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Major substructure in the M31 Outer Halo: the East Cloud

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ABSTRACT

We present the first detailed analysis of the East Cloud, a highly disrupted diffuse stellar substructure in the outer halo of M31. The core of the substructure lies at a projected distance of ~ 100 kpc from the centre of M31 in the outer halo, with possible extensions reaching right into the inner halo. Using Pan-Andromeda Archaeological Survey photometry of red giant branch stars, we measure the distance, metallicity and brightness of the cloud. Using *Hubble Space Telescope* data, we independently measure the distance and metallicity to the two globular clusters coincident with the East Cloud core, PA-57 and PA-58, and find their distances to be consistent with the cloud. Four further globular clusters coincident with the substructure extensions are identified as potentially associated. Combining the analyses, we determine a distance to the cloud of 814_{-9}^{+20} kpc, a metallicity of $[\text{Fe}/\text{H}] = -1.2 \pm 0.1$, and a brightness of $M_V = -10.7 \pm 0.4$ mag. Even allowing for the inclusion of the potential extensions, this accounts for less than 20 per cent of the progenitor luminosity implied by the luminosity–metallicity relation. Using the updated techniques developed for this analysis, we also refine our estimates of the distance and brightness of the South-West Cloud, a separate substructure analysed in the previous work in this series.

Key words: galaxies: individual: M31 – Local Group – galaxies: stellar content.

1 INTRODUCTION

The study of galactic formation and evolution through the identification of fossil remnants, also known as galactic archaeology, is critical to building our understanding of the universe. A key part of this, according to standard Λ CDM theory, is hierarchical structure formation, the process of accretion by which galaxies merge and grow to form ever larger structures. The long dynamical time-scales in the outer regions of galactic haloes mean that they act as historical records of their long accretion history. Major mergers, violent events which erase the visible history of the galaxy, are key processes to galactic formation. However, by studying the many smaller accretions still visible in the outer halo, we can piece together the history of the Local Group. This provides data critical to modelling

structure formation, thus helping to gain a greater understanding of the underlying processes.

The Andromeda galaxy (M31), our nearest large neighbour, is a reasonable analogue for our own galaxy, and offers a panoramic view unavailable in the Milky Way. A tremendous amount of effort has already gone into the analysis of M31. Extensive deep optical surveys such as the Pan-Andromeda Archaeological Survey (PAndAS; McConnachie et al. 2009) and the Spectroscopic and Photometric Landscape of Andromeda’s Stellar Halo (SPLASH) survey (Gilbert et al. 2012) have enabled the analysis of the various components which make up the galactic halo in unrivalled detail, including the bulk properties of the stellar halo itself (e.g. Ibata et al. 2014). Many new dwarf galaxies have been discovered (e.g. Martin et al. 2013), bringing the current total for M31 dwarf spheroidals up to 33, and the large homogeneous data coverage has enabled consistent comparison of their properties (e.g. McConnachie 2012; Martin et al., in preparation).

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The globular cluster (GC) population consists of well over 500 confirmed GCs (see the Revised Bologna Catalogue, Galleti et al. 2004), including almost a hundred outer halo objects (Veljanoski et al. 2013 and references therein; Huxor et al. 2014a). The outer halo GCs are preferentially spatially coincident with diffuse stellar substructures, with a chance alignment of this significance of less than 1 per cent (Mackey et al. 2010; Veljanoski et al. 2014).

Studies of diffuse stellar substructures in M31 have tended to focus on inner halo features, such as the north eastern shelf, the northern spur, the G1 clump, and the giant stellar stream (e.g. Ferguson et al. 2005; Faria et al. 2007; Richardson et al. 2008; Bernard et al. 2015). However, key properties of the halo such as the bulk rotation of the GC population (Veljanoski et al. 2014), or the plane of dwarf galaxies (Conn et al. 2013; Ibata et al. 2013), which itself exhibits consistent rotation, could only be uncovered by doing a complete analysis of the halo. Thus, it is critical that we complete the analysis of the major substructures in the outer halo.

In Bate et al. (2014), hereafter [Paper I](#), we presented the first detailed analysis of a diffuse stellar substructure in the outer halo of M31, the South-West Cloud (SWC), determining its progenitor to be amongst M31's brightest dwarf galaxies prior to disruption. We concluded that at least one of the three GCs coincident with the SWC is associated with the SWC (Gilbert et al. 2012), with a second association confirmed by a follow-up in Mackey et al. (2014). Here, we present the results of an analogous analysis of a similarly significant substructure located on the opposite side of M31 (in projection), dubbed the East Cloud (Lewis et al. 2013). We also apply improved and new techniques to reanalyse the properties of the SWC throughout.

In Section 2, we discuss the PAndAS data and contamination model used throughout this paper. Section 3 contains contamination-corrected stellar density maps of the regions around the SWC and East Cloud, while also showing the locations of the nearby GCs. In Section 4, we use a Bayesian technique to measure the magnitude of the tip of the red giant branch (TRGB), and so estimate a distance to the East Cloud. The TRGB technique simultaneously fits for metallicity, and is described in full in a companion paper (Conn et al., submitted). In Section 5, we use two methods for estimating the present day luminosity of both the East Cloud and the SWC. The ‘Dwarf Method’ is an improved version of the technique we used in [Paper I](#), which is calibrated against the many dwarf galaxies present in the PAndAS data. For the new ‘Population Method’, we introduce ‘flux chains’ developed in a companion paper (Martin et al., in preparation), spatially resolved forward modelled colour-magnitude diagram (CMD) fits to the PAndAS data for a collection of single stellar populations and a contamination population.

In Section 6, we measure stellar metallicities by comparing them to theoretical isochrones for ancient RGB stars at the distance of M31. This metallicity is compared with the estimate from the TRGB method for consistency. Using *Hubble Space Telescope* (HST) data, we present the detailed analysis of the GCs in Section 7. By fitting templates to the two GCs coincident with the largest East Cloud overdensity, we are able to estimate their distances and metallicities. Finally, we discuss the implications of these measurements and conclude in Section 8.

Throughout this paper, we assume the distance modulus to M31 to be $(m - M)_0 = 24.46 \pm 0.05$, or 779_{-18}^{+19} kpc (Conn et al. 2012).

2 PANDAS DATA

As discussed in [Paper I](#), the photometry of M31 used in this paper was obtained as part of the PAndAS Large Program on the 3.6-metre

Canada–France–Hawaii Telescope. Using the 0.96×0.94 deg² field of view MegaPrime camera, *g*- and *i*-band imaging was taken of M31 and M33, out to distances of approximately 150 and 50 kpc, respectively, with a total area of more than ~ 390 deg².

A description of the PAndAS survey can be found in McConnachie et al. (2009), with full details of the data reduction and a public release of the data in forthcoming publications (Ibata et al. 2014; McConnachie et al., in preparation). To summarize, all observations were taken in generally excellent seeing conditions ($\lesssim 0.8$ arcsec), with a mean seeing of 0.67 arcsec in *g* band and 0.60 arcsec in *i* band. The median depth is $g = 26.0$ mag and $i = 24.8$ mag (5σ).

The images were preprocessed by CFHT staff using their ELIXIR pipeline, before being processed using a version of the CASU photometry pipeline (Irwin & Lewis 2001) adapted for CFHT/MegaPrime observations. The resulting catalogue contains a single photometrically-calibrated *g*, *i* entry for each detected object (see [Paper I](#) for more detail).

For this work, we use all objects in the final catalogue that have been reliably classified as stars in both bands (aperture photometry classifications of -1 or -2 in both *g* and *i*, which corresponds to point sources up to 2σ from the stellar locus). The CFHT instrumental magnitudes *g* and *i* are converted to dereddened magnitudes g_0 and i_0 on a source-by-source basis, using the following relationships from Schlegel, Finkbeiner & Davis (1998): $g_0 = g - 3.793E(B - V)$ and $i_0 = i - 2.086E(B - V)$.

Despite every effort to systematically cover the PAndAS survey region, holes do occur at the location of bright saturated stars, chip gaps, and a few failed CCDs. These holes have been filled with fake stars by duplicating information from nearby regions (for details, see Ibata et al. 2014). The fake entries are utilized to construct smooth stellar density maps, but are otherwise excluded from our calculations.

