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# OceanGliders: A Component of the Integrated GOOS

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The *OceanGliders* program started in 2016 to support active coordination and enhancement of global glider activity. *OceanGliders* contributes to the international efforts of the Global Ocean Observation System (GOOS) for Climate, Ocean Health, and Operational Services. It brings together marine scientists and engineers operating gliders around the world: (1) to observe the long-term physical, biogeochemical, and biological ocean processes and phenomena that are relevant for societal applications; and, (2) to contribute to the GOOS through real-time and delayed mode data dissemination. The *OceanGliders* program is distributed across national and regional observing systems and significantly contributes to integrated, multi-scale and multi-platform sampling strategies. *OceanGliders* shares best practices, requirements, and scientific knowledge needed for glider operations, data collection and analysis. It also monitors global glider activity and supports the dissemination of glider data through regional and global databases, in real-time and delayed modes, facilitating data access to the wider community. *OceanGliders* currently supports national, regional and global initiatives to maintain and expand the capabilities and application of gliders to meet key global challenges such as improved measurement of ocean boundary currents, water transformation and storm forecast.

**Keywords:** *in situ* ocean observing systems, gliders, boundary currents, storms, water transformation, ocean data management, autonomous oceanic platforms, GOOS

## INTRODUCTION

The ocean is an important component of the global earth system influencing the global/regional climate, weather, ecosystems, living resources and biodiversity. The ocean plays a major role in many human activities including coastal protection, tourism, search and rescue, defense and security, shipping, aquaculture and fisheries, offshore industry and marine renewable energy. Ocean observation serves to enable us to better understand ocean functions and to meet the societal needs related to these activities. The Intergovernmental Oceanographic Commission (IOC of UNESCO) developed the Global Ocean Observing System (GOOS) more than two decades ago to coordinate the different national efforts in terms of sustained ocean observations throughout the world and to maximize the societal benefits of ocean observations. The GOOS has three observation panels for the development of observing

strategies for climate, biogeochemistry and biology/ecosystems and the Observation Coordination group (OCG) of the World Meteorological Organization (WMO)/Intergovernmental Oceanographic Commission (IOC) Joint Commission on Oceanography and Marine Meteorology (JCOMM) for technical coordination of on-going observations. GOOS also serves as the ocean component of the Global Climate Observing system (GCOS). It is implemented through GOOS Regional Alliances and supported by a wide range of bodies, such as the Committee on Earth Observing Satellites (CEOS), the Partnership for Observation of the Global Ocean (POGO) and the GEO Blue Planet initiative.

The OceanObs'99 conference stimulated the first design of the GOOS and 10 years later, the OceanObs'09 conference assessed the progress made in implementing the GOOS. At that time, an international consensus was reached on how the GOOS should continue to evolve. Discussions around the GOOS highlighted

the tremendous potential value for physical, biogeochemical, and biological observations, particularly in the transition between the open ocean and the coastal environment, which is a key area for societal issues, economical applications and at the same time is a prime area for autonomous underwater glider (Davis et al., 2002) observations. Gliders were considered in this global framework from the very beginning. Developed in the 1980–1990s (Lee and Rudnick, 2018), they arose from the vision that a network of small, intelligent, mobile and cheap observing platforms could fill sampling gaps left by the other ocean observing platforms (Stommel, 1989). This idea was first discussed at OceanObs'99 (see Conference Statement<sup>1</sup>), when the technology was immature, and further developed at OceanObs'09, when the technology was still maturing but poised to make a substantial contribution to global ocean observing (Testor et al., 2010). It was agreed that gliders could fill important gaps left by other observing systems and thus greatly enhance the GOOS if fully integrated into the system, and recommendations were made for the next decade.

## Progress Over the Last Decade

Since OceanObs'09, autonomous underwater gliders have reached a mature state and are now operated routinely. They offer persistent fine resolution observations in the coastal and open ocean, even at high latitudes (at least during summer months). Typically, gliders profile from the surface to the bottom, or to 200–1,000 m depth, taking 0.5–6 h to complete a cycle from the surface to depth and back. During that time they travel 0.5–6 km horizontally at speeds of about 1 km/h, even during very severe weather conditions. Deployments of about a year are now possible, with deployments of 3–6 months now routine, and survey tracks extending over 1,000s kilometers. Sensors on gliders measure physical variables such as pressure, temperature, salinity, currents, turbulence and wind speed (Cauchy et al., 2018), biological variables relevant to phytoplankton and zooplankton, and ecologically important chemical variables such as dissolved oxygen, irradiance, carbon dioxide, pH (Saba et al., 2018), nitrate and hydrocarbon. Gliders have been developed to sample under-sea ice and ice shelves (Webster et al., 2015; Nelson et al., 2016; Lee et al., 2017), to recover data from other deep instruments via acoustic telemetry and send them to land while at the surface (Send et al., 2013), to detect acoustic tags on fishes (Oliver et al., 2013, 2017) and marine mammals. Improved gliders have reached depths of up to 6,000 m (Osse and Eriksen, 2007). All these improvements greatly open up the range of possible applications.

Their unique sampling capacities (high resolution and long term) are especially suitable for some key oceanic phenomena. They have yielded major scientific breakthroughs, revealing new insights into ocean physical, biogeochemical and biological processes. In particular, there are new results on (1) high latitudes oceanography, air-sea-ice interactions and intermediate/deep convection, (2) the variability of boundary currents, (3) (sub)mesoscale processes, (4) phytoplankton phenology and biogeochemistry, (5) higher trophic levels and biology, (6) shallow and marginal seas, (7) climate and variability of the

water column, (8) internal waves, turbulence, tides, diffusivity and vertical mixing, and (9) particles fluxes and sedimentology (see **Table 1**).

Glider data are used for many applications in ocean physics, chemistry and biology (Rudnick, 2016). Glider data management by the scientific community has made data available to the public in real time for classical measured variables. Ocean numerical modeling and forecast activities already benefit from these data (**Table 1**). Models of ocean circulation, particularly for regional and coastal domains, have benefited from glider data in terms of validation and data assimilation, particularly in regional and coastal models. Glider data can improve hurricane intensity forecast models and has led to major results in ocean forecasting, weather forecasting including hurricane intensity, climatologies, and state estimates.

Underwater gliders will enable us to enter a new era of ocean observation and state estimates more effectively, meeting the needs of society and marine researchers. Gliders are a vital component in the portfolio of ocean observing platforms for most of the national ocean observation agencies. These agencies have invested in developing glider observing capability, and there are now about 400–500 gliders in the world actively being used to better observe the ocean (it is difficult to have exact numbers but based on our community knowledge we estimate ~250 gliders in the USA; ~100 in Europe; ~50 in China; ~30 in Australia; ~30 in Canada; 9 in Mexico; 9 in South Korea; 5 in South Africa; 3 in Israel; 3 in Peru; 2 in New Zealand; 2 in India, 2 in Taiwan, etc.). Glider technology has also been used by the private sector during the last decade for applications in pollution events, defense, environment, and the offshore industry (Fragoso et al., 2016).

## The Evolution of a Glider Observing Community-OceanGliders

Today, underwater gliders are operated by many teams around the world that have developed end-to-end systems able to steer their gliders and collect their data through their own facilities and Iridium satellite-based communications. Glider deployments are challenging because they must be managed in real-time throughout their deployment with the two-way communications needed for active piloting by the different operating teams. Glider technology requires a high level of expertise on the scientific and technological aspects in order to effectively operate the vehicles. Thanks to networking, coordination and capacity-building, training, liaison between providers and users, advocacy, and provision of expert advice, the global glider community has become more organized, grown rapidly, and responded to some of the system challenges. The idea for a glider community emerged in October 2005 at the first “EGO (Everyone's Gliding Observatories) Workshop and Glider School” and since then, collaborations have further developed. EGO Workshops and Glider Schools have been organized on an annual basis, to present and discuss scientific and technological issues, and to train and engage new users and countries worldwide. The formation of a user group and global coordination has improved glider operational reliability and data management, and resulted in improved glider monitoring, ocean observing and developments of the glider platform. Over the last decade, this coordination

