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PERTURBATION OF RUELLE RESONANCES AND FAURE-SJÖSTRAND ANISOTROPIC SPACE

YANNICK GUEDES BONTHONNEAU

ABSTRACT. Given an Anosov vector field X_0 , all sufficiently close vector fields are also of Anosov type. In this note, we check that the anisotropic spaces described by Faure and Sjöstrand and by Dyatlov and Zworski can be chosen adapted to any smooth vector field sufficiently close to X_0 in C^1 norm.

1. Introduction

In this note, M will denote a compact manifold of dimension n, and X_0 a smooth Anosov vector field on M. That is, there exists a splitting

$$TM = \mathbb{R}X_0 \oplus E_0^u \oplus E_0^s$$
.

The vector field X_0 never vanishes. The splitting is invariant under the flow of X_0 , which is denoted φ_t^0 . We also have constants $C, \beta > 0$ such that for all $t \geq 0$,

$$||d\varphi_{-t|E_0^u}^0|| \le Ce^{-\beta t}$$
 and $||d\varphi_{t|E_0^s}^0|| \le Ce^{-\beta t}$ (1.1)

(here the norm is a fixed norm a priori, and one can check that although the constants depend on that choice of norm, their existence does not).

Starting with [2], several authors have built some anisotropic spaces of distributions to study the spectral properties of hyperbolic dynamics, of which Anosov flows are a prime example. This enables the study of so-called Ruelle–Pollicott resonances, originally defined using the (quite different) techniques of Markov partitions [14, 13]. They appeared as the poles of some zeta functions, popularized by Smale [15].

Since there is no canonical way to build those spaces, various constructions have been developed. In [1], one can find a thorough review of the literature, weighting the different advantages that each construction has to offer. In 2008, Faure and Sjöstrand [7] introduced such a construction. In its functional analytic aspects, it relied on microlocal analysis tools. Provided one understands standard tools in that field, one can present these spaces in the following fashion:

$$\mathcal{H}_G := \operatorname{Op}(e^{-G})L^2(M)$$

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(here Op denotes a classical quantization, and $G \in S^{\log}(T^*M)$). Using these technique led to new developments. For example the description of the correspondence between classical and quantum spectrum in constant curvature at the level of eigenfunctions. Several results already obtained have also been reproved using these techniques. For example the meromorphic continuation of the dynamical zeta function, proved in general by [9] and in the smooth case with microlocal methods by [6].

So far, one particular aspect of the theory that was not reproduced by the microlocal techniques are perturbations. In this note, we will explain how this can be done. The first step will be to prove:

Theorem 1.1. Let X_0 be a C^{∞} Anosov vector field on a compact manifold M. There exists $\eta > 0$ such that the following holds: For any R > 0, we can find $G \in S^{\log}(T^*M)$ such that for $\|X - X_0\|_{\mathcal{C}^1} < \eta$ and $X \subset C^{\infty}$, the spectrum of X acting on \mathcal{H}_G is discrete in

$$\{s \in \mathbb{C} \mid \Re s > -R\}.$$

This discrete spectrum corresponds to the poles of the Schwartz kernel of the resolvent of the flow, so it does not really depend on the choice of G; it is called the Ruelle-Pollicott spectrum of resonances of X. Our next result is

Corollary 1.2. Consider $\lambda_1, \ldots, \lambda_N$ a finite set of resonances (counted with multiplicity) of X_0 and $\epsilon \mapsto X_{\epsilon}$ a C^{∞} family of C^{∞} vector fields perturbating X_0 . Then, there is an $\epsilon_0 > 0$ such that we can find continuous functions $\lambda_i(\epsilon)$ on $]-\epsilon_0, \epsilon_0[$, and an open set $\Omega \subset \mathbb{C}$ such that $\lambda_i(\epsilon) \in \Omega$, and the intersection of the spectrum of X_{ϵ} with Ω is the set $\{\lambda_1(\epsilon), \ldots, \lambda_N(\epsilon)\}$. Additionally, the resonances are smooth functions of ϵ where they do not intersect.

