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Static spherically symmetric Einstein-Vlasov bifurcations of the Schwarzschild spacetime

Fatima Ezzahra Jabiri *

January 22, 2020

Abstract

We construct a one-parameter family of static and spherically symmetric solutions to the Einstein-Vlasov system bifurcating from the Schwarzschild spacetime. The constructed solutions have the property that the spatial support of the matter is a finite, spherically symmetric shell located away from the black hole. Our proof is mostly based on the analysis of the set of trapped timelike geodesics and of the effective potential energy for static spacetimes close to Schwarzschild. This provides an alternative approach to the construction of static solutions to the Einstein-Vlasov system in a neighbourhood of black hole vacuum spacetimes.

Contents

1	Introduction	2
2	Preliminaries and basic background material 2.1 The Einstein-Vlasov system 2.2 Static and Spherically symmetric solutions 2.2.1 Metric ansatz 2.2.2 Vlasov field on static and spherically symmetric spacetimes 2.3 The Schwarzschild spacetime and its timelike geodesics 2.4 Ansatz for the distribution function 2.5 Reduced Einstein equations 2.6 Rein's work on solutions with a Schwarzschild-like black hole	$ \begin{array}{r} 4 \\ 5 \\ 6 \\ 6 \\ 7 \\ 10 \\ 12 \\ 15 \\ \end{array} $
3	Statement of the main result	18
4	Solving the reduced Einstein Vlasov system4.1Set up for the implicit function theorem4.2Radii of the matter shell4.3Regularity of the matter terms4.4The condition (2.61) is satisfied4.5Solving for μ 4.5.1G is well defined on \mathcal{U} 4.5.2G is continuously Fréchet differentiable on \mathcal{U} 4.6Conclusions	 19 21 27 30 32 32 33 34
A	ppendix	36
\mathbf{A}	Study of the geodesic motion in the exterior of Scwharzschild spacetime	36

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1 Introduction

The relativistic kinetic theory of gases plays an important role in the description of matter fields surrounding black holes such as plasmas or distribution of stars [22], [6]. In particular, Vlasov matter is used to analyse galaxies or globular galaxies where the stars play the role of gas particles and where collisions between these are sufficiently rare to be neglected, so that the only interaction taken into account is gravitation.

In the geometric context of general relativity, the formulation of relativistic kinetic theory was developed by Synge [34], Israel [15] and Tauber and Weinberg [35]. We also refer to the introduction of [1] for more details. In this work, we are interested in the Vlasov matter model. It is described by a particle distribution function on the phase space which is transported along causal geodesics, resulting in the Vlasov equation. The latter is coupled to the equations for the gravitational field, where the source terms are computed from the distribution function. In the non-relativistic setting, i.e. the Newtonian framework, the resulting nonlinear system of partial differential equations is the Vlasov-Poisson (VP) system [26], while its general relativistic counterpart forms the Einstein-Vlasov (EV) system. Collisionless matter possesses several attractive features from a partial differential equations viewpoint. On any fixed background, it avoids pathologies such as shock formation, contrary to more traditional fluid models. Moreover, one has global solutions of the VP system in three dimensions for general initial data [23], [20].

The local well-posedness of the Cauchy problem for the EV system was first investigated in [9] by Choquet-Bruhat. Concerning the nonlinear stability of the Minkowski spacetime as the trivial solution of the EV system, it was proven in the case of spherically symmetric initial data by Rendall and Rein [25] in the massive case and by Dafermos [10] for the massless case. The general case was recently shown by Fajman, Joudioux and Smulevici [13] and independently by Lindblad-Taylor [19] for the massive case, and by Taylor [36] for the massless case. Nonlinear stability results have been given by Fajman [12] and Ringtröm [29] in the case of cosmological spacetimes. See also [33], [5], [11], [38], [32] for several results on cosmological spacetimes with symmetries.

In stellar dynamics, equilibrium states can be described by stationary solutions of the VP or EV system. Static and spherically symmetric solutions can be obtained by assuming that the distribution function has the following form

$$f(x,v) = \Phi(E,\ell),$$

where E and ℓ are interpreted as the energy and the total angular momentum of particles respectively. In fact, in the Newtonian setting, the distribution function associated to a stationary and spherically symmetric solution to the VP system is necessarily described by a function depending only on E and ℓ . Such statement is referred to as Jean's theorem [16], [17], [7]. However, it has been shown that its generalisation to general relativity is false in general [31].

A particular choice of Φ , called the polytropic ansatz, which is commonly used to construct static and spherically symmetric states for both VP and EV system is given by

$$\Phi(E,\ell) := \begin{cases} (E_0 - E)^{\mu} \ell^k, & E < E_0, \\ 0, & E \ge E_0. \end{cases}$$
(1.1)

where $E_0 > 0$, $\mu > -1$ and k > -1. In [27], Rein and Rendall gave the first class of asymptotically flat, static, spherically symmetric solutions to EV system with finite mass and finite support such that Φ depends only on the energy of particles. In [24], Rein extended the above result for distribution functions depending also on ℓ , where Φ is similar to the polytropic ansatz (1.1): $\Phi(E,\ell) = \phi(E)(\ell - \ell_0)_+^k$, $\phi(E) = 0$ if $E > E_0$, k > -1 and $\ell_0 \ge 0$. Among these, there are singularity-free solutions with a regular center, and also solutions with a Schwarzschild-like black hole. Other results beyond spherical symmetry were recently established. In [3], static and axisymmetric solutions to EV system were constructed by Rein-Andréasson-Kunze and then extended in [4] to establish the existence of rotating stationary and axisymmetric solutions to the Einstein-Vlasov system. The constructed solutions are obtained as bifurcations of a spherically symmetric Newtonian steady state. We note that the proof is based on the application of the implicit function theorem and it can be traced back to Lichtenstein [18] who proved the existence of non-relativistic, stationary, axisymmetric self-gravitating fluid balls. Similar arguments were adapted by Andréasson-Fajman-Thaller in [2] to prove the existence of static spherically symmetric solutions of the Einstein-Vlasov-Maxwell system with non-vanishing cosmological constant. Recently, Thaller has constructed in [37] static and axially symmetric shells of the Einstein-Vlasov-Maxwell system.

In this paper, we construct static spherically symmetric solutions to the EV system which contain a matter shell located in the exterior region of the Schwarzschild black hole. This provides an alternative construction to that of Rein [24], See remarks 1 and 2 below for a comparison of our works and results. Our proof is based on the study of trapped timelike geodesics of spacetimes closed to Schwarzschild. In particular, we show (and exploit) that for some values of energy and total angular momentum (E, ℓ) , the effective potential associated to a particle moving in a perturbed Schwarzschild spacetime and that of a particle with same (E, ℓ) moving in Schwarzschild are similar. Our distribution function will then be supported on the set of trapped timelike geodesics, and this will lead to the finiteness of the mass and the matter shell's radii.

Recall that the effective potential energy E_{ℓ}^{Sch} of a particle of rest mass m = 1 and angular momentum ℓ , moving in the exterior of region of the Schwarzschild spacetime is given by

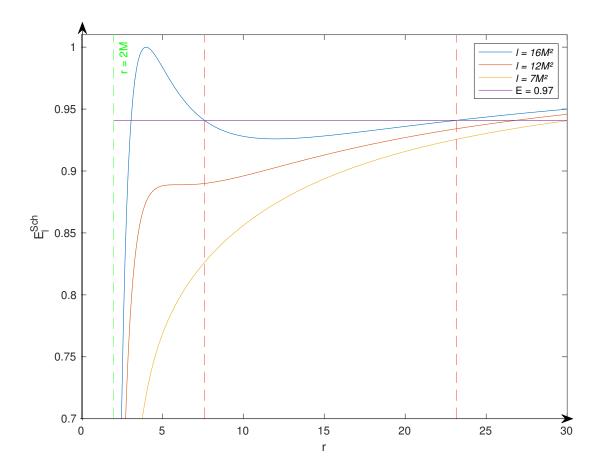


Figure 1: Shape of the effective potential energy E_{ℓ}^{Sch} for three cases of ℓ , with M = 1, E = 0.97.

$$E_{\ell}^{Sch}(r) = \left(1 - \frac{2M}{r}\right) \left(1 + \frac{\ell}{r^2}\right).$$
(1.2)

In particular, trapped geodesics occur when the equation

$$E_{\ell}^{Sch}(r) = E^2, \tag{1.3}$$

admits three distinct roots $r_0^{Sch}(E, \ell) < r_1^{Sch}(E, \ell) < r_2^{Sch}(E, \ell)$. We state now our main result:

Theorem 1. There exists a 1-parameter family of smooth, static, spherically symmetric asymptotically flat spacetimes $(\mathcal{M}, g_{\delta})$ and distribution functions $f^{\delta} : \Gamma_1 \to \mathbb{R}_+$ solving the Einstein-Vlasov system given by equations (2.1), (2.6) and (2.8), such that f^{δ} verifies

$$\forall (x,v) \in \Gamma_1, \ f^{\delta}(x,v) = \Phi(E^{\delta},\ell;\delta)\Psi(r,(E^{\delta},\ell),g_{\delta}).$$
(1.4)

where $\Phi(\cdot, \cdot; \delta)$ is supported on a compact set B_{bound} of the set of parameters (E, ℓ) corresponding to trapped timelike trajectories, Ψ is a positive cut-off function, defined below (cf. (2.45)) which selects the trapped geodesics with parameters $(E, \ell) \in B_{bound}$, Γ_1 is the mass shell of particles with rest mass m = 1, and E^{δ} is the local energy with respect to the metric g_{δ} .

Moreover, the resulted spacetimes contain a shell of Vlasov matter in the following sense: there exist $R_{min} < R_{max}$ such that the metric is given by Schwarzschild metric of mass M in the region $[2M, R_{min}]$, by Schwarzschild metric of mass M^{δ} in the region $[R_{max}, \infty[$, and f^{δ} does not identically vanish in the region $[R_{min}, R_{max}]$.

Remark 1. Compared to the work of Rein [24], the solutions constructed here are bifurcating from Schwarzschild and therefore, a priori small. Moreover, the ansatz used in this work is different from that used by Rein. In particular, it is not polytropic. Another difference is that we do not use the Tolman-Oppenheimer-Volkov equation (2.82) in our argument. See Theorem 2 for the exact assumptions on the profile Φ .

Remark 2. A posteriori, in the small data case, one can check that the distribution functions constructed by Rein are supported on trapped timelike geodesics. However, not all the trapped geodesics are admissible in his construction. In our case, we include a more general support, cf. Section 2.6 for more details on this part.

Remark 3. The support of $\Phi(E, \ell; \delta)$ has two connected components: one corresponds to geodesics which start near $r_0(E, \ell)$ and reach the horizon in a finite proper time, and the other one corresponds to trapped geodesics. Ψ is introduced so that it is equal to 0 outside B_{bound} and equal to a cut-off function depending on the r variable (cf (2.46)), χ on B_{bound} . The latter is equal to 0 on the first connected component of the support of $\Phi(E, \ell; \delta)$ and to 1 on the second component. This allows to eliminate the undesired trajectories. The reason behind the use of this cut-off function is related to the non-validity of Jean's theorem in general relativity [31].

The paper is organised as follows. In Section 2, we present basic background material on the Einstein-Vlasov system and the geodesic motion in the Schwarzschild exterior. We also present the ansatz for the metric and the distribution function and we reduce the Einstein equations to a system of ordinary differential equations in the metric components. We end this section with a short description of Rein's construction to compare it with ours. In Section 3, we give a detailed formulation of our main result. In Section 4, we prove Theorem 1. To this end, we control quantitatively the effective potential and the resulting trapped timelike geodesics for static spherically symmetric spacetimes close to Schwarzschild. The main theorem is then obtained by application of the implicit function theorem. Finally, Appendix A contains a proof of Proposition 1 concerning the classification of timelike geodesics in the Schwarzschild spacetime.

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2 Preliminaries and basic background material

In this section, we introduce basic material necessary for the rest of the paper.

2.1 The Einstein-Vlasov system

In this work, we study the Einstein field equations for a time oriented Lorentzian manifold (\mathcal{M}, g) in the presence of matter

$$Ric(g) - \frac{1}{2}gR(g) = 8\pi T(g),$$
 (2.1)

where Ric denotes the Ricci curvature tensor of g, R denotes the scalar curvature and T denotes the energymomentum tensor which must be specified by the matter theory. The model considered here is the Vlasov matter. It is assumed that the latter is represented by a scalar positive function $f: T\mathcal{M} \to \mathbb{R}$ called the distribution function. The condition that f represents the distribution of a collection of particles moving freely in the given spacetime is that it should be constant along the geodesic flow, that is

$$L[f] = 0,$$
 (2.2)

where L denotes the Liouville vector field. The latter equation is called the Vlasov equation. In a local coordinate chart (x^{α}, v^{β}) on $T\mathcal{M}$, where (v^{β}) are the components of the four-momentum corresponding to x^{α} , the Liouville vector field L reads

$$L = v^{\mu} \frac{\partial}{\partial x^{\mu}} - \Gamma^{\mu}{}_{\alpha\beta}(g) v^{\alpha} v^{\beta} \frac{\partial}{\partial v^{\mu}}$$
(2.3)

and the corresponding integral curves satisfy the geodesic equations of motion

$$\begin{cases} \frac{dx^{\mu}}{d\tau}(\tau) = v^{\mu}, \\ \frac{dv^{\mu}}{d\tau}(\tau) = -\Gamma^{\mu}_{\ \alpha\beta}v^{\alpha}v^{\beta}, \end{cases}$$
(2.4)

where $\Gamma^{\mu}_{\ \alpha\beta}$ are the Christoffel symbols given in the local coordinates x^{α} by

$$\Gamma^{\mu}_{\ \alpha\beta} = \frac{1}{2}g^{\mu\nu} \left(\frac{\partial g_{\beta\nu}}{\partial x^{\alpha}} + \frac{\partial g_{\alpha\nu}}{\partial x^{\beta}} - \frac{\partial g_{\alpha\beta}}{\partial x^{\nu}}\right)$$

and where τ is an affine parameter which corresponds to the proper time in the case of timelike geodesics. The trajectory of a particle in $T\mathcal{M}$ is an element of the geodesic flow generated by L and its projection onto the spacetime manifold \mathcal{M} corresponds to a geodesic of the spacetime.

It is easy to see that the quantity $\mathcal{L}(x,v) := \frac{1}{2}v^{\alpha}v^{\beta}g_{\alpha\beta}$ is conserved along solutions of (2.4)¹. In the case of timelike geodesics this corresponds to the conservation of the rest mass m > 0 of the particle. In the following, we will consider only particles with the same rest mass so that we can set $\mathcal{L}(x,v) = -\frac{m^2}{2}$. Furthermore, for physical reasons, we require that all particles move on future directed timelike geodesics. Therefore, the distribution function is supported on the seven dimensional manifold of $T\mathcal{M}^2$, called the *the mass shell*, denoted by Γ_m and defined by

$$\Gamma_m := \{(x, v) \in T\mathcal{M} : g_x(v, v) = -m^2, \text{ and } v^\alpha \text{ is future pointing}\}.$$
(2.5)

We note that by construction Γ_m is invariant under the geodesic flow.

We assume that there exist local coordinates on \mathcal{M} , denoted by $(x^{\alpha})_{\alpha=0\cdots 3}$ such that $x^0 = t$ is a smooth strictly increasing function along any future causal curve and its gradient is past directed and timelike. Then, the condition

$$g_{\alpha\beta}v^{\alpha}v^{\beta} = -1$$
 where v^{α} is future directed

allows to write v^0 in terms of (x^{α}, v^a) . It is given by

$$v^{0} = -(g_{00})^{-1} \left(g_{0j} v^{j} + \sqrt{(g_{0j} v^{j})^{2} - g_{00} (m^{2} + g_{ij} v^{i} v^{j})} \right).$$

¹We note that \mathcal{L} is the Lagrangian of a free-particle.

²See [30] Lemma.7

Therefore, Γ_m can be parametrised by (x^0, x^a, v^a) . Hence, the distribution function can be written as a function of (x^0, x^a, v^a) and the Vlasov equation has the form

$$\frac{\partial f}{\partial x^0} + \frac{v^a}{v^0} \frac{\partial f}{\partial x^a} - \Gamma^a{}_{\alpha\beta} \frac{v^\alpha v^\beta}{v^0} \frac{\partial f}{\partial v^a} = 0.$$
(2.6)

In order to define the energy-momentum tensor which couples the Vlasov equation to the Einstein field equations, we introduce the natural volume element on the fibre $\Gamma_{m,x} := \{v^{\alpha} \in T_x \mathcal{M} : g^{\alpha\beta}v^{\alpha}v^{\beta} = -m^2, v^0 > 0\}$ of Γ_m at a point $x \in \mathcal{M}$ given in the adapted local coordinates (x^0, x^a, v^a) by

$$d\mathrm{vol}_x(v) := \frac{\sqrt{-\det(g_{\alpha\beta})}}{-v_0} dv^1 dv^2 dv^3.$$
 (2.7)

The energy momentum tensor is now defined by

$$\forall x \in \mathcal{M} \quad T_{\alpha\beta}(x) := \int_{\Gamma_{m,x}} v_{\alpha} v_{\beta} f(x,v) \, d\mathrm{vol}_{x}(v), \tag{2.8}$$

where $f = f(x^0, x^a, v^a)$ and $dvol_x(v) = dvol_x(v^a)^3$. In order for (2.8) to be well defined, f has to have certain regularity and decay properties. One sufficient requirement would be to demand that f have compact support on Γ_x , $\forall x \in \mathcal{M}$ and it is integrable with respect to v. In this work, we assume that all particles have the same rest mass and it is normalised to 1. From now on, the mass shell Γ_1 will be denoted by Γ . Finally, we refer to (2.1) and (2.6) with T given by (2.8) as the Einstein-Vlasov system.