<sup>1</sup><http://www.oceanobs09.net/work/oo99.php>

**TABLE 1** | Highlights on results during the past decade using the glider technology.

High latitudes oceanography, air-sea-ice interactions, or intermediate/deep convection	Beszczynska-Möller et al., 2011; Frajka-Williams et al., 2011; Beaird et al., 2012, 2013; Evans et al., 2013; Fan et al., 2013; Høydalsvik et al., 2013; Kohut et al., 2013; Queste et al., 2013; Guihen et al., 2014; Heywood et al., 2014; Carvalho et al., 2016; Houpert et al., 2016; Nelson et al., 2016; Azaneu et al., 2017; Couto et al., 2017; Jones and Smith, 2017; Lee et al., 2017; Timmermans and Winsor, 2013; Weingartner et al., 2013; Thompson et al., 2014; Ullgren et al., 2014; Venables and Meredith, 2014; Schofield et al., 2015; Swart et al., 2015; Thomalla et al., 2015; Testor et al., 2018; Våge et al., 2018; Viglione et al., 2018
Variability of boundary currents	Pascual et al., 2010; Pattiaratchi et al., 2010, 2017; Ramp et al., 2011; Todd et al., 2011a,b, 2016, 2018; Albretsen et al., 2012; Davis et al., 2012; McClatchie et al., 2012; Sherwin et al., 2012; Høydalsvik et al., 2013; Johnston et al., 2013; Lien et al., 2014, 2015; Pietri et al., 2014; Schaeffer and Roughan, 2015; Schönau et al., 2015; Yang et al., 2015; Lee et al., 2016; Mensah et al., 2016; Schaeffer et al., 2016a; Zaba and Rudnick, 2016; Andres et al., 2017; Anutaliya et al., 2017; Durand et al., 2017; Todd, 2017; Todd and Locke-Wynn, 2017; Aulicino et al., 2018; Houpert et al., 2018; Krug et al., 2018; Seim and Edwards, 2019
Mesoscale and submesoscale processes	Bouffard et al., 2010, 2012; Baird et al., 2011; Baird and Ridgway, 2012; Heslop et al., 2012; Mahadevan et al., 2012; Ruiz et al., 2012; Todd et al., 2012, 2013; Alvarez et al., 2013; Pelland et al., 2013, 2014, 2016, 2018; Pietri et al., 2013; Piterberg et al., 2013; Timmermans and Winsor, 2013; Caldeira et al., 2014; Hristova et al., 2014; Bosse et al., 2015, 2016; Everett et al., 2015; Farrar et al., 2015; Omand et al., 2015; Schönau and Rudnick, 2015, 2017; Sherwin et al., 2015; Borrione et al., 2016; Caballero et al., 2016; Freitas et al., 2016; Mauri et al., 2016; Thompson et al., 2016; Thomsen et al., 2016; Brannigan et al., 2017; Buffett et al., 2017; Du Plessis et al., 2017; Gourdeau et al., 2017; Itoh and Rudnick, 2017; Karstensen et al., 2017; Kokkini et al., 2017; Krug et al., 2017; Mancero-Mosquera et al., 2017; Margirier et al., 2017; Morrow et al., 2017; Pascual et al., 2017; Ruan et al., 2017; Yu et al., 2017; Zacharia et al., 2017; Gula et al., 2019
Phytoplankton phenology and biogeochemistry	Asper et al., 2011; Briggs et al., 2011; Martin et al., 2011; Xu et al., 2011; Alkire et al., 2012, 2014; Cetinić et al., 2012, 2015; Pierce et al., 2012; Gower et al., 2013; Zhao et al., 2013; FOLONI-Neto et al., 2014; Kaufman et al., 2014, 2017; Olita et al., 2014, 2017; Biddle et al., 2015; Evans et al., 2015; Hemsley et al., 2015; Nicholson et al., 2015; Queste et al., 2015; Seegers et al., 2015; Adams et al., 2016; Cotroneo et al., 2016; Fiedler et al., 2016; Jacox et al., 2016; Loginova et al., 2016; Pizarro et al., 2016; Porter et al., 2016; Schaeffer et al., 2016b; Schuette et al., 2016; Thomsen et al., 2016; Bosse et al., 2017; Hemming et al., 2017; Mayot et al., 2017; Ross et al., 2017; Thomalla et al., 2017; Little et al., 2018
Higher trophic levels and biology	Kahl et al., 2010; Klinck et al., 2012; McClatchie et al., 2012; Powell and Ohman, 2012, 2015; Wall et al., 2012; Baumgartner et al., 2013, 2014; Ohman et al., 2013; Oliver et al., 2013; Guihen et al., 2014; Kohut et al., 2014a; Pelland et al., 2014; Ainley et al., 2015; Goericke and Ohman, 2015; Swart et al., 2016; Kusel et al., 2017; Taylor and Lembke, 2017; Benoit-Bird et al., 2018; Chave et al., 2018
Shallow and marginal seas	Castelao et al., 2010; Shulman et al., 2010; Karstensen et al., 2014; Kohut et al., 2014b; Mazzini et al., 2014; Schaeffer et al., 2014; Piero Mazzini et al., 2015; Qiu et al., 2015; Dever et al., 2016; Mahjabin et al., 2016; Saldias et al., 2016; Heslop et al., 2017; Zarokanellos et al., 2017
Climate and variability of the water column	Cole and Rudnick, 2012; Schlundt et al., 2014; Domingues et al., 2015; Farrar et al., 2015; Houpert et al., 2015; Damerell et al., 2016; Schaeffer et al., 2016a; Rudnick et al., 2017; Portela et al., 2018
Internal waves, turbulence, tides, diffusivity and vertical mixing	Alford et al., 2012; Thorpe, 2012; Beaird et al., 2013; Johnston et al., 2013; Rainville et al., 2013, 2017; Fer et al., 2014; Peterson and Fer, 2014; Boettger et al., 2015; Cronin et al., 2015; Johnston and Rudnick, 2015; Palmer et al., 2015; Klymak et al., 2016; Hall et al., 2017; Schultze et al., 2017; St Laurent and Merrifield, 2017; Todd, 2017; Evans et al., 2018; Ma et al., 2018; Scheifele et al., 2018
Particles fluxes and sedimentology	Briggs et al., 2011; Miles et al., 2013; Bourrin et al., 2015; Omand et al., 2015; Many et al., 2016; Churnside et al., 2017; Durrieu de Madron et al., 2017
Ocean forecasting, climatology, and state estimates	Dobricic et al., 2010; Oke et al., 2010, 2015; Zhang et al., 2010a,b; Chudong et al., 2011; Ramp et al., 2011; Todd et al., 2011a, 2012; Yaremchuk et al., 2011; Jones et al., 2012; Melet et al., 2012; Mourre and Alvarez, 2012; Gangopadhyay et al., 2013; L'Heveder et al., 2013; Li et al., 2013; Rayburn and Kamenkovich, 2013; Wilkin and Hunter, 2013; Alvarez and Mourre, 2014; Chen et al., 2014; Drillet et al., 2014; Mourre and Chiggiato, 2014; Ngodock and Carrier, 2014; Pan et al., 2014, 2017; Durski et al., 2015; Miles et al., 2015; Rudnick et al., 2015; Estournel et al., 2016a,b; Fragoso et al., 2016; Kerry et al., 2016, 2018; Chao et al., 2017a,b; Damien et al., 2017; Dong et al., 2017; Goni et al., 2017; Halliwell et al., 2017; Kurapov et al., 2017; Onken, 2017; Todd and Locke-Wynn, 2017; Verdy et al., 2017

activity has also developed nationally and regionally. Many national facilities have been established to serve their national communities such as the IMOS (Integrated Marine Observing System) Ocean Gliders facility, Ocean Gliders Canada, GMOG (Grupo de Monitoreo Oceanográfico con Gliders) in Mexico, MARS (Marine Autonomous and Robotic Systems) in the UK, Norwegian National Facility for Ocean Gliders (NorGliders) in Norway, “Parc National de Gliders” in France, etc. Glider groups have also been set up for coordination within integrated ocean observation initiatives such as the Integrated Ocean Observing System (IOOS), the Integrated Marine Observing System (IMOS) and the European Ocean Observing System (EOOS)/EuroGOOS.

There are now several levels of coordination and this greatly facilitates scientific and technological exchanges between glider operators and users, in academia and industry.

Building on this diverse community, the *OceanGliders* program started in September 2016 at the 7th EGO conference. It was set up in recognition of the maturity of the glider systems and their potential role in the GOOS in coming years. The *OceanGliders* program as a component of the GOOS was approved by the Joint WMO-IOC Technical Commission for Oceanography and Marine Meteorology (JCOMM) at their 5th Intergovernmental Session in October 2017 and the *OceanGliders* Steering Team reports to OCG. Here we review the progress

made in implementing a glider component of the GOOS, one of the key recommendations from OceanObs'09, present the recently established program and components, and offer a vision for the coming decade.

## MOVING FROM THE REGIONAL TO THE GLOBAL

The progress of gliders in moving from a developing to a mature technology is exemplified by the programs that have been run continuously for over 10 years, for example, in the California Current (Adams et al., 2016; Rudnick et al., 2017), and the Solomon Sea (Davis et al., 2012). Long-term observations lasting several years are becoming widespread (Heslop et al., 2012; Schaeffer et al., 2016a; Yu et al., 2017; Du Plessis et al., 2019). The capability to sustain these programs relies on the improved dependability of gliders (Brito et al., 2014; Rudnick et al., 2016a; Brito and Griffiths, 2018) and the experience, skill and confidence of the operators. The success of these projects can be summarized in the likelihood of a glider completing a desired mission, and the fraction of the time that a glider is in the water. Typical success rates of 0.9 have been achieved by experienced teams. The delivery of data from gliders in real time has become routine, with main glider data assembly centers in Europe (EGO/Coriolis<sup>2</sup>), Australia (IMOS<sup>3</sup>), and the USA (IOOS<sup>4</sup>).

