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▶ To cite this version:

Juliette Blanchet, Gilles Molinié, Julien Touati. Spatial analysis of trend in extreme daily rainfall in southern France. Climate Dynamics, 2018, 51 (3), pp.799-812. 10.1007/s00382-016-3122-7. hal-03087655

HAL Id: hal-03087655 https://hal.science/hal-03087655v1

Submitted on 22 Oct 2024

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Spatial analysis of trend in extreme daily rainfall

in southern France

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February 12, 2016

7 Abstract

This paper makes a regional evaluation of trend in yearly maxima of daily rainfall in southern France, both at point and spatial scales on a regular grid of $8 \times 8 \text{km}^2$. In order to filter out the high variability of rainfall maxima, the current analysis is based on a non-stationary GEV modeling in which the location parameter is allowed to vary with time. Three non-stationary models are considered for each series of maxima by constraining the location parameter to vary either linearly, linearly after a given date or linearly up to a final date. Statistical criteria are used to compare these models and select the best starting or final point of putative trends. The analysis shows that, at regional scale, the best distribution of maxima involves a linear trend starting in year 1985 and that this trend is significant in half the region, including most of the mountain ranges and part of the Rhône valley. Increases in yearly maxima are considerable since they reach up more than 60 mm/day in 20 years, which is more than 40% of the average maximum in this area.

1 Introduction

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An exceptional number of heavy rainfall and flooding events occurred in 2014. A storm struck
the Brittany region of western France at the end of December 2013 and the subsequent flood
lasted until mid January 2014. In February, the Ulla storm passed over Brittany and flooded
again along its way to Great Britain. Southeastern Europe (Serbia, Croatia, Romania) faced
flood events in May, the Basque county (southwestern France) in July, northeastern France in
August, the eastern shore of Spain and southern France in Fall and then Italy in November and

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December. Is this sudden large number of floods due to natural climate variability, or is it a consequence of anthropogenic climate change?

Already at the end of the 70's, [Charney et al., 1979] envisioned the possible impact of human 29 activity on climate at a global scale. Then the successive Assessment Reports (AR) of IPCC 30 strengthened the evidence of a global change whose main manifestation is an increase in global 31 temperature. [IPCC, 2013] states that global surface temperature has increased by about 0.9°C between 1880 and 2012, with a particularly marked warming since the 1970s. Analyzing climate 33 change impact on precipitation is more arduous, first because precipitation is highly variable and second because its change in recent past shows multiple facets ([Alpert et al., 2002]). Mean precipitation increased under the 40°N area in Europe, Russia, United States, South America and the center of Australia between 1951 and 2010, whereas it decreased over the same period in 37 Eastern Asia, Southern Europe and most of Africa ([IPCC, 2013]). Then what about extreme precipitation? Some studies support a causal relationship. [Planton et al., 2008], working in the context of CMIP3 simulations, shows the impact of global warming on the French climate and specifically on precipitation extremes at the end of the century. However, according to 41 [Gallant et al., 2013], this conclusion is not supported by the recent climate records at European 42 scale. Indeed, despite a clear warming signal in continental indices of temperature, no significant trend is detected in continental indices of precipitation. Is there any trend hidden by the spatial integration of [Gallant et al., 2013]? Focusing on point rainfall measurements, several 45 studies illustrate the spatial variability of extreme precipitation trends over these last decades. [Haylock and Goodess, 2004] reports an increase in the occurrence of heavy rainfall days (defined 47 as the number of days with daily amounts above the 90th percentile) in northern Europe during 48 winter, while it decreases in southern Europe. [Zolina, 2014] considers the length of heavy 49 rainfall period as an extreme rainfall characteristics and shows that trends in these lengths are 50 highly variable across Germany. [Schmidli and Frei, 2005] uses 12 extreme precipitation indices to characterize swiss rainfall records and finds again highly variable trends. In particular, the number of heavy rainfall days in winter decreases in northeastern Switzerland while it increases 53 in the Southeast. [Toreti et al., 2010] shows that trend in the probability of observing an extreme event varies along the mediterranean coast, with a significant negative trends found in 6 of the 20 studied costal sites. Still in the mediterranean region, [Alpert et al., 2002] shows that extreme 56 daily rainfall from Spain to Israel increased between 1951 and 1990 in spite of the fact that total 57 rainfall generally decreased.

Regarding recent trends in extreme precipitation in southern France, [Norrant and Douguédroit, 2004]
finds an increase in the 95th percentile of daily and monthly rainfall, however the inter-annual
variability of the 95th percentile suggests that this is only due to the occurrence of few high

values at the beginning of the study period. Analysing regional trends in monthly and annual maximum series of precipitation in seven homogeneous climatological zones in southern France, 63 [Pujol et al., 2007b] finds a significant increase in both annual and monthly maxima in October in the southern part of the Massif Central and a decrease in March and an increase in April in the Langedoc-Roussillon. [Pujol et al., 2007a] studies the regional evolution of daily peaksover-threshold records in the same climatological zones and finds an increase of the occurrence and intensity of extreme daily rainfall in the southern part of the Massif Central, as well as an increase in the intensity of extreme rainfall in the Languedoc-Roussillon. Focusing on the southern region including the Cévennes-Vivarais mountain range prone to flash flood events, 70 [Tramblay et al., 2013] shows in a peaks-over-threshold approach that a slight increase in the number of the most extreme rainfall events are observed since 1980, however no significant trend is detected with a Mann-Kendall test, neither in the event magnitudes nor in the number 73 of occurrences per year. Still in the same region, [Tramblay et al., 2011] shows that time is a valid covariate for modelling peaks-over-threshold intensity, indicating an increasing trend in the magnitude of heavy rainfall events between 1958 and 2008. [Soubeyroux et al., 2015] finds local 76 upward trends in annual maxima of daily precipitation in the french Mediterannean area with 77 a Mann-Kendall test, however this increase is usually not significant. Finally studying seasonal maxima of daily precipitation in the Cévennes-Vivarais range, [Vautard et al., 2015] finds local 79 upward trends with a median increase of about 5\% per decade but few of the local trends are 80 significant. 81

