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Cellular Automata and Kan Extensions

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Abstract

In this paper, we formalize precisely the sense in which the application of cellular automaton to partial configuration is a natural extension of its local transition function through the categorical notion of Kan extension. In fact, the two possible ways to do such an extension and the ingredients involved in their definition are related through Kan extensions in many ways. These relations provide additional links between computer science and category theory, and also give a new point of view on the famous Curtis-Hedlung theorem of cellular automata from the extended topological point of view provided by category theory. These relations provide additional links between computer science and category theory. No prior knowledge of category theory is assumed.

1 Introduction

Cellular automata are usually presented either as a local behavior extended to a global and uniform one or as a continuous uniform global behavior for the appropriate topology[1]. We offer here a third, fruitful, point of view easing many generalizations of the concepts pioneered by cellular automata, *e.g.* via so-called global transformation[4, 2]. The goal of this paper is not to elaborate on these generalizations but to focus on some simple foundational bridges allowing these generalizations. In particular, we focus on Kan extensions, a categorical notion allowing, as we show here, to capture local/global descriptions[3]. While categories are generalizations of monoids and posets, the case of cellular automata can be fully treated in terms of posets only. Once the involved structures made clear via posets, the transition to category is precisely what enables the generalizations in a surprisingly smooth way as discussed in the final section.

In this paper, we recall the direct definitions of cellular automata on groups, local transition function, global transition shift, shift action, and also consider the counterparts of these functions on arbitrary partial configurations. This bigger picture allows to show that the various local/global relations between these objects are all captured by left and right Kan extensions, the latter providing an alternative definition of these objects. The proofs are provided in detail to show how the concept can be easily manipulated once understood. We also introduce slightly more generality than one would typically need in order to enrich the presentation of Kan extensions in a hopefully useful way. In the final section, we comment on the link with Curtis-Hedlung theorem and discuss briefly the smooth transition to more general systems where the space itself has to evolve.

2 Cellular Automata and Kan Extensions

Let us give some basic definitions to fix the notations. We also note small caveats early on, to avoid having to deal with many unrelated details at the same time in a single proof or construction latter on.

2.1 Cellular Automata

Definition 1. A group is a set G with a binary operation $\cdot : G \times G \rightarrow G$ which is associative, which has a neutral element 1 and for which any $g \in G$ has inverse g^{-1} . A right action of the group on a set X is a binary operation $- \blacktriangleleft - : X \times G \rightarrow X$ such that $x \blacktriangleleft 1 = x$ and $(x \blacktriangleleft g) \blacktriangleleft h = x \blacktriangleleft (g \cdot h)$.

In cellular automata, the group G represents the space, each element $g \in G$ being at the same time an absolute and a relative position. This space is decorated with states that evolve through local interactions only. The classical formal definitions go as follows and work with the entire, often infinite, space.

Definition 2. A cellular automaton on a group G is given by a neighborhood $N \subseteq G$, a finite set of states Q , and a local transition function $\delta : Q^N \rightarrow Q$. The elements of the set Q^N are called local configurations. The elements of the set Q^G are called global configurations and a right action $- \blacktriangleleft - : Q^G \times G \rightarrow Q^G$ is defined on Q^G by $(c \blacktriangleleft g)(h) := c(g \cdot h)$. The global transition function $\Delta : Q^G \rightarrow Q^G$ of such a cellular automaton is defined as $\Delta(c)(g) := \delta((c \blacktriangleleft g) \upharpoonright N)$.

Proposition 3. The latter right action is indeed a right action.

Proof. For any $g, h \in G$, we have $((c \blacktriangleleft g) \blacktriangleleft h)(i) = (c \blacktriangleleft g)(h \cdot i) = c(g \cdot h \cdot i) = (c \blacktriangleleft (g \cdot h))(i)$ for any $i \in G$, so $((c \blacktriangleleft g) \blacktriangleleft h) = (c \blacktriangleleft (g \cdot h))$ and also $(c \blacktriangleleft 1)(i) = c(1 \cdot i) = c(i)$ as required by Definition 1 of right actions. \square

This choice of definition and right notation for the so called shift action has two advantages. Firstly, the definition of the action is a simple associativity. Secondly, when instantiated with $G = \mathbb{Z}$ with sum, the content of $c \blacktriangleleft 5$ is the content of c shifted to the left, as the symbols indicates. Indeed, for $c' = c \blacktriangleleft 5$, $c'(-5) = c(0)$ and $c'(0) = c(5)$.

Proposition 4. For all $c \in Q^G$ and $g \in G$, $\Delta(c)(g)$ is only function of $c \upharpoonright g \cdot N$.

Proof. Indeed, $\Delta(c)(g) = \delta((c \blacktriangleleft g) \upharpoonright N)$ so the value is determined by $(c \blacktriangleleft g) \upharpoonright N$. But for any $n \in N$, $(c \blacktriangleleft g)(n) = c(g \cdot n)$ by definition of \blacktriangleleft . \square

In common cellular automata terms, this proposition means that the neighborhood of g is $g \cdot N$, in this order. Let us informally call objects of the form $c \upharpoonright g \cdot N \in \bigcup_{g \in G} Q^{g \cdot N}$ a “shifted local configurations”. Note that, at our level of generality, two different positions $g \neq g' \in G$ might have the same neighborhood $g \cdot N = g' \cdot N$. Although the injectivity of the function $(- \cdot N)$ could be a useful constraints to add, which is often verified in practice, we do not impose it so the reader should keep this in mind. A second thing to keep in mind is that we do not require here that the neighborhood should be finite. This is done only because this property is not used in the formal development below.