Underwater gliders play a special role in observing systems designed to support regional modeling activities, because gliders generate many profiles at controlled locations. The potential for glider development was recognized quite early on, leading to the influential Autonomous Ocean Sampling Network (Ramp et al., 2009). Glider data are often used with models for two purposes: (1) verification, meaning to evaluate model output for fidelity to the ocean; and/or, (2) assimilation, the use of data to constrain model output (Edwards et al., 2015; Hayes et al., 2019). Models can either (1) forecast ocean variables in advance of any access to data for verification; or (2) hindcast to deliver state estimates that use data to create a complete set of ocean variables. Many combinations of using glider data for verification or assimilation of forecast or hindcast models have been tried in many regions around the world. For example, off California, Kurapov et al. (2017) used glider data (Rudnick et al., 2017) to verify a forecast model, while Chao et al. (2018) assimilated the same glider data to create forecasts. Temperature and salinity data from these gliders were assimilated into a state estimate (Todd et al., 2011a, 2012; Zaba et al., 2018), while velocity data were not assimilated so they could be used for verification. In the Mediterranean, Dobricic et al. (2010) showed the large-scale impact of the repetition of a glider section and in particular when depth-average currents were also assimilated while Mourre and Chiggiato (2014) and Onken (2017) assimilated glider data for a forecast and verified against data from a ship survey. A state estimate of the tropical Pacific (Verdy et al., 2017) was verified against withheld glider

observations on either side of the Pacific basin. These examples illustrate the character of recent work. Ongoing work is expected to improve regional observing modeling in the coming decade.

Underwater gliders are especially well-suited for sustained, fine-spatial-resolution observations near the ocean boundaries. They allow cross-front measurements to help resolve mesoscale/sub-mesoscale fronts and associated shear-driven instabilities in both the coastal and open ocean. The long times for deployments of gliders are possible because they move slowly (10s cm/s) and because energy lost to drag is proportional to the cube of the speed through water. Gliders must profile continuously in order to make way through water, so fine resolution in the order of a few kilometers is common. Gliders can be deployed and recovered from small boats, thereby minimizing costs and allowing flexible operation. Sustained, fine-resolution operations near boundaries are ideal for monitoring the regional effects of climate variability. Gliders fill the gap between the coast and the open ocean, as tracks of thousands of kilometers are typical, making traversing the 200 nautical mile Exclusive Economic Zone practical. Gliders could revolutionize regional oceanographic observing just as Argo did for observing the open ocean over the last two decades.

## OceanGliders Terms of Reference

The international *OceanGliders* program was created as a component of the GOOS with the broad goals of strengthening the glider community (users, scientists, engineers, operators, manufacturers) and facilitating the sustained worldwide use of gliders for the benefit of society and science<sup>5</sup>. An initial structure and set of governance rules were agreed upon, as well as more detailed ways to maintain and develop the program, briefly summarized in **Table 2**. Because of their proven ability to fill gaps and needs in the existing observation system, gliders are on the cusp of a transition from isolated, regional use by a few expert teams, to widespread use around the globe by coordinated groups with a wider range of applications. The glider community has realized the many benefits of sharing expertise, best practices, data, and even infrastructure components among existing and new members. Providing a global program, in which new ideas can be discussed and coordinated for larger-scale adoption, will turn regional efforts into integrated global efforts. This fits perfectly into the GOOS mission to promote feasible, high-impact observing programs.

## Data Management

*OceanGliders* targets high-impact, societally-relevant, science-based observing through a number of initial scientific Task Teams (*OceanGliders* TT). They are developed in the following section, but one Task Team in particular relates to the smooth, coordinated functioning of each TT with each other and with the rest of the GOOS: the data management TT. This team aims to address the needs of long-term observation aspects of data management, benefiting the wider community, supporting and encouraging scientists designing and executing process studies, as well as engineers developing new gliders, sensors, and computing

<sup>2</sup><http://www.coriolis.eu.org/Data-Products/Catalogue#/metadata/589bfa51-2219-4cc8-a19e-83f3c3f27bb4>

<sup>3</sup><https://portal.aodn.org.au/>

<sup>4</sup><https://gliders.ioos.us/data/>

<sup>5</sup><https://www.ego-network.org/dokuwiki/doku.php?id=public:goosgstt>

**TABLE 2** | Summary of *OceanGliders* terms of reference and objectives.

Purpose	To provide scientific leadership to promote and strengthen the glider community and facilitate their sustained use globally in order to respond to the integrated requirements of the Global Ocean Observing system (GOOS). Oversee the development and implementation of a global-scale glider array for observing key regions of the ocean on the long term, based on national and regional projects ( <a href="https://www.ego-network.org/dokuwiki/lib/exe/fetch.php?media=public:gst:glider-st_tor.pdf">https://www.ego-network.org/dokuwiki/lib/exe/fetch.php?media=public:gst:glider-st_tor.pdf</a> )
Membership	Anyone willing to contribute to the different Task Teams is considered as a member, keeping in mind the focus on developing sustained glider activity and the “Framework for Ocean Observing.”
Steering Team	Reflect and represent the sustained glider activity and to drive <i>OceanGliders</i> toward its goal of filling gaps in GOOS/GCOS
Exec Committee	Chair, co-Chair, Task Teams Leaders and GOOS advisor
Task Teams	Design network, define targets for Task Teams missions (optimum strategy) Define science implementation plans Describe scientific requirements and societal requirements Describe the global costs and cost-effectiveness Define the contribution of Task Teams in a multi-platform system designed to address scientific and societal issues, including unique roles of gliders
Meetings	Annual Steering Committee meetings

technologies to participate in metadata and data management. Data management implies not only data repositories of a certain standard, but the guidance and coordination in the development of new standards and best practices (Pearlman et al., 2019) for data collection, processing, and quality control. Data management requires metadata and its description, storage, and access. One of the benefits of coordination will be improved and sustained quality control of glider data.

### Network Monitoring and Data Dissemination

One main goal for glider operators is to make data publicly available and in particular to publish data in near-real time on the GTS (Global Telecommunication System) and in CF (Climate and Forecast) compliant formats for operational services. They provide their metadata and data to a Data Assembly Center (DAC) in charge of the data management and linked to a Global Data Assembly Center (GDAC) for further dissemination and archive. Three *de facto* GDACs are currently operating: Australia (IMOS), Europe and partners (EGO/Coriolis), and the United States (IOOS). Each GDAC has adopted similar strategies and conventions: CF-compliant NetCDF observation file formats can be uploaded by operators, and public sites and tools are provided for downloading and visualization. There are minor differences in formats, and the implementation of tools for raw file conversion, discovery, download and visualization varies widely. Numerous regional and local efforts have developed important tools but this has made it painfully obvious that coordination is needed for global-scale visibility and availability of ocean observations of known quality control. Initial efforts by IMOS, EGO/Coriolis and IOOS at collecting daily glider data

illustrate some of the extent of glider activity worldwide over the past decade (Figures 1, 2). This also represents the commitments from glider teams that have fed these systems, showing most of the glider deployments carried out so far in the world. The next step of unifying and providing data seamlessly from any region through one portal must be simpler. Already, the three GDACs have shared detailed information on how to upload, discover, download, and visualize using their tools. Simplifications have been made to provide easy access among the GDACs. This information will be centralized as in Figure 3 and accessible on the *OceanGliders* website [www.oceangliders.org](http://www.oceangliders.org) and will be an important tool to monitor global glider activity and promote its objectives.

The first dedicated global glider data management meeting has stimulated further developments (Genova, Italy, 17–19 September, 2018). Besides sharing expertise and latest developments at the regional level, this meeting produced a global consensus about how glider data can be made more useful to society, considering both historical and near real time data sets, now and in the future. Short-term goals include: setting up a solution to access all glider data in a single format; define indices for glider activity monitoring; handling the real time and delayed mode quality controls and assessments at the global level. Further development and sharing of best practices on data and metadata management are key for the *OceanGliders* Data Management Task Team. To that end, there is now a new central directory at [www.oceanbestpractices.net](http://www.oceanbestpractices.net), hosted by IODE, for *OceanGliders*.

Glider-specific tools have been developed at the GDAC and regional/institutional (or DAC) level to complement the other elements of the GOOS. The unique trajectory character of glider data, and of the wide range of metadata can cause these tools to be quite complex. Even the familiar concepts of “cruise,” “mission,” “transect,” and “profile” do not adequately describe the nature of glider flight and programmable behavior in real time.

