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# VON NEUMANN'S INEQUALITY FOR TENSORS 

STÉPHANE CHRÉTIENAND TIANWEN WEI


#### Abstract

For two matrices in $\mathbb{R}^{n_{1} \times n_{2}}$, the von Neumann inequality says that their scalar product is less than or equal to the scalar product of their singular spectrum. In this short note, we extend this result to real tensors and provide a complete study of the equality case.


## 1. Introduction

The goal of this paper is to generalize von Neumann's inequality from matrices to tensors. Consider two matrices $X$ and $Y$ in $\mathbb{R}^{n_{1} \times n_{2}}$. Denote their singular spectrum, i.e. the vector of their singular values, by $\sigma(X)$ (resp. $\sigma(Y)$ ). The classical matrix von Neumann's inequality [6] says that

$$
\langle X, Y\rangle \leq\langle\sigma(X), \sigma(Y)\rangle,
$$

and equality is achieved if and only if $X$ and $Y$ have the same singular subspaces. Von Neumann's inequality, and the characterization of the equality case in this inequality, are important in many aspects of mathematics.

For tensors, the task of generalizing Von Neumann's inequality is rendered harder because of the necessity to appropriately define the singular values and the Singular Value Decomposition(SVD). In this paper, we will use the SVD defined in [1], which is based on the Tucker decomposition.

Our main result is given in Theorem 3.1 below and gives a characterization of the equality case. We expect this result to be useful for the description of the subdifferential of some tensor fonctions as the matrix counterpart has proved for matrix functions [4]. Such functions occur naturally in computational statistics, machine learning and numerical analysis [2, 3] due to the recent interest of sparsity promoting norms as a convex surrogate to rank penalization.

## 2. Main facts about tensors

Let $D$ and $n_{1}, \ldots, n_{D}$ be positive integers. Let $\mathcal{X} \in \mathbb{R}^{n_{1} \times \cdots \times n_{D}}$ denote a $D$-dimensional array of real numbers. We will also denote such arrays as tensors.
2.1. Basic notations and operations. A subtensor of $\mathcal{X}$ is a tensor obtained by fixing some of its coordinates. As an example, fixing one coordinate $i_{d}=k$ in $\mathcal{X}$ for some $k \in\left\{1, \ldots, n_{d}\right\}$ yields a tensor in $\mathbb{R}^{n_{1} \times \cdots \times n_{d-1} \times n_{d+1} \times \cdots \times n_{D}}$. In the sequel, we will denote this subtensor of $\mathcal{X}$ by $\mathcal{X}_{i_{d}=k}$.

The fibers of a tensor are subtensors that have only one mode, i.e. obtained by fixing every coordinate except one. The mode- $d$ fibers are the vectors

$$
\left(\mathcal{X}_{i_{1}, \ldots, i_{d-1}, i_{d}, i_{d+1}, \ldots, i_{D}}\right)_{i_{d}=1, \ldots, n_{d}}
$$

They extend the notion of columns and rows from the matrix to the tensor framework. For a matrix, the mode- 1 fibers are the columns and the mode- 2 fibers are the rows.

The mode- $d$ matricization $\mathcal{X}_{(d)}$ of $\mathcal{X}$ is obtained by forming the matrix whose columns are the mode- $d$ fibers of the tensor, arranged in the lexicographic ordering [7]. Clearly, the $k$ th column of $\mathcal{X}_{(d)}$ consists of the entries of $\mathcal{X}_{i_{d}=k}$.

The mode- $d$ multiplication of a tensor $\mathcal{X} \in \mathbb{R}^{n_{1} \times \cdots \times n_{D}}$ by a matrix $U \in$ $\mathbb{R}^{n_{d}^{\prime} \times n_{d}}$, denoted by $\mathcal{X} \times{ }_{d} U$, gives a tensor in $\mathbb{R}^{n_{1} \times \cdots \times n_{d}^{\prime} \times \cdots \times n_{D}}$. It is defined as

$$
\left(\mathcal{X} \times_{d} U\right)_{i_{1}, \ldots, i_{d-1}, i_{d}^{\prime}, i_{d+1}, \ldots, i_{D}}=\sum_{i_{d}=1}^{n_{d}} \mathcal{X}_{i_{1}, \ldots, i_{d-1}, i_{d}, i_{d+1}, \ldots, i_{D}} U_{i_{d}^{\prime}, i_{d}}
$$

