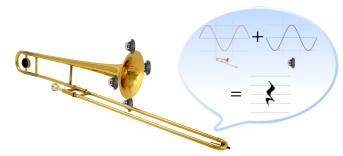




Loudspeaker Optimisation for Active Control of Trombone Radiation



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Trombone spectrum & directivity (Eyring, Leishman, & Strong, 2014)

Lp(1m) = 110 dBSPL

Context

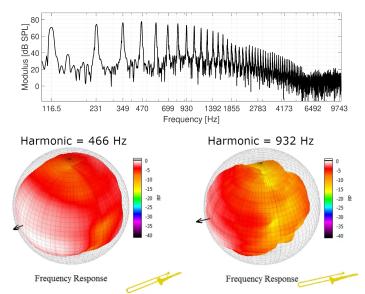
State of the art Aim of this work

Primary source characterization

Control source optimisation

Optimal control

Conclusions



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(Klawikowski, 2019)

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(Klawikowski, 2019)

Advantage:

Trombone sound level reduced - between 10 and 20 dB

- between 10 and 20 d

(Ancell, 1960)

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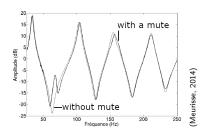
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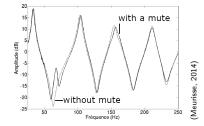
Conclusions



Klawikowski, 2019)

Advantage:

Trombone sound level reduced - between 10 and 20 dB (Ancell, 1960)



Drawback:

Input impedance so timbre and way of playing changed

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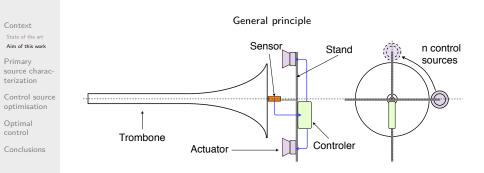
Conclusions

Control actuator suspended at trumpet bell opening (Pickett, 1998)



Drawbacks:

- too heavy,
- sound muffled,
- high sound level to provide (up to 130 dBSPL).



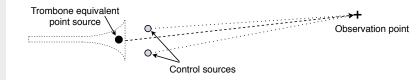
- Aim of the work : control the radiated power of the trombone
- Constraints : low modification of impedance, light

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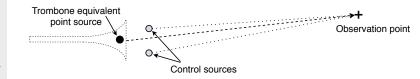
- Work objectives:
 - trombone equivalent point source:
 - Position? Volume velocity?

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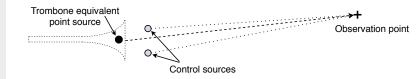
- Work objectives:
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 - Ioudspeaker:
 - Required diaphragm excursion, electrical power, number of speakers?

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- Work objectives:
 - trombone equivalent point source:
 - Position? Volume velocity?
 - Ioudspeaker:
 - Required diaphragm excursion, electrical power, number of speakers?
 - optimal control:
 - Impact of number and position of the control sources on radiation?

Summary

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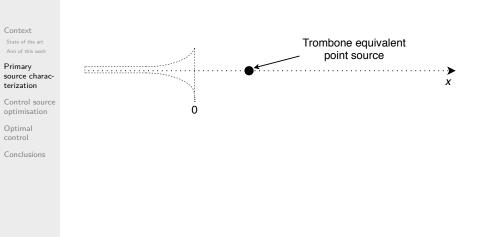
Conclusions

Primary source characterization

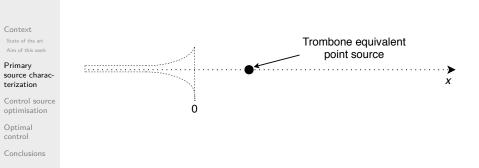
3 Control source optimisation



Aim



Aim



Position and volume velocity according to:

- the frequency (fundamental and harmonics),
- the dynamic marking (piano, mezzo-forte, forte).

