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Longitudinal impedance and coherent synchrotron radiation models for ThomX storage ring

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Abstract

This article deals with the design of an impedance model (including geometric, resistive wall and coherent synchrotron radiation (CSR) wakefields) for ThomX, a 50 MeV electron storage ring designed to work in pulsed mode. The beam dynamics is very different from usual damped storage rings and is strongly dominated by collective effects. The geometric and resistive wall impedance model is obtained using simulation or analytical modelling of the individual elements and is checked using wire measurements on prototypes. The CSR is simulated in a rectangular vacuum chamber to take into account transient effects and resonances. From these models, two distinct regimes of beam dynamics stand out, driven respectively by the CSR and by the geometric impedance.

Keywords: Beam coupling impedance, Coherent synchrotron radiation, Wire measurement, Wakefield

1. Introduction

ThomX is a compact laser-electron storage rings (LESR) [1], a Compton backscattering X-ray source, which is being built at LAL, Orsay, France [2, 3]. ThomX storage ring design parameters are shown in Table 1. In this machine, electrons are accelerated and injected into a storage ring where they interact

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6 with a laser to produce 1×10^{13} photons per second in the hard X-ray range (50
7 to 90 KeV). As usual in LESR, such as TTX-II [4], NESTOR [5] or ThomX, the
8 beam can suffer from strong degradation by single, multiple Touschek scattering
9 and Compton interaction. To counter this effect, the machine works in pulsed
10 mode: a new bunch is injected every 20 ms while the older one is extracted [6].
11 The global aim of the machine is to maximise the X-ray flux produced by tak-
12 ing care of the spectral and angular flux [7]. The electron storage ring has been
13 designed with this intent which makes the electron beam dynamics very differ-
14 ent from the beam dynamics in usual storage rings dedicated to synchrotron
15 radiation production [8, 6, 9, 10]. The difference results from damping times
16 long compared to the storage time. As the electron dynamics is not damped,
17 it is crucial to manage the collective effects (defined as the interaction of the
18 particles with each other as well as with its environment) as, once the beam is
19 perturbed it will not recover within the storage time. In addition, the beam is
20 injected without longitudinal matching and the lattice has a strong nonlinear
21 dependence on energy of the momentum compaction. Due to the previous con-
22 siderations, the bunch undergoes a transient regime of filamentation at injection
23 until it has fully filled the RF bucket [6]. Besides, the injected electron bunch
24 has a low energy, 50 MeV, a relatively high charge, 1 nC, and a short duration,
25 a few ps, which implies very strong collective effects. In particular, the coherent
26 synchrotron radiation (CSR) is expected to play a strong role during the tran-
27 sient regime as the injected bunch length is short. After the transient regime,
28 the bunch length is much longer and the CSR impact is expected to be much
29 more reduced compared to the geometric and resistive walls (RW) wakefields.

30 During the design phase of an accelerator project, the different beam cou-
31 pling impedance sources should be estimated and summarised in an impedance
32 budget. The impedance budget can then be used to ensure that the wake-
33 fields will not prevent achieving nominal performances, which for ThomX means
34 avoiding any degradation on the X-rays flux or quality. Also, a good knowledge
35 of the machine impedance allows for a better discrimination of possible insta-
36 bility sources. Unfortunately strong discrepancies have been noted between

Table 1: ThomX nominal storage ring design parameters. The range of values given for the emittance, the relative energy spread and the bunch duration correspond to typical beam properties at injection depending on the linac setup.

Parameter	Value	Units
Beam energy E_0	50	MeV
Emittance (rms, normalised) $\epsilon_{x,y}$	7 - 9	mm.mrad
Rel. energy spread at inj. (rms) σ_δ	0.2 - 0.6	%
Bunch duration at inj. (rms) σ_s	6 - 16	ps
Bunch charge Q	1	nC
Circumference L_0	18	m
Number of bunch	1	
Current I	16.7	mA
Trans./long. damping time $\tau_{x,y}/\tau_s$	1/0.5	s
Momentum compaction factor α_1	0.0124	
Tune x/y, Q_x/Q_y	3.17/1.74	
Storage time before ext./inj. T_{store}	20	ms

37 measured data and prediction based on computed impedance budgets [11]. A
38 way to check the impedance estimations, obtained by numeric simulation or by
39 analytic development, is to use bench measurements [12, 13]. As a basis for
40 future complete analysis of the beam dynamics in the presence of collective ef-
41 fects, we present in this paper the simulated and measured impedance models
42 for the geometric, resistive walls and CSR wakefields for ThomX storage ring.
43 We show that the CSR is dominant with respect to impedance during the tran-
44 sient regime when the bunch length is short. After the transient regime, the
45 bunch length is much longer and the CSR impact is reduced compared to the
46 geometric and RW wakefields.

47 The geometric and RW model has been obtained using either numerical
48 simulations or an analytical model for each of the different components. It is
49 presented in section 2. The simulations have then been cross-checked against
50 bench measurements using the coaxial wire method, the measurement results
51 are shown in section 3 and the detailed error estimate is presented in appendix.
52 Finally, the CSR has been simulated, taking into account rectangular chamber
53 and drifts, using the CSRZ code [14] and the results are presented in section 4.

54 **2. ThomX RW and geometric impedance model**

55 When it was possible, the storage ring elements have been simulated using
 56 CST [15] up to 50 GHz corresponding to a bunch length of $\sigma_z = 2$ mm, which is
 57 the bunch length at injection. For higher frequencies, the geometric impedance
 58 contribution is much smaller than the CSR one and thus can be neglected in
 59 the specific case of ThomX. CST wakefield solver can be used to compute the
 60 fields generated by a beam when said beam is going through 3D structures. It
 61 takes into account both of the geometric and the resistive wall wakefields and
 62 has been benchmarked multiple times against theory and other codes [15, 16].
 63 When numerical simulation was not possible, due to thin coating on kicker
 64 magnets, an analytic model was used.

65 The plots of the real part and of the imaginary part of the longitudinal
 66 impedance Z_{\parallel} are shown in Fig. 1. The contribution of each element type is
 67 represented by the different coloured areas. The summary of the impedance
 68 budget is shown in Table 2. The loss factor k_{\parallel} for each individual element is
 69 computed for a $\sigma = 2$ mm bunch and the relative contribution of each type to
 70 the total loss factor $k_{\parallel,T} = 6.73$ V pC⁻¹ is shown. We will now go through the
 contribution of each element.

Table 2: Summary of all the elements composing ThomX storage ring and of their relative contribution to the impedance budget. Loss factor k_{\parallel} computed for a Gaussian longitudinal distribution of $\sigma_z = 2$ mm.

Element	Number	k_{\parallel} (V/pC)	% of $k_{\parallel,T}$
Bellows	18	1.54×10^{-2}	4.1 %
BPMs	12	3.59×10^{-2}	6.3 %
IP clearing electrodes	2	1.20×10^{-2}	0.4 %
IP chamber	1	1.23×10^{-1}	1.8 %
Pumping ports	15	4.13×10^{-2}	9.2 %
Kickers	2	4.1×10^{-1}	12.2 %
Septum	1	1.14	17.0 %
FBT	1	1.52×10^{-1}	2.3 %
RF Cavity + Tapers	1	3.14	46.7 %
Total		$k_{\parallel,T} = 6.73$	100 %

71

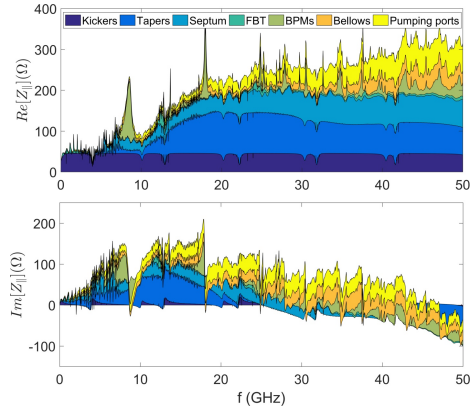


Figure 1: Real and imaginary part of the longitudinal impedance Z_{\parallel} for ThomX storage ring (without the RF cavity contribution). Each component contribution to the total impedance is represented by a coloured area. The full sum corresponds to the upper limit of the yellow (pumping ports) area.