2.1 Contamination model

Three sources of contamination in the PAndAS data set can affect our study of substructure in the M31 outer halo: foreground Milky Way stars, unresolved compact background galaxies, and M31 halo stars. We account for this contamination using a model developed empirically from the PAndAS data in Martin et al. (2013). In this model, the density of contaminants Σ at a given location (ξ, η) and a given colour and magnitude $(g_0 - i_0, i_0)$ is given by a three component exponential:

$$\Sigma_{(g_0-i_0, i_0)}(\xi, \eta) = \exp(\alpha_{(g_0-i_0, i_0)}\xi + \beta_{(g_0-i_0, i_0)}\eta + \gamma_{(g_0-i_0, i_0)}). \quad (1)$$

The coordinates (ξ, η) in this model, and throughout this paper, are a tangent-plane projection centred on M31. The contamination model is defined over the colour and magnitude ranges $0.2 \leq (g_0 - i_0) \leq 3.0$ and $20 \leq i_0 \leq 24$. This model allows us to generate a CMD for contamination at any location in the PAndAS footprint. From these contamination CMDs, we can generate contamination luminosity functions and stellar densities for any region of the PAndAS survey. For full details, see Martin et al. (2013).

3 STELLAR DENSITY MAPS

In [Fig. 1](#), we show a contamination-subtracted stellar density map in tangent-plane projection centred on M31 for the entire PAndAS region. Stars in this map were chosen to be consistent with metal-poor RGB populations at the distance of M31, using a colour–magnitude box defined by the following $(g_0 - i_0, i_0)$ vertices: (0.4, 23.5),

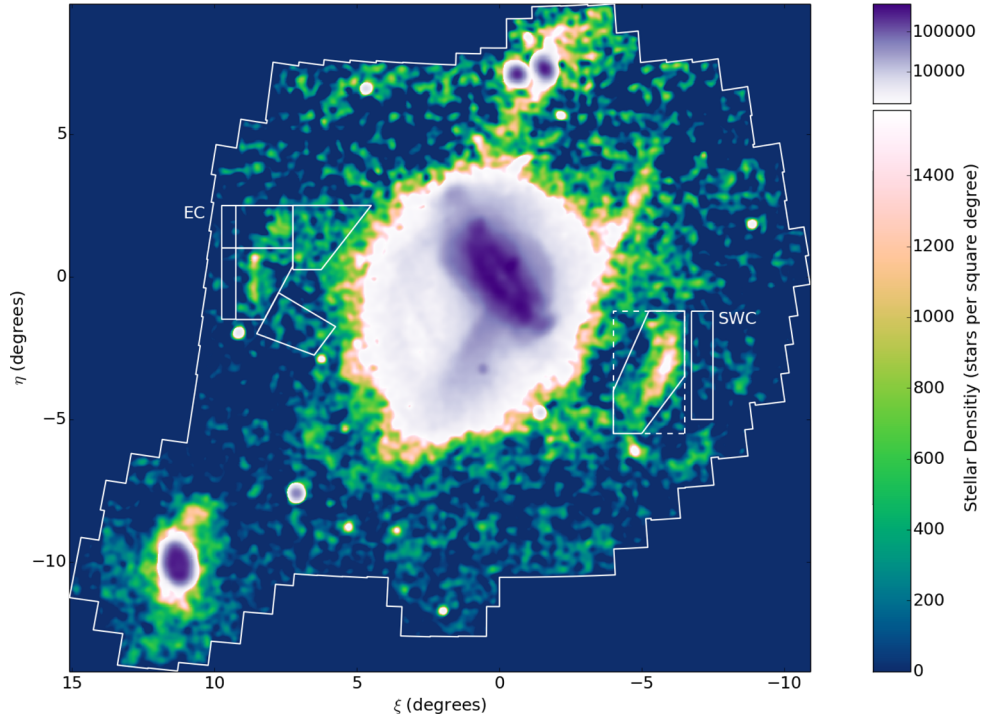


Figure 1. Stellar density map of PAndAS stars with dereddened colours and magnitudes consistent with metal-poor RGB populations at the distance of M31. Pixels are $0.025^\circ \times 0.025^\circ$, and the map has been smoothed using a Gaussian with a dispersion of $\sigma = 0.1^\circ$. It is displayed in tangent-plane projection centred on M31, with scaling chosen to highlight the East Cloud and SWC. This map has been foreground contamination-subtracted, as in Paper I (see Martin et al. 2013 for full details). This and all subsequent colour maps in this paper were generated using the ‘cubehelix’ scheme (Green 2011).

(0.7, 20.9), (2.3, 20.9), (1.6, 23.5). This captures the approximate metallicity range $-2.5 < [Fe/H] < -1.0$. The map is plotted on $0.025^\circ \times 0.025^\circ$ pixels, and smoothed with a Gaussian with dispersion $\sigma = 0.1^\circ$.

The white boundaries mark the target fields, and where relevant their corresponding contamination fields. The focus of this paper, the East Cloud, is marked by the fields on the left of M31. Since Paper I, we have improved our techniques and developed new methods for brightness and distance estimation, so for consistency we also reanalyse the SWC, marked by the fields on the right of M31. These fields and their various subfields are shown in more detail in Figs 2 and 3.

The SWC is made up of a single large cloud, with what looks like an extension to the South-East, as was discussed in Paper I. The East Cloud is even more disrupted, with a dominant cloud in the Southern field East Cloud South (ECS), with a detached cloud to the North in East Cloud North (ECN). The South-West and North-West show potential extensions in fields East Cloud South-West (ECSW) and East Cloud North-West (ECNW), respectively, forming a single large arc running through the four East-Cloud fields.

For this paper, we focus on the main populations marked ECS and ECN, as the extensions are difficult to separate from the rest of the M31 population due to both their proximity to M31 and their very low surface brightness. The remaining fields ECSBG, ECNBG, and SWCBG are used for contamination estimation for one of the brightness estimation methods. These fields were chosen for their proximity to their corresponding target fields ECS, ECN, and SWC, while avoiding obvious substructure, and giving a good representation of the full extent of the Galactic latitude the target fields encompass (represented by the η coordinate).

There are six GCs in the vicinity of the East Cloud (Huxor et al. 2014a), marked in Fig. 2. All six appear to lie along the arc made

by the East Cloud substructure, and the two GCs PAndAS-57 and PAndAS-58 lie very close in projection to the densest part of the substructure.

While stellar membership for dwarf galaxies is typically modelled by radial density profile, the structures we are interested in are so disrupted that this is not feasible. Instead, we use stellar density relative to the peak density in the target field.

For the purposes of this paper, we use the relative stellar density maps smoothed with the 0.10° dispersion Gaussian kernel as a method for determining membership probability. This dispersion was chosen to give a clear view of the connected region around each target. Stars are assigned a probability p for membership in a target equal to the stellar density in the pixel in which they fall. This probability is scaled relative to the peak in the target field, such that a star lying in the peak density pixel has a membership probability of $p = 1$.

Thus, the relative stellar density maps for the East Cloud and the SWC, shown in Figs 2 and 3, can be used as membership probability maps; however, these membership probabilities should only be taken seriously within fields ECS, ECN, and SWC. These maps are primarily used for distance estimation, but are also used to establish membership cutoffs for brightness and metallicity estimates. The cutoff used is a scaled stellar density of 0.25 of the target maximum (marked by a contour in the Figures).

4 DISTANCES

Here, we estimate the distance to the East Cloud utilizing the entirety of the combined fields ECS and ECN. For this estimate, we employ the TRGB standard candle, determined by a model fitting technique as introduced in Conn et al. (submitted). In summary, the method fits a three-dimensional surface to the CMD of the combined

