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Generalized Gaussian quasi-maximum likelihood estimation for most common
time series

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Abstract

We propose a consistent estimator for the parameter shape of the generalized gaussian noise in the class of causal time series including ARMA, AR(\infty), GARCH, ARCH(\infty), ARMA-GARCH, APARCH, ARMA-APARCH,..., processes. As well we prove the consistency and the asymptotic normality of the Generalized Gaussian Quasi-Maximum Likelihood Estimator (GGQMLE) for this class of causal time series with any fixed parameter shape, which over-performs the efficiency of the classical Gaussian QMLE.

Keywords:
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Quasi maximum likelihood, Efficiency of estimators, Strong consistency, Asymptotic normality, ARMA-ARCH processes.

1. Introduction

This paper is first devoted to estimate the parameter shape $r_0$ of the white noise density from an observed trajectory of an affine causal process. This class of time series was already defined and studied in Duchenes and Francq (2008), Bardet and Wintenberger (2009) and Bardet \textit{et al.} (2017). Hence, we will consider an observed sample $(X_1, \cdots, X_n)$ where $(X_t)_{t \in \mathbb{Z}}$ is a solution of the following equation:

\begin{equation}
X_t = M_{\theta^0}(\{X_{t-k}\}_{k \geq 1}) \xi_t + f_{\gamma^0}(\{X_{t-k}\}_{k \geq 1}), \quad t \in \mathbb{Z},
\end{equation}

where

- $\theta^0 \in \Theta \subset \mathbb{R}^d$, $d \in \mathbb{N}^*$ and $\gamma^0 \in \Gamma \subset \mathbb{R}^e$, $e \in \mathbb{N}^*$ are two unknown vectors of parameters, also called the “true” parameters (but $d$ and $e$ are known);
- $(\xi_t)_{t \in \mathbb{Z}}$ is a sequence of centred independent identically distributed random variables (i.i.d.r.v.) with symmetric probability distribution, i.e. $\xi_0 \overset{\text{d}}{=} -\xi_0$, and such as there exists $r_0 \geq 1$ and $s \geq \min(2, r_0)$ satisfying

\begin{equation}
E(\xi_0) = 0, \quad E(|\xi_0|^s) = 1 \quad \text{and} \quad E(|\xi_0|^r) < \infty.
\end{equation}

- For $x = \{x_n\}_{n \in \mathbb{N}} \in \mathbb{R}^\infty$ where $\mathbb{R}^\infty$ is the space of real sequences with a finite number of non zero terms, $(\theta, \{x_n\}_{n \in \mathbb{N}}) \rightarrow M_{\theta}(\{x_n\}_{n \in \mathbb{N}}) \in (0, \infty)$ and $(\gamma, \{x_n\}_{n \in \mathbb{N}}) \rightarrow f_{\gamma}(\{x_n\}_{n \in \mathbb{N}}) \in \mathbb{R}$ are two known applications.

In Bardet and Wintenberger (2009) and Bardet \textit{et al.} (2017), it was proved that all the most famous stationary time series used in econometrics, such as ARMA, AR(\infty), GARCH, ARCH(\infty), TARCH, ARMA-GARCH processes can be written as a causal stationary solution of (1).
The maximum of the conditional quasi-likelihood method, Gaussian QMLE, is the most used to estimate the parameters of the models for stochastic processes. This method was mainly built using the Gaussian instrumental density, see for instance Berkes et al. (2003) or Francq and Zakoian (2004) for GARCH\((p, q)\) processes, Francq and Zakoian (2013) for ARMA-GARCH processes, Straumann and Mikosch (2006) for general heteroskedastic models, and Bardet and Wintenberger (2009) for the general class of affine causal models. Trindade et al. (2006) studies the ARMA and GARCH models driven by asymmetric Laplace noise, Bardet et al. (2017) estimated the model parameters using the Laplacian QMLE, i.e. the estimator is constructed from a Laplacian conditional density. Even if the obtained estimators are consistent only under moment conditions on the conditional density, it could be But theoretically, the divergence of true innovation density can greatly increase the variance of the estimates, increasing with the cost of ignoring true distribution innovation.

In order to avoid this arbitrary choice of QML conditional density, Lii and Rosenblatt (1992) proposed an approximate procedure of maximum average non-reversible moving average processes driven by a non-Gaussian noise, Francq et al. (2011) proposed a two stage non Gaussian QML estimation for GARCH processes based on generalized Gaussian errors, Jianqing et al. (2014) proposed a three step quasi-maximum likelihood procedure. The generalized Gaussian density also known as the Generalized Error Distribution (denoted \(\text{GED}(r)\)) with \(r > 0\) or the power Gamma distribution is given by

\[
g_r(x) = \frac{1}{\Gamma(1/r)} \frac{x^{1-1/r}}{\Gamma(\frac{r+1}{r})} e^{-x^{1/r}} \quad \text{for } x \in \mathbb{R}. \quad (3)
\]

Note that \(g_1\) is the Laplace density and \(g_2\) is the Gaussian one. If \(Z_t\) follows a \(\text{GED}(r)\), then

\[
\mathbb{E}(Z_t) = 0 \quad \text{and} \quad \mathbb{E}(Z_t^{1/r}) = 1. \quad (4)
\]

Moreover, we have the following result and notation:

\[
m_r(p) = \mathbb{E}(Z_t^p) = r^{\frac{p}{r} - 1} \frac{\Gamma(\frac{r+1}{r})}{\Gamma(\frac{r+1}{r})} \quad \text{for any } p > 0. \quad (5)
\]

In this paper, we propose a new two stage estimation procedure leading to a Pseudo Generalized Gaussian Quasi-Maximum Likelihood Estimator (PGGQMLE) in the general case of affine causal process.

1. Firstly, we assume that \((Z_t)\) in (1) is a white noise distributed following a \(\text{GED}(r_0)\) with \(r_0 \geq 1\) an unknown parameter. Then \(r_0\) is estimated by \(\hat{r}\) using jointly the Gaussian and Laplacian QMLEs of \(\theta_0\). The strong consistency of \(\hat{r}\) is established.

2. Secondly, after showing that the Generalized Gaussian Quasi-Maximum Likelihood Estimator (GGQMLE) of \(\theta_0\), i.e. a quasi-maximum likelihood estimator built using a \(\text{GED}(r)\) as an instrumental density (see below), is strongly consistent for any \(r > 1\), by replacing \(r\) with \(\hat{r}\) a PGGQMLE is obtained and its consistency is also established.

The following Section 2 provides the definitions and assumptions. Section 3 studies the estimator \(\hat{r}\) of the parameter shape \(r\) and its consistency is established. Then, the asymptotic behavior of the PGGQML estimator is studied in Section 4, while the results of Monte-Carlo experiments are presented in Section 6.

