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1 Linear High-Order Deterministic Tree 2 transducers with Regular look-ahead

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12 — Abstract —

13 We introduce the notion of high-order deterministic top-down tree transducers (HODT) whose outputs
14 correspond to simply-typed lambda-calculus formulas. These transducers are natural generalizations
15 of known models of top-tree transducers such as: Deterministic Top-Down Tree Transducers, Macro
16 Tree Transducers, Streaming Tree Transducers. . . We focus on the linear restriction of high order
17 tree transducers with look-ahead ($\text{HODTR}_{\text{lin}}$), and prove this corresponds to tree to tree functional
18 transformations defined by Monadic Second Order (MSO) logic. We give a specialized procedure for
19 the composition of those transducers that uses a flow analysis based on coherence spaces and allows
20 us to preserve the linearity of transducers. This procedure has a better complexity than classical
21 algorithms for composition of other equivalent tree transducers, but raises the order of transducers.
22 However, we also indicate that the order of a $\text{HODTR}_{\text{lin}}$ can always be bounded by 3, and give a
23 procedure that reduces the order of a $\text{HODTR}_{\text{lin}}$ to 3. As those resulting $\text{HODTR}_{\text{lin}}$ can then be
24 transformed into other equivalent models, this gives an important insight on composition algorithm
25 for other classes of transducers. Finally, we prove that those results partially translate to the case of
26 almost linear HODTR: the class corresponds to the class of tree transformations performed by MSO
27 with unfolding (not closed by composition), and provide a mechanism to reduce the order to 3 in
28 this case.

29 **2012 ACM Subject Classification** Theory of computation \rightarrow Transducers; Theory of computation \rightarrow
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38 **1** Introduction

39 Tree Transducers formalize transformations of structured data such as Abstract Syntax Trees,
 40 XML, JSON, or even file systems. They are based on various mechanisms that traverse tree
 41 structures while computing an output: Top-Down and Bottom-Up tree transducers [17, 4]
 42 which are direct generalizations of deterministic word transducers [8, 7, 3], but also more
 43 complex models such as macro tree transducers [11] (MTT) or streaming tree transducers [1]
 44 (STT) to cite a few.

45 Logic offers another, more descriptive, view on tree transformations. In particular,
 46 Monadic Second Order (MSO) logic defines a class of tree transformations (MSOT) [5, 6] which
 47 is expressive and is closed under composition. It coincides with the class of transformations
 48 definable with MTT enhanced with a regular look-ahead and restricted to finite copying
 49 [9, 10], and also with the class of STT [1].

50 We argue here that simply typed λ -calculus gives a uniform generalisation of all these
 51 different models. Indeed, they can all be considered as classes of programs that read input
 52 tree structures, and, at each step, compose tree operations which in the end produce the
 53 final output. Each of these tree operations can be represented using simply typed λ -terms.

54 In this paper, we define top-down tree transducers that follow the usual definitions of such
 55 machines, except that rules can produce λ -terms of arbitrary types. We call these machines,
 56 High-Order Top-down tree transducers, or High-Order Deterministic Tree Transducers
 57 (HODT) in the deterministic case. This class of transducers naturally contains top-down
 58 tree transducers, as they are HODT of order 0 (the output of rules are trees), but also MTT,
 59 which are HODT of order 1 (outputs are tree contexts). They also contain STT, which can
 60 be translated directly into HODT of order 3 with some restricted continuations. Also, STT
 61 traverse their input tree represented as a string in a leftmost traversal (a stream). This
 62 constraint could easily be adapted to our model but would yield technical complications that
 63 are not the focus of this paper. Finally, our model generalizes High Level Tree Transducers
 64 defined in [12], which also produce λ -term, but restricted to the safe λ -calculus case.

65 In this paper we focus on the *linear* and *almost linear* restrictions of HODT. In terms of
 66 expressiveness, linear HODTR (HODTR_{lin}) corresponds to the class of MSOT. This links
 67 our formalism to other equivalent classes of transducers, such as finite-copying macro-tree
 68 transducers [9, 10], with an important difference: the linearity restriction is a simple syntactic
 69 restriction, whereas finite-copying or the equivalent single-use-restricted condition are both
 70 global conditions that are harder to enforce. For STT, the linearity condition corresponds to
 71 the copyless condition described in [1] and where the authors prove that any STT can be
 72 made copyless.

73 The relationship of HODTR_{lin} to MSOT is made via a transformation that *reduces the*
 74 *order* of transducers. We indeed prove that for any HODTR_{lin}, there exists an equivalent
 75 HODTR_{lin} whose order is at most 3. This transformation allows us to prove then that
 76 HODTR_{lin} are equivalent to Attribute Tree Transducers with the single use restriction
 77 (ATT_{sur}). In turn, this shows that HODTR_{lin} are equivalent to MSOT [2].

78 One of the main interests of HODTR_{lin} is that λ -calculus also offers a simple composition
 79 algorithm. This approach gives an efficient procedure for composing two HODTR_{lin}. In
 80 general, this procedure raises the order of the produced transducer. In comparison, com-
 81 position in other equivalent classes are either complex or indirect (through MSOT). In any
 82 case, our procedure has a better complexity. Indeed, it benefits from higher-order which
 83 permits a larger number of implementations for a given transduction. The complexity of the
 84 construction is also lowered by the use of a notion of determinism slightly more liberal than

85 usual that we call *weak determinism*.

86 The last two results allow us to obtain a composition algorithm for other equivalent
87 classes of tree transducer, such as MTT or STT: compile into $\text{HODTR}_{\text{lin}}$, compose, reduce
88 the order, and compile back into the original model. The advantage of this approach over
89 the existing ones is that the complex composition procedure is decomposed into two simpler
90 steps (the back and forth translations between the formalisms are unsurprising technical
91 procedures). We believe in fact that existing approaches [12, 1] combine in one step the two
92 elements, which is what makes them more complex.

93 The property of order reduction also applies to a wider class of HODT, *almost linear*
94 HODT (HODTR_{al}). Again here, this transformation allows us to prove that this class of
95 tree transformations is equivalent to that of Attribute Tree Transducers which is known to
96 be equivalent to MSO tree transformations with unfolding [2], i.e. MSO tree transduction
97 that produce Directed Acyclic Graphs (i.e. trees with shared sub-trees) that are unfolded to
98 produce a resulting tree. We call these transductions Monadic Second Order Transductions
99 with Sharing (MSOTS). Note however that HODTR_{al} are not closed under composition.

