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# **Experimental evidence for crustal control over seismic fault segmentation**

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## **ABSTRACT**

**Strike-slip faults are described as continuous structures, while they are actually formed of successive segments separated by geometrical complexities. Although this along-strike segmentation is known to affect the overall dynamics of earthquakes, the physical processes governing the scale of this segmentation remain unclear. Here, we use analogue models to investigate the structural development of strike-slip faults and the physical parameters controlling segmentation. We show that length of fault segments is regular along strike, and scales linearly with the thickness of the brittle material. Variations of the rheological properties only have minor effects on the scaling relationship. Ratios between the segment length and the brittle material thickness are similar for co-seismic ruptures and sandbox experiments. This supports a model where crustal seismogenic thickness controls fault geometry. Finally, we show that the**

**geometrical complexity acquired during the strike-slip fault formation withstands cumulative displacement. Thus, inherited complexity impedes the formation of an ever straighter fault, and might control the length of earthquakes ruptures.**

## **INTRODUCTION**

Strike-slip faults are discontinuous features formed by a succession of segments, separated by geometrical complexities, such as bends, or relay zones (Fig. 1.a, S1)(e.g. Segall and Pollard, 1980). Although the size of these complexities is highly variable, even the smaller ones can significantly affect initiation, propagation, and termination of earthquakes (e.g. King and Nabelek, 1985; Wesnousky, 2006; Klinger et al., 2005; Manighetti et al., 2007), implying their persistence at seismogenic depth (e.g. Schwartz and Coppersmith, 1984; Wei et al., 2011; Schwartz, 2018). Fault discontinuities also modulate amplitude and style of co-seismic surface deformation (Klinger et al., 2006; Vallée et al., 2008), and might stop ruptures propagation if larger than 5 km (e.g. Wesnousky, 2006). Recently, numerical simulations of rupture scenarios have confirmed the strong dependency of earthquake rupture models on the geometry of the fault system (e.g. Aochi and Ulrich, 2015; Lozos, 2016; Klinger et al., 2018). As a consequence, understanding the genesis of the segmentation and its scaling is critical for physics-based earthquake modeling, as well as for hazard assessment, since complexities impact the earthquake rupture length, and thus its magnitude.

Based on experimental, seismological, and geomorphological studies, fault segmentation was first described as fractal (e.g. Aviles et al., 1987; Okubo and Aki, 1987). Alternatively, it was suggested that faults are composed of a fixed number of segments, implying a segment length varying between faults (e.g. Manighetti et al., 2015).

Conversely, studies based on co-seismic rupture maps have argued in favor of a constant segment length of about  $18 \text{ km} \pm 5 \text{ km}$ , independent of the regional tectonic setting or the earthquake magnitude, suggesting an external controlling factor, which is assumed to be the seismogenic crust thickness (e.g. Bilham and Williams, 1985; Klinger, 2010)(Fig. 1.a). However, detailed co-seismic rupture maps are available only for a limited number of earthquakes, preventing a reliable statistical analysis. The lack of data combined with our limited knowledge of the fault segmentation process prevent us from discriminating between these models.

To tackle the origin of strike-slip fault segmentation, we followed an analogue modeling approach, which provides the complete geometrical evolution of the fault structure while accumulating slip. Moreover, a large number of experiments can be conducted, allowing for a thorough exploration of the impact of the geometrical and rheological parameters.

## **ANALOGUE MODELING OF STRIKE-SLIP FAULTS**

Numerous analogue studies already focused on the formation and final geometry of strike-slip faults systems (Dooley and Schreurs, 2012 and references therein). In experiments with sand overlying a straight basal dislocation, the first structures to appear are the Riedel shears (R-shears)(Riedel, 1929; Naylor et al., 1986), propagating upward (e.g. Ueta et al., 2000, Cambonie et al., 2018), oriented at the surface at an angle of  $\varphi_{\text{int}}/2$  relative to strike-slip basal fault ( $\varphi_{\text{int}}$ , angle of internal friction of the material). This orientation is due to the helicoidal shape of the Riedels (Fig 1,b) (Naylor et al., 1986; Mandl, 1987). The next structures to appear are first, synthetic shears (S-shear) that only slightly deviate from the strike of the basal fault, and finally P-shears, which cross the basal fault in the opposite direction. Eventually, coalescence of these different

shears leads to the formation of an anastomosed fault zone (e.g. Naylor et al., 1986; Richard et al., 1995).