2. Definition and assumptions

2.1. Definition of the estimator

Assume that \((X_1, \ldots, X_n)\) is an observed trajectory of \(X\) solution of (1) where \(\theta^0 \in \Theta \subset \mathbb{R}^d\) and \(\gamma^0 \in \Gamma \subset \mathbb{R}^e\) are unknown. For estimating \(\theta^0\) and \(\gamma^0\) we consider the log-likelihood of \((X_1, \ldots, X_n)\) conditionally to \((X_0, X_{-1}, \ldots)\). If \(g\) is the probability density (with respect to Lebesgue measure) of \(\zeta_0\), then, from the affine causal definition of \(X\), this conditional log-likelihood is equal to:

\[
\sum_{t=1}^{n} \log \left( \frac{1}{M_{\theta}} g(X_t - f_t \gamma_{\hat{\gamma}}) \right)
\]

2.
where $M'_0 := M_0(X_{t-1}, X_{t-2}, \cdots)$ and $f'_y := f_y(X_{t-1}, X_{t-2}, \cdots)$, with the assumption that $M'_0 > 0$. However, $M'_0$ and $f'_y$ are generally not computable since $X_0, X_1, \ldots$ are unknown. Thus, a quasi-log-likelihood is considered instead of the log-likelihood and it is defined by:

$$
\log(Q^{(g)}_{(y)}(X_1, \cdots, X_n)) = \sum_{t=1}^{n} \log \left( \frac{1}{M'_0} g \left( \frac{X_t - \hat{f}'_y}{M'_0} \right) \right),
$$

with $\hat{f}'_y := f_y(X_{t-1}, \ldots, X_1, u)$ and $\hat{M}'_0 := M_0(X_{t-1}, \ldots, X_1, u)$, where $u = (u_n)_{n \in \mathbb{N}}$ is a finitely non-zero sequence $(u_n)_{n \in \mathbb{N}}$. The choice of $(u_n)_{n \in \mathbb{N}}$ does not have any consequences on the asymptotic behaviour of $L_n$, and $(u_n)$ could typically be chosen as a sequence of zeros. Finally, a Quasi-Maximum Likelihood Estimator (QMLE) of $(\theta^*, \gamma^*)$ can be defined with the respect of the choice of $g$

$$
\hat{\phi}^{(g)} = \hat{\phi}^{(g)}(\hat{\theta}, \hat{\gamma}) := \arg \max_{(\theta, \gamma) \in \Theta} \log(Q^{(g)}_{(y)}(X_1, \cdots, X_n)).
$$

The aim of this paper is to propose a new choice of the function $g$, while the QMLE is generally built with $g = g_2$ the standard Gaussian distribution (denoted Gaussian QMLE) or, less often, with $g = g_1$ the standard Laplacian distribution (denoted Laplacian QMLE). Now, we will consider more generally $g = g_r$.

As a consequence, for any $1 \leq r \leq s$ with $s$ defined in (2), then the equation (1) can be written again:

$$
X_t = M_{0^r}(X_{t-1}, X_{t-2}, \cdots) \xi^{(r)}_t + f_y(X_{t-1}, X_{t-2}, \cdots), \quad t \in \mathbb{Z}
$$

with $\xi^{(r)}_t = \xi(\mathbb{E}(|\xi_0|^{1/r}))^{1/r}$, implying $\mathbb{E}(|\xi^{(r)}_t|) = 1$ and $M_{0^r} = (\mathbb{E}(|\xi_0|^{1/r}))^{1/r} M_{0^r}$. Then, we can define the Generalized Gaussian Quasi Maximum Likelihood $\hat{\phi}^{(g)} = (\hat{\theta}, \hat{\gamma})$ of $\phi^* = (\theta^*, \gamma^*)$ that is defined by

$$
\hat{\phi}^{(g)} = (\hat{\theta}, \hat{\gamma}) := \arg \min_{(\theta, \gamma) \in \Theta} \sum_{t=1}^{n} \hat{q}_t(\theta, \gamma) \quad \text{where} \quad \hat{q}_t(\theta, \gamma) := \log(|\hat{M}'_0|) + \frac{1}{r} |\hat{M}'_0|^{-1}|X_t - \hat{f}'_y|.
$$

In other words, this estimator is equal to $\hat{\phi}^{(g)}$ when $g = g_r$ the GED($r$) density.

**Remark 2.1.** We also see that for $r = 2$ the Generalized Gaussian contrast is the Gaussian contrast and for $r = 1$ it is the Laplacian one.

Bardet and Wintenberger (2009) and Bardet et al. (2017) have respectively proved the consistency and the asymptotic normality of $\hat{\phi}^{(g)}$ and $\hat{\phi}^{(g)}$ respectively. Using these both these consistent estimators, we begin with the estimation of the parameter shape $\gamma_0$ when the distribution of $\xi_0$ is exactly a GED($\gamma_0$).

2.2. Existence and stationarity

First we will provide some sufficient conditions for insuring the existence and stationarity of a solution of (1) such as $\mathbb{E}(|X_0|^{s}) < \infty$ with $s \geq 1$. As it was already done in Doukhan and Wintenberger (2007), several Lipschitz-type inequalities on $f_y$ and $M_0$ can be used for obtaining this $s$-order stationarity of an ergodic causal solution of (1). First, denote $\|g_0\|_{\Phi} = \sup_{\|\Phi\| \leq 1} \|g_0\|$ where $\Phi \in \mathbb{R}^{d \times r}$ and $\|\cdot\|$ is the usual Euclidian norm. Now, let us introduce the generic symbol $K_{\phi}$ for any function $K_{\phi} : \mathbb{R}^{n} \mapsto \mathbb{R}^{m}$ or $M_{\mu}(\mathbb{R})$ (for instance $K_{\phi} = f_{\phi}$ or $M_{\phi}$ or their derivatives). For $k = 0, 1, 2$, define a Lipschitz assumption on function $K_{\phi}$:

**Assumption (A_k(K, \Phi))** $\forall x \in \mathbb{R}^{\infty}, \phi \in \Phi \mapsto K_{\phi}(x) \in C^k(\Phi)$ and $\partial^k_{\phi} K_{\phi}$ satisfies $\|\partial^k_{\phi} K_{\phi}(0)\|_{\Phi} < \infty$ and there exists a sequence $(\alpha_j^{(k)}(K, \Phi))$ of nonnegative numbers such that $\forall x, y \in \mathbb{R}^{\infty}$

$$
\|\partial^k_{\phi} K_{\phi}(x) - \partial^k_{\phi} K_{\phi}(y)\|_{\Phi} \leq \sum_{j=1}^{\infty} \alpha_j^{(k)}(K, \Phi) |x_j - y_j|, \quad \text{with} \quad \sum_{j=1}^{\infty} \alpha_j^{(k)}(K, \Phi) < \infty.
$$
For ensuring a stationary $s$-order solution of (1), where $s \geq 1$, define the set

$$\Phi(s) := \{ \phi = (\theta, \gamma) \in \mathbb{R}^{d \times r}, (A_0(f, [\phi])) \text{ and } (A_0(M, [\phi])) \text{ hold},$$

$$\sum_{j=1}^{\infty} \alpha_j^{(0)}(f, [\phi]) + (\mathbb{E}[|\xi_0|^r])^{1/r} \sum_{j=1}^{\infty} \alpha_j^{(0)}(M, [\phi]) < 1\}.$$ 

Then, from Doukhan and Wintenberger (2007), we obtain:

**Proposition 2.1.** If $\phi_{0s} \in \Phi(s)$ for some $s \geq 1$, then there exists a unique causal $(X_t)$ independent of $(\zeta_{t})_{t \geq s}$ for $t \in \mathbb{Z}$ solution $X$ of (1), which is stationary, ergodic and satisfies $\mathbb{E}[|X_0|^r] < \infty$.

Thus, the stationarity and $r$-order of a solution of (6) is ensured from this corollary:

**Corollary 2.1.** If $\phi \in \Phi'(r)$, with:

$$\Phi'(r) := \{ \phi = (\theta, \gamma) \in \mathbb{R}^{d \times r}, (A_0(f, [\phi])) \text{ and } (A_0(M, [\phi])) \text{ hold},$$

$$\sum_{j=1}^{\infty} \alpha_j^{(0)}(f, [\phi]) + \sum_{j=1}^{\infty} \alpha_j^{(0)}(M, [\phi]) < 1\},$$

then there exists a unique causal solution $X$ of (6), which is stationary, ergodic and satisfies $\mathbb{E}[|X_0|^r] < \infty$.

2.3. Additive assumptions required for the estimation

Fix some compact subset $\Phi$ of $\Phi(s) \subset \mathbb{R}^{d \times r}$. We will consider the following assumptions:

(Ainf) There exists $M > 0$ such that $\inf_{(\theta, \gamma) \in \Phi} M_{\theta}(x) \geq M$ for all $x \in \mathbb{R}^{\infty}$.

