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# Wreath/cascade products and related decomposition results for the concurrent setting of Mazurkiewicz traces

**Bharat Adsul**

IIT Bombay, India  
adsul@cse.iitb.ac.in

**Paul Gustin** 

LSV, ENS Paris-Saclay, CNRS, Université Paris-Saclay, France  
paul.gustin@ens-paris-saclay.fr

**Saptarshi Sarkar**

IIT Bombay, India  
sapta@cse.iitb.ac.in

**Pascal Weil**

Univ. Bordeaux, LaBRI, CNRS UMR 5800, F-33400 Talence, France  
CNRS, ReLaX, IRL 2000, Siruseri, India  
pascal.weil@labri.fr

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## Abstract

We develop a new algebraic framework to reason about languages of Mazurkiewicz traces. This framework supports true concurrency and provides a non-trivial generalization of the wreath product operation to the trace setting. A novel local wreath product principle has been established. The new framework is crucially used to propose a decomposition result for recognizable trace languages, which is an analogue of the Krohn-Rhodes theorem. We prove this decomposition result in the special case of acyclic architectures and apply it to extend Kamp's theorem to this setting. We also introduce and analyze distributed automata-theoretic operations called local and global cascade products. Finally, we show that aperiodic trace languages can be characterized using global cascade products of localized and distributed two-state reset automata.

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## 1 Introduction

Transformation monoids provide an abstraction of transition systems. One of the key tools in their analysis is the notion of wreath product [7, 20, 18] which, when translated to the language of finite state automata, corresponds to the cascade product. In the cascade product of automata  $A$  and  $B$ , with  $A$  ‘followed by’  $B$ , the automaton  $A$  runs on the input sequence, while the automaton  $B$  runs on the input sequence as well as the state sequence produced by the automaton  $A$ . The wreath product principle (see [20, 18, 17]) is a key result which relates a language accepted by a cascade/wreath product to languages accepted by the individual automata.



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In this work, we are interested in generalizing the wreath product operation from the sequential setting to the concurrent setting involving multiple processes. Towards this, we work with Mazurkiewicz traces (or simply traces) [12, 6] which are well established as models of true concurrency, and asynchronous automata [21] which are natural distributed finite state devices working on traces. A trace represents a concurrent behaviour as a labelled partial order which faithfully captures the distribution of events across processes, and causality and concurrency between them. An asynchronous automaton runs on the input trace in a distributed fashion and respects the underlying causality and concurrency between events. During the run, when working on an event, only the local states of the processes participating in that event are updated; the rest of the processes remain oblivious to the occurrence of the event at this point.

A natural generalization of the above mentioned sequential cascade product to asynchronous automata  $A$  and  $B$  is as follows: the asynchronous automaton  $A$  runs on the input trace, thus assigning, for each event, a local state for every process participating in that event. Now the asynchronous automaton  $B$  runs on the input trace with the *same* set of events which are *additionally* labelled by the previous local states of the participating processes in  $A$ . It is easy to capture this operational semantics by another asynchronous automaton which we call the *local* cascade product of  $A$  and  $B$ . Such a construction is used in [2] to provide an asynchronous automata-theoretic characterization of aperiodic trace languages.

Here we propose a new algebraic framework to deal with the issues posed by the concurrent setting. More precisely, we introduce a new class of transformation monoids called *asynchronous transformation monoids* (in short, *atm's*). These monoids make a clear distinction between local and global ‘states’ and allow us to reason about whether a global transformation is essentially induced by a particular subset of processes. Recall that, from a purely algebraic viewpoint, the set of all traces forms a free partially commutative monoid in which *independent* actions commute [6]. In order to recognize a trace language via an atm, we introduce the notion of an *asynchronous morphism* which exploits the locality of the underlying atm. It is rather easy to see that asynchronous morphisms are the algebraic counterparts of asynchronous automata.

One of the central results here is a wreath product principle in the new algebraic framework. It turns out that the *standard* wreath product operation yields an operation on asynchronous transformation monoids. Let  $T_1$  and  $T_2$  be atm's and  $T_1 \wr T_2$  be the wreath product atm. Our *local* wreath product principle describes a trace language recognized by  $T_1 \wr T_2$  in terms of a *local asynchronous transducer* which is a natural *causality and concurrency preserving* map from traces to traces (over an appropriately extended alphabet), and trace languages recognized by  $T_1$  and  $T_2$ . It is a novel generalization of the standard wreath product principle. The work [8] presents a wreath product principle for traces in the setting of transformation monoids but it seems less significant since it uses *non-trace* structures.

The importance of the standard wreath product operation is clearly highlighted by the fundamental Krohn-Rhodes decomposition theorem [11] which, broadly speaking, says that any finite transformation monoid can be simulated by wreath products of ‘simple’ transformation monoids. The wreath product principle along with the Krohn-Rhodes theorem can be used to provide alternate and conceptually simpler proofs (see [14, 3]) of several interesting classical results about formal languages of words such as the theorems due to Schützenberger [19], McNaughton-Papert [13] and Kamp [9] which together show the equivalence between star-free, aperiodic, first-order-definable and linear-temporal-logic definable word languages. Motivated by these applications, we investigate an analogue of the fundamental Krohn-Rhodes decomposition theorem over traces. We use the new algebraic

framework to propose a simultaneous generalization of the Krohn-Rhodes theorem (for word languages) and Zielonka's theorem (for trace languages). The proof of this generalization for the special case of acyclic architectures is another significant result. As an application, we extend Kamp's theorem: we show a natural local temporal logic to be expressively complete.

It turns out that asynchronous morphisms into wreath products correspond to the aforementioned distributed automata-theoretic local cascade products. We also introduce the *global* cascade product operation and show that it can be realized as the local cascade product with the help of the ubiquitous gossip automaton from [16].

Our final major contribution concerns aperiodic trace languages and is in the spirit of the Krohn-Rhodes theorem for the aperiodic case. We establish that aperiodic trace languages can be characterized using global cascade products of localized and distributed two-state reset automata. The proof of this characterization crucially uses an expressively complete process-based local temporal logic over traces from [4].

The rest of the paper is organized as follows. After setting up the preliminaries in Section 2, we develop the new algebraic framework in Section 3 and establish the local wreath product principle. In Section 4, we postulate a new decomposition result, and we prove it for acyclic architectures. We introduce and analyze local and global cascade products in Section 5. The global cascade product based characterization of aperiodic trace languages appears in Section 6. Finally, we conclude in Section 7. Due to space constraints some proofs and examples are omitted and can be found in the extended version [1].

## 2 Preliminaries

### 2.1 Basic Notions in Trace Theory

Let  $\mathcal{P}$  be a finite set of agents/processes. A *distributed alphabet* over  $\mathcal{P}$  is a family  $\tilde{\Sigma} = \{\Sigma_i\}_{i \in \mathcal{P}}$ . Let  $\Sigma = \bigcup_{i \in \mathcal{P}} \Sigma_i$ . For  $a \in \Sigma$ , we set  $\text{loc}(a) = \{i \in \mathcal{P} \mid a \in \Sigma_i\}$ . By  $(\Sigma, I)$  we denote the corresponding trace alphabet, i.e.,  $I$  is the *independence relation*  $\{(a, b) \in \Sigma^2 \mid \text{loc}(a) \cap \text{loc}(b) = \emptyset\}$  induced by  $\tilde{\Sigma}$ . The corresponding *dependence relation*  $\Sigma^2 \setminus I$  is denoted by  $D$ .

A  $\Sigma$ -labelled poset is a structure  $t = (E, \leq, \lambda)$  where  $E$  is a set,  $\leq$  is a partial order on  $E$  and  $\lambda: E \rightarrow \Sigma$  is a labelling function. For  $e, e' \in E$ , define  $e \triangleleft e'$  if and only if  $e < e'$  and for each  $e''$  with  $e \leq e'' \leq e'$  either  $e = e''$  or  $e' = e''$ . For  $X \subseteq E$ , let  $\downarrow X = \{y \in E \mid y \leq x \text{ for some } x \in X\}$ . For  $e \in E$ , we abbreviate  $\downarrow\{e\}$  by simply  $\downarrow e$ .

A *trace* over  $\tilde{\Sigma}$  is a finite  $\Sigma$ -labelled poset  $t = (E, \leq, \lambda)$  such that

- If  $e, e' \in E$  with  $e \triangleleft e'$  then  $(\lambda(e), \lambda(e')) \in D$
- If  $e, e' \in E$  with  $(\lambda(e), \lambda(e')) \in D$ , then  $e \leq e'$  or  $e' \leq e$

Let  $TR(\tilde{\Sigma})$  denote the set of all traces over  $\tilde{\Sigma}$ . Henceforth a trace means a trace over  $\tilde{\Sigma}$  unless specified otherwise. Let  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ . The elements of  $E$  are referred to as *events* in  $t$  and for an event  $e$  in  $t$ ,  $\text{loc}(e)$  abbreviates  $\text{loc}(\lambda(e))$ . Further, let  $i \in \mathcal{P}$ . The set of  $i$ -events in  $t$  is  $E_i = \{e \in E \mid i \in \text{loc}(e)\}$ . This is the set of events in which process  $i$  participates. It is clear that  $E_i$  is totally ordered by  $\leq$ .