Experiment

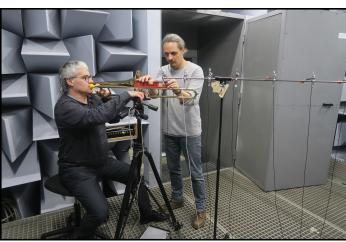


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Experiment

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Aim of this work

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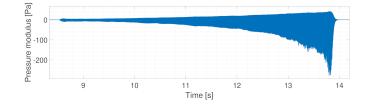
Control source optimisation

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Sound at 23 cm from horn

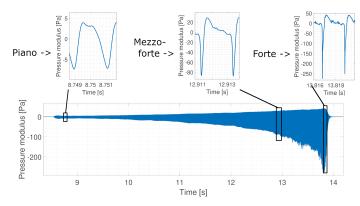
B flat 4 (f = 466 Hz) during 5 seconds.



Experiment

Sound at 23 cm from horn

B flat 4 (f = 466 Hz) during 5 seconds.



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Volume velocity & position calculation

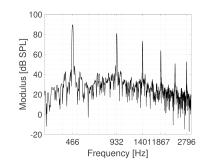
Example for one dynamic marking, for one note and one microphone position:

Primary source characterization

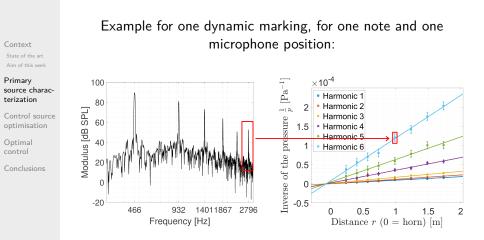
State of the art

Control source optimisation

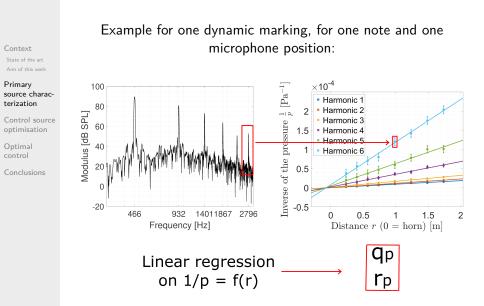
Optimal control

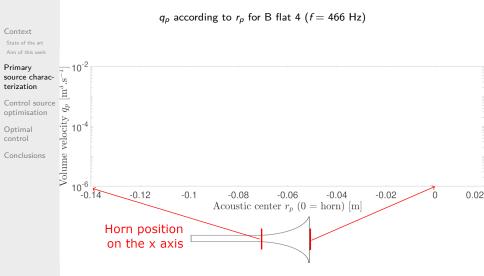


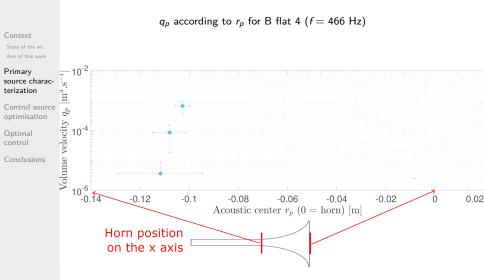
Volume velocity & position calculation

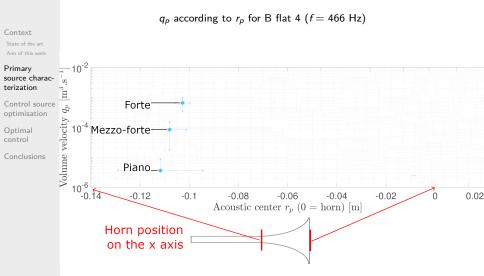


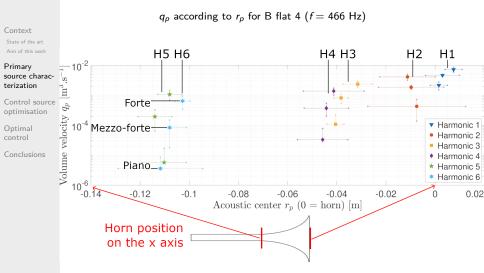
Volume velocity & position calculation











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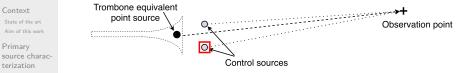
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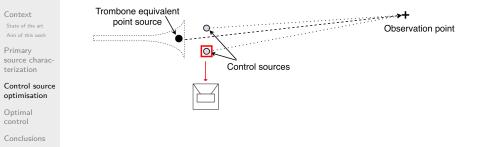


