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Laminar supersonic sphere wake unstable bifurcations

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ABSTRACT

The laminar sphere unstable bifurcations are sought at a Mach number of $M_\infty = 1.2$. Global stability performed on steady axisymmetric base flows determines the regular bifurcation critical Reynolds number at $Re_{cr}^{reg} = 650$, identifying a steady planar-symmetric mode to cause the loss of the wake axisymmetry. When global stability is performed on steady planar-symmetric base flows, a Hopf bifurcation is found at $Re_{cr}^{Hopf} = 875$ and an oscillatory planar-symmetric mode is temporally amplified. Despite some differences due to highly compressible effects, the supersonic unstable bifurcations present remarkably similar characteristics to their incompressible counterparts, indicating a robust laminar wake behavior over a large range of flow speeds. A new bifurcation for steady planar-symmetric base flow solutions is found above $Re > 1000$, caused by an anti-symmetric mode consisting of a 90° rotation of the dominant mode. To investigate this reflectional symmetry breaking bifurcation in the nonlinear framework, unsteady nonlinear calculations are carried out up to $Re = 1300$ and dynamic mode decomposition (DMD) based on the combination of input data low-dimensionalization and compressive sensing is used. While the DMD analysis confirms dominance and correspondence in terms of modal spatial distribution with respect to the global stability mode responsible for the Hopf bifurcation, no reflectional symmetry breaking DMD modes were found, asserting that the reflectional symmetry breaking instability is not observable in the nonlinear dynamics. The increased complexity of the wake dynamics at $Re = 1300$ can be instead explained by nonlinear interactions that suggest the low-frequency unsteadiness to be linked to the destabilization of the hairpin vortex shedding limit cycle.

NOMENCLATURE

CFL	Courant–Friedrichs–Lewy number	Re	Reynolds number
C_L	lift coefficient	Re_{cr}^{Hopf}	Hopf bifurcation critical Reynolds number
DMD	dynamic mode decomposition	Re_{cr}^{reg}	regular bifurcation critical Reynolds number
D_s^*	dimensional sphere diameter	St	Strouhal number, non-dimensional frequency
E	total energy	t	time
L_{sep}	base flow separation length	$[u, v, w]^T$	streamwise, transversal, and vertical velocities
M_∞	inflow Mach number	$[u_x, u_r, u_\theta]^T$	streamwise, radial, and azimuthal velocities
PS	planar-symmetric	$[x, y, z]^T$	streamwise, transversal, and vertical coordinates
PSD	power spectral density	ΔT	Krylov time step
\mathbf{q}	conservative variables' state vector	Δt	integration time step
\mathbf{q}_b	base flow conservative variables' state vector	λ	complex eigenvalue
\mathbf{q}'	perturbation conservative variables' state vector	ρ	density
$\hat{\mathbf{q}}$	eigenfunction conservative variables' state vector	σ	growth rate
		σ_{NL}	growth rate obtained from nonlinear calculations
		ω	angular frequency

I. INTRODUCTION

For many engineering applications, the appearance of large-scale unsteadiness represents a design operability limiting factor. The increase of drag and flow-induced vibrations consequent to the unsteadiness onset are not only detrimental for the overall performances but can eventually lead to structural failure due to fatigue. Fundamental studies on three-dimensional (3D) unsteady dynamics associated with axisymmetric bodies, like a sphere, have shown been to be physically relevant to understand more complex configurations, such as launcher after-bodies or re-entry capsules. The incompressible behavior of the space-time dynamics of a flow past a sphere has been well documented in the past both experimentally^{1–5} and numerically.^{6–14} While the interest of the scientific community for the incompressible regime is still very high and numerous studies have been recently done,^{15–20} very limited information exists regarding the effects of compressibility, especially at supersonic speeds.

The scientific community currently seems to agree on the stabilizing effect of the Mach number ($M_\infty = U_\infty^*/c_\infty^*$ with U_∞^* and c_∞^* being the dimensional free-stream velocity and speed of sound, respectively) both at subsonic and supersonic speeds for sphere wakes^{21–25} and other flow configurations as thin wakes²⁶ and boundary layers on rotating disks.²⁷ The first (pitchfork or regular) and secondary (supercritical Hopf) unstable bifurcations for an incompressible flow past a sphere are responsible for the loss of spatial axisymmetry and for causing the flow to become unsteady, respectively. Although they are seen to persist in the compressible regime, the corresponding critical Reynolds numbers move toward higher values for increasing Mach number, indicating its stabilizing effect on the wake dynamics. However, no unstable bifurcations at supersonic speeds were found in the Reynolds number ($Re = U_\infty^* D_s^*/\nu_\infty^*$ with ν_∞^* being the dimensional free-stream kinematic viscosity and D_s^* being the dimensional sphere diameter) range considered ($Re < 600$), and the flow system was shown to be globally stable and, more precisely, temporally steady and spatially axisymmetric. Evidence of the existence of unstable bifurcations in the supersonic regime was recently given in a set of direct numerical simulations at higher Reynolds numbers by Nagata *et al.*,²³ who found the flow to first lose its spatial axisymmetry and then become unsteady via the shedding of hairpin vortices downstream of the sphere, like for its subsonic counterpart. The experiments of Nagata *et al.*²⁸ at free-flight conditions examined schlieren visualizations of a sphere at $0.9 < M_\infty < 1.6$ and $3900 < Re < 380\,000$ and also showed that an unsteadiness existed at $Re = 8100$ and $M_\infty = 1.4$. However, neither the mechanisms driving the onset of instabilities nor a characterization of the unsteady behavior was given in detail. An interesting and less investigated flow regime that presents wake dynamic instabilities is the transonic one. Riahi *et al.*²⁵ performed calculations of incompressible and compressible spheres with an improved new immersed boundary method and accurately captured different flow configurations. Among these, an unsteady (alternating hairpin) wake was found at $M_\infty = 0.95$ and $Re = 600$, for which a shock wave forms on the sphere wake. Other relevant studies showing the effect of cooled/heated²⁹ or rotating³⁰ laminar sphere are worth mentioning for the Mach number range investigated ($0.3 < M_\infty < 2.0$).

Despite some evidence in the literature, a precise identification and characterization of the regular and Hopf bifurcations of a supersonic sphere wake are still lacking. The present work aims at

extending the analysis done in the work of Sansica *et al.*,²⁴ for which no evidence of the unstable bifurcations was found at $M_\infty = 1.2$ and Reynolds numbers up to $Re = 380$. The current objective is therefore to perform fully 3D global stability analysis on a sphere wake at the same Mach number but in a higher Reynolds number range between $Re = 500$ and 1300 , with the intent to stretch the boundaries of the state-of-the-art knowledge toward an unknown and less documented region of the $M-Re$ plane.

The paper is organized as follows: the problem formulation, comprehensive of the description of the governing equations and stability problem, is presented in Sec. II; code features and numerical simulation setup details are reported in Sec. III; the results obtained on base flow solutions and by global stability analysis around regular and Hopf bifurcations are described in Sec. IV; Sec. IV also includes global stability and dynamic mode decomposition (DMD)³¹ analyses up to $Re = 1300$, for which a new bifurcation is found; some conclusions and future work opportunities are discussed in Sec. V.

II. PROBLEM FORMULATION

A. Governing equations

The compressible 3D Navier–Stokes (N–S) equations for a perfect gas can be written in the non-dimensional form as

$$\frac{\partial \mathbf{q}}{\partial t} = \mathcal{N}(\mathbf{q}), \quad (1)$$

where $\mathbf{q} = [\rho, \rho \mathbf{u}, \rho E]^T$ is the state vector in the conservative form (with ρ , \mathbf{u} , and E being the fluid density, the velocity vector, and the total energy, respectively) and t is the time. The differential nonlinear N–S operator \mathcal{N} can be explicitly expanded as

$$\mathcal{N}(\mathbf{q}) = -\nabla \cdot \begin{pmatrix} \rho \mathbf{u} \\ \rho \mathbf{u} \otimes \mathbf{u} + p \mathbf{I} - \boldsymbol{\tau} \\ \rho E \mathbf{u} + p \mathbf{u} - \boldsymbol{\tau} \mathbf{u} + \mathbf{q}_h \end{pmatrix} \quad (2)$$

with

$$\begin{aligned} p &= (\gamma - 1)\rho E - \frac{1}{2}\mathbf{u} \cdot \mathbf{u}, \\ \boldsymbol{\tau} &= \mu \left[(\nabla \otimes \mathbf{u} + \nabla \otimes \mathbf{u}^T) - \frac{2}{3}(\nabla \cdot \mathbf{u})\mathbf{I} \right], \\ \mathbf{q}_h &= -\frac{\mu C_p}{Pr} \nabla T, \end{aligned} \quad (3)$$

where p is the pressure, $\boldsymbol{\tau}$ is the viscous stress tensor, C_p is the heat capacity at constant pressure, μ is the dynamic viscosity, Pr is the Prandtl number, T is the temperature, and \mathbf{q}_h is the heat flux. The Prandtl number is assumed to be constant and, being the fluid considered air, equal to $Pr = 0.72$. The dynamic viscosity is assumed to follow Sutherland’s law as

$$\mu = T^{3/2} \frac{1 + T_s}{T + T_s}, \quad (4)$$

where $T_s = 110.4 \text{ K}/T_{i,\infty}^*$ with $T_{i,\infty}^*$ being the dimensional free-stream stagnation temperature (the superscript $*$ indicates dimensional quantities). The array of the streamwise, vertical, and transverse directions is indicated by $\mathbf{x} = [x, y, z]^T$.

The time and length scales are made dimensionless using U_∞^*/D_s^* and D_s^* , respectively, where U_∞^* is the free-stream velocity and D_s^* is the sphere diameter. The dimensionless frequency or

Strouhal number (non-dimensionalized by the sphere diameter and free-stream velocity) is defined as $St = \omega/2\pi$. Similarly to the studies of Nagata *et al.*,^{22,23} Sansica *et al.*,²⁴ and Riahi *et al.*,²⁵ for the high-Mach and low-Reynolds number regimes considered, the dimensional sphere diameters are in the range $D_s^* = 30 \mu\text{m} - 80 \mu\text{m}$. A practical application regards gas-particle multi-phase flows in a solid rocket motor at take off,³² where the alumina particles of size $30 \mu\text{m} - 200 \mu\text{m}$ released in the exhaust supersonic jet could be modeled as tiny spheres. However, the main objective here is to provide a better understanding of the wake dynamics of axisymmetric bodies at supersonic speeds to help unraveling the physics of more complex configurations, such as launcher after-bodies^{21,33} or re-entry capsules,³⁴ for which some similarities exist.

B. Stability problem

The stability problem is based upon the use of the linearized N-S equations. The first step to obtain this linearized set of equations is to assume that the nonlinear system in Eq. (1) admits an equilibrium solution, \mathbf{q}_b , defined by $\mathcal{N}(\mathbf{q}_b) = 0$ and referred to as the fixed point or base flow. The standard small perturbation technique is used to decompose the instantaneous flow into base flow and small disturbances $\mathbf{q}(\mathbf{x}, t) = \mathbf{q}_b(\mathbf{x}) + \varepsilon \mathbf{q}'(\mathbf{x}, t)$, with $\varepsilon \ll 1$. By assuming that the perturbations are infinitesimal, all nonlinear fluctuating terms are ignored and the linearized N-S equations can be written as

$$\frac{\partial \mathbf{q}'}{\partial t} = \mathcal{L}(\mathbf{q}'), \quad (5)$$

where $\mathbf{q}' = [\rho', \rho' \mathbf{u}_b + \rho_b \mathbf{u}', \rho' E_b + \rho_b E']^T$ is the state vector of conservative perturbation variables and $\mathcal{L} = \partial \mathcal{N} / \partial \mathbf{q} |_{\mathbf{q}_b}$ is the Jacobian operator obtained by linearizing the N-S operator \mathcal{N} around the base flow \mathbf{q}_b . By choosing the normal mode or wave solution $\mathbf{q}'(\mathbf{x}, t) = \widehat{\mathbf{q}}(\mathbf{x}) \exp(\lambda t) + c.c$ (with *c.c.* indicating the complex conjugate) and being \mathbf{L} the discrete form of \mathcal{L} , the eigenproblem $\mathbf{L}\widehat{\mathbf{q}} = \lambda \widehat{\mathbf{q}}$ is obtained. The complex eigenvalue can be split into its real and imaginary parts $\lambda = \sigma + i\omega$, where σ is the temporal growth rate and ω is the angular frequency. While the angular frequency characterizes the oscillatory behavior, the temporal growth rate indicates whether the equilibrium state bifurcates to another solution. This bifurcation is expressed in a linear framework by the existence of eigenmodes with a corresponding positive growth rate. It is important to stress that no explicit forcing is imposed and the current approach can only detect instabilities that are self-sustained in the numerical domain under exam. Convective instabilities that might grow and/or decay within the domain considered will be “lost” among the modes in the continuous stable branch.

