# Linear high-order deterministic tree transducers with regular look-ahead 

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## 1 Introduction

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# Linear High-Order Deterministic Tree transducers with Regular look-ahead 


#### Abstract

_ Abstract We introduce the notion of high-order deterministic top-down tree transducers (HODT) whose outputs correspond to single-typed lambda-calculus formulas. These transducers are natural generalizations of known models of top-tree transducers such as: Deterministic Top-Down Tree Transducers, Macro Tree Transducers, Streaming Tree Transducers... We focus on the linear restriction of high order tree transducers with look-ahead $\left(\mathrm{HODTR}_{\text {lin }}\right)$, and prove this corresponds to tree to tree functional transformations defined by Monadic Second Order (MSO) logic. We give a specialized procedure for the composition of those transducers that uses a flow analysis based on coherence spaces and allows us to preserve the linearity of transducers. This procedure has a better complexity than classical algorithms for composition of other equivalent tree transducers, but raises the order of transducers. However, we also indicate that the order of a HODTR $_{\text {lin }}$ can always be bounded by 3 , and give a procedure that reduces the order of a $\operatorname{HODTR}_{\text {lin }}$ to 3 . As those resulting $\mathrm{HODTR}_{\text {lin }}$ can then be transformed into other equivalent models, this gives an important insight on composition algorithm for other classes of transducers. Finally, we prove that those results partially translate to the case of almost linear HODTR: the class corresponds to the class of tree transformations performed by MSO with unfolding (not closed by composition), and provide a mechanism to reduce the order to 3 in this case.


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Tree Transducers formalize transformations of structured data such as Abstract Syntax Trees, XML, JSON, or even file systems. They are based on various mechanisms that traverse tree structures while computing an output: Top-Down and Bottom-Up tree transducers [18, 4] which are direct generalizations of deterministic word transducers [8, 7, 3], but also more complex models such as macro tree transducers [11] (MTT) or streaming tree transducers [1]

Logic offers another, more descriptive, view on tree transformations. In particular, Monadic Second Order (MSO) logic defines a class of tree transformations (MSOT) [5, 6] which

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## 34:2 Linear High-Order Deterministic Tree transducers with Regular look-ahead

is expressive and is closed under composition. It coincides with the class of transformations definable with MTT enhanced with a regular look-ahead and restricted to finite copying [9, 10], and also with the class of STT [1].

We argue here that simply typed $\lambda$-calculus gives a uniform generalisation of all these different models. Indeed, they can all be considered as classes of programs that read input tree structures, and, at each step, compose tree operations which in the end produce the final output. Each of these tree operations can be represented using simply typed $\lambda$-terms.

In this paper, we define top-down tree transducers that follow the usual definitions of such machines, except that rules can produce $\lambda$-terms of arbitrary types. We call these machines, High-Order Top-down tree transducers, or High-Order Deterministic Tree Transducers (HODT) in the deterministic case. This class of transducers naturally contains top-down tree transducers, as they are HODT of order 0 (the output of rules are trees), but also MTT, which are HODT of order 1 (outputs are tree contexts). They also contain STT, which can be translated directly into HODT of order 3 with some restricted continuations. Also, STT traverse their input tree represented as a string in a leftmost traversal (a stream). This constraint could easily be adapted to our model but would yield technical complications that are not the focus of this paper. Finally, our model generalizes High Level Tree Transducers defined in [12], which also produce $\lambda$-term, but restricted to the safe $\lambda$-calculus case.

In this paper we focus on the linear and almost linear restrictions of HODT. In terms of expressiveness, linear HODTR ( HODTR $_{\text {lin }}$ ) corresponds to the class of MSOT. This links our formalism to other equivalent classes of transducers, such as finite-copying macro-tree transducers $[9,10]$, with an important difference: the linearity restriction is a simple syntactic restriction, whereas finite-copying or the equivalent single-use-restricted condition are both global conditions that are harder to enforce. For STT, the linearity condition corresponds to the copyless condition described in [1] and where the authors prove that any STT can be made copyless.

The relationship of $\operatorname{HODTR}_{\text {lin }}$ to MSOT is made via a transformation that reduces the order of transducers. We indeed prove that for any $\operatorname{HODTR}_{\text {lin }}$, there exists an equivalent $\operatorname{HODTR}_{\text {lin }}$ whose order is at most 3. This transformation allows us to prove then that HODTR $_{\text {lin }}$ are equivalent to Attribute Tree Transducers with the single use restriction $\left(\mathrm{ATT}_{\text {sur }}\right)$. In turn, this shows that HODTR ${ }_{\text {lin }}$ are equivalent to MSOT [2].

One of the main interests of $\operatorname{HODTR}_{\text {lin }}$ is that $\lambda$-calculus also offers a simple composition algorithm. This approach gives an efficient procedure for composing two $H_{O D T R}^{\text {lin }}$. In general, this procedure raises the order of the produced transducer. In comparison, composition in other equivalent classes are either complex or indirect (through MSOT). In any case, our procedure has a better complexity. Indeed, it benefits from higher-order which permits a larger number of implementations for a given transduction. The complexity of the construction is also lowered by the use of a notion of determinism slightly more liberal than usual that we call weak determinism.

The last two results allow us to obtain a composition algorithm for other equivalent classes of tree transducer, such as MTT or STT: compile into HODTR $_{\text {lin }}$, compose, reduce the order, and compile back into the original model. The advantage of this approach over the existing ones is that the complex composition procedure is decomposed into two simpler steps (the back and forth translations between the formalisms are unsurprising technical procedures). We believe in fact that existing approaches $[12,1]$ combine in one step the two elements, which is what makes them more complex.

The property of order reduction also applies to a wider class of HODT, almost linear HODT (HODTR ${ }_{\text {al }}$ ). Again here, this transformation allows us to prove that this class of
${ }_{134}-x^{A}$ is in $\Lambda^{A}(\Sigma)$,

## 2 Definitions

## $2.1 \lambda$-calculus

tree transformations is equivalent to that of Attribute Tree Transducers which is known to be equivalent to MSO tree transformations with unfolding [2], i.e. MSO tree transduction that produce Directed Acyclic Graphs (i.e. trees with shared sub-trees) that are unfolded to produce a resulting tree. We call these transductions Monadic Second Order Transductions with Sharing (MSOTS). Note however that HODTR ${ }_{\text {al }}$ are not closed under composition.

Section 2 presents the technical definitions used throughout the paper. In particular, it gives the definitions of the various notions of transducers studied in the paper and also the notion of weak determinism. Section 3 studies the expressivity of linear and almost linear higher-order transducer by relating them to MSOT and MSOTS. It focuses more specifically on the order reduction procedure that is at the core of the technical work. Section 4 presents the composition algorithm for linear higher-order transducers. This algorithm is based on Girard's coherence spaces and can be interpreted as a form of partial evaluation for linear higher-order programs. Finally we conclude.

This section presents the main formalisms we are going to use throughout the paper, namely simply typed $\lambda$-calculus, finite state automata and high-order transducers.

Fix a finite set of atomic types $\mathcal{A}$, we then define the set of types over $\mathcal{A}$, types $(\mathcal{A})$, as the types that are either an atomic type, i.e. an element of $\mathcal{A}$, or a functional type $(A \rightarrow B)$, with $A$ and $B$ being in types $(\mathcal{A})$. The operator $\rightarrow$ is right-associative and $A_{1} \rightarrow \cdots \rightarrow A_{n} \rightarrow B$ denotes the type $\left(A_{1} \rightarrow\left(\cdots \rightarrow\left(A_{n} \rightarrow B\right) \cdots\right)\right)$. The order of a type $A$ is inductively defined by $\operatorname{order}(A)=0$ when $A \in \mathcal{A}$, and $\operatorname{order}(A \rightarrow B)=\max (\operatorname{order}(A)+1, \operatorname{order}(B))$.

A signature $\Sigma$ is a triple $(C, \mathcal{A}, \tau)$ with $C$ being a finite set of constants, $\mathcal{A}$ a finite set of atomic types, and $\tau$ a mapping from $C$ to types $(\mathcal{A})$, the typing function.

We allow ourselves to write $\operatorname{types}(\Sigma)$ to refer to the set types $(\mathcal{A})$. The order of a signature is the maximal order of a type assigned to a constant (i.e. $\max \{\operatorname{order}(\tau(c)) \mid c \in C\}$ ). In this work, we mostly deal with tree signatures which are of order 1 and whose set of atomic types is a singleton. In such a signature with atomic type $o$, the types of constants are of the form $o \rightarrow \cdots \rightarrow o \rightarrow o$. We write $o^{n} \rightarrow o$ for an order- 1 type which uses $n+1$ occurrences of $o$, for example, $o^{2} \rightarrow o$ denotes $o \rightarrow o \rightarrow o$. When $c$ is a constant of type $A$, we may write $c^{A}$ to make explicit that $c$ has type $A$. Two signatures $\Sigma_{1}=\left(C_{1}, \mathcal{A}_{1}, \tau_{1}\right)$ and $\Sigma_{2}=\left(C_{2}, \mathcal{A}_{2}, \tau_{2}\right)$ so that for every $c$ in $C_{1} \cap C_{2}$ we have $\tau_{1}(c)=\tau_{2}(c)$ can be summed, and we write $\Sigma_{1}+\Sigma_{2}$ for the signature $\left(C_{1} \cup C_{2}, \mathcal{A}_{1} \cup \mathcal{A}_{2}, \tau\right)$ so that if $c$ is in $C_{1}, \tau(c)=\tau_{1}(c)$ and if $c$ is in $C_{2}$, $\tau(c)=\tau_{2}(c)$. The sum operation over signatures being associative and commutative, we write $\Sigma_{1}+\cdots+\Sigma_{n}$ to denote the sum of several signatures.

We assume that for every type $A$, there is an infinite countable set of variables of type $A$. When two types are different the set of variables of those types are of course disjoint. As with constants, we may write $x^{A}$ to make it clear that $x$ is a variable of type $A$.

When $\Sigma$ is a signature, we define the family of simply typed $\lambda$-terms over $\Sigma$, denoted $\Lambda(\Sigma)=\left(\Lambda^{A}(\Sigma)\right)_{A \in \operatorname{types}(\Sigma)}$, as the smallest family indexed by types $(\Sigma)$ so that:

- if $c^{A}$ is in $\Sigma$, then $c^{A}$ is in $\Lambda^{A}(\Sigma)$,
- if $A=B \rightarrow C$ and $M$ is in $\Lambda^{C}(\Sigma)$, then $\left(\lambda x^{B} . M\right)$ is in $\Lambda^{A}(\Sigma)$,
- if $M$ is in $\Lambda^{B \rightarrow A}(\Sigma)$ and $N$ is in $\Lambda^{B}(\Sigma)$, then $(M N)$ is in $\Lambda^{A}(\Sigma)$.

The term $M$ is a pure $\lambda$-term if it does not contain any constant $c^{A}$ from $\Sigma$. When the type is irrelevant we write $M \in \Lambda(\Sigma)$ instead of $M \in \Lambda^{A}(\Sigma)$. We drop parentheses when it does not bring ambiguity. In particular, we write $\lambda x_{1} \ldots x_{n} . M$ for $\left(\lambda x_{1}\left(\ldots\left(\lambda x_{n} . M\right) \ldots\right)\right.$ ), and $M_{0} M_{1} \ldots M_{n}$ for $\left(\left(\ldots\left(M_{0} M_{1}\right) \ldots\right) M_{n}\right)$.

The set $\operatorname{fv}(M)$ of free variables of a term $M$ is inductively defined on the structure of $M$ :

- $\operatorname{fv}(c)=\emptyset$,
- $\operatorname{fv}(x)=\{x\}$,
- $\mathrm{fv}(M N)=\mathrm{fv}(M) \cup \mathrm{fv}(N)$,
- $\mathrm{fv}(\lambda x . M)=\mathrm{fv}(M)-\{x\}$.

Terms which have no free variables are called closed. We write $M\left[x_{1}, \ldots, x_{k}\right]$ to emphasize that $\mathrm{fv}(M)$ is included in $\left\{x_{1}, \ldots, x_{k}\right\}$. When doing so, we write $M\left[N_{1}, \ldots, N_{k}\right]$ for the capture avoiding substitution of variables $x_{1}, \ldots, x_{k}$ by the terms $N_{1}, \ldots, N_{k}$. In other contexts, we simply use the usual notation $M\left[N_{1} / x_{1}, \ldots, N_{k} / x_{k}\right]$. Moreover given a substitution $\theta$, we write $M . \theta$ for the result of applying this (capture avoiding) substitution and we write $\theta\left[N_{1} / x_{1}, \ldots, N_{k} / x_{k}\right]$ for the substitution that maps the variables $x_{i}$ to the terms $N_{i}$ but is otherwise equal to $\theta$. Of course, we authorize such substitutions only when the $\lambda$-term $N_{i}$ has the same type as the variable $x_{i}$.

We take for granted the notions of $\beta$-contraction, noted $\rightarrow_{\beta}, \beta$-reduction, noted ${ }^{*}{ }_{\beta}$, $\beta$-conversion, noted $={ }_{\beta}$, and $\beta$-normal form for terms.

Consider closed terms of type $o$ that are in $\beta$-normal form and that are built on a tree signature, they can only be of the form $a t_{1} \ldots t_{n}$ where $a$ is a constant of type $o^{n} \rightarrow o$ and $t_{1}, \ldots, t_{n}$ are closed terms of type $o$ in $\beta$-normal form. This is just another notation for ranked trees. So when the type $o$ is meant to represent trees, types of order 1 which have the form $o \rightarrow \cdots \rightarrow o \rightarrow o$ represent functions from trees to trees, or more precisely tree contexts. Types of order 2 are types of trees parametrized by contexts. The notion of order captures the complexity of the operations that terms of a certain type describe.

A term $M$ is said linear if each variable (either bound or free) in $M$ occurs exactly once in $M$. A term $M$ is said syntactically almost linear when each variable in $M$ of non-atomic type occurs exactly once in $M$. Note that, through $\beta$-reduction, linearity is preserved but not syntactic almost linearity.

For example, given a tree signature $\Sigma_{1}$ with one atomic type $o$ and two constants $f$ of type $o^{2} \rightarrow o$ and $a$ of type $o$, the term $M=\left(\lambda y_{1} y_{2} . f y_{1}\left(f a y_{2}\right)\right) a(f x a)$ with free variable $x$ of type $o$ is linear because each variable ( $y_{1}, y_{2}$ and $x$ ) occurs exactly once in $M$. The term $M$ contains a $\beta$-redex so: $\left(\lambda y_{1} y_{2} . f y_{1}\left(f a y_{2}\right)\right) a(f x a) \rightarrow_{\beta}\left(\lambda y_{2} . f a\left(f a y_{2}\right)\right)(f x a) \rightarrow_{\beta} f a(f a(f x a))$. The term $f a(f a(f x a))$ has no $\beta$-redex so it is the $\beta$-normal form of $M$.

Another example: the term $M_{2}=(\lambda y . f y y)(x a)$ with free variable $x$ of type $o \rightarrow o$ is syntactically almost linear because the variable $y$ which occurs twice in the term is of the atomic type $o$. It $\beta$-reduces to the term $M_{2}^{\prime}=f(x a)(x a)$ which is not syntactically almost linear, so $\beta$-reduction does not preserve syntactical almost linearity.

We call a term almost linear when it is $\beta$-convertible to a syntactically almost linear term. Almost linear terms are characterized also by typing properties (see [16]).

### 2.2 Tree Automata

We present here the classical definition of deterministic bottom-up tree automaton (BOT) adapted to our formalism. A BOT A is a tuple $\left(\Sigma_{P}, \Sigma, R\right)$ where:

- $\Sigma=(C,\{o\}, \tau)$ is a first-order tree signature, the input signature,
- $\Sigma_{P}=\left(P,\{o\}, \tau_{P}\right)$ is the state signature, and is such that for every $p \in P, \tau_{P}(p)=o$. Constants of $P$ are called states,
- $R$ is a finite set of rules of the form $a p_{1} \ldots p_{n} \rightarrow p$ where:
- $p, p_{1}, \ldots, p_{n}$ are states of $P$,
- $a$ is a constant of $\Sigma$ with type $o^{n} \rightarrow o$.

An automaton is said deterministic when there is at most one rule in $R$ for each possible left hand side. It is non-deterministic otherwise.

Apart from the notation, our definition differs from the classical one by the fact there are no final states, and hence, the automaton does not describe a language. This is due to the fact that BOT will be used here purely for look-ahead purposes.

### 2.3 High-Order Deterministic top-down tree Transducers

From now on we assume that $\Sigma_{i}$ is a tree signature for every number $i$ and that its atomic type is $o_{i}$.

A Linear High-Order Deterministic top-down Transducer with Regular look-ahead $\left(\operatorname{HODTR}_{\mathrm{lin}}\right) T$ is a tuple $\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R, \mathrm{~A}\right)$ where:

- $\Sigma_{1}=\left(C_{1},\left\{o_{1}\right\}, \tau_{1}\right)$ is a first-order tree signature, the input signature,
- $\Sigma_{2}=\left(C_{2},\left\{o_{2}\right\}, \tau_{2}\right)$ is a first-order tree signature, the output signature,
- $\Sigma_{Q}=\left(Q,\left\{o_{1}, o_{2}\right\}, \tau_{s}\right)$ is the state signature, and is such that for every $q \in Q, \tau_{s}(q)$ is of the form $o_{1} \rightarrow A_{q}$ where $A_{q}$ is in types $\left(\Sigma_{2}\right)$. Constants of $Q$ are called states,
- $q_{0} \in Q$ is the initial state,
- A is a BOT over the tree signature $\Sigma_{1}$, the look-ahead automaton, with set of states $P$,
- $\quad R$ is a finite set of rules of the form

$$
q(a \vec{x})\langle\vec{p}\rangle \rightarrow M\left(q_{1} x_{1}\right) \ldots\left(q_{n} x_{n}\right)
$$

where:
$=q, q_{1}, \ldots, q_{n} \in Q$ are states of $\Sigma_{Q}$,
$=a$ is a constant of $\Sigma_{1}$ with type $o_{1}^{n} \rightarrow o_{1}$,
$=\vec{x}=x_{1}, \ldots, x_{n}$ are variables of type $o_{1}$, they are the child trees of the root labeled $a$,

- $\vec{p}=p_{1}, \ldots, p_{n}$ are in $P$ (the set of states of the look-ahead A),
- $M$ is a linear term of type $A_{q_{1}} \rightarrow \cdots \rightarrow A_{q_{n}} \rightarrow A_{q}$ built on signature $\Sigma_{2}+\Sigma_{Q}$.
- there is one rule per possible left-hand side (determinism).

Notice that we have given states a type of the form $o_{1} \rightarrow A$ where $A \in \operatorname{types}\left(o_{2}\right)$. The reason why we do this is to have a uniform notation. Indeed, a state $q$ is meant to transform, thanks to the rules in $R$, a tree built in $\Sigma_{1}$ into a $\lambda$-term built on $\Sigma_{2}$ with type $A_{q}$. So we simply write $q M N_{1} \ldots N_{n}$ when we want to transform $M$ with the state $q$ and pass $N_{1}, \ldots, N_{n}$ as arguments to the result of the transformation. We write $\Sigma_{T}$ for the signature $\Sigma_{1}+\Sigma_{2}+\Sigma_{Q}$. Notice also that the right-hand part of a rule is a term that is built only with constants of $\Sigma_{2}$, states from $\Sigma_{Q}$ and variables of type $o_{1}$. Thus, in order for this term to have a type in types $\left(\Sigma_{2}\right)$, it is necessary that the variables of type $o_{1}$ only occur as the first argument of a state in $\Sigma_{Q}$. Finally, remark that we did not put any requirement on the type of the initial state. So as to restrict our attention to transducers as they are usually understood, it suffices to add the requirement that the initial state is of type $o_{1} \rightarrow o_{2}$. However, we consider as well that transducers may produce programs instead of first order terms.

The linearity constraint on $M$ affects both bound variables and the free variables $x_{1}, \ldots, x_{n}$, meaning that all of the subtrees $x_{1}, \ldots, x_{n}$ are used in computing the output. That will be important for the composition of two transducers because if the first transducer fails in a branch of its input tree then the second transducer, applied to that tree, must fail too. This restriction forcing the use of input subtrees does not reduce the model's
expressivity because we can always add a state $q$ which visits the subtree but only produces the identity function on type $o_{2}$ (this state then has type $A_{q}=o_{1} \rightarrow o_{2} \rightarrow o_{2}$ ).

Almost linear high-order deterministic top-down transducer with regular look-ahead $\left(\operatorname{HODTR}_{\mathrm{al}}\right)$ are defined similarly, with the distinction that a term $M$ appearing as a righthand side of a rule should be almost linear.

As we are concerned with the size of the composition of transducers, we wish to relax a bit the notion of $\mathrm{HODTR}_{\text {lin }}$. Indeed, when composing $\mathrm{HODTR}_{\text {lin }}$ we may have to determinize the look-ahead so as to obtain a $\operatorname{HODTR}_{\text {lin }}$, which may cause an exponential blow-up of the look-ahead. However if we keep the look-ahead non-deterministic, the transducer stays deterministic in the weaker sense that only one rule of the transducer can apply when it is actually run. For this we adopt a slightly relaxed notion of deterministic transducer that we call high-order weakly deterministic top-down transducer with regular look-ahead (HOWDTR ${ }_{\text {lin }}$ ). They are similar to $\mathrm{HODTR}_{\text {lin }}$ but they can have nondeterministic automata as look-ahead with the proviso that when $q\left(a x_{1} \ldots x_{n}\right)\left\langle p_{1}, \ldots, p_{n}\right\rangle \rightarrow$ $M\left[x_{1}, \ldots, x_{n}\right]$ and $q\left(a x_{1} \ldots x_{n}\right)\left\langle p_{1}^{\prime}, \ldots, p_{n}^{\prime}\right\rangle \rightarrow M^{\prime}\left[x_{1}, \ldots, x_{n}\right]$ are two distinct rules of the transducer then it must be the case that for some $i$ there is no tree that is recognized by both $p_{i}$ and $p_{i}^{\prime}$. This property guarantees that when transforming a term at most one rule can apply for every possible state. Notice that it suffices to determinize the look-ahead so as to obtain a $\mathrm{HODTR}_{\text {lin }}$ from a HOWDTR ${ }_{\text {lin }}$, and therefore the two models are equivalent.
 that the input signature of $T$ is $\Sigma_{1}$ and its output signature is $\Sigma_{2}$.

A transducer $T$ induces a notion of reduction on terms. A $T$-redex is a term of the form $q\left(a M_{1} \ldots M_{n}\right)$ if and only if $q\left(a x_{1} \ldots x_{n}\right)\left\langle p_{1}, \ldots, p_{n}\right\rangle \rightarrow M\left[x_{1}, \ldots, x_{n}\right]$ is a rule of $T$ and (the $\beta$-normal forms of) $M_{1}, \ldots, M_{n}$ are respectively accepted by A with the states $p_{1}, \ldots, p_{n}$. In that case, a $T$-contractum of $q\left(a M_{1} \ldots M_{n}\right)$ is $M\left[M_{1}, \ldots, M_{n}\right]$. Notice that $T$-contracta are typed terms and that they have the same type as their corresponding $T$-redices. The relation of $T$-contraction relates a term $M$ and a term $M^{\prime}$ when $M^{\prime}$ is obtained from $M$ by replacing one of its $T$-redex with a corresponding $T$-contractum. We write $M \rightarrow_{T} M^{\prime}$ when $M T$-contracts to $M^{\prime}$. The relation of $\beta$-reduction is confluent, and so is the relation of $T$-reduction as transducers are deterministic, moreover, the union of the two relations is terminating. It is not hard to prove that it is also locally confluent and thus confluent. It follows that $\rightarrow_{\beta, T}$ (which is the union of $\rightarrow_{\beta}$ and $\rightarrow_{T}$ ) is confluent and strongly normalizing. Given a term $M$ built on $\Sigma_{T}$, we write $|M|_{T}$ to denote its normal form modulo $=_{\beta, T}$.