2.2. Higher Order Singular Value Decomposition (HOSVD). The Tucker decomposition of a tensor is a very useful decomposition, which can be chosen so that with appropriate orthogonal transformations, one can reveal a tensor $\mathcal{S}$ hidden inside $\mathcal{X}$ with interesting rank and orthogonality properties. More precisely, we have

$$
\begin{equation*}
\mathcal{X}=\mathcal{S}(\mathcal{X}) \times_{1} U^{(1)} \times_{2} U^{(2)} \cdots \times_{D} U^{(D)} \tag{2.1}
\end{equation*}
$$

where each $U^{(d)} \in \mathbb{R}^{n_{d} \times n_{d}}$ is orthogonal and $\mathcal{S}(\mathcal{X})$ is a tensor of the same size as $\mathcal{X}$ defined as follows. Moreover, subtensors $\mathcal{S}(\mathcal{X})_{i_{d}=k}$ for $k=1, \ldots, n_{d}$ are all orthogonal to each other for each $d=1, \ldots, D$.
2.2.1. Relationship with matricization. A tensor can be matricized along each of its modes. Let $\otimes$ denote the standard Kronecker product for matrices. Then, the mode- $d$ matricization of a tensor $\mathcal{X} \in \mathbb{R}^{n_{1} \times \cdots \times n_{D}}$ is given by

$$
(2 \mathscr{X}\}_{d)}=U^{(d)} \cdot \mathcal{S}(\mathcal{X})_{(d)} \cdot\left(U^{(d+1)} \otimes \cdots \otimes U^{(D)} \otimes U^{(1)} \otimes \cdots \otimes U^{(d-1)}\right)^{t}
$$

Take the (usual) SVD of the matrix $\mathcal{X}_{(d)}$

$$
\mathcal{X}_{(d)}=U^{(d)} \Sigma^{(d)} V^{(d)^{t}}
$$

and based on (2.2), we can set

$$
\mathcal{S}(\mathcal{X})_{(d)}=\Sigma^{(d)} V^{(d)^{t}}\left(U^{(d+1)} \otimes \cdots \otimes U^{(D)} \otimes U^{(1)} \otimes \cdots \otimes U^{(d-1)}\right)
$$

where $\mathcal{S}(\mathcal{X})_{(d)}$ is the mode- $d$ matricization of $\mathcal{S}(\mathcal{X})$. One proceeds similarly for all $d=1, \ldots, D$ and one recovers the orthogonal matrices $U^{(1)}, \ldots, U^{(D)}$ which allow us to decompose $\mathcal{X}$ as in (2.1).
2.2.2. The spectrum. The mode- $d$ spectrum is defined as the vector of singular values of $\mathcal{X}_{(d)}$ and we will denote it by $\sigma^{(d)}(\mathcal{X})$. Notice that this construction implies that $\mathcal{S}(\mathcal{X})$ has orthonormal fibers for every modes. With a slight abuse of notation, we will denote by $\sigma$ the mapping which to each tensor $\mathcal{X}$ assigns the vector $1 / \sqrt{D}\left(\sigma^{(1)}, \ldots, \sigma^{(D)}\right)$ of all mode- $d$ singular spectra.


Figure 1. A block-wise diagonal tensor.

## 3. Main Result

3.1. The main theorem. The main result of this paper is the following theorem.

Theorem 3.1. Let $\mathcal{X}, \mathcal{Y} \in \mathbb{R}^{n_{1} \times \cdots \times n_{D}}$ be tensors. Then for all $d=1, \ldots, D$, we have

$$
\begin{equation*}
\langle\mathcal{X}, \mathcal{Y}\rangle \leqslant\left\langle\sigma^{(d)}(\mathcal{X}), \sigma^{(d)}(\mathcal{Y})\right\rangle . \tag{3.3}
\end{equation*}
$$

The equality in (3.3) holds simultaneously for all $d=1, \ldots, D$ if and only there exist orthogonal matrices $W^{(d)} \in \mathbb{R}^{n_{d} \times n_{d}}$ for $d=1, \ldots, D$ and tensors $\mathcal{D}(\mathcal{X}), \mathcal{D}(\mathcal{Y}) \in \mathbb{R}^{n_{1} \times \cdots \times n_{D}}$ such that

$$
\begin{aligned}
\mathcal{X} & =\mathcal{D}(\mathcal{X}) \times_{1} W^{(1)} \cdots \times_{D} W^{(D)} \\
\mathcal{Y} & =\mathcal{D}(\mathcal{Y}) \times_{1} W^{(1)} \cdots \times_{D} W^{(D)}
\end{aligned}
$$

where $\mathcal{D}(\mathcal{X})$ and $\mathcal{D}(\mathcal{Y})$ satisfy the following properties:

- $\mathcal{D}(\mathcal{X})$ and $\mathcal{D}(\mathcal{Y})$ are block-wise diagonal with the same number and size of blocks.
- Let $L$ be the number of blocks and $\left\{\mathcal{D}_{l}(\mathcal{X})\right\}_{l=1, \ldots, L}$ (resp. $\left.\left\{\mathcal{D}_{l}(\mathcal{Y})\right\}_{i=l, \ldots, L}\right)$ be the blocks on the diagonal of $\mathcal{D}(\mathcal{X})$ (resp. $\mathcal{D}(\mathcal{Y})$ ). Then for each $l=1, \ldots, L$, the two blocks $\mathcal{D}_{l}(\mathcal{X})$ and $\mathcal{D}_{l}(\mathcal{Y})$ are proportional.
3.2. Proof of the main theorem. In this section, we prove Theorem 3.1. If $\mathcal{X}$ or $\mathcal{Y}$ is a zero tensor, then the result is trivial. In the sequel, we assume that both $\mathcal{X}$ and $\mathcal{Y}$ are non-zero tensors.
3.2.1. The "if" part. The "if" part of the result is straightforward. Notice that $\langle\mathcal{X}, \mathcal{Y}\rangle=\langle\mathcal{D}(\mathcal{X}), \mathcal{D}(\mathcal{Y})\rangle$ and the singular vectors of $\mathcal{X}$ (resp. Y) are equal to those of $\mathcal{D}(\mathcal{X})$ (resp. $\mathcal{D}(\mathcal{Y})$ ). Therefore, it remains to prove that

$$
\begin{equation*}
\langle\mathcal{D}(\mathcal{X}), \mathcal{D}(\mathcal{Y})\rangle=\left\langle\sigma^{(d)}(\mathcal{D}(\mathcal{X})), \sigma^{(d)}(\mathcal{D}(\mathcal{Y}))\right\rangle, \quad d=1, \ldots, D . \tag{3.4}
\end{equation*}
$$

The conditions that $\mathcal{D}(\mathcal{X})$ and $\mathcal{D}(\mathcal{Y})$ are block-wise diagonal and that $\mathcal{D}_{i}(\mathcal{X})$ and $\mathcal{D}_{i}(\mathcal{Y})$ are proportional implies that each row of $\mathcal{D}_{(d)}(\mathcal{X})$ and that of $\mathcal{D}_{(d)}(\mathcal{Y})$ are parallel. It then follows that $\mathcal{D}_{(d)}(\mathcal{X})$ and $\mathcal{D}_{(d)}(\mathcal{Y})$ have the same left and right singular vectors. Then, applying the matrix von Neumann's result immediately gives (3.4).
3.2.2. The "only if" part: first step. Assume that

$$
\langle\mathcal{X}, \mathcal{Y}\rangle=\left\langle\sigma^{(d)}(\mathcal{X}), \sigma^{(d)}(\mathcal{Y})\right\rangle, \quad d=1, \ldots, D
$$

By the classical results of matrix von Neumann's inequality, we know that the equality holds if and only if there exist orthogonal matrices $U^{(d)}$ and $V^{(d)}$ such that

$$
\begin{align*}
& \mathcal{X}_{(d)}=U^{(d)} \operatorname{Diag}\left(\sigma^{(d)}(\mathcal{X})\right) V^{(d)^{t}} \text { and }  \tag{3.5}\\
& \mathcal{Y}_{(d)}=U^{(d)} \operatorname{Diag}\left(\sigma^{(d)}(\mathcal{Y})\right) V^{(d)^{t}}
\end{align*}
$$

for all $d=1, \ldots, D$. From this remark, we obtain the following HOSVD of $\mathcal{X}$ and $\mathcal{Y}$ :

$$
\begin{aligned}
\mathcal{X} & =\mathcal{S}(\mathcal{X}) \times_{1} U^{(1)} \cdots \times_{D} U^{(D)}, \\
\mathcal{Y} & =\mathcal{S}(\mathcal{Y}) \times_{1} U^{(1)} \cdots \times_{D} U^{(D)} .
\end{aligned}
$$

3.2.3. The "only if" part: second step. We now show that subtensors $\mathcal{S}(\mathcal{X})_{i_{d}=k}$ and $\mathcal{S}(\mathcal{Y})_{i_{d}=k}$ must be parallel for all $k=1, \ldots, n_{d}$ and $d=1, \ldots, D$.

