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Application of electron tomography of dislocations in beam-sensitive quartz to the determination of strain components

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ABSTRACT

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Plasticity
Dislocation
Tomography
Electron-beam sensitive material
Quartz
Climb
von Mises criterion

In this study we apply electron tomography of dislocations to quartz with a view to assess whether the von Mises-Taylor criterion is satisfied or violated in a deformed crystal of quartz. We propose a method to perform electron tomography with few projected images which allows extension of this technique to beam-sensitive materials such as quartz. The 3D characterization of the dislocation microstructure allows the evaluation of contributions to dislocation mobility with no ambiguity. From the geometrical characteristics of the dislocations and their Burgers vectors, we show how to identify the non-zero components of the strain tensor. We show that in the quartz grain investigated, the von-Mises-Taylor criterion is satisfied thanks to the climb of $\langle c+a \rangle$ dislocations.

1. Introduction

The book of Nicolas and Poirier (1976) "Crystalline Plasticity and Solid State Flow in Metamorphic Rocks" has represented a milestone in transferring metallurgical knowledge to structural geology. Despite the complexities of crystal structure of minerals and compositional variation of minerals and rocks, their plastic deformation, like metals, involves the motion of crystal defects. In naturally deformed samples, microstructures are often the only record left by past tectonic events and their detailed study is essential to decipher the thermomechanical history experienced by the rocks. Compared to metals, often of cubic symmetry, most minerals exhibit low crystallographic symmetry, which in turn allows only a limited number of slip systems to be activated (Barber et al. 2010). According to the Von Mises-Taylor criterion (von Mises 1928; Taylor 1938), at least five independent slip systems must operate to satisfy the conditions of continuity of displacement at crystal boundaries and accommodate an arbitrary imposed deformation. This criterion can be relaxed to four slip systems if strain is inhomogeneous and only local accommodation is required (Hutchinson 1977; Nebozhyn et al., 2000; Detrez et al. 2015; Castelnau et al. 2020). Nevertheless the Von Mises-Taylor criterion is not satisfied in many minerals and other deformation mechanisms such as crack opening, frictional sliding, kinking,

twinning, dislocation climb, high-temperature grain boundary sliding, or diffusion creep may be necessary to deform polycrystalline rocks (Groves and Kelly 1969). Here, we propose a novel approach based on a detailed characterization of a dislocation microstructure by tomography in transmission electron microscopy (TEM) to assess its capability of achieving an arbitrary imposed deformation. In this study, quartz will be used as a case study to illustrate the methodology that we introduce.

In quartz, dislocations were first evidenced by Willis (1952) from growth spirals on a surface. Evidence for basal slip was first reported by Christie et al. (1964). In this trigonal structure, basal glide involves three $1/3\left\langle11\overline{2}0\right\rangle$ slip directions referred to as $\langle a\rangle$ (Baëta and Ashbee 1969). Blacic (1975) reports, as a function of increasing temperature, a transition from $\langle a\rangle$ -basal to [0001] ($\langle c\rangle$) prismatic ({m}) $\left\{10\overline{1}0\right\}$ glide. Ball and White (1978) pointed the apparent difficulty of satisfying the von Mises criterion for general plasticity by activation of $\langle a\rangle$ -basal and $\langle c\rangle$ -prismatic glide alone. In particular, with these slip systems, strains parallel to the [0001] axis cannot be produced in any single grain in response to imposed stresses. They proposed that the deformation of quartzite in the crust involves activation of dislocation climb to allow general plasticity of the polycrystalline aggregate. This fundamental limitation can also be solved by activation of $\langle c+a\rangle$ glide involving

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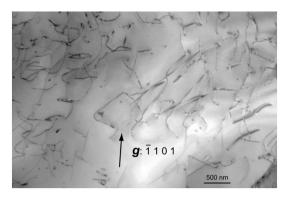


Fig. 1. Typical dislocation microstructure obtained in kinematical bright field condition with the $\overline{1}101$ diffraction vector.