2.2 Static and Spherically symmetric solutions

2.2.1 Metric ansatz

We are looking for static and spherically symmetric asymptotically flat solutions to the EV system. Therefore, we consider the following ansatz for the metric, written in standard (t, r, θ, ϕ) coordinates:

$$g = -e^{2\mu(r)}dt^2 + e^{2\lambda(r)}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2).$$
 (2.9)

with boundary conditions at infinity:

$$\lim_{r \to \infty} \lambda(r) = \lim_{r \to \infty} \mu(r) = 0.$$
(2.10)

Since we consider solutions close to a Schwarzschild spacetime of mass M > 0 outside from the black hole region, we fix a manifold of the form

$$\mathcal{O} := \mathbb{R} \times]2M, \infty[\times S^2. \tag{2.11}$$

$$t \quad r \quad \theta, \phi \tag{2.12}$$

2.2.2 Vlasov field on static and spherically symmetric spacetimes

The distribution function f is conserved along the geodesic flow. Hence, any function of the integrals of motion will satisfy the Vlasov equation. In this context, we look for integrals of motion for the geodesic equation (2.4) on a static and spherically symmetric background. By symmetry assumptions, the vector fields

$$\xi_t = \frac{\partial}{\partial t},\tag{2.13}$$

generating stationarity, and

$$\xi_1 = -\cos\phi\cot\theta \frac{\partial}{\partial\phi} - \sin\phi \frac{\partial}{\partial\theta},\tag{2.14}$$

³The latin indices run from 1...3.

$$\xi_2 = -\sin\phi\cot\theta\frac{\partial}{\partial\phi} + \cos\phi\frac{\partial}{\partial\theta},\tag{2.15}$$

$$\xi_3 = \frac{\partial}{\partial \phi} \tag{2.16}$$

generating spherical symmetry are Killing. Therefore, the quantities

$$E(x,v) := -g_x(v,\xi_t) = e^{\mu(r)}\sqrt{m^2 + (e^{\lambda(r)}v^r)^2 + (rv^\theta)^2 + (r\sin\theta v^\phi)^2},$$
(2.17)

$$\ell_1(x,v) := g_x(v,\xi_1) = r^2 \left(-\sin\phi v^\theta - \cos\theta\sin\theta\cos\phi v^\phi \right), \qquad (2.18)$$

$$\ell_2(x,v) := g_x(v,\xi_2) = r^2 \left(\cos\phi v^\theta - \cos\theta\sin\theta\sin\phi v^\phi\right),\tag{2.19}$$

$$\ell_z(x,v) := g_x(v,\xi_3) = r^2 \sin^2 \theta v^{\phi}, \qquad (2.20)$$

are conserved. In particular, E and

$$\ell := \ell(r, \theta, v^{\theta}, v^{\phi}) = \ell_1^2 + \ell_2^2 + \ell_z^2 = r^4 \left((v^{\theta})^2 + \sin^2 \theta (v^{\phi})^2 \right)$$
(2.21)

are conserved. We recall that $m := -g_{\alpha\beta}v^{\alpha}v^{\beta}$ is also a conserved quantity. Since all particles have the same rest mass m = 1, E becomes

$$E = E(r, v^r, v^{\theta}, v^{\phi}) = e^{\mu(r)} \sqrt{1 + (e^{\lambda(r)}v^r)^2 + (rv^{\theta})^2 + (r\sin\theta v^{\phi})^2}.$$
(2.22)

Note that E and ℓ can be interpreted respectively as the energy and the total angular momentum of the particles.

2.3 The Schwarzschild spacetime and its timelike geodesics

The Schwarzschild family of spacetimes is a one-parameter family of spherically symmetric Lorentzian manifolds, indexed by M > 0, which are solutions to the Einstein vacuum equations

$$Ric(g) = 0. (2.23)$$

The parameter M denotes the ADM mass. The *domain of outer communications* of these solutions can be represented by \mathcal{O} and a metric which takes the form

$$g_{Sch} = -e^{2\mu^{Sch}(r)}dt^2 + e^{2\lambda^{Sch}(r)}dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2), \qquad (2.24)$$

where

$$e^{2\mu^{Sch}(r)} = 1 - \frac{2M}{r}$$
 and $e^{2\lambda^{Sch}(r)} = \left(1 - \frac{2M}{r}\right)^{-1}$. (2.25)

In this work, we shall be interested in particles moving in the exterior region. We note that the study of the geodesic motion is included in the classical books of general relativity. See for example [8, Chapter 3] or [21, Chapter 33]. We recall here a complete classification of timelike geodesics in order to be self contained. The delineation of Schwarzschild's geodesics requires solving the geodesic equations given by (2.4). Therefore, we need to integrate a system of 8 ordinary differential equations. However, the symmetries of the Schwarzschild spacetime and the mass shell condition

$$\mathcal{L}(x,v) = -\frac{m^2}{2} \tag{2.26}$$

imply the complete integrability of the system.

Let $(x^{\alpha}, v^{\alpha}) = (t, r, \theta, \phi, v^{t}, v^{r}, v^{\theta}, v^{\phi})$ be a local coordinate system on $T\mathcal{M}$. The quantities

$$E = -v_t, \quad \ell = r^4 \left((v^{\theta})^2 + \sin^2 \theta (v^{\phi})^2 \right), \quad \ell_z = r \sin \theta v^{\phi}.$$

are then conserved along the geodesic flow. Besides, the mass shell condition on Γ takes the form

$$-e^{2\mu^{Sch}(r)}(v^{t})^{2} + e^{2\lambda^{Sch}(r)}(v^{r})^{2} + r^{2}\left((v^{\theta})^{2} + \sin^{2}\theta(v^{\phi})^{2}\right) = -1$$

which is equivalent to

$$E^{2} = E_{\ell}^{Sch}(r) + (e^{\lambda^{Sch}}v^{r})^{2}, \quad \text{where} \quad E_{\ell}^{Sch}(r) = e^{2\mu^{Sch}(r)} \left(1 + \frac{\ell}{r^{2}}\right).$$
(2.27)

and implies

$$E_{\ell}^{Sch}(r) \le E^2 \tag{2.28}$$

for any geodesic moving in the exterior region.

Let $\gamma: I \to \mathcal{M}$ be a timelike geodesic in the spacetime, defined on interval $I \subset \mathbb{R}$. In the adapted local coordinates (x^{α}, v^{α}) , we have

$$\gamma(\tau) = (t(\tau), r(\tau), \theta(\tau), \phi(\tau)) \quad \text{and} \quad \gamma'(\tau) = (v^t(\tau), v^r(\tau), v^\theta(\tau), v^\phi(\tau)).$$

Besides, γ satisfies the geodesic equations of motion (2.4). One can easily see from the equations

$$v_t = -E, \tag{2.29}$$

$$r\sin\theta v^{\phi} = \ell_z,\tag{2.30}$$

$$(rv^{\theta})^2 + \frac{\ell_z^2}{\sin^2\theta} = \ell, \qquad (2.31)$$

$$(e^{\lambda^{Sch}(r)}v^{r})^{2} - e^{-2\mu^{Sch}(r)}E^{2} + \left(1 + \frac{\ell}{r^{2}}\right) = 0$$
(2.32)

that if we solve the geodesic motion in the radial direction $r(\tau)$ then we can integrate the remaining equations of motion. More precisely, if one solves for r then we get t from (2.29), ϕ from (2.30) and θ from (2.31). Therefore, we will study the geodesic equation projected only in the radial direction i.e we consider the reduced system

$$\frac{dr}{d\tau} = v^r,\tag{2.33}$$

$$\frac{dv^r}{d\tau} = -\Gamma^r{}_{\alpha\beta}v^\alpha v^\beta. \tag{2.34}$$

Straightforward computations of the right hand side of the second equation lead to

$$\Gamma^{r}{}_{\alpha\beta}v^{\alpha}v^{\beta} = \frac{M}{r^{2}}\left(1 - \frac{2M}{r}\right)^{-1}E^{2} - \frac{M}{r^{2}}\left(1 - \frac{2M}{r}\right)^{-1}(v^{r})^{2} - \frac{1}{r^{3}}\left(1 - \frac{2M}{r}\right)\ell.$$

We combine the latter expression with (2.32), to obtain

$$\frac{dv^r}{d\tau} = -\frac{M}{r^2} \left(1 + \frac{\ell}{r^2}\right) + \frac{\ell}{r^3} \left(1 - \frac{2M}{r}\right).$$

Now, by (2.27), it is easy to see that

$$\frac{dv^r}{d\tau} = -\frac{1}{2}E_\ell^{Sch'}(r).$$

In order to lighten the notations, we denote v^r by w. Thus, we consider the differential system

$$\frac{dr}{d\tau} = w, \tag{2.35}$$

$$\frac{dw}{d\tau} = -\frac{1}{2}E_{\ell}^{Sch'}(r).$$
(2.36)

We classify solutions of (2.35)-(2.36) based on the shape of E_{ℓ}^{Sch} as well as the roots of the equation

$$E^2 = E_{\ell}^{Sch}(r).$$
 (2.37)

More precisely, we state the following proposition. We include a complete proof of this classical result in Appendix A.

Proposition 1. Consider a timelike geodesic $\gamma : I \to \mathcal{M}$ of the Schwarzschild exterior of mass M > 0parametrised by $\gamma(\tau) = (t(\tau), r(\tau), \theta(\tau), \phi(\tau))$ and normalised so that $g_{Sch}(\dot{\gamma}, \dot{\gamma}) = -1$. Let E and ℓ be the associated energy and total angular momentum defined respectively by $E := -v_t$ and $\ell := r^4 ((v^\theta)^2 + \sin^2 \theta (v^\phi)^2)$. Then, we have the following classification

- 1. If $\ell \leq 12M^2$, then
 - (a) if $\sqrt{\frac{8}{9}} < E < 1$, then the orbit starts at some point $r_0 > 2M$, the unique root of the equation (2.37), and reaches the horizon r = 2M in a finite proper time.
 - (b) if $E \ge 1$, then the equation (2.37) admits no positive roots, and the orbit goes to infinity $r = +\infty$ in the future, while in the past, it reaches the horizon r = 2M in finite affine time.
 - (c) if $E = \sqrt{\frac{8}{9}}$, then $\ell = 12M^2$. In this case, the equation (2.37) admits a unique triple root, given by $r_c = 6M$. The orbit is circular of radius r_c .
- 2. If $\ell > 12M^2$, then
 - (a) if $\ell = \ell_{lb}(E)$, the geodesic is a circle of radius $r_{max}^{Sch}(\ell)$, given by

$$r_{max}^{Sch}(\ell) = \frac{\ell}{2M} \left(1 - \sqrt{1 - \frac{12M^2}{\ell}} \right).$$
(2.38)

Here, $\ell_{lb}(E)$ is given by

$$\ell_{lb}(E) := \frac{12M^2}{1 - 4\alpha - 8\alpha^2 + 8\alpha\sqrt{\alpha^2 + \alpha}}, \qquad \alpha := \frac{9}{8}E^2 - 1.$$
(2.39)

- (b) if $\ell < \ell_{lb}(E)$,
 - i. if $E \ge 1$, then the equation (2.37) admits no positive roots. Hence, the orbit goes to infinity $r = +\infty$ in the future, while in the past, it reaches the horizon r = 2M in finite affine time.
 - ii. otherwise, the orbit starts at some point $r_0 > 2M$, the unique root of the equation (2.37), and reaches the horizon (r = 2M) in a finite proper time.
- (c) otherwise, if $\ell > \ell_{lb}(E)$,
 - i. if $E \ge 1$, then the equation (2.37) admits two positive distinct roots $2M < r_0 < r_2$ and two orbits are possible
 - A. The geodesic starts at r_0 and reaches the horizon in a finite proper time.
 - B. The orbit is hyperbolic, so unbounded. The orbit starts from infinity, hits the potential barrier at r_2 , the biggest root of the equation (2.37), and goes back to infinity.
 - ii. otherwise, if E < 1, and necessarily $\ell \leq \ell_{ub}(E)$, where $\ell_{ub}(E)$ is given by

$$\ell_{ub}(E) := \frac{12M^2}{1 - 4\alpha - 8\alpha^2 - 8\alpha\sqrt{\alpha^2 + \alpha}},$$
(2.40)

A. if $\ell = \ell_{ub}(E)$, the geodesic is a circle of radius $r_{min}^{Sch}(\ell)$, given by

$$r_{min}^{Sch}(\ell) = \frac{\ell}{2M} \left(1 + \sqrt{1 - \frac{12M^2}{\ell}} \right).$$
(2.41)

- B. If $\ell < \ell_{ub}(E)$, then the equation (2.37) admits three distinct roots $2M < r_0^{Sch}(E,\ell) < r_1^{Sch}(E,\ell) < r_2^{Sch}(E,\ell)$, and two orbits are possible
 - The geodesic starts from $r_0^{Sch}(E, \ell)$ and reaches the horizon in a finite time.

• The geodesic is periodic. It oscillates between an aphelion $r_2^{Sch}(E, \ell)$ and a perihelion $r_1^{Sch}(E, \ell)$.

Remark 4. In view of (4.18), the lower bound $E \ge \sqrt{\frac{8}{9}}$ holds along any orbit.

In view of the above proposition, we introduce \mathcal{A}_{bound} , the set of (E, ℓ) parameters corresponding to trapped (non-circular) geodesics.

Definition 1.

$$\mathcal{A}_{bound} := \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \right[: E < 1, \quad \ell_{lb}(E) < \ell < \ell_{ub}(E) \right\}.$$
(2.42)

Note in view of the orbits described in 2.c.ii.B that given $(E, \ell) \in \mathcal{A}_{bound}$, two cases are possible: the orbit is either trapped or it reaches the horizon in a finite proper time.

2.4 Ansatz for the distribution function

We are interested in static and spherically symmetric distribution functions. For simplicity, we fix the rest mass of the particles to be 1. In this context, we assume that $f: \Gamma_1 \to \mathbb{R}_+$ takes the form

$$f(t, r, \theta, \phi, v^r, v^\theta, v^\phi) = \Phi(E, \ell) \Psi_\eta(r, (E, \ell), \mu).$$
(2.43)

where

• $\Phi : \mathcal{A}_{bound} \to \mathbb{R}_+$ is a C^2 function on its domain and it is supported on B_{bound} , a set of the form $[E_1, E_2] \times [\ell_1, \ell_2]$, where E_1, E_2, ℓ_1 and ℓ_2 verify

$$\sqrt{\frac{8}{9}} < E_1 < E_2 < 1 \quad \text{and} \quad \ell_{lb}(E_2) < \ell_1 < \ell_2 < \ell_{ub}(E_1).$$
(2.44)

• $\eta > 0$ is constant that will be specified later, $\Psi_{\eta}(\cdot, \cdot, \mu) \in C^{\infty}(\mathbb{R} \times \mathcal{A}_{bound}, \mathbb{R}_{+})$ is a cut-off function depending on the metric coefficient μ , such that

$$\Psi_{\eta}(\cdot, (E, \ell), \mu) := \begin{cases} \chi_{\eta}(\cdot - r_1(\mu, (E, \ell))), & (E, \ell) \in B_{bound} \\ 0 & (E, \ell) \notin \mathcal{A}_{bound}, \end{cases}$$
(2.45)

where r_1 is a positive function of (μ, E, ℓ) which will be defined later ⁴ and $\chi_{\eta} \in C^{\infty}(\mathbb{R}, \mathbb{R}_+)$ is a cut-off function defined by

$$\chi_{\eta}(s) := \begin{cases} 1 & s \ge 0, \\ \le 1 & s \in [-\eta, 0], \\ 0 & s < -\eta. \end{cases}$$
(2.46)

• E and ℓ are defined respectively by (2.22), (2.21).

Based on the monotonicity properties of ℓ_{ub} , ℓ_{ub} r_{min}^{Sch} and r_{max}^{Sch} , the set B_{bound} is included in \mathcal{A}_{bound} . More precisely, we state the following lemma

Lemma 1. Let $\ell \in]12M^2, \infty[$

• r_{max}^{Sch} decreases monotonically from 6M to 3M on $]12M^2, \infty[$.

 ${}^{4}r_{1}$ will be the second largest root of the equation $e^{2\mu(r)}\left(1+\frac{\ell}{r^{2}}\right)=E^{2}$ corresponding to the metric g.

• r_{min}^{Sch} increases monotonically from 6M to ∞ on $]12M^2, \infty[$.

Let $E \in \left[\sqrt{\frac{8}{9}}, 1 \right[,$

• ℓ_{lb} grows monotonically from $12M^2$ to $16M^2$ when E grows from $\sqrt{\frac{8}{9}}$ to 1.

• ℓ_{ub} grows monotonically from $12M^2$ to ∞ when E grows from $\sqrt{\frac{8}{9}}$ to 1.

Moreover, $\forall (E, \ell) \in [E_1, E_2] \times]\ell_{lb}(E_2), \ell_{lb}(E_1)[$

$$\ell_{lb}(E) < \ell_{lb}(E_2) < \ell < \ell_{ub}(E_1) < \ell_{ub}(E)$$

Proof. The proof is straightforward in view of (2.38), (2.41), (2.39) and (2.40).

Hence, by the above lemma, $[E_1, E_2] \times]\ell_{lb}(E_2), \ell_{lb}(E_1)[\subset \mathcal{A}_{bound}$ and in particular, $B_{bound} \subset \subset \mathcal{A}_{bound}$. Finally, we note that all trapped geodesics lie in the region $]4M, \infty[:$

Lemma 2. Let $(E, \ell) \in B_{bound}$. Let $r_i^{Sch}(E, \ell)^5$, $i \in \{0, 1, 2\}$ be the three roots of the equation

$$e^{2\mu^{Sch}(r)}\left(1+\frac{\ell}{r^2}\right) = E^2.$$
 (2.47)

Then,

- $r_0^{Sch}(E, \cdot)$ decreases monotonically on $]\ell_1, \ell_2[$ and $r_0^{Sch}(\cdot, \ell)$ increases monotonically on $]E_1, E_2[$.
- $r_1^{Sch}(E,\cdot)$ increases monotonically on $]\ell_1, \ell_2[$ and $r_1^{Sch}(\cdot, \ell)$ decreases monotonically on $]E_1, E_2[$.
- $r_2^{Sch}(E, \cdot)$ decreases monotonically on $]\ell_1, \ell_2[$ and $r_2^{Sch}(\cdot, \ell)$ increases monotonically on $]E_1, E_2[$.

Moreover,

$$\forall (E,\ell) \in A_{bound} \quad : \quad r_1^{Sch}(E,\ell) > 4M$$

Proof. First we note that the equation (2.47) is cubic in $\frac{1}{r}$. Its roots can be obtained analytically by Cardan's formula and in particular, depend smoothly on (E, ℓ) . Besides, the roots are simple. Otherwise, the orbit would be circular. Therefore,

$$(E_{\ell}^{Sch})'(r_i^{Sch}(E,\ell)) \neq 0$$

 r_i^{Sch} verify

$$E^2 = E_\ell^{Sch}(r_i^{Sch}(E,\ell))$$

We derive the latter equation with respect to E and ℓ to obtain

$$\frac{\partial r_i^{Sch}}{\partial \ell}(E,\ell) = -\frac{\frac{\partial E_\ell^{Sch}}{\partial \ell}(r_i^{Sch}(E,\ell))}{(E_\ell^{Sch})'(r_i^{Sch}(E,\ell))}, \quad \text{and} \quad \frac{\partial r_i^{Sch}}{\partial E}(E,\ell) = -\frac{2E}{(E_\ell^{Sch})'(r_i^{Sch}(E,\ell))}$$

We use the monotonicity properties of E_{ℓ}^{Sch} on $]2M, \infty[$ to determine the sign of the above derivatives. For the second point, we use the monotonicity properties of r_1^{Sch} , r_{max}^{Sch} and ℓ_{ub} to obtain

$$\forall (E,\ell) \in \mathcal{A}_{bound} : r_1^{Sch}(E,\ell) > r_1^{Sch}(E,\ell_{lb}(E)) \text{ and } r_{max}^{Sch}(\ell_{lb}(E)) > r_{max}^{Sch}(\ell_{lb}(1)).$$

Besides, by the definition on ℓ_{ub} (the value of the angular momentum such that $E^{max}(\ell) = E_{\ell}^{Sch}(r_{max}^{Sch}(\ell)) = E^2$), we have

$$r_1^{Sch}(E,\ell_{lb}(E)) = r_{max}^{Sch}(\ell_{lb}(E))$$

⁵We note that the dependence of r_i in (E, ℓ) is smooth.