100 Section 2 presents the technical definitions used throughout the paper. In particular, it
101 gives the definitions of the various notions of transducers studied in the paper and also the
102 notion of weak determinism. Section 3 studies the expressivity of linear and almost linear
103 higher-order transducer by relating them to MSOT and MSOTS. It focuses more specifically
104 on the order reduction procedure that is at the core of the technical work. Section 4 presents
105 the composition algorithm for linear higher-order transducers. This algorithm is based on
106 Girard's coherence spaces and can be interpreted as a form of partial evaluation for linear
107 higher-order programs. Finally we conclude.

108 2 Definitions

109 This section presents the main formalisms we are going to use throughout the paper, namely
110 simply typed λ -calculus, finite state automata and high-order transducers.

111 2.1 λ -calculus

112 Fix a finite set of atomic types \mathcal{A} , we then define the set of types over \mathcal{A} , $\text{types}(\mathcal{A})$, as the
113 types that are either an atomic type, i.e. an element of \mathcal{A} , or a functional type $(A \rightarrow B)$, with
114 A and B being in $\text{types}(\mathcal{A})$. The operator \rightarrow is right-associative and $A_1 \rightarrow \dots \rightarrow A_n \rightarrow B$
115 denotes the type $(A_1 \rightarrow (\dots \rightarrow (A_n \rightarrow B) \dots))$. The order of a type A is inductively defined
116 by $\text{order}(A) = 0$ when $A \in \mathcal{A}$, and $\text{order}(A \rightarrow B) = \max(\text{order}(A) + 1, \text{order}(B))$.

117 A signature Σ is a triple (C, \mathcal{A}, τ) with C being a finite set of *constants*, \mathcal{A} a finite set of
118 *atomic types*, and τ a mapping from C to $\text{types}(\mathcal{A})$, *the typing function*.

119 We allow ourselves to write $\text{types}(\Sigma)$ to refer to the set $\text{types}(\mathcal{A})$. The order of a signature
120 is the maximal order of a type assigned to a constant (i.e. $\max\{\text{order}(\tau(c)) \mid c \in C\}$). In this
121 work, we mostly deal with tree signatures which are of order 1 and whose set of atomic types
122 is a singleton. In such a signature with atomic type o , the types of constants are of the form
123 $o \rightarrow \dots \rightarrow o \rightarrow o$. We write $o^n \rightarrow o$ for an order-1 type which uses $n + 1$ occurrences of o ,
124 for example, $o^2 \rightarrow o$ denotes $o \rightarrow o \rightarrow o$. When c is a constant of type A , we may write c^A
125 to make explicit that c has type A . Two signatures $\Sigma_1 = (C_1, \mathcal{A}_1, \tau_1)$ and $\Sigma_2 = (C_2, \mathcal{A}_2, \tau_2)$
126 so that for every c in $C_1 \cap C_2$ we have $\tau_1(c) = \tau_2(c)$ can be summed, and we write $\Sigma_1 + \Sigma_2$
127 for the signature $(C_1 \cup C_2, \mathcal{A}_1 \cup \mathcal{A}_2, \tau)$ so that if c is in C_1 , $\tau(c) = \tau_1(c)$ and if c is in C_2 ,
128 $\tau(c) = \tau_2(c)$. The sum operation over signatures being associative and commutative, we
129 write $\Sigma_1 + \dots + \Sigma_n$ to denote the sum of several signatures.

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130 We assume that for every type A , there is an infinite countable set of variables of type A .
 131 When two types are different the set of variables of those types are of course disjoint. As
 132 with constants, we may write x^A to make it clear that x is a variable of type A .

133 When Σ is a signature, we define the family of simply typed λ -terms over Σ , denoted
 134 $\Lambda(\Sigma) = (\Lambda^A(\Sigma))_{A \in \text{types}(\Sigma)}$, as the smallest family indexed by $\text{types}(\Sigma)$ so that:

- 135 ■ if c^A is in Σ , then c^A is in $\Lambda^A(\Sigma)$,
- 136 ■ x^A is in $\Lambda^A(\Sigma)$,
- 137 ■ if $A = B \rightarrow C$ and M is in $\Lambda^C(\Sigma)$, then $(\lambda x^B.M)$ is in $\Lambda^A(\Sigma)$,
- 138 ■ if M is in $\Lambda^{B \rightarrow A}(\Sigma)$ and N is in $\Lambda^B(\Sigma)$, then (MN) is in $\Lambda^A(\Sigma)$.

139 The term M is a *pure* λ -term if it does not contain any constant c^A from Σ . When the type
 140 is irrelevant we write $M \in \Lambda(\Sigma)$ instead of $M \in \Lambda^A(\Sigma)$. We drop parentheses when it does
 141 not bring ambiguity. In particular, we write $\lambda x_1 \dots x_n.M$ for $(\lambda x_1(\dots(\lambda x_n.M)\dots))$, and
 142 $M_0 M_1 \dots M_n$ for $((\dots(M_0 M_1)\dots)M_n)$.

143 The set $\text{fv}(M)$ of free variables of a term M is inductively defined on the structure of M :

- 144 ■ $\text{fv}(c) = \emptyset$,
- 145 ■ $\text{fv}(x) = \{x\}$,
- 146 ■ $\text{fv}(MN) = \text{fv}(M) \cup \text{fv}(N)$,
- 147 ■ $\text{fv}(\lambda x.M) = \text{fv}(M) - \{x\}$.

148 Terms which have no free variables are called *closed*. We write $M[x_1, \dots, x_k]$ to emphasize that
 149 $\text{fv}(M)$ is included in $\{x_1, \dots, x_k\}$. When doing so, we write $M[N_1, \dots, N_k]$ for the capture
 150 avoiding substitution of variables x_1, \dots, x_k by the terms N_1, \dots, N_k . In other contexts,
 151 we simply use the usual notation $M[N_1/x_1, \dots, N_k/x_k]$. Moreover given a substitution θ ,
 152 we write $M.\theta$ for the result of applying this (capture avoiding) substitution and we write
 153 $\theta[N_1/x_1, \dots, N_k/x_k]$ for the substitution that maps the variables x_i to the terms N_i but is
 154 otherwise equal to θ . Of course, we authorize such substitutions only when the λ -term N_i
 155 has the same type as the variable x_i .

156 We take for granted the notions of β -contraction, noted \rightarrow_β , β -reduction, noted $\xrightarrow{*}_\beta$,
 157 β -conversion, noted $=_\beta$, and β -normal form for terms.