72 *2.1. Bellows, BPMs and pumping ports*

73 ThomX beam pipe has an octagonal cross section and most of the elements
 74 have the same shape to avoid impedance increase due to tapered sections. The
 75 bellows have integrated RF fingers with the same octagonal cross section in
 76 order to shield the beam from the irregular surface of the bellows, see Fig. 2.
 77 The 18 bellows of the storage ring amount to 4.1 % of the total loss factor $k_{\parallel,T}$.

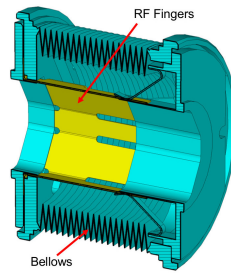


Figure 2: CST model of the bellows with RF fingers.

78

79 There are different types of beam position monitors (BPMs) in ThomX stor-
 80 age ring. Their design is based on SOLEIL BPMs [17, 18], which is a classic
 81 button BPM bloc with four electrodes. In ThomX, some BPMs have double

82 BPM blocs with six or eight electrodes. The additional buttons are used as
83 ion clearing electrodes to avoid ion trapping by the electron beam [8, 19]. In a
84 button BPM, the electromagnetic fields excited by the beam can be trapped in
85 the structure. There are two main trapped modes, at 8.6 GHz and at 18.0 GHz,
86 which correspond to the modes created between the BPM button and the BPM
87 bloc housing the button. The fields can also propagate and resonate in the
88 dielectric material composing the vacuum insulator and act back on the beam.
89 These resonant modes, located around 14 GHz, have a lower amplitude com-
90 pared to the main ones. The loss factor value in Table 2 for the BPMs corre-
91 sponds to a double BPM bloc with six buttons.

92 *2.2. Interaction point*

93 In addition to BPM, there are also two stand-alone clearing electrodes lo-
94 cated at the interaction point (IP) and at the point symmetric to the IP. Each
95 of them is composed of two BPM buttons. The vacuum chamber at the IP is a
96 special design, the interaction laser needs to be able to enter and exit the cham-
97 ber in order to produce X-rays via Compton interaction with the electron beam.
98 Two windows have then been cut in the curved sections of the IP chamber which
99 contributes to the machine impedance. As it is not possible to simulate curved
100 section in CST, the same windows have been adapted to a straight line geometry
101 similar to the one of the IP chamber to estimate the wakefield generated.

102 *2.3. Pumping ports*

103 ThomX pumping ports consist of a circular opening in the vertical plane
104 behind a grid which continues ThomX typical cross section. There are several
105 types of pumping ports in the storage ring, some of them in bent regions. The
106 bent pumping port impedance is assumed to be the same as the ones in straight
107 sections. As for the bellows, the pumping port impedance is of the broad band
108 type, with a very low amplitude at the lower frequencies but the amplitude
109 slowly increases at higher frequencies. Around 50 GHz, the bellows, the pump-
110 ing ports and the BPMs account for more than 50 % of the total broad band
111 impedance.

112 2.4. Kickers

113 Kickers are often complex pieces to handle with respect to impedance estima-
114 tion, as shown by the high number of publications focusing on kicker impedance
115 evaluation. ThomX kickers are composed of an elliptic ceramic chamber which
116 is coated by a thin (≈ 100 nm) layer of titanium which is partially oxidised on
117 surface due to the air contact during the manufacturing process. The chamber
118 has to allow the magnetic field, produced by the fast kicker magnets, to go
119 inside the chamber for the kicker to be effective which is why the ceramic is
120 used as the body of the chamber. In the same time, the chamber is coated by
121 a conductor in order to allow the image current to flow along the coating and
122 limit heating and wakefield emission.

123 But having a ceramic chamber also mean than the beam electromagnetic
124 field can reach outside of the chamber and can interact with outside materials.
125 In particular, the magnet system is composed of rectangular ferrite yokes. The
126 interaction of the beam electromagnetic field with the ferrite is a concern as it is
127 known to produce high impedance for past kickers [20, 21, 22]. But this type of
128 element, with thin coatings and ferrite, is very complex to simulate on software
129 like CST because the huge number of mesh cells needed to take into account
130 the different scales. Even with adaptive mesh cells, the 3D model would still
131 need more than 10^9 mesh cells in order to correctly model both the thin coating
132 and the rest of the structure. An eventual simulation this way would take much
133 more memory and computation time than what is affordable.

134 So to evaluate the kicker impedance, an analytical model close to the kicker
135 geometry and allowing to tackle the issues raised was used: the multi-layered
136 cylindrical chamber model [23] computed using IW2D [24]. This model allows to
137 derive the impedance of a 2D (i.e. infinite in the longitudinal direction) axisym-
138 metric structure composed of different circular layers. This model is very well
139 adapted to the ceramic chamber, as the ceramic and the coatings have uniform
140 width (supposedly for the titanium and its oxidised part) corresponding well to
141 a layered model. For the magnet system part, which is further from the beam,
142 its geometry is neither axisymmetric nor uniform but it will be approximated

143 as so. The elliptic geometry of ThomX kickers has been taken into account
 144 using Yokoya factors to correct the results given for a circular geometry [25].
 145 Compared to simulations, the advantage of using an analytical model is that it
 146 is very easy to get the impedance up to very high frequency, up to 1 THz for
 147 this study.

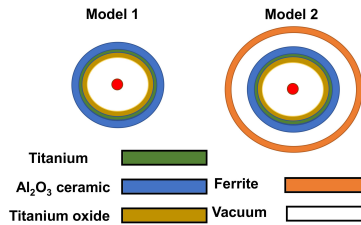


Figure 3: Models used in IW2D based on ThomX kicker geometry. The parameter used for the materials are shown in Table 3.

Table 3: Parameter used in IW2D for ThomX kicker materials: ρ_{DC} is the DC resistivity of the layer, τ is the resistivity relaxation time, ϵ_b is the real part of the dielectric constant, χ_m is the magnetic susceptibility, f_m is the permeability relaxation frequency and h is the layer thickness.

Material	ρ_{DC} (Ω m)	τ (s)	ϵ_b	χ_m	f_m (Hz)	h (m)
Titanium oxide TiO_2	10^{13} (10^{11} to 10^{15})	0	1	0	∞	10×10^{-9}
Titanium Ti	5.5×10^{-7}	$5.7 \times 10^{-16} \approx 0$	1	0	∞	90×10^{-9}
Aluminium oxide Al_2O_3	10^{12}	0	9.8	0	∞	5×10^{-3}
Ferrite	10^6	0	1	2000	∞	15×10^{-9}

148 Using IW2D, several layered models were used to design a more realistic
 149 kicker model, see Fig. 3. The first model is composed of layers of vacuum,
 150 titanium oxide, titanium and then of alumina ceramic. The second one has
 151 two additional layers, a vacuum layer followed by a ferrite layer. The model
 152 1 is used to cover the two kicker extremities where there is no ferrite and the
 153 model 2 is used for the central part which houses the magnet system. The

154 longitudinal impedance produced by this realistic kicker model is shown in Fig.
 155 4. The impedance spectrum is composed of an important broad band component
 156 with oscillations with a period of 10 GHz. The large value of the broad band
 157 maximum is due to the bad conductivity of both the ceramic and the titanium
 158 oxide. The oscillations are linked to the high dielectric constant, $\epsilon_b = 9.8$, of
 159 the ceramic. The high magnetic susceptibility of the ferrite, $\chi_m \approx 2000$, leads
 160 to the high frequency impedance oscillations seen on the spectrum and on the
 high amplitude resonance at 58 GHz.

