

Solar photosphere magnetization

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via the law in magnetized media $\vec{B} = \mu_0 (\vec{H} + \vec{M})$

Observations: a recent review by Horst Balthasar (2018, Solar Phys. 293, 120)

« The Problem of the Height Dependence of Solar Magnetic Fields in Sunspots »

- any method, from the simplest (model integration like Pahlke & Wiehr, 1990, 6 spectral lines) to the most sophisticated (several node SIR code inversion)

any line
any telescope (ground-based, spatial like HINODE/SOT/SP)

all agree into

|dBz/dz| ≈ 3 G/km (vertical gradient) whereas |dBx/dx + dBy/dy| ≈ 0.3 G/km (horizontal gradient)

 \Rightarrow divergence \neq 0

much larger than the measurement inaccuracies

for 1.5e-3 polarimetric accuracy, typically 10 G inaccuracy on the longitudinal field and 20 G inaccuracy on the transverse field (Bommier, V., 2007, A&A, 464, 323 and further results.)

Sami Solanki (2003, Astron. Astrophys. Rev., 11, 153) wrote on p. 184 « No satisfactory solution has been found as yet for the unexpectedly small vertical gradients obtained by applying the div $\vec{B} = 0$ condition. »

<u>What is measured is \vec{H} </u>

Zeeman hamiltonian of an atom embedded in magnetised matter $-\mu_0 \vec{m} \cdot \vec{H}$ (\vec{m} : atomic magnetic moment)

First demonstration in Langevin (1905, Annales de Chimie et de Physique, 5, 70)

Our demonstration:

After a macroscopic average:

$$\vec{B} = \mu_0 \left(\vec{H} + \vec{M} \right)$$

 \vec{B} : the magnetic *induction*

 \vec{H} : the magnetic *field*

 \vec{M} : the density of magnetic moments or *magnetization*, including

- the atomic magnetic moments \vec{m}
- the magnetic moment of the free charges spiralling about the field

Magnetic energy in a magnetized medium

$$\frac{1}{2}\int \vec{H} \cdot \vec{B} \ d^{3}\vec{r} = \frac{\mu_{0}}{2}\int \vec{H} \cdot \left(\vec{H} + \vec{M}\right) \ d^{3}\vec{r} = \underbrace{\frac{\mu_{0}}{2}\int H^{2} \ d^{3}\vec{r}}_{\text{field energy}} + \underbrace{\frac{\mu_{0}}{2}\int \vec{M} \cdot \vec{H} \ d^{3}\vec{r}}_{\text{matter energy in the field}}$$

– taking into account the external field source contribution (Jackson, 1975), the Zeeman hamiltonian results into $-\mu_0 \vec{m} \cdot \vec{H}$

- the surrounding magnetic moments originate the *depolarizing field* $\vec{H}_{d} \subset \vec{H}$ (Weiss, 1907, Journal de Physique Théorique et Appliquée, 6, 661)

$\underline{\operatorname{div}}\overline{H}$ may be non-zero, but $\operatorname{div}\overline{H}$ has to be fed via $\operatorname{div}\overline{M}$

in a plasma $\mu_0 \vec{M} = -\frac{\beta}{2}\vec{B}$

in the solar photosphere the neutral H density is $n_{_H} \sim 10^{^{16}} \text{ cm}^{^{-3}} \Rightarrow \text{ neutral } \beta \sim 1$

but the electron density is $n_e \sim 10^{12} \text{ cm}^{-3} \Rightarrow \text{charged } \beta \sim 10^{-4} \Rightarrow \mu_0 \vec{M} \ll \mu_0 \vec{H}, \vec{B}$

Our proposal for fedding div \vec{H} : the electron thermal escape inside the Sun

- at 0.5 R_{\odot} , the e⁻ thermal velocity is 14 × the escape velocity (protons 0.34)
- initially, e⁻ and protons are in same number
 - their electric field roughly cancel by pair
 - therefore, an escaping e- is submitted to the electric field of a single proton
- at 0.5 R_☉, the e⁻ thermal velocity is 6 × the escape velocity from the corresponding proton
- but when the electron density decreases, the electron becomes submitted to several protons - the density ratio for the e- thermal velocity 3 x smaller than the escape velocity from protons is $\sim 6 \times 10^3 \approx 18^3$
- each layer expands towards exterior up to 9 = 18/2 x its width. The spreading velocity is extremely slow (1.7 m/year)
- the summation over 9 layers densities leads to e⁻ photosphere density similar to the H density

 $\vec{B} = \mu_0 (\vec{H})$

- at the H density, |dHz/dz| ≈ 3 G/km is recovered
- the corresponding protons remain inside the star (total charge \sim 0)

Rebuild \vec{B} (for MHD modeling) from the \vec{H} measurements

 \vec{B} is responsible for the Lorentz forces induced on the charged matter by the magnetic field

For rebuilding \vec{B} , 2 possibilities:

- if the charge density n_{ep} is known for computing β (of charges) : $\mu_0 \vec{M} = -\frac{\mu}{2}$

- else, numerically rebuild \vec{M} from its measured divergence $\operatorname{div} \vec{M} = -\operatorname{div} \vec{H}$
 - div \tilde{M} is known because div \tilde{H} is measured (from 2-line measurements)
 - the direction of \hat{M} is known because $\hat{B}, \hat{H}, \hat{M}$ are all parallel
 - \Rightarrow the derivative of M along its direction is known
 - allocate an appropriate limit condition

$$\left. \begin{array}{c} + \vec{M} \\ \\ \frac{\beta}{2} \vec{B} \end{array} \right\} \Longrightarrow \mu_0 \vec{H} = \left(1 + \frac{\beta}{2} \right) \vec{B}$$