Considering only the dominating resonance (with maximal real part), this was proved in several contexts [3, 10], and the proof for several resonances is the same as for only one; however we could not find a reference for this general statement. A similar statement should also hold in finite regularity (if X_0 is C^r with r > 1), but we are not using the best tools to tackle this type of question, so we ignore it altogether.

While this paper was being elaborated, other authors were considering a similar question, to study Fried's conjecture in [12]; discussing with them helped improve the present note. I also thank Y. Chaubet for the discussion that led to Lemma 4.3.

2. Microlocal proof of the main theorem

In what follows, we consider X to be another vector field, assumed to be close to X_0 in \mathcal{C}^1 norm — we will be clear when we use that assumption. We will denote by φ_t the corresponding flow. The notation $*^{(0)}$ means that the statement is valid both for the object related to X_0 and X.

While the fundamental ideas are always similar, there are several ways to present the proof of Theorem 1.1. We will use the version that was presented in [6]. They use spaces of the form \mathcal{H}_{rG} . They assume that as $|\xi| \to +\infty$,

$$G \sim \mathbf{m}(x,\xi) \log(1+|\xi|),$$

m being a smooth 0-homogeneous function on T^*M . The action of X can be lifted to T^*M by considering the Hamiltonian flow $\Phi_t(x,\xi)$ generated by $p=\xi(X)$:

$$\Phi_t(x,\xi) = (\varphi_t(x), (d_x \varphi_t)^{-1T} \xi).$$

We denote by X_* the generator of that flow. Since p is 1-homogeneous, Φ_t also is, and it acts on $S^*M = T^*M/\mathbb{R}^+ \simeq \partial T^*M$. The proof of [6] is based on the use of the notion of sinks and sources. A sink for Φ_t is a Φ_t -invariant conical closed set $L \subset T^*M$ such that there exists a conical neighborhood U of $L \cap \partial T^*M$ and constants C', β' such that for $\xi \in U$, t > 0,

$$|\Phi_t(\xi)| \ge \frac{1}{C'} e^{\beta' t} |\xi|,$$

and $\Phi_t(U \cap \partial T^*M) \to L \cap \partial T^*M$ as $t \to +\infty$. A source is a sink for Φ_{-t} . One can define subbundles of T^*M of particular interest by setting

$$E_{00}^* = (E_0^u \oplus E_0^s)^{\perp}, \quad E_{u0}^* = (\mathbb{R}X_0 \oplus E_0^s)^{\perp}, \quad E_{s0}^* = (E_0^u \oplus \mathbb{R}X_0)^{\perp}.$$

One gets the decomposition

$$T^*M = E_{00}^* \oplus E_{u0}^* \oplus E_{s0}^*. \tag{2.1}$$

The bundles $E_{u,s,0}^*$ are invariant under the corresponding flow Φ_t . One can check that E_{u0}^* is a sink, and E_{s0}^* is a source for Φ_t^0 .

The proofs of Propositions 3.1 and 3.2 in [6] require the following input.

- (1) The flow Φ_t admits a source E_u^* and a sink E_s^* . Both are contained in $\{p=0\}=X^{\perp}$.
- (2) Given neighborhoods U_u and U_s as in the definition of sinks and sources, there is a T>0 such that $\Phi_t(U_s^c\cap X^\perp)\subset U_u$ and $\Phi_{-t}(U_u^c\cap X^\perp)\subset U_s$ for all t>T.
- (3) the weight **m** satisfies

$$\mathbf{m} = 1 \text{ on } U_u, \quad \mathbf{m} = -1 \text{ on } U_s, \quad X_* \mathbf{m} \ge 0.$$

(We have inverted E_u^* and E_s^* from their article because we consider X-s with $\Re s > -C$ instead of $-iX - \lambda$ with $\Im \lambda > -C$).