There are too many to exhaustively list here, but notable examples include: GliderScope<sup>6</sup> (Hanson et al., 2017), IOOS<sup>7</sup>, EGO GFCP<sup>8</sup>, NorGliders GliderPage<sup>9</sup>, SOCIB<sup>10</sup> (Troupin et al., 2015), MARS<sup>11</sup>, and GANDALF<sup>12</sup>. Going forward, standardized data and metadata interfaces will benefit the future development of such tools and enable easier, global access to the full set of quality-controlled glider data and metadata [e.g., the Sensor Web Enablement framework and associated standards (Bröring et al., 2017)].

### Emerging Requirements

Glider data management will need to encompass developments within the glider networks, the GOOS and outside of the oceanographic domain in order to anticipate future changes in global data management. The implementation of Findable-Accessible-Interoperable-Reusable (FAIR) data principles is a

<sup>6</sup><http://imos.org.au/gliderscope/>

<sup>7</sup><https://gliders.ioos.us/map/>

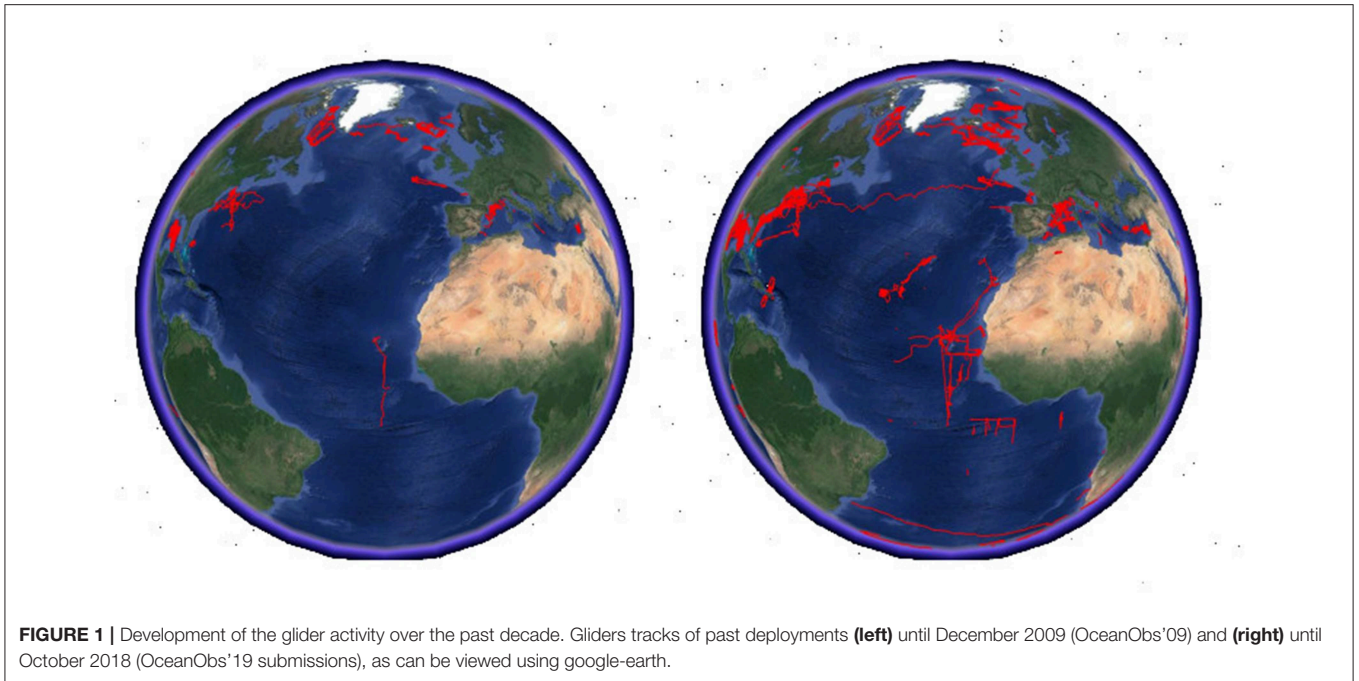
<sup>8</sup><https://www.ego-network.org/dokuwiki/doku.php>

<sup>9</sup><http://gp.gfi.uib.no>

<sup>10</sup><http://www.socib.eu/?seccion=observingFacilities&facility=glider>

<sup>11</sup><https://mars.noc.ac.uk/>

<sup>12</sup><http://gandalf.gcoos.org>



common theme in environmental data management and will place demands for development on glider data infrastructure (Tanhua et al., 2019). The integration of data from different networks within the GOOS and the implementation of new Essential Ocean Variables (EOVs) are also emerging as requirements. Furthermore, additional demands on data management will emerge with such as automated piloting (e.g., Chang et al., 2015; Smedstad et al., 2015) and operational glider network monitoring technologies.

## ADDRESSING GLOBAL OBSERVING NEEDS

The *OceanGliders* group met to discuss possible areas of focus and beyond the central need for improved data management, identified three key areas of focus for the developing program. These areas of interest were organized into Task Teams (TT) whose goals are to address the societal needs for ocean data and to entrain the community into discussions around the role of gliders in meeting these needs. It is expected that the mission-based TTs will organically develop by organizing the different initiatives into integrated and coordinated global efforts.

### Boundary Currents

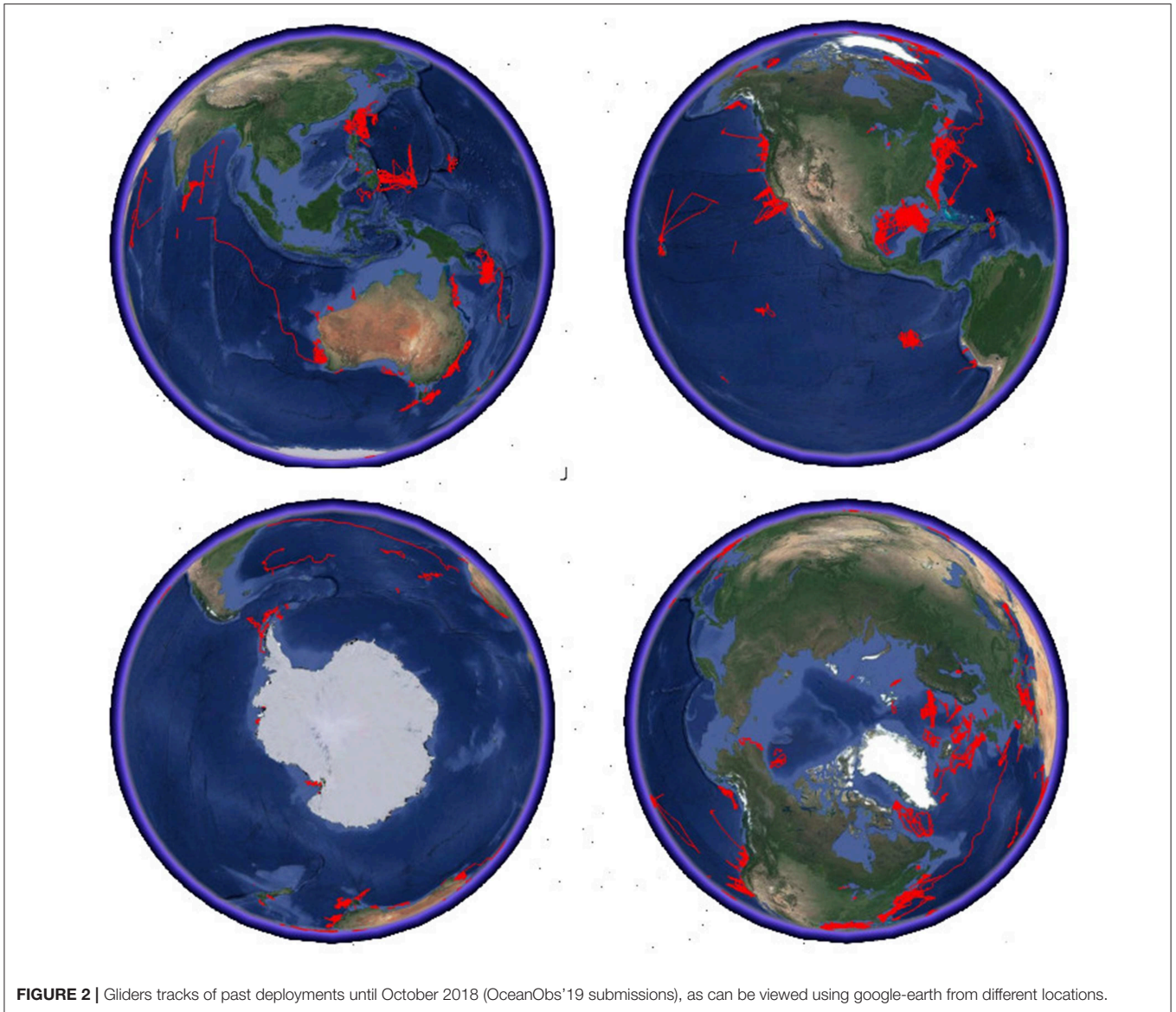
Society experiences changes in the global ocean at the ocean's boundaries. These boundary regions are the nexus of societal use of the ocean for fisheries, transportation, and recreation. The boundary regions are also where the intense ocean currents are key to the transport of mass, heat, salt, biogeochemical variables and plankton. In the large ocean basins, the subtropical western boundary currents dominate the surface poleward transport of warm water or equatorward transport of cold water at depth

and are major drivers of climate variability. Subtropical eastern boundary currents are often upwelling systems that comprise some of the most biologically productive regions in the world and host the world's Oxygen Minimum Zones (OMZ). Subpolar eastern boundary currents induce significant poleward heat transport in the downwelling eastern part of the subpolar gyres. Boundary currents in marginal seas provide the major means of exchange with the open ocean and impact regional ecosystems. Finally, the communication between the coast and open ocean is regulated by the boundary currents that flow along the continental slopes, affecting ecosystems, flood levels, erosion and commercial activity. To summarize, there is a great need for sustained observations of these highly dynamic boundary current regions.

