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Improvements on Lifespan Modeling of the Insulation of Low Voltage Machines with Response Surface and Analysis of Variance

Antoine Picot, David Malec and Pascal Maussion

Abstract- The aim of this paper is to present some improvements of the method for modeling the lifespan of insulation materials in a partial discharge regime. The first step is based on the design of experiments which is well-known for reducing the number of experiments and increasing the accuracy of the model. Accelerated aging tests are carried out to determine the lifespan of polyestearimide insulation films under different various stress conditions. A lifespan model is achieved, including an original relationship between the logarithm of the insulation lifespan and that of electrically applied stress and an exponential form of the temperature. The significance of the resulting factor effects are tested through the analysis of variance. Moreover, response surface is helpful to take into account some second order terms in the model and to improve its accuracy. Finally, the model validity is tested with additional points which have not been used for modeling.

Index terms—Diagnosis, dielectrics, insulation, insulation testing, accelerated aging, lifespan estimation, condition monitoring, modeling, aging, response surface, analysis of variance (ANOVA)

I. NOMENCLATURE

E_i	Effect of factor number i
E_{ii}	Effect of the square of factor number i
E_{ij}	Effect of interaction between factor number i and factor number j
n	Number of experiments
F_i	Level of factor i, could be +1, -1 or any value between -1 and +1
\hat{E}	Effect vector composed of the different E_{ij} terms
X	Experimental matrix
Y	Y is the experimental Weibull's vector
M	Average experimental value
L	Lifespan in minutes
T	Temperature in °C
V	Voltage in V
F	Frequency in Hz
V_A	Variance of factor A
N	Number of samples = number of repetitions
k	Number of factors (k=3)
n_0	Number of center points
dof	Degrees of freedom

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II. INTRODUCTION

Low voltage electric machines are increasingly submitted to heavy electric constraints and their lifespan becomes nowadays a concern. Among many papers, [1] have reported that stator-winding insulation is one of the weakest components in a drive (around 40% of failures). Materials involved in electric ageing affect the insulation system lifespan. Many operating factors such as voltage, frequency, temperature, pressure, etc. could have a dramatic effect as these stresses can synergize as shown in [2]. The existing models of degradation or of lifespan differ slightly from one paper to another but they are all based on physics and include some factors which are specific to the material or the aging mechanism. As examples, [3]-[4] include the physical, thermal and electro-mechanical aspects of the electrical aging process. Additionally, the choice of the lifespan forms remains critical for model accuracy. Various forms can be found in different works such as [5] where they mainly involve a log-based relationship for frequency and voltage and an exponential form for the temperature. Nevertheless, there is no comprehensive model for insulation lifespan prediction under different combined stresses and this phenomenon remains complex and difficult to understand and to model, especially with PWM supply.

Experimental tests are necessary to assess lifespan modeling but full aging tests for all the factors involved in the aging process under nominal conditions could be time consuming. As a consequence, accelerated aging tests which are about to speed up the degradation, are generally performed in order to study and predict the lifespan. IGBT modules in high temperature power cycling are tested in [6] whereas nano-structured enamels on twisted pairs are tested in [7] under severe waveforms but it does not give any lifespan model.

The “Design of Experiments” (DoE) [8] was helpful in many cases either for optimization or modeling purposes. The principle of this methodology is to organize and carry out just the required number of experiments in order to obtain the most accurate information for a specific problem. Its performance has been put in evidence in different applications, especially in chemistry and mechanics, where a high volume of parameters have to be simultaneously optimized. In recent years, DoE have been successfully used

in electrical engineering for electrical machine design (induction, reluctance, synchronous...) [9]-[11] or for the control of power electronic devices [12]-[13]. In the field of insulation lifespan modeling, [14] provides a model with some statistical analysis to test which parameters are significant or not. A set of 8 tests are carried out for each combination of the stress factors (Voltage, Temperature and Frequency). To be more cost effective, this paper will try to reduce this number of tests. But, it is important to check whether the results remain statistically significant or not and Analysis of Variance (ANOVA) will be employed.