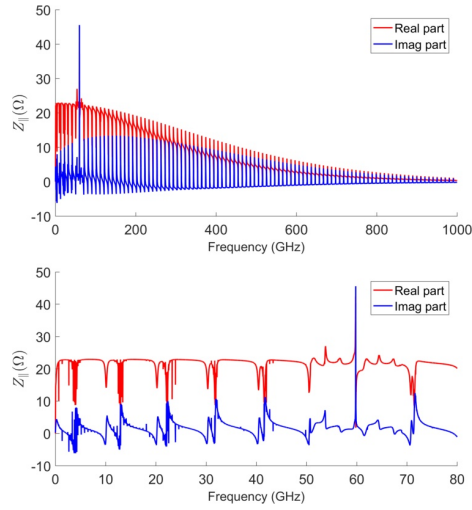


Figure 4: Longitudinal impedance produced by the kicker versus frequency. Real part is in red and imaginary part in blue. The top plot is the full spectrum from DC to 1 THz and the bottom one is a zoom ranging from DC to 80 GHz. This results corresponds to 126 mm of model 1 and 204 mm of model 2.

161

162 Several approximations were made to obtain the kicker impedance. The
 163 actual geometry of the magnet system is neglected, some physical parameters of
 164 the materials (i.g. χ_m) are known to be frequency dependent but not considered
 165 as such in this model and the value of most of the parameters is subject to large
 166 uncertainties. The value of χ_m for the ferrite layer which has been used is the
 167 DC value, which should lead to overestimate the impedance (χ_m is supposed
 168 to decrease with f). In order to estimate the error due to large parameter
 169 uncertainties, the models 1 and 2 composing the final kicker model have been

170 computed for different parameters within their probable range. Overall, the
171 error ΔZ due to the lack of knowledge about material parameter should be
172 $\Delta Z \approx \pm 5 \Omega$. This corresponds to a 20 % error on the estimation of the loss
173 factor k_{\parallel} for the kickers.

174 *2.5. Septum, transverse feedback (FBT) and RF cavity*

175 The septum chamber is designed to allow the beam injection and extraction
176 while shielding the stored beam from the septum DC magnet. The main body
177 of the chamber is shielded from the constant magnetic field produced by the
178 septum magnet with a thin layer of mu-metal. Mu-metal is metal with an
179 high relative magnetic permeability μ_r which prevent the DC component of the
180 magnetic field to go through it. Thanks to this mu-metal layer, the stored beam
181 is not affected by the septum magnet magnetic field.

182 The septum chamber is a complex piece with respect to impedance esti-
183 mation because it presents many different features impacting the impedance.
184 Firstly, the septum chamber begins with a taper transition from the ThomX
185 cross section to a rectangular cross section. Then, this rectangular cross section
186 is reduced in the horizontal plane to allow for the injection/extraction windows,
187 this transition corresponds to a step in and then to a step out in the horizontal
188 plane. Finally, the central part shows both a pumping grid on one side and
189 the mu-metal shield all around this central region. The mu-metal magnetic
190 permeability is highly frequency dependant, $\mu_r = 520 \times 10^3$ at DC and $\mu_r =$
191 80×10^3 at 60 Hz. It is possible to use frequency dependant materials in CST,
192 but in practice the computational cost explodes when trying to use it to model
193 thin layers for a high frequency range. So, as it is known that the magnetic
194 permeability of the mu-metal decreases very quickly with frequency [26], the
195 relative magnetic permeability of the mu-metal has been set to 1 in the wake-
196 field simulations. The impedance found for the septum is broad band and very
197 characteristic of a step transition with a frequency cut-off around 5.5 GHz.

198 The transverse feedback (FBT) aims to damp the injection jitter and to
199 suppress transverse instabilities. It uses a stripline kicker composed of four

200 electrodes, which reproduces ThomX cross section, connected to electrical feed-
 201 through at both ends. The electrodes are supported by ceramic (marcor) holders
 202 and are connected to the feed-through via copper foils. In order to minimise the
 203 impedance, 0.5 mm capacitive gaps have been added on each side of the elec-
 204 trodes. This capacitive gap, combined with the inductance of the feedthroughs
 205 and copper foils, and the $50\ \Omega$ electric impedance of the electrodes, creates a low
 206 pass filter [27]. The cut-off frequency of this filter depends on the height of the
 207 capacitive section h . CST simulations have been done for several values of the
 208 height of the capacitive section h , varying h from 0 mm to 15 mm, in order to
 209 find the value that would minimise the impedance. The design with $h = 10$ mm
 210 is chosen as it allows to reduce the loss factor from $k_{\parallel,h=0mm} = 0.21\ \text{V pC}^{-1}$ to
 211 $k_{\parallel,h=10mm} = 0.15\ \text{V pC}^{-1}$ for a $\sigma_z = 2$ mm bunch length.

212 The RF cavity used in ThomX is a 500 MHz single cell copper cavity of the
 213 ELETTRA type [28], tapers are used to adjust its cross section to ThomX vac-
 214 uum chamber one. As time domain wakefield simulations are not well adapted
 215 to compute the impedance of an RF cavity, the cavity has been simulated in
 216 the frequency domain. The longitudinal and transverse modes of the cavity
 217 have been simulated with eigenmode solvers and measured using a vector net-
 218 work analyser (VNA) in transmission mode [29]. The impedance of the RF
 219 cavity can then be built using the RLC resonator model [30]. The RF cavity
 220 contribution to the total impedance is not shown in Fig. 1 as its impedance
 221 only corresponds to very high amplitude, narrow resonances. The tapers have
 222 been simulated in CST and their impedance is broad band with a frequency
 223 cut-off around 10 GHz. The value indicated in Table 2 corresponds to the loss
 224 factor of both the RF cavity and its tapers simulated together, $k_{\parallel,RF+tapers} =$
 225 $3.14\ \text{V pC}^{-1}$, which is superior to the sum of the loss factor of its two components
 226 taken individually $k_{\parallel,RF} + k_{\parallel,tapers} \approx 2.97\ \text{V pC}^{-1}$.

227 3. Impedance measurements using the coaxial wire method

228 Impedance evaluation is not always a straightforward affair, using analytical
 229 models provide an exact solution but the model seldom corresponds to the real

230 object one wants to evaluate. Nowadays, electromagnetic simulations are very
231 powerful and perfected tools but this often come with an increased difficulty
232 to set the numerous parameters of these “black boxes” like solvers. Because
233 of this difficulty to parameter, it is possible to get a simulation result far from
234 reality if the simulation is incorrectly set. RF measurements have the advantage
235 to allow the component direct measurement, contrary to analytical models and
236 simulations where a model has to be set. But the measurement is difficult, not
237 always easy to interpret and is not possible for every elements. Finally, beam
238 measurements of the impedance allow the accuracy of an existing impedance
239 model to be checked. But, in most cases, it comes too late in the process to
240 allow for the element modification if too big an impedance is detected.