158 Consider closed terms of type o that are in β -normal form and that are built on a tree
 159 signature, they can only be of the form $a t_1 \dots t_n$ where a is a constant of type $o^n \rightarrow o$ and
 160 t_1, \dots, t_n are closed terms of type o in β -normal form. This is just another notation for
 161 ranked trees. So when the type o is meant to represent trees, types of order 1 which have
 162 the form $o \rightarrow \dots \rightarrow o \rightarrow o$ represent functions from trees to trees, or more precisely tree
 163 contexts. Types of order 2 are types of trees parametrized by contexts. The notion of order
 164 captures the complexity of the operations that terms of a certain type describe.

165 A term M is said *linear* if each variable (either bound or free) in M occurs exactly once
 166 in M . A term M is said *syntactically almost linear* when each variable in M of non-atomic
 167 type occurs exactly once in M . Note that, through β -reduction, linearity is preserved but
 168 not syntactic almost linearity.

169 For example, given a tree signature Σ_1 with one atomic type o and two constants f of type
 170 $o^2 \rightarrow o$ and a of type o , the term $M = (\lambda y_1 y_2. f y_1 (f a y_2)) a (f x a)$ with free variable x of type
 171 o is linear because each variable (y_1 , y_2 and x) occurs exactly once in M . The term M contains
 172 a β -redex so: $(\lambda y_1 y_2. f y_1 (f a y_2)) a (f x a) \rightarrow_\beta (\lambda y_2. f a (f a y_2)) (f x a) \rightarrow_\beta f a (f a (f x a))$.
 173 The term $f a (f a (f x a))$ has no β -redex so it is the β -normal form of M .

174 Another example: the term $M_2 = (\lambda y. f y y) (x a)$ with free variable x of type $o \rightarrow o$ is
 175 syntactically almost linear because the variable y which occurs twice in the term is of the
 176 atomic type o . It β -reduces to the term $M'_2 = f (x a) (x a)$ which is not syntactically almost
 177 linear, so β -reduction does not preserve syntactical almost linearity.

178 We call a term *almost linear* when it is β -convertible to a syntactically almost linear
179 term. Almost linear terms are characterized also by typing properties (see [15]).

180 2.2 Tree Automata

181 We present here the classical definition of deterministic bottom-up tree automaton (BOT)
182 adapted to our formalism. A BOT \mathbf{A} is a tuple (Σ_P, Σ, R) where:

- 183 ■ $\Sigma = (C, \{o\}, \tau)$ is a first-order tree signature, the *input signature*,
- 184 ■ $\Sigma_P = (P, \{o\}, \tau_P)$ is the *state signature*, and is such that for every $p \in P$, $\tau_P(p) = o$.
- 185 Constants of P are called *states*,
- 186 ■ R is a finite set of rules of the form $a p_1 \dots p_n \rightarrow p$ where:
 - 187 ■ p, p_1, \dots, p_n are states of P ,
 - 188 ■ a is a constant of Σ with type $o^n \rightarrow o$.

189 An automaton is said *deterministic* when there is at most one rule in R for each possible
190 left hand side. It is *non-deterministic* otherwise.

191 Apart from the notation, our definition differs from the classical one by the fact there are no
192 final states, and hence, the automaton does not describe a language. This is due to the fact
193 that BOT will be used here purely for look-ahead purposes.

194 2.3 High-Order Deterministic top-down tree Transducers

195 From now on we assume that Σ_i is a tree signature for every number i and that its atomic
196 type is o_i .

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198 (HODTR_{lin}) T is a tuple $(\Sigma_Q, \Sigma_1, \Sigma_2, q_0, R, \mathbf{A})$ where:

- 199 ■ $\Sigma_1 = (C_1, \{o_1\}, \tau_1)$ is a first-order tree signature, the *input signature*,
- 200 ■ $\Sigma_2 = (C_2, \{o_2\}, \tau_2)$ is a first-order tree signature, the *output signature*,
- 201 ■ $\Sigma_Q = (Q, \{o_1, o_2\}, \tau_s)$ is the *state signature*, and is such that for every $q \in Q$, $\tau_s(q)$ is of
202 the form $o_1 \rightarrow A_q$ where A_q is in $\text{types}(\Sigma_2)$. Constants of Q are called *states*,
- 203 ■ $q_0 \in Q$ is the *initial state*,
- 204 ■ \mathbf{A} is a BOT over the tree signature Σ_1 , the *look-ahead* automaton, with set of states P ,
- 205 ■ R is a finite set of rules of the form
206 $q(a \vec{x}) \langle \vec{p} \rangle \rightarrow M(q_1 x_1) \dots (q_n x_n)$
207 where:
208
 - 209 ■ $q, q_1, \dots, q_n \in Q$ are states of Σ_Q ,
 - 210 ■ a is a constant of Σ_1 with type $o_1^n \rightarrow o_1$,
 - 211 ■ $\vec{x} = x_1, \dots, x_n$ are variables of type o_1 , they are the child trees of the root labeled a ,
 - 212 ■ $\vec{p} = p_1, \dots, p_n$ are in P (the set of states of the look-ahead \mathbf{A}),
 - 213 ■ M is a linear term of type $A_{q_1} \rightarrow \dots \rightarrow A_{q_n} \rightarrow A_q$ built on signature $\Sigma_2 + \Sigma_Q$.
 - 214 ■ there is one rule per possible left-hand side (determinism).

215 Notice that we have given states a type of the form $o_1 \rightarrow A$ where $A \in \text{types}(o_2)$. The
216 reason why we do this is to have a uniform notation. Indeed, a state q is meant to transform,
217 thanks to the rules in R , a tree built in Σ_1 into a λ -term built on Σ_2 with type A_q . So
218 we simply write $q M N_1 \dots N_n$ when we want to transform M with the state q and pass
219 N_1, \dots, N_n as arguments to the result of the transformation. We write Σ_T for the signature
220 $\Sigma_1 + \Sigma_2 + \Sigma_Q$. Notice also that the right-hand part of a rule is a term that is built only
221 with constants of Σ_2 , states from Σ_Q and variables of type o_1 . Thus, in order for this
222 term to have a type in $\text{types}(\Sigma_2)$, it is necessary that the variables of type o_1 only occur as

223 the first argument of a state in Σ_Q . Finally, remark that we did not put any requirement
 224 on the type of the initial state. So as to restrict our attention to transducers as they are
 225 usually understood, it suffices to add the requirement that the initial state is of type $o_1 \rightarrow o_2$.
 226 However, we consider as well that transducers may produce *programs* instead of first order
 227 terms.