Comparing (3.5) with (2.2), we deduce that

$$
\mathcal{S}_{(d)}(\mathcal{X})=\left(\begin{array}{c}
\sigma_{1}^{(d)}(\mathcal{X}) \cdot p_{1}^{t}  \tag{3.6}\\
\vdots \\
\sigma_{n_{d}}^{(d)}(\mathcal{X}) \cdot p_{n_{d}}^{t}
\end{array}\right)
$$

where $p_{i}^{t}$ denotes the $i$ th row of matrix $V^{(d)^{t}}\left(U^{(d+1)} \otimes \cdots \otimes U^{(D)} \otimes U^{(1)} \otimes \cdots \otimes U^{(d-1)}\right)$. Similarly, we have

$$
\mathcal{S}_{(d)}(\mathcal{Y})=\left(\begin{array}{c}
\sigma_{1}^{(d)}(\mathcal{Y}) \cdot p_{1}^{t}  \tag{3.7}\\
\vdots \\
\sigma_{n_{d}}^{(d)}(\mathcal{Y}) \cdot p_{n_{d}}^{t}
\end{array}\right) .
$$

Comparing now (3.6) and (3.7) reveals that the $i$ th row of $\mathcal{S}_{(d)}(\mathcal{X})$ and the $i$ th row of $\mathcal{S}_{(d)}(\mathcal{Y})$ must be proportional, for all $i=1, \ldots, n_{d}$. Formally, this means

$$
\begin{equation*}
\sigma_{i_{d}}^{(d)}(\mathcal{Y}) \cdot \mathcal{S}(\mathcal{X})_{i_{1} \cdots i_{d} \cdots i_{D}}=\sigma_{i_{d}}^{(d)}(\mathcal{X}) \cdot \mathcal{S}(\mathcal{Y})_{i_{1} \cdots i_{d} \cdots i_{D}} \tag{3.8}
\end{equation*}
$$

for all possible values of $i_{1}, \ldots, i_{D}$.
3.2.4. The "only if" part: third step. For $d=1, \ldots, D$, let $r_{x}^{(d)}$ (resp. $r_{y}^{(d)}$ ) be the rank of $\mathcal{S}_{(d)}(\mathcal{X})\left(\right.$ resp. $\left.\mathcal{S}_{(d)}(\mathcal{Y})\right)$. Let $\left(i_{1}, \ldots, i_{D}\right)$ be such that

$$
\begin{aligned}
&\left(i_{1}, \ldots, i_{D}\right) \not \leq \\
&\left(i_{1}, \ldots, i_{D}\right) \nsucceq\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right) \\
&\left.(1), \ldots, r_{y}^{(D)}\right) .
\end{aligned}
$$

Then, $\mathcal{S}(\mathcal{Y})_{i_{1}, \ldots, i_{D}}=0$ but there exists $d \in\{1, \ldots, D\}$ such that $\sigma_{i_{d}}^{(d)}(\mathcal{Y})>0$. Using (3.8), we obtain that $\mathcal{S}(\mathcal{X})_{i_{1}, \ldots, i_{D}}=0$. Thus, if $r_{x}^{(d)}>r_{y}^{(d)}$ for some $d=1, \ldots, D$, then there exists some

$$
\left(i_{1}, \ldots, i_{D}\right)>\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right)
$$

such that $\mathcal{S}(\mathcal{X})_{i_{1}, \ldots, i_{D}} \neq 0$ and thus, $r_{x}^{(d)}>r_{y}^{(d)}$ for all $d=1, \ldots, D$. By symmetry, we deduce that either $r_{x}^{(d)}>r_{y}^{(d)}$ for all $d=1, \ldots, D$, or $r_{x}^{(d)}<r_{y}^{(d)}$ for all $d=1, \ldots, D$ or else $r_{x}^{(d)}=r_{y}^{(d)}$ for all $d=1, \ldots, D$.
3.2.5. The "only if" part: fourth step. Assume that $\left(r_{x}^{(1)}, \ldots, r_{x}^{(D)}\right) \leq\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right)$. The other case may be treated in the same way (with an overlap in the equality case) by interchanging the role of $\mathcal{X}$ and $\mathcal{Y}$. For all $\left(i_{1}, \ldots, i_{D}\right) \leq$ $\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right)$, we have $\sigma_{i_{d}}^{(d)}(\mathcal{Y})>0$ for all $d=1, \ldots, D$. Thus, (3.8) gives

$$
\mathcal{S}(\mathcal{X})_{i_{1} \cdots i_{d} \cdots i_{D}}=\frac{\sigma_{i_{d}}^{(d)}(\mathcal{X})}{\sigma_{i_{d}}^{(d)}(\mathcal{Y})} \cdot \mathcal{S}(\mathcal{Y})_{i_{1} \cdots i_{d} \cdots i_{D}} .
$$