241 For these reasons, when building an impedance model for a machine, com-
242 mon wisdom says that, ideally, one should use at least two different methods for
243 each element one wants to evaluate. In order to constitute ThomX impedance
244 model, the main method which was chosen is time domain simulation using
245 CST. Then, when possible, RF measurements were done in order to cross check
246 the simulation results. This section describes the impedance measurements done
247 using the coaxial wire method. It first focuses on the setup used and on the
248 measurement limitations, the measurement of the bellows with and without RF
249 fingers, see Fig. 2, is then presented and compared with simulations.

250 *3.1. Measurement setup*

251 Impedance measurements using the classical coaxial wire method use the
252 fact that electromagnetic field produced by an ultrarelativistic beam is close to
253 the one produced by a coaxial TEM transmission line [31]. It is then possible
254 to measure the impedance using a Vector Network Analyser (VNA) matched to
255 the TEM transmission line created by a Device Under Test (DUT) and a wire
256 inserted inside the DUT. The VNA measures the transmission parameter S_{21} ,
257 which corresponds to the ratio of the output power wave to the input power
258 wave. The measurement of the DUT is carried out with respect to an ideal
259 reference line in order to remove any effect coming from the setup. The principle

260 of the measurement is described in more detail in [12, 13]. The log-formula has
 261 been chosen for the impedance evaluation from the RF measurements [32]:

$$Z = 2Z_L \ln \left(\frac{S_{21_{DUT}}}{S_{21_{REF}}} \right) \quad (1)$$

262 where Z_L is the line impedance of the DUT. The log-formula has the advantage
 263 of being able to correctly resolve lumped impedance parts while keeping an
 264 acceptable error for distributed impedance parts [12].

265 The measurement setup is presented in Fig. 5. A half shell flange is used
 266 to support the measurement setup, an RF bulkhead going through the half
 267 shell links the cable going to the VNA (Vector Network Analyser) to the RF
 268 connector. A coaxial cable brazed on the RF connector and stripped on the
 269 end tip is used as an antenna. A resistor is brazed on the stripped tip of this
 270 coaxial cable in order to match the two coaxial lines. Then the CuBe (Copper
 271 Beryllium) wire is brazed on the other end of the resistor. A metallic plate is
 272 used to separate the RF connector part from the measurement part. If there
 273 is no separation then the TEM modes created between the external conductor
 274 of the coaxial conductor can propagate and disrupt the measurement. In order
 275 to damp reflections on this plate, RF absorbing foam has been glued to it. In
 276 the aim of improving repeatability, the plate and the foam have been glued to a
 277 metallic support which can be removed to screw the RF connector and tauten
 278 the wire.

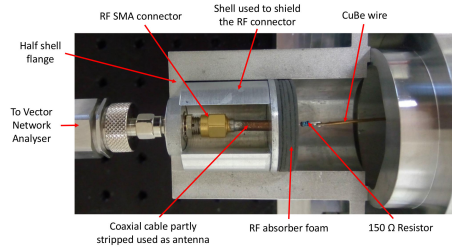


Figure 5: Measurement setup for longitudinal impedance using the coaxial wire method

279 A TEM coaxial line is created by the wire going trough the vacuum chamber.
 280 In order for the electromagnetic wave from the VNA to propagate without

281 reflections to the system along the wire, the two lines $Z_0 = 50 \Omega$ and Z_L must
282 be adapted by a matching resistor [13].

283 The line impedance Z_L of a ThomX beam pipe has been simulated using
284 CSTTM MW for different wire diameters and compared with the analytic for-
285 mula for the case of round chambers. In this case, it is necessary to determine an
286 equivalent diameter D_{eq} for ThomX cross section which is not cylindrical. The
287 value of this equivalent diameter $D_{eq} = 30.9$ mm is chosen so that the analytical
288 results match the simulations. The material of the wire is chosen to be copper
289 beryllium (CuBe) in order to be able to tauten the wire without stretching it.
290 The half shell flanges have been designed to have a diameter of $D_{eq} = 30.9$ mm
291 to have the same line impedance Z_L as the vacuum pipe one.

292 In order to be able to measure high impedance components, it is important
293 to have the highest line impedance Z_L possible [13]. Ideally the line impedance
294 should be much higher than the DUT impedance. However, there is a com-
295 promise to be made between the frequency precision and attenuation of the
296 signal with respect to the wire diameter which will be explain briefly in the
297 measurements section [33, 34]. Firstly, we started to do measurements with a
298 wire diameter of $d = 1$ mm which gives a line impedance of $Z_L = 205.7 \pm 6.0$
299 Ω . In this case, the matching is done using a resistor of $R_s = Z_L - Z_0 \approx 150 \Omega$.
300 To compare the impact of wire thickness, the measurements were also done with
301 thinner wires of 0.1 mm and of 0.025 mm. Using thinner wires increase the line
302 impedance Z_L and allow for a better precision when measuring high impedance
303 components. These additional measurements will also help to determine the
304 influence of the wire diameter on the signal attenuation. The line impedance
305 corresponding to the 0.1 mm and 0.025 mm wires were calculated with respect
306 to analytic formula and they are equal to 343.76 Ω and 426.88 Ω respectively
307 [13].

308 *3.2. Measurement limitations*

309 The coaxial wire measurement of the impedance has many limitations which
310 can prevent a good measurement. Some limitations come from the setup and

311 other come from the method used to do the measurement.

312 A first limitation is fixed by the calibration done on the VNA before doing the
313 measurement. Using a calibration kit valid down to -40 dB it is not possible to
314 accurately measure below -40 dB. This means that, using Eq. (1), the maximum
315 impedance value which can be precisely measured using this setup is $Z_{max} =$
316 $-2Z_L \ln(-40dB) \approx 1900 \Omega$ with 1 mm wire. This limit is further reduced
317 because the measurement of the reference has to be taken into account.

318 A second limitation would be due to the repeatability of the measurements.
319 When doing coaxial wire measurements many aspects change from measurement
320 to measurement and may increase the uncertainty of the measurement: the
321 brazing and the tautening of the wire, the positioning of the RF absorbing
322 foam, the screwing of the half shell flanges on the DUT, ... In order to decrease
323 the statistical errors, several measurements have been taken and the impedance
324 is computed from the averaged value. Systematic errors include the effect of
325 the wire thickness and the limitations of the log-formula. A support to fix the
326 positioning of the RF foam is used and the measurement is done in a clean room
327 with fixed temperature and pressure. A precise error quantification has been
328 done to estimate this limitation, see Appendix A.

329 Lastly the coaxial wire method has been shown to be inaccurate below the
330 beam pipe cut-off frequency [35]. The stretched wire perturb the behaviour of
331 the electromagnetic field by allowing TEM waves with zero cut-off frequencies
332 whereas, in realistic situation with a beam, these modes would not be able to
333 propagate. The cut-off frequency (TE_{11}) for a round pipe is given by $f_c = \frac{j_{1,1}c}{2\pi R}$
334 with $j_{1,1}$ the first root of the Bessel function J_1 , c the speed of light and R the
335 radius of the beam pipe. For ThomX cross section, if the value $R_{eq} = \frac{D_{eq}}{2}$ is
336 used then, $f_c = 5.7$ GHz. The method is known to give good results above 30 %
337 of the cut-off [35], for ThomX this would mean above $1.3f_c \approx 7.4$ GHz. Below
338 7.4 GHz, the amplitude and frequency shift introduced by the wire can be seen
339 as an additional error on the measurement.