228 The linearity constraint on M affects both bound variables and the free variables
 229 x_1, \dots, x_n , meaning that all of the subtrees x_1, \dots, x_n are used in computing the out-
 230 put. That will be important for the composition of two transducers because if the first
 231 transducer fails in a branch of its input tree then the second transducer, applied to that tree,
 232 must fail too. This restriction forcing the use of input subtrees does not reduce the model's
 233 expressivity because we can always add a state q which visits the subtree but only produces
 234 the identity function on type o_2 (this state then has type $A_q = o_1 \rightarrow o_2 \rightarrow o_2$).

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 236 (HODTR_{al}) are defined similarly, with the distinction that a term M appearing as a right-
 237 hand side of a rule should be almost linear.

238 As we are concerned with the size of the composition of transducers, we wish to re-
 239 lax a bit the notion of HODTR_{lin}. Indeed, when composing HODTR_{lin} we may have to
 240 determinize the look-ahead so as to obtain a HODTR_{lin}, which may cause an exponen-
 241 tial blow-up of the look-ahead. However if we keep the look-ahead non-deterministic, the
 242 transducer stays deterministic in the weaker sense that only one rule of the transducer
 243 can apply when it is actually run. For this we adopt a slightly relaxed notion of determ-
 244 inistic transducer that we call high-order weakly deterministic top-down transducer with
 245 regular look-ahead (HOWDTR_{lin}). They are similar to HODTR_{lin} but they can have *non-*
 246 *deterministic automata* as look-ahead with the proviso that when $q(a x_1 \dots x_n) \langle p_1, \dots, p_n \rangle \rightarrow$
 247 $M[x_1, \dots, x_n]$ and $q(a x_1 \dots x_n) \langle p'_1, \dots, p'_n \rangle \rightarrow M'[x_1, \dots, x_n]$ are two distinct rules of the
 248 transducer then it must be the case that for some i there is no tree that is recognized by
 249 both p_i and p'_i . This property guarantees that when transforming a term at most one rule
 250 can apply for every possible state. Notice that it suffices to determinize the look-ahead so as
 251 to obtain a HODTR_{lin} from a HOWDTR_{lin}, and therefore the two models are equivalent.

252 Given a HODTR_{lin}, a HODTR_{al} or a HOWDTR_{lin} T , we write $T :: \Sigma_1 \longrightarrow \Sigma_2$ to mean
 253 that the input signature of T is Σ_1 and its output signature is Σ_2 .

254 A transducer T induces a notion of reduction on terms. A T -redex is a term of the form
 255 $q(a M_1 \dots M_n)$ if and only if $q(a x_1 \dots x_n) \langle p_1, \dots, p_n \rangle \rightarrow M[x_1, \dots, x_n]$ is a rule of T and
 256 (the β -normal forms of) M_1, \dots, M_n are respectively accepted by \mathbf{A} with the states p_1, \dots, p_n .
 257 In that case, a T -contractum of $q(a M_1 \dots M_n)$ is $M[M_1, \dots, M_n]$. Notice that T -contracta
 258 are typed terms and that they have the same type as their corresponding T -redices. The
 259 relation of T -contraction relates a term M and a term M' when M' is obtained from M
 260 by replacing one of its T -redex with a corresponding T -contractum. We write $M \rightarrow_T M'$
 261 when M T -contracts to M' . The relation of β -reduction is confluent, and so is the relation
 262 of T -reduction as transducers are deterministic, moreover, the union of the two relations is
 263 terminating. It is not hard to prove that it is also locally confluent and thus confluent. It
 264 follows that $\rightarrow_{\beta, T}$ (which is the union of \rightarrow_{β} and \rightarrow_T) is confluent and strongly normalizing.
 265 Given a term M built on Σ_T , we write $|M|_T$ to denote its normal form modulo $=_{\beta, T}$.

266 Then we write $\text{rel}(T)$ for the relation:

$$267 \{(M, |q_0 M|_T) \mid M \text{ is a closed term of type } o_1 \text{ and } |q_0 M|_T \in \Lambda(\Sigma_2)\}.$$

268 Notice that when $|q_0 M|_T$ contains some states of T , as it is usual, the pair $(M, |q_0 M|_T)$
 269 is not in the relation.

270 Given a finite set of trees L_1 on Σ_1 and L_2 included in $\Lambda^{A_{q_0}}$, we respectively write $T(L_1)$
 271 and $T^{-1}(L_2)$ for the image of L_1 by T and the inverse image of L_2 by T .

272 We give an example of a $\text{HODTR}_{\text{lin}} T$ that computes the result of additions of numeric
 273 expressions (numbers being represented in unary notation). For this we use an input tree
 274 signature with type o_1 , and constants Z^{o_1} , S^{o_1} and $\text{add}^{o_1 \rightarrow o_1 \rightarrow o_1}$ which respectively denote
 275 zero, the successor function and addition. The output signature is similar but different to
 276 avoid confusion: it uses the type o_2 and constants O^{o_2} , $N^{o_2 \rightarrow o_2}$ which respectively denote
 277 zero and successor.

278 We do not really need the look-ahead automaton for this computation, so we omit it for
 279 this example. We could have a blank look-ahead automaton A with one state l and rules:
 280 $A(Z) = l$, $A(Sl) = l$, $A(\text{add } ll) = l$; which would not change the result of the transducer.

281 The transducer has two states: q_0 of type $o_1 \rightarrow o_2$ (the initial state), and q_i of type
 282 $o_1 \rightarrow o_2 \rightarrow o_2$. The rules of the transducer are the following:

283 ■ $q_0(Z) \rightarrow O$, $q_0(Sx) \rightarrow N(q_i x O)$,

284 ■ $q_0(\text{add } xy) \rightarrow q_i x (q_i y O)$,

285 ■ $q_i(Z) \rightarrow \lambda x.x$,

286 ■ $q_i(Sx) \rightarrow \lambda y.N(q_i x y)$,

287 ■ $q_i(\text{add } xy) \rightarrow \lambda z.q_i x (q_i y z)$,

288 As an example, we perform the transduction of the following term $\text{add}(S(SZ))(S(S(SZ)))$:

$$\begin{aligned} & q_0(\text{add}(S(SZ))(S(S(SZ)))) \rightarrow_T (q_i(S(SZ)))(q_i(S(S(SZ)))O) \\ 289 & \xrightarrow{*}_T (\lambda y_1.N((\lambda y_2.N((\lambda x.x)y_2))y_1))((\lambda y_3.N((\lambda y_4.N((\lambda y_5.N((\lambda x.x)y_5))y_4))y_3))O) \\ & \xrightarrow{*}_{\beta} N(N(N(N(O)))) \end{aligned}$$

290 The state q_i transforms a sequence of n symbols S into a λ -term of the form $\lambda x.N^n(x)$,
 291 and the *add* maps both its children into such terms and composes them. The state q_0 simply
 292 applies O to the resulting term.

