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Roughness and scaling properties of oxide glass surfaces at the nanoscale

Zhen Zhang, Simona Ispas, and Walter Kob* Laboratoire Charles Coulomb (L2C), University of Montpellier and CNRS, F-34095 Montpellier, France (Dated: July 16, 2020)

Abstract

Using atomistic computer simulations we determine the roughness and topographical features of melt-formed (MS) and fracture surfaces (FS) of oxide glasses. We find that the topography of the MS is described well by the frozen capillary wave theory. The FS are significant rougher than the MS and depend strongly on glass composition. The height-height correlation function for the FS shows an unexpected logarithmic dependence on distance, in contrast to the power-law found in experiments. We thus conclude that on length scales less than 10 nm FS are not self-affine fractals. Surface roughness plays a crucial role for the functional properties of a material, including friction [1, 2], adhesion [3] and transport properties [4]. Understanding the nature and modifying this roughness is thus of great practical importance. In comparison with the surfaces of crystalline materials, the surfaces of amorphous materials such as glasses has received much less attention since the disorder renders the probing and characterization of such systems difficult [5–10]. Since a glass is an out of equilibrium system, the properties of its surface depends on the process by which it has been produced. Usually one considers two types of pristine (i.e., without post-processing) glass surfaces: i) Melt-formed surfaces (MS) which result from cooling a liquid with a free surface to the solid state and ii) Fracture surfaces (FS) resulting from a mechanical failure.

The topography of a MS is often described using the concept of a frozen liquid interface [11, 12], i.e., upon cooling the sample, the capillary waves at the surface freeze at a temperature T_0 . Thus the roughness of a pristine MS is predicted to be $\sigma = \sqrt{k_{\rm B}T_0/\gamma}$, where σ is the standard deviation of the surface height fluctuation, $k_{\rm B}$ is Boltzmann's constant, and γ is the surface tension at T_0 . Atomic force microscope (AFM) experiments on oxide glass surfaces have shown that this prediction works well if one uses for T_0 the glass transition temperature [13–15]. This theoretical framework also predicts that the height-height correlation function

$$\Delta z(r) = \sqrt{\left\langle [z(r+x) - z(r)]^2 \right\rangle_x} \quad , \tag{1}$$

which gives the height difference between two points separated by a distance r along a direction x, increases like $(\Delta z)^2 \propto \ln r$. This logarithmic dependence was validated experimentally with r ranging from around 10 nm to 1000 nm [13]. However, for r < 10 nm the dependence on r is basically unknown.

Describing the topography of the FS is more difficult than that for the MS since the former results from a highly non-linear process which involves a complex interplay between heterogeneities in the composition, microstructure, and mechanical properties present in a glass (see, e.g. [16–18] for reviews). Experimental studies of oxide glasses have shown that the roughness of the FS depends strongly on the composition [14, 19, 20] and is larger than the one found in MS [14]. AFM measurements have given evidence that the FS of various materials can be described as self-affine fractals [21], i.e., the height-height correlation function scales like $\Delta z \propto r^{\zeta}$. Here ζ is the roughness (or Hurst) exponent which was found to

depend on the fracture mode, the length scale considered, and the material [19, 20, 22–24]. However, whether this self-affine description for the FS holds also down to the nanometer scale is still an open question since at such small scales the finite size of the probing tip severely restricts the spatial resolution [25–27].

Here, using large scale atomistic simulations, we provide quantitative insight into the topographical features of oxide glasses for the length scales ranging from a few Angströms to several tens of nanometers. In particular we analyze the morphology, roughness, symmetry, and statistical scaling of the MS and FS, i.e., surfaces which have very distinct manufacturing histories.