Clearly the variety of methodologies is a source of difficulty for summarizing the results 82 on this topic. Two main approaches are usually undertaken. The first one is based on cli-83 mate indices ([Karl et al., 1996]). The usual methodology is to define a bench of indices that 84 are relevant for the studied region and to estimate changes in each of them by fitting regression models (e.g. [Frich et al., 2002], [Klein Tank and Können, 2003], [Zolina et al., 2008], [Alexander et al., 2006], [Karl et al., 1996], [Zhang et al., 2011]), or by comparing empirical probability density functions for various periods (e.g. [Alexander et al., 2006]). ETCCDI (Expert Team on Climate Change Detection, Monitoring and Indices) recommends the use of 27 indices, among which 11 are related to precipitation and usually describe 'moderate extremes' typically occurring several times a year ([Zhang et al., 2011]). This wide spectrum of indices 91 intends to cope implicitly with the great variety of rainfall regimes that can result from precipitation interacting with air dynamics ([Schertzer and Lovejoy, 1987, Gupta and Waymire, 1979, Fabry, 1996, Fraedrich and Larnder, 1993). There are as many random variables characterizing the rain intensity as there are spatial and temporal resolutions, i.e. an infinity. The approach by indices chooses to summarize these many random variables by few statistics, but then part

of the information on the random variables is lost.

The second set of approaches focuses on the heaviest rainfalls but fully characterized them 98 by modeling their probability density function. These approaches are linked to the statistical 99 theory of extreme values. The current study focuses on annual maxima (so-called "block-maxima 100 approach") and models them with the so-called Generalized Extreme Value (GEV) distribution 101 ([Coles, 2001]). This approach shows the advantage of being scale-independent: whatever the 102 temporal and spatial scales of precipitations at hand, extreme value theory insures that the 103 right distribution to be used is the GEV distribution (whose parameters, of course, are ex-104 pected to vary from one scale to another, see [Blanchet et al., 2015]). Thus the same theoretical 105 framework can be used for analyzing precipitations at different scales. This is particularly in-106 teresting for rainfall since rainfall severity depends on the duration and spatial extension of 107 the events ([Ramos et al., 2005, Molinié et al., 2012, Ceresetti et al., 2010]). This is also par-108 ticularly convenient for trend analysis because trends in extremes at different scales can be 109 analyzed in an easy and universal way through the use of non-stationary GEV distributions 110 ([Marty and Blanchet, 2012, Katz et al., 2002, Westra and Sisson, 2011]). 111

The goal of this article is to provide a regional evaluation of trend in yearly maxima of daily 112 rainfall in southern France in the recent past (several decades), both at point and spatial scales on a regular grid of $8 \times 8 \text{km}^2$. For this, we place ourself in a statistical extreme value frame-114 work, which is convenient and theoretically-founded as soon as yearly maxima are concerned. A 115 novelty of this study compared to the litterature in the region ([Norrant and Douguédroit, 2004, 116 Pujol et al., 2007a, Pujol et al., 2007b, Tramblay et al., 2011, Tramblay et al., 2013, Soubeyroux et al., 2015, 117 Vautard et al., 2015) is that not only local but also areal rainfalls are considered. A difference 118 with [Tramblay et al., 2012] is that here the surface of aggregation is about 10 times smaller 119 than the smallest considered area therein, which enables to study trends at finer space-scales. A 120 second difference is that, unlike in [Pujol et al., 2007a, Pujol et al., 2007b] for example, trends 121 are first assessed locally, which makes possible to reveal the spatial variability of trends and to 122 highlight that the great majority of the significant trends are actually found in quite specific 123 spots. Regional testing is performed in a second step quite similarly to [Pujol et al., 2007b] but 124 focusing on the sub-region where trends are the most significant rather than mixing inhomoge-125 neous trends encountred over the region. 126

The article is organized as follows. Section 2 presents the data and region of study. Section
3 describes the methodology based on non-stationary GEV distributions. The methodology is
neither region- nor scale-specific and could be applied at any space and time scales. Currently
it is applied to daily point and areal rainfall on a grid of 8×8 km² in southern France. Section
4 discusses the results and a conclusion finishes the article.

2 Studied region and data

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The studied region broadly covers the lower basin of the Rhône River (Figure 1). It includes 133 the southeastern edge of the Massif Central towards the West and the first foothills of the 134 Alps towards the East. It is surrounded by the Mediterranean Sea towards the South. The 135 region features a rather flat alluvial plain containing the Rhône delta with on its edges two 136 mountain ridges with elevations reaching between 1500 and 2000m a.s.l. in less than 30 to 50 km. 137 The highest peaks located along the eastern branch of the V-shaped Massif Central mountain 138 (Mounts Aigoual, Lozère, Gerbier de Jonc and Mézenc) are aligned with an orientation of N-139 30°-E. On the other side of the Rhône Valley, the main peak line is oriented N-160°-E. This funnel-shaped domain is known to experience severe storms generating flash-floods from various 141 foothill rivers. Both sides of the valley can be affected as shown by quite recent severe events 142 causing numerous human losses and considerable damages that occurred in 1992 on the Ouvèze 143 River ([Sénési et al., 1996]) and in 2002 on the Gard River ([Delrieu et al., 2005]). Nevertheless a strong dissymmetry exists in terms of occurrence of such events in this area. The Massif Central 145 edge, called Cévennes-Vivarais region, experiences most of the extreme storms and resulting 146 flash-floods (Figure 2 of [Nuissier et al., 2008]). 147

This study makes use of both point and areal daily rainfall. Point rainfall stems from a rain-148 gage network maintained by Météo-France and covering the French administrative departments 149 of Ardèche, Drôme, Gard, Haute-Loire, Herault, Lozère and Vaucluse, with a surface of about 150 38,000 km² (see Fig. 1). The network covers at most the 1958-2014 period. The SAFRAN database ([Quintana-Seguí et al., 2008]) provides the areal rainfall on a regular grid of 8×8 152 km². It covers the region in 1078 cells (excluding the Mediterranean Sea), see Fig. 1. Daily 153 SAFRAN data are available for the 1958-2013 period, with no missing value. Since flash floods 154 occur in Autumn in this region, we restrict all series to the three months of September, October and November. In order to filter out the point series with too many missing values, the following steps are applied sequentially: 157

- 1. For a given station, an autumnal maximum is considered as missing if its rank is smaller than $pmiss \times N$ where pmiss is the proportion of missing values for that autumn, and N is the number of observed autumns.
- 2. The whole station is excluded from the analysis if less than 20 autumns are missing.