Proposition 5. The function $- \cdot N : G \rightarrow \mathbf{2}^G$ is not necessarily injective.

Proof. Considering any group G and $N = G$, we have $g \cdot N = G$ for any $g \in G$. Considering the group $G = \mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}$ and $N = \{(0, 0), (1, 0)\}$, we have $(0, 0) + N = (1, 0) + N = \{(0, 0), (1, 0)\}$ because of the torsion. \square

Because of this, it is useful to replace the shifted local configuration, *i.e.* the union $\bigcup_{g \in G} Q^{g \cdot N}$, by the disjoint union $\bigcup_{g \in G} (\{g\} \times Q^{g \cdot N})$. The elements of the latter are the form $(g \in G, c \in Q^{g \cdot N})$ and keep track of the considered “center” of the neighborhood. More explicitly, two elements $(g_0, c \upharpoonright g_0 \cdot N), (g_1, c \upharpoonright g_1 \cdot N) \in \bigcup_{g \in G} (\{g\} \times Q^{g \cdot N})$ are different as soon as $g_0 \neq g_1$ even if $g_0 \cdot N = g_1 \cdot N$. This encodes things according to the intuition of a centered neighborhood.

2.2 The Poset of (Partial) Configurations

In the previous formal statements, one sees different kinds of configurations, explicitly or implicitly: global configurations $c \in Q^G$, local configurations $(c \blacktriangleleft g) \upharpoonright N \in Q^N$, “shifted local configuration” $c \upharpoonright g \cdot N \in Q^{g \cdot N}$, and their resulting “placed states” $(g \mapsto \Delta(c)(g)) \in Q^{\{g\}}$. In the cellular automata literature, one often considers configurations defined on other subsets of the space, *e.g.* finite connected subsets. More generally, we are interested in all partial configurations Q^S for arbitrary subsets $S \subseteq G$. The restriction operation $(- \upharpoonright -)$ used many times above gives a partial ordering of these partial configurations.

Definition 6. A (partial) configuration c is a partial function from G to Q . Its domain of definition is denoted $|c|$ and called its support. The set of all configurations is denoted $\text{Conf} = \bigcup_{S \subseteq G} Q^S$. We extend the previous right action \blacktriangleleft and define it to map each $c \in \text{Conf}$ to $c \blacktriangleleft g$ having support $|c \blacktriangleleft g| = \{h \in G \mid g \cdot h \in |c|\}$ and states $(c \blacktriangleleft g)(h) = c(g \cdot h)$.

Proposition 7. The latter right action is well-defined and is a right action.

Proof. The configuration $c \blacktriangleleft g$ is well-defined on all of its support. Indeed for any $h \in |c \blacktriangleleft g|$, $(c \blacktriangleleft g)(h) = c(g \cdot h)$ and $g \cdot h \in |c|$ by definition of h . The right action property is verified as in the proof of Proposition 3. \square

Let us restate Proposition 4 more precisely using Definition 6.

Proposition 8. For all $c \in Q^G$ and $g \in G$, $(c \blacktriangleleft g) \upharpoonright N = (c \upharpoonright g \cdot N) \blacktriangleleft g$.

Proof. Indeed, $|(c \upharpoonright g \cdot N) \blacktriangleleft g| = \{h \in G \mid g \cdot h \in |(c \upharpoonright g \cdot N)|\} = \{h \in G \mid g \cdot h \in g \cdot N\} = N = |(c \blacktriangleleft g) \upharpoonright N|$. Also for any $n \in N$, $((c \blacktriangleleft g) \upharpoonright N)(n) = (c \blacktriangleleft g)(n) = c(g \cdot n)$ and $((c \upharpoonright g \cdot N) \blacktriangleleft g)(n) = (c \upharpoonright g \cdot N)(g \cdot n) = c(g \cdot n)$. \square

Definition 9. A partial order on a set X is a binary relation $\preceq \subseteq X \times X$ which is reflexive, transitive, and antisymmetric. A set endowed with a partial order is called a partially ordered set, or poset for short.

Definition 10. Given any two configurations $c, c' \in \text{Conf}$, we set $c \preceq c'$ if and only if $\forall g \in |c|, g \in |c'| \wedge c(g) = c'(g)$. This is read “ c is a subconfiguration of c' ” or “ c' is a superconfiguration of c ”.

Proposition 11. The set Conf with this binary relation is a poset. In this poset, the “shifted local configurations” $c \blacktriangleleft g$ for $c \in Q^N$ and $g \in G$ are subconfigurations of the (appropriate) global configurations $c' \in Q^G$. Shifted local configurations form an antichain. Global configurations form an antichain.