III. SYSTEM DESCRIPTION AND BASIC DoE

The testbench itself and the tested insulation materials have been fully described in [14]. It consists of steel plates coated with polyetherimide (PEI - thermal class: 180°C) films which are widely used in rotating machine insulation systems (15cm x 9cm with a 90µm coating).

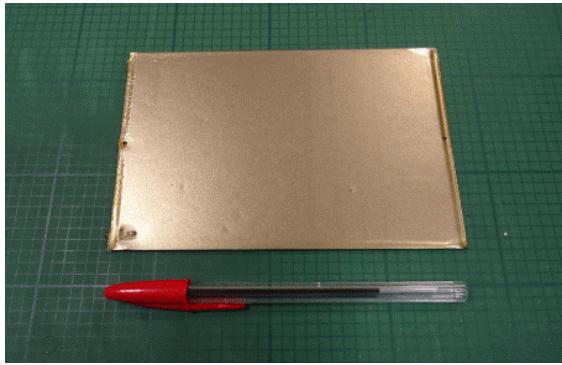


Fig. 1. Tested 90µm coated steel plate (15cm x 9cm)

Eight samples were tested in our experimental setup, shown in Fig.2. Under electrical stress, the steel plate acts as the first electrode and a spherical stainless steel electrode (diameter: 1mm) is the second. Samples were placed in a climatic chamber where the temperature is fully controlled. The lifespan of each sample was measured using a timer (one per sample) which stopped counting as soon as the current increased and crossed a threshold at which the corresponding sample broke down. The faulty specimen was disconnected while the survivors remained under voltage and at the controlled temperature. Accelerated aging tests are carried out in order to relate the applied external stresses (factors) to the insulation lifespan (response). Lifespan data in this paper is presented according to Weibull's statistical processing [15], which is commonly used for breakdown data treatment.



Fig. 2. The experimental setup for accelerated aging tests, climatic chambers and power electronic.

The failure process is driven by several stresses acting simultaneously such as electrical, thermal, mechanical and ambient stresses. The experimental aging conditions of these accelerated tests were chosen to ensure that the insulation degradation is mainly due to the partial discharges. However, for simplicity and because of their influence, only three major parameters were studied:

- 1) the square wave applied HVDC (V),
- 2) the frequency of the applied voltage (F),
- 3) temperature (T).

TABLE I
LEVELS OF THE THREE STRESS FACTORS

Factors	Level (-1)	Level (+1)	Level (0)
Log (Voltage (kV))	Log(1)	Log(3)	Log(1.73)
Log((Frequency (kHz)))	Log(5)	Log(15)	Log(8.7)
Exp(-b.Temperature (°C))	Exp(55b)	Exp(-180b)	Exp(26.7b)

with $b = 5.64 \times 10^{-3}$

The basic data treatment of the PEI insulation film lifespan relies on the Design of Experiments as written in [16] and [14]. The corresponding plans and results are recalled in Table II and Table III for an easy understanding. Table II gives all the 2^3 (3 factors, 2 levels each) possible combinations between the different factor levels whereas Table III lists the sample lifespans (in minutes). They lead to a first model presenting a logarithmic form of electrical stress (i.e. voltage and frequency) and an exponential form of the temperature as expressed in (1). The coefficients of the model are listed in Table IV.

$$\begin{aligned} \text{Log}(L) \sim & M + E_V \cdot \text{log}(V) + E_F \cdot \text{log}(F) + E_T \cdot \text{exp}(-bT) + \\ & E_{FV} \cdot \text{log}(V) \cdot \text{log}(F) + E_{FT} \cdot \text{log}(V) \cdot \text{exp}(-bT) + \\ & E_{FT} \cdot \text{log}(F) \cdot \text{exp}(-bT) + E_{VFT} \cdot \text{log}(V) \cdot \text{log}(F) \cdot \text{exp}(-bT) \end{aligned} \quad (1)$$