(Id) For all $(\theta, \gamma) \in \Phi$, $(f^t_{\theta, \gamma} = f^t_{\theta, \gamma})$ and $M^t_{\theta} = M^t_{\theta}$ a.s.) $\Rightarrow \theta = \theta_0$ and $\gamma = \gamma_0$.

(Var) One of the families $(\partial f^t_{\gamma}/\partial \gamma_i)_{1 \leq i \leq d}$ or $(\partial M^t_{\theta}/\partial \theta)_{1 \leq i \leq d}$ is a.e. linearly independent, where:

$$\frac{\partial f^t_{\gamma}}{\partial \gamma} := \frac{\partial f^t_{\gamma}}{\partial \gamma}(X_{t-1}, \ldots)$$
$$\frac{\partial M^t_{\theta}}{\partial \theta} := \frac{\partial M^t_{\theta}}{\partial \theta}(X_{t-1}, \ldots).$$

The condition [(Id)] is a usual identifiability condition while the condition (Var) is needed for ensuring the finiteness of the asymptotic variance in the result on asymptotic normality.

3. Estimation of the parameter shape $r_0$

In this section we propose a method to estimate the parameter shape $r_0$ when $(\zeta_t)$ is supposed to exactly follow a GED($r_0$) with $r_0 \geq 1$.

3.1. Construction of the estimator in case of GED($r_0$) white noise

Assume now that $\zeta_0$ follows a GED($r_0$) and $(X_1, \ldots, X_n)$ is an observed trajectory of $(X_t)$ that satisfies (1). In this case, a straightforward relation can be established between $M_{\theta, r}$ and $M_{\theta, 1}$:

**Lemma 3.1.** For any $r \geq 1$, when $(X_1, \ldots, X_n)$ is an observed trajectory of $(X_t)$ that satisfies (1) and $\zeta_0$ follows a GED$(r_0)$, then

$$M_{\theta, r} = M_{\theta, 1}^{-1/r} \left( \frac{\Gamma(1 + \frac{1}{r})}{\Gamma(\frac{r+1}{r})} \right)^{1/r}$$

and

$$f^t_{\theta, r} = f^t_{\theta, 1}. \quad (9)$$
Proof. Here we use the relation provided by the rewriting of (1), i.e.
\[ M_{\theta^0} = M_{\theta^*} \left( \mathbb{E}[|\xi_0|^r] \right)^{-1/r} \]  
and the moment equality (5) and that induce (9).

In the sequel we will consider two particular cases \( r = 1 \), corresponding to the Laplacian QMLE and \( r = 2 \), corresponding to the classical Gaussian QMLE. Hence using the results of Lemma 3.1 we obtain:
\[
\left( \frac{M'_{\theta^0}}{M'_{\theta^*}} \right)^2 = \frac{\Gamma(\frac{2}{r})}{\Gamma(\frac{1}{r}) \Gamma(\frac{3}{r})} := H(r_0).
\]  
This function \( H \) is a continuous and increasing function so it is invertible. The forthcoming Figure 1 exhibits the graph of \( H \).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{graph_H.png}
\caption{Graph of the function \( H(r) \)}
\end{figure}

The relation (11) leads to the definition of an estimator \( \hat{r}_n \) of the parameter shape \( r_0 \) given by the expression
\[
\hat{r}_n = H^{-1} \left( \frac{1}{n} \sum_{i=1}^{n} \left( \frac{\hat{M}'_{\theta^0}}{\hat{M}'_{\theta^*}} \right)^2 \right),
\]  
since \( \theta^1 \) and \( \theta^2 \) are unknown and can be estimated using QMLE estimators.

3.2. Consistency of \( \hat{r}_n \)

Now we study the consistency of the proposed estimator \( \hat{r}_n \) for the shape parameter \( r_0 \).

**Theorem 3.1.** Let \( X \) be a stationary solution of the equation (1) where \( \xi_0 \) follows a GED\( (r_0) \) and \( \phi^{0*} \in \Phi \), a compact subset of \( \Phi(2) \). Assume also that Assumptions (A\( _0(f, \Phi) \)), (A\( _0(M, \Phi) \)), (Ainf) and (Id) hold with
\[
\alpha^{(0)}_j (f, \Phi) + \alpha^{(0)}_j (M, \Phi) = O(j^{-\ell}) \text{ for some } \ell > 3/2.
\]  
Then the estimator \( \hat{r}_n \) is strongly consistent, i.e.
\[
\hat{r}_n \xrightarrow{a.s.} r_0 \text{ as } n \to \infty.
\]
Proof of Theorem 3.1. It is clear that \( \widehat{h}(\theta_1^s, \theta_2^s) := \left( \frac{\widehat{\phi}_n}{M_n} \right)^2 = H(r_0) \) for any \( t \in \mathbb{Z} \) by definition of \( \theta_1^s \) and \( \theta_2^s \). As a consequence, \( h_n(\theta_1^*, \theta_2^*) := \frac{1}{n} \sum_{i=1}^{n} \widehat{e}(\theta_1^*, \theta_2^*) = H(r_0) \). But since the function \( \theta \in \mathbb{R}^d \mapsto M_\theta(x) \) is supposed to be a continuous function for any \( x \in \mathbb{R}^d \), the function \( (\theta^1, \theta^2) \in \mathbb{R}^{2d} \mapsto h_n(\theta^1, \theta^2) \) is also almost surely a continuous function.

Bardet and Wintenberger (2009) proved that \( \overline{\theta}_n \overset{a.s.}{\to} \theta_1^s \), Bardet et al. (2017) proved that \( \overline{\theta}_n \overset{a.s.}{\to} \theta_1^s \) under the assumptions. Therefore \( h_n(\overline{\theta}_n, \overline{\theta}_n) - h_n(\theta_1^*, \theta_2^*) \overset{a.s.}{\to} 0 \), i.e. \( h_n(\overline{\theta}_n, \overline{\theta}_n) \overset{a.s.}{\to} H(r_0) \). Since the function \( H^{-1} \) is also a continuous function, the proof is established.

4. Consistency of the Pseudo-Generalized Gaussian Quasi-Maximum Likelihood Estimator

In this section we first study the consistency of the Generalized Gaussian Quasi-Maximum Likelihood Estimator (GGQMLE).

Theorem 4.1. Let \( X \) be a stationary solution of the equation (6) with \( 1 \leq r \leq s \) and \( \phi^s \in \Phi \) for a compact subset \( \Phi \subset \Phi(r) \) defined in (8) under Assumptions (A0(\( f, \Phi \)), (A0(\( M, \Phi \))). Assume also that Assumptions (Ainf) and (Id) hold with

\[
\alpha^0(f, \Phi) + \alpha^0(M, \Phi) = O(f^{-\ell}) \quad \text{for some} \quad \ell > \max \left\{ \frac{2}{r+1}, 1 \right\}, \tag{14}
\]

Then, for any \( r \geq 1 \), \( \overline{\phi}_n \overset{a.s.}{\to} \phi^s \) with \( \phi^s \) defined in (6).

Remark 4.1. When \( s \geq r + 1 \), the bound in (14) is obtained with \( \ell > 1 \). As a consequence, long-range dependent processes such as FARIMA processes (that are particular cases of AR(\( \infty \)) processes) can also be considered.