Therefore,

$$r_1^{Sch}(E,\ell) > r_{max}^{Sch}(\ell_{lb}(1)).$$

To conclude, it suffices to note that $\ell_{lb}(1) = 16M^2$ so that, when using (2.38), we obtain

$$r_{max}^{Sch}(\ell_{lb}(1)) = 4M$$

This ends the proof.

Remark 5. The choice of an open set for the range of ℓ allow us eliminate the critical values leading to circular orbits which correspond to double roots of the equation (2.37): the points $(E_1, \ell_{ub}(E_1))$ and $(E_2, \ell_{lb}(E_2))$.

2.5 Reduced Einstein equations

After specifying the ansatz for the metric and for the distribution function, we compute the energy-momentum tensor associated to (2.9) and the distribution function (2.43). In order to handle the mass shell condition, we introduce the new momentum variables

$$p^{0} := -e^{\mu(r)}v^{t}, \quad p^{1} := e^{\lambda(r)}v^{r}, \quad p^{2} := rv^{\theta}, \quad p^{3} := r\sin\theta v^{\phi},$$
 (2.48)

so that the associated frame

$$e_0 := e^{-\mu(r)} \frac{\partial}{\partial t}, \quad e_1 := e^{-\lambda(r)} \frac{\partial}{\partial r}, \quad e_2 := \frac{1}{r} \frac{\partial}{\partial \theta}, \quad e_3 := \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}, \tag{2.49}$$

forms an orthonormal frame of $T_x \mathcal{M}$. In terms of the new momentum coordinates, the mass shell condition becomes

$$-(p^0)^2 + (p^1)^2 + (p^2)^2 + (p^3)^2 = -1$$
 i.e. $p^0 = \sqrt{1 + |p|^2}$

where $p = (p^1, p^2, p^3) \in \mathbb{R}^3$ and $|\cdot|$ is the Euclidean norm on \mathbb{R}^3 . It is convient to introduce an angle variable $\chi \in [0, 2\pi[$ such that

$$v^{\theta} = \frac{\sqrt{\ell}\cos\chi}{r^2}, \qquad v^{\phi} = \frac{\sqrt{\ell}\sin\chi}{r^2\sin\theta}$$

so that

$$r^4 (v^{\theta})^2 + r^4 \sin^2 \theta (v^{\phi})^2 = \ell.$$

We also introduce the effective potential in the metric (2.9)

$$E_{\ell}(r) := e^{2\mu(r)} \left(1 + \frac{\ell}{r^2} \right).$$
(2.50)

In local coordinates, the energy momentum tensor reads

$$\begin{split} T_{\alpha\beta}\left(x\right) &= \int_{\Gamma_x} v_{\alpha} v_{\beta} f(x^{\mu}, v^a) d_x \mathrm{vol}(v^a), \\ &= \int_{\Gamma_x} v_{\alpha} v_{\beta} \Phi(E(x^{\mu}, v^a), \ell(x^{\mu}, v^a)) \Psi_{\eta}(r, (E(x^{\mu}, v^a), \ell(x^{\mu}, v^a)), \mu) d_x \mathrm{vol}(v) \end{split}$$

where $d_x \operatorname{vol}(v)$ is given by (2.7), $E(x^{\mu}, v^a)$ and $\ell(x^{\mu}, v^a)$ are respectively given by (2.22) and (2.21). Here, $x^{\mu} = (t, r, \theta, \phi)$ and $v^a = (v^r, v^{\theta}, v^{\phi})$. We make a first change of variables $(v^r, v^{\theta}, v^{\phi}) \to (p^1, p^2, p^3)$ to get

$$\begin{split} T_{\alpha\beta}\left(x\right) &= \int_{\mathbb{R}^3} v_{\alpha}(p) v_{\beta}(p) \Phi\left(E(r,|p|),\ell(r,p)\right) \Psi_{\eta}(r,(E(r,|p|),\ell(r,p)),\mu) \; \frac{d^3p}{\sqrt{1+|p|^2}} \\ &= 2 \int_{[0,+\infty[\times\mathbb{R}^2]} v_{\alpha}(p) v_{\beta}(p) \Phi\left(E(r,|p|),\ell(r,p)\right) \Psi_{\eta}(r,(E(r,|p|),\ell(r,p)),\mu) \; \frac{d^3p}{\sqrt{1+|p|^2}}. \end{split}$$

We perform a second change of variables $(p^1, p^2, p^3) \mapsto (E(r, |p|), \ell(r, p), \chi)$. We compute the p^i s in terms of the new variables:

$$(p^{1})^{2} = E^{2}(r, |p|)e^{-2\mu(r)} - 1 - \frac{\ell(r, p)}{r^{2}}, \qquad p^{2} = \frac{\sqrt{\ell(r, p)}\cos\chi}{r}, \qquad p^{3} = \frac{\sqrt{\ell(r, p)}\sin\chi}{r}.$$

Now it is easy to see that the domain of (E, ℓ, χ) is given by $D_r \times [0, 2\pi]$ where

$$D_r := \{ (E, \ell) \in]0, \infty[\times [0, \infty[: E_\ell(r) \le E^2] \}.$$
(2.51)

By straightforward computations of the Jacobian, we get

$$\frac{d^3p}{\sqrt{1+|p|^2}} = \frac{1}{2r^2\sqrt{E^2 - E_\ell(r)}} \, dE d\ell d\chi$$

Therefore, the energy momentum tensor becomes

$$T_{\alpha\beta}(x) = \int_{D_r} \int_{[0,2\pi[} u_{\alpha} u_{\beta} \Phi(E,\ell) \Psi_{\eta}(r,(E,\ell,\mu) \frac{1}{r^2 \sqrt{E^2 - E_{\ell}(r)}} \, dE d\ell d\chi,$$

where

$$u_t^2 = E^2, \quad u_r^2 = e^{2\lambda(r) - 2\mu(r)} \left(E^2 - E_\ell(r) \right), \quad , u_\theta^2 = \ell \cos^2 \chi, \quad u_\phi^2 = \ell \sin^2 \theta \sin^2 \chi.$$

Hence, the non-vanishing energy-momentum tensor components are given by

$$\begin{split} T_{tt}(r) &= \frac{2\pi}{r^2} \int_{D_r} E^2 \Psi_{\eta}(r, (E, \ell, \mu)) \frac{\Phi(E, \ell)}{\sqrt{E^2 - E_{\ell}(r)}} \, dE d\ell, \\ T_{rr}(r) &= \frac{2\pi}{r^2} \int_{D_r} e^{2(\lambda(r) - \mu(r))} \Psi_{\eta}(r, (E, \ell, \mu) \Phi(E, \ell) \sqrt{E^2 - E_{\ell}(r)} \, dE d\ell, \\ T_{\theta\theta}(r) &= \frac{\pi}{r^2} \int_{D_r} \Psi_{\eta}(r, (E, \ell, \mu) \Phi(E, \ell) \frac{\ell}{\sqrt{E^2 - E_{\ell}(r)}} \, dE d\ell, \\ T_{\phi\phi}(r, \theta) &= \sin^2 \theta T_{\theta\theta}(r). \end{split}$$

It remains to compute the Einstein tensor

$$G_{\alpha\beta} = Ric_{\alpha\beta} - \frac{1}{2}g_{\alpha\beta}R(g)$$

with respect to the metric (2.9). Straightforward computations lead to

$$\begin{split} G_{tt} &= \frac{e^{2\mu(r)}}{r^2} \left(e^{-2\lambda(r)} \left(2r\lambda'(r) - 1 \right) + 1 \right), \\ G_{rr} &= \frac{e^{2\lambda(r)}}{r^2} \left(e^{-2\lambda(r)} \left(2r\mu'(r) + 1 \right) - 1 \right), \\ G_{\theta\theta} &= re^{-2\lambda(r)} \left(r\mu'^2(r) - \lambda'(r) + \mu'(r) - r\mu'(r)\lambda'(r) + r\mu''(r) \right), \\ G_{\phi\phi} &= \sin^2 \theta G_{\theta\theta}, \end{split}$$

while the remaining components vanish. Therefore, the Einstein-Vlasov system is reduced to the following system of differential equations with respect the radial variable r:

$$e^{-2\lambda(r)} (2r\lambda'(r) - 1) + 1 = 8\pi^2 e^{-2\mu(r)} \int_{D_r} E^2 \Psi_\eta(r, (E, \ell, \mu) \Phi(E, \ell) \frac{\Phi(E, \ell))}{\sqrt{E^2 - E_\ell(r)}} dEd\ell,$$
(2.52)
$$e^{-2\lambda(r)} (2r\mu'(r) + 1) - 1 = 8\pi^2 e^{-2\mu(r)} \int_{D_r} \Phi(E, \ell) \Psi_\eta(r, (E, \ell, \mu) \sqrt{E^2 - E_\ell(r)}) dEd\ell,$$
(2.53)

$$\left(r\mu'^{2}(r) - \lambda'(r) + \mu'(r) - r\mu'(r)\lambda'(r) + r\mu''(r)\right) = \frac{4\pi^{2}}{r^{3}}e^{2\lambda(r)}\int_{D_{r}} \Phi(E,\ell)\Psi_{\eta}(r,(E,\ell,\mu)\frac{\ell}{\sqrt{E^{2} - E_{\ell}(r))}} \frac{dEd\ell}{(2.54)}$$

We perform a last change of variable $E = e^{\mu(r)} \varepsilon$ and we set

$$G_{\Phi}(r,\mu) := \frac{2\pi}{r^2} \int_1^{\infty} \int_0^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon, \ell) \Psi_{\eta}(r, (e^{\mu(r)}\varepsilon, \ell, \mu)) \frac{\varepsilon^2}{\sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}}} \, d\ell d\varepsilon, \tag{2.55}$$

$$H_{\Phi}(r,\mu) := \frac{2\pi}{r^2} \int_1^{\infty} \int_0^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon, \ell) \Psi_{\eta}(r, (e^{\mu(r)}\varepsilon, \ell, \mu)) \sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}} \, d\ell d\varepsilon.$$
(2.56)

The equations (2.52) and (2.53) become

$$e^{-2\lambda(r)} \left(2r\lambda'(r) - 1\right) + 1 = 8\pi r^2 G_{\Phi}(r,\mu), \qquad (2.57)$$

$$e^{-2\lambda(r)} \left(2r\mu'(r)+1\right) - 1 = 8\pi r^2 H_{\Phi}(r,\mu).$$
(2.58)

We call the latter nonlinear system for μ and λ the reduced Einstein-Vlasov system.

We note that when inserting the ansatz of f (2.43) in the definition of the energy momentum tensor, the matter terms G_{Φ} and H_{Φ} become functionals of the yet unknown metric function μ and of the radial position r. Besides, from the reduced Einstein-Vlasov system (2.57)-(2.58), we will show that one can express λ in terms of the unknown metric μ so that we are left with the problem of solving only for μ . Therefore, we will define the solution operator used in the implicit function theorem for μ only. For this, let $\rho > 0$ and R > 0 be such that:

$$R > \max_{(E,\ell)\in B_{bound}} r_2^{Sch}(E,\ell),$$
$$0 < 2M + \rho < \min_{(E,\ell)\in B_{bound}} r_0^{Sch}(E,\ell)$$

and set $I :=]2M + \rho, R[$. We will solve (2.57)-(2.58) on I. Then, we extend the solution to $]2M, \infty[$ by the Schwarzschild solution. In this context, we state the following lemma:

Lemma 3. Let $\rho > 0$ and $R > 2M + \rho$. Let (λ, μ) be a solution of the reduced Einstein Vlasov system such that f is on the form (2.43), with boundary conditions

$$\lambda(\rho + 2M) = -\frac{1}{2}\log\left(1 - \frac{2M}{2M + \rho}\right) := \lambda_0, \qquad (2.59)$$

and

$$\mu(\rho + 2M) = \frac{1}{2} \log\left(1 - \frac{2M}{2M + \rho}\right) := \mu_0.$$
(2.60)

Moreover, we assume that

$$\forall r \in I \quad , \quad 2m(\mu)(r) < r. \tag{2.61}$$

where

$$m(\mu)(r) := M + 4\pi \int_{2M+\rho}^{r} s^2 G_{\Phi}(s,\mu) \, ds.$$
(2.62)

Then, we have

$$e^{-2\lambda(r)} = 1 - \frac{2m(\mu)(r)}{r}.$$
(2.63)

Besides,

$$\mu(r) = \mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\mu)(s)}{s}} \left(4\pi s H_{\Phi}(s,\mu) + \frac{1}{s^2} m(\mu)(s) \right) \, ds.$$
(2.64)

Proof. We integrate (2.57) between $2M + \rho$ and some $r \in I$ to obtain

$$\int_{2M+\rho}^{r} s(2\lambda' e^{-2\lambda(s)}) \, ds - \int_{2M+\rho}^{r} e^{-2\lambda(s)} \, ds + (r - (2M+\rho)) = 8\pi \int_{2M+\rho}^{r} s^2 G_{\Phi}(s,\mu) \, ds.$$

We integrate by parts the first term of the left hand side to have

$$e^{-2\lambda(r)} = 1 + \frac{2M + \rho}{r} \left(e^{-2\lambda(2M + \rho)} - 1 \right) - \frac{8\pi}{r} \int_{2M + \rho}^{r} s^2 G_{\Phi}(s, \mu) \, ds,$$

Since

$$e^{-2\lambda(2M+\rho)} = 1 - \frac{2M}{2M+\rho},$$

$$\forall r \in I, \quad e^{-2\lambda(r)} = 1 - \frac{2m(\mu)(r)}{r}$$

where

we have

$$\forall r \in I , \ m(\mu)(r) := M + 4\pi \int_{2M+\rho}^{r} s^2 G_{\Phi}(s,\mu) \, ds.$$
(2.66)

Thus, the solution of (2.57) is given by (2.65). In order to find μ , we use (2.65) so that we can write (2.58) on the form

$$\mu'(r) = e^{2\lambda(r)} \left(4\pi r H_{\Phi}(r,\mu) + \frac{1}{r^2} m(\mu)(r) \right).$$
(2.67)

Now, we integrate the latter equation between $2M + \rho$ and $r \in I$ to obtain

$$\mu(r) = \mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\mu)(s)}{s}} \left(4\pi s H_{\Phi}(r,\mu) + \frac{1}{s^2} m(\mu)(s) \right) \, ds.$$
(2.68)

2.6 Rein's work on solutions with a Schwarzschild-like black hole

In order to contrast it with our approach, we give an overview of Rein's proof [24] concerning the construction of static spherically symmetric solutions to the Einstein-Vlasov system with a Schwarzschild-like black hole such that the spacetime has a finite mass and the matter field has a finite radius. Firstly, one starts with an ansatz of the form

$$f(x,p) = \Phi(E,\ell) = \phi(E)(\ell - \ell_0)_+^l, \quad E > 0, \quad \ell \ge 0,$$
(2.69)

where $\ell_0 \ge 0$, l > 1/2 and $\phi \in L^{\infty}(]0, \infty[)$ is positive with $\phi(E) = 0$, $\forall E > E_0$ for some $E_0 > 0$.

In this context, we note that a necessary condition to obtain a steady state for the Einstein-Vlasov system with finite total mass is that Φ must vanish for energy values larger than some cut-off energy $E_0 \ge 0$ [28]. The same result was proven in [7] for the Vlasov-Poisson system. This motivates the choice of the cut-off function ϕ .

Under the above ansatz with a metric on the form (2.9), the Einstein Vlasov system becomes

$$e^{-2\lambda(r)} \left(2r\lambda'(r) - 1\right) + 1 = 8\pi r^2 \overline{G}_{\Phi}(r,\mu(r)), \qquad (2.70)$$

$$e^{-2\lambda(r)} \left(2r\mu'(r)+1\right) - 1 = 8\pi r^2 \overline{H}_{\Phi}(r,\mu(r)), \qquad (2.71)$$

$$e^{-2\lambda(r)}\left(\mu'' + (\mu' + \frac{1}{r})(\mu' - \lambda')\right) = 8\pi \overline{K}_{\Phi}(r, \mu(r))$$
(2.72)

where

$$\overline{G}_{\Phi}(r,u) = c_l r^{2l} e^{-(2l+4)u} g_{\phi} \left(e^u \sqrt{1 + \frac{\ell_0}{r^2}} \right),$$
(2.73)

$$\overline{H}_{\Phi}(r,u) = \frac{c_l}{2l+3} r^{2l} e^{-(2l+4)u} h_{\phi} \left(e^u \sqrt{1 + \frac{\ell_0}{r^2}} \right), \qquad (2.74)$$

$$\overline{K}_{\Phi}(r,u) = (l+1)H_{\Phi}(r,u) + \frac{c_l}{2}\ell_0 r^{2l-2} e^{-(2l+2)u} k_{\phi} \left(e^u \sqrt{1 + \frac{\ell_0}{r^2}} \right),$$
(2.75)

(2.76)

(2.65)

where g_{ϕ} , h_{ϕ} and k_{ϕ} are defined by

$$g_{\phi}(t) := \int_{t}^{\infty} \phi(\varepsilon)\varepsilon^{2}(\varepsilon^{2} - t^{2})^{l + \frac{1}{2}}d\varepsilon, \qquad (2.77)$$

$$h_{\phi}(t) := \int_{t}^{\infty} \phi(\varepsilon) (\varepsilon^{2} - t^{2})^{l + \frac{3}{2}} d\varepsilon, \qquad (2.78)$$

$$k_{\phi}(t) := \int_{t}^{\infty} \phi(\varepsilon) (\varepsilon^{2} - t^{2})^{l + \frac{1}{2}} d\varepsilon$$
(2.79)

(2.80)

and c_l is defined by

$$c_l := 2\pi \int_0^1 \frac{s^l}{\sqrt{1-s}} ds.$$
 (2.81)

More precisely, we have

Proposition 2 (Rein, [24]). Let Φ satisfy the assumptions stated above. Then for every $r_0 \geq 0$, $\lambda_0 \geq 0$ and $\mu_0 \in \mathbb{R}$ with $\lambda_0 = 0$ if $r_0 = 0$, there exists a unique solution $\lambda, \mu \in C^1([r_0, \infty[)$ of the reduced Einstein equations (2.70)-(2.71) with

$$\lambda(r_0) = \lambda_0, \qquad \mu(r_0) = \mu_0.$$

Local existence is first proven for $\lambda, \mu \in C^1([r_0, R])$ where $R > r_0$. Then, solutions are shown to extend to $R = \infty$. To this end, we note the crucial use of the Tolman-Oppenheimer-Volkov (TOV) equation:

$$p'(r) = -\mu'(r)(p(r) + \rho(r)) - \frac{2}{r}(p(r) - p_T(r)),$$

$$\rho(r) = \overline{G}_{\Phi}(r, \mu(r)), \quad p(r) = \overline{H}_{\Phi}(r, \mu(r)), \text{ and } p_T(r) = \overline{K}_{\Phi}(r, \mu(r)).$$
(2.82)

 ρ , p and p_T are interpreted respectively as the energy density, the radial pressure and the tangential pressure. In order to construct solutions outside from the Schwarzschild black hole, the assumption $\ell_0 > 0$ plays an important role in having vacuum between 2M and some $r_0 > 2M$, to be defined below. The construction is then based on gluing a vacuum region and a region containing Vlasov matter. A posteriori, one can check that the spacetime has a finite total ADM mass and the matter has a finite radius. For the gluing,

- one starts by fixing a Schwarzschild black hole of mass M, and one then imposes a vacuum region until $r_0 > 2M$. The position r_0 will be chosen in the following way:
 - 1. First, one can fix $E_0 = 1$. We note that, according to Proposition 1, there can be no bounded orbits for $E_0 > 1$ in the Schwarzschild spacetime, which motivates this value of E_0^6 . This implies

$$\overline{G}_{\Phi}(r,u) = \overline{H}_{\Phi}(r,u) = 0 \quad \text{if } e^u \sqrt{1 + \frac{\ell_0}{r^2}} \ge 1,$$
$$\overline{G}_{\Phi}(r,u), \overline{H}_{\Phi}(r,u) > 0 \quad \text{if } e^u \sqrt{1 + \frac{\ell_0}{r^2}} < 1.$$

In particular, the Schwarzschild metric with mass M solves the reduced Einstein-Vlasov system for all r > 2M such that

$$\sqrt{1 - \frac{2M}{r}}\sqrt{1 + \frac{\ell_0}{r^2}} \ge 1.$$

 $^{^{6}}$ In the small data regime, one expects that the range of parameters leading to trapped geodesics to be close to that of Schwarzschild.