TABLE II
EXPERIMENTAL RESULTS WITH THREE FACTORS AT 2 LEVELS EACH : 8 EXPERIMENTS WITH 8 SAMPLES EACH

Test n°	Log(V) Log(F) $e^{(-bT)}$			Lifespan (minutes)							
	F1	F2	F3	Sample no. 1	Sample no. 2	Sample no. 3	Sample no. 4	Sample no. 5	Sample no. 6	Sample no. 7	Sample no. 8
1	-1	-1	-1	378	418	568	587	634	642	786	850
2	-1	-1	1	25	29	23	29	26	30	24	31
3	-1	1	-1	169	187	268	268	343	364	162	322
4	-1	1	1	14.5	14.25	13.4	13.8	14.8	15	13	15.5
5	1	-1	-1	26	30	28	33	24	29	28	35
6	1	-1	1	6	6.5	6.2	6.8	5.5	6.5	6	6.3
7	1	1	-1	14	16.21	15.07	15.5	15.28	16	12.5	14.8
8	1	1	1	2.2	2.233	1.133	1.65	2.033	1.516	0.933	1.4

TABLE III
FULL FACTORIAL DESIGN MATRIX FOR THREE FACTORS WITH 2 LEVELS EACH

Test n°	Log(V) Log(F) $e^{(-bT)}$			Log(V).Log(F)	$\frac{\text{Log}(V).e^{(-bT)}}{\text{Log}(F).e^{(-bT)}}$	$\frac{\text{Log}(F).e^{(-bT)}}{\text{Log}(V).e^{(-bT)}}$	$\frac{\text{Log}(V).Log(F)}{\text{Log}(F).e^{(-bT)}}$	$\frac{\text{Log}(V).Log(F)}{\text{Log}(V).e^{(-bT)}}$	Weibull
	M	F1	F2	F3	I(V.F)	I(V.T)	I(F.T)	I(V.F.T)	
1	1	-1	-1	-1	1	1	1	-1	2.824
2	1	-1	-1	1	1	-1	-1	1	1.453
3	1	-1	1	-1	-1	1	-1	1	2.459
4	1	-1	1	1	-1	-1	1	-1	1.167
5	1	1	-1	-1	-1	-1	1	1	1.486
6	1	1	-1	1	-1	1	-1	-1	0.806
7	1	1	1	-1	1	-1	-1	-1	1.187
8	1	1	1	1	1	1	1	1	0.255

Tests at the center of the study domain

Model : $\text{Log}(L) = f[\text{Log}(V), \text{Log}(F) \text{ and } \exp(-bT)]$

9	1	0	0	0	0	0	0	0	1.43
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The factor effect calculation can be achieved by a simple matrix inversion through the following relationship (2), where (\hat{E}) is the 8×1 effect vector, Y is the 8×1 experimental Weibull's vector of the and X is the 8×8 matrix composed of experiment levels, the dark grey part in Table III.

$$\hat{E} = X^{-1} \cdot Y \quad (2)$$

TABLE IV
EFFECT VALUES FOR THE LIFESPAN MODEL, VECTOR \hat{E}

Model	Effect
M	1.45
Log(V)	-0.53
Log(F)	-0.19
Exp(-bT)	-0.54
$I_{\text{Log}(V).\text{Log}(F)}$	-0.03
$I_{\text{Log}(V).\exp(-bT)}$	0.12
$I_{\text{Log}(F).\exp(-bT)}$	-0.03
$I_{\text{Log}(F).\text{Log}(F).\exp(-bT)}$	-0.05

Once this factors have been calculated as in any kind of regression problem, tests of hypotheses are helpful in measuring their usefulness and whether their contribution to the model are significant or no. The following section describes the analysis of variance which is carried out as test of significance.