Underwater gliders are particularly effective at measuring and monitoring subsurface biogeochemical fields that are both key to marine ecosystem productivity and involved in some of the most pressing ocean challenges like ocean acidification and hypoxia. For instance, glider capabilities are well-suited to sample the upwelling source waters transported to the edge of the continental shelf by eastern boundary currents. Recent studies in the Pacific and Atlantic reveal details of the spatial structure and time evolution of, for example, low-oxygen zones in such regions (Pierce et al., 2012; Pietri et al., 2013; Adams et al., 2016; Pizarro et al., 2016; Thomsen et al., 2016; Karstensen et al., 2017).

From their earliest conception, underwater gliders were viewed as components of observing/modeling systems, and progress over the past decade has proven the efficacy of this approach. The data provided by underwater gliders are a natural match for regional models of coastal ocean circulation. These regional models are necessary, as the currents and water properties in the coastal ocean vary on the relatively small scales





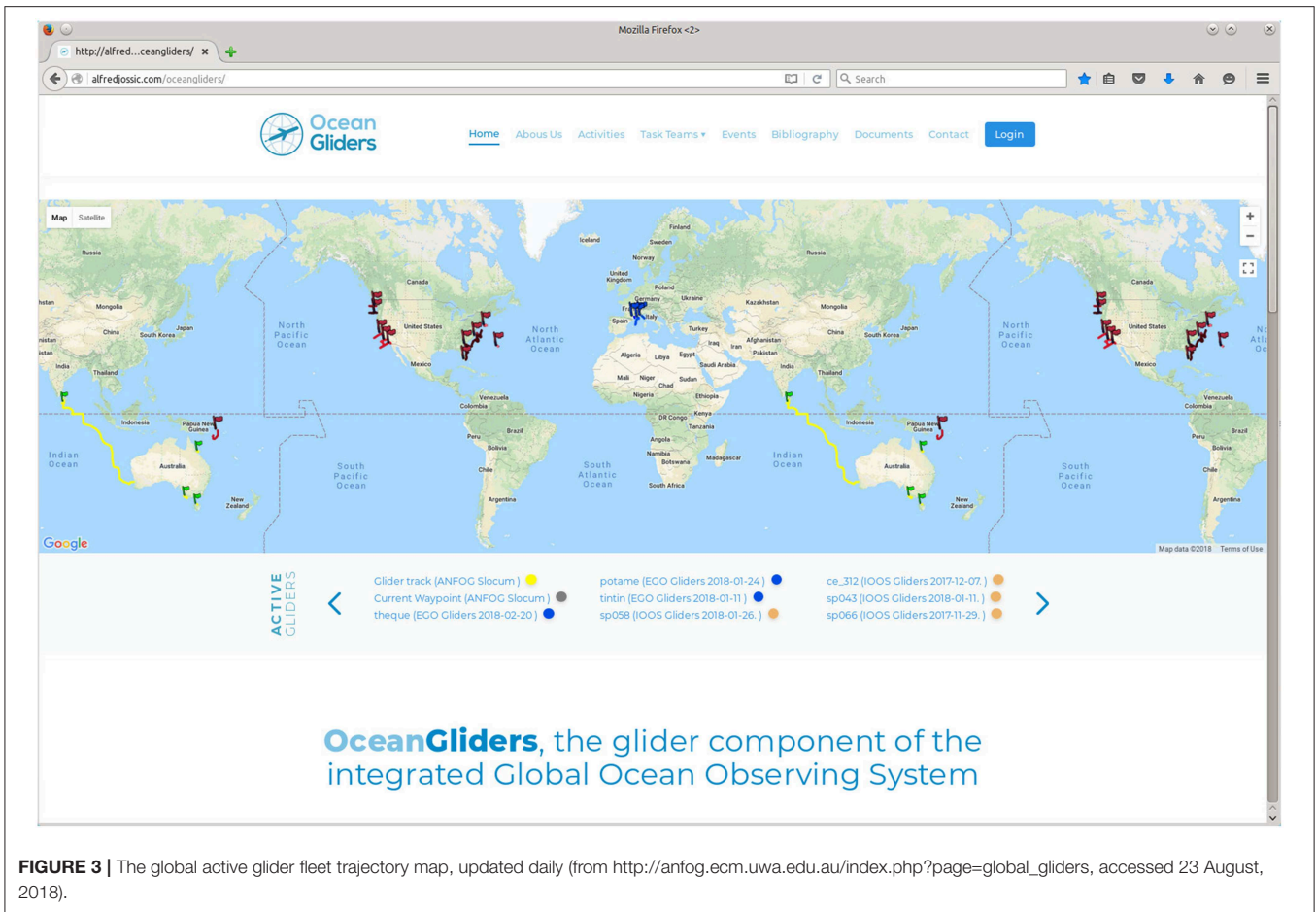
set by topography. Accurate forecasting depends on initialization on these small scales, which can be satisfied by a network of gliders.

The most widespread application of sustained glider programs has been in boundary currents. These efforts range from the significant western boundary currents, to the highly productive eastern boundary upwelling systems, to regionally important boundary currents in marginal seas. Initial targets are often the mean and variability of velocity, temperature, and salinity, and now moving to include biogeochemical and biological variables. As the sustained time series increase in length, interannual climate variability is resolved. The remarkable increase in sustained glider observations in the last 10 years is summarized below and illustrated by **Figures 4–6**.

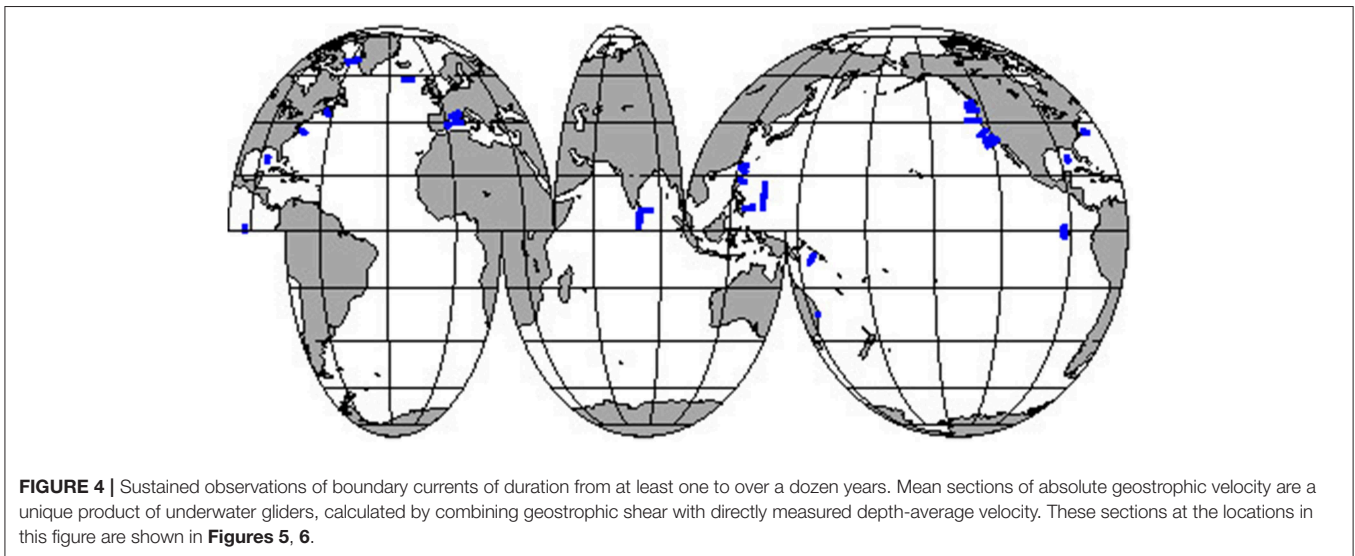
Sustained projects in the Atlantic include observations on the western, eastern and northern boundaries of the North Atlantic. The marginal seas of the Atlantic, including the

Mediterranean and the Gulf of Mexico are also home to long-term observations.