III. NUMERICAL METHOD

An in-house solver is used to compute the compressible N-S equations, both nonlinear and linearized formulations, on multi-block structured grids with a finite-volume approach. To compute the convective fluxes, the Roe scheme³⁵ is extended to the third order in combination with a MUSCL approach and all flux limiters are set to be inactive. A second order centered scheme is used to differentiate the viscous terms. A dual time stepping method is used to advance the N-S solution in time by an implicit pseudo-unsteady approach.³⁶

The steady base flow calculations are computed by setting the Courant–Friedrichs–Lewy (CFL) number equal to 10, allowing the filtering of possible unsteadiness and obtaining converged steady fixed points until the residuals of the state variables in the L_2 -norm are at least 10^{-8} . The boundary conditions used are as follows: no-slip velocity, adiabatic temperature, and pressure extrapolation on the walls; a uniform velocity is imposed at the numerical domain inflow; characteristic boundary conditions are set at the domain lateral boundaries and outflow to minimize wave reflections. A series of validation test cases for both incompressible and compressible (up to supersonic) flow regimes are performed to verify the correct functioning of the nonlinear solver and are presented in the [Appendix](#).

Some preliminary tests (not shown here) on nonlinear unsteady calculations have been carried out to select the time integration parameters. For both nonlinear and linear unsteady calculations, the values that minimize computational costs and assure a solution independent of the time integration parameters are as follows: the CFL number for the pseudo-unsteady sub-iterations is set to 10, the maximum number of sub-iterations is 35, and the integration time step size is $\Delta t = 9.31 \times 10^{-3}$. The boundary conditions selected for the (nonlinear) steady base flow solutions are also used for the unsteady calculations in both nonlinear and linearized forms.

However, it is important to emphasize that, although the same discretization schemes and boundary conditions are used for both nonlinear and linear calculations, some adaptation to comply with the linearization procedure had to be taken into account. Concerning the spatial discretization, the Roe scheme is based on the Jacobian matrix of the new flux function associated with the linearized equations.³⁷ The boundary conditions are also linearized and modified: zero-velocity perturbations are enforced on the sphere wall and domain inlet, and the characteristic boundary conditions are evaluated on the base flow solution.

A matrix-free method^{38,39} is used to solve the eigenproblem $\mathbf{L}\widehat{\mathbf{q}} = \lambda \widehat{\mathbf{q}}$. It is possible to introduce the exponential propagator $\mathbf{M} = \exp(\mathbf{L}\Delta T)$ that linearly advances the perturbation solution in time as $\mathbf{q}'(t^{n+1}) = \mathbf{M}\mathbf{q}'(t^n)$ with $t^{n+1} = t^n + \Delta T$. An Arnoldi algorithm^{40–42} is coupled to the linear solver^{24,43–45} to extract the leading eigenmodes of \mathbf{M} . The time step between two consecutive linear snapshots is $\Delta T = 400 \times \Delta t$ and $\Delta T = 200 \times \Delta t$ for the study of the regular and Hopf bifurcations, respectively. The Krylov subspace dimension is set between 60 and 100 to assure the convergence of the least temporally damped/most temporally amplified eigenmode(s) to be lower than at least 10^{-6} .

A. Simulation setup

The numerical domain is composed of six blocks and its topology is displayed in [Figs. 1\(a\)](#) and [1\(b\)](#). The grid resolution is $(n_x, n_y, n_z) = (281, 141, 141)$ for each block, considering a fine clustering of grid points in the vicinity of the sphere walls and in the wake region. To avoid spurious reflections, the grid is stretched near all lateral boundaries and outflow. Inflow, outflow, and lateral boundaries are set to be $L_{in} = 20 D_s^*$, $L_{out} = 60 D_s^*$, and $L_{lat} = 30 D_s^*$, respectively. The center of the sphere is located at $(x, y, z) = (0, 0, 0)$ and its non-dimensional diameter is unitary. The location of boundary conditions and the main characteristic scales are presented in [Figs. 1\(c\)](#) and [1\(d\)](#). The Reynolds number based on free-stream

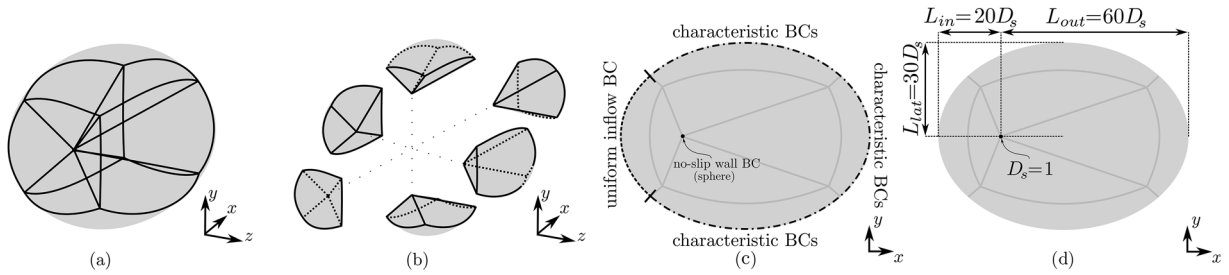


FIG. 1. Assembled (a) and exploded (b) six-block grid topology. Location of boundary conditions (c) and domain characteristic length scales (d) with respect to the sphere diameter.

quantities and sphere diameter spans from $Re = 500$ to 1300 , having evidence of the existence of both regular and Hopf bifurcations in this range.²³ The flow conditions are summarized in Table I. Grid resolution and domain size sensitivity studies for both base flow solutions and global stability results are presented in the Appendix, ensuring the suitability of the present numerical setup.

IV. RESULTS

As a first exploratory campaign, fully 3D unsteady nonlinear simulations have been carried out for $Re = 600$, 850 , and 1000 . A probe located just downstream of the sphere at $(x, y, z) = (1.0, 0.0, 0.0)$ is used to record the streamwise velocity time histories for the three cases. Similarly to the work of Nagata *et al.*,²³ while the cases at $Re = 600$ and 850 are steady, an unsteady periodic behavior at $St = 0.134$ appears for the $Re = 1000$ case (further details about the unsteady spatio-temporal dynamics are given in Sec. IV C).

The sphere wakes of these three cases fundamentally differ not only temporally but also spatially: while the wake is axisymmetric for $Re = 600$, the planar-symmetry characterizes the wakes at $Re = 850$ and 1000 . The zero-streamwise velocity iso-line (black solid line) is plotted over the contours of the density gradient for the two perpendicular $x-z$ (first row) and $x-y$ (second row) planes for the solutions at $Re = 600$ [(a)–(d)], $Re = 850$ [(b)–(e)], and $Re = 1000$ [(c)–(f)] in Fig. 2. The projection of the 3D streamlines onto both planes is also represented (white solid lines). The unsteady solution at $Re = 1000$ has been time-averaged over five periods (eight samples per period) of the periodic behavior recorded by the streamwise velocity probe. As the selection of the plane where the axisymmetry is lost is equiprobable, for better clarity, the anti-symmetry plane of any solution presented throughout the whole paper has been rotated to match the $x-y$ plane. The bow shock that forms in front of the sphere is rather Reynolds-insensitive and it is steady also for the $Re = 1000$ case. The separated region downstream of the body

switches from an axisymmetry structure at $Re = 600$ to a planar-symmetric one at $Re = 850$ and 1000 . In a time-averaged sense, the separated region for $Re = 1000$ is significantly reduced in length with respect to the steady $Re = 850$ case. The streamlines upstream of the bow shock are all parallel to the flow direction and spiral axisymmetrically downstream of the sphere for $Re = 600$. For the $Re = 850$ and 1000 cases, the streamlines are instead spiraling asymmetrically in the $x-y$ plane and cause the sphere wake to bend upwards. The sphere wake flow at $M_\infty = 1.2$ for these three representative cases, therefore, changes both its temporal and spatial characteristics in this Reynolds number range: the wake is first steady and axisymmetric at $Re = 600$, then steady and planar-symmetric at $Re = 850$, and finally unsteady and planar-symmetric at $Re = 1000$. Similarly to what happens at incompressible^{6,8,10,11,13,14} and compressible high-subsonic^{21,22,24} speeds, the sphere wake first loses its axisymmetry and then its steady state, indicating the existence of a regular and a Hopf bifurcation, respectively.

To determine and characterize these two bifurcations from a global stability point of view, an appropriate choice of the base flow solutions needs to be done. Considering the type of bifurcations that the fully 3D unsteady nonlinear calculations indicate, it is possible to conclude that for increasing Reynolds numbers, (a) steady axisymmetric base flow solutions become unstable with respect to the regular bifurcation and (b) steady planar-symmetric base flow solutions become unstable with respect to the Hopf bifurcation. In Sec. IV A, different approaches are used to obtain the base flow solutions depending on the nature of the bifurcation to be investigated and their main features are described.

A. Baseflow solutions

Based on the flow features identified by the fully 3D unsteady nonlinear calculations, the two following different strategies for the calculation of the base flow solutions used in the global stability analyses are adopted:

- (1) *Base flow solutions for the regular bifurcation—steady forced symmetry:* The objective is to identify the bifurcation that causes the loss of the wake axisymmetry. In this sense, axisymmetric (and steady) solutions represent the stable/unstable base flows below/above the regular bifurcation critical Reynolds number (Re_{cr}^{reg}). Thus, a new set of steady axisymmetric base flow solutions is obtained by artificially

TABLE I. Inflow parameters.

Free-stream Mach number	$M_\infty = 1.2$
Free-stream stagnation temperature	$T_{i,\infty}^* = 287 \text{ K}$
Free-stream stagnation pressure	$p_{i,\infty}^* = 1.013 \times 10^5 \text{ Pa}$
Reynolds number	$Re \in [500; 1300]$

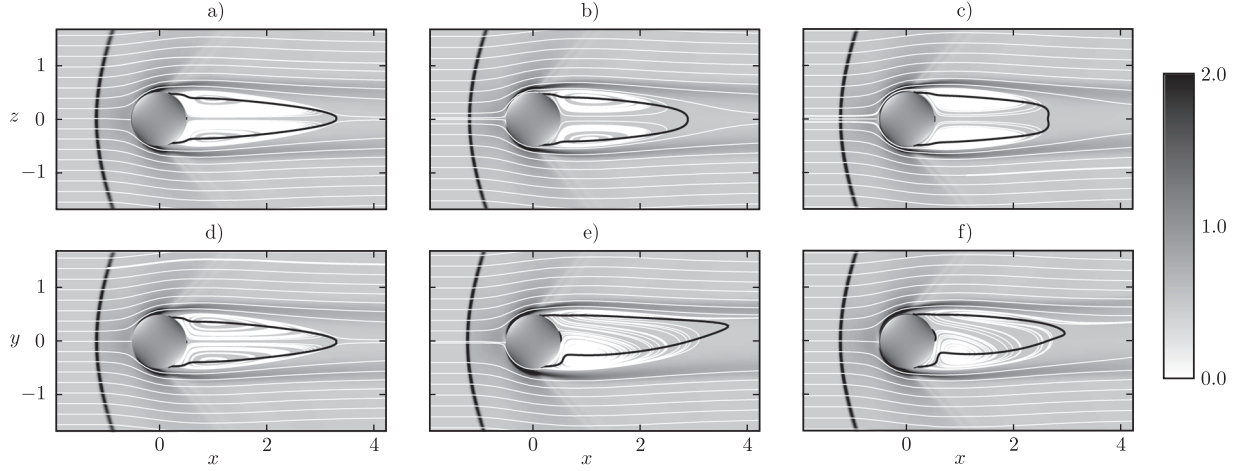


FIG. 2. Three-dimensional streamlines projected onto x - z [(a)–(c)] and x - y [(d)–(f)] planes superimposed to the density gradient contours for the $Re = 600$ [(a) and (d)], $Re = 850$ [(b) and (e)], and $Re = 1000$ [(c) and (f)] cases. The separated region is indicated by the solid black line.

forcing the flow symmetry taking into consideration only a quarter of sphere in the Reynolds number range $Re = 500$ – 750 . The numerical domain is therefore longitudinally sliced via two perpendicular cuts passing through the sphere center and applying symmetry boundary conditions to the newly formed lateral boundaries. Although this set of base flow solutions has been obtained on a quarter of domain, it is important to stress that the stability calculations presented in Sec. IV B are fully 3D. Thus, once the steady solution in the quarter of domain has sufficiently converged, a 3D axisymmetric solution must be constructed by revolution.