IV. SIGNIFICANCE AND REPETITION NUMBER USING ANOVA

A. ANOVA presentation

ANOVA is a widely used statistical model separating the total variability found within a data set into two components: random and systematic factors. It has been demonstrated in [17] that ANalysis Of Variance (ANOVA) is a very interesting technique to assess the statistical significance of the different factor effects in many different applications in the wide field of electrical engineering. A new rotor shape for a high-speed interior permanent-magnet synchronous motor is presented in [18]. Its design is based on a full factorial experimental design and leads to a significant reduction in the amount of permanent magnet

employed. Moreover, the design factors of the greatest influence are identified with the help of ANOVA. This method has also been used in [19] in order to evaluate student's performance in tests and exams after supervisory control and data acquisition (SCADA) and robotics experiments in control and automation education. The study put in evidence the usefulness of experimental practice even on low cost experimental setups. Energy production from PV generators is monitored in [20] and ANOVA helps to get concise information about the energy produced by all the inverters for comparison purposes.

B. Significance and ANOVA

Some of the factor effects computed in the ageing model proposed in section I are close to 0. These effects might not be significant and might be only due to the variability of the data, i.e. caused by non-controlled factors. To use ANOVA, two conditions must be verified:

- data must be normally distributed for each factor,
- the different data must be independent.

Variance V_i due to the specific factor i is compared to the variance of the data set, called the residual variance V_r . If the factor is not significant, the variance V_i will be very close to V_r . On the contrary, the variance V_i will be proportionately higher than V_r . The ratio $F_{exp}=V_i/V_r$ is computed and tested using a Fisher-Snedecor test. This method tests the equality of both variances. So, the null hypothesis is to consider the effect of A as non-significant. In this case, the ratio F_{exp} should be less than a threshold F_{lim} . The effect of A is considered as statistically significant if F_{exp} is greater than F_{lim} . The threshold F_{lim} is defined according to the table of upper critical values of the F-distribution depending on the degrees of freedom of the data and the test significance level (generally fixed at 5%). For each test, a residue r_{ij} is computed as the difference between the lifetime obtained for a particular repetition j and the average lifetime obtained for this particular experiment i . The residual variance V_r is computed for all experiments i and repetitions j according to (3):

$$V_r = \frac{\sum r_{ij}^2}{dof_r} \quad (3)$$

where dof_r is the number of degrees of freedom for the residues. If we consider a DoE with N experiments and k repetitions for each test, the degrees of freedom for each test will be equal to $k-1$ and so the number of degrees of freedom for the residues will be $dof_r=N(k-1)$. For each factor i , a variance V_i is computed as follows:

$$V_i = \frac{n \sum E_i^2}{dof_i} \quad (4)$$

where n is the number of tests when factor F_i is to a certain level, E_i is the effect of the factor i and dof_i its number of degrees of freedom. The number of tests n can be computed as the total number of tests $N.k$ divided by the number of levels l_i for the factor i . The number of degrees of freedom is equal to the number of levels of the factor minus 1. The variance V_i can then be expressed in (5):

$$V_i = \frac{N \cdot k \sum E_i^2}{l_i(l_i - 1)} \quad (5)$$

The square of the effect is summed as many times as the number of levels. In the case of an interaction between two factors i and j , the variance V_{ij} is computed as:

$$V_{ij} = \frac{n \sum I_{ij}^2}{dof_{ij}} \quad (6)$$

with I_{ij} the effect of the interaction between factors i and j . The number of repetitions n is calculated as $N/(l_i l_j)$ and the number of degrees of freedom dof_{ij} is equal to the product of the number of degrees of freedom for factors i and j . The expression of V_{ij} is then:

$$V_{ij} = \frac{N \cdot k \sum I_{ij}^2}{l_i l_j (l_i - 1)(l_j - 1)} \quad (7)$$

The square of the interactions is summed as many times as there are possibilities of combination between the levels of the different factors. For example, if factors i and j are both two-levels factors, there are $4(=2^2)$ possible combinations ($[+1; +1]$, $[+1; -1]$, $[-1; +1]$, $[-1; -1]$).