We investigate two archetypical compositions for oxide glasses, namely pure SiO₂ and binary Na₂O-xSiO₂, with x = 3, 4, 5, 7, 10, and 20. The atomic interactions are described by a two-body effective potential (SHIK) [28, 29] which has been shown to give a reliable description of the structural, mechanical and surface properties of sodium silicate glasses [30, 31]. Our samples contain typically 2.3×10^6 atoms, corresponding to box sizes of around 20 nm×30 nm×50 nm (in the x, y, and z directions, respectively). Periodic boundary conditions were applied in the x and y directions while in the z-direction we introduced (in the melt) two free surfaces. The samples were melted and equilibrated at a high temperature (composition dependent) and then cooled down to 300 K under zero pressure. In the following we will refer to these two surfaces, generated by the melt-quench procedure, as MS. The glass samples were then subjected to an uniaxial tension with a strain rate of 0.5 ns⁻¹ in the y-direction until complete fracture occurred, creating thus two FS. The surface atoms were identified by using a well-established geometric method [32] which allows thus to study the topographical features of the surfaces. More details on the sample preparation and surface construction are given in the Supplemental Material (SM).

Figure 1 shows the (color coded) height fluctuations of the surfaces for three representatives compositions: Silica, NS10 ($\approx 9\%$ Na₂O), and NS3 (25% Na₂O). The top and bottom panels are for the MS and FS, respectively and the z = 0 level has been determined such that the mean of the fluctuations is zero. For the MS, panels (a-c), one recognizes that the amplitude of these height fluctuations seems to be independent of the composition, and that also the spatial extent of the structures are independent of the Na₂O content. In contrast to this, the FS, panels (d-f), show height fluctuations that are larger than the ones for the MS and clearly grow in amplitude and extent if the concentration of Na₂O increases. Also



Figure 1. Surface morphology. Melt-formed surfaces (a-c) and fracture surfaces (d-f) for three representative glass compositions. For the FS, the crack propagates in the negative y-direction and the crack front is parallel to the x-direction. From left to right the compositions are silica, NS10, and NS3, respectively.

one recognizes that the surfaces seem to be anisotropic and in the following we will quantify these observations.

Figures 2(a) and (b) show the distribution of the surface height z for different glass compositions. For the MS, panel (a), we find that this distribution is basically independent of the composition, in agreement with the snapshots shown in Fig. 1. In contrast to this, the distribution for the FS shows a clear dependence on the composition in that it becomes wider with increasing Na₂O concentration (i.e., smaller x). The change of the surface height distribution is directly related to the surface roughness σ , which is defined as the standard deviation of height fluctuations. (Note that σ of the FS is basically independent of the distance from the fracture origin, see Fig. S1.) Figure 2(c) shows σ as a function of the mole concentration of Na₂O. For the MS, σ is around 0.25 nm for silica and 0.23 nm for NS3, thus showing indeed a very mild dependence on the composition. This observation is likely related to the fact that the MS are rich in Na [31], i.e. a species that plastifies the glass, thus allowing to smooth out even small irregularities. Using the capillary wave theory mentioned above it is possible to estimate the roughness of the MS from the surface tension, and for the case of silica one finds $\sigma \approx 0.26$ nm (data point labelled "intrinsic") [14], in very good agreement with our simulation result.



Figure 2. (a) and (b): Surface height distribution as a function of the composition. The mean surface height $\langle z \rangle$ is equal to zero. Heights with z > 0 point towards the vacuum. (c) Roughness of the surfaces. The dashed lines are linear fits to the data. Experimental data are from Ref. [14]. The triangle corresponds to the intrinsic roughness of silica surface as estimated from the theory of frozen capillary waves. (d) Skewness of the surface height distribution.

The roughness of the FS is higher than the one for the MS, in agreement with the qualitative impression given by Fig. 1, and shows a clear dependence on the Na₂O content in that it increases from ≈ 0.42 nm for silica to ≈ 0.82 nm for NS3. The increase of σ with Na₂O concentration can be rationalized by the fact that, with the addition of Na, the glass becomes increasing ductile when subjected to mechanical loading [30, 33, 34]. This increase of ductility originates from the enhanced heterogeneities in the micro-structure and the local plasticity of the glass, leading to a rougher fracture surface [35, 36]. (See Fig. S2(a) for the dependence of σ on the strain rate.)

Also included in the graph are the experimental values of the roughness for silica glass surfaces as obtained from AFM measurements [14]. One observes that these experimental data are somewhat below our simulation values and the theoretical prediction (for the MS). This discrepancy might be due to the insufficient spatial resolution of this experimental technique (see also the discussion below).