Proof of Theorem 4.1. Using the assumptions, \( (X_t) \) is also a solution of (6). The proof of the theorem is divided into two parts and follows the same procedure than in Bardet and Wintenberger (2009). Consider \( (\overline{q}(\theta, \gamma))_{\theta \in \Theta} \) defined in (7) and \( (q_t)_{\gamma \in \Theta} \) defined by

\[
q_t(\theta, \gamma) := \log |M_\theta'\gamma| + \frac{1}{r} |M_\theta'\gamma|^r |X_t - f_t^\gamma|, \tag{15}
\]

1. We first prove that

\[
\left\| \frac{1}{n} \sum_{t=1}^{n} q_t(\theta, \gamma) - \mathbb{E}(q_t(\theta, \gamma)) \right\|_{\Theta} \overset{a.s.}{\to} 0. \tag{16}
\]

(i) In the same way and for the same reason in the proof of Theorem 1 of Bardet et al. (2017), a uniform (on \( \Theta \)) strong law of large numbers is satisfied by \( (q_t(\theta, \gamma))_{\gamma \in \Theta} \), which is a sequence of martingale increments, is implied by establishing \( \mathbb{E}(\|q_t(\phi)\|_{\Theta}) < \infty \). But for all \( t \in \mathbb{Z} \),

\[
\left| q_t(\theta, \gamma) \right| \leq \log |M_\theta'\gamma| + \frac{1}{r} |M_\theta'\gamma|^r |X_t - f_t^\gamma| \leq \frac{|X_t - f_t^\gamma|}{r M'} + \frac{\log |M'_\theta|}{M} + |M'_\theta| \leq C (|X_t'| + |f_t'| + |M'_\theta| + 1),
\]

with \( C > 0 \) that does not depend on \( \theta, \gamma \). But, since \( \Theta \subset \Phi(r) \) implying \( \mathbb{E}(|X_t'|) < \infty \), and as it was already proved in Bardet and Wintenberger (2009), \( \mathbb{E}(\sup_{\theta \in \Theta} (|M_\theta'\gamma| + |f_t'|) < \infty) \). Therefore \( \mathbb{E}(\|q_t(\theta, \gamma)\|_{\Theta}) < \infty \) and (16) holds.

2. Moreover, we also have:

\[
\left\| \frac{1}{n} \sum_{t=1}^{n} (q_t(\theta, \gamma) - \widehat{q}_t(\theta, \gamma)) \right\|_{\Theta} \overset{a.s.}{\to} 0. \tag{17}
\]
Indeed, for any $t \geq 1$ and $(\theta, \gamma) \in \Theta$, and using several times the mean value Theorem,
\[
\begin{align*}
     r |\hat{q}_t(\theta, \gamma) - q_t(\theta, \gamma)| &\leq r \left| \log(||\hat{M}_t^\gamma||) - \log(||M_0^\gamma||) \right| + ||\hat{M}_t^\gamma||^{-1} |X_t - \hat{f}_t^\gamma| - ||M_0^\gamma||^{-1} |X_t - f_t^\gamma| \\
     &\leq \frac{r}{M} ||\hat{M}_t^\gamma - M_0^\gamma|| + |X_t - f_t^\gamma| + r ||\hat{M}_t^\gamma||^{-1} - ||M_0^\gamma||^{-1} |X_t - f_t^\gamma| \\
     &\leq \frac{r}{M} ||\hat{M}_t^\gamma - M_0^\gamma|| + 2^{r-1} |X_t| + |f_t^\gamma| \times \frac{r}{M^r} ||\hat{M}_t^\gamma - M_0^\gamma|| \\
     &\leq \frac{1}{M} r |Z_t|^{r-1} |\hat{f}_t^\gamma - f_t^\gamma| + \frac{1}{M} r |Z_t|^{r-1} |\hat{f}_t^\gamma - f_t^\gamma|
\end{align*}
\]
where $|Z_t| \leq \max(|X_t - \hat{f}_t^\gamma|, |X_t - f_t^\gamma|) \leq 2 |X_t| + |\hat{f}_t^\gamma| + |f_t^\gamma|$. Therefore, there exists $C > 0$ depending on $r$ and $M$ such that
\[
|\hat{q}_t(\theta, \gamma) - q_t(\theta, \gamma)| \leq C \left( (1 + |X_t|') + |f_t^\gamma|' \right) ||\hat{M}_t^\gamma - M_0^\gamma|| + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||' \leq C \left( (1 + (\mathbb{E}(X_t)' + |f_t^\gamma|') ||\hat{M}_t^\gamma - M_0^\gamma|| + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||' \right) \leq C \left( (\mathbb{E}(X_t)' + |f_t^\gamma|') ||\hat{M}_t^\gamma - M_0^\gamma|| + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||' \right)
\]
As a consequence, if $r \leq s \leq r + 1$, using H"{o}lder Inequality with $p = (r + 1)/r$ and $q = r + 1$, we obtain
\[
\begin{align*}
     \mathbb{E}(||\hat{q}_t(\theta, \gamma) - q_t(\theta, \gamma)||_\phi^{(r+1)}) &\leq C \mathbb{E} \left( (1 + |X_t|') + |f_t^\gamma|' \right) ||\hat{M}_t^\gamma - M_0^\gamma||^{(r+1)} + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||'(r+1) \leq C \left( (\mathbb{E}(X_t)' + |f_t^\gamma|') ||\hat{M}_t^\gamma - M_0^\gamma|| + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||' \right) \leq C \left( (\mathbb{E}(X_t)' + |f_t^\gamma|') ||\hat{M}_t^\gamma - M_0^\gamma|| + (|X_t|' + |f_t^\gamma|') ||f_t^\gamma||' \right)
\end{align*}
\]
Using again Bardet and Wintenberger (2009), we know that max $\max(\mathbb{E}(X_t)'), \mathbb{E}(|f_t^\gamma'|')$, $\mathbb{E}(|f_t^\gamma||') < \infty$. Moreover, we also have
\[
\begin{align*}
     \mathbb{E}(||\hat{M}_t^\gamma - M_0^\gamma||_\phi^r) &\leq \mathbb{E}(|X_0|' \left( \sum_{k=0}^{\infty} \alpha_k^0(M, \Phi) \right)^r) \quad \text{and} \quad \mathbb{E}(||f_t^\gamma - f_0^\gamma||_\phi^r) \leq \mathbb{E}(|X_0|' \left( \sum_{k=0}^{\infty} \alpha_k^0(f, \Phi) \right)^r)
\end{align*}
\]
Finally, we obtain that there exists $C > 0$ not depending on $t$ sur as for any $t \geq 1$,
\[
\begin{align*}
     \mathbb{E}(||\hat{q}_t(\theta, \gamma) - q_t(\theta, \gamma)||_\phi^{(r+1)}) &\leq C \sum_{k=0}^{\infty} (\alpha_k^0(M, \Phi) + \alpha_k^0(f, \Phi)) r \leq C t^{-(r+1)/3} \leq C t^{-(r+1)/3},
\end{align*}
\]
from (14). Using Corollary 1 of Kounias and Weng (1969), (17) is established if there exists $u \in (0, 1]$ such as
\[
\sum_{t \geq 1} \frac{1}{u} \mathbb{E}(||q_t(\theta, \gamma) - \hat{q}_t(\theta, \gamma)||_\phi^u) < \infty.
\]
It is such the case with $u = s/(r + 1)$, since we have:
\[
\sum_{t \geq 1} \frac{1}{u} \mathbb{E}(||q_t(\theta, \gamma) - \hat{q}_t(\theta, \gamma)||_\phi^u) \leq C \sum_{t \geq 1} t^{-(r+1)/3} < \infty.
\]
In case of $s \geq r + 1$, it is sufficient to consider the previous case with $s = r + 1$.