- (2) *Base flow solutions for the Hopf bifurcation—steady fully 3D:* The objective is to identify the bifurcation that causes the onset of the unsteadiness in the planar-symmetric solutions. In this regard, steady (and planar-symmetric) solutions represent stable/unstable base flows below/above the Hopf bifurcation critical Reynolds number (Re_{cr}^{Hopf}). For this reason, the implicit pseudo-unsteady approach³⁶ at $CFL = 10$ is used to artificially filter any possible unsteadiness and obtain the fully 3D steady base flow solutions in the Reynolds number range $Re = 600$ – 1000 . Since the steady calculations are fully 3D and no axisymmetry is artificially imposed, these base flow solutions can be either steady axisymmetric or steady planar-symmetric. While only the steady planar-symmetric solutions are used for the characterization of the Hopf bifurcation, this set of calculations can also serve to nonlinearly identify the regular bifurcation critical Reynolds number and verify the corresponding linear calculations. The wake axisymmetry is, in fact, broken between $Re = 645$ and 650 , as it will be confirmed by the global linear stability results presented in Sec. IV B.

Figure 3 and Table II summarize the Reynolds number evolution of the base flow separated region lengths for the two calculation strategies described above. The separation lengths for some

selected Reynolds numbers obtained with unsteady fully 3D calculations are also reported. When the wake is planar-symmetric, the separated region length is calculated by operating an average in the azimuthal direction. If an unsteadiness onsets, the separation length is also time-averaged over five periods (eight samples per period) of the periodic behavior recorded by a streamwise velocity probe in the wake region.

Below $Re = 650$, the fully 3D approach predicts an axisymmetric solution, suggesting that the regular bifurcation threshold is around this Reynolds number value. Similarly to the incompressible counterpart (as shown in the inset of Fig. 3, where the incompressible results from Sansica *et al.*²⁴ are added), the separation length calculated with the fully 3D approach above the regular bifurcation is

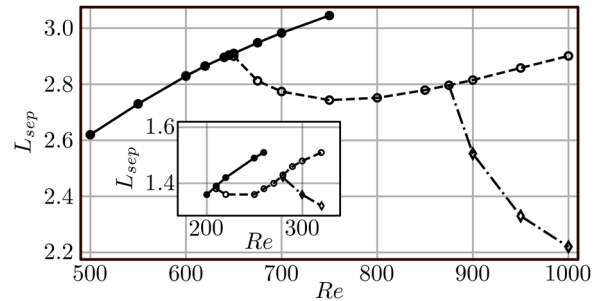


FIG. 3. Reynolds number evolution of the separation region length for the steady forced symmetry (solid line with full circle symbols), steady fully 3D (dashed line with empty circle symbols), and unsteady fully 3D (dashed-dotted line with empty diamond symbols) approaches. All separation lengths are obtained by averaging in the azimuthal direction. The separation lengths for the unsteady fully 3D calculations are also time-averaged. The inset plot shows the results for the incompressible sphere wake flow, taken from the work of Sansica *et al.*²⁴ The same line styles are used to indicate the different wake configurations of the incompressible solutions.

TABLE II. Separation region lengths and symmetry characteristics for the steady forced symmetry, steady fully 3D, and unsteady fully 3D calculations. AS and PS stand for axisymmetric and planar-symmetric solutions, respectively.

Re	Steady	Steady	Unsteady
	Forced symmetry	Fully 3D	Fully 3D
	L_{sep}	L_{sep}	L_{sep}
500	2.620 (AS)	×	×
550	2.730 (AS)	×	×
600	2.830 (AS)	2.830 (AS)	2.830 - (AS)
620	2.865 (AS)	2.865 (AS)	×
640	2.896 (AS)	2.896 (AS)	×
645	2.904 (AS)	2.904 (AS)	×
650	2.910 (AS)	2.900 (PS)	×
675	2.948 (AS)	2.812 (PS)	×
700	2.983 (AS)	2.774 (PS)	×
750	3.045 (AS)	2.743 (PS)	×
800	×	2.752 (PS)	2.752 (PS)
850	×	2.779 (PS)	2.779 (PS)
875	×	2.797 (PS)	2.797 (PS)
900	×	2.815 (PS)	2.553 (PS)
950	×	2.858 (PS)	2.330 (PS)
1000	×	2.901 (PS)	2.220 (PS)

shorter (in an azimuthally averaged sense) than the forced axisymmetric solution at the same Reynolds number. Another similarity with the incompressible sphere wake is the fact that the separated region length initially decreases just above the regular bifurcation to then monotonically increase after reaching a minimum. Below $Re = 875$, the unsteady fully 3D calculations predict steady solutions and indicate that the Hopf bifurcation must be around this Reynolds number value. In agreement with the incompressible counterpart, the span and time-averaged separated region above $Re = 875$ are significantly shorter than the corresponding steady solutions. Although the incompressible and supersonic results are qualitatively showing the same trends, some quantitative differences exist. While the non-dimensional separation length (or equivalently the size of the separation with respect to the sphere diameter) is much larger in the supersonic regime, the rate of growth of the unstable base flow separation lengths with the Reynolds number around the bifurcation is higher for the incompressible case. Another important quantitative discrepancy regards the Reynolds number difference between

the two bifurcations, which is about four times larger for the supersonic case. These differences again confirm the stabilizing effect of the Mach number on the onset of instabilities.

B. Regular bifurcation

The fully 3D axisymmetric base flows, artificially obtained by the revolution of the steady solutions calculated on a quarter of sphere, are used to investigate the regular bifurcation for the Reynolds numbers $Re = 600, 620, 640, 645, 648, 649, 650, 675$, and 700 . Global stability analysis is performed on these base flows, and the growth rate Reynolds number evolution of the least temporally damped/most temporally amplified non-oscillatory mode is plotted in Fig. 4(a). The shaded area for negative values of σ indicates temporally damped modes. The regular bifurcation threshold can be identified for a critical Reynolds number of $Re_{cr}^{reg} = 650$. As confirmed by the fully 3D base flow calculations presented in Sec. IV A and in agreement with the work of Nagata *et al.*,²³ this critical Reynolds number value defines the transition from a steady axisymmetric solution to a steady planar-symmetric one. Interestingly, the slope of the growth rate Reynolds evolution around the incompressible regular bifurcation is lower than the supersonic one (see Ref. 24). The full eigenspectrum for the $Re = 700$ case is presented in Fig. 4(b), where it is possible to see that only the non-oscillatory eigenvalue at $(\sigma, St) = (0.024, 0.0)$ is temporally amplified. Although not shown here, the modes on the continuous branch are spatially localized in the far wake. Generally, while modes below $St = 0.05$ preserve axisymmetry, those at higher frequencies have an $m = 1$ azimuthal character and resemble the mode shape responsible for the Hopf bifurcation (shown later in Sec. IV C).

The corresponding eigenmode is represented in Fig. 5 by plotting the real part of the streamwise, vertical, and transverse eigenvelocities. To better appreciate the azimuthal character of the mode, the streamwise, vertical, and transversal eigenvelocities (\hat{u} , \hat{v} , and \hat{w} , respectively) have been transformed from the Cartesian to cylindrical coordinates to obtain the streamwise, radial, and azimuthal (\hat{u}_s , \hat{u}_r , and \hat{u}_θ , respectively) ones. All eigenvelocities in the present paper have been normalized with the maximum of the real part of the streamwise eigenvelocity. The mode is characterized by an azimuthal distribution corresponding to an $m = 1$ mode, and the perturbations in the streamwise eigenvelocity extend far downstream of the sphere body. Two “petal-like” structures appear due to the expansions generated on the sphere downstream of the bow shock. It must be emphasized that, except for the petal-like structures appearing on the sphere caused by high compressibility effects, the resemblance of the eigenmode with its incompressible counterpart is evident.

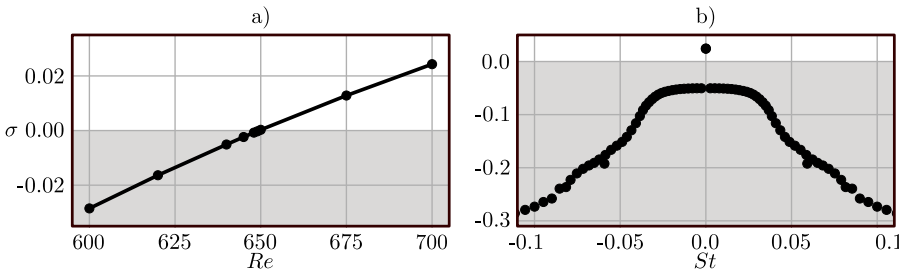


FIG. 4. Regular bifurcation global stability analysis: (a) Reynolds number evolution of the growth rate of the least temporally damped/most temporally amplified non-oscillatory global mode; (b) eigenspectrum in the St - σ plane for the $Re = 700$ case. The stable part of the plots has been shaded in light gray.

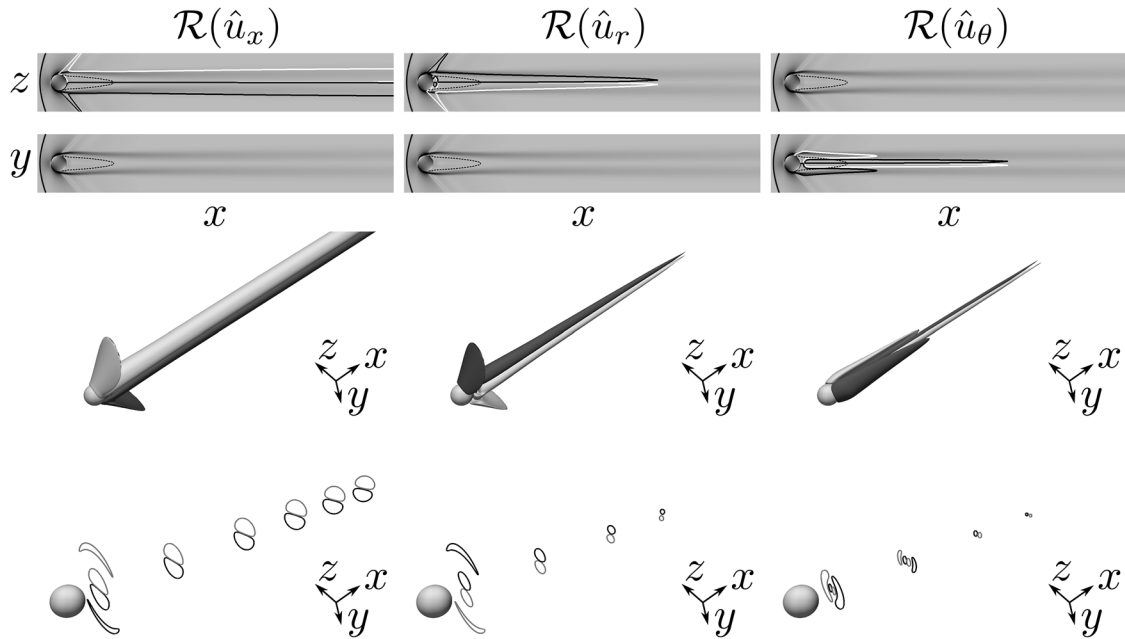


FIG. 5. Global mode at $(\sigma, St) = (0.024, 0.0)$ for the $Re = 700$ case: 2D iso-lines in the x - z and x - y planes (first and second rows, respectively), 3D iso-surfaces (third row), and 2D projections of the iso-lines in the y - z planes at $x = 1, 4, 8, 12, 16, 20$ (fourth row) of the real part of the streamwise (first column), radial (second column), and azimuthal (third column) eigenvelocities for the levels $\hat{u}_x = \pm 0.05$, $\hat{u}_r = \pm 0.05$, and $\hat{u}_\theta = \pm 0.05$, respectively. The white and black iso-lines and iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively. The base flow density gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations, with the zero-streamwise velocity iso-line indicated by the dashed black line.

