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► **To cite this version:**

Selda Çalkavur, Patrick Solé. Some Multisecret-Sharing Schemes over Finite Fields. Mathematics , 2020, 10.3390/math8050654 . hal-02553818

HAL Id: hal-02553818

<https://hal.science/hal-02553818>

Submitted on 24 Apr 2020

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Some Multisecret-Sharing Schemes over Finite Fields

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Version April 24, 2020 submitted to Mathematics



Abstract: A secret sharing scheme is a method of assigning shares for a secret to some participants such that only some distinguished subsets of these subsets can recover the secret while other subsets cannot. Such schemes can be used for sharing a private key, for digital signatures or sharing the key that can be used to decrypt the content of a file. There are many methods for secret sharing. One of them was developed by Blakley. In this work, we construct a multisecret-sharing scheme over finite fields. The reconstruction algorithm is based on Blakley's method. We determine the access structure and obtain a perfect and ideal scheme.

Keywords: secret sharing; multisecret-sharing scheme; finite field; vector space

1. Introduction

A cryptosystem is an implementation of cryptographic techniques providing information security services. Encryption is the process of scrambling a message and can provide a means of securing information. A secret sharing scheme is an encryption method. The secret s is divided into n pieces called shares. The pieces alone have no information about the secret, but the secret can be reached by combining some pieces.

Secret sharing was first introduced by Shamir [1] and Blakley [2] in 1979. Shamir's scheme is constructed based on the Lagrange interpolation polynomial, as a (t, n) -threshold secret sharing scheme. In a (t, n) -threshold secret sharing scheme, the secret is divided into n shares and distributed each share to one of n parties called shareholders. Only t or more shareholders combining their shares together can recover the secret while $t - 1$ or fewer shareholders cannot obtain any information about the secret. There are several schemes [3–7] based on Shamir's scheme.

Blakley's method is based on finite geometry. In this scheme, the geometry of hyperplanes over a finite field is used to solve the secret sharing problem [8]. To generate a (t, n) -threshold scheme, each of the n participants is given a hyperplane equation in a t -dimensional space over a finite field. In some cases, each hyperplane passes through a certain point. The secret is the intersection point of the hyperlanes. Once participants need to reconstruct the secret by solving the system of equations [9].

Multisecret-sharing schemes are one of the most important families of secret sharing schemes, since the secret has been constructed as multi party not single party. Thus, it is more difficult to reach the secret than for a single secret sharing scheme. Some multisecret-sharing schemes are constructed in [6,7,10–13]. In these schemes [6,13,14], there is a set of which consists of r secrets. The elements of this set can be shared and reconstructed at the same time or none of the r secrets can be retrieved. However, every (r, m, n) -multisecret-sharing scheme gives r single secret (m, n) -threshold schemes [15]. Especially, we presented in [10] a multisecret sharing scheme based on error correcting codes. Moreover, in [16], we constructed a new multisecret-sharing scheme based on LCD codes. The reconstruction algorithm is given by using Blakley's method.

35 In cryptosystems, the secure storage of private keys is an important problem. Secret sharing
 36 satisfies the distribution the private keys to the participants safely and does not trust a creature and
 37 central system. One type of such systems is blockchain systems. The private keys check the important
 38 seeds such as money and identities in this system. Their loss can have serious consequences. Thus,
 39 the distributed storage blockchain (DSB) scheme is introduced in [17,18]. Krawczyk [19] consolidated
 40 the DSB scheme with Shamir's [1] secret sharing scheme and private key encryption and information
 41 dispersal algorithm (IDA) [20]. The DSB scheme decreases the storage to a part of the original
 42 blockchain's impose.

43 Proactive secret sharing (PSS) was proposed by Herzberg et al. [21]. This is a stronger scheme by
 44 means of security. PSS is effective in the sharing of the shares to the participants when the secret s is
 45 kept. The participants get the new pieces of the secret s . These pieces are independent of the old ones
 46 and then the old pieces are removed. PSS protects the secret s from possible attacks.

47 Maram et al. [22] presented CHURP (CHURn-Robust Proactive Secret Sharing). CHURP satisfies
 48 a secure secret sharing in dynamic setting. The collection of nodes keeps the secret changes in this
 49 scheme. It is also constructed for blockchains and has a simpler structure.