340 As the limitations are severe, in our case the coaxial wire method is only
341 used to validate the simulation tools and methods.

342 *3.3. Measurement of the reference section*

343 In order to measure impedance by the wire method, it is necessary to measure
344 an “ideal reference line” corresponding to $S_{21_{REF}}$ in Eq. (1). This measurement
345 is used as the reference to take into account the defaults of the setup and the
346 particular geometry of the beam pipe cross section. The reference section used
347 here is a plain vacuum pipe using ThomX cross section. Ideally, the reference
348 section and the DUT should have the same length. But in our case, there are
349 many objects of different length to measure and it does not seem justified to
350 make new reference sections for each object to measure.

351 Two length of reference section were measured, 100 mm and 500 mm. The
352 two S_{21} measurements give very similar results but the longer section shows
353 small oscillations on top of the general behaviour shown by both sections. As
354 the difference between two sections of very different length is small enough, it
355 is legitimate to use one of these two measurement as reference for a DUT no
356 matter its length. For smaller DUT, which size is around 100 mm, the smaller
357 one is used and for bigger DUT the other is used. The comparison of the 100
mm and 500 mm can be seen in Fig.6.

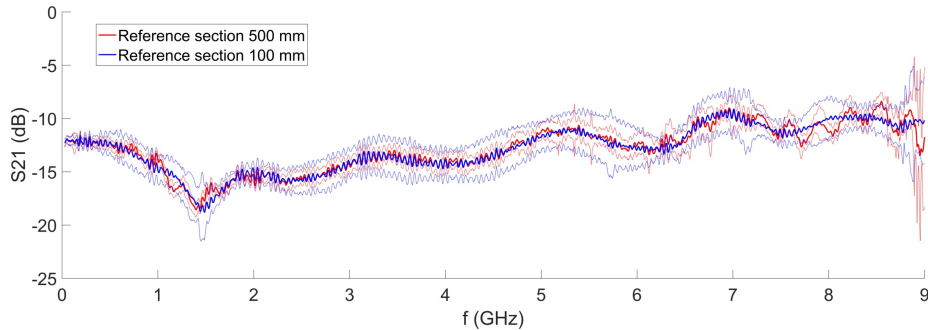


Figure 6: S_{21} measurement of ThomX reference section, the 100 mm section is plotted in blue and the 500 mm section in red. The mean value for the set of 5 measurements is plotted in plain line and the 95 % CI is shown in dotted lines.

358

359 *3.4. Measurements*

360 The RF measurement of the bellows has been done with and without the
361 RF fingers to test the effectiveness of the RF fingers in suppressing the trapped

362 modes. The transmission parameter S_{21} for these measurements is shown in
 363 Fig. 7. The measurement of bellows with RF fingers is very close to the ref-
 364 erence measurement which indicates that the shielding works as intended. The
 365 measurement without RF fingers shows strong resonance peaks which clearly
 stand out of the reference measurement.

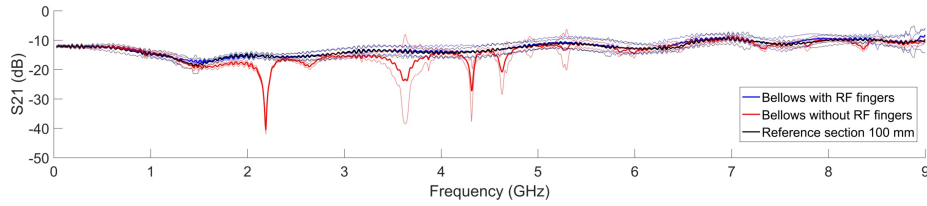


Figure 7: S_{21} measurement of ThomX bellows, with RF fingers in blue, without RF fingers in red and the 100 mm reference section in black. The mean value for the set of 5 measurements is plotted in plain line and the 95 % CI is shown in dotted lines.

366

367 Figure 8 shows the real part of the impedance obtained using the log formula,
 368 Eq. (1). It is compared with CST simulations of the impedance for both cases,
 369 in dotted lines with RF fingers for the top plot and without RF fingers for
 370 the bottom plot for the 1 mm diameter wire. For the bellows with RF fingers,
 371 the measurement agrees very well with the simulation which gives a very low
 372 impedance.

373 For the bellows without RF fingers, firstly the measurements were done with
 374 1 mm wire. The simulation agrees relatively well with the measurement as the
 375 four peaks found in simulation also appears in the measurement. The two strong
 376 peaks at 2.1 GHz and 3.5 GHz in the simulation are shifted respectively at 2.2
 377 GHz and 3.6 GHz in the measurement and have a lower amplitude value by
 378 a factor 8 to 10. The two smaller peaks at 4.4 GHz and 4.8 GHz are shifted
 379 respectively at 4.3 GHz and 4.6 GHz but have comparable amplitude. The
 380 differences in amplitude and the shifts in frequency can be explained by the
 381 variable geometry of a real bellows compared to the fixed bellows modelled in
 382 CST simulation, the loss in the resistors and the attenuation due to the thickness
 383 of the wire [36]. For example, the resistors used for line impedance matching
 384 can bring additional noise for high frequency applications. The current density

385 is related to frequency for resistor which creates additional noise and power
386 loss [34]. For comparison, the same measurements were done with the thinner
387 wire of 0.1 mm. The reproducibility error with 0.1 mm wire on the bellow and
388 reference section measurements were reduced nearly half compared to the 1 mm
389 wire measurements and even more in the case of the high resonance peaks as
390 it can be seen in Figure 9. The most likely reason is the change in the wire
391 tension coming from the difficulty in stretching the 1 mm wire. With the 0.1
392 mm wire, the frequency shift with respect to the impedance calculations was
393 reduced significantly as it can be seen in Figure 10 however the attenuation gets
394 bigger with the thinner wire [36]. Also the strong field distortion due to the
395 insertion of the wire creates frequency shifts in impedance spectrum decreasing
396 when the wire diameter gets smaller [33, 34]. In the measurement, the peaks
397 are broader than in the simulations as all the components of the real bellows do
398 not resonate at the same frequency due to small variations in the bellows period
399 which do not exist in the perfect model used for simulations. As a good trade
400 off between the frequency precision and the attenuation, it was decided to use
401 0.1 mm wire for future measurements. It is important to note the effectiveness
402 of the RF fingers in suppressing the high impedance measured without the RF
403 fingers.

404 In addition to the bellows, measurements have also been performed on sev-
405 eral prototypes of BPMs, of pumping ports and of the RF cavity and its tapers
406 [8, 29]. Despite the important uncertainty and the limited frequency range of
407 the measurements, they have allowed to check that the elements were correctly
408 represented in CST, and that the element design and manufacture is suited to
409 produce low impedance elements.

