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Understanding the internal dynamics of elliptical galaxies without non-baryonic dark matter

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ABSTRACT

Assuming virial equilibrium and Newtonian dynamics, low-mass early-type galaxies have larger velocity dispersions than expected from the amount of baryons they contain. The conventional interpretation of this finding is that their dynamics is dominated by non-baryonic matter. However, there is also strong evidence that many low-mass early-type galaxies formed as tidal dwarf galaxies, which would contain almost no dark matter. Using an extensive catalogue of early-type galaxies, we therefore discuss how the internal dynamics of early-type galaxies in general can be understood by replacing the assumption of non-baryonic dark matter with two alternative assumptions. The first assumption is that Milgromian dynamics (i.e. M_{OD}ified Newtonian Dynamics [MOND]) is valid, which changes the effective gravitational force in the weak-field limit. The second assumption is that binary stars affect the observed line-of-sight velocity dispersions. Some moderate discrepancies between observed and predicted velocity dispersions remain also when these effects are implemented. Nevertheless, the observed velocity dispersions in early-type galaxies can then easily be explained without invoking the presence of non-baryonic dark matter in them, but with already documented variations of the galaxy-wide stellar initial mass function and non-equilibrium dynamics in some of the low-mass early-type galaxies.

Key words: galaxies: dwarf – galaxies: elliptical and lenticular, CD – galaxies: kinematics and dynamics.

1 INTRODUCTION

The currently prevailing cosmological model is the Λ cold dark matter (Λ CDM) model, which is named for the two principal components of the energy content of the Universe according to that model. These components are dark energy (represented by a cosmological constant Λ in Einstein's field equations) and non-baryonic CDM.

According to that model, the Universe has expanded to its present-day volume from an extremely dense configuration, and the initial distribution of CDM was not completely homogeneous. These inhomogeneities grow with time, and this effect is the strongest in the regions with the highest initial densities. Thus, the density contrast between the densest regions of the Universe and the overall density of the Universe increases with time. When the density contrast between a certain region of space and the overall density of the Universe surpasses a critical value, this region decouples from the overall expansion of the Universe completely, and the CDM within it collapses into a self-gravitating CDM-halo.

Out of the baryons that are captured within the CDM-haloes during their collapse, the first galaxies of the Universe are thought to form. The number of CDM-haloes predicted by the model decreases with increasing mass (Guo et al. 2011), so that the Λ CDM-model predicts a large number of primordial dwarf galaxies (PDGs) with masses $M < 10^{10} M_{\odot}$ that form within CDM-haloes.

On the other hand, in encounters between gas-rich disc galaxies, the tidal forces acting on the discs can lead to the formation of long tidal tails in which self-gravitating structures may form, as numerical calculations have shown (Barnes & Hernquist 1992; Elmegreen, Kaufman & Thomasson 1993; Bournaud 2010). These newly formed structures have masses of up to $10^9 M_{\odot}$ (Elmegreen et al. 1993; Bournaud & Duc 2006) and have radii of the order of ~ 1 kpc (Wetzstein, Naab & Burkert 2007; Bournaud, Duc & Emsellem 2008). It has also been shown that these objects can survive on a time-scale of 10^9 yr with sites of long-lasting star formation (Bournaud & Duc 2006; Recchi et al. 2007; Ploekinger et al. 2014). Given these properties, the structures emerging in the tidal tails can be considered galaxies (cf. Bournaud et al. 2007; Forbes & Kroupa 2011). Due to their small mass and their tidal origin, such galaxies have been named tidal dwarf galaxies (TDGs).

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The TDGs consist only of baryonic matter, even if the progenitors of the TDGs contained a substantial amount of CDM (Barnes & Hernquist 1992; Duc, Bournaud & Masset 2004; Bournaud & Duc 2006). The reason is that the baryonic matter that becomes part of a TDG has before the encounter been part of thin rotating discs, and therefore occupied only a small region in phase space. CDM, on the other hand, is distributed spheroidally and is made up of particles on random orbits, so that its density in phase space is low, while it occupies a large volume. However, in an encounter, only matter within the same region of phase space can end up on similar trajectories in phase space, while this is a prerequisite for the formation of a bound object through gravitational collapse (Bournaud 2010). Given that TDGs thus contain only negligible amounts of CDM, in contrast to PDGs with the same amount of baryonic matter, it would be natural if the PDGs and the TDGs would constitute populations that are distinguishable by their properties; not only due to their different origin, but also due to their different composition (Kroupa et al. 2010; Kroupa 2012; Dabringhausen & Kroupa 2013; Kroupa 2015).

Interacting galaxies with bridges of matter connecting them or elongated arc extending from them have indeed been observed (for instance the Antennae Galaxies and the Mice Galaxies), and already Zwicky (1956) argued that these filaments can be explained with tidal forces acting between the galaxies, and that new galaxies may form in them. The observed filaments indeed closely resemble the tidal tails that appear in numerical calculations of galaxy encounters and subsequent TDG formation (e.g. Barnes & Hernquist 1992; Elmegreen et al. 1993; Bournaud & Duc 2006; Wetzstein et al. 2007). Observed stellar systems that are candidates for TDGs due to their age and their vicinity to tidal tails to have been found by numerous authors (e.g. Mirabel, Dottori & Lutz 1992; Duc & Mirabel 1994, 1998; Monreal-Ibero et al. 2007; Yoshida et al. 2008; Duc et al. 2011; Duc et al. 2014).

The observed counterparts of the PDGs are usually thought to be dwarf elliptical galaxies (dEs; see Ferguson & Binggeli 1994 and Lisker 2009 for reviews on dEs) and dwarf spheroidal galaxies (dSphs; see Mateo 1998 for a review on dSphs). As far as their radii and ages are concerned, the observed dEs and dSphs have properties that seem consistent with the properties expected for PDGs (see e.g. Li, De Lucia & Helmi 2010 and Guo et al. 2011). If the low-mass dEs and dSphs are assumed to be in virial equilibrium and that Newtonian dynamics is valid in them, they also have mass-to-light ratios that cannot be explained with the amount of baryons they contain (Mateo 1998; Strigari et al. 2008; Wolf et al. 2010; Tollerud et al. 2012; Toloba et al. 2014). This seems consistent with the notion that these galaxies are embedded in CDM-haloes. To a lesser extent, elevated mass-to-light ratios have also been found for more massive and more luminous dEs (Toloba et al. 2014). Note that according to Ferguson & Binggeli (1994), there is no fundamental difference between dEs and dSphs except for their mass. For this reason, dSphs are considered low-mass dEs in the following.

Thus, on first sight it seems indeed like two distinct populations of dwarf galaxies can be identified in observations. The old, seemingly dark matter-dominated systems could be identified with the PDGs, and the young, star-forming systems near interacting galaxies can be identified with the TDGs, which supports the Λ CDM model (Kroupa et al. 2010). However, while observed TDG candidates usually are young, TDGs could theoretically also be almost as old as the Universe (Bournaud & Duc 2006; Ploechinger et al. 2014, 2015). The low age of most observed TDG candidates is most likely a selection effect, because they are usually identified by their close vicinity to interacting galaxies. However, as time passes by,

the TDGs are not necessarily close to their progenitors any longer, while the indications for an interaction between the parent galaxies become harder to observe. This raises the question what old TDGs would look like, and whether there are two old populations of which one can be associated with the PDGs and the other with the TDGs.

Dabringhausen & Kroupa (2013) argued that the dEs may be old TDGs, since the young observed TDG candidates would evolve naturally on to the sequence that dEs constitute in mass–radius parameter space. This notion is supported by the fact that the spatial distribution of dEs in the Local Group is highly anisotropic. Most of them can be attributed to one of four planar structures (Pawlowski, Kroupa & Jerjen 2013). The best known of these planar structures are the discs of satellite galaxies (DoSs) around the Milky Way (MW) and the Andromeda Galaxy (M31; Kroupa, Theis & Boily 2005; Metz & Kroupa 2007; Pawlowski, Pflamm-Altenburg & Kroupa 2012; Ibata et al. 2013). These DoSs appear to be rotationally supported structures (Metz, Kroupa & Libeskind 2008; Hammer et al. 2013; Ibata et al. 2013), and evidence for rotation being a common feature of DoSs has also been found outside the Local Group (Ibata et al. 2014). The formation of such rotationally supported planar structures would be natural if the low-mass dEs that constitute them are TDGs, but difficult to understand if they formed as primordial structures in agreement with the Λ CDM model (Kroupa et al. 2005; Pawlowski et al. 2012; Pawlowski et al. 2014). Some specific models for the formation of the satellite systems of the MW and M31 via the creation of TDGs have been tested successfully in numerical simulations (Fouquet et al. 2012; Hammer et al. 2013; Yang et al. 2014). Also, the number of satellite galaxies tends to be higher the more pronounced the bulge of a galaxy is, which again supports the notion that satellite galaxies are created through interactions and merger of primordial galaxies, since also the host galaxies become dynamically hotter through interactions (Kroupa et al. 2010; López-Corredoira & Kroupa 2016). Thus, there is evidence for the dEs being old TDGs instead of PDGs. However, if this is correct, the high-mass-to-light ratios derived for many dEs under the assumptions of virial equilibrium and Newtonian dynamics (cf. Mateo 1998; Strigari et al. 2008; Wolf et al. 2010; Tollerud et al. 2012; Toloba et al. 2014) cannot be explained with CDM, since TDGs contain no CDM (cf. Barnes & Hernquist 1992; Bournaud 2010).

Given the absence of CDM in dEs if they are old TDGs, we investigate how well the internal dynamics of early-type galaxies (ETGs) can be understood without CDM. To this end, we test in this paper how the dynamics of ETGs would be affected if the assumption that they contain CDM is replaced by one of two alternative assumptions, or the combination of the two alternative assumptions.