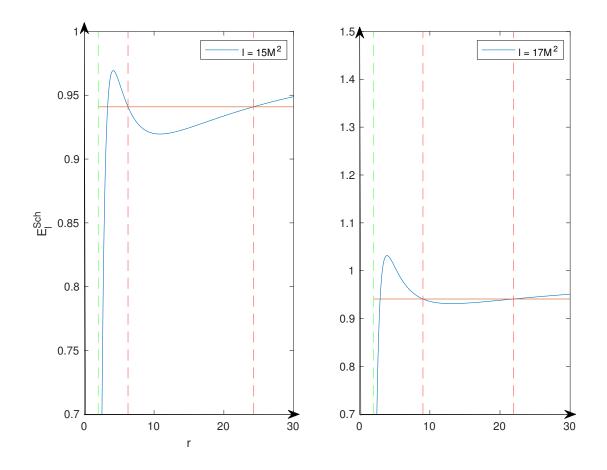


Figure 2: The three roots of the equation $E_{\ell}^{Sch}(r) = E^2$ with E = 0.97 and M = 1 for two cases of ℓ : Left panel $\ell < 16M^2$, which corresponds to the case where $E^{max}(\ell) < 1$. Right panel : $\ell > 16M^2$, where $E^{max}(\ell) > 1$.

This imposes $\ell_0 > 16M^2$ and we have vacuum region when $r \in [r_-, r_+]$, where

$$r_{\pm} := \frac{\ell_0 \pm \sqrt{\ell_0^2 - 16M^2\ell_0}}{4M}.$$

Define

$$\mathcal{A}_{bound}^{Rein} = \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, 1\left[\times \left[\ell_0, \infty\right]\right] \right\}.$$
(2.83)

Note that $\mathcal{A}_{bound}^{Rein}$ is strictly included in \mathcal{A}_{bound} . Indeed, there exists trapped geodesics of the Schwarzschild spacetime such that E < 1 and $\ell < 16M^2$, cf Figure 2.6 and Proposition 1. In contrast, our solutions can be possibly supported on $\left[\sqrt{\frac{8}{9}}, 1\right[\times]12M^2, +\infty[$.

2. Now, one can impose the distribution function to be zero in the region $]2M, r_{-}[$ and extend the metric with a Schwarzschild metric up to 2M. Note that in this context, the ansatz on f is no longer valid for r > 2M so that the distribution function is not purely a function of E and ℓ . This is related to our cut-off function χ_{η} . In fact, we recall from Proposition 1 that for a particle with

 $(E, \ell) \in \mathcal{A}_{bound}$, two orbits are possible. The cut-off function selects only the trapped ones which are located in the region $r \ge r_1(E, \ell)$, "similar to" the region $r \ge r_+$ in Rein's work.

• Next, one can impose initial data at $r_0 := r_+$ to be

$$\mu_0 := \sqrt{1 - \frac{2M}{r_0}}, \qquad \lambda_0 := \frac{1}{\sqrt{1 - \frac{2M}{r_0}}}$$

and apply Proposition 2. The solution to the Einstein Vlasov system is then obtained on $[r_0, \infty]$ and extended to the whole domain by gluing it to the Schwarzschild metric at r_0 .

3 Statement of the main result

In this section, we give a more detailed formulation of our result. More precisely, we have

Theorem 2. Let M > 0 and let $\mathcal{O} = \mathbb{R} \times]2M, \infty[\times S^2$ be the domain of outer communications parametrised by the standard Schwarzschild coordinates (t, r, θ, ϕ) . Let $B_{bound} \subset \subset \mathcal{A}_{bound}$ be a compact subset of the set \mathcal{A}_{bound} defined in the following way:

- Fix $E_1, E_2 \in \left(\sqrt{\frac{8}{9}}, 1\right)$ such that $E_1 < E_2$,
- Let $[\ell_1, \ell_2]$ be any compact subset of $]\ell_{lb}(E_2), \ell_{ub}(E_1)[$, where ℓ_{lb} and ℓ_{ub} are respectively defined by (2.39) and (2.40).
- *Set*

$$B_{bound} := [E_1, E_2] \times [\ell_1, \ell_2]. \tag{3.1}$$

Let $\Phi : \mathcal{A}_{bound} \times \mathbb{R}_+ \to \mathbb{R}_+$ be a C^2 function with respect to the first two variables, C^1 with respect to the third variable and such that

- $\forall \delta \in [0, \infty[, \Phi(\cdot, \cdot; \delta) \text{ is supported in } B_{bound}.$
- $\forall (E,\ell) \in \mathcal{A}_{bound}$, $\Phi(E,\ell;0) = \partial_{\ell} \Phi(E,\ell;0) = 0$, does not identically vanish and $\forall \delta > 0, \Phi(\cdot,\cdot,\delta)$ does not identically vanish on B_{bound} .

Then, there exists $\delta_0 > 0$ and a one-parameter family of functions

$$(\lambda^{\delta}, \mu^{\delta})_{\delta \in [0, \delta_0[} \in (C^2(]2M, \infty[))^2, f^{\delta} \in C^2(\mathcal{O} \times \mathbb{R}^3)$$

with the following properties

- 1. $(\lambda^0, \mu^0) = (\lambda^{Sch}, \mu^{Sch})$ corresponds to a Schwarzschild solution with mass M.
- 2. For all $(E, \ell) \in B_{bound}$, the equation

$$e^{\mu^{\delta}(r)}\left(1+\frac{\ell}{r^2}\right) = E^2$$

admits three distinct positive roots $2M < r_0(\mu^{\delta}, E, \ell) < r_1(\mu^{\delta}, E, \ell) < r_2(\mu^{\delta}, E, \ell)$. Moreover, there exists $\eta > 0$ depending only on δ_0 such that

$$r_0(\mu^{\delta}, E, \ell) + \eta < r_1(\mu^{\delta}, E, \ell)$$

3. The function f^{δ} takes the form

$$f^{\delta}(x,v) = \Phi(E^{\delta},\ell;\delta)\Psi_{\eta}\left(r,(E^{\delta},\ell),\mu^{\delta}\right),\,$$

for $(x, v) \in \mathcal{O} \times \mathbb{R}^3$ with coordinates $(t, r, \theta, \phi, v^r, v^{\theta}, v^{\phi})$ and where

$$E^{\delta} := e^{2\mu^{\delta}(r)} \sqrt{1 + (e^{\lambda^{\delta}(r)} v^{r})^{2} + (rv^{\theta})^{2} + (r\sin\theta v^{\phi})^{2}} \quad , \quad \ell := r^{4} \left((v^{\theta})^{2} + \sin^{2}\theta (v^{\phi})^{2} \right), \tag{3.2}$$

and Ψ_{η} is defined by (2.45)-(2.46).

4. Let g^{δ} be defined by

$$g^{\delta}_{(t,r,\theta,\phi)} = -e^{2\mu^{\delta}(r)}dt^{2} + e^{2\lambda^{\delta}(r)}dr^{2} + r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2}), \qquad (3.3)$$

then $(\mathcal{O}, g_{\delta}, f^{\delta})$ is a static and spherically symmetric solution to the Einstein-Vlasov system (2.1) - (2.6) - (2.8) describing a matter shell orbiting a Schwarzschild like black hole in the following sense:

• $\exists R_{min}^{\delta}, R_{max}^{\delta} \in]2M, \infty[$ called the matter shell radii, which satisfy

$$R_{min}^{\delta} < R_{max}^{\delta}, \quad and \quad R_{min}^{\delta} > 4M$$

• $\forall r \in]2M, R^{\delta}_{min}[\cup]R^{\delta}_{max}, \infty[,$

$$f^{\delta}(x,v) = 0,$$

• $\exists \tilde{r} \in]R^{\delta}_{min}, R^{\delta}_{max}[,$

$$f^{o}(\tilde{r},\cdot) > 0.$$

- The metric g^{δ} is given by the Schwarzschild metric with mass M in the region $]2M, R^{\delta}_{min}[$.
- $\exists M_{\delta} > M$ such that the metric g^{δ} is again given by the Schwarzschild metric with mass M^{δ} in the region $]R^{\delta}_{max}, \infty[$.

4 Solving the reduced Einstein Vlasov system

4.1 Set up for the implicit function theorem

In this section, we define the solution mapping on which we are going to apply the implicit function theorem.

Theorem 3 (Implicit function theorem ⁷). Let \mathcal{B}_1 , \mathcal{B}_2 and X be Banach spaces and G a mapping from an open subset \mathcal{U} of $\mathcal{B}_1 \times X$ into \mathcal{B}_2 . Let (u_0, σ_0) be a point in \mathcal{U} satisfying

- 1. $G[u_0, \sigma_0] = 0$,
- 2. G is continuously Fréchet differentiable on U,
- 3. the partial Fréchet derivative with respect to the first variable $L = G^1_{(u_0,\sigma_0)}$ is invertible.

Then, there exists a neighbourhood \mathcal{N} of σ_0 in X such that the equation $G[u, \sigma] = 0$ is solvable for each $\sigma \in \mathcal{N}$, with solution $u = u_{\sigma} \in \mathcal{B}_1$.

We recall that a mapping $G: \mathcal{U} \subset \mathcal{B}_1 \times X \to \mathcal{B}_2$ is said to be Fréchet differentiable at a point $(u, \sigma) \in \mathcal{U}$ if there exits a continuous linear map $L(u, \sigma): \mathcal{B}_1 \times X \to \mathcal{B}_2$ such that

$$\lim_{||(\delta u,\delta\sigma)||_{\mathcal{B}_1\times X}\to 0} \frac{||G(u+\delta u,\sigma+\delta\sigma)-G(u,\sigma)-L(u,\sigma)\cdot(\delta u,\delta\sigma)||_{\mathcal{B}_2}}{||(\delta u,\delta\sigma)||_{\mathcal{B}_1\times X}} = 0.$$

 $^{^7\}mathrm{See}$ Theorem 17.6 , Ch. 17 of [14] for a proof.

G is Fréchet differentiable if it is Fréchet differentiable at every point $(u, \sigma) \in \mathcal{U}$. It is continuously Fréchet differentiable if the mapping

$$L: \mathcal{U} \to \mathcal{L}(\mathcal{B}_1 \times X, \mathcal{B}_2),$$
$$(u, \sigma) \mapsto L(u, \sigma)$$

is continuous. For every $(u, \sigma) \in \mathcal{U}$ such that G is Fréchet differentiable, the map $L(u, \sigma)$ is called the Fréchet

differential at (u, σ) of G and it is noted $DG_{(u,\sigma)}$. By the partial Fréchet derivatives of G, denoted $G^1_{(u,\sigma)}$, $G^2_{(u,\sigma)}$ at (u, σ) , we mean the bounded linear mappings from \mathcal{B}_1 , X respectively, into \mathcal{B}_2 defined by

$$G^{1}_{(u,\sigma)}(h) := DG_{(u,\sigma)}(h,0) , \ G^{2}_{(u,\sigma)}(k) := DG_{(u,\sigma)}(0,k),$$

for $h \in \mathcal{B}_1, k \in X$.

Solutions to the reduced Einstein-Vlasov system will be obtained by perturbing the Schwarzschild spacetime using a bifurcation parameter $\delta > 0$. The latter turns on in the presence of Vlasov matter supported on $B_{bound} \subset \mathcal{A}_{bound}$. To this end, we transform the problem of finding solutions to the differential equation (2.67) into the problem of finding zeros of an operator G, for which we will apply the implicit function theorem. The Schwarzschild metric and the parameter $\delta = 0$, more precisely $(\mu^{Sch}, 0)$, will be a zero of this operator.

For this, we adjust the ansatz (2.43) to make the dependence on δ explicit:

$$f = \Phi(E,\ell;\delta)\chi_n(r - r_1(\mu, E,\ell)), \qquad (4.1)$$

such that

$$\forall (E,\ell) \in \mathcal{A}_{bound}, \quad \Phi(E,\ell;0) = 0$$

where $\Phi: \mathcal{A}_{bound} \times \mathbb{R}_+ \to \mathbb{R}_+$. We will impose in the following some regularity conditions on Φ so that the solution operator is well defined. Assuming that (λ, μ, f) solve the EV-system, we can apply Lemma 3 with the ansatz (4.1) to obtain

$$e^{-2\lambda(r)} = 1 - \frac{2m(\mu;\delta)(r)}{r},$$
(4.2)

where

$$m(\mu;\delta)(r) := M + 4\pi \int_{2M+\rho}^{r} s^2 G_{\Phi}(s,\mu;\delta) \, ds,$$
(4.3)

$$\mu'(r) = e^{2\lambda(r)} \left(4\pi r H_{\Phi}(r,\mu;\delta) + \frac{1}{r^2} m(\mu;\delta)(r) \right)$$
(4.4)

and

$$\mu(r) = \mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\mu;\delta)(s)}{s}} \left(4\pi s H_{\Phi}(s,\mu;\delta) + \frac{1}{s^2} m(\mu;\delta)(s) \right) \, ds \tag{4.5}$$

where

$$G_{\Phi}(r,\mu;\delta) := \frac{\pi}{r^2} \int_1^{\infty} \int_0^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \frac{\varepsilon^2}{\sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}}} \, d\ell d\varepsilon, \tag{4.6}$$

$$H_{\Phi}(r,\mu;\delta) := \frac{\pi}{r^2} \int_1^{\infty} \int_0^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}} \, d\ell d\varepsilon. \tag{4.7}$$

As we mention before, we will apply Theorem 3 to solve (4.4). Once obtained, we deduce λ and f through (4.30) and (4.1). We define now the function space in which we will obtain the solutions of (4.4). We consider the Banach space

$$\mathcal{X} := \left(C^1(\overline{I}), || \cdot ||_{C^1(\overline{I})} \right), \qquad I =]2M + \rho, R[\tag{4.8}$$

and we recall the definition of the C^1 norm on $C^1(\overline{I})$.

$$\forall g \in C^1(\overline{I}) \quad : \quad ||g||_{C^1(\overline{I})} := ||g||_{\infty} + ||g'||_{\infty}.$$
(4.9)

We define $\mathcal{U}(\tilde{\delta}_0) \subset \mathcal{X} \times [0, \tilde{\delta}_0[$ for some $\tilde{\delta}_0 \in]0, \delta_{max}[$ as

$$\mathcal{U}(\tilde{\delta}_0) := \left\{ (\mu; \delta) \in \mathcal{X} \times [0, \tilde{\delta}_0[: ||\mu - \mu^{Sch}||_{C^1(\overline{I})} < \tilde{\delta}_0 \right\} = B(\mu^{Sch}, \tilde{\delta}_0) \times [0, \tilde{\delta}_0[,$$
(4.10)

where $B(\mu^{Sch}, \tilde{\delta}_0)$ is the open ball in \mathcal{X} of centre μ^{Sch} and radius $\tilde{\delta}_0$ and δ_{max} is defined by

$$\delta_{max} := \min\left\{ \min_{(E,\ell) \in B_{bound}} r_0^{Sch}(E,\ell) - (2M+\rho), R - \max_{(E,\ell) \in B_{bound}} r_2^{Sch}(E,\ell) \right\}$$

 $\tilde{\delta}_0$ will be chosen small enough so that the three roots of the equation (2.50) exist and so that the condition

$$\forall r \in I , \qquad 2m(\mu; \delta)(r) < r \tag{4.11}$$

is satisfied. Besides, we make the following assumptions on Φ :

- $(\Phi_1) \ \forall \delta \in [0, \tilde{\delta}_0[, \ \operatorname{supp} \Phi(\cdot; \delta) \subset B_{bound},$
- $(\Phi_2) \ \Phi \text{ is } C^1 \text{ with respect to } \delta \text{ and } \exists C > 0, \forall (E, \ell) \in B_{bound}, \forall \delta \in [0, \tilde{\delta}_0[, |\Phi(E, \ell; \delta)| \le C, \delta_0]$
- $(\Phi_3) \Phi$ is C^2 with respect to (E, ℓ) .