dislocations with $1/3\langle 11\overline{2}3\rangle$ Burgers vectors. Evidence for activation of $\langle c + a \rangle$ glide was first reported by Baëta and Ashbee (1969) and further confirmed by TEM by Trepied and Doukhan (1982) in quartz single crystals compressed along the [0001] axis at temperatures above 973 K. Activation of slip systems induces crystal preferred orientations in rocks (Nicolas and Poirier 1976) which can be linked to seismic anisotropy (Mainprice and Nicolas 1989). This direction of research has been very active in the last decades, with the development of EBSD measurements and Visco-Plastic Self-Consistent (VPSC) models. Surprisingly, in these studies, the role of $\langle c + a \rangle$ glide has only been marginally considered. Alternatively, a number of models have been based on a succession of slip systems with increasing temperature, $\langle a \rangle$ -glide is successively activated in the easy basal plane, and then in the rhombohedral planes (acute rhombs $\pi \Big\{ 10\overline{1}2 \Big\}$ and $\pi' \Big\{ 01\overline{1}2 \Big\}$, and positive $r \Big\{ 10\overline{1}1 \Big\}$ and negative $z\Big\{01\overline{1}1\Big\}$ rhombs) followed by $\langle a \rangle$ -prismatic $(m\Big\{10\overline{1}0\Big\})$ and finally $\langle c \rangle$ -prismatic (see Morales et al. 2011; Keller and Stipp 2011; Morales et al. 2014). However, the activation of those planes does not solve the von Mises-Taylor criterion issue raised by Ball and White (1978). Looking beyond the activation of slip systems, activation of climb (as suggested by Ball and White (1978)) is not the only alternative. Violation of the von Mises-Taylor criterion leads to stress concentration at the grain boundaries which can be released by crack opening or activation of grain boundary sliding. Activation of grain boundary sliding in quartz had been proposed in quartz-rich rocks by Fliervoet et al. (1997), Rutter and Brodie (2004), Fukuda et al. (2018) and Tokle et al. (2019). Microstructural evidence for the activation of grain boundary sliding is difficult to established as demonstrated by recent studies of Maruyama and Hiraga (2017), Quintanilla-Terminel et al. (2017) and Bollinger et al. (2019).

In the present study, we show that the validity of the von Mises-Taylor criterion can be assessed from a detailed, 3D, characterization of the dislocation microstructure since the kinematics of glide is fully determined from a dislocation's geometry (knowing its Burgers vector). Our approach is presented in the "Theory" section of this paper. Conventional TEM usually provides 2D projections of the dislocation microstructure which is not sufficient to determine the slip plane. 3D dislocations structures can be reconstructed by tomography as first demonstrated by Barnard et al. (2006) (see a recent review on this technique by Feng et al. (2020)). The strong sensitivity of quartz to electron irradiation (see for instance Fig. 2 of Barber et al. 2010) is however a limitation to perform electron tomography which usually involves long acquisition of image series at varying tilt. In Section 2, we propose a novel method to perform electron tomography with few projected images which extends this technique to beam-sensitive materials. In Section 3, we show how the strain components produced by the dislocation microstructure can be calculated from the elements characterized in electron microscopy (dislocation geometry, Burgers

vector). The results presented in Section 4 are analyzed in Section 5 in the light of the ability of the observed microstructure to produce a general deformation in the grain. We conclude with some perspectives offered by this work toward more quantitative studies.

2. Materials and Methods

2.1. Specimen

Here we characterize dislocation microstructures in quartz grains from a Bohemian (Czech Republic) granulite. The specimen was mechanically polished down to a thickness of 30 μm , then ion milled with Ar-ions to achieve electron transparency. A thin carbon layer was deposited to ensure electron conduction on the thin-foil. An example of typical dislocation microstructure is shown in Fig. 1.

