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Analysis of accurate and stable finite volume scheme for anisotropic diffusion equations with drift

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Abstract

This work addresses the development and analysis of a second-order accurate finite volume scheme for parabolic equations with anisotropy on general simplicial meshes. The discretization involves only vertex unknowns without processing additional ones. The scheme construction makes use of a nonlinear transformation of the linear elliptic term. Two propositions are presented for the approximation of the mobility function at the interfaces. The existence of positive solutions for the discrete system is guaranteed thanks to the proved a priori estimates. The energy dissipation of the scheme is moreover ensured. The convergence of the approach is established. Numerical tests are given to show the efficiency, accuracy and robustness of the proposed approach, with respect to the anisotropy, while a particular emphasis is set on the effects of the approximate mobility. They also confirm the obtained theoretical results, especially the decay of the free energy when time grows.

1 Introduction

Anisotropic convection-diffusion equations are essential in modeling many real-world problems arising from complex reservoir models [18], chemotaxis processes [29] and systems of semiconductor devices [4]. In such an application the numerical approximation of the model should ideally persevere the physical properties of the continuous problem. For instance, in the context of porous media flows the permeability can be strongly anisotropic and highly heterogeneous. Then, in these situations, the approximate solution accounting for the saturation or the concentration must be nonnegative in order to avoid nonphysical oscillations. This holds the name of a discrete maximum principle. Moreover, in the numerical modeling of semiconductors, the control of some dissipated entropies is of crucial importance to understand the large time behavior of the physics being modeled. Hence, developing consistent, accurate and cheap numerical methods of type finite volumes on general meshes respecting the underlined properties is of great importance.

In view of its fundamental role, extensive research has been devoted to the discrete maximum principle for anisotropic linear diffusion problems. The pioneer two-point flux approximation (TPFA) scheme fulfills this property by construction [23]. In the presence of convective effects, it is recommended to employ the Scharfetter-Gummel approach of the TPFA scheme [16, 37] instead of the upwind version for better accuracy and stability. Unfortunately, these methods necessitates a stringent orthogonality condition on the mesh together with a scalar isotropic tensor. From a general viewpoint, it is well understood that no linear finite volume method for the linear diffusion preserves unconditionally the physical ranges of the approximate solution [21, 35] without additional assumptions. A tough attention was then given to nonlinear versions [10, 24, 32, 33, 34, 38]. Most of these schemes make use of a convex splitting of the flux in the co-normal direction. Other unknowns, placed at the vertices or edges etc, are required to define accurately each component and they can be eliminated after that. Although they are accurate of second-order, these kinds of methods does not fulfill the coercivity of the scheme without further assumptions on

the mesh and the anisotropic ratio. To ensure the latter, a general approach was addressed in [11]. It is applied to centered scheme or merely built on coercive centered finite volume methods. Yet, consistency or convergence is valid when a numerical assumption holds. Recently, a few convergent positive schemes were designed and analyzed for degenerate parabolic equations with anisotropy, see for instance [13, 25, 26, 36]. The methodology used in these references is accurate of first order for the diffusion since the idea is based on an unwinding strategy of Godunov type. In the work [14], the authors proposed and investigated an accurate vertex approximation gradient methodology. It uses vertex and cell unknowns where the latter are eliminated at the solver level. Also, the implementation of this methodology shows that the iterative solver is extremely sensible to highly anisotropic ratios of the permeability when the discrete mobility function is given by a centered arithmetic mean.

On the other hand, the considered model problem is dissipated and possesses an energy functional of Lyapunov type. The control of the latter allows to obtain relevant information on the asymptotic behavior of the solutions such as the exponential decay to the equilibrium [30, 31]. In the discrete setting, the large time behavior has been addressed in [7, 5] using a Two-Point finite volume discretizations together with the Scharfetter-Gummel strategy. Establishing finite volume methods coupling between the energy diminishing, optimal accuracy, as well as positivity for such a model under general assumptions on the data and on the mesh is quite challenging. Only few papers have been devoted to such a topic in the context of multi-point framework [12, 14].

In this paper, we propose a vertex-centered finite volume scheme on general simplicial meshes applied to a basic anisotropic linear diffusion equation with drift, due to its practical importance. The main objective of this contribution consists in extending the ideas of the scheme presented in [36]. Indeed, even if the discretization elaborated in [36] enjoys some advantages, it however suffers from several limitations. For instance, we reveal :

- the numerical convergence is only first order in space;
- it does not allow the control of the free energy;
- it is not suitable to preserve the long time behavior of the solutions since the methodology is based on the upwinding, see [6] for deep details.

In the present contribution, we aim to dispense with the previous items weakening the use of [36]. We below recall and state the assets of the new scheme.

- Unknowns are only placed at the vertices, which turns out the computational cost cheaper;
- accuracy of second order;
- the control of the free energy;
- preserving the asymptotic of solutions as fast as possible (numerical exponential decay).
- handling highly anisotropic and heterogeneous domains;
- honoring the physical bounds (positivity) on the approximate solution;
- theoretical convergence towards the continuous solution of the mathematical problem.

The task is first achieved by formulating the elliptic term into a very specific nonlinear manner allowing the dissipation of the entropy function. Next, we use the spacial discretization elaborated in [36]. Moreover, in [36], we employed an upwind approximation of the mobility-like function. In the current paper, we take advantage of a centered scheme to avoid the reduction in the numerical convergence rate. Two propositions on the centered approximation can be made. First, one has the possibility to take the arithmetic mean value as done for instance in [13]. Second, one considers a fractional logarithmic average. Both of them respect the above prescribed physical properties of the solutions and allow the convergence of the numerical scheme from a theoretical point of view. In practice, the first choice does not support highly anisotropic tensors whereas the behavior of the logarithmic centered choice is independent of anisotropy.

The content of this paper is outlined as follows. We next state the mathematical model we are interested in as well as the definition of weak solutions. Section 2 describes the finite volume discretization, namely the spacial and temporal meshes, the reconstruction operators and the discrete functional spaces. We next present the proposed numerical scheme under its pointwise and concise forms. In Section 3, we establish several properties of the scheme, especially the energy estimates, estimations on the free energy of the system

and existence of discrete solutions. In Section 4, we study the convergence of these solutions towards a weak solution by means of a recent compactness argument. Finally, Section 5 shows numerical assessment of errors produced by our method and their associate convergence rates. The approach robustness with respect to the tensor anisotropy is also tested. It is illustrated that the proposed methodology is free diminishing in the sense that the energy dissipates in the course of time.

Let Ω be a bounded connected open polyhedral subset of \mathbb{R}^d ($d \in \mathbb{N}^*$) with a Lipschitz boundary Γ . Let us set $Q_{t_f} = \Omega \times (0, t_f)$ where $t_f > 0$ is time. In this work, we are interested in the model example

$$s_t - \operatorname{div} \left(\mathbb{D} \nabla s + s \mathbb{D} \nabla G(x) \right) = 0 \quad \text{in } Q_{t_f}, \quad (1.1)$$

with the no-flux boundary condition

$$\left(\mathbb{D} \nabla s + s \mathbb{D} \nabla G(x) \right) \cdot \mathbf{n} = 0 \quad \text{on } \Gamma \times [0, t_f), \quad (1.2)$$

and the initial state of the solution

$$s(0, \cdot) = s^0(x) \quad \text{in } \Omega. \quad (1.3)$$

The approach we adapt here is based on an equivalent formulation of the potential. Therefore, the equation (1.1) rewrites

$$s_t - \operatorname{div} \left(s \mathbb{D} \nabla (\log(s) + G(x)) \right) = 0 \quad \text{in } Q_{t_f}. \quad (1.4)$$

Now, let us state the main assumptions on the physical data of the problem. They are mandatory to give a proper sense to the sought solutions.

(H₁) The matrix \mathbb{D} is symmetric and uniformly elliptic in the sense that there exist α_0 and α_1 such that

$$\alpha_0 |u|^2 \leq \mathbb{D}(x)u \cdot u \leq \alpha_1 |u|^2 \quad \forall a.e. \ x \in \Omega \text{ and } \forall u \in \mathbb{R}^d.$$

(H₂) The exterior potential G is a nonnegative function of $\mathcal{C}^1(\bar{\Omega}, \mathbb{R})$.

(H₃) The initial datum s^0 is nonnegative and belongs to $L^1(\Omega)$. We define the convex mapping $\mathcal{H} : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ by

$$\mathcal{H}(v) = v \log(v) - v + 1. \quad (1.5)$$

We require that this function possesses a finite entropy condition on s^0 i.e.

$$\int_{\Omega} \mathcal{H}(s^0(x)) \, dx < +\infty, \quad \text{and} \quad \int_{\Omega} s^0(x) \, dx > 0. \quad (1.6)$$

The following statement surveys the definition of a weak solution.

Definition 1.1. *Under Assumptions (H₁)-(H₃), a measurable function $s : Q_{t_f} \rightarrow (0, +\infty)$ is said to be a weak solution to the problem (1.1)-(1.3) if the following items are fulfilled.*

(i) $\mathcal{H}(s) \in L^\infty(0, t_f; L^1(\Omega))$ and $\xi(s) := \sqrt{s} \in L^2(0, t_f; H^1(\Omega))$.

