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## VDesign A Formal Problem Optimization Software

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### Actors in the preliminary design field



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### Characteristics of the models

#### Model types

Motor, Turbine, Electrical devices...

### The easy part

- Continuous models
- Analytical (derivatives available)
- Small decision space

#### The no so easy part

- Non Linear
- Internal analytical problem resolution parameterized by the decision variables
  - Derivative less trivial

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### Real life models

### Falcon 2000 (Dassault Aviation)

- 1000 equations
- Analytic Model
- $\rightarrow\,$  Gives the wing span, plane size, autonomy

### Electrical Motor (Somfy)

- 600 equations
- Analytic Model
- $\rightarrow\,$  Gives the power output, weight, heating...

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### The Standalone Software

### **Optimization Software**

- Provides a formalism for the description of the model
- Solve the optimization

### Product Designer

• Fit the problem into the software formalism

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### The Standalone Software

#### Method mastery

The software, oriented for the method allow fine tuning of the parameters for optimal use of the method.

#### Comparing methods

- Methods are adapted to specific problems (linear, nonlinear, constrained, unconstrained, ...)
- The user is not a specialist of those considerations
- He will test out several methods

#### Product designer increased workload

The problem has to be described in the formalism of each software

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### The Aggregating Software

### Optimization Expert

- Designs an optimization method
- Implements the method following the Software API

### Software

- Provide a unified problem description formalism
- Provide an API for optimization solver
- Drive the optimization process

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### Product Designer

• Fit the problem into the software formalism

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#### Product Designer

- Describe the physical model
- Describe the industrial constraints

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### The Aggregating Software

#### Product designer reduced workload

- One language to learn for all methods
- Easy comparison of methods

### Product design update

- Black box
  - Update the function and re-compile it
  - Documentation should be maintained
- Domain Specific Language
  - Easier to read, accessibility without expertise.
  - The more advanced the language capabilities, the hardest to understand.

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### Preliminary Design Concerns

#### Confusion of concerns

In preliminary design, the optimization problem definition is dvided in two parts:

- O Physical model definition (little to no variation)
- Physico-economic constraints (possibly frequent and major variations)

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### The Preliminary Design, Role-Oriented Software

Physics Expert

Describe the physical model.

### Product Sizing Engineer

Imposes physico-economic constraints

#### Software

Provide formalism and API to the different actors

### Optimization Expert

- Designs an optimization method
- Implements the method following the Software API

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### VDesign

### A suite of tools

- Analytical Editor
- Sizing Table editor
- Optimization Trace

- Computation Server
- Optimization Method API

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### Capabilities

- Provide a formalism for the Physics Expert
- Provide an environment for the Product Sizing Engineer
- Exposes an API for the Optimization Expert

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# Modeling

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Modeling			

### Natural mathematical language formal grammar

Description of the model through equations

 $\| y=a*cos(x)+b*sin(x);$ 

• No programming language artifacts (var, param, func...)

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- Explicit typing (real, matrix, complex) is optional
- Definition order not imposed
- Allows interpretation of the model
  - → Computation of exact derivatives
- Code generation

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# Sizing

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### Sizing

#### What we have

Model with named inputs and outputs.

#### Optimization Problem Definition Environment

- Meta-language (XML) for a standard description.
- Adapted edition tools
- Environment providing several optimization methods

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- Gradient based
- Evolutionary (PSO, DE)
- To be contributed

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### Optimization framework

≪Interface» 躍 Optimizer					
🏶 + optimize( problem	, trace,	logger): OptimizationControlle			

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$$\begin{array}{ll} \min_{\substack{x \in \Delta \\ \text{with} \end{array}} & f(x) \\ \text{with} & c_E(x) = 0 \\ \text{and} & c_I(x) \le 0 \end{array}$$

«Interface» 🕎 OptimizationProblem
-
<ul> <li>+ getCostFunction(): Function</li> <li>+ getDimension(): int</li> <li>+ getUpperBounds(): F</li> <li>+ getLowerBounds(): F</li> <li>+ hasGradient(): boolea</li> <li>+ hasHessian(): boolea</li> <li>+ getGradient(): Function</li> <li>+ getHessian(): Function</li> <li>+ isCSP(): boolear</li> </ul>

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### Optimization framework

### API

- Allows addition of methods with minimal workload
- One class (with one method) to implement: OptimizationProblem

• Requires comprehension of only 2 to 3 classes:

OptimizationProblem Accessors to the problem definition elements OptimizationController Handle for the optimization convergence result (success, point, value of objective)

AlgorithmLogger Trace of the process

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Interoperability			

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### Computation Server

- Originated from a request to run the optimization from an excel sheet.
- Allows a sequence of computation without stopping the environment (gain of bootstrap time)

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- Socket-based, with textual communication language.
  - $\rightarrow$  Network access
- Currently sequential version.

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### Features

#### Modeling

- cos, sin, tan, cos<sup>-1</sup>, sin<sup>-1</sup>, tan<sup>-1</sup>, atan<sup>2</sup>, cosh, sinh, tanh, cosh<sup>-1</sup>, sinh<sup>-1</sup>, tanh<sup>-1</sup>
- bessel<sup>n</sup><sub>i</sub>, bessel<sup>n</sup><sub>j</sub>, bessel<sup>n</sup><sub>k</sub>, bessel<sup>n</sup><sub>y</sub>
- abs, exp, log, pow, sqrt
- ceil, floor, round
- heaviside, if, min, max
- arg, mod, imag, real
- transpose, Id
- Complexes, Matrices

- integration (*integral*)
- ordinary differential equations (*ode*)
- implicit system (*implicit*)
- interpolation (interp)
- function optimization (*fmin*)
- find optimal point (findMinimum)
- indexed sum and product (sum, prod)
- black-box execution (exec)

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Features			

### Sizing

- All type of constraints (lower bound, upper bound, interval, equality)
- Maximization and minimization.
- Selection of decision variables
- Definition of indicative initial point

### Optimization

- Automatic differentiation of the model
- Implementations of PSO, Cobyla and VF13 optimization methods
- Logging and Reporting
- Export of optimized model, constraint definition and process trace.

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Features			

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### Symbolic Computation

API for computation of other arithmetics (i.e. interval)

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# Questions?

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