Here, we investigate if the first structures to appear during the formation of strike-slip faults can be responsible for the long-term segmentation. As these faults result from the linkage of the S-shears, the initial discontinuities between them at the locations of the Riedels might persist and give rise to geometrical complexities. Therefore, we consider the distance between two adjacent Riedels as equivalent to a fault segment. Although dependency of the length of Riedels on the thickness of the frictional material had already been suspected, it was never indisputably demonstrated (Tchalenko, 1970; Atmaoui et al., 2006, Hatem et al., 2017). Thus, we first evaluate the influence of the material thickness on the inter-Riedels distance, and then the impact of intrinsic properties of the material.

We used an analogue model set-up known as Riedel experiments in a 1.2m x 0.8m box (detailed set-up in Supp. Mat., Fig. S2). The model reproduces brittle deformation in a non-cohesive material during the onset of a strike-slip fault in a homogeneous sandpack above a straight-basal fault. To test the impact of the frictional properties on the fault geometry, we used four different Aeolian sands with different internal frictions (Sand 1,  $\varphi_{\text{int}}=43.7^\circ$ ; Sand 2,  $\varphi_{\text{int}}=35.6^\circ$ ; Sand 3,  $\varphi_{\text{int}}=33.4^\circ$ ; Sand 4,  $\varphi_{\text{int}}=22.1^\circ$ ) and variable basal materials, such as PVC ( $\varphi_b=13^\circ$ ) Alkor-foil ( $\varphi_b=18^\circ$ ) and sand paper ( $\varphi_b>43.7^\circ$ ). Some of these sands are poured and have a rate-hardening behavior (sand 2, 3 and 4), while sand 1 is sedimented and rate-weakening (see Supp. Mat. for material properties). A camera placed above the box records the deformation every 0.5mm of basal displacement to generate orthoimages of the sandbox surface, with a resolution of the order of the grain size. Moreover, to assess how the shear is accommodated by the different structures, we computed the incremental displacement field from optical images correlation using

Micmac software (Rosu et al., 2015). The set-up is intentionally simple to limit the number of free parameters and to ensure a good control on the boundary conditions of the experiment. The aim of these experiments is not to reproduce details of a realistic strike-slip fault evolution, but to retrieve relationships between fault-characteristic patterns and properties of material.

For each sandpack thickness ( $T$ ), three parameters were extracted from surface images for each Riedel: the inter-Riedel distances ( $S$ ) measured parallel to the trace of the basal fault, the Riedels length ( $L$ ), and the angle ( $\alpha$ ) formed by the Riedel with the direction of the basal fault (Fig. 1.c). We ran repeated experiments with thicknesses varying from 2 to 5 cm (Table S1). Only the experiments with thicknesses lower or equal to 5cm were free of edge effects (Fig. S3). The minimum thickness is constrained by the ability of the sand to develop the 3D helicoidal shape of Riedel shears. When sand is thinner than 1.5 cm, instead of the Riedel shears, a continuous fault directly appears at the surface (Fig. S4).

To provide robust correlations between thickness, material properties, and fault geometry, we need repeated experimental measurements. As several Riedels are visible in each experiment, we checked that we could use them as independent measurements to improve statistical significance (see verification in Supp. Mat.). In the following, for clarity's sake, only average quantities per experiment are presented and discussed (individual measurements in Supp. Mat. Fig. S7-S11).

## **SCALING RELATIONSHIPS DERIVED FROM SANDBOX**

Surface images of the experiments for different thicknesses ( $T$ ) show that the deformed area widens and the inter-Riedel distance ( $S$ ) increases for thicker sandpack (Fig. 2.a).

Indeed, systematic measurements of (S) for different (T) show a linear correlation between those parameters (Fig. 2.b), with a scale factor of about 2.8 for Sand 1.