We deduce from this equation that for two indices $\left(i_{1}, \ldots, i_{D}\right)$ and $\left(i_{1}^{\prime}, \ldots, i_{D}^{\prime}\right)$, if
(i) there exists some $d$ in $\{1, \ldots, D\}$ such that $i_{d}=i_{d}^{\prime}$,
(ii) $\mathcal{S}(\mathcal{X})_{i_{1}, \cdots, i_{d}, \cdots, i_{D}}$ and $\mathcal{S}(\mathcal{X})_{i_{1}^{\prime}, \cdots, i_{d}^{\prime}, \cdots, i_{D}}$ are different from zero, then

$$
\left(\mathcal{S}(\mathcal{X})_{i_{1} \cdots i_{d} \cdots i_{D}}, \mathcal{S}(\mathcal{X})_{i_{1}^{\prime}, \cdots, i_{d}^{\prime}, \cdots, i_{D}}\right)=\rho \cdot\left(\mathcal{S}(\mathcal{Y})_{i_{1} \cdots i_{d} \cdots i_{D}}, \mathcal{S}(\mathcal{Y})_{i_{1}^{\prime}, \cdots, i_{d}^{\prime}, \cdots, i_{D}}\right),
$$

where

$$
\rho=\frac{\sigma_{i_{1}}^{(1)}(\mathcal{X})}{\sigma_{i_{1}}^{(1)}(\mathcal{Y})}=\cdots=\frac{\sigma_{i_{D}}^{(D)}(\mathcal{X})}{\sigma_{i_{D}}^{(D)}(\mathcal{Y})}>0 .
$$

3.2.6. The "only if" part: fifth step. Let $\rho_{1}>\cdots>\rho_{L}$ denote the possible values of the ratio $\sigma_{i_{d}}^{(d)}(\mathcal{X}) / \sigma_{i_{d}}^{(d)}(\mathcal{Y})$, for all $\left(i_{1}, \ldots, i_{D}\right) \leq\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right)$. Let $I_{d, l}, d=1, \ldots, D, l=1, \ldots, L$ denote the possibly empty set of indices in $\left\{1, \ldots, r_{x}^{(d)}\right\}$ such that

$$
\frac{\sigma_{i_{d}}^{(d)}(\mathcal{X})}{\sigma_{i_{d}}^{(d)}(\mathcal{Y})}=\rho_{l}
$$

and let $m_{d, l}$ denote the cardinality of $I_{d, l}$. Then, for each $d=1, \ldots, D$, we can find a permutation $\pi_{d}$ on $\left\{1, \ldots, n_{d}\right\}$ such that $\pi_{d}\left(I_{d, 1}\right)=\left\{1, \ldots, m_{d, 1}\right\}$, $\pi_{d}\left(I_{d, 2}\right)=\left\{m_{d, 1}+1, \ldots, m_{d, 1}+m_{d, 2}\right\}$, and so on and so forth.

Thus, for each mode $d=1, \ldots, D$, there exists a permutation matrix $\Pi_{d}$ such that the matrices

$$
\mathcal{D}(\mathcal{X})=\mathcal{S}(\mathcal{X}) \times_{1} \Pi_{1} \cdots \times_{D} \Pi_{D},
$$

and

$$
\mathcal{D}(\mathcal{Y})=\mathcal{S}(\mathcal{Y}) \times_{1} \Pi_{1} \cdots \times_{D} \Pi_{D}
$$

contain $L$ blocks and each block in $\mathcal{D}(\mathcal{X})$ is proportionnal to the corresponding block in $\mathcal{D}(\mathcal{Y})$. Moreover, any entry $\mathcal{D}(\mathcal{X})_{i_{1}, \ldots, i_{D}}$ with $\left(i_{1}, \ldots, i_{D}\right) \leq$ $\left(r_{x}^{(1)}, \ldots, r_{x}^{(D)}\right)$ and lying outside the union of these $L$ blocks is null since if it were not, by (3.8) combined with $\left(r_{x}^{(1)}, \ldots, r_{x}^{(D)}\right) \leq\left(r_{y}^{(1)}, \ldots, r_{y}^{(D)}\right)$, it would be proportionnal to a nonzero component $\mathcal{D}(\mathcal{Y})_{i_{1}, \ldots, i_{D}}$ with two different ratios, thus a contradiction.

Finally, setting $W^{(d)}=\Pi_{d} U^{(d)}$ for $d=1, \ldots, D$ achieves the proof.

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