50 In the area of cryptocurrency, and blockchain design, secret sharing schemes (SSS) are used
 51 extensively, in particular in electronic voting [23], data storage [18], and wallet management [24]. The
 52 most used of these schemes is the Shamir scheme [1]. In this note, we explore a variant of an alternative
 53 scheme, the Blakley scheme. We show that the Blakley scheme is not adapted to finite fields. We give a
 54 multisecret scheme which exploits similar ideas.

55 The rest of the paper is organised as follows. In Section 2, we introduce Blakley's secret sharing
 56 scheme based on hyperplane geometry over the reals, and show it cannot work over finite fields.
 57 In Section 3, we construct a new multisecret-sharing scheme by using linear algebra over finite fields.
 58 We use Blakley's method and determine the access structure. Section 4 collects the concluding remarks.

59 2. Preliminaries

60 2.1. Blakley Threshold Secret Sharing Scheme

In a (t, n) -Blakley Scheme, the dealer selects a secret point $X = (x_1, x_2, \dots, x_t)$ from \mathbb{R}^t . The secret
 key to be shared is the first coordinate of X . Other coordinates of X are random. For each participant
 $u \in P$, the dealer selects a random vector

$$A_u = (a_{u_1}, a_{u_2}, \dots, a_{u_t}) \quad (1)$$

from \mathbb{R}^t and assigns the scalar

$$y_u = A_u X^T = \sum_{i=1}^t a_{u_i} x_i$$

61 as the secret share to user u .

In other words, the dealer assigns a hyperplane equation that is passing through X to each
 participant u . When a t -member coalition $W = \{u_1, u_2, \dots, u_t\}$ is present, they have t -hyperplanes
 passing through X . The linear system formed by the shares of $u_i \in W$ is

$$\begin{pmatrix} A_{u_1} \\ A_{u_2} \\ \vdots \\ A_{u_t} \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_t \end{pmatrix} = \begin{pmatrix} y_{u_1} \\ y_{u_2} \\ \vdots \\ y_{u_t} \end{pmatrix}$$

$$M_W X^T = Y_W^T \quad (2)$$

62 where Y_W denotes the $1 \times t$ vector formed by the shares of participants included in W . Since all entries
 63 in M_W are generated randomly, M_W is nonsingular with probability one: the set of singular matrices

64 forming a hypersurface in n^2 dimensions is of measure zero for the Lebesgue measure. Since M_W is
 65 nonsingular, the subset W can find the secret by solving the linear system in Equation (2). When a
 66 coalition W' of size $t' < t$ is present, it only sees t' columns of A , yielding an underdetermined system
 67 to solve.

68 Qualified coalitions find the secret and unqualified coalitions gain no information about the secret.

Remark 1. *The Blakley scheme does not work well if we replace \mathbb{R} with a finite field, because the probabilistic argument for the nonsingularity of M_w breaks down. Building a matrix of order n over the finite field $GF(q)$ by choosing its rows at random will not give a nonsingular matrix with probability one, even for large matrix order. The probability $P(n, q)$ of building a nonsingular n by n matrix over $GF(q)$ by random choice is*

$$P(n, q) = |GL(n, q)|q^{-n^2} = \prod_{j=1}^n (1 - 1/q^j),$$

69 by $|GL(n, q)| = \prod_{j=1}^n (q^n - q^{n-j})$ [25]. Since the infinite product $\prod_{j=1}^{\infty} (1 - 1/q^j)$ converges, we see that
 70 $P(n, q)$ tends to a finite value $\neq 1$ for $n \rightarrow \infty$.

71 For instance, for $q = 2$, we have the numerical approximation $P(n, 2) \sim 0.29$, for $n \rightarrow \infty$.

72 2.2. Ramp Secret Sharing Scheme

73 **Ramp secret sharing scheme** is a cryptographic method to encode a secret s into multiple shares
 74 s_1, \dots, s_n that only from specified subsets of the shares one can recover s . In ramp schemes, a secret
 75 can be shared among a group of participants in such a way that only sets of at least k participants can
 76 reconstruct the secret and $k - 1$ participants cannot [26].