The first assumption that we consider is that the ETGs obey Milgromian dynamics (MODified Newtonian Dynamics [MOND]) instead of Newtonian dynamics. Milgromian dynamics has been suggested more than 30 yr ago by Milgrom (1983a) as a modification to Newtonian dynamics in the limit of very weak space–time curvature. So far, Milgromian dynamics has been very successful in quantifying the internal dynamics of galaxies without dark matter (Sanders & McGaugh 2002; Famaey & McGaugh 2012), even though it still has problems on larger scales (see discussion in Famaey & McGaugh 2012). There is a long history of studying the detailed dynamics of elliptical galaxies in Milgromian dynamics, from the most massive ellipticals (Milgrom & Sanders 2003; Schuberth et al. 2006; Tiret et al. 2007; Milgrom 2012) to the least massive ones (McGaugh & Wolf 2010; McGaugh & Milgrom 2013; Lüghausen, Famaey & Kroupa 2014), showing globally quite good

an agreement. In particular, scaling relations for the dark haloes inferred around ellipticals in Newtonian dynamics have been shown to conform to Milgromian expectations (Richtler et al. 2011). However, studies of individual ETGs also reveal that some problems can occur when the dynamics of ETGs is modelled only with Milgromian dynamics. For instance, Samurović (2014) considered a sample of 10 ETGs, and found that he can explain with his models the dynamics in the centres of nine of them without dark matter, if he assumes Milgromian dynamics instead of Newtonian dynamics. However, his models still imply dark matter at larger radii for five out of these nine ETGs. As an example for an ETG that can be modelled well with Milgromian dynamics instead of CDM, we mention NGC 5128 (Samurović 2010), while NGC 1399 is an example for a galaxy where models with Milgromian dynamics still imply the presence of dark matter (Richtler et al. 2008; Samurović 2016). However, Milgrom (2012) showed that in isolated ellipticals surrounded by a hot gas corona, his Milgromian predictions based on the hydrostatic equilibrium assumption are actually broadly correct in NGC 1521 out to no less than 200 kpc (corresponding to more than $10 R_e$ according to data on that galaxy in the NASA/IPAC Extragalactic Database¹), while problematic galaxies such as NGC 1399 tend to reside in the centre of galaxy clusters where additional missing mass is known to be needed (e.g. Angus, Famaey & Buote 2008). While many of the above studies test the gravitational potential of ETGs out to several effective radii, and also in great detail by taking, for instance, different assumptions on anisotropy into account, they also deal only with rather small samples of ETGs, or even individual ETGs. The reason is that these approaches usually rely on a sufficiently large number of objects that trace the potential of the studied galaxies, like a large population of globular clusters or a large number of planetary nebulae (or alternatively on large amounts of hot gas). The necessary data on the tracer population can only be obtained in rather expensive observations, if a suitable population exists at all around a given galaxy. For instance, the typical sizes of populations of globular clusters increase roughly with the luminosities of their host ETGs, which implies that low-mass ETGs only have a few globular clusters, if any. This is exemplified with the low-mass ETGs in the Local Group, which are mostly accompanied by no globular clusters, in contrast to massive ETGs like NGC 1399 or NGC 4486, which are accompanied by hundreds or even thousands of globular clusters. We therefore take here a different approach, which is to base our Milgromian estimate for each ETG on quantities that characterize every ETG and are relatively easy to observe. This allows us to consider a very large sample of ETGs that covers the whole luminosity range of ETGs, and use it to study the general trend of the Milgromian predictions, even though our estimate for each individual ETG is not very accurate. Another important caveat is that our approach is also not sensitive to the dynamics in the outskirts of the ETGs, in contrast to the more detailed studies mentioned above.

The second assumption is that we consider an influence of binary stars on the observed internal dynamics of a galaxy. A possible effect of binaries is often neglected in estimates of the mass of galaxy from its internal dynamics. However, binaries increase the observed internal velocity dispersions of galaxies, and thus lead to too high mass estimates from the internal dynamics if binaries are neglected (Kouwenhoven & de Grijs 2008). We note that Kouwenhoven & de Grijs (2008) discuss star clusters instead of ETGs. However, the underlying problem is in either case that the observed motion of

a single star is only due to the gravitational potential of the star cluster or the ETG to which it is bound, while the observed motion of the constituent stars of a binary has two components. The first component is the motion of these constituents is their motion as a gravitationally bound system around their common centre of mass. The second component is the motion of the centre of mass of the binary within the gravitational potential of the star cluster or the ETG. However, star clusters are in this context more complicated than ETGs, since star clusters typically have relaxation times lower than a Hubble time and can thus be dynamically evolved, while this can be excluded for ETGs (Forbes & Kroupa 2011). This means in particular that star clusters can become mass segregated, i.e. that more massive bodies slow down and tend to gather in the centre of the evolving star cluster due to energy equipartition (Binney & Tremaine 1987). This implies that the dynamics of more massive bodies becomes different to that of lighter bodies, and binaries as systems consisting of two stars are indeed expected to be more massive than single stars. Nevertheless, fig. 9 in Kouwenhoven & de Grijs (2008) suggests that in stellar systems that approach masses and effective radii of ETGs, the internal dynamics of binaries becomes an important component of the observed dynamics of the system, i.e. the combination of the internal dynamics of the binaries and their dynamics as systems within the potential of their hosts. It can therefore be concluded that the results by Kouwenhoven & de Grijs (2008) indicate that a population of binaries is also of relevance for our study on ETGs.

This paper is organized as follows. In Section 2, we give a brief description of the data that we use. In Section 3, it is described how the internal velocity dispersions of ETGs are estimated from the amount of baryonic matter they contain, assuming either Newtonian dynamics or Milgromian dynamics. It is also described in that section how binaries affect the observed internal velocity dispersion of ETGs, and it is discussed how mass estimates appearing in this paper shall be interpreted. In Section 4, the methods described in Section 3 are used to quantify the expected internal dynamics and the resulting mass estimates for a sample of over 1500 ETGs, from giant elliptical galaxies to dSphs. The calculated velocity dispersions are compared to observed values. In Section 5, we give our conclusions.

2 DATA

2.1 Selection criteria for the sample of ETGs

For a comparison between the theoretical predictions of the internal velocity dispersions in ETGs with observed values, an appropriate sample of ETGs is needed. In this paper, the catalogue of ETGs compiled by Dabringhausen & Fellhauer (2016) is used. This catalogue comprises 1715 ETGs, which span the whole luminosity range of ETGs from faint dSphs to giant elliptical galaxies. The quantities from that catalogue that are relevant for this paper are the effective half-light radii of the ETGs, R_e , their Sérsic indices, n , their observed central line-of-sight (LOS) velocity dispersions, σ_{obs} , and the masses of their stellar populations, M_s . We also collect their V -band luminosities, L_V , which are relevant for a discussion of the expected V -band mass-to-light ratios (M/L_V) of the galaxies. We require for all ETGs that we select from the catalogue by Dabringhausen & Fellhauer (2016) that at least M_s , R_e , n , and L_V are given, while a value for σ_{obs} can be missing. This results to a sample of 1559 ETGs, and for 723 of them we also have an estimate for their σ_{obs} from the catalogue by Dabringhausen & Fellhauer (2016). However, with some assumptions that are introduced in Section 3,

¹ <http://ned.ipac.caltech.edu/>

estimates on the expected LOS velocity dispersions of ETGs can be made based on their M_s , R_e , and n , and thus for every galaxy considered in this paper due to our selection criteria on ETGs from the catalogue by Dabringhausen & Fellhauer (2016).

While we refer the reader to Dabringhausen & Fellhauer (2016) for a detailed description of their catalogue, we also give in the following some basic information on the data in their catalogue that are relevant for this paper.

2.2 Effective half-light radii

The effective half-light radii, R_e , published in Dabringhausen & Fellhauer (2016) are based on observed values from a multitude of papers and have been homogenized for their catalogue. If angular radii are published in their sources, they transform them into pc using the distance estimates they adopted for the galaxies in their catalogue. Values for R_e given in pc in the source papers are transformed by Dabringhausen & Fellhauer (2016) into angular radii using the distance estimates given in the source papers, and then transformed back into pc again using the respective distance estimates listed in Dabringhausen & Fellhauer (2016).

2.3 Sérsic indices

The Sérsic indices, n , given in the catalogue by Dabringhausen & Fellhauer (2016) are adopted from the literature they used, if they are available there. If not, they calculate n from R_e using

$$\log_{10}(n) = 0.28 + 0.52 \log_{10} \left(\frac{R_e}{\text{kpc}} \right), \quad (1)$$

which is a relation that Caon, Capaccioli & D’Onofrio (1993) derived from observational data.

2.4 Velocity dispersions

In the context of this paper, we have to distinguish carefully between the LOS velocity dispersion of the tracer population due to the gravitational potential of the ETG, and the observed LOS velocity dispersion. We denote the former as σ_0 , and the latter as σ_{obs} . The two quantities are often used interchangeably, i.e. it is assumed that σ_{obs} indicates the motion of the tracer population due to the gravitational potential of their host system. However, this is conceptually wrong if the tracer population are binaries, i.e. systems with internal dynamics. Nevertheless, setting $\sigma_{\text{obs}} = \sigma_0$ is an extremely good approximation for ETGs above a certain luminosity limit, as will be discussed in Section 4.1.

Dabringhausen & Fellhauer (2016) follow the usual convention by designating the central LOS velocity dispersions of the ETGs as σ_0 , while the quantities that they actually list in their catalogue are values for σ_{obs} according to the above definitions for σ_0 and σ_{obs} . Their data on σ_{obs} are taken from the literature they use, if such a value was published there. If only the average observed LOS velocity dispersion within R_e , σ_e , is available from the literature they use, they estimate σ_{obs} using the relation

$$\log_{10} \left(\frac{\sigma_{\text{obs}}}{\text{km s}^{-1}} \right) = 1.0478 \log_{10} \left(\frac{\sigma_e}{\text{km s}^{-1}} \right) - 0.0909, \quad (2)$$

which is obtained from a least-squares fit to data on 260 ETGs in Cappellari et al. (2013), while taking the data on the velocity dispersions within the central parsec of the ETGs in Cappellari et al. (2013) as a measure for σ_{obs} . By construction, equation (2) cannot be used on ETGs with $R_e < 1$ kpc, which is why Dabringhausen &

Fellhauer (2016) set $\sigma_{\text{obs}} = \sigma_e$ for such ETGs. This is well motivated by the findings that $R_e = 1$ kpc corresponds to $n \approx 1.9$ according to equation (1), and that the velocity dispersion profiles of galaxies with $n \lesssim 2$ are almost flat within their R_e (Graham & Colless 1997; Simonneau & Prada 2004).

2.5 Masses of the stellar populations

The estimates on M_s given in Dabringhausen & Fellhauer (2016) are based on a large set of models for simple stellar populations (SSPs) by Bruzual & Charlot (2003). These SSPs are defined as stellar populations that have formed instantly at a certain time with a certain metallicity. More specifically, Dabringhausen & Fellhauer (2016) obtain M_s of a given ETG by first searching an SSP model by Bruzual & Charlot (2003) that represents the age and the colours of the ETG the best, then adopting the M/L_V predicted by the according SSP model as the M/L_V of the ETG, and finally multiplying this M/L_V by the L_V of the ETG. The colours of the ETGs serve in this context as indicators for the metallicities of their stellar populations, since the metallicity determines the colours of an SSP with a given age, while colours are much easier to observe than metallicities.

The data on the ages of the stellar populations of the ETGs that Dabringhausen & Fellhauer (2016) use in the estimates of M_s come from the literature that they consider, or are the average value of galaxies with similar L_V , if no age was published for a given ETG. Also the data on the colours that Dabringhausen & Fellhauer (2016) require for their estimates of M_s comes from the literature that they use, if such data is published there. If no data was published there, Dabringhausen & Fellhauer (2016) adopt colours that are typical for ETGs with similar L_V . There are also cases where only L_V is available for an ETG that Dabringhausen & Fellhauer (2016) consider. In that case, both age and colours are set to values that are typical for ETGs of that L_V .

Note that the ages considered for the stellar populations of the ETGs are characteristic ages, since the stellar populations of ETGs do not form instantly (see for instance Thomas et al. 2005 and Weisz et al. 2014). As a consequence, they are composed of stars with different metallicities, so that also the metallicities that are adopted for the stellar populations of ETGs are effective values that are supposed to characterize them with a single number. This implies that in reality the dependency between metallicities and colours of real stellar populations in ETGs is not necessarily as clear as suggested by SSP models.