2.2. Transmission electron microscopy

TEM analyses were conducted with a FEI® Tecnaï G²-20 Twin microscope operating at 200 kV with a LaB₆ filament, associated with a "Spinning Star" precession module (Vincent and Midgley 1994) from the Nanomegas Company. Electron tomography has been performed by acquiring tilt series with a double tilt sample-holder in diffraction contrast imaging mode. The crystal of interest is oriented so as to identify a diffraction vector with a high structure factor to produce wellcontrasted images. Here we use g: 1101 which belongs to the family of diffraction vectors with the highest structure factor in quartz. Imaging is performed in the weak-beam dark-field (WBDF) mode to keep a high signal to noise ratio. In these conditions background contrasts are heterogeneous because of the occurrence of thickness fringes. Also, the contrast of dislocations inclined in the thin foil oscillates. In order to get homogeneous contrast for both background and dislocations, we have induced a precession of the electron beam (Rebled et al. 2011; Mussi et al. 2014; Mussi et al. 2015a, b; Mussi et al. 2017) with a precession angle of 0.1° to ensure that the electron beam is not masked by the objective aperture (necessary to reveal dislocation contrasts). Electron tomography of dislocations requires a perfect alignment of the diffraction vector along the sample-holder principal axis, in order to keep the dislocation contrast constant all over the tilt series acquisitions. Following accurate tilt series alignments (with spatial precision better than 5 nm) dislocation tomography reconstructions are obtained using the weighted back-projection (WBP) algorithm (Herman et al. 1976) accessible on the TomoJ plugin (Messaoudi et al. 2007) from the free ImageJ software. Reconstruction algorithms are aimed at transforming a tilt series into a stack. The determinations of dislocation position in reconstructed volumes are accurate in the sample-holder accessible angular range (interpolation calculation of the algorithm); however they are less accurate in the missing-wedge (extrapolation calculation of the algorithm). Consequently, reconstructed dislocation thicknesses are thin in the sample-holder accessible angular range and thick in the missingwedge, so their geometries take the form of ribbons. To improve the reconstructed volume qualities, dislocations have been directly redrawn into the volumes using the free UCSF Chimera software (Pettersen et al. 2004; Liu et al. 2014; Mussi et al. 2016; Mussi et al. 2017).

Burgers vector indexing is performed using the thickness fringe method developed by Ishida et al. (1980). This technique consists of counting the number of thickness fringes that end on the dislocation terminations. This number corresponds to the ${\it g.b}$ scalar product where ${\it g}$ is the diffraction vector and ${\it b}$ the Burgers vector. Even if this method is underused by the community of TEM users (Wiezorek et al. 1997; Miyajima and Walte 2009), it is useful to characterize the Burgers vectors of materials sensitive to electron beam as it considerably limits the WBDF micrograph acquisition number.

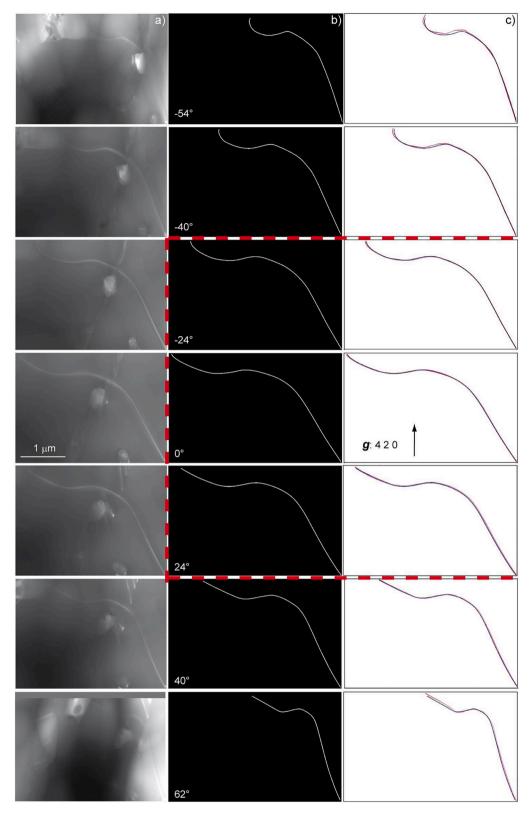


Fig. 2. Reconstruction method for few projected images in garnet. a) Seven projected micrographs (projection angles of -54° , -40° , -24° , 0° , 24° , 40° and 62°) extracted from the raw aligned tilt series obtained in WBDF conditions with the 420 diffraction vector and a precession angle of 0.1° ; b) corresponding projected micrographs redrawn in black and white contrast; c) superposition of projected images extracted from the reconstructed volume (in red) and the redrawn micrographs of Fig. 2b (in blue), where the reconstructed volume has been obtained using only 4 redrawn micrographs for projection angles of -24° , -8° , 8° and 24° . The projected images extracted from the reconstruction volume accurately fit the original micrographs even for high projection angles. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