C. Hopf bifurcation

Before describing the global stability results for the Hopf bifurcation, nonlinear unsteady fully 3D simulations are performed at $Re = 800, 850, 875, 900, 950,$ and 1000 to give a qualitative validation against that of Nagata *et al.*²³ and provide a verification of the corresponding linear calculations. The nonlinear unsteady fully 3D calculations are restarted from the corresponding steady planar-symmetric fully 3D solution and let evolve in time. No forcing has been explicitly added to the simulation, and the unsteadiness slowly builds up from numerical noise. Similarly to the work of Nagata *et al.*,²³ an unsteadiness only appears above $Re = 875$. The time

evolution of the streamwise velocity recorded by a probe in the sphere wake at $(x, y, z) = (1.0, 0.0, 0.0)$ is reported in Fig. 6(a) for the $Re = 1000$ case, showing a long linear transient between the (initial) steady solution and the nonlinearly saturated state. The linear transient and part of the nonlinearly saturated state have been removed up to $t \approx 1400$ (indicated by the dashed vertical gray line), and the corresponding power spectral density (PSD), calculated over about 85 periods of the dominant hairpin shedding frequency, is shown in Fig. 6(b), indicating a limit cycle of self-sustained periodic oscillations at a Strouhal number of $St = 0.134$. The velocity time history during the linear transient phase preceding the limit cycle evolves with a specific “nonlinear” growth rate, σ_{NL} . Despite the fact of being

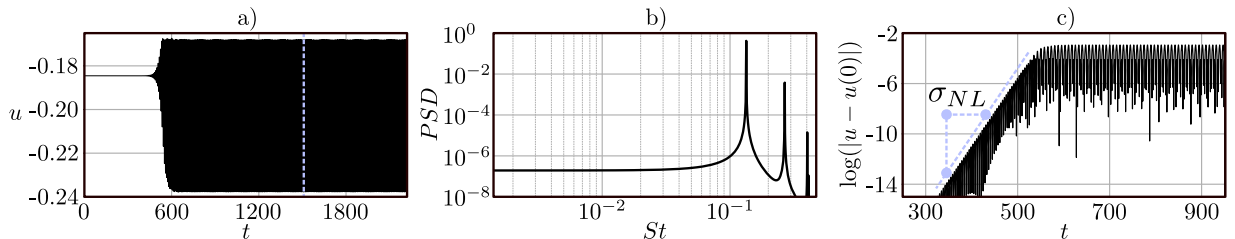


FIG. 6. Unsteady nonlinear calculation at $Re = 1000$: (a) time evolution of the streamwise velocity in the sphere wake at $(x, y, z) = (1.0, 0.0, 0.0)$ and (b) corresponding power spectral density. A zoom on the linear transient of the natural logarithm of the absolute value of the base flow subtracted streamwise velocity time evolution (c) shows the nonlinear growth rate σ_{NL} .

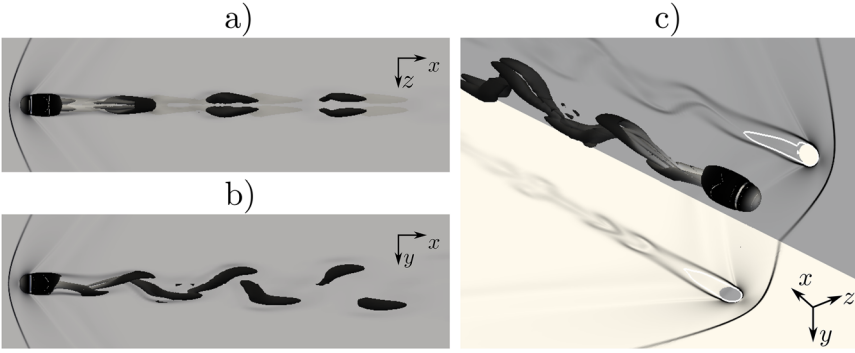


FIG. 7. Unsteady nonlinear calculation at $Re = 1000$: planar [(a) and (b)] and 3D (c) views of the iso-surfaces of the Q-criterion at a level of $Q = 0.5$. The instantaneous density gradient contours are also added (levels between 0.0 and 2.0).

calculated during the linear transient phase, the term “nonlinear” refers here to the type of calculation to avoid confusion with the “linear” growth rate calculated by global stability analysis. Figure 6(c) shows a zoom of the linear transient phase in the natural logarithmic scale for the absolute value of the base flow subtracted streamwise velocity time evolution. The calculated nonlinear growth rate is $\sigma_{NL} \approx 0.054$. The spatial flow configuration is visualized by the planar and 3D views of the Q-criterion iso-surfaces in Fig. 7, where the instantaneous density gradient contours are also added to the planar views. The Q-criterion iso-surfaces are colored by the streamwise velocity (the light to dark colors correspond to the levels from -0.35 to 1.15). Despite the existence of an axisymmetric bow shock in front of the sphere, these visualizations show that the unsteady dynamics in the sphere wake is characterized by planar-symmetric hairpin vortex shedding. A first important remark must be made on the fact that a very similar behavior characterizes the unsteady incompressible sphere wake above the Hopf bifurcation threshold, both in terms of non-dimensional frequency value and spatial structures.

To describe the Hopf bifurcation and precisely identify the threshold value, global stability analysis is performed for $Re = 850, 870, 873, 874, 875, 876, 880, 900, 950,$ and 1000 on the fully 3D steady planar-symmetric base flows presented in Sec. IV A. The growth rate Reynolds number evolution of the least temporally damped/most temporally amplified oscillatory mode is plotted in Fig. 8(a), where the shaded area for negative values of σ indicates stable base flow cases. The Hopf bifurcation threshold is identified for a critical Reynolds number of $Re_{cr}^{Hopf} = 875$, defining the transition from steady to unsteady wake dynamics. The full eigenspectrum for the $Re = 1000$ case is presented in Fig. 8(b), showing that the oscillatory eigenvalue at $(\sigma, St) = (0.054, 0.124)$ is temporally amplified. First

of all, it is useful to remark that the growth rate predicted by linear stability analysis and the one calculated in the transient phase of the nonlinear unsteady calculations at $Re = 1000$ ($\sigma_{NL} \approx 0.054$, see Sec. IV C) are the same, verifying the correct functioning of the linear solver with respect to its nonlinear counterpart. As already seen for other flow configurations or regimes,^{14,24,46} the linear stability analysis predicted frequency is instead slightly underestimated with respect to the nonlinear one. The real part of the eigenvalues corresponding to the $(\sigma, St) = (0.054, 0.124)$ mode is visualized in Fig. 9. Similarly to the regular bifurcation, the temporally amplified mode above the Hopf bifurcation in the supersonic regime spatially resembles its incompressible counterpart. The velocity perturbations are packed into planar-symmetric structures whose wavelength is about $3 \times D_s$ and extend in the wake far downstream of the sphere. The planar-symmetry of this mode is not broken, i.e., it has the same spatial symmetry of the base flow. A quantitative difference between this supersonic Mach number and the incompressible counterpart is that the slope of the growth rate Reynolds evolution around the critical instability onset value is lower (see Ref. 24), meaning that for the supersonic case, the planar-symmetric steady state is preserved over a larger range of Reynolds numbers. The appearance of the Hopf bifurcation with respect to the regular one is, in fact, retarded. This retardation can be confirmed by comparing the difference between the Hopf and regular critical Reynolds numbers, being about 60 in the incompressible regime and 225 at $M_\infty = 1.2$.

In the region of temporally damped eigenmodes ($\sigma < 0$) presented in Fig. 8(b), one mode at $(\sigma, St) = (-0.021, 0.142)$ seems to be moving away from the continuous branch and get closer to the temporally amplified region ($\sigma > 0$). It, therefore, seems natural to wonder what happens to this mode for a further increase of

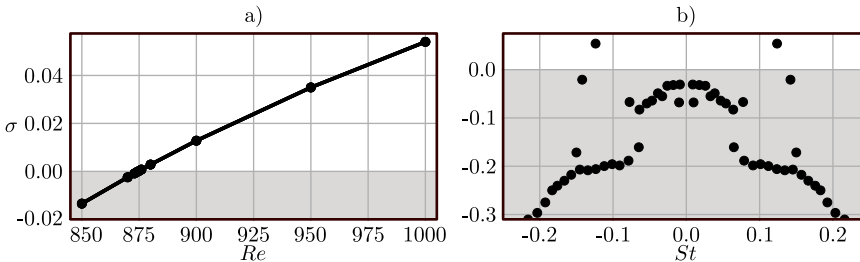


FIG. 8. Hopf bifurcation global stability analysis: (a) Reynolds number evolution of the growth rate of the least temporally damped/most temporally amplified unsteady global mode; (b) eigenspectrum in the St - σ plane for the $Re = 1000$ case. The stable part of the plots has been shaded in light gray.

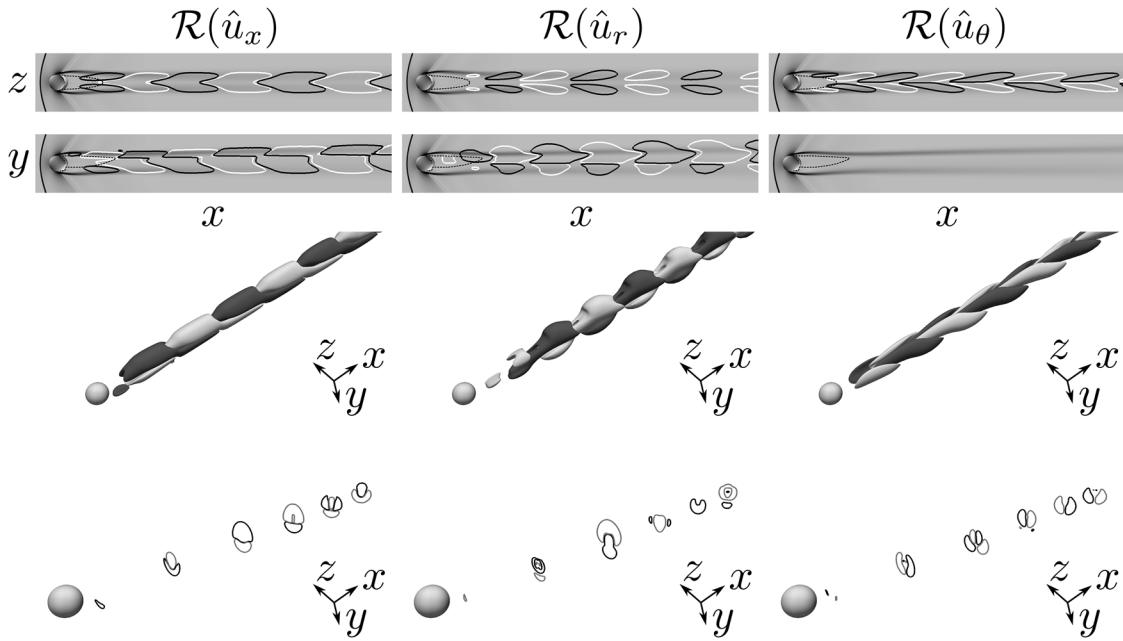


FIG. 9. Global mode at $(\sigma, St) = (0.054, 0.124)$ for the $Re = 1000$ case: 2D iso-lines in the x - z and x - y planes (first and second rows, respectively), 3D iso-surfaces (third row), and 2D projections of the iso-lines in the y - z planes at $x = 1, 4, 8, 12, 16, 20$ (fourth row) of the real part of the streamwise (first column), radial (second column), and azimuthal (third column) eigenvelocities for the levels $\hat{u}_x = \pm 0.20$, $\hat{u}_r = \pm 0.20$, and $\hat{u}_\theta = \pm 0.20$, respectively. The white and black iso-lines and iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively. The base flow density gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations with the zero-streamwise velocity iso-line indicated by the dashed black line.

the Reynolds number. The evolution and the characteristics of this mode are discussed in Sec. IV D.