Then we write $\operatorname{rel}(T)$ for the relation:
$\left\{\left(M,\left|q_{0} M\right|_{T}\right) \mid \mathrm{M}\right.$ is a closed term of type $o_{1}$ and $\left.\left|q_{0} M\right|_{T} \in \Lambda\left(\Sigma_{2}\right)\right\}$.
Notice that when $\left|q_{0} M\right|_{T}$ contains some states of $T$, as it is usual, the pair $\left(M,\left|q_{0} M\right|_{T}\right)$ is not in the relation.

Given a finite set of trees $L_{1}$ on $\Sigma_{1}$ and $L_{2}$ included in $\Lambda^{A_{q_{0}}}$, we respectively write $T\left(L_{1}\right)$ and $T^{-1}\left(L_{2}\right)$ for the image of $L_{1}$ by $T$ and the inverse image of $L_{2}$ by $T$.

We give an example of a $\mathrm{HODTR}_{\text {lin }} T$ that computes the result of additions of numeric expressions (numbers being represented in unary notation). For this we use an input tree signature with type $o_{1}$, and constants $Z^{o_{1}}, S^{o_{1}}$ and $\operatorname{add}^{o_{1} \rightarrow o_{1} \rightarrow o_{1}}$ which respectively denote zero, the successor function and addition. The output signature is similar but different to avoid confusion: it uses the type $o_{2}$ and constants $O^{o_{2}}, N^{o_{2} \rightarrow o_{2}}$ which respectively denote zero and successor.

We do not really need the look-ahead automaton for this computation, so we omit it for this example. We could have a blank look-ahead automaton A with one state $l$ and rules: $\mathrm{A}(Z)=l, \mathrm{~A}(S l)=l, \mathrm{~A}(\operatorname{add} l l)=l$; which would not change the result of the transducer.

The transducer has two states: $q_{0}$ of type $o_{1} \rightarrow o_{2}$ (the initial state), and $q_{i}$ of type $o_{1} \rightarrow o_{2} \rightarrow o_{2}$. The rules of the transducer are the following:

- $q_{0}(Z) \rightarrow O, q_{0}(S x) \rightarrow N\left(q_{i} x O\right)$,
- $q_{0}(\operatorname{add} x y) \rightarrow q_{i} x\left(q_{i} y O\right)$,
- $q_{i}(Z) \rightarrow \lambda x . x$,
- $q_{i}(S x) \rightarrow \lambda y . N\left(q_{i} x y\right)$,
- $q_{i}(\operatorname{add} x y) \rightarrow \lambda z \cdot q_{i} x\left(q_{i} y z\right)$,

As an example, we perform the transduction of the following term $\operatorname{add}(S(S Z))(S(S(S Z)))$ :

$$
\begin{aligned}
& q_{0}(\operatorname{add}(S(S Z))(S(S(S Z)))) \quad \rightarrow_{T} \quad\left(q_{i}(S(S Z))\right)\left(q_{i}(S(S(S Z))) O\right) \\
& \stackrel{*}{\rightarrow}_{T}\left(\lambda y_{1} \cdot N\left(\left(\lambda y_{2} \cdot N\left((\lambda x \cdot x) y_{2}\right)\right) y_{1}\right)\right)\left(\left(\lambda y_{3} \cdot N\left(\left(\lambda y_{4} \cdot N\left(\left(\lambda y_{5} \cdot N\left((\lambda x \cdot x) y_{5}\right)\right) y_{4}\right)\right) y_{3}\right)\right) O\right) \\
& \stackrel{*}{*}_{\beta} N(N(N(N(N O))))
\end{aligned}
$$

The state $q_{i}$ transforms a sequence of $n$ symbols $S$ into a $\lambda$-term of the form $\lambda x . N^{n}(x)$, and the $a d d$ maps both its children into such terms and composes them. The state $q_{0}$ simply applies $O$ to the resulting term.

Note that our reduction strategy here has consisted in first computing the $T$-redices and then reducing the $\beta$-redices. This makes the computation simpler to present. As we mentioned above a head-reduction strategy would lead to the same result.

The order of the $\operatorname{HODTR}_{\text {lin }} T$ is $\max \left\{\operatorname{order}\left(A_{q}\right) \mid q \in Q\right\}$. Before going further, we want to discuss how our framework relates to other transduction models. More specifically how the notion of order of transformations generalizes the DTOP and MTT transduction models: if we relax the constraint of linearity of our transducers, then DTOP and MTT can be seen as non-linear transducers of order 0 and 1 respectively. In contrast of these, we chose to study the constraint of linearity instead of the constraint of order and, in this paper, we will explore the benefits of this approach. Firstly we will explain why increasing the order beyond order 3 does not increase the expressivity of neither $H_{O D T R}^{\text {lin }}$ nor $\operatorname{HODTR}_{\text {al }}$. Next we will show how HODTR $_{\text {lin }}$ and HOWDTR ${ }_{\text {lin }}$ both capture the expressivity of tree transformations defined by monadic second order logic. Lastly, we will prove that, contrary to MTT, the class of $\mathrm{HODTR}_{\text {lin }}$ transformations is closed under composition, we will give an algorithm for computing the composition of $\operatorname{HODTR}_{\text {lin }}$ and $H_{O W D T R}^{\text {lin }}$, and explain why using HOWDTR ${ }_{\text {lin }}$ avoids an exponential blow-up in the size of the composition transducer.

## 3 Order reduction and expressiveness

In this section we outline a construction that transforms a transducer of $\operatorname{HODTR}_{\text {lin }}$ or $\operatorname{HODTR}_{\text {al }}$ into an equivalent linear or almost linear transducer of order $\leq 3$. These two constructions are similar and central to proving that $H_{O D T R}^{\text {lin }}$ and $H_{O D T R}^{a l}$ are respectively equivalent to Monadic Second Order Transductions from trees to trees (MSOT) and to Monadic Second Order Transductions from trees to terms (i.e. trees with sharing) (MSOTS). We will later show that there are translations between $\operatorname{HODTR}_{\text {lin }}$ of order 3 and attribute tree transducers with the single use restriction and between $\mathrm{HODTR}_{\mathrm{al}}$ of order 3 and attribute tree transducers. These two models are known to be respectively equivalent to MSOT and MSOTS [2].

The central idea in the construction consists in decomposing $\lambda$-terms $M$ into pairs $\left\langle M^{\prime}, \sigma\right\rangle$ where $M^{\prime}$ is a pure $\lambda$-term and $\sigma$ is a substitution of variables with the following properties:

- $M={ }_{\beta} M^{\prime} . \sigma$,
- the free variables of $M^{\prime}$ have at most order 1,
- for every variable $x, \sigma(x)$ is a closed $\lambda$-term,
- the number of free variables in $M^{\prime}$ is minimal.

In such a decomposition, we call the term $M^{\prime}$ a template. In case $M$ is of type $A$, linear or almost linear, it can be proven that $M^{\prime}$ can be taken from a finite set [15]. The linear case is rather simple, but the almost linear case requires some precaution as one needs first to put $M$ in syntactically almost linear form and then make the decomposition. Though the almost linear case is more technical the finiteness argument is the same in both cases and is based on proof theoretical arguments in multiplicative linear logic which involves polarities in a straightforward way.

The linear case conveys the intuition of decompositions in a clear manner. One takes the normal form of $M$ and then delineates the largest contexts of $M$, i.e. first order terms that are made only with constants and that are as large as possible. These contexts are then replaced by variables and the substitution $\sigma$ is built accordingly. The fact that the contexts are chosen as large as possible makes it so that no introduced variable can have as argument a term of the form $x M_{1} \ldots M_{n}$ where $x$ is another variable introduced in the process. Therefore, the new variables introduced in the process bring one negative atom and several (possibly 0) positive ones and all of them need to be matched with positive and negative atoms in the type of $M$ as, under these conditions, they cannot be matched together. This explains why there are only finitely many possible templates for a fixed type.

- Theorem 1. For all type $A$ built on tree signature $\Sigma$, the set of templates of closed linear (or almost linear) terms of type $A$ is finite.

Moreover, the templates associated with a $\lambda$-term can be computed compositionally (i.e. from the templates of its parts). As a result, templates can be computed by the look-ahead of HODTR ${ }_{\text {lin }}$ or of $\operatorname{HODTR}_{\mathrm{al}}$. When reducing the order, we enrich the look-ahead with template information while the substitution that is needed to reconstruct the produced term is outputted by the new transducer. The substitution is then performed by the initial state used at the root of the input tree which then outputs the same result as the former transducer. The substitution can be seen as a tuple of order 1 terms. It is represented as a tuple using Church encoding, i.e. a continuation. This makes the transducer we construct be of order 3 .

- Theorem 2. Any HODTR ${ }_{\text {lin }}$ (resp. HODTR ${ }_{\text {al }}$ ) has an equivalent $H O D T R_{\text {lin }}$ (resp. $H O D T R_{a l}$ ) of order 3.

The proof of this result shows that every $\operatorname{HODTR}_{\text {lin }}$ (or $\mathrm{HODTR}_{\mathrm{al}}$ ) can be seen as mapping trees to tuples of contexts and combining these contexts in a linear (resp. almost linear) way. This understanding of $\mathrm{HODTR}_{\text {lin }}$ and of $\mathrm{HODTR}_{\text {al }}$ allows us to prove that they are respectively equivalent to Attribute Tree Transducers with Single Use Restriction $\left(\mathrm{ATT}_{\text {sur }}\right)$; and to Attribute Tree Transducers (ATT). Then, using [2], we can conclude with the following expressivity result:

- Theorem 3. HODTR $R_{\text {lin }}$ are equivalent to MSOT and HODTR ${ }_{\text {al }}$ are equivalent to MSOTS.

The proof that $\mathrm{HODTR}_{\text {lin }}$ are equivalent to MSOT could have been simpler by using the equivalence with MTT with the single-use restricted property instead of ATT, but we would still need to use ATT to show that HODTR ${ }_{\text {al }}$ are equivalent to MSOTS.

## 4 Composition of HODTR ${ }_{\text {lin }}$

As we are interested in limiting the size of the transducer that is computed, and even though our primary goal is to compose HODTR $_{\text {lin }}$, this section is devoted to the composition of HOWDTR $_{\text {lin }}$. Indeed, working with non-deterministic look-aheads allows us to save the possibly exponential cost of determinizing an automaton.

### 4.1 Semantic analysis

Let $T_{1}=\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R_{1}, \mathrm{~A}_{1}\right)$ and $T_{2}=\left(\Sigma_{P}, \Sigma_{2}, \Sigma_{3}, p_{0}, R_{2}, \mathrm{~A}_{2}\right)$ be two Linear High-Order Weakly Deterministic tree Transducers with Regular look-ahead. The rules of $T_{1}$ can be written: $\quad q(a \vec{x})\langle\vec{\ell}\rangle \rightarrow M\left(q_{1} x_{1}\right) \ldots\left(q_{n} x_{n}\right) \quad$ where $q, q_{1}, \ldots, q_{n} \in Q$ are states of $T_{1}$, $\vec{\ell}=\ell_{1}, \ldots, \ell_{n}$ are states of $\mathrm{A}_{1}$ and the $\lambda$-term $M$ is of type $A_{q_{1}} \rightarrow \cdots \rightarrow A_{q_{n}} \rightarrow A_{q}$. Our goal is to build a $\operatorname{HOWDTR}_{\text {lin }} T:: \Sigma_{1} \rightarrow \Sigma_{3}$ that does the composition of $T_{1}$ and $T_{2}$, so we want to replace a rule such as that one with a new rule which corresponds to applying $T_{2}$ to the term $M$.

In order to do so, we need, for each $o_{2}$ tree in $M$, to know the associated state $\ell \in L_{2}$ of $T_{2}$ 's look-ahead, and the state $p \in P$ of $T_{2}$ which is going to process that node. So with any such tree we associate the pair $(p, \ell)$. In this case we call $(p, \ell)$ the token which represents the behavior of the tree. In general, we want to associate tokens not only with trees, but also with $\lambda$-terms of higher order. For example, we map an occurrence of a symbol $a \in \Sigma_{2}$ of type $o_{2} \rightarrow o_{2} \rightarrow o_{2}$, whose arguments $x_{1}$ and $x_{2}$ (of type $o_{2}$ ) respectively have look-ahead states $\ell_{1}$ and $\ell_{2}$ and are processed by states $p_{1}$ and $p_{2} \in P$ of $T_{2}$, to the token $\left(p_{1}, \ell_{1}\right) \multimap\left(p_{2}, \ell_{2}\right) \multimap(p, \ell)$ where $(p, \ell)$ is the token of the tree $a x_{1} x_{2}$ (of type $\left.o_{2}\right)$. We formally define tokens as follows:

- Definition 4. The set of semantic tokens $\llbracket A \rrbracket$ over a type $A$ built on atomic type $o_{2}$ is defined by induction:

$$
\llbracket o_{2} \rrbracket=\left\{(p, \ell) \mid p \in P, \ell \in L_{2}\right\} \quad \llbracket A \rightarrow B \rrbracket=\{f \multimap g \mid f \in \llbracket A \rrbracket, g \in \llbracket B \rrbracket\}
$$

Naturally, the semantic token associated with a $\lambda$-term $M$ of type $A$ built on atomic type $o_{2}$ will depend on the context where the term $M$ appears. For example a tree of atomic type $o_{2}$ can be processed by any state $p \in P$ of $T_{2}$, and a term of type $A \rightarrow B$ can be applied to any argument of type $A$. But for any such $M$ taken out of context, there exists a finite set of possible tokens for it. For example, a given tree of type $o_{2}$ can be processed by any state $p \in P$ depending on the context, but it has always the same look-ahead $\ell \in L_{2}$.

In order to define the set of possible semantic tokens for a term, we use a system of derivation rules. The following derivation rules are used to derive judgments that associate a term with a semantic token. So a judgment $\Gamma \vdash M: f$ associates term $M$ with token $f$, where $\Gamma$ is a substitution which maps free variables in $M$ to tokens. The rules are:

$$
\begin{aligned}
& \frac{p(a \vec{x})\left\langle\ell_{1}, \ldots, \ell_{n}\right\rangle \xrightarrow{T_{2}} M\left(p_{1} x_{1}\right) \ldots\left(p_{n} x_{n}\right) \quad \mathrm{A}_{2}\left(a\left(\ell_{1}, \ldots, \ell_{n}\right)\right)=\ell}{\vdash a:\left(p_{1}, \ell_{1}\right) \multimap \cdots \multimap\left(p_{n}, \ell_{n}\right) \multimap(p, \ell)} \\
& \frac{\Gamma_{1} \vdash M: f \multimap g \quad \Gamma_{2} \vdash N: f}{\Gamma_{1}, \Gamma_{2} \vdash M N: g} \\
& \frac{\Gamma, x^{A}: f \vdash M: g}{\Gamma \vdash \lambda x^{A} \cdot M: f \multimap g}
\end{aligned}
$$

Using this system we can derive, for any term $M^{A}$, all the semantic tokens that correspond to possible behaviours of $M^{A}$ when it is processed by $T_{2}$.

### 4.2 Unicity of derivation for semantic token judgements

We will later show that we can compute the image of $M$ from the derivation of the judgement $\vdash M: f$, assuming that $f$ is the token that represents the behaviour of $T_{2}$ on $M$. But before that we need to prove that for a given term $M$ and token $f$ the derivation of the judgement $\vdash M: f$ is unique:

- Theorem 5. For every type $A$, for every term $M$ of type $A$ and every token $f \in \llbracket A \rrbracket$, there is at most one derivation $\mathcal{D}:: \vdash M: f$.

This theorem relies in part on the fact that tokens form a coherent space, as introduced by Girard in [14], the proof is detailed in the appendix.

Now that we have shown that there is only one derivation per judgement $\vdash M: f$, we are going to see how to use that derivation in order to compute the term $N$ that is the image of $M$ by transducer $T_{2}$.

### 4.3 Collapsing of token derivations

We define a function (we call it collapsing function) which maps every derivation $\mathcal{D}:: \vdash M: f$ to a term $\overline{\mathcal{D}}$ which corresponds to the output of transducer $T_{2}$ on term $M$ assuming that $M$ has behaviour $f$.

- Definition 6. Let $\mathcal{D}$ be a derivation. We define $\overline{\mathcal{D}}$ by induction on $\mathcal{D}$, there are different cases depending on the first rule of $\mathcal{D}$ :

If $\mathcal{D}$ is of the form:

$$
\frac{p(a \vec{x})\left\langle\ell_{1}, \ldots, \ell_{n}\right\rangle \xrightarrow{T_{2}} N\left(p_{1} x_{1}\right) \ldots\left(p_{n} x_{n}\right) \quad \mathrm{A}_{2}\left(a\left(\ell_{1}, \ldots, \ell_{n}\right)\right)=\ell}{\vdash a:\left(p_{1}, \ell_{1}\right) \multimap \cdots \multimap\left(p_{n}, \ell_{n}\right) \multimap(p, \ell)}
$$

then $\overline{\mathcal{D}}=N$,
if $\mathcal{D}$ is of the form:
$\frac{\mathcal{D}_{1}:: \Gamma_{1} \vdash N_{1}: f \multimap g \quad \mathcal{D}_{2}:: \Gamma_{2} \vdash N_{2}: f}{\Gamma_{1}, \Gamma_{2} \vdash N_{1} N_{2}: g}$
then $\overline{\mathcal{D}}=\overline{\mathcal{D}}_{1} \overline{\mathcal{D}}_{2}$,
if $\mathcal{D}$ is of the form:
$\frac{\mathcal{D}_{1}:: \Gamma, x^{A}: f \vdash N: g}{\Gamma \vdash \lambda x^{A} \cdot N: f \multimap g}$
then $\overline{\mathcal{D}}=\lambda x . \overline{\mathcal{D}_{1}}$,
if $\mathcal{D}$ is of the form:
$\frac{f \in \llbracket A \rrbracket}{x^{A}: f \vdash x^{A}: f}$
then $\overline{\mathcal{D}}=x^{\bar{f}}$.
We can check that, for all derivation $\mathcal{D}:: \vdash M: f$, the term $\overline{\mathcal{D}}$ is of type $\bar{f}$ given by: $\overline{(p, \ell)}=A_{p}$ and $\overline{f \multimap g}=\bar{f} \rightarrow \bar{g}$.

Now that we have associated, with any pair $(M, f)$ such that $f$ is a semantic token of term $M$, a term $N=\overline{\mathcal{D}}$ which represents the image of $M$ by $T_{2}$, we need to show that replacing $M$ with $N$ in the computation of transducers leads to the same results.

### 4.4 Construction of the transducer which realizes the composition

We recall some notations: $T_{1}=\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R_{1}, \mathrm{~A}_{1}\right)$ and $T_{2}=\left(\Sigma_{P}, \Sigma_{2}, \Sigma_{3}, p_{0}, R_{2}, \mathrm{~A}_{2}\right)$ are two $\operatorname{HOWDTR}_{\mathrm{lin}}, Q=\left\{q_{1}, \ldots, q_{m}\right\}$ is the set of states of $T_{1}$ and, for every state $q_{i} \in Q$, we note $A_{q_{i}}$ the type of $q_{i}(t)$ when $t$ is a tree of type $o_{1}$. For all type $A$ built on $o_{2}$, the set of tokens of terms of type $A$ is noted $\llbracket A \rrbracket$ and is finite.

Previously, we saw how to apply transducer $T_{2}$ to terms $M$ of type $A$ built on the atomic type $o_{2}$, so we can apply $T_{2}$ to terms which appear on the left side of rules of $T_{1}$ : $q(a \vec{x})\langle\vec{\ell}\rangle \rightarrow M\left(q_{i_{1}} x_{1}\right) \ldots\left(q_{i_{n}} x_{n}\right)$. In a rule such as this one, in order to replace term $M$ with term $N=\overline{\mathcal{D}}$ where $\mathcal{D}$ is the unique derivation of the judgement $\vdash M: f$, we need to know which token $f$ properly describes the behaviour of $T_{2}$ on $M$. The computation of that token is done in the look-ahead automaton A of $T$.

We define the set of states of A as: $L=L_{1} \times \llbracket A_{q_{1}} \rrbracket \times \cdots \times \llbracket A_{q_{m}} \rrbracket$
With any tree $t$ (of type $o_{1}$ ) we want to associate the look-ahead of $T_{1}$ on $t$ and, for each state $q_{i} \in Q$ of $T_{1}$, a token of $q_{i}(t)$. The transition function of the look-ahead automaton A is defined by, for all $\left(\ell_{1}, f_{1,1}, \ldots, f_{1, n}\right), \ldots,\left(\ell_{n}, f_{m, 1}, \ldots, f_{m, n}\right) \in L$ :

$$
a\left(\ell_{1}, f_{1,1}, \ldots, f_{1, m}\right) \ldots\left(\ell_{n}, f_{n, 1}, \ldots, f_{n, m}\right) \xrightarrow{\mathrm{A}}\left(\ell, f_{1}, \ldots, f_{m}\right)
$$

where $a \ell_{1} \ldots \ell_{n} \xrightarrow{\mathrm{~A}_{1}} \ell$ and, for all state $q_{i} \in Q, f_{i}$ is such that in $T_{1}$ there exists a rule $q_{i}(a \vec{x})\left\langle\ell_{1}, \ldots, \ell_{n}\right\rangle \xrightarrow{T_{7}} M\left(q_{i_{1}} x_{1}\right) \ldots\left(q_{i_{n}} x_{n}\right)$ and a derivation of the judgement $\vdash M: f_{1, i_{1}} \multimap$ $\cdots \multimap f_{n, i_{n}} \multimap f_{i}$. Note that this look-ahead automaton is non-deterministic in general, but the transducer is weakly deterministic in the sense that, at each step, even if several look-ahead states are possible, only one rule of the transducer can be applied.

We define the set of states $Q^{\prime}$ of transducer $T$ by:
$Q^{\prime}=\left\{(q, f) \mid q \in Q, f \in \llbracket A_{q} \rrbracket\right\} \cup\left\{q_{0}^{\prime}\right\}$
Then we define the set $R$ of rules of transducer $T$ as the set of rules of the form:
$(q, f)(a \vec{x})\left\langle\left(\ell_{1}, f_{1,1}, \ldots, f_{1, m}\right), \ldots\right\rangle \xrightarrow{T} \overline{\mathcal{D}}\left(\left(q_{i_{1}}, f_{1}\right) x_{1}\right) \ldots\left(\left(q_{i_{n}}, f_{n}\right) x_{n}\right)$
such that there exists in $T_{1}$ a rule: $q(a \vec{x})\left\langle\ell_{1}, \ldots\right\rangle \xrightarrow{T_{7}} M\left(q_{i_{1}} x_{1}\right) \ldots\left(q_{i_{n}} x_{n}\right)$ and $\mathcal{D}$ is a derivation of the judgement $\vdash M: f_{1, i_{1}} \multimap \cdots \multimap f_{n, i_{n}} \multimap f$.

Because of Theorem 5 proved in the appendix, that set of rules is weakly deterministic.
To that set $R$ we then add rules for the initial state $q_{0}^{\prime}$, which simply replicate the rules of states of the form $\left(q_{0},\left(p_{0}, \ell\right)\right)$ : for all $a \in \Sigma_{1}$, all $\left(\ell_{1}, f_{1,1}, \ldots, f_{1, m}\right), \ldots,\left(\ell_{n}, f_{n, 1}, \ldots, f_{n, m}\right) \in$ $L$ and all rule in $R$ of the form:
$\left(q_{0},\left(p_{0}, l\right)\right)(a \vec{x})\left\langle\left(\ell_{1}, f_{1,1}, \ldots, f_{1, m}\right), \ldots\right\rangle \xrightarrow{T} M\left(\left(q_{1}, f_{1}\right) x_{1}\right) \ldots\left(\left(q_{n}, f_{n}\right) x_{n}\right)$
where $p_{0}$ is the initial state of $T_{2}$ and $l \in L_{2}$ is a state of the look-ahead automaton of $T_{2}$, we add the rule:
$q_{0}^{\prime}(a \vec{x})\left\langle\left(\ell_{1}, f_{1,1}, \ldots, f_{1, m}\right), \ldots\right\rangle \xrightarrow{T} M\left(\left(q_{1}, f_{1}\right) x_{1}\right) \ldots\left(\left(q_{n}, f_{n}\right) x_{n}\right)$
This set $R$ of rules is still weakly deterministic according to Theorem 5 .
We have thus defined the $\operatorname{HOWDTR}_{\text {lin }} T=\left(\Sigma_{Q^{\prime}}, \Sigma_{1}, \Sigma_{3}, q_{0}^{\prime}, R, \mathrm{~A}\right)$.