Proof. As can be readily seen, since each global configuration restricts to many shifted local configurations, and recalling that an antichain is a subset S of the poset such that neither $x \preceq x'$ nor $x' \preceq x$ hold for any $x, x' \in S$. \square

2.3 Kan Extensions (in the 2-Category of Posets)

Given three sets A, B and C such that $A \subseteq B$, we say that a function $g : B \rightarrow C$ extends a function $f : A \rightarrow C$ if $g \upharpoonright A = f$, or equivalently if $g \circ i = f$ where i is the obvious injective function from A to B . For a given $f : A \rightarrow C$, there are typically many possible extensions. Roughly speaking, Kan extensions formalizes, among many things, the mathematical practice where extensions are rarely arbitrary. One usually chooses the “best” or “most natural” extensions. There is therefore an implicit comparison considered between the extensions.

This is the reason why Kan extensions are formally defined at the level of 2-categories: A, B, C are objects, f, g, i , and all (not necessarily “most natural”) extensions are 1-morphisms between these objects, and the “naturality” comparison between the 1-morphisms are 2-morphisms. However, we do not need to discuss things at this level of generality here. For our particular case, the objects are posets, the 1-morphisms are monotonic functions and the monotonic functions are compared pointwise.

Definition 12. *Given two posets (X, \preceq_X) and (Y, \preceq_Y) , a function $f : X \rightarrow Y$ is said to be monotonic if for all $x, x' \in X$, $x \preceq_X x'$ implies $f(x) \preceq_Y f(x')$.*

Proposition 13. *For any $g \in G$, the function $- \blacktriangleleft g$ is monotonic.*

Proof. For any $g \in G$, the its right action is monotonic because the domain of definition of the configuration is only shifted, so that a bigger domain of definition stays bigger once shifted. \square

Definition 14. *Given two posets (X, \preceq_X) and (Y, \preceq_Y) , we define the binary relation $- \Rightarrow -$ on the set of all monotonic functions from X to Y by $f \Rightarrow f' \iff \forall c \in \text{Conf}, f(c) \preceq_Y f'(c)$.*

Proposition 15. *Given two posets (X, \preceq_X) and (Y, \preceq_Y) , the set of monotonic functions between them together with this binary relation forms a poset.*

Proof. As one can easily check. \square

Definition 16. *In this setting, given three posets A, B and C , and three monotonic functions $i : A \rightarrow B$, $f : A \rightarrow C$ and $g : B \rightarrow C$, g is said to be the left (resp. right) Kan extension of f along i if g is the \Rightarrow -minimum (resp. \Rightarrow -maximum) element in the set of monotonic functions $\{h : B \rightarrow C \mid f \Rightarrow h \circ i\}$ (resp. $\{h : B \rightarrow C \mid h \circ i \Rightarrow f\}$).*

This concept is particularly useful because, whenever it applies, it is also a complete characterization as stated in the following proposition in the left case.

Proposition 17. *The left Kan extension g is unique when it exists.*

Proof. It is defined as the minimum of a set, and a minimum is always unique when it exists. \square

Another suggestive way to read the concept of Kan extensions with respect to this paper is to say that a function g on a poset can be summarized into, or generated by, a part of its behavior f on just a small part of the poset. Note however that i does not need to be injective in this definition.

3 Kan Extensions in Cellular Automata

3.1 A First Approach To Partial Configurations

The first, intuitive, approach is to take a configuration c , look for all places g where the whole neighborhood $g \cdot N$ is defined and to take the local transition result of these places only. We first give a direct formal definition, and then show that this is a left Kan extension.

3.1.1 A Direct Definition

Definition 18. *The interior of a subset $S \subseteq G$ is $\text{int}(S) = \{g \in G \mid g \cdot N \subseteq S\}$.*

Definition 19. *The coarse transition function $\Phi : \text{Conf} \rightarrow \text{Conf}$ is defined for all $c \in \text{Conf}$ as $|\Phi(c)| = \text{int}(|c|)$ and $\Phi(c)(g) = \delta((c \blacktriangleleft g) \upharpoonright N)$.*

Proposition 20. *For any $c \in \text{Conf}$ and $g \in G$, the statements $g \in \text{int}(|c|)$, $g \cdot N \subseteq |c|$, and $N \subseteq |c \blacktriangleleft g|$ are equivalent. (So Φ is well-defined in Definition 19.)*

Proof. The first and second statements are equivalent by Definition 18 of int . The second and third statements are equivalent by Definition 6 of \blacktriangleleft . \square

Remember Proposition 5. If we do have injectivity of neighborhoods, we have $\text{int}(g \cdot N) = \{g\}$. But since we do not assume it, we only have the following.

Proposition 21. *Let $S \subseteq G$. In general, $S \subseteq \text{int}(S \cdot N)$ but we do not necessarily have equality, even when $S = \{g\}$ for some $g \in G$.*

Proof. Consider the examples in the proof of Proposition 5. \square

Another useful remark on which we come back below is the following.

Proposition 22. *For any $g \in G$, any $M \subsetneq N$, and any $c \in Q^{g \cdot M}$, $|\Phi(c)| = \emptyset$.*

Proof. By Definition 19 of Φ . \square

3.1.2 Characterization as a Left Kan Extension

The coarse transition function Φ is defined on the set of all configurations Conf and we claim that it is generated, in the Kan extension sense, by the local transition function δ shifted everywhere. We define the latter, with Proposition 5 in mind.