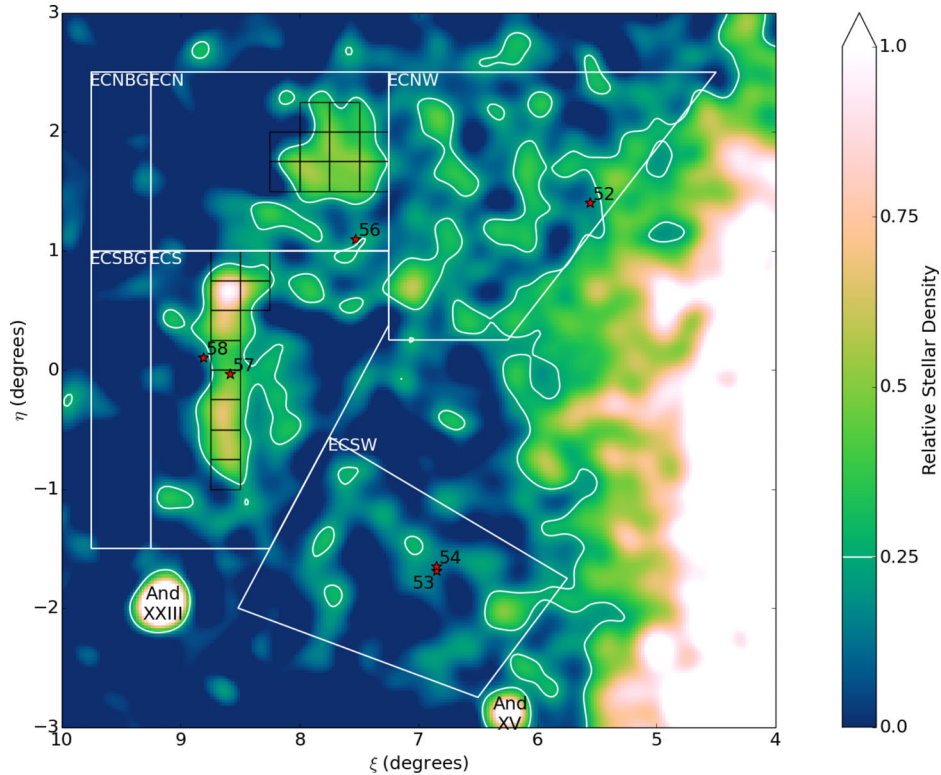


Figure 2. Map of East Cloud contamination-subtracted relative stellar density. Pixels are $0.025^\circ \times 0.025^\circ$, and have been smoothed with a Gaussian with 0.10° dispersion. The colour gradient is scaled relative to the peak in the main body of the East Cloud subfields (which lies in ECS), with contours at a relative density of 0.25 (white). The positions of known GCs in the region are marked with red stars. The flux chain pixels used for surface brightness estimation have been outlined in black (see Section 5.1). The white boundaries mark four separate EC fields, and the two background fields used for the primary EC fields. The small bright overdensities to the South-East and South-West are the dwarf galaxies AndXXIII and AndXV, respectively.

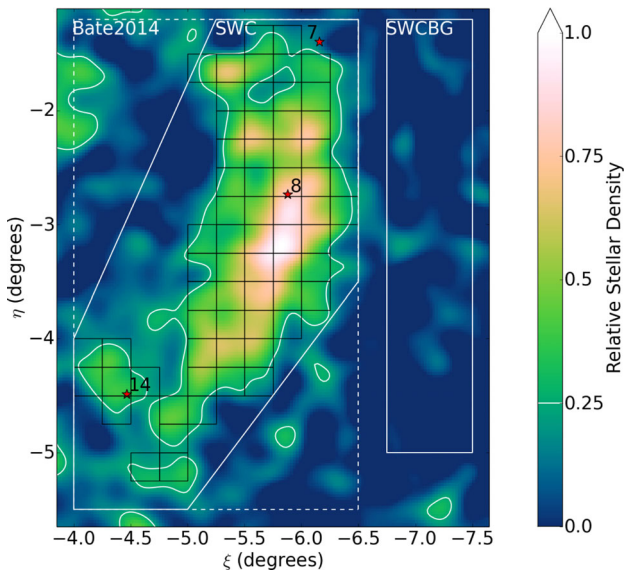


Figure 3. Map of South-West Cloud contamination-subtracted relative stellar density. Pixels are $0.025^\circ \times 0.025^\circ$, and have been smoothed with a Gaussian with 0.10° dispersion. The colour gradient is scaled relative to the peak in the main body of the SWC, with contours at a relative density of 0.25 (white). The positions of known GCs in the region are marked with red stars. The flux chain pixels used for surface brightness estimation have been outlined in black (see Section 5.1). The white boundaries mark the original SWC field used by Bate et al. (2014, dashed), the tighter SWC field used by this work (solid), and the background field for the SWC.

stellar population, modelling the stellar density at a given magnitude and colour as the sum of a RGB component and a contamination component.

The RGB component is modelled as an isochrone grid, using theoretical isochrones from the Dartmouth Stellar Evolution Database (Dotter et al. 2008). The metallicity range spanned by the grid is weighted by a Gaussian profile, such that isochrones at the centre of the Gaussian receive the highest weighting. We equate the centre of the Gaussian with the best-fitting metallicity of the structure’s RGB, while the width of the Gaussian we shall refer to as the RGB width, which is distinct from the metallicity spread as calculated in Section 6. The isochrones are shifted along the magnitude axis to find the best-fitting location of the TRGB.

We fix the age of the isochrone grid at 13 Gyr for our East Cloud (and SWC) measurements as is the case throughout this contribution. The contamination component is a Hess diagram generated for the location of the East Cloud within the PAndAS survey area, as outlined in Martin et al. (2013). The ratio of the RGB component to the contamination component is then an additional fitted parameter. The method is essentially a two-dimensional extension of the Luminosity Function fitting algorithm introduced in Conn et al. (2011) and Conn et al. (2012).

In order to model the photometric uncertainty in the PAndAS data, we convolve the model CMD generated as described above with a two-dimensional Gaussian kernel using an approximated uncertainty in both i and g bands of 0.015 mag. While the uncertainty in our fitted magnitude range varies from ~ 0.005 to 0.035, the 0.015 mag used is a good approximation to the expected uncertainty within the region we expect to find the TRGB. With regard to blending,

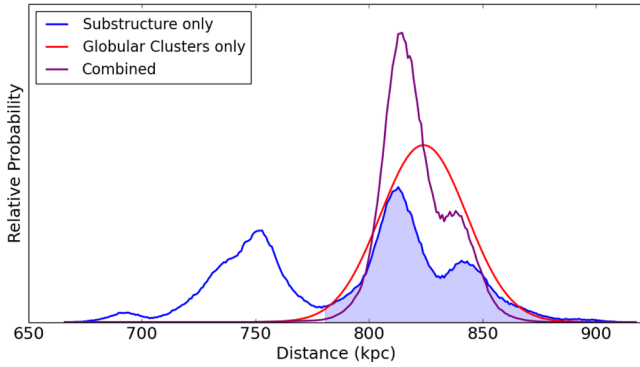


Figure 4. Probability distributions for the distance to the East Cloud. The probability distribution as determined from the combined fields ECS and ECN using the TRGB standard candle is plotted in blue. The distribution determined from the HB of the GCs PA-57 and PA-58 is plotted in red (see Section 7). The purple distribution is the multiplication of these two distributions, yielding our best-fitting distance measurement to the East Cloud of 814^{+20}_{-9} kpc. The shaded region in blue indicates the region taken for a more restrictive measurement, guided by the combined fit.

we have found that it is only an issue where the stellar density is very high, such as in the centres of some of M31’s larger dwarf spheroidal satellites. Overcrowding of this kind is not an issue in any of the structures presented in this contribution. Likewise, data incompleteness is not an issue for the fitted magnitude range, with the survey reaching a depth of some two to three full magnitudes deeper than our cutoff.

Due to the very low contrast of the East Cloud (a contamination in excess of 98 per cent is determined by our TRGB fitting algorithm), we obtain a very broad, multiple peaked probability distribution in the TRGB, indicating that the algorithm is heavily influenced by a small number of stars in the region of the tip. This probability distribution appears in Fig. 4 in blue.

The distance measurement obtained for the GCs PA-57 and PA-58 in Section 7 is represented by the red Gaussian. Since deeper photometry was available for this measurement, it was possible to utilize the horizontal branch (HB) as a standard candle – which is much better populated than the region of the TRGB, hence the tighter distance constraints. Nevertheless, in multiplying the two distributions together (the purple distribution in Fig. 4), we are able to provide a further constraint on the distance, assuming the association of the GCs. From this distribution, we find a best-fitting distance to the structure of 814^{+20}_{-9} kpc.

Additionally, we obtain a best-fitting metallicity of $-1.4^{+0.2}_{-0.1}$ dex and a best-fitting RGB width of 0.3 ± 0.1 dex. Restricting the distance probability distribution to the broad peak consistent with the PA-57/PA-58 measurement (the blue shaded region in Fig. 4) has little effect except to reduce the uncertainty, yielding a best-fitting metallicity of -1.4 ± 0.1 dex while the best-fitting RGB width is unchanged. The best-fitting model produced by the TRGB algorithm is shown in Fig. 5. The distance of the East Cloud from the centre of M31 is estimated at 111^{+13}_{-1} kpc, or alternatively 119^{+14}_{-4} kpc, if the restricted fitted range is taken.