3. From (16) and (17), we deduce
\[
\begin{align*}
     \left\| \frac{1}{n} \sum_{i=1}^{n} \hat{q}_i(\theta, \gamma) - \mathbb{E}(q_t(\theta, \gamma)) \right\|_{\Theta} &\rightarrow_{n \rightarrow \infty} 0.
\end{align*}
\]
Moreover, for $\phi = (\theta, \gamma) \in \Phi$, we study
\[
L(\phi) = -\mathbb{E}(q_0(\phi)).
\]
which can also be consider as a Kullback-Lieber discrepancy. Using $E(\zeta_t | f)$ = 1, we obtain:

$$
L(\phi) = - \frac{1}{r} E \left( \log \left( \sum_{t=1}^{r} \left( \frac{M_t'}{\hat{M}_0'} \right) | \zeta_t + f_t^\gamma - f_t^\delta \right) \right)
$$

$$
\Rightarrow L(\phi^*) - L(\phi) = \frac{1}{r} E \left( \log \left( \frac{M_{t+}'}{\hat{M}_{0+}'} \right) \right) - 1
$$

But for $\zeta_t$ following a symmetric probability distribution, for any $m \in \mathbb{R}^r$, $E((\zeta_t + m | f) > E(\zeta_t | f) = 1$. Therefore, for $\theta \neq \theta^*$, if $f_t \neq f_{\theta^*}$ (else > is replaced by ≥),

$$
L(\phi^*) - L(\phi) > 1 \frac{1}{r} E \left( \log \left( \frac{M_{t+}'}{\hat{M}_{0+}'} \right) \right)
$$

with $h(x) = \log(x) - 1 + x$. But for any $x \in (0, 1) \cup (1, \infty)$, $h(x) > 0$ and $h(1) = 0$. Therefore if $M_0 \neq M_{\theta^*}$, $L(\phi^*) - L(\phi) > 0$ (> 0 is replaced by $= 0$ if $M_0 = M_{\theta^*}$). This implies Condition (id) that $L(\phi^*) - L(\phi) > 0$ for all $\theta \in \Theta, \theta \neq \theta^*$. Hence a supremum of $L(\phi)$ is only reached for $\phi = \phi^*$, which is the unique maximum, and this the same behavior for $\sum_{i=1}^{r} q_i(t, \gamma)$ from (20), implying $\phi^*_n \xrightarrow{n \to \infty} \phi^*$.

Since $\phi^* = (\gamma^*, \theta^*)$, it is clear that for $\tilde{\theta}^* \xrightarrow{n \to \infty} \theta^*$ for any $r \leq s$. Concerning the parameter $\theta$, we will add the following assumption on the function $M_0$ with $p$ a positive real number:

(HM)(p): For any $C > 0$ and $\theta \in \mathbb{R}^d, C \times M_0(\cdot) = M_{C \theta^p}(\cdot)$.

Examples: Assumption (HM)(p) is trivially satisfied in case of ARMA or AR(\infty) processes with $p = 1$, but also for GARCH($p, q$) processes with $p = 1$, or APARCH($p, \delta, q$) processes with $p = \delta$.

As a consequence, under Assumption (HM)(p), we have:

$$
\theta^* = (E(\zeta_t | f))^\gamma \theta^p.
$$

Even if $p$, $r_0$ and $r$ are known, the is generally unknown. But in the particular case where $\zeta_0$ follows a GED($r_0$), using (5), we obtain:

$$
\theta^* = (r_0^{r_0 - 1} \Gamma\left(\frac{r_0 + 1}{2}\right) \Gamma\left(\frac{r_0 + 1}{2}\right) r_0^{p/r}) \theta^p.
$$

Therefore, if $\zeta_0$ follows a GED($r_0$), $\tilde{\theta}^0$ can also be used for estimating $\theta^p$ for any $1 \leq r \leq s$. But which parameter $r$ has to be chosen for estimated the parameters $\theta^p$ and $\gamma^p$? Clearly, when $r_0$ is known, the choice $r = r_0$ is induced by the following property:

Property 4.1. Let $X$ be a stationary solution of the equation (1) where $\zeta_0$ follows a GED($r_0$) and $\phi^p \in \Phi$, a compact subset of $\Phi(r_0)$. Assume also that Assumptions (A0($f, \Phi$)), (A0($M, \Phi$)), (Ainf) and (Id) hold with

$$
\alpha_j^{(0)}(f, \Phi) + \alpha_j^{(0)}(M, \Phi) = O(j^{-2}) \text{ for some } \ell > 1.
$$

Then the estimator $\tilde{\theta}^{(n)}$ is asymptotically efficient (its renormalized asymptotic covariance behaves as the Cramèr-Rao bound).
Proof of Property 4.1. Denote \( \overline{L}_n(\phi) = \frac{1}{n} \sum_{i=1}^{n} q_i(\theta, \gamma) \) and \( L_n(\phi) = \frac{1}{n} \log (f_{(X_1, \ldots, X_n)}(X_1, \ldots, X_n)) \), where \( f_{(X_1, \ldots, X_n)} \) is the probability density of the vector \((X_1, \ldots, X_n)\) with respect to the Lebesgue measure when \((\zeta_i)\) is a white noise following a GED(r_0) distribution. Then, if \( \hat{\phi}_n \) := \( \text{Argmax}_{\phi \in \Phi} L_n(\phi) \) then \( \hat{\phi} \) is the classical maximum likelihood estimator.

Using Daniels (1961), we know that \( \hat{\phi} \) is asymptotically efficient.

But \( \overline{L}_n(\phi) = \overline{L}_n(\phi) + \frac{1}{n} \log (f_{(X_1)}(X_1)) \) and therefore \( \overline{L}_n(\phi) = \overline{L}_n(\phi) + O_P(1/n) \).

Moreover \( \overline{L}_n(\phi) = \frac{1}{n} \sum_{i=1}^{n} \overline{q}_i(\theta, \gamma) + O_P(1/n) \) under condition (21). As a consequence, \( \hat{\phi}_n = \hat{\phi}(n) + O_P(1/n) \) and therefore \( \hat{\phi}(n) \) is also asymptotically efficient.

What can be done if \( r_0 \) is unknown? We can use the previous estimator \( \overline{r}_n \) of \( r_0 \) and plug-in it in the formula of the estimator of \( \phi \). Hence:

Property 4.2. Under the assumptions of Property 4.1 but with estimator of \( \phi \), a compact subset of \( \Phi(\nu) \) with \( \nu = \max (r_0, 2) \), then \( \phi_{(n)} \overset{a.s.}{\longrightarrow} \phi^{0a} \) where \( \phi^{0a} \) defined in (1).

Proof of Property 4.2. The function \( r \in (1, \infty) \to \phi_{(r)} \) is a.s. a continuous function. As a consequence, using \( \overline{r}_n \overset{a.s.}{\longrightarrow} r_0 \) obtained in Theorem 3.1 and \( \phi_{(n)} \overset{a.s.}{\longrightarrow} \phi^{0a} \) obtained in Property 4.1, we obtain \( \phi_{(n)} \overset{a.s.}{\longrightarrow} \phi^{0a} \).

5. Examples

In this section, we explicitly apply the proposed two stage estimation procedure to several classical time series that are affine causal models: AR(p), GARCH(p, q) and APARCH(p, δ, q) processes.

1/ AR(p) processes: Consider the equation of an AR(p) process, i.e.

\[
X_t = \alpha^0 + \sum_{i=1}^{p} \beta_i X_{t-i}, \quad t \in \mathbb{Z},
\]

where \( \mu^0 \in \mathbb{R}, \alpha^0 > 0, \sum_{i=1}^{\infty} |\beta_i| < 1 \) and \((\zeta_i)_{i \in \mathbb{Z}}\) is a white noise satisfying (2).

Such AR(p) process is a special case of the affine causal process (1) with \( M_0 = \alpha \) and \( f_j = \mu + \sum_{i=1}^{p} \beta_i X_{t-i} \) where \( \theta = \alpha \) and \( \gamma = (\mu, \beta_1, \ldots, \beta_p) \).