(ii) *The integral identity holds*

$$- \int_{Q_{t_f}} s \psi_t \, dx \, dt - \int_{\Omega} s^0 \psi(\cdot, 0) \, dx + \int_{Q_{t_f}} \mathbb{D} \left(\nabla s + s \nabla G(x) \right) \cdot \nabla \psi \, dx \, dt = 0, \quad \forall \psi \in \mathcal{C}_c^\infty(\bar{\Omega} \times [0, t_f]). \quad (1.7)$$

The existence of a weak solution is ensured thanks to the arguments developed in [1]. We define the free energy \mathfrak{E} and the dissipation \mathfrak{J} for the evolutive equation (1.1) by

$$\mathfrak{E}(t) = \int_{\Omega} \mathcal{H}(s) + sG \, dx, \quad \mathfrak{J}(t) = \int_{\Omega} s \mathbb{D} \nabla (\log(s) + G) \cdot \nabla (\log(s) + G) \, dx.$$

Formally, taking $\psi = \log(s) + G$ in the weak formulation (1.7) implies the energy-dissipation relationship

$$\frac{d\mathfrak{E}}{dt} + \mathfrak{J} = 0.$$

Using the fact that $\mathfrak{J} \geq 0$ we get

$$\frac{d\mathfrak{E}}{dt} = -\mathfrak{J} \leq 0. \quad (1.8)$$

Thereby, the free energy is diminishing in time. This structural feature was intensively employed to study the large time behavior of solutions thanks to entropy's methods. For more details on this strategy, we refer to the article [15]. In the recent years, a particular attention was paid to setting the entropy principles from a numerical point of view. For instance, the numerical investigation of asymptotic of solutions to convection-diffusion equations based on the discrete version of the entropy methodology can be found [5, 17, 27] in the framework of TPFA schemes. We also mention the work [12] where a discrete duality finite volume scheme enjoying (1.8) was studied. We will see later on that our methodology respects the decay of the free energy even on anisotropic situations.

2 Finite volume discretization

In this section, we set the discrete tools that are necessary to define and study the proposed numerical scheme.

2.1 Meshes and reconstruction operators

Spacial discretization : the domain Ω is discretized with two different partitions. The first one consists in an admissible finite element triangulation referred to as the primal mesh. The second one or the dual mesh is built around the vertices of the elements. While the presentation of the terminologies below can be extended to the 3D setting, we rather expose the 2D version in order to keep the ease readability of the discrete framework.

Let \mathcal{T} be a conforming triangulation of Ω composed of triangles satisfying $\bigcup_{T \in \mathcal{T}} \bar{T} = \bar{\Omega}$. We define x_T the mass center and h_T the diameter of the simplex $T \in \mathcal{T}$. Also, let ρ_T be the largest diameter of the inscribed ball in T . The size and regularity of the primal mesh are respectively given by

$$h_{\mathcal{T}} = \max_{T \in \mathcal{T}} h_T, \quad \text{and} \quad \Theta_{\mathcal{T}} = \max_{T \in \mathcal{T}} \frac{h_T}{\rho_T}.$$

When $h_{\mathcal{T}}$ tends to zero, we assume that the refined meshes \mathcal{T}_h of the same triangulation has a uniformly bounded regularity $\Theta_{\mathcal{T}_h}$ [19].

We denote \mathcal{V} the set of vertices of the mesh, and \mathcal{V}_T the nodes of the simplex $T \in \mathcal{T}$. We can label each vertex of T thanks to the permutation τ acting on \mathcal{V}_T as depicted on the left side of Figure 1. We denote \mathcal{T}_i the set of elements having in common the vertex $i \in \mathcal{V}$. We assign a unique dual cell or control volume K_i centered at i for any given node $i \in \mathcal{V}$. A simple way to construct K_i is to connect the center of any triangle $T \in \mathcal{T}_i$ by the mid point of edges of T sharing the same vertex i . Given two finite volumes K_i and $K_{\tau(i)}$ we set $\overline{\sigma_{i\tau(i)}^T} = \overline{K_i} \cap \overline{K_{\tau(i)}} \cap \bar{T}$. The notation $|\sigma_{i\tau(i)}^T|$ represents the $(d-1)$ -dimensional measure of $\sigma_{i\tau(i)}^T$. The unit normal on this interface oriented from K_i to $K_{\tau(i)}$ is denoted by $\mathbf{n}_{\sigma_{i\tau(i)}^T}$. The set $\mathcal{E}_{K_i}^T$ refers to all the edges of K_i contained in the triangle $T \in \mathcal{T}_i$. We designate by x_i the center of the control volume K_i , and by $|K_i|$ the d -dimensional measure of K_i . The set of the control volumes K_i will be referred to as \mathcal{M} . Note that x_i denotes also the coordinate of the node i .

Remark 2.1. *In case of $d \geq 3$ one always can label the faces sharing a vertex $i \in \mathcal{V}_T$ for some element T thanks to a suitable permutation τ . A possible way to do so is given as follows. First, we fix the combination*

$$\tau^*(i) = \tau(i)\tau \circ \tau(i) \cdots \tau^d(i), \quad \tau^d = \underbrace{\tau \circ \cdots \circ \tau}_{d \text{ times}}$$

such that $\tau^{d+1}(i) = i$. Then we apply τ d -times on $i\tau^(i)$ to obtain all faces sharing the node i . In this case, we would use the notation $\sigma_{i\tau^*(i)}^T$ instead of $\sigma_{i\tau(i)}^T$ for the dual interfaces.*

Temporal discretization : the time interval $(0, t_f)$ is discretized thanks to a uniform subdivision given by the increasing sequence $(t^k)_{k=0, \dots, N}$ such that $t^1 = 0$ and $t^N = t_f$. Then, the time step is fixed to

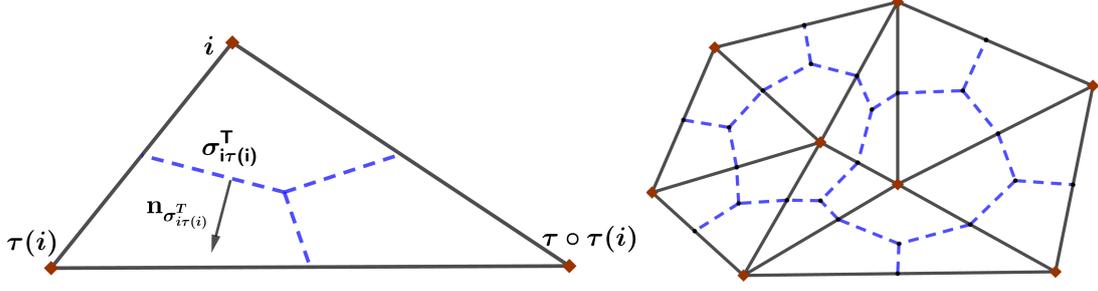


Figure 1: The spacial discretization of $T \in \mathcal{T}$ (left) and illustration of the dual mesh (right).

$\Delta t = t_f/N$. This uniform stepping is only taken to avoid heavy notations. The proofs carried out in this paper can be broadened to nonuniform time steps without any technical issues.

Reconstruction operators : first, let us define $X_{\mathcal{T}}$ the standard \mathbb{P}_1 finite elements space on \mathcal{T} . We consider $(\varphi_i)_{i \in \mathcal{V}}$ the classical basis of $X_{\mathcal{T}}$ satisfying $\varphi_i(x_j) = 1$ if $j = i$ and $\varphi_i(x_j) = 0$ else. We define the reconstruction operator $\pi_{\mathcal{T}} : \mathbb{R}^{\#\mathcal{V}} \rightarrow X_{\mathcal{T}}$ by setting

$$\pi_{\mathcal{T}}u = \sum_{i \in \mathcal{V}} u_i \varphi_i, \quad \forall u \in \mathbb{R}^{\#\mathcal{V}}.$$

Similarly, let $X_{\mathcal{M}}$ be the space of piecewise constant functions on the dual mesh \mathcal{M} . We define the piecewise constant operator $\pi_{\mathcal{M}} : \mathbb{R}^{\#\mathcal{V}} \rightarrow X_{\mathcal{M}}$ such that

$$\pi_{\mathcal{M}}u = \sum_{i \in \mathcal{V}} u_i \mathbf{1}_{K_i}, \quad \forall u \in \mathbb{R}^{\#\mathcal{V}}.$$

If g a nonlinear function from \mathbb{R} into \mathbb{R} . We adopt the convention making $g(u) = (g(u_i))_{i \in \mathcal{V}}$ for every $u \in \mathbb{R}^{\#\mathcal{V}}$. Then, one has

$$\pi_{\mathcal{T}}g(u) = \sum_{i \in \mathcal{V}} g(u_i) \varphi_i, \quad \text{and} \quad \pi_{\mathcal{M}}g(u) = \sum_{i \in \mathcal{V}} g(u_i) \mathbf{1}_{K_i}, \quad \forall u \in \mathbb{R}^{\#\mathcal{V}}.$$

Let $\{\pi_{\mathcal{T}}^k u\}_{k=0, \dots, N}$ be a sequence of functions of $X_{\mathcal{T}}$ and let $\{\pi_{\mathcal{M}}^k u\}_{k=0, \dots, N}$ be a family of functions of the trial space $X_{\mathcal{M}}$. We define the time-dependent reconstruction functions $\pi_{\mathcal{T}, \Delta t}$, $\pi_{\mathcal{M}, \Delta t}$ respectively by

$$\pi_{\mathcal{T}, \Delta t}u(\cdot, t) = \pi_{\mathcal{T}}^k u, \quad \text{and} \quad \pi_{\mathcal{M}, \Delta t}u(\cdot, t) = \pi_{\mathcal{M}}^k u, \quad \forall t \in (t^{k-1}, t^k], \quad \forall k = 1, \dots, N. \quad (2.1)$$

This conduct us to define the time-dependent discrete gradient $\nabla \pi_{\mathcal{T}, \Delta t}u$ by

$$\nabla \pi_{\mathcal{T}, \Delta t}u(\cdot, t) = \nabla \pi_{\mathcal{T}}^k u, \quad \forall t \in (t^{k-1}, t^k], \quad \forall k = 1, \dots, N.$$

The following result establishes the link between some reconstruction functions and the discrete gradient.