2.3. Tomography with few projected images and low angular ranges

To determine the best working conditions to perform electron tomography on specimens sensitive to electron beam, a tilt series from a previous study has been used. This tilt series was acquired on a deformed garnet sample which is less sensitive to irradiation damage. It was acquired every 2° from -54° to 62°. Reconstructing a good quality 3D dislocation microstructure with few projected images and a low angular range requires favorable reconstruction conditions. That is why we decided to analyze only a few dislocations that are not far from the tilt axis, so that reconstruction algorithm extrapolations can be minimized. The dislocations of each projected images have been redrawn to ensure a black and white contrast, since discrete 3D reconstructions give access to better quality volumes than continuous grey level reconstructions (Batenburg and Sijbers 2011). Fig. 2a and b show 7 raw and redrawn projected images among the 59 projected images of the tilt series. An electron tomography volume has been reconstructed with only 4 redrawn projected images and an angular range of only $+/-24^{\circ}$, i.e. projection angles (angles between the normal of the thin foil and the electron beam direction for a specific tilt angle) of -24° , -8° , 8° and 24° (red rectangle with dotted lines in Fig. 2). Then, the reconstructed dislocations are redrawn into the reconstructed volume using Chimera software (Liu et al. 2014; Mussi et al. 2016; Mussi et al. 2017). Fig. 2c reveals small deviations between the positions of the redrawn reconstructed dislocations and the redrawn dislocations of projected images (approximately the dislocation thicknesses) even for high projected angles such as -54° and 62° . Consequently, we conclude that tomographic reconstructions performed near tilted axes with dislocation micrographs redrawn in black and white reflect real dislocation microstructures for only 4 projected images and a low angular range of only 48° (+/- 24°).

3. Theory: Inferring strain(-rate) components from dislocation geometry

3.1. Dislocation glide

A dislocation with a Burgers vector \boldsymbol{b} gliding on a plane with normal $\boldsymbol{n^g}$ (index "g" stands for glide) produces a shear proportional to tensor \boldsymbol{b} $\otimes \boldsymbol{n^g}$ or equivalently to $\hat{\boldsymbol{b}} \otimes \hat{\boldsymbol{n}^g}$ with $\hat{\boldsymbol{b}}$ and $\hat{\boldsymbol{n}^g}$ the unit vectors parallel to \boldsymbol{b} and $\boldsymbol{n^g}$. Here, \otimes is the dyadic product (the dyadic product of two vectors $\hat{\boldsymbol{a}}$ and $\hat{\boldsymbol{b}}$ is a second order tensor \boldsymbol{A} with component $\boldsymbol{A_{ij}} = a_i b_j$). To express g = g the associated symmetric strain tensor, one defines the Schmid tensor \boldsymbol{S} :

$$\overset{=}{S} = \frac{1}{2} \left(\widehat{b} \otimes \widehat{n}^g + \widehat{n}^g \otimes \widehat{b} \right)$$

$$S_{ij}^g = \frac{1}{2} \left(b_i n_j^g + b_j n_i^g \right)$$

which is symmetric and traceless, i.e. $S_{11}^g + S_{22}^g + S_{33}^g = 0$ since \widehat{b} and \widehat{n}^g are orthogonal. Plastic deformation due to dislocation glide is isochoric.

Therefore, S has only five independent components, for example S_{11}^g , S_{22}^g , S_{23}^g , S_{12}^g and S_{13}^g .

3.2. Dislocation climb

Climb is the non-conservative displacement of a dislocation outside its glide plane due to the absorption or emission of point defects. It concerns only non-screw dislocations, *i.e.* when dislocations with a Burgers vector has a non-zero edge component. The climb of an edge dislocation produces a normal strain (Lebensohn et al. 2010; Yuan et al. 2018) along the direction of the Burgers vector, *i.e.* a strain tensor proportional to:

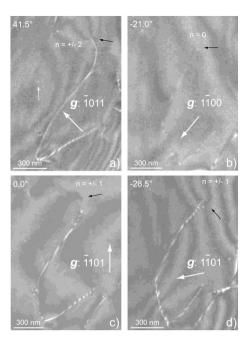


Fig. 3. Dislocation 1A (see Table 1). Burgers vector indexing by the thickness fringe method (Ishida et al. 1980). a) WBDF micrograph obtained with ${\bf g}$: $\overline{1}011$ (projection angle of 41.5°) showing a dislocation where ${\bf g}.{\bf b}=\pm 2$ (small black arrow), a small dislocation loop of approximately 9 nm in diameter is indicated by a small white arrow; b) WBDF micrograph obtained with ${\bf g}$: $1\overline{1}00$ (projection angle of -21.0°) showing a dislocation where ${\bf g}.{\bf b}=0$ (small black arrow); c) WBDF micrograph obtained with ${\bf g}$: $1\overline{1}01$ (projection angle of 0°) showing a dislocation where ${\bf g}.{\bf b}=\pm 1$ (small black arrow); d) WBDF micrograph obtained with ${\bf g}$: $1\overline{1}01$ (projection angle of -28.5°) showing a dislocation where ${\bf g}.{\bf b}=\pm 1$ (small black arrow). These four diffraction conditions are characteristic of a $1/3 \left[11\overline{23}\right]$ Burgers vector.

$$\stackrel{=}{S}^{c} = \widehat{b} \otimes \widehat{b}$$

$$S_{ii}^c = b_i b_j$$

4. Results

To reduce electron beam irradiation effects, a small condenser aperture (100 µm in diameter) and a small spot size (11.3 nm in diameter) are used. Pixels have been gathered four by four to intensify the contrast by a factor 16 without increasing the electron dose. Contrast adjustments are performed in the vicinity of the zones of interest and analyses are performed as quickly as possible to minimize beam damage. Each tilt series is composed of four WBDF micrographs acquired with a small precession angle, an exposure time of 20s and projection angles of -30° , -10° , 0° and 25° respectively (these projection angles are chosen to avoid the dynamic contrasts of zone axes). An example of Burgers vector indexing is described on Fig. 3 for the dislocation 1A (Table 1). Two thickness fringes end on the dislocation for a $\overline{1}011$ diffraction vector (small black arrow on Fig. 3a), no interaction is observed for $\mathbf{g} =$ $1\overline{1}00$ (Fig. 3b), one fringe ends on the dislocation for a $\overline{1}101$ diffraction vector (Fig. 3c), and one for $1\overline{1}01$ (Fig. 3d). We can conclude that the Burgers vector of this dislocation is $1/3 |11\overline{23}|$.

Then we perform tilt series alignments in several small zones where the Burgers vectors of dislocations have been indexed. We use nanometric dislocation loops near the studied dislocations (see the small white arrow on Fig. 3a) as reference points to perform accurate tilt series alignments. After alignments, the dislocations of interest have been redrawn in white with a black background (Fig. 4b), then the dislocation

Table 1 Summary of dislocation characterizations where we report the occurrence of the planes containing some segments of the dislocations (see figures). The angle between the Burgers vector \boldsymbol{b} and the normal of those planes is reported in the last column. In some cases, determination of those planes is imprecise when their projection is horizontal (*) or when the segments are very short (**); their values are given to provide an estimation of the angle between the planes and the

Burgers vectors.

Dislocation (Burgers vector b)	Segment	Lying planes (Normal n)	$(\widehat{n,b})$
$1/3[\overline{2}110]$ dislocations			
03B		$(\overline{32}53)$	58°
05B	1	$(1\overline{1}03)$	70°
	2	$(\overline{32}53)$	58°
5B	1	(3253)**	58°
	2	(1120)	60°
	3	(<u>1</u> 101)*	47°
	4	$(101\frac{7}{11}5)$	40°
	5	$(11\overline{2}0)$	60°
	6	(3148)	69°
2H	1	(3301)	33°
	2	(3301)	33°
1C	1	$(31\overline{4}2)$	49°
	2	$(\overline{1}101)$	47°
2C	1	(1 2 3 11)	85°
	2	(1100)	30°
	3	$(10\overline{1}0)$	30°
	4	$(3\overline{128})$	68°
3I	1	(1 3 2 17)	86°
	2	(1341)	76°
[0001] dislocations		()	500
1D	1	(1101)*	52°
	2	$(\overline{1}011)**$	52°
	3	(1101)**	52°
op.	4	(3631)	81°
2B		$(31\overline{4}8)$	30°
$1/3 \left[11\overline{23} \right]$ dislocations	1	(-)	E10
1A	1	$(\overline{3}121)$	51°
	2	$\left(\overline{32}53\right)$	20°
10	3	$(0\overline{1}16)$	32°
1B		$\left(22\overline{4}3\right)$	82°
$1/3 \left[11\overline{2}3 \right]$ dislocation	•		000
3E	1	$\left(\overline{2}111\right)$	90°
	2	(2134)**	11°