To test the potential effect of the material properties, we first performed experiments with sands of different internal friction. The three sets of experiments exhibit the same trend: (S) increases with (T) (Fig. 2.c, S7), and the measurements distributions are well modeled by linear relationships. Nevertheless, depending on the internal friction, the slope of the best-fit lines changes, indicating a partial control of the material properties on the size of the structures. The slope is 1.43 for the smaller friction ( $\phi_{\text{int}}=33.4^\circ$ , Sand 3), 1.61 for the intermediate friction ( $\phi_{\text{int}}=35.6^\circ$ , Sand 2), and 2.76 for the highest one ( $\phi_{\text{int}}=43.7^\circ$ , Sand 1). As Sand 2 and 3 present relatively similar relationships (Fig. 2.c) and are both strain-hardening, we cannot exclude from our data that the discrepancy between Sand 1 and other sands could be due to its strain-weakening properties instead of its internal friction (Fig. S11). Nevertheless, as Riedel shears form when shear stress reaches the static friction (Tchalenko, 1970, Ritter et al. 2018), we think that the internal friction, of the sands controls the relation between S and T, and not its strain hardening or weakening property.

Using different materials to test the impact of the internal friction might also change the basal friction between the different experiments. To assess a possible trade-off between these two parameters, we conducted three series of experiments using Sand 1 with different basal materials (Fig. 2.d, S7). For the three tested basal frictions we observed linear relations between (S) and (T). The slopes of the regressions are quite similar, and only the intercepts change slightly (Fig. 2.d). The associated change of x-axis intercept corresponds to the minimal thickness necessary to develop the Riedels-helicoid. This observation suggests that the basal friction impacts the formation of the helicoid,

probably by changing the width of the deformed area at depth (see Supp. Mat. mechanical implications).

We then examined the effect of the cohesion on the inter-Riedel distance ( $S$ ), using non-cohesive (Sand 3) and strongly cohesive (Sand 4) sands (Fig. 2.e, S8). Again, ( $S$ ) increases linearly with ( $T$ ). The two linear regressions present the same slope but shifted intercepts, with a larger value for the highly cohesive sand (of about 1.5 cm). However, this difference may not be significant in view of the small number of experiments associated to a high dispersion of the Sand 4 measurements, interpreted as resulting from heterogeneities in the sand mixture due to its electro-static charge (see Supp. Mat.). We consider that cohesion only marginally affects the fault geometry, as ( $S$ ) is only slightly affected whereas all parameters vary and uncertainties are significant.

## **COMPARISON OF EXPERIMENTAL RESULTS WITH EARTHQUAKE SURFACE- RUPTURES GEOMETRY**

This new set of experiments demonstrates unambiguously that the inter-Riedel distance ( $S$ ) is directly controlled by the thickness of the sandpack ( $T$ )(Fig. 2), while the material properties have secondary effects. The internal friction controls the scaling factor of the linear relation between ( $S$ ) and ( $T$ ), whereas the basal friction and the cohesion only marginally impact this relation. The width and rheology of the basal deformation zone, which are not addressed here, might also affect the size of structures (Hatem et al. 2017, Zuza et al. 2017, Yang et al. 2020).

According to field studies, strike-slip fault segments, measured between two successive relay zones, have similar lengths independently of the local tectonic setting (Klinger, 2010). Thus, it was suggested that the average length of fault segments scales with the thickness of the seismogenic crust (Bilham and Williams, 1985; Klinger, 2010), with a

ratio close to 1. To compare our experiments with natural observations, we selected sands 2 and 3, both non-dilatant and with frictions within the same range as standard upper crust materials ( $\mu \sim 0.7$ ) (e.g. Byerlee, 1978).

For comparison, the inter-Riedel distance and the length of fault segments were normalized respectively by the thickness of sand and of seismogenic crust, which is derived from the literature (details in Supp. Mat.). The average normalized length for natural fault segments is 1.16, and for sands 2 and 3 it is 1.17 and 1.3, which are indistinguishable from the natural case (Fig. 3). Moreover, individual ratio values are all in a narrow range ( $\sigma=0.43$ ), which indicates that such similarity is not coincidental. This supports the hypothesis that the length of continental strike-slip segments is directly controlled by the thickness of the seismogenic crust.