Lemma 2.1. (see [36]) *Let $\pi_{\mathcal{T}}u$ be in $X_{\mathcal{T}}$. We consider the piecewise constant functions $\pi_{\mathcal{T}}\bar{u}$ and $\pi_{\mathcal{T}}\underline{u}$ defined respectively by*

$$\pi_{\mathcal{T}}\bar{u}(x) = \max_{y \in T} \pi_{\mathcal{T}}u(y) \quad \text{and} \quad \pi_{\mathcal{T}}\underline{u}(x) = \min_{y \in T} \pi_{\mathcal{T}}u(y), \quad \forall x \in T, \quad \forall T \in \mathcal{T}.$$

Then, one gets

$$\|\pi_{\mathcal{T}}\bar{u} - \pi_{\mathcal{T}}\underline{u}\|_{L^2(\Omega)} \leq \#\mathcal{V}_T h_{\mathcal{T}} \|\nabla \pi_{\mathcal{T}}u\|_{L^2(\Omega)^d}. \quad (2.2)$$

As a consequence

$$\|\pi_{\mathcal{M}}u - \pi_{\mathcal{T}}u\|_{L^2(\Omega)} \leq \#\mathcal{V}_T h_{\mathcal{T}} \|\nabla \pi_{\mathcal{T}}u\|_{L^2(\Omega)^d}. \quad (2.3)$$

2.2 Description of the numerical scheme

For the sake of simplicity we set $\Upsilon(s) = \log(s) + G$ throughout the paper. Without loss of generality, we assume that the tensor \mathbb{D} is constant per triangles. Before presenting of the proposed numerical scheme, we would like to survey how we derive the main discrete terms. Let us select a control volume K_i for some $i \in \mathcal{V}$. We integrate on K_i with $\partial K_i = \bigcup_{T \in \mathcal{T}_i} \bigcup \sigma_{i\tau(i)}^T$ and make use of Green's formula to get

$$- \int_{\partial K_i} s \mathbb{D} \nabla \Upsilon(s) \cdot \mathbf{n} \, d\sigma = - \sum_{T \in \mathcal{T}_i} \sum_{\sigma_{i\tau(i)}^T \in \mathcal{E}_{K_i}^T} \int_{\sigma_{i\tau(i)}^T} s \nabla \Upsilon(s) \cdot \mathbb{D} \mathbf{n}_{\sigma_{i\tau(i)}^T} \, d\sigma, \quad (2.4)$$

Being a finite volume method, our construction is based on the discretization of the local continuous fluxes. Following [36] we propose the following centered scheme to the integral flux across the interface $\sigma_{i\tau(i)}^T$

$$- \int_{\sigma_{i\tau(i)}^T} s \nabla \Upsilon(s) \cdot \mathbb{D} \mathbf{n}_{\sigma_{i\tau(i)}^T} \, d\sigma \approx \sqrt{s_{i\tau(i)}} \mathcal{G}_{i\tau(i)}^T(s_{\mathcal{T}}), \quad (2.5)$$

where $\sqrt{s_{i\tau(i)}}$ is given by one of the two different means

$$\sqrt{s_{i\tau(i)}} = \sqrt{\frac{s_i + s_{\tau(i)}}{2}}, \quad \sqrt{s_{i\tau(i)}} = \begin{cases} 2 \frac{\sqrt{s_i} - \sqrt{s_{\tau(i)}}}{\log(s_i) - \log(s_{\tau(i)})}, & \text{if } s_i \neq s_{\tau(i)}, \\ s_i, & \text{otherwise} \end{cases}. \quad (2.6)$$

The quantity $\mathcal{G}_{i\tau(i)}^T(s_{\mathcal{T}})$ is a numerical flux-like function that approximates $\sqrt{s} \nabla \Upsilon(s)$ along the co-normal vector $\mathbb{D} \mathbf{n}_{\sigma_{i\tau(i)}^T}$

$$\mathcal{G}_{i\tau(i)}^T(s_{\mathcal{T}}) = \sum_{j \in \mathcal{V}_T} a_{ij}^T \sqrt{s_{j\tau(j)}} \left(\Upsilon(s_j) - \Upsilon(s_{\tau(j)}) \right). \quad (2.7)$$

where the weight a_{ij}^T is given by [36]

$$a_{ij}^T = \frac{1}{|T|} \left| \sigma_{i\tau(i)}^T \right| \left| \sigma_{j\tau(j)}^T \right| \mathbb{D} \mathbf{n}_{\sigma_{i\tau(i)}^T} \cdot \mathbf{n}_{\sigma_{j\tau(j)}^T}.$$

To avoid small time steps in case of strong anisotropic ratios of the tensor \mathbb{D} we consider a fully implicit (backward Euler) discretization in time. Then, the numerical scheme consists in finding a sequence $(s_i^k)_i$ solving the algebraic set of equations at each time iteration $k = 1, \dots, N$

$$s_i^0 = \frac{1}{|K_i|} \int_{K_i} s^0(x) \, dx, \quad \forall i \in \mathcal{V}, \quad (2.8)$$

$$|K_i| \frac{s_i^k - s_i^{k-1}}{\Delta t} + \sum_{T \in \mathcal{T}_i} \sum_{\sigma_{i\tau(i)}^T \in \mathcal{E}_{K_i}^T} \sqrt{s_{i\tau(i)}^k} \mathcal{G}_{i\tau(i)}^T(s_{\mathcal{T}}^k) = 0, \quad \forall i \in \mathcal{V}, \quad (2.9)$$

$$s_i^k > 0, \quad \forall i \in \mathcal{V}. \quad (2.10)$$

The last constraint gives sense to sought discrete solutions because the use of the log function. The above system can be rewritten under a compact form. This formulation is of chief importance since it allows to straightforwardly conduct the analysis of the resulting finite volume scheme in a rigorous setting. To this purpose, we introduce the local diagonal matrix $(\mathcal{S}_{ij}^T)_{1 \leq i, j \leq \#\mathcal{V}_T}$ whose entries are

$$\mathcal{S}_{ij}^T = \begin{cases} \sqrt{s_{i\tau(i)}^k} & \text{if } j = \tau(i) \\ 0 & \text{if } j \neq \tau(i) \end{cases}.$$

For every $u \in \mathbb{R}^{\#\mathcal{V}_T}$, we denote $\delta_T u$ the vector of $\mathbb{R}^{\#\mathcal{V}_T}$ such that the component number i is $(\delta_T u)_i = u_i - u_{\tau(i)}$. We next define the discrete L^2 -semi-norm for two vectors $u_{\mathcal{T}}, v_{\mathcal{T}} \in \mathbb{R}^{\#\mathcal{V}}$ by

$$\llbracket u_{\mathcal{T}}, v_{\mathcal{T}} \rrbracket_{\mathcal{T}} = \sum_{i=1}^{\#\mathcal{V}} |K_i| u_i v_i.$$

Therefore, the equivalent form of the numerical scheme is obtained by performing a discrete integration by parts in space. It reads

$$\left[\left[\frac{s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}}{\Delta t}, v_{\mathcal{T}} \right]_{\mathcal{T}} + \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T v_{\mathcal{T}} \right] = 0, \quad \forall v_{\mathcal{T}} \in X_{\mathcal{T}}, \forall k = 1, \dots, N. \quad (2.11)$$

where the symmetric matrix \mathcal{A}^T is defined by $\mathcal{A}^T = (a_{ij}^T)_{1 \leq i, j \leq \#\mathcal{V}_T}$. By taking $v_{\mathcal{T}} = \mathbf{1}_{\mathcal{T}}$ in (2.11) we recover the discrete conservation of mass property

$$\left[s_{\mathcal{T}}^k, \mathbf{1}_{\mathcal{T}} \right]_{\mathcal{T}} = \int_{\Omega} \pi_{\mathcal{M}} s \, dx = \int_{\Omega} s^0 \, dx, \quad \forall k = 1, \dots, N. \quad (2.12)$$

The following lemma is the keystone result for the convergence analysis of our scheme. It shows in particular that the matrix \mathcal{A}^T is definite-positive.

Lemma 2.2. *There exist two positive constant μ_1 and μ_2 that depends only on α_0 , α_1 and the mesh regularity so that for all $T \in \mathcal{T}$, one has*

$$\mu_1 \frac{|T|}{h_T^2} \delta_T u \cdot \delta_T u \leq \delta_T u \cdot \mathcal{A}^T \delta_T u \leq \mu_2 \frac{|T|}{h_T^2} \delta_T u \cdot \delta_T u, \quad \forall u \in \mathbb{R}^{\#\mathcal{V}_T}. \quad (2.13)$$

Proof. The proof is carried out in [36]. It extends the ideas provided in [9, 14]. \square

Remark 2.2. *Observe that $\sqrt{s_{i\tau(i)}}$ can take other possible mean values framed by the ones given in (2.6).*

In the sequel, unless specified, we denote C generic positive constants that depends only on the physical data described in (\mathbf{H}_1) - (\mathbf{H}_3) and possibly on the regularity of the mesh.

3 A priori estimates and existence of discrete solutions

A priori estimates serve for multiple purposes. They ensure the stability of the proposed approach, namely the coercivity of the scheme and the decay of the free energy. By coercivity means that we can control the approximate gradient $\xi(s)$. As we are going to see, this property allows to prove existence of the finite volume scheme. Therefore, one can derive a positive lower bound on any discrete solution. Contrary to [14] our energy estimates, namely the next result, are not based on the energy-dissipation estimations.

Proposition 3.1. *Let $(s_i^k)_{i \in \mathcal{V}}$ be a sequence such that the finite volume scheme (2.8)-(2.10) holds. Then, there exist positive constants C_1 , C_2 , and C_3 , depending only on the physical data and the regularity of the mesh such that*

$$\sum_{T \in \mathcal{T}} |T| \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \leq C_1, \quad (3.1)$$

$$\Delta t \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2 \leq C_2, \quad (3.2)$$

$$\Delta t \left\| \nabla \pi_{\mathcal{T}}^k \xi(s) \right\|_{L^2(\Omega)^d} \leq C_3. \quad (3.3)$$

Proof. First, we observe that $s_{i\tau(i)}^k \leq s_i^k + s_{\tau(i)}^k$ and $|T| \leq C |T \cap K_i|$ for all $i \in \mathcal{V}_T$. Summing by dual cells and using the mass conservation property (2.12) we directly check

$$\sum_{T \in \mathcal{T}} |T| \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \leq 2C \sum_{i \in \mathcal{V}} |K_i| s_i^k \leq 2C \|s^0\|_{L^1(\Omega)} = C_1.$$

Next, we take $v_{\mathcal{T}} = \log(s_{\mathcal{T}}^k)$ in the formulation (2.11). This gives

$$E_1 + E_2 + E_3 = 0, \quad (3.4)$$

where each term writes

$$\begin{aligned} E_1 &= \frac{1}{\Delta t} \llbracket s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}, \log(s_{\mathcal{T}}^k) \rrbracket_{\mathcal{T}}, \\ E_2 &= \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \log(s_{\mathcal{T}}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \log(s_{\mathcal{T}}^k), \\ E_3 &= \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T G_{\mathcal{T}} \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \log(s_{\mathcal{T}}^k). \end{aligned}$$