- The Davis Strait was observed repeatedly during 2005–2014 to quantify the exchange between the Arctic Ocean/Baffin Bay and the subpolar North Atlantic (**Figure 5A**; Beszczynska-Möller et al., 2011; Curry et al., 2014; Webster et al., 2015). Although this effort succeeded in collecting year-round observations across the seasonally ice-covered strait, challenging logistics, harsh operating conditions and funding prevented continuous occupation of the section over the entire 2005–2014 period.
- The warm water paths of the North Atlantic Current over the Rockall-Hatton Plateau at 58°N are being observed using repeat glider sections between 15 and 21°W as part of OSNAP since 2014 (**Figure 5E**; Houpert et al., 2018; Lozier et al., 2019).

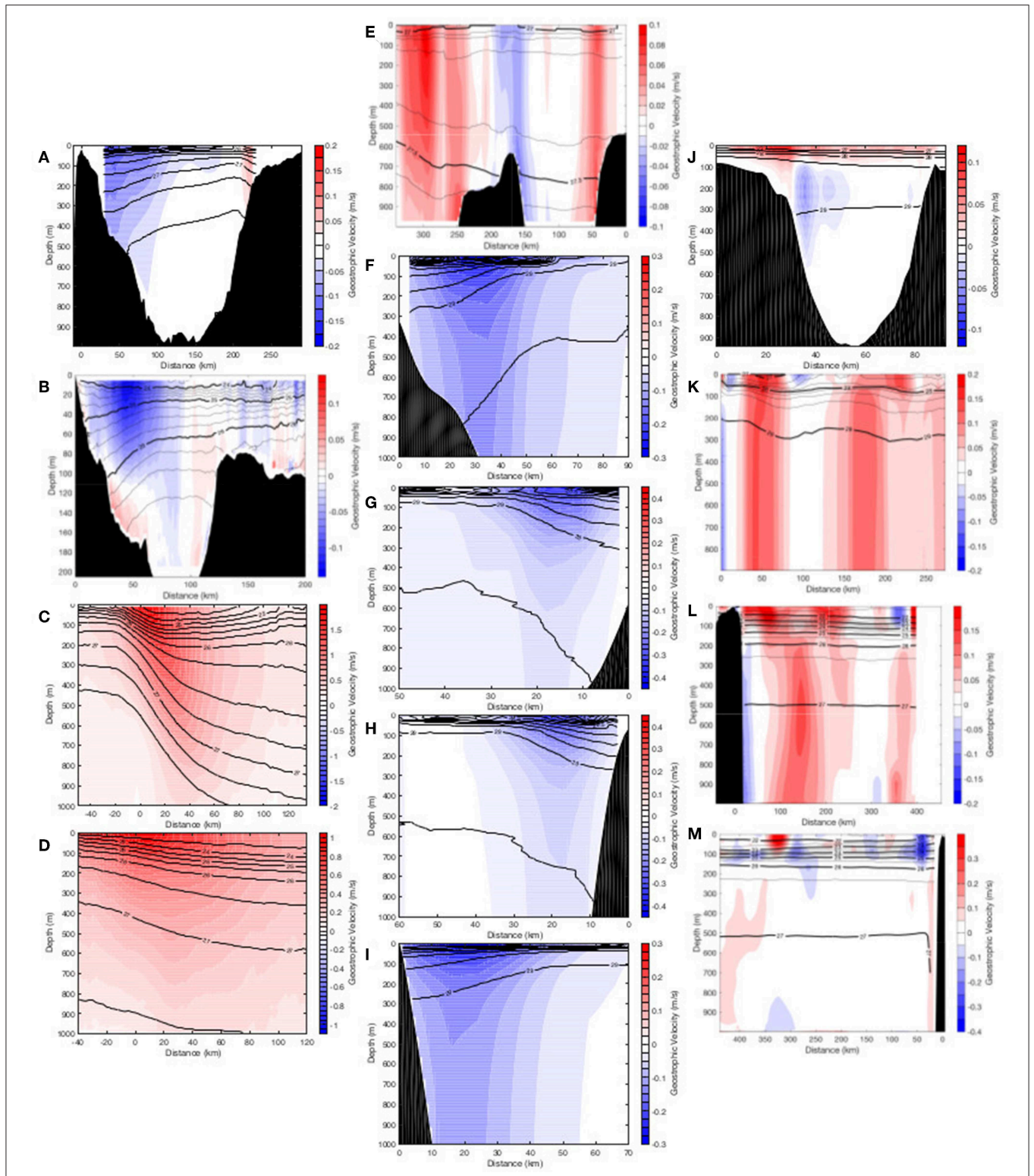


**FIGURE 3** | The global active glider fleet trajectory map, updated daily (from [http://anfog.ecm.uwa.edu.au/index.php?page=global\\_gliderns](http://anfog.ecm.uwa.edu.au/index.php?page=global_gliderns), accessed 23 August, 2018).

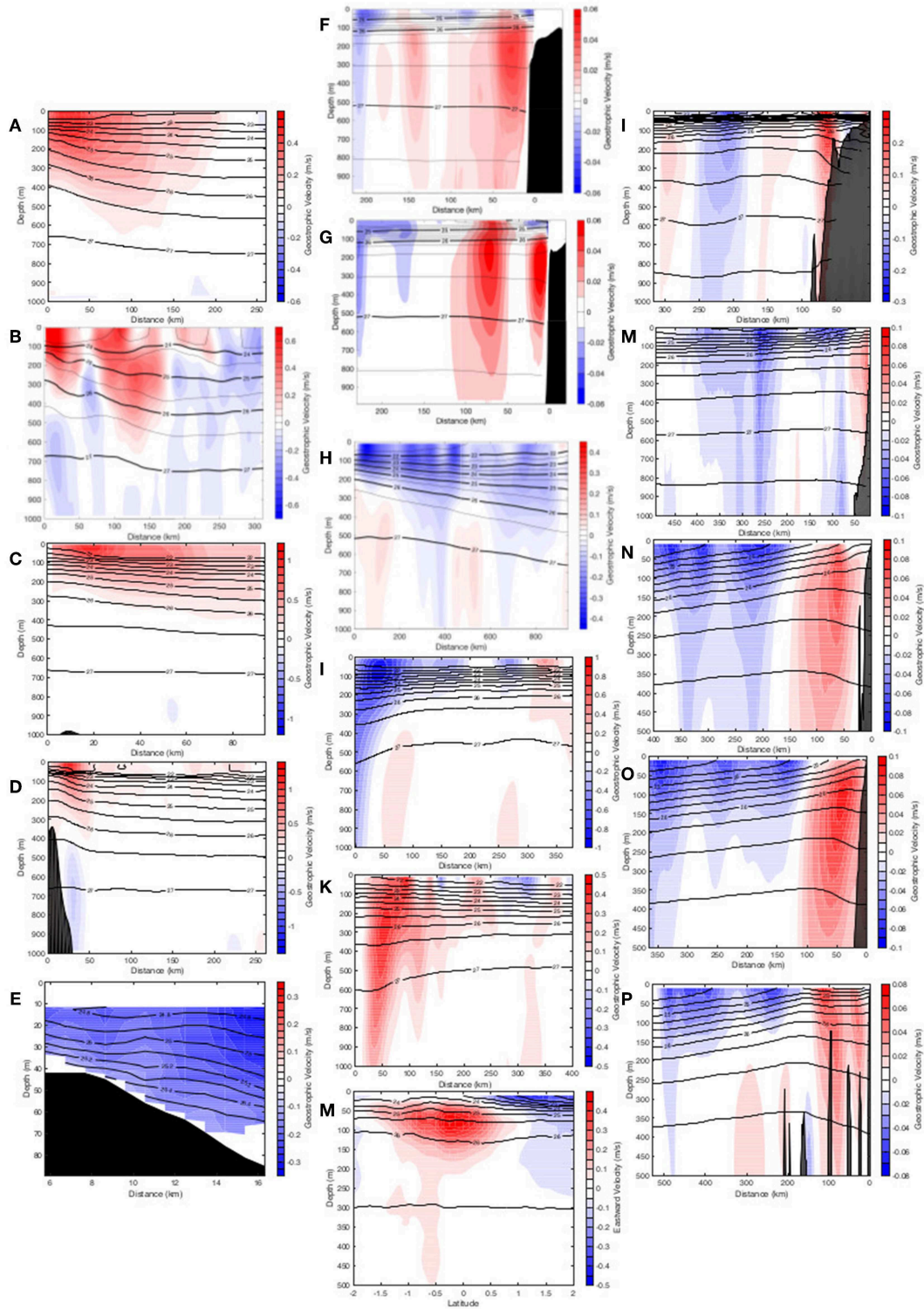


**FIGURE 4** | Sustained observations of boundary currents of duration from at least one to over a dozen years. Mean sections of absolute geostrophic velocity are a unique product of underwater gliders, calculated by combining geostrophic shear with directly measured depth-average velocity. These sections at the locations in this figure are shown in **Figures 5, 6**.