410 **4. Coherent synchrotron radiation impedance model using CSRZ**

411 In this section, a coherent synchrotron radiation (CSR) impedance model for
412 ThomX storage ring is developed following the same idea as for the geometric
413 and resistive wall impedance. The CSR community usually uses a different
414 convention for the impedance and the wake functions compared to the one use

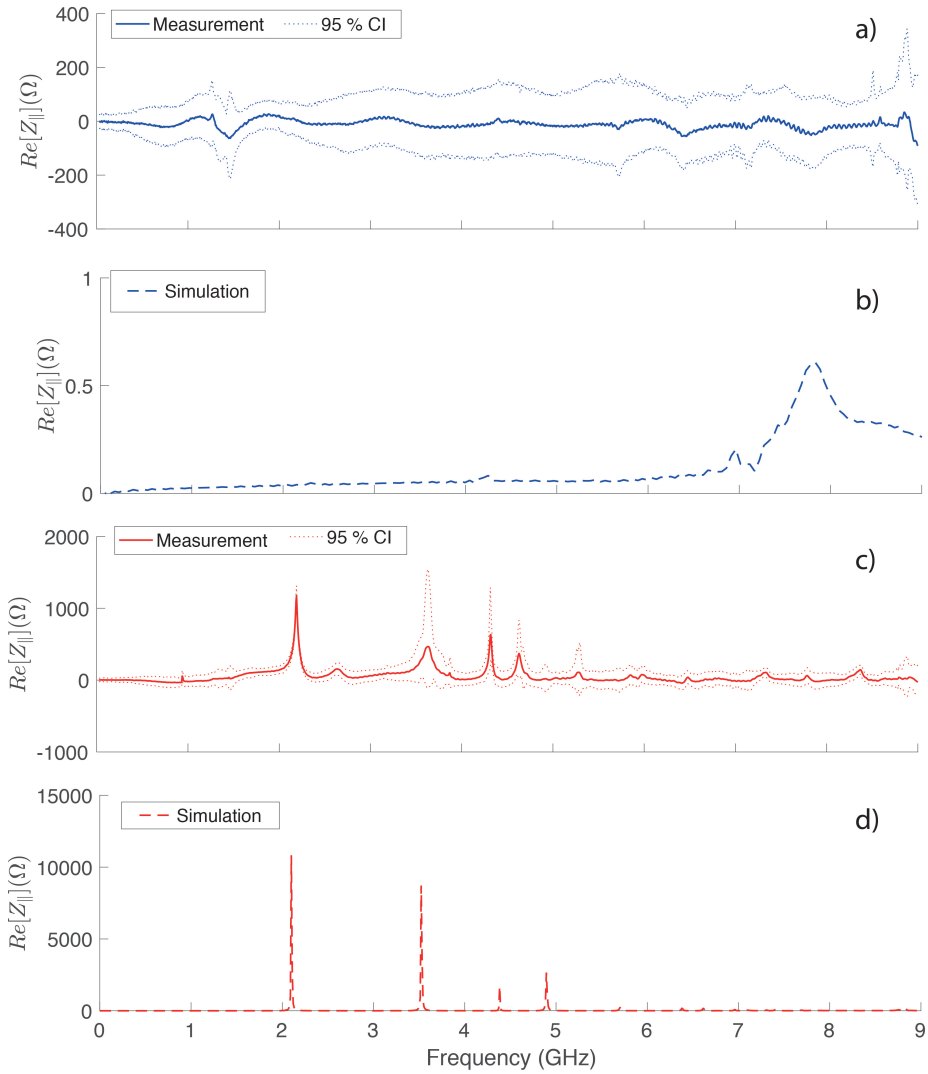


Figure 8: Real part of the impedance of ThomX bellows : a) Measurement with RF fingers, b) Simulations with RF fingers, c) Measurements without RF fingers, d) Simulations with RF fingers. The mean value for the set of 5 measurements is plotted in plain line and the 95 % CI is shown in thin dotted lines for a) and c).

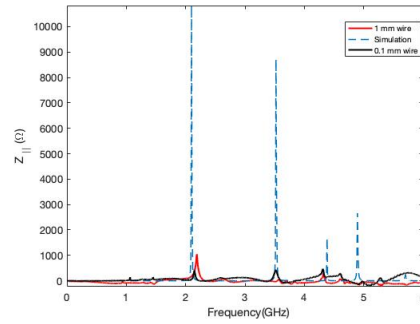


Figure 9: The real part of the simulated and measured impedances for 1 mm and 0.1 mm wire

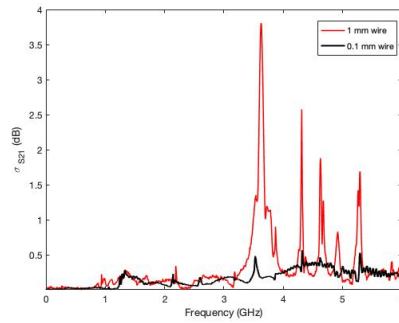


Figure 10: The standard deviation on the below measurements for 1 mm and 0.1 mm wire

415 here and used in the literature for the geometric and resistive wall wakefields
416 [15, 30, 37]. In the CSR convention, a positive wake function corresponds to an
417 energy loss and the impedance spectrum is the complex conjugate of the one
418 use here. This section keeps using the same convention used in this paper but
419 plots $-Im[Z]$ in the impedance spectrum in order to keep the usual display of
420 the impedance for the CSR.

421 The steady-state parallel plate model is often used to estimate the CSR
422 impedance [38, 39, 40]. In this model, an electron (point like charge) moves
423 in between two perfectly conducting plates separated by a distance h on the
424 horizontal direction. As it takes into account the shielding created by the beam
425 pipe walls, this model adds a threshold f_{sh} below which the CSR impedance is
426 very strongly reduced compared to the free space model [38, 39].

427 These simple models correspond to a steady-state situation where the elec-
428 tron bunch trajectory is perfectly circular. In most real machines, the dipoles
429 are interleaved with drift spaces which introduce transient effects at dipole en-
430 trance and exit. The CSR fields emitted in the dipoles are guided by the vacuum
431 chamber, acting as a waveguide, and propagate along the beam in the straight
432 sections, see (c) of Fig. 11. This effect, also called “drift CSR”, is more im-
433 portant if the machine contains short dipole magnets. Some more complicated
434 analytical models take into account transient effects [41, 42].

435 In addition to transient effects, the CSR fields can also be reflected, some-
436 times multiple times, on the transverse beam pipe walls, as in (b) of Fig. 11.
437 The reflections on the outer walls lead to head-tail effects while the reflections
438 on the inner walls lead to tail-head effects. When the magnet is long compared
439 to the vacuum chamber width a , the CSR fields can resonate within the vacuum
440 chamber and excite the eigenmodes of the vacuum chamber [14]. Furthermore,
441 the CSR fields radiated in a dipole can propagate until the next dipole and
442 interfere with the new CSR fields produced in this second dipole [14].

443 For now, the only way to consider all these effects is to use numerical methods
444 which allow to simulate the CSR wakefield or CSR impedance for a given beam-
445 line and vacuum chamber geometry. The CSRZ code, by Demin Zhou, is a

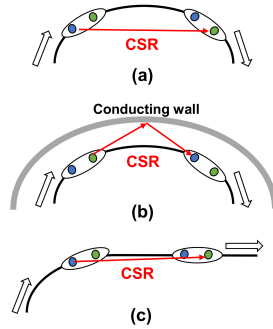


Figure 11: Schematics of the electron interaction within a bunch due to coherent synchrotron radiation (CSR). White arrows show the propagation direction of the bunch and red arrows the emitted CSR field. The bunch is represented by an ellipse with the black contour with inside an electron of the tail in blue and one of the head in green. (a): effect of CSR in free space, the CSR radiated by the tail affects the head of the bunch. (b): effect of the walls, the CSR radiated by the head is reflected on the walls and affects the tail. (c): transient effect at dipole exit, the CSR field emitted at the dipole exit travels parallel to the bunch and interacts with it during the drift.