A subset  $c \subseteq E$  is a *configuration* of  $t$  if and only if  $\downarrow c = c$ . We let  $\mathcal{C}_t$  denote the set of all configurations of  $t$ . Notice that  $\emptyset$ , the empty set, and  $E$  are configurations. More importantly,  $\downarrow e$  is a configuration for every  $e \in E$ . There are two natural transition relations that one may associate with the configurations of  $t$ . The event based transition relation  $\Rightarrow_t \subseteq \mathcal{C}_t \times E \times \mathcal{C}_t$  is defined by  $c \xRightarrow{e}_t c'$  if and only if  $e \notin c$  and  $c \cup \{e\} = c'$ . The action based transition relation  $\rightarrow_t \subseteq \mathcal{C}_t \times \Sigma \times \mathcal{C}_t$  is defined by  $c \xrightarrow{a}_t c'$  if and only if there exists  $e \in E$  such that  $\lambda(e) = a$  and  $c \xRightarrow{e}_t c'$ .

Now we turn our attention to the important operation of concatenation of traces. Let  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$  and  $t' = (E', \leq', \lambda') \in TR(\tilde{\Sigma})$ . Without loss of generality, we can assume  $E$  and  $E'$  to be disjoint. We define  $tt' \in TR(\tilde{\Sigma})$  to be the trace  $(E'', \leq'', \lambda'')$  where

- $E'' = E \cup E'$ ,
- $\leq''$  is the transitive closure of  $\leq \cup \leq' \cup \{(e, e') \in E \times E' \mid (\lambda(e), \lambda'(e')) \in D\}$ ,
- $\lambda'': E'' \rightarrow \Sigma$  where  $\lambda''(e) = \lambda(e)$  if  $e \in E$ ; otherwise,  $\lambda''(e) = \lambda'(e)$ .

This operation, henceforth referred to as *trace concatenation*, gives  $TR(\tilde{\Sigma})$  a monoid structure. Observe that, with  $a$  (resp.  $b$ ) denoting the singleton trace with the only event labelled  $a$  (resp.  $b$ ), if  $(a, b) \in I$  then  $ab = ba$  in  $TR(\tilde{\Sigma})$ .

A basic result in trace theory gives a presentation of the trace monoid as a quotient of the *free* word monoid  $\Sigma^*$ . See [6] for more details. Let  $\sim_I \subseteq \Sigma^* \times \Sigma^*$  be the congruence generated by  $ab \sim_I ba$  for  $(a, b) \in I$ .

► **Proposition 1.** *The canonical morphism from  $\Sigma^* \rightarrow TR(\tilde{\Sigma})$ , sending a letter  $a \in \Sigma$  to the trace  $a$ , factors through the quotient monoid  $\Sigma^*/\sim_I$  and induces an isomorphism from  $\Sigma^*/\sim_I$  to the trace monoid  $TR(\tilde{\Sigma})$ .*

## 2.2 Transformation Monoids and Trace Languages

A map from a set  $X$  to itself is called a *transformation* of  $X$ . Under function composition, the set of all such transformations forms a monoid; let us denote this monoid by  $\mathcal{F}(X)$ . The function composition  $f_1 f_2$  applies from left-to-right, that is,  $(f_1 f_2)(\cdot) = f_2(f_1(\cdot))$ .

A *transformation monoid* (or simply *tm*) is a pair  $T = (X, M)$  where  $M$  is a submonoid of  $\mathcal{F}(X)$ . The tm  $(X, M)$  is called *finite* if  $X$  is finite.

► **Example 2.** Consider  $X = \{1, 2\}$  with the monoid  $M = \{\text{id}_X, r_1, r_2\}$  where  $\text{id}_X$  is the identity transformation and  $r_i$  maps every element in  $X$  to element  $i$ . Note that  $r_1 r_2 = r_2$  and  $r_2 r_1 = r_1$ . Then  $(X, M)$  is a tm. We will refer to it as  $U_2$ . ◻

Let  $T = (X, M)$  be a tm. By a morphism  $\varphi$  from  $TR(\tilde{\Sigma})$  to  $T$ , we mean a (monoid) morphism  $\varphi: TR(\tilde{\Sigma}) \rightarrow M$ . We abuse the notation and also write this as  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$ . Observe that, if  $(a, b) \in I$ , then as  $ab = ba$  in  $TR(\tilde{\Sigma})$ ,  $\varphi(a)$  and  $\varphi(b)$  must commute in  $M$ . In fact, in view of Proposition 1, any function  $\varphi: \Sigma \rightarrow M$  which has the property that  $\varphi(a)$  and  $\varphi(b)$  commute for every  $(a, b) \in I$ , can be uniquely extended to a morphism from  $TR(\tilde{\Sigma})$  to  $M$ .

Transformation monoids can be naturally used to recognize trace languages. Let  $L \subseteq TR(\tilde{\Sigma})$  be a trace language. We say that  $L$  is *recognized by* a tm  $T = (X, M)$  if there exists a morphism  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$ , an *initial* element  $x_{\text{in}} \in X$  and a *final* subset  $X_{\text{fin}} \subseteq X$  such that  $L = \{t \in TR(\tilde{\Sigma}) \mid \varphi(t)(x_{\text{in}}) \in X_{\text{fin}}\}$ . A trace language is said to be *recognizable* if it is recognized by a finite tm.

## 3 New Algebraic Framework

### 3.1 Asynchronous Transformation Monoids

Recall that we have a fixed finite set  $\mathcal{P}$  of processes. If  $\mathcal{P}$  is clear from the context, we use the simpler notation  $\{X_i\}$  to denote the  $\mathcal{P}$ -indexed family  $\{X_i\}_{i \in \mathcal{P}}$ . The elements of the sets in a  $\mathcal{P}$ -indexed family will be typically called *states*.

We begin with some notation involving local and global states. Suppose that each process  $i \in \mathcal{P}$  is equipped with a finite non-empty set of *local  $i$ -states*, denoted  $S_i$ . We set  $S = \bigcup_{i \in \mathcal{P}} S_i$  and call  $S$  the set of *local states*. We let  $P$  range over non-empty subsets of  $\mathcal{P}$  and let  $i, j$

range over  $\mathcal{P}$ . A  $P$ -state is a map  $s: P \rightarrow S$  such that  $s(j) \in S_j$  for every  $j \in P$ . We let  $S_P$  denote the set of all  $P$ -states. We call  $S_{\mathcal{P}}$  the set of all *global states*.

If  $P' \subseteq P$  and  $s \in S_P$  then  $s_{P'}$  is  $s$  restricted to  $P'$ . We use the shorthand  $-P$  to indicate the complement of  $P$  in  $\mathcal{P}$ . We sometimes split a global state  $s \in S_{\mathcal{P}}$  as  $(s_P, s_{-P}) \in S_P \times S_{-P}$ . We let  $S_a$  denote the set of all  $\text{loc}(a)$ -states which we also call  $a$ -states for simplicity. Thus if  $\text{loc}(a) \subseteq P$  and  $s$  is a  $P$ -state we shall write  $s_a$  to mean  $s_{\text{loc}(a)}$ .

Now we are ready to introduce a new class of transformation monoids.

► **Definition 3.** An asynchronous transformation monoid (in short, atm)  $T$  (over  $\mathcal{P}$ ) is a pair  $(\{S_i\}, M)$  where

- $S_i$  is a finite non-empty set for each process  $i \in \mathcal{P}$ .
- $M$  is a submonoid of  $\mathcal{F}(S_{\mathcal{P}})$ , the monoid of all transformations from  $S_{\mathcal{P}}$  to itself.

Note that this definition is dependent on  $\mathcal{P}$  and an atm  $T = (\{S_i\}, M)$  naturally induces the tm  $(S_{\mathcal{P}}, M)$ . We abuse the notation and write  $T$  also for this tm.

A crucial feature of the definition of an atm is that it makes a clear distinction between local and global states. Observe that the underlying transformations operate on global states. It will be useful to know whether a global transformation is essentially induced by a particular subset of processes. We develop some notions to make this precise.

Fix an atm  $(\{S_i\}, M)$  and  $P \subseteq \mathcal{P}$ . Let  $f: S_P \rightarrow S_P$  be a map. We define  $g: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  as: for  $s \in S_{\mathcal{P}}$ ,

$$g(s) = s' \text{ iff } f(s_P) = s'_P \text{ and } s_{-P} = s'_{-P}$$

We refer to  $g$  as the extension of  $f$ . More generally,  $h: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  is said to be a  $P$ -map if it is the extension of some  $f: S_P \rightarrow S_P$ . Note that, in this case, for all  $s = (s_P, s_{-P}) \in S_{\mathcal{P}}$ ,  $h((s_P, s_{-P})) = (f(s_P), s_{-P})$  and  $f$  is uniquely determined by  $h$ . It is worth pointing out that a map  $h: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  with the property that for every  $s \in S_{\mathcal{P}}$  there exists  $s'_P \in S_P$  such that  $h((s_P, s_{-P})) = (s'_P, s_{-P})$  is *not* necessarily a  $P$ -map. This condition merely says that the  $(-P)$ -component of a global state is not updated by  $h$ . The update of the  $P$ -component may still depend on the  $(-P)$ -component.