Thanks to the convexity of the function \mathcal{H} defined in (1.5) we obtain

$$\frac{1}{\Delta t} \llbracket \mathcal{H}(s_{\mathcal{T}}^k) - \mathcal{H}(s_{\mathcal{T}}^0), \mathbf{1}_{\mathcal{T}} \rrbracket_{\mathcal{T}} \leq E_1. \quad (3.5)$$

According to the Cauchy-Schwarz inequality, the fact that $|G(x_i) - G(x_{\tau(i)})| \leq \|\nabla G\|_{\infty} h_T$ for all $i \in \mathcal{V}_T$, Lemma 2.2 and the estimation (3.1) we get

$$\begin{aligned} |E_3| &\leq (E_2)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T G_{\mathcal{T}} \cdot \mathcal{A}^T \mathcal{S}^T \delta_T G_{\mathcal{T}} \right)^{\frac{1}{2}} \\ &\leq C (E_2)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(G(x_i) - G(x_{\tau(i)}) \right)^2 \right)^{\frac{1}{2}} \\ &\leq C \|\nabla G\|_{\infty} (E_2)^{\frac{1}{2}} \left(\sum_{T \in \mathcal{T}} |T| \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \right)^{\frac{1}{2}} \leq C (E_2)^{\frac{1}{2}}. \end{aligned}$$

By virtue of Young's inequality we infer

$$|E_3| \leq C + \frac{1}{2} E_2. \quad (3.6)$$

In addition, we combine (3.4)–(3.6) and use the finite entropy condition (1.6) to ensure the uniform bound $\Delta t E_2 \leq C$. Owing to (2.13) we check that

$$\Delta t \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2 \leq C_2.$$

Applying once more Lemma 2.2 yields

$$\|\nabla \pi_{\mathcal{T}}^k \xi(s)\|_{L^2(\Omega)^d}^2 \leq \mu_1 \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} \left(\xi(s_i^k) - \xi(s_{\tau(i)}^k) \right)^2.$$

Now, if $s_{i\tau(i)}^k$ is the second choice of (2.6) we automatically obtain by construction that

$$\|\nabla \pi_{\mathcal{T}}^k \xi(s)\|_{L^2(\Omega)^d}^2 \leq \frac{\mu_1}{4} \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2.$$

On the other hand, if $s_{i\tau(i)}^k$ is the first choice of (2.6) we employ the elementary inequality

$$\left| \xi_i^k - \xi_{\tau(i)}^k \right| \leq \frac{1}{2} \max(\xi_i^k, \xi_{\tau(i)}^k) \left| \log(s_i^k) - \log(s_{\tau(i)}^k) \right|,$$

to deduce

$$\begin{aligned} \|\nabla \pi_{\mathcal{T}}^k \xi(s)\|_{L^2(\Omega)^d}^2 &\leq \mu_1 \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} \frac{1}{4} \max(s_i^k, s_{\tau(i)}^k) \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2 \\ &\leq \frac{\mu_1}{2} \sum_{T \in \mathcal{T}} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2. \end{aligned}$$

We therefore derive the estimation (3.3). \square

Let us elaborate the discrete counterpart of the energy-dissipation relationship (1.8). To this end, we define the approximate free energy by

$$\mathfrak{E}_h^k = \llbracket \mathcal{H}(s_{\mathcal{T}}^k), \mathbf{1}_{\mathcal{T}} \rrbracket_{\mathcal{T}} + \llbracket G_{\mathcal{T}}, s_{\mathcal{T}}^k \rrbracket_{\mathcal{T}} \geq 0, \quad \forall k = 0, \dots, N. \quad (3.7)$$

The approximate dissipation is given by

$$\mathfrak{J}_h^k = \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k). \quad (3.8)$$

Proposition 3.2. *The finite volume scheme is free diminishing (2.8)-(2.10) in the sense that*

$$\frac{\mathfrak{E}_h^k - \mathfrak{E}_h^{k-1}}{\Delta t} + \mathfrak{J}_h^k \leq 0, \quad \forall k = 1, \dots, N. \quad (3.9)$$

Consequently, the discrete free energy is bounded and is decreasing in time

$$0 \leq \mathfrak{E}_h^k \leq \mathfrak{E}_h^{k-1} \leq \|\mathcal{H}(s^0)\|_{L^1(\Omega)} + \|G\|_{\infty} \|s^0\|_{L^1(\Omega)}, \quad \forall k = 1, \dots, N. \quad (3.10)$$

Furthermore, the time integral of the discrete dissipation is uniformly bounded

$$0 \leq \sum_{k=1}^N \Delta t \mathfrak{J}_h^k \leq \|\mathcal{H}(s^0)\|_{L^1(\Omega)} + \|G\|_{\infty} \|s^0\|_{L^1(\Omega)}. \quad (3.11)$$

Finally, there holds

$$\|\pi_{\mathcal{M}, \Delta t} \mathcal{H}(s)\|_{L^{\infty}(0, t_f; L^1(\Omega))} \leq \|\mathcal{H}(s^0)\|_{L^1(\Omega)} + \|G\|_{\infty} \|s^0\|_{L^1(\Omega)}. \quad (3.12)$$

Proof. We proceed as in [14]. By selecting $v_{\mathcal{T}} = \Upsilon(s_{\mathcal{T}}^k)$ in the formulation (2.11) we see

$$\llbracket s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}, \Upsilon(s_{\mathcal{T}}^k) \rrbracket_{\mathcal{T}} + \Delta t \mathfrak{J}_h^k = 0, \quad \forall k = 1, \dots, N.$$

Thanks to the convexity of the function $\mathcal{H}(s) + sG$ and the nonnegativity of \mathfrak{J}_h^k we infer

$$\mathfrak{E}_h^k - \mathfrak{E}_h^{k-1} \leq \llbracket s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}, \Upsilon(s_{\mathcal{T}}^k) \rrbracket_{\mathcal{T}} + \Delta t \mathfrak{J}_h^k, \quad \forall k = 1, \dots, N.$$

This proves in particular 3.9. We now apply the Jensen inequality to obtain $|K_i| \mathcal{H}(s_i^0) \leq \int_{K_i} \mathcal{H}(s^0) dx$ for all $i \in \mathcal{V}$. Whence, we show (3.10). The inequality (3.11) is a direct consequence of (3.9)-(3.10). The last inequality (3.12) results from (3.7), (3.10) and Assumption **(H₂)**. This finishes up the proof. \square

Lemma 3.1. *Let $(s_i^k)_{i \in \mathcal{V}}$ be a family fulfilling the numerical scheme (2.8)-(2.10). Then, there exists a positive constant $\eta_{h, \Delta t} > 0$ depending on the mesh parameters such that*

$$s_i^k \geq \eta_{h, \Delta t}, \quad \forall i \in \mathcal{V}, \quad \forall k = 1, \dots, N. \quad (3.13)$$

Proof. By the mass conservation equality 2.12 and the assumption (1.6), one can find some $i_0 \in \mathcal{V}$ so that one has

$$s_{i_0}^k \geq \frac{1}{|\Omega|} \int_{\Omega} s^0(x) dx.$$

As a consequence

$$s_{i_0 \tau(i_0)}^k \geq \frac{1}{2|\Omega|} \int_{\Omega} s^0(x) dx, \quad \text{and} \quad \log(s_{i_0}) \geq -C'.$$

Owing to (3.2) we claim for all $T \in \mathcal{T}_{i_0}$, the set of elements sharing the vertex i_0 , that

$$s_{i_0 j}^k \left(\log(s_{i_0}^k) - \log(s_j^k) \right)^2 \leq C'_{h, \Delta t}, \quad \forall j \in \mathcal{V}_T$$

We deduce that, $\log(s_j^k) \geq -C''_{h, \Delta t}$, $\forall j \in \mathcal{V}_T$, $\forall T \in \mathcal{T}_{i_0}$. We conclude the proof by induction, which is an adaptation of the argument provided in [13, Lemma 3.10]. \square

We now state without proof the existence of discrete solutions at each time level. The proof is based on the topological degree's argument [20]. The main idea consists in choosing a suitable homotopy function yielding a monotone scheme whose existence is shown by mimicking the guidelines of [22]. Using the energy estimate (3.3) and the positivity estimate (3.13) allow to prove the uniform continuity of the residual function, coming from the finite volume scheme (2.8)-(2.9), on a compact subset of $(\mathbb{R}_*^+)^{\#\mathcal{T}}$. Then, no solution could exist on the boundary of this compact which implies directly the existence of at least one solution. More details can be consulted in [14].

Proposition 3.3. *For every $k = 1, \dots, N$, there exists at least a solution $(s_i^k)_{i \in \mathcal{V}}$ to the finite volume scheme (2.8)-(2.10).*

4 Convergence of the finite volume scheme

In this section we are concerned with the convergence proof of the numerical scheme. To this end, we should establish some compactness arguments. A possible way to do that is to derive uniform estimations on the space and time translations [23]. Instead of using this traditional strategy, we here apply the practical time-compactness recently elaborated in [2]. This ensures the existence of a convergent sub-sequence of discrete solutions. Furthermore, the limit of the latter has to be identified to a weak solution. We first require the following results.

Lemma 4.1. *(see [23, 26]) For a given $a \in \mathbb{R}^d$, let us set $Q_{t_f, a} = \Omega_a \times (0, t_f)$ with $\Omega_a = \{x \in \Omega / [x, a] \subset \Omega\}$. Then, there exists a positive constant C independent of the discretization parameters such that the following integral satisfies*

$$\int_{Q_{t_f, a}} |\pi_{\mathcal{M}, \Delta t} u(x+a, t) - \pi_{\mathcal{M}, \Delta t} u(x, t)| \, dx \, dt \leq C |a| \left(\sum_{k=1}^N \Delta t \|\nabla \pi_{\mathcal{T}}^k u\|_{L^2(\Omega)^d}^2 \right)^{\frac{1}{2}}, \quad (4.1)$$

for all $\pi_{\mathcal{M}, \Delta t} u$ defined by (2.1).