D. Reflectional symmetry breaking bifurcation

The analysis of the Hopf bifurcation suggests the possibility to have multiple temporally amplified modes for increasing Reynolds number. While it is important to say that the bifurcation following the Hopf one should be analyzed by performing the stability of the limit cycle with a Floquet analysis (i.e., on the unsteady periodic base flow), the objective of the present section is to spatially and temporally characterize the second bifurcation of the steady planar-symmetric base flow solutions. The observability of this instability in the nonlinear dynamics will be addressed in Sec. IV E. For this reason, and with the same principle adopted to obtain the base flow

solutions between $Re = 600$ and 1000 to study the Hopf bifurcation, steady fully 3D calculations are performed for only three other Reynolds numbers, $Re = 1100, 1200,$ and 1300 . The corresponding base flow solutions still present the same planar-symmetry found up to $Re = 1000$, and the azimuthally averaged base flow separation lengths are $L_{sep} = 2.992, 3.083,$ and 3.171 for $Re = 1100, 1200,$ and 1300 , respectively.

These steady planar-symmetric base flow solutions are used to perform global stability analysis. The mode mentioned in Sec. IV C, which at $Re = 1000$ was moving away from the continuous branch, becomes temporally amplified between $Re = 1000$ and 1100 , indicating the existence of a new bifurcation. In addition, a handful of other modes move away from the continuous branch and tend toward positive values of the growth rate. As well as the mode responsible for the Hopf bifurcation (named M1) and the second mode just found to become temporally amplified at $Re = 1100$ (named M2), the other

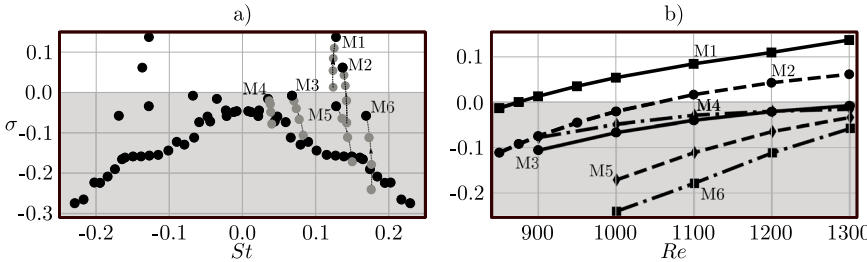


FIG. 10. (a) Eigenspectrum in the St - σ plane for the $Re = 1300$ case. (b) Reynolds number evolution of the growth rate of the modes leaving the continuous branch and indicated as M1-M6. The stable part of the plots has been shaded in light gray.

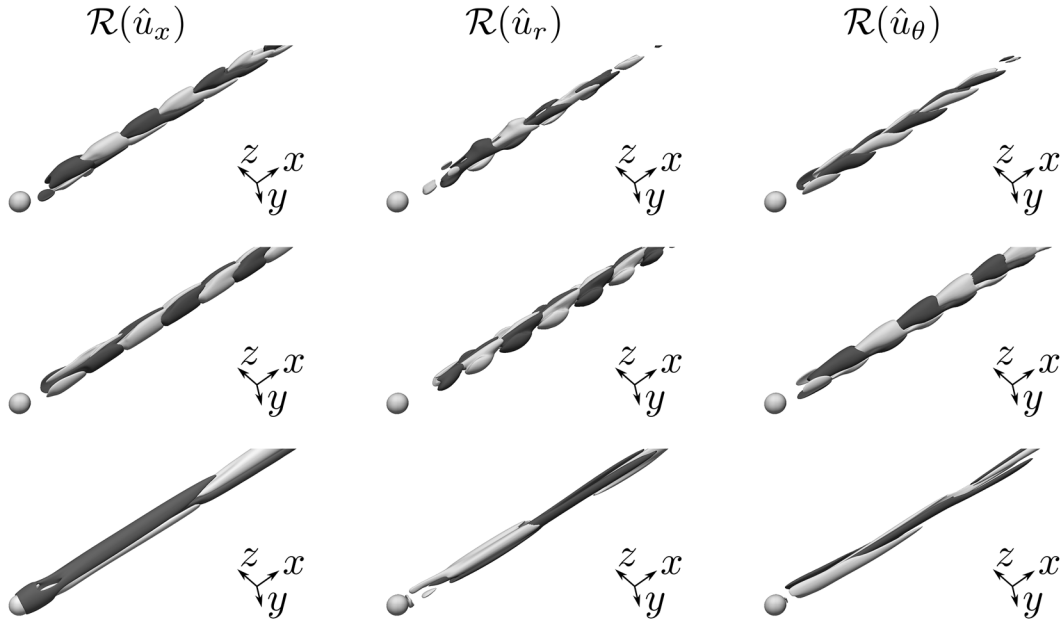


FIG. 11. Global stability modes at (first row—M1) $(\sigma, St) = (0.137, 0.128)$, (second row—M2) $(\sigma, St) = (0.062, 0.137)$, and (third row—M4) $(\sigma, St) = (-0.016, 0.035)$ for the $Re = 1300$ case: 3D iso-surfaces of the real part of the streamwise (first column), radial (second column), and azimuthal (third column) eigenvelocities for the levels $\hat{u}_x = \pm 0.20$, $\hat{u}_r = \pm 0.20$, and $\hat{u}_\theta = \pm 0.20$, respectively. The white and black iso-lines and iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively.

modes moving away from the continuous branch are named M3, M4, M5, and M6 based on their vicinity to the temporally amplified region of the spectrum and indicated in Fig. 10(a), where the eigenspectrum for the $Re = 1300$ case is shown. The Reynolds number evolution of modes M1–M6 is tracked by using dark gray full circle symbols and arrows in Fig. 10(a) but also explicitly plotted in Fig. 10(b). Modes M3–M6 approach more or less rapidly $\sigma = 0$, but all remain stable for this Reynolds range, at least up to the highest Reynolds number investigated. While the identification of further bifurcations due to these modes is not intended, it is relevant to look at the corresponding eigenfunctions. Since mode M3 is just a longer wavelength version of M2 and modes M5 and M6 are practically identical to M1 and M2, respectively, only the M1,

M2, and M4 modes are plotted in Figs. 11 and 12. While mode M1 virtually presents no differences with respect to the mode responsible for the Hopf bifurcation reported in Fig. 9 except for being localized slightly closer to the sphere, it is interesting to see that the newly temporally amplified mode M2 corresponds to a 90° rotation of mode M1 with respect to the x -axis. Following the definition proposed by Fabre, Auguste, and Magnaudet,¹¹ who refer to the dominant mode that retains the base flow symmetry as “reflectional symmetry preserving” and to the sub-dominant rotated mode as “reflectional symmetry breaking,” the newly found bifurcation is named “reflectional symmetry breaking” bifurcation. Although at supersonic speeds, this reflectional symmetry breaking bifurcation confirms the intuition of Fabre, Auguste, and Magnaudet¹¹ and what

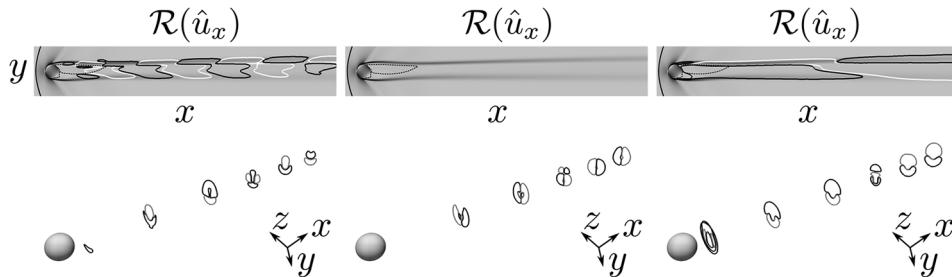


FIG. 12. Global stability modes at (first column—M1) $(\sigma, St) = (0.137, 0.128)$, (second column—M2) $(\sigma, St) = (0.062, 0.137)$, and (third column—M4) $(\sigma, St) = (-0.016, 0.035)$ for the $Re = 1300$ case: 2D iso-lines projected onto (first row) the x - y planes and (second row) several y - z planes at $x = 1, 4, 8, 12, 16, 20$ of the real part of the streamwise eigenvelocities for the levels $\hat{u}_x = \pm 0.20$. The white and black iso-lines indicate the positive and negative perturbation eigenvelocities, respectively. The base flow density gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations with the zero-streamwise velocity iso-line indicated by the dashed black line.

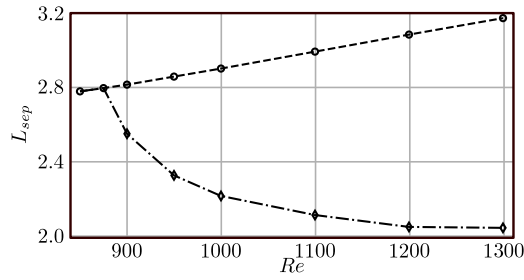


FIG. 13. Reynolds number evolution of the separation region length for the steady fully 3D (dashed line with empty circle symbols) and unsteady fully 3D (dashed-dotted line with empty diamond symbols). All separation lengths are obtained by averaging in the azimuthal direction. The separation lengths for the unsteady fully 3D calculations are also time-averaged.

found by Sansica *et al.*²⁴ for incompressible cases, for which an anti-symmetric sub-dominant mode becomes temporally amplified if the Reynolds number is sufficiently large. Although M4 is just a longer wavelength version of M1, it was preferred to plot this mode rather than the less temporally damped M3 for comparisons that will be done in Sec. IV E. It should be noted that none of these modes breaks the planar-symmetry of the base flow. Finally, the reader should also keep in mind that M3 and M6 are also rotated of 90° , in the same way as for mode M2.

E. Observability of the reflectional symmetry breaking bifurcation in the nonlinear wake dynamics

The reflectional symmetry breaking bifurcation described in Sec. IV D was found for steady planar-symmetric base flow solutions. However, the bifurcation successive to the Hopf one should be instead sought by performing a limit cycle stability study

on the unsteady periodic base flow with a Floquet analysis (out of scope for the present work). The observability of the reflectional symmetry breaking bifurcation in the nonlinear wake dynamics is therefore addressed by performing nonlinear unsteady calculations at $Re = 1100, 1200,$ and 1300 . The nonlinear unsteady calculations have been restarted from the corresponding steady planar-symmetric base flow solutions, in the same way done for the nonlinear analysis shown in Sec. IV C for $Re = 1000$. As the flow features at $Re = 1100$ and 1200 are very similar to those at $Re = 1300$, the analysis will mainly focus on the comparisons of the latter with the $Re = 1000$ case.