C. Application to the DoE results

The ANOVA is now applied to the results obtained by the DoE described in section III in order to evaluate the significance of each effect. The normality of the distribution for each experiment is tested using a Shapiro-Wilk test and will not be described here. The Shapiro-Wilk test has been chosen because it is well designed for small populations (between 3 and 5000) as explained in [21]. The independence of the different data is ensured by the fact that each test has been realized independently on different coated steel plates.

DoE has been realized with 3 factors and 2 levels for each. $N=8$ ($=2^3$) experiments have been set with $k=8$ repetitions for each. The number of degrees of freedom is $dof=1$ for every factor and interaction and $dof_r=8 \times 7=56$ for the residues. According these degrees of freedom, the theoretical threshold of the Fisher test evaluating the significance of the different factors is $F_{lim}=4.00$. An effect will then be considered as significant if $F_{exp}>F_{lim}$. The results obtained applying the ANOVA on the DoE is summed up in Table V.

TABLE V
SIGNIFICANCE OF THE DOE FACTORS EFFECTS WITH $k=8$ REPETITIONS

Factor	dof	Variance	$F_{exp}=V_r/V_i$	F_{lim}	Significant?
V	1	17.0371	2218.6	4.00	Yes
F	1	2.3610	307.4	4.00	Yes
T	1	17.8524	2324.7	4.00	Yes
V,F	1	0.0209	2.7	4.00	No
V,T	1	0.3286	42.8	4.00	Yes
F,T	1	0.0169	2.2	4.00	No
V,F,T	1	0.1229	16.0	4.00	Yes
Residues	56	0.0077			

Table V confirms that voltage and temperature are the two most significant factors. Consequently, their interaction should be significant too. The effect of the frequency is significant but its interactions with other factors are not. This seems logical because the effect of these interactions were very low, $I(V,F)=-0.0295$ and $I(F,T)=-0.0265$. Nevertheless, the interaction $I(V,F,T)$ is statistically significant according to ANOVA although its effect might seem low, $I(V,F)=-0.0506$. Accordingly, interaction effects between frequency and temperature, frequency and voltage, should not be taken into account in the ageing model.

D. Number of repetitions needed

This method can also be used to predict how many repetitions are needed so a factor effect is significant. The Fisher test can indeed be used to define the minimum number k to have $F_{exp} > F_{lim}$. To do so, the residual variance is supposed known which is often true as it is part of the knowledge of a product due to experience. The minimal effect that must be significant is named E_{mini} . Knowing E_{mini} and V_r , it is then possible to estimate the minimal number of repetitions so E_{mini} is considered as significant by using the relation $V_r/V_r > F_{lim}$. The expression of V_i defined in (4) is injected this relation, for k repetitions, we have:

$$\frac{k}{F_{lim}} > \frac{l_i(l_i - 1)V_r}{N \sum E_i^2} \quad (8)$$

F_{lim} depends on dof_i which is fixed by the number of levels for the factor i and $dof_i = N \cdot (k-1)$ with N with the number of experiments. So, F_{lim} depends only on k . This method is applied to the model obtained by the DoE. The effects of interactions between frequency and temperature and between voltage and frequency are not taken into account because it has been demonstrated in the former section that they were not significant. So, the number of experiments of the DoE is now $N=8-2=6$. The minimal effect we want to be significant is $I(V,F,T)=0.0506$. The same residual variance $V_r=0.0077$ than it has been obtained in Table 1 with 8 repetitions is chosen as it is considered as a correct estimation of the residual variance. The results for 2, 3 and 4 repetitions are presented in Table VI.