Provided conditions (1)–(3) are satisfied, the proof in [6] applies, and we obtain the following. For any R, one can find an r > 0 such that the spectrum of X on \mathcal{H}_{rG} is discrete in $\{\Re s > -R\}$. For our purposes this is not sufficient because we cannot let the r depend on X as long as X is close enough to X_0 . However, one can give a rough estimate on the value of r.

Following the proof of Proposition 2.6 in [6], one finds that it applies (and this is the condition for the proof of Propositions 3.1 and 3.2 to also apply) if r satisfies

$$rc > C_0 + \sup_{T^*M} \frac{X_*|\xi|}{|\xi|}.$$

Let us explain how one obtains the constants c and C_0 . The c comes from Lemma C.1 in [6]. For some $T_1 > 0$, one has $|\Phi_{T_1}(\xi)| > 2|\xi|$ for all $\xi \in U_u$, and c is defined by

$$\int_0^{T_1} |\Phi_t(x,\xi)| \, dt \le \frac{1}{c} |\xi|, \quad \forall \xi \in T^*M.$$

We deduce that

$$c = \Lambda e^{-\Lambda T_1} = \Lambda \left(\frac{C'}{2}\right)^{\frac{\Lambda}{\beta'}},$$

where $|\Phi_t(x,\xi)| \leq e^{\Lambda|t|} |\xi|$ for $\xi \in T^*M$, and C', β' are the constants in the definition of being a sink for E_u^* . The constant Λ can be estimated directly as $\Lambda \leq \|dX\|_{L^{\infty}}$ by usual estimates.

The constant C_0 in the proof of Proposition 2.6 is chosen at the end of the proof to absorb some other terms. To be more precise, C_0 has to satisfy $C_0 > 4C_1$, where

$$\Re\langle (X-s)u,u\rangle \le C_1 \|u\|_{L^2},$$

for all $u \in L^2(M)$. We get $C_1 = \|\operatorname{div} X\|_{L^{\infty}}/2 - \Re s$. Finally, we get

$$r > r_X(s) := \frac{1}{\Lambda} \left(\frac{2}{C'} \right)^{\frac{\Lambda}{\beta'}} \left(2 \|\operatorname{div} X\|_{L^{\infty}} - 4\Re s + \sup_{T^*M} \frac{X_* |\xi|}{|\xi|} \right).$$

We call $r_X(s)$ the *minimal strength*, and this is called the *threshold condition*. The proof of Theorem 1.1 will thus be done if we can prove the following lemma:

Lemma 2.1. There are conical open sets U_u and U_s , $\mathbf{m} \in C^{\infty}(S^*M)$ and $\eta > 0$ such that whenever $\|X - X_0\|_{C^1} < \eta$, X satisfies (1), (2) and (3), with U_u (resp. U_s) an admissible neighborhood for E_u^* (resp. E_s^*). Additionally, the constants C' and β' satisfy

$$C' > \frac{C}{2}, \quad \beta' > \frac{\beta}{2},$$

where C, β are the constants defined in equation (1.1). The minimal strength $r_X(s)$ is thus bounded uniformly.

Except for the construction of the weight function **m**, our Lemma can probably be seen as a corollary of structural stability for Anosov flows [4]. However, we can give a full proof directly, which is quite elementary.

A last remark is that to work with the spaces $\operatorname{Op}(e^{-rG})H^k(M) = \mathcal{H}_{rG+k\log\langle\xi\rangle}$, the same proof applies. The threshold conditions become $r+k > r_X(s)$ and $r-k > r_X(s)$, i.e. $r > r_X(s) + |k|$.

3. Building the weight function

This section is devoted to proving Lemma 2.1. We are now working in S^*M . We start by building a weight adapted to X_0 , following the strategy for [8]. We denote by $\Phi_t^{(0),\infty}$ the flow $\Phi_t^{(0)}$ projected on S^*M . Recall the following:

Lemma 3.1. The bundles E_0^u and E_0^s are continuous. In particular, there is a positive lower bound for the angle between any two bundles in E_0^u , E_0^s , $E_0^0 = \mathbb{R}X_0$.