In view of (4.5), we define the solution operator G corresponding to μ by

$$G: \mathcal{U}(\delta_0) \to \mathcal{X}$$
$$(\tilde{\mu}; \delta) \mapsto G(\tilde{\mu}; \delta)$$

where $\forall r \in \overline{I}$,

$$G(\tilde{\mu};\delta)(r) := \tilde{\mu}(r) - \left(\mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\tilde{\mu};\delta)(s)}{s}} \left(4\pi s H_{\Phi}(s,\tilde{\mu};\delta) + \frac{1}{s^2} m(\tilde{\mu};\delta)(s)\right) \, ds\right). \tag{4.12}$$

We verify the steps allowing to apply Theorem 3. In Subsection 4.2 below, we show that we have a welldefined ansatz for f, that is the existence of a matter shell surrounding the black hole after a well chosen $\tilde{\delta}_0$. In Subsection 4.3, we investigate the regularity of the matter terms and in Subsection 4.4, we check that (2.61) is always satisfied after possibly shrinking $\tilde{\delta}_0$.

4.2 Radii of the matter shell

In this section, we show that for a suitable choice of $\tilde{\delta}_0$, $\forall \mu \in B(\mu^{Sch}, \tilde{\delta}_0)$, there exists $R_{min}(\mu), R_{max}(\mu) \in I$ satisfying $R_{min}(\mu) < R_{max}(\mu)$, such that $\operatorname{supp}_r f \subset [R_{min}(\mu), R_{max}(\mu)]$. We also show that the ansatz for f (2.43) is well defined. More precisely, we state the following result

Proposition 3. Let $0 < \tilde{\delta}_0 < \delta_{max}$. Then, there exists $\delta_0 \in]0, \tilde{\delta}_0]$ such that $\forall \mu \in B(\mu^{Sch}, \delta_0), \forall (E, \ell) \in B_{bound}$, there exist unique $r_i(\mu, (E, \ell)) \in B(r_i^{Sch}(E, \ell), \delta_0)^8, i \in \{0, 1, 2\}$ such that $r_i(\mu, (E, \ell))$ solve the equation

$$e^{2\mu(r)}\left(1+\frac{\ell}{r^2}\right) = E^2.$$
 (4.13)

Moreover, there are no other roots for the above equation outside the balls $B(r_i^{Sch}(E, \ell), \delta_0)$.

Remark 6. A direct application of the implicit function theorem would yield the existence of the three roots but for neighbourhoods of μ^{Sch} which a priori may depend on (E, ℓ) . Thus, we revisit its proof in order to obtain bounds uniform in (E, ℓ) .

$${}^{8}B(r_{i}^{Sch}(E,\ell),\delta_{0}) = \left\{ r \in I : |r - r_{i}^{Sch}(E,\ell)| < \delta_{0} \right\}.$$

Proof. 1. Existence and uniqueness: Let $(E, \ell) \in B_{bound}$. Consider the mapping

$$F^{E,\ell} : B(\mu^{Sch}, \tilde{\delta}_0) \times I \to \mathbb{R}$$

$$(\mu ; r) \mapsto E_{\ell}(r) - E^2 = e^{2\mu(r)} \left(1 + \frac{\ell}{r^2}\right) - E^2.$$

We have

- $F^{E,\ell}$ is continuously Fréchet differentiable on $B(\mu^{Sch}, \tilde{\delta}_0) \times I$. In fact,
 - $\forall \mu \in B(\mu^{Sch}, \tilde{\delta}_0)$, the mapping $r \mapsto F^{E,\ell}(\mu, r)$ is continuously differentiable on I with derivative

$$\frac{\partial F^{E,\ell}}{\partial r}(\mu,r) = 2e^{2\mu(r)} \left(\left(1 + \frac{\ell}{r^2}\right)\mu'(r) - \frac{\ell}{r^3} \right).$$

• It is easy to see that the mapping $\overline{F}^{E,\ell}: \mu \mapsto \overline{F}^{E,\ell}[\mu](r) := F^{E,\ell}(\mu,r)$ is continuously Fréchet differentiable on $B(\mu^{Sch}, \tilde{\delta}_0)$ with Fréchet derivative:

$$\forall \mu \in B(\mu^{Sch}, \tilde{\delta}_0) , \ \forall \tilde{\mu} \in \mathcal{X}, \quad D\overline{F}^{E,\ell}(\mu)[\tilde{\mu}](r) = 2\tilde{\mu}(r)e^{2\mu(r)}\left(1 + \frac{\ell}{r^2}\right)$$

- Since the Fréchet differentials with respect to each variable exist and they are continuous, $F^{E,\ell}$ is continuously Fréchet differentiable on $B(\mu^{Sch}, \tilde{\delta}_0) \times I$.
- The points $(\mu^{Sch}, r_0^{Sch}(E, \ell)), (\mu^{Sch}, r_1^{Sch}(E, \ell))$ and $(\mu^{Sch}, r_2^{Sch}(E, \ell))$ are zeros for $F^{E,\ell}$.
- The differential of $F^{E,\ell}$ with respect to r at these points does not vanish. Otherwise, the trajectory is circular which is not possible since $(E, \ell) \in \mathcal{A}_{bound}$.

We define the following mapping on $I: \forall \mu \in B(\mu^{Sch}, \tilde{\delta}_0),$

$$F^{E,\ell}_{\mu}(r) := r - \phi(E,\ell) F^{E,\ell}(\mu,r),$$

where ϕ is defined by

$$\phi(E,\ell) = \left(\frac{\partial F^{E,\ell}}{\partial r}(\mu^{Sch}, r_i^{Sch}(E,\ell))\right)^{-1}$$

We will show that there exists $0 < \delta_0 < \tilde{\delta}_0$, uniform in (E, ℓ) such that $\forall \mu \in B(\mu^{Sch}, \tilde{\delta}_0), F_{\mu}^{E,\ell}$ is a contraction on $\overline{B}(r_i^{Sch}(E, \ell), \delta_0)$.

Since $F^{E,\ell}$ is differentiable with respect to r, we have

$$\forall r \in I$$
, $\frac{\partial F^{E,\ell}_{\mu}}{\partial r}(r) = 1 - \phi(E,\ell) \frac{\partial F^{E,\ell}}{\partial r}(\mu,r)$

Since the mappings $(E, \ell) \mapsto r_i^{Sch}$ and $(E, \ell) \mapsto F^{E,\ell}(\mu, r)$ depend smoothly on (E, ℓ) and since B_{bound} is compact, there exists C > 0 such that $\forall (E, \ell) \in B_{bound}$

$$|\phi(E,\ell)| \le C.$$

Moreover, there exists $\delta_0 < \tilde{\delta}_0$ such that $\forall (E, \ell) \in B_{bound}$, $\forall (\mu, r) \in B(\mu^{Sch}, \delta_0) \times B(r_i^{Sch}(E, \ell), \delta_0)$,

$$\left|\frac{\partial F^{E,\ell}}{\partial r}(\mu,r) - \frac{\partial F^{E,\ell}}{\partial r}(\mu^{Sch},r_i^{Sch}(E,\ell))\right| \leq \frac{1}{2(C+1)}$$

In fact,

$$\begin{split} &\frac{\partial F^{E,\ell}}{\partial r}(\mu,r) - \frac{\partial F^{E,\ell}}{\partial r}(\mu^{Sch},r_i^{Sch}(E,\ell)) = \\ &2e^{\mu(r)}\left(\left(1+\frac{\ell}{r^2}\right)\mu'(r) - \frac{\ell}{r^3} - \left(1+\frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^2}\right)\mu'(r_i^{Sch}(E,\ell)) + \frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^3}\right) \\ &+ 2\left(\left(1+\frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^2}\right)\mu'(r_i^{Sch}(E,\ell)) - \frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^3}\right)\left(e^{2\mu(r)} - e^{2\mu^{Sch}(r)}\right) \end{split}$$

Since B_{bound} is compact and the different quantities depend continuously on (E, ℓ) , there exists $C_0 > 0$ such that $\forall (E, \ell) \in B_{bound}$,

$$\left| 2 \left(\left(1 + \frac{\ell}{\left(r_i^{Sch}(E,\ell) \right)^2} \right) \mu'(r_i^{Sch}(E,\ell)) - \frac{\ell}{\left(r_i^{Sch}(E,\ell) \right)^3} \right) \left(e^{2\mu(r)} - e^{2\mu^{Sch}(r)} \right) \right| \le C_0 \left| e^{2\mu(r)} - e^{2\mu^{Sch}(r)} \right| \le C_0 C_1 \tilde{\delta}_0.$$

Similarly, we have

$$\left|\frac{\ell}{r^3} - \frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^3}\right| = \ell \left|\frac{r^2 - 2rr_i^{Sch}(E,\ell) + \left(r_i^{Sch}(E,\ell)\right)^2}{r^3 r_i^{Sch}(E,\ell)^3}\right| \left|r - r_i^{Sch}(E,\ell)\right| \le C_0 \tilde{\delta}_0$$

and

$$\left| \left(1 + \frac{\ell}{r^2} \right) \mu'(r) - \left(1 + \frac{\ell}{\left(r_i^{Sch}(E,\ell)\right)^2} \right) \mu'(r_i^{Sch}(E,\ell)) \right| \le \left| \left(1 + \frac{\ell}{r^2} \right) \left(\mu'(r) - \mu'(r_i^{Sch}(E,\ell)) \right| + \left| \ell \mu'(r_i^{Sch}(E,\ell) \left(\frac{1}{r^2} - \frac{1}{\left(r_i^{Sch}(E,\ell)\right)^2} \right) \right| \le C_0 \tilde{\delta}_0.$$

Moreover, $r \mapsto e^{2\mu(r)}$ is bounded on *I*. Therefore, we choose δ_0 so that

$$\left.\frac{\partial F^{E,\ell}}{\partial r}(\mu,r)-\frac{\partial F^{E,\ell}}{\partial r}(\mu^{Sch},r_i^{Sch})\right|\leq \frac{1}{2(C+1)}$$

Hence, we obtain

$$\left|\frac{\partial F^{E,\ell}_{\mu}}{\partial r}(r) - \frac{\partial F^{E,\ell}_{\mu^{Sch}}}{\partial r}(r^{Sch}_i)\right| \le \frac{C}{2(C+1)} \le \frac{1}{2}.$$

Since $\frac{\partial F^{E,\ell}_{\mu^{Sch}}}{\partial r}(r^{Sch}_i(E,\ell)) = 0$, we get

$$\left|\frac{\partial F_{\mu}^{E,\ell}}{\partial r}(r)\right| \le \frac{1}{2}.$$

Now, we show that

$$\forall r \in B(r_i^{Sch}(E,\ell),\delta_0) , \quad \left| F_{\mu}^{E,\ell}(r) - r_i^{Sch}(E,\ell) \right| \le \delta_0$$

We have $\forall (E, \ell) \in B_{bound}, \forall r \in B(r_i^{Sch}(E, \ell), \delta_0)$

$$\begin{split} F^{E,\ell}_{\mu}(r) - r^{Sch}_{i}(E,\ell) &= F^{E,\ell}_{\mu}(r) - F_{\mu^{Sch}}r^{Sch}_{i} \\ &= F^{E,\ell}_{\mu}(r) - F_{\mu}(r^{Sch}_{i}(E,\ell)) + F^{E,\ell}_{\mu}(r^{Sch}_{i}(E,\ell)) - F_{\mu^{Sch}}(r^{Sch}_{i}(E,\ell)). \end{split}$$

By the mean value theorem,

$$\left|F_{\mu}^{E,\ell}(r) - F_{\mu}(r_{i}^{Sch}(E,\ell))\right| \leq \frac{1}{2}|r - r_{i}^{Sch}(E,\ell)| \leq \frac{\delta_{0}}{2}$$

Moreover, by the same argument above, we show that there exists C > 0 independent from (E, ℓ) such that

$$\left|F_{\mu}^{E,\ell}(r_i^{Sch}) - F_{\mu^{Sch}}(r_i^{Sch}(E,\ell))\right| \le C\delta_0.$$

Therefore, we can update δ_0 so that

$$\left|F_{\mu}^{E,\ell}(r) - r_i^{Sch}\right| \le \delta_0.$$

It remains to show that $F^{E,\ell}_{\mu}$ is a contraction on $\overline{B}(r^{Sch}_i(E,\ell),\delta_0), \ \forall \mu \in B(\mu^{Sch},\delta_0)$. For this, we have by the mean value theorem,

$$\left|F_{\mu}^{E,\ell}(r_1) - F_{\mu}^{E,\ell}(r_2)\right| \le \frac{1}{2}|r_1 - r_2|, \quad \forall r_1, r_2 \in B(r_i^{Sch}(E,\ell), \delta_0).$$

Thus, we can apply the fixed point theorem to obtain : there exists $\delta_0 < \tilde{\delta}_0$ such that

$$\forall (E,\ell) \in B_{bound}, \ \forall \mu \in B(\mu^{Sch}, \delta_0) \ \exists ! r_i^{E,\ell} : B(\mu^{Sch}, \delta_0) \to B(r_i^{Sch}(E,\ell), \delta_0) \text{ such that } F^{E,\ell}(\mu, r_i^{E,\ell}(\mu)) = 0$$

2. <u>Regularity</u>: It remains to show that $\forall (E, \ell) \in B_{bound}$, the mapping $r_i^{(E,\ell)}$ is continuously Fréchet differentiable on $B(\mu^{Sch}, \delta_0)$. In order to lighten the expressions, we will not write the dependence of r_i on (E, ℓ) .

First, we show that r_i is Lipschitz. For this, let $\mu, \overline{\mu} \in B(\mu^{Sch}, \delta_0)$ and set

$$r = r_i(\mu), \qquad \overline{r} = r_i(\overline{\mu}).$$

We have

$$\begin{aligned} r - \overline{r} &= r_i(\mu) - r_i(\overline{\mu}) \\ &= F_\mu(r) - F_{\overline{\mu}}(\overline{r}) \\ &= F_\mu(r) - F_\mu(\overline{r}) + F_\mu(\overline{r}) - F_{\overline{\mu}}(\overline{r}) \\ &= F_\mu(r) - F_\mu(\overline{r}) + \phi(E,\ell) \left(F^{E,\ell}(\mu,\overline{r}) - F^{E,\ell}(\overline{\mu},\overline{r}) \right) \end{aligned}$$

We have

$$|F_{\mu}(r) - F_{\mu}(\overline{r})| \le \frac{1}{2} |r - \overline{r}|$$

and

$$\left|\phi(E,\ell)\left(F^{E,\ell}(\mu,\overline{r}) - F^{E,\ell}(\overline{\mu},\overline{r})\right)\right| \le C \left||\mu - \overline{\mu}|\right|_{\mathcal{X}}$$

Therefore,

$$|r - \overline{r}| \le 2C \, ||\mu - \overline{\mu}||_{\mathcal{X}} \, .$$

Thus, r_i is Lipschitz, so continuous on $B(\mu^{Sch}, \delta_0)$. Since

$$\begin{aligned} \forall r \in B(r_i^{Sch}, \delta_0), \quad \left| \frac{\partial F_{\mu}^{E,\ell}}{\partial r}(r) \right| &\leq \frac{1}{2}, \\ \sum \left(\frac{\partial F_{\mu}^{E,\ell}}{\partial r}(r) \right)^k \text{ converges to } \left(1 - \frac{\partial F_{\mu}^{E,\ell}}{\partial r}(r) \right)^{-1} &= \frac{1}{\phi(E,\ell)} \frac{\partial F^{E,\ell}}{\partial r}. \text{ Hence,} \\ \forall r \in B(r_i^{Sch}, \delta_0), \forall \mu \in B(\mu^{Sch}, \delta_0), \quad \frac{\partial F^{E,\ell}}{\partial r}(r, \mu) \neq 0. \end{aligned}$$

Since $F^{E,\ell}$ is differentiable at $(\overline{\mu}, \overline{r})$, we have

$$0 = F^{E,\ell}(\mu,r) - F^{E,\ell}(\overline{\mu},\overline{r}) = D_{\mu}F^{E,\ell}(\overline{\mu},\overline{r}) \cdot (\mu - \overline{\mu}) + \partial_{r}F^{E,\ell}(\overline{\mu},\overline{r})(r - \overline{r}) + o\left(||\mu - \overline{\mu}||_{\mathcal{X}} + |r - \overline{r}|\right)$$

0.

By the above estimates we have

$$o(|r - \overline{r}|) = o(||\mu - \overline{\mu}||_{\mathcal{X}}).$$

Therefore,

$$r - \overline{r} = -\left(\partial_r F^{E,\ell}(\overline{\mu},\overline{r})\right)^{-1} D_{\mu} F^{E,\ell}(\overline{\mu},\overline{r}) \cdot (\mu - \overline{\mu}) + o(||\mu - \overline{\mu}||)$$

3. Finally, we note that after updating δ_0 , we obtain

$$\left|\left|E_{\ell} - E_{\ell}^{Sch}\right|\right|_{C^{1}(\overline{I})} < \delta_{0}.$$
(4.14)

In fact, $\forall r \in \overline{I}$,

$$E_{\ell}(r) - E_{\ell}^{Sch}(r) = \left(1 + \frac{\ell}{r^2}\right) \left(e^{2\mu}(r) - e^{2\mu^{Sch}}(r)\right)$$

We have

$$\left|e^{2\mu}(r) - e^{2\mu^{Sch}}(r)\right| \le C\delta_0,$$

and $r \mapsto 1 + \frac{\ell}{r^2}$ is bounded. Therefore, we can control $||E_{\ell} - E_{\ell}^{Sch}||_{\infty}$. Now, we compute $\forall r \in I$

$$\begin{aligned} E'_{\ell}(r) - E^{Sch'}_{\ell}(r) &= 2e^{2\mu(r)} \left(\mu'(r) \left(1 + \frac{\ell}{r^2} \right) - \frac{\ell}{r^3} \right) - 2e^{2\mu^{Sch}(r)} \left(\mu^{Sch'}(r) \left(1 + \frac{\ell}{r^2} \right) - \frac{\ell}{r^3} \right) \\ &= -\frac{2\ell}{r^3} \left(e^{2\mu(r)} - e^{2\mu^{Sch}(r)} \right) + 2 \left(1 + \frac{\ell}{r^2} \right) \left(\mu'(r)e^{2\mu(r)} - \mu^{Sch'}(r)e^{2\mu^{Sch}(r)} \right) \end{aligned}$$

We control the last term in the following way

$$\begin{aligned} \left| \mu'(r)e^{2\mu(r)} - \mu^{Sch'}(r)e^{2\mu^{Sch}(r)} \right| &\leq \left| \mu'(r) \left(e^{2\mu(r)} - e^{2\mu^{Sch}(r)} \right) \right| + \left| \left(\mu'(r) - \mu^{Sch'}(r) \right) e^{2\mu^{Sch}(r)} \right| \\ &\leq C\delta_0. \end{aligned}$$

4. Uniqueness of the roots on \overline{I} : We show, after possibly shrinking δ_0 , that $\forall \mu \in B(\mu^{Sch}, \delta_0) \forall (E, \ell) \in \overline{B_{bound}}$, there are no others roots of the equation (4.13). First, we set

$$\forall r \in \overline{I}$$
, $P_{E,\ell}(r) := E_{\ell}(r) - E^2$

and

$$\forall r \in \overline{I} , \quad P_{E,\ell}^{Sch}(r) := E_{\ell}^{Sch}(r) - E^2$$