- The Nova Scotia Current was observed during 2011–2014 by repeat glider sections as part of the Ocean Tracking Network (**Figure 5B**; Dever et al., 2016) and re-established by Fisheries and Oceans Canada in 2018 as part of its monitoring programs.
- Along the East Coast of the United States, a program of routine glider surveys across the Gulf Stream is underway. Commanded to steer across strong currents of the western boundary current, gliders are able to occupy cross-Gulf Stream transects as they are advected downstream (**Figure 5C**; Todd



**FIGURE 5 |** Mean sections of geostrophic velocity from the Atlantic, Mediterranean and Indian Ocean. Sections in the Atlantic include (A) the Davis Strait, (B) the Nova Scotia Current off the east coast of Canada, (C) the Gulf Stream off the eastern US coast, (D) the Gulf of Mexico Loop Current, and (E) the North Atlantic Current west of the UK. Sections in the Northern Current System of the Mediterranean Sea are (F–I) along the southern coast of France, (J) between the Spanish coast and the island of Ibiza, and (K) between Sardinia Island and Menorca. In the Indian Ocean, sections are off the (L) east and (M) south coast of Sri Lanka. The sections are oriented generally west to east or south to north, and positive geostrophic velocity is primarily northward or eastward.



**FIGURE 6 |** Mean sections of geostrophic velocity from the Pacific. Sections in the western Pacific include the Kuroshio offshore of (A,B) Taiwan and (C,D) Luzon, and in (E) the East Australian Current, (H) the North Equatorial Current, (I) the Mindanao Current, and (J) the New Guinea Coastal Current of the Solomon Sea. Sections in the eastern Pacific include (F,G) two off Washington, (L) one off Oregon and four off the California coast at (M) Trinidad Head, (N) Monterey Bay, (O) Point Conception, and (P) Dana Point. A mean section across the equator at 93°W off the Galapagos (K) was measured by acoustic Doppler profilers, as geostrophy falls at the equator. The sections are oriented generally west to east or south to north, and positive velocity is primarily northward or eastward.

et al., 2016, 2018; Todd, 2017; Todd and Locke-Wynn, 2017; Gula et al., 2019).

- The Gulf of Mexico Loop Current was observed starting in 2007, and continuously during 2011–2014 with a focus on mean structure, eddies and separation processes (**Figure 5D**; Rudnick et al., 2015; Todd et al., 2016). Along-gradient glider trajectories of mesoscale eddies ubiquitous in the central and western Gulf of Mexico have been repeatedly carried out since May 2016 to present as a component of a quasi-continuous (90% of time) monitoring program conducted by GMOG.
- European Slope Current at 56.5N as part of the sustained Ellett Line program. Gliders have been occupying this section in winter since 2009, and several times per year since 2015 (Sherwin et al., 2015).
- In the Western Mediterranean, repeat glider transects have been conducted to monitor the variability of the Northern Current System, over 10 years in the north of the basin (**Figures 5E–H**; Testor et al., 2018), for 6 years at a circulation “choke” point (**Figure 5I**; Heslop et al., 2012), for 8 years at the Mallorca Channel (Barceló-Llul et al., 2019) and more recently between Sardinia and Balearic Islands (**Figure 5J**) and between Mallorca Island and the African coast (Cotroneo et al., 2016; Aulicino et al., 2018).
- The Norwegian Atlantic Current Observatory has undertaken long term glider monitoring across 2 transects over 4 years, monitoring northward flow to the Arctic regions (Høydalsvik et al., 2013). Gliders have been used to monitor the topographic steering of warm Atlantic waters toward Arctic tidewater glaciers on the west Spitsbergen margin (Fraser et al., 2018).
- Since 2012, gliders have been deployed in the Subantarctic Zone of the South Atlantic each year, as part of the Southern Ocean Seasonal Cycle Experiments (SOSCEX; Swart et al., 2012). Deployment have covered all seasons except late austral autumn to assess bio-physical interactions from sub seasonal to seasonal scales (Du Plessis, 2015; Swart et al., 2015; Thomalla et al., 2015; Little et al., 2018; Du Plessis et al., 2019).
- Repeated sections were carried out off Cape Verde Islands as part of the Collaborative Research Center 754 (DFG; Oschlies et al., 2018), Senegal (Kolodziejczyk et al., 2018) and Angola, primarily to study the OMZ.

Projects in the Indian Ocean range from the Bay of Bengal to the currents that connect to the Southern Ocean:

- Gliders in the Bay of Bengal off the east and south coasts of Sri Lanka (**Figures 5K,L**; Lee et al., 2016).
- Repeated sections in the Agulhas Current since 2017 as part of Gliders IN the Agulhas (GINA; Krug et al., 2018) following the Shelf Agulhas Glider Experiment (SAGE) in 2015. Initial results include observations of cyclones on the inshore edge of the current (Krug et al., 2017).
- Many cross sections of the Leeuwin Current, the poleward flowing eastern boundary current in the southern Indian Ocean (Pattiaratchi et al., 2017).

Projects in the Pacific include sustained observations in the eastern boundary current of the North Pacific, and both the

midlatitude and low-latitude western boundary currents of the North and South Pacific:

- The Kuroshio off Taiwan (**Figures 6A–D**; Lien et al., 2014; Yang et al., 2015), the North Equatorial Current north of Palau (**Figure 6H**; Schönau and Rudnick, 2015) and the Mindanao Current off the Philippines (**Figure 6I**; Schönau and Rudnick, 2017) were occupied continuously from 2007 to 2014 to quantify transports and water masses as part of the project Origins of the Kuroshio and Mindanao Current (OKMC). Observations began again in 2017 with a line off Taiwan.
- Repeated sections across Solomon Sea were made for nearly a decade to monitor the low latitude western boundary current that feeds the Pacific equatorial current system from the Southern Hemisphere (**Figure 6J**; Davis et al., 2012).
- The California Underwater Glider Network has occupied three lines in the California Current System for the past decade with a primary goal of monitoring the regional effect of climate variability as caused by El Niño (**Figures 6N–P**; Rudnick et al., 2017). A fourth line off northern California has been occupied for 2 years (**Figure 6M**).
- The inshore edge of the East Australian Current (EAC) has had repeated sections run since 2010 (**Figure 6E**) to observe the separation of the current, and the momentum balance at that point (Schaeffer and Roughan, 2015), the hydrographic structure of the current (Schaeffer et al., 2016a), the biogeochemistry (Schaeffer et al., 2016b).
- Sections across the California Current, immediately south of the West Wind Drift bifurcation region, were occupied continuously from 2003 to 2009, and then annually, for 6–9 months per year, from 2010 to 2015 (**Figures 6F,G**). These observations provide data to advance the understanding of the regional response to climate variability and California Undercurrent Eddies (Pelland et al., 2013).
- The Ocean Observatories Initiative began occupying 5 sections off Oregon and Washington, starting in 2014 to address the influence of climate variability on eastern boundary ecosystems. One of these lines, off Oregon, has been occupied continuously since spring 2006 (**Figure 6L**; Mazzini et al., 2014).
- Repeated sections off Peru started in 2008 (Pietri et al., 2013) to study the Humbolt system.
- Repeated sections off Chile (Pizarro et al., 2016) primarily to study the OMZ.
- Repeated sections in the Coral Sea adjacent to the north Queensland coast (Australia) have been used to estimate boundary current transport (Ridgway and Godfrey, 2015).
- The Equatorial Current System was observed during 2013–2016 using acoustic Doppler profilers (Todd et al., 2017; **Figure 6H**), as geostrophy fails at the equator. These measurements were undertaken as part of the Repeat Observations by Gliders in the Equatorial Region (ROGER) program (Rudnick, 2016).
- Glider transects at 37.9°N across the East Korean Warm Current along the Korean Peninsula have been conducted since 2017.

Underwater gliders can measure absolute geostrophic velocity. The geostrophic shear may be calculated from glider sections by estimating the horizontal gradient of density. This shear is referenced to the depth-average velocity that is calculated by dead reckoning between navigational fixes at the beginning and end of dives. This absolute, depth-dependent geostrophic velocity normal to the glider section allows calculation of the transport of mass, heat and salt. These transports are the fundamental quantities needed for baseline monitoring of boundary currents. Much work has been done to quantify the scales resolved and the accuracy of the velocity. For example, high frequency motions, such as internal waves, are projected into spatial variability in a glider section, with the result that horizontal wavelengths longer than 30 km are resolved in midlatitudes (Rudnick and Cole, 2011). The accuracy of the depth-average velocity, is of order  $0.01 \text{ ms}^{-1}$ , as inferred in early design studies, and confirmed by decades of observations (Rudnick et al., 2018). The sustained observations have produced several estimates of the boundary currents (Figures 4–6).