Although this approach does not capture the effects of a dynamic rupture, it sheds light upon the way faults sections grow to eventually coalesce into an apparent continuous structure. Interestingly, our experiments show that even when the cumulative displacement during the experiment starts to be large enough to dismantle the Riedels and to allow coalescence of successive S-shears into a longer fault, the initial geometric discontinuity related to the location of the Riedel is preserved (Fig. 4.a). Riedels act as inherited faults influencing the location of subsequent deformation. In the case of strike-slip faults, such discontinuities will turn into relay zones, either compressional or extensional. Indeed, in nature faults form in crust that already went through multiple stages of deformation and that displays local geological variation. Thus the simple scenario of faults structured only according to the thickness of the brittle crust is likely modulated by inherited crustal heterogeneities, resulting in some relay zones being larger than others. Sandbox experiments can also present such variability with larger complexities randomly appearing (Fig. S14), suggesting that the initial orientation of the

S-shears might also influence the size of the relay zones. Other studies have proposed that the off-fault deformation of earthquakes could be related to the reactivation of these Riedels (Hatem et al. 2017), although we could not observe such reactivation in our experiments. Moreover, in nature evidence of the initial Riedels structures is tenuous, as they accommodate a very short amount of deformation before being passively offset by the main active fault, which explains their weak morphological expression at the surface. These results show that the first stages of deformation determine the long-term scaling of the of strike-slip faults segmentation: Riedels create a regular pattern of geometrical complexities, which is inherited throughout the fault history (Fig. 4.b). This pattern of segmentation does not seem to experience significant changes even after the Riedels have ceased to be active, as we keep seeing it on the coseismic-rupture map. Thus, this questions the paradigm that faults become even more linear while accumulating displacement through time, and thus prone to larger earthquakes. Instead, strike-slip fault geometry may retain a constant level of complexity, which controls the size of earthquakes.

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## FIGURES

Figure 1: **a.** Surface rupture map of the 1992 Landers earthquake, California. Segmentation (black lines), according to Klinger (2010). **b.** Evolutionary scheme of the formation of strike-slip faults, seen from the surface, and a 3D sketch to illustrate the helicoidal-shape of the Riedels. **c.** Top view of the sandbox, with the measured parameters, S: inter-Riedel distance, L: Riedel length,  $\alpha$ : angle between the Riedel and the basement fault.