We claim that for δ_0 sufficiently small, there exists C > 0 such that $\forall (E, \ell) \in B_{bound}, \forall r \in J :=$ $\overline{I} \backslash \bigcup_{i=0,1,2} B(r^{Sch}_i(E,\ell),\delta_0)$ we have

$$\left| P_{E,\ell}^{Sch}(r) \right| > C\delta_0$$

In fact, by the monotonicity properties of $P^{Sch}_{E,\ell},$ it is easy to see that

$$\begin{aligned} \forall (E,\ell) \in B_{bound} \,, \, \forall r \in J \,: \, \left| P_{E,\ell}^{Sch}(r) \right| &\geq \max \left\{ \left| P_{E,\ell}^{Sch}(r_0^{Sch}(E,\ell) - \delta_0) \right| \,, P_{E,\ell}^{Sch}(r_0^{Sch}(E,\ell) + \delta_0) \right. \\ &\, \left. \left. \left. P_{E,\ell}^{Sch}(r_1^{Sch}(E,\ell) - \delta_0) \right| \,, P_{E,\ell}^{Sch}(r_1^{Sch}(E,\ell) + \delta_0) \right. \\ &\left. \left| P_{E,\ell}^{Sch}(r_2^{Sch}(E,\ell) - \delta_0) \right| \,, P_{E,\ell}^{Sch}(r_2^{Sch}(E,\ell) + \delta_0) \right\} . \end{aligned}$$

Now, we show that for all |h| sufficiently small, there exist C(h) > 0 uniform in (E, ℓ) such that

$$|P^{Sch}_{E,\ell}(r^{Sch}_i(E,\ell)+h)| > C(h).$$

We have

$$P_{E,\ell}^{Sch}(r_i^{Sch}(E,\ell)+h) = P_{E,\ell}^{Sch}(r_i^{Sch}(E,\ell)) + h(P_{E,\ell}^{Sch})'(r_i^{Sch}(E,\ell)) + o(h),$$

where o(h) is uniform in (E, ℓ) by continuity of $(P_{E,\ell}^{Sch})^{(k)}$ with respect to (E, ℓ) and compactness of B_{bound} . Moreover, $r_i^{Sch}(E, \ell)$ are simple roots so that $(P_{E,\ell}^{Sch})'(r_i^{Sch}(E, \ell)) \neq 0$ and $(E, \ell) \mapsto (P_{E,\ell}^{Sch})'(r_i^{Sch}(E, \ell))$ is continuous. Hence, for h sufficiently small, we obtain

$$|P_{E,\ell}^{Sch}(r_i^{Sch}(E,\ell)+h)| > |h| \left| (P_{E,\ell}^{Sch})'(r_i^{Sch}(E,\ell)) \right| > C|h|,$$

where C is some constant which uniform in δ_0 and (E, ℓ) . Therefore, we update δ_0 so that

$$\left|P_{E,\ell}^{Sch}(r_i^{Sch}(E,\ell)\pm\delta_0)\right| > C\delta_0.$$

Now, let $\delta_1 < \delta_0$. Then, $\forall \mu \in B(\mu^{Sch}, \delta_1) \subset B(\mu^{Sch}, \delta_0)$, $\forall (E, \ell) \in B_{bound}$, $r_i(\mu, E, \ell)$ is unique in the ball $B(r_i^{Sch}(E, \ell), \delta_0)$. Moreover, $\forall r \in J$, we have

$$P_{E,\ell}(r) = P_{E,\ell}(r) - P_{E,\ell}^{Sch}(r) + P_{E,\ell}^{Sch}(r).$$

By the triangular inequality, the latter implies for $\delta_1 < C\delta_0$ that

$$\forall r \in J, \qquad |P_{E,\ell}(r)| > -\delta_1 + C\delta_0 > 0.$$

Therefore, after updating δ_1 , $P_{E,\ell}$ does not vanish outside the balls $B(r_i^{Sch}(E,\ell),\delta_1)$. This yields the uniqueness.

Lemma 4. $\forall \mu \in B(\mu^{Sch}, \delta_0), r_i(\mu, \cdot)$ have the same monotonicity properties as r_i^{Sch} . More precisely, $\forall (E, \ell) \in B_{bound}$,

- $r_0(\mu, E, \cdot)$ decreases on $]\ell_1, \ell_2[$ and $r_0(\mu, \cdot, \ell)$ increases on $]E_1, E_2[$,
- $r_1(\mu, E, \cdot)$ increases on $|\ell_1, \ell_2|$ and $r_1(\mu, \cdot, \ell)$ decreases on $|E_1, E_2|$,
- $r_2(\mu, E, \cdot)$ decreases on $]\ell_1, \ell_2[$ and $r_2(\mu, \cdot, \ell)$ increases on $]E_1, E_2[$.

The proof of the latter lemma is straightforward.

Therefore, using the above monotonicity properties of $r_1(\mu, \cdot)$ and $r_2(\mu, \cdot)$ one can define the radii of the matter shell in the following way:

$$R_{min}(\mu) := r_1(\mu, E_2, \ell_1) \tag{4.15}$$

and

$$R_{max}(\mu) := r_2(\mu, E_2, \ell_1). \tag{4.16}$$

Since $\forall (E, \ell) \in \mathcal{A}_{bound}, r_1^{Sch}(E, \ell) > 4M$, we can update δ_0 such that

 $\forall (E,\ell) \in B_{bound} , r_1(\mu, E, \ell) > 4M.$

In particular,

$$R_{min}(\mu) > 4M. \tag{4.17}$$

Now, we need to define $\eta > 0$ appearing in the ansatz of f, (2.43). We choose $\eta > 0$ independent of (μ, E, ℓ) such that

 $r_1(\mu, E, \ell) - r_0(\mu, E, \ell) > \eta > 0.$

Lemma 5. There exists $\eta > 0$ independent of μ, E, ℓ such that for all $\mu \in B(\mu^{Sch}, \delta_0)$ and for all $(E, \ell) \in B_{bound}$ we have $r_1(\mu, E, \ell) - r_0(\mu, E, \ell) > \eta > 0$.

Proof. For this, we set

$$h^{Sch}: B_{bound} \to \mathbb{R}$$

 $(E, \ell) \mapsto r_1^{Sch}(E, \ell) - r_0^{Sch}(E, \ell)$

By monotonicity properties of r_i^{Sch} , it is easy to see that $h^{Sch}(\cdot, \ell)$ is decreasing and $h^{Sch}(E, \cdot)$ is increasing. Therefore, one can easily bound h:

$$\forall (E,\ell) \in B_{bound}, \ h^{Sch}(E,\ell) \ge h^{Sch}(E_2,\ell) \ge h^{Sch}(E_2,\ell_1) > 0.$$

Thus, $\exists \eta > 0$ such that $\forall (E, \ell) \in B_{bound}$

$$h^{Sch}(E,\ell) > 2\eta.$$

Now we set

$$h: B(\mu^{Sch}, \delta_0) \times B_{bound} \to \mathbb{R}$$

($\mu; (E, \ell)$) $\mapsto h(\mu, (E, \ell)) := r_1(\mu, E, \ell) - r_0(\mu, E, \ell).$

We have, $\forall \mu \in B(\mu^{Sch}, \delta_0), \forall (E, \ell) \in B_{bound}$

$$h(\mu, E, \ell) = h(\mu, (E, \ell)) - h^{Sch}(E, \ell) + h^{Sch}(E, \ell) > -2\delta_0 + 2\eta.$$

It remains to update δ_0 so that the latter inequality is greater than η .

Now that we have justified the ansatz for f, it remains to check that $\operatorname{supp}_r f \subset [R_{min}(\mu), R_{max}(\mu)]$. To this end, we state the following result

Lemma 6. Let $\mu \in B(\mu^{Sch}, \delta_0)$ and f be a distribution function of the form (2.43). Then

$$supp_r f \subset [R_{min}(\mu), R_{max}(\mu)]$$

Proof. Let $(x^{\mu}, v^{a}) \in \Gamma$ and denote by r its radial component. Let $E(x^{\mu}, v^{a})$ and $\ell(x^{\mu}, v^{a})$ be defined by (2.22) and (2.21). If $r \in \operatorname{supp}_{r} f$, then

$$\Phi(E, \ell) > 0$$
, and $\Psi_{\eta}(r, E, \ell, \mu) > 0$.

Therefore, $(E, \ell) \in B_{bound}$ and

$$\Psi_{\eta}(r, E, \ell, \mu) = \chi_{n}(r - r_{1}(\mu, (E, \ell))) > 0$$

Hence,

$$r \ge r_1(\mu, E, \ell) - \eta > r_0(\mu, E, \ell).$$

The last inequality is due to the definition of η . Now since $(E, \ell) \in B_{bound}$, the equation $E_{\ell}(\tilde{r}) = E^2$ admits three distinct positive roots. Moreover, we have

$$E_{\ell}(r) \le E^2 \tag{4.18}$$

for any geodesic moving in the exterior region. Therefore,

 $r \in [2M + \rho, r_0(\mu, E, \ell)] \cup [r_1(\mu, E, \ell), r_2(\mu, E, \ell)].$

Hence, r must lie in the region $[r_1(\mu, E, \ell), r_2(\mu, E, \ell)]$. By construction of $R_{min}(\mu)$ and $R_{max}(\mu)$, we conclude that

$$r \in [R_{min}(\mu), R_{max}(\mu)].$$

4.3 Regularity of the matter terms

In this section, we show that the matter terms G_{ϕ} and H_{Φ} given by respectively (4.6) and (4.7) are well defined on $I \times \mathcal{U}(\delta_0)$. Then, we investigate their regularity with respect to each variable. Let $(r, \mu; \delta) \in I \times \mathcal{U}(\delta_0)$ and let $\varepsilon \in [1, \infty[$ and $\ell \in [0, r^2(\varepsilon^2 - 1)[$. Note that if $r^2(\varepsilon^2 - 1) < \ell_1$, then $\ell < \ell_1$ and

$$\Phi(e^{\mu(r)}\varepsilon,\ell;\delta) = 0,$$

since $\operatorname{supp}_{\ell} \Phi \subset [\ell_1, \ell_2]$. Therefore,

$$G_{\Phi}(r,\mu;\delta) = \frac{2\pi}{r^2} \int_1^{\infty} \int_0^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \frac{\varepsilon^2}{\sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}}} \, d\ell d\varepsilon,$$
$$= \frac{2\pi}{r^2} \int_{\sqrt{1 + \frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \int_{\ell_1}^{r^2(\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \frac{\varepsilon^2}{\sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}}} \, d\ell d\varepsilon.$$

We make a first change of variable from ℓ to $\tilde{\ell} := \ell - \ell_1$,

$$G_{\Phi}(r,\mu;\delta) = \frac{2\pi}{r^2} \int_{\sqrt{1+\frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \int_{0}^{r^2(\varepsilon^2-1)-\ell_1} \Phi(e^{\mu(r)}\varepsilon,\tilde{\ell}+\ell_1;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\tilde{\ell}+\ell_1),\mu) \frac{\varepsilon^2}{\sqrt{(\varepsilon^2-1-\frac{\ell_1}{r^2})-\frac{\tilde{\ell}}{r^2}}} d\tilde{\ell}d\varepsilon.$$

We make a second change of variable from $\tilde{\ell}$ to $s := \frac{\tilde{\ell}}{r^2(\varepsilon^2 - 1) - \ell_1}$,

$$G_{\Phi}(r,\mu;\delta) = 2\pi \int_{\sqrt{1+\frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \varepsilon^2 \left(\varepsilon^2 - \left(1+\frac{\ell_1}{r^2}\right)\right)^{\frac{1}{2}} g_{\Phi}(r,\mu,e^{\mu(r)}\varepsilon;\delta) d\varepsilon$$

where g_{Φ} is defined by

$$g_{\Phi}(r,\mu,E;\delta) := \int_{0}^{1} \Phi(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1};\delta)\Psi_{\eta}(r,E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1}),\mu)\frac{ds}{\sqrt{1-s}}$$
(4.19)

We make a last change of variable from ε to $E := e^{\mu(r)} \varepsilon$ to obtain

$$G_{\Phi}(r,\mu;\delta) = 2\pi e^{-4\mu(r)} \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_1}{r^2}}}^{E_2} E^2 \left(E^2 - e^{2\mu(r)}\left(1+\frac{\ell_1}{r^2}\right)\right)^{\frac{1}{2}} g_{\Phi}(r,\mu,E;\delta) dE.$$
(4.20)

With the same change of variables we compute

$$\begin{split} H_{\Phi}(r,\mu;\delta) &= \frac{2\pi}{r^2} \int_{1}^{\infty} \int_{0}^{r^2 (\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}} \, d\ell d\varepsilon \\ &= \frac{2\pi}{r^2} \int_{\sqrt{1 + \frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \int_{\ell_1}^{r^2 (\varepsilon^2 - 1)} \Phi(e^{\mu(r)}\varepsilon,\ell;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\ell),\mu) \sqrt{\varepsilon^2 - 1 - \frac{\ell}{r^2}} \, d\ell d\varepsilon \\ &= \frac{2\pi}{r^2} \int_{\sqrt{1 + \frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \int_{0}^{r^2 (\varepsilon^2 - 1) - \ell_1} \Phi(e^{\mu(r)}\varepsilon,\tilde{\ell} + \ell_1;\delta) \Psi_{\eta}(r,(e^{\mu(r)}\varepsilon,\tilde{\ell} + \ell_1),\mu) \sqrt{\left(\varepsilon^2 - 1 - \frac{\ell_1}{r^2}\right) - \frac{\tilde{\ell}}{r^2}} \, d\tilde{\ell} d\varepsilon \\ &= 2\pi \int_{\sqrt{1 + \frac{\ell_1}{r^2}}}^{e^{-\mu(r)}E_2} \left(\left(\varepsilon^2 - \left(1 + \frac{\ell_1}{r^2}\right)\right)^{\frac{3}{2}} h_{\Phi}(r,\mu,e^{\mu(r)}\varepsilon;\delta) d\varepsilon, \end{split}$$

where h_{Φ} is defined by

$$h_{\Phi}(r,\mu,E;\delta) := \int_{0}^{1} \Phi(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1};\delta)\Psi_{\eta}(r,(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1}),\mu)\sqrt{1-s}\,ds.$$
(4.21)

Therefore,

$$H_{\Phi}(r,\mu;\delta) = 2\pi e^{-4\mu(r)} \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_1}{r^2}}}^{E_2} \left(E^2 - e^{2\mu(r)}\left(1+\frac{\ell_1}{r^2}\right)\right)^{\frac{3}{2}} h_{\Phi}(r,\mu,E;\delta) \, dE.$$
(4.22)

It is clear that h_{ϕ} is well defined on $I \times C^1 \times \mathcal{U}(\delta_0)$. Since $s \mapsto \frac{1}{\sqrt{1-s}}$ is integrable, g_{ϕ} is well defined on $I \times C^1 \times \mathcal{U}(\delta_0)$. Now we state a regularity result of G_{Φ} and H_{Φ} .

- **Proposition 4.** 1. g_{Φ} and h_{Φ} defined respectively by (4.19) and (4.21) are C^2 with respect to r and E respectively on I, $]E_1, E_2[$ and C^1 with respect to δ on $[0, \delta_0[$. Furthermore, they are continuously Fréchet differentiable with respect to μ on $B(\mu^{Sch}, \delta_0)$.
 - 2. Similarly, G_{Φ} and H_{Φ} are continuously Fréchet differentiable with respect to μ on $B(\mu^{Sch}, \delta_0)$, C^2 with respect to r and C^1 with respect to δ .

Proof. The proof is based on the regularity of the ansatz function as well as on the regularity of r_1 .

- 1. By the dominated convergence theorem, regularity of Φ , its compact support and the assumption (Φ_2) , it is easy to see that g_{Φ} and h_{Φ} are C^2 with respect to r and E on their domain and C^1 with respect to δ .
 - For the differentiability of g_{Φ} and h_{Φ} with respect to μ : let $(r, E, \delta) \in I \times]E_1, E_2[\times [0, \delta]]$ and let $\mu \in B(\mu^{Sch}, \delta_0)$, we have

$$g_{\Phi}(r,\mu,E;\delta) = \int_{0}^{1} \Phi(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1};\delta)\Psi_{\eta}(r,(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1}),\mu)\frac{ds}{\sqrt{1-s}} = \int_{0}^{1} \Phi(E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1};\delta)\chi_{\eta}(r-r_{1}(\mu,E,sr^{2}(e^{-2\mu(r)}E^{2}-1) + (1-s)\ell_{1}))\frac{ds}{\sqrt{1-s}}.$$

Since r_1 is continuously Fréchet differentiable on $B(\mu^{Sch}, \delta_0)$, χ_{η} is smooth on \mathbb{R} and $\Phi(\cdot, \cdot; \delta)$ is C^2 on B_{bound} , the mappings

$$\phi: \mu \mapsto \Phi(E, sr^2(e^{-2\mu(r)}E^2 - 1) + (1 - s)\ell_1; \delta) =: \overline{\Phi}(s, \mu)$$

and

$$\psi: \mu \mapsto \chi_{\eta}(r - r_1(\mu, E, sr^2(e^{-2\mu(r)}E^2 - 1) + (1 - s)\ell_1))$$

are continuously Fréchet differentiable on $B(\mu^{Sch}, \delta_0)$. Their Fréchet derivatives are respectively given by : $\forall \tilde{\mu} \in \mathcal{X}$,

$$D\phi(\mu)[\tilde{\mu}] = -2sr^2 E^2 \tilde{\mu}(r)\partial_\ell \Phi(E, sr^2(e^{-2\mu(r)}E^2 - 1) + (1 - s)\ell_1; \delta)e^{-2\mu(r)}$$

and

$$D\psi(\mu)[\tilde{\mu}] = -\left(D_{\mu}\overline{r}_{1}(s,\mu)[\tilde{\mu}] - 2sr^{2}E^{2}\tilde{\mu}(r)\partial_{\ell}\overline{r}_{1}(s,\mu)e^{-2\mu(r)}\right)\chi_{\eta}'(r-\overline{r}_{1}(s,\mu))$$

where

$$\overline{r}_1(s,\mu) := r_1(\mu, e^{\mu(r)}\varepsilon, sr^2(e^{-2\mu(r)}E^2 - 1) + (1-s)\ell_1)$$

Since χ_n is either 0 or 1 on the support of $\Phi(E, \ell; \delta)$, we have

$$D\psi(\mu)[\tilde{\mu}] = 0.$$

Therefore, for all $\tilde{\mu} \in \mathcal{X}$ sufficiently small,

$$\begin{split} g_{\Phi}(r,\mu+\tilde{\mu};\delta)(r) &= \int_{0}^{1} \overline{\Phi}(s,\mu+\tilde{\mu})\psi(\mu+\tilde{\mu})(s) \, ds \\ &= \int_{0}^{1} \left(\phi(\mu)(s) + D\phi(\mu)[\tilde{\mu}](s) + O\left(||\tilde{\mu}||^{2}_{C^{1}(\overline{I})}\right) \right) \left(\psi(\mu)(s) + O\left(||\tilde{\mu}||^{2}_{C^{1}(\overline{I})}\right) \right) \, ds \\ &= \int_{0}^{1} \overline{\Phi}(s)\psi(\mu)(s) + \psi(\mu)(s)D\phi(\mu)[\tilde{\mu}](s) + O\left(||\tilde{\mu}||^{2}_{C^{1}(\overline{I})}\right) \, ds \\ &= g_{\Phi}(\mu)(r) + \int_{0}^{1} \psi(\mu)(s)D\phi(\mu)[\tilde{\mu}](s) \frac{ds}{\sqrt{1-s}} + O\left(||\tilde{\mu}||^{2}_{C^{1}(\overline{I})}\right) \, ds \end{split}$$

Note that we didn't write the dependence of ϕ, ψ and g_{Φ} on the remaining variables in order to lighten the expressions. Now we define

$$Dg_{\Phi}(\mu)[\tilde{\mu}](r) := -\int_0^1 \psi(\mu)(s) D\phi(\mu)[\tilde{\mu}](s) \frac{ds}{\sqrt{1-s}}$$

It is clear that $Dg_{\Phi}(\mu)$ is a linear mapping from \mathcal{X} to \mathbb{R} . Besides, since r_1 is continuously Fréchet differentiable on $B(\mu^{Sch}, \delta_0)$, g_{Φ} is also continuously Fréchet differentiable.