Step 1. in the above procedure is inspired from [Papalexiou and Koutsoyiannis, 2013] but differs in that here the probability to select a maxima is more continuously related to the proportion of missing values. The idea is essentially to consider that an incomplete year with a large proportion of missing values (large *pmiss*) may still have observed the maximum value if that

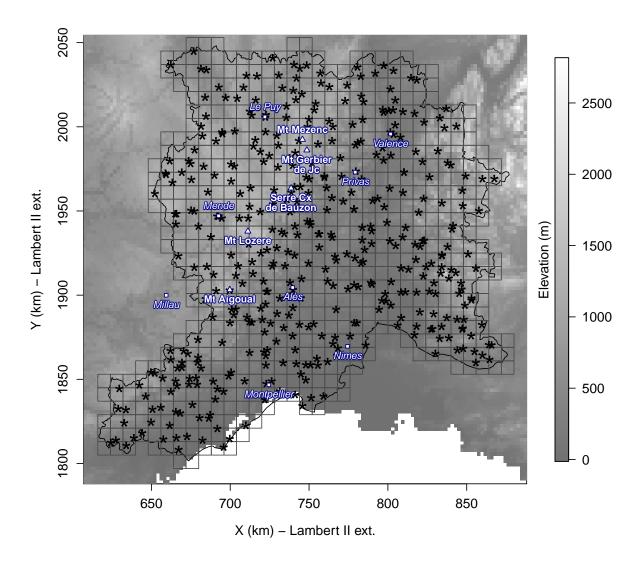


Figure 1: Main features of the region of analysis: elevation above sea level, main mountain peaks (white triangles) and main cities (white squares). Point rainfalls are provided by daily raingages (stars) and areal rainfalls by SAFRAN grids of size $8 \times 8 \text{ km}^2$ (squares). The black border delineates the instrumented area (French administrative departments of Ardèche, Drôme, Gard, Haute-Loire, Hérault, Lozère and Vaucluse).

value is large compared to the other maxima (i.e. its rank is large). Applying this selection procedure, we finally end up with a set of 428 daily point series.

168 3 Method

3.1 Modeling of maxima

Let R be the random variable of annual maximum rainfall intensity (in mm/h) at a given spatio-temporal scale, and at a given location. We model the statistical distribution of R using the so-called Generalized Extreme Value (GEV) distribution. The reason for this latter choice relies in Extreme Value Theory ([Coles, 2001], chapter 3), which insures that this is the only possible distribution of independent and identically distributed (i.i.d.) maxima. In the stationary case, the cumulative distribution function of R, $\Pr(R \leq r)$, is then given by ([Coles, 2001, Katz et al., 2002]):

$$F(r;\mu,\sigma,\xi) = \begin{cases} \exp\left\{-\left(1 + \xi \frac{r-\mu}{\sigma}\right)^{-1/\xi}\right\} & \text{if } \xi \neq 0, \text{ provided } 1 + \xi \frac{r-\mu}{\sigma} > 0, \\ \exp\left\{-\exp\left(-\frac{r-\mu}{\sigma}\right)\right\} & \text{if } \xi = 0. \end{cases}$$
 (1)

Here μ , $\sigma > 0$, and ξ are the location (mm/h), scale (mm/h), and shape (dimensionless) param-177 eters, respectively. Three sub-families of distributions (EV-I, EV-II and EV-III, also known as Gumbel, Fréchet and Reverse Weibull distributions) can be derived from the GEV depending on 179 the sign of its shape parameter, which governs the tail of the distribution. If the shape parameter 180 $\xi > 0$, then the GEV distribution is said to be heavy tailed. This is often the case for rainfall 181 data, in particular in our study area ([Ceresetti et al., 2010]). The case $\xi = 0$ corresponds to the Gumbel case whose distribution is light-tailed. This is also often used in hydrological studies 183 ([Borga et al., 2005]) although there is some evidence that the more general GEV distribution 184 should be preferred ([Papalexiou and Koutsoyiannis, 2013]). The case when $\xi < 0$ is the Re-185 verse Weibull case, corresponding to upper-bounded random variables with upper-end point at $\mu + \sigma/|\xi|$. The case $\xi \leq -0.5$ corresponds to distributions with a very short bounded upper tail, 187 which is unlikely to occur in practice ([Coles, 2001]). 188

In the non-stationary case, the GEV parameters vary with time (years). In this article, the location parameter is assumed to be a function $\mu(t)$, whilst the scale and shape parameters are constant. Three non-stationary models for $\mu(t)$ are considered:

• A linear trend:

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$$\mu(t) = \mu_0 + \mu_1 t,\tag{2}$$

• A linear trend starting in year t_0 :

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$$\mu(t) = \begin{cases} \mu_0, & t \le t_0, \\ \mu_0 + \mu_1(t - t_0), & t \ge t_0. \end{cases}$$
 (3)

• A linear trend before year t_0 :

$$\mu(t) = \begin{cases} \mu_0 + \mu_1(t - t_0), & t \le t_0, \\ \mu_0, & t \ge t_0. \end{cases}$$
(4)

The linear case in $\mu(t)$ (Eq. 2) is used in many studies to model non-stationarities in precipitation extremes (e.g. [Katz et al., 2002]). Here we extend this idea by allowing the change to start in some year t_0 (Eq. 3) or to finish in some year t_0 (Eq. 4). [Panthou et al., 2013] uses in West Africa a different model with a jump in t_0 , i.e. $\mu(t)$ takes value μ_0 before the change point t_0 and μ_1 after t_0 . This induces a discontinuity in the distribution of maxima which seems unrealistic in the region and will not be considered hereafter.

The three above equations involve two unknown parameters for $\mu(t)$, instead of one parameter in the stationary case. This latter case is actually a particular case of Eqs. 2 to 4 under $\mu_1 = 0$. This property will be used in the next section to make trend hypothesis test. The corresponding GEV distribution is obtained by replacing in (1) μ by $\mu(t)$. Since the mean of the GEV distribution is a linear function of μ while its stardard deviation is independent of μ , the mean of annual maxima is expected to experience a linear trend under Eq. 2, or a linear trend with change point under Eqs. 3 and 4, while the standard deviation of the maxima is expected to be constant within the observed period for all models.