Another important aspect about the values for M_s taken from the catalogue by Dabringhausen & Fellhauer (2016) is that in the SSP models on which they are based, the stellar initial mass function (IMF) is assumed to be canonical. According to the canonical IMF, the number of newly forming stars as a function of their mass is a power law with the Salpeter slope ($\alpha = -2.3$) for stellar masses above $0.5 M_{\odot}$, but with a flatter slope ($\alpha = -1.3$) for lower stellar masses. This canonical IMF is consistent with many observations in the solar neighbourhood, but there is also evidence for deviations from the canonical IMF in more distant stellar populations (see Kroupa et al. 2013 for a review on the IMF).

2.6 V-band luminosities

The data on L_V in the catalogue by Dabringhausen & Fellhauer (2016) are either based on direct observations of the individual ETGs, or are derived from these data using their statistical properties. Dabringhausen & Fellhauer (2016) prefer data for L_V based on direct observations, which they obtain from apparent V-band

magnitudes collected from many sources in the literature and the distance estimates they adopt for the according galaxies. They perform some basic homogenization for this type of data, using overlaps between the different samples of galaxies introduced in the literature that they use. This is done in order to take care of offsets between the different data samples, which most likely originate from observations with different telescopes at different times, and different procedures for data reduction. If no published value for the apparent V -band magnitude of a galaxy was available from the literature, while there was such data from neighbouring passbands, Dabringhausen & Fellhauer (2016) use linear relations between L_V and luminosities in those other passbands in order to estimate L_V of the galaxy.

It turns out that the availability of L_V is the bottleneck for our selection of ETGs from the catalogue by Dabringhausen & Fellhauer (2016) due to its key role for estimating M_s , so that in the end only 1559 ETGs of the 1715 ETGs listed in the catalogue by Dabringhausen & Fellhauer (2016) are considered here. Dabringhausen & Fellhauer (2016) found data on R_e for all ETGs in their catalogue but two, and thus they also give values for n for them, which are calculated by equation (1) if they found no previously published value for n . However, an estimate for M_s by the methods in Dabringhausen & Fellhauer (2016) is impossible without knowing L_V , while Dabringhausen & Fellhauer (2016) give an estimate for M_s also if only L_V is known, even though these estimates are by construction inferior to the estimates where they have additional observed parameters at their disposal.

3 METHODS

3.1 Predictions for the velocity dispersions in ETGs

3.1.1 General assumptions

With some additional assumptions apart from the ones Dabringhausen & Fellhauer (2016) made for their catalogue (see Section 2), the central velocity dispersion of an ETG is here estimated from its M_s , R_e , and n .

The first assumption is that the ETGs are not embedded in haloes of non-baryonic dark matter and that moreover mass follows light in them.

The second assumption is that M_s , i.e. the mass of the matter that is locked up in stars and stellar remnants, is indeed a good approximation for M , which denotes the mass of the total baryonic matter contained in the ETG. This assumption is motivated by the findings that ETGs contain little gas (Young et al. 2011) and dust (Dariush et al. 2016). Defining M_N as the mass that is projected within R_e , the combination of this assumption with the previous assumption implies that

$$M_N = \frac{M}{2} = \frac{M_s}{2}, \quad (3)$$

i.e. that M_N is half of the matter contained by the ETG, since the first assumption then implies that the stellar population does not vary throughout the ETG. Whether M_N indeed accounts well for the baryonic matter in the ETG is however also a question of how well the assumed SSP approximates the properties of the actual stellar population of the ETG. With a poor choice for the SSP, the estimate of M_N may be wrong by up to a factor of a few. The importance of the choice of the SSP (most notably the IMF with which it formed) is for instance illustrated in table 5 in Samurović (2014). However, even for a fixed IMF, different ages and metallicities can

imply substantial changes in M_N for a given luminosity. This can be seen for instance in the data by Bruzual & Charlot (2003), who provide the SSP-models on which our estimates of M_s and thus M_N are based. The combination of the first and the second assumption also implies that the composition of the stellar population does not change significantly spatially within the ETG.

The third assumption is that the density profiles of the ETGs can be approximated as spherically symmetric. As a consequence of this assumption, we use R_e in the following for estimating the masses and LOS velocity dispersions of the ETGs.

The fourth assumption is that the anisotropy parameter, β , of the galaxy is close to zero (cf. equation 4-53b in Binney & Tremaine 1987). This means that systematic patterns in the motions of the stars of the galaxy can be neglected. As a consequence, the mass of the ETG will be overestimated if $-\infty < \beta < 0$ (i.e. if the stellar orbits in the ETG are predominately circular) and underestimated if $0 < \beta < 1$ (i.e. if the orbits in the ETG are predominately radial).

The fifth assumption is that the ETG is in virial equilibrium. This means that the ETG has settled into a configuration where its gravitational potential and thus its density profile does not depend on time. This assumption implies in particular that the ETG is not significantly disturbed by tidal forces, i.e. external, time-dependent gravitational fields. Tidal fields increase the actually observed internal velocity dispersions and may even disrupt galaxies (Kroupa 1997; Fellhauer & Kroupa 2006; McGaugh & Wolf 2010; Casas et al. 2012; Yang et al. 2014; Domínguez et al. 2016).

Finally, as a sixth assumption, a law of gravity that governs the internal dynamics of the ETG has to be adopted. We discuss the case of Newtonian dynamics in Section 3.1.2 and the case of Milgromian dynamics in Section 3.1.3.

3.1.2 Newtonian dynamics

If Newtonian dynamics is adopted, and the other assumptions given in Section 3.1.1 are justifiable as well, the total mass of the ETG can be approximated with

$$M = M_s = \frac{K_V}{G} R_e \sigma_0^2, \quad (4)$$

which is a relation derived by (Bertin, Ciotti & Del Principe 2002) using the virial theorem (see their equation 7). In this equation, G is the gravitational constant, R_e is the effective half-light radius, σ_0 is the central LOS velocity dispersion of the tracer population, and K_V is the virial coefficient. Recall that even for ETGs in virial equilibrium, σ_0 is not necessarily equal to the observed LOS velocity dispersion, σ_{obs} (see Section 2.4). The equality of the total mass, M , and the total mass of the stellar population, M_s , follows from equation (3), and thus from the assumptions that we make for our study. The value for K_V depends on the Sérsic index n as

$$K_V(n) = \frac{73.32}{10.465 + (n - 0.94)^2} + 0.954 \quad (5)$$

according to equation (11) in Bertin et al. (2002).

In equations (4) and (5), M (which is equal to M_s in the context of this paper) is treated as an unknown parameter that can be estimated from observed values for R_e , n , and σ_0 . We now consider the case that M_s , R_e , and n are known parameters taken from the catalogue by Dabringhausen & Fellhauer (2016), while σ_N , i.e. the LOS velocity dispersion based on the assumption of Newtonian dynamics, is treated as the unknown parameter. In order to estimate σ_N , we

replace σ_0 in equation (4) with σ_N , and solve the equation for the unknown parameter. This yields

$$\sigma_N = \sqrt{\frac{2 G M_N}{K_V R_c}}, \quad (6)$$

where also equation (3) was used in order to replace M with M_N .

3.1.3 Milgromian dynamics

If Milgromian dynamics instead of Newtonian dynamics is assumed, another estimator for the LOS velocity dispersion is needed. One common choice for faint systems is based on the ‘deep-MOND virial relation’ (e.g. McGaugh & Milgrom 2013). However, given the wide range of internal accelerations probed by our sample, this estimator is not valid in most systems, and we thus take here a less precise but more general approach based on the ‘phantom dark matter’ distribution (see below).

The general idea of Milgromian dynamics is that, at the most basic level in highly symmetric systems, the gravitational acceleration, a is related to the gravitational acceleration according to Newtonian dynamics, a_N by

$$a_N = \mu(a/a_0) a, \quad (7)$$

where a_0 is the critical acceleration (Milgrom 1983a). Below a_0 , the gravitational force acting on a test particle is for a given matter distribution stronger than predicted by Newtonian dynamics. Note that the gravitational accelerations within the Solar system are higher than a_0 by at least four orders of magnitudes (cf. fig. 11 in Famaey & McGaugh 2012).

The transition between the regime of Newtonian dynamics and Milgromian dynamics is given by an interpolating function that has to satisfy

$$\mu(a/a_0) \rightarrow 1 \quad \text{for } a \gg a_0 \quad (8)$$

and

$$\mu(a/a_0) \rightarrow a \quad \text{for } a \ll a_0. \quad (9)$$

Even though gravitational accelerations in the Solar system are high compared to a_0 , this interpolating function is tightly constrained in its strong field limit from very precise constraints on the precession of Saturn perihelion obtained by Cassini radio science tracking data (Hees et al. 2016). However, the shape of the interpolating function in the range of accelerations probed by galaxies is less constrained, and according to Famaey & Binney (2005) and Zhao & Famaey (2006), a possible choice for the interpolating function there is the simple μ function,

$$\mu(a/a_0) = \frac{(a/a_0)}{1 + (a/a_0)}. \quad (10)$$

Inserting equation (10) into equation (7) and solving for a leads to

$$a = \frac{a_N}{2} \left(1 + \sqrt{1 + \frac{4 a_0}{a_N}} \right), \quad (11)$$

which relates the acceleration according to Milgromian dynamics to the acceleration according to Newtonian dynamics. Following Famaey & Binney (2005), we set $a_0 = 1.2 \times 10^{-10} \text{ m s}^{-2}$ in our paper.

More generally, Milgromian dynamics can be formulated such that the generalized Poisson equation is given as

$$\nabla^2 \Phi = 4\pi G \left[\rho_N + \frac{1}{8\pi G} \nabla \cdot \left[\left(\sqrt{1 + \frac{4 a_0}{a_N}} - 1 \right) \mathbf{a}_N \right] \right], \quad (12)$$

where the first term within the brackets on the right is the density of actual matter, ρ_N , and the second term follows from the potential this matter would create according to Newtonian dynamics (Milgrom 2010; Lüghausen et al. 2014). While this second term does not correspond to the density of a type of actual matter, it can be interpreted as the density of ‘phantom dark matter’, ρ_{PDM} (Lüghausen et al. 2014). Taking the sum of ρ_N and ρ_{PDM} as the apparent matter density in Milgromian dynamics, ρ_M , the Poisson equation assumes in Milgromian dynamics the same form that is known from Newtonian dynamics, but with ρ_M instead of ρ_N . On this basis, problems in Milgromian dynamics can be treated mathematically like problems in Newtonian dynamics, once ρ_M is known. Hence, M_M can in principle be found by integrating ρ_M over a volume and the velocity dispersion of a system that obeys Milgromian dynamics can be estimated with the equations that are known from Newtonian dynamics, if M_N is replaced with M_M .