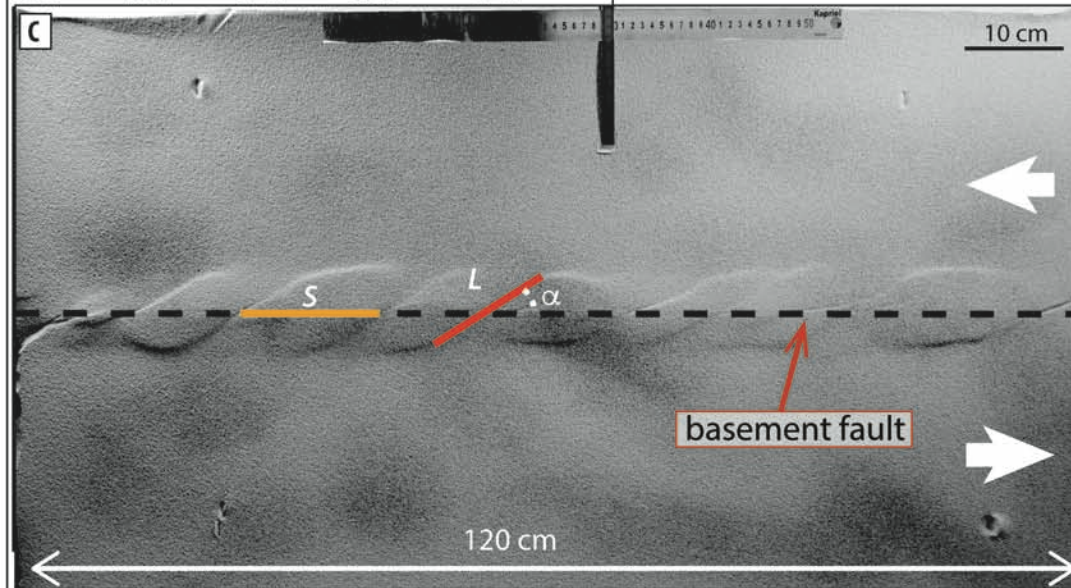
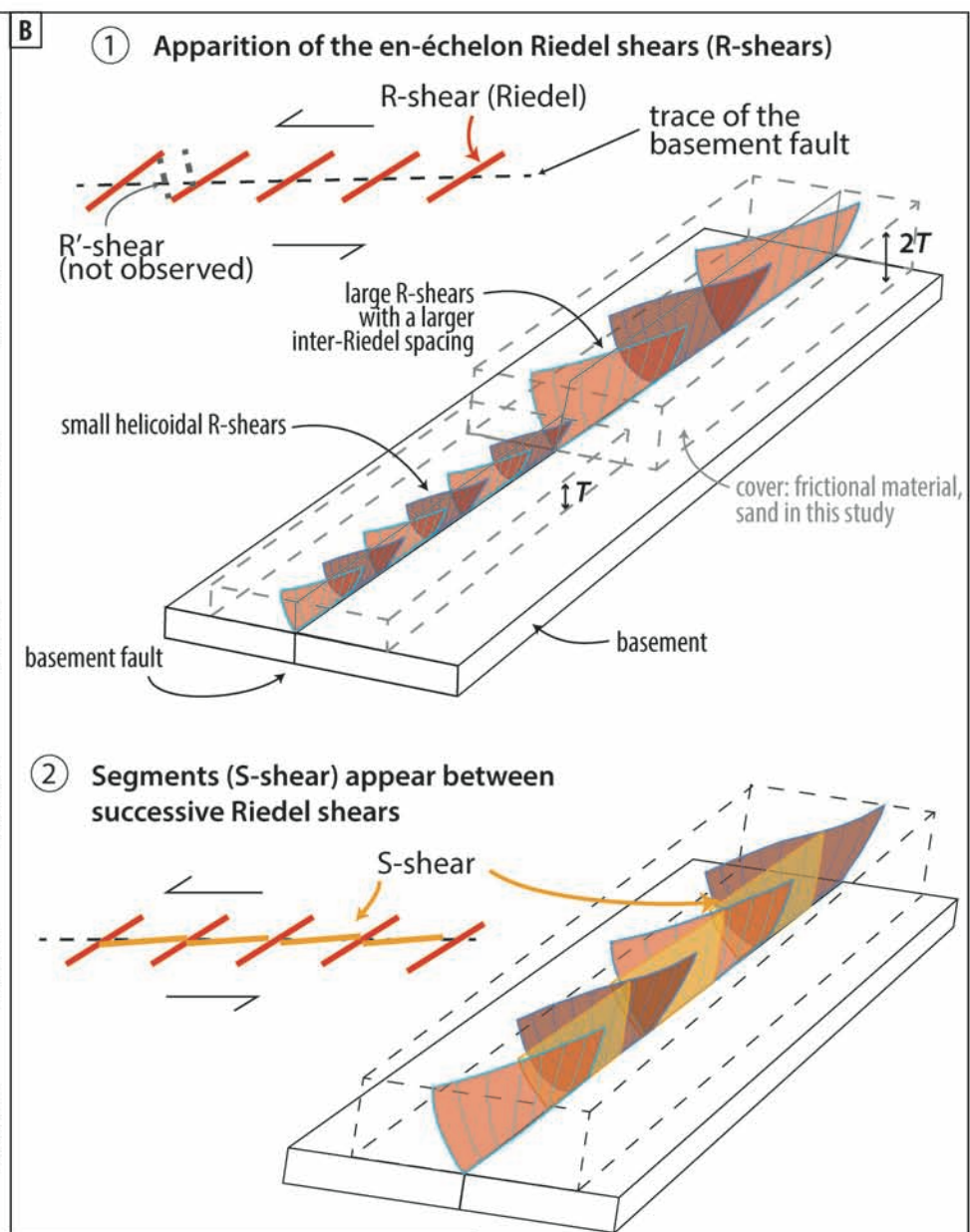
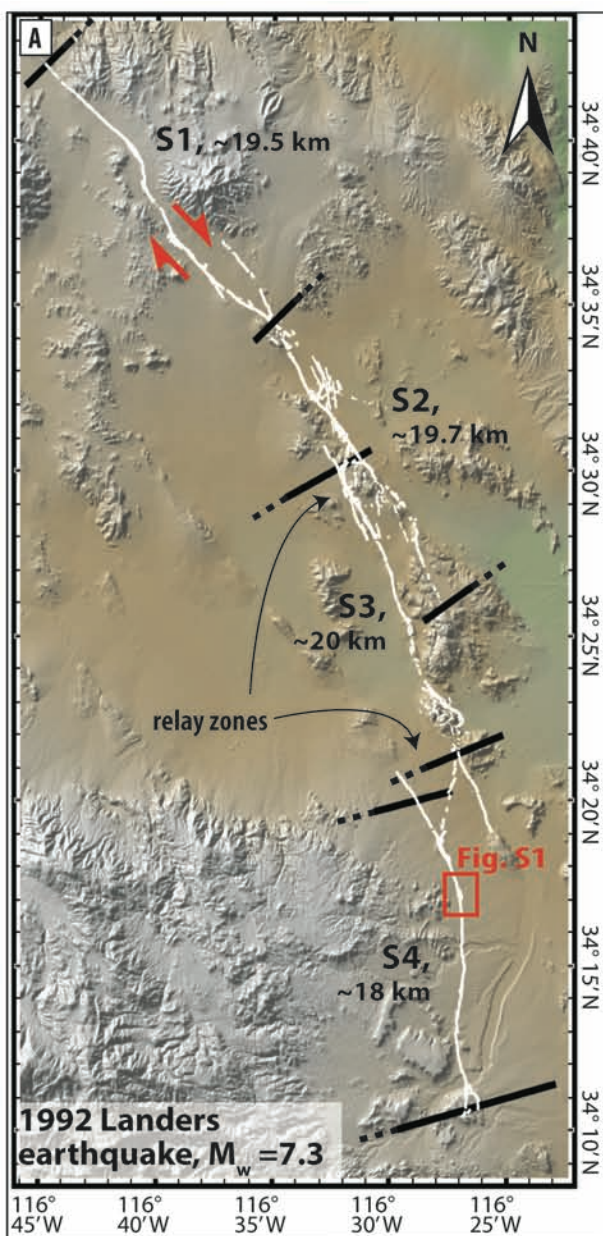
Figure 2: Comparison between inter-Riedel distance (S) and sandpack thickness (T) for different frictional and cohesional properties of the sand. **a.** Pictures of the top of the sandbox