Definition 23. *We define Loc to be the poset $\text{Loc} = \bigcup_{g \in G} (\{g\} \times Q^{g \cdot N})$ with trivial partial order $(g, c) \preceq (g', c') \iff (g, c) = (g', c')$. The “fully shifted local transition function” $\bar{\delta} : \text{Loc} \rightarrow \text{Conf}$ is defined, for any $(g, c) \in \text{Loc}$ as $|\bar{\delta}(g, c)| = \{g\}$ and $\bar{\delta}(g, c)(g) = \delta(c \blacktriangleleft g)$. The second projection of Loc is the monotonic function $\pi_2 : \text{Loc} \rightarrow \text{Conf}$ defined as $\pi_2(g, c) = c$.*

Proposition 24. *Loc is a poset and $\bar{\delta}$ and π_2 are monotonic functions.*

Proof. Indeed, the identity relation is an order relation and any function respects the identity relation. \square

Proposition 25. *The coarse transition function Φ is monotonic.*

Proof. Indeed, take $c, c' \in \text{Conf}$ such that $c \preceq c'$. We want to prove that $\Phi(c) \preceq \Phi(c')$ and this is equivalent to:

$$\begin{aligned} & \forall g \in |\Phi(c)|, g \in |\Phi(c')| \wedge \Phi(c)(g) = \Phi(c')(g) \\ \iff & \forall g \in \text{int}(|c|), g \in \text{int}(|c'|) \wedge \delta(c \blacktriangleleft g \uparrow N) = \delta(c' \blacktriangleleft g \uparrow N) \\ \iff & \forall g \in G \text{ s.t. } g \cdot N \subseteq |c|, g \cdot N \subseteq |c'| \wedge \delta(c \blacktriangleleft g \uparrow N) = \delta(c' \blacktriangleleft g \uparrow N), \end{aligned}$$

by Definition 6 of \preceq , Definition 19 of Φ , and Definition 18 of int . The final statement is implied by:

$$\begin{aligned} & \forall g \in G \text{ s.t. } g \cdot N \subseteq |c|, g \cdot N \subseteq |c'| \wedge c \blacktriangleleft g \uparrow N = c' \blacktriangleleft g \uparrow N \\ \iff & \forall g \in G \text{ s.t. } g \cdot N \subseteq |c|, g \cdot N \subseteq |c'| \wedge \forall n \in N, (c \blacktriangleleft g)(n) = (c' \blacktriangleleft g)(n) \\ \iff & \forall g \in G \text{ s.t. } g \cdot N \subseteq |c|, g \cdot N \subseteq |c'| \wedge \forall n \in N, c(g \cdot n) = c'(g \cdot n), \end{aligned}$$

the last equivalence being by Definition 6. To prove it, take $g \in G$ such that $g \cdot N \subseteq |c|$, and $n \in N$. Since $c \preceq c'$ and $g \cdot n \in |c|$, we have $g \cdot n \in |c'|$, and $c(g \cdot n) = c'(g \cdot n)$ as wanted. \square

Proposition 26. *Φ is the left Kan extension of $\bar{\delta}$ along $\pi_2 : \text{Loc} \rightarrow \text{Conf}$.*

Proof. By Definition 16 of left Kan extensions, we need to prove firstly that Φ is such that $\bar{\delta} \Rightarrow \Phi \circ \pi_2$, and secondly that it is smaller than any other such monotonic functions.

For the first part, $\bar{\delta} \Rightarrow \Phi \circ \pi_2$ is equivalent to:

$$\begin{aligned} & \forall (g, c) \in \text{Loc}, \bar{\delta}(g, c) \preceq \Phi(c) \text{ (Defs. 14 and 23 of } \Rightarrow \text{ and } \pi_2) \\ \iff & \forall (g, c) \in \text{Loc}, \forall h \in |\bar{\delta}(g, c)|, h \in |\Phi(c)| \wedge \bar{\delta}(g, c)(h) = \Phi(c)(h) \text{ (D. 10 of } \preceq) \\ \iff & \forall (g, c) \in \text{Loc}, g \in |\Phi(c)| \wedge \delta(c \blacktriangleleft g) = \Phi(c)(g) \text{ (Def. 23 of } \bar{\delta}) \\ \iff & \forall (g, c) \in \text{Loc}, g \cdot N \in |c| \wedge \delta(c \blacktriangleleft g) = \delta((c \blacktriangleleft g) \uparrow N) \text{ (Defs 18, 19 of } \Phi). \end{aligned}$$

This last statement is true by Definition 23 of Loc , since $c \in Q^{g \cdot N}$.

For the second part, let $F : \text{Conf} \rightarrow \text{Conf}$ be a monotonic function such that $\bar{\delta} \Rightarrow F \circ \pi_2$. We want to show that $\Phi \Rightarrow F$, which is equivalent to:

$$\begin{aligned} & \forall c \in \text{Conf}, \Phi(c) \preceq F(c) \text{ (Def. 14 of } \Rightarrow) \\ \iff & \forall c \in \text{Conf}, \forall g \in |\Phi(c)|, g \in |F(c)| \wedge \Phi(c)(g) = F(c)(g) \text{ (Def. 10 of } \preceq) \\ \iff & \forall c \in \text{Conf}, \forall g \in \text{int}(|c|), g \in |F(c)| \wedge F(c)(g) = \delta((c \blacktriangleleft g) \uparrow N) \text{ (Def. 19)} \end{aligned}$$

