

Nonlinear modes for a discrete mechanical system with rigid contact

Sokly Heng, Stéphane Junca, Mathias Legrand

▶ To cite this version:

Sokly Heng, Stéphane Junca, Mathias Legrand. Nonlinear modes for a discrete mechanical system with rigid contact. 11th World Congress on Computational Mechanics (WCCM XI), Jul 2014, Barcelona, Spain. hal-03186031

HAL Id: hal-03186031

https://hal.science/hal-03186031

Submitted on 30 Mar 2021

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



NONLINEAR MODES FOR A DISCRETE MECHANICAL SYSTEM WITH RIGID CONTACT

Sokly HENG¹, Stéphane JUNCA², and Mathias LEGRAND³

- ¹ Université de Nice Sophia-Antipolis, Laboratoire JAD & Team COFFEE INRIA, Parc Valrose, 06108 Nice, France, i03e05@yahoo.com
- ² Université de Nice Sophia-Antipolis, Laboratoire JAD & Team COFFEE INRIA, Parc Valrose, 06108 Nice, France, Stephane.junca@unice.fr
- ³ McGill University, Department of Mechanical Engineering, 817 Sherbrooke Street West Montreal, Quebec H3A 0C3, Canada, mathias.legrand@mcgill.ca

Key words: nonlinear vibrations, perfectly elastic rigid unilateral contact, non-smooth modal analysis.

Nonlinear normal modes (NNM) [2, 3] are useful tools to study nonlinear vibrations for mechanical systems. We are interested in finding NNM in the context of perfectly elastic unilateral contact. To this end is investigated a discrete model representing a flexible thin rod in contact against a frictionless rigid foundation [4]. This one dimensional model is essentially given by coupled harmonic oscillators with an unilateral rigid contact against a wall. We assume that the contact preserves energy. A natural mathematical formulation is derived and important features for this N dof system are explored: grazing contact, periodic solutions.

Let us give a flavor of our results for the simple 2 dof case: (u_1, v_1, u_2, v_2) belonging to the phase space \mathbb{R}^4 and $v_i = \dot{u}_i$. Families of periodic trajectories are computed and the associated non-smooth invariant manifolds are investigated. The problem is clearly

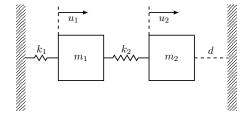
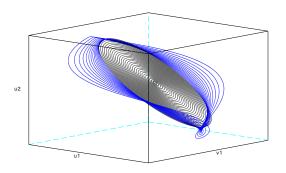


Figure 1: Discrete model with N=2 dof

nonlinear but we use a linear procedure introduced in [5] and generalized for N dof, N > 2. The vibratory energy is continuously increased in order to reach grazing as well as transverse unilateral contact conditions. The corresponding autonomous periodic orbits



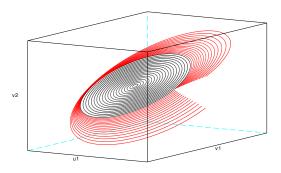


Figure 2: Invariant manifolds supporting autonomous periodic trajectories in variables (left) (u_1, v_1, u_2) and (right) (u_1, v_1, v_2)

are organized on non-smooth invariant manifolds of dimension 2 in the state space of the system of interest.

This applied mathematical subject has many applications and opportunities in Mechanical Engineering, in particular, in aeronautic where unilateral contact occurrences are becoming common due to the use of more flexible and lighter structures implying larger displacements.

REFERENCES

- [1] J. Bastien, F. Bernardin, and C.-H. Lamarque, Non smooth deterministic or stochastic discrete dynamical systems. Applications to models with friction or impact. Wiley, 2013.
- [2] D. Jiang, C. Pierre, and S. Shaw. Large-amplitude non-linear normal mode of piecewise linear systems. *Journal of Sound and Vibration*, Vol. **272**, 869–891, 2004.
- [3] G. Kerschen, M. Peeters, J.C. Golinval, and A.F. Vakakis. Nonlinear normal modes, Part I: A useful framework for the structural dynamics. *Mechanical Systems and Signal Processing*, Vol. **23**, 170–194, 2009.
- [4] D. Laxalde and M. Legrand. Nonlinear modal analysis of mechanical systems with frictionless contact interfaces. *Mechanical Systems and Signal Processing* Vol. **47**(4), 469—478, 2011.
- [5] M. Pascal. Dynamics and stability of a two degree of freedom oscillator with an elastic stop. J. Comput. Nonlinear Dynam. (1), 94-102, 2006.