In addition to the East Cloud, we also apply the new method outlined in Conn et al. (submitted) to the SWC, with the best-fitting model shown in Fig. 6. Via this method, we determine a distance to the cloud as a whole of 757^{+9}_{-30} kpc. This is consistent with the results recently published in Bate et al. (2014), where a TRGB distance of 793^{+45}_{-45} kpc was estimated. This new distance corresponds to a distance from the centre of M31 of 85^{+7}_{-1} kpc. Additionally, we

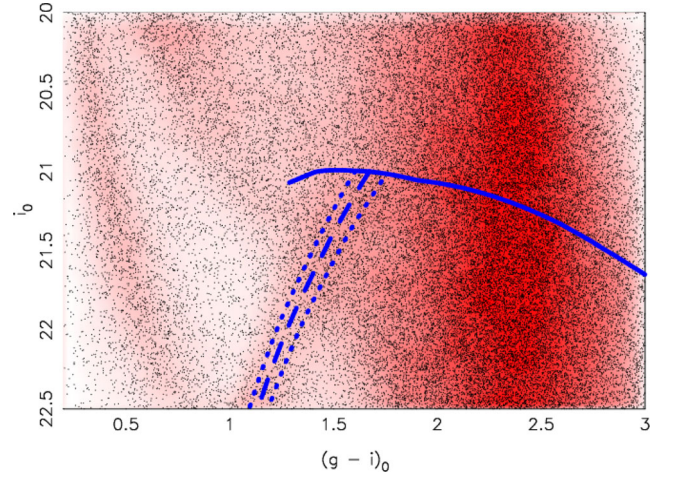


Figure 5. Best-fitting model generated by the TRGB algorithm for the East Cloud. The model height (density) as a function of magnitude i_0 and colour $(g_0 - i_0)$ is indicated by the shade of red at that location. The observed stars are marked by black dots. An isochrone representing the best-fitting central metallicity of the data is shown as a blue dashed line. The blue dotted lines on either side are representative of the RGB width – they do not represent the uncertainty in the best-fitting metallicity value. The solid blue line denotes the magnitude of the TRGB as a function of colour.

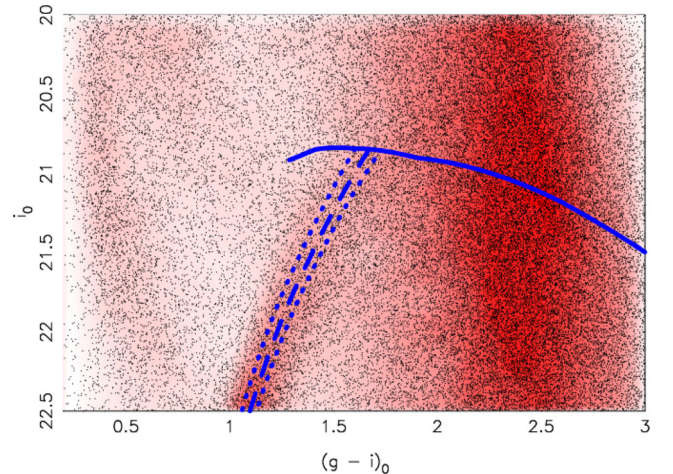


Figure 6. Best-fitting model generated by the TRGB algorithm for the SWC. The model height (density) as a function of magnitude i_0 and colour $(g_0 - i_0)$ is indicated by the shade of red at that location. The observed stars are marked by black dots. An isochrone representing the best-fitting central metallicity of the data is shown as a blue dashed line. The blue dotted lines on either side are representative of the RGB width – they do not represent the uncertainty in the best-fitting metallicity value. The solid blue line denotes the magnitude of the TRGB as a function of colour.

determine a metallicity of -1.4 ± 0.1 dex which is in keeping with the -1.3 ± 0.1 dex estimated by Bate et al. (2014). As for the East Cloud, we find a relatively narrow RGB width, with a best-fitting value of 0.3 ± 0.1 dex proposed by our algorithm.

5 BRIGHTNESS

Here, we present brightness estimates for the main substructures of the East Cloud in ECS and ECN. We also analyse the SWC, both as a consistency check, and to update our estimate from Paper I, using the techniques developed for this analysis. Two different methods are used to reconstruct the brightness of these substructures. The

first method, which we call ‘the Dwarf Method’, is an improvement upon the method used in [Paper I](#), and uses the PAndAS data directly. The second method, which we call ‘the Population Method’, uses spatially resolved forward modelled single stellar population fits to the PAndAS data, which we call ‘flux chains’, detailed in Section 5.1. We discuss the methods in detail in Section 5.2, and present our total brightness estimates. Surface brightness estimates are discussed in Section 5.3.

5.1 Flux chains

In a companion paper (Martin et al., in preparation), we perform the forward modelling of the PAndAS CMDs for every 15×15 arcmin² pixel in the survey footprint. For a given pixel, the CMD is modelled as the contamination CMD expected for this location, as defined by Martin et al. (2013), combined with the sum of 23 simple stellar populations. These stellar populations are at the distance of M31 [$m - M$]₀ = 24.46], with an age of 13 Gyr, and with metallicity [Fe/H] that varies between -2.3 and -0.1 in 0.1 dex increments. These stellar populations are based on the PARSEC isochrones (Bressan et al. 2012) and luminosity functions for a Kroupa (2001) initial mass function (IMF).

The number of stars per component of the model (the contamination and the 23 simple stellar populations) within the M31 RGB region is inferred through a Markov Chain Monte Carlo approach by enforcing that they are strictly positive, that the number of stars in the contamination component follows a Poissonian prior centred around the number of stars expected in the Martin et al. (2013) model, and that the total number of stars in the pixel has a Poissonian prior centred on the observed number of stars in the CMD selection box for this pixel.

In an additional step, for each simple stellar population, the resulting numbers of stars within the CMD selection box are converted into surface brightnesses in the g and i bands through the determination of the fraction of flux contained in the selection box for the given stellar population (see fig. 1 of Martin et al. 2013 for the location of this selection box). A given chain produced by the algorithm therefore contains a sampling of the 24-parameter probability density function of surface brightnesses for the 23 simple stellar populations as well as the contamination component of the model, which we consider as a nuisance parameter for the current analysis.

Stellar density maps built from these flux chains, for the regions corresponding to Figs 2 and 3, are shown in Figs 7 and 8. For these figures, the flux chains are grouped into three metallicity populations, $-2.3 \leq [\text{Fe}/\text{H}] \leq -1.5$ (low/blue), $-1.4 \leq [\text{Fe}/\text{H}] \leq -1.0$ (intermediate/green), and $-0.9 \leq [\text{Fe}/\text{H}] \leq -0.2$ (high/red). The substructures we are interested in are most dominant in the intermediate range, so show up in the maps as a green haze. Near the East Cloud, some dwarf galaxies are clearly visible in blue, and the inner halo is also visible as a red glow to the West. The metallicity of the East Cloud will be discussed in more detail in Section 6.

The pixels are quite large compared to the maps in Section 3, and thus we can only approximate the regions selected by the 25 per cent membership probability contour. The pixels selected to correspond to this region are outlined in black in both Figs 2 and 3, and Figs 7 and 8.

5.2 Total brightness

Both methods for estimating the brightness convert the CFHT g - and i -band photometry, in which the PAndAS data were taken and

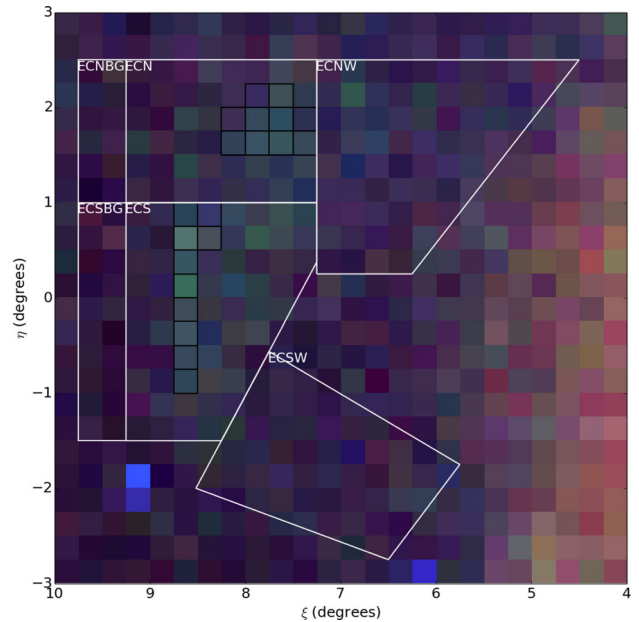


Figure 7. Map of the East Cloud flux based on the chains discussed in Section 5.1. Pixels are $0.25^\circ \times 0.25^\circ$. The populations are split into three metallicity ranges, $-2.3 \leq [\text{Fe}/\text{H}] \leq -1.5$ (low/blue), $-1.4 \leq [\text{Fe}/\text{H}] \leq -1.0$ (intermediate/green), and $-0.9 \leq [\text{Fe}/\text{H}] \leq -0.2$ (high/red). The flux chain pixels used for surface brightness estimation have been outlined in black. The white boundaries are as in Fig. 2. The bright blue overdensities to the South-East and South-West are the dwarf galaxies AndXXIII and AndXV, respectively.