293 Note that our reduction strategy here has consisted in first computing the T -redices
 294 and then reducing the β -redices. This makes the computation simpler to present. As we
 295 mentioned above a head-reduction strategy would lead to the same result.

296 The order of the $\text{HODTR}_{\text{lin}} T$ is $\max\{\text{order}(A_q) \mid q \in Q\}$. Before going further, we want
 297 to discuss how our framework relates to other transduction models. More specifically how
 298 the notion of order of transformations generalizes the DTOP and MTT transduction models:
 299 if we relax the constraint of linearity of our transducers, then DTOP and MTT can be
 300 seen as non-linear transducers of order 0 and 1 respectively. In contrast of these, we chose
 301 to study the constraint of linearity instead of the constraint of order and, in this paper,
 302 we will explore the benefits of this approach. Firstly we will explain why increasing the
 303 order beyond order 3 does not increase the expressivity of neither $\text{HODTR}_{\text{lin}}$ nor HODTR_{al} .
 304 Next we will show how $\text{HODTR}_{\text{lin}}$ and $\text{HOWDTR}_{\text{lin}}$ both capture the expressivity of tree
 305 transformations defined by monadic second order logic. Lastly, we will prove that, contrary
 306 to MTT, the class of $\text{HODTR}_{\text{lin}}$ transformations is closed under composition, we will give an
 307 algorithm for computing the composition of $\text{HODTR}_{\text{lin}}$ and $\text{HOWDTR}_{\text{lin}}$, and explain why
 308 using $\text{HOWDTR}_{\text{lin}}$ avoids an exponential blow-up in the size of the composition transducer.

309 **3 Order reduction and expressiveness**

310 In this section we outline a construction that transforms a transducer of $\text{HODTR}_{\text{lin}}$ or
 311 HODTR_{al} into an equivalent linear or almost linear transducer of order ≤ 3 . These two
 312 constructions are similar and central to proving that $\text{HODTR}_{\text{lin}}$ and HODTR_{al} are respect-
 313 ively equivalent to Monadic Second Order Transductions from trees to trees (MSOT) and to
 314 Monadic Second Order Transductions from trees to terms (i.e. trees with sharing) (MSOTS).
 315 We will later show that there are translations between $\text{HODTR}_{\text{lin}}$ of order 3 and attribute tree

316 transducers with the *single use restriction* and between HODTR_{al} of order 3 and attribute
 317 tree transducers. These two models are known to be respectively equivalent to MSOT and
 318 MSOTS [2].

319 The central idea in the construction consists in decomposing λ -terms M into pairs $\langle M', \sigma \rangle$
 320 where M' is a pure λ -term and σ is a substitution of variables with the following properties:

- 321 ■ $M =_{\beta} M'.\sigma$,
- 322 ■ the free variables of M' have at most order 1,
- 323 ■ for every variable x , $\sigma(x)$ is a closed λ -term,
- 324 ■ the number of free variables in M' is minimal.

325 In such a decomposition, we call the term M' a *template*. In case M is of type A , linear or
 326 almost linear, it can be proven that M' can be taken from a finite set [14]. The linear case is
 327 rather simple, but the almost linear case requires some precaution as one needs first to put
 328 M in syntactically almost linear form and then make the decomposition. Though the almost
 329 linear case is more technical the finiteness argument is the same in both cases and is based
 330 on proof theoretical arguments in multiplicative linear logic which involves polarities in a
 331 straightforward way.

332 The linear case conveys the intuition of decompositions in a clear manner. One takes
 333 the normal form of M and then delineates the largest contexts of M , i.e. first order terms
 334 that are made only with constants and that are as large as possible. These contexts are
 335 then replaced by variables and the substitution σ is built accordingly. The fact that the
 336 contexts are chosen as large as possible makes it so that no introduced variable can have
 337 as argument a term of the form $x M_1 \dots M_n$ where x is another variable introduced in the
 338 process. Therefore, the new variables introduced in the process bring one negative atom
 339 and several (possibly 0) positive ones and all of them need to be matched with positive and
 340 negative atoms in the type of M as, under these conditions, they cannot be matched together.
 341 This explains why there are only finitely many possible templates for a fixed type.

342 ► **Theorem 1.** *For all type A built on tree signature Σ , the set of templates of closed linear*
 343 *(or almost linear) terms of type A is finite.*

344 Moreover, the templates associated with a λ -term can be computed compositionally (i.e.
 345 from the templates of its parts). As a result, templates can be computed by the look-ahead
 346 of $\text{HODTR}_{\text{lin}}$ or of HODTR_{al} . When reducing the order, we enrich the look-ahead with
 347 template information while the substitution that is needed to reconstruct the produced term
 348 is outputted by the new transducer. The substitution is then performed by the initial state
 349 used at the root of the input tree which then outputs the same result as the former transducer.
 350 The substitution can be seen as a tuple of order 1 terms. It is represented as a tuple using
 351 Church encoding, i.e. a continuation. This makes the transducer we construct be of order 3.

352 ► **Theorem 2.** *Any $\text{HODTR}_{\text{lin}}$ (resp. HODTR_{al}) has an equivalent $\text{HODTR}_{\text{lin}}$ (resp.*
 353 *HODTR_{al}) of order 3.*

354 The proof of this result shows that every $\text{HODTR}_{\text{lin}}$ (or HODTR_{al}) can be seen as mapping
 355 trees to tuples of contexts and combining these contexts in a linear (resp. almost linear)
 356 way. This understanding of $\text{HODTR}_{\text{lin}}$ and of HODTR_{al} allows us to prove that they are
 357 respectively equivalent to Attribute Tree Transducers with Single Use Restriction (ATT_{sur});
 358 and to Attribute Tree Transducers (ATT). Then, using [2], we can conclude with the following
 359 expressivity result:

360 ► **Theorem 3.** *$\text{HODTR}_{\text{lin}}$ are equivalent to MSOT and HODTR_{al} are equivalent to MSOTS.*

361 The full proofs of these are rather technical and are not detailed here, but they appear
 362 in the full version of the article. The proof that $\text{HODTR}_{\text{lin}}$ are equivalent to MSOT could
 363 have been simpler by using the equivalence with MTT with the *single-use restricted* property
 364 instead of ATT, but we would still need to use ATT to show that HODTR_{al} are equivalent
 365 to MSOTS.