So take $c \in \text{Conf}$ and $g \in \text{int}(|c|)$, and consider $d_g = c \uparrow g \cdot N$. Since $d_g \preceq c$ and F is monotonic, we have $F(d_g) \preceq F(c)$. Moreover $\bar{\delta} \Rightarrow F \circ \pi_2$ and $(g, d_g) \in \{g\} \times Q^{g \cdot N} \subseteq \text{Loc}$, so $\bar{\delta}(g, d_g) \preceq F(d_g)$ by Definitions 14 and 23 of \Rightarrow and π_2 . By transitivity $\bar{\delta}(g, d_g) \preceq F(c)$. By Definition 23 of $\bar{\delta}$ and Definition 10 of \preceq , we obtain $g \in |F(c)|$, and $F(c)(g) = \bar{\delta}(g, d_g)(g) = \delta((c \blacktriangleleft g) \uparrow N)$, as wanted. \square

As a sidenote, remark that to have the equality $\bar{\delta} = \Phi \circ \pi_2$, one needs to have that the injectivity of neighborhood function. Indeed, without injectivity, we have two different $g, g' \in G$ having the same neighborhood M , *i.e.* $M = g \cdot N = g' \cdot N$. This means that, given any local configuration $c \in Q^M$ on this neighborhood, each pair $(g, c), (g', c) \in \text{Loc}$ have different results $\bar{\delta}(g, c) \in Q^{\{g\}}$ and $\bar{\delta}(g', c) \in Q^{\{g'\}}$ with different support $\{g\}$ and $\{g'\}$. However, their common projection $\pi_2(g, c) = \pi_2(g', c) = c$ have a unique result $\Phi(c)$ with a support such that $\{g, g'\} \subseteq |\Phi(c)|$. So we have a strict comparison $\bar{\delta} \Rightarrow \Phi \circ \pi_2$. When the neighborhood function is injective, π_2 is also injective and the previous situation can not occur so we have equality $\bar{\delta} = \Phi \circ \pi_2$.

3.2 A Second Approach To Partial Configurations

3.2.1 A Direct Definition

For some applications, the previous definitions are too naive. For example, it is common to consider two cellular automata to be essentially the same if they generate the same global transition functions. However, here, two such cellular automata give different coarse transition function if they have a different neighborhood.

To refine the previous definitions, a second approach is to take a configuration c , and look at all places for which the result is already determined by the partial data defined in c . So we consider all $g \in G$ for which all completions of the data present on the defined neighborhood $g \cdot N \cap |c|$ into a configuration on the complete neighborhood $g \cdot N$ always lead to the same result by δ .

Definition 27. For any $c \in \text{Conf}$ and $g \in G$, let $c_g := c \upharpoonright (g \cdot N \cap |c|)$.

Definition 28. Given a configuration $c \in \text{Conf}$, its determined subset is $\text{det}(c) = \{g \in G \mid \exists q \in Q, \forall c' \in Q^{g \cdot N}, c' \upharpoonright |c_g| = c_g \implies \delta(c' \blacktriangleleft g) = q\}$. For any $g \in \text{det}(c)$, we denote $q_{c,g} \in Q$ the unique state q having the mentioned property.

Note that this definition depends on the cellular local transition function δ and on the data of the configuration, contrary to Definition 18 of interior that only depends on its neighborhood N and on the support of the configuration.

Definition 29. Given a cellular automaton, its fine transition function $\phi : \text{Conf} \rightarrow \text{Conf}$ is defined as $|\phi(c)| := \text{det}(c)$ and $\phi(c)(g) := q_{c,g}$, *i.e.* $\phi(c)(g) = \delta(c' \blacktriangleleft g)$ for any $c' \in Q^N$ such that $c' \upharpoonright |c_g| = c_g$.

Proposition 30. The fine transition function ϕ is well defined.

Proof. This is the case precisely because we restrict the support of $\phi(c)$ to the determined subset of the c . \square

Proposition 31. Consider the constant cellular automaton $\delta(c) = q \forall c \in Q^N$ for a specific $q \in Q$ and regardless of the neighborhood N chosen to represent it. We have $|\phi(c)| = G$ for any $c \in \text{Conf}$.

Proof. Indeed, even with no data at all, *i.e.* for c such that $|c| = \emptyset$, the result at all position is determined and is q . \square

3.2.2 Characterization as a Right Kan Extension

As for the coarse transition function, the fine transition function ϕ is defined on the set of all configurations Conf and we claim that it is generated, in the Kan extension sense. We consider two ways to generate it and start by the simplest one. The second one is considered in the following section using sub-local configurations to be closer to the direct definition.

Proposition 32. *For any $g \in G$, the function $-_g : \text{Conf} \rightarrow \text{Conf}$ of Definition 27 is monotonic.*

Proof. As one can easily check. \square

Proposition 33. *The fine transition function ϕ is monotonic.*

Proof. Indeed, take $c_0, c_1 \in \text{Conf}$ such that $c_0 \preceq c_1$. We want to prove that $\phi(c_0) \preceq \phi(c_1)$ and this is equivalent to:

$$\begin{aligned} & \forall g \in |\phi(c_0)|, g \in |\phi(c_1)| \wedge \phi(c_0)(g) = \phi(c_1)(g) \text{ (Def 10 of } \preceq) \\ \iff & \forall g \in \det(c_0), g \in \det(c_1) \wedge q_{c_0, g} = q_{c_1, g} \text{ (Def 29 of } \phi) \end{aligned}$$