- Theorem 7. $T=T_{2} \circ T_{1}$

Finally, we will analyze the complexity of this algorithm and show that using the algorithm on $\mathrm{HOWDTR}_{\text {lin }}$ instead of $\mathrm{HODTR}_{\text {lin }}$ avoids an exponential blow-up of the size of the produced transducer.

First the set of states $Q^{\prime}$ of $T$ is of size $\left|Q^{\prime}\right|=1+\Sigma_{q \in Q}\left|\llbracket A_{q} \rrbracket\right|$ where $\left|\llbracket A_{q} \rrbracket\right|$ is the number of tokens of type $A_{q} \cdot\left|\llbracket A_{q} \rrbracket\right|=\left(|P|\left|L_{2}\right|\right)^{\left|A_{q}\right|}$ where $|P|$ is the number of states of transducer $T_{2},\left|L_{2}\right|$ is the number of states of the look-ahead automaton of transducer $T_{2}$ and $\left|A_{q}\right|$ is the size of the type $A_{q}$. So the size of $Q^{\prime}$ is $O\left(\Sigma_{q \in Q}\left(|P|\left|L_{2}\right|\right)^{\left|A_{q}\right|}\right)$, that is a polynomial in the size of $T_{2}$ to the power of the size of types of states of $T_{1}$.

It is important to note that the set $\llbracket A_{q} \rrbracket$ of tokens of type $A_{q}$ is where $\operatorname{HOWDTR}_{\text {lin }}$ and HODTR $_{\text {lin }}$ differ in their complexity: the deterministic alternative to the weakly deterministic $T$ would require to store with the state not a single token, but a set of two-by-two coherent tokens, that would bring the size of $Q^{\prime}$ to $1+\Sigma_{q \in Q} 2^{\left|\llbracket A_{q} \rrbracket\right|}$ which would be exponential in the size of $T_{2}$ and doubly exponential in the size of types of $T_{1}$.

Then there is the look-ahead automaton: its set of states is $L=L_{1} \times \llbracket A_{q_{1}} \rrbracket \times \cdots \times \llbracket A_{q_{m}} \rrbracket$. So the number of states is in $O\left(\left|L_{1}\right|\left(|P|\left|L_{2}\right|\right)^{\Sigma_{q \in Q}\left|A_{q}\right|}\right)$. The size of the set of rules of the look-ahead automaton is in $O\left(\Sigma_{a^{(n)} \in \Sigma_{1}}|L|^{n+1}\right)$ where $n$ is the arity of the constant $a^{(n)}$.

Finally there is the set $R$ of rules of $T$. For every judgement $\vdash M: f_{1, i_{1}} \multimap \cdots \multimap f_{n, i_{n}} \multimap$ $f$, finding a derivation $\mathcal{D}$ of that judgement and computing the corresponding $\overline{\mathcal{D}}$ is in $O\left(|M|^{2}\right)$ time where $|M|$ is the size of $M$. The number of possible rules is in $O\left(\Sigma_{a a^{(n) \in \Sigma_{1}}}\left(\left|Q^{\prime}\right|\right)^{n+1}\right)$. So computing $R$ is done in time $O\left(|R|^{2} \Sigma_{a^{(n)} \in \Sigma_{1}}\left(\left|Q^{\prime}\right|\right)^{n+1}\right)$ where $R$ is the set of rules of $T_{1}$. With a fixed input signature $\Sigma_{1}$, the time complexity of the algorithm computing $T$ is a polynomial in the sizes of $T_{1}$ and $T_{2}$, with only the sizes of types of states of $T_{1}$ as exponents.

Note that, as our model generalizes other classes of transducers, it is possible to perform their composition in our setting. Thanks to results of Theorem 2, it is then possible to reduce the order of the result of the composition, and obtain a $H_{O D T R}^{l i n}$ that can be converted back in those other models. This methods gives an important insight on the composition procedure for those other formalisms.

In comparison, the composition algorithms for equivalent classes of transductions are either not direct or very complex as they essentially perform composition and order reduction at once. For instance, composition of single used restricted MTT is obtained through MSO ([11]). High-level tree transducers [12] go through a reduction to iterated pushdown tree transducers and back. The composition algorithm for Streaming Tree Transducers described in [1] is direct, but made complex by the fact that the algorithm hides this reduction of order.

The double-exponential complexity of composition of $\mathrm{HODTR}_{\text {lin }}$ compares well to the non-elementary complexity of composition in equivalent non-MSOT classes of transducers. Although the simple exponential complexity of composition in MSOT is better, we should account for the fact that the MSOT model does not attempt to represent the behavior of programs.

## 5 Conclusion and future work

In this paper we have presented a new mechanical characterization of Monadic Second Order Transductions. This characterization is based on simply typed $\lambda$-calculus which allows us to generalize with very few primitives most of the mechanisms used to compute the output in the transducer literature. The use of higher-order allows us to propose an arguably simple algorithm for computing the composition of linear higher-order transducers which coincide with MSOT. The correctness of this algorithm is based on denotation semantics (coherence spaces) of $\lambda$-calculus and the heart of the proof uses logical relations. Thus, the use of $\lambda$-calculus allows us to base our work on standard tools and techniques rather than developing our own tools as is often the case when dealing with transducers. Moreover, this work sheds some light on how composition is computed in other formalisms. Indeed, we argue that for $M T T_{\text {sur }}, \mathrm{STT}$, or $A R R_{\text {sur }}$, the composition must be the application of our composition algorithm followed by the order reduction procedure that we use to prove the equivalence with logical transductions.

The notion of higher-order transducer has already been studied [12, 19, 17], however, there is still some work to be done to obtain direct composition algorithms. We plan to generalize our approach of the linear case to the general one and devise a semantic based partial evaluation for the composition of higher-order transducers.

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## Linear High-Order Deterministic Tree transducers with Regular look-ahead

## A Order reduction

## A. 1 Templates

## A.1.1 Linear templates

Proof of Theorem 1
In order to show that the set of linear templates of a given type $A$ is finite, we use notions and properties defined in [16]: the definitions of positive and negative subtype occurrences and subpremises in $A$ and what it entails in the structure of terms of type $A$.

For any type $A$, we can label occurrences of subtypes in $A$ as positive or negative using the following rules:

- $A$ is positive, we note it $A^{+}$,
- if $B \rightarrow C$ is a positive subtype of $A$ then $B$ is negative and $C$ is positive, we note it $\left(B^{-} \rightarrow C^{+}\right)^{+}$,
- if $B \rightarrow C$ is a negative subtype of $A$ then $B$ is positive and $C$ is negative, we note it $\left(B^{+} \rightarrow C^{-}\right)^{-}$.
For example, if $A=((o \rightarrow o) \rightarrow(o \rightarrow o)) \rightarrow((o \rightarrow o) \rightarrow(o \rightarrow o))$ is a type built on the atomic tree type $o$, then we can label occurrences of subtypes of $A$ as follows: $\left(\left(o^{-} \rightarrow o^{+}\right)^{+} \rightarrow\left(o^{+} \rightarrow o^{-}\right)^{-}\right)^{-} \rightarrow\left(\left(o^{+} \rightarrow o^{-}\right)^{-} \rightarrow\left(o^{-} \rightarrow o^{+}\right)^{+}\right)^{+}$.

So, for all subtype occurrence $A^{\prime}=A_{1} \rightarrow \ldots A_{n} \rightarrow o$, if $A^{\prime}$ is positive then $A_{1}^{-} \rightarrow$ $\ldots A_{n}^{-} \rightarrow o^{+}$, if $A^{\prime}$ is negative then $A_{1}^{+} \rightarrow \ldots A_{n}^{+} \rightarrow o^{-}$.

With any closed linear term $M$ in $\beta$-normal form of type $A$ we associate a bijection from the set of positive occurrences of the atomic type $o$ in $A$ to the set of negative occurrences of the atomic type $o$ in $A$, we call it the trace of $M$ and note it $\Theta(M)$.

We show how to compute $\Theta(M)$ on an example. To a term $M=\lambda y_{1} y_{2} y_{3} \cdot y_{1}\left(\lambda y_{4} \cdot y_{2} y_{4}\right) y_{3}$ of type $A=\left(\left(o^{-} \rightarrow o^{+}\right) \rightarrow o^{+} \rightarrow o^{-}\right) \rightarrow\left(o^{+} \rightarrow o^{-}\right) \rightarrow o^{-} \rightarrow o^{+}$we have:


The trace is computed by induction on $M$ :
First $M$ introduces $y_{1}, y_{2}$ and $y_{3}$ :

$$
\frac{\left(\left(o^{-} \rightarrow o^{+}\right) \rightarrow o^{+} \rightarrow o^{-}\right)}{y_{1}} \rightarrow \frac{\left(o^{+} \rightarrow o^{-}\right)}{y_{2}} \rightarrow \underset{y_{3}}{o^{-}} \rightarrow o^{+}
$$

Then, because $y_{1}$ is the head variable of $M$, the output type of $M$ corresponds to the output type of $y_{1}$ :


Then in the arguments of $y_{1}$ we introduce $y_{4}$ and we have two terms of type $o^{+}$to match
with output types $o^{-}$of variables:


Those are mapped to $y_{2}$ and $y_{3}$ :


Finally the argument of $y_{2}$ is $y_{4}$ :


This is how we compute the trace of a linear term in linear normal form. The function which associates a trace with any linear term in linear normal form is injective, and it is possible, given a trace $\Theta(M)$, to compute the term $M$. For example:




However injective, the $\Theta$ function is not surjective in general, meaning there are bijections from positive to negative atomic subtype occurrences that do not correspond to any term. For example, for type $A=((o \rightarrow o) \rightarrow o \rightarrow o) \rightarrow(o \rightarrow o) \rightarrow o \rightarrow o$, there are only 3 terms in linear normal form of type $A$, and only 3 corresponding traces (the three examples we have shown so far). Any other bijection between positive and negative atomic subtype occurrences is not a trace either because it binds variable $y_{4}$ outside of its scope: or because some variable
 would not appear in the term: $\quad\left(\left(o^{-} \rightarrow o^{+}\right) \rightarrow o^{+} \rightarrow o^{-}\right) \rightarrow\left(o^{+} \rightarrow o^{-}\right) \rightarrow o^{-} \rightarrow o_{y_{3}}$

The consequence of this is that the number of closed linear terms in linear normal form of a given type $A$ is bounded by the number of bijections between $A$ 's sets of positive and negative atomic subtype occurrences. In order to have a bound on the number of linear templates of a type, we extend the trace function from closed linear terms to linear terms with free variables which represent tree contexts, i.e. with type of the form $o^{n} \rightarrow o$. Again we show how it works on an example: the template $M=\lambda y_{1} y_{2} y_{3} . C_{1}\left(y_{1}\left(\lambda y_{4} . y_{2} y_{4}\right) C_{2}\right) y_{3}$ with tree contexts $C_{1}$ and $C_{2}$ of respective types $o \rightarrow o \rightarrow o$ and $o$, $M=\lambda y_{1} y_{2} y_{3} . C_{1}$


Naturally, the free variables provide new atomic subtype occurrences and the positivity and negativity of those are computed as if $C_{1}$ and $C_{2}$ were variables like $y_{2}$ and $y_{3}$. If a
tree context is of the form $o^{n} \rightarrow o$ then it has 1 negative and $n$ positive atomic subtype occurrences.

In order to show that the set of linear templates of a type is finite, we use the fact that templates are minimal decompositions: it means that there can not be a tree context that is directly applied to another tree context. This implies that, in the trace of a template, a positive atomic subtype occurrence of a tree context can not be mapped to a negative atomic subtype occurrence in a tree context. Since there is exactly one negative atomic subtype occurrence per tree context, the number of tree contexts in a template of type $A$ is bounded by the number of positive atomic subtype occurrences in $A$. On the other hand, the number of positive atomic subtype occurrences in the tree contexts is bounded by the number of negative atomic subtype occurrences in $A$. So, for any given type $A$, the number of tree contexts of a linear template is bounded, the arity $n$ of these tree contexts is bounded and, for each tree contexts setting, the number of traces (and therefore the number of templates) is bounded. Consequently, for all type $A$ the number of linear templates of type $A$ is bounded (by $n^{n}$ where $n$ is the size of type $A$ ).

## A.1.2 Almost linear templates

Before we get to almost linear templates, we need to introduce $\eta$-contraction and $\eta$-long form for terms. An $\eta$-redex is a term of the form $(\lambda x .(M x))$ when $x \notin \mathrm{fv}(M)$ and its $\eta$-contractum is the term $M$. The relation of $\eta$-contraction, $\rightarrow_{\eta}, \eta$-reduction, $\xrightarrow{*}_{\eta}$, and $\eta$-conversion, $={ }_{\eta}$, are defined similarly to $\beta$-contraction. So as to compare $\lambda$-terms, we use the union of $\beta$-contraction and $\eta$-contration, $\rightarrow_{\beta \eta}$. But this can be done by putting terms in a particular form: the $\eta$-long form. A term $M$ is said to be in $\eta$-long form whenever if $N$ is a subterm of $M$ that has type $A \rightarrow B$ then either $N$ is of the form $\lambda x . N^{\prime}$, or its occurrence in $M$ is applied to some argument. For every term $M$ there is a term $M^{\prime}$ in $\eta$-long form such that $M={ }_{\eta} M^{\prime}$ and moreover $M={ }_{\beta \eta} N$ iff given $M^{\prime}$ and $N^{\prime}$ that are $\eta$-long forms of $M$ and $N$, $M^{\prime}={ }_{\beta} N^{\prime}$.

In the case of almost linear templates, we first define an almost linear normal form for terms that are equivalent to almost linear terms. For this we use results by M. Kanazawa [16] (2012) on almost affine lambda terms. Note that these results are applicable to both almost affine and almost linear terms. This report characterizes almost linear terms as terms that have the negatively non-duplicated property, consequently almost linear terms are terms that are both non-erasing (each bound variable is used at least once) and have the negatively non-duplicated property.

The other result of that paper we are using is a lemma (Lemma 8 page 13), which, for every negatively non-duplicated term $M$ in $\eta$-long $\beta$-normal form, builds, through a deterministic procedure, an almost affine term $M^{\prime}$ that $\beta$-reduces to $M$. The way $M^{\prime}$ is computed from $M$ is by successively factorizing variables $y$ that are not of atomic type but occur at several places in $M$. For any such variable $y$, the negatively non-duplicated property implies that there are terms $N_{1}, \ldots, N_{m}$ such that $y$ always occurs in a term $y N_{1} \ldots N_{m}$ of atomic type in $M$; then there is a subterm $M_{y}$ of $M$ containing all occurrences of $y N_{1} \ldots N_{m}$, that term $M_{y}$ is $\beta$-equivalent to the term $\left(\lambda y^{\prime} \cdot M_{y}^{\prime}\right)\left(y N_{1} \ldots N_{m}\right)$ where $M_{y}^{\prime}=M_{y}\left[y N_{1} \ldots N_{m} / y^{\prime}\right]$. By replacing $M_{y}$ with $\left(\lambda y^{\prime} . M_{y}^{\prime}\right)\left(y N_{1} \ldots N_{m}\right)$ in $M$ we remove the copying of the non atomic variable $y$ and instead have the copying of variable $y^{\prime}$ which is of atomic type. By applying this process to every copied variable of non-atomic type in $M$ we get the almost linear term $M^{\prime} \beta$-equivalent to $M$.

With any term $M$ equivalent to an almost linear term, we associate the almost linear term $M^{\prime}$ obtained by applying that process to the $\eta$-long $\beta$-normal form of $M$. Since two
equivalent terms $M_{1}$ and $M_{2}$ have the same $\eta$-long $\beta$-normal form, they are associated with the same almost linear term $M^{\prime}$. Therefore we have a normal form for all term that is equivalent to an almost linear term, we call it the almost linear normal form.

Once we have the almost linear normal form, we can apply the same reasoning as the one for linear templates. Because of the process of factorizing copied non-atomic variables, almost linear templates can be more complex than linear ones. But since the number of distinct non-atomic variables in a term $M$ is bounded by the size of the type of $M$, the number of almost linear templates of a type $A$ is bounded by $n_{\text {templates }} *\left(n_{\text {fact }}\right)^{n_{\text {var }}}$ where $n_{\text {templates }}$ is the number of linear templates of type $A, n_{\text {fact }}$ is a bound on the number of templatewise distinct possible factorizations of a non-atomic variable (i.e. two factorizations are templatewise distinct only if the templates of the factorized terms are distinct) and $n_{v a r}$ is a bound on the number of non-atomic variables. We saw before that $n_{\text {templates }} \leq n^{n}$ where $n$ is the size of the type $A$. The number of non-atomic variables is bounded by the size $n$ of the type $A$. The template of a factorized term only depends on at which subterm $M_{y}$ of $M$ the factorization happens, and the number of templatewise distinct such $M_{y}$ is bounded by the size of the template, so $n_{f a c t} \leq 2 n$. Therefore the number of almost linear templates of a given type $A$ of size $n$ is bounded by $n^{2 n}$.

## A. 2 Effective order reduction

We will use the following notation: if a $\lambda$-term $M$ is associated to the decomposition $\left\langle M^{\prime}, \sigma\right\rangle$ where $M^{\prime}$ is a template and $\sigma$ a substitution of the free variables in $M^{\prime}$, then we note $\mathfrak{T}(M)=\left(M^{\prime},\left(\sigma\left(y_{1}\right), \ldots, \sigma\left(y_{n}\right)\right)\right)$ where $y_{1}, \ldots, y_{n}$ are the free variables in $M$. In this case we allow $=$ to mean equal up to renaming of free variables. For all type $A$ we note $t\langle A\rangle$ the set of templates of terms of type $A$.

## A.2.1 Linear case

Before proving theorem 2 we first prove a useful lemma:

- Lemma 8. Let $M\left[x_{1}, \ldots, x_{n}\right]$ be a linear term built on signature $\Sigma_{1}$ with typed free variables $x_{1}^{A_{1}}, \ldots, x_{n}^{A_{n}}$, let $t_{1}, \ldots, t_{n}$ be linear templates of $x_{1}, \ldots, x_{n}$. Then there is a linear template $t$ and tree contexts $C_{1}, \ldots, C_{\ell}$ with free variables $y_{1,1}, \ldots, y_{1, \ell_{1}}, \ldots, y_{n, 1}, \ldots, y_{n, \ell_{n}}$ such that, for all linear terms $N_{1}, \ldots, N_{n}$ with $\mathfrak{T}\left(N_{i}\right)=\left(t_{i},\left(C_{i, 1}, \ldots, C_{i, \ell_{i}}\right)\right)$ for all $i$ :

$$
\mathfrak{T}\left(M\left[x_{1} / N_{1}, \ldots, x_{n} / N_{n}\right]\right)=\left(t,\left(C_{1}, \ldots, C_{\ell}\right)\left[y_{i, j} / C_{i, j}\right]_{i \leq n, j \leq \ell_{i}}\right)
$$

Proof. For all $i \leq n: N_{i}={ }_{\beta \eta} t_{i}\left[y_{i, 1} / C_{i, 1}, \ldots, y_{i, \ell_{i}} / C_{i, \ell_{i}}\right]$, where $y_{i, 1}, \ldots, y_{i, \ell_{i}}$ are the free variables of $t_{i}$, because $\mathfrak{T}\left(N_{i}\right)=\left(t_{i},\left(C_{i, 1}, \ldots, C_{i, \ell_{i}}\right)\right)$. Then we define $t$ and $\left(C_{1}, \ldots, C_{\ell}\right)$ as the template and tree-contexts of the $\lambda$-term $M\left[x_{1} / t_{1}, \ldots, x_{n} / t_{n}\right]$ on the signature $\Sigma \cup$ $\left\{y_{i, j}\right\}_{i \leq n, j \leq \ell_{i}}$ (it is a tree signature because variables $y_{i, j}$ are tree-contexts and therefore of order at most 1 ). Consequently :

$$
\begin{aligned}
M\left[x_{1} / N_{1}, \ldots, x_{n} / N_{n}\right] & =M\left[x_{1} / t_{1}, \ldots, x_{n} / t_{n}\right]\left[y_{i, 1} / C_{i, 1}, \ldots, y_{i, \ell_{i}} / C_{i, \ell_{i}}\right] \\
& =t\left[z_{1} / C_{1}, \ldots, z_{\ell} / C_{\ell}\right]\left[y_{1,1} / C_{1,1}, \ldots, y_{n, \ell_{n}} / C_{n, \ell_{n}}\right]
\end{aligned}
$$

and so :

$$
\mathfrak{T}\left(M\left[x_{1} / N_{1}, \ldots, x_{n} / N_{n}\right]\right)=\left(t,\left(C_{1}, \ldots, C_{\ell}\right)\left[y_{i, j} / C_{i, j}\right]_{i \leq n, j \leq \ell_{i}}\right)
$$

Now we can prove theorem 2 in the linear case:
Proof. Let $T=\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R\right.$, A $)$ be a $\operatorname{HODTR}_{\text {lin }}$. We note $L$ the set of states of A. We want to define a $\operatorname{HODTR}_{\text {lin }} T^{\prime}=\left(\Sigma_{Q^{\prime}}, \Sigma_{1}, \Sigma_{2}, q_{0}^{\prime}, R^{\prime}, \mathrm{A}^{\prime}\right)$ of order 3 equivalent to $T$.

We start by defining the look-ahead automaton $\mathrm{A}^{\prime}$ and its set of states $L^{\prime}=L \times$ $t\left\langle A_{q_{0}}\right\rangle \ldots t\left\langle A_{q_{m}}\right\rangle$ where $A_{q_{0}}, \ldots, A_{q_{m}}$ are the output type of the states in $Q$ and $t\langle A\rangle$ is the set of templates of type $A$. So this look-ahead associates, with every input tree $N$, the look-ahead A on tree $N$ and, for each state $q_{i}$, the template of $q_{i}(N)$. Lemma 8 shows how to compute the template of a term $M\left[x_{1}, \ldots, x_{n}\right]$ using the templates of $x_{1}, \ldots, x_{n}$, then we define the rules of $\mathrm{A}^{\prime}$ accordingly so that, for all input tree $N$, the state of the look-ahead $\mathrm{A}^{\prime}$ on tree $N$ is $\left(l, t_{0}, t_{1}, \ldots, t_{m}\right)$ where $l$ is the look-ahead of A on $N$ and, for all $i \leq m, t_{i}$ is the template of $q_{i}(N)$. We prove this by induction on the input tree, the induction step is a direct application of lemma 8 .

Then we define the set of states $Q^{\prime}$ of $T^{\prime}: Q^{\prime}=\left\{\left(q_{i}, t\right) \mid q_{i} \in Q, t \in t\left\langle A_{q_{i}}\right\rangle\right\} \cup\left\{q_{0}^{\prime}\right\}$. We will now define the rules in $R^{\prime}$ so that, for all $q_{i} \in Q, t \in t\left\langle A_{q_{i}}\right\rangle$ and for all input tree $N:\left(q_{i}, t\right)(N)=\left(C_{1}, \ldots, C_{\ell}\right)$ (using continuations to represent the tuple) such that $\mathfrak{T}\left(q_{i}(N)\right)=\left(t,\left(C_{1}, \ldots, C_{\ell}\right)\right)$. For all state $\left(q_{i}, t\right) \in Q^{\prime}$, input tree constant $f$ of arity $n$, input tree variables $x_{1}, \ldots, x_{n}$ and their look-ahead states $l_{1}, \ldots, l_{n}$ in $L$ and $l_{1}^{\prime}, \ldots, l_{n}^{\prime}$ in $L^{\prime}$, and for all rule in $R$ of the form : $q_{i}\left(f x_{1} \ldots x_{n}\right)\left\langle l_{1}, \ldots, l_{n}\right\rangle \rightarrow M\left[x_{1}, \ldots, x_{n}\right]$ where variable $x_{1}$ is processed by state $q_{i_{1}}, x_{2}$ by $q_{i_{2}}$ and so on, we add the following rule in $R^{\prime}$ :

$$
\begin{aligned}
& \left(q_{i}, t\right)\left(f x_{1} \ldots x_{n}\right)\left\langle l_{1}^{\prime}, \ldots, l_{n}^{\prime}\right\rangle \rightarrow \\
& \quad \lambda k \cdot\left(q_{i_{1}}, t_{1}\right) x_{1}\left(\lambda y_{1,1}, \ldots y_{1, \ell_{1}} \ldots\left(q_{i_{n}}, t_{n}\right) x_{n}\left(\lambda y_{n, 1} \ldots y_{n, \ell_{n}} \cdot k C_{1} \ldots C_{\ell}\right) \ldots\right)
\end{aligned}
$$

This is a way of setting variables $y_{1,1}, \ldots, y_{1, \ell_{1}}$ to the tree contexts $\left(C_{1,1}, \ldots, C_{1, \ell_{1}}\right)=$ $\left(q_{i_{1}}, t_{1}\right)\left(x_{1}\right)$, it is necessary because using a projection on the tuple every time a tree context $C_{1, i}$ is used would break linearity.