For \( 0 < \alpha < \beta < \infty, \) and \( 0 < \rho < 1, \) define

\[
\Theta = [\alpha, \beta] \quad \text{and} \quad \Gamma = [\mu, \beta_1, \ldots, \beta_p] \in \mathbb{R}^{p+1}, \quad |\mu| \leq \rho^{-1} \quad \text{and} \quad \sum_{i=1}^{p} |\beta_i| \leq \rho.
\]

Moreover, since \( M_0 \) is a real constant not depending of the time, the parameter shape estimator defined in 12 becomes

\[
\overline{r}_n = \mathbb{H}^{-1} \left( \frac{\sigma_{0a}}{\sigma_{1a}} \right)^2.
\]

Then, the Generalized Gaussian Quasi-Maximum Likelihood Estimator \( \hat{\phi}_{(n)} \) is defined by

\[
\hat{\phi}_{(n)} := \text{Argmin}_{(\theta, \gamma) \in \Theta \times \Gamma} \sum_{i=1}^{n} \overline{q}_i(\theta, \gamma) \quad \text{where} \quad \overline{q}_i(\theta, \gamma) := \log (\alpha) + \frac{1}{t_n} |\alpha|^{-1} |X_t - (\mu + \sum_{i=1}^{p} \beta_i X_{t-i})|. \]

with \( X_0 = X_{-1} = \ldots = X_{-p} = 0 \) by convention.

Then the assumptions of Property 4.1 and 4.2 are satisfied since the Lipshitz coefficients of \( M_0 \) and \( f_j \) and their derivatives decrease exponentially fast (see for instance Bardet and Winterberger (2009)).

2/ GARCH process: The GARCH(p, q) process has been introduced by Bollerslev (1986) as the solution of equations

\[
\begin{align*}
X_t &= \sigma_t \zeta_t, \\
\sigma_t^2 &= \omega^0 + \sum_{i=1}^{p} \alpha_i \sigma_{t-i}^2 + \sum_{j=1}^{q} \beta_j \sigma_{t-j}^2,
\end{align*}
\]

where \( \zeta_t \) is a white noise. Then, if \( \sigma_{(n)} = \text{Argmax}_{(\alpha, \beta) \in \Theta \times \Gamma} \sum_{i=1}^{n} \overline{q}_i(\theta, \gamma) \) where \( \overline{q}_i(\theta, \gamma) := \log (\alpha) + \frac{1}{t_n} |\alpha|^{-1} |X_t - (\mu + \sum_{i=1}^{p} \beta_i X_{t-i})|, \)

with \( X_0 = X_{-1} = \ldots = X_{-p} = 0 \) by convention.

Then the assumptions of Property 4.1 and 4.2 are satisfied since the Lipshitz coefficients of \( M_0 \) and \( f_j \) and their derivatives decrease exponentially fast (see for instance Bardet and Winterberger (2009)).
where $\omega^0 > 0$, $\alpha^0_i \geq 0$ for $i = 1, \ldots, p$ and $\beta^0_j \geq 0$ for $j = 1, \ldots, q$ with $a^0_p, \beta^0_p$ positive and

$$\sum_{i=1}^{p} \alpha^0_i + \sum_{j=1}^{q} \beta^0_j < 1.$$ 

As a consequence $(X_i)$ is a stationary process such as $\mathbb{E}(|X_0|) < \infty$ (see for instance Bardet and Wintenberger (2009)). Such GARCH process is a special case of affine causal process (1) where $M'_0 = \sigma_t(\theta)$ and $f'_0 = 0$, we denote here $\theta = (\omega, \alpha_1, \ldots, \alpha_p, \beta_1, \ldots, \beta_q)$ and $(\sigma_t(\theta))$, satisfies the recurrence relationship

$$\sigma^2_t(\theta) = \omega + \sum_{i=1}^{p} \alpha^0_i X_{t-i}^2 + \sum_{j=1}^{q} \beta^0_j \sigma^2_{t-j}(\theta) \quad \text{for any } t \in \mathbb{Z}.$$ 

Now define $\Theta$ such as:

$$\Theta = \{ \theta \in [0, \infty)^{p+q+1}, \rho \leq \omega \leq 1/\rho, \sum_{i=1}^{p} \alpha^0_i + \sum_{j=1}^{q} \beta^0_j \leq \rho' \}.$$ 

with $0 < \rho, \rho' < 1$, and this ensuring the stationarity of $(X_i)$ for any $\theta \in \Theta$. Using Lemma 3.1 we get

$$\tilde{r}_n = H^{-1} \left( \frac{1}{n} \sum_{i=1}^{n} \frac{\sigma^2_t(\theta^{(1)})}{\sigma^2_t(\theta^{(2)})} \right)$$

where $\sigma^2_t$ is defined using $(X_i)_{i \in \mathbb{N}} = 0$.

We estimate $\theta$ by the Generalized Gaussian Quasi-Maximum Likelihood Estimator $\hat{\theta}_n^{(\omega)}$ defined by

$$\hat{\theta}_n^{(\omega)} : = \text{Argmin}_{\theta \in \Theta} \left( \frac{1}{n} \sum_{i=1}^{n} \left( \log |M'_0| + \frac{1}{r_n} \left| \frac{X_i}{M'_0} \right| \right) \right).$$

Then the assumptions of Property 4.1 and 4.2 are satisfied since the Lipshitz coefficients of $M_0$ and $f_j$ and their derivatives decrease exponentially fast (see for instance Bardet and Wintenberger (2009)).

3/ APARCH process: The APARCH($p, \delta, q$) processes have been introduced by Ding et al. (1993) as the solution of equations

$$\begin{cases} X_i = \sigma_t \zeta_t, \\ \sigma_t^2 = \omega^0 \xi^0 + \sum_{j=1}^{p} \alpha_j^0 (X_{t-j} - \gamma^0_j \xi_{t-j})^\delta + \sum_{j=1}^{q} \beta_j^0 \sigma^{2}_{t-j}, \end{cases}$$

where $\delta \geq 1$, $\omega^0 > 0$, $-1 < \gamma^0_j < 1$ and $\alpha^0_j \geq 0$ for $i = 1, \ldots, p$, $\beta^0_j \geq 0$ for $j = 1, \ldots, q$ satisfying $\sum_{j=1}^{q} \beta^0_j < 1$. In the sequel the parameter $\delta$ is supposed to be known.

More generally, we denote now

$$\theta = (\omega, \alpha_1, \ldots, \alpha_p, \gamma_1, \ldots, \gamma_p, \beta_1, \ldots, \beta_q),$$

with $\omega > 0$, $-1 < \gamma_i < 1$ and $\alpha_i \geq 0$ for $i = 1, \ldots, p$, $\beta_j \geq 0$ for $j = 1, \ldots, q$ satisfying $\sum_{j=1}^{q} \beta^0_j < 1$. Then conditions of stationarity of $(X_i)$ can be deduced. Indeed, using $L$ the usual backward operator such as $LX_i = X_{i-1}$, then $(1 - \sum_{j=1}^{q} \beta_j L)^{-1}$ exists and simple computations imply for $t \in \mathbb{Z}$:

$$\sigma^2_t(\theta) = \left( 1 - \sum_{j=1}^{q} \beta_j L \right)^{-1} \left[ \omega + \sum_{i=1}^{p} \alpha_i (1 - \gamma^0_i \xi_{t-i})^\delta + \alpha_i (1 + \gamma^0_i (-\min(X_{t-i}, 0))^\delta \right]$$

$$= b_0(\theta) + \sum_{i=1}^{p} b^+_i(\theta) (\max(X_{t-i}, 0))^\delta + \sum_{i=1}^{q} b^-_i(\theta) (\max(-X_{t-i}, 0))^\delta.$$ 

where $b_0(\theta) = \omega (1 - \sum_{j=1}^{q} \beta_j L)^{-1}$ and the coefficients $(b^+_i(\theta), b^-_i(\theta))_{i \geq 1}$ are defined by the recursion relations

$$\begin{cases} b^+_i(\theta) = \sum_{k=1}^{p} \beta_k b^+_i(\theta) + \alpha_i (1 - \gamma_i)^\delta \quad \text{with} \quad \alpha_i (1 - \gamma_i) = 0 \quad \text{for} \quad i > p, \\ b^-_i(\theta) = \sum_{k=1}^{q} \beta_k b^-_i(\theta) + \alpha_i (1 + \gamma_i)^\delta \quad \text{with} \quad \alpha_i (1 + \gamma_i) = 0 \quad \text{for} \quad i > p. \end{cases}$$

(27)
with \( b^*_i(\theta) = b^*_i(\theta) = 0 \) for \( i \leq 0 \).