Let us now state and prove an estimate on the dual norm of the discrete time derivative. Let $\psi \in \mathcal{C}_c^\infty(\bar{\Omega} \times (0, t_f))$. In the sequel, we denote $\psi_{\mathcal{T}}^k$ the vector of $\mathbb{R}^{\#\mathcal{V}}$ such that $(\psi_{\mathcal{T}}^k)_i = \psi(x_i, t^k)$ for all $i = 1, \dots, \#\mathcal{V}$.

Lemma 4.2. *The exists a positive constant that depends only on the physical data and the regularity of the mesh such that*

$$\sum_{k=1}^N \llbracket s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}, \psi_{\mathcal{T}}^k \rrbracket_{\mathcal{T}} \leq C \|\nabla \psi\|_{\infty}, \quad \forall \psi \in \mathcal{C}_c^\infty(\bar{\Omega} \times [0, t_f]). \quad (4.2)$$

Proof. We consider $v_{\mathcal{T}} = \psi_{\mathcal{T}}^k$ in the concise form of the scheme (2.11). Then, we obtain the splitting

$$X + Y = 0,$$

where

$$\begin{aligned} X &= \sum_{k=1}^N \llbracket s_{\mathcal{T}}^k - s_{\mathcal{T}}^{k-1}, \psi_{\mathcal{T}}^k \rrbracket_{\mathcal{T}}, \\ Y &= \sum_{k=1}^N \Delta t \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \psi_{\mathcal{T}}^k. \end{aligned}$$

Applying the Cauchy-Schwarz inequality on the last term, making use of 2.13, employing the smoothness of the test function ψ and (3.1) yields

$$\begin{aligned} |Y|^2 &\leq \left(\sum_{k=1}^N \Delta t \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \Upsilon(s_{\mathcal{T}}^k) \right) \left(\sum_{k=1}^N \Delta t \sum_{T \in \mathcal{T}} \mathcal{S}^T \delta_T \psi_{\mathcal{T}}^k \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \psi_{\mathcal{T}}^k \right) \\ &\leq C \|\nabla \psi\|_{\infty} \sum_{T \in \mathcal{T}} |T| \sum_{i \in \mathcal{V}_T} s_{i\tau}^k \leq C \|\nabla \psi\|_{\infty}. \end{aligned}$$

This concludes the proof of the required inequality. \square

Proposition 4.1. *We assume that (\mathbf{H}_1) - (\mathbf{H}_3) are fulfilled. Let $(\mathcal{T}_m)_m$ be a sequence of refined mesh to \mathcal{T} such that $h_{\mathcal{T}_m}, \Delta t_m$ goes to 0 as m tends to infinity. Then, there exists a measurable function $s : Q_{t_f} \rightarrow (0, +\infty)$ so that the following convergences hold up to a subsequence*

$$\pi_{\mathcal{M}_m, \Delta t_m} s, \pi_{\mathcal{T}_m, \Delta t_m} s \longrightarrow s \quad \text{a.e. in } Q_{t_f}, \text{ and strongly in } L^1(Q_{t_f}) \quad (4.3)$$

$$\nabla \pi_{\mathcal{T}_m, \Delta t_m} \xi(s) \longrightarrow \nabla \xi(s) \quad \text{weakly in } L^2(0, t_f; H^1(\Omega)). \quad (4.4)$$

Proof. According to the energy estimate (3.3) we have the uniform boundedness in $L^2(Q_{t_f})^d$ of the sequence $(\nabla \pi_{\mathcal{T}_m, \Delta t_m} \xi(s))_m$. Then, there exists a function $\zeta \in L^2(Q_{t_f})^d$

$$\nabla \pi_{\mathcal{T}_m, \Delta t_m} \xi(s) \longrightarrow \zeta, \quad \text{weakly in } L^2(Q_{t_f})^d, \quad \text{as } m \rightarrow +\infty. \quad (4.5)$$

Next, the mass conservation property gives a uniform estimation on the sequence $(\pi_{\mathcal{M}_m, \Delta t_m} \xi(s))_m$ in $L^2(Q_{t_f})$ where we recall that $\xi(s) = \sqrt{s}$. Thanks to Lemma 2.1, we infer that $(\pi_{\mathcal{T}_m, \Delta t_m} \xi(s))_m$ is uniformly bounded the same space. Now, by virtue of Lemma 4.1 and Lemma 4.2 we apply the compactness argument [2, Theorem 3.9] to ensure the existence of a subsequence converging a.e. to a measurable function $s : Q_{t_f} \rightarrow (0, +\infty)$, i.e.

$$\pi_{\mathcal{M}_m, \Delta t_m} s \longrightarrow s \quad \text{a.e. in } Q_{t_f}, \quad \text{as } m \rightarrow +\infty.$$

We recall that

$$\|\mathcal{H}(\pi_{\mathcal{M}_m, \Delta t_m} s)\|_{L^1(Q_{t_f})} \leq C.$$

Then, the sequence $(\pi_{\mathcal{M}_m, \Delta t_m} s)$ is equi-integrable thanks to De La Vallée Poussin criterion [8]. Consequently, Vitali's convergence theorem claims the strong convergence of the above sequence i.e.

$$\pi_{\mathcal{M}_m, \Delta t_m} s \longrightarrow s \quad \text{strongly in } L^1(Q_{t_f}), \quad \text{as } m \rightarrow +\infty.$$

In view of Lemma 2.1, we deduce

$$\pi_{\mathcal{T}_m, \Delta t_m} s = \pi_{\mathcal{T}_m, \Delta t_m} \xi^2(s) \longrightarrow s \quad \text{strongly in } L^1(Q_{t_f}) \text{ and a.e. in } Q_{t_f}, \quad \text{as } m \rightarrow +\infty.$$

To conclude the proof, it suffices to employ the identification of the limit process to check that $\zeta = \nabla \xi(s)$ in the sense of distributions. \square

Now, we are in a position to identify the limit function of the previous result as a weak solution.

Proposition 4.2. *Keeping the statement of Proposition 4.1, the obtained function s is indeed a weak solution to the continuous model (1.1)-(1.3) in the sense of Definition 1.1.*

Proof. Following [14], one show that $\mathcal{H}(s)$ belongs to $L^\infty(0, t_f; L^1(\Omega))$. Let us now take $v_{\mathcal{T}_m}^{k-1} = \psi_{\mathcal{T}_m}^{k-1}$ in the discrete weak formulation (2.11) and sum on $k = 1, \dots, N$. Then, the latter is decomposed as follows

$$X_m + Y_m + Z_m = 0. \quad (4.6)$$

$$\begin{aligned} X_m &= \sum_{k=1}^N \llbracket s_{\mathcal{T}_m}^k - s_{\mathcal{T}_m}^{k-1}, \psi_{\mathcal{T}_m}^k \rrbracket_{\mathcal{T}_m}, \\ Y_m &= \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathcal{S}^T \delta_T \log(s_{\mathcal{T}_m}^k) \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \psi_{\mathcal{T}_m}^k, \\ Z_m &= \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathcal{S}^T \delta_T G_{\mathcal{T}_m} \cdot \mathcal{A}^T \mathcal{S}^T \delta_T \psi_{\mathcal{T}_m}^k. \end{aligned}$$

Notice that $\psi_{\mathcal{T}_m}^N = 0_{\mathbb{R}^{\#\mathcal{T}_m}}$. Performing a discrete integration in time implies

$$\begin{aligned} X_m &= - \llbracket s_{\mathcal{T}_m}^0, \psi_{\mathcal{T}_m}^0 \rrbracket_{\mathcal{T}_m} - \sum_{k=1}^N \Delta t_m \left\llbracket s_{\mathcal{T}_m}^{k-1}, \frac{\psi_{\mathcal{T}_m}^k - \psi_{\mathcal{T}_m}^{k-1}}{\Delta t_m} \right\llbracket_{\mathcal{T}_m}, \\ &= - \int_{Q_{t_f}} \pi_{\mathcal{M}_m, \Delta t_m} s(\cdot, -\Delta t_m) D\pi_{\mathcal{M}_m, \Delta t_m} \psi \, dx \, dt - \int_{\Omega} s^0 \pi_{\mathcal{M}_m, \Delta t_m} \psi(x, 0) \, dx. \end{aligned}$$

where $D\pi_{\mathcal{M}_m, \Delta t_m} \psi$ is discrete time derivative given by

$$D\pi_{\mathcal{M}_m, \Delta t_m} \psi(x, t) = \frac{\psi_i^k - \psi_i^{k-1}}{\Delta t_m}, \quad \forall (x, t) \in K_i \times (t^{k-1}, t^k], \forall T \in \mathcal{T}_m, \forall k \geq 1.$$

It follows from the smoothness of the test function ψ that $(D\pi_{\mathcal{M}_m, \Delta t_m} \psi)_m$ (resp. $(\pi_{\mathcal{M}_m, \Delta t_m} \psi(\cdot, 0))_m$) converges uniformly towards ψ_t (resp. $\psi(\cdot, 0)$). Thanks to (4.3) we get

$$X_m = - \int_{Q_{t_f}} s \, \psi \, dx \, dt - \int_{\Omega} s^0 \psi(x, 0) \, dx, \quad \text{as } m \rightarrow +\infty.$$

Let us now study the convergence of the diffusive part Y_m . To this purpose, we first consider

$$\begin{aligned} Y_m^* &= 2 \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \xi(s_{T, \min}^k) \delta_T \xi(s_{\mathcal{T}_m}^k) \cdot \mathcal{A}^T \delta_T \psi_{\mathcal{T}_m}^k, \\ &= 2 \int_{Q_{t_f}} \pi_{\mathcal{T}_m, \Delta t_m} \widehat{\xi}(s) \nabla \pi_{\mathcal{T}_m, \Delta t_m} \xi(s) \cdot \nabla \pi_{\mathcal{T}_m, \Delta t_m} \psi \, dx \, dt. \end{aligned}$$

where $s_{T, \min}^k = \min_{i \in \mathcal{V}_T} \{s_i^k\}$ and we have defined

$$\pi_{\mathcal{T}_m, \Delta t_m} \widehat{\xi}(s) = \xi(s_{T, \min}^k), \quad \forall (x, t) \in T \times (t^{k-1}, t^k], \forall T \in \mathcal{T}_m, \forall k \geq 1.$$