Take $g \in \det(c_0)$. We want to prove that $g \in \det(c_1)$, which means by Definition 28 of $\det(c_1)$:

$$\exists q \in Q, \forall c'_1 \in Q^{g \cdot N}, c'_1 \upharpoonright |c_{1g}| = c_{1g} \implies \delta(c'_1 \blacktriangleleft g) = q$$

We claim that the property is verified with $q = q_{c_0, g}$. Indeed, take any $c'_1 \in Q^{g \cdot N}$ such that $c'_1 \upharpoonright |c_{1g}| = c_{1g}$. We also have that $c'_1 \upharpoonright |c_{0g}| = c_{0g}$ since the hypothesis $c_0 \preceq c_1$ implies $c_{0g} \preceq c_{1g}$ by Proposition 32. By Definition 28 of $\det(c_0)$, we obtain that $\delta(c'_1 \blacktriangleleft g) = q_{c_0, g}$, so $q = q_{c_0, g}$ has the wanted property, which implies that $g \in \det(c_1)$ as wanted. But the above property of q set it to be precisely what we denote by $q_{c_1, g}$ (Def 28 of $q_{c_1, g}$), so $q_{c_0, g} = q_{c_1, g}$. \square

Proposition 34. *The fine transition function ϕ is the right Kan extension of the global transition function Δ along the inclusion $i : Q^G \rightarrow \text{Conf}$.*

Proof. By Definition 16 of right Kan extensions, we need to prove firstly that ϕ is such that $\phi \circ i \Rightarrow \Delta$, and secondly that it is greater than any other such monotonic functions.

For the first part, we actually have $\phi \circ i = \Delta$ since for any $c \in Q^G$, $|\phi(c)| = \det(c) = G = |\Delta(c)|$ and for any $g \in G$, we have $\phi(c)(g) = q_{c, g} = \delta(c_g \blacktriangleleft g) = \delta((c \upharpoonright g \cdot N) \blacktriangleleft g) = \delta((c \blacktriangleleft g) \upharpoonright N) = \Delta(c)(g)$ by Defs. 29, 28, 27, 2 of ϕ , \det , c_g and Δ and Prop. 8.

For the second part, let $f : \text{Conf} \rightarrow \text{Conf}$ be a monotonic function such that $f \circ i \Rightarrow \Delta$. We want to show that $f \Rightarrow \phi$, which is equivalent to:

$$\begin{aligned} & \forall c \in \text{Conf}, f(c) \preceq \phi(c) \text{ (Def. 14 of } \Rightarrow) \\ \iff & \forall c \in \text{Conf}, \forall g \in |f(c)|, g \in |\phi(c)| \wedge f(c)(g) = \phi(c)(g) \text{ (Def. 10 of } \preceq) \\ \iff & \forall c \in \text{Conf}, \forall g \in |f(c)|, g \in \det(c) \wedge f(c)(g) = q_{c, g} \text{ (Def. 35 of } \phi) \\ \iff & \forall c \in \text{Conf}, \forall g \in |f(c)|, \forall c' \in Q^{g \cdot N}, c \preceq c' \implies f(c)(g) = \delta(c' \blacktriangleleft g) \text{ (D. 28)} \end{aligned}$$

So take $c \in \text{Conf}$ and $g \in |f(c)|$ and $c' \in Q^{g \cdot N}$ such that $c \preceq c'$. Consider any $c'' \in Q^G$ such that $c' \preceq c''$ (or equivalently $c'' \upharpoonright g \cdot N = c'$). Since f is monotonic, we have $f(c) \preceq f(c'')$, which means that $f(c)(g) = f(c'')(g)$ by Def. 10. But since $f \circ i \Rightarrow \Delta$, we have $f(c)(g) = \Delta(c'')(g) = \delta((c'' \blacktriangleleft g) \upharpoonright N)$ by Def. 14 of \Rightarrow and Def. 2 of Δ . But by Prop. 8, $(c'' \blacktriangleleft g) \upharpoonright N = (c'' \upharpoonright g \cdot N) \blacktriangleleft g = c' \blacktriangleleft g$. \square

3.3 Introducing Sub-Local Configurations

The direct definition of the fine transition function is explicitly about assigning a result for a configuration c at a given $g \in G$ even when the whole neighborhood $g \cdot N$ is not complete. By isolating these “shifted sub-local configuration” in the poset of configurations, we can (right-)extend the local transition to them and show that, in the same way as the coarse transition function is the left Kan extension of the local transition function, the fine transition function is the left Kan extension of the sub-local transition function.

3.3.1 Direct Definition

Definition 35. We define $\text{Sub} = \bigcup_{g \in G, M \subseteq N} (\{g\} \times Q^{g \cdot M})$ with partial order defined as $(g, c) \preceq (g', c')$ if and only if $g = g'$ and $c \preceq c'$. The “fully shifted sub-local transition function” $\underline{\delta} : \text{Sub} \rightarrow \text{Conf}$ is defined, for any $g \in G$, any $M \subseteq N$ and any $c \in Q^{g \cdot M}$, as $|\underline{\delta}(g, c)| = \{g\} \cap \det(c)$ and, if $g \in \det(c)$, $\underline{\delta}(g, c)(g) = q_{c', g}$, i.e. $\underline{\delta}(g, c)(g) = \delta(c' \blacktriangleleft g)$ for any $c' \in Q^{g \cdot N}$ such that $c = c' \upharpoonright |c|$. The second projection of Sub is the function $\pi_2 : \text{Sub} \rightarrow \text{Conf}$ defined as $\pi_2(g, c) = c$.