As a consequence, an APARCH process is a special case of the affine causal process with \( f^*_{\theta} \equiv 0 \) and \( M^*_{\theta} = \sigma^2_{\theta}(\theta) \).

Therefore \( a_j^{(0)}(f, \Theta) = 0 \) and simple computations imply \( a_j^{(0)}(M, \{\theta\}) = \sup_{\theta \in \Theta} \max(|b^*_j(\theta)|^{1/\delta}, |b^*_j(\theta)|^{1/\delta}) \) and we established in Bardet et al. (2017) that the sequence \( (a_j^{(0)}(M, \{\theta\})) \), decreases exponentially fast. Thus, with \( 0 < \rho, \rho' < 1 \) define the compact set \( \Theta \) by

\[
\Theta = \left\{ \theta \in \mathbb{R}^{2p + q + 1} \mid \rho \leq \omega \leq 1/\rho \text{ and } \sum_{j=1}^{\infty} \max (|b_j^*|^{1/\delta}, |b_j^*|^{1/\delta}) \leq \rho' \right\}. \tag{28}
\]

For \( \theta^* \in \Theta \), the estimator of the parameter shape \( r_0 \) in the case of an APARCH process is

\[
\hat{r}_n = H^{-1} \left( \frac{1}{n} \sum_{j=1}^{\infty} \frac{\sigma_j^2(\hat{\theta}_n^{(1)})}{\sigma_j^2(\hat{\theta}_n^{(1)})} \right). \tag{29}
\]

Since we have an estimation \( \hat{r}_n \) for the parameter shape \( r \), we use it in the estimation of \( \hat{\theta}_n \)

\[
\hat{\theta}_n^{(r)} := \text{Argmin}_{\theta \in \Theta} \sum_{j=1}^{\infty} \left( \log (M^j_\theta) + \frac{1}{r_n} \frac{X_j}{M^j_\theta} \right).
\]

Then the assumptions of Property 4.1 and 4.2 are satisfied since the Lipshitz coefficients of \( M_\theta \) and \( f_\theta \) and their derivatives decrease exponentially fast (see for instance Bardet et al. (2017)).

6. Numerical Results

In order to illustrate the interest of the estimate of the parameter shape \( r \), we realize Monte-Carlo experiments on the behavior of Gaussian QMLE, Laplace QMLE and the Pseudo Generalized Gaussian QMLE, for GARCH and APARCH processes and several sizes of sample \( (n = 100, n = 1000 \text{ and } n = 5000) \). More precisely, we will consider:

- a GARCH(1, 1) process defined by \( X_t = \sigma_t \zeta_t \), where \( \sigma_t^2 = \alpha_0 + \alpha_1 X_{t-1}^{2} + \beta \sigma_{t-1}^2 \) with \( \alpha_0 = 0.2, \alpha_1 = 0.4 \) and \( \beta = 0.2 \);

- an APARCH(1, \( \delta \), 1) process defined by \( X_t = \sigma_t \zeta_t \), where \( \sigma_t^2 = \alpha_0 + \alpha_1 (|X_{t-1}| - \gamma X_{t-1})^{\delta} + \beta \sigma_{t-1}^2 \) and \( \alpha_0 = 0.2, \alpha_1 = 0.4, \gamma = 0.8, \beta = 0.2 \) and \( \delta = 1.2(\delta \text{ is supposed to be known}).

6.1. Estimation of \( r \)

We first consider white noise \( (\zeta_t)_{t \in \mathbb{Z}} \) such that the distribution of \( \zeta_0 \) is a generalized Gaussian distributions for several values of \( r \): \( r = 1 \) (Laplace distribution), \( r = 1.3, r = 1.7, r = 2 \) (Gaussian distribution) and \( r = 2.6 \). Using 1000 independent replications of both the processes, \( r \) is estimated by \( \hat{r}_n \) defined in (12) and its root-mean-square error (RMSE) is computed and reported in forthcoming tables 1 and 2.

<table>
<thead>
<tr>
<th>( r = 1 )</th>
<th>( r = 1.3 )</th>
<th>( r = 1.7 )</th>
<th>( r = 2 )</th>
<th>( r = 2.6 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( n = 100 )</td>
<td>0.362</td>
<td>0.366</td>
<td>0.650</td>
<td>1.007</td>
</tr>
<tr>
<td>( n = 1000 )</td>
<td>0.064</td>
<td>0.084</td>
<td>0.122</td>
<td>0.158</td>
</tr>
<tr>
<td>( n = 5000 )</td>
<td>0.030</td>
<td>0.039</td>
<td>0.051</td>
<td>0.071</td>
</tr>
</tbody>
</table>

Table 1: RMSE of \( \hat{r}_n \) for the GARCH(1, 1) process particular case from 1000 independent replications.

Conclusion of the numerical results: The simulations exhibit that the larger the sample size \( n \) the smaller the RMSE of the parameter shape estimator \( \hat{r}_n \). They also show that the larger the shape parameter \( r \) the larger the RMSE of \( \hat{r}_n \). More precisely, it seems that the RMSE of \( \hat{r}_n/r \) is only depending on \( n \).
6.2. Comparisons of Gaussian, Laplacian and Pseudo-Gaussian Generalized QMLE

Now consider \( r \) variance white noise \((\zeta_0^r)\). Hence, to allow comparison of the estimators, we have chosen the usual normalization of the model writing with unit variance:

- the Gaussian distribution \( N(0, 1) \);
- the centered Laplacian distribution \( \mathcal{L}(1/\sqrt{2}) \);
- the Uniform distribution \( \mathcal{U}([-\sqrt{3}, \sqrt{3}]) \);
- the renormalized Student distribution \( \sqrt{3/5} t_s \).

Hence, to allow comparison of the estimators, we have chosen the usual normalization of the model writing with unit variance white noise \((\zeta_0)\). We first assume that \( \zeta_0 \) follows a Generalized Gaussian distribution \( \text{GED}(0, \alpha, \beta) \) to within one multiplicative constant, with \( r_0 \geq 1 \), and therefore \( \zeta_0 = (m_{r_0}(2))^{-1/2} Z_0 \) for obtaining \( \mathbb{E}(\zeta_0^2) = 1 \). Then we can write with \( r_0 \geq 1 \):

In the sequel, we will consider white noises \((\zeta_0)\) where \( \zeta_0 \) follows several different probability distributions with unit variance:

- the Gaussian distribution \( N(0, 1) \);
- the centered Laplacian distribution \( \mathcal{L}(1/\sqrt{2}) \);
- the Uniform distribution \( \mathcal{U}([-\sqrt{3}, \sqrt{3}]) \);
- the renormalized Student distribution \( \sqrt{3/5} t_s \).

Hence, to allow comparison of the estimators, we have chosen the usual normalization of the model writing with unit variance white noise \((\zeta_0)\). We first assume that \( \zeta_0 \) follows a Generalized Gaussian distribution \( \text{GED}(r_0) \) to within one multiplicative constant, with \( r_0 \geq 1 \), and therefore \( \zeta_0 = (m_{r_0}(2))^{-1/2} Z_0 \) for obtaining \( \mathbb{E}(\zeta_0^2) = 1 \). Then we can write with \( r_0 \geq 1 \):

\[
X_t = M_{\mu^r_0}^r \cdot \zeta_t = M_{\mu^r_0}^r \cdot (m_{r_0}(2))^{-1/2} \zeta_t^r
\]

with \( \zeta_0^r \) a white noise such as \( \zeta_0^r \) follows the \( \text{GED}(r_0) \) distribution defined in (3).