A further property of interest is the symmetry of the surfaces, which can be quantified by the skewness γ_1 of the surface height distribution. The question of interest is whether or not the two sides of the surface (facing the vacuum/facing the glass) are statistically equivalent. Figure 2(d) shows that the MS have a negative γ_1 , i.e. there are more deep holes than high protrusions, while for the FS γ_1 is positive, i.e. there are more high protrusions than deep holes. The result for the FS is coherent with the view that during the fracture process the breaking of bridges or chain-like structures gives rise to a spiky surface. Note that a non-vanishing γ_1 indicates that the capillary wave theory cannot be strictly valid since this approach predicts $\gamma_1 = 0$. (See Fig. S3 for the surface properties at elevated temperatures.)

To characterize the structure of the surfaces on larger scales it is useful to look at the height-height correlation function defined in Eq. (1). Figure 3(a) shows $(\Delta z)^2$ as a function of r for the MS of silica and NS3. Two (orthogonal) directions are considered and, as expected, they give the same result, indicating that the MS is isotropic. Moreover, we note that the curves for silica are slightly above the ones for NS3, indicating that the MS of silica is a bit rougher than the one of NS3, in agreement with Fig. 2(c). One also observes that $(\Delta z)^2$ increases logarithmically with r, in agreement with the prediction of the frozen capillary wave approach [11]. Since AFM experiments on MS have found the same r-dependence for $r \geq 10$ nm [13], we can conclude that this theory gives a reliable description for length scales that range from the atomic (sub-nanometer) to the micrometer scale.



Figure 3. (a) and (b): Surface height correlation function (linear-log scale) for the MS (a) and FS (b). (c) and (d): Same data as in (a) and (b) but on log-log scale. Note that the ordinates for the left and right panels are not the same. The labels x and y correspond to the direction parallel to the crack front and the direction of crack growth, respectively.

For the FS, Fig. 3(b), we find that $\Delta z(r)$ (no square!) shows a linear increase with $\ln r$, thus a dependence that is very different from the one found for the MS. In this case the roughness depends on the direction in which it is measured. The curve for the *x*-direction (parallel to the crack front) is about 15% higher than the one for the *y*-direction (orthogonal to the crack front), irrespective of glass composition. In addition, the slope of the linear regime depends not only on the composition but also on the probing direction. This results indicate that the FS is anisotropic, and its roughness depends on the composition,

in agreement the experimental findings on the FS of oxide glasses [19, 20, 24]. Note that at large r all of the curves tend to saturate, a behavior that is most likely related to the fact that the sample is finite and hence fluctuations are bounded. The parameters obtained from a logarithmic fit to the small r data in panels (a) and (b), as well as for other compositions, are shown in Fig. S4. We also confirmed that the strain rate used for the fracture simulation has only a weak effect on these parameters [Fig. S2(b)].

In Fig. 3(c) and (d) we show on log-log scale the same data as plotted in Fig. 3(a) and (b), respectively. It is evident that this type of presentation of the data does not rectify it, demonstrating that on the length scales we have explored the height-height correlation is not given by a power-law, i.e. neither surface has the characteristics of a fractal. Instead, the $\ln r$ -dependence we find for the FS is in qualitative agreement with theoretical and numerical studies on the fracture surface of heterogeneous materials (mode I fracture, i.e. tensile loading) [37, 38].

Our finding that the FS cannot be described as a self-affine fractal on the length scales we have considered is at odds with AFM measurements that have reported a power-law dependence of $\Delta z(r)$ down to the scale of 1 nm [20, 24]. To elucidate the origin of this discrepancy one has to recall that the size of an AFM tip is finite which limits the lateral resolution of the measurements [25, 26] and can induces biases in the characterization of the surface [27].

In order to investigate the effect of spatial resolution we have convoluted our FS with a two-dimensional Gaussian filter [39] of width ω (see SM) and then recalculated the height-height correlation function for this smoothed surface. In Fig. 4 we show for the case of the FS of silica the resulting correlation functions for different values of ω . The curve $\omega = 0$ corresponds to the original (non-smoothed) data. We find that with increasing ω the value of Δz decreases significantly since the convolution irons out the deep holes/high spikes. Surprisingly, we note that at small r the convoluted signal can be described well with a power-law, and that the r-range in which this functional form is observed increases with ω while the exponent ζ is independent of w. For $\omega = 2.8$ nm, the correlation function of the convoluted surface in the y-direction [Fig. 4(a)] matches very well the AFM data by Ponson *et al.* [24]. The exponent of the power-law is $\zeta \approx 0.8$, i.e. the claimed "universal" roughness exponent found in previous experimental studies [16, 20, 23, 24]. The data in the x-direction, panel (b), shows qualitatively the same variation as the ones in the y-direction.