In pure spherical symmetry, the Newtonian gravitational acceleration at the radius R of a spherical mass distribution is given as

$$a_N(R) = \frac{G M(R)}{R^2}, \quad (13)$$

where $M(r)$ is the total mass within the radius R and G is the Newtonian gravitational constant. At the radius R_c , a_N can be approximated with

$$a_N = \frac{G M_N}{R_c^2}. \quad (14)$$

Inserting equation (14) into equation (11) leads to

$$a = \frac{G M_N}{2 R_c^2} \left(1 + \sqrt{1 + \frac{4 a_0 R_c^2}{G M_N}} \right). \quad (15)$$

Equation (14) also implies that in Newtonian dynamics the mass M_N enclosed within the radius R_c can be expressed in terms of R_c and the acceleration a_N acting on a test particle at R_c . In analogy to this, an apparent mass according to Milgromian dynamics can be introduced as

$$M_M = \frac{a R_c^2}{G} = \frac{M_N}{2} \left(1 + \sqrt{1 + \frac{4 a_0 R_c^2}{G M_N}} \right), \quad (16)$$

where equation (15) was used for the last equality. Based on this estimate for the apparent mass, the prediction for the central LOS velocity dispersion in an ETG in Milgromian dynamics is

$$\sigma_M = \sqrt{\frac{2 G M_M}{K_V R_c}}, \quad (17)$$

which is analogous to equation (6) for Newtonian dynamics. We also have to assume that most of our systems will not be affected by the external field effect of Milgromian dynamics. Although this could be an issue for some of the faintest systems (McGaugh & Milgrom 2013) and those close to the centre of galaxy clusters, it is safe to assume that this will not affect the majority of our systems and the general trends (e.g. Richtler et al. 2011).

3.2 The effect of binaries on observed velocity dispersions

The catalogue by Dabringhausen & Fellhauer (2016) contains observed central LOS velocity dispersions, σ_{obs} , for many of the galaxies for which we predict σ_{N} and σ_{M} here. For a comparison between σ_{obs} and σ_{N} or σ_{M} , it has to be considered that σ_{N} and σ_{M} only quantify the velocity dispersion of a tracer population within the potential of the ETG. Suspecting similar conditions like among field stars in the MW, the tracer population that is used to infer σ_{obs} is not a population of only single stars, but a mixture of single stars and multiple systems, of which most are binaries (Abt & Levy 1976; Duquennoy & Mayor 1991). Thus, some members of the tracer population in actual ETGs possess an internal structure that influences σ_{obs} . We seek to quantify this influence in the following.

The orbital motions of stars in a binary system are uncorrelated with the orbital motions of the binary systems (and single stars) in the potential of the ETG. Thus, assuming that all stars are either single stars or part of a binary, the influence of binary stars on σ_{obs} can be quantified as

$$\sigma_{\text{obs}}^2 = (1 - f)\sigma_0^2 + f(\sigma_0^2 + \sigma_{\text{bin}}^2) = \sigma_0^2 + f\sigma_{\text{bin}}^2, \quad (18)$$

where f is the fraction of binaries among all centre-of-mass systems (i.e. single stars and binaries), σ_0 is the velocity dispersion of the centre-of-mass systems due to virialized motion in the potential of the ETG, and σ_{bin} quantifies the LOS component of the typical orbital velocity of the stars in binaries.

Gieles et al. (2010) derive an analytic approximation for σ_{bin} , which can be formulated as

$$\sigma_{\text{bin}}^2 = \frac{1}{3} \left(\frac{2q^{3/2}}{1+q} \right)^{4/3} \left(\frac{\pi G m_1}{2P} \right)^{2/3}, \quad (19)$$

where q is the mass ratio of the two components of the binary, m_1 is the typical mass of the more massive component of the binary, and P is the typical orbital period in the binaries.

In order to find an appropriate value for σ_{bin} , and consequently σ_{obs} , the properties of the binary populations in ETGs have to be constrained. As the ETGs have old stellar populations, the binaries that are relevant here are those, where the components are stars with masses of about one solar mass or less, i.e. G-stars or M-stars. Duquennoy & Mayor (1991) found that the distribution of orbital periods of G-dwarf binaries peak at $P \approx 180$ yr, and that the binary fraction for these systems is $f \approx 0.4$ when no constraints on P are made. Minor (2013) finds that the Fornax, Sculptor, and Sextans dSphs are consistent with having similar populations of binaries as the binary population that Duquennoy & Mayor (1991) observed in the Galactic field, while the Carina dSph either contains fewer binaries or binaries with wider separations. Relevant for an increase of σ_{obs} due to binaries are in particular the close binaries, since their components have higher orbital velocities (McConnachie & Côté 2010). For rather tight binaries (i.e. binaries with $P \lesssim 20$ yr), observations suggest $0.2 \lesssim f \lesssim 0.3$ (Carney et al. 2005; Marks & Kroupa 2011). In this paper, we use in equation (19) $q = 0.6$ (cf. Gieles et al. 2010), $P = 10$ yr, and $m_1 = 1 M_{\odot}$, which leads to $\sigma_{\text{bin}} = 2.3 \text{ km s}^{-1}$. In equation (18), we consider the cases $f = 0$ (i.e. no binaries) and $f = 0.3$.

In the following, predictions for σ_{obs} made with equation (18) for $f = 0.3$ will be denoted as $\sigma_{\text{N}}^{\text{bin}}$ if σ_0 in equation (18) is set to σ_{N} , and as $\sigma_{\text{M}}^{\text{bin}}$, if σ_0 in equation (18) is set to σ_{M} . For $f = 0$, binaries have no impact on the velocity dispersions, and they are denoted as σ_{N} for the Newtonian case and as σ_{M} for the Milgromian case. As

a summarizing term for different predictions for σ_{obs} , we will use σ_{pred} .

The number we calculate with equation (19), and consequently the estimates on σ_{obs} with equation (18) are no more than rough estimates. However, given the current knowledge on binary populations in ETGs (McConnachie & Côté 2010; Minor 2013), it seems unlikely that the effect of binaries on σ_{obs} will be much larger than what we consider with our assumptions. In any case, we note that the exponents in equation (19) are rather close to unity, so that the estimate of σ_{bin} , and the predictions for σ_{obs} of ETGs are of the right order of magnitude, if the values for the parameters f , q , m_1 , and P are.

We also note that in equation (19), binaries are considered as systems that obey Newtonian dynamics. It may therefore seem inconsistent to use σ_{bin} to estimate σ_{obs} with equation (18) in a system, where the motion of the centre-of-mass systems is assumed to obey to Milgromian dynamics. However, we assume $P = 10$ yr for the typical orbital period in binaries, and if the binary system has a total mass of $1 M_{\odot}$, $P = 10$ yr corresponds to a semimajor axis of almost 5 au with Kepler's third law. This is similar to the semimajor axis of the orbit of Jupiter, where the gravitational acceleration due to the Sun is still larger than a_0 by about than five orders of magnitude, as illustrated in fig. 11 in Famaey & McGaugh (2012).

Another important aspect about equation (19) is that it neglects the contribution of the less luminous component of the binary to σ_{bin} . Gieles et al. (2010) justify this by noting that the more massive component of the binary is also the more luminous, and thus has the most impact on σ_{obs} . This is a safe assumption also for the case of binaries in ETGs. The most important tracers for σ_{obs} in an ETG are stars with masses close to $1 M_{\odot}$, since these are the brightest stars that have not evolved into stellar remnants yet in old stellar populations, as they are usually found in ETGs. If such stars are one of the components in a binary, they are also very likely to be the more massive object in it, since a likely companion for a star with a mass close to $1 M_{\odot}$ in an ETG is either a less massive star that is still on the main sequence, or a white dwarf. Both these types of companions are certainly the less luminous component of the binary, and also white dwarfs are usually less massive than $1 M_{\odot}$, even if they originate from stars that were initially more massive than $1 M_{\odot}$ (see Kalirai et al. 2008).

3.3 Estimates for the mass-to-light ratios of ETGs

At least formally, mass estimates for ETGs can be made with equation (4) when σ_0 in equation (4) is replaced with σ_{N} , $\sigma_{\text{N}}^{\text{bin}}$, σ_{M} , $\sigma_{\text{M}}^{\text{bin}}$, and σ_{obs} . In the following, the resulting quantities will be denoted as M_{N} , $M_{\text{N}}^{\text{bin}}$, M_{M} , $M_{\text{M}}^{\text{bin}}$, and M_{obs} , respectively. As a summarizing term for M_{N} , $M_{\text{N}}^{\text{bin}}$, M_{M} , and $M_{\text{M}}^{\text{bin}}$, we use M_{pred} . When mass estimates are made from observational data, σ_{obs} is quite often identified with σ_0 in the literature. However, this is not strictly correct if the ETGs contain binaries, while it is generally an excellent approximation for ETGs with luminosities $L_{\odot} \lesssim 10^8 L_{\odot}$ (see Section 4.2).

While M_{N} would actually be an estimate for the real mass of an ETG, if it contains no binaries and its internal dynamics is Newtonian, the quantities $M_{\text{N}}^{\text{bin}}$, M_{M} , and $M_{\text{M}}^{\text{bin}}$ are not. Instead, they are best understood as quantities that allow us to decide how well M_{obs} can be understood from only the likely amount of baryons in the ETGs, given the additional assumptions laid out in Sections 3.1.3 and 3.2. $M_{\text{pred}} \approx M_{\text{obs}}$ indicates that the dynamics of the ETG can be explained without additional assumptions, while a possible

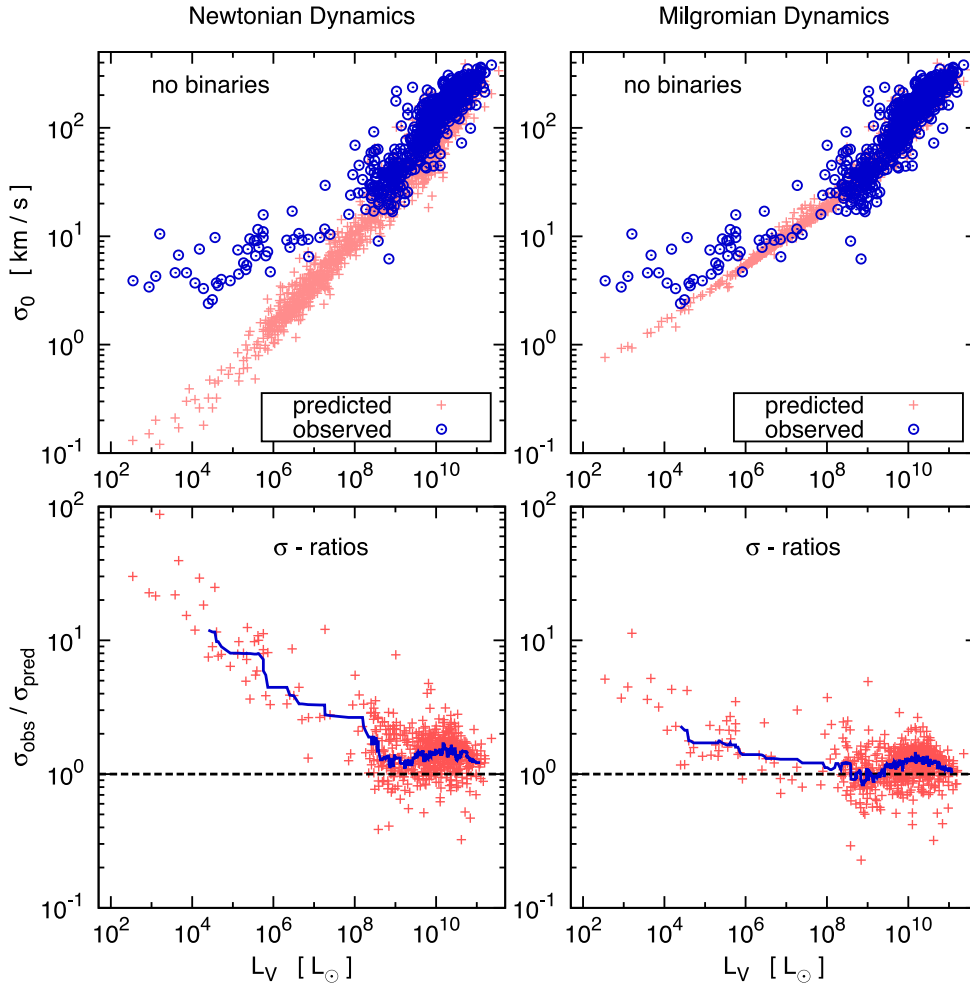


Figure 1. The Comparison between σ_{pred} and σ_{obs} of the ETGs, without considering a possible effect of binaries. In the panels on the left, Newtonian dynamics is assumed for calculating σ_{pred} , and Milgromian dynamics in the panels on the right. In the two top panels, the values for σ_{obs} are plotted on top of the values for σ_{pred} . The two bottom panels show the ratio between σ_{obs} and σ_{pred} for the ETGs, where both quantities are known. The solid lines in the bottom panels quantify the change of the median value of $\sigma_{\text{obs}}/\sigma_{\text{pred}}$ with luminosity. Note that the method for finding these median values does not allow us to assign median values to the luminosities of the 10 faintest and the 10 brightest galaxies shown in the figure. The dashed lines in these panels indicate equality between the predictions and the observations.

interpretation for $M_{\text{pred}} < M_{\text{obs}}$ is that the ETG contains additional, dark, but not necessarily non-baryonic matter.