TABLE VI
ESTIMATION OF THE MINIMUM NUMBER k OF REPETITIONS TO CONSIDER $I(V,F,T)$ AS SIGNIFICANT

k	F_{lim}	k/F_{lim}	$k \cdot V_r/V_i$	Significant ?
4	4.41	0.907	0.499	Yes
3	4.75	0.631	0.499	Yes
2	5.99	0.334	0.499	No

Table II shows that 3 repetitions at least are needed to consider the effect of the interaction between voltage, frequency and temperature as significant. This is an interesting result demonstrating that even if the effect of the double interaction is low, only 3 repetitions could have been done to observe a significant effect, which would reduce the total number of tests to run to 18 instead of 64. Next section will try to see if the model prediction might be improved with second order terms

V. RESPONSE SURFACE METHODOLOGY FOR MODEL IMPROVEMENT

The design of experiments can be seen as a regression method that gives to a model which can include some non-linear relationships between the stress variables. But the resulting model is limited to single factors (voltage V or temperature T for example) or products between them (VT) while some other effects such as the square of the voltage (V^2) could be influent as well and cannot be included in the first order model achieved with DoE. In these cases, Response surface methodology (RSM) is a good candidate to complete the investigations and to provide extended models [22]. RSM has been used in [23] for the multi-objective optimal design of isolated dc–dc converters. For the power loss and the weight of the converter, The impact of different factor such as voltages, currents or model parameters, transformer heat-transfer coefficient for example are taken into account. Besides RSM method in [24] gives an analytical model of some parameters (such as weight, detent force, and thrust force) of a permanent-magnet type transverse flux linear motor (TFLM). The objective functions of a Particle Swarm Optimization (PSO) algorithm for the motor design optimization are based on these model parameters.

In this paper, Response Surface Methodology will be used to improve previous work on lifespan modeling of the insulation of low voltage machines. A specific design is built in order to fit a second order model, which means that the experimental surface is supposed to be fitted on a particular form. The method of least squares enables to estimate the regression coefficients in this multiple linear regression model. The response estimation, r , is then given by a second order polynomial, according to (9).

$$\eta = M + \sum_{i=1}^k E_i x_i + \sum_{i=1}^k E_{ii} x_i^2 + \sum_{i=1}^{k-1} \left(\sum_{j=i+1}^k E_{ij} x_i x_j \right) \quad (9)$$

According to the objective, Central Composite Designs are used. They are specifically designed to solve optimization problems and to give the optimal solution. A central composite design is defined by :

- a complete 2^k factorial design, extracted from Table II and Table III,
- n_0 repetitions on center points, for statistic analysis. The factors will now have 3 levels (-1, 0 and 1),
- 2 axial points on the axis of each parameter generally situated at a distance of $\sqrt{2}$ from the design center. In our case will be taken as 1 for experimental reasons, i.e. the limitations of the test bench, as level 1 for parameter T corresponds to 180°C which is already the maximum reachable temperature.

It is important to notice that this identification does not require a new complete experimental procedure as the 8 experiments of the DoE in section II are included in this extension of the regression method. It only needs $n_0 + 2k$

additional experiments, 12 experiments in this case. These points contribute to estimation of quadric terms of the fitted model, i.e. give information on the curvature of the model [22]. Figure 3 shows an example of a face-centered cube design for 3 variables with 3 levels each (-1, 0, +1), whereas the corresponding experimental plan can be found in Table VII hereafter.