However, we find that one needs to apply stronger smoothing to match quantitatively the convoluted surfaces with the experimental ones, a result that is related to the fact that the FS is anisotropic and the surface profile in the direction parallel to the crack front is rougher than the one in the y-direction. These results indicate that the power-law observed in experiments on the scale of a few nanometers might be an artifact of insufficient resolution of the surface measurements and that in reality the correlation function takes higher values than that extracted from AFM studies.



Figure 4. Influence of spatial resolution on the surface height correlation for the FS of SiO₂. (a) and (b) are for the direction orthogonal and parallel to the crack front, respectively. A Gaussian filter (width ω) was applied to smooth the surface. The curves labeled $\omega = 0$ correspond to the original data. Also included are experimental data from AFM measurements of fracture surfaces produced by sub-critical crack propagation [20, 24].

In conclusion, the results of this work reveal how the topographical features of glass surfaces reflect the way they have been produced. While melt-formed surfaces can be described in a satisfactory manner by means of frozen capillary waves, surfaces originating from a fracture process exhibit a logarithmic growth of the height-height correlation, a result that so far has not been obtained from microscopic calculations. A recent atomistic simulation study of metal-based materials (in both crystalline and amorphous forms) has found that compression-induced rough surfaces are self-affine on the length scale of 1-100 nm, a result that was attributed to atomic-scale fluctuations in plastic flow [40]. Together with our simulation results one thus can conclude that, for amorphous solids, the surface topography on small length scales depends strongly on the manufacturing history and the type of material considered. Further research exploring how material composition and deformation mode affects the surface topography will thus be very valuable.

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* Corresponding author: walter.kob@umontpellier.fr

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Supplemental Material: Roughness and scaling properties of oxide glass surfaces at the nanoscale

Zhen Zhang¹, Simona Ispas¹, and Walter Kob¹

¹Laboratoire Charles Coulomb (L2C), University of Montpellier and CNRS, F-34095 Montpellier, France

In this Supplemental Material, we provide information regarding the following points: 1) Details of the simulation and sample preparation, 2) Details of the procedure used for constructing the surfaces, 3) Test whether roughness depends on the distance to origin of the fracture, 4) Influence of strain rate and temperature on surface topography, 5) Extracted parameters from the height-height correlation function, 6) Details on the surface smoothing.

1. Simulation details and sample preparation

We consider glasses with the composition SiO_2 and $Na_2O-xSiO_2$, NSx, with x =3, 4, 5, 7, 10, and 20. Approximately 2, 300, 000 atoms were placed randomly in the simulation box which had a fixed volume determined by the experimental value of glass density at room temperature [41]. Using periodic boundary conditions in three dimensions these samples were first melted and equilibrated at 6000 K for 80 ps in the canonical ensemble (NVT) and then cooled and equilibrated at a lower temperature T_1 (still in liquid state) for another 160 ps. The temperature T_1 ranges from 3000 K for SiO₂ to 2000 K for NS3 (25) mole % Na₂O), see Ref. [31, 36] for details. Subsequently we cut the sample orthogonal to the z-axis, and added an empty space, thus creating two free surfaces i.e. the sample had the geometry of a slab. Periodic boundary conditions were applied in all three directions. In order to ensure that the two free surfaces do not interact with each other, the thickness of the vacuum layer varied from 6 nm for silica to 14 nm for NS3. These samples were then equilibrated at T_1 for 1.6 ns, a time span that is sufficient to allow the reconstruction of the surfaces and the equilibration of the interior of the samples. Subsequently the liquid samples were cooled via a two-stage quenching: A cooling rate of $\gamma_1 = 0.125$ K/ps was used to quench the samples from T_1 to a temperature T_2 and a faster cooling rate $\gamma_2 = 0.375$ K/ps to cool them from T_2 to 300 K. Finally, the samples were annealed at 300 K for 800 ps. The temperature T_2 at which the cooling rate changes was chosen to be at least 200 K below the simulation glass transition temperature T_g , i.e., depending on composition, 1500 K $\geq T_2 \geq 800$ K, see Refs. [31, 36] for details. At T_2 , we also switched the simulation ensemble from NVT to NPT (at zero pressure) so that the generated glass samples were not under macroscopic stress at room temperature.