microstructures have been reconstructed with the WBP algorithm (Herman et al. 1976) and finally the resulting 3D dislocations have been directly redrawn in the volume (Fig. 4c) using the Chimera software (Liu et al. 2014; Mussi et al. 2016; Mussi et al. 2017). The complete dislocation reconstruction corresponding to Fig. 3 is presented on Fig. 4. From Fig. 4d, with a projection angle of -12° , the black dislocation segment projection appears rectilinear which suggests that the plane which contains this dislocation segment is edge-on. Knowing the thin foil orientation, it is possible to characterize this plane which is $\left(0\overline{1}16\right)$, at approximately 12° from the (0001) plane. Similarly, two other planes,

 $\left(\overline{32}53\right)$ and $\left(\overline{3}121\right)$ can be characterized for this dislocation, for projection angles of 46° and 85° respectively. Dislocation 1A, with the Burgers vector $1/3\left[11\overline{23}\right]$ appears to exhibit a complex three-dimensional configuration, with no segment in glide configuration.

Fig. 5 shows the characterization of a [0001] dislocation shown along several projection angles. From Fig. 5e and j, the projections of this dislocation appear rectilinear with tilt angles of -57° and 123° respectively. Therefore, this dislocation is located in $\left(31\overline{4}8\right)$. The normal of this plane is at a 30° angle to the Burgers vector, *i.e.* it is not a glide configuration.

Fig. 6 describes the geometry of a 1/3 $\boxed{2}110$ dislocation (2C). This is the most commonly indexed Burgers vector of dislocations determined in our study, see Table 1. Here again, the geometry is 3D. This dislocation can be subdivided into four segments (in blue, light blue, black and grey colors respectively), each contained in a specific habit plane (Fig. 6). Two of them are prismatic planes: $(1\overline{1}00)$ and $(10\overline{1}0)$ plane which do not contain the Burgers vector. The black and the grey segments belong to the $(\overline{1}\ \overline{2}\ 3\ 11)$ and $(3\overline{1}28)$ planes respectively (Fig. 6b, e, h and i). Except for $(\overline{1}\ \overline{2}\ 3\ 11)$ which is slightly ambiguous, all segments depart significantly from glide configuration. A similar conclusion can be drawn for any other 1/3 $[\overline{2}110]$ dislocation characterized (Table 1).

Fig. 7 shows the only unambiguous case for a glide configuration found in this study (dislocation 3E, Table 1). This dislocation has a $1/3\left[11\overline{2}3\right]$ Burgers vector. It is composed of 2 segments: a black segment whose projection appears rectilinear for a tilt angle of -68° (Fig. 7c) and a purple segment whose projection is rectilinear for a tilt angle of $+85^\circ$ (Fig. 7h). The purple segment is in glide configuration in the $\left(\overline{2}111\right)$, the second order pyramidal plane. The dislocation is, however, not purely in a glide configuration since the black segment (although its plane is not determined precisely), deviates significantly from the glide plane.

Table 1 summarizes all characterizations. It must be noted that this sampling does not capture all dislocations in the area studied. Since tomography is performed only for an individual diffraction vector $g = (\overline{1}101)$, some dislocations (e.g. $1/3[11\overline{2}0], 1/3[\overline{1}2\overline{1}3]$ and $1/3[2\overline{1}13]$) are out of contrast. No conclusion can be drawn for these dislocations.