This is a very usual lemma, contained in [11, Theorem 3.2].

Lemma 3.2. Given $\epsilon > 0$, there exists T > 0 such that when $t \geq T$, for $\xi \in S^*M$,

$$d(\xi, E_{s0}^*) > \epsilon \implies d(\Phi_t^{0,\infty}(\xi), E_{u0}^* \oplus E_{00}^*) \le \epsilon$$

and

$$d(\xi, E_{u0}^* \oplus E_{00}^*) > \epsilon \implies d(\Phi_{-t}^{0,\infty}(\xi), E_{s0}^*) \le \epsilon.$$

In the proof, the constant $0 < C < \infty$ may change at every line, but it is always controlled by the lower bound on the angles between the bundles.

Proof. Since the angles between the distributions $E_{u0,s0,00}^*$ are bounded below, we have a constant C > 0 such that if $\xi = \xi_s + \xi_u + \xi_0$ is the decomposition with respect to (2.1),

$$d(\xi, E_{s0}^*) > \epsilon \implies |\xi_u + \xi_0| > C\epsilon.$$

Next, we also have

$$|\xi_0| = \sup_{|u|=1} \xi_0(u) = \sup \{ \xi(\alpha X_0) \mid \|\alpha X_0 + u'\| = 1, \ u' \in E_0^u \oplus E_0^s \}.$$

By the bounded angle property, if $\|\alpha X_0 + u'\| = 1$, we have $|\alpha| \leq C$. We deduce $(X_0 \text{ never vanishes!})$

$$\frac{1}{C}|\xi(X_0)| \le |\xi_0| \le C|\xi(X_0)|.$$

Since by definition, $\varphi_{t*}^0(X_0) = X_0$, $(\Phi_t^0(\xi))(X_0(\varphi_t(x))) = \xi(X_0)$, we deduce that

$$|\Phi_t^0(\xi)| \ge \frac{1}{C}(|\Phi_t^0(\xi_u)| + |\Phi_t^0(\xi_0)|) \ge (|\xi_u| + |\xi_0|)/C^2 \ge \epsilon/C^3.$$

In particular, again using the bounded angle property,

$$d(\Phi_t^{0,\infty}(\xi), E_{u0}^* \oplus E_{00}^*) \le C \frac{|\Phi_t^0(\xi_s)|}{|\Phi_t^0(\xi)|} \le \frac{C}{\epsilon} e^{-\beta t}.$$

To obtain the first implication, taking $T \ge (\log C - 2\log \epsilon)/\beta$ will suffice, and for the second implication, a similar reasoning will apply.

Since E_{s0}^* and $E_{u0}^* \oplus E_{00}^*$ are continuous and transverse, for $\epsilon > 0$ small enough,

$$\{\xi \mid d(\xi, E_{s0}^*) \le \epsilon\} \cap \{\xi \mid d(\xi, E_{u0}^* \oplus E_{00}^*) \le \epsilon\} = \emptyset.$$

For such an $\epsilon > 0$, we pick $m_0 \in \mathcal{C}^{\infty}(S^*M)$ taking values in [0,1] such that

$$\{\xi \mid d(\xi, E_{s0}^*) \leq \epsilon\} \subset \{m_0 = 0\} \quad \text{and} \quad \{\xi \mid d(\xi, E_{u0}^* \oplus E_{00}^*) \leq \epsilon\} \subset \{m_0 = 1\}.$$

Then, let

$$m := \int_{-T}^{T} m_0 \circ \Phi_t^{0,\infty} dt.$$

The derivative of m along the flow $\Phi_t^{0,\infty}$ is

$$F := m_0 \circ \Phi_T^{0,\infty} - m_0 \circ \Phi_{-T}^{0,\infty}$$

(it is a smooth function). Consider a point $\xi \in S^*M$ such that

$$F(\xi) = 0.$$

Assume that $m_0(\xi) \in]0,1[$. Then by definition of T, we get that $m_0(\Phi_T^{0,\infty}(\xi)) = 1$ and $m_0(\Phi_{-T}^{0,\infty}(\xi)) = 0$ so that $F(\xi)$ cannot vanish. This contradiction implies that $m_0(\xi)$ is either 0 or 1. By symmetry, we can assume that $m_0(\xi) = 0$.