The following lemma provides a characterization of  $P$ -maps. We skip the easy proof.

► **Lemma 4.** Let  $h: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$ . Then  $h$  is a  $P$ -map if and only if for every  $s$  in  $S_{\mathcal{P}}$ ,  $[h(s)]_{-P} = s_{-P}$  and for every  $s, s'$  in  $S_{\mathcal{P}}$ ,  $s_P = s'_P$  implies that  $[h(s)]_P = [h(s')]_P$ .

A simple but crucial observation regarding  $P$ -maps is recorded in the following lemma.

► **Lemma 5.** Let  $f, g: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  be such that  $f$  is a  $P$ -map and  $g$  is a  $P'$ -map. If  $P \cap P' = \emptyset$ , then  $fg = gf$ .

► **Example 6.** Fix a process  $\ell \in \mathcal{P}$ . We define the atm  $U_2[\ell] = (\{S_i\}, M)$  where,  $S_{\ell} = \{1, 2\}$  and for each  $i \neq \ell$ ,  $S_i$  has exactly one element. Observe that  $S_{\mathcal{P}}$  has only two global states which are completely determined by their  $\ell$ -components. We will identify a global state with its  $\ell$ -component. The monoid  $M$  is  $\{\text{id}_{S_{\mathcal{P}}}, r_1, r_2\}$  where  $\text{id}_{S_{\mathcal{P}}}$  is the identity transformation and  $r_i$  maps every global state to the global state  $i$ . Note that  $r_1$  and  $r_2$  are  $\{\ell\}$ -maps. ◻

## 3.2 Asynchronous Morphisms

Now we fix a distributed alphabet  $\tilde{\Sigma} = \{\Sigma_i\}_{i \in \mathcal{P}}$  over  $\mathcal{P}$  and introduce special morphisms from the trace monoid  $TR(\tilde{\Sigma})$  to atm's.

► **Definition 7.** Let  $T = (\{S_i\}, M)$  be an atm. An asynchronous morphism from  $TR(\tilde{\Sigma})$  to  $T$  is a (monoid) morphism  $\varphi: TR(\tilde{\Sigma}) \rightarrow M$  such that, for  $a \in \Sigma$ ,  $\varphi(a)$  is a  $\text{loc}(a)$ -map (or simply, an  $a$ -map). We also write this as  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$ .

It is important to observe that, contrary to the sequential case, a morphism from  $TR(\tilde{\Sigma})$  to  $M$  is not necessarily an asynchronous morphism from  $TR(\tilde{\Sigma})$  to the atm  $T = (\{S_i\}, M)$ . In a morphism  $\psi: TR(\tilde{\Sigma}) \rightarrow M$ , for  $(a, b) \in I$ ,  $\psi(a)$  and  $\psi(b)$  must commute; however for some  $a \in \Sigma$ ,  $\psi(a)$  may not be an  $a$ -map.

► **Example 8.** Consider  $\mathcal{P} = \{p_1, p_2, p_3\}$ ,  $\tilde{\Sigma} = \{\Sigma_{p_1} = \{a, b\}, \Sigma_{p_2} = \{b, c\}, \Sigma_{p_3} = \{c\}\}$  and the atm  $U_2[p_1] = (\{S_i\}, M)$  where  $M = \{\text{id}, r_1, r_2\}$ . Recall that  $r_1$  and  $r_2$  are  $\{p_1\}$ -maps. The function  $\psi(a) = \text{id}$ ,  $\psi(b) = r_2$  and  $\psi(c) = r_1$  extends to a morphism from  $TR(\tilde{\Sigma})$  to the monoid  $M$ . However, it is not an asynchronous morphism to the atm  $U_2[p_1]$  as  $\psi(c)$  (being  $r_1$ ) is not a  $\{p_2, p_3\}$ -map.  $\lrcorner$

A fundamental result about asynchronous morphisms is stated in the following lemma. Its proof follows from Proposition 1 and Lemma 5, and can be found in [1].

► **Lemma 9.** Let  $T = (\{S_i\}, M)$  be an atm. Further, let  $\varphi: \Sigma \rightarrow M$  be such that, for  $a \in \Sigma$ ,  $\varphi(a)$  is an  $a$ -map. Then  $\varphi$  can be uniquely extended to an asynchronous morphism from  $TR(\tilde{\Sigma})$  to  $T$ .

► **Example 10.** Consider the setup of Example 8. The function  $\varphi(a) = r_1$ ,  $\varphi(b) = r_2$  and  $\varphi(c) = \text{id}$  extends to an asynchronous morphism from  $TR(\tilde{\Sigma})$  to  $U_2[p_1]$ .  $\lrcorner$

Now we extend the notion of trace-language recognition from tm's to atm's via asynchronous morphisms. Let  $L \subseteq TR(\tilde{\Sigma})$  be a trace language. We say that  $L$  is recognized by an atm  $T = (\{S_i\}, M)$  if there exists an asynchronous morphism  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$ , an initial element  $s_{\text{in}} \in S_{\mathcal{P}}$  and a final subset  $S_{\text{fin}} \subseteq S_{\mathcal{P}}$  such that

$$L = \{t \in TR(\tilde{\Sigma}) \mid \varphi(t)(s_{\text{in}}) \in S_{\text{fin}}\}.$$

In the rest of this subsection, we bring out the intimate relationship between asynchronous morphisms and asynchronous automata. We begin with the description of an asynchronous automaton – a model introduced by Zielonka for concurrent computation on traces.

An asynchronous automaton  $A$  over  $\tilde{\Sigma}$  is a structure  $(\{S_i\}_{i \in \mathcal{P}}, \{\delta_a\}_{a \in \Sigma}, s_{\text{in}})$  where

- $S_i$  is a finite non-empty set of local  $i$ -states for each process  $i$
- For  $a \in \Sigma$ ,  $\delta_a: S_a \rightarrow S_a$  is a transition function on  $a$ -states
- $s_{\text{in}} \in S_{\mathcal{P}}$  is an initial global state

Observe that an  $a$ -transition of  $A$  reads and updates only the local states of the agents which participate in  $a$ . As a result, actions which involve disjoint sets of agents are processed concurrently by  $A$ . For  $a \in \Sigma$ , let  $\Delta_a: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  be the extension of  $\delta_a: S_a \rightarrow S_a$ . Clearly, if  $(a, b) \in I$  then  $\Delta_a$  and  $\Delta_b$  commute. Similar to  $\mathcal{P}$ -indexed families, we will follow the convention of writing  $\{Y_a\}$  to denote the  $\Sigma$ -indexed family  $\{Y_a\}_{a \in \Sigma}$ .

Now we describe the notion of a run of  $A$  on an input trace. A trace run is easiest to define using configurations. Towards this, fix a trace  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ . Recall that (see Section 2.1)  $\mathcal{C}_t$  is the set of all configurations of  $t$  and  $\rightarrow_t \subseteq \mathcal{C}_t \times \Sigma \times \mathcal{C}_t$  is the natural action based transition relation on configurations. A trace run of  $A$  over  $t \in TR(\tilde{\Sigma})$  is a map  $\rho: \mathcal{C}_t \rightarrow S_{\mathcal{P}}$  such that  $\rho(\emptyset) = s_{\text{in}}$ , and for every  $(c, a, c')$  in  $\rightarrow_t$ , we have  $\Delta_a(\rho(c)) = \rho(c')$ . As  $A$  is deterministic,  $t$  admits a unique trace run; it will be denoted by  $\rho_t$ .

Let  $L \subseteq TR(\tilde{\Sigma})$  be a trace language. We say that  $L$  is accepted by  $A$  if there exists a subset  $S_{\text{fin}} \subseteq S_{\mathcal{P}}$  of final global states such that  $L = \{t = (E, \leq, \lambda) \in TR(\tilde{\Sigma}) \mid \rho_t(E) \in S_{\text{fin}}\}$ .



Our aim is to associate with  $A$ , a natural atm  $T_A$  and an asynchronous morphism  $\varphi_A$  such that languages accepted by  $A$  are precisely the languages recognized via  $\varphi_A$ .

We first describe the *transition* monoid  $M_A$  associated to  $A$ . It is possible to extend the global transition functions  $\{\Delta_a\}$  to arbitrary traces using Proposition 1. For  $t \in TR(\tilde{\Sigma})$ , we denote this extended global transition function by  $\Delta_t: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$ . It is easy to check that, for  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ ,  $\Delta_t(s_{in}) = \rho_t(E)$ . Further, as expected, for  $t, t' \in TR(\tilde{\Sigma})$ , the function composition  $\Delta_t \Delta_{t'}$  is identical to  $\Delta_{tt'}$ . We let  $M_A$  be the finite set of functions  $\{\Delta_t \mid t \in TR(\tilde{\Sigma})\}$ . Clearly, it is a monoid under the usual composition of functions.

