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Spatial Triplet Markov Trees for Auxiliary Variational Inference in Spatial Bayes Networks

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Outline

- 1 Introduction
- 2 The probabilistic models
 - Markov Tree network
 - Spatial Bayes Network
 - STMT network
- 3 Variational Inference
 - The method
 - Several VIs on a small example
 - Experimental results
- 4 Conclusion & Perspectives

Introduction

Bayesian Networks: main definitions

- Also known as acyclic Directed Graphical Models (DGM)
- Let $\mathcal{G} = (\mathcal{S}, \mathcal{E})$ be a directed graph:
 - Directed edges link *parents* vertices $\mathcal{P}(s)$ and son vertice $s \in \mathcal{S}$
 - Vertices without any parent are root vertices (denoted r)
- Random variables associated to each vertice
- Define local conditional probabilities $p(x_r)$ or $p(x_s|\mathbf{x}_{\mathcal{P}(s)})$
 - \rightarrow They define joint distribution on \mathcal{G} :

$$p(\mathbf{x}) = \prod_{r \in \text{roots}} p(x_r) \prod_{s \in \mathcal{S} \setminus \text{roots}} p(x_s | \mathbf{x}_{\mathcal{P}(s)})$$
(1)

Inference basics

Inference tasks:

- compute marginals $p(x_s)$
- compute conditionals $p(x_s|\mathbf{x}_{p(s)})$
- compute a mode of the distribution

```
(e.g. Maximum A Posteriori (MAP): \hat{x} = \operatorname{argmax}_{x} p(x), Maximum Posterior Modes (MPM): \hat{x_s} = \operatorname{argmax}_{x_s} p(x_s))
```



Direct computations in Bayes Networks:

 Forward Backward (Stratonovich 1965) / Belief Propagation (Pearl 1982)

Approximate computations in general DGM:

- Loopy Belief Propagation (Weiss 2000)
- MCMC: Gibbs sampling (Geman et al. 1984)
- Variational Inference (Jordan et al. 1999)

Bayesian Networks: popularity

Hidden Markov Models (Baum et al. 1966) (Dymarski 2011) Bayesian Networks with latent X and observed variables Y. Widely known for:

- Stock index forecasting (Gorynin et al. 2017)
- Speech processing (Toda 2011)
- Gene prediction (Stanke et al. 2006)

Hidden Markov Chain with Independent Noise:

$$p(\mathbf{x}, \mathbf{y}) = p(x_r) \prod_{s \in \bar{S}} p(x_s | x_{s-1}) \prod_{s \in S} p(y_s | x_s)$$

$$(2)$$

Hidden Markov Chain (direct computations)

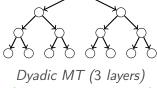
The probabilistic models

Markov Tree (MT) Bayesian Networks

Vertices (except roots) have one parent.

MT joint distribution (Monfrini et al. 2003):

$$p(\mathbf{x}) = p(x_r) \prod_{s \in \bar{S}} p(x_s | x_{s-}).$$
 (3)



- Dyadic MT (3 layers)
 (direct computations)
- *Dyadic* tree: 1 root and 2 sons/vertice (except last layer).
- Quadtree: 1 root and 4 sons/vertice (except last layer).

Exact inference dyadic/quad trees:

 Upward-Downward (Durand et al. 2004) (principled approach to get the marginals in dyadic MT).

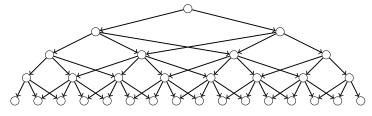
$$p(x_s) = \sum_{x_{s-}} p(x_{s-}) p(x_s | x_{s-}).$$
 (4)

Spatial Bayesian Networks (SBN)

A SBN is a Bayesian network with joint distribution (this paper):

$$p(\mathbf{x}) = p(x_r) \prod_{s \in \bar{S}} p(x_s | x_{s^-}, x_{v(s)}), \tag{5}$$

v associates a father's neighbour: not a Markov Tree! The *spatial context* is modeled but the numerous loops makes inference complex and approximate.