The goal of the *OceanGliders* Boundary Ocean Observing Network (BOON) is to provide coordination for a global observing program. Because boundary currents invariably reside in EEZs, their observation must depend on regional efforts respectful of the coastal countries. The goal of BOON is to sustain observations year-round. The result will be a global network of regional networks that monitor boundary current variability across international borders to the world's benefit.

The *OceanGliders* BOON complements existing ocean observing networks. Argo has transformed ocean science with its global coverage. BOON connects Argo's observations of the open ocean with the coastal ocean by operating the transects that are required to monitor boundary currents. BOON expands the footprint of site-specific moorings of OceanSites by repeated sections that may connect to mooring locations. Repeated surveys by ships form the backbone for many existing regional efforts, in some cases going back decades. BOON will step change our ability to observe boundary current variability in real-time, across all seasons and in difficult conditions and locations, building on the historical record and improving temporal and spatial resolution by overlapping with these ship surveys. BOON will identify gaps in the observation of boundary currents, with the goal of filling them by the most appropriate technology (Todd et al., 2019).

## Storms

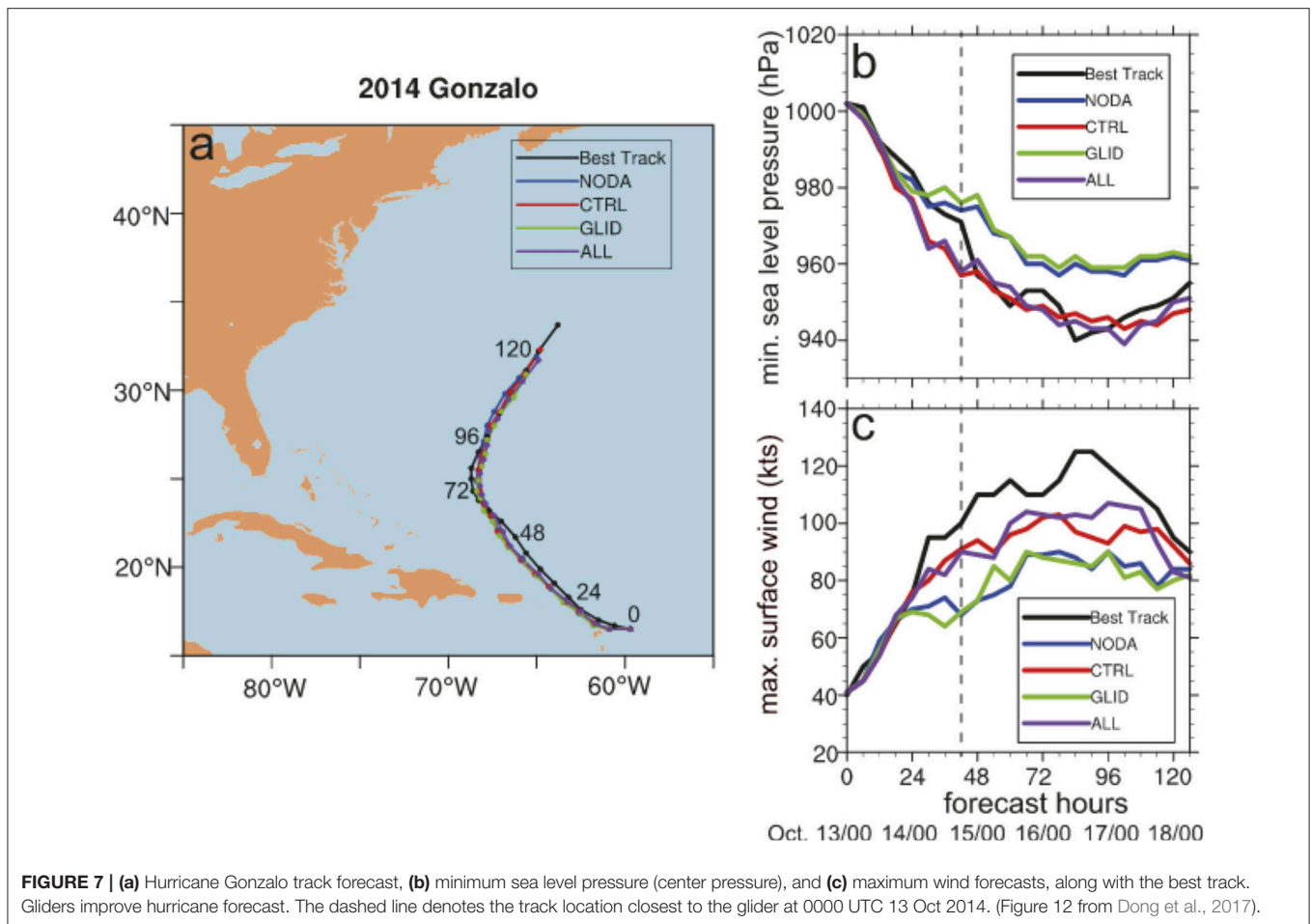
Tropical and extra-tropical storms are among the most destructive natural events on Earth. Tropical storms cause an average of 10,000 deaths per year and will potentially cost the global economy more than \$9.7 trillion over the next century. Growing coastal populations, urbanization, and rising sea levels magnify our vulnerabilities to storms, escalating the need for more accurate storm tracking, intensity and impact forecasts. Tropical storm tracking forecasting has shown steady improvement over the past 25 years due, in part, to the improvements in the global atmospheric forecast ensembles. But similar improvements in tropical storm intensity forecasts have

lagged, in part due to the paucity of upper ocean data defining its pre-storm heat content, the inability of operational ocean models to forecast with sufficient accuracy the rapid changes in upper ocean heat content in conditions of extreme forcing, and the uncertainty in the processes that influence the transfer of heat between the ocean and atmosphere. Tropical storm impacts, such as wind and storm surge, require accurate tracking and intensity forecasts.

Gliders have been the critical observing system element for two study areas in particular, one focused on an area of potential rapid intensification surrounding the Caribbean Islands, and another in the Mid Atlantic Bight where rapid intensity reductions have challenged forecasters.

In the tropical Atlantic and Caribbean Sea, early research carried out by NOAA/AOML, NOAA/NHC, and University of Miami scientists has demonstrated that the upper ocean is linked to hurricane intensification and/or weakening provided that the appropriate atmospheric conditions are present (Shay et al., 2000). For example, several studies have shown how major hurricanes, including Hurricane *Katrina* (2005), rapidly intensified while traveling over a warm Loop Current and Eddy feature in the Gulf of Mexico (Mainelli et al., 2008). Studies carried out for other Atlantic hurricanes have shown the close link between the upper ocean heat content and the intensity changes observed in Cat 3 and above hurricanes. Since this link has been established in this region, efforts are now geared toward improving hurricane intensification forecasts of numerical operational and experimental models to produce a correct representation of the upper ocean density (temperature and salinity) structure. For example, recent research has shown that the appropriate initialization of the ocean component within the HYCOM-HWRF intensity forecast model has improved the representation of the upper ocean while reducing the error of the intensity forecast of Hurricane *Gonzalo* (2014) by almost 50% (Dong et al., 2017; Figure 7). In this case, underwater glider data were critical to improving the hurricane forecast because they were the only ocean observations that captured the salinity-stratified barrier layer that inhibited the mixing of colder subsurface waters and subsequent upper ocean cooling ultimately allowing for hurricane intensification (Domingues et al., 2015).

NOAA OAR research has established the relationship between hurricane intensity and the Mid Atlantic's two-layer water column. The missing essential ocean feature is the unseen bottom Cold Pool. This vast (1,000 km long  $\times$  100 km wide) cold water mass ( $\sim 10^\circ\text{C}$ ) lies below a thin warm layer ( $>28^\circ\text{C}$ ) during the Atlantic hurricane season and is unobservable by satellites. By deploying autonomous underwater gliders ahead of Mid Atlantic land-falling hurricanes, the Cold Pool was mapped and its evolution monitored, leading to the discovery of rapid storm induced mixing that cooled the ocean ahead-of-eye-center by up to  $11^\circ\text{C}$  (Glenn et al., 2016). This new ahead-of-eye-center cooling process was shown to be region-wide in multiple hurricanes (Seroka et al., 2017) and is responsible for over 75% of the observed storm-driven cooling in the Mid Atlantic since 1985 (Glenn et al., 2016). Furthermore, the cooling of the surface ocean by the entrainment of the sub-surface Cold Pool was the missing component required to accurately forecast