after ~11-12 mm of displacement for experiments with a 2, 3 and 4 cm-thick sandpack. **b., c., d., e.** Average inter-Riedel distance (S) per experiment versus sand-pack thickness (T) for Sand 1 (b.); for three different sands with different internal friction (c); for three different basal materials to study the basal friction effect (d); and for two sands with different cohesion (e). Note that for clarity's sake, for Sand 1 on graphics c and d, we represent the average value by thickness rather than by experiment.

Figure 3 : Normalised length of individual fault segments for several continental strike-slip earthquakes (Klinger, 2010, Lauer et al., 2018) and for individual analogue-fault segments. Sand 1 is shown only for comparison. The length is normalized to inferred seismogenic thickness or sand thickness accordingly. Values of seismogenic crust thicknesses are estimated from the literature (see Supp. Mat.)

Figure 4: **a.** Curl of the incremental displacement field for a 4 cm-thick experiment (T=4cm) at three different stages of the deformation (d=7.5mm, d=10mm, d=13mm). The curl is derived from the correlation image between two successive pictures of the sandbox surface. It highlights the location of shear. The location of the different active faults (R-shear, S-shear) is highlighted. **b.** Scheme of the 3D-structures of a strike-slip fault at the crustal scale.

Figure 3 : Normalised length of individual fault segments for several continental strike-slip earthquakes (Klinger, 2010, Lauer et al., 2018) and for individual analogue-fault segments (see Fig. S13 for comparison with sands 1 and 4). The length is normalized to inferred seismogenic thickness or sand thickness accordingly. Values of seismogenic crust thicknesses are estimated from the literature (see Supp. Mat.)



③ S-shears coalesce and form a continuous fault; Riedel shears are no longer active but passively translated