Together with the stationary case, four GEV models are thus considered, with respectively
three (stationary case) and four (non-stationary case, Eqs. 2 to 4) unknown parameters. These
parameters have to be estimated for each series of maxima. In order to insure that enough data
are available, we consider:

- the linear case of Eq. 2 for all series having at least 20 years of observations (which is met by all series);
 - the linear case with change point in t_0 of Eqs. 3 and 4 for all series having at least 20 years of observations both before and after t_0 .

Since the series span over the 1958-2014 period, possible years of change t_0 will be considered between 1977 and 1995. Models of Eqs. 3 and 4 may or may not be considered for a given series, depending on its observation range and on t_0 .

All the models are fitted by maximum likelihood ([Coles, 2001], chapter 3.3), independently for each raingage and SAFRAN series. Let consider a given series of n annual maximum intensities, denoted $\mathbf{r} = (r_1, \dots, r_n)$, and (t_1, \dots, t_n) the corresponding years. Assuming independence

of annual maxima, the log-likelihood in the non-stationary case is given by

$$\log L(\mu_0, \mu_1, \sigma, \xi) = -n \log(\sigma) - (1 + 1/\xi) \sum_{i=1}^n \tilde{r}_i - \sum_{i=1}^n \tilde{r}_i^{-1/\xi}$$
(5)

224 where

$$\tilde{r}_i = 1 + \xi \left(\frac{r_i - \mu(t_i)}{\sigma} \right), \tag{6}$$

and $\mu(t)$ is a function of μ_0 and μ_1 as in Eqs. 2, 3 or 4, depending on the considered model. The log-likelihood in the stationary-case is function of (μ_0, σ, ξ) and is also given by Eq. 5, replacing $\mu(t_i)$ by μ_0 in Eq. 6. Denoting θ the three or four GEV parameters, the most likely parameters are those such that $\hat{\theta} = \arg \max_{\theta} L(\theta)$. Since there is no explicit solution, $\hat{\theta}$ is obtained numerically. Standard errors of the trend μ_1 in the non-stationary models of Eqs. 2 to 4 are obtained from the approximate normality of the maximum likelihood estimator (see [Coles, 2001], chapter 2.6.4) as

$$\operatorname{std}(\hat{\mu}_1) = \sqrt{(I^{-1})_{22}}$$

where $(I^{-1})_{22}$ is the element (2,2) of the inverse of the observed information matrix I defined by

$$I = \begin{pmatrix} -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0^2} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \mu_1} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \sigma} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \xi} \\ -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \mu_1} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_1^2} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_1 \partial \sigma} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_1 \partial \xi} \\ -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \sigma} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_1 \partial \sigma} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \sigma^2} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \sigma \partial \xi} \\ -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_0 \partial \xi} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \mu_1 \partial \xi} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \sigma \partial \xi} & -\frac{\partial^2 \log L(\hat{\theta})}{\partial \xi^2} \end{pmatrix}$$

3.2 Model selection

Given the estimated models of the previous section, we now wish to decide for each series whether any of the non-stationary model is preferred to the stationary assumption, and if so which one and for which year of change. Here we use GEV likelihood criteria, even for the selection of the best year of change. It has two main advantages over the usual statistical tests relying not on GEV assumptions (see [Beaulieu et al., 2012] for a recent review). First, several studies showed the better performance of the GEV framework when dealing with extreme data ([Katz, 2013, Mallakpour and Villarini, 2015]). Second it allows us to use a common methodological framework throughout all the process of selection of the best non-stationary model, selection of the best year of change, estimation of the trend and testing of trend significance.

In a first step we compare the non-stationary models to one another and select at regional scale which of them give(s) the best model-data fit. Since all considered non-stationary models have four degrees-of-freedom, namely $(\mu_0, \mu_1, \sigma, \xi)$, we can simply compare their likelihoods and select the subset of them giving the highest mean log-likelihood in the region. However,

strictly speaking, this cannot be considered has a regional test for two reasons: first, likelihood
comparisons are, strictly speaking, not statistical tests. Second there is spatial dependence
among the data and therefore among the likelihoods. This first step can therefore only give
evidence about a possible non-stationary model, but not a final decision.

Now let \mathcal{M} be a putative non-stationary model selected at the previous step. In a second step 244 we focus on each series independently. We wish to assess for each of them whether \mathcal{M} should indeed be preferred to the stationary model \mathcal{M}_0 . First evidence is obtained by comparing 246 the penalized likelihoods under \mathcal{M} and \mathcal{M}_0 , with a penalization accounting for the difference 247 in degrees-of-freedom between the two models. We use the well-known Akaike and Bayesian 248 Information criteria (respectively AIC, [Akaike, 1974] and BIC, [Schwarz, 1978]), which only differ in the penalizing term. Let $L_{\mathcal{M}}$ and $L_{\mathcal{M}_0}$ be the likelihoods under \mathcal{M} and \mathcal{M}_0 (Eq. 5) 250 and $\hat{\theta}$ and $\hat{\theta}_0$ the corresponding most likely parameters. Difference in AIC and BIC between 251 both models is given by: 252

$$\Delta AIC = 2\{\log L_{\mathcal{M}}(\hat{\theta}) - \log L_{\mathcal{M}_0}(\hat{\theta}_0)\} - 2 \tag{7}$$

$$\Delta BIC = 2\{\log L_{\mathcal{M}}(\hat{\theta}) - \log L_{\mathcal{M}_0}(\hat{\theta}_0)\} - \log(n)$$
(8)

Positive values of Δ AIC (resp. Δ BIC) gives evidence of preference for the non-stationary model \mathcal{M} rather than \mathcal{M}_0 . Since our series have length greater than 20 (thus $\log(n) > 2$), BIC penalizes free parameters more strongly than AIC, which tends to favor models with more parameters, especially for small samples ([Wit et al., 2012]). A way to statistically test model \mathcal{M} versus \mathcal{M}_0 is to perform a likelihood ratio test (LRT, [Coles, 2001], chapter 2.6). The test applies here because \mathcal{M}_0 is a particular case of all considered non-stationary models (corresponding to $\mu_1 = 0$ in Eqs. 2 to 4). Define

$$D = 2\{\log L_{\mathcal{M}}(\hat{\theta}) - \log L_{\mathcal{M}_0}(\hat{\theta}_0)\}$$
(9)

to be the deviance statistic. Then, for large n, under the null hypothesis that the series comes from the stationary model \mathcal{M}_0 (i.e. $H_0: \mu_1 = 0$), D should follow a χ_1^2 distribution. Hence, a test of the validity of \mathcal{M}_0 relatively to \mathcal{M} at the level of significance α is to reject the stationary model \mathcal{M}_0 in favor of \mathcal{M} if D is greater than the $(1 - \alpha)$ quantile of the χ_1^2 distribution.