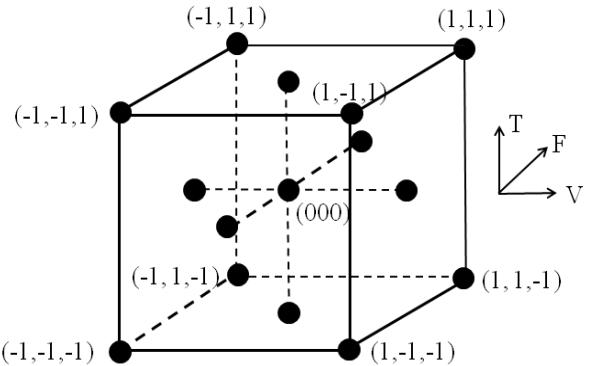


Fig. 3 Face-centered cube design

TABLE VII
RESPONSE SURFACE MATRIX FOR THREE FACTORS WITH 3 LEVELS EACH INCLUDING THE FULL FRACTIONAL PLAN FROM TABLE III

Test n°	M	Log(V)	Log(F)	$e^{(-bT)}$	$\text{Log}(V)^2$	$\text{Log}(F)^2$	$e^{(-bT)2}$	$\text{Log}(V).\text{Log}(F)$	$\text{Log}(V).\text{e}^{(-bT)}$	$\text{Log}(F).\text{e}^{(-bT)}$	$\text{Log}(V).$ $\text{Log}(F).$ $e^{(-bT)}$	Weibull 8 exp	Weibull 4 exp
		F1	F2	F3	$F1^2$	$F2^2$	$F3^2$	I(V.F)	I(V.T)	I(F.T)	I(V.F.T)	Log(L)	Log(L)
1	1	-1	-1	-1	1	1	1	1	1	1	-1	2.824	2.72
2	1	1	-1	-1	1	1	1	-1	-1	1	1	1.486	1.44
3	1	-1	1	-1	1	1	1	-1	1	-1	1	2.46	2.382
4	1	1	1	-1	1	1	1	1	-1	-1	-1	1.187	1.152
5	1	-1	-1	1	1	1	1	1	-1	-1	1	1.453	1.483
6	1	1	-1	1	1	1	1	-1	1	-1	-1	0.806	0.814
7	1	-1	1	1	1	1	1	-1	-1	1	-1	1.167	1.192
8	1	1	1	1	1	1	1	1	1	1	1	0.255	0.27
9	1	-1	0	0	1	0	0	0	0	0	0	1.769	1.751
10	1	1	0	0	1	0	0	0	0	0	0	0.881	0.815
11	1	0	-1	0	0	1	0	0	0	0	0	1.704	1.649
12	1	0	1	0	0	1	0	0	0	0	0	1.314	1.271
13	1	0	0	-1	0	0	1	0	0	0	0	1.985	2.004
14	1	0	0	1	0	0	1	0	0	0	0	0.997	0.939
15	1	0	0	0	0	0	0	0	0	0	0	1.432	1.43
16	1	0	0	0	0	0	0	0	0	0	0	1.444	1.44
17	1	0	0	0	0	0	0	0	0	0	0	1.45	1.39
18	1	0	0	0	0	0	0	0	0	0	0	1.46	1.39
19	1	0	0	0	0	0	0	0	0	0	0	1.42	1.41
20	1	0	0	0	0	0	0	0	0	0	0	1.437	1.413

TABLE VIII
EFFECT VALUES FOR THE LIFESPAN MODEL, VECTOR \hat{E}

Model	Effect calculated from 8 exp. for model SRM8	Effect calculated from 4 exp. for model SRM4
M	1.4383	1.4092
Log(V)	-0.5056	-0.5036
Log(F)	-0.1891	-0.1887
exp(-bT)	-0.5265	-0.4997
Log(V) ²	-0.1112	-0.1218
Log(F) ²	0.0725	0.0782
e ^{(-bT)2}	0.0548	0.0651
I _{Log(V).Log(F)}	-0.0249	-0.0256
I _{Log(V).exp(-bT)}	0.1315	0.1147
I _{Log(F). exp(-bT)}	-0.0218	-0.026
I _{Log(F).Log(F). exp(-bT)}	-0.0412	-0.036

The vector effect \hat{E} is then calculated with the mean square fit, as expressed in (10)

$$\hat{E} = (X^t X)^{-1} \cdot X^t \cdot Y \quad (10)$$

Vector Y could be either the 13° column of Table VII when taking into account the full experimental results or the 14° column of Table VII in case of a reduced set of experiments. Fig. 4 shows for example the non linearity of the response surface associated to model xx, limited to the most influent factors, i.e. V and T.