Using Lemma 2.1 we estimate

$$\begin{aligned} \left\| \pi_{\mathcal{T}_m, \Delta t_m} \widehat{\xi}(s) - \pi_{\mathcal{T}_m, \Delta t_m} \xi(s) \right\|_{L^2(\Omega)} &\leq \left\| \pi_{\mathcal{T}_m, \Delta t_m} \overline{\xi}(s) - \pi_{\mathcal{T}_m, \Delta t_m} \underline{\xi}(s) \right\|_{L^2(\Omega)} \\ &\leq h_{\mathcal{T}_m} C \left(\sum_{k=1}^N \Delta t_m \left\| \nabla \pi_{\mathcal{T}_m}^k \xi(s) \right\|_{L^2(\Omega)^d} \right)^{\frac{1}{2}} \\ &\leq Ch_{\mathcal{T}_m} \rightarrow 0, \quad \text{as } m \rightarrow +\infty. \end{aligned}$$

We deduce in particular that

$$\pi_{\mathcal{T}_m, \Delta t_m} \widehat{\xi}(s) \longrightarrow \xi(s) \quad \text{strongly in } L^2(Q_{t_f}), \quad \text{as } m \rightarrow +\infty. \quad (4.7)$$

Thereby, we can pass to the limit in Y_m^* to obtain

$$Y_m^* \longrightarrow Y = 2 \int_{Q_{t_f}} \sqrt{s} \nabla \sqrt{s} \cdot \nabla \psi \, dx \, dt = \int_{Q_{t_f}} \nabla s \cdot \nabla \psi \, dx \, dt, \quad \text{as } m \rightarrow +\infty.$$

We furthermore define local diagonal matrix $(\mathfrak{S}_{ij}^T)_{1 \leq i, j \leq \#\mathcal{V}_T}$ such that

$$\mathfrak{S}_{ij}^T = \begin{cases} \sqrt{s_{T, \min}^k} & \text{if } j = \tau(i) \\ 0 & \text{if } j \neq \tau(i) \end{cases}.$$

We denote $\mathcal{S}^{T,2}$ the diagonal matrix corresponding to the second choice of (2.6). Note that Y_m^* can be rewritten under the form

$$Y_m^* = \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathcal{S}^{T,2} \delta_T \log(s_{\mathcal{T}_m}^k) \cdot \mathcal{A}^T \mathfrak{G}^T \delta_T \psi_{\mathcal{T}_m}^k = \sum_{k=1}^N \sum_{T \in \mathcal{T}_m} \delta_T \xi(s_{\mathcal{T}_m}^k) \cdot \mathcal{A}^T \mathfrak{G}^T \delta_T \psi_{\mathcal{T}_m}^k.$$

Let us moreover set

$$Y_m^{**} = \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathcal{S}^T \delta_T \log(s_{\mathcal{T}_m}^k) \cdot \mathcal{A}^T \mathfrak{G}^T \delta_T \psi_{\mathcal{T}_m}^k.$$

Observe that $s_{T,min}^k \leq s_{i\tau(i)}^k$, for every $i \in \mathcal{V}_T$ for the both choices given in (2.6). Also, the regularity of ψ gives $|\psi_i^k - \psi_{\tau(i)}^k| \leq \|\nabla \psi\|_\infty h_T$ for all $i \in \mathcal{V}_T$ and $k \geq 0$. We subtract the last two identities. We utilize once more the Cauchy-Schwarz inequality, the result (2.13), Proposition 3.1, and Lemma 2.1 to find that

$$\begin{aligned} |Y_m^* - Y_m^{**}| &= \left| \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathfrak{G}^T \delta_T \log(s_{\mathcal{T}_m}^k) \cdot (\mathcal{S}^{T,2} - \mathcal{S}^T) \mathcal{A}^T \delta_T \psi_{\mathcal{T}_m}^k \right| \\ &\leq C \|\nabla \psi\|_\infty \left(\sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \left(\log(s_i^k) - \log(s_{\tau(i)}^k) \right)^2 \right)^{\frac{1}{2}} \\ &\quad \times \left(\sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} |T| \|\mathcal{S}^{T,2} - \mathcal{S}^T\|_\infty^2 \right)^{\frac{1}{2}} \\ &\leq C_\psi \left\| \pi_{\mathcal{T}_m, \Delta t_m} \overline{\xi(s)} - \pi_{\mathcal{T}_m, \Delta t_m} \underline{\xi(s)} \right\|_{L^2(\Omega)} \\ &\leq C_\psi h_{\mathcal{T}_m}, \quad \text{as } m \rightarrow +\infty. \end{aligned}$$

Similarly, one shows that $|Y_m - Y_m^{**}| \rightarrow 0$, as $m \rightarrow +\infty$. To conclude, it remains to treat the convective potential term Z_m . Mimicking an analogous reasoning we consider

$$\begin{aligned} Z_m^* &= \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathfrak{G}^T \delta_T G_{\mathcal{T}_m} \cdot \mathcal{A}^T \mathfrak{G}^T \delta_T \psi_{\mathcal{T}_m}^k \\ &= \int_{Q_{t_f}} \pi_{\mathcal{T}_m, \Delta t_m} \widehat{\xi(s)}^2 \nabla \pi_{\mathcal{T}_m} G \cdot \nabla \pi_{\mathcal{T}_m, \Delta t_m} \psi \, dx \, dt. \end{aligned}$$

The regularity of the potential G entails the uniform convergence of the sequence $(\nabla \pi_{\mathcal{T}_m} G)_m$ towards ∇G in Ω . Thanks to the strong convergence (4.7) we get

$$Z_m^* \rightarrow Z = \int_{Q_{t_f}} s \nabla G \cdot \nabla \psi \, dx \, dt, \quad \text{as } m \rightarrow +\infty.$$

We continue in the same fashion by setting

$$Z_m^{**} = \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \mathcal{S}^T \delta_T G_{\mathcal{T}_m} \cdot \mathcal{A}^T \mathfrak{G}^T \delta_T \psi_{\mathcal{T}_m}^k.$$

Thanks to the smoothness of G we have $|G(x_i) - G(x_{\tau(i)})| \leq \|\nabla G\|_\infty h_T$ for all $i \in \mathcal{V}_T$ and $k \geq 0$. We

follow the previous arguments together with (3.1) to discover

$$\begin{aligned}
|Z_m^* - Z_m^{**}| &= \left| \sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} (\mathfrak{S}^T - \mathcal{S}^T) \delta_T G_{\mathcal{T}_m} \cdot \mathcal{A}^T \mathfrak{S}^T \delta_T \psi_{\mathcal{T}_m}^k \right| \\
&\leq C \|\nabla \psi\|_\infty \left(\sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} |T| \|\mathfrak{S}^T - \mathcal{S}^T\|_\infty^2 \right)^{\frac{1}{2}} \\
&\quad \times \left(\sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} \frac{|T|}{h_T^2} \sum_{i \in \mathcal{V}_T} s_{T,min}^k (G(x_i) - G(x_{\tau(i)}))^2 \right)^{\frac{1}{2}} \\
&\leq C_\psi \|\nabla G\|_\infty \left\| \pi_{\mathcal{T}_m, \Delta t_m} \overline{\xi(s)} - \pi_{\mathcal{T}_m, \Delta t_m} \underline{\xi(s)} \right\|_{L^2(\Omega)} \left(\sum_{k=1}^N \Delta t_m \sum_{T \in \mathcal{T}_m} |T| \sum_{i \in \mathcal{V}_T} s_{i\tau(i)}^k \right)^{\frac{1}{2}} \\
&\leq C_{\psi, G} h_{\mathcal{T}_m}, \quad \text{as } m \rightarrow +\infty.
\end{aligned}$$

We adapt the above procedure the same steps to establish that $|Z_m - Z_m^{**}| \rightarrow 0$, as $m \rightarrow +\infty$. Hence, the proof is complete. \square

5 Numerical tests

The goal of this section is to validate the efficiency and the robustness of our methodology through several examples including anisotropic and heterogeneous tensors. We solve the algebraic system (2.8)-(2.9) issuing from the numerical scheme by the Newton method. To take into account the singularity of the function log near 0, we cut the initial guess ($s_{\mathcal{T}}^k$) such that $(s_{\mathcal{T}}^k) = \max((s_{\mathcal{T}}^k), 10^{-10})$. The stopping criterion for the iterative loop is fixed to 10^{-10} . Here we consider $\Omega = (0, 1)^2$ the computational domain. It is covered by a family of refined triangular meshes coming from benchmarking problems [28]. We refer to Figure 2 for a depiction of this triangulation. In order to identify in a straightforward way the analytical solution to the

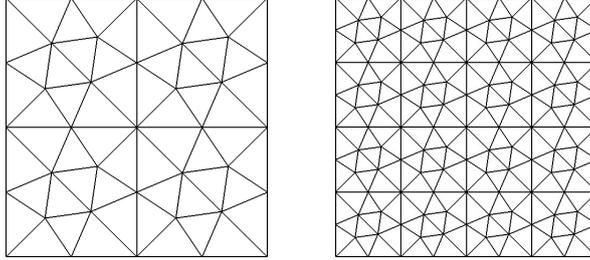


Figure 2: First two meshes of the considered triangulation.

continuous problem, we take a diagonal tensor \mathbb{D}

$$\mathbb{D}(x, y) = \begin{pmatrix} \mathbb{D}_{xx}(x, y) & 0 \\ 0 & \mathbb{D}_{yy}(x, y) \end{pmatrix}.$$

To evaluate the convergence speed of our approach, we calculate the numerical errors between the computed solution and the analytical one using the following norms

$$\|\pi_{\mathcal{M}, \Delta t} s - s_e\|_r = \|\pi_{\mathcal{M}, \Delta t} s - s_e\|_{L^r(Q_{t_f})}, \quad r = 2, \infty.$$

5.1 Accuracy of the scheme

In this subsection we test the efficiency and the robustness of our scheme using a known exact solution to the continuous problem being inspired by [14]. We first consider a constant tensor \mathbb{D} . Then, the solution

reads

$$s_e(x, y, t) = e^{-ct+0.5y} \left(0.5 \sin(\pi y) + \pi \cos(\pi y) \right) + \pi e^{y-0.5},$$

where the final time is fixed to $t_f = 0.2$ and $c = \mathbb{D}_{yy}(\pi^2 + 0.25)$. The initial condition is then $s^0 = s_e(\cdot, 0)$. This state degenerates on the segment $[0, 1] \times \{1\}$. The exterior potential is set to $G(x, y) = -y$. The second eigenvalue of \mathbb{D} is taken as $\mathbb{D}_{yy}(x, y) = 1$. In terms of the anisotropy ratio of the tensor \mathbb{D} , we also compare both formulas of the mobility function given in (2.6). The first expression will be referred to as arithmetic-mean while the second one will be called log-mean. In this example the time step is proportional to the size of the mesh. We report in the following tables the obtained results. Each table displays the number of the mesh vertices, the size of the spacial mesh, the time step, the errors as well as their convergence rates, and the minimum (s_{min}) of the computed solution $\pi_{\mathcal{M}}^k s$ for $k \geq 1$.