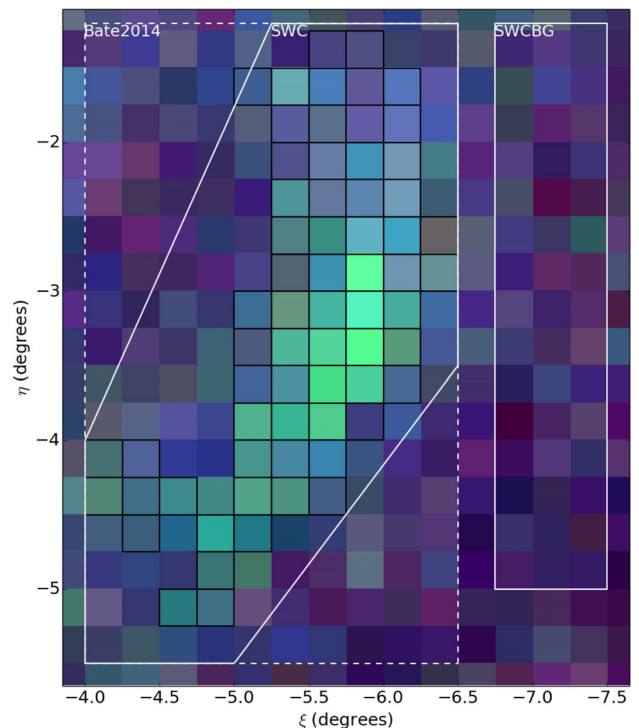


Figure 8. Map of the SWC flux based on the chains discussed in Section 5.1. Pixels are $0.25^\circ \times 0.25^\circ$. The populations are split into three metallicity ranges, $-2.3 \leq [\text{Fe}/\text{H}] \leq -1.5$ (low/blue), $-1.4 \leq [\text{Fe}/\text{H}] \leq -1.0$ (intermediate/green), and $-0.9 \leq [\text{Fe}/\text{H}] \leq -0.2$ (high/red). The flux chain pixels used for surface brightness estimation have been outlined in black. The white boundaries are as in Fig. 3.

Table 1. Apparent magnitude estimates.

Target	Dwarf Method	Population Method
SWC	12.6 ± 0.3	13.1 ± 0.2
ECS	13.8 ± 0.4	14.3 ± 0.3
ECN	14.3 ± 0.5	14.8 ± 0.3
ECS and ECN	13.3 ± 0.4	13.8 ± 0.3

the flux chains were generated, into the V band using the following colour transform (Ibata et al. 2007):

$$V_0 = \begin{cases} -0.033 + 0.714(g_0 - i_0) + i_0, & (g_0 - i_0) < 1.850, \\ -0.480 + 0.956(g_0 - i_0) + i_0, & (g_0 - i_0) \geq 1.850, \end{cases}$$

The first method is an improvement upon the method used in Paper I. We call this new method ‘the Dwarf Method’. We define a target region within the tangent plane projection of M31 and then select all stellar entries from the PAndAS catalogue with colours and magnitudes consistent with metal-poor RGB populations at the distance of M31, using the same colour–magnitude selection box as in Section 3. Due to the disrupted nature of the SWC and EC structures, rather than using a radial boundary, we include all stars with a membership probability $p \geq 0.25$ (following Paper I). This cutoff is marked by a contour in Figs 2 and 3, specifically for the target regions SWC, ECS, and ECN.

A luminosity function is built for the target from the stars within the contour. A Poisson deviate n is randomly selected from the Poisson distribution with mean value N , where N is the number of stars used to build the luminosity function. The luminosity function is then sampled n times to get an initial estimate of the target flux. Stars outside this contour are used to define the contamination for each target. A flux estimate is produced for the local contamination similarly, which is used to correct the target flux estimate. This process is repeated 10^4 times to estimate the total flux of the target.

In order to correct for unresolved light, we measure the brightness of available Andromeda dwarf galaxies within the PAndAS footprint, and calibrate against their V -band brightnesses listed in McConnachie (2012). This process is covered in detail in Paper I and remains largely unchanged, still resulting in a final calibration by a factor of -1.9 ± 0.2 mag. The results from this method are summarized in Table 1.

The second method, let us call this ‘the Population Method’, uses the single stellar population chains from Martin et al. (in preparation) discussed in Section 5.1. Using the same target regions from the first method, we select which pixels to sample chains from. For a particular entry in the chains, we sum the fluxes of all the pixels in the target for each population.

As the chains do not allow a negative contribution from any of the populations, there is a small statistical positive bias that results in slightly higher counts in pixels with small numbers of stars. In addition to this, there is a small positive bias towards very metal poor populations ($[\text{Fe}/\text{H}] \leq -2.0$) for the East Cloud fields, due to an overlapping blue population from the PAndAS Milky Way Stream (Martin et al. 2014) which is not included in the smooth contamination model. However, this is of little concern as both the SWC and EC objects contain a negligible number of stars of such low metallicity (see Fig. 9 in the next section).

To ensure that the contamination has been completely removed, and account for the positive bias, we select adjacent visually empty regions around the targets to estimate the local contamination flux contribution, see Figs 7 and 8. The results from this method are summarized in Table 1.

Table 2. Absolute magnitude estimates.

Target	Magnitude
SWC	-11.3 ± 0.3
ECS	-10.2 ± 0.4
ECN	-9.7 ± 0.4
ECS and ECN	-10.7 ± 0.4

Table 3. Surface brightness estimates.

Target	Dwarf Method	Population Method
SWC	31.8 ± 0.3	31.7 ± 0.6
ECS	31.6 ± 0.4	32.8 ± 0.2
ECN	31.6 ± 0.5	33.2 ± 0.2
ECS and ECN	31.6 ± 0.4	33.0 ± 0.2

While the results from the two methods shown in Table 1 are consistent, there is a 0.5 mag systematic offset between them. This indicates that the -1.9 mag correction factor used in the Dwarf Method may be too large by 0.5 mag. This offset is not entirely surprising, as this adjustment matches the SWC and EC structures to Andromeda’s dwarf galaxy population, which are much less extended and disrupted. The Population Method does not require any such adjustment factor, instead using population fits to the PAndAS data directly. Assuming that the weak link is the -1.9 mag correction used in the Dwarf Method, and applying adjustments based on the distances in Section 4, gives the absolute magnitude estimates shown in Table 2. We have attributed the 0.5 mag systematic offset to the Dwarf Method correction factor; however, it is worth noting that this value could be indicative of possible systematic errors for Population Method.

Although both methods use the PAndAS data, they approach the problem of brightness estimation from very different angles, so the fact that they produce such consistent results, not just for the East Cloud but also for the SWC, bolsters confidence.

5.3 Surface brightness

To calculate the surface brightness, the Dwarf Method assumes the area of the object to be that contained within the contour representing 25 percent of the peak stellar density, shown in Figs 2 and 3. The large pixel size used in the Population Method makes surface brightness estimation difficult for such small objects, but pixels corresponding to this contour were selected manually to best approximate the region.

The results of the two methods for computing surface brightness are consistent for the SWC; however, due to the extreme faintness of the EC structures, consistent results are not recovered for the EC; the results are summarized in Table 3. Each method is prone to different issues for such small faint structures as the EC. The Dwarf Method suffers significantly trying to estimate the surface brightness of the EC, as the contamination in this region is very strong, suggesting that a population fitter would fare much better. Unfortunately, the Population Method suffers as well due to the small size of the structure. As the pixel size used in the Population Method is quite large (a necessity to get reasonable signal for the fit), it makes the estimation of the area within such a specific and small contour very inaccurate. The true value of the surface brightness of these structures is likely to sit between the results of the two methods. It remains that both structures have very low surface brightness, around 32 magnitudes per square arc second.

