



Study of the impact of a wind farm over the radio navigation systems of an airport by using the Method of Moments (MoM) and Physical Optics (PO)

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 - Physical Optics (PO)
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Motivation







Motivation







Introduction

Radio Navigation System	Working Frequency	Measurement	
VOR	108-117.975 MHz	Bearing	
DME	960-1215 MHz	Distance	
NDB	190-1750 kHz	Bearing	
ILS	108-111.975 MHz	Localiser	
	328.6-335.4 MHz	Glide path	
	75 MHz	Marker Beacon	
MLS	5030.4-5150.0 MHz	Microwave Landing system	
TACAN	960-1215 MHz	Bearing + distance	





Introduction

$$\vec{E}_{received} \neq \vec{E}_{free-space}$$

Sources of error in the measured parameters :

- Shadowing effects (Lost LOS).
- Multipath (ground + obstacles).
- Weather (atmospheric effects).
- Mountainous terrain.
- Electronic noise.
- Interference of other antennas.
- Doppler from moving obstacles.



Example - Bearing Angle TACAN







Comparison frequency domain methods

	МоМ	MoM-MLACA	PO/PTD
Precision	$\star\star\star\star$	$\star\star\star\star$	$\star \star$
Memory Usage	*	$\star \star$	$\star \star \star$
CPU time	\star	$\star \star$	$\bigstar\bigstar\bigstar$
	Z J = E	$(t_{i+1})^{(t_{i+1})} = (t_{i+1})^{(t_{i+1})} = (t_{$	$\begin{array}{l} PEC\\ \mathbf{J}(\mathbf{r}) = 2\mathbf{\hat{n}} \times \mathbf{H}(\mathbf{r})\\ \mathbf{M}(\mathbf{r}) = 0 \end{array}$



MoM - MLACA

- Computational complexity : $O(N^3) \rightarrow O(N^2 \log N)$
- Necessary memory : $O(N^2) \rightarrow O(N\log^2 N)$
- Object split hierarchically into near and far interactions









MoM - MLACA

- Computational complexity : $O(N^3) \rightarrow O(N^2 \log N)$
- Necessary memory : $O(N^2) \rightarrow O(N\log^2 N)$
- Far interactions compressed with MLACA



Iterative method : Need for GMRES + preconditioner

Physical Optics (PO)



• The induced currents \vec{J}_S are approximated by the currents that would exist in a point of the surface if it was located in an infinite plane tangent to the surface in that point.

•
$$\vec{J}_{PO} = \hat{n} \times \vec{H} = \begin{cases} 2\hat{n} \times \vec{H}^i & \text{in lit region} \\ 0 & \text{in shadowed region} \end{cases}$$

- Local approximation: \vec{J}_S depends only on \hat{n} and \vec{H}^i .
- Equivalent currents: $\vec{J}_{eq} = \vec{J}_S \approx \vec{J}_{PO}$ and we compute \vec{E}^S radiated by \vec{J}_{eq} as the radiation of \vec{J}_{PO} in free space.
- In the far field:

$$\vec{E}^{S} = -j\omega\mu \frac{e^{-jkr}}{4\pi r}\vec{r} \times \vec{r} \times \iint_{Slit} 2\hat{n} \times \vec{H}^{i} \ e^{jk\hat{r}\cdot\vec{r}'}ds'$$





Limitations of PO

- Fails when R curvature < λ .
- Fails in wedges : use edge diffraction (PTD).



- Assumes $\vec{J}_S \approx 0$ in the shade region. Does not account for creeping waves.
- Does not account for surface wave diffraction at surface discontinuities.



- Artificial discontinuity in \vec{J}_{PO} at the limit between lit and shadow regions produces an error term.
- Not multibouncing.

Numerical Results

- EDA-Workshop »Radar Signatures & EM Benchmarks« 2017
- Test case 3: Rotating Wind Turbine.
- Rotor diameter: 96m.
- Height : 150m.
- Source at (-20km,0,0).
- Frequency : 3Ghz.
- Unknowns at $\lambda/4$: 12.5M
- Output : Nearfield at x=[-5km,20km] y=[-0.5km,0.5km] z=0m
- Simulated with PO (justified by the results at smallest frequencies.







Numerical Results – 3GHz





Numerical Results - 3GHz





Numerical Results – MoM vs PO 600 MHz



600MHz - x=250m









Numerical Results – MoM vs PO

30MHz – x=250m

150MHz – x=250m





Numerical Results – 600MHz

• Two wind turbines at 600MHz

• N = 4M

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Conclusion

- We have shown the interest of frequency domain simulation methods in the study of the impact of a wind farm over a radio navigation system.
- The choice of simulation technique depends on the complexity of the problem and the carrier frequency of the system.
- We advise to use a high precision method such as the MoM for a simplified problem to use it as reference. It allows to justify the use of a high frequency approximation method such as PO or GTD.
- The performed simulations to reproduce the system behavior depend on the system itself. In particular, we have shown the procedure for the bearing angle estimation of a TACAN radio navigation system.
- The impact of the shadowing effects of a wind turbine on the received electric field has been presented.