In Tables 1-6, we observe that the second-order accuracy of the method is achieved for several anisotropic ratios less than 10 even on coarse meshes. This fact holds for both the log-mean and the arithmetic mean of the mobility-like function. We also record that the solution remains positive as established in Lemma 3.1. When the tensor becomes strongly anisotropic $\mathbb{D}_{xx} \geq 100$, the underlined features are preserved for the log-mean case as provided in Tables 7-8. However, the arithmetic-mean choice turns out to break down the iterative solver. In order to converge, it necessitates a stringent constraint on the time step, that is $\Delta t/h^2$ should be less than $1/\mathbb{D}_{xx}$, which allows extremely small time steps and makes the computational cost exorbitant.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.106 E-00	-	0.550 E-00	-	1.620
129	0.125	0.78 E-02	0.279 E-01	1.917	0.153 E-00	1.849	0.559
481	0.063	0.20 E-02	0.740 E-02	1.938	0.401 E-01	1.954	0.157
1857	0.031	0.48 E-03	0.182 E-02	1.975	0.101 E-01	1.948	0.039
7297	0.016	0.12 E-03	0.183 E-03	2.012	0.273 E-02	1.971	0.011

Table 1: Numerical errors with the log-mean choice of the mobility and $\mathbb{D}_{xx} = 0.1$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.104 E-00	-	0.544 E-00	-	1.628
129	0.125	0.78 E-02	0.273 E-01	1.934	0.149 E-00	1.867	0.566
481	0.063	0.20 E-02	0.719 E-02	1.946	0.389 E-01	1.961	0.160
1857	0.031	0.48 E-03	0.177 E-02	1.979	0.972 E-02	1.953	0.040
7297	0.016	0.12 E-03	0.467 E-03	2.010	0.264 E-02	1.970	0.011

Table 2: Numerical errors with the arithmetic-mean choice of the mobility and $\mathbb{D}_{xx} = 0.1$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t} s - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.104 E-00	-	0.530 E-00	-	1.628
129	0.125	0.78 E-02	0.274 E-01	1.916	0.150 E-00	1.825	0.557
481	0.063	0.20 E-02	0.727 E-02	1.938	0.392 E-01	1.953	0.156
1857	0.031	0.48 E-03	0.179 E-02	1.976	0.969 E-02	1.973	0.039
7297	0.016	0.12 E-03	0.473 E-03	2.010	0.257 E-02	2.014	0.010

Table 3: Numerical errors with the log-mean choice of the mobility and $\mathbb{D}_{xx} = 1$.

5.2 Large time behavior

This example focuses on the asymptotic behavior of our numerical scheme when time becomes large. It is inspired from [12]. We keep the same data of the first test except \mathbb{D} and t_f . According to [3], the exact

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.102 E-00	-	0.524 E-00	-	1.635
129	0.125	0.78 E-02	0.268 E-01	1.936	0.146 E-00	1.843	0.563
481	0.063	0.20 E-02	0.705 E-02	1.947	0.381 E-01	1.962	0.158
1857	0.031	0.48 E-03	0.173 E-02	1.981	0.937 E-02	1.977	0.040
7297	0.016	0.12 E-03	0.458 E-03	2.008	0.247 E-02	2.013	0.011

Table 4: Numerical errors with the arithmetic-mean choice of the mobility and $\mathbb{D}_{xx} = 1$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.930 E-01	-	0.509 E-00	-	1.630
129	0.125	0.78 E-02	0.248 E-01	1.909	0.144 E-00	1.820	0.549
481	0.063	0.20 E-02	0.659 E-02	1.933	0.380 E-01	1.944	0.153
1857	0.031	0.48 E-03	0.169 E-02	1.979	0.944 E-02	1.965	0.038
7297	0.016	0.12 E-03	0.403 E-03	2.002	0.250 E-02	2.006	0.010

Table 5: Numerical errors with the log-mean choice of the mobility and $\mathbb{D}_{xx} = 10$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.920 E-01	-	0.503 E-00	-	1.635
129	0.125	0.78 E-02	0.241 E-01	1.930	0.140 E-00	1.844	0.555
481	0.063	0.20 E-02	0.638 E-02	1.942	0.368 E-01	1.953	0.155
1857	0.031	0.48 E-03	0.156 E-02	1.983	0.910 E-02	1.970	0.039
7297	0.016	0.12 E-03	0.416 E-03	2.004	0.242 E-02	2.003	0.010

Table 6: Numerical errors with the arithmetic-mean choice of the mobility and $\mathbb{D}_{xx} = 10$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.783 E-01	-	0.508 E-00	-	1.582
129	0.125	0.78 E-02	0.225 E-01	1.801	0.141 E-00	1.848	0.516
481	0.063	0.20 E-02	0.597 E-02	1.935	0.372 E-01	1.950	0.142
1857	0.031	0.48 E-03	0.147 E-02	1.972	0.940 E-02	1.942	0.035
7297	0.016	0.12 E-03	0.388 E-03	2.018	0.280 E-02	1.832	0.009

Table 7: Numerical errors with the log-mean choice of the mobility and $\mathbb{D}_{xx} = 100$.

$\#\mathcal{V}$	$h_{\mathcal{T}}$	Δt	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _2$	rate	$\ \pi_{\mathcal{M},\Delta t s} - s_e\ _{\infty}$	rate	s_{min}
37	0.250	0.31 E-01	0.783 E-01	-	0.508 E-00	-	1.554
129	0.125	0.78 E-02	0.225 E-01	1.765	0.141 E-00	1.921	0.501
481	0.063	0.20 E-02	0.597 E-02	1.956	0.372 E-01	1.832	0.137
1857	0.031	0.48 E-03	0.147 E-02	1.967	0.940 E-02	1.559	0.034
7297	0.016	0.12 E-03	0.388 E-03	2.043	0.280 E-02	1.879	0.009

Table 8: Numerical errors with the log-mean choice of the mobility and $\mathbb{D}_{xx} = 1000$.

solution converges to the following stationary-state as the time tends to infinity

$$s^{\infty} = \left(\int_{\Omega} s^0 dx / \int_{\Omega} e^{-G} dx \right) e^{-G}.$$

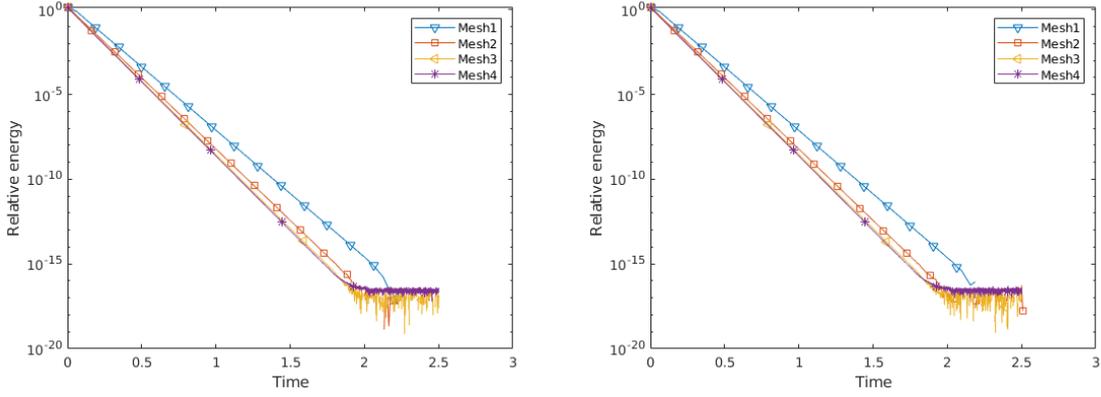


Figure 3: Relative free energy with the log-mean choice of the mobility (left) and the arithmetic-mean (right) for $\mathbb{D}_{xx} = \mathbb{D}_{yy} = 1$, and $t_f = 2.5$ on the first four meshes.

Therefore, the discrete counterpart of the steady-state solution $s_{\mathcal{T}}^{\infty} = (s_i^{\infty})_{i \in \mathcal{V}}$ reads

$$s_i^{\infty} = \left(\int_{\Omega} s^0 dx / \sum_{j \in \mathcal{V}} |K_j| e^{-G(x_j, y_j)} \right) e^{-G(x_i, y_i)}.$$

To illustrate the long time behavior of the proposed approach we look at the evolution of the discrete relative energy given as follows

$$\mathfrak{E}_h^k - \mathfrak{E}_h^{\infty} = \llbracket s_{\mathcal{T}}^k \log(s_{\mathcal{T}}^k / s_{\mathcal{T}}^{\infty}) - s_{\mathcal{T}}^k + s_{\mathcal{T}}^{\infty}, \mathbf{1}_{\mathcal{T}} \rrbracket_{\mathcal{T}}, \quad \forall k = 0, \dots, N.$$

We represent on Figure 3-4 this quantity as a function of time for the log-mean and arithmetic-mean approximations of mobility in the isotropic and the anisotropic cases. The first plot addresses the isotropic case with $\mathbb{D}_{xx} = \mathbb{D}_{yy} = 1$ and $t_f = 2.5$. It shows that the relative free energy is rapidly diminishing towards 0. The second plot concerns the anisotropic case $\mathbb{D}_{xx} = 1$ and $\mathbb{D}_{yy} = 0.05$ with $t_f = 40$. We also observe the exponential decreasing of the free energy towards its stationary state. This requires more time, which is due to the impact of the tensor \mathbb{D} .