- In the same way, we obtain regularity for h_{Φ} .
- 2. Regularity for G_{Φ} and H_{Φ} are straightforward. In particular, their Fréchet derivatives with respect to μ are respectively given by $\forall \tilde{\mu} \in \mathcal{X}$

$$D_{\mu}G_{\Phi}(r,\mu;\delta)[\tilde{\mu}] = 2\pi e^{-4\mu(r)} \left(-4\tilde{\mu}(r) \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_{1}}{r^{2}}}}^{E_{2}} E^{2} \left(E^{2} - e^{2\mu(r)} \left(1+\frac{\ell_{1}}{r^{2}}\right) \right)^{\frac{1}{2}} g_{\Phi}(r,\mu,E;\delta) dE + \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_{1}}{r^{2}}}}^{E_{2}} -\frac{E^{2}\tilde{\mu}(r)e^{2\mu(r)} \left(1+\frac{\ell_{1}}{r^{2}}\right)}{\sqrt{E^{2} - e^{2\mu(r)} \left(1+\frac{\ell_{1}}{r^{2}}\right)}} g_{\Phi}(r,\mu;\delta) + E^{2} \left(E^{2} - e^{2\mu(r)} \left(1+\frac{\ell_{1}}{r^{2}}\right) \right)^{\frac{1}{2}} D_{\mu}g_{\Phi}(r,\mu,E;\delta)[\tilde{\mu}] dE \right)$$

$$(4.23)$$

and

$$D_{\mu}H_{\Phi}(r,\mu;\delta)[\tilde{\mu}] = 2\pi e^{-4\mu(r)} \left(-4\tilde{\mu}(r) \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_{1}}{r^{2}}}}^{E_{2}} E^{2} \left(E^{2} - e^{2\mu(r)} \left(1 + \frac{\ell_{1}}{r^{2}} \right) \right)^{\frac{3}{2}} h_{\Phi}(r,\mu,E;\delta) dE + \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_{1}}{r^{2}}}}^{E_{2}} -3E^{2}\tilde{\mu}(r)e^{2\mu(r)} \left(1 + \frac{\ell_{1}}{r^{2}} \right) \sqrt{E^{2} - e^{2\mu(r)} \left(1 + \frac{\ell_{1}}{r^{2}} \right)} h_{\Phi}(r,\mu,E;\delta) + E^{2} \left(E^{2} - e^{2\mu(r)} \left(1 + \frac{\ell_{1}}{r^{2}} \right) \right)^{\frac{1}{2}} D_{\mu}h_{\Phi}(r,\mu,E;\delta)[\tilde{\mu}]dE \right).$$

$$(4.24)$$

4.4 The condition (2.61) is satisfied

In this section, we show that we can choose δ_0 even smaller so that the condition (2.61) is satisfied. More precisely, we state the following lemma

Lemma 7. There exists $\delta_0 \in [0, \tilde{\delta}_0]$ such that $\forall (\mu; \delta) \in \mathcal{U}(\delta_0), \forall r \in I$

$$2m(\mu;\delta)(r) < r. \tag{4.25}$$

Moreover, there exists C > 0 such that $\forall r \in \overline{I}$,

$$\left(1 - \frac{2m(\mu;\delta)(r)}{r}\right)^{-1} < C.$$

Proof. 1. First, we recall

$$2m(\mu;\delta)(r) := 2M + 8\pi \int_{2M+\rho}^{r} s^2 G_{\Phi}(s,\mu;\delta) \ ds$$

where $G_{\Phi}(s,\mu;\delta)$ is given by

$$G_{\Phi}(r,\mu;\delta) = 2\pi e^{-4\mu(r)} \int_{e^{\mu(r)}\sqrt{1+\frac{\ell_1}{r^2}}}^{E_2} E^2 \left(E^2 - e^{2\mu(r)}\left(1+\frac{\ell_1}{r^2}\right)\right)^{\frac{1}{2}} g_{\Phi}(r,\mu,E;\delta) dE.$$

2. If $2M + \rho < r \leq R_{min}(\mu)$, then

$$2m(\mu;\delta)(r) = 2M < r$$

Hence, the condition (2.61) is always satisfied. Besides, $\forall r \in [2M + \rho, R_{min}(\mu)]$, we have

$$\left(1 - \frac{2m(\mu;\delta)(r)}{r}\right)^{-1} < 1 + \frac{2M}{\rho}.$$

3. Now, let $r \ge R_{min}(\mu)$. We claim that $\exists C > 0$, independent of (μ, δ) such that

$$||r \mapsto 8\pi G_{\Phi}(r,\mu;\delta)||_{C^1(\overline{I})} \le C\delta_0.$$

In fact, for a fixed $r \in I$ we write

$$G_{\Phi}(r,\mu;\delta) = G_{\Phi}(r,\mu^{Sch};0) + D_{\mu}G_{\Phi}(r,\mu^{Sch};0)[\mu-\mu^{Sch}] + \delta\partial_{\delta}G_{\Phi}(r,\mu^{Sch};0) + O\left(||\mu-\mu^{Sch}||^{2}_{C^{1}(\overline{I})} + \delta^{2}\right)$$

= $\delta\partial_{\delta}G_{\Phi}(r,\mu^{Sch};0) + O(\delta_{0}),$

where we used

$$G_{\Phi}(r,\mu^{Sch};0) = D_{\mu}G_{\Phi}(r,\mu^{Sch};0)[\mu-\mu^{Sch}] = 0.$$

Now we have

$$\begin{aligned} \partial_{\delta} G_{\Phi}(r,\mu^{Sch};0) &= \\ 2\pi \left(1 - \frac{2M}{r}\right)^{-2} \int_{\sqrt{\left(1 - \frac{2M}{r}\right)\left(1 + \frac{\ell_1}{r^2}\right)}}^{E_2} E^2 \left(E^2 - \left(1 - \frac{2M}{r}\right)\left(1 + \frac{\ell_1}{r^2}\right)\right)^{\frac{1}{2}} \partial_{\delta} g_{\Phi}(r,\mu^{Sch},E;0) \, dE. \end{aligned}$$

Since $r \in \overline{I}$ and by the the (Φ_2) assumption and the definition of χ_{η} , there exists C > 0 independent of $(r, \mu; \delta)$ such that

$$\forall E \in [E_1, E_2], \forall r \in I \ \left| \partial_{\delta} g_{\Phi}(r, \mu^{Sch}, E; 0) \right| \le C$$

Therefore,

$$\begin{aligned} \left| \partial_{\delta} G_{\Phi}(r, \mu^{Sch}; 0) \right| \\ &\leq 2C\delta\pi \left(1 - \frac{2M}{2M + \rho} \right)^{-2} \int_{\sqrt{\left(1 - \frac{2M}{r}\right)\left(1 + \frac{\ell_1}{r^2}\right)}}^{E_2} E^2 \left(E^2 - \left(1 - \frac{2M}{2M + \rho} \right) \left(1 + \frac{\ell_1}{(2M + \rho)^2} \right) \right)^{\frac{1}{2}} dE + O(\delta_0) \\ &\leq C\delta \int_0^{E_2} E^3 dE + O(\delta_0) \\ &\leq C\delta_0. \end{aligned}$$

This yields the result. We have, by (4.17), $\forall \mu \in B(\mu^{Sch}, \delta_0)$,

$$R_{min}(\mu) > 4M.$$

Therefore,

$$2m(\mu;\delta)(r) \leq \frac{R_{min}(\mu)}{2} + \frac{C\delta_0}{3} \left(r^3 - R_{min}(\mu)^3\right)^2 \\ \leq \frac{R_{min}(\mu)}{2} + \frac{CR^2\delta_0}{3}r \\ \leq \left(\frac{1}{2} + \frac{CR^2\delta_0}{3}\right)r.$$

It remains to update δ_0 so that

$$\frac{1}{2} + \frac{CR^2\delta_0}{3} < 1.$$

We take for example

$$\delta_0 = \min\left(\delta_0, \frac{3}{4CR^2}\right).$$

Therefore, $\forall r \geq R_{min}(\mu)$, we have

$$\left(1 - \frac{2m(\mu;\delta)(r)}{r}\right)^{-1} < 4.$$

This concludes the proof.

4.5 Solving for μ

We check in a number of steps that the mapping G defined by (4.12) satisfies the conditions for applying the implicit function theorem:

- 1. First, we need to check that G is well defined on $\mathcal{U}(\delta_0)$.
- 2. It is clear that $(\mu^{Sch}; 0)$ is a zero for G.
- 3. Next, we need to check that G is continuously Fréchet differentiable on $\mathcal{U}(\delta_0)$.
- 4. Finally, we have to show that the partial Fréchet derivative with respect to the first variable μ at the point (μ^{Sch} ; 0):

$$\mathcal{L}: C^1(\overline{I}) \to C^1(\overline{I})$$
$$\mu \mapsto DG_{(\mu^{Sch};0)}(\mu;0)$$

is invertible.

Provided the above facts hold, we can now apply Theorem 3 to the mapping $G: \mathcal{U} \to \mathcal{X}$ to obtain:

Theorem 4. There exists $\delta_1, \delta_2 \in]0, \delta_0[$ and a unique differentiable solution map

$$\mu: [0, \delta_1[\to B\left(\mu^{Sch}, \delta_2\right) \subset C^1(\overline{I})$$

such that $S(0) = \mu^{Sch}$ and

$$G(\mu(\delta); \delta) = 0, \quad \forall \delta \in [0, \delta_1]$$

The remainder of this section is devoted to the proofs of steps 1 to 4.

4.5.1 G is well defined on \mathcal{U}

Let $(\mu; \delta) \in \mathcal{U}(\delta_0)$. Recall the definition of G

$$G(\mu;\delta)(r) := \mu(r) - \left(\mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\mu;\delta)(s)}{s}} \left(4\pi s H_{\Phi}(s,\mu;\delta) + \frac{1}{s^2} m(\mu;\delta)(s)\right) \, ds\right).$$

By Lemma 7, there exists C > 0 such that

$$\forall r \in I, \ \left(1 - \frac{2m(\mu;\delta)(r)}{r}\right)^{-1} < C.$$

$$(4.26)$$

Besides, $\forall r \in I$,

$$\int_{2M+\rho}^{r} \left(4\pi s H_{\Phi}(s,\mu;\delta) + \frac{1}{s^2} m(\mu;\delta)(s) \right) \frac{ds}{1 - \frac{2m(\mu;\delta)(s)}{s}} \leq \int_{2M+\rho}^{R_{max}(\mu)} \left(4\pi s H_{\Phi}(s,\mu;\delta) + \frac{1}{s^2} m(\mu;\delta)(s) \right) \frac{ds}{1 - \frac{2m(\mu;\delta)(s)}{s}}.$$

The integral of the right hand side is finite. Therefore, $G(\mu; \delta_0)$ is well defined on *I*. Moreover, by Proposition 4 and lemma 7 we have

- $r \mapsto H_{\Phi}(r,\mu;\delta)$ is C^1 on I,
- $r \mapsto m(\mu; \delta)(r)$ is C^1 on I,

Hence, $G(\mu; \delta)$ is well defined and it is C^1 on I. Moreover, it easy to control its C^1 norm thanks to (4.26) and the compact support of $r \mapsto H_{\Phi}(r, \mu; \delta)$ and $r \mapsto G_{\Phi}(r, \mu(r), \mu; \delta)$.

4.5.2 G is continuously Fréchet differentiable on \mathcal{U}

Let $(\mu; \delta) \in \mathcal{U}(\delta_0)$. First, we show the differentiability with respect to μ . In this context, we drop the dependence on δ in order to lighten the expressions. Our first claim is that G has the Fréchet derivative with respect to μ given by $\forall \tilde{\mu} \in C^1(\overline{I}), \forall r \in I$,

$$D^{1}G(\mu)[\tilde{\mu}](r) := \tilde{\mu}(r) - \int_{2M+\rho}^{r} \frac{2}{s} \frac{1}{\left(1 - \frac{2m(\mu)(s)}{s}\right)^{2}} Dm(\mu)[\tilde{\mu}](s) \left(4\pi s H_{\Phi}(s,\mu) + \frac{1}{s^{2}}m(\mu)(s)\right) + \frac{1}{1 - \frac{2m(\mu)(s)}{s}} \left(4\pi s D_{\mu}H_{\Phi}(s,\mu)[\tilde{\mu}] + \frac{1}{s^{2}}Dm(\mu)[\tilde{\mu}](s)\right) ds,$$

$$(4.27)$$

where $Dm(\mu)$ is the Fréchet derivative of m with respect to μ , given by

$$Dm(\mu)[\tilde{\mu}](r) = 4\pi \int_{2M+\rho}^{r} s^2 D_{\mu} G_{\Phi}(s,\mu)[\tilde{\mu}] ds.$$
(4.28)

We need to prove

$$\lim_{\||\tilde{\mu}\||_{C^{1}(\overline{I})} \to 0} \frac{\left| \left| G(\mu + \tilde{\mu}) - G(\mu) - D^{1}G(\mu)[\tilde{\mu}] \right| \right|_{C^{1}(\overline{I})}}{\|\tilde{\mu}\|_{C^{1}(\overline{I})}} = 0.$$

We will only prove in details

$$\lim_{\||\tilde{\mu}\||_{C^{1}(\overline{I})} \to 0} \frac{\|m(\mu + \tilde{\mu}) - m(\mu) - Dm(\mu)[\tilde{\mu}]\|_{C^{1}(\overline{I})}}{\|\tilde{\mu}\|_{C^{1}(\overline{I})}} = 0.$$

The remaining terms are treated in the same way thanks to the estimate (4.26), the compact support in r of the matter terms as well as their regularity. Let $r \in I$. We compute

$$m(\mu + \tilde{\mu})(r) - m(\mu)(r) - Dm(\mu)[\tilde{\mu}](r) = 4\pi \int_{2M+\rho}^{r} s^2 \left(G_{\Phi}(s,\mu + \tilde{\mu}) - G_{\Phi}(s,\mu) - D_{\mu}G_{\Phi}(s,\mu)[\tilde{\mu}]\right) ds.$$

Since G_{Φ} is continuously Fréchet differentiable with respect to μ , we write in a neighbourhood of the point μ with a fixed s

$$G_{\Phi}(s,\mu+\tilde{\mu}) = G_{\Phi}(s,\tilde{\mu}) + D_{\mu}G_{\Phi}(s,\mu)[\tilde{\mu}] + O\left(||\tilde{\mu}||_{C^{1}(\overline{I})}^{2}\right).$$

Therefore,

$$|m(\mu + \tilde{\mu})(r) - m(\mu)(r) - Dm(\mu)[\tilde{\mu}](r)| \lesssim ||\tilde{\mu}||_{C^{1}(\overline{I})}^{2},$$

so that

$$\lim_{\|\tilde{\mu}\|_{C^{1}(\overline{I})} \to 0} \frac{||m(\mu + \tilde{\mu}) - m(\mu) - Dm(\mu)[\tilde{\mu}]||_{\infty}}{||\tilde{\mu}||_{C^{1}(\overline{I})}} = 0$$

It remains to control the C^1 norm of $m(\mu + \tilde{\mu}) - m(\mu) - Dm(\mu)[\tilde{\mu}]$. It is clear that the latter is C^1 on I and the derivative is given by $\forall r \in I$:

$$m(\mu + \tilde{\mu})'(r) - m(\mu)'(r) - Dm(\mu)[\tilde{\mu}]'(r) = 4\pi r^2 \left(G_{\Phi}(r, \mu + \tilde{\mu}) - G_{\Phi}(r, \mu) - D_{\mu}G_{\Phi}(r, \mu)[\tilde{\mu}] \right) \right)$$

= $O\left(||\tilde{\mu}||^2_{C^1(\overline{I})} \right),$

which implies

$$\lim_{\|\tilde{\mu}\|_{C^{1}(\overline{I})} \to 0} \frac{\|m(\mu + \tilde{\mu})' - m(\mu)' - Dm(\mu)[\tilde{\mu}]'\|_{\infty}}{\|\tilde{\mu}\|_{C^{1}(\overline{I})}} = 0$$

To conclude, we show that the Fréchet derivative is continuous on $B(\mu^{Sch}, \delta_0)$. Let $\mu_1, \mu_2 \in B(\mu^{Sch}, \delta_0)$ and let $\tilde{\mu} \in C^1(\overline{I}) ||\tilde{\mu}||_{C^1(\overline{I})} \leq 1$, we compute $\forall r \in I$

$$Dm(\mu_1)(\tilde{\mu})(r) - Dm(\mu_2)(\tilde{\mu})(r) = 4\pi \int_{2M+\rho}^r s^2 \left(D_{\mu}G_{\Phi}(s,\mu_1)[\tilde{\mu}] \right) - D_{\mu}G_{\Phi}(s,\mu_2)[\tilde{\mu}] \right) ds.$$

We use the regularity results of Proposition 4 and the estimate $||\tilde{\mu}||_{C^1(\overline{I})} \leq 1$ to estimate each term by $||\mu_1 - \mu_2||_{C^1(\overline{I})}$. Similarly, we control $||Dm(\mu_1)(\tilde{\mu})' - Dm(\mu_2)(\tilde{\mu})'||_{\infty}$. By taking the supremum on $||\tilde{\mu}||_{C^1(\overline{I})}$, we obtain

$$||Dm(\mu_1) - Dm(\mu_2)||_{\mathcal{L}(C^1(\overline{I}), C^1(\overline{I}))} \lesssim ||\mu_1 - \mu_2||_{C^1(\overline{I})}$$

Finally, when $\mu_1 \to \mu_2$ in $C^1(\overline{I})$ we obtain $Dm(\mu_1) \to Dm(\mu_2)$ in $\mathcal{L}(C^1(\overline{I}), C^1(\overline{I}))$. This proves the continuity.