$_{\scriptscriptstyle 4}$ 4 Results and Discussion

265 4.1 Exploratory analysis: spatial features of maxima

This section contextualizes the daily rainfall maxima in the region. More detailed analyzes can be found in [Ceresetti et al., 2012] and [Molinié et al., 2012] for example. Figure 2 maps

the average of maximum intensity (left) and the 95% quantile of maxima (right), both for the 268 point (raingages) and areal (SAFRAN) rainfall data. On average the largest maxima of both 269 point and areal rainfall are found along the Cévennes-Vivarais slope facing South-East. It is 270 interesting to notice that the highest averages of areal rainfall maxima are located over the 271 northern part of the Cévennes-Vivarais slope, around the Serre de la Croix de Bauzon. All 272 along the Cévennes-Vivarais slope, river regularly spaced of about 15km have dug deep valleys. Around the Serre, these secondary valleys are oriented West-East (while Northwest-southeast 274 elsewhere) i.e. perpendicular to the southern mediterranean flux. At this spot, the averages 275 of point and areal rainfall maxima are of the same order of magnitude, i.e. around 6 mm/h 276 accumulated over one day, which is about 140 mm/day. Going more southwest, around Mont 277 Aigoual, the average maximum of areal and point rainfall depart more. Mont Aigoual is well 278 known for experiencing heavy rainfall. The average maximum of point rainfall is similar that of 279 the Serre de la Croix de Bauzon. However, the area around Mont Aigoual is far less prone to 280 heavy rainfall and therefore the maximum of areal rainfall is one third of that of point rainfall. 281 Elsewhere in the study region, areal and point rainfalls are in a good agreement indicating that 282 the homogeneity scale of the average maximum is at least of 8 km. 283

It is important to keep in mind that the average filters out the variety of events impacting 284 the region. The right panel of Figure 2 intends to illustrate this variety by displaying the 95%-285 quantile of point and areal rainfall maxima. Again rainfall is quite homogeneous around the 286 Serre de la Croix de Bauzon where the largest point and areal rainfall maxima are similar. The 287 largest point rainfalls are found in the foothills around the town of Alès, which departs from 288 the location of the largest average maxima. In this area, the 95%-quantile of point rainfall 289 maxima is more than twice that of areal rainfall maxima, which illustrates the spatial variability 290 of the largest maxima. The two spots experiencing the largest maxima, namely the foothills 291 around the town of Alès and around the Serre de la Croix de Bauzon, are prone to stationary 292 rainfall. Some processes favoring the stationarity of deep convection over the foothills such as 293 the cold pool have been revealed in [Ducrocq et al., 2008], while [Miniscloux et al., 2001] and 294 [Anquetin et al., 2003] show that the mountain shoulders perpendicular to the atmospheric flow 295 can sustain shallow convection. 296

4.2 Trend analysis

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Now we address the question of whether daily rainfall maxima have exhibited a significant trend in the study region since 1958. A simple way of detecting trends in time series is to fit regression models. However fitting a linear trend on rainfall maxima reveals some weaknesses in terms of robustness due to the high variability of rainfall maxima. Therefore we prefer the use of GEV-

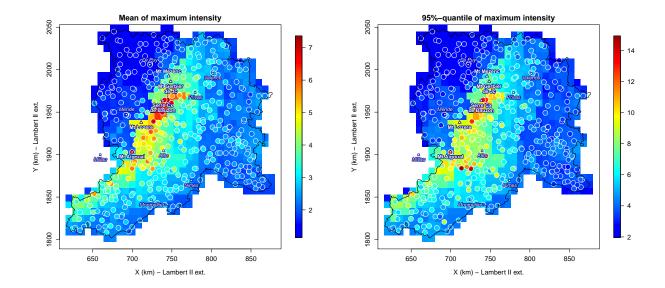


Figure 2: Maps of the daily data. Left: Mean maximum intensity (mm/h). Right: 95%-quantile of maximum intensity (mm/h).

based models (Section 3.1) in order to filter out the seldom occurrence of exceptionally high maxima in the series. An illustration is given by the following robustness analysis. First, we fit to each point series of yearly maxima i) the GEV model of Eq. 1 with linearly varying location parameter (Eq. 2) and ii) a linear regression. Second, we remove the overall maximum of each point series and fit to these new series the two previous models. Figure 3 shows the histograms of the differences in trend estimates, for the two cases. Among the 428 point series, 300 (70%) have an absolute difference smaller than 0.1 mm/day/year in the GEV modeling versus only 184 (43%) when using a regression model, which clearly illustrates a lower sensitivity of the GEV modeling to sampling.