Next, we define the *transition* atm of  $A$  to be  $T_A = (\{S_i\}, M_A)$  and the natural map  $\varphi_A: TR(\tilde{\Sigma}) \rightarrow M_A$  sending  $t$  to  $\Delta_t$ . It is clear that  $\varphi_A$  is a morphism of monoids. Furthermore, it is an asynchronous morphism from  $TR(\tilde{\Sigma})$  to  $T_A$ ; this is because, for  $a \in \Sigma$ ,  $\varphi_A(a) = \Delta_a$  is in fact an  $a$ -map of the atm  $T_A$ . The map  $\varphi_A$  is called the *transition* (asynchronous) morphism of  $A$ . Note that, for  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ ,

$$\varphi_A(t)(s_{in}) = \Delta_t(s_{in}) = \rho_t(E)$$

We refer to the above statement as the *duality* between a run of  $A$  and an evaluation of  $\varphi_A$ .

The following lemma summarizes the above discussion for later reference and its proof is immediate.

► **Lemma 11.** *Given an asynchronous automaton  $A = (\{S_i\}, \{\delta_a\}, s_{in})$  over  $\tilde{\Sigma}$ , the transition atm  $T_A = (\{S_i\}, M_A)$  and the transition asynchronous morphism  $\varphi_A: TR(\tilde{\Sigma}) \rightarrow T_A$  are effectively constructible. Moreover, if  $L$  is a trace language, then  $L$  is accepted by  $A$  if and only if it is recognized by  $T_A$  via  $\varphi_A$  with  $s_{in}$  as the initial state.*

We now provide a form of converse to Lemma 11. Towards this, we fix an atm  $T = (\{S_i\}, M)$ , a state  $s_{in} \in S_{\mathcal{P}}$  and an asynchronous morphism  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$ . Since  $\varphi$  is an asynchronous morphism,  $\varphi(a)$  is an  $a$ -map, and is an extension of some  $\delta_a: S_a \rightarrow S_a$  over  $a$ -states. We set  $A_\varphi = (\{S_i\}, \{\delta_a\}, s_{in})$  over  $\tilde{\Sigma}$ . It turns out that the transition monoid of  $A_\varphi$  is the image of  $\varphi$ , a submonoid of  $M$  and the transition morphism of  $A_\varphi$  is the appropriate restriction of  $\varphi$  to this submonoid. The next lemma is easy to prove and we skip its proof.

► **Lemma 12.** *Given  $T = (\{S_i\}, M)$ ,  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$  and  $s_{in} \in S_{\mathcal{P}}$ , the asynchronous automaton  $A_\varphi$  over  $\tilde{\Sigma}$  is effectively constructible. Moreover, a trace language  $L \subseteq TR(\tilde{\Sigma})$  is recognized by  $T$  via  $\varphi$  (with initial state  $s_{in}$ ) if and only if it is accepted by  $A_\varphi$ .*

### 3.3 Asynchronous Wreath Product

We begin with the crucial definition of a wreath product of transformation monoids. For sets  $U$  and  $V$ , we denote the set of all functions from  $U$  to  $V$  by  $\mathcal{F}(U, V)$ .

► **Definition 13** (Wreath Product). *Let  $T_1 = (X, M)$  and  $T_2 = (Y, N)$  be two tm's. We define  $T = T_1 \wr T_2$  to be the tm  $(X \times Y, M \times \mathcal{F}(X, N))$  where, for  $m \in M$  and  $f \in \mathcal{F}(X, N)$ ,  $(m, f)$  represents the following transformation on  $X \times Y$ :*

$$\text{for } (x, y) \in X \times Y, \quad (m, f)((x, y)) = (m(x), f(x)(y))$$

*The tm  $T$  is called the wreath product of  $T_1$  and  $T_2$ . It turns out that, for  $(m_1, f_1), (m_2, f_2)$  in  $M \times \mathcal{F}(X, N)$ , the composition law  $(m_1, f_1)(m_2, f_2) = (m, f)$  is such that  $m = m_1 m_2$  and for  $x \in X, f(x) = f_1(x) + f_2(m_1(x))$ . Here  $+$  denotes the composition operation of  $N$ .*

It is a standard fact that the wreath product operation is associative [7]. We now adapt this operation to asynchronous transformation monoids.



► **Definition 14.** Let  $T_1 = (\{S_i\}, M)$  and  $T_2 = (\{Q_i\}, N)$  be two atm's. We define their asynchronous wreath product, also denoted by  $T_1 \wr T_2$ , to be the atm  $(\{S_i \times Q_i\}, M \times \mathcal{F}(S_{\mathcal{P}}, N))$ . An element  $(m, f) \in M \times \mathcal{F}(S_{\mathcal{P}}, N)$  represents the following global<sup>1</sup> transformation on  $S_{\mathcal{P}} \times Q_{\mathcal{P}}$ :

$$\text{for } (s, q) \in S_{\mathcal{P}} \times Q_{\mathcal{P}}, \quad (m, f)((s, q)) = (m(s), f(s)(q))$$

The composition law on  $M \times \mathcal{F}(S_{\mathcal{P}}, N)$  is the same as in Definition 13.

An important observation is that the tm associated with  $T_1 \wr T_2$  is the wreath product of the tm's  $(S_{\mathcal{P}}, M)$  and  $(Q_{\mathcal{P}}, N)$  associated with  $T_1$  and  $T_2$  respectively. Sometimes, we will refer to the asynchronous wreath product simply as wreath product. The associativity of the asynchronous wreath product operation follows immediately.

We now present an important combinatorial lemma regarding the 'support' of a global transformation in the wreath product. It plays a crucial role later.

► **Lemma 15.** Fix atm's  $T_1 = (\{S_i\}, M)$  and  $T_2 = (\{Q_i\}, N)$ . Let  $(m, f) \in M \times \mathcal{F}(S_{\mathcal{P}}, N)$  represent a  $P$ -map in  $T_1 \wr T_2$  for some subset  $P \subseteq \mathcal{P}$ . Then

- $m$  is a  $P$ -map in  $T_1$ .
- For every  $s \in S_{\mathcal{P}}$ ,  $f(s)$  is a  $P$ -map in  $T_2$ . Further, if  $s, s' \in S_{\mathcal{P}}$  are such that  $s_P = s'_P$ , then  $f(s) = f(s')$ .

**Proof.** Fix  $x_0 \in S_{-P}$  and  $y_0 \in Q_{-P}$ . We define  $g_1: S_{\mathcal{P}} \rightarrow S_{\mathcal{P}}$  and  $g_2: S_{\mathcal{P}} \times Q_{\mathcal{P}} \rightarrow Q_{\mathcal{P}}$  by  $g_1(x) = [m((x, x_0))]_P$  and  $g_2(x, y) = [f((x, x_0))(y, y_0)]_P$ . We first show that for all  $s \in S_{\mathcal{P}}, q \in Q_{\mathcal{P}}$ ,  $(m, f)((s, q)) = ((g_1(s_P), s_{-P}), (g_2(s_P, q_P), q_{-P}))$ . Take an arbitrary  $(s, q) \in S_{\mathcal{P}} \times Q_{\mathcal{P}}$ . Then consider the global state  $((s_P, x_0), (q_P, y_0))$  sharing the same  $P$ -component as  $(s, q)$  and the fixed  $-P$ -component  $(x_0, y_0)$ . By the wreath product action (see Definition 13),  $(m, f)((s_P, x_0), (q_P, y_0)) = (m((s_P, x_0)), f((s_P, x_0))(q_P, y_0))$ . Being a  $P$ -map,  $(m, f)$  does not change the  $-P$ -component of any global state. So we have  $m((s_P, x_0)) = [m((s_P, x_0))]_P$  and  $f((s_P, x_0))(q_P, y_0) = [f((s_P, x_0))(q_P, y_0)]_P$ .

Let  $(m, f)((s, q)) = (s', q')$ . Since  $(m, f)$  is a  $P$ -map and the two global states  $(s, q)$  and  $((s_P, x_0), (q_P, y_0))$  share the same  $P$ -component, by Lemma 4,  $s'_P = [m((s_P, x_0))]_P$  and  $q'_P = [f((s_P, x_0))(q_P, y_0)]_P$ . Further,  $s'_{-P} = s_{-P}$  and  $q'_{-P} = q_{-P}$ . Using the definitions of  $g_1$  and  $g_2$ , we immediately see that  $(m, f)((s, q)) = ((g_1(s_P), s_{-P}), (g_2(s_P, q_P), q_{-P}))$ . However, by the wreath product action,  $(m, f)((s, q)) = (m(s), f(s)(q))$ . Comparing this with the previous expression, we have  $m(s) = (g_1(s_P), s_{-P})$  and  $f(s)(q) = (g_2(s_P, q_P), q_{-P})$ . The result now follows from Lemma 4. ◀

### 3.4 Local Wreath Product Principle

Let  $A = (\{S_i\}, \{\delta_a\}, s_{in})$  be an asynchronous automaton over  $\tilde{\Sigma}$ . Based on  $A$  and  $\tilde{\Sigma}$ , we define the alphabet  $\Sigma^{\parallel s} = \{(a, s_a) \mid a \in \Sigma, s \in S_{\mathcal{P}}\}$  where a letter  $a$  in  $\Sigma$  is extended with local  $a$ -state information of  $A$ . This can naturally be viewed as a distributed alphabet  $\widetilde{\Sigma^{\parallel s}}$  where  $\forall a \in \Sigma, \forall s \in S_{\mathcal{P}}, (a, s_a) \in \Sigma_i^{\parallel s}$  if and only if  $a \in \Sigma_i$ . Then  $A$  induces the following transducer over traces.