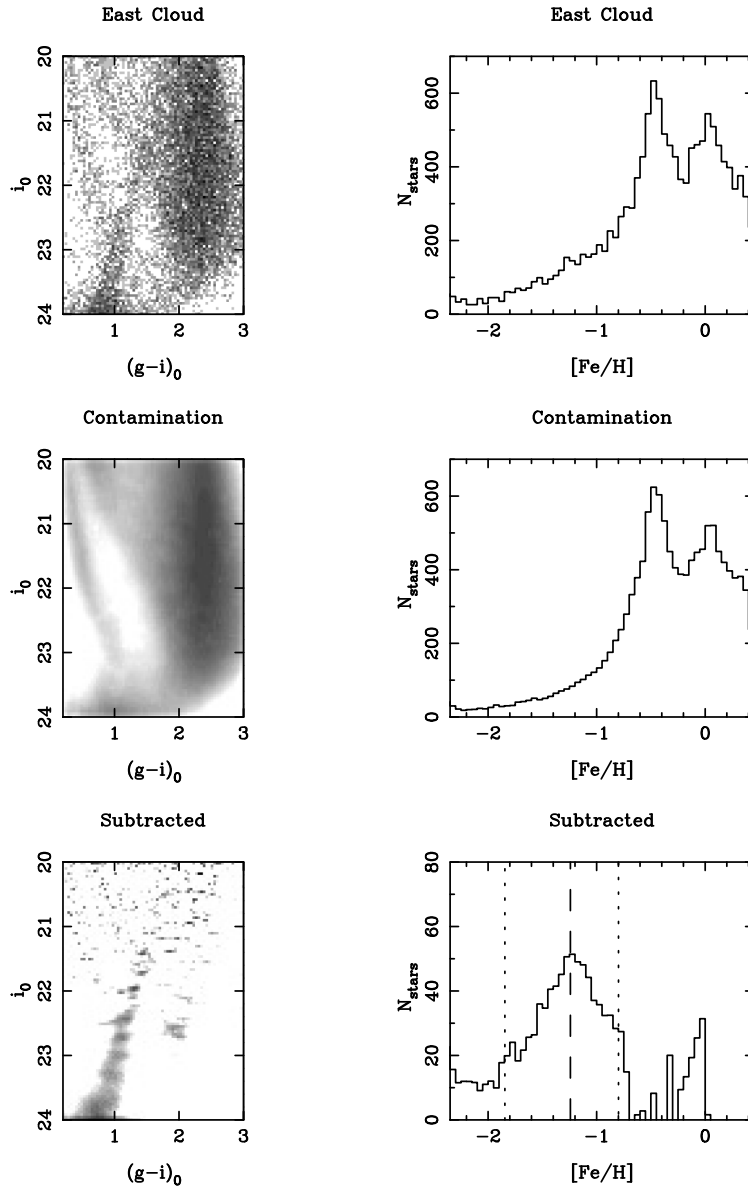


Figure 9. Left: Hess diagrams for the East Cloud (top), the contamination model for the same region (middle), and the Monte Carlo sampled residual of the East Cloud minus the contamination (bottom). The Hess diagrams are displayed with logarithmic scaling, and contain only stars with a membership probability $p \geq 0.25$. Right: MDF generated using The Dartmouth Stellar Evolution data base 2012 isochrones for a 13 Gyr population with $[\alpha/H] = 0.0$ (Dotter et al. 2008), and assuming a distance to the East Cloud of 814 kpc. In the bottom-right panel, the median is marked by a dashed line, and the dotted lines contain 68 per cent of the distribution.

6 METALLICITIES

Using the TRGB method in Section 4, we estimated the metallicity of the East Cloud to be $-1.4^{+0.2}_{-0.1}$ dex. Here, we use the technique from Paper I to estimate the metallicity, to ensure a consistent comparison between the East Cloud and the SWC.

We estimate metallicities for the stars in the East Cloud by comparison with theoretical isochrones from the Dartmouth Stellar Evolution Database (Dotter et al. 2008). We restrict ourselves to isochrones with a 13 Gyr age, $[\alpha/Fe] = 0.0$, and metallicity $-2.5 \leq [Fe/H] \leq 0.5$ in 0.05 dex steps. Dartmouth isochrones are available in CFHT/MegaCam filters, so no filter transformations are necessary.

Isochrones are shifted to the best-fitting East Cloud distance discussed in Section 4, 814 kpc. The dereddened $g_0 - i_0$ colours and

i_0 magnitudes of each individual star are compared to the grid of isochrones, and each star is assigned the metallicity of the nearest isochrone. Stars further than 0.05 in colour or magnitude from any isochrone are excluded. Furthermore, we use only stars in regions ECS and ECN (see Fig. 2), with membership probabilities $p \geq 0.25$, as defined in Section 3.

In this way, we are able to build up metallicity distribution functions (MDFs) for East Cloud stars. In the top panels of Fig. 9, we show the results of this process: the left-hand panel shows a Hess diagram for stars with East Cloud membership probability $p \geq 0.25$, and the right-hand panel shows the resulting MDF.

As we have already seen, the East Cloud is heavily affected by foreground contamination. To account for this, we use the contamination model presented in Martin et al. (2013). As described in

Bate et al. (2014), we use this model to construct Hess diagrams and an MDF for the foreground contamination in East Cloud pixels above the membership probability cutoff. The contamination model is shown in the middle panels of Fig. 9. We note that in order to use the contamination model, we must restrict ourselves to the following colour and magnitude ranges: $0.2 \leq (g_0 - i_0) \leq 3.0$, $20 \leq i_0 \leq 24$.

The contamination-subtracted Hess diagram and MDF are shown in the bottom panels of Fig. 9. There is a clear peak in the MDF at $[\text{Fe}/\text{H}] \sim -1.2$, which we identify as the East Cloud.

The median metallicity we measure for the East Cloud is $[\text{Fe}/\text{H}] = -1.2 \pm 0.1$. This measurement takes into account errors in stellar magnitudes by Monte Carlo sampling the PAndAS catalogue 1000 times, and uncertainty in the estimated East Cloud distance determined in the previous section. As expected, this measurement is consistent with the result obtained from the distance measurement technique in Section 4, which used the same isochrone set.

As in Bate et al. (2014), we measure the error-corrected standard deviation of the metallicity distribution, which we call the metallicity spread. This is calculated by treating photometric errors as metallicity differences $\Delta[\text{Fe}/\text{H}]$, and then Monte Carlo sampling 1000 times to build up an average $\Delta[\text{Fe}/\text{H}]$ distribution. The width of this distribution gives us the contribution of the photometric errors to the observed metallicity spread. When subtracted in quadrature, we obtain an intrinsic metallicity spread of 0.58 ± 0.03 . We also repeated our analysis using tighter RGB colour–magnitude cuts (see Section 3); the median metallicity is unchanged, however the metallicity spread is marginally smaller.

7 GLOBULAR CLUSTERS

Two M31 GCs have positions that project on to the main body of the East Cloud – these are PA-57 and PA-58 (see Huxor et al. 2014b). These clusters also share closely matching radial velocities that are separated from the M31 systemic velocity by $\sim 100 \text{ km s}^{-1}$. The apparent spatial coincidence of PA-57, PA-58, and the East Cloud at a radius where the surface density of both GCs and substructures is extremely low, combined with the matching radial velocities of PA-57 and PA-58, can be used to argue on a statistical basis that all three are very likely to be physically associated (see Veljanoski et al. 2014).¹

We obtained deep *HST* imaging of both PA-57 and PA-58 as part of program GO-12515 (PI: Mackey), using the Wide Field Channel (WFC) of the Advanced Camera for Surveys (ACS). The data were taken on 2011 December 01 and 2012 March 05 for PA-57 and PA-58, respectively. Both clusters were imaged three times with the *F606W* filter and three times with the *F814W* filter, with small telescope dithers between exposures. Single-frame integration times were 821 s in *F606W* and 867 s in *F814W*.

Reduced ACS/WFC data obtained from the *HST* archive have already been corrected for charge-transfer efficiency losses using a pixel-based method (e.g. Anderson & Bedin 2010). We photometered these corrected images using version 2.0 of the *DOLPHOT* package (Dolphin 2000) to perform point spread function (PSF) fitting, following a procedure very similar to that described by Mackey et al. (2013b). For both clusters, we set the *DOLPHOT* parameter `fit-sky` = 3, to fit the sky for each star locally within the photometry

¹ Of course, conclusive verification requires a velocity measurement derived directly from the East Cloud itself.