For a discussion of the extreme mass-to-light ratios reported for many low-mass ETGs in the literature, we divide M_{pred} and M_{obs} by the V -band luminosities listed for these galaxies in the catalogue by Dabringhausen & Fellhauer (2016).

4 RESULTS

4.1 Velocity dispersions

Fig. 1 shows comparisons between σ_{N} and σ_{M} with σ_{obs} . Thus, a possible influence of binaries on the observed velocity dispersions of ETGs is neglected in Fig. 1. In the left-hand panels, the case of Newtonian dynamics is considered (i.e. the estimated velocity dispersion is σ_{N}), and in the right-hand panels, the case of Milgromian dynamics is considered (i.e. the estimated velocity dispersion is σ_{M}).

In the two top panels of Fig. 1, the observed internal velocity dispersions of the ETGs, σ_{obs} , are plotted on top of σ_{N} (left-hand panel) and σ_{M} (right-hand panel). In particular for ETGs with V -band lu-

minosities $10^5 L_{\odot} \lesssim L_V \lesssim 10^9 L_{\odot}$, σ_{N} and σ_{M} can be calculated for many ETGs, for which σ_{obs} is not yet known, and is quite challenging to observe. Note that due to our selection criteria on the ETGs in the catalogue by Dabringhausen & Fellhauer (2016), R_e , K_V (which is calculated from n with equation 5), and M_s are available for all ETGs considered in this paper, as is detailed in Section 2.1. The values for M_{N} and M_{M} follow from the M_s of the galaxies with the assumptions made in Section 3. Thus σ_{N} and σ_{M} can be calculated for all ETGs considered here with equations (6) and (17), respectively.

For the ETGs for which also σ_{obs} is known, $\sigma_{\text{obs}}/\sigma_{\text{N}}$ is shown in the lower left panel and $\sigma_{\text{obs}}/\sigma_{\text{M}}$ is shown in the lower right panel of Fig. 1.

The solid (blue) line in the bottom left panel of Fig. 1 serves as a quantification of a characteristic value for $\sigma_{\text{obs}}/\sigma_{\text{N}}$ in dependency of L_V . For obtaining this quantification, we consider all ETGs for which σ_{N} and σ_{obs} are known, and number them consecutively by ascending luminosity. From this list, we construct all possible subsets that contain 21 ETGs with consecutive numbers, i.e. all subsets that comprise all galaxies from the $i - 10$ th brightest to the $i + 10$ th brightest ETG on the list. These subsets are

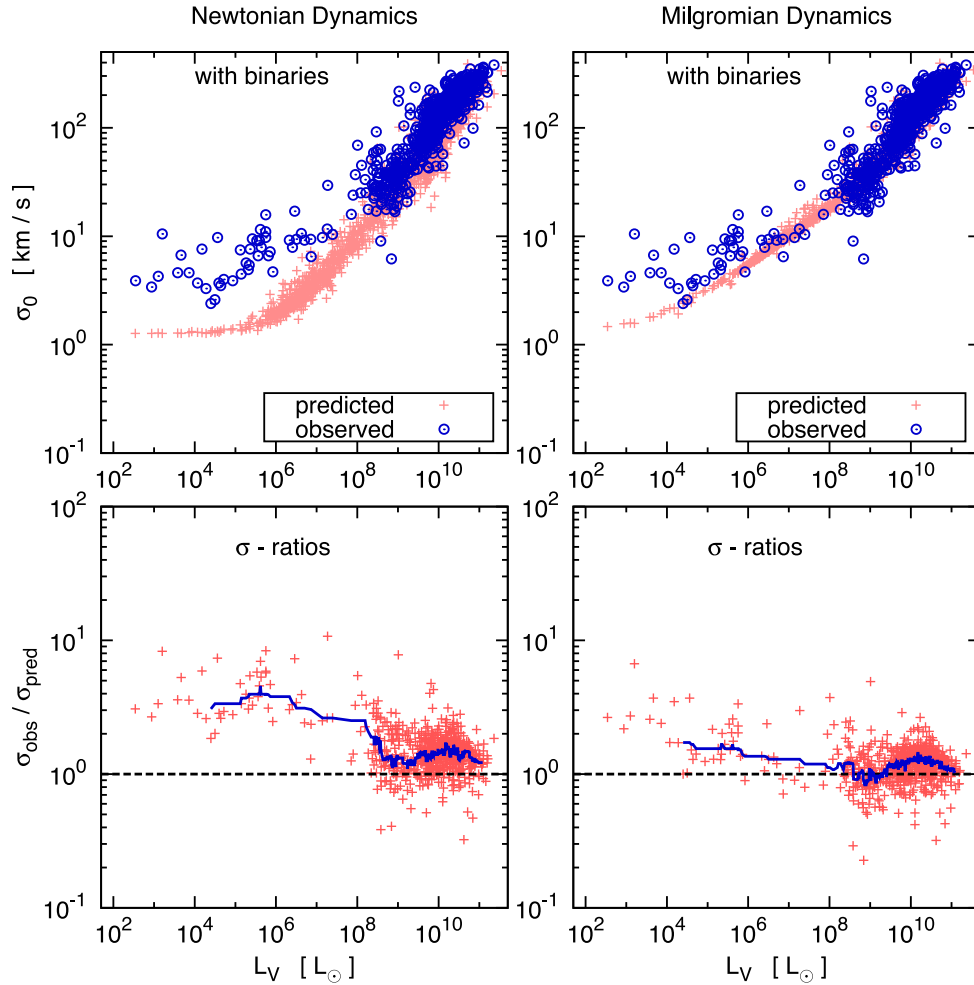


Figure 2. As Fig. 1, but assuming that 30 per cent of the stars in the ETGs are part of a binary.

then sorted by $\sigma_{\text{obs}}/\sigma_N$, and the 11th highest value for $\sigma_{\text{obs}}/\sigma_N$ among this subset is then chosen for the characteristic $\sigma_{\text{obs}}/\sigma_N$ for ETGs with the luminosity of the i th ETG. By construction, this method cannot assign characteristic $\sigma_{\text{obs}}/\sigma_N$ to the 10 least luminous and the 10 most luminous ETGs, but to all other ETGs. However, the advantage of this method is that the impact of ETGs with exceptional $\sigma_{\text{obs}}/\sigma_N$ on the estimates of the typical $\sigma_{\text{obs}}/\sigma_N$ is minimized.

The solid (blue) line in the right bottom panel of Fig. 1 shows the same quantity as the solid (blue) line in the bottom left panel of that figure, but for Milgromian dynamics instead of Newtonian dynamics.

Fig. 2 is organized as Fig. 1, but in Fig. 2, σ_N is replaced by σ_N^{bin} , and σ_M is replaced by σ_M^{bin} . Thus, the difference between Figs 1 and 2 is that in Fig. 2 the influence of binaries is taken into account, as described and quantified in Section 3.2.

It can be seen in Figs 1 and 2 that the *observed* internal velocity dispersions of ETGs with luminosities $L_V \lesssim 10^6 L_\odot$ depend only weakly on the luminosity of the galaxies, if at all. Together with the assumptions of Newtonian dynamics and a common characteristic radius of 300 pc for all low-mass ETGs, this observation is the basis for the claim by Strigari et al. (2008), which is a common mass scale of about $10^7 M_\odot$ for low-luminosity ETGs. Strigari et al. (2008) suggest this mass scale as the characteristic mass of the least-massive CDM-haloes, in which galaxies can form. The faintest

ETGs would consist almost exclusively of CDM according to this interpretation. Using $R_e = 300$ pc and the data on σ_{obs} in equation (4), this common mass scale of $10^7 M_\odot$ for low-luminosity ETGs can be reproduced quite well, even though Strigari et al. (2008) obtained their result from a more involved modelling of the velocity dispersions in CDM-haloes.

However, observationally, the characteristic radii of faint ETGs do depend on their luminosities, if R_e is taken as an indicator of the characteristic radii (see for instance, fig. 1 in Misgeld & Hilker 2011). This argues against the common mass scale for faint ETGs suggested by Strigari et al. (2008), because according to them, the faint ETGs would mostly consist of dark matter even in their centres. The dark matter would therefore dominate the internal dynamics of the galaxies. The most straight-forward expectation is in this case that the distribution of the baryons reflects the distribution of the dark matter, i.e. extended dark matter haloes would tend to contain extended galaxies. Thus, if the amount of baryonic matter the DM-haloes contain does not depend on the total mass of the DM-halo, the extension of the galaxies should not depend on their baryonic mass, and thus their luminosity. However, in reality, the least extended galaxies are also the ones that contain the least baryons. This would imply that the most concentrated dark matter haloes, which provide the deepest potential wells for a given halo mass, would nevertheless be the haloes that retain the least baryons, which is at least not intuitive. It is indeed problematic to reproduce the common mass

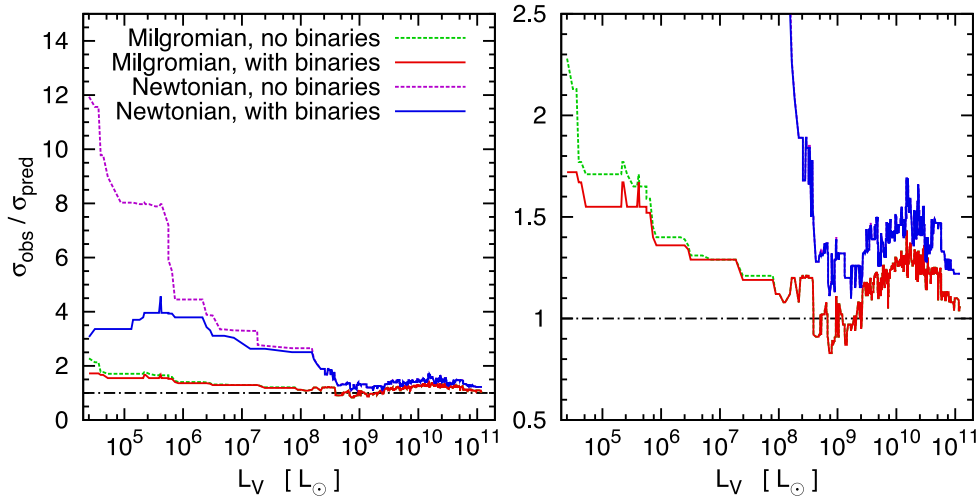


Figure 3. Comparison between the different relations quantifying the typical $\sigma_{\text{obs}}/\sigma_{\text{pred}}$ of ETGs, which are shown in the bottom panels of Figs 1 and 2. The different assumptions that enter the values for σ_{pred} are specified in the left-hand panel. The left-hand panel shows the full range of the relations, while the right-hand panel zooms in on the range where σ_{obs} and σ_{pred} are similar.

scale claimed by Strigari et al. (2008) in simulations (Kroupa et al. 2010).