SBN (based on a dyadic tree) with 4 layers (approximate computations)

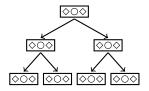
Spatial Triplet Markov Tree Bayesian Networks

In STMT, T = (X, V) and V auxiliary process (this paper) and (Courbot et al. 2018).

T is a Markov Tree with joint distribution:

$$p(\mathbf{t}) = p(\mathbf{t}_r) \prod_{s \in \bar{S}} p(\mathbf{t}_s | \mathbf{t}_{s-}), \tag{6}$$

with t_s a triplet $(x_s, v_s^{\leftarrow}, v_s^{\rightarrow})$



STMT (Markov property) (direct computations)

Spatial Triplet Markov Tree Bayesian Networks

In STMT, T = (X, V) and V auxiliary process (this paper) and (Courbot et al. 2018).

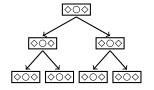
T is a Markov Tree with joint distribution:

$$p(\mathbf{t}) = p(\mathbf{t}_r) \prod_{s \in \bar{S}} p(\mathbf{t}_s | \mathbf{t}_{s-}), \tag{6}$$

with t_s a triplet $(x_s, v_s^{\leftarrow}, v_s^{\rightarrow})$ such that:

$$p(\boldsymbol{t}_{s}|\boldsymbol{t}_{s-}) = p(x_{s}|x_{s-},\boldsymbol{v}_{s-})p(v_{s}^{\leftarrow}|x_{s-},\boldsymbol{v}_{s-})p(v_{s}^{\rightarrow}|x_{s-},\boldsymbol{v}_{s-}).$$
 (7)

The transitions are specially designed to model the *spatial context*.



STMT (Markov property)
(direct computations)



STMT (all edges)
(direct computations)

Test the ability to capture spatial context by *clamped* sampling from Markov Random Field (MRF) realizations











Average different rate from MRF

Test the ability to capture spatial context by *clamped* sampling from Markov Random Field (MRF) realizations











Average different rate from MRF





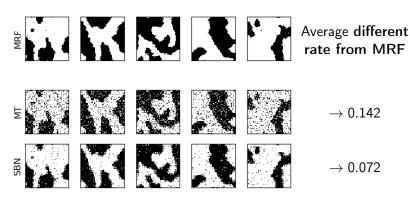




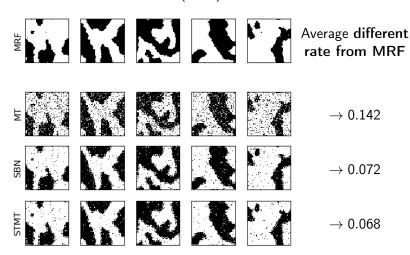


 $\rightarrow 0.142$

Test the ability to capture spatial context by *clamped* sampling from Markov Random Field (MRF) realizations



Test the ability to capture spatial context by *clamped* sampling from Markov Random Field (MRF) realizations



■ SBN and STMT seem to capture the *spatial context*

Variational Inference

The method

VI recasts inference into a maximization problem (Jordan et al. 1999):

$$-\mathbb{KL}(q(\mathbf{x})||p(\mathbf{x})) = \mathbb{E}_q[\log p(\mathbf{x})] - \mathbb{E}_q[\log q(\mathbf{x})], \tag{8}$$

where:

- p is the target distribution (SBN here)
- q is the variational distribution (structured or not)

The method

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where:

- p is the target distribution (SBN here)
- q is the variational distribution (structured or not)

Extended to integrate auxiliary variables (Agakov et al. 2004)

$$egin{aligned} -\mathbb{KL}(q(m{x},m{v})|| ilde{p}(m{x},m{v})) &= \mathbb{E}_q[\log ilde{p}(m{x},m{v})] - \mathbb{E}_q[\log q(m{x},m{v})], \ &= \mathbb{E}_q[\log ilde{p}(m{x})] + \mathbb{E}_q[\log ilde{p}(m{v}|m{x})] - \mathbb{E}_q[\log q(m{x},m{v})]. \end{aligned}$$