The output type of such a state $\left(q_{i}, t\right)$ is $\left(A_{1} \rightarrow \ldots A_{\ell} \rightarrow o\right) \rightarrow o$ where $o$ is the atomic output tree type and $A_{i}$ is the type of the $i$-th free variable of $t$, then, since the order of one of the $A_{i}$ is at most 1 , the order of the output type of $\left(q_{i}, t\right)$ is at most 3 . So the order of $T^{\prime}$ is at most 3 .

Note that if state $q_{0}$ has output type $o$, the only template for that type is the term $x$ where $x$ is a free variable of type $o$. Then for the initial state $q_{0}^{\prime}$ of output type $o$, we add special rules in $R^{\prime}$. For all rule already in $R^{\prime}$ of the form : $\left(q_{0}, t\right)\left(f x_{1} \ldots x_{n}\right)\langle\vec{\ell}\rangle \rightarrow\left(C_{1}\right)$ where $\left(C_{1}\right)$ is the unary tuple of type $(o \rightarrow o) \rightarrow o$ containing the tree $C_{1}$ of type $o$, we add the rule : $q_{0}^{\prime}\left(f x_{1} \ldots x_{n}\right)\langle\vec{\ell}\rangle \rightarrow C_{1}$.

For all $q_{i} \in Q, t \in t\left\langle A_{q_{i}}\right\rangle$ and for all input tree $N$ such that $\mathfrak{T}\left(q_{i}(N)\right)=\left(t,\left(C_{1}, \ldots, C_{\ell}\right)\right)$ : $\left(q_{i}, t\right)(N) \rightarrow_{R^{\prime}}^{*}\left(C_{1}, \ldots, C_{\ell}\right)$; we prove this by induction on the input tree $N$. Again the induction is a direct application of Lemma 8.

Finally we conclude by applying this property to state $q_{0} \in Q$ and template $x \in t\langle o\rangle$, and replacing the first rule applied to $\left(q_{0}, x\right)$ by the corresponding rule on $q_{0}^{\prime}$.

## A.2.2 Almost linear case

We first prove the equivalent of lemma 8 for the almost linear case :

- Lemma 9. Let $M\left[x_{1}, \ldots, x_{n}\right]$ be an almost linear term on signature $\Sigma_{1}$ with typed free variables $x_{1}^{A_{1}}, \ldots, x_{n}^{A_{n}}$, let $t_{1}, \ldots, t_{n}$ be almost linear templates of $x_{1}, \ldots, x_{n}$. Then there is
an almost linear template $t$ and tree contexts $C_{1}, \ldots, C_{\ell}$ with free variables $y_{1,1}, \ldots, y_{n, \ell_{n}}$ such that, for all almost linear terms $N_{1}, \ldots, N_{n}$ with $\mathfrak{T}\left(N_{i}\right)=\left(t_{i},\left(C_{i, 1}, \ldots, C_{i, \ell_{i}}\right)\right)$ for all $i$ :

$$
\mathfrak{T}\left(M\left[x_{1} / N_{1}, \ldots, x_{n} / N_{n}\right]\right)=\left(t,\left(C_{1}, \ldots, C_{\ell}\right)\left[y_{i, j} / C_{i, j}\right]_{i \leq n, j \leq \ell_{i}}\right)
$$

Proof. The key to this proof is to notice that the property of being an almost linear $\lambda$-term is preserved by substitution of variables with almost linear $\lambda$-terms and by $\beta \eta$-equivalence. It ensures that the term $M\left[x_{1} / N_{1}, \ldots, x_{n} / N_{n}\right]$ is $\beta \eta$-equivalent to an almost linear $\lambda$-term. The rest of the proof works like that of lemma 8 .

Then the order reduction theorem for almost linear transducers (theorem 2) is proven similarly to the linear case, but using lemma 9 as the almost linear extension of lemma 8 .

## B Equivalence with MSOT and MSOTS

## B. 1 Definition of ATT

Attribute grammars [13] are ways to formalize a class of syntax directed translation based on context free grammar. They amount to equip a context-free grammar with semantics attributes that propagate along the abstract syntax tree. These semantics attributes are synthesized when their value is propagated bottom-up and inherited when they are propagated top-down.

Attributed tree transducers, as defined by [2, 13], correspond to the combination of a relabeling attribute grammar and an attribute grammar whose attributes are trees. The relabeling simulates both the finite state control and the look-ahead automaton of usual transducers. In our setting, they can be seen as HODT with look-ahead whose rules are of the form $q\left(a x_{1} \ldots x_{n}\right) \rightarrow b q_{1}\left(x_{1}\right) \ldots q_{n}\left(x_{n}\right)$, where $a \in \Sigma, b \in \Delta$ and $a$ and $b$ have the same arity. We call REL the class of transductions defined this way.

Formally, an attributed tree transducer from the input alphabet $\Sigma$ to the output alphabet $\Delta$ is a tuple ( $\Sigma, \Delta, S, I$, out, $R$, root $)$ where:

- $\Sigma$ is the input alphabet,
- $\Delta$ is the output alphabet,
- $S$ and $I$ are the finite set of respectively synthesized and inherited attributes,
- out $\in S$, the meaning attribute,
- $R$, the rules, is a function that maps elements $a$ of $\Sigma$ of arity $n$ to equations of the form $(\alpha, i)=M\left(\alpha_{1}, i_{1}\right) \ldots\left(\alpha_{k}, i_{k}\right)$ for every $(\alpha, i)$ in $(S \times\{0\} \cup I \times[1, n])$ where $M$ is a linear $\lambda$-term of type $o^{k} \rightarrow o$ built on the signature $\Delta$ and where $\left(\alpha_{j}, i_{j}\right)$ are pairwise distinct constants that have atomic type and where $\alpha_{j}$ is in $S \cup I$ and $i_{j}$ is in [ $\left.0, n\right]$.
- root, the initialization of inherited attributes which maps elements $a$ of $\Sigma$ to equations of the form $(\alpha, 0)=M\left(\alpha_{1}, 0\right) \ldots\left(\alpha_{k}, 0\right)$ for every $\alpha$ in $I$, where $M$ is a linear $\lambda$-term of type $o^{k} \rightarrow o$ built on the signature $\Delta$ and, for all $j \leq k,\left(\alpha_{j}, 0\right)$ is a constant of atomic type and $\alpha_{j}$ is in $S \cup I$.
Now given an input tree $N$ built on signature $\Sigma$, we let $V_{N}$ be the set of paths of $N$ that is inductively defined by, for $N=a N_{1} \ldots N_{n}: V_{N}=\{\epsilon\} \cup \bigcup_{i=1}^{n}\left\{i . u \mid u \in V_{N_{i}}\right\}$. For $u$ in $V_{N}$, we write $N \bigsqcup_{u}$ for the subterm of $N$ that is at path $u$ and which is defined as $N \bigsqcup_{\epsilon}=N$, $\left(a N_{1} \ldots N_{n}\right) \operatorname{l}_{i u}=N_{i} \downharpoonright_{u}$. For $u$ in $V_{N}$, we let $l a b_{N}(u)$ be the constant $a$ in $\Sigma$ such that $N \iota_{u}=a N_{1} \ldots N_{n}$. Consider $v$ in $V_{N l_{u}}$, we have that $\left(N \vdash_{u}\right) \iota_{v}=N \downarrow_{u v}$. Therefore the operation that appends $u$ in front of an element of $V_{\left.N\right|_{u}}$ defines an injection from $V_{N l_{u}}$ into $V_{N}$ that preserves the designated term.

The attribute transducer associates with each element of $V_{N}$ a set of attributes. Formally, it builds a set of equations whose left-hand side belong to $A(N)=(S \cup I) \times V_{N}$. We call the elements of $A(N)$ attribute instances or simply attributes of $N$ when the context is clear. For $u \in V_{N}$, the subset $A_{u}(N)=\{(\alpha, u) \mid \alpha \in S \cup I\}$ is the set of attributes associated with $N$ at path $u$. For each attribute $(\alpha, v) \in A\left(N{L_{u}}^{\prime}\right)$ we define $u .(\alpha, v)$ as the attribute $(\alpha, u v) \in A(N)$. Given a set of attribute instances $S$, we write $u . S$ for the set $\{(\alpha, u v) \mid(\alpha, v) \in S\}$. Then the following identity holds $u . A_{v}\left(\left.N\right|_{u}\right)=A_{u v}(N)$.

The attribute transducer associates an equation with every attribute $(\alpha, u)$ of $A(N)$ as follows. If an equation $E_{(\alpha, i)} \in R(a)$ is of the form $(\alpha, i)=M\left(\alpha_{1}, i_{1}\right) \ldots\left(\alpha_{n}, i_{n}\right)$ then, for all path $u \in V_{N}$ such that $\operatorname{lab}_{N}(u)=a$, the equation $(\alpha, u . i)=M\left(\alpha_{1}, u . i_{1}\right) \ldots\left(\alpha_{n}, u . i_{n}\right)$ is the equation for the attribute $(\alpha, u . i)$ and is noted $u . E_{(\alpha, i)}$. The operation $u$. on equations naturally extends to sets of equations. We note $E q_{u}(N)$ the set of equations $u . R\left(l a b_{N}(u)\right)$, and $E q_{u \downarrow}(N)$ the set of equations $\bigcup_{v \in V_{N \perp u}} E q_{u v}(N)$. Then the set of equations associated with $N(\operatorname{noted} E q(N))$ is $E q(N)=E q_{\epsilon \downarrow}(N)=\bigcup_{u \in V_{N}} E q_{u}(N)$. The complete set of equations of $N($ noted $C E q(N))$ is $C E q(N)=\operatorname{root}\left(\operatorname{lab_{N}}(\epsilon)\right) \cup E q(N)$. We will also use the notation $C E q_{u \uparrow}(N)$ for the set $C E q(N) \backslash E q_{u \downarrow}(N)$ for all $u \in V_{N}$.

We represent the way attributes depend on each other using graph as follows. With an equation $E_{(\alpha, i)} \in R(a)$ of the form $(\alpha, i)=M\left(\alpha_{1}, i_{1}\right) \ldots\left(\alpha_{n}, i_{n}\right)$ we associate the directed graph $G\left(E_{(\alpha, i)}\right)$ whose set of vertices is $V=\left\{(\alpha, i),\left(\alpha_{1}, i_{1}\right), \ldots,\left(\alpha_{n}, i_{n}\right)\right\}$ and set of edges is $E=\left\{\left((\alpha, i),\left(\alpha_{j}, i_{j}\right)\right) \mid j \in[1, n]\right\}$. Define the operation of non-disjoint union of graphs whose sets of vertices are not necessarity disjoint as follows: for all graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right), G_{1} \cup G_{2}=\left(V_{1} \cup V_{2}, E_{1} \cup E_{2}\right)$. For all set $E q$ of equations we define the graph $G(E q)$ associated with the set of equations $E q$ as $\bigcup_{E \in E q} G(E)$. We define the operation $u$. on such graphs by: u. $G(E q)=G(u . E q)$. The dependency graph and complete dependency graph of $N$ are $G(E q(N))$ and $G(C E q(N))$ respectively, and they are noted $D(N)$ and $C D(N)$ respectively. Similarly, we will use the notations $D_{u \downarrow}(N)$ for the graph $G\left(E q_{u \downarrow}(N)\right)$ and $C D_{u \uparrow}(N)$ for the graph $G\left(E q_{u \uparrow}(N)\right)$.

Note that in $D(N)$, there are no edges pointing to inherited attributes of the root node of $N$ (attributes in $I \times\{\epsilon\}$ ).

When $C D(N)$ is acyclic, the attribute grammar is said non-circular on $N$ and we note $\operatorname{Ord}(C D(N))$ the set of its topological sorts (i.e. the total orders which embed into the partial order on nodes induced by the acyclic graph $C D(N)$ ). In that case, we can associate with every attribute of $N$ a tree built on $\Delta$ by applying the equations in $C E q(N)$. Indeed, a topological sort of the acyclic graph $C D(N)$ gives an order in which we can evaluate the attributes of $N$, i.e. associate with them a term built on $\Delta$. Then the tree associated with the attribute (out, $\epsilon$ ) is the result of the attribute tree transducer. An attribute tree transducer is said non-circular when for every $N, C D(N)$ is acyclic. We note ATT the class of transductions that are defined by Attribute Tree Transducers. When moreover for every $N$ the dependency graph is a tree, the Attribute Tree Transducer is said single use restricted. We note $\mathrm{ATT}_{\text {sur }}$ the class of transductions that are defined by single use restricted Attribute Tree Transducers.

- Theorem 10. [2]

We have the following equivalences:

- $\mathrm{REL} \circ A T T=M S O T S$,
- $\mathrm{REL} \circ A T T_{\text {sur }}=M S O T$,


## B. $2 R E L \circ A T T \subseteq H_{O D T R}$ al and $R E L \circ$ ATT $_{\text {sur }} \subseteq H_{O D T R}^{\text {lin }}$

In this part we want to prove that the composition of a relabeling attribute grammar with an attributed tree transducer can be modeled by a $\operatorname{HODTR}_{\mathrm{al}}$, and that if the attributed tree transducer is single use restricted then the translated $H_{O D T R}^{a l}$ is a $H_{O D T R}^{\text {lin }}$.

The order in which the attributes are computed is important, in that regard we need a few more definitions.

## B.2.1 Definitions and notations

For all tree $N$, we note $C D^{\top}(N)$ the graph obtained from $C D(N)$ by adding a vertex noted $\top$ and an edge $(($ out,$\epsilon), \top)$, and, for all $u \in V_{N}$, we note $C D_{u \uparrow}^{\top}(N)$ the graph obtained similarly from $C D_{u \uparrow}(N)$ by adding a vertex $\top$ and an edge $((o u t, \epsilon), \top)$. We note $A^{\top}(N)=\{\top\} \cup A(N)$ and, for all path $u \in V_{N}, A_{u}^{\top}(N)=\{\top\} \cup A_{u}(N)$.

We use the convention that $u . \top=u^{-1} \cdot \top=\top$.
For all graph $G=(V, E)$ and set $V^{\prime}$, we note $\operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}$ the subgraph of the transitive closure of $G$ induced by $V^{\prime} \cap V$.

- Lemma 11. For all graphs $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$ and set $V$, if $V_{1} \cap V_{2} \subseteq V$, then $\operatorname{tr}\left(G_{1} \cup G_{2}\right)_{\left.\right|_{V}}=\operatorname{tr}\left(\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}\right)_{\left.\right|_{V}}$.

Proof. The set of vertices of both $\operatorname{tr}\left(G_{1} \cup G_{2}\right)_{\left.\right|_{V}}$ and $\operatorname{tr}\left(\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}\right)_{\left.\right|_{V}}$ is $V \cap\left(V_{1} \cup V_{2}\right)$.
For all vertices $x$ and $y$, if there is in $\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}}$ a path from $x$ to $y$ there exists a path from $x$ to $y$ in $G_{1}$. Then for all path in $\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}$ from $x$ to $y$ there is a path from $x$ to $y$ in $G_{1} \cup G_{2}$. So, for all edge $(x, y)$ in the graph $\operatorname{tr}\left(\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}\right)_{\left.\right|_{V}}$ there is an edge $(x, y)$ in $\operatorname{tr}\left(G_{1} \cup G_{2}\right)_{\left.\right|_{V}}$.

Let $(x, y) \in V^{2}$ be an edge of the graph $\operatorname{tr}\left(G_{1} \cup G_{2}\right)_{\left.\right|_{V}}$, then there is a path $w$ from $x$ to $y$ in $G_{1} \cup G_{2}$. This path can be written $w=w_{1} \ldots w_{n}$ where $w_{1}, \ldots, w_{n}$ are paths in either $G_{1}$ or $G_{2}$ and, for all $i \leq n-1$, if $w_{i}$ is a path in $G_{1}$ then $w_{i+1}$ is a path in $G_{2}$ and if $w_{i}$ is a path in $G_{2}$ then $w_{i+1}$ is a path in $G_{1}$. Then, for all $i \leq n-1$, the end vertex of path $w_{i}$ is in $V_{1} \cap V_{2}$. Since $V_{1} \cap V_{2} \subseteq V$ and $x$ and $y$ are in $V$, all start and end vertices of paths $w_{1}, \ldots, w_{n}$ are in $V$. Then for all path $w_{i}$ in $\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}}$ there is a path $w_{i}^{\prime}$ with same start and end vertices in the graph $G_{1}$. Therefore, noting $w_{i}^{\prime}=w_{i}$ if $w_{i}$ is a path in $G_{2}$ but not $G_{1}$ for all $i \leq n, w_{1}^{\prime}, \ldots, w_{n}^{\prime}$ is a path from $x$ to $y$ in $\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}$. So there is an edge $(x, y)$ in the graph $\operatorname{tr}\left(\operatorname{tr}\left(G_{1}\right)_{\left.\right|_{V}} \cup G_{2}\right)_{\left.\right|_{V}}$.

- Definition 12. For all tree path $u \in V_{N}$, we define the synthesis graph of path $u$ in $N$, noted $G S_{u}(N)$, as the graph $u^{-1} \cdot\left(\operatorname{tr}\left(D_{u \downarrow}(N)\right)_{\left.\right|_{A_{u}(N)}}\right)$.

For all tree path $u \in V_{N}$, we call the inheritance graph of path $u$ in $N$, noted $G I_{u}(N)$, the graph $u^{-1} \cdot\left(\operatorname{tr}\left(C D_{u \uparrow}^{\top}(N)\right)_{V^{\prime}}\right)$ where $V^{\prime}$ is the subset of $A_{u}^{\top}(N)$ of vertices connected to the vertex $\top$ in the graph $C D_{u \uparrow}^{\top}(N)$.

For every tree $N$ and path $u \in V_{N}$, the sets of nodes of $G S_{u}(N)$ and $G I_{u}(N)$ are $A_{\epsilon}\left(N \vdash_{u}\right)$ and $A_{\epsilon}^{\top}\left(N \vdash_{u}\right)$ respectively, since these sets are not dependent on the tree $N$ or the path $u$ we simply note them $A_{\epsilon}=(S \cup I) \times\{\epsilon\}$ and $A_{\epsilon}^{\top}=\{\top\} \cup A_{\epsilon}$ respectively.

- Lemma 13. For all $u \in V_{N}$, the edges of the $\operatorname{graph} G S_{u}(N)$ are of the form $((\alpha, \epsilon),(\gamma, \epsilon))$ with $\alpha \in S \cup I$ and $\gamma \in S$.
- Lemma 14. For all $u \in V_{N}, G S_{u}(N)=\operatorname{tr}\left(G(R(a)) \bigcup_{1 \leq i \leq n} i . G S_{u i}(N)\right)_{\left.\right|_{A_{\epsilon}^{\top}}}$ where $n$ is the arity of the node at path $u$ in $N$.

Proof. We note $G_{0}$ the graph $\operatorname{tr}\left(G(R(a)) \bigcup_{1 \leq i \leq n} i . G S_{u i}(N)\right)_{\left.\right|_{A_{e}^{\top}}}$. The graphs $G_{0}$ and $G S_{u}(N)$ have the same set of vertices $A_{\epsilon}$.

Let $(x, y)$ be an edge of the graph $G_{0}$, then, by definition of $G_{0}$, there is a path from u.x to $u . y$ in the graph $\bigcup_{i \leq n} u i . G S_{u i}(N) \cup u . G(R(a))$ (this works because $u$. is only a renaming of the attributes). By definition, any edge in $u \cdot G(R(a))$ is in $D_{u \downarrow}(N)$. For all $i \leq n$ and for all edge $\left(x_{i}, y_{i}\right)$ in $u i . G S_{u i}(N)$ there is a path in $D_{u i \downarrow}(N)$ from $x_{i}$ to $y_{i}$, then this path also exists in the graph $D_{u \downarrow}(N)$. Then there is in the graph $D_{u \downarrow}(N)$ a path from u.a to u.b. So the set of edges of $G_{0}$ is included in the set of edges of $G S_{u}(N)$.

Let $(x, y)$ be an edge of $G S_{u}(N)$, then there is in the graph $D_{u \downarrow}(N)$ a path from $u . x$ to $u . y$. This path is of the form $w_{1} e_{1} w_{2} \ldots w_{m} e_{m} w_{m+1}$ where $e_{1}, \ldots, e_{m}$ are edges in $u \cdot G(R(a))$ and $w_{1}, \ldots, w_{m+1}$ are paths with no edges in $u \cdot G(R(a))$. Since $D_{u \downarrow}(N)=$ $u \cdot G(R(a)) \cup \bigcup_{1 \leq i \leq n} D_{u i \downarrow}(N)$ and the graphs $D_{u i \downarrow}(N)$ have disjoint sets of vertices, for all $j \leq m+1$ there is an index $i_{j} \leq n$ such that the path $w_{j}$ is in the graph $D_{u i_{j} \downarrow}(N)$. Then for all $j \leq m+1$, noting $x_{j}$ and $y_{j}$ the respective start and end of path $w_{j}$, there is an edge $\left(x_{j}, y_{j}\right)$ in the graph $u i_{j} . G S_{u i_{j}}(N)$. Then the path $\left(x_{1}, y_{1}\right) e_{1} \ldots e_{m}\left(x_{m+1}, y_{m+1}\right)$ is in the graph $\bigcup_{i \leq n} u i . G S_{u i}(N) \cup u \cdot G(R(a))$, with $u . x=x_{1}$ and $u . y=y_{m+1}$. So there is a path from $x$ to $y$ in the graph $\bigcup_{i \leq n} i . G S_{u i}(N) \cup G(R(a))$, therefore there is an edge $(x, y)$ in the graph $\operatorname{tr}\left(\bigcup_{i \leq n} i . G S_{u i}(N) \cup \bar{G}(R(a))\right)_{\left.\right|_{A_{\epsilon}}}$, so that edge is in $G_{0}$.

So $G_{0}=G S_{u}(N)$.

- Lemma 15. There exists a bottom-up tree automaton A, whose set of states is the set of directed acyclic graphs with set of vertices $A_{\epsilon}$, which associates with any node in a tree $N$ the graph $G S_{u}(N)$.

Proof. We define the bottom-up tree automaton $\mathrm{A}=\left(\Sigma_{P}, \Sigma_{1}, R_{\mathrm{A}}\right)$ where $P$ is the set of states of the form $p_{G}$ where $G=(V, E)$ is a directed acyclic graph with $V=A_{\epsilon}$ and $E \subseteq\{((\alpha, \epsilon),(\gamma, \epsilon)) \mid \alpha \in S \cup I, \gamma \in S\}$, i.e. potential synthesis graphs according to lemma 13 ; and $R_{\mathrm{A}}$ is the set of rules of the form $a\left(p_{G_{1}} \ldots p_{G_{n}}\right) \rightarrow p_{G_{0}}$ where $a$ is a tree constant in $\Sigma_{1}$ of arity $n$, and $G_{0}$ is the graph $\operatorname{tr}\left(\bigcup_{i \leq n} i . G_{i} \cup G(R(a))\right)_{\left.\right|_{A_{\epsilon}}}$ where $G(R(a))$ is the graph induced by the equations of the attribute transducer associated with the tree constant $a$.