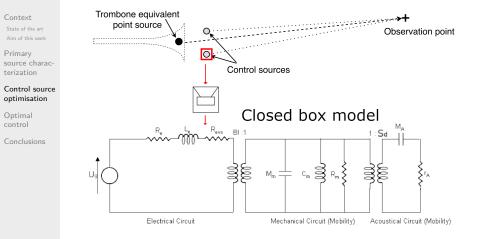
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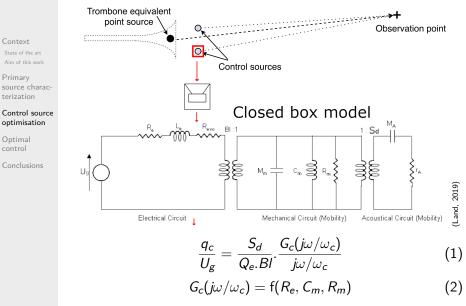
Context

Primary

terization







Loudspeaker parameters

Constraints

- Context
- State of the art Aim of this work
- Primary source characterization

Control source optimisation

- Optimal control
- Conclusions

- onstraints
- fs = \pm 100 Hz
- $xmax = \pm 5 mm$
- High power capacity

- Weight: light
- Diameter: \leq 4"
- High sensitivity

Loudspeaker parameters

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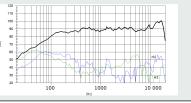
- fs = \pm 100 Hz
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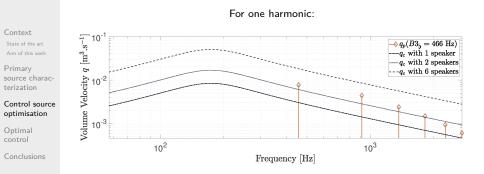
Manufactured speaker: Beyma 3FR30Nd

- fs = 188 Hz
- xmax: \pm 4.5 mm
- Power capacity: 30 W
- Weight: 0.25 kg
- Diameter: 3"
- Sensitivity: 92 dBSPL 1W/1m

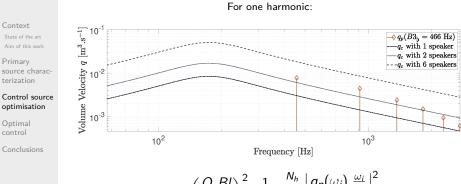




Required power



Required power



$$P = \left(\frac{Q_e Bl}{S_d N_s}\right)^2 \frac{1}{2.Z_e} \sum_{i=1}^{N_h} \left| \frac{q_p(\omega_i) \cdot \frac{\omega_i}{\omega_c}}{G_c(\frac{\omega_i}{\omega_c})} \right|^2$$
(3)

Number of speakers	1	2	3	4	5	6	7	8
Needed power (W)	476	119	53	30	19	13	10	7.5

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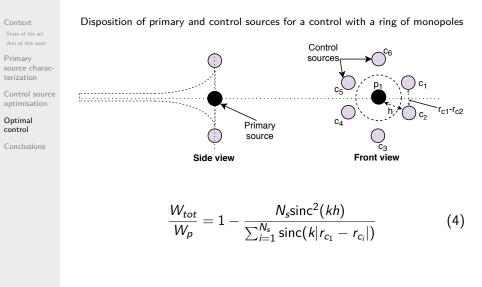
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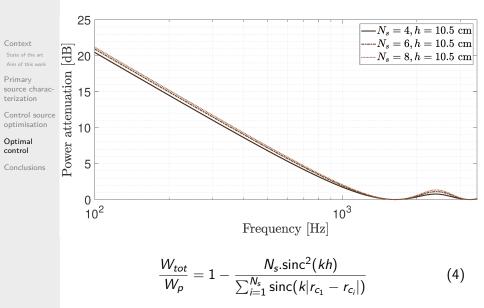