In that case, by Lemma 3.2, we get that $m_0(\Phi_T^{0,\infty}(\xi)) = m_0(\Phi_{-T}^{0,\infty}(\xi)) = 0$. Then, using Lemma 3.2 again, we get that $m_0(\Phi_{-t}^{0,\infty}(\xi)) = 0$ for $t \geq 0$. In particular, we have

$$m(\xi) = \int_0^T m_0(\Phi_t^{0,\infty}(\xi)) dt < T.$$

Conversely, if we assumed that $m_0(\xi) = 1$, we would find that

$$m(\xi) > T$$
.

Now, we deduce the following crucial lemma.

Lemma 3.3. There are constants $\varepsilon, \delta > 0$ such that

$${|m-T|<\varepsilon}\subset {F(\xi)\geq \delta}.$$

Proof. Since $\{F(\xi) = 0\}$ is compact, the inf of |m - T| is attained and, by the preceding argument, is strictly positive. Denote it by 2δ .

Now, consider

$$\ell(\varepsilon) := \sup \{ d(\xi, \{ F = 0 \}) \mid F(\xi) \le \varepsilon \}.$$

By continuity of F and compacity of S^*M , we have that $\ell(\varepsilon) \to 0$ as $\varepsilon \to 0$. Finally, since m is continuous, we have an $\varepsilon' > 0$ such that whenever $d(\xi, \{F = 0\}) < \varepsilon', |m - T| > \delta$. It suffices then to take ε such that $\ell(\varepsilon) < \varepsilon'$.

Let us now come back to our perturbation problem. Consider $X = X_0 + \lambda V$ with V a smooth vector field with $\|V\|_{\mathcal{C}^1} \leq 1$, and $\lambda > 0$ small. The vector fields generating $\Phi_t^{(0)}$ are the Hamiltonian vector fields of the principal symbols of $-iX_{(0)}$, which are $\xi(X_{(0)})$. In particular, they involve the first derivative of the vector fields $X_{(0)}$, so that they are $\mathcal{O}(\lambda)$ - \mathcal{C}^0 -close, with a constant depending on V only through $\|V\|_{\mathcal{C}^1}$.

Then the corresponding vector fields on S^*M , X_0^{∞} and $X^{\infty} = X_0^{\infty} + \lambda V^{\infty}$ that generate the boundary flows $\Phi_t^{(0),\infty}$ also are $\mathcal{O}(\lambda)$ - \mathcal{C}^0 -close, since they are the projection on $T(S^*M)$ of the previous Hamiltonian vector fields. Observe that

$$X^{\infty}m = X_0^{\infty}m + \lambda \int_{-T}^{T} V^{\infty}(m_0 \circ \Phi_t^{0,\infty}) dt$$

Since $||V^{\infty}||_{L^{\infty}} = \mathcal{O}(1)$, the integral in the RHS is of size $\mathcal{O}(T\lambda)$. Now we will use our previous arguments. Let χ be a smooth function on \mathbb{R} , such that χ is constant equal to -1 in $]-\infty, -\varepsilon]$ and constant equal to 1 in $[\varepsilon, +\infty[$, and strictly increasing in $[-\varepsilon, \varepsilon]$. Let

$$\mathbf{m} := \chi(m - T).$$

We get directly that

$$X_0^{\infty} \mathbf{m} \geq 0.$$

But we also have

$$X^{\infty}\mathbf{m} = \chi'(m-T) \left[X_0^{\infty} m + \lambda \int_{-T}^{T} V^{\infty}(m_0 \circ \Phi_t^{0,\infty}) dt \right].$$

On the support of $\chi'(m-T)$, we have $X_0^{\infty}m \geq \delta$. In particular, with λ smaller than $\eta_0 = \delta/CT$ with C > 0 large enough, we get that $X^{\infty}\mathbf{m} \geq 0$.