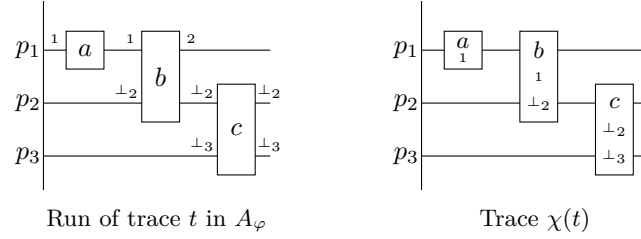
► **Definition 16** (Local Asynchronous Transducer). Let  $\chi_A: TR(\tilde{\Sigma}) \rightarrow TR(\widetilde{\Sigma^{\parallel s}})$  be defined as follows. If  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ , then  $\chi_A(t) = t'$  where  $t' = (E, \leq, \mu) \in TR(\widetilde{\Sigma^{\parallel s}})$  with the labelling  $\mu: E \rightarrow \Sigma^{\parallel s}$  defined by:

<sup>1</sup> a global state (resp.  $P$ -state) of  $T_1 \wr T_2$  is canonically identified with an element of  $S_{\mathcal{P}} \times Q_{\mathcal{P}}$  (resp.  $S_{\mathcal{P}} \times Q_{\mathcal{P}}$ )

$$\forall e \in E, \mu(e) = (a, s_a) \text{ where } a = \lambda(e) \text{ and } s = \rho_t(\downarrow e \setminus \{e\})$$

(recall that  $\rho_t$  is the unique trace run of  $A$  over  $t$ ). We call  $\chi_A$  the local asynchronous transducer of  $A$ .

► **Example 17.** Let  $\chi$  be the local asynchronous transducer associated to  $A_\varphi$  where  $\varphi$  is as in Example 10. Figure 1 shows the run of  $A_\varphi$  on a trace  $t \in TR(\widetilde{\Sigma})$  (by showing local process states before and after each event), and the resulting trace  $\chi(t) \in TR(\widetilde{\Sigma}^{\parallel s})$ . ◻



■ **Figure 1** Local asynchronous transducer output on a trace;  $S_{p_2} = \{\perp_2\}$ ,  $S_{p_3} = \{\perp_3\}$ .

Note that, in general,  $\chi_A$  is not a morphism of monoids. The following lemma is a straightforward consequence of the definition of  $\chi_A$  and the duality between trace runs of  $A$  and evaluations of the asynchronous morphism  $\varphi_A$ .

► **Lemma 18.** Let  $t \in TR(\widetilde{\Sigma})$  with factorization  $t = t'a$  (where  $a \in \widetilde{\Sigma}$ ), and  $s = \varphi_A(t')(s_{in})$ . Then the trace  $\chi_A(t) \in TR(\widetilde{\Sigma}^{\parallel s})$  factors as  $\chi_A(t) = \chi_A(t')(a, s_a)$ .

► **Theorem 19.** Let  $A$  be an asynchronous automaton over  $\widetilde{\Sigma}$  and  $\chi_A$  be the corresponding local asynchronous transducer. If  $L \subseteq TR(\widetilde{\Sigma}^{\parallel s})$  is recognized by an atm  $T$ , then  $\chi_A^{-1}(L)$  is recognized by the atm  $T_A \wr T$ .

**Proof.** Let  $\psi: TR(\widetilde{\Sigma}^{\parallel s}) \rightarrow T = (\{Q_i\}, N)$  be an asynchronous morphism, which recognizes  $L$  with  $q_{in} \in Q_{\mathcal{P}}$  as the initial global state, and  $Q_{fin} \subseteq Q_{\mathcal{P}}$  as the set of final global states. Then  $L = \{t \in TR(\widetilde{\Sigma}^{\parallel s}) \mid \psi(t)(q_{in}) \in Q_{fin}\}$ . Note that, for  $(a, s_a) \in \Sigma^{\parallel s}$ ,  $\psi((a, s_a))$  is an  $a$ -map (that is, an extension of a map from  $Q_a$  to  $Q_a$ ; recall that  $\text{loc}((a, s_a)) = \text{loc}(a)$ ).

For  $a \in \Sigma$ , we set  $\eta(a) = (\varphi_A(a), f_a)$  where  $f_a: S_{\mathcal{P}} \rightarrow N$  is defined by  $f_a(s) = \psi((a, s_a))$ . It is easy to check that  $\eta(a)$  is an  $a$ -map (that is, an extension of a map from  $S_a \times Q_a$  to  $S_a \times Q_a$ ). By Lemma 9, this uniquely defines an asynchronous morphism  $\eta: TR(\widetilde{\Sigma}) \rightarrow T_A \wr T$ .

Let  $t = (E, \leq, \lambda) \in TR(\widetilde{\Sigma})$ . We write  $\eta(t) = (\pi_1(t), \pi_2(t))$ . It follows from the definition of wreath product that  $\pi_1(t) = \varphi_A(t)$ . Now we claim that  $\pi_2(t)(s_{in}) = \psi(\chi_A(t))$ . We prove this by induction on the cardinality of  $E$ . Suppose  $t = t'a$ . Then  $\eta(t) = \eta(t')\eta(a)$ . As a result, we have  $(\pi_1(t), \pi_2(t)) = (\pi_1(t'), \pi_2(t'))(\pi_1(a), \pi_2(a))$ . Therefore, for  $s \in S_{\mathcal{P}}$ ,  $\pi_2(t)(s) = \pi_2(t')(s) + \pi_2(a)(\pi_1(t')(s))$ . In particular, it holds with  $s = s_{in}$ . Recall that  $\pi_1(t') = \varphi_A(t')$ . Also, by induction,  $\pi_2(t')(s_{in}) = \psi(\chi_A(t'))$ . Hence, with  $s = \varphi_A(t')(s_{in})$ ,

$$\begin{aligned} \pi_2(t)(s_{in}) &= \pi_2(t')(s_{in}) + \pi_2(a)(\pi_1(t')(s_{in})) \\ &= \psi(\chi_A(t')) + \pi_2(a)(s) \\ &= \psi(\chi_A(t')) + \psi((a, s_a)) \\ &= \psi(\chi_A(t')(a, s_a)) \\ &= \psi(\chi_A(t)) \end{aligned}$$

The last equality follows from Lemma 18. So,  $t \in \chi_A^{-1}(L)$  if and only if  $\chi_A(t) \in L$  if and only if  $\psi(\chi_A(t))(q_{\text{in}}) \in Q_{\text{fin}}$  if and only if  $\pi_2(t)(s_{\text{in}})(q_{\text{in}}) \in Q_{\text{fin}}$  if and only if  $\eta(t)(s_{\text{in}}, q_{\text{in}}) \in S_{\mathcal{P}} \times Q_{\text{fin}}$ . This shows that  $\eta$  recognizes  $\chi_A^{-1}(L)$  with  $(s_{\text{in}}, q_{\text{in}}) \in S_{\mathcal{P}} \times Q_{\mathcal{P}}$  as the initial global state, and  $S_{\mathcal{P}} \times Q_{\text{fin}} \subseteq S_{\mathcal{P}} \times Q_{\mathcal{P}}$  as the set of final global states.  $\blacktriangleleft$

Now we focus our attention on what is usually termed as the wreath product principle.

► **Theorem 20** (Local Wreath Product Principle). *Let  $T_1$  and  $T_2$  be atm's and let  $L \subseteq TR(\tilde{\Sigma})$  be a trace language recognized by an asynchronous morphism  $\eta: TR(\tilde{\Sigma}) \rightarrow T_1 \wr T_2$ , with initial global state  $(s_{\text{in}}, q_{\text{in}})$ . For each  $a \in \Sigma$ , let  $\eta(a) = (m_a, f_a)$ . Then  $\varphi: TR(\tilde{\Sigma}) \rightarrow T_1$ , defined by  $\varphi(a) = m_a$ , is an asynchronous morphism. Finally, let  $A = A_\varphi$  be the asynchronous automaton associated to  $\varphi$  and  $s_{\text{in}}$ , and let  $\chi_A$  be the corresponding local asynchronous transducer. Then  $L$  is a finite union of languages of the form  $U \cap \chi_A^{-1}(V)$ , where  $U \subseteq TR(\tilde{\Sigma})$  is recognized by  $T_1$ , and  $V \subseteq TR(\Sigma^{\parallel s})$  is recognized by  $T_2$ .*

**Proof.** We write  $T_1 = (\{S_i\}, M)$  and  $T_2 = (\{Q_i\}, N)$ . Consider  $a \in \Sigma$  and the  $a$ -map  $\eta(a) = (m_a, f_a) \in M \times \mathcal{F}(S_{\mathcal{P}}, N)$ . This means that  $\eta(a)$  is an extension of a map from  $S_a \times Q_a$  to  $S_a \times Q_a$ . By Lemma 15,  $m_a \in M$  is an  $a$ -map (of  $T_1$ ) and  $f_a: S_{\mathcal{P}} \rightarrow N$  is such that, for  $s \in S_{\mathcal{P}}$ ,  $f_a(s) \in N$  is an  $a$ -map (of  $T_2$ ) and it depends only on  $s_a$ . In particular,  $f_a: S_{\mathcal{P}} \rightarrow N$  may be viewed as  $f_a: S_a \rightarrow N$ . Below we will use  $f_a$  in this sense.