At saturation, the nonlinear time-averaged solution is calculated by collecting eight samples per period of the frequency at $St = 0.148$, over five periods of the lowest peak at $St = 0.024$. The time and azimuthally averaged separation lengths (dashed-dotted line with empty diamond symbols) are plotted in Fig. 13 with the azimuthally averaged separation lengths of the corresponding base flow solutions (dashed line with empty circle symbols). For increasing Reynolds number, the nonlinear time-averaged separation length tends to reach a minimum, similarly to what found at incompressible regimes.^{14,24,47}

The time evolution of the streamwise velocity recorded in the sphere wake at $(x, y, z) = (1.0, 0.0, 0.0)$ is reported in Fig. 14(a) for the $Re = 1300$ case. The initial linear transient is removed up to $t \approx 350$ [indicated by the vertical gray dashed line in Fig. 14(a)], and the corresponding PSD distribution, calculated over about 70 periods of the dominant hairpin shedding frequency, is shown in Fig. 14(b). It is possible to see that the spectrum is much richer with respect to the one at $Re = 1000$ (Fig. 6) and many peaks appear also at lower frequencies [$St = \mathcal{O}(10^{-2})$]. The mid frequency energy peaks [$St = \mathcal{O}(10^{-1})$] are in the same Strouhal number range of the linear dominant and reflectional symmetry breaking instabilities and represent possible candidates to be their nonlinear counterparts.

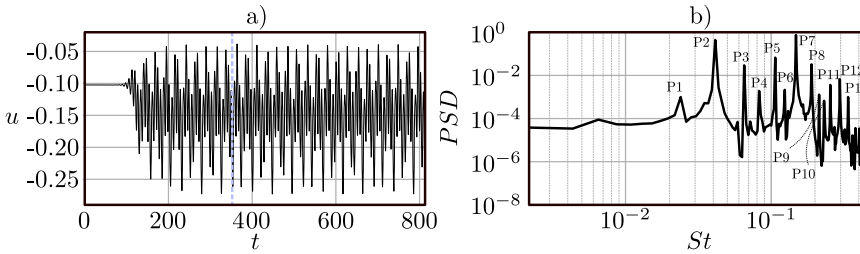


FIG. 14. Unsteady nonlinear calculation at $Re = 1300$: (a) time evolution of the streamwise velocity fluctuations in the sphere wake at $(x, y, z) = (1.0, 0.0, 0.0)$ and (b) corresponding power spectral density.

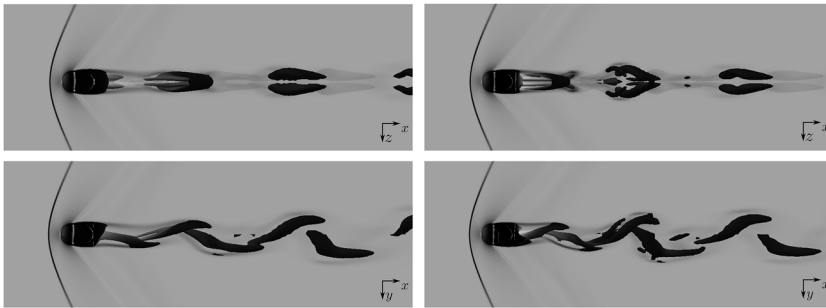


FIG. 15. Unsteady nonlinear calculation at $Re = 1000$ (first column) and $Re = 1300$ (second column): planar views of the iso-surfaces of the Q-criterion at a level of $Q = 0.5$. The instantaneous density-gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations.

TABLE III. Nonlinear interaction analysis for the $Re = 1300$ case. The peaks are numbered and indicated in Fig. 14.

Peak no.	1	2	3	4	5	6	7	8	9	10	11	12	13
Strouhal	0.024	0.041	0.065	0.083	0.107	0.125	0.148	0.188	0.213	0.232	0.256	0.297	0.340
	$f_0 - 3f_1$	f_1	$f_0 - 2f_1$	$2f_1$	$f_0 - f_1$	$3f_1$	f_0	$f_0 + f_1$	$2f_0 + 2f_1$	$f_0 + 2f_1$	$2f_0 - f_1$	$2f_0$	$2f_0 + f_1$

The instantaneous Q-criterion iso-surfaces for the $Re = 1000$ (first column) and $Re = 1300$ (second column) cases are plotted in the planar views reported in Fig. 15 and colored by the streamwise velocity (the light to dark colors correspond to the levels from -0.35 to 1.15). No large differences can be discerned, except for a slightly shorter wavelength of the shed hairpin vortices for the $Re = 1300$ case, in agreement with a slightly higher shedding frequency ($St = 0.134$ for the $Re = 1000$ case vs $St = 0.148$ for the $Re = 1300$ case). It is also important to say that for the Reynolds number range considered, no wake modulation, oscillation, or helical motions were found like at lower Mach numbers.²³

One last comment regards the Reynolds evolution of the problem nonlinearity. While from the spectrum in Fig. 6 for the $Re = 1000$ case, it is easily recognizable the presence of the fundamental frequency at $St = 0.134$ and its first ($St = 0.268$) and second ($St = 0.402$) harmonics, for the $Re = 1300$ case, the analysis is relatively more complex. The latter is strongly nonlinear, and it is necessary to distinguish the fundamental frequencies, here f_0 and f_1 , and what results from nonlinear interactions, i.e., the harmonics nf_0 and mf_1 and quadratic or triadic interactions: $nf_0 \pm mf_1$ with n, m being the real positive integers. By taking $f_0 = 0.148$ (peak “P7” in

Fig. 14) and $f_1 = 0.041$ (peak “P2”), we can, for example, obtain $2f_0 = 0.296$ (peak “P12”), $f_0 + f_1 = 0.189$ (peak “P8”), $f_0 - f_1 = 0.107$ (peak “P5”), and so on. The nonlinear interactions for all peaks in Fig. 14 for PSD values above 10^{-4} are summarized in Table III. By subtracting the mean value and normalizing the oscillation amplitude of the lift-coefficient time-histories, the phase plots [$\hat{C}_L(t)$ vs $\dot{\hat{C}}_L(t)$] reported in Fig. 16 reinforce the perception of different nonlinear dynamics complexity at $Re = 1000$ and $Re = 1300$. The phase space passes from a limit cycle forming a single loop ($Re = 1000$) to a new limit cycle with three or four loops ($Re = 1300$). This indicates that the low frequency peak found at $St = 0.041$ for the $Re = 1300$ case may be linked to the destabilization of the limit cycle at $St = 0.148$.

F. Dynamic mode decomposition analysis

Since the Floquet analysis is out of scope for the present work, an alternative methodology to shed some light on the observability of the reflectional symmetry breaking bifurcation can be given by a DMD analysis³¹ performed on the unsteady nonlinear calculations.

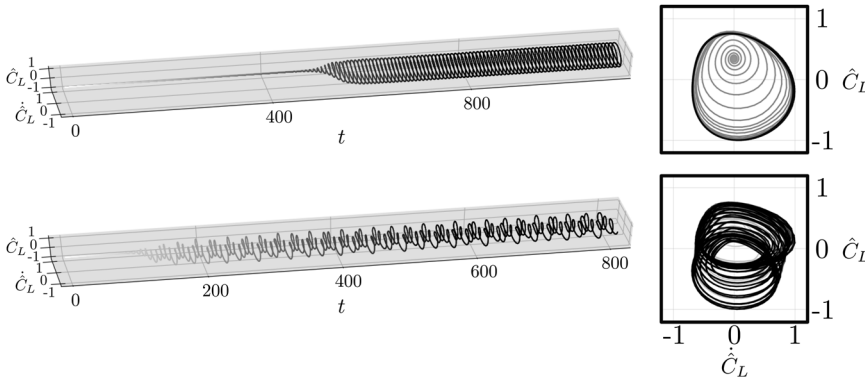


FIG. 16. Mean value subtracted and amplitude normalized lift-coefficient phase plots for the $Re = 1000$ (first row) and $Re = 1300$ (second row) cases. The darker color of the trajectory indicates the time advancement.

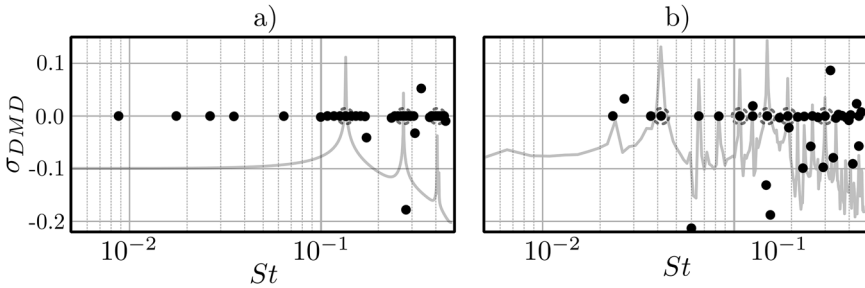


FIG. 17. DMD growth rates for the $Re = 1000$ (a) and $Re = 1300$ (b) cases represented by full black circles. The corresponding PSDs are also reported as a solid gray line. The modes selected using the compressive sensing technique are indicated by the dark dashed-line circles.

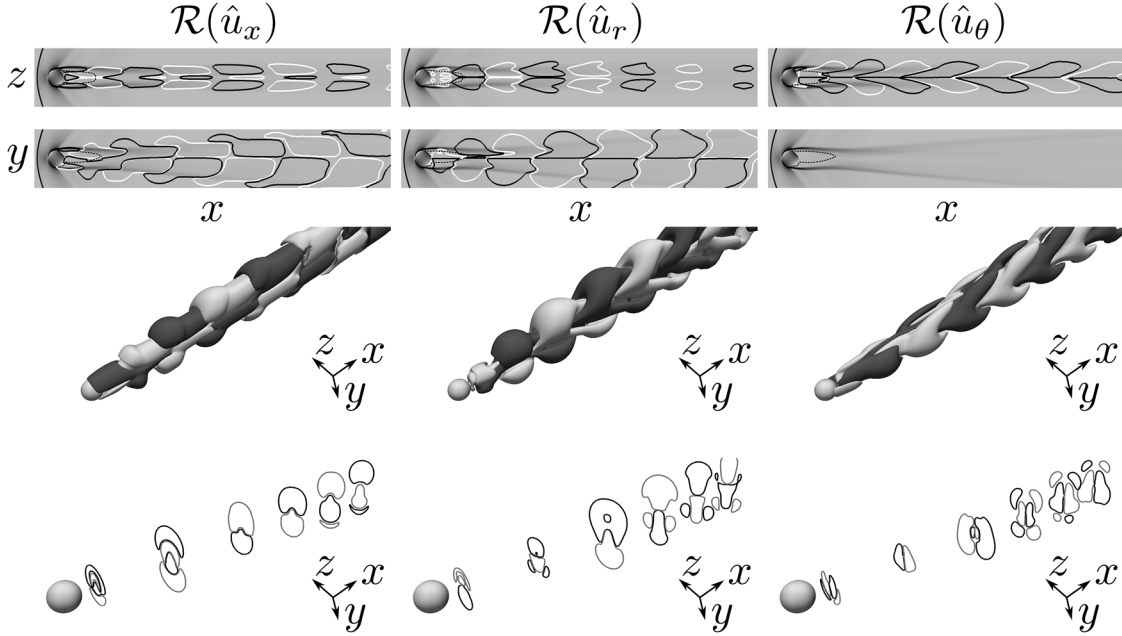


FIG. 18. DMD mode at $St = 0.134$ for the $Re = 1000$ case: 2D iso-lines in the x - z and y - z planes (first and second rows, respectively), 3D iso-surfaces (third row), and 2D projections of the iso-lines in the x - y planes at $x = 1, 4, 8, 12, 16, 20$ (fourth row) of the real part of the streamwise (first column), radial (second column), and azimuthal (third column) eigenvelocities for the levels $\hat{u}_x = \pm 0.20$, $\hat{u}_r = \pm 0.20$, and $\hat{u}_\theta = \pm 0.20$, respectively. The white and black iso-lines and iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively. The time-averaged density gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations with the zero-streamwise velocity iso-line indicated by the dashed black line.