Lemma 3.4. There is an $0 < \eta \le \eta_0$ such that the following holds. Let X be a C^1 vector field such that $\|X - X_0\|_{\mathcal{C}^1} \le \eta$. Then Φ_t , when restricted to $\{\xi(X) = 0\}$, has a source E_s^* contained in $\{\mathbf{m} = -1\}$ and a sink E_u^* contained in $\{\mathbf{m} = 1\}$.

There exists a T > 0, depending only on η , such that $\Phi_t(\{\mathbf{m} > -1\}) \subset \{\mathbf{m} = 1\}$ for all $t \geq T$ (and the converse statement in negative time also holds).

Proof. Following the arguments in the proof of Lemma 3.2, we can find open cones $V_1 \subset V_2$ containing E_{u0}^* as small as desired, such that $\overline{V_1} \subset V_2$, and for some t > 0, $\Phi_0^0(V_2) \subset V_1$, and $|\Phi_0^0(\xi)| > 3|\xi|$ for all $\xi \in V_2$.

Since $||V||_{\mathcal{C}^1} \leq 1$, for λ small enough, we find that $\Phi_t(V_2) \subset V_1'$, where $V_1 \subset V_1' \subset V_2$, and $\overline{V_1'} \subset V_2$. We also get that $|\Phi_t(\xi)| > 2|\xi|$ for all $\xi \in V_2$. Now, we let

$$E_u^*(x) := \{ \xi \in V_2(x) \mid \Phi_{-t}(\xi) \in V_2 \text{ for all } t \ge 0 \}.$$

Since we can write this as a decreasing intersection of compact sets (compact in $T_x^*M \cup S_x^*M$), it is non empty, closed, and it is a cone by linearity of Φ_t . We deduce that E_u^* is a sink for Φ_t .

Likewise, we can find similar cones around E_{s0}^* for negative times, and obtain that the corresponding E_s^* is a source.

For the points that are neither in the source nor in the sink, we can directly use Lemma 3.2. Finally, since we could choose the neighborhood V_2 as small as desired, since $E_u^* \subset V_2$, and since $\mathbf{m} = +1$ in a neighborhood of E_{u0}^* , the proof is complete.

4. Perturbation of resonances

The main step in the proof of [6] is to prove the following (their Proposition 3.4). They use semi-classical spaces

$$\mathcal{H}_{h,rG} := \operatorname{Op}_h(e^{-rG})L^2(M),$$

 Op_h being now a semi-classical quantization with small parameter h > 0. This space is the same as \mathcal{H}_{rG} , albeit with a different, equivalent norm depending on h > 0. We fix Q a positive self-adjoint pseudor which is microsupported and elliptic around the zero section.

Lemma 4.1. Under the assumptions from section 2, for $0 < h \le h_0$, for $r > r_X(\Re s)$ and $|\Im s| \le h^{-1/2}$, hX - Q - s is invertible on $\mathcal{H}_{h,rG}$ and

$$\left\| (hX - Q - s)^{-1} \right\| \le \frac{C}{h}.$$

One can check that the constants h_0 and C can be estimated as

$$\frac{1}{h_0}, C \leqslant ||X||_{C^{N(r)}},$$

where the number of derivatives N(r) depends only on r and the dimension. Now, we consider a smooth family X_{ϵ} of vector fields perturbating X_0 . From Lemma 2.1, we can find $\epsilon_0 > 0$, and r(s) a non increasing function of $\Re s$, so that $r(s) \geq r_{X_{\epsilon}}(s)$ for all $\epsilon \in]-\epsilon_0, \epsilon_0[$. Using Lemma 4.1, we get a uniform control lemma:

Lemma 4.2. Consider X_{ϵ} a smooth family of vector fields perturbating X_0 . Then there is $\epsilon_0 > 0$ such that the following holds. Given any $s_0 > 0$, k and $r > r(s_0) + |k|$, there is $h_k > 0$ such that for $0 < h < h_k$, $\Re s > \Re s_0$, $|\Im s| < h^{-1}$ and $|\epsilon| < \epsilon_0$,

$$X_{\epsilon} - h^{-1}Q - s$$

is invertible on $\mathcal{H}_{h,rG+k\log\langle\xi\rangle}$. The inverse is then bounded as $\mathcal{O}(1)$ independently of ϵ .