Now we define an asynchronous morphism  $\psi: TR(\Sigma^{\parallel s}) \rightarrow T_2$  as follows:  $\psi((a, s_a)) = f_a(s_a)$ . Note that, by Lemma 9,  $\psi$  is indeed an asynchronous morphism as  $f_a(s_a)$  is an  $a$ -map. Further, as  $m_a$  is an  $a$ -map,  $\varphi: TR(\tilde{\Sigma}) \rightarrow T_1$ , defined by  $\varphi(a) = m_a$ , also extends to an asynchronous morphism.

Our aim is to express  $L$  in terms of languages recognized by  $T_1$  and  $T_2$ . It suffices to show the result when  $L$  is recognized with a single final global state, say  $(s_{\text{fin}}, q_{\text{fin}})$ . Then  $L = \{t \in TR(\tilde{\Sigma}) \mid \eta(t)((s_{\text{in}}, q_{\text{in}})) = (s_{\text{fin}}, q_{\text{fin}})\}$ .

For  $t \in TR(\tilde{\Sigma})$ , we write  $\eta(t) = (\pi_1(t), \pi_2(t))$ . It follows from the definition of  $\varphi$  that  $\varphi(t) = \pi_1(t)$ . Hence, we can alternatively write  $L$  as

$$L = \{t \in TR(\tilde{\Sigma}) \mid \varphi(t)(s_{\text{in}}) = s_{\text{fin}} \text{ and } \pi_2(t)(s_{\text{in}})(q_{\text{in}}) = q_{\text{fin}}\}$$

Let  $U = \{t \in TR(\tilde{\Sigma}) \mid \varphi(t)(s_{\text{in}}) = s_{\text{fin}}\}$ . Then, with  $W = \{t \in TR(\tilde{\Sigma}) \mid \pi_2(t)(s_{\text{in}})(q_{\text{in}}) = q_{\text{fin}}\}$ ,  $L = U \cap W$ . By using essentially the same ideas as in the proof of Theorem 19, we can show that  $\pi_2(t)(s_{\text{in}}) = \psi(\chi_A(t))$ . Therefore,  $W = \{t \in TR(\tilde{\Sigma}) \mid \psi(\chi_A(t))(q_{\text{in}}) = q_{\text{fin}}\}$ .

It follows that, with  $V = \{t' \in TR(\Sigma^{\parallel s}) \mid \psi(t')(q_{\text{in}}) = q_{\text{fin}}\}$ ,  $W = \chi_A^{-1}(V)$ . Clearly,  $U$  is recognized by the atm  $T_1$  (via  $\varphi$ ),  $V$  is recognized by the atm  $T_2$  (via  $\psi$ ) and  $L = U \cap \chi_A^{-1}(V)$ . This completes the proof.  $\blacktriangleleft$

## 4 Towards a Decomposition Result

In this section, we use the algebraic framework developed so far to propose an analogue of the fundamental Krohn-Rhodes decomposition theorem over traces. We first recall the Krohn-Rhodes theorem in the purely algebraic setting of transformation monoids. We briefly explain how it is used to analyze/decompose morphisms from the free monoid and point out some difficulties that arise when we consider morphisms from the trace monoid.

Let  $M$  and  $N$  be monoids. We say that  $M$  divides  $N$  (in notation,  $M \prec N$ ) if  $M$  is a homomorphic image of some submonoid of  $N$ . This notion can be extended to transformation monoids. Let  $(X, M)$  and  $(Y, N)$  be two tm's. We say that  $(X, M)$  divides  $(Y, N)$ , denoted  $(X, M) \prec (Y, N)$ , if there exists a pair of mappings  $(f, \varphi)$  where  $f: Y \rightarrow X$  is a surjective

function and  $\varphi: N' \rightarrow M$  is a surjective morphism from a submonoid  $N'$  of  $N$ , such that  $\varphi(n)(f(y)) = f(n(y))$  for all  $n \in N'$  and all  $y \in Y$ .

Recall that  $U_2 = (\{1, 2\}, \{\text{id}, r_1, r_2\})$  denotes the *reset* transformation monoid on two elements. Along with it, the following class of transformation monoids plays an important role in the Krohn Rhodes theorem.

► **Example 21.** Let  $G$  be a group. Then  $(G, G)$  is a tm where the monoid element  $g$  represents the transformation  $m_g: G \rightarrow G$  of the set  $G$ , which is the right multiplication by  $g$ . In other words, for  $h \in G, m_g(h) = hg$ . ◀

We are now in a position to state the Krohn-Rhodes theorem [11]. See [20] for a classical proof of the theorem, and [5] for a modern proof.

► **Theorem 22 (Krohn-Rhodes Theorem).** *Every finite transformation monoid  $T = (X, M)$  divides a wreath product of the form  $T_1 \wr \dots \wr T_n$  where each factor  $T_i$  is either  $U_2$  or is of the form  $(G, G)$  for some non-trivial simple group  $G$  dividing  $M$ .*

Henceforth, we will be dealing with only finite tm's and sometimes we will omit the qualifier 'finite'. Now we turn our attention to the use of this decomposition theorem for analysing word languages recognized by morphisms from the free monoid.

► **Definition 23.** *Let  $\varphi: \Sigma^* \rightarrow T = (X, M)$  be a morphism. Further, let  $\psi: \Sigma^* \rightarrow T' = (Y, N)$  be another morphism. We say that  $\psi$  simulates  $\varphi$  if there exists a surjective function  $f: Y \rightarrow X$  such that, for all  $a \in \Sigma$  and all  $y \in Y$ ,  $f(\psi(a)(y)) = \varphi(a)(f(y))$ .*

$$\begin{array}{ccc} Y & \xrightarrow{\psi(a)} & Y \\ f \downarrow & & \downarrow f \\ X & \xrightarrow{\varphi(a)} & X \end{array}$$

■ **Figure 2** Visual illustration of condition  $f(\psi(a)(y)) = \varphi(a)(f(y))$  in Definition 23

Observe that if  $\psi$  simulates  $\varphi$  then a language recognized by  $\varphi$  is also recognized by  $\psi$ .

► **Proposition 24.** *Let  $\varphi: \Sigma^* \rightarrow T = (X, M)$  be a morphism. Then there exists a morphism  $\psi: \Sigma^* \rightarrow T'$  which simulates  $\varphi$  such that the tm  $T'$  is of the form  $T_1 \wr \dots \wr T_n$  where each factor  $T_i$  is either  $U_2$  or  $(G, G)$  for some non-trivial simple group  $G$  dividing  $M$ .*

**Proof.** Given  $T$ , we get  $T' = T_1 \wr \dots \wr T_n = (Y, N)$  by the Krohn-Rhodes theorem. Since  $T \prec T'$ , there exists a pair of mappings  $(f, \theta)$  where  $f: Y \rightarrow X$  is a surjective function and  $\theta: N' \rightarrow M$  is a surjective morphism from a submonoid  $N'$  of  $N$ , such that  $\theta(n)(f(y)) = f(n(y))$  for all  $n \in N'$  and all  $y \in Y$ . Construct  $\psi: \Sigma \rightarrow N$  by mapping  $\psi(a)$ , for each  $a$  in  $\Sigma$ , to an arbitrary element in  $\theta^{-1}(\varphi(a))$ . Thanks to the fact that  $\Sigma^*$  is a free monoid,  $\psi$  uniquely extends to a morphism  $\psi: \Sigma^* \rightarrow T'$ . It is easily checked that  $\psi$  simulates  $\varphi$ . ◀

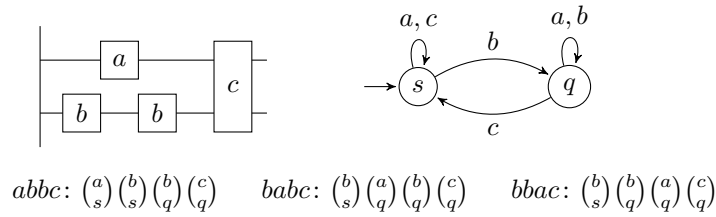
Combined with the wreath product principle, the above proposition provides a powerful inductive tool to prove many non-trivial results in the theory of finite words. See [14, 3].

Motivated by these applications, we look for an analogue of the above proposition for the setting of traces. We now point to some problems that arise if one tries to naively lift the Krohn-Rhodes theorem to the setting of traces. The first problem is that, unlike in the

## 46:12 Wreath products in the concurrent setting

word scenario, division does not imply simulation of morphisms from the *trace monoid*. By simulation of morphisms from the trace monoid, we simply mean an obvious adaptation of the Definition 23 to the morphisms from the trace monoid. See the extended version [1] for an example of the problem of the first kind. The second problem is that even if there is a morphism from  $TR(\tilde{\Sigma})$  to a wreath product of tm's, in general it does not induce morphisms from trace monoids to the individual tm's beyond the first one. This is primarily because the output of the *sequential* transducer associated with the first tm is *not* a trace.