77 A linear ramp secret sharing scheme is called t -**privacy** if from no set of size t one can guess any
 78 information about the secret, but from some set of size $t + 1$ can recover some information about it.

79 3. Multisecret-Sharing Schemes over Finite Fields

80 3.1. Notation

In this section, we consider a finite extension $\mathbb{F} = \mathbb{F}_q^m$ of the finite field $K = \mathbb{F}_q$ as a vector space over K . Then, \mathbb{F} has dimension m over K and if $\{\alpha_1, \dots, \alpha_m\}$ is a basis of \mathbb{F} over K , each element $\alpha \in \mathbb{F}$ can be uniquely represented in the form

$$\alpha = c_1\alpha_1 + \dots + c_m\alpha_m$$

81 with $c_j \in K$ for $1 \leq j \leq m$.

82 3.2. Scheme Description

83 In this subsection, we examine a multisecret-sharing scheme over finite fields. To explain the
 84 reconstruction method, we use Blakley's algorithm.

- 85 • Let the vector space \mathbb{F}_q^m be both the secret space and the participants set.
- 86 • Let any vector of \mathbb{F}_q^m be the secret.

The m secrets are the m coordinates of a vector $X \in \mathbb{F}_q^m$. Let P denote an m -subset of participants. For each participant $u \in P$, the dealer selects a random vector

$$A_u = (a_{u_1}, a_{u_2}, \dots, a_{u_t}) \quad (3)$$

from \mathbb{F}_q^m and assigns the scalar

$$y_u = A_u X^T = \sum_{i=1}^t a_{u_i} x_i$$

as the secret share to user u . The linear system formed by the shares of $u_i \in W$ is

$$\begin{pmatrix} A_{u_1} \\ A_{u_2} \\ \vdots \\ A_{u_t} \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_t \end{pmatrix} = \begin{pmatrix} y_{u_1} \\ y_{u_2} \\ \vdots \\ y_{u_t} \end{pmatrix}$$

$$M_W X^T = Y_W^T \quad (4)$$

87 Thus, we obtain a linear equation system in X and the secret can be retrieved by solving this system,
88 provided M_W is non singular, or, equivalently, the family $(A_u)_{u \in W}$ is free.

89 **Theorem 1.** *This multisecret-sharing scheme has the following properties:*

- 90 (1) *The access structure consists of sets of m elements.*
91 (2) *No subset of size less than m can be used in recovering the secret.*

92 **Proof.** The following facts are immediate by basic linear algebra. (1) Any basis of \mathbb{F}_q^m can recover the
93 secret by combining their shares, as the matrix of the system is nonsingular in that case.

94 (2) The above system is undetermined in that case, because the matrix of the system is
95 not square. \square

96 **Corollary 1.** *This multisecret-sharing scheme is a (m, m) -threshold secret sharing scheme.*

97 **Proof.** The secret is recovered thanks to the basis elements of \mathbb{F}_q^m in this scheme. Thus, each minimal
98 access set consists of m elements. The size of secret is m , since it is any vector of \mathbb{F}_q^m . That is,
99 in this scheme, all m secrets of X can be determined together. Therefore, the new scheme is a
100 (m, m) -threshold scheme. \square

101 **Corollary 2.** *The multisecret-sharing scheme satisfying the above theorem is also a ramp secret sharing scheme
102 with $m - 1$ privacy.*

103 **Proof.** The number of participants retrieving the secret is m . This means the size of minimal access
104 subsets is m . Thus, this scheme is also a ramp secret sharing scheme with $m - 1$ privacy by definition
105 of a ramp secret sharing scheme. \square

106 3.3. Statistics on Coalitions

Theorem 2. *Let \mathbb{F}_q^m be the finite extension over the finite field \mathbb{F}_q . In a multisecret-sharing scheme over \mathbb{F}_q , the
number of minimal coalitions is*

$$\frac{|GL(m, q)|}{m!} = \prod_{j=1}^m (q^m - q^{m-j}).$$

107 **Proof.** Recall that, in our scheme, the secret space is the finite extension \mathbb{F}_q^m and the minimal access
108 sets consist of the bases. These m participants can recover the secret together. Thus, the number of
109 minimal coalitions is the number of rows of a nonsingular matrix of order m over \mathbb{F}_q up to ordering.
110 This number is calculated by the above formula. \square