After the glass samples were prepared we introduced on one of its free surfaces a "scratch" in the form of a triangular notch spanning the sample in the y-direction of width and depth of 3 nm and 2 nm, respectively. Subsequently we applied to the sample a strain, with a constant rate= 0.5 ns^{-1} , until it broke. Due to the presence of the notch, the place at which the fracture initiated could be changed at will. More details can be found in Ref. [36].

The interaction between the atoms are given by a pairwise effective potential proposed by Sundararaman et al. (SHIK) [28, 29], which has been found to give a good quantitative description of the bulk and surface properties of sodo-silicate glasses [30, 31]. Its functional form is given by

$$V(r_{ij}) = \frac{q_i q_j e^2}{4\pi\epsilon_0 r_{ij}} + A_{ij} e^{-r_{ij}/B_{ij}} - \frac{C_{ij}}{r_{ij}^6} \quad , \tag{2}$$

where r_{ij} is the distance between two atoms of species *i* and *j*. This potential uses partial charges q_i for different atomic species: The charges for Si and Na are, respectively, fixed at 1.7755*e* and 0.5497*e*, while the charge of O depends on composition and is given by requesting charge neutrality of the sample, i.e.,

$$q_{\rm O} = \frac{(1-y)q_{\rm Si} + 2yq_{\rm Na}}{2-y},\tag{3}$$

where y is the molar concentration of Na₂O, i.e., $y = (1 + x)^{-1}$. The other parameters of the potential, A_{ij} , B_{ij} and C_{ij} , occurring in Eq. (2) are given in Refs. [28, 29]. Note that, following Ref. [28], the Coulombic part in Eq. (2) was treated via the Wolf method.

Temperature and pressure were controlled using a Nosé-Hoover thermostat and barostat [42–44]. All simulations were carried out using the Large-scale Atomic/Molecular Massively Parallel Simulator software (LAMMPS) [45] with a time step of 1.6 fs.

The results presented in this manuscript correspond to one melt-quench sample for each composition. However, we emphasize that the system sizes considered in this study are sufficiently large to make sample-to-sample fluctuations negligible. For the MS, the results for the two surfaces on the top and bottom sides of the glass sample were averaged. For the FS, twelve surfaces, resulting from six independent fracture (by changing the location of the notch), were averaged. The error bars were estimated as the standard error of the mean of the samples.

2. Identifying the surface

In order to have a reliable description of the surface one needs a method that allows to map the positions of the atoms onto a well-defined mathematical surface. The algorithm that we use for constructing this surface mesh is based on the alpha-shape method of Edelsbrunner and Mücke [32]. It starts with the Delaunay tetrahedrization of the input point set, i.e. the atoms in the sample. From the resulting tetrahedra, all tessellation elements are then evaluated by comparing their circumspheres to a reference probe sphere that has a radius R_{α} . The elements (with circumsphere radius R) which satisfy $R < R_{\alpha}$ are classified as solid, and the union of all solid Delaunay elements defines the geometric shape of the atomistic solid. A robust realization of this algorithm is implemented in OVITO [46].

It is important to mention that the probe sphere radius R_{α} is the length scale which determines how many details and small features of the solid's geometric shape are resolved. To construct the geometric surfaces for the glass samples, we use $R_{\alpha} = 3.2$ Å, i.e., the typical distance between neighboring Si atoms. This choice allows to resolve fine surface features and avoids artificial holes in the constructed surfaces. We note, however, that a small change of R_{α} (e.g. ± 0.5 Å) will not alter significantly the results presented in the manuscript, see Refs. [31, 36] for details. Finally, we mention that for the FS we have not used for the analysis the parts of the surface that are closer than ≈ 5 nm to the top/bottom MS in order to avoid the influence of these surfaces onto the properties of the FS.