► **Example 25.** Assume the DFA in Figure 3 represents the induced morphism to the first tm in a wreath product chain. The figure below shows the outputs of the sequential transducer associated with this DFA on three different linearizations of a single input trace. These outputs have different sets of letters and can not constitute a single trace. ◻



■ **Figure 3** Sequential transducer outputs for all linearizations of a trace

Prior work in [8] devised a wreath product principle for traces, but it uses non-trace structures to circumvent the second problem, thus limiting its applicability.

As seen in the previous section, the new algebraic framework of asynchronous structures supports true concurrency and is well suited to reason about trace languages. Most importantly, an asynchronous morphism to a wreath product chain gives rise to asynchronous morphisms to individual atm's of the chain (see the proof of Theorem 20 for an illustration). This can be seen as a resolution of the second problem mentioned above.

Going ahead, we extend the notion of simulation to the case when the 'simulating' morphism is an asynchronous morphism to an atm.

► **Definition 26.** Let  $\varphi: TR(\tilde{\Sigma}) \rightarrow T = (X, M)$  be a morphism to a tm. Further, let  $T' = (\{S_i\}, N)$  be an atm and  $\psi: TR(\tilde{\Sigma}) \rightarrow T'$  be an asynchronous morphism. We say that  $\psi$  is an asynchronous simulation of  $\varphi$  (or simply  $\psi$  simulates  $\varphi$ ) if there exists a surjective function  $f: S_{\mathcal{P}} \rightarrow X$  such that, for all  $a \in \Sigma$  and all  $s \in S_{\mathcal{P}}$ ,  $f(\psi(a)(s)) = \varphi(a)(f(s))$ .

The fundamental theorem of Zielonka [21] states that every recognizable language is accepted by some asynchronous automaton. See [15] for another proof of the theorem. From the viewpoint of our algebraic setup and the previous definition, it guarantees the existence of a simulating asynchronous morphism.

► **Theorem 27 (Zielonka's Theorem).** Let  $\varphi: TR(\tilde{\Sigma}) \rightarrow T$  be a morphism to a finite tm. There exists an asynchronous morphism  $\psi: TR(\tilde{\Sigma}) \rightarrow T'$ , to a finite atm, which simulates  $\varphi$ .

Recall that the atm  $U_2[\ell]$ , defined in Example 6, is a natural extension of the tm  $U_2$  to the process  $\ell$ . In a similar vein, for a group  $G$ , the atm  $G[\ell]$  denotes the natural extension of the tm  $(G, G)$  from Example 21 to the process  $\ell$ . We will use a similar notation to extend a tm to an atm localized to a particular process.

Now we formulate the following decomposition question:

► **Question 1.** Let  $\varphi: TR(\tilde{\Sigma}) \rightarrow (X, M)$  be a morphism to a finite tm. Does there exist an asynchronous morphism  $\psi: TR(\tilde{\Sigma}) \rightarrow T'$  to a finite atm, such that  $\psi$  simulates  $\varphi$ , and the atm  $T'$  is of the form  $T_1 \wr \dots \wr T_n$  where each factor  $T_i$  is, for some  $\ell \in \mathcal{P}$ , either the atm  $U_2[\ell]$  or is of the form  $G[\ell]$  for some non-trivial simple group  $G$  dividing  $M$ ?

In view of our discussion so far, it is clear that the above question asks for a simultaneous generalization of the Krohn-Rhodes theorem for the setting of words (that is, Proposition 24), and Zielonka's theorem for the setting of traces (that is, Theorem 27). Question 1 in general remains open. However we answer it positively in a particular case, namely that of acyclic architectures, which is general enough to include the common client-server settings.

► **Definition 28.** Let  $\tilde{\Sigma} = \{\Sigma_i\}_{i \in \mathcal{P}}$  be a distributed alphabet. Then its communication graph is  $G = (\mathcal{P}, E)$  where  $E = \{(i, j) \in \mathcal{P} \times \mathcal{P} \mid i \neq j \text{ and } \Sigma_i \cap \Sigma_j \neq \emptyset\}$ . If the communication graph is acyclic, then the distributed alphabet is called an acyclic architecture.

Observe that if  $\tilde{\Sigma}$  is an acyclic architecture, then no action is shared by more than two processes. The work [10] provides a simpler proof of Zielonka's theorem in this case.

► **Theorem 29.** If  $\tilde{\Sigma}$  is an acyclic architecture, then Question 1 admits a positive answer.

## 5 Local and Global Cascade Products

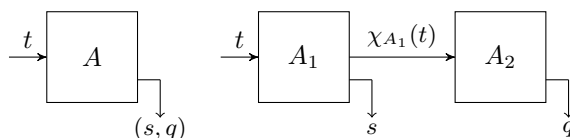
In this section, we introduce distributed automata-theoretic operations called local and global cascade products.

### 5.1 Local Cascade Product

As seen before, asynchronous morphisms are the algebraic counterparts of asynchronous automata. It turns out that an asynchronous morphism into a wreath product of atm's corresponds to the 'local cascade product' of asynchronous automata. See [1] for details. Here we simply define the local cascade product of two asynchronous automata.

► **Definition 30.** Let  $A_1 = (\{S_i\}, \{\delta_a\}, s_{in})$  over  $\tilde{\Sigma}$ , and  $A_2 = (\{Q_i\}, \{\delta_{(a, s_a)}\}, q_{in})$  over  $\tilde{\Sigma}^{\parallel s}$ . We define the local cascade product of  $A_1$  and  $A_2$  to be the asynchronous automaton  $A_1 \circ_{\ell} A_2 = (\{S_i \times Q_i\}, \{\Delta_a\}, (s_{in}, q_{in}))$  over  $\tilde{\Sigma}$ , where, for  $a \in \Sigma$  and  $(s_a, q_a) \in S_a \times Q_a$ ,  $\Delta_a((s_a, q_a)) = (\delta_a(s_a), \delta_{(a, s_a)}(q_a))$ .

The operational working of  $A = A_1 \circ_{\ell} A_2$  can be understood in terms of  $A_1$  and  $A_2$  using the local asynchronous transducer  $\chi_{A_1}: TR(\tilde{\Sigma}) \rightarrow TR(\tilde{\Sigma}^{\parallel s})$  (associated with  $A_1$ ) as follows: for an input trace  $t \in TR(\tilde{\Sigma})$ , the run of  $A$  on  $t$  ends in global state  $(s, q)$  if and only if the run of  $A_1$  on  $t$  ends in global state  $s$  and the run of  $A_2$  on  $\chi_{A_1}(t)$  ends in global state  $q$ . This



■ **Figure 4** Operational view of local cascade product

operational cascade of  $A_1$  followed by  $A_2$  is summarized in the right part of the Figure 4 and is the essence of the local wreath product principle. Further, it is not difficult to check that the local cascade product is associative and  $\chi_{A_1 \circ_{\ell} A_2}(t) = \chi_{A_2}(\chi_{A_1}(t))$  for all  $t \in TR(\tilde{\Sigma})$ .

## 5.2 Global Asynchronous Transducer and its Local Implementation

Let  $A = (\{S_i\}, \{\delta_a\}, s_{in})$  be an asynchronous automaton over  $\tilde{\Sigma}$ . Recall that the local asynchronous transducer  $\chi_A$  preserves the underlying set of events and, at an event, simply records the previous local states of the processes *participating* in that event.

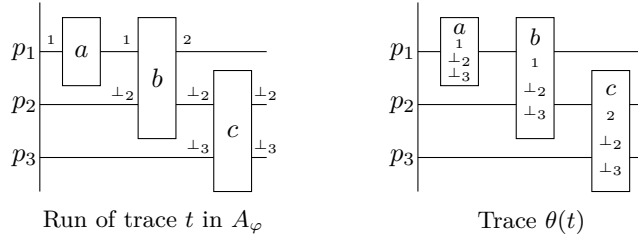
Now we introduce a natural variant of  $\chi_A$  which is called the *global asynchronous transducer*. In this variant, at an event, we record the *maximal/best global state* that causally precedes the current event. This is the best global state that the processes participating in the current event are (collectively) aware of. It is important to note that the global and local asynchronous transducers coincide in the sequential setting.

We first define the alphabet  $\Sigma^{S_{\mathcal{P}}} = \Sigma \times S_{\mathcal{P}}$  where each letter in  $\Sigma$  is extended with global state information of  $A$ . This can naturally be viewed as a distributed alphabet  $\tilde{\Sigma}^{S_{\mathcal{P}}}$  where for all  $a \in \Sigma$  and  $s \in S_{\mathcal{P}}$ , we have  $(a, s) \in \tilde{\Sigma}_i^{S_{\mathcal{P}}}$  if and only if  $a \in \Sigma_i$ .