366 4 Composition of $\text{HODTR}_{\text{lin}}$

367 As we are interested in limiting the size of the transducer that is computed, and even though
 368 our primary goal is to compose $\text{HODTR}_{\text{lin}}$, this section is devoted to the composition of
 369 $\text{HOWDTR}_{\text{lin}}$. Indeed, working with non-deterministic look-aheads allows us to save the
 370 possibly exponential cost of determinizing an automaton.

371 4.1 Semantic analysis

372 Let $T_1 = (\Sigma_Q, \Sigma_1, \Sigma_2, q_0, R_1, \mathbf{A}_1)$ and $T_2 = (\Sigma_P, \Sigma_2, \Sigma_3, p_0, R_2, \mathbf{A}_2)$ be two Linear High-Order
 373 Weakly Deterministic tree Transducers with Regular look-ahead. The rules of T_1 can be
 374 written: $q(a \vec{x}) \langle \vec{\ell} \rangle \rightarrow M(q_1 x_1) \dots (q_n x_n)$ where $q, q_1, \dots, q_n \in Q$ are states of T_1 ,
 375 $\vec{\ell} = \ell_1, \dots, \ell_n$ are states of \mathbf{A}_1 and the λ -term M is of type $A_{q_1} \rightarrow \dots \rightarrow A_{q_n} \rightarrow A_q$. Our
 376 goal is to build a $\text{HOWDTR}_{\text{lin}} T :: \Sigma_1 \rightarrow \Sigma_3$ that does the composition of T_1 and T_2 , so we
 377 want to replace a rule such as that one with a new rule which corresponds to applying T_2 to
 378 the term M .

379 In order to do so, we need, for each o_2 tree in M , to know the associated state $\ell \in L_2$
 380 of T_2 's look-ahead, and the state $p \in P$ of T_2 which is going to process that node. So
 381 with any such tree we associate the pair (p, ℓ) . In this case we call (p, ℓ) the *token* which
 382 represents the behavior of the tree. In general, we want to associate *tokens* not only with
 383 trees, but also with λ -terms of higher order. For example, we map an occurrence of a symbol
 384 $a \in \Sigma_2$ of type $o_2 \rightarrow o_2 \rightarrow o_2$, whose arguments x_1 and x_2 (of type o_2) respectively have
 385 look-ahead states ℓ_1 and ℓ_2 and are processed by states p_1 and $p_2 \in P$ of T_2 , to the *token*
 386 $(p_1, \ell_1) \multimap (p_2, \ell_2) \multimap (p, \ell)$ where (p, ℓ) is the token of the tree $a x_1 x_2$ (of type o_2). We
 387 formally define *tokens* as follows:

388 ► **Definition 4.** *The set of semantic tokens $\llbracket A \rrbracket$ over a type A built on atomic type o_2 is*
 389 *defined by induction:*

$$390 \quad \llbracket o_2 \rrbracket = \{(p, \ell) \mid p \in P, \ell \in L_2\} \quad \llbracket A \rightarrow B \rrbracket = \{f \multimap g \mid f \in \llbracket A \rrbracket, g \in \llbracket B \rrbracket\}$$

391 Naturally, the semantic token associated with a λ -term M of type A built on atomic type
 392 o_2 will depend on the context where the term M appears. For example a tree of atomic type
 393 o_2 can be processed by any state $p \in P$ of T_2 , and a term of type $A \rightarrow B$ can be applied to
 394 any argument of type A . But for any such M taken out of context, there exists a finite set
 395 of possible tokens for it. For example, a given tree of type o_2 can be processed by any state
 396 $p \in P$ depending on the context, but it has always the same look-ahead $\ell \in L_2$.

397 In order to define the set of possible semantic tokens for a term, we use a system of
 398 derivation rules. The following derivation rules are used to derive judgments that associate
 399 a term with a semantic token. So a judgment $\Gamma \vdash M : f$ associates term M with token f ,
 400 where Γ is a substitution which maps free variables in M to tokens. The rules are:

$$401 \quad \frac{p(a \vec{x}) \langle \ell_1, \dots, \ell_n \rangle \xrightarrow{T_2} M(p_1 x_1) \dots (p_n x_n) \quad \mathbf{A}_2(a(\ell_1, \dots, \ell_n)) = \ell}{\vdash a : (p_1, \ell_1) \multimap \dots \multimap (p_n, \ell_n) \multimap (p, \ell)}$$

402

$$403 \quad \frac{\Gamma_1 \vdash M : f \multimap g \quad \Gamma_2 \vdash N : f}{\Gamma_1, \Gamma_2 \vdash MN : g}$$

$$404 \quad \frac{\Gamma, x^A : f \vdash M : g}{\Gamma \vdash \lambda x^A. M : f \multimap g} \quad \frac{f \in \llbracket A \rrbracket}{x^A : f \vdash x^A : f}$$

406 Using this system we can derive, for any term M^A , all the semantic tokens that correspond
407 to possible behaviours of M^A when it is processed by T_2 .

408 4.2 Unicity of derivation for semantic token judgements

409 We will later show that we can compute the image of M from the derivation of the judgement
410 $\vdash M : f$, assuming that f is the token that represents the behaviour of T_2 on M . But before
411 that we need to prove that for a given term M and token f the derivation of the judgement
412 $\vdash M : f$ is unique:

413 ► **Theorem 5.** *For every type A , for every term M of type A and every token $f \in \llbracket A \rrbracket$, there
414 is at most one derivation $\mathcal{D} :: \vdash M : f$.*

415 This theorem relies in part on the fact that tokens form a *coherent space*, as introduced
416 by Girard in [13]. The full proof of this theorem is not detailed here but can be found in the
417 full version of the article on Hal.

418 Now that we have shown that there is only one derivation per judgement $\vdash M : f$, we are
419 going to see how to use that derivation in order to compute the term N that is the image of
420 M by transducer T_2 .