We observe that

$$(X-s)(X-h^{-1}Q-s)^{-1} = 1 + h^{-1}Q(X-h^{-1}Q-s)^{-1}$$

Let us denote $D(X, s) = h^{-1}Q(X - h^{-1}Q - s)^{-1}$. Since Q is smoothing, D(X, s) is trace class. In particular, the resonances of X in $\Omega_{h,s_0} = \{\Re s > \Re s_0, |\Im s| < h^{-1/2}\}$ are the s's such that the Fredholm determinant

$$F(X,s) := \det(\mathbb{1} + D(X,s))$$

vanishes. For fixed X \mathcal{C}^1 -close to X_0 , $F(X,\cdot)$ is a holomorphic function in Ω_{h,s_0} . Now, we consider a smooth family X_{ϵ} . We observe that

$$\partial_{\epsilon} F(X_{\epsilon}, s) = F(X_{\epsilon}, s) \operatorname{Tr} \left[(1 + D(X_{\epsilon}, s))^{-1} \partial_{\epsilon} D(X_{\epsilon}, s) \right]$$

and

$$\partial_{\epsilon} D(X_{\epsilon}, s) = h^{-1} Q(X_{\epsilon} - h^{-1} Q - s)^{-1} \partial_{\epsilon} X_{\epsilon} (X_{\epsilon} - h^{-1} Q - s)^{-1}.$$

Since in the Tr in the formula for $\partial_{\epsilon} F$ the operators are smoothing, this trace does not depend on the Sobolev space with respect to which we are taking the trace. We will denote by $\|\cdot\|_{\text{Tr}}$ the norm on the space $\mathcal{L}^1(\mathcal{H}_{h,rG},\mathcal{H}_{h,rG})$. Additionally,

$$||F(X_{\epsilon}, s)(1 + D(X_{\epsilon}, s))^{-1}|| \le \exp 2||D||_{\operatorname{Tr}} + 1$$

is uniformly bounded (see equation B.5.15 in [5]). From the formula, we deduce that $\partial_{\epsilon} F(X_{\epsilon}, s)$ defines a holomorphic function in the s parameter. In particular, to obtain estimates on its derivatives in s, it suffices to estimate

$$\begin{aligned} \|\partial_{\epsilon}D(X_{\epsilon},s)\|_{\mathrm{Tr}} &\leq Ch^{-1}\|Q(X_{\epsilon}-h^{-1}Q-s)^{-1}\partial_{\epsilon}X_{\epsilon}\|_{\mathrm{Tr}} \\ &\leq Ch^{-1}\|\partial_{\epsilon}X_{\epsilon}\|_{\mathcal{H}_{h,rG}\to\mathcal{H}_{h,rG-\log(\xi)}}\|Q\|_{\mathcal{L}^{1}(\mathcal{H}_{h,rG-\log(\xi)},\mathcal{H}_{h,rG})} \\ &= \mathcal{O}(h^{-2-n}) \end{aligned}$$

(with a constant C changing at every line). Here, we needed $(X - h^{-1}Q - s)^{-1}$ to be bounded on $\mathcal{H}_{h,rG-\log\langle\xi\rangle}$, so that the computation is only valid for $h < h_1$.

By an induction argument, we obtain that for $h < h_k$,

$$|\partial_{\epsilon}^k F(X_{\epsilon}, s)| < C_k h^{-(2+n)k},$$

so that $\epsilon, s \mapsto F(X_{\epsilon}, s)$ is valued in

$$\mathcal{C}^{k}(]-\epsilon_{0},\epsilon_{0}[,\mathscr{O}(\Re s>-\Re s_{0},|\Im s|\leq h^{-1/2})).$$

Since the resonances do not depend on the choice of space, it does not matter if we were using \mathcal{H}_{rG} or $\mathcal{H}_{h,rG+k\log\langle\xi\rangle}$.