► **Definition 31** (Global Asynchronous Transducer). *Let  $A$  be an asynchronous automaton over  $\tilde{\Sigma}$ . The global asynchronous transducer of  $A$  is the map  $\theta_A: TR(\tilde{\Sigma}) \rightarrow TR(\tilde{\Sigma}^{S_{\mathcal{P}}})$  defined as follows. If  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$ , then  $\theta_A(t) = (E, \leq, \mu) \in TR(\tilde{\Sigma}^{S_{\mathcal{P}}})$  with the labelling  $\mu: E \rightarrow \Sigma \times S_{\mathcal{P}}$  defined by:*

$$\forall e \in E, \mu(e) = (a, s) \text{ where } a = \lambda(e) \text{ and } s = \rho_t(\downarrow e \setminus \{e\})$$

► **Example 32.** For  $t$  and  $A_{\varphi}$  from Example 17, Figure 5 shows its global asynchronous transducer output  $\theta(t)$ . Note the difference from Figure 1. For example, here the only  $p_3$ -event has process  $p_1$  state 2 in its label (which is the best process  $p_1$  state in its causal past) even though processes  $p_1$  and  $p_3$  never interact directly. ◻



■ **Figure 5** Global asynchronous transducer output on a trace

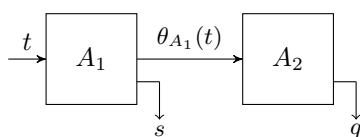
It is possible, albeit non-trivial, to give a uniform translation from the automaton  $A$  to another automaton  $\mathcal{G}(A)$  such that the global asynchronous transducer of  $A$  is realized by the local asynchronous transducer of  $\mathcal{G}(A)$ . It turns out that one must make crucial use of the latest information that the agents have about each other when defining the automaton  $\mathcal{G}(A)$ . It has been shown in [16] that this information can be kept track of by a deterministic asynchronous automaton. See [1] for more details.

## 5.3 Global Cascade Product

Now we are ready to define a cascade model which uses the global asynchronous transducer.

► **Definition 33** (Operational Global Cascade Product). *Let  $A_1 = (\{S_i\}, \{\delta_a\}, s_{in})$  be an asynchronous automaton over  $\tilde{\Sigma}$ , and  $A_2 = (\{Q_i\}, \{\delta_{(a,s)}\}, q_{in})$  be an asynchronous automaton over  $\tilde{\Sigma}^{S_{\mathcal{P}}}$ . Then their operational global cascade product, denoted by  $A_1 \circ_g A_2$ , is a cascade model where, for any input trace  $t \in TR(\tilde{\Sigma})$ ,  $A_1$  runs on  $t$  (and ‘outputs’  $\theta_{A_1}(t)$ ) and  $A_2$  runs on  $\theta_{A_1}(t)$ . See Figure 6.*





■ **Figure 6** Operational view of global cascade product

Note that  $A_1 \circ_g A_2$  is not, a priori, an asynchronous automaton, but in view of the discussion in the preceding subsection, it is simulated by the asynchronous automaton  $\mathcal{G}(A_1) \circ_\ell A_2$ .

For simplicity, we view  $A_1 \circ_g A_2$  as an automaton with  $S_{\mathcal{P}} \times Q_{\mathcal{P}}$  as its global states, and extend the notions of run, acceptance etc. to it in a natural way (see [1]). Henceforth, we refer to the operational global cascade product as the simply global cascade product. It turns out that the global cascade product is associative in a natural sense. See [1] for more details. Thanks to this, we can also talk about the global cascade product of a *sequence* of asynchronous automata.

The following *global cascade product principle* is an easy consequence of the definitions.

► **Theorem 34** (Global Cascade Product Principle). *Let  $A$  (resp.  $B$ ) be a global cascade product over  $\tilde{\Sigma}$  (resp.  $\tilde{\Sigma}^{S_{\mathcal{P}}}$ ), where  $S_{\mathcal{P}}$  is the set of global states of  $A$ . Then any language  $L \subseteq TR(\tilde{\Sigma})$  accepted by  $A \circ_g B$  is a finite union of languages of the form  $U \cap \theta_A^{-1}(V)$  where  $U \subseteq TR(\tilde{\Sigma})$  is accepted by  $A$ , and  $V \subseteq TR(\tilde{\Sigma}^{S_{\mathcal{P}}})$  is accepted by  $B$ .*

## 6 Temporal Logics, Aperiodic Trace Languages & Cascade Products

An automata-theoretic consequence of Theorem 29 is that any aperiodic trace language (that is, a trace language recognized by an aperiodic monoid) over an acyclic architecture is accepted by a local cascade product of localized two-state reset automata. We call these automata  $U_2[\ell]$  as well. In this section, we generalize this result to any distributed alphabet, but using global cascade product of  $U_2[\ell]$ s.

Our proof uses a process-based past local temporal logic (over traces) called  $\text{LocTL}[Y_i, S_i]$  that exactly defines aperiodic trace languages. This expressive completeness property of  $\text{LocTL}[Y_i, S_i]$  is an easy consequence of a non-trivial result from [4], where the future version of a similar local temporal logic is shown to coincide with first-order logic definable, equivalently, aperiodic trace languages. The syntax of  $\text{LocTL}[Y_i, S_i]$  is as follows.

Event formula  $\alpha = a \mid \neg\alpha \mid \alpha \vee \beta \mid Y_i \alpha \mid \alpha S_i \alpha \quad a \in \Sigma, i \in \mathcal{P}$

Trace formula  $\beta = \exists_i \alpha \mid \neg\beta \mid \beta \vee \gamma$

The semantics of the logic is given below. Each event formula is evaluated at an event of a trace. Let  $t = (E, \leq, \lambda) \in TR(\tilde{\Sigma})$  be a trace with  $e \in E$ . For any event  $x$  in  $t$  and  $i \in \mathcal{P}$ , we denote by  $x_i$  the unique maximal event of  $(\downarrow x \setminus \{x\}) \cap E_i$ , if it exists.

$t, e \models a$	if $\lambda(e) = a$
$t, e \models \neg\alpha$	if $t, e \not\models \alpha$
$t, e \models \alpha \vee \beta$	if $t, e \models \alpha$ or $t, e \models \beta$
$t, e \models Y_i \alpha$	if $e_i$ exists, and $t, e_i \models \alpha$
$t, e \models \alpha S_i \alpha'$	if $e \in E_i$ and $\exists f \in E_i$ such that $f < e$ and $t, f \models \alpha'$ and $\forall g \in E_i \quad f < g < e \Rightarrow t, g \models \alpha$

## 46:16 Wreath products in the concurrent setting

Note that the since operator is a strict version.  $\text{LocTL}[Y_i, S_i]$  trace formulas are evaluated for traces, with the following semantics.

$$t \models \exists_i \alpha \quad \text{if there exists a maximal } i\text{-event } e \text{ in } t \text{ such that } t, e \models \alpha$$

The semantics of the boolean combinations of trace formulas are obvious. Any  $\text{LocTL}[Y_i, S_i]$  trace formula  $\beta$  over  $\tilde{\Sigma}$  defines the trace language  $L_\beta = \{t \in TR(\tilde{\Sigma}) \mid t \models \beta\}$ . The following theorem gives a global cascade product characterization of  $\text{LocTL}[Y_i, S_i]$  definable languages.

► **Theorem 35.** *A trace language is defined by a  $\text{LocTL}[Y_i, S_i]$  formula if and only if it is accepted by a global cascade product of  $U_2[\ell]$ .*

By the expressive completeness of  $\text{LocTL}[Y_i, S_i]$  from [4], this gives a new characterization of aperiodic or equivalently, first-order logic definable trace languages in terms of global cascade products of localized two state asynchronous reset automata. It is in the spirit of the classical Krohn-Rhodes theorem for aperiodic word languages.

We now give a temporal logic characterization of local cascade product of  $U_2[\ell]$ . The local temporal logic  $\text{LocTL}[S_i]$  is simply the fragment of  $\text{LocTL}[Y_i, S_i]$  where  $Y_i$  is disallowed. The semantics is inherited. It is unknown whether the logic  $\text{LocTL}[S_i]$  is as expressive as  $\text{LocTL}[Y_i, S_i]$ .

► **Theorem 36.** *A trace language is defined by a  $\text{LocTL}[S_i]$  formula if and only if it is recognized by a local cascade product of  $U_2[\ell]$ .*

Note that if our postulated decomposition (see Question 1) were true, it would imply that  $\text{LocTL}[S_i]$  is expressively complete, which would be a stronger temporal logic characterization for aperiodic trace languages than what is currently known. In particular, by Theorem 29,  $\text{LocTL}[S_i]$  is expressively complete over tree architecture. And this holds true for any distributed alphabet where Question 1 admits a positive answer.

## 7 Conclusion

We have presented an algebraic framework equipped with wreath products and proved a wreath product principle which is well suited for the analysis of trace languages. Building on this framework, we have postulated a natural decomposition theorem which has been proved for the case of acyclic architectures. This special case already provides an interesting generalization of the Krohn-Rhodes theorem. It simultaneously proves Zielonka's theorem for acyclic architectures.

The wreath product operation in the new framework, when viewed in terms of automata, manifests itself in the form of a local cascade product of asynchronous automata. We have also proposed global cascade products of asynchronous automata and applied them to arrive at a novel decomposition of aperiodic trace languages. This is a non-trivial and truly concurrent generalization of the cascade decomposition of aperiodic word languages using two-state reset automata.

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