446 FORTRAN 90 code which allows to compute the CSR impedance of a beam
 447 by numerical integration of Maxwell's equations in the paraxial approximation
 448 [14, 43]. The code considers a beam pipe of constant rectangular cross section
 449 with a curvature defined by an arbitrary function of the longitudinal coordinate
 450 s . It brings the possibility to simulate CSR with the real disposition of the
 451 dipole magnets in a lattice. The code assumes a constant Gaussian bunch in
 452 every dimensions. After the geometry defined by the user, an infinite straight
 453 section can be added to integrate the CSR fields produced in bends and can
 take into account additional transient effects.

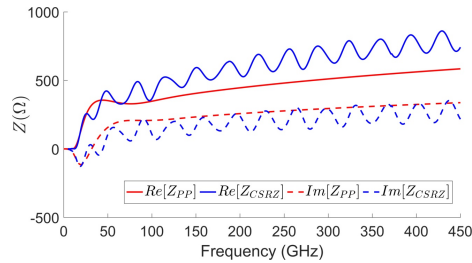


Figure 12: CSR impedance computed with the parallel plate model Z_{PP} (steady-state) in red and using CSRZ for a single ThomX ring dipole Z_{CSRZ} . The real part of the impedance is shown in plain lines and the imaginary part in dotted lines. Parameters: $L = 0.2964$ m, $R = 0.3773$ m, $h = 28$ mm, $a = 40$ mm.

454

455 A ThomX storage ring dipole has been simulated using CSRZ, approximat-
 456 ing ThomX vacuum chamber with a beam pipe of rectangular cross section with
 457 an horizontal dimension of $a = 40$ mm and a vertical one of $h = 28$ mm. In fig-
 458 ure 12, the CSR impedance computed with CSRZ for a single bend in ThomX,
 459 Z_{CSRZ} , is compared to the CSR impedance computed using the parallel plate
 460 model Z_{PP} . Both the analytic model and the numerical calculation agree on
 461 the frequency value for the CSR threshold, around 11 GHz. Compared to the
 462 very smooth impedance of the parallel plate model, the impedance computed
 463 using CSRZ shows oscillations corresponding to the resonances of the CSR fields
 464 within the rectangular vacuum chamber both in the real and in the imaginary
 465 part. The amplitude difference between the curves is due to the transient ef-
 466 fects which increase the amplitude of the real part and decrease the one of the
 imaginary part.

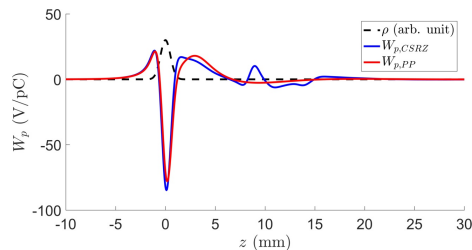


Figure 13: CSR wake potential radiated by a Gaussian longitudinal charge density ρ ($\sigma_z = 0.5$ mm) for a ThomX ring dipole with the parallel plate model $W_{p,PP}$ and with CSRZ $W_{p,CSRZ}$. The head of the bunch corresponds to negative z values and the tail to positive z values.

467

468 The wake potential $W_{p,CSRZ}$ generated by the Z_{CSRZ} impedance spectrum
 469 for a Gaussian bunch of $\sigma_z = 0.5$ mm is shown in Fig. 13. It is compared to the
 470 wake potential of the parallel plate model $W_{p,PP}$, the amplitude of $W_{p,CSRZ}$ is
 471 slightly more important due to the transient effects. The $z < 0$ zone is similar
 472 for the two wake potentials, which means that the tail-head interaction is not
 473 affected by the inner walls of the vacuum chamber in this case. The $z > 0$ zone is
 474 modified compared to the parallel plate case, with a longer wake trailing behind
 475 the bunch. This change is brought by the effect of the outer walls, bringing an
 476 additional head-tail interaction, and the resonances within the vacuum chamber.

477 The CSRZ simulation has also been performed for multiple bends in order to
478 estimate the effect of the CSR field interference [8]. The interference between the
479 CSR emitted in each bend produces additional oscillations on the real part and
480 imaginary part of the impedance which are amplified as more and more dipoles
481 are added. For the full ring, the impedance spectrum is full of resonant peaks
482 but keeps the same mean amplitude as Z_{CSRZ} . Unfortunately, this computation
483 is very long, several months of calculation for the full ThomX 18 m ring with
484 a frequency step thin enough to resolve properly these peaks in the impedance
485 spectrum.

486 5. Summary and conclusion

487 An impedance model, for both the geometric wakefields and the coherent
488 synchrotron radiation (CSR), has been designed for the particular case of
489 ThomX [2, 3], a laser-electron storage rings [1] for X-ray production via Compton
490 backscattering.

491 The geometric and resistive wall impedance model designed is based on sim-
492 ulations of every elements of the storage ring. Then the coaxial wire method
493 has been used to measure prototypes of the storage ring elements to check the
494 simulations. A precise evaluation of the different error sources of these mea-
495 surements has been done and highlights the important uncertainty of this type
496 of measurements. Nevertheless, the measurements have allowed to validate the
497 simulations. As the simulation of the kicker impedance was not possible, because
498 of very thin coatings, an analytical model, the multi-layered cylindrical cham-
499 ber [23], has been used to evaluate the kicker impedance. The total impedance
500 budget has been presented, corresponding to a loss factor of $k_{\parallel,T} = 6.73 \text{ V pC}^{-1}$
501 for a Gaussian bunch of $\sigma = 2 \text{ mm}$. To this value, the RF cavity and its tapers
502 contribute for 47 %, the septum chamber for 17 %, the kickers for 12 % and the
503 rest is distributed among the other components of ThomX storage ring.

504 The CSR impedance model has been obtained by simulation of the beam in
505 a rectangular vacuum chamber. It has allowed to take into account transient

506 effects, due to straight sections in between dipoles, and resonances, due to re-
507 flections on the beam pipe, using the CSRZ code [14, 43]. The result has been
508 compared with the parallel plate model and has shown the importance of the
509 transient effects and resonances in ThomX dipoles.

510 These impedance models have been used to extract pseudo wake functions
511 which are used to feed the codes currently used for ThomX beam dynamics stud-
512 ies. The analysis of these two models provide important insight on the influence
513 of collective effects in ThomX beam dynamics. The quantity $Re[Z]|\tilde{\rho}|$ is related
514 to the total energy loss of a bunch of spectrum $\tilde{\rho}$ due to the impedance Z [30].
515 This quantity is shown for both impedance models for a short bunch, $\sigma_s = 2$ mm
516 $= 6.6$ ps, and for a longer bunch, $\sigma_s = 6$ mm $= 20$ ps, in Fig. 14. At injection,
517 the bunch corresponds to the short bunch case, for which the dominant effect is
518 the CSR. After some time, the bunch has fully filled the RF bucket due to the
519 filamentation induced by the longitudinal mismatch at injection. For the long
520 bunch obtained, the effect of the CSR is small compared to the geometric and
521 resistive wall wakefields. It confirms that, in ThomX case, simulating the geo-
522 metric impedance up to 50 GHz is enough. As, for short bunches for which high
523 frequencies are important, the CSR is the dominant effect. This simple analysis
524 also highlights two distinct regimes for the longitudinal dynamics. A transient
525 regime during which the CSR has a strong impact due both to the injection of
526 a short bunch and to the filamentation [8]. And another regime, which starts
527 after the emittance dilution, which corresponds to the classic potential-well dis-
528 tortion.

