flow dynamics of the dense basal region cannot be observed directly because of the visual lim-695 itations of the optical shadowgraph method. Under the influence of gravity, the upper 696 dilute suspension at critical particle concentration collapsed on the inclined plane form-697 ing the particle-driven gravity current. Compared to gas-particle turbulent systems with 698 critical volume concentrations less than  $\sim 0.03 - 0.04$ , the high value of the critical con-699 centration observed here could be attributed to different grain-fluid interaction. It is prob-700 able that the clustering instabilities control the critical concentration of gas-particle flows, 701 in response to different settling rates between individual particles and clusters. This phys-702 ical mechanism is mainly controlled by the grain inertia through the Stokes number, which 703 is usually defined as the ratio between the particle inertial response time and the tur-704 bulent timescale (Warhaft, 2009). For liquid-particle systems, however, further work will 705 be necessary to highlight the physical mechanisms controlling the critical concentration 706 of particles. 707

#### 708 6 Conclusion

Well-controlled laboratory experiments focusing on the entrance of gas-fluidized 709 granular flows into water have been performed, and backed up by theoretical models, to 710 understand better the motion of geophysical granular flows going down a mountainside, 711 then entering the sea, a lake or a river, and finally progagating underwater for what can 712 be a considerable distance. The consideration of fluidized granular flows ensured a more 713 suitable modelling of highly-mobile fine-grained geophysical flows, which are predisposed 714 to reach the coast and generate turbidity currents. First, the presence of a water body 715 promoted the generation of a granular jet over the free-surface, a leading and largest wave, 716 and a turbulent mixing zone from which a particle-driven gravity current was sponta-717 neously formed. Overall, hydrodynamic forces played a dissipative role by slowing and 718 reducing the spreading of the granular mass along the bottom plane. However, a low amount 719 of grains were still transported by the turbulent fluid like a gravity current propagating 720 far away, showing both the dissipative and driving role of the fluid. Then, the granular 721 jet and the particle-driven gravity current were analyzed by tracking the spatio-temporal 722

evolution of the jet crest and the current front, respectively. The trajectory of the gran-723 ular jet was well described by the theoretical prediction of frictionless ballistic motion, 724 for which the initial parameters of the model depended on the flow-front velocity and 725 the slope angle of the inclined plane. The flow dynamics of particle-driven gravity cur-726 rents was described in two distinguished regions beneath the water surface, namely along 727 the inclined plane and the horizontal plane, referred to as the near- and far-field regions, 728 respectively. In the near-field region, the propagation of the current mainly depended 729 on the flow rate per unit width q and the temporal evolution of the front position scaled 730 with time as  $x_f \sim (qq)^{1/3}t$ , with q the gravitational acceleration, in agreement with ear-731 lier findings. Then, the granular inflow was stopped and the finite volume affected the 732 motion of the current from the above-mentioned scaling. In the far-field region, the evo-733 lution of the front position was similar to that of homogeneous gravity currents in the 734 full-depth lock-exchange configuration. The particle-driven gravity current first evolved 735 with a constant-front velocity in the so-called slumping regime, then the front deceler-736 ated and its position scaled as  $x_f \sim t^{2/3}$  in the inertial self-similar regime. During the 737 slumping regime, the constant flow-front velocity was only controlled by the height of 738 the current depending on the water depth. More specifically, the bulk particle concen-739 tration of the current was roughly constant, i.e.  $\phi \sim 0.13 \pm 0.035$  (in volume), in the 740 range of parameters considered. This result is interpreted as a critical concentration reached 741 in turbulent fluid-particle flows, above which the excess of particles cannot be maintained 742 by the turbulent fluid. 743

This study provides the conclusions that highly mobile fine-grained geophysical flows 744 entering water are predisposed to generate granular jets above the free surface and di-745 lute particle-driven gravity currents underwater. Both can be fairly well predicted us-746 ing simple theoretical models capturing most of the physical mechanisms, which are of 747 interest for geophysical purposes. Lastly, the bulk particle concentration of gravity cur-748 rents generated by rapid granular flows entering water reaches a threshold, which needs 749 further work to investigate the influence of grains properties (e.g., density, diameter) and 750 to support this outcome by direct measurements. 751

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