Having selected the GEV-based framework for trend analysis, we now estimate a GEV model to each point and areal series with $\mu(t)$ constrained to vary either linearly (Eq. 2), linearly after a given date t_0 (Eq. 3) or linearly up to a final date t_0 (Eq. 4). We first select which of these non-stationary models fits better the data at regional scale. As explained in Section 3.2, first evidence can be obtained by comparing the mean likelihoods of the different models within the region. Since models of Eqs. 3 and 4 have a change point t_0 , which is fixed but unknown, we make estimation of these models by varying t_0 between years 1977 and 1994, in order to insure that 20 years of data are available before the first change point (1977) and after the last one (1994). Figure 4 plots the regional mean of the likelihoods of the non-stationary models, for both point (left) and areal (right) rainfall, as a function of the change point (since the linear model has no change point, it is depicted with horizontal line). In the top of Figure 4 the mean is computed over the stations whose series of maxima has no missing year between 1958 and 2013, which is the observation period of SAFRAN data. Thus each point of Figure 4 is a

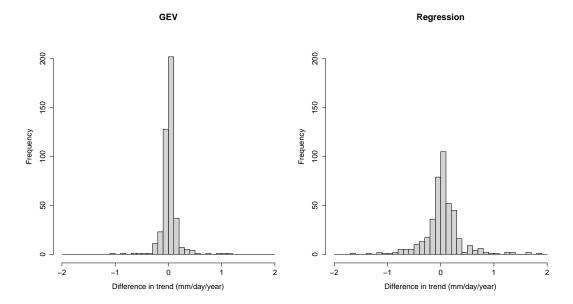


Figure 3: Histogram of difference in trend magnitude (mm/day/year) estimated with and without the overall maximum of each series of yearly point maxima, under either (left) the nonstationary GEV distribution of Eq.2, or (right) a linear regression model.

mean of 88 likelihoods for the point data, and a mean of 682 likelihoods for the areal ones. The same conclusions are drawn from mean log-likelihood comparison in the two cases: whatever the year of change, the model with a recent trend (green line) is more likely than the model with a trend since 1958 (black line), which is itself more likely than a model with a trend in the first subperiod (red line). The best model has a change point in 1985 with a linear trend afterwards. One may be concerned by the fact that the best change point occurs in 1985, which is exactly the center of the observation period. In order to check that there is no bias here, we repeat the same process but we make the GEV estimations on a reduced database starting in 1963 (thus skipping the 5 first years). The bottom of Figure 4 shows that the same conclusion is drawn: at regional scale, the selected model is the non-stationary model of Eq. 3 with a change point in 1985 – which is not anymore the center of the period.

Let stress however that, since rainfall maxima are likely to be spatially correlated over the region ([Bernard et al., 2013]), their joint probability density function is not a product of marginal probabilities, and thus the log-likelihood sum in Figure 4 is not a proper likelihood. Therefore, although Figure 4 gives first insight about some potential starting date of the trend at regional scale, one should keep in mind that this selection criterium relies somehow on an assumption of independence that is unlikely to hold. This assumption is actually made in the large majority of the studies of trends in extremes, including that of [Vautard et al., 2015] for extreme rainfall in the same region, due to the theoretical difficuty in modeling dependence in extremes ([Davison et al., 2012], [Cooley et al., 2012]). A complementary view not relying on

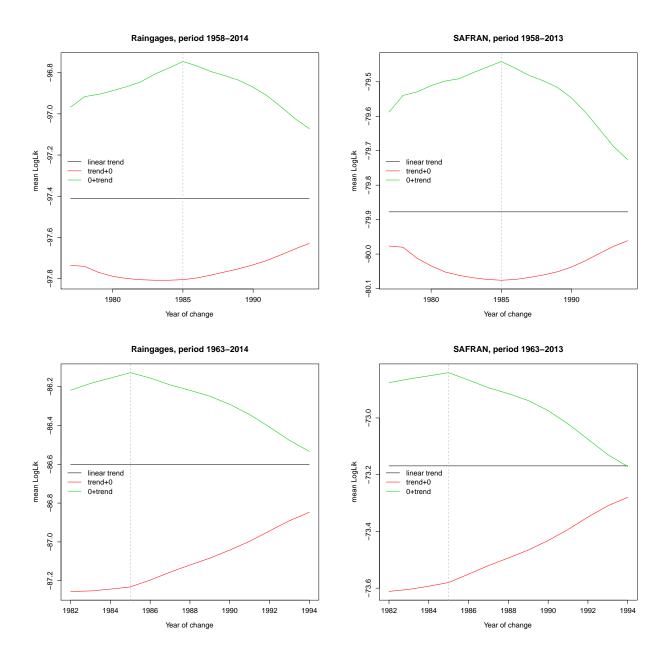


Figure 4: Mean log-likelihood for the three non-stationary models with respect to the year of change for both point (left) and areal (right) rainfall (since the linear model has no change point, it is depicted with horizontal line). Top: for the series with no missing years since 1958. Bottom: for the series with no missing years since 1963.

any regional modeling is obtained by checking for each series independently whether the non-stationary model performs statistically better than the stationary one. Due to its clear better performance compared to the two other considered non-stationary models (see Figure 4), we here focus only on model of Eq. 3 with a trend starting at some date. Figure 5 shows, for each year of change, the percentage of series for which model of Eq. 3 is statistically better than the stationary model. Here we use the selection criteria presented section 3.2, namely AIC and BIC, which are, strictly speaking, not statistical tests but penalized likelihood criteria, and the LRT at levels 5% and 10%, giving in total four criteria per series. Figure 5 reveals a good concordance between the results obtained with AIC and the LRT at level 10% on the one hand (plain lines), and between BIC and the LRT at level 5% on the other hand (dotted lines). Therefore, although they are strictly speaking not statistical tests, AIC and BIC are actually roughly equivalent to likelihood ratio testing. Figure 5 also shows that less trends are detected as significant with BIC than with AIC, which was expected since the former uses a stronger penalization (compare Eq. 7 to 8). The same applies obviously to the two likelihood ratio tests. One finding is that, whatever the criteria, a larger proportion of trends are detected as significant for the point maxima than for the areal ones (compare the blue lines to the red lines). Another finding is that, when using moderately strict tests (in AIC and the LRT at level 10%), all years of changes between the 80's and the 90's seem to be almost as likely, but when the test becomes stricter (in BIC and the LRT at level 5%), the year 1985 pops out as the most likely, which agrees with the results of Figure 4.