111 3.4. Security Analysis

112 Assume that $t < m$ participants collude together and agree to pool their share to try and guess
113 the secret. For the attack to be better than random choice, we must assume that their corresponding
114 vectors A_u are linearly independent. Assuming they correspond to a system of t linearly independent
115 vectors, they can be completed into a basis in $X(t, m, q)$ ways. In general, this quantity is a complicated

116 combinatorial coefficient. Let us assume the most favorable case to the attackers, that is $t = m - 1$.
 117 In that situation, the basis extension vector is any vector that is not in the linear span of the $m - 1$
 118 vectors attached to the colluders. Thus, $X(t, m, q) = q^m - q^{m-1}$. This vector being chosen, there are q
 119 choices for its share.

120 Thus, the probability of success of the attack is $\frac{1}{(q-1)(q^m - q^{m-1})}$. To make this quantity small, we
 121 should operate the system with a large m . Having a large q would increase the computational burden
 122 of the field arithmetic.

123 3.5. Information Theoretic Efficiency

The ratio of the size of the secret to the size of the participants gives the information rate [27] of the secret sharing scheme. In this scheme, the secret is a vector of dimension m and its size is m . The sharings are the sets of basis elements and their size is m . Thus, the information rate is

$$\rho = \frac{m}{m} = 1.$$

124 This scheme is **ideal**, since $\rho = 1$.

125 3.6. Comparison with other Schemes

126 In this section, we compare our scheme with other secret sharing schemes in the literature by
 127 means of, in order, the number of participants, the size of a secret, and the number of coalitions for
 128 an arithmetic over \mathbb{F}_q . We denote by A, B , and C these three quantities in the following table. In the
 129 fourth column, the symbol t denotes the error-correcting capacity of code. As a basis of comparison, in
 130 Columns 2–4, we consider an $[n, k, d \geq 2t + 1]$ -code over $GF(q)$. For codes of similar alphabets and
 131 dimensions, the new scheme allows exponentially more participants and more coalitions, compared to
 132 the other schemes, for a secret size of the same order of magnitude.

133 Massey's scheme has a single secret sharing system, not a multisecret-sharing. To recover the
 134 secret, the linear algebra in Ding's scheme is used. The reconstruction algorithm is based on the
 135 decoding in Çalkavur et al. scheme [10]. In our new system, to recover the secret, we use Blakley's
 136 method. However, the secret will be retrieved safely since the system has m independent equations
 137 and m unknowns. This means there exists a unique solution in the system.

<i>System</i>	[28]	[15]	[10]	<i>This paper</i>
<i>A</i>	$n - 1$	n	n	q^m
<i>B</i>	q	q^k	q^k	q
<i>C</i>	$\binom{n}{k}$	$\binom{n}{k}$	$\geq \binom{n}{d-t}$	$\frac{\prod_{i=0}^{m-1} (q^m - q^i)}{m!}$
ρ	1	$\frac{k}{k-1}$	1	1

138 4. Conclusions

139 In [29], Çalkavur et al. introduced a new multisecret-sharing scheme based on vector spaces over
 140 the \mathbb{F} vector space \mathbb{F}^m for some field \mathbb{F} . In this work, we generalise the results in [29] and construct a
 141 multisecret-sharing scheme over finite fields. We use Blakley's algorithm to explain the recovering
 142 method of a secret. We determine the access structure, examine the statistics on coalitions and show the
 143 ideality and perfectness of our scheme. Attack analysis indicates that the important security parameter
 144 is the dimension m of the vector space we consider.

145 Compared to other schemes based on finite fields, our scheme displays for the same order of
 146 magnitude of parameters more users and more coalitions. It is also a multisecret scheme.

147 **Author Contributions:** Investigation, P.S.; and supervision, S.Ç. All authors have read and agreed to the published
148 version of the manuscript.

149 **Funding:** This research received no external funding.

150 **Conflicts of Interest:** The authors declare no conflict of interest.

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