Now consider \( r \geq 1 \). We can write:

\[
X_t = M_{\mu^r_0}^r \cdot \zeta_t = \left( \frac{m_{r_0}(r)}{m_{r_0}(2)} \right)^{1/r} \left( M_{\mu^r_0}^r \right)^{2/r} \zeta_t^r = M_{\mu^r_0}^{2/r} \cdot \zeta_t^r,
\]

with \( \zeta_0^r = \zeta_t \left( \frac{m_{r_0}(2))^{1/2}}{m_{r_0}(r)} \right) \) and therefore \( \mathbb{E}(\zeta_t^r | \theta(r)) = 1 \). As a consequence,

1. For GARCH(1, 1) process, we have \((M_{\mu^r_0}^{2/r})^2 = a_0^{(2r)} + a_1^{(2r)}X_{t-1}^2 + \beta^{(2r)}(M_{\mu^r_0}^{2/r})^2\). Then we deduce

\[
(M_{\mu^r_0})^2 = \frac{(m_{r_0}(r))^{2/r}}{m_{r_0}(2)} \left( a_0^{(2r)} + a_1^{(2r)}X_{t-1}^2 + \beta^{(2r)}(M_{\mu^r_0}^{2/r})^2 \right) = a_0^{(r)} + a_1^{(r)}X_{t-1}^2 + \beta^{(r)}(M_{\mu^r_0})^2
\]

\[
\Rightarrow \begin{cases}
\alpha_0^{(r)} = \frac{(m_{r_0}(r))^{2/r}}{m_{r_0}(2)} a_0^{(2r)}
\alpha_1^{(r)} = \frac{(m_{r_0}(r))^{2/r}}{m_{r_0}(2)} a_1^{(2r)}
\beta^{(r)} = \beta^{(2r)}
\end{cases}
\]

Thus, we will compare three estimators of \( \theta^{(2r)} = (a_0^{(2r)}, a_1^{(2r)}, \beta^{(2r)}) \):

- the classical Gaussian QMLE \( \hat{\theta}_n^{(2)} = (\tilde{\alpha}_0^{(2)}, \tilde{\alpha}_1^{(2)}, \tilde{\beta}^{(2)}) \) defined in (7);

<table>
<thead>
<tr>
<th>( n )</th>
<th>( r = 1 )</th>
<th>( r = 1.3 )</th>
<th>( r = 1.7 )</th>
<th>( r = 2 )</th>
<th>( r = 2.6 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>0.522</td>
<td>0.672</td>
<td>1.560</td>
<td>2.946</td>
<td>2.386</td>
</tr>
<tr>
<td>1000</td>
<td>0.073</td>
<td>0.090</td>
<td>0.756</td>
<td>0.218</td>
<td>0.271</td>
</tr>
<tr>
<td>5000</td>
<td>0.029</td>
<td>0.036</td>
<td>0.067</td>
<td>0.089</td>
<td>0.117</td>
</tr>
</tbody>
</table>

Table 2: RMSE of \( \hat{\theta}_n \) for the APARCH(1, 1) process particular case from 1000 independent replications.
Remark: Since $\theta$ is obtained from the reciprocal function $H^{-1}$, it could not be defined if the condition $\frac{1}{n} \sum_{i=1}^{n} \left( \frac{Y_{i}}{Y_{i}^{\delta}} \right)^{2} < \infty$.
0.75 is not satisfied. As a consequence, in the numerical procedure we set $\hat{r}_n = 10$ when $\frac{1}{n} \sum_{t=1}^{n} \left( \tilde{M}_t \tilde{\theta}_{(1)}^{(1)} \right)^2 \geq 0.74$. This is a very common case when we take the uniform distribution as the one of the white noise.

The results are presented in Tables 3 and 4.

<table>
<thead>
<tr>
<th></th>
<th>$\tilde{L}$</th>
<th>$\tilde{N}$</th>
<th>$\tilde{t}_3$</th>
<th>$\tilde{U}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$n = 100$</td>
<td>$\alpha_0$</td>
<td>0.622</td>
<td>0.096</td>
<td>0.102</td>
</tr>
<tr>
<td></td>
<td>$\alpha_1$</td>
<td>0.801</td>
<td>0.253</td>
<td>0.279</td>
</tr>
<tr>
<td></td>
<td>$\beta$</td>
<td>0.392</td>
<td>0.230</td>
<td>0.273</td>
</tr>
<tr>
<td></td>
<td>$\text{Sum}$</td>
<td>1.816</td>
<td>0.580</td>
<td>0.654</td>
</tr>
<tr>
<td>$\tilde{r}_n$</td>
<td>1.323</td>
<td>2.540</td>
<td>1.647</td>
<td>8.872</td>
</tr>
<tr>
<td>$n = 1000$</td>
<td>$\alpha_0$</td>
<td>0.043</td>
<td>0.039</td>
<td>0.043</td>
</tr>
<tr>
<td></td>
<td>$\alpha_1$</td>
<td>0.102</td>
<td>0.092</td>
<td>0.102</td>
</tr>
<tr>
<td></td>
<td>$\beta$</td>
<td>0.104</td>
<td>0.102</td>
<td>0.111</td>
</tr>
<tr>
<td></td>
<td>$\text{Sum}$</td>
<td>0.250</td>
<td>0.234</td>
<td>0.256</td>
</tr>
<tr>
<td>$\tilde{r}_n$</td>
<td>1.021</td>
<td>2.035</td>
<td>1.224</td>
<td>9.789</td>
</tr>
<tr>
<td>$n = 5000$</td>
<td>$\alpha_0$</td>
<td>0.018</td>
<td>0.017</td>
<td>0.019</td>
</tr>
<tr>
<td></td>
<td>$\alpha_1$</td>
<td>0.042</td>
<td>0.040</td>
<td>0.044</td>
</tr>
<tr>
<td></td>
<td>$\beta$</td>
<td>0.046</td>
<td>0.046</td>
<td>0.051</td>
</tr>
<tr>
<td></td>
<td>$\text{Sum}$</td>
<td>0.106</td>
<td>0.102</td>
<td>0.114</td>
</tr>
<tr>
<td>$\tilde{r}_n$</td>
<td>1.001</td>
<td>2.008</td>
<td>1.198</td>
<td>9.995</td>
</tr>
</tbody>
</table>

Table 3: Sample mean of $\tilde{r}_n$ and Root-Mean Square Error of the components of $\tilde{\theta}_n^{(1)}$, $\tilde{\theta}_n^{(2)}$ and $\tilde{\theta}_n^{(3)}$ for the considered GARCH(1, 1) processes.

Conclusion of the numerical results: Firstly, the simulations exhibit that the larger the sample size $n$ the smaller the RMSE of the estimators. Secondly, as we suspected, $\tilde{\theta}_n^{(1)}$ and $\tilde{\theta}_n^{(2)}$ give the best results when the white noise distribution is Laplace (respectively Gaussian). Thirdly, globally, it is $\tilde{\theta}_n^{(3)}$ which provides the best results when $n \geq 1000$ (otherwise for $n = 100$ a bad estimation of $r_0$ can be damaging to it). For uniform and Student distributions that are not GED distributions, the procedure automatically searches for the nearest GED. The PGGQMLE estimator $\tilde{\theta}_n^{(3)}$ uses this to provide an estimator as close as possible to the one obtained by maximizing the "true" conditional quasi-likelihood.
Table 4: Sample mean of $\hat{r}_n$ and Root-Mean Square Error of the components of $\theta_0^n$, $\theta_1^n(1)$ and $\theta_2^n(2)$ for the considered APARCH(1, 1) processes.

References