Fig. 3 shows a comparison between the median ratios of $\sigma_{\text{obs}}/\sigma_{\text{pred}}$, which are shown in the bottom panels of Figs 1 and 2. It is thus shown in Fig. 3 how well σ_{obs} can be explained based on the probable amount of baryons in the ETGs, based on our assumptions regarding the laws of gravity governing the internal dynamics of ETGs (Newtonian dynamics or Milgromian dynamics), and our assumptions regarding the population of binaries in the ETGs. The dash-dotted line at $\sigma_{\text{obs}}/\sigma_{\text{pred}}$ indicates equality between predictions and observations. If the relations for the typical values for $\sigma_{\text{obs}}/\sigma_{\text{pred}}$ are above that line, then σ_{obs} tends to be larger than σ_{pred} . This is indeed the case for Newtonian dynamics at all luminosities, also when the effect of binaries on σ_{obs} is considered. Such a tendency also exists in Milgromian dynamics, but to a much lesser extent than in Newtonian dynamics. The conventional, but not the only way to interpret this finding is to assume that there is additional matter in the ETGs, which has not been accounted for in the estimates for σ_{pred} and M_{pred} .

Fig. 3 also illustrates that the impact of binaries on σ_{obs} is only noticeable below a certain luminosity. The reason is that σ_0 increases with mass (and thus luminosity) of the ETGs, while σ_{bin} is assumed to be the same in all of them, so that σ_{bin} has no appreciable impact on σ_{obs} for large σ_0 (cf. equation 18). In the case of Newtonian dynamics, binaries have virtually no effect on σ_{obs} of ETGs with $L_V \gtrsim 10^8 L_\odot$, but a very strong effect on ETGs with $L_V \lesssim 10^6 L_\odot$. Milgromian dynamics boosts σ_0 especially in the faint ETGs, which have a low density. Thus, in the case of Milgromian dynamics, the effect of binaries on σ_{obs} is much milder, and is unlikely to be of practical relevance in ETGs with $L_V \gtrsim 10^5 L_\odot$.

The best agreement between observations and predictions is achieved when Milgromian dynamics and a population of binaries are assumed for the ETGs. The median ratio between observed and predicted velocity dispersions rarely deviates by more than 30 per cent from unity. However, only for about 100 ETGs with luminosities between a few $10^8 L_\odot$ and a few $10^9 L_\odot$, the median ratio between observed and predicted velocity dispersions does not deviate significantly from unity. At other luminosities, the deviations may not be large, but they reflect properties of the data beyond

purely statistical effects. The trend to a larger-than-expected σ_{obs} for ETGs with high luminosities is based on data on 500 ETGs. For the ETGs with low luminosities, the trend for σ_{obs} being above the expectation for ETGs with $L_V < 10^7 L_\odot$ is based on only about 50 objects, but is undeniable nevertheless. If the ETGs are assumed to obey to Newtonian dynamics, or do not contain binaries, the modelled velocity dispersions underestimate the observed ones significantly more. On the other hand, the internal velocity dispersions of ETGs can neither in Milgromian dynamics nor in Newtonian dynamics fully be explained with our simple assumptions, even if every star is considered to be a part of binary (i.e. assuming $f = 1$ instead of $f = 0.3$), while leaving the other parameters unchanged. Also then, the low-mass ETGs would still have internal velocity dispersions which tend to be higher than predicted, while the assumed population would contain much more and much tighter binaries than what seems consistent with observed stellar populations (see Section 3.2 for a discussion of probable parameters for a population of binaries). This issue deserves more study though, because dynamical population synthesis predicts low-mass dwarf galaxies to have higher binary fractions than massive elliptical galaxies (Marks & Kroupa 2011), and our approach to quantifying the effect of binaries is quite approximate.

4.2 Mass-to-light ratios and masses

Figs 4 and 5 show comparisons between the predictions for the masses and mass-to-light ratios of ETGs.

The different predictions for the masses, M_{pred} , shown in Figs 4 and 5 are obtained with equation (4), using σ_{pred} (i.e. the different predictions for σ_{obs}), and σ_{obs} itself, respectively. As noted in Section 3.3, the resulting M_{pred} do not necessarily represent masses, in the sense that they actually measure the amount of matter in the galaxy. Instead, $M_{\text{N}}^{\text{bin}}$, M_{M} , and $M_{\text{M}}^{\text{bin}}$ are quantities that help to determine how well M_{obs} can be understood in terms of the assumptions that enter the estimates of $M_{\text{N}}^{\text{bin}}$, M_{M} , and $M_{\text{M}}^{\text{bin}}$, respectively. (M_{N} on the other hand is a real mass estimate, while the assumptions that enter it and the results obtained from it can be wrong.) M_{obs} is usually interpreted as an estimate for the actual mass of an ETG, but depends on assumptions itself, notably that Newtonian dynamics is valid in the ETGs, that the ETG is in virial equilibrium and that

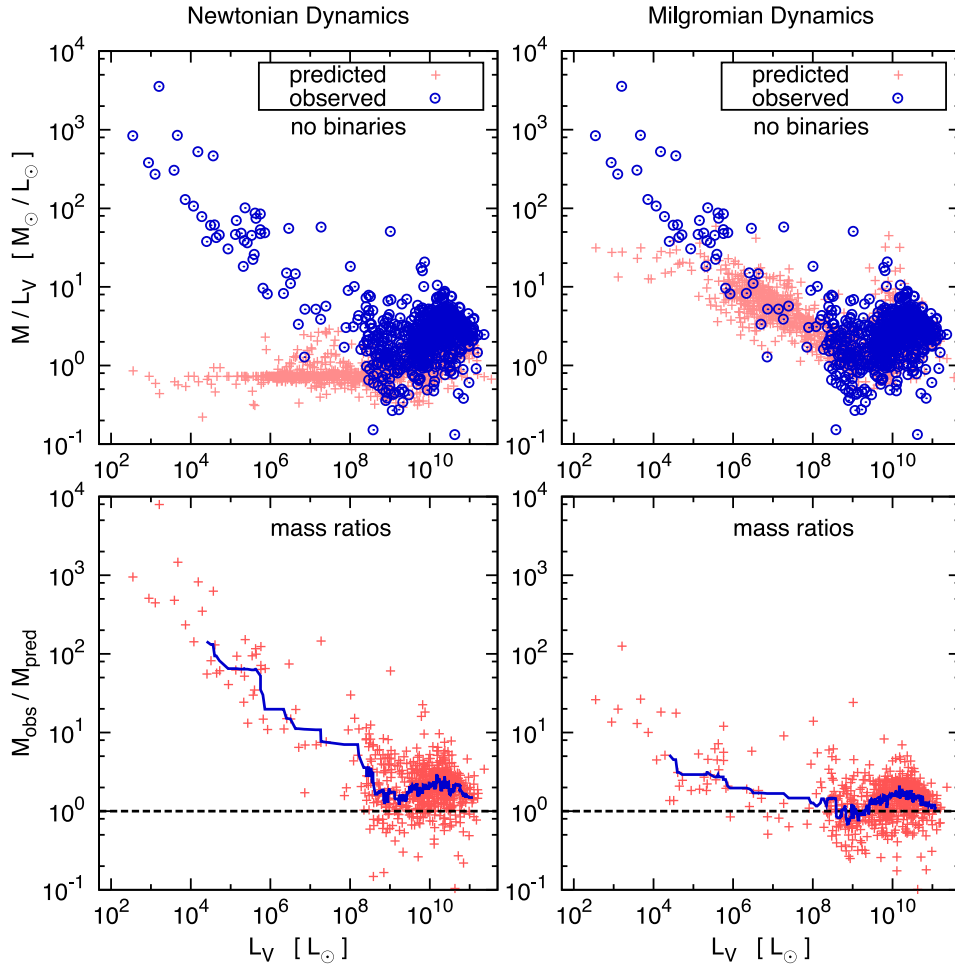


Figure 4. The Comparison between M_{pred} and M_{obs} of the ETGs, without considering a possible effect of binaries. In the panels on the left, Newtonian dynamics is assumed for calculating M_{pred} , and Milgromian dynamics in the panels on the right. In the two top panels, the values for M_{obs} are plotted on top of the values for M_{pred} . The two bottom panels show the ratio between M_{obs} and M_{pred} for the ETGs where both quantities are known. The solid lines in the bottom panels quantify the change of the median value of $M_{\text{obs}}/M_{\text{pred}}$ with luminosity. Note that the method for finding these median values does not allow us to assign median values to the luminosities of the 10 faintest and the 10 brightest galaxies shown in the figure. The method is described in detail in Section 4.1. The dashed lines in these panels indicate equality between the predictions and the observations.

the effect of binaries on σ_{obs} is negligible. However, in contrast to $M_{\text{N}}^{\text{bin}}$, M_{M} , and $M_{\text{M}}^{\text{bin}}$, M_{obs} , as well as M_{N} , truly measure the amount of matter in the ETG, if the assumptions made for estimating M_{obs} or M_{N} are correct. If $M_{\text{obs}} > M_{\text{N}}$, $M_{\text{obs}} > M_{\text{N}}^{\text{bin}}$, $M_{\text{obs}} > M_{\text{M}}$, or $M_{\text{obs}} > M_{\text{M}}^{\text{bin}}$ is found for an ETG, one way to interpret such a result is that the galaxy contains additional matter, while other interpretations are possible as well (see Section 5).

In Fig. 4, M_{obs} is compared to M_{N} and M_{M} , respectively. Thus, a possible effect of binaries on the mass estimates is neglected in this figure.

In the two top panels of Fig. 4, the estimates for M_{obs}/L_V are plotted on top of M_{N}/L_V (left-hand panel) and M_{M}/L_V (right-hand panel). In particular for ETGs with V -band luminosities $10^5 L_{\odot} \leq L_V \leq 10^9 L_{\odot}$, M_{obs} cannot be calculated for all ETG for which M_{N} and M_{M} can be calculated. The reason is that σ_{obs} is not yet known for many of these faint ETGs, since observations that allow us to derive their σ_0 become the more challenging, the fainter they are and the lower their surface brightness is. Thus, σ_0 has been estimated for many faint ETGs in the Local Group by now, but the majority of ETGs with V -band luminosities $10^5 L_{\odot} \leq L_V \leq 10^9 L_{\odot}$ shown in Fig. 4 are members of galaxy clusters other than the Local Group.