Once the geometric surface is constructed, i.e., the mesh points of the surface are identified, we first fit a plane to the set of mesh points using a least squares fitting procedure. Finally, a linear interpolation is applied to the triangular mesh to obtain a uniform quadratic grid which is subsequently used to determine the morphology and roughness of the surface.

3. Dependence of roughness on the distance from the fracture origin

Since the formation of the FS is a strongly out-of-equilibirum process it could be that the roughness depends on the distance the crack has propagated from its origin, i.e., the notch. To test for this possibility we have divided the surface into four segments along the y-direction, i.e., in the direction the crack propagated, see Fig. S1(a). For each of these segments we have determined the roughness σ and in Fig. S1(b) we show for selected glass compositions the value of σ in these segments. The graph shows that within the accuracy of the data there is no dependence on the segment number, i.e., on the distance from the fracture origin.



Figure S1. (a) Height map z(x, y) of a fracture surface of the NS3 glass. The surface is divided into 4 equal segments along the crack propagation direction. (b) Roughness σ of the surface segments along the crack propagation direction for three different glass compositions.

4. Dependence of roughness and topography on strain rate and temperature

The results in the main text have been obtained for a strain rate of 0.5 ns⁻¹. Since it is well known that the properties of glasses depend on the production history [47], it can be expected that also the properties of the fracture surface will depend on these details. One key parameter for the fracture process is the strain rate, $\dot{\epsilon}$, used to deform the sample and in Fig. S2(a) we show for the case of silica the roughness σ as a function of this parameter. One sees that for high rates the roughness is about a factor of two higher than the σ we obtain for $\dot{\epsilon} = 0.5 \text{ ns}^{-1}$. This result is reasonable since a high rate will not allow the crack to find energetically favorable pathways and hence results in a surface that is rough. However, once $\dot{\epsilon}$ is lowered to 0.5 ns^{-1} , σ is basically independent of the strain rate and hence we can conclude that the roughness we present in the main text should correspond to the case of real experiments on dynamic fracture.

A similar conclusion can be reached for the topography of the surface since, see Fig. S2(b), the height-height correlation functions for the intermediate and low strain rates are basically identical.



Figure S2. Influence of strain rate on the roughness and scaling property of the fracture surface for the case of silica. The data are plotted on linear-log scale. In panel (b), x and y correspond to the direction parallel to the crack front (dashed lines) and the direction of crack growth (solid lines), respectively.

A further important parameter that influences the topography of a surface is the temperature. The results presented in the main text are for the temperature T = 300 K. In Fig. S3 we show how the roughness and the skewness γ_1 depend on the temperature at which the surfaces are probed. To get this data for the MS we used the configurations obtained during the quench procedure. For the FS we annealed the samples at 600-800 K (NS3-silica) for 160 ps before we cooled them down in a step-wise manner to the temperatures of interest. At each T we annealed the samples for 160 ps before starting to strain them until fracture occurred.

The figure shows that for the case of the MS, panel (a), the roughness of the silica surface is basically independent of T, i.e. increasing temperature does not allow the surface to fluctuate with significantly larger amplitudes. This result is reasonable in view of the strong bonds present in this kind of glass. In contrast to this we find for NS3 a significant T-dependence in the roughness, although the absolute change is small (10%). This result is likely related to the fact that the mobility of the Na atoms depends strongly on T, thus allowing for a significant softening of the network structure.



Figure S3. Effect of temperature on surface properties. Upper and lower panels are for the MS and FS, respectively. (a) and (c): T-dependence of surface roughness. Vertical dashed lines in (a) indicates the T_g of the silica and NS3 glasses. (b) and (d): The skewness characterizes the asymmetric property of the surfaces.

Also included in the graph are the estimated values for the glass transition temperature T_g (vertical dashed lines). Naively one can expect that below T_g the topography of the surface is given by the thermal (harmonic) fluctuation of the atoms around their average positions, i.e., a $T^{1/2}$ dependence. The NS3 data clearly shows that this view is too simplistic since, as mentioned above, a change of T leads to a modification of the local elastic constants and as a consequence the T-dependence of σ is much stronger than expected for a purely harmonic system.