In this definition, a given sub-local configuration can result either in an empty configuration when the transition is not determined, or in a configuration with only singleton support when the transition is determined.

Note that for a given cellular automaton, it is possible to restrict the poset Sub to an antichain. Indeed, any time a result is determined by a sub-local configuration (g, c) , all bigger sub-local configuration (g, c') with $c \preceq c'$ does not contribute anything new. We do not elaborate on this because this antichain would be different for each cellular automaton, blurring the global picture presented below.

3.3.2 Characterization as a Right Kan Extension

Proposition 36. The fully shifted sub-local transition function $\underline{\delta}$ is monotonic

Proof. As usual, take $(g, c), (g', c') \in \text{Sub}$ such that $(g, c) \preceq (g', c')$. First note that $g = g'$ by Definition 35. We want to prove that $\underline{\delta}(g, c) \preceq \underline{\delta}(g, c')$ and this is equivalent to:

$$\begin{aligned} & \forall h \in |\underline{\delta}(c)|, h \in |\underline{\delta}(c')| \wedge \underline{\delta}(c)(h) = \underline{\delta}(c')(h) \\ \iff & \forall h \in \{g\} \cap \det(c), h \in \{g\} \cap \det(c') \wedge q_{c, g} = q_{c', g} \\ \iff & g \in \det(c) \implies g \in \det(c') \wedge q_{c, g} = q_{c', g}, \end{aligned}$$

by Definition 6 of \preceq and Definition 35 of $\underline{\delta}$. The end of this proof is similar to the one of Proposition 33. \square

Proposition 37. The fully shifted sub-local transition function $\underline{\delta}$ is the right Kan extension of the fully shifted local transition function $\bar{\delta}$ along the inclusion $i : \text{Loc} \rightarrow \text{Sub}$.

Proof. By Definition 16 of right Kan extensions, we need to prove firstly that $\underline{\delta}$ is such that $\underline{\delta} \circ i \Rightarrow \bar{\delta}$, and secondly that it is greater than any other such monotonic functions.

For the first part, $\underline{\delta} \circ i \Rightarrow \bar{\delta}$ is equivalent to:

$$\begin{aligned} & \forall (g, c) \in \text{Loc}, \underline{\delta}(g, c) \preceq \bar{\delta}(g, c) \text{ (Def. 14 of } \Rightarrow) \\ \iff & \forall (g, c) \in \text{Loc}, \forall h \in |\underline{\delta}(g, c)|, h \in |\bar{\delta}(g, c)| \wedge \underline{\delta}(g, c)(h) = \bar{\delta}(g, c)(h) \text{ (D. 10 } \preceq) \\ \iff & \forall (g, c) \in \text{Loc}, g \in \det(c) \implies g \in |\bar{\delta}(g, c)| \wedge q_{c,g} = \bar{\delta}(g, c)(g) \text{ (Def. 35 of } \underline{\delta}) \\ \iff & \forall (g, c) \in \text{Loc}, g \in \det(c) \implies g \in \{g\} \wedge q_{c,g} = \delta(c \blacktriangleleft g) \text{ (Def 23 of } \bar{\delta}). \end{aligned}$$

This last statement is true by Def. 28 of $q_{c,g}$.

For the second part, let $f : \text{Sub} \rightarrow \text{Conf}$ be a monotonic function such that $f \circ i \Rightarrow \bar{\delta}$. We want to show that $f \Rightarrow \underline{\delta}$, which is equivalent to:

$$\begin{aligned} & \forall (g, c) \in \text{Sub}, f(g, c) \preceq \underline{\delta}(g, c) \text{ (Def. 14 of } \Rightarrow) \\ \iff & \forall (g, c) \in \text{Sub}, \forall h \in |f(g, c)|, h \in |\underline{\delta}(g, c)| \wedge f(g, c)(h) = \underline{\delta}(g, c)(h) \text{ (Def. 10)} \\ \iff & \forall (g, c) \in \text{Sub}, \forall h \in |f(g, c)|, h \in \{g\} \cap \det(c) \wedge f(g, c)(h) = q_{c,g} \text{ (Def. 35)} \end{aligned}$$

So take $(g, c) \in \text{Sub}$ and $h \in |f(g, c)|$. Consider any $c' \in \text{Loc}$ such that $c \preceq c'$. Since f is monotonic, we have $f(g, c) \preceq f(g, c')$, which means that $h \in |f(g, c')|$ and $f(c)(h) = f(c')(h)$ by Def. 10. But since $f \circ i \Rightarrow \bar{\delta}$, we have $h \in |\bar{\delta}(g, c')| = \{g\}$ and $f(g, c')(h) = \bar{\delta}(g, c')(h) = \delta(c' \blacktriangleleft g)$ by Def. 14 of \Rightarrow and Def. 23 of $\bar{\delta}$. Since this is true for any c' , this establishes exactly the defining property of $\det(c)$ by Def. 28. \square

3.3.3 The Second Approach as a Left Kan Extension

Proposition 38. *The projection function $\pi_2 : \text{Sub} \rightarrow \text{Conf}$ is monotonic.*

Proof. As can be readily checked in Definition 35 \square

Proposition 39. *ϕ is the left Kan extension of $\underline{\delta}$ along $\pi_2 : \text{Sub} \rightarrow \text{Conf}$.*

Proof. By Definition 16 of left Kan extensions, we need to prove firstly that ϕ is such that $\underline{\delta} \Rightarrow \phi \circ \pi_2$, and secondly that it is smaller than any other such monotonic functions.