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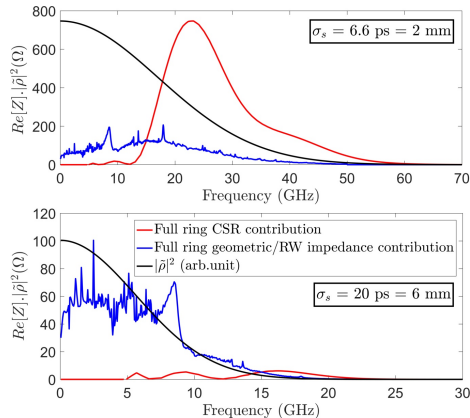


Figure 14: Plots of the product $Re[Z]|\bar{\rho}|^2$ versus the frequency for different bunch length σ_s . The impedance Z corresponds to the CSR impedance of the full storage ring for the red line ($8 \times Z_{CSRZ}$, see Fig. 12). The impedance Z corresponds to the full geometric/RW impedance model, see Fig. 1, for the blue line. The black line shows the modulus squared of the bunch spectrum $|\bar{\rho}|^2$ is arbitrary units (arb. unit).

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 541 IN2P3.

542 Appendix A. Errors estimate for the coaxial wire measurement

543 The main source of error in the impedance measurement is due to the S_{21}
 544 measurements, especially the error on the repeatability of the measurements.
 545 A bunch of 5 different measurements of each pieces measured have been done
 546 to test these bias. After each measurement, the brazing and the tautening of
 547 the wire were changed. The typical value for the standard deviation is about
 548 $\sigma_{S_{21}} = 0.4$ dB but it increases with frequency.

549 As the error is inferred from a small set of repeated measurements, type
 550 A uncertainty, a Student t-distribution for the error is assumed [44]. So the
 551 standard uncertainty is given by $u_{S_{21M}} = \sqrt{\frac{\nu}{\nu-2}}\sigma$, with $\nu = N - 1$ degrees of

Variable (Unit)	ErrorType	Probability distribution	Standard uncertainty u
$S21_{REF/DUT}$ (dB)	Repeatability	Student	$u_{SM} = \sqrt{\frac{4}{4-2}}\sigma_{S21} \approx 0.57$ (Variable)
$S21_{REF/DUT}$ (dB)	VNAB Cal- i- bra- tion	Triangular	$u_{SC} = \frac{0.2}{\sqrt{6}} \approx 0.082$
$S21_{REF/DUT}$ (dB)	VNAB Res- o- lu- tion	Rectangular	$u_{SR} = \frac{0.02}{2\sqrt{3}} \approx 0.0082$
d (mm)	Manufacturing	Gaussian	$u_d = 0.1$
D_{eq} (mm)	Modelization	Gaussian	$u_D = 0.1$

Table A.4: Sources of errors for impedance measurements. The standard uncertainty for the repeatability of $S21_{REF/DUT}$ is computed for $\sigma_{S21} = 0.4$ dB

552 freedom, N the number of measurement in a set and σ the standard deviation
553 of the measurement set.

554 Other sources of errors, type B uncertainty, for the $S21$ measurement are the
555 VNA resolution limit and calibration. The VNA used to do the measurement
556 is an Anritsu MS4624B, last calibration check in a metrology laboratory shown
557 a maximum error of $e = 0.2$ dB (at -50 dB) when compared to a reference. A
558 triangular distribution of the errors is assumed as this value e is the maximum
559 error and not the most probable error. The resolution limit of the VNA is
560 $r = 0.02$ dB at maximum. In this case a rectangular distribution of the errors
561 is assumed as all values v are equally likely in $[v - \frac{r}{2}, v + \frac{r}{2}]$.

562 In addition to the error on the $S21$ measurement there is also an error on
563 the determination of the line impedance Z_L . The error on the wire diameter d
564 is given by the manufacturer $u_d = 0.1$ mm. The error for ThomX equivalent
565 diameter D_{eq} is the fitting error which is about $u_D = 0.1$ mm. Table A.4
566 shows the summary of the different error components, their sources and their
567 respective probability distribution.

568 Using uncertainty propagation on Eq. (1) gives the composed standard un-

569 certainty of the impedance measurement u_Z in Eq. (A.1) [44]. The standard
 570 uncertainty on the $S21$ measurement u_S is given by: $u_S = u_{S_M} + u_{S_C} + u_{S_R}$.
 571 With u_{S_C} the standard uncertainty on the calibration, u_{S_R} the standard un-
 572 certainty on the resolution. The standard uncertainty on the repeatability of
 573 the measurement u_{S_M} depends on the object measured and on the frequency
 574 considered.

$$u_Z = \frac{Z_v}{\pi} \sqrt{\ln^2 \left(\frac{S21_{DUT}}{S21_{REF}} \right) \left(\frac{u_D^2}{D^2} + \frac{u_d^2}{d^2} \right)} + \ln^2 \left(\frac{D}{d} \right) \left(\frac{u_{S_{DUT}}^2}{S21_{DUT}^2} + \frac{u_{S_{REF}}^2}{S21_{REF}^2} \right)} \quad (\text{A.1})$$

575 But Eq. (A.1) is not usable in this state as when using uncertainty propa-
 576 gation formulas the standard uncertainties u_S should be absolute uncertainty.
 577 As it is shown in Eq. (A.2) to Eq. (A.4), the absolute uncertainties in dB (with
 578 index dB) change into relative uncertainties when changed back in linear scale
 579 (with index L). Furthermore the transformation from dB scale to linear scale
 580 leads to an asymmetry of the uncertainty boundaries.

$$S21_{dB} - u_{S_{dB}} < S21_{dB} < S21_{dB} + u_{S_{dB}} \quad (\text{A.2})$$

$$\frac{S21_L}{u_{S_L}} < S21_L < S21_L u_{S_L} \quad (\text{A.3})$$

$$S21_L + S21_L \left(\frac{1}{u_{S_L}} - 1 \right) < S21_L < S21_L + S21_L (u_{S_L} - 1) \quad (\text{A.4})$$

582 Finally Eq. (A.5) is obtained, in which all the quantities are in linear scale,
 583 and gives the upper and lower composed standard uncertainties. For example
 584 if the transmission parameter $S21$ for the reference is measured at -10 dB, for
 585 the DUT at -15 dB and that both measurements have a standard deviation of
 586 $\sigma_{S21} = 0.4$ dB at this frequency point then the impedance measured is $Z =$
 587 $237_{-46}^{+49} \Omega$. In that case, 98 % of the uncertainty on the impedance is due to the
 588 uncertainty on $S21$ measurements and 2 % on the line impedance Z_L .

$$u_Z^\pm = \frac{Z_v}{\pi} \sqrt{\ln^2 \left(\frac{S21_{DUT}}{S21_{REF}} \right) \left(\frac{u_D^2}{D^2} + \frac{u_d^2}{d^2} \right)} + \ln^2 \left(\frac{D}{d} \right) \left(u_{DUT}^{\pm 2} + u_{REF}^{\pm 2} \right)} \quad (\text{A.5})$$

$$u^+ = u_{SL} - 1 \quad (\text{A.6})$$

$$u^- = \frac{1}{u_{SL}} - 1 \quad (\text{A.7})$$

589 All measurement results are shown with their 95 % confidence interval (CI)
 590 corresponding to the extended uncertainty using Student coefficient $k = 2.78$
 591 ($N = 5$). In the case of the previous example, the extended uncertainties to 95
 592 % CI gives $Z = 237^{+137}_{-127} \Omega$. The important uncertainty found comfort us in the
 593 idea that this measurement should only be used to validate the simulation tools
 594 and methods.
 595

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