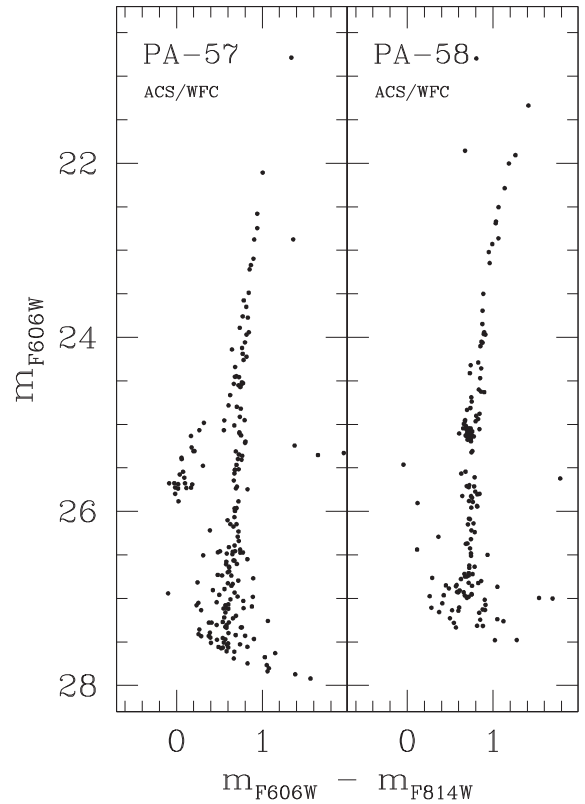


Figure 10. ACS/WFC CMDs for PA-57 and PA-58. Only stars within 30 arcsec of the cluster centres are plotted.

aperture as part of a two-parameter PSF fit. To excise spurious detections, non-stellar objects, and objects with poor photometry from our catalogues we selected only those sources classified as stellar by *DOLPHOT*, with valid measurements in all six input frames, and possessing a global sharpness parameter between ± 0.05 in each filter, and a crowding parameter ≤ 0.07 mag in each filter. The final photometry is on the VEGAMAG scale of Sirianni et al. (2005).

We use artificial star tests to quantify the individual photometric uncertainties and assess the detection completeness. For each real star, we generate 500 artificial stars of the same brightness, with positions uniformly distributed within an annulus spanning 0.5–5 arcsec of its coordinates. Using *DOLPHOT*, we add a single artificial star to the image at a time, and then attempt to measure it. Once this process is complete, we apply the same quality filter as described above. For each real star, we then assign a detection completeness according to the ratio of the number of successfully measured artificial stars to the number of input stars, and obtain an estimate of the photometric uncertainty by quantifying the scatter in the differences between input and measured magnitudes for the artificial stars. In uncrowded parts of the target clusters (i.e. outside ≈ 5 arcsec from their centres), the 50 per cent completeness level is at $m_{F606W} \approx 27.2$ and $m_{F814W} \approx 26.6$; however, in the central regions these limits are as much as ~ 1.5 mag brighter.

Fig. 10 shows our CMDs for PA-57 and PA-58. To minimize contamination from non-cluster members, we plot only stars lying within 30 arcsec of the cluster centres. The two CMDs have quite distinct morphologies indicating that the clusters have rather different properties. PA-57 has a steep RGB and a blue HB, characteristic of an ancient (> 10 Gyr old), metal-poor population. PA-58, on the other hand, has an upper RGB that is substantially more curved, and a strikingly short HB that is exclusively red – in fact, more of a

Table 4. Results of CMD registration between our target and template clusters.

Name	[Fe/H]	Δc (mag)	Δm (mag)	$E(B - V)_{\text{template}}$	μ_{template}	$E(B - V)_{\text{cluster}}$	μ_{cluster}
PA-57						(0.066)	
M92	-2.4	0.050 ± 0.005	8.25 ± 0.05	0.021	16.43	0.074	24.55
M53	-2.0	0.045 ± 0.005	9.95 ± 0.05	0.023	14.80	0.071	24.63
PA-58						(0.062)	
Terzan 7	-0.6	-0.030 ± 0.005	7.50 ± 0.05	0.088	17.02	0.056	24.60
Palomar 12	-0.8	0.045 ± 0.005	8.27 ± 0.05	0.037	16.40	0.085	24.55

red clump than a typical GC HB. In this sense it strongly resembles two of the clusters known to be associated with the SWC – PA-7 and PA-8 – which have inferred ages at least 2 Gyr younger than the oldest Milky Way GCs (see Mackey et al. 2013a).

We estimate the metallicity, foreground reddening, and line-of-sight distance of PA-57 and PA-58 by matching fiducial sequences from several Milky Way GCs to their CMDs. Appropriate template clusters are selected from the sample observed by the ACS Galactic globular cluster Treasury Survey (see Sarajedini et al. 2007), and photometry was obtained from the online data base for this project² (Anderson et al. 2008). In identifying suitable template clusters, we search for objects possessing comparable upper RGB curvature and HB morphology to PA-57 and PA-58. A small amount of experimentation revealed the clusters M92 (NGC 6341) and M53 (NGC 5024) to be good matches for PA-57, and the clusters Terzan 7 and Palomar 12 to be good matches for PA-58.

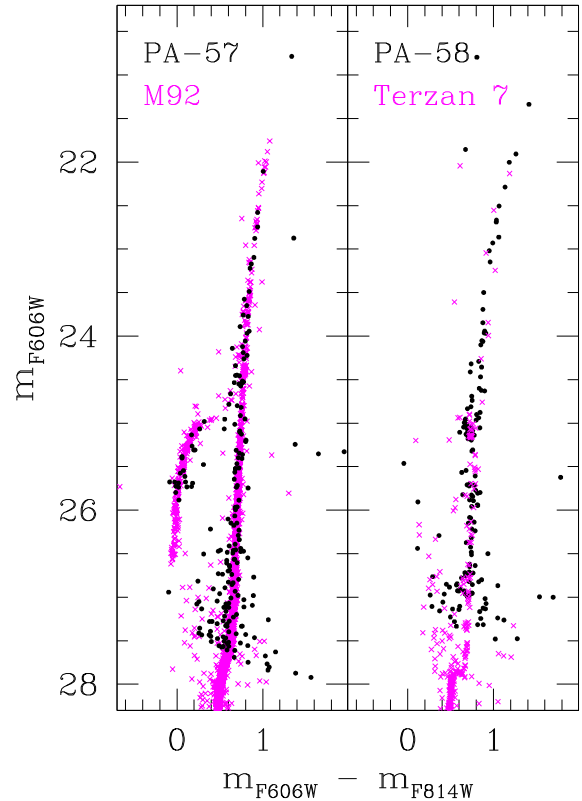
We align the template CMDs to those of PA-57 and PA-58 using a procedure very similar to that described by Mackey et al. (2006, 2007). The vertical offset, Δm , required to register the two CMDs was determined largely via the observed HB level, while the horizontal offset, Δc , is determined using the colour of the RGB near the HB level. Adopting suitable extinction coefficients from Schlafly & Finkbeiner (2011) – i.e. $A_{F606W} = 2.471E(B - V)$ and $A_{F814W} = 1.526E(B - V)$, where $E(B - V)$ is determined from the maps of Schlegel et al. (1998) – allows the foreground reddening and distance modulus for a given target cluster to be expressed in terms of the same quantities for the template clusters, and Δm and Δc :

$$E(B - V)_{\text{cluster}} = 1.058\Delta c + E(B - V)_{\text{template}}$$

$$\mu_{\text{cluster}} = \Delta m - 2.615\Delta c + \mu_{\text{template}}. \quad (2)$$

Thus, the final uncertainty on measurements for the target cluster is determined by both the precision to which the CMDs can be registered, and the precision with which the reddening and distance of the template object are known. Note that this assumes the target cluster and the template cluster are identical in terms of age, [Fe/H], and $[\alpha/\text{Fe}]$; small variations in these properties result in additional second-order systematic uncertainties.

The results of our alignment process are shown in Table 4, and examples of registered CMDs are displayed in Fig. 11. The assumed foreground reddening for the template clusters comes from the Schlegel, Finkbeiner & Davis (1998) maps; also listed (in parentheses) are the values derived from these maps for the target clusters, which can be used as a consistency check on the measurements determined using Δc . Values for the metallicity and distance of the template clusters come from Dotter et al. (2010), who derived these quantities directly from the same photometric data set we employ here. The one exception is the distance for Terzan 7, which we

**Figure 11.** CMDs for PA-57 and PA-58, aligned with the template clusters M92 and Terzan 7, respectively.

take from Siegel et al. (2011) (who again used the Treasury survey photometry, but studied Terzan 7 in detail). Uncertainties on the template distances are difficult to ascertain – Dotter et al. (2010) do not provide formal uncertainties on their measurements, but there are substantial variations amongst the literature – see for example the 2010 revision of the Harris (1996) catalogue. Terzan 7 represents an extreme example – Dotter et al. (2010) find a distance modulus of 17.15 for this cluster, while the Harris catalogue lists 16.79, derived from the HB luminosity measured by Buonanno et al. (1995). Our assumed value represents a suitable compromise. Given the excellent precision with which we are able to register the CMDs, it is safe to assume that uncertainties in the known distances to the template clusters dominate our overall error budget, such that the uncertainties on our individual distance measurements are of the order of ~ 0.1 mag.