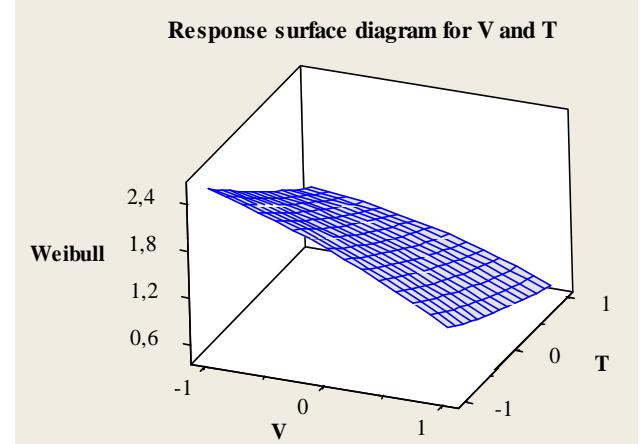


Fig. 4. Response surface diagram for 2 parameters, V and T, out of the 3 parameters involved in the model (V, F and T).

Other experiments inside the experimental domain are carried out such as the 11 points in Table IX, in order to check the models validity. It presents and compares the different results obtained with different models:

- DoE model has been built from 8 experiments focusing only on the main influential factors and interactions,
- SRM8 model relies on 8 experiments and includes only the most influent factors,
- SRM4 model is only based on 4 experiments randomly chosen out of the 8 experiments of SRM8 model and includes only the most influent factors.

It turns out that the use of the SRM increases the model precision and that a limited number of experiments (4 instead of 8) do not dramatically affect the corresponding model precision.

TABLE IX
EXPERIMENTAL POINTS FOR MODEL VERIFICATION I.E. POINTS INSIDE THE EXPERIMENTAL DOMAIN BUT NOT INCLUDED IN TABLE II AND III

	V level	F level	T level	Weibull Exp. Result (8 exp.)	DoE Model (8 exp.)	% Difference	SRM8 Model (8 exp.)	% Difference	SRM4 Model (4 exp.)	% Difference
2kV; 10 kHz; 117.5 °C	0.262	0.262	0.694	1.017	0.920	-9.5%	0.937	-7.9%	0.928	-8.4%
1kV; 5kHz; 20°C	-1	-1	-0.061	2.089	2.206	5.6%	2.137	2.3%	2.098	0.7%
2kV; 10kHz; 100°C	0.262	0.262	0.587	1.069	0.974	-8.9%	0.982	-8.1%	0.970	-9.4%
1.7 kV; 15 kHz; 26.7°C	0	1	0	1.314	1.266	-3.6%	1.321	0.5%	1.298	2.1%
1.7 kV; 8.6 kHz; 180°C	0	0	1	0.997	0.924	-7.4%	0.970	-2.7%	0.978	4.1%
3 kV; 8.7 kHz; 26.7°C	1	0	0	0.881	0.935	6.0%	0.822	-6.7%	0.785	-3.7%
2kV; 10kHz; 62.5°C	0.262	0.262	0.320	1.165	1.109	-4.9%	1.101	-5.5%	1.081	-7.4%
1.5 kV; 7.5 kHz; -17.5°C	-0.262	-0.262	-0.481	1.771	1.915	8.1%	1.901	7.4%	1.858	5.3%
1kV; 8.6 kHz; 26.7°C	-1	-0.013	0.004	1.769	1.976	11.7%	1.833	3.6%	1.791	2.3%
1.73 kV; 5 kHz; 26.7°C	0	-1.000	0	1.704	1.642	-3.7%	1.699	-0.3%	1.675	-1.2%
1.73kV; 8.6kHz; -55°C	0	0	-1	1.986	1.993	0.4%	2.023	1.9%	1.978	-1.1%

VI. CONCLUSION

This paper has improved the previous work on lifespan modeling of the insulation of low voltage machines with the help of some statistical tools such as response surface and analysis of variance. It has been shown how the most influential factors can be identified, that the SRM increases modelling accuracy and that an experiment number reduction is possible with low risks.

The final objective of this work is to extend the validity domain of the model, primarily towards low constraint levels, for prognostic purposes. Other constraints such as pressure will be included in future work.

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