We check now the differentiability with respect to δ . We claim that

$$D_{\delta}G(\delta)(r) = -\int_{2M+\rho}^{r} \frac{2}{s} \frac{1}{\left(1 - \frac{2m(\mu)(s)}{s}\right)^{2}} m'(\delta)(s) \left(4\pi s H_{\Phi}(s,\delta) + \frac{1}{s^{2}}m(\mu)(s)\right) + \frac{1}{1 - \frac{2m(\mu)(s)}{s}} \left(4\pi s \partial_{\delta} H_{\Phi}(s;\delta) + \frac{1}{s^{2}}m'(\delta)(s)\right) ds,$$

$$(4.29)$$

where

$$m'(\delta)(s) = 4\pi \int_{2M+\rho}^{r} s^2 \partial_{\delta} G_{\Phi}(s,\mu;\delta) \, ds,$$

and

$$\partial_{\delta} H_{\Phi}(s; \delta) = \partial_{\delta} H_{\Phi}(s, \mu; \delta).$$

Again, we dropped the dependance on μ in order to lighten the expressions. By regularity assumptions on Φ with respect to the third variable, the compact support of the matter terms and by the dominated convergence theorem, G is C^1 with respect to the parameter δ .

We check the third step: we evaluate the derivative of G with respect to μ at the point $(\mu^{Sch}, 0)$. For this we use Proposition 4 and the fact that $\Phi(\cdot, \cdot; 0) = \partial_{\ell} \Phi(\cdot, \cdot; 0) = 0$ to obtain

$$D_{\mu}G_{\Phi}(s,\mu^{Sch};0) = D_{\mu}H_{\Phi}(s,\mu^{Sch};0) = 0.$$

Therefore, $D_{\mu}G(\mu^{Sch}; 0)$ is reduced to the identity, which is invertible. Since all the assumptions are satisfied, we apply Theorem 3 to obtain Theorem 4.

4.6 Conclusions

In this section, we deduce from Theorem 4 the remaining metric component and the expression of the matter terms. More precisely, we set $\forall \delta \in [0, \delta_1]$

$$\lambda^{\delta}(r) := -\frac{1}{2} \log \left(1 - \frac{2m(\mu(\delta); \delta)}{r} \right), \quad \forall r \in I.$$
(4.30)

 λ^{δ} is well defined since

 $\forall r \in I, \qquad r > 2m(\mu(\delta);\delta).$

As for the matter field, we set $\forall (x^{\alpha}, v^{a}) \in \mathcal{O} \times \mathbb{R}^{3}$

$$f^{\delta}(x^{\alpha}, v^{a}) := \Phi(E_{\delta}, \ell; \delta) \Psi_{\eta} \left(r - r_{1}(\mu(\delta), E^{\delta}, \ell) \right), \qquad (4.31)$$

where

$$E^{\delta} = e^{2\mu_{\delta}(r)}\sqrt{1 + (e^{\lambda^{\delta}(r)}v^{r})^{2} + (rv^{\theta})^{2} + (r\sin\theta v^{\phi})^{2}}$$

and ℓ is given by (2.21).

Such f^{δ} is a solution to the Vlasov equation (2.2) since Φ is a solution and Ψ_{η} is constant on the support of Φ . Furthermore, we set the *energy density* to be

$$\rho_{\delta}(r) := G_{\Phi}(r, \mu(\delta); \delta), \tag{4.32}$$

We define the radii of the matter shell to be

$$R_{\min}^{\delta} := R_{\min}(\mu(\delta)) \tag{4.33}$$

and

$$R_{max}^{\delta} := R_{max}(\mu(\delta)), \tag{4.34}$$

where R_{min} and R_{max} are defined by (4.15) and (4.16). Finally, we define the total mass by

$$M^{\delta} := M + 4\pi \int_{R^{\delta}_{min}}^{R^{\delta}_{max}} r^2 \rho_{\delta}(r) \, dr.$$
(4.35)

It is easy to see that $\mu(\delta)$ and λ^{δ} are actually C^2 on *I*. In fact, since $\mu(\delta)$ is C^1 on *I*, $m(\mu(\delta); \delta)$ given by (4.3) is C^2 on *I* and $r \mapsto H(r, \mu(\delta); \delta)$ is C^1 on *I* by Proposition 4. Moreover,

$$G(\mu(\delta);\delta) = 0$$

That is $\mu(\delta)$ is implicitly given by

$$\mu(\delta)(r) = \left(\mu_0 + \int_{2M+\rho}^r \frac{1}{1 - \frac{2m(\mu(\delta);\delta)(s)}{s}} \left(4\pi s H_{\Phi}(s,\mu(\delta);\delta) + \frac{1}{s^2} m(\mu(\delta);\delta)(s)\right) \, ds\right).$$

From the above equation it is clear that $\mu(\delta)$ is C^2 on I. Therefore, λ^{δ} is also C^2 on I and f^{δ} is also C^2 with respect to r.

It remains to extend the solution on $]2M, \infty[$. It suffices to extend (μ, λ) by $(\mu^{Sch}, \lambda^{Sch})$ of mass M on the domain $]2M, 2M + \rho]$, and by $(\mu^{Sch}, \lambda^{Sch})$ of mass M^{δ} on the domain $[R, \infty[$. We recall that the matter field vanishes in these regions thanks to its compact support. Thus, (μ, λ) are still C^2 on $]2M, \infty[$. This ends the proof of Theorem 2.

A Study of the geodesic motion in the exterior of Scwharzschild spacetime

We present a detailed study of the geodesic motion in the exterior region of a fixed Schwarzschild spacetime. We will classify the geodesics based on the study of the effective energy potential. Such a classification is of course classical and we refer to [8, Chapter 3] or [21, Chapter 33] for more details. In this section, we prove Proposition 1.

• First, note that E_{ℓ}^{Sch} is a cubic function in $\frac{1}{r}$. Its derivative is given by

$$\forall r > 2M , \quad E_{\ell}^{Sch'}(r) = \frac{2}{r^4} \left(Mr^2 - \ell r + 3M\ell \right).$$

Three cases are possible :

1. $E_{\ell}^{Sch'}$ has two distinct roots $r_{max}^{Sch} < r_{min}^{Sch}$, where r_{max}^{Sch} and r_{min}^{Sch} correspond respectively to the maximiser and the minimiser of E_{ℓ}^{Sch} . They are given by

$$r_{max}^{Sch}(\ell) = \frac{\ell}{2M} \left(1 - \sqrt{1 - \frac{12M^2}{\ell}} \right),$$
$$r_{min}^{Sch}(\ell) = \frac{\ell}{2M} \left(1 + \sqrt{1 - \frac{12M^2}{\ell}} \right).$$

The extremums of E_{ℓ}^{Sch} are given by

$$E^{min}(\ell) = E_{\ell}^{Sch}(r_{min}^{Sch}) = \frac{8}{9} + \frac{\ell - 12M^2}{9Mr_{min}^{Sch}(\ell)},\tag{A.1}$$

$$E^{max}(\ell) = E_{\ell}^{Sch}(r_{max}^{Sch}) = \frac{8}{9} + \frac{\ell - 12M^2}{9Mr_{max}^{Sch}(\ell)}.$$
 (A.2)

In fact, we compute

$$1 - \frac{2M}{r_{\min}^{Sch}(\ell)} = 1 - \frac{4M^2}{\ell \left(1 - \sqrt{1 - \frac{12M^2}{\ell}}\right)} = \frac{2}{3} - \frac{1}{3}\sqrt{1 - \frac{12M^2}{\ell}}$$

and

$$1 + \frac{\ell}{r_{\min}^{Sch}(\ell)^2} = 1 + \frac{\ell}{36M^2} \left(1 + \sqrt{1 - \frac{12M^2}{\ell}}\right)^2.$$

Therefore,

$$\begin{split} E_{\ell}^{Sch}(r_{min}^{Sch}(\ell)) &= \left(1 - \frac{2M}{r_{min}^{Sch}(\ell)}\right) \left(1 + \frac{\ell}{r_{min}^{Sch}(\ell)^2}\right) \\ &= \left(\frac{2}{3} + \frac{\ell}{18M^2} + \frac{\ell}{18M^2}\sqrt{1 - \frac{12M^2}{\ell}}\right) \left(\frac{2}{3} - \frac{1}{3}\sqrt{1 - \frac{12M^2}{\ell}}\right) \\ &= \frac{8}{9} + \frac{\ell - 12M^2}{9Mr_{min}^{Sch}(\ell)}, \end{split}$$

where the last expression is obtained by straightforward computations. We do the same thing for $E^{max}(\ell)$. This case occurs if and only if $\ell > 12M^2$.

2. $E_{\ell}^{Sch'}$ has one double root at $r_c = 6M$. The extremum of E_{ℓ}^{Sch} is given by

$$E_{\ell}^c = \frac{8}{9}.$$

This case occur if and only if $\ell = 12M^2$.

3. $E_{\ell}^{Sch'}$ has no real roots. Then, E_{ℓ}^{Sch} is monotonically increasing from 0 to $+\infty$. This case occurs if and only if $\ell < 12M^2$.

We refer to Figure 1 in the introduction for the shape of the potential energy in the three cases.

• Note that by the mass shell condition (2.27), we have

$$E^2 \ge E_\ell^{Sch}(r)$$

for any timelike geodesic moving in the exterior region. In particular,

$$E^2 \ge E^{min}(\ell) \ge \frac{8}{9}.$$

Therefore, we obtain a lower bound on E:

$$E \ge \sqrt{\frac{8}{9}}.$$

• Now, we claim that the trajectory is a circle of radius $r_0^{Sch} > 2M$ if and only if

$$E_{\ell}^{Sch}(r_0^{Sch}) = E^2 \quad \text{and} \quad E_{\ell}^{Sch'}(r_0^{Sch}) = 0.$$
 (A.3)

Indeed, if the motion is circular of radius r_0^{Sch} , then $\forall \tau \in \mathbb{R} : r(\tau) = r_0^{Sch}$. Thus,

 $\forall \tau \in \mathbb{R}$, $w(\tau) = \dot{r}(\tau) = 0$ and $\dot{w}(\tau) = 0$.

Besides, it is a solution to the system (2.35)-(2.36). Therefore

$$\forall \tau \in \mathbb{R} , \ E_{\ell}^{Sch'}(r_0^{Sch}) = E_{\ell}^{Sch'}(r(\tau)) = 0.$$

By (2.27), we have

$$\forall \tau \in \mathbb{R} , w(\tau)^2 + E_{\ell}^{Sch}(r(\tau)) = E^2$$

In particular,

$$E_{\ell}^{Sch}(r_0^{Sch}) = E^2.$$

Now, let us suppose that there exists $r_0^{Sch} > 2M$ such that

$$E_{\ell}^{Sch}(r_0^{Sch}) = E^2$$
 and $E_{\ell}^{Sch'}(r_0^{Sch}) = 0.$

By the above assumption, we have w = 0 and $E_{\ell}^{Sch'}(r_0^{Sch}) = 0$ so that the point $(r_0^{Sch}, 0)$ is a stationary point $\forall \ell \geq 12M^2$. Furthermore,

- $$\begin{split} 1. \ r_0^{Sch} &= 6, \, \text{if} \, \ell = 12M^2, \\ 2. \ r_0^{Sch} &\in \left\{ r_{min}^{Sch}(\ell), r_{max}^{Sch}(\ell) \right\}, \, \text{if} \, \ell > 12M^2. \end{split}$$

The circular orbits are thus characterised by (A.3).

• We consider now the case $\ell > 12M^2$ and the equation

$$E^2 = E_\ell^{Sch}(r). \tag{A.4}$$

Let $(\ell, E) \in \left] 12M^2, \infty \right[\times \left] \frac{8}{9}, \infty \right[$. Four cases may occur:

1. If $E^2 = E_{\ell}^{min}$ or $E^2 = E_{\ell}^{max}$, then r_{min}^{Sch} or r_{max}^{Sch} satisfy (A.3), so that they are double roots. Besides, we note that $\ell = \ell_{ub}$ where

$$\ell_{ub}(E) := \frac{12M^2}{1 - 4\alpha - 8\alpha^2 - 8\alpha\sqrt{\alpha^2 + \alpha}} \qquad \alpha := \frac{9}{8}E^2 - 1 \tag{A.5}$$

satisfies $E^2 = E_{\ell}^{min}$. In fact, we solve the equation below for ℓ

$$\frac{8}{9} + \frac{\ell - 12M^2}{9\frac{\ell}{2}\left(1 + \sqrt{1 - \frac{12M^2}{\ell}}\right)} = E^2.$$

We make the following change of variables

$$\alpha := \frac{9}{8}E^2 - 1$$
 and $X := \sqrt{\frac{\ell - 12M^2}{\ell}}$

The equation becomes

$$\frac{X^2}{4\left(1+X\right)} = \alpha,$$

which is easily solvable for X. We can then obtain $\ell_{ub}(E)$. Similarly, we obtain ℓ_{lb} defined by

$$\ell_{lb}(E) := \frac{12M^2}{1 - 4\alpha - 8\alpha^2 + 8\alpha\sqrt{\alpha^2 + \alpha}},$$
(A.6)

which solves the equation $E^2 = E_{\ell}^{max}$.

- 2. If $E^2 > E_{\ell}^{max}$, then two cases occur
 - (a) $E^2 < 1$. The equation (A.4) has one simple root $r_2^{Sch}(E, \ell) > r_{min}^{Sch}(\ell)$
 - (b) $E^2 \ge 1$. The equation (A.4) has no positive roots. The trajectories in this case are similar to the trajectories in case 3 (where $\ell < 12M^2$).
- 3. $E^2 \in [E_{\ell}^{min}, E_{\ell}^{max}]$. Again, two cases occur
 - (a) $E^2 < 1$. Then the equation (A.4) admits three simple positive roots $r_i^{Sch}(E, \ell)$

$$r_0^{Sch}(E,\ell) < r_{max}^{Sch}(\ell) < r_1^{Sch}(E,\ell) < r_{min}^{Sch}(\ell) < r_2^{Sch}(E,\ell).$$
(A.7)

(b) $E^2 \ge 1$. The equation (A.4) admits two simple positive roots $r_i^{Sch}(E, \ell)$

$$r_0^{Sch}(E,\ell) < r_{max}^{Sch}(\ell) < r_1^{Sch}(E,\ell) < r_{min}^{Sch}(\ell).$$
(A.8)

- We consider now the case $\ell \leq 12M^2$. Three cases may occur:
 - If E² = ⁸/₉, then the equation (A.4) has one triple positive root r_c = 6M.
 If ⁸/₉ < E² < 1, then the equation (A.4) has one simple positive root r₁^{Sch}(E, ℓ).
 If E² ≥ 1, then the equation (A.4) no positive roots.
- Based on the above cases, we define the following parameters sets

$$\mathcal{A}_{circ} := \left\{ \left(\sqrt{\frac{8}{9}}, 12M^2 \right) \right\} \bigcup \left\{ (E, \ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \left[: E^2 < 1, \quad \ell = \ell_{ub}(E) \right] \right\}$$

$$\bigcup \left\{ (E, \ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \left[: \ell = \ell_{lb}(E) \right] \right\},$$
(A.9)

$$\mathcal{A}_{bound} := \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \right[: E^2 < 1, \quad \ell_{lb}(E) < \ell < \ell_{ub}(E) \right\}, \tag{A.10}$$

$$\mathcal{A}_{unbound} := \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \right[: E^2 \ge 1, \quad \ell > \ell_{lb}(E) \right\},$$
(A.11)

$$\mathcal{A}_{abs} := \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, \infty \right[\times \left] 12M^2, \infty \right[: E^2 < 1, \quad \ell < \ell_{lb}(E) \right\} \bigcup \left\{ (E,\ell) \in \left] \sqrt{\frac{8}{9}}, 1 \right[\times \left] 0, 12M^2 \right[\right\} \\ \bigcup \left\{ E \in \left] \sqrt{\frac{8}{9}}, 1 \right[, \ell = 12M^2 \right\}.$$
(A.12)

• Now, we determine the nature of orbits (circular, bounded, unbounded, "absorbed by the black hole") in terms of the parameters (E, ℓ) as well as the initial position and velocity. Let $\ell \in [0, \infty[, \tilde{r} \in]2M, \infty[$ and $\tilde{w} \in \mathbb{R}$. We compute

$$E = \sqrt{E_{\ell}^{Sch}(\tilde{r}) + \tilde{w}^2}.$$

1. If $(E, \ell) \in \mathcal{A}_{bound}$, then there exists $r_i^{Sch} := r_i^{Sch}(E, \ell), i \in \{0, 1, 2\}$ solutions of (A.4) and satisfying (A.7). Now recall that

$$E_{\ell}^{Sch}(r) \le E^2, \quad \forall r > 2M. \tag{A.13}$$

This implies that \tilde{r} must lie in the region $[2M, r_0^{Sch}] \cup [r_1^{Sch}, r_2^{Sch}]$. Two cases are possible

- either the geodesic starts at r_0^{Sch} and reaches the horizon r=2M in a finite proper time,
- or the geodesic is trapped between r_1^{Sch} and r_2^{Sch} .
- 2. If $(E, \ell) \in \mathcal{A}_{unbound}$, then there exists $r_i^{Sch} := r_i^{Sch}(E, \ell), i \in \{0, 1, \}$ solutions of (A.4) and satisfying (A.8). By (A.13), \tilde{r} must lie in the region $]2M, r_0^{Sch}] \cup [r_1^{Sch}, \infty[$. Therefore, two cases are possible
 - either the geodesic starts at r_0^{Sch} and reaches the horizon r = 2M in a finite proper time,
 - or the geodesic stars from infinity, hits the potential barrier at r_1^{Sch} and comes back to infinity.
- 3. If $(E, \ell) \in \mathcal{A}_{abs}$, then the equation (A.4) has at most one positive root r_0^{Sch} . Two cases are possible:
 - The geodesic starts at r_0^{Sch} and reaches the horizon in a finite proper time.
 - The geodesic starts from infinity and reaches the horizon in a finite time.
- 4. If $(E, \ell) \in \mathcal{A}_{circ}$, then the equation (A.4) admits one triple root if $E = \sqrt{\frac{8}{9}}$ or a double root. In this case, the geodesic is a circle.

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