For the $Re = 1000$ and 1300 cases, 350 snapshots with a temporal interval of 1.057 are collected at saturation. The snapshots are 3D flow fields composed of density, velocities, and pressure for each domain cell and therefore very large. The conventional DMD approach³¹ is limited by the large memory required. For this reason, low-dimensionalization is applied to the input dataset.⁴⁸ Eighty one proper orthogonal decomposition (POD) modes are obtained by incremental POD⁴⁹ and used for the dimensionality reduction. Total-least-squares DMD⁵⁰ was then applied to the low dimensional datasets. The dominant DMD modes are identified by means of the compressive sensing technique based on the greedy approach.⁵¹ Further details of the modal analysis framework can be found in the work of Ohmichi, Kobayashi, and Kanazaki,⁵¹ where the “FBasis” modal analysis tool developed at the Japan Aerospace Exploration Agency (JAXA) is described in detail.

The DMD growth rates are reported in Fig. 17 for the $Re = 1000$ (a) and $Re = 1300$ (b) cases. The PSD distributions presented in Figs. 6(b) and 14(b) have been added (solid dashed gray line) to facilitate the correspondence of each peak with the DMD modes. For the $Re = 1000$ case, the compressive sensing technique identifies as dominant DMD modes those at frequencies (in order of dominance) $St = 0.134, 0.268$, and 0.402 . These modes correspond to the three peaks found in the PSD distribution. The most dominant mode is the one at $St = 0.134$, and the other two only represent its first and second higher harmonics, which will therefore not be discussed. The eigenvelocities corresponding to the dominant fundamental DMD mode are reported in Fig. 18. A strong link with

the nonlinear dynamics exists, and the footprint of the shed hairpins seems clearer in the DMD eigenfunctions, as visible from the azimuthal eigenvelocity component. One of the main discrepancies between the global stability and the DMD modes consists of the different development of the eigenwake in the streamwise direction. As shown in Fig. 19, both eigenwakes have similar wavelengths and bend upwards following the deflection of the separated region (indicated by the dashed line). While the wake of the global stability mode is confined in a narrow region behind the sphere, the DMD mode diverges while moving downstream of the body. The distortion of the basic flow by nonlinear effects and larger diffusion is at the origin of this spreading effect. The latter is taken into account in the

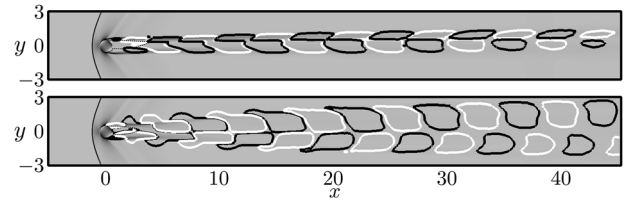


FIG. 19. $Re = 1000$ case: comparison between the streamwise eigenvelocities of the global stability (top) and DMD (bottom) modes. The base flow (top) and time-averaged (bottom) density gradient contours (levels between 0.0 and 2.0) are added to the planar visualizations with the zero-streamwise velocity iso-lines indicated by the dashed black line.

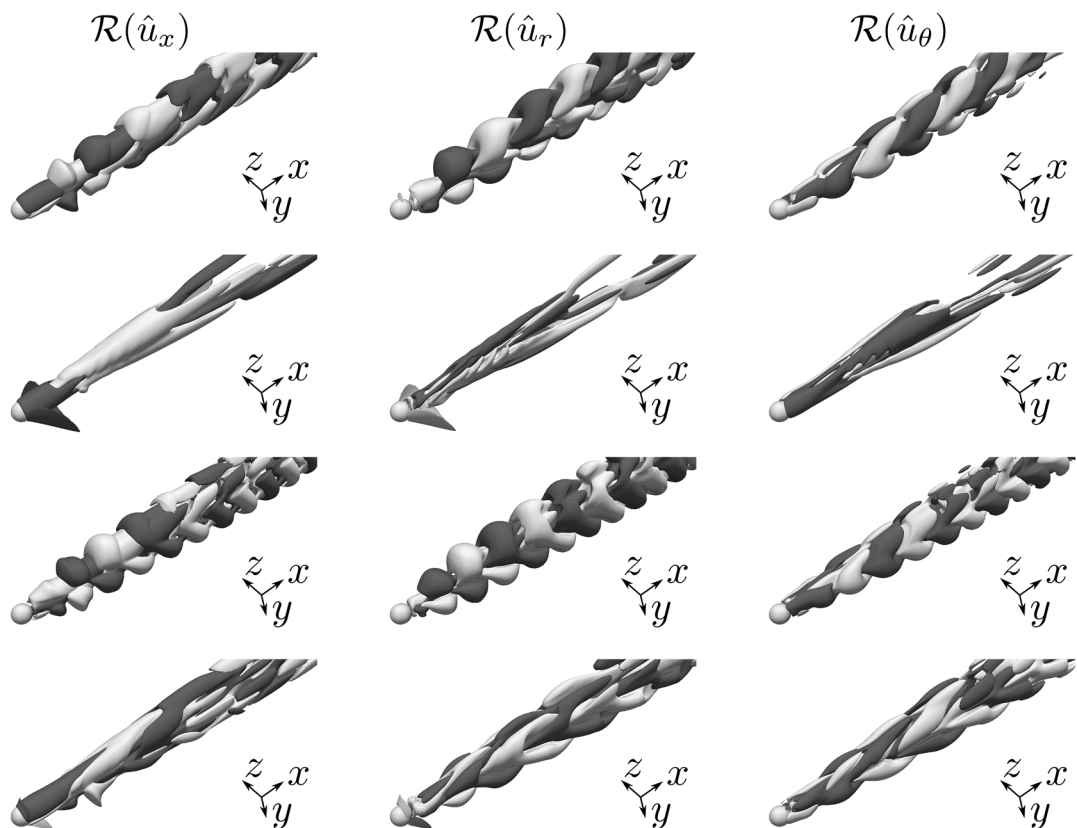


FIG. 20. DMD modes for the $Re = 1300$ case at (first row) $St = 0.148$, (second row) $St = 0.041$, (third row) $St = 0.190$, and (fourth row) $St = 0.107$: 3D iso-surfaces of the real part of the streamwise (first column), radial (second column), and azimuthal (third column) eigenvelocities for the levels $\hat{u}_x = \pm 0.20$, $\hat{u}_r = \pm 0.20$, and $\hat{u}_\theta = \pm 0.20$, respectively. The white and black iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively.

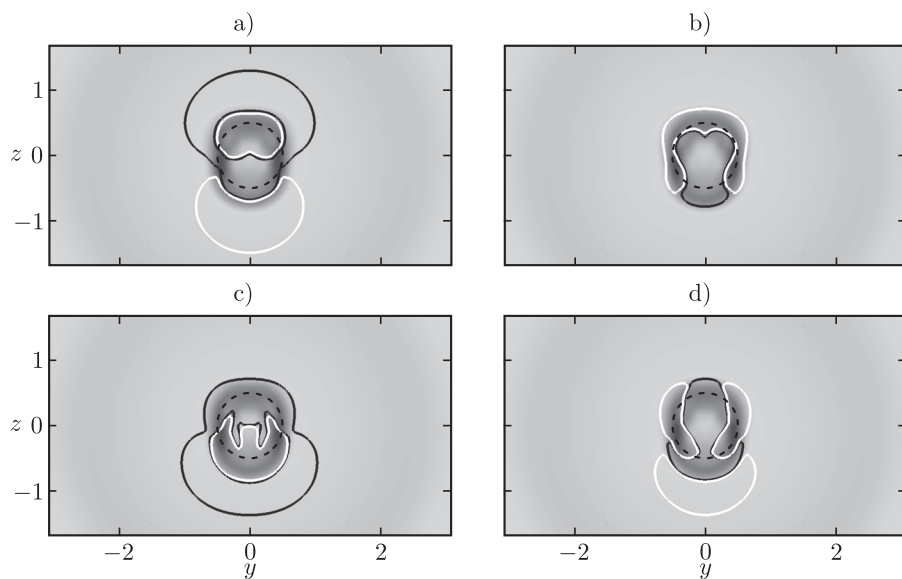


FIG. 21. DMD modes for the $Re = 1300$ case at (a) $St = 0.148$, (b) $St = 0.041$, (c) $St = 0.190$, and (d) $St = 0.107$: 2D iso-lines projected onto the y - z plane at $x = 4$ of the real part of the streamwise eigenvelocities for the levels $\hat{u}_x = \pm 0.20$. The white and black iso-lines indicate the positive and negative perturbation eigenvelocities, respectively. The time-averaged density gradient contours (levels between 0.0 and 2.0) are added in the background with the zero-streamwise velocity iso-line indicated by the dashed black line.

time-averaged flow, around which the DMD modes are calculated. Despite these differences, the similarities with the temporally amplified global mode presented in Fig. 9 are evident. Both the global and the DMD modes are arranged spatially in packets of similar wavelength shape, have the same azimuthal character, and extend very far downstream of the body in the sphere wake region. To further highlight the similarities between the dominant global stability and DMD modes, two movies (“Re1000-GSA-Mode.mp4” and “Re1000-DMD-Mode.mp4” for the global stability and DMD modes, respectively) of the iso-surfaces of the eigenvelocities for the same levels presented in Figs. 9 and 18 (top: \hat{u}_x , middle: \hat{u}_r , and bottom: \hat{u}_θ) during six periods of their corresponding frequency are provided as the [supplementary material](#).

The compressive sensing technique for the $Re = 1300$ case indicates as most dominant modes those at (in order of dominance) $St = 0.148, 0.041, 0.296, 0.190$, and 0.107 . While the $St = 0.296$ mode is just the first harmonic of $St = 0.148$, the eigenvelocities corresponding to the remaining four DMD modes are reported in Figs. 20 and 21. The $St = 0.148$ mode [first row in Figs. 20 and 21(a)] is the same found as dominant in the DMD analysis at $Re = 1000$ and represents the nonlinear counterpart of the dominant linear global instability. The $St = 0.041$ [second row in Figs. 20 and 21(b)], $St = 0.190$ [third row in Figs. 20 and 21(c)], and $St = 0.107$ [fourth row in Figs. 20 and 21(d)] DMD modes present some similarities with the dominant mode but at a higher level of spatial complexity due to nonlinear interactions. All the dominant modes have retained planar-symmetry, and no reflectional symmetry breaking ones are present. To make sure the reflectional symmetry breaking mode is not present among the sub-dominant modes, all DMD modes were carefully checked, but no evidence was found. It can therefore be concluded that the global stability mode responsible for the reflectional symmetry breaking bifurcation is not observable in the nonlinear wake dynamics.

V. CONCLUSIONS

The increase of Mach number has a stabilizing effect on the sphere wake dynamics.^{21–25} At supersonic speeds, no evidence of the regular and Hopf bifurcations, respectively, responsible for the loss of axisymmetry and the appearance of unsteadiness in incompressible sphere wakes, was found in both nonlinear^{22,25} and linear²⁴ frameworks. The Reynolds number must be significantly increased in order for these unstable bifurcations to reappear.²³

A global stability analysis is here carried out for sphere wakes at $M_\infty = 1.2$ in the Reynolds number range $Re \in [500; 1300]$. Steady axisymmetric and steady planar-symmetric base flow solutions are selected to investigate the regular and Hopf bifurcations, respectively. The steady axisymmetric base flows, obtained by forcing the axisymmetry on a quarter of sphere, are found to become unstable at a critical Reynolds number of $Re_{cr}^{reg} = 650$, identifying a steady planar-symmetric mode to be responsible for the occurrence of a regular bifurcation. The steady planar-symmetric base flows, instead, show the appearance of a Hopf bifurcation at $Re_{cr}^{Hopf} = 875$, where an unsteady planar-symmetric eigenmode is the cause for the periodic hairpin vortex shedding in the sphere wake. Some differences intrinsic of the highly compressible flow conditions exist with respect to the incompressible counterparts. The supersonic

base flows are characterized by the formation of a bow shock in front of the sphere and the presence of expansions on the sphere body. The critical Reynolds numbers at $M_\infty = 1.2$ move toward higher values, and the difference between the two critical thresholds is more than four times bigger than in the incompressible regime. However, remarkably similar features exist between incompressible and compressible (up to supersonic) configurations. The same types of unstable bifurcations persist, and the wake dynamics is analogous in both spatial and temporal senses. This work, therefore, closely links the laminar sphere wake dynamics over a large range of flow velocities, from incompressible to (at least low) supersonic regimes.