For them, the effort of estimating their σ_0 would require extremely deep and time-consuming observations, if they are possible at all with presently available instruments.

For all ETGs for which M_{obs} , M_{N} , and M_{M} are available, $M_{\text{obs}}/M_{\text{N}}$ is shown in the bottom left panel and $M_{\text{obs}}/M_{\text{M}}$ is shown in the bottom right panel. The solid (blue) lines in both panels quantify the median of the ratios $M_{\text{obs}}/M_{\text{N}}$, and $M_{\text{obs}}/M_{\text{M}}$, respectively, as a function of L_V . These relations are obtained as described in Section 4.1 for the median of $\sigma_{\text{obs}}/\sigma_{\text{N}}$.

Fig. 5 is organized as Fig. 4, but in Fig. 5, M_{N} is replaced by $M_{\text{N}}^{\text{bin}}$, and M_{M} is replaced by $M_{\text{M}}^{\text{bin}}$. Thus, the difference between the two figures is that in Fig. 5, the influence of binaries is taken into account in the predictions on the masses of ETGs.

Fig. 6 shows a comparison between the median ratios of $M_{\text{obs}}/M_{\text{pred}}$, as shown in the bottom panels of Figs 4 and 5. It is thus shown in Fig. 6, how well M_{obs} can be explained based on the probable amount of baryons in the ETGs, based on our assumptions regarding the laws of gravity governing the internal dynamics of ETGs (Newtonian dynamics or Milgromian dynamics), and our assumptions regarding the population of binaries in the ETGs.

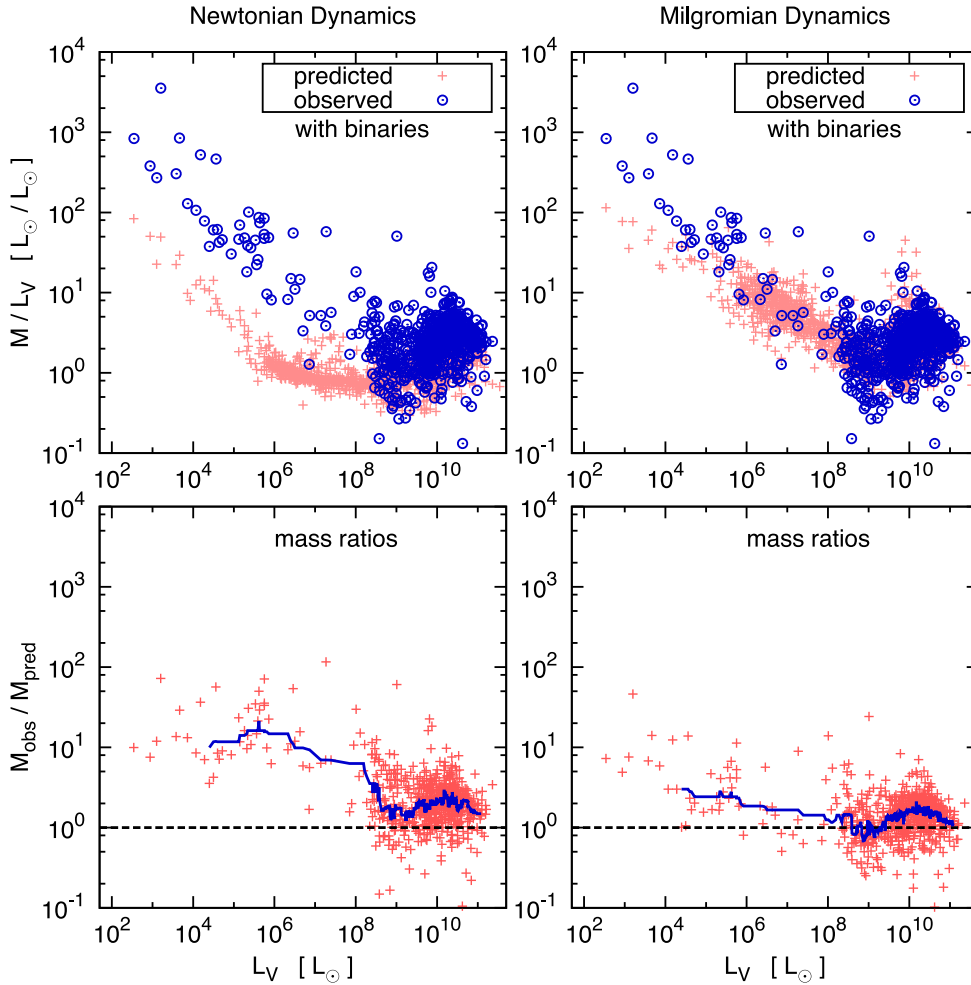


Figure 5. As Fig. 4, but assuming that 30 per cent of the stars in the ETGs are part of a binary.

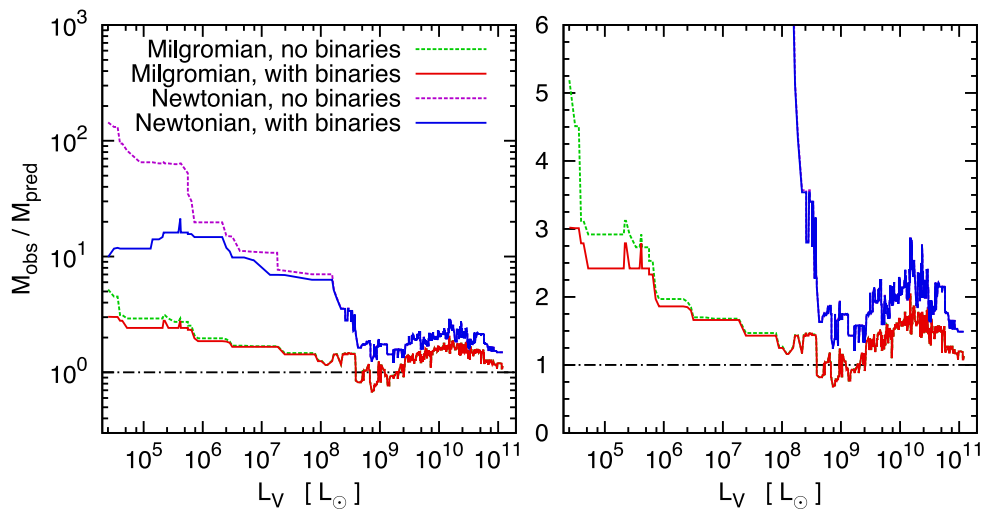


Figure 6. Comparison between the medians of the ratios between M_{obs} and the predicted masses of ETGs, as shown in the bottom panels of Figs 4 and 5. The left-hand panel shows the full range of the relations quantifying the ratios between M_{obs} and the predicted masses of the ETGs. The assumptions made for the different predictions on the masses of the ETGs are indicated in the left-hand panel of the figure. The right-hand panel of this figure shows the same relations as the left-hand panel, but zooms in on the range where the ratio between observed and predicted masses is close to unity.

Basically, Fig. 6 shows the same trends as Fig. 3. However, with Fig. 6, it is more straightforward to discuss what these trends imply for mass estimates and the matter content of ETGs. This is done in the following section.

5 DISCUSSION AND CONCLUSION

Motivated by the notion that many, if not most dEs might be TDGs (Okazaki & Taniguchi 2000; Kroupa et al. 2010; Dabringhausen & Kroupa 2013), and would then contain basically no dark matter (cf. Barnes & Hernquist 1992; Bournaud 2010), we discuss how the elevated internal velocity dispersions of ETGs could be understood without dark matter. In this context, we have made two assumptions, which are well motivated by observations. The first assumption is that the ETGs obey to Milgromian dynamics (Milgrom 1983a) instead of Newtonian dynamics. Milgromian dynamics formulates a deviation from Newtonian gravity in the limit of very weak gravitational fields, which is extremely successful in quantifying the dynamics of galaxies (Famaey & McGaugh 2012). The second assumption is that many stars are part of a binary system, as it is observed in resolved stellar populations (Duquennoy & Mayor 1991; Carney et al. 2005), including some low-mass dEs (Simon et al. 2011; Minor 2013).

It is well known that if virial equilibrium and Newtonian dynamics are assumed, the observed velocity dispersions, σ_{obs} , of ETGs tend to be larger than what is expected based on the baryonic matter in ETGs. This is true over the whole luminosity range of ETGs, even though the typical magnitude of the discrepancy depends on the luminosity of the ETGs (see Figs 1–3). Therefore, masses estimated based on σ_{obs} are larger than expected as well (see Figs 4–6). This discrepancy is probably even larger than apparent in this paper, since isotropy is assumed here for the stellar orbits in the ETGs (see the fourth assumption in Section 3.1.1), while the observed LOS velocity distributions of over 2000 ETGs studied by Vudragović, Samurović & Jovanović (2016) indicate that radial orbits are preferred over tangential orbits in them. Consequently, Vudragović et al. (2016) find for their sample of ETGs that more realistic mass estimates based on the internal dynamics are on average about 10 per cent higher than expected under the assumption of isotropy. The noted discrepancy between mass estimates based on the internal dynamics of ETGs and mass estimates based on the amount of baryons detected in them is usually interpreted as a presence of non-baryonic dark matter, especially in massive systems which are unlikely to be disturbed by tidal forces.

As it is expected, the discrepancy between observed and predicted velocity dispersions (and consequently the discrepancy on the mass estimates based on them) decreases if Milgromian dynamics instead of Newtonian dynamics is assumed. However, also in this case, there are luminosity intervals, where σ_{obs} is on average higher than values predicted based on the baryonic matter in the ETGs. This concerns objects more luminous than a few $10^9 L_{\odot}$ and objects less luminous than $10^6 L_{\odot}$.

In Newtonian dynamics, binaries could significantly boost the observed velocity dispersions of systems with luminosities $L_V \lesssim 10^6 L_{\odot}$, however not to an extent that the dynamics of the systems could be explained without dark matter, as long as they are in virial equilibrium. This does not exclude that the σ_{obs} of individual low-mass ETGs could be explained within the measurement uncertainties, if binaries are considered. However, the trend to strongly elevated σ_{obs} for the population of low-mass ETGs as a whole remains obvious (Hargreaves, Gilmore & Annan 1996; McConnachie & Côté 2010).

In Milgromian dynamics, the expected velocity dispersions of centre-of-mass systems in the gravitational potential of a galaxy are increased compared to the case of Newtonian dynamics. The contribution of binary stars to σ_{obs} is however independent of the motions of the stars in the potential of the galaxy. In consequence, the contribution of binary stars to σ_{obs} in Milgromian dynamics is small in comparison to the case of Newtonian dynamics; also because typical binary systems are so tightly bound that they can still be considered as Newtonian systems, so that assuming Milgromian dynamics has no effect on the orbital velocities of typical binaries. In consequence, the effect of binaries is rather weak on the σ_{obs} of ETGs with luminosities $L_V \lesssim 10^5 L_{\odot}$, and basically non-existent for more luminous ETGs. In Newtonian dynamics, the effect of binaries on σ_{obs} of low-luminosity ETGs is much more pronounced, and includes ETGs with luminosities $L_V \lesssim 10^6 L_{\odot}$ (see Fig. 3).