5. Discussion and conclusion

Several facts emerge from this study which cannot be drawn without a detailed characterization. Firstly, all potential Burgers vectors of the quartz structure have been characterized i.e. $\langle a \rangle$, [c] and $\langle c + a \rangle$. This probably results from a deformation occurring at high temperature since this sample went through the granulite facies. All dislocations exhibit rather complex 3D configurations. Two processes lead to 3D dislocation microstructures: cross-slip and climb. Here tomography allows us to exclude cross-slip as the most prevalent process, since dislocation segments in glide configurations are almost never found. Climb is a major process acting in this specimen. This is consistent with the observation of several sub-grain boundaries. From our study, we can derive all parameters which are necessary to infer the strain components produced by the dislocations characterized either by glide (in the only occurrence observed: dislocations 3E) or by climb. Based on these results and theory presented in Section 3, we can report which dislocation provides a non-zero contribution for each component of the strain tensor:

$$\bar{\varepsilon} = \begin{pmatrix} \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} & \left\{ c + a_3 & c - a_3 \right\} \\ \left\{ c + a_3 & c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\} & \left\{ c - a_3 \right\} \\ \left\{ c - a_3 \right\}$$

The above expression is given in a reference frame with the x-axis taken parallel to the crystallographic direction $[a_1]$ of the quartz lattice, and the z-axis parallel to direction [c]. The glide of dislocation 3E (c- a_3) fills five components of the strain tensor, but since these components are all proportional to each other (due to a single slip system), the dislocation 3E only provides one independent system. Using the method described in Castelnau et al. (2020), one can also show that four components of the climb strain tensor are independent. As these are complementary to those due to glide, the combination of glide and climb satisfies the five necessary systems of the von Mises-Taylor criterion. The striking observation is that, from our non-exhaustive characterization, one is able to conclude that the dislocation microstructure is sufficient to produce a general deformation since all components of the strain tensor are non-zero and independent. In the literature, it has usually been assumed that the von Mises-Taylor criterion is satisfied by climb (implied by $\langle a \rangle$ or [c] dislocations) or by $\langle c + a \rangle$ glide. We find here a completely different situation where $\langle c + a \rangle$ climb is critical to ensure general deformation.

6. Perspectives

The present study demonstrates that electron tomography can be applied successfully to a beam-sensitive mineral such as quartz. We show that the simultaneous determination of all characteristics of dislocations (*i.e.* the Burgers vector and the line geometry) provide crucial information on the deformation mechanisms at play. Such a characterization is beyond standard observation at the TEM since sample-holder tilt places limitations on determinations of critical imaging information. The electron tomography reconstruction can be used to overcome these physical limitations and to examine the dislocation geometry from all orientations. In the present study which is only a proof of concept, the conclusions presented are only semi-quantitative since we only identify the non-zero strain components. Developments toward a quantitative determination of the components of the strain tensor are, in principle, possible since the results of our calculations could be weighted by the

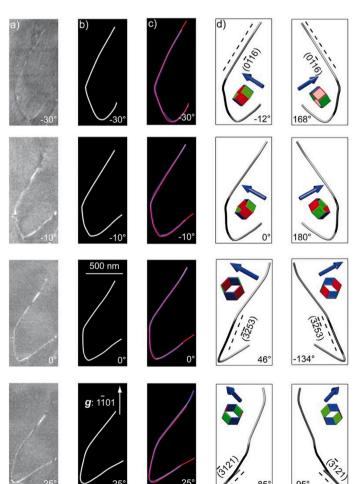


Fig. 4. Reconstruction method for few projected images of Fig. 3 dislocation 1A whose Burgers vector is $1/3[11\overline{23}]$. a) Four aligned projected micrographs (projection angles of -30° , -10° , 0° and 25°) obtained in WBDF conditions with the $\overline{1}101$ diffraction vector and a precession angle of 0.1° ; b) corresponding redrawn projected micrographs in black and white contrast; c) superimposed of projected images extracted from the reconstructed volume (in blue) and the redrawn micrographs of Fig. 3b (in red); d) Projected images extracted from the reconstructed volume for eight projected angles, where the $(\overline{3253})$ plane is edge-on for the projected angles of 46° , the $(\overline{3}121)$ plane is edge-on for the projected angles of 85° and the $(0\overline{1}16)$ plane is edge-on for the projected angles of -12° . This reconstruction gives us the opportunity to characterize three mixed climb systems: $\pm 1/3 \left[11\overline{23} \right] \left(\overline{3}121 \right), \pm 1/3 \left[11\overline{23} \right] \left(\overline{32}53 \right)$ $\pm 1/3 \left[11\overline{23} \right] \left(0\overline{1}16 \right)$ (in grey, black and grey respectively), for the same dislocation. The crystal orientation is materialized by the colored hexagonal prism and the Burgers vector is shown by the blue arrow. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