Overall, we find that PA-57 is a very metal-poor cluster, with [Fe/H] somewhere between -2.0 and -2.4 – its CMD matches those for M92 and M53 equally well. PA-58 is much more metal-rich, with [Fe/H] ~ -0.7 . Given that both Terzan 7 and Palomar 12 are substantially younger than the oldest Galactic GCs (Dotter

² http://www.astro.ufl.edu/~ata/public_hstgc/

Table 5. Properties of the East Cloud.

Milky Way distance	814_{-9}^{+20} kpc
M31 distance	111_{-1}^{+13} kpc
Apparent V -band magnitude	13.8 ± 0.3 mag
Absolute V -band magnitude	-10.7 ± 0.4 mag
Average V -band surface brightness	31.6 ± 0.4 mags arcsec $^{-2}$
Metallicity [Fe/H]	-1.2 ± 0.1
Metallicity spread Δ [Fe/H]	0.58 ± 0.03

et al. 2010 find ages for these clusters of 8.00 ± 0.75 Gyr and 9.50 ± 0.75 Gyr, respectively), the good agreement between the CMD for PA-58 and those for the template clusters suggests that PA-58 is likely to be a similarly young cluster. These results are strongly suggestive that the progenitor of the East Cloud underwent significant chemical evolution over many Gyr before it was destroyed by M31.

We have determined two independent distance measurements to the East Cloud by matching two different templates to each of PA-57 and PA-58. A straight average of the results gives a distance modulus of 24.58 with an uncertainty of the order of ~ 0.05 mag. This corresponds to a line-of-sight distance of 824 ± 19 kpc.

8 DISCUSSION AND CONCLUSIONS

Like the SWC covered in Paper I, the East Cloud is one of the brightest stellar substructures in the outer halo of M31 today. We can use the luminosity–metallicity relation (Kirby et al. 2011) to estimate the luminosity of the East Cloud progenitor:

$$[\text{Fe}/\text{H}] = -2.06 + (0.40 \pm 0.05) \log_{10} \left(\frac{L_{\text{tot}}}{10^5 L_{\odot}} \right) \quad (3)$$

For a median metallicity of $[\text{Fe}/\text{H}] = -1.2$, the progenitor luminosity is $\sim 1.4 \times 10^7 L_{\odot}$, which corresponds to an absolute V -band magnitude of $M_V \approx -13.0$ mag. This high metallicity implies that the East Cloud progenitor was of comparable brightness to the SWC progenitor, and thus was amongst the brightest of Andromeda’s satellites. However, the East Cloud is much more extended and diffuse than the SWC, making characterization more difficult.

Comparing with the brightness estimate determined in Section 5, the luminosity–metallicity relation suggests that the present day East Cloud represents approximately 12 per cent of the progenitor’s original luminosity. With clear signs of disruption, it is likely that we are seeing a heavily disrupted remnant today. Key properties of the East Cloud, including distances, luminosities, and metallicities have each been calculated using multiple methods, and are summarized in Table 5.

Distances to the main East Cloud substructure were calculated using a TRGB method, detailed in another paper in this series (Conn et al., submitted). By fitting templates to the coincident GCs PA-57 and PA-58, we established an independent measure of the distance to the cloud, under the assumption that the clusters are associated. Comparing stars in the East Cloud to theoretical stellar isochrones for a 13 Gyr population, gives a metallicity of $[\text{Fe}/\text{H}] = -1.2 \pm 0.1$. This is consistent with the metallicity parameter returned by TRGB method fit. Metallicities were also calculated for the two GCs coincident with the East Cloud. Given the substantial difference between their metallicities, we suspect that the East Cloud progenitor underwent significant chemical evolution prior to its eventual disruption. This is consistent with the broad MDF found for the East Cloud substructure.

The luminosity was estimated using two methods, the ‘Dwarf Method’ and the ‘Population Method’. The ‘Dwarf Method’ is calibrated against estimates of the luminosities of the Andromeda dwarf galaxies. The ‘Population Method’ is directly estimated from forward modelled single stellar population fits to the PAndAS data. These methods returned consistent estimates for the SWC and the East Cloud, and are an improvement on the work presented in Paper I.

With the new lower estimate of -11.3 ± 0.3 mag for the absolute magnitude of the SWC, we can say that it is much more disrupted than previously thought, with the current visible structure representing only approximately 40 per cent of the luminosity of the progenitor object estimated by Paper I. It is unclear where to draw the boundaries for such extended objects as the SWC and the EC. As discussed in Paper I, there is a significant extension to the South-East of the SWC which may potentially be part of the SWC, and could represent a portion of the absent 60 per cent of the the progenitor.

It is even less clear where to draw the boundaries for the East Cloud. ECS and ECN are disjointed, but could easily be part of the same progenitor, as we have assumed throughout, and further to this there are signs of more potentially related structure in ECNW to the West of ECN and in ECSW to the South-West of ECS. Adding these structures to the total for the East Cloud would raise the total brightness by a further half a magnitude, and would suggest a much more diffuse structure overall.

However, even if we include the extended wings, this would only raise the portion of the implied progenitor that we are observing from 12 to 18 per cent. It is clear that the East Cloud is much more disrupted than the SWC. This conclusion is supported by its lower surface brightness and greater physical extent. Furthermore, unlike the SWC, there are no signs of nearby HI (Lewis et al. 2013), suggesting that the gas was stripped at an earlier stage, and that the East Cloud has either been disrupted more violently or over a longer time-scale than the SWC.

The fact that two GCs are seen to be associated with the core of the East Cloud, and possibly up to another four with its full extent, adds further weight to the argument that we are only observing a relatively small fraction of the original progenitor. A useful (albeit crude) statistic in this context is the GC specific frequency, which is defined as the number of GCs per unit luminosity of the host galaxy, normalized to a host with $M_V = -15$. Specifically, $S_N = N_{\text{GC}} 10^{0.4(M_V + 15)}$, where N_{GC} is the total number of GCs (Harris & van den Bergh 1981).

Assuming our derived luminosity for the core of the East Cloud, plus the association of PA-57 and PA-58, returns a specific frequency of ~ 166 . This is much larger than is commonly seen for other dwarf galaxies (Miller et al. 1998; Miller & Lotz 2007; Georgiev et al. 2010; Harris, Harris & Alessi 2013). If we instead use our estimate of the progenitor luminosity using the metallicity derived in Section 6, we find $S_N \sim 13$, which sits right in the midst of the typically observed range for dwarfs. Similarly, the present luminosity of the SWC together with its three coincident GCs suggests $S_N \sim 91$, which is very high; however, using our estimate of the progenitor luminosity derived from the median metallicity reduces this to $S_N \sim 33$.

It is interesting to speculate briefly as to whether the four GCs projected on to the two features extending away from the East Cloud might also be associated with this structure. Including all four would raise the specific frequency to ~ 38 , which is not unreasonably high; furthermore, the velocities for these clusters measured by Veljanoski et al. (2014) exhibit a gradient that is not inconsistent with a

stream-like association. Sakari et al. (2015) provided abundance estimates for a variety of elements for PA-53, PA-54, and PA-56, derived from integrated-light spectra. These are consistent with a joint accretion origin; in the event that one or more of these objects prove to be associated with the underlying substructure, the abundances could provide useful information about the chemical evolution of the East Cloud progenitor. HST photometry for the clusters in question would enable precise distance measurements that would more definitively test the possibility of their membership, and help place the locus of the substructure in three dimensions relative to the M31 centre.

Ideally, follow up spectroscopy will confirm the associations between the extension fields ECSW and ECNW, the core fields ECS and ECN, and the GCs, but this is likely to be extremely challenging due to the very high levels of contamination in the extensions, combined with the very diffuse substructure. Outer halo substructures as faint and diffuse as the East Cloud represent the limit of what is possible to recover from the PAndAS data alone.

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