Optimal control

Power attenuation - Number of speakers impact (Bolton, 1995)

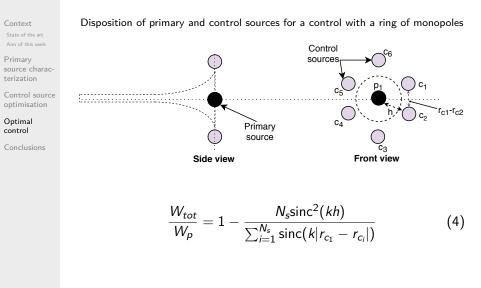


Power attenuation - Number of speakers impact (Bolton, 1995)

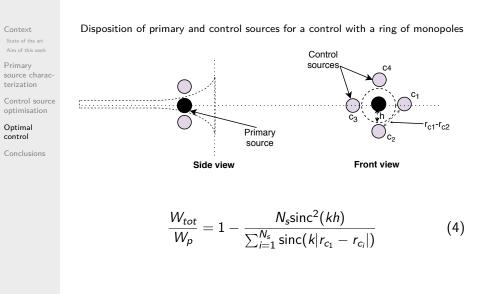


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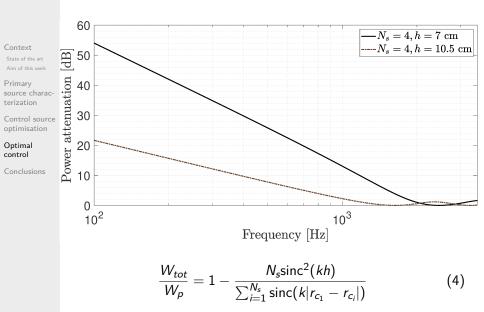
Power attenuation - Position of speakers impact (Bolton, 1995)



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Power attenuation - Position of speakers impact (Bolton, 1995)



Conclusions

Conclusion:

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Conclusions

- primary source: $q_{p_{\max}} = 0,01 \text{ m}^3.\text{s}^{-1}$, $-12 \text{ cm} \ge r_p \ge 0 \text{ cm}$,
- chosen loudspeaker: P_{capacity} = 30 W, 4 speakers minimum to control the 6 first harmonics,
- optimal control: efficient attenuation until $kh = n\pi$ (f = 1500 Hz).

To be followed:

- optimal control model for shifting and moving primary source,
- comparison theory/experiment,
- impact of an external control on input impedance,
- directivity control.

Annexe

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$$\frac{q_c}{U_g} = \frac{S_d}{Q_e.Bl} \cdot \frac{G_c(j\omega/\omega_c)}{j\omega/\omega_c}$$
(5)

$$G_c(j\omega/\omega_c) = f(R_e, C_m, R_m)$$
(6)

$$G_c(j\omega/\omega_c) = \frac{(j\omega/\omega_c)^2}{(j\omega/\omega_c)^2 + Q_{tc}^{-1}(j\omega/\omega_c) + 1}$$
(7)

$$Q_{tc} = \frac{Q_{ec}Q_{mc}}{Q_{ec} + Q_{mc}} \tag{8}$$

$$Q_{ec} = \frac{Re}{\omega_c C_{as}} \left(\frac{Sd}{BI}\right)^2$$
(9)
$$Q_{mc} = \frac{1}{\omega_c C_m R_m}$$
(10)