

The scalar orbit of the virtual Kähler-Ricci flow Alexandru Iosif

▶ To cite this version:

Alexandru Iosif. The scalar orbit of the virtual Kähler-Ricci flow. 2020. hal-02453356

HAL Id: hal-02453356 https://hal.science/hal-02453356v1

Preprint submitted on 23 Jan 2020

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

THE SCALAR ORBIT OF THE VIRTUAL KÄHLER-RICCI FLOW

ALEXANDRU IOSIF

ABSTRACT. We introduce the virtual Kähler-Ricci flow and propose it as a conjectural framework for representing meromorphic functions in one complex variable.

Let (M, g_0) be a Kähler manifold of finite dimension and let Ric_0 be its Ricci curvature tensor. Let P be a polynomial in the variables g(s)and $\operatorname{Ric}(s)$ and coefficients in the field \mathbb{M} of meromorphic functions in one complex variable s. We would like to generalize the notion of Kähler-Ricci flow as follows.

Definition 1. The virtual Kähler-Ricci flow $\mathfrak{R}_{P;(M,q_0)}$ of (M, g_0) is

$$\{(M, g(t)) : t \in \mathbb{C}, \ \frac{dg}{ds} = P(g(s), \operatorname{Ric}(s)), \ g(0) = g_0\}.$$

By setting P = -2Ric(s), one obtains the following result due to Bando (e.g. [1, Section 1.1.3]).

Theorem 2. Every element of $\mathfrak{R}_{-2Ric(s);(M,g_0)}$ is a Kähler manifold.

Proof. If $P = -2\operatorname{Ric}(s)$, then the virtual Kähler-Ricci Flow is a Kähler-Ricci flow. But the Kähler condition is preserved under the Kähler-Ricci flow.

Let $(M, g(t)) \in \mathfrak{R}_{P;(M,g_0)}$. If g(t) is a positive definite Hermitian matrix at each point of M, then $\operatorname{Ric}(t)$ is the Ricci curvature of g(t). This motivates the following generalization.

Definition 3. The virtual Ricci curvature is $\operatorname{Ric}(t)$ and the mean virtual scalar curvature $\sigma(t)$ is the mean of $\operatorname{tr}_{g(t)}\operatorname{Ric}(t)$. The Ricci orbit of (M, g_0) is $\operatorname{Ric}(s)$ and its scalar orbit is $\sigma(s)$.

The following problems are the motivation for the above generalizations.

Problem 4. Given a meromorphic function $\mu(s)$, does there exist a Kähler manifold (M, g_0) and a polynomial P such that $\mu(s)$ is the scalar orbit of $\mathfrak{R}_{P;(M,g_0)}$ and, for every zero t of $\mu(t)$, g(t) is a real, positive definite, symmetric matrix?

ALEXANDRU IOSIF

If the answer to the previous problem were yes, then we could associate to each zero of $\mu(s)$ a (flat) Kähler manifold.

Problem 5. Given a Kähler manifold (M, g_0) , find a P, or prove that there is none, such that (M, g(s)) is Kähler if and only if $\sigma(s) = 0$.

It would be interesting to restrict this study to polynomials P such that the virtual Kähler-Ricci Flow has a unique solution. This would make the notion of orbit in the definition above a nicer object. A natural question that arises is the following.

Question 6. What is the algebraic structure of the set of polynomials *P* which lead to a virtual Kähler-Ricci Flow with a unique solution?

Note that a generalization of the Chern-Gauss-Bonnet theorem (or, more generally, of the Atiyah-Singer Theorem) is needed. It should be more general in the sense that it should cover the case of degenerated manifolds (that is, which fail to have a real curvature, or, in particular, a Hermitian metric).

References

 Jian Song and Ben Weinkove, An introduction to the Kähler-Ricci flow, Springer, 2013, pp. 89–188.

JRC-COMBINE, AACHEN, GERMANY Email address: iosif@aices.rwth-aachen.de

 $\mathbf{2}$