Panel (b) shows that temperature does not really affect the skewness of the distribution, i.e. the fact that the surface has more deep cavities than high peaks is independent of T. Only for the case of NS3 we find at intermediate and high T a slight increase of γ_1 , i.e., at these high temperatures the system becomes sufficiently soft that the distribution of the fluctuation becomes symmetric since the sample starts to liquify.

For the case of the FS, panel (c), we see that neither silica nor NS3 show a significant T-dependence of σ . This observation is coherent with the observation, Ref. [36], that during the fracture process the *local* temperature of the system close to the crack front is so high (because of the breaking of the bonds) that for the resulting surface it is irrelevant at which temperature the fracture happens. In agreement with this argument we find that also the skewness of the height distribution, panel (d), is independent of T.

5. Parameters describing the height-height correlation function

In the main text we have shown that the functional form describing the height-height correlation function $\Delta z(r)$ depends on the type of surface considered: $[\Delta z(r)]^2 = A \ln(r/\lambda)$ for the MS and $\Delta z(r) = A \ln(r/\lambda)$ for the FS, see Fig. 3. In Fig. S4 we show how the prefactor A and the length scale λ depend on the composition of the glass. Panel (a) shows the prefactor A of the logarithmic dependence for the case of the MS. Although the scattering of the data is substantial, there is good evidence that A has a maximum at intermediate concentrations of Na. One possibility to rationalize this observation is to recall that within the frozen capillary wave theory this prefactor is given by [13]

$$A = \frac{k_B T_f}{\pi \gamma} \quad , \tag{4}$$

where γ is the surface tension. The freezing temperature T_f decreases with increasing Na

concentration, and it can be expected that the surface tension does the same. Hence γ^{-1} is an increasing function of the Na₂O concentration and thus it is not unreasonable (although not guaranteed) that the product of these two factors give a maximum at intermediate values of the Na₂O content.



Figure S4. Parameters of the logarithmic fit to the height correlation function of the surfaces at 300 K. (a) and (b) are for the MS, and (c) and (d) are for the FS. The fitting was performed only for the data at r < 1 nm, see Fig. 3. The expressions used for the fit are given in the graphs as well. x and y corresponds to the direction parallel to the crack front and the direction of crack growth, respectively. The lines in (b) and (d) are linear fits to the data sets.

Panel (b) shows the compositional dependence of the length scale λ and we see that with increasing Na₂O the length scale increases weakly. This observation agrees with the idea of the capillary wave theory which identifies λ as the smallest length scales over which one can use this approach. Since it is well known that systems containing Na have a more complex structure than pure silica, because of the presence of ion-conducting channels [48–50], we can expect that this minimum wave-length is larger for NS3 than for silica, rationalizing the observed trend in panel (b).

For the case of the FS, panels (c) and (d), we find that the prefactor A as well as the length scale λ increase significantly (by more than 50%) in the *x*-range considered. Although we have no explanation why, for both quantities, this dependence is linear in the Na concentration, this qualitative trend is reasonable since an increasing Na content will increase the plasticity of the system and hence allow for a height-height correlation that has a larger amplitude and extents to larger distances.

6. Smoothing of the surface

In the main text we have presented the results on the height-height correlation function once the surface fluctuations were smoothed by convoluting them with a 2D Gaussian. To do this smoothing of the surface defined by points that are on the quadratic grid we proceeded as follows: The weight function is given by

$$f(r) = \frac{1}{2\pi\omega^2} e^{-\frac{r^2}{2\omega^2}},$$
 (5)

where $r = \sqrt{(x - x_0)^2 + (y - y_0)^2}$ is the in-plane distance from a given grid point (x, y) to the reference grid point (x_0, y_0) , and ω controls the shape of the weight function. We consider only the grid points with $r < 2\omega$. Thus the smoothed surface height $z'(x_0, y_0)$ is given by

$$z'(x_0, y_0) = \frac{\sum_{i=1}^{N} z(x_i, y_i) f(r_i)}{\sum_{i=1}^{N} f(r_i)},$$
(6)

where N is the number of grid points that satisfy $r < 2\omega$. By varying the value of ω , different levels of smoothing can be applied to the original surface and thus the influence of spatial resolution on the surface properties can be investigated.