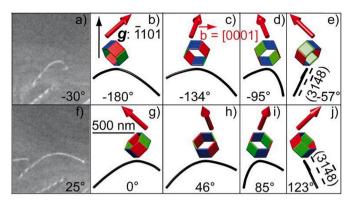


Fig. 5. Electron tomography reconstruction for a [0001] dislocation (2B), obtained with the $\overline{1}101$ diffraction vector, and shown in a) and f). Projected angle of a) -30°; b) -180°; c) -134°; d) -95°; e) -57°; f) 25°; g) 0°; h) 46°; i) 85°; and j) 123°. The plane containing the dislocation is edge-on for a projection angle of -57° and a projection angle of 123°. The [0001] Burgers vector is represented by the red arrow. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

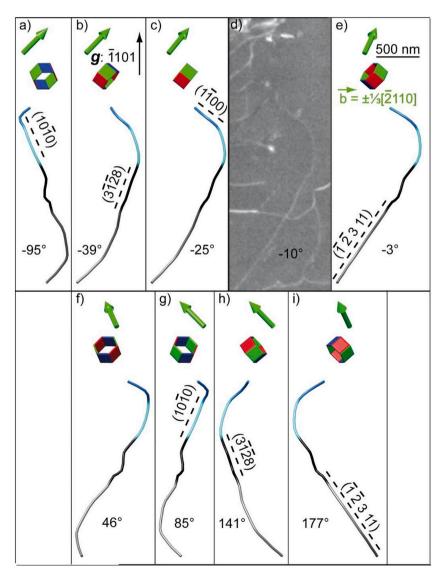


Fig. 6. Electron tomography reconstruction for dislocation (shown in d), with a $1/3\left[\overline{2}110\right]$ Burgers vector (shown by the green arrow), obtained with the $\overline{1}101$ diffraction vector: projected angle of a) -95°; b) -39°; c) -25°; d) -10°; e) -3°; f) 46°; g) 85°; h) 141°; and i) 177°. The $\left(1\overline{1}00\right)$ plane containing the blue dislocation segment is edge-on for a projection angle of -25°; the $\left(10\overline{1}0\right)$ plane containing the light blue dislocation segment is edge-on for a projection angle of 95° and a projection angle of 85°; the plane containing the black dislocation segment is edge-on for a projection angle of -39° and a projection angle of 141°; and the plane containing the grey dislocation segment is edge-on for a projection angle of -3° and a projection angle of 177°. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

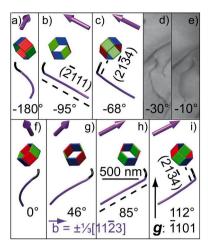


Fig. 7. Electron tomography reconstruction for dislocation 3E (shown in d,e), with a $1/3\left[11\overline{2}3\right]$ Burgers vector (shown by the purple arrow), obtained with the $\overline{1}101$ diffraction vector: projected angle of a) -180°; b) -95°; c) -68°; d) -30°; e) -10°; f) 0°; g) 46°; h) 85°; and i) 112°. The $\left(\overline{2}111\right)$ 2nd order pyramidal glide plane of the purple dislocation segment is edge-on for a projection angle of -95° and a projection angle of 85°; and the plane containing the black dislocation segment is edge-on for a projection angle of 112°. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

dislocation line length (which is accessible from tomographic study). To be relevant, such study should ensure that all dislocations present in the grain are in contrast and analyzed. The only limitation will then be the sampling which is always a difficulty in the TEM. This can however be achieved if the grains are small enough to be fully characterized.

Author contributions

AM and PC designed the study, AM performed the TEM investigations. AM post-treated and analyzed the data with JG. OC performed the theoretical analysis. AM, OC and PC wrote the original draft.

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Declaration of Competing Interest

None.

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