At $Re = 1000$, the global stability analysis shows that a sub-dominant mode is approaching the temporally amplified region of the spectrum. For this reason, the global stability analysis performed on steady axisymmetric base flows is extended up to $Re = 1300$. The sub-dominant mode becomes temporally amplified between $Re = 1000$ and $Re = 1100$ and its spatial distribution corresponds to a 90° rotation of the dominant mode, confirming some speculations done on the sphere wake instabilities in the incompressible flow regime about the existence of a “reflectional symmetry breaking” bifurcation.^{11,24} The latter was, however, found by global stability analysis performed around steady planar-symmetric base flow solutions, while to study the bifurcation successive to the Hopf one, a periodic base flow solution should instead be used for a Floquet analysis. Floquet analysis being out of scope for the present work, the observability of this reflectional symmetry breaking bifurcation in the nonlinear wake dynamics is checked by carrying out unsteady nonlinear calculations in the range $Re = 1000$ – 1300 . The wake spectral energy content interests a wide range of frequencies as the Reynolds number increases, and several PSD peaks, representing potential nonlinear counterparts of the linear instabilities, appear. For both $Re = 1000$ and $Re = 1300$, DMD analysis indicates the dominant mode to be related to the nonlinear hairpin vortex shedding and its spatial distribution closely resembles the corresponding global stability mode responsible for the Hopf bifurcation. At $Re = 1300$, many sub-dominant modes are also detected, but evidence of nonlinear reflectional symmetry breaking modes was not found. The wake dynamics seems rather to be governed by nonlinear interactions that suggest the low frequency unsteadiness to be related to the destabilization of the hairpin vortex shedding limit cycle.

The absence of rotated DMD modes shows the need to perform global stability Floquet analysis on periodic base flows to characterize physical bifurcations successive to the Hopf one. Evidence of wake modulations and wake helical motions superimposed to the hairpin vortex shedding exists at lower speeds,²³ suggesting the possibility to determine subsequent bifurcations and offering future investigation opportunities. It is in the authors’ opinions that due to the stabilizing effect of the Mach number (as seen in Ref. 23), the same mechanisms presented here might be preserved at higher speeds, most likely just accompanied by a shift of the critical Reynolds numbers toward higher values. Only for much higher Mach numbers in the hypersonic range, for which the bow-shock forming in front of the body will “wrap” closely around the sphere, new physics might appear. Finally, another regime of interest could be the transonic one, for which shocks will form on the sphere surface or on the sphere wake and may be generating some buffet-like phenomenon.

SUPPLEMENTARY MATERIAL

See the [supplementary material](#) for the temporal animations of the global stability (“Re1000-GSA-Mode.mp4”) and DMD (“Re1000-DMD-Mode.mp4”) modes at $Re = 1000$ during six periods of their corresponding frequency. The iso-surfaces of the streamwise (top plot), radial (middle plot), and azimuthal (bottom plot) eigen-velocities for the levels $\hat{u}_x = \pm 0.20$, $\hat{u}_r = \pm 0.20$, and $\hat{u}_\theta = \pm 0.20$, respectively. The white and black iso-surfaces indicate the positive and negative perturbation eigenvelocities, respectively.

APPENDIX: SOLVER VALIDATION AND SENSITIVITY STUDIES

1. Validation

The same numerical setup and grid described in Sec. III are used for the validation of the nonlinear solver. The results obtained with the present solver are compared over a range of different speeds, from the incompressible regime to the supersonic one. For the incompressible regime, the experimental results of Taneda⁵² and the numerical ones by Tomboulides, Orszag, and Karniadakis,⁷ Magnaudet, Rivero, and Fabre,⁵³ and Johnson and Patel⁵⁴ in the Reynolds number range between $Re = 25$ and 200 are selected. To approximate the incompressible flow conditions with the present compressible solver, the Mach number has been set to $M_\infty = 0.1$. In agreement with the literature, for each Reynolds number considered ($Re = 25, 50, 100, 150$, and 200), the solutions consist of steady and axisymmetric wakes. The length of the separated region for each Reynolds number is plotted in Fig. 22, where the benchmark solutions are also added. The agreement with the literature is remarkable and the present results almost coincide with those of Tomboulides, Orszag, and Karniadakis.⁷ To verify the effects of compressibility up to supersonic speeds, the works of Johnson and Patel⁵⁴ and Nagata *et al.*²² (the values have been digitalized from the paper) are used, and Table IV summarizes the validation test results by listing the separation lengths for different Mach numbers at $Re = 150$. In agreement with the benchmark solutions, the wakes are all steady and axisymmetric. An excellent comparison is obtained against Johnson and Patel⁵⁴ at $M_\infty = 0.3$, for which the relative percentage error is below 2.5%. Considering that the work by Nagata *et al.*²² is the only present in the literature for this range of Mach and Reynolds numbers, for the $M_\infty = 0.8$ and 1.2 cases, the relative percentage error is

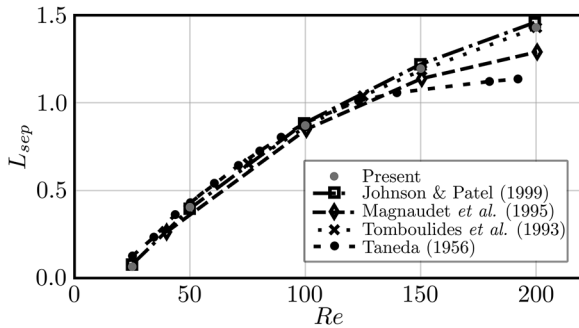


FIG. 22. Validation for incompressible sphere wake test cases.

TABLE IV. Validation for compressible (up to supersonic) sphere wake separation lengths. The results are compared against those of Nagata *et al.*²² (NNT&F) and Johnson and Patel⁵⁴ (J and P).

Mach	Reynolds	Present	NNT&F	Δerr (%)	J and P	Δerr (%)
0.30	150	1.25	1.14	9.65	1.22	2.46
0.80	150	1.78	1.74	2.30	×	×
1.20	150	0.90	0.95	5.26	×	×

around 5% or below. A general satisfactory agreement is achieved, and the correct functioning of the nonlinear solver is confirmed.

2. Grid resolution and domain sensitivity studies

The sensitivity of both base flow solutions and global stability analysis to grid refinement and domain size is here presented. The reader should note that the six-block elliptical domain topology is maintained for all cases. The domain and grid resolution used to produce the results presented in Sec. IV are indicated as G1-D1. For the grid refinement study, the domain size is kept fixed and a coarser grid with $(n_x, n_y, n_z) = (225, 113, 113)$ per block (named G0-D1) and a finer grid with $(n_x, n_y, n_z) = (337, 169, 169)$ per block (named G2-D1) are considered. For the domain size sensitivity study, a smaller domain with $(L_{in}, L_{out}, L_{lat}) = (10, 30, 15)$ (named G1-D0) and a larger domain with $(L_{in}, L_{out}, L_{lat}) = (40, 120, 60)$ (named G1-D2) are used. The grid distribution is kept fixed, and elliptical layers of grid points are simply removed or added to account for a smaller or larger domain. For this reason, the grid resolution per block only changes only in the radial direction and is $(n_x, n_y, n_z) = (225, 141, 141)$ and $(n_x, n_y, n_z) = (316, 141, 141)$ for the G1-D0 and G1-D2 cases, respectively. These details of the grid resolution and domain size are summarized in Table V. To evaluate the effect of grid refinement and domain size, the separation length and the least temporally damped/most temporally amplified eigenvalue are chosen as sensitivity indicators for the base flow solution and global stability analysis, respectively. Two Reynolds numbers are selected for each bifurcation in order to consider a stable and an unstable case: $Re = 600$ and $Re = 650$ for the regular and $Re = 850$ and $Re = 900$ for the Hopf bifurcation. Table VI reports the values of the sensitivity indicators for the examined cases along with the relative percentage error with respect to the values of the G1-D1 case. For all cases, the base flow separation length sensitivity is below 2.5% and the numerical grid/domain G1D1 used as reference throughout the paper can therefore be considered suitable for the base flow

TABLE V. Sensitivity studies on grid resolution and domain size. Details of the numerical setup.

Case	$n_x \times n_y \times n_z$	$L_{in} \times L_{out} \times L_{lat}$
G1-D1	$281 \times 141 \times 141$	$20 \times 60 \times 30$
G0-D1	$225 \times 113 \times 113$	$20 \times 60 \times 30$
G2-D1	$337 \times 169 \times 169$	$20 \times 60 \times 30$
G1-D0	$225 \times 141 \times 141$	$10 \times 30 \times 15$
G2-D2	$316 \times 141 \times 141$	$40 \times 120 \times 60$

TABLE VI. Sensitivity studies on grid resolution and domain size. Values of the sensitivity indicators and relative percentage error. The growth rate and the Strouhal number have been pre-multiplied by 100 and 10, respectively.

$Re = 600$						
Case	L_{sep}	$err_{L_{sep}} (%)$	$\sigma(\times 100)$	$err_{\sigma} (%)$	$St(\times 10)$	$err_{St} (%)$
G1-D1	2.830	×	-2.851	×	0.000	×
G0-D1	2.829	0.04	-3.028	6.2	0.000	0.0
G2-D1	2.877	1.66	-2.701	5.3	0.000	0.0
G1-D0	2.815	0.53	-2.936	3.0	0.000	0.0
G1-D2	2.832	0.07	-2.877	0.9	0.000	0.0
$Re = 650$						
Case	L_{sep}	$err_{L_{sep}} (%)$	$\sigma(\times 100)$	$err_{\sigma} (%)$	$St(\times 10)$	$err_{St} (%)$
G1-D1	2.910	×	0.0274	×	0.000	×
G0-D1	2.912	0.07	-0.0123	144.9	0.000	0.0
G2-D1	2.965	1.89	0.0246	10.2	0.000	0.0
G1-D0	2.901	0.31	0.0246	10.2	0.000	0.0
G1-D2	2.912	0.17	0.0236	13.9	0.000	0.0
$Re = 850$						
Case	L_{sep}	$err_{L_{sep}} (%)$	$\sigma(\times 100)$	$err_{\sigma} (%)$	$St(\times 10)$	$err_{St} (%)$
G1-D1	2.779	×	-1.346	×	1.242	×
G0-D1	2.777	0.07	-1.540	14.4	1.244	0.2
G2-D1	2.847	2.45	-1.428	6.1	1.237	0.4
G1-D0	2.764	0.53	-1.291	4.1	1.242	0.0
G1-D2	2.783	0.14	-1.340	0.5	1.242	0.0
$Re = 900$						
Case	L_{sep}	$err_{L_{sep}} (%)$	$\sigma(\times 100)$	$err_{\sigma} (%)$	$St(\times 10)$	$err_{St} (%)$
G1-D1	2.815	×	1.279	×	1.241	×
G0-D1	2.814	0.04	1.078	15.7	1.243	0.2
G2-D1	2.872	2.02	1.204	5.9	1.235	0.5
G1-D0	2.803	0.42	1.317	3.0	1.241	0.0
G1-D2	2.817	0.07	1.286	0.6	1.241	0.0

calculations. In terms of global stability results, while the frequencies are nearly insensitive to grid resolution or domain size (relative percentage error below 0.5%), the growth rate values present larger variations. Except for the $Re = 650$ case, whose growth rate is very small being the first unstable case of the regular bifurcation and the sensitivities on these small numbers are larger, the growth rate sensitivity of the G1-D1 case with respect to finer grids or larger domains is at worst $\approx 6\%$.

DATA AVAILABILITY

The data that support the findings of this study are available from the corresponding author upon reasonable request.

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