421 4.3 Collapsing of token derivations

422 We define a function (we call it collapsing function) which maps every derivation $\mathcal{D} :: \vdash M : f$
423 to a term $\overline{\mathcal{D}}$ which corresponds to the output of transducer T_2 on term M assuming that M
424 has behaviour f .

425 ► **Definition 6.** *Let \mathcal{D} be a derivation. We define $\overline{\mathcal{D}}$ by induction on \mathcal{D} , there are different
426 cases depending on the first rule of \mathcal{D} :*

427 *If \mathcal{D} is of the form:*

$$428 \quad \frac{p(a \vec{x}) \langle \ell_1, \dots, \ell_n \rangle \xrightarrow{T_2} N(p_1 x_1) \dots (p_n x_n) \quad \mathbf{A}_2(a(\ell_1, \dots, \ell_n)) = \ell}{\vdash a : (p_1, \ell_1) \multimap \dots \multimap (p_n, \ell_n) \multimap (p, \ell)}$$

429 *then $\overline{\mathcal{D}} = N$,*

430 *if \mathcal{D} is of the form:*

$$431 \quad \frac{\mathcal{D}_1 :: \Gamma_1 \vdash N_1 : f \multimap g \quad \mathcal{D}_2 :: \Gamma_2 \vdash N_2 : f}{\Gamma_1, \Gamma_2 \vdash N_1 N_2 : g}$$

432 *then $\overline{\mathcal{D}} = \overline{\mathcal{D}_1} \overline{\mathcal{D}_2}$,*

433 *if \mathcal{D} is of the form:*

$$434 \quad \frac{\mathcal{D}_1 :: \Gamma, x^A : f \vdash N : g}{\Gamma \vdash \lambda x^A. N : f \multimap g}$$

435 *then $\overline{\mathcal{D}} = \lambda x. \overline{\mathcal{D}_1}$,*

436 if \mathcal{D} is of the form:

$$437 \frac{f \in \llbracket A \rrbracket}{x^A : f \vdash x^A : f}$$

438 then $\overline{\mathcal{D}} = x^{\overline{f}}$.

439 We can check that, for all derivation $\mathcal{D} :: \vdash M : f$, the term $\overline{\mathcal{D}}$ is of type \overline{f} given by:
440 $(\overline{p}, \overline{\ell}) = A_p$ and $\overline{f} \multimap g = \overline{f} \rightarrow \overline{g}$.

441 Now that we have associated, with any pair (M, f) such that f is a semantic token of
442 term M , a term $N = \overline{\mathcal{D}}$ which represents the image of M by T_2 , we need to show that
443 replacing M with N in the computation of transducers leads to the same results.

444 4.4 Construction of the transducer which realizes the composition

445 We recall some notations: $T_1 = (\Sigma_Q, \Sigma_1, \Sigma_2, q_0, R_1, A_1)$ and $T_2 = (\Sigma_P, \Sigma_2, \Sigma_3, p_0, R_2, A_2)$ are
446 two HOWDTR_{lin}, $Q = \{q_1, \dots, q_m\}$ is the set of states of T_1 and, for every state $q_i \in Q$, we
447 note A_{q_i} the type of $q_i(t)$ when t is a tree of type o_1 . For all type A built on o_2 , the set of
448 tokens of terms of type A is noted $\llbracket A \rrbracket$ and is finite.

449 Previously, we saw how to apply transducer T_2 to terms M of type A built on the
450 atomic type o_2 , so we can apply T_2 to terms which appear on the left side of rules of T_1 :
451 $q(a \overrightarrow{x}) \langle \overline{\ell} \rangle \rightarrow M(q_{i_1} x_1) \dots (q_{i_n} x_n)$. In a rule such as this one, in order to replace term M
452 with term $N = \overline{\mathcal{D}}$ where \mathcal{D} is the unique derivation of the judgement $\vdash M : f$, we need to
453 know which token f properly describes the behaviour of T_2 on M . The computation of that
454 token is done in the look-ahead automaton A of T .

455 We define the set of states of A as: $L = L_1 \times \llbracket A_{q_1} \rrbracket \times \dots \times \llbracket A_{q_m} \rrbracket$

456 With any tree t (of type o_1) we want to associate the look-ahead of T_1 on t and, for each
457 state $q_i \in Q$ of T_1 , a token of $q_i(t)$. The transition function of the look-ahead automaton A
458 is defined by, for all $(\ell_1, f_{1,1}, \dots, f_{1,m}), \dots, (\ell_n, f_{n,1}, \dots, f_{n,m}) \in L$:

$$459 a(\ell_1, f_{1,1}, \dots, f_{1,m}) \dots (\ell_n, f_{n,1}, \dots, f_{n,m}) \xrightarrow{A} (\ell, f_1, \dots, f_m)$$

460 where $a \ell_1 \dots \ell_n \xrightarrow{A} \ell$ and, for all state $q_i \in Q$, f_i is such that in T_1 there exists a rule
461 $q_i(a \overrightarrow{x}) \langle \ell_1, \dots, \ell_n \rangle \xrightarrow{T_1} M(q_{i_1} x_1) \dots (q_{i_n} x_n)$ and a derivation of the judgement $\vdash M : f_{1,i_1} \multimap$
462 $\dots \multimap f_{n,i_n} \multimap f_i$. Note that this look-ahead automaton is non-deterministic in general,
463 but the transducer is weakly deterministic in the sense that, at each step, even if several
464 look-ahead states are possible, only one rule of the transducer can be applied.

465 We define the set of states Q' of transducer T by:

$$466 Q' = \{(q, f) \mid q \in Q, f \in \llbracket A_q \rrbracket\} \cup \{q'_0\}$$

467 Then we define the set R of rules of transducer T as the set of rules of the form:

$$468 (q, f)(a \overrightarrow{x}) \langle (\ell_1, f_{1,1}, \dots, f_{1,m}), \dots \rangle \xrightarrow{T} \overline{\mathcal{D}}((q_{i_1}, f_1) x_1) \dots ((q_{i_n}, f_n) x_n)$$

469 such that there exists in T_1 a rule: $q(a \overrightarrow{x}) \langle \ell_1, \dots \rangle \xrightarrow{T_1} M(q_{i_1} x_1) \dots (q_{i_n} x_n)$ and \mathcal{D} is a
470 derivation of the judgement $\vdash M : f_{1,i_1} \multimap \dots \multimap f_{n,i_n} \multimap f$.

471 Because of Theorem 5 that set of rules is weakly deterministic.

472 To that set R we then add rules for the initial state q'_0 , which simply replicate the rules of
473 states of the form $(q_0, (p_0, \ell))$: for all $a \in \Sigma_1$, all $(\ell_1, f_{1,1}, \dots, f_{1,m}), \dots, (\ell_n, f_{n,1}, \dots, f_{n,m}) \in$
474 L and all rule in R of the form:

$$475 (q_0, (p_0, \ell))(a \overrightarrow{x}) \langle (\ell_1, f_{1,1}, \dots, f_{1,m}), \dots \rangle \xrightarrow{T} M((q_1, f_1) x_1) \dots ((q_n, f_n) x_n)$$

476 where p_0 is the initial state of T_2 and $\ell \in L_2$ is a state of the look-ahead automaton of
477 T_2 , we add the rule :

$$478 q'_0(a \overrightarrow{x}) \langle (\ell_1, f_{1,1}, \dots, f_{1,m}), \dots \rangle \xrightarrow{T} M((q_1, f_1) x_1) \dots ((q_n, f_n) x_n)$$

479 This set R of rules is still weakly deterministic according to Theorem 5.

480 We have thus defined the HOWDTR_{lin} $T = (\Sigma_{Q'}, \Sigma_1, \Sigma_3, q'_0, R, A)$.

481 ► **Theorem 7.** $T = T_2 \circ T_1$

482 Finally, we will analyze the complexity of this algorithm and show that using the
483 algorithm on HOWDTR_{lin} instead of HODTR_{lin} avoids an exponential blow-up of the size
484 of the produced transducer.

485 First the set of states Q' of T is of size $|Q'| = 1 + \sum_{q \in Q} \llbracket A_q \rrbracket$ where $\llbracket A_q \rrbracket$ is the number
486 of tokens of type A_q . $\llbracket A_q \rrbracket = (|P| |L_2|)^{|A_q|}$ where $|P|$ is the number of states of transducer
487 T_2 , $|L_2|$ is the number of states of the look-ahead automaton of transducer T_2 and $|A_q|$ is
488 the size of the type A_q . So the size of Q' is $O(\sum_{q \in Q} (|P| |L_2|)^{|A_q|})$, that is a polynomial in
489 the size of T_2 to the power of the size of types of states of T_1 .

490 It is important to note that the set $\llbracket A_q \rrbracket$ of tokens of type A_q is where HOWDTR_{lin} and
491 HODTR_{lin} differ in their complexity: the deterministic alternative to the weakly deterministic
492 T would require to store with the state not a single token, but a set of two-by-two coherent
493 tokens, that would bring the size of Q' to $1 + \sum_{q \in Q} 2^{\llbracket A_q \rrbracket}$ which would be exponential in the
494 size of T_2 and doubly exponential in the size of types of T_1 .

495 Then there is the look-ahead automaton: its set of states is $L = L_1 \times \llbracket A_{q_1} \rrbracket \times \dots \times \llbracket A_{q_m} \rrbracket$.
496 So the number of states is in $O(|L_1| (|P| |L_2|)^{\sum_{q \in Q} |A_q|})$. The size of the set of rules of the
497 look-ahead automaton is in $O(\sum_{a^{(n)} \in \Sigma_1} |L|^{n+1})$ where n is the arity of the constant $a^{(n)}$.

498 Finally there is the set R of rules of T . For every judgement $\vdash M : f_{1,i_1} \multimap \dots \multimap f_{n,i_n} \multimap$
499 f , finding a derivation \mathcal{D} of that judgement and computing the corresponding $\overline{\mathcal{D}}$ is in $O(|M|^2)$
500 time where $|M|$ is the size of M . The number of possible rules is in $O(\sum_{a^{(n)} \in \Sigma_1} (|Q'|)^{n+1})$.
501 So computing R is done in time $O(|R|^2 \sum_{a^{(n)} \in \Sigma_1} (|Q'|)^{n+1})$ where R is the set of rules of T_1 .
502 With a fixed input signature Σ_1 , the time complexity of the algorithm computing T is a
503 polynomial in the sizes of T_1 and T_2 , with only the sizes of types of states of T_1 as exponents.

504 Note that, as our model generalizes other classes of transducers, it is possible to perform
505 their composition in our setting. Thanks to results of Theorem 2, it is then possible to reduce
506 the order of the result of the composition, and obtain a HODTR_{lin} that can be converted
507 back in those other models. This methods gives an important insight on the composition
508 procedure for those other formalisms.

509 In comparison, the composition algorithms for equivalent classes of transductions are
510 either not direct or very complex as they essentially perform composition and order reduction
511 at once. For instance, composition of single used restricted MTT is obtained through MSO
512 ([11]). High-level tree transducers [12] go through a reduction to iterated pushdown tree
513 transducers and back. The composition algorithm for Streaming Tree Transducers described
514 in [1] is direct, but made complex by the fact that the algorithm hides this reduction of order.

515 The double-exponential complexity of composition of HODTR_{lin} compares well to the
516 non-elementary complexity of composition in equivalent non-MSOT classes of transducers.
517 Although the simple exponential complexity of composition in MSOT is better, we should
518 account for the fact that the MSOT model does not attempt to represent the behavior of
519 programs.

520 **5 Conclusion and future work**

521 In this paper we have presented a new mechanical characterization of Monadic Second Order
522 Transductions. This characterization is based on simply typed λ -calculus which allows us to
523 generalize with very few primitives most of the mechanisms used to compute the output in
524 the transducer literature. The use of higher-order allows us to propose an arguably simple
525 algorithm for computing the composition of linear higher-order transducers which coincide
526 with MSOT. The correctness of this algorithm is based on denotation semantics (coherence

spaces) of λ -calculus and the heart of the proof uses logical relations. Thus, the use of λ -calculus allows us to base our work on standard tools and techniques rather than developing our own tools as is often the case when dealing with transducers. Moreover, this work sheds some light on how composition is computed in other formalisms. Indeed, we argue that for MTT_{sur} , STT, or ARR_{sur} , the composition must be the application of our composition algorithm followed by the order reduction procedure that we use to prove the equivalence with logical transductions.

The notion of higher-order transducer has already been studied [12, 18, 16], however, there is still some work to be done to obtain direct composition algorithms. We plan to generalize our approach of the linear case to the general one and devise a semantic based partial evaluation for the composition of higher-order transducers.

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