For the first part, $\underline{\delta} \Rightarrow \phi \circ \pi_2$ is equivalent to:

$$\begin{aligned} & \forall (g, c) \in \text{Sub}, \underline{\delta}(g, c) \preceq \phi(c) \text{ (Defs. 14 and 35 of } \Rightarrow \text{ and } \pi_2) \\ \iff & \forall (g, c) \in \text{Sub}, \forall h \in |\underline{\delta}(g, c)|, h \in |\phi(c)| \wedge \underline{\delta}(g, c)(h) = \phi(c)(h) \text{ (Def 10 of } \preceq) \\ \iff & \forall (g, c) \in \text{Sub}, g \in \det(c) \implies g \in |\phi(c)| \wedge q_{c,g} = \phi(c)(g) \text{ (Def. 35 of } \underline{\delta}) \\ \iff & \forall (g, c) \in \text{Sub}, g \in \det(c) \implies g \in \det(c) \wedge q_{c,g} = q_{c,g} \text{ (Def 29 of } \phi), \end{aligned}$$

a most trivial statement.

For the second part, let $f : \text{Conf} \rightarrow \text{Conf}$ be a monotonic function such that $\underline{\delta} \Rightarrow f \circ \pi_2$. We want to show that $\phi \Rightarrow f$, which is equivalent to:

$$\begin{aligned} & \forall c \in \text{Conf}, \phi(c) \preceq f(c) \text{ (Def. 14 of } \Rightarrow) \\ \iff & \forall c \in \text{Conf}, \forall g \in |\phi(c)|, g \in |f(c)| \wedge \phi(c)(g) = f(c)(g) \text{ (Def. 10 of } \preceq) \\ \iff & \forall c \in \text{Conf}, \forall g \in \det(c), g \in |f(c)| \wedge q_{c,g} = f(c)(g) \text{ (Def. 29 of } \phi) \end{aligned}$$

So take $c \in \text{Conf}$ and $g \in \det(c)$. Since $c_g \preceq c$ and f is monotonic, we have $f(c_g) \preceq f(c)$. Moreover $\bar{\delta} \Rightarrow f \circ \pi_2$ and $(g, c_g) \subseteq \text{Sub}$ so $\underline{\delta}(g, c_g) \preceq f(c_g)$ by Definitions 14 and 23 of \Rightarrow and π_2 . By transitivity $\underline{\delta}(g, c_g) \preceq f(c)$. By Definition 35 of $\underline{\delta}$ and Definition 10 of \preceq , we therefore have $g \in |f(c)|$, and $f(c)(g) = \underline{\delta}(g, c_g)(g) = q_{c,g}$. \square

4 Final Discussion

There are additional simple structural facts to note about the monotonic functions considered. The first one is that the shift action on partial configurations, as given in Definition 6, is the right Kan extension of the shift action on global configurations, as given in Definition 2. Another one is that $\Phi \Rightarrow \phi$, hence the names of these transition functions, coarse and fine. In fact, any monotonic function $f : \text{Conf} \rightarrow \text{Conf}$ such that $\bar{\delta} \Rightarrow f \circ \pi_2$ is necessarily such that $\Phi \Rightarrow f \Rightarrow \phi$. This shows, in some sense, the efficiency of the simple constraints of monotonicity and $\bar{\delta} \Rightarrow f \circ \pi_2$.

In the formal development presented here, we explicitly “copy” a single local behavior δ on all $g \in G$ to obtain $\bar{\delta}$ and work with it. It is readily possible to put a different behavior on each $g \in G$, with no real modification to the proofs. The statements are therefore valid for non-uniform cellular automata and automata networks. As mentioned in the beginning, we did not even use the finiteness of the neighborhood either. At this point, the reader might have the feeling that these results are not really about cellular automata, and there are at least three answers to that. The first answer is that one could easily impose the shift and simultaneously prevent the use of a highly redundant “fully shifted local transition function”, but this requires using a category. The latter is very similar to the poset, except that the yes/no question “is this configuration a subconfiguration of this other one ?” is replaced by “where does this configuration appear in this other one ?” [4]. The goal of this paper is indeed to introduce the concepts needed for this other point of view, among many others. The second answer is that the proofs are more about the decomposition/composition process involved in the local/global definition of cellular automata. Because of the simplicity of cellular spaces, groups, the description is very simple to make “directly”. In other situations, a Kan extension presentation can be the most effective way to describe the spatial extensions/restriction, for example when the space is an evolving graph [4]. The third answer is that, with small modifications, this result is very related to the Curtis-Hedlung theorem. Indeed, if one restores the finite neighborhoods and finite states constraints, one can see that the poset of finite support configurations is a “generating” part of the poset of open subsets of the product topology. In this case, the fine transition function ϕ can be viewed as encoding an important part of the topological behavior of the global transition function Δ .

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