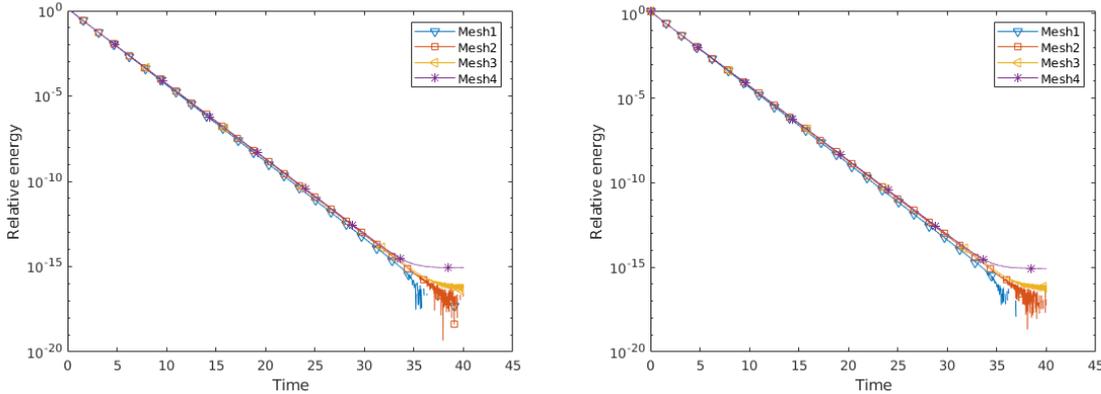


Figure 4: Relative free energy with the log-mean choice of the mobility (left) and the arithmetic-mean (right) for $\mathbb{D}_{xx} = 1$, $\mathbb{D}_{yy} = 0.05$, and $t_f = 40$ on the first four meshes.

5.3 Heterogeneous five-spot problem

The objective of this last test is to exhibit the applicability of our scheme to a situation where the anisotropy is dependent on the position. This example is termed the five-spot problem in the context of porous media flows. Let us set $\Omega = \Omega_1 \cup \Omega_2$ such that $\Omega_1 = \{(x, y) \in \Omega / x \leq 0.5\}$ and $\Omega_2 = \Omega \setminus \Omega_1$. Let us next consider the heterogeneous tensor

$$\mathbb{D}(x, y) = \begin{cases} \begin{pmatrix} 0.5 & 0 \\ 0 & 0.1 \end{pmatrix} & \text{if } (x, y) \in \Omega_1 \\ \begin{pmatrix} 0.01 & 0 \\ 0 & 0.01 \end{pmatrix} & \text{if } (x, y) \in \Omega_2 \end{cases}$$

The domain is initially empty, that is $s^0 = 0$. The potential is chosen as $G(x, y) = x$. We impose a Dirichlet boundary condition $s|_{\partial\Omega^D} = 1$ on the left portion $\partial\Omega^D = \{x = 0\} \times \{0 \leq y \leq 0.5\}$ and an outflow condition on the right zone located at $\{x = 1\} \times \{0.5 \leq y \leq 1\}$. The remainder border is assumed impervious. For the simulation, we use the third mesh of the family depicted in (2). The obtained results are plotted on Figure 5-6. The first figure shows the solution computed accurately using the log-mean approximation of the mobility while the second one exhibits the solution of the scheme using the arithmetic mean. Both approaches produce the expected behavior. It also is observed that the medium Ω_1 is more permeable than Ω_2 , which is due to the contrast of the intrinsic permeabilities. We moreover remark that our scheme generates no undershoots. These facts are finally confirmed by the cross section of the solution at the point $(0, 0.4)$ illustrated in Figure 7.

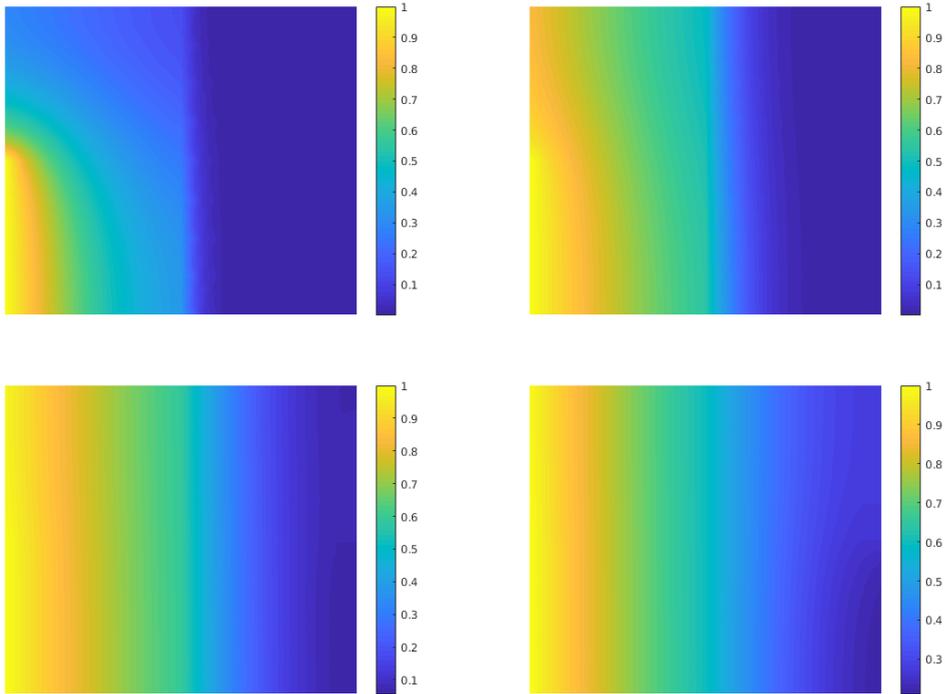


Figure 5: From left-up to right-bottom, the log-mean approximate solution for different simulation times $t \in \{0.25, 1, 4, 10\}$.

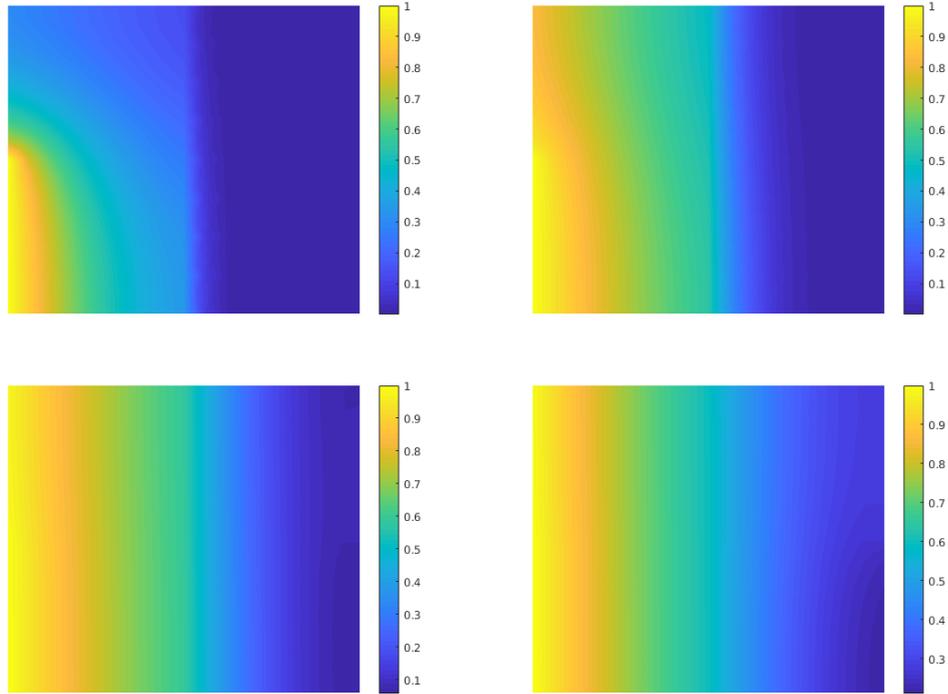


Figure 6: From left-up to right-bottom, the arithmetic-mean approximate solution for different simulation times $t \in \{0.25, 1, 4, 10\}$.

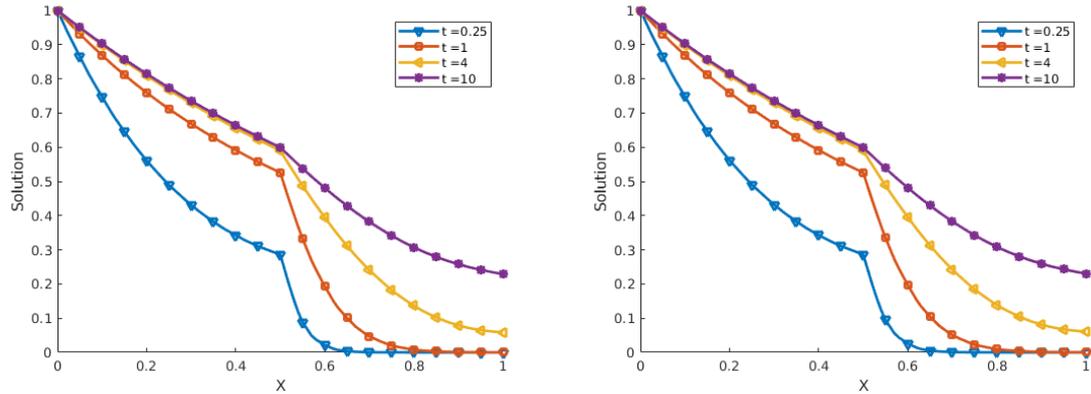


Figure 7: Log-mean (left) and arithmetic-mean (right) cross section of the computed solution at the point $(0, 0.4)$ for $t \in \{0.25, 1, 4, 10\}$.

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