Thus, also in Milgromian dynamics, binaries cannot fully explain the high σ_{obs} of ETGs. This is even the case when the observationally motivated binary fraction $f = 0.3$ is increased to $f = 1.0$, while leaving the other parameters that describe the assumed binary population unchanged. In consequence, the observed σ_{obs} , and consequently the M_{obs} , tend to be elevated for ETGs with luminosities $L_V \lesssim 10^6 L_{\odot}$ and for ETGs with luminosities $L_V \gtrsim 10^{10} L_{\odot}$, even if Milgromian dynamics is assumed. We note that Janz et al. (2016) recently used the dynamical models of fast-rotator ETGs by Cappellari et al. (2015) based on ATLAS^{3D2} and SLUGGS³ data to show that Milgromian predictions based on the interpolating function used in this study (the ‘simple’ μ -function; equation 10) are globally well in-line with the data. However, they note that spiral galaxies are better fitted with the ‘standard’ interpolating function (equation 10 in Milgrom 1983b). Nevertheless, we insist on the fact that also the ‘simple’ μ -function has been shown in the past to reproduce brilliantly the rotation curves of spiral galaxies (Gentile, Famaey & de Blok 2011). The quality of the fits is in this case more a matter of the adopted stellar M/L ratios than of the adopted μ -function, and the M/L ratios of stellar populations depend on their age, their metallicity, and their IMF, which are all uncertain quantities for unresolved stellar populations.

However, apart from the inclusion of binaries, there are also two other assumptions made in this study that merit some discussion.

The first assumption is that the ETGs are in virial equilibrium. If this assumption is wrong, the mass of the system will be overestimated (see e.g. Kroupa 1997).

The second assumption is that the ETGs formed with a canonical IMF as it is parametrized in Kroupa (2001) or Chabrier (2003), i.e. an IMF that has the Salpeter-slope for stellar masses larger than $0.5 M_{\odot}$, but flattens for lower stellar masses.⁴ This assumption is implicitly made by adopting the values for the M_s of the ETGs taken from Dabringhausen & Fellhauer (2016). ETGs are stellar systems with rather old stellar populations, and in such systems there are in principle two possibilities how a variation of the IMF could increase the mass-to-light ratio with respect to the canonical IMF. The first possibility is an IMF overabundant in low-mass stars (bottom-heavy IMF), so that more mass is attributed to the total stellar population by a large population of very faint low-mass stars. The second possibility is an IMF overabundant in high-mass stars, which have

² <http://www-astro.physics.ox.ac.uk/atlas3d/>

³ <http://sluggs.swin.edu.au/Start.html>

⁴ Within observational limitations, both these formulations of the canonical IMF are identical (Kroupa et al. 2013).

evolved into stellar remnants. Thus, for a given luminosity, either a bottom-heavy IMF or a top-heavy IMF would imply a higher mass for the ETG in comparison to an ETG that formed with the canonical IMF (Cappellari et al. 2012).

Concerning the ETGs with luminosities $L_V \gtrsim 10^{10} L_\odot$, we note that their masses and densities imply that they can hardly be disturbed by tidal fields. Thus, the assumption of virial equilibrium is well justified for them. For their IMFs, we note that Tortora et al. (2014) already discussed the observed σ_{obs} and M_{obs} in the inner parts of 220 massive ETGs covered in the ATLAS^{3D} survey (Cappellari et al. 2011) under the premise of Milgromian dynamics instead of non-baryonic dark matter. They found that also in Milgromian dynamics, the observed σ_{obs} and M_{obs} are better explained with a Salpeter IMF, i.e. an IMF that has (in contrast to the canonical IMF) the Salpeter-slope down to the lowest stellar masses. Samurović (2014) confirms this trend in a very detailed study of 10 massive ETGs. However, since the canonical IMF has often been argued to be universal for all star formation based on observed stellar populations in the local Universe, indications for a Salpeter IMF in massive ETGs and a canonical IMF in nearby star clusters contradict the paradigm of an universal IMF (Kroupa et al. 2013). On the other hand, the notion of a canonical IMF in the most massive ETGs has indeed been challenged in the past years, not only based on their mass-to-light ratios. Some absorption lines in spectra of galaxies are sensitive to the presence of low-mass stars, and the observed strength of these spectral features in the most luminous ETGs have been taken as evidence that the IMF in them was highly bottom-heavy when most of their stars formed (van Dokkum & Conroy 2010; Ferreras et al. 2013). However, the high-mass-to-light ratios that the results by van Dokkum & Conroy (2010) imply may be in conflict with constraints on the mass-to-light ratios of elliptical galaxies set by mass estimates from gravitational lensing (Leier et al. 2016). Weidner et al. (2013), in contrast, argue that the galaxy-wide IMF in the most massive ETGs was top-heavy when most of their stars formed. They base their argument on the notions that the IMF may be top-heavy in the most massive star clusters (Dabringhausen et al. 2012; Marks et al. 2012), that massive star clusters form if its star formation rate in a galaxy is high (Weidner, Kroupa & Larsen 2004), and that the star formation rates in massive ETGs were high when they formed (Thomas et al. 2005). However, using the fact that neutron stars become visible as X-ray sources when they accrete matter, Peacock et al. (2014) searched for a dependency between the number of neutron stars per unit luminosity and the total luminosity of ETGs. Such a dependency would be expected, if the IMF for high-mass stars varies with the luminosity of ETGs, but Peacock et al. (2014) found that their results are consistent with a universal (i.e. non-varying, but not necessarily canonical) IMF in ETGs. However, Peacock et al. (2014) did not specifically test a galaxy-wide top-heavy IMF. Moreover, Peacock et al. (2014) implicitly assume Newtonian dynamics in their study and a more moderate variation of the IMF than the case they discuss is not excluded. Thus, in summary, the discrepancy between M_{pred} and M_{obs} lies well within the range of what could be explained with a variation of the IMF. However, the nature of the unidentified matter in centres of high-luminosity ETGs is still an open question, but it is not necessarily non-baryonic.

Concerning the ETGs with luminosities $L_V \lesssim 10^6 L_\odot$, i.e. the low-mass ETGs where σ_{obs} and consequently M_{obs} is also in Milgromian dynamics clearly above M_{pred} , we note that the Leo T dSph may contain more gas than stars (Belokurov et al. 2007), but usually dSphs contain only little baryonic matter apart from the baryonic matter in stars. Also a variation of the IMF could hardly

alter the mass of the stellar systems to the extent that Figs 4–6 imply for low-mass galaxies. However, at least in Newtonian dynamics, low-mass, dark matter-free systems in the MW are vulnerable to tidal forces, which can increase the internal velocity dispersions, and consequently elevate the estimates for the mass of the object under the (in this case wrong) assumption that they are in tidal equilibrium (Kroupa 1997; Casas et al. 2012, Domínguez et al. 2016). Tidal forces may even disrupt a stellar system. Such a system may still be detected as an overdensity of stars, for which σ_{obs} and R_e can be observed, but an estimate of the mass of the system based on equation (4), where virial equilibrium is assumed, is clearly impossible. If such an estimate is performed nevertheless, the result is an extreme overestimate of the mass of the object (Kroupa 1997).

Besides their (at least apparently) high-mass-to-light ratios, there is also other evidence for low-mass ETGs being tidally disturbed. McGaugh & Wolf (2010) found that the ellipticity of dwarf galaxies in the Local Group is correlated with their luminosity, so that the least luminous ETGs (i.e. the most vulnerable to tidal forces) tend to be the least spherical, and a departure from a round shape can be caused by external forces acting on a galaxy. Furthermore, McGaugh & Wolf (2010) find that the ETGs that are the closest to their hosts (the MW or M31), i.e. the ones that are subjected to the strongest tidal forces, also tend to be the ones that are the least spherical. More detailed observations of single galaxies show further peculiarities that can be interpreted as evidence for non-equilibrium dynamics for many of these ETGs, like elongated or irregular shapes, asymmetric surface-brightness profiles, or asymmetric velocity-dispersion profiles (e.g. Belokurov et al. 2006, 2007; Walker et al. 2009; Muñoz, Geha & Willman 2010; Willman et al. 2011; Deason et al. 2012). We note, however, that most if not all of these peculiarities can also be explained, if their stellar populations formed as groups of star clusters embedded in dark matter haloes (Assmann et al. 2013a,b). On the other hand, substructures are more likely to be preserved in cored dark matter haloes, which are motivated by observational properties of low-mass ETGs (Gilmore et al. 2007), but are still a huge challenge to Λ CDM theory, especially in low-mass galaxies (Governato et al. 2012; Di Cintio et al. 2014; Oñorbe et al. 2015).

Thus, the internal velocity dispersions and the internal structure of low-mass ETGs can in principle be understood as consequences of their formation in dark matter haloes, while for an explanation without dark matter non-equilibrium dynamics in low-mass objects has to be assumed. There is however strong evidence that many, if not most low-mass ETGs are TDGs (e.g. Kroupa et al. 2010; Dabringhausen & Kroupa 2013) and as such basically free of dark matter (e.g. Bournaud 2010). For instance, it is apparently quite common for low-mass ETGs to be part of rotationally supported discs of satellites around more massive galaxies (e.g. Ibata et al. 2014). This could easily be understood by the conservation of angular momentum in the encounters of primordial galaxies if the low-mass ETGs are TDGs, while the Λ CDM model predicts a much more isotropic distribution and predominately random motions for PDGs around their hosts (Kroupa et al. 2005; Pawlowski et al. 2014).

In the context of understanding ETGs (especially low-mass ETGs) as objects without non-baryonic dark matter, Milgromian dynamics makes the discrepancies between observed and predicted internal dynamics either disappear (at least for objects with luminosities close to $10^9 L_\odot$) or become less extreme and therefore easier to explain. For high-mass ETGs, assuming Milgromian dynamics implies that the discrepancy between observed and predicted internal velocity dispersions can be explained with a galaxy-wide

IMF that varies within reasonable parameters. For low-mass ETGs, assuming Milgromian dynamics implies that some of them are probably disturbed by tidal fields, but not necessarily all of them, as can be seen in Figs 1–3. This scenario appears more likely than the case that virtually *all* low-mass ETGs are out of virial equilibrium, as assuming Newtonian dynamics would suggest for them, unless they contain non-baryonic dark matter.

It remains to be seen how effective the creation of TDGs in Milgromian dynamics is, and how they evolve in the tidal fields in Milgromian dynamics, and thus how well the notion that low-mass ETGs are TDGs that obey Milgromian dynamics agrees with the observations. Candlish, Smith & Fellhauer (2015) and Lüghausen, Famaey & Kroupa (2015) have implemented Milgromian dynamics into the RAMSES code (Teyssier 2002), and have thereby created tools that will help to tackle such questions numerically. Ultimately, understanding the nature of low-mass ETGs, i.e. whether they are primordial objects that formed in dark matter haloes or whether they are TDGs, may help to create a revised cosmological model, since the doubts have been cast on the Λ CDM model, which is the currently prevailing cosmological model (Kroupa et al. 2010; Famaey & McGaugh 2012, 2013; Kroupa 2012, 2015).

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