Figure 6 maps the series with a significant trend starting in 1985 according to each criterium of Figure 5. The most striking feature is that AIC and the likelihood ratio test at level 10% on one hand, and BIC and the likelihood ratio test at level 5% on the other hand, give the same spatial patterns of trends. So not only the percentage of trends (Figure 5) are similar in each case, but also the same series are detected as non-stationary. Grossly speaking, yearly maxima of daily rainfall over both the Alps and the Cévennes-Vivarais relief, the foothills and the Rhône river valley are likely to vary linearly with time since 1985. This forms a sub-region of exactly half the size the original region where 95% of the significant trends are located (dotted delineation in Figure 6). Furthermore, comparison of point and areal cases in the two maps shows that trends are variable at small-scale. This localized pattern of trends is smoothed out in SAFRAN rainfalls because these are computed as weighted averages of raingage series ([Quintana-Seguí et al., 2008, Vidal et al., 2010]) that may exhibit inhomogeneous trends, explaining why less significant trends are found for the areal maxima. Figure 7 shows the magnitude of the estimated trends (left) together with their standard errors (middle) computed following the method of Section 3.1. Most of the study area has undergone an increase in daily

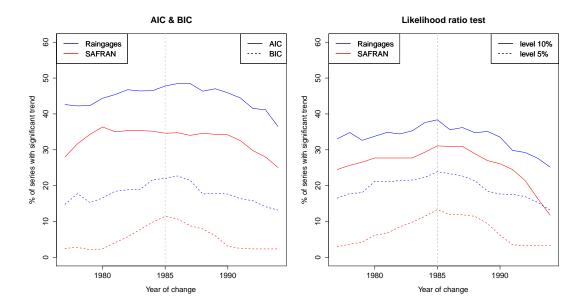


Figure 5: Percentage of series for which the non-stationary GEV distribution of Eq. 3 is preferred to the stationary GEV model of Eq. 1 when the year of change ranges between 1977 and 1994. Preferrence is assessed using AIC (plain-left), BIC (dotted-left) or the likelihood ratio test at levels 10% (plain-right) and 5% (dotted-right).

rainfall maxima since 1985 with larger values in the eastern sub-region where most significant 379 trends are found (see Figure 6). The largest increases of point rainfall maxima are found in two 380 spots: first, along the Cévennes-Vivarais mountain range where increases reach more than 60 381 mm/day in 20 years. This is however also where uncertainty in the highest, with standard errors 382 around 50% of this increase. Second, around the town of Alès with increases up to about 45 383 mm/day in 20 years, however again with standard errors of about 50% of this increase. Inter-384 estingly, these two spots feature respectively the largest averages and the largest absolute values of rainfall maxima (see Fig. 2). The largest trends in areal rainfall maxima are found in the 386 whole Cévennes-Vivarais slope with up to 1.5 mm/day/year increase. This area features also 387 the largest averages of yearly areal maxima (see Fig. 2). Thus, whatever point or areal rainfall, 388 the largest trends are found where rainfall maxima are the largest. This is however In order to 389 filter out this effect, we display in the right panel of Figure 7 the trend magnitudes relatively to 390 the averages of rainfall maxima. The same two spots, around Alès and the Cévennes-Vivarais 391 slope, still feature among the largest relative trends with increases in the last 20 years reaching 392 up to 40% of the average maxima in these areas. Few other spots stand out: the southwest of 393 the region, which is prone to heavy rainfall events when southeasterly low level flux is blocked by 394 the Pyrenees mountains at the South and by the Massif Central at the North, sustaining deep 395 convection ([Ducrocq et al., 2008, Duffourg and Ducrocq, 2011]); the coastal region of Montpellier and the northern part of the Rhône river valley around the town of Valence. There, the 397

Vercors and Massif Central mountains are closed (about 20 km) drawing a strait where flows 398 the Rhône river. This topography may block southerly air mass flux. [Froidurot et al., 2015] 399 notices that 3-hourly rainfall is considerable in this area and features a marked diurnal cycle. 400 One possible mechanism is the influence of the sea breeze which can penetrate inland up to 401 Valence ([Bastin et al., 2005, Drobinski et al., 2006]) and which has been associated to rain in 402 other coastal areas ([Pielke, 1974, Hill et al., 2010]). On the other hand, the mountainous areas south of the Massif Central or the area west of Montpellier have experienced very little increase, 404 if not decrease, in the last 20 years (see Fig. 7). This high variability of trends shows that 405 complex physical processes play a role in the occurrence of trends in the region. 406

The previous results show significance of local trends. Still remains the question: is the 407 number of trends detected in Figure 6 significant at regional scale? Answering this question 408 belongs to the domain of field significance. If the maxima were independent, then field sig-409 nificance could be obtained either by comparing the distribution of the local test p-values 410 to the uniform distribution ([Vogel and Kroll, 1989]), or of the number of rejection of local 411 tests to the binomial distribution ([Livezey and Chen, 1983]), or by considering the regional 412 likelihood as a sum of local likelihoods and applying any test of non-stationarity, e.g. LRT, 413 possibily correcting for the effective degrees of freedom due to spatially dependent trends ([Bretherton et al., 1999, Vautard et al., 2015]). However, applying these tests in our case would 415 be inconsistent owing to the spatial dependence of rainfall maxima ([Bernard et al., 2013]). It 416 would tend to an overestimation of the regional p-value and thus an underestimation of the 417 Type I error rate. Thus, properly testing field significance requires taking into account the 418 spatial correlation among maxima: is the number of trends detected in Figure 6 significant at 419 regional scale, given the spatial correlation of the rainfall maxima? We address this question by 420 a bootstrap procedure ([Douglas et al., 2000, Renard et al., 2008, Pujol et al., 2007b]), which is 421 an iterative simulation procedure allowing to empirically estimate the distribution of the number 422 of locally significant trends under the null hypothesis that the series of maxima are stationary 423 but spatially correlated. We use 1000 bootstrap runs. Each run consists of the following steps 424 ([Renard et al., 2008]): (i) Sample the years with replacement and create the new database 425 obtained by replacing the original series of maxima by the maxima corresponding to these boot-426 strapped years; (ii) Apply the four tests of Figure 6 to each bootstrapped series; (iii) Maps the 427 series with significant trends as in Figure 6. In the end, 1000 maps such as those of Figure 6 428 are obtained. Comparing the number of significant trends in the original maps of Figure 6 to the bootstrapped maps gives an approximate p-value of the test of field significance, estimated 430 as the proportion of the bootstrapped maps showing more significant trends than Figure 6. Ta-431 ble 1 shows these p-values depending on the database, on the criterium for local testing and on