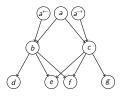
 $ilde{p}$ is extended with auxiliary variables (with condition: $ilde{p}(\mathbf{x}) = p(\mathbf{x})$)

A small SBN example I

■ Target distribution:

Let
$$\mathbf{x} = (a, a^{\leftarrow}, a^{\rightarrow}, b, c, d, e, f, g),$$

 $p(\mathbf{x})$ has a SBN factorization



(approximate computations)

A small SBN example I

■ Target distribution:

Let
$$\mathbf{x} = (a, a^{\leftarrow}, a^{\rightarrow}, b, c, d, e, f, g),$$

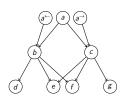
 $p(\mathbf{x})$ has a SBN factorization

Variational approximation:

Mean-Field (MF) approximation:

$$q^{MF}(\mathbf{x}) = \prod_{i} q(x_i) \qquad (10)$$

 \rightarrow Independent random variables



(approximate computations)







f g

MF approximation (direct computations)

A small SBN example I

■ Target distribution:

Let
$$\mathbf{x} = (a, a^{\leftarrow}, a^{\rightarrow}, b, c, d, e, f, g),$$

 $p(\mathbf{x})$ has a SBN factorization

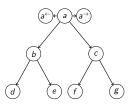
(approximate computations)

Variational approximation:

Markov Tree (MT) approximation:

$$q^{MT}(\mathbf{x}) = q(x_r) \prod_{s \in \bar{S}} q(x_s | x_{s^-}).$$
 (10)

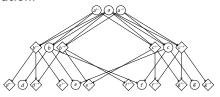
 $\rightarrow q^{MT}$ is MT structured



MT approximation (direct computations)

A small SBN example II

■ Target distribution:



(approximate computations)

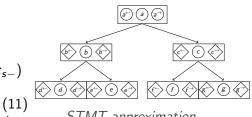
 $ilde{p}(m{x},m{v})$ is a SBN with auxialiary variables (and $ilde{p}(m{x})=p(m{x})$)

Variational approximation:

STMT approximation:

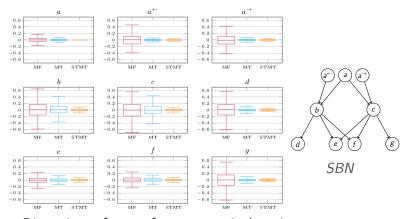
$$q^{STMT}(\mathbf{t}) = q(\mathbf{t}_r) \prod_{s \in \overline{s}} q(\mathbf{t}_s | \mathbf{t}_{s-})$$

 $ightarrow q^{STMT}$ is STMT structured



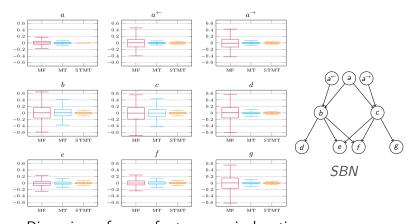
STMT approximation (direct computations)

Small network example: model proximity



ightarrow Dispersions of errors for true marginals estimation (1000 trials)

Small network example: model proximity



- ightarrow Dispersions of errors for true marginals estimation (1000 trials)
 - Error dispersion : MF VI > MT VI > STMT VI
 - STMT seems to best capture the enhanced correlations of SBN

Conclusion & Perspectives

Conclusion & Perspectives

Conclusions:

- 2 new tree-structured models with rich correlations
- Importance of the triplet structure for exact approaches in more complex networks.
- Auxiliary variables in probabilistic models can be an efficient asset if the model is well-thought!

Perspectives:

- Analytical comparison STMT/SBN
- Extend the work to quadtrees for image processing

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