We consider now a finite sequence $\lambda_1, \ldots, \lambda_N$ of resonances of X_0 counted with multiplicity. For $\delta > 0$ let $\Omega_\delta := \{s \mid d(s, \{\lambda_1, \ldots, \lambda_N\}) < \delta\}$. Consider some $\delta > 0$, and some s_0 so that $r(s_0) > r(\lambda_i - \delta)$ for all i. Then for $\delta, h > 0$ small enough, $\Omega_\delta \subset \Omega_{h,s_0}$, and for some $\delta' > 0$, $|F(X_0,s)| > \delta'$ for $s \in \partial \Omega_\delta$. In particular, there is $\epsilon'_0 < \epsilon_0$ such that $|F(X_\epsilon, s)| > \delta'/2$ for $d(s, \{\lambda_1, \ldots, \lambda_N\}) = \delta$ and $|\epsilon| < \epsilon'_0$.

By the Rouché theorem, we deduce that the zeroes of $F(X_{\epsilon}, s)$ in Ω_{δ} can be parametrized by continuous functions, which are \mathcal{C}^{∞} when the resonances are simple. This proves Corollary 1.2.

As a remark, let us consider spectral projectors. We come back to classical operators (h=1). Retaking the notations of Corollary 1.2, we consider an open set Ω , and $\lambda_1(\epsilon), \ldots, \lambda_N(\epsilon)$ continuous functions such that the spectrum of X_{ϵ} intersected with Ω is exactly $\{\lambda_1(\epsilon), \ldots, \lambda_N(\epsilon)\}$ counted with multiplicity. Next, we pick a closed curve γ contained in Ω , assuming that it does not contain any $\lambda_i(0)$. Then this remains true on some interval $|\epsilon| < \epsilon'$. As a consequence, for each such ϵ , the following operator is well defined:

$$\Pi_{\gamma}(\epsilon) = \int_{\gamma} (X_{\epsilon} - s)^{-1} ds.$$

By usual arguments, one can show that for $r > r(s_0) + |k|$, where $s_0 = \inf \Re \gamma(t)$, it is a bounded projector in $\mathcal{L}(\mathcal{H}_{rG+k\log\langle\xi\rangle})$. Using the resolvent formula, we get for $|\epsilon| < \epsilon'$,

$$\partial_{\epsilon} \Pi_{\gamma} = \int_{\Gamma} (X_{\epsilon} - s)^{-1} \partial_{\epsilon} X_{\epsilon} (X_{\epsilon} - s)^{-1} ds,$$

which is a bounded operator from \mathcal{H}_{rG} to $\mathcal{H}_{rG-\log\langle\xi\rangle}$ and also from $\mathcal{H}_{rG+\log\langle\xi\rangle}$ to \mathcal{H}_{rG} . On the other hand, since Π_{γ} has finite rank and is a projector, its derivatives also have finite rank. This comes from the relation

$$\partial_{\epsilon}\Pi = \Pi\partial_{\epsilon}\Pi + (\partial_{\epsilon}\Pi)\Pi.$$

Since it has finite rank, the range of $\partial_{\epsilon}\Pi$ is contained in \mathcal{H}_{rG} , and it is bounded on that space (provided $r > r_0 + 1$). By induction, we deduce

Lemma 4.3. Consider a closed curve γ such that for $|\epsilon| < \epsilon_0$ no resonance crosses γ . Then, for $r > r(s_0) + k + 1$, $\epsilon \mapsto \Pi_{\gamma}(\epsilon)$ is a C^k family of bounded operators on \mathcal{H}_{rG} .

Since the generator is elliptic in the direction of the flow, one could probably refine this statement to show that Π_{γ} gains regularity in that direction, however we will not investigate this here.

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