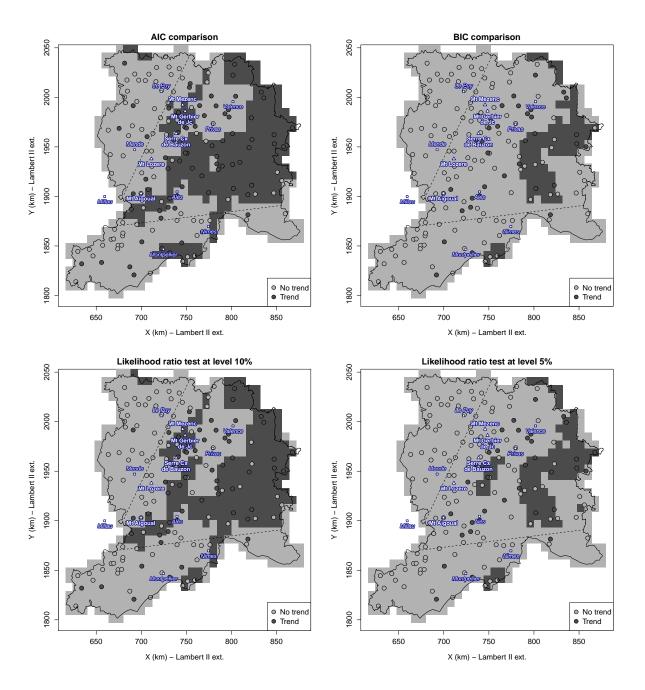


Figure 6: Test of trend at daily scale. The considered non-stationary model is that of Eq. 3 with a change in 1985. Preferrence is assessed using AIC (top-left), BIC (top-right) or the likelihood ratio test at levels 10% (bottom-left) and 5% (bottom-right). The dotted lines delineate the border of the eastern sub-region where the large majority of the significant trends are found.

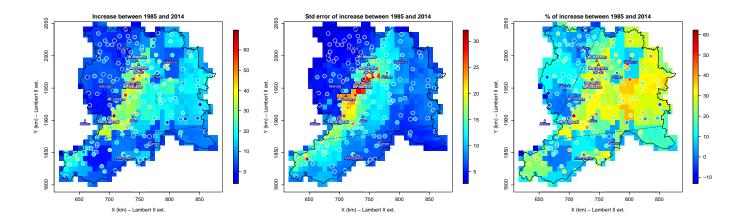


Figure 7: Trend in yearly maxima of daily rainfall accumulation between 1985 and 2014. Left: Magnitude of increase (mm/day). Middle: Standard error of increase (mm/day). Right: Percentage of increase with respect to the average maxima of the series. The dotted lines delineate the border of the eastern sub-region where the large majority of the significant trends are found.

		AIC	BIC	LRT 10%	LRT 5%
whole region	Raingages	3.5 **	4.3 **	2.8 **	4.2 **
eastern region	Raingages	2.3 **	3.2 **	2.2 **	3 **
whole region	SAFRAN	13.4	17	8.8 *	16
eastern region	SAFRAN	6.5 *	10 *	3.6 **	9.1 *

Table 1: Proportion (%) of the bootstrap runs detecting more significant trends than those detected on the original data, when considering either the whole region or the eastern part. The criteria to detect trends are AIC, BIC and LRT at levels 10% and 5%. Very significant trends at regional scale are shown with ** (p-value smaller that 5%), moderately significant trend with * (p-value between 5% and 10%).

the considered region. Point rainfall maxima show highly positive trends at the regional scale with all criteria (first row of Table 1), whereas areal rainfalls are moderately significant with a LRT at level 10% and non significant otherwise (third row). When restricting to the eastern sub-region where the large majority of the significant trends are (see Figure 6), trends in point rainfall maxima become even more significant (second row) and trends in areal maxima become all significant, and even very significant with a LRT at level 10% (fourth row).

5 Conclusion

This study addresses trends in yearly maxima of daily point and areal rainfall in southern France. The adopted methodology is to model the statistical distribution of rainfall maxima by different cases of non-stationary GEV models in which the location parameter changes linearly

with years either after or before a given date. Such non-stationary models assume a translation 443 of the distribution of maxima from year to year towards higher or lower values, before or after 444 a given date. The stationary model is a particular case when the linear trend is null. The 445 proposed methodology for trend analysis involves three steps. First, all the considered non-446 stationary models are estimated for each point and areal rainfall series of maxima. Second, 447 the best model is selected at regional scale by likelihood comparisons, which also allows us to select the best trend-starting/ending date. Third the corresponding non-stationary model is 449 objectively tested for each series of maxima to assess significance of the trends, both at local 450 and regional scales. 451

This statistical framework is applied to 52 years of both point and areal rainfall data on 452 $8 \times 8 \text{ km}^2$ grids in southern France. The results show a fairly good accordance of the detected 453 trends for the two spatial scales. At regional scale, the most likely starting date of the trend 454 lies between the 80's and the 90's, with 1985 as the most likely. The trend in point rainfall 455 is highly significantly positive in half the region including most of the mountain ranges and 456 part of the Rhône valley. Spatial rainfall also indicates positive trends in these area, however 457 usually of lower magnitude and thus of lower significance. In terms of trend magnitude, two 458 spots stand particularly out for the two spatial scales: the Cévennes-Vivarais ridge and around 459 Alès. These two spots feature both the largest rainfall maxima and the largest trends, which can 460 reach an increase in yearly maxima of more than 62 mm/day in 20 years. This is considerable 461 since it represents more than 40% of the average maximum in this area. Such a high relative 462 increase occurs also in areas where maxima are rather moderate, such as the Rhone river valley, 463 while the mountainous region south of the Massif Central and the area west of Montpellier have 464 experienced very little increase, if not decrease. 465

These results question the processes leading to trends. How are these results in agreement 466 with the well-known Clausius-Clapeyron relationship? If the atmosphere contains more precip-467 itable water due to global warming, why does it imprint rainfall maxima in some regions and 468 not in others? Insights on the amount of precipitable water (e.g. [Duffourg and Ducrocq, 2011]) 469 are necessary to understand the occurrence of trends. However the question of rainfall sampling 470 is of primary importance. Better understanding may be gained by analysing trends in sub-471 daily rainfall maxima, which are less prone to stationary precipitation ([Ceresetti et al., 2010, 472 Molinié et al., 2012). Unfortunately such chronological rainfall series are usually neither long 473 enough nor dense enough to provide reliable statistics at regional scale. 474

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