Lemma 14 implies by induction that automaton A indeed associates with any node at path $u$ in $N$ the synthesis graph $G S_{u}(N)$ of $N$ at path $u$.

- Definition 16. For all tree path $u \in V_{N}$, The interface graph of $N$ at path $u$ (noted $\left.G_{u}(N)\right)$ is the directed acyclic graph $u^{-1} \cdot\left(\operatorname{tr}\left(C D^{\top}(N)\right)_{\left.\right|_{V^{\prime}}}\right)$ where $V^{\prime}$ is the subset of $A_{u}^{\top}(N)$ of vertices connected to the vertex $\top$ in the graph $C D^{\top}(N)$.
- Lemma 17. For all path $u \in V_{N}, G_{u}(N)=\operatorname{tr}\left(G S_{u}(N) \cup G I_{u}(N)\right)_{V_{V^{\prime}}}$ where $V^{\prime}$ is the subset of $A_{\epsilon}^{\top}$ of vertices connected to the vertex $\top$ in the graph $G S_{u}(N) \cup G I_{u}(N)$.

Proof. We note $G=\operatorname{tr}\left(G S_{u}(N) \cup G I_{u}(N)\right)_{\left.\right|_{V^{\prime}}}$. We first prove the following claim:
$\triangleright$ Claim 18. For all $x, y \in A_{\epsilon}^{\top}$, there is a path from $u . x$ to $u . y$ in the graph $C D^{\top}(N)$ if and only if there is a path from $x$ to $y$ in the graph $G S_{u}(N) \cup G I_{u}(N)$.

Proof. Assume there is a path from $u . x$ to $u . y$ in $C D^{\top}(N)$. Since $C D^{\top}(N)=C D_{u \uparrow}^{\top}(N) \cup$ $D_{u \downarrow}(N)$, this path can be seen as a sequence of paths $w_{1} \ldots w_{m}$ alternating between graphs $C D_{u \uparrow}^{\top}(N)$ and $D_{u \downarrow}(N)$ (if $w_{i}$ is a path in the graph $C D_{u \uparrow}^{\top}(N)$ then $w_{i+1}$ is a path in $D_{u \downarrow}(N)$ and conversely). We note $x_{i}$ and $y_{i}$ the respective start and end of path $w_{i}$ for all $i \leq m$. For all $i \leq m-1$, since the vertex $y_{i}=x_{i+1}$ is in both graphs $C D_{u \uparrow}^{\top}(N)$ and $D_{u \downarrow}(N)$, it must be in the set $A_{u}(N)$. Then there is an edge $\left(x_{i}, y_{i}\right)$ in either $\operatorname{tr}\left(C D_{u \uparrow}^{\top}(N)\right)_{\left.\right|_{A_{u}(N)}}$ or
$\operatorname{tr}\left(D_{u \downarrow}(N)\right)_{\left.\right|_{A_{u}(N)}}$ for all $i \leq m$. Because $x=u^{-1} \cdot x_{1}$ and $y=u^{-1} \cdot y_{m}$, there is in the graph $G S_{u}(N) \cup G I_{u}(N)$ a path from $x$ to $y$.

Assume there is a path from $x$ to $y$ in $C D^{\top}(N)$. That path is of the form
$\left(x_{1}, x_{2}\right)\left(x_{2}, x_{3}\right) \ldots\left(x_{m}, x_{m+1}\right)$ where, for each $i \leq m,\left(x_{i}, x_{i+1}\right)$ is an edge of either $G S_{u}(N)$ or $G I_{u}(N)$. So, for all $i \leq m$, there is either in $C D_{u \uparrow}^{\top}(N)$ or in $D_{u \downarrow}(N)$ a path from $u . x_{i}$ to $u \cdot x_{i+1}$. Therefore we have in the graph $C D^{\top}(N)$ a path from $u \cdot x=u \cdot x_{1}$ to $u \cdot y=u \cdot x_{m+1}$.

This claim applied with $y=\top$ implies that $G$ and $G_{u}(N)$ have the same sets of vertices. The claim also implies that $(x, y)$ is an edge of $G$ if and only if $(x, y)$ is an edge of $G_{u}(N)$. So $G=G_{u}(N)$ for all path $u \in V_{N}$.

- Lemma 19. For all directed acyclic graph $G=(V, E)$, and subset $V^{\prime} \subseteq V$ of vertices, and for all two vertices $x, y \in V^{\prime}$, noting $\operatorname{tr}(G)_{V_{V^{\prime}}}=\left(V^{\prime}, E^{\prime}\right)$ the subgraph of the transitive closure of $G$ induced by the subset $V^{\prime}$ of vertices, if the graph $\left(V^{\prime}, E^{\prime} \cup\{(x, y)\}\right)$ is acyclic then the $\operatorname{graph}(V, E \cup\{(x, y)\})$ is also acyclic.

Proof. We use ad absurdum reasoning. We assume that the graph $\left(V^{\prime}, E^{\prime} \cup\{(x, y)\}\right)$ is acyclic and that there is a cycle in the graph $(V, E \cup\{(x, y)\})$. Since $(V, E)$ is acyclic the edge $(x, y)$ is part of the cycle, so the cycle is of the form $(x, y)\left(y, x_{1}\right) \ldots\left(x_{n}, x\right)$ with vertices $x_{1}, \ldots, x_{n} \in V$. Then there is a path from $y$ to $x$ in $G$, therefore there is an edge $(y, x)$ in $\operatorname{tr}(G)_{V^{\prime}}$, so $(y, x) \in E^{\prime}$. Then $\left(V^{\prime}, E^{\prime} \cup\{(x, y)\}\right)$ is not acyclic, which leads to a contradiction.

We will use the notations $A_{[1, n]}=\bigcup_{1 \leq j \leq n}(S \cup I) \times\{j\}, A_{[0, n]}=\bigcup_{0 \leq j \leq n}(S \cup I) \times\{j\}$ (with the convention that $0=\epsilon$ ), $A_{[1, n]}^{\top}=\{\top\} \cup A_{[1, n]}$ and $A_{[0, n]}^{\top}=\{\top\} \cup \bar{A}_{[0, n]}$.

- Definition 20. For all path $u \in V_{N}$, we define the local dependency graph of $N$ at path $u$, noted $G_{u \cdot[0, n]}(N)$ where $n$ is the arity of lab $b_{N}(u)$, as the graph $u^{-1} \cdot \operatorname{tr}\left(C D^{\top}(N)\right)_{\left.\right|_{V^{\prime}}}$ where $V^{\prime}$ is the set of vertices in $u . A_{[0, n]}^{\top}$ that are connected to the vertex $\top$ in the graph $C D^{\top}(N)$.
- Lemma 21. For all tree $N$ and path $u \in V_{N}$, noting $a=l a b_{N}(u)$ the constant of the node at path $u$ in $N$ and $n$ its arity, the local dependency graph $G_{u \cdot[0, n]}(N)$ of $N$ at path $u$ is $\operatorname{tr}\left(G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j . G S_{u j}(N)\right)_{\left.\right|_{V^{\prime}}}$ where $V^{\prime}$ is the set of vertices in $A_{[0, n]}^{\top}$ that are connected to the vertex $T$ in the graph $G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j . G S_{u j}(N)$.
Proof. We first prove the following claim:
$\triangleright$ Claim 22. For all vertices $x, y \in A_{[0, n]}^{\top}$, there is in the graph $C D^{\top}(N)$ a path from $u . x$ to $u . y$ if and only if there is a path from $u . x$ to $u . y$ in the graph $G=\operatorname{tr}\left(C D_{u \uparrow}^{\top}(N)\right)_{\left.\right|_{A_{u}^{\top}(N)}} \cup$ $u . G(R(a)) \cup \bigcup_{1 \leq i \leq n} \operatorname{tr}\left(D_{u i \downarrow}(N)\right)_{\left.\right|_{A_{u j}(N)}}$.
Proof. If there is a path from u.x to $u . y$ in $G$ then, because $C D^{\top}(N)=C D_{u \uparrow}^{\top}(N) \cup$ $u . G(R(a)) \cup \bigcup_{1 \leq i \leq n} D_{u i \downarrow}(N)$, there must be a path from $u . x$ to $u . y$ in $C D^{\top}(N)$.

If there is a path from $u . x$ to $u . y$ in $C D^{\top}(N)$, then this path can be seen as a sequence $w_{1} \ldots w_{m}$ of paths where each $w_{j}$ with $j \leq m$ is a path in either one of the following $n+2$ graphs: $C D_{u \uparrow}^{\top}(N), D_{u 1 \downarrow}(N), \ldots D_{u n \downarrow}(N), u \cdot G(R(a))$, and, for each $j \leq m-1, w_{j+1}$ is a path in a different graph than $w_{j}$. Noting $x_{j}$ the end of path $w_{j}$ or start of path $w_{j+1}$, since $w_{j}$ and $w_{j+1}$ are paths of a different graph among $C D_{u \uparrow}^{\top}(N), D_{u 1 \downarrow}(N), \ldots D_{u n \downarrow}(N)$ and $u . G(R(a))$, $x_{j}$ is in the intersection of the sets of vertices of these two graphs, which is necessarily included in the set $u \cdot A_{[0, n]}^{\top}(N) . x_{0}=u . x$ and $x_{m}=u . y$ are also in the set $u \cdot A_{[0, n]}^{\top}(N)$. This implies that if $w_{j}$ is a path in $C D_{u \uparrow}^{\top}(N)$ then there is $\operatorname{in} \operatorname{tr}\left(C D_{u \uparrow}^{\top}(N)\right)_{\left.\right|_{A_{u}^{\top}(N)}}$ a path $w_{j}^{\prime}$ from $x_{j-1}$ to $x_{j}$. Also if $w_{j}$ is a path in $D_{u i \downarrow}(N)$ then there is in $\operatorname{tr}\left(D_{u i \downarrow}(N)\right)_{\left.\right|_{A_{j}(N)}}$ a path $w_{j}^{\prime}$ from $x_{j-1}$ to
$x_{j}$. So there is in the graph $G=\operatorname{tr}\left(C D_{u \uparrow}^{\top}(N)\right)_{\left.\right|_{A_{u}^{\top}(N)}} \cup u . G(R(a)) \cup \bigcup_{1 \leq i \leq n} \operatorname{tr}\left(D_{u i \downarrow}(N)\right)_{\left.\right|_{A_{u j}(N)}}$ a path from $u . x$ to u.y.

Since $G_{u \cdot[0, n]}(N)=u^{-1} \cdot \operatorname{tr}\left(C D^{\top}(N)\right)_{\left.\right|_{u, A_{[0, n]}} ^{\top}}$ and $\operatorname{tr}\left(G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j \cdot G S_{u j}(N)\right)_{\left.\right|_{A_{[0, n]}^{\top}} ^{\top}}=u^{-1} \cdot \operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}$, the claim implies that the set of vertices of the graph $G_{u .[0, n]}(N)$ is the set $V^{\prime}$ of vertices in $A_{[0, n]}^{\top}$ that are connected to the vertex $\top$ in the graph $G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j . G S_{u j}(N)$.

It also entails that, for all vertices $x, y \in V^{\prime}$, there is in the graph $G_{u \cdot[0, n]}(N)$ an edge $(x, y)$ if and only if $(x, y)$ is an edge in the graph $\operatorname{tr}\left(G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j . G S_{u j}(N)\right)_{\left.\right|_{V^{\prime}}}$.

Therefore $G_{u .[0, n]}(N)=\operatorname{tr}\left(G I_{u}(N) \cup G(R(a)) \cup \bigcup_{1 \leq j \leq n} j . G S_{u j}(N)\right)_{\left.\right|_{V^{\prime}}}$.

- Corollary 23. The local dependency graph $G_{u \cdot[0, n]}(N)$ can be computed using only the constant lab ${ }_{N}(u)$, the inheritance graph of $N$ at path $u$ and the synthesis graphs of $N$ at paths $u 1, \ldots, u n$.
- Lemma 24. If $C D^{\top}(N)$ is a tree then, for all path $u \in V_{N}, G_{u .[0, n]}(N)$ is a tree.

Proof. We use ad absurdum reasoning. We assume that $G_{u .[0, n]}(N)$ is not a tree, so there exists two nodes $x, y$ and two distinct paths from $x$ to $y$ in $G_{u .[0, n]}(N)=u^{-1} \cdot \operatorname{tr}\left(C D^{\top}(N)\right)_{\left.\right|_{V^{\prime}}}$. Then there are two distinct paths from $u . x$ to $u . y$ in $C D^{\top}(N)$, then $C D^{\top}(N)$ is not a tree.

- Corollary 25. If the ATT is single use restricted then for all input tree $N$ and path $u \in V_{N}$, the graph $G_{u \cdot[0, n]}(N)$ is a tree.


## B.2.2 Topological sorts

In order to sequentialize the computation of attributes, we use topological sorts of the graphs of dependency prevously defined. We will later need to use induction on the sorted attributes, in order to facilitate that we define our topological sorts as sequences of attributes:

- Definition 26. We call a total order $<$ on a finite set $V$ compatible with a directed acyclic graph $G=(V, E)$ if, for all edge $\left(v, v^{\prime}\right) \in E, v<v^{\prime}$.

Noting $n$ the size of the set $V$, for all sequence $\tau=v_{1} \ldots v_{n} \in V^{*}$ of length $n$ such that $i \neq j \Rightarrow v_{i} \neq v_{j}$ for all $1 \leq i, j \leq n$, we associate with $\tau$ the unique total order $<$ on $V$ such that $i<j \Leftrightarrow v_{i}<v_{j}$ for all $1 \leq i, j \leq n$.

We call a sequence $\tau \in V^{*}$ a topological sort of a directed acyclic graph $G=(V, E)$ if it is of length $n$ and the total order $<$ associated with it is compatible with $G$.

- Lemma 27. For all directed acyclic graph $G$ we can build a topological sort $\tau$ of $G$.

Proof. We build $\tau$ inductively. We note $G=(V, E)$.
Since $G$ is acyclic there exists a vertex $x$ of $G$ which has no incoming edges. We use induction and assume we can build a topological sort $\tau^{\prime}$ of the subgraph of $G$ induced by the set $V \backslash\{x\}$ of vertices. Then $\tau=x \tau^{\prime}$ is a topological sort of $G$.

- Lemma 28. For all path $u \in V_{N}$ any topological sort $\tau$ of $G_{u}(N)$ is of the form $\tau=\tau^{\prime}(\alpha, \epsilon) \top$ with $\alpha \in S$.

Proof. By definition of $G_{u}(N)$, from any vertex of $G_{u}(N)$ there is a path to $\top$, so a topological sort of $G_{u}(N)$ must end with $\top$. The form of the rules of the attribute transducer imply that if there is a path in $G_{u}(N)$ from $(\gamma, \epsilon)$ to $\top$ with $\gamma \in I$ then there must exists $\alpha \in S$
and a path in the graph $G_{u}(N)$ from $(\alpha, \epsilon)$ to $(\gamma, \epsilon)$. So any topological sort of $G_{u}(N)$ ends with $(\alpha, \epsilon) \top$ for some $\alpha \in S$.

- Definition 29. For all sets $V$ and $V^{\prime}$ such that $V^{\prime} \subset V$, for all graph $G=(V, E)$ and topological sort $\tau$ of $G$, we call topological subsort induced by the subset $V^{\prime}$, and we note $\left.\tau\right|_{V^{\prime}}$, the biggest subsequence of $\tau$ included in $V^{* *}$.
- Lemma 30. For all directed acyclic graph $G=(V, E)$, topological sort $\tau$ of $G$ and subset $V^{\prime}$ of $V,\left.\tau\right|_{V^{\prime}}$ is a topological sort of $\operatorname{tr}(G)_{V_{V^{\prime}}}$.
Proof. We note $G^{\prime}=\operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}=\left(V^{\prime}, E^{\prime}\right)$. Let $(a, b)$ be an edge in $E^{\prime}$, then there is a path in the graph $G$ from $a$ to $b$ of the form $a v_{1} \ldots v_{m} b$. So, noting $<_{\tau}$ the total order on $V$ associated with $\tau, a<_{\tau} v_{1}<_{\tau} \cdots<_{\tau} v_{m}<_{\tau} b$. Therefore $a<_{\tau} b$, and $a$ appears in the sequence $\tau$ strictly before $b$. Then $a$ appears in the sequence $\left.\tau\right|_{V^{\prime}}$ strictly before $b$, and $a<_{\tau^{\prime}} b$ where $<_{\tau^{\prime}}$ is the total order on $V^{\prime}$ associated with $\left.\tau\right|_{V^{\prime}}$.

We have shown that $<_{\tau^{\prime}}$ is compatible with $G^{\prime}$, so $\left.\tau\right|_{V^{\prime}}$ is a topological sort of $\operatorname{tr}(G)_{V_{V^{\prime}}}$.

- Lemma 31. For all directed acyclic graph $G=(V, E)$, subset $V^{\prime}$ of $V$ and topological sort $\tau^{\prime}$ of $\operatorname{tr}(G)_{V^{\prime}}$, there exists a topological sort $\tau$ of $G$ such that $\tau^{\prime}=\left.\tau\right|_{V^{\prime}}$.
Proof. We note $x_{1}, \ldots, x_{n}$ the vertices in $V^{\prime}$ such that $\tau^{\prime}=x_{1} \ldots x_{n}$, and $\operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}=\left(V^{\prime}, E^{\prime}\right)$. We note $E_{\tau^{\prime}}$ the set of edges $E_{\tau^{\prime}}=\left\{\left(x_{i}, x_{j}\right)\right\}_{1 \leq i<j \leq n}$, then we show that the graph $G^{\prime}=$ $\left(V^{\prime}, E^{\prime} \cup E_{\tau^{\prime}}\right)$ is acyclic.

If $G^{\prime}$ contained a cycle, it would imply that there was in $\left(V^{\prime}, E^{\prime}\right)$ a path from $x_{j}$ to $x_{i}$ with $i<j$, which is contradicts the fact that $\tau^{\prime}=x_{1} \ldots x_{n}$ is a topological sort of $\left(V^{\prime}, E^{\prime}\right)$.

Since $\left(V^{\prime}, E^{\prime} \cup E_{\tau^{\prime}}\right)$ is acyclic, we can use lemma 19 and deduce that $\left(V, E \cup E_{\tau^{\prime}}\right)$ is also acyclic. Then there exists a topological sort $\tau$ of $\left(V, E \cup E_{\tau^{\prime}}\right)$. Because $E_{\tau^{\prime}}=\left\{\left(x_{i}, x_{j}\right)\right\}_{1 \leq i<j \leq n}$ and by definition of topological sorts: $\left.\tau\right|_{V^{\prime}}=\tau^{\prime}$. Also $\tau$ is a topological sort of $G$.

Definition 32. For all graphs $G$ and $\tilde{G}$ with the same set of vertices, we say that $\tilde{G}$ is an over-specification of $G$, and we note $\tilde{G} \unrhd G$, if all topological sort of $\tilde{G}$ is a topological sort of $G$.

- Lemma 33. The relation $\unrhd$ has the following properties:

1. for all graphs $G_{1}, G_{2}$ and $G_{3}, G_{1} \unrhd G_{2} \unrhd G_{3} \Rightarrow G_{1} \unrhd G_{3}$ (transitivity),
2. for all graphs $G=(V, E)$ and $\tilde{G}=(V, \tilde{E}), E \subseteq \tilde{E} \Rightarrow \tilde{G} \unrhd G$,
3. for all graph $G=(V, E), G \unrhd \operatorname{tr}(G)_{\mid V} \unrhd G$,
4. for all graphs $G$ and $\tilde{G}$ and set $V^{\prime}, \tilde{G} \unrhd G \Rightarrow \operatorname{tr}(\tilde{G})_{\left.\right|_{V^{\prime}}} \unrhd \operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}$
5. for all graphs $G_{1}, G_{2}, \tilde{G}_{1}$ and $\tilde{G}_{2}, \tilde{G}_{1} \unrhd G_{1}$ and $\tilde{G}_{2} \unrhd G_{2} \Rightarrow \tilde{G}_{1} \cup \tilde{G}_{2} \unrhd G_{1} \cup G_{2}$

Proof.

1. Implied by the definition of $\unrhd$.
2. Implied by the definition of topological sorts.
3. The previous point implies that $\operatorname{tr}(G)_{\left.\right|_{V}} \unrhd G$. For all topological sort $\tau$ of $G$, by transitivity of the order associated with $\tau, \tau$ is also a topological order of the transitive closure $\operatorname{tr}(G)_{\left.\right|_{V}}$ of $G$. So $G \unrhd \operatorname{tr}(G)_{\mid V}$.
4. For all topological sort $\tau^{\prime}$ of $\operatorname{tr}(\tilde{G})_{\left.\right|_{V^{\prime}}}$, according to lemma 31, there is a topological sort $\tau$ of $\tilde{G}$ such that $\left.\tau\right|_{V^{\prime}}=\tau^{\prime}$. Then $\tau$ is also a topological sort of $G$ and, according to lemma $30, \tau^{\prime}=\left.\tau\right|_{V^{\prime}}$ is a topological sort of $\operatorname{tr}(G)_{\left.\right|_{V^{\prime}}}$.
5. Let us assume that $\tilde{G}_{1} \unrhd G_{1}$ and $\tilde{G}_{2} \unrhd G_{2}$ with $G_{1}=\left(V_{1}, E_{1}\right)$ and $G_{2}=\left(V_{2}, E_{2}\right)$. For all topological sort $\tau$ of $\tilde{G}_{1} \cup \tilde{G}_{2}$, according to lemma $30,\left.\tau\right|_{V_{1}}$ and $\left.\tau\right|_{V_{2}}$ are topological sorts of $\tilde{G}_{1}$ and $\tilde{G}_{2}$ respectively. So $\left.\tau\right|_{V_{1}}$ and $\left.\tau\right|_{V_{2}}$ respectively are topological sorts of $G_{1}$ and $G_{2}$. So $\tau$ is a topological sort of $G_{1} \cup G_{2}$. Therefore $\tilde{G}_{1} \cup \tilde{G}_{2} \unrhd G_{1} \cup G_{2}$.
${ }_{1114}$ is also the set of vertices connected to $\top$ in the graph $\bigcup_{1<i \leq n} i . G_{i} \cup G(R(a)) \cup G I_{u}(N)$
1115 Then, according to lemma 21, $G_{u \cdot[0, n]}(N)=\operatorname{tr}\left(\bigcup_{1 \leq i \leq n} i . G_{i} \cup G(R(a)) \cup G I_{u}(N)\right)_{\left.\right|_{V^{\prime \prime}}}$. So
${ }_{1116} G$ can be obtained from $G_{u .[0, n]}(N)$ by adding edges, therefore $G \unrhd G_{u .[0, n]}(N)$. So $\tau$ is a 1117 topological sort of $G_{u .[0, n]}(N)$.

- Lemma 36. For all path $u \in V_{N}$ any topological sort $\tau$ of $G_{u \cdot[0, n]}(N)$ is of the form $\tau=\tau^{\prime}(\alpha, \epsilon) \top$ with $\alpha \in S$.

Proof. Similar to proof of lemma 28.
From now on, when we introduce a topological sort $\tau$ over a subset of $A_{\epsilon}^{\top}$ or $A_{[0, n]}^{\top}$, we assume it is of the form described in lemmas 28 and 36 .

## B.2.3 Sequentializing the computation of attributes

For all input tree $N$ and path $u \in V_{N}$, a topological sort of the interface graph $G_{u}(N)$ gives an order in which the attibutes can be computed. The type of the output $\lambda$-term of the subtree $N \downharpoonright_{u}$ then depends on the topological sort of $G_{u}(N)$ which gives the computation order of the attributes. That type is defined as follows:

- Definition 37. For all topological sort $\tau$ over a subset of $A_{\epsilon}^{\top}$ (of the form described in lemma 28), we associate with $\tau$ the type $t(\tau)$ inductively defined by:
- if $\tau$ is of the form $(\alpha, \epsilon) \tau^{\prime}$ with $\alpha \in S$ then $t(\tau) \triangleq o \times t\left(\tau^{\prime}\right)$,
- if $\tau$ is of the form $(\alpha, \epsilon) \tau^{\prime}$ with $\alpha \in I$ then $t(\tau) \triangleq o \rightarrow t\left(\tau^{\prime}\right)$,
- if $\tau=(\alpha, \epsilon) \top$ where $\alpha \in S$, then $t(\tau) \triangleq o$.

For all input tree $N$ and path $u \in V_{N}$, we want to associate a $\lambda$-term with the subtree $N \iota_{u}$ of $N$ which sequentializes the computation of the attributes of the node at path $u$, in order to do so we use a topological sort of the interface graph at path $u$ in $N$, with the following semantics:

- Definition 38. For all topological sort $\tau$ over the set $A_{\epsilon}^{\top}$, term $N$ and path $u \in V_{N}$, noting $\operatorname{Att}(N,(\alpha, u))$ the tree associated with the attribute $(\alpha, u)$ in the ATT, we define $\mathcal{R}_{\tau}(N, u)$ by induction on $\tau$ :
- $\mathcal{R}_{(\alpha, u) \tau^{\prime}}(N, u) \triangleq\left\{\left(M_{1}, M_{2}\right) \mid M_{1} \rightarrow_{\beta \eta}^{*} \operatorname{Att}(N,(\alpha, u)), M_{2} \in \mathcal{R}_{\tau^{\prime}}(N, u)\right\}$ if $\alpha \in S$,
- $\mathcal{R}_{(\alpha, u) \tau^{\prime}}(N, u) \triangleq\left\{M \mid M(\operatorname{Att}(N,(\alpha, u))) \in \mathcal{R}_{\tau^{\prime}}(N, u)\right\}$ if $\alpha \in I$.
- $\mathcal{R}_{(\alpha, \epsilon) \top}(N, u) \triangleq\left\{M \mid M \rightarrow_{\beta \eta}^{*} \operatorname{Att}(N,(\alpha, u))\right\}$ where $\alpha \in S$.

Notice that terms in $\mathcal{R}_{\tau}(N, u)$ have type $t(\tau)$.

- Lemma 39. For all terms $M$ and $M^{\prime}$ that are $\beta \eta$-equivalent,
$M \in \mathcal{R}_{\tau}(N, u) \Leftrightarrow M^{\prime} \in \mathcal{R}_{\tau}(N, u)$
Proof. Straightforward induction on $\tau$.
For the purpose of clarity, we will use a special notation for the binding of variables: for binding a variable $x$ to a term $M$ inside a term $M^{\prime}$, in place of $\left(\lambda x . M^{\prime}\right) M$ we will write let $x=M$ in $M^{\prime}$. We want to build a $\lambda$-term which computes the term associated with a node depending on the terms associated with its child nodes. That will depend on a topological sort of the local dependency graph, which gives an order to compute the attributes of the nodes and its child nodes. We use the following definition:
- Definition 40. For all tree constant a of arity $n$ in $\Sigma$, for all topological sort $\tau$ over a subset of $A_{[0, n]}^{\top}$, injective substitution var which associates variables of type o with attributes and injective substitution Cont which associates variables with indices between 1 and $n$ such that for all $i \in[1, n]$, Cont $(i)$ is of type $t\left(\left.\tau\right|_{A_{i}^{\top}}\right)$, we define the term $\mathbb{M}_{a}(\tau$, var, Cont) by induction on $\tau$ as follows:

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    158 - if \(\tau=(\alpha, 0) \top\) with \(\alpha \in S\) then : \(\mathbb{M}_{a}(\tau, \operatorname{var}, \operatorname{Cont}) \triangleq \operatorname{var}(R(a)((\alpha, 0)))\)
1159 - if \(\tau=(\alpha, 0) \tau^{\prime}\) with \(\alpha \in S\) and \(\tau^{\prime} \neq \top\) then:
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1161
1162
    \(\mathbb{M}_{a}(\tau, \operatorname{var}\), Cont \() \triangleq\) let \(y_{(\alpha, 0)}=\operatorname{var}(R(a)((\alpha, 0)))\) in
        \(\left(y_{(\alpha, 0)}, \mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, 0) \rightarrow y_{(\alpha, 0)}\right]\right.\right.\), Cont \(\left.)\right)\)
    - if \(\tau=(\gamma, 0) \tau^{\prime}\) with \(\gamma \in I\) then :
    \(\mathbb{M}_{a}(\tau, \operatorname{var}\), Cont \() \triangleq \lambda y_{(\gamma, 0)} \cdot \mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, 0) \rightarrow y_{(\gamma, 0)}\right]\right.\), Cont \()\)
- if \(\tau=(\alpha, i) \tau^{\prime}\) with \(\alpha \in S, i \neq 0\) and \(\left.\tau\right|_{A_{i}^{\top}} \neq(\alpha, i) \top\) then:
    \(\mathbb{M}_{a}(\tau, \operatorname{var}, \operatorname{Cont}) \triangleq \operatorname{let}\left(y_{(\alpha, i)}, X_{i}^{\prime}\right)=\operatorname{Cont}(i)\) in
        \(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.\), Cont \(\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\)
    with \(X_{i}^{\prime}\) a fresh variable of type \(t\left(\left.\tau^{\prime}\right|_{A_{i}^{\top}}\right)\).
- if \(\tau=(\alpha, i) \tau^{\prime}\) with \(\alpha \in S, i \neq 0\) and \(\left.\tau\right|_{A_{i}^{\top}}=(\alpha, i) \top\) then:
    \(\mathbb{M}_{a}(\tau, v a r\), Cont \() \triangleq\) let \(y_{(\alpha, i)}=\operatorname{Cont}(i)\) in \(\mathbb{M}_{a}\left(\tau^{\prime}, v a r \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.\), Cont \()\)
    where Cont \({ }^{\prime}\) is Cont from which we removed the association \([i \rightarrow \operatorname{Cont}(i)]\).
- if \(\tau=(\gamma, i) \tau^{\prime}\) with \(\gamma \in I\) and \(i \neq 0\) then:
    \(\mathbb{M}_{a}(\tau, \operatorname{var}\), Cont \() \triangleq\) let \(y_{(\gamma, i)}=\operatorname{var}(R(a)((\gamma, i)))\) and \(X_{i}^{\prime}=\operatorname{Cont}(i) y_{(\gamma, i)}\) in
                                    \(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, i) \rightarrow y_{(\gamma, i)}\right]\right.\), Cont \(\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\)
    where \(X_{i}^{\prime}\) is a fresh variable of type \(t\left(\left.\tau^{\prime}\right|_{A_{i}^{\top}}\right)\).
Then we prove that \(\mathbb{M}_{a}\) fits the semantics we have chosen:
- Lemma 41. For all constant a of arity \(n\) in \(\Sigma\), and for all topological sort \(\tau\) over a subset of \(A_{[0, n]}^{\top}\), noting \(\tau_{i}=\left.\tau\right|_{A_{i}^{\top}}\) for \(i \leq n\), noting \(M=\mathbb{M}_{a}(\tau\), var, Cont) where var is the empty substitution and for all \(i \in[1, n]\), Cont \((i)=X_{i}\) with \(X_{i}\) a free variable of type \(t\left(\tau_{i}\right)\), then \(M\) is of type \(t\left(\tau_{0}\right)\) and, for all tree \(N\) and path \(u \in V_{N}\) such that \(l a b_{N}(u)=a\) and \(\tau\) is a topological sort of \(G_{u .[0, n]}(N)\), for all terms \(M_{1} \in \mathcal{R}_{\tau_{1}}(N, u 1), \ldots, M_{n} \in \mathcal{R}_{\tau_{n}}(N, u n)\) :
\[
M\left[X_{1} / M_{1}, \ldots, X_{n} / M_{n}\right] \in \mathcal{R}_{\tau_{0}}(N, u)
\]
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Proof. We first prove a more general claim by induction on $\tau$ :
$\triangleright$ Claim 42. For all topological sort $\tau$ over a subset of $A_{[0, n]}^{\top}$, for all tree $N$ and path $u \in V_{N}$ such that $l a b_{N}(u)=a$ and $\tau$ is a topological sort of $G_{u .[0, n]}(N)$, for all injective mapping var from attributes to variables such that, for all $(\alpha, i) \in \tau$, all attribute appearing in $R(a)((\alpha, i))$ is either in $\tau$ or in the domain of var, for all function Cont associating variables with indices $i \in[1, n]$ and for all substitution $\sigma$ of the variables in Cont such that $\forall i \in[1, n], \sigma(\operatorname{Cont}(i)) \in \mathcal{R}_{\tau_{i}}(N, u i)$ with $\tau_{i}=\left.\tau\right|_{A_{i}^{\top}}:$
$\sigma \circ \nu\left(\mathbb{M}_{a}(\tau\right.$, var, Cont $\left.)\right) \in \mathcal{R}_{\tau_{0}}(N, u)$
where $\nu$ is the variable substitution such that for all attribute ( $\alpha, i$ ) in dom(var):
$\nu(\operatorname{var}((\alpha, i)))=\operatorname{Att}(N,(\alpha, u i))$.
Proof. We fix a topological sort $\tau$ over a subset of $A_{[0, n]}^{\top}$, an input tree $N$, a path $u \in V_{N}$ such that $l a b_{N}(u)=a$ and $\tau$ is a topological sort of $G_{u \cdot[0, n]}(N)$, an injective mapping var from attributes to variables such that, noting dom(var) its domain, for all $(\alpha, i) \in \tau$, all attribute appearing in $R(a)((\alpha, i))$ is either in $\tau$ or in dom(var). We note $\nu$ the variable substitution such that for all attribute $(\alpha, i) \in \operatorname{dom}(\operatorname{var}), \nu(\operatorname{var}((\alpha, i)))=\operatorname{Att}(N,(\alpha, u i))$ (exists because var is injective), we also fix a function Cont associating variables with indices in $[1, n]$, and a substitution $\sigma$ of the free variables in Cont such that $\forall i \in[1, n], \sigma(\operatorname{Cont}(i)) \in \mathcal{R}_{\tau_{i}}(N, u i)$ where $\tau_{i}=\left.\tau\right|_{A_{i}^{\top}}$.

We assume the induction hypothesis for all topological sort $\tau^{\prime}$ shorter (with a smaller number of elements) than $\tau$.

As in the definition of $\mathbb{M}_{a}$ we have 6 cases:

- if $\tau=(\alpha, 0) \top$ with $\alpha \in S$ then $\mathbb{M}_{a}(\tau, \operatorname{var}$, Cont $) \triangleq \operatorname{var}(R(a)((\alpha, 0)))$. In this case $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau, \operatorname{var}\right.$, Cont $\left.)\right)=\nu \circ \operatorname{var}(R(a)((\alpha, 0)))$. Since all attributes appearing in $R(a)((\alpha, 0))$ are in dom $(v a r)$, and $\forall(\alpha, i) \in \operatorname{dom}(v a r), \nu(\operatorname{var}((\alpha, i)))=\operatorname{Att}(N,(\alpha, u i))$. Then by definition of $\operatorname{Att}(N,(\alpha, u))$ with $l a b_{N}(u)=a$ : $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau, \operatorname{var}\right.$, Cont $\left.)\right)=\operatorname{Att}(N,(\alpha, u)) \in \mathcal{R}_{(\alpha, 0) \top}(N, u)$.
- if $\tau=(\alpha, 0) \tau^{\prime}$ with $\alpha \in S$ and $\tau^{\prime} \neq \top$ then $\mathbb{M}_{a}(\tau, v a r$, Cont $) \triangleq$ let $y_{(\alpha, 0)}=\operatorname{var}(R(a)((\alpha, 0)))$ in $\left(y_{(\alpha, 0)}, \mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, 0) \rightarrow y_{(\alpha, 0)}\right]\right.\right.$, Cont $\left.)\right)$.
The induction hypothesis implies that $\sigma \circ \nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, v a r\right.\right.$, Cont $\left.)\right) \in \mathcal{R}_{\tau_{0}^{\prime}}(N, u)$ where $\nu^{\prime}=\nu \uplus\left[y_{(\alpha, 0)} \rightarrow \operatorname{Att}(N,(\alpha, u))\right]$. Similarly to the case $\tau=(\alpha, 0) \top$ : $\nu(\operatorname{var}(R(a)((\alpha, 0))))=\operatorname{Att}(N,(\alpha, u))$.
Therefore $\sigma \circ \nu\left(\mathbb{M}_{a}\left((\alpha, 0) \tau^{\prime}, v a r\right.\right.$, Cont $\left.)\right) \in \mathcal{R}_{(\alpha, 0) \tau_{0}^{\prime}}(N, u)$.
- if $\tau=(\gamma, 0) \tau^{\prime}$ with $\gamma \in I$ then
$\mathbb{M}_{a}(\tau, \operatorname{var}$, Cont $) \triangleq \lambda y_{(\gamma, 0)} \cdot \mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, 0) \rightarrow y_{(\gamma, 0)}\right]\right.$, Cont $)$. The induction hypothesis entails that $\sigma \circ \nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, 0) \rightarrow y_{(\gamma, 0)}\right]\right.\right.$, Cont $\left.)\right) \in \mathcal{R}_{\tau_{0}^{\prime}}(N, u)$ where
$\nu^{\prime}=\nu \uplus\left[y_{(\gamma, 0)} \rightarrow \operatorname{Att}(N,(\gamma, u))\right]$. Then, by definition of $\mathcal{R}_{(\gamma, 0) \tau_{0}^{\prime}}(N, u)$ for $\gamma \in I$, $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau\right.$, var, Cont $\left.)\right) \in \mathcal{R}_{(\gamma, 0) \tau_{0}^{\prime}}(N, u)$.
- if $\tau=(\alpha, i) \tau^{\prime}$ with $\alpha \in S, i \neq 0$ and $\tau_{i} \neq(\alpha, i) \top$ then $\mathbb{M}_{a}(\tau$, var, Cont $) \triangleq$
let $\left(y_{(\alpha, i)}, X_{i}^{\prime}\right)=\operatorname{Cont}(i)$ in $\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.$, Cont $\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)$ where $X_{i}^{\prime}$ is a fresh variable of type $t\left(\tau_{i}^{\prime}\right)$. Noting $\left(M_{1}, M_{2}\right)=\sigma(\operatorname{Cont}(i)) \in \mathcal{R}_{(\alpha, i) \tau_{i}^{\prime}}(N, u i)$, we have $M_{1} \rightarrow_{\beta \eta}^{*} \operatorname{Att}(N,(\alpha, u i))$ and $M_{2} \in \mathcal{R}_{\tau_{i}^{\prime}}(N, u i)$. So we apply the induction hypothesis on $\sigma^{\prime} \circ \nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.\right.$, Cont $\left.\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\right)$ where
$\nu^{\prime}=\nu \uplus\left[y_{(\alpha, i)} \rightarrow \operatorname{Att}(N,(\alpha, u i))\right]$ and $\sigma^{\prime}$ is obtained from $\sigma$ by removing the association $[\operatorname{Cont}(i) \rightarrow \sigma(\operatorname{Cont}(i))]$ and adding $\left[X_{i}^{\prime} \rightarrow M_{2}\right]$. So
$\sigma \circ \nu\left(\mathbb{M}_{a}(\tau\right.$, var, Cont $\left.)\right)={ }_{\beta \eta} \sigma^{\prime} \circ \nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.\right.$, Cont $\left.\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\right)$
and therefore $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau\right.$, var, Cont $\left.)\right) \in \mathcal{R}_{\tau_{0}}(N, u)$.
- if $\tau=(\alpha, i) \tau^{\prime}$ with $\alpha \in S, i \neq 0$ and $\tau_{i}=(\alpha, i) \top$ then $\mathbb{M}_{a}(\tau$, var, Cont $) \triangleq$
let $y_{(\alpha, i)}=\operatorname{Cont}(i)$ in $\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\alpha, i) \rightarrow y_{(\alpha, i)}\right]\right.$, Cont $\left.{ }^{\prime}\right)$ where Cont' is Cont from which we removed the association $i \rightarrow \operatorname{Cont}(i)$. This case is analogous to the previous one, and with the same arguments we reach the conclusion that $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau, v a r, \operatorname{Cont})\right) \in \mathcal{R}_{\tau_{0}}(N, u)$.
- if $\tau=(\gamma, i) \tau^{\prime}$ with $\gamma \in I$ and $i \neq 0$ then
$\mathbb{M}_{a}(\tau, \operatorname{var}$, Cont $) \triangleq$ let $y_{(\gamma, i)}=\operatorname{var}(R(a)((\gamma, i)))$ and $X_{i}^{\prime}=\operatorname{Cont}(i) y_{(\gamma, i)}$ in

$$
\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, i) \rightarrow y_{(\gamma, i)}\right], \text { Cont } \circ\left[i \rightarrow X_{i}^{\prime}\right]\right)
$$

where $X_{i}^{\prime}$ is a fresh variable of type $t\left(\tau_{i}^{\prime}\right)$. We have $\sigma(\operatorname{Cont}(i)) \in \mathcal{R}_{(\gamma, i) \tau_{i}^{\prime}}(N, u i)$ and $\nu(\operatorname{var}(R(a)((\gamma, i))))={ }_{\beta \eta} \operatorname{Att}(N,(\gamma, u i))$, then
$\sigma(\operatorname{Cont}(i)) \nu(\operatorname{var}(R(a)((\gamma, i)))) \in \mathcal{R}_{\tau_{i}^{\prime}}(N, u i)$. We apply the induction hypothesis on $\sigma^{\prime} \circ$ $\nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, i) \rightarrow y_{(\gamma, i)}\right]\right.\right.$, Cont $\left.\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\right)$ where $\nu^{\prime}=\nu \uplus\left[y_{(\gamma, i)} \rightarrow \operatorname{Att}(N,(\gamma, u i))\right]$ and $\sigma^{\prime}$ is obtained from $\sigma$ by removing the association $[\operatorname{Cont}(i) \rightarrow \sigma(\operatorname{Cont}(i))]$ and adding $\left[X_{i}^{\prime} \rightarrow \sigma(\operatorname{Cont}(i)) \nu(\operatorname{var}(R(a)((\gamma, i))))\right]$. Therefore $\sigma \circ \nu\left(\mathbb{M}_{a}(\tau, v a r\right.$, Cont $\left.)\right)=$ $\sigma^{\prime} \circ \nu^{\prime}\left(\mathbb{M}_{a}\left(\tau^{\prime}, \operatorname{var} \uplus\left[(\gamma, i) \rightarrow y_{(\gamma, i)}\right]\right.\right.$, Cont $\left.\left.\circ\left[i \rightarrow X_{i}^{\prime}\right]\right)\right) \in \mathcal{R}_{\tau_{0}}(N, u)$.
This ends the inductive proof of the claim.
Since $\tau$ is a topological sort of the graph $G_{u .[0, n]}(N)$, for all $(\alpha, i) \in \tau$, all attribute appearing in $R(a)((\alpha, i))$ is in $\tau$. Therefore we can apply the claim on $\tau$ with $\operatorname{Cont}(i)$ the substitution such that $\operatorname{Cont}(i)=X_{i}$ for $i \in[1, n], \sigma$ the substitution such that $\sigma\left(X_{i}\right)=M_{i}$ for $i \in[1, n]$ and var and $\nu$ empty substitutions. So :

$$
\mathbb{M}_{a}(\tau, \text { var }, \text { Cont })\left[X_{1} / M_{1}, \ldots, X_{n} / M_{n}\right]=\sigma\left(\mathbb{M}_{a}(\tau, \text { var }, \text { Cont })\right) \in \mathcal{R}_{\tau_{0}}(N, u)
$$

1251 Lemma 43. For all tree constant $a$ of arity $n$ in $\Sigma$, for all topological sort $\tau$ over a subset

1275 Definition 45. With $G$ (root) the graph whose set of vertices is $A_{\epsilon}^{\top}$ an edges represent
${ }_{1288} \quad$ Then we prove that $\mathbb{M}_{\text {root }}$ computes the right output:
1289 Lemma 46. For all subsort $\tau$ of a topological sort of $G($ root $)$, for all tree $N$ such that $\tau$ is ${ }_{1290}$ a topological sort of $G_{\epsilon}(N)$ and for all term $M_{0} \in \mathcal{R}_{\tau}(N, \epsilon)$, the term $\mathbb{M}_{\text {root }}(\tau) M_{0} \beta$-reduces 1291 to the output of the ATT on input $N$.

Proof. Similar to lemma 41.
Lemma 47. For all subsort $\tau$ of a topological sort of $G($ root $)$, injective substitution var which associates variables of type o with attributes and variable $X_{0}$ of type $t(\tau)$, the term $\mathbb{M}_{\text {root }}\left(\tau\right.$, var, $\left.X_{0}\right)$ is almost linear in general and linear if the ATT is single use restricted.

Proof. Similar to lemmas 43 and 44.

- Definition 48. Let $T=\left(\Sigma_{1}, \Sigma_{2}, S, I\right.$, out, $R$, root $)$ be an ATT.

We define the $\operatorname{HODTR}_{a l} \mathbb{H} \mathbb{O}(T) \triangleq\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R^{\prime}, \mathrm{A}\right)$ by:

- A, the look-ahead automaton, is the bottom-up tree automaton given by lemma 15,
- $\Sigma_{Q}$ is the signature of the set of states, which is
$Q \triangleq\left\{q_{0}\right\} \cup\left\{q_{\tau(\alpha, \epsilon) \top} \mid \tau(\alpha, \epsilon) \top\right.$ is a topological sort on a subset of $A_{\epsilon}^{\top}$ and $\left.\alpha \in S\right\}$, the number of states is $|Q|=|S \cup I|$ !. The type of a state $q_{\tau}$ is $o_{1} \rightarrow t(\tau)$, where $t(\tau)$ is defined in definition 37,
- $\Sigma_{1}$ and $\Sigma_{2}$ are respectively the input and output tree signatures from the ATT T,
- $R^{\prime}$ is the set of rules, it includes the rules the form:

$$
q_{\tau_{0}}(a \vec{x})\langle\vec{\ell}\rangle \rightarrow M\left(q_{\tau_{1}} x_{1}\right) \ldots\left(q_{\tau_{n}} x_{n}\right)
$$

where $\vec{\ell}=\ell_{1}, \ldots, \ell_{n}$ are the states of look-ahead associated with the subtrees $\vec{x}=$ $x_{1}, \ldots, x_{n}$ respectively and, noting $\tau=f\left(a, \tau_{0},\left(\ell_{1}, \ldots, \ell_{n}\right)\right)$ the topological sort computed in lemma 35, for all $1 \leq j \leq n$ : $\tau_{j}$ is the topological sort $\tau_{j}=j^{-1}$. $\left(\left.\tau\right|_{A_{j}^{\top}}\right)$. And with $M=$ let $X_{1}=q_{\tau_{1}}\left(x_{1}\right)$ and $\ldots X_{n}=q_{\tau_{n}}\left(x_{n}\right)$ in $\mathbb{M}_{a}(\tau$, var, Cont) where var is the empty substitution, Cont $=\left[i \rightarrow X_{i}\right]_{i \in[1, n]}$ and $\mathbb{M}_{a}$ is defined in definition 40 .
To that first set of rules we add special rules for the initial state $q_{0}$ : for all rule already in $R^{\prime}$ of the form $q_{\tau_{0}}(a \vec{x})\langle\vec{\ell}\rangle \rightarrow M$ where $\tau_{0}$ is a subsort of a topological sort of $G$ (root), we add to $R^{\prime}$ the rule:

$$
q_{0}(a \vec{x})\langle\vec{\ell}\rangle \rightarrow \mathbb{M}_{\text {root }}\left(\tau_{0}\right) M
$$

A complexity analysis on the size of $\mathbb{H O}(T)$ reveals that, noting $m=|S|+|I|$ the number of attributes, $n$ the maximum arity of a symbol in $\Sigma_{1}$ and $p$ the number of symbols in $\Sigma_{1}$, the number of states in the look-ahead automaton of $\mathbb{H O}(T)$ grows in $e^{m^{2}}$ (graphs with attributes as vertices), the number of states of $\mathbb{H O}(T)$ grows with $m$ ! (orderings on the set of attributes). Then the number of rules of $\mathbb{H O}(T)$ grows in $m!* p * e^{m^{2} * n}$ and the size of these rules grows linearly with the size of the rules of $T$ and the number $m$ of attributes. Note that the only non-linear factor is $m!* e^{m^{2} * n}$ and comes from the potentially big numbers of accessible synthesis graphs and topological sorts of synthesis graphs, which could be smaller in practical cases.

Theorem 49. For all $A T T T$, the $\operatorname{HODTR}_{\text {al }} T^{\prime}=\mathbb{H O}(T)$ is equivalent to $T$, and $T^{\prime}$ is linear if $T$ is single use restricted.

Proof. Let $N$ be an input tree of $T^{\prime}$.
For all path $u \in V_{N}$, according to lemma 15 , the look-ahead state associated with the node at path $u$ in $N$ is the synthesis graph $G S_{u}(N)$ of $N$ at path $u$.

Then a straighforward downward induction using lemma 35 shows that for all non- $\epsilon$ path $u \in V_{N}$ the node at path $u$ in $N$ is processed by a state of the form $q_{\tau}$ where $\tau$ is a topological sort of $G_{u}(N)$.

A straighforward upward induction using lemma 41 proves that for all non- $\epsilon$ path $u \in V_{N}$ the result of the computation of $q_{\tau}\left(N l_{u}\right)$ is a term in $\mathcal{R}_{\tau}(N, u)$.
${ }_{1341}$ Proof. The relabeling $P$ can be modeled by a simple HODTR ${ }_{\text {lin }}$. Then we can compose it ${ }_{1342}$ with $\mathbb{H O}(T)$ in order to obtain a $\operatorname{HODTR}_{\mathrm{al}} T^{\prime}$ equivalent to $P \circ T$ such that if $T$ is single ${ }_{1343}$ use restricted then $\mathbb{H O}(T)$ is linear and therefore $T^{\prime}$ is also linear.

1344 Corollary 51. The class MSOT is included in the class $H_{O D T R}$ lin and the class MSOTS ${ }_{1345}$ is included in the class HODTR ${ }_{a l}$.

## B. 3 HODTR $_{\text {al }} \subseteq$ REL $\circ$ ATT and HODTR ${ }_{\text {lin }} \subseteq$ REL $\circ$ ATT $_{\text {sur }}$

- Theorem 52. For all $\operatorname{HODTR}_{a l} T=\left(\Sigma_{Q}, \Sigma_{1}, \Sigma_{2}, q_{0}, R, \mathrm{~A}\right)$ there exists a relabeling attribute ${ }_{1348}$ grammar $P$ and an $A T T T^{\prime}$ such that $T$ is equivalent to $P \circ T^{\prime}$ and, if $T$ is linear, then $T^{\prime}$ ${ }_{1349}$ is single use restricted.
${ }_{1350}$ Proof. First we assume that $T$ is the result of the order reduction procedure described in 1351 the proof of theorem 2, so the result of applying a state $q \in Q$ to an input tree $N$ is a tuple ${ }^{1352}$ of tree contexts: $q(N) \rightarrow_{T}\left(C_{1}, \ldots, C_{n}\right)$.

1355 build a relabeling attribute grammar $P$ that computes, for each node of an input tree $N$ ${ }_{1356}$ which rule of $T$ would be applied to it. Then $T^{\prime}$ will compute the actual results of applying 1357 these rules.
${ }_{1358} \quad$ Since each state $q$ of $T$ computes a tuple of contexts, we need attributes to simulate 1359 tree contexts. We can do this by mapping the free variables of a tree context to inherited 1360 attributes, and mapping the tree context to a synthesized attribute. For example a tree ${ }_{1361}$ context $C_{1}=f y_{1} y_{2}$, where $f$ is a tree constant of arity 2 and $y_{1}$ and $y_{2}$ are free variables, 1362 will be represented by one synthesized attribute $\alpha_{1}$ linked to two inherited attributes $\beta_{1}$ and ${ }_{1363} \beta_{2}$ by the equation: $\left(\alpha_{1}, \epsilon\right)=f\left(\beta_{1}, \epsilon\right)\left(\beta_{2}, \epsilon\right)$. This way we can build an ATT $T^{\prime}$ such that ${ }_{1364} P \circ T^{\prime}$ is equivalent to $T$.
${ }_{1365} \quad$ Furthermore, if $T$ is linear, then each tree context is used exactly once, so attributes are never used twice and $T^{\prime}$ is single use restricted.

- Corollary 53. $H O D T R_{a l} \subseteq \mathrm{REL} \circ A T T$ and $H O D T R_{\text {lin }} \subseteq \mathrm{REL} \circ A T T_{\text {sur }}$.

Finally we can conclude, thanks to theorem 10 , that $\operatorname{HODTR}_{\mathrm{al}}=\mathrm{MSOTS}$ and $\operatorname{HODTR}_{\text {lin }}$ ${ }_{1369}^{1368}=$ MSOT (theorem 3)

## C Composition

## C. 1 Proof of theorem 5

${ }_{1372}$ In order to prove that for all term $M$ of type $A$ and all token $f \in \llbracket A \rrbracket$ there is at most ${ }_{1373}$ one derivation of the judgement $\vdash M: f$, we first need to introduce known definitions and 1374 properties of coherent spaces under the framework of linear logic, as first introduced by
1375 Girard in [14].

## Coherent spaces

Our main goal now is to indicate that for all term $M$ of type $A$ and all token $f \in \llbracket A \rrbracket$ which corresponds to a behaviour of $M$, there is only one possible derivation for the judgement $\vdash M: f$, which will be the key trick to preserve linearity in composition. In order to prove that, we will see that tokens form a coherent space.

First, we define a coherence relation $\frown_{A} \subseteq \llbracket A \rrbracket \times \llbracket A \rrbracket$ for all type $A$ by induction on $A$ :

- Definition 54. For all $p, p^{\prime} \in P$ and $\ell, \ell^{\prime} \in L_{2}$,
$(p, \ell) \frown_{o_{2}}\left(p^{\prime}, \ell^{\prime}\right) \Leftrightarrow \ell=\ell^{\prime}$
For all type $A, B \in \operatorname{types}\left(o_{2}\right)$, for all $f, f^{\prime} \in \llbracket A \rrbracket$ and $g, g^{\prime} \in \llbracket B \rrbracket$ :
$f \multimap g \frown_{A \rightarrow B} f^{\prime} \multimap g^{\prime} \Leftrightarrow\left(f \frown_{A} f^{\prime} \Rightarrow\left(g \frown_{B} g^{\prime} \wedge\left(f \neq f^{\prime} \Rightarrow g \neq g^{\prime}\right)\right)\right)$
Intuitively, two tokens are coherent if they can both be derived from the same term. For tokens of a tree for instance, that means that they must share the same look-ahead.

We also define the corresponding incoherence relation $\asymp_{A} \in \llbracket A \rrbracket \times \llbracket A \rrbracket$ : intuitively, two tokens are incoherent if they can not both be possible distinct tokens for the same term, so if they are either not coherent together, or if they are equal.

- Definition 55. For all type $A$ built on $o_{2}$ :
$f \asymp_{A} f^{\prime} \Leftrightarrow \neg\left(f \frown_{A} f^{\prime}\right) \vee f=f^{\prime}$
The incoherence relation allows us to give a simpler alternative definition of the coherence relation $\frown_{A \leftarrow B}$ between tokens in $\llbracket A \rightarrow B \rrbracket$ : for all $f, f^{\prime} \in \llbracket A \rrbracket$ and $g, g^{\prime} \in \llbracket B \rrbracket$,

$$
f \multimap g \frown_{A \rightarrow B} f^{\prime} \multimap g^{\prime} \Leftrightarrow\left(f \frown_{A} f^{\prime} \Rightarrow g \frown_{B} g^{\prime}\right) \wedge\left(g \asymp_{B} g^{\prime} \Rightarrow f \asymp_{A} f^{\prime}\right)
$$

- Theorem 56. For all type $A$ and term $M^{A}$ of type $A$, if there exists two semantic tokens $f, f^{\prime} \in \llbracket A \rrbracket$ associated with $M^{A}$, i.e. the judgments $\vdash M: f$ and $\vdash M: f^{\prime}$ are derivable, then $f$ and $f^{\prime}$ are coherent: $f \frown_{A} f^{\prime}$.

In order to prove this theorem, we need to prove a stronger theorem, by induction on term $M$ :

- Theorem 57. If there exists two derivations $\mathcal{D}:: \Gamma \vdash M: f$ and $\mathcal{D}^{\prime}:: \Gamma^{\prime} \vdash M: f^{\prime}$ then $\Gamma \multimap f \frown \Gamma^{\prime} \multimap f^{\prime}$.

Here, when writing $\Gamma \multimap f$ with $\Gamma=x_{1}: f_{1}, \ldots, x_{n}: f_{n}$, we mean by $\Gamma$ the tensor product $\left(f_{1}, \ldots, f_{n}\right)$.

Proof. We prove this by induction on term $M$ :
If $M=a$ is a constant from $\Sigma_{2}$ then the last rules of $\mathcal{D}$ and $\mathcal{D}^{\prime}$ are:
$\mathcal{D}:: \frac{p(a \vec{x})\left\langle\ell_{1}, \ldots, \ell_{n}\right\rangle \xrightarrow{T_{2}} M\left(p_{1} x_{1}\right) \ldots\left(p_{n} x_{n}\right) \quad \mathrm{A}_{2}\left(a\left(\ell_{1}, \ldots, \ell_{n}\right)\right)=\ell}{\vdash a:\left(p_{1}, \ell_{1}\right) \multimap \cdots \multimap\left(p_{n}, \ell_{n}\right) \multimap(p, \ell)}$
$\mathcal{D}^{\prime}:: \frac{p^{\prime}(a \vec{x})\left\langle\ell_{1}^{\prime}, \ldots, \ell_{n}^{\prime}\right\rangle \xrightarrow{T_{2}} M\left(p_{1}^{\prime} x_{1}\right) \ldots\left(p_{n}^{\prime} x_{n}\right) \quad \mathrm{A}_{2}\left(a\left(\ell_{1}^{\prime}, \ldots, \ell_{n}^{\prime}\right)\right)=\ell^{\prime}}{\vdash a:\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right) \multimap \cdots \multimap\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right) \multimap\left(p^{\prime}, \ell^{\prime}\right)}$

If $\left(\left(p_{1}, \ell_{1}\right), \ldots,\left(p_{n}, \ell_{n}\right)\right) \subseteq\left(\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right), \ldots,\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right)\right)$ then $\left(\ell_{1}, \ldots, \ell_{n}\right)=\left(\ell_{1}^{\prime}, \ldots, \ell_{n}^{\prime}\right)$, therefore $\ell=\ell^{\prime}$ and so $(p, \ell) \subset\left(p^{\prime}, \ell^{\prime}\right)$. If $\left(\left(p_{1}, \ell_{1}\right), \ldots,\left(p_{n}, \ell_{n}\right)\right) \subset\left(\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right), \ldots,\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right)\right)$ and $(p, \ell)=$ ( $p^{\prime}, \ell^{\prime}$ ) then $p=p^{\prime}$ and, since $\ell_{i}=\ell_{i}^{\prime}$ for all $i$ and $T_{2}$ is deterministic, $p_{i}=p_{i}^{\prime}$ for all $i$. This shows that $\left(\left(p_{1}, \ell_{1}\right), \ldots,\left(p_{n}, \ell_{n}\right)\right) \frown\left(\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right), \ldots,\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right)\right)$ and $(p, \ell)=\left(p^{\prime}, \ell^{\prime}\right)$ implies that $\left(\left(p_{1}, \ell_{1}\right), \ldots,\left(p_{n}, \ell_{n}\right)\right)=\left(\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right), \ldots,\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right)\right)$. As a consequence,
$\left(\left(p_{1}, \ell_{1}\right), \ldots,\left(p_{n}, \ell_{n}\right)\right) \multimap(p, \ell) \doteq\left(\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right), \ldots,\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right)\right) \multimap\left(p^{\prime}, \ell^{\prime}\right)$. So we have shown the equivalent statement: $\left(p_{1}, \ell_{1}\right) \multimap \ldots\left(p_{n}, \ell_{n}\right) \multimap(p, \ell) \frown\left(p_{1}^{\prime}, \ell_{1}^{\prime}\right) \multimap \ldots\left(p_{n}^{\prime}, \ell_{n}^{\prime}\right) \multimap\left(p^{\prime}, \ell^{\prime}\right)$.

If $M=N_{1} N_{2}$ then the last rules of $\mathcal{D}$ and $\mathcal{D}^{\prime}$ respectively are of the form:

$$
\frac{\Gamma_{1} \vdash N_{1}: g \multimap f \quad \Gamma_{2} \vdash N_{2}: g}{\Gamma_{1}, \Gamma_{2} \vdash N_{1} N_{2}: f} \quad \frac{\Gamma_{1}^{\prime} \vdash N_{1}: g^{\prime} \multimap f^{\prime} \quad \Gamma_{2}^{\prime} \vdash N_{2}: g^{\prime}}{\Gamma_{1}^{\prime}, \Gamma_{2}^{\prime} \vdash N_{1} N_{2}: f^{\prime}}
$$

Through the induction hypothesis, we get that $\Gamma_{1} \multimap(g \multimap f) \subset \Gamma_{1}^{\prime} \multimap\left(g^{\prime} \multimap f^{\prime}\right)$ and $\Gamma_{2} \multimap g \frown \Gamma_{2}^{\prime} \multimap g^{\prime}$. Then $\Gamma_{1}, \Gamma_{2} \frown \Gamma_{1}^{\prime}, \Gamma_{2}^{\prime}$ implies that $\Gamma_{1} \frown \Gamma_{1}^{\prime}$ and $\Gamma_{2} \frown \Gamma_{2}^{\prime}$, which means that $g \multimap f \frown g^{\prime} \multimap f^{\prime}$ and $g \frown g^{\prime}$, which in turn implies that $f \frown f^{\prime}$. Reciprocally, assuming that $f \asymp f^{\prime}$, we have two cases depending on whether or not $g \asymp g^{\prime}$. On the one hand we have that $g \asymp g^{\prime}$ implies that $\Gamma_{2} \asymp \Gamma_{2}^{\prime}$ and therefore $\Gamma_{1}, \Gamma_{2} \asymp \Gamma_{1}^{\prime}, \Gamma_{2}^{\prime}$, on the other hand we have that $f \asymp f^{\prime}$ and $g \asymp g^{\prime}$ imply that $g \multimap f \asymp g^{\prime} \multimap f^{\prime}$ and so $\Gamma_{1} \asymp \Gamma_{1}^{\prime}$ and $\Gamma_{1}, \Gamma_{2} \asymp \Gamma_{1}^{\prime}, \Gamma_{2}^{\prime}$. In either case $f \asymp f^{\prime}$ implies that $\Gamma_{1}, \Gamma_{2} \asymp \Gamma_{1}^{\prime}, \Gamma_{2}^{\prime}$. Finally we can conclude that $\Gamma_{1}, \Gamma_{2} \multimap f \frown \Gamma_{1}^{\prime}, \Gamma_{2}^{\prime} \multimap f^{\prime}$

If $M=\lambda x^{B} . N$ then $f=g \multimap h, f^{\prime}=g^{\prime} \multimap h^{\prime}$ and the last rules of $\mathcal{D}$ and $\mathcal{D}^{\prime}$ respectively are:

$$
\frac{\Gamma, x^{B}: g \vdash N: h}{\Gamma \vdash \lambda x^{B} \cdot N: g \multimap h} \quad \frac{\Gamma^{\prime}, x^{B}: g^{\prime} \vdash N: h^{\prime}}{\Gamma^{\prime} \vdash \lambda x^{B} \cdot N: g^{\prime} \multimap h^{\prime}}
$$

The induction hypothesis gives $\left(\Gamma, x^{B}: g\right) \multimap h \frown\left(\Gamma^{\prime}, x^{B}: g^{\prime}\right) \multimap h^{\prime}$, which we can write: $(\Gamma, g) \multimap h \frown\left(\Gamma^{\prime}, g^{\prime}\right) \multimap h^{\prime}$ using the tensor product, and that is equivalent to $\Gamma \multimap(g \multimap h) \frown \Gamma^{\prime} \multimap\left(g^{\prime} \multimap h^{\prime}\right)$.

If $M=x^{A}$ then $f, f^{\prime} \in \llbracket A \rrbracket$. So $\Gamma=x^{A}: f$ and $\Gamma^{\prime}=x^{A}: f^{\prime}$ and derivations $\mathcal{D}$ and $\mathcal{D}^{\prime}$ are:

$$
\frac{f \in \llbracket A \rrbracket}{x^{A}: f \vdash x^{A}: f} \quad \frac{f^{\prime} \in \llbracket A \rrbracket}{x^{A}: f^{\prime} \vdash x^{A}: f^{\prime}}
$$

Trivially $f \subset f^{\prime} \Rightarrow f \subseteq f^{\prime}$ and $f \asymp f^{\prime} \Rightarrow f \asymp f^{\prime}$, therefore $f \multimap f \frown f^{\prime} \multimap f^{\prime}$. So $\Gamma \multimap f \subset \Gamma^{\prime} \multimap f^{\prime}$.

We have shown theorem 57 , of which theorem 56 is a particular case, by induction on $M$. Indeed if $M$ is a closed term and $\Gamma$ and $\Gamma^{\prime}$ are empty substitutions then $\Gamma \multimap f$ is $f$ and $\Gamma^{\prime} \multimap f^{\prime}$ is $f^{\prime}$, therefore $f \frown f^{\prime}$.

We have shown that any two tokens derivable for a same term are coherent. So the set of tokens derivable for a given term $M^{A}$ form a clique in the coherence graph of $\llbracket A \rrbracket$, we call it the coherent state of term $M^{A}$ in $\llbracket A \rrbracket$.

Now, using the previous theorem, we will be able to prove that there is only one way of deriving any given derivable judgement $\vdash M: f$.

## Unicity of derivation for semantic token judgements

We can now prove theorem 5:

Proof. Because subterms of $M$ may have free variables, we add a substitution $\Gamma$ to the induction hypothesis:
"If there exists two derivations $\mathcal{D}:: \Gamma \vdash M: f$ and $\mathcal{D}^{\prime}:: \Gamma \vdash M: f$ then $\mathcal{D}$ and $\mathcal{D}^{\prime}$ are the same."

We prove this by induction on term $M$, so there are four distinct cases.
If $M=a$ is a constant from $\Sigma_{2}$ or if $M=x$ is a free variable in $\Gamma$ then derivations $\mathcal{D}$ and $\mathcal{D}^{\prime}$ are axioms so they must be equal.

If $M=N_{1} N_{2}$ then the last rules of $\mathcal{D}$ and $\mathcal{D}^{\prime}$ respectively are of the form:

$$
\frac{\Gamma_{1} \vdash N_{1}: g \multimap f \quad \Gamma_{2} \vdash N_{2}: g}{\Gamma_{1}, \Gamma_{2} \vdash N_{1} N_{2}: f} \quad \frac{\Gamma_{1}^{\prime} \vdash N_{1}: g^{\prime} \multimap f \quad \Gamma_{2}^{\prime} \vdash N_{2}: g^{\prime}}{\Gamma_{1}^{\prime}, \Gamma_{2}^{\prime} \vdash N_{1} N_{2}: f}
$$

where $\Gamma_{1}, \Gamma_{2}=\Gamma=\Gamma_{1}^{\prime}, \Gamma_{2}^{\prime}$. Since the variables substituted by substitutions $\Gamma_{1}$ and $\Gamma_{1}^{\prime}$ must be the free variables in term $N_{1}, \Gamma_{1}=\Gamma_{1}^{\prime}$ (because dom $\left(\Gamma_{1}\right)=\mathrm{FV}\left(N_{1}\right)=\operatorname{dom}\left(\Gamma_{1}^{\prime}\right)$ ). Similarly, we deduce that $\Gamma_{2}=\Gamma_{2}^{\prime}$. Then we can apply theorem 57 to the derivations of $\Gamma_{2} \vdash N_{2}: g$ and $\Gamma_{2}^{\prime} \vdash N_{2}: g^{\prime}$, and to the derivations of $\Gamma_{1} \vdash N_{1}: g \multimap f$ and $\Gamma_{1}^{\prime} \vdash N_{1}: g^{\prime} \multimap f$. The first application yields $g \frown g^{\prime}\left(\right.$ since $\left.\Gamma_{2}=\Gamma_{2}^{\prime}\right)$, the second yields $g \multimap f \frown g^{\prime} \multimap f$ (because $\Gamma_{1}=\Gamma_{1}^{\prime}$ ), together they imply that $g=g^{\prime}$. Finally we can apply the induction hypothesis to get unicity of a derivation of $\Gamma_{1} \vdash N_{1}: g \multimap f$ and unicity of a derivation of $\Gamma_{2} \vdash N_{2}: g$, this implies that derivations $\mathcal{D}$ and $\mathcal{D}^{\prime}$ are the same.

If $M=\lambda x^{B} . N$ then $f=g \multimap h$ and the last rule of $\mathcal{D}$ and $\mathcal{D}^{\prime}$ is the same:

$$
\frac{\Gamma, x^{B}: g \vdash N: h}{\Gamma \vdash \lambda x^{B} \cdot N: g \multimap h}
$$

The induction hypothesis implies the unicity of a derivation of $\Gamma, x^{B}: g \vdash N: h$, which entails the unicity of a derivation of $\Gamma \vdash \lambda x^{B} . N: g \multimap h$.

## C. 2 Proof of theorem 7

First we need to prove that collapsed derivations of semantic tokens accurately represent the application of $T_{2}$ on terms, in order to do so we use a logical relation.

## Logical relation

Our logical relation is indexed on a type $A$ and a semantic token $f \in \llbracket A \rrbracket$, it is defined as follows:

- Definition 58. We define the logical relation $R_{f}^{A}$, for all type $A$ built on atomic type $o_{2}$ and for all semantic token $f \in \llbracket A \rrbracket$, by induction on type $A$ :

$$
\begin{aligned}
& R_{(p, \ell)}^{o_{2}}=\left\{(M, N) \mid p\left(M\left\llcorner_{\beta}\right) \stackrel{T_{2}}{=} N \downharpoonright_{\beta}, \mathrm{A}_{2}\left(M \downharpoonright_{\beta}\right)=\ell\right\}\right. \\
& R_{f \rightarrow g}^{A \rightarrow B}=\left\{(M, N) \mid \forall\left(M^{\prime}, N^{\prime}\right) \in R_{f}^{A},\left(M M^{\prime}, N N^{\prime}\right) \in R_{g}^{B}\right\}
\end{aligned}
$$

Now we prove the adequation of this logical relation: for all type $A \in \operatorname{types}\left(o_{2}\right)$, token $f \in \llbracket A \rrbracket$ and for any closed terms $M$ and $N$ of respective types $A$ and $\bar{f}$ :

$$
\exists \mathcal{D}:: \vdash M: f \text { and } \overline{\mathcal{D}}={ }_{\beta \eta} N \Rightarrow(M, N) \in R_{f}^{A}
$$

We prove a more general claim by induction on term $M$ :

## 1482

## 1483

Theorem 59. For all type $A \in \operatorname{types}\left(o_{2}\right)$, token $f \in \llbracket A \rrbracket$, terms $M$ of type $A$ and $N$ of type $\bar{f}$. For all substitutions of variables $\Gamma$ and $\sigma$ such that $\Gamma(x)=g \Rightarrow \sigma(x) \in R_{g}^{B}$ and $\operatorname{dom}(\Gamma)=\mathrm{FV}(M):$

$$
\exists \mathcal{D}:: \Gamma \vdash M: f \wedge \overline{\mathcal{D}}={ }_{\beta \eta} N \quad \Rightarrow \quad\left(M .\left(\pi_{1} \circ \sigma\right), N .\left(\pi_{2} \circ \sigma\right)\right) \in R_{f}^{A}
$$

In order to prove this theorem, we first need to show that the logical relation is compatible with $\beta$-reduction (and $\eta$-expansion):

- Lemma 60. For all type $A$ and token $f \in \llbracket A \rrbracket$, for all terms $M, N, M^{\prime}, N^{\prime}$ such that $M={ }_{\beta \eta} M^{\prime}$ and $N={ }_{\beta \eta} N^{\prime}:(M, N) \in R_{f}^{A} \Rightarrow\left(M^{\prime}, N^{\prime}\right) \in R_{f}^{A}$.
Proof. We prove this lemma by induction on type $A$. Let $M, N, M^{\prime}, N^{\prime}$ be terms such that $M={ }_{\beta \eta} M^{\prime}, N={ }_{\beta \eta} N^{\prime}$ and $(M, N) \in R_{f}^{A}$.

If $A=o_{2}$ and $f=(p, \ell)$ then $p\left(M \downharpoonright_{\beta}\right) \stackrel{T_{2}}{=} N \downharpoonright_{\beta}$ and $\mathrm{A}_{2}\left(M \downharpoonright_{\beta}\right)=\ell$. So $p\left(M^{\prime}\left\llcorner_{\beta}\right)=p\left(M\left\llcorner_{\beta}\right) \stackrel{T_{2}}{=} N \downharpoonright_{\beta}=N^{\prime} \downharpoonright_{\beta}\right.\right.$ and $\mathrm{A}_{2}\left(M^{\prime}\left\llcorner_{\beta}\right)=\mathrm{A}_{2}\left(M \downharpoonright_{\beta}\right)=\ell\right.$. In that case $\left(M^{\prime}, N^{\prime}\right) \in$ $R_{f}^{A}$.
$B \rightarrow C$ and $f=g \multimap h$ then, for all $\left(M_{1}, N_{1}\right) \in R_{g}^{B},\left(M M_{1}, N N_{1}\right) \in R_{h}$. Since $=_{\beta \eta} M^{\prime}$ and $N={ }_{\beta \eta} N^{\prime}$, we have $\left(M M_{1}, N N_{1}\right)={ }_{\beta \eta}\left(M^{\prime} M_{1}, N N_{1}\right)$ and, by induction hypothesis on type $C,\left(M^{\prime} M_{1}, N^{\prime} N_{1}\right) \in R_{h}^{C}$. So $\left(M^{\prime}, N^{\prime}\right) \in R_{g \rightarrow h}^{B \rightarrow C}$.

We can now prove theorem 59.
Proof. We use an induction on term $M$.
Let $A \in \operatorname{types}\left(o_{2}\right)$, token $f \in \llbracket A \rrbracket$, terms $M$ of type $A$ and $N$ of type $\bar{f}$. Let $\Gamma$ and $\sigma$ substitutions of variables such that $\Gamma(x)=g \Rightarrow \sigma(x) \in R_{g}^{B}$ and $\operatorname{dom}(\Gamma)=\mathrm{FV}(M)$. Let $\mathcal{D}$ a derivation of the judgement $\Gamma \vdash M: f$ (unique according to theorem 5). Assume that $\overline{\mathcal{D}}={ }_{\beta \eta} N$. We want to prove $\left(M .\left(\pi_{1} \circ \sigma\right), N .\left(\pi_{2} \circ \sigma\right)\right) \in R_{f}^{A}$.

In most cases, we will show that $\left(M .\left(\pi_{1} \circ \sigma\right), \overline{\mathcal{D}} \cdot\left(\pi_{2} \circ \sigma\right)\right) \in R_{f}^{A}$ and conclude using lemma 60. We distinguish four cases depending on $M$, one for each derivation rule as head of derivation $\mathcal{D}$ :

If $M=x^{A}$ then the head rule of $\mathcal{D}$ is:

$$
\frac{f \in \llbracket A \rrbracket}{x^{A}: f \vdash x^{A}: f}
$$

Since $\Gamma\left(x^{A}\right)=f$, we have $\sigma\left(x^{A}\right) \in R_{f}^{A}$. So $\left(M .\left(\pi_{1} \circ \sigma\right), N .\left(\pi_{2} \circ \sigma\right)\right)=\left(\pi_{1}\left(\sigma\left(x^{A}\right)\right), \pi_{2}\left(\sigma\left(x^{A}\right)\right)\right) \in$ $R_{f}^{A}$.

If $M=M_{1} M_{2}$ then the head rule of $\mathcal{D}$ is:

$$
\frac{\mathcal{D}_{1}:: \Gamma_{1} \vdash M_{1}: f^{\prime} \multimap f \quad \mathcal{D}_{2}:: \Gamma_{2} \vdash M_{2}: f^{\prime}}{\Gamma_{1}, \Gamma_{2} \vdash M_{1} M_{2}: f}
$$

where $\Gamma=\Gamma_{1}, \Gamma_{2}$ such that the domains of $\Gamma_{1}$ and $\Gamma_{2}$ are the sets of free variables of $M_{1}$ and $M_{2}$ respectively. Similarly, we can split substitution $\sigma$ into $\sigma_{1}$ and $\sigma_{2}$ in order to apply the induction hypothesis on $\mathcal{D}_{1}$ with $\sigma_{1}$ and on $\mathcal{D}_{2}$ with $\sigma_{2}$. Noting $B$ the type of $M_{2}$ we get:

$$
\left(M_{1} \cdot\left(\pi_{1} \circ \sigma_{1}\right), \overline{\mathcal{D}_{1}} \cdot\left(\pi_{2} \circ \sigma_{1}\right)\right) \in R_{f^{\prime} \rightarrow f}^{B \rightarrow A} \quad\left(M_{2} \cdot\left(\pi_{1} \circ \sigma_{2}\right), \overline{\mathcal{D}_{2}} \cdot\left(\pi_{2} \circ \sigma_{2}\right)\right) \in R_{f^{\prime}}^{B}
$$

By definition of $R_{f^{\prime} \rightarrow f}^{B \rightarrow A}$ we get $\left(M_{1} \cdot\left(\pi_{1} \circ \sigma_{1}\right) M_{2} \cdot\left(\pi_{1} \circ \sigma_{2}\right), \overline{\mathcal{D}_{1}} \cdot\left(\pi_{2} \circ \sigma_{1}\right) \overline{\mathcal{D}_{2}} \cdot\left(\pi_{2} \circ \sigma_{2}\right)\right) \in R_{f}^{A}$. So $\left(\left(M_{1} M_{2}\right) \cdot\left(\pi_{1} \circ \sigma\right),\left(\overline{\mathcal{D}_{1}} \overline{\mathcal{D}_{2}}\right) \cdot\left(\pi_{2} \circ \sigma\right)\right) \in R_{f}^{A}$. Since $\overline{\mathcal{D}}=\overline{\mathcal{D}_{1}} \overline{\mathcal{D}_{2}}$, we conclude using lemma 60 .

If $M=\lambda x^{B} \cdot M^{\prime}$ then the head rule of $\mathcal{D}$ is:
$\frac{\mathcal{D}^{\prime}:: \Gamma, x^{B}: g \vdash M^{\prime}: f^{\prime}}{\Gamma \vdash \lambda x^{B} \cdot M^{\prime}: g \multimap f^{\prime}}$
where $A=B \rightarrow C$ and $f=g \multimap f^{\prime}$. First we show that $\left(\lambda x . M^{\prime} .\left(\pi_{1} \circ \sigma\right), \lambda x \cdot \overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma\right)\right) \in$ $R_{g \rightarrow f^{\prime}}^{B \rightarrow C}$. Let $\left(M_{0}, N_{0}\right) \in R_{g}^{B}$. In order to use the induction hypothesis we define $\Gamma^{\prime}=\Gamma, x^{B}: g$ and the substitution $\sigma^{\prime}=\sigma \circ\left[x \leftarrow\left(M_{0}, N_{0}\right)\right]$, then: $\left(M^{\prime} .\left(\pi_{1} \circ \sigma^{\prime}\right), \overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma^{\prime}\right)\right) \in R_{f^{\prime}}^{C}$. Because of the definition of $\sigma^{\prime}$ we have: $\left(\lambda x \cdot M^{\prime} .\left(\pi_{1} \circ \sigma\right)\right) M_{0}={ }_{\beta \eta} M^{\prime} .\left(\pi_{1} \circ \sigma^{\prime}\right)$ and $\left(\lambda x \cdot \overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma\right)\right)={ }_{\beta \eta}$ $\overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma^{\prime}\right)$. Using lemma 60 we deduce that $\left(\left(\lambda x \cdot M^{\prime} .\left(\pi_{1} \circ \sigma\right)\right) M_{0},\left(\lambda x \cdot \overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma\right)\right) N_{0}\right) \in R_{f^{\prime}}^{C}$. This proves that $\left(\lambda x \cdot M^{\prime} .\left(\pi_{1} \circ \sigma\right), \lambda x \cdot \overline{\mathcal{D}^{\prime}} .\left(\pi_{2} \circ \sigma\right)\right) \in R_{g \rightarrow f^{\prime}}^{B \rightarrow C}$. We conclude using lemma 60 .

If $M=a$ then the head rule of $\mathcal{D}$ is:

$$
\frac{p(a \vec{x})\left\langle\ell_{1}, \ldots, \ell_{n}\right\rangle \xrightarrow{T_{2}} N^{\prime}\left(p_{1} x_{1}\right) \ldots\left(p_{n} x_{n}\right) \quad \mathrm{A}_{2}\left(a\left(\ell_{1}, \ldots, \ell_{n}\right)\right)=\ell}{\vdash a:\left(p_{1}, \ell_{1}\right) \multimap \cdots \multimap\left(p_{n}, \ell_{n}\right) \multimap(p, \ell)}
$$

Since $\Gamma$ is the empty substitution, we only need to prove $(M, N) \in R_{\left(p_{1}, \ell_{1}\right) \rightarrow \ldots \multimap(p, \ell)}^{o_{2} \rightarrow \ldots o_{2}}$. In order to do this we define the property $\mathcal{P}(i)$ for $0 \leq i \leq n$ by:

$$
\begin{aligned}
& \mathcal{P}(i)=" \text { For all }\left(M_{1}, N_{1}\right) \in R_{\left(p_{1}, \ell_{1}\right)}^{o_{2}}, \ldots,\left(M_{i}, N_{i}\right) \in R_{\left(p_{i}, \ell_{i}\right)}^{o_{2}}, \\
& \text { we have }\left(M M_{1} \ldots M_{i}, N^{\prime} N_{1} \ldots N_{i}\right) \in R_{\left(p_{i+1}, \ell_{i+1}\right) \rightarrow \ldots\left(p_{n}, \ell_{n}\right)-\circ(p, \ell)}^{o_{2} \rightarrow \ldots o_{2}}
\end{aligned}
$$

We prove $\mathcal{P}(i)$ by downward induction for $0 \leq i \leq n$.
We start by proving $\mathcal{P}(n)$ :
let $\left(M_{1}, N_{1}\right) \in R_{\left(p_{1}, \ell_{1}\right)}^{o_{2}}, \ldots,\left(M_{n}, N_{n}\right) \in R_{\left(p_{n}, \ell_{n}\right)}^{o_{2}}$. So for all $i \leq n$, we have $\left.p_{i}\left(M_{i} L_{\beta}\right) \stackrel{T_{2}}{=} N_{i}\right|_{\beta}$ and $\mathrm{A}_{2}\left(M_{i} \downharpoonright_{\beta}\right)=\ell_{i}$. Now we look at $p\left(M M_{1} \ldots M_{n} \downharpoonright_{\beta}\right)$ :

$$
\begin{aligned}
p\left(\left(M M_{1} \ldots M_{n}\right)\left\llcorner_{\beta}\right)\right. & =p\left(a \left(M_{1}\left\llcorner_{\beta}\right) \ldots\left(M_{n}\left\llcorner_{\beta}\right)\right)\right.\right. \\
& \stackrel{T_{2}}{=} N^{\prime}\left(p _ { 1 } ( M _ { 1 } \llcorner _ { \beta } ) ) \ldots \left(p_{n}\left(M_{n}\left\llcorner_{\beta}\right)\right)\right.\right. \\
& \stackrel{T_{2}}{=} N^{\prime}\left(N _ { 1 } \llcorner _ { \beta } ) \ldots \left(N_{n}\left\llcorner_{\beta}\right)\right.\right. \\
& \stackrel{T_{2}}{=}\left(N^{\prime} N_{1} \ldots N_{n}\right) \downharpoonright_{\beta}
\end{aligned}
$$

Note that we can apply the rule of $T_{2}$ because we know that $\mathrm{A}_{2}\left(M_{i} L_{\beta}\right)=\ell_{i}$ for all $i \leq n$. Then we check $\mathrm{A}_{2}\left(\left(M M_{1} \ldots M_{n}\right) \downharpoonright_{\beta}\right)$ :

$$
\begin{aligned}
\mathrm{A}_{2}\left(\left(M M_{1} \ldots M_{n}\right)\left\llcorner_{\beta}\right)\right. & =\mathrm{A}_{2}\left(a\left(M_{1}\left\llcorner_{\beta}\right) \ldots\left(M_{n} \downharpoonright_{\beta}\right)\right)\right. \\
& =\mathrm{A}_{2}\left(a \ell_{1} \ldots \ell_{n}\right) \\
& =\ell
\end{aligned}
$$

We have shown $\mathcal{P}(n)="\left(M M_{1} \ldots M_{n}, N^{\prime} N_{1} \ldots N_{n}\right) \in R_{(p, \ell)}^{o_{2}} "$.
Next we prove the induction step, for $1 \leq j \leq n, \mathcal{P}(j) \Rightarrow \mathcal{P}(j-1)$ : we assume $\mathcal{P}(j)$ and want to prove $\mathcal{P}(j-1)$.
Let $\left(M_{1}, N_{1}\right) \in R_{\left(p_{1}, \ell_{1}\right)}^{o_{2}}, \ldots,\left(M_{j-1}, N_{j-1}\right) \in R_{\left(p_{j-1}, \ell_{j-1}\right)}^{o_{2}}$. According to $\mathcal{P}(j)$, for all

$\left(M M_{1} \ldots M_{j-1}, N^{\prime} N_{1} \ldots N_{j-1}\right) \in R_{\left(p_{j}, \ell\right) \rightarrow\left(p_{j+1}, \ell_{j+1}\right) \rightarrow \ldots \rightarrow(p, \ell)}^{o_{2} \rightarrow \ldots \rightarrow o_{2}}$ and $\mathcal{P}(j-1)$ is true.
Therefore, by induction, $\mathcal{P}(0)="\left(M, N^{\prime}\right) \in R_{\left(p_{1}, \ell_{1}\right) \rightarrow \cdots-(p, \ell)}^{o_{2} \rightarrow \ldots o_{2}}$ " is true. Since
$N^{\prime}=\overline{\mathcal{D}}={ }_{\beta \eta} N$ we can conclude that $(M, N) \in R_{\left(p_{1}, \ell_{1}\right) \rightarrow \ldots \multimap(p, \ell)}^{o_{2} \rightarrow \ldots o_{2}}$ using lemma 60.
This ends the proof of theorem 59.

As a corollary of theorem 59 we get that if there exists a derivation $\mathcal{D}$ of a judgement $\vdash M: f$ then $\left(M,\left.\overline{\mathcal{D}}\right|_{\beta \eta}\right) \in R_{f}^{A}$.

With this corollary we can now prove theorem 7 .

## Proof of theorem 7

With $T$ defined in section 4.4, we prove that $T=T_{2} \circ T_{1}$.
Proof. We first prove the following statement by induction on a tree $t$ of type $o_{1}$ :
For all state $q \in Q$ of transducer $T_{1}$ and for all token $f \in \llbracket A_{q} \rrbracket$ such that $q(t) \xrightarrow{T_{子}} M$ and

Let $t=a t_{1} \ldots t_{n}$ a tree of type $o_{1}, q \in Q$ a state of $T_{1}$ and $f \in \llbracket A_{q} \rrbracket$ a token such that $q(t) \xrightarrow{T_{T}} M$ and $\vdash M: f$. Then there is a rule:
$q\left(a t_{1} \ldots t_{n}\right) \xrightarrow{T_{7}} M_{0}\left(q_{1} t_{1}\right) \ldots\left(q_{n} t_{n}\right)$
If term $M_{0}$ forgets one or several of its arguments, then there exists a term $M_{0}^{\prime}$ which uses all its arguments such that $M_{0}\left(q_{1} t_{1}\right) \ldots\left(q_{n} t_{n}\right)={ }_{\beta \eta} M_{0}^{\prime}\left(q_{i_{1}} t_{i_{1}}\right) \ldots\left(q_{i_{m}} t_{i_{m}}\right)$ where $i_{1}, \ldots, i_{m}$ are the indices of the arguments used by $M_{0}$. For the sake of clarity we forget this renaming of variables and proceed assuming $M_{0}$ uses all of its arguments.

Since the computation of $q(t) \xrightarrow{T_{7}} M$ terminates and $M_{0}$ uses all its arguments: for all $i \leq n$, the computation of $q_{i}\left(t_{i}\right)$ by $T_{1}$ terminates, we note its result $M_{i}$ (a term of type $A_{q_{i}}$ ). Therefore $M_{0} M_{1} \ldots M_{n} \rightarrow_{\beta \eta}^{*} M$. So $\vdash M_{0} M_{1} \ldots M_{n}: f$ and there exists $f_{1} \in \llbracket A_{q_{1}} \rrbracket, \ldots, f_{n} \in \llbracket A_{q_{n}} \rrbracket$ such that $\vdash M_{0}: f_{1} \multimap \cdots \multimap f_{n} \multimap f$ and, for all $i \leq n, \vdash M_{i}: f_{i}$. Then we can apply the induction hypothesis to each tree $t_{i}$ with state $q_{i}$ and token $f_{i}$ : for all $i \leq n$, there is a term $N_{i}$ such that $\left(q_{i}, f_{i}\right)\left(t_{i}\right) \xrightarrow{T} N_{i}$ and $\left(M_{i}, N_{i}\right) \in R_{f_{i}}^{A_{q_{i}}}$.

Because of the rule $q\left(a t_{1} \ldots t_{n}\right) \xrightarrow{T_{7}} M_{0}\left(q_{1} t_{1}\right) \ldots\left(q_{n} t_{n}\right)$ in $T_{1}$, there must be in $T$ a rule:

$$
(q, f)\left(a t_{1} \ldots t_{n}\right) \xrightarrow{T} \overline{\mathcal{D}_{0}}\left(\left(q_{1}, f_{1}\right)\left(t_{1}\right)\right) \ldots\left(\left(q_{n}, f_{n}\right)\left(t_{n}\right)\right)
$$

Where $\mathcal{D}_{0}$ is the derivation of the judgement $\vdash M_{0}: f_{1} \multimap \cdots \multimap f_{n} \multimap f$. So
$(q, f)\left(a t_{1} \ldots t_{n}\right) \xrightarrow{T} \overline{\mathcal{D}_{0}} N_{1} \ldots N_{n}$.
By using theorem 59 (adequation) on $\mathcal{D}_{0}$ we get $\left(M_{0}, \overline{\mathcal{D}_{0}}\right) \in R_{f_{1} \rightarrow \ldots f_{n} \rightarrow f}^{A_{q_{1}} \rightarrow \ldots A_{q_{n}} \rightarrow A_{q}}$. By definition of the logical relation, we obtain $\left(M_{0} M_{1} \ldots M_{n}, \overline{\mathcal{D}_{0}} N_{1} \ldots N_{n}\right) \in R_{f}^{A_{q}}$. Finally we apply lemma 60. So, with $N=\overline{\mathcal{D}_{0}} N_{1} \ldots N_{n}$, we have $(q, f)(t) \xrightarrow{T} N$ and $(M, N) \in R_{f}^{A_{q}}$.

Let $t_{1}$ be a tree of type $o_{1}$. Assume that $T_{2} \circ T_{1}\left(t_{1}\right)=t_{3}$. Then there is a term $t_{2}$ of type $o_{2}$ such that $q_{0}\left(t_{1}\right) \xrightarrow{T_{7}} t_{2}$ and $p_{0}\left(t_{2}\right) \xrightarrow{T_{2}} t_{3}$. Then we can derive the judgement $\vdash t_{2}:\left(p_{0}, \ell\right)$ where $\ell$ is the look-ahead of $T_{2}$ on tree $t_{2}$ and $p_{0}$ is the initial state of $T_{2}$. So there exists a term $N$ such that $\left(q_{0},\left(p_{0}, \ell\right)\right)\left(t_{1}\right) \xrightarrow{T} N$ and $\left(t_{2}, N\right) \in R_{\left(p_{0}, \ell\right)}^{o_{2}}$. By definition of the logical relation we have: $p_{0}\left(t_{2}\right) \stackrel{T_{2}}{=} N L_{\beta}$, so $t_{3}=N L_{\beta}$ and $\left(q_{0},\left(p_{0}, \ell\right)\right)\left(t_{1}\right) \xrightarrow{T} t_{3}$. Thanks to the definition of $R$, we can conclude that $q_{0}^{\prime}\left(t_{1}\right) \xrightarrow{T} t_{3}$. So $T_{2} \circ T_{1}\left(t_{1}\right)=t_{3}$ implies that $T\left(t_{1}\right)=t_{3}$.

For the reverse implication, we first show by induction on tree $t$ that, for all state $q \in Q$ and token $f \in \llbracket A_{q} \rrbracket$, if $(q, f)(t) \xrightarrow{T} N$ then there exists a term $M$ such that $q(t) \xrightarrow{T_{7}} M$, $\vdash M: f$ and $(M, N) \in R_{f}^{A_{q}}$.

Let $t=a t_{1} \ldots t_{n}$ a tree of type $o_{1}$ with $(q, f)(t) \xrightarrow{T} N$. So there is a rule of $T$ such that $(q, f)(t) \xrightarrow{T} N_{0}\left(\left(q_{1}, f_{1}\right)\left(t_{1}\right)\right) \ldots\left(\left(q_{n}, f_{n}\right)\left(t_{n}\right)\right)$. Then there are $N_{1}, \ldots, N_{n}$ such that $(q, f)(t) \xrightarrow{T} N_{0} N_{1} \ldots N_{n}, N={ }_{\beta \eta} N_{0} N_{1} \ldots N_{n}$ and, for all $i \leq n,\left(q_{i}, f_{i}\right)\left(t_{i}\right) \xrightarrow{T} N_{i}$. Then we apply the induction hypothesis and get $M_{i}$ such that $q_{i}\left(t_{i}\right) \xrightarrow{T_{7}} M_{i}$ and $\vdash M_{i}: f_{i}$. There is in $T_{1}$ a rule $q(t) \xrightarrow{T_{7}} M_{0}\left(q_{1} t_{1}\right) \ldots\left(q_{n} t_{n}\right)$, so $q(t) \xrightarrow{T_{7}} M_{0} M_{1} \ldots M_{n}$, with $\vdash M_{0}: f_{1} \multimap \ldots f_{n} \multimap f$. So for $M=M_{0} M_{1} \ldots M_{n}$ we have $\vdash M: f$. Finally we deduce that $(M, N) \in R_{f}^{A_{q}}$ using the property we proved earlier in this proof and the lemma 60.

1596 Now we try to show that $T\left(t_{1}\right)=t_{3} \Rightarrow T_{2} \circ T_{1}\left(t_{1}\right)=t_{3}$. Assume that $T\left(t_{1}\right)=t_{3}$. Then ${ }_{1597} q_{0}^{\prime}\left(t_{1}\right) \xrightarrow{T} t_{3}$, so there exists a token $\left(p_{0}, \ell\right) \in \llbracket o_{2} \rrbracket$ such that $\left(q_{0},\left(p_{0}, \ell\right)\right)\left(t_{1}\right) \xrightarrow{T} t_{3}$. So there ${ }_{1598}$ exists a term $M$ such that $q\left(t_{1}\right) \xrightarrow{T_{7}} M, \vdash M: f$ and $\left(M, t_{3}\right) \in R_{\left(p_{0}, \ell\right)}^{o_{2}}$. Then, by definition of 1599 the logical relation: $p_{0}\left(M \bigsqcup_{\beta}\right) \xrightarrow{T_{2}} t_{3}$. So $T_{2} \circ T_{1}\left(t_{1}\right)=t_{3}$.
${ }_{1600} \quad$ So the transduction of $T$ is the composition of the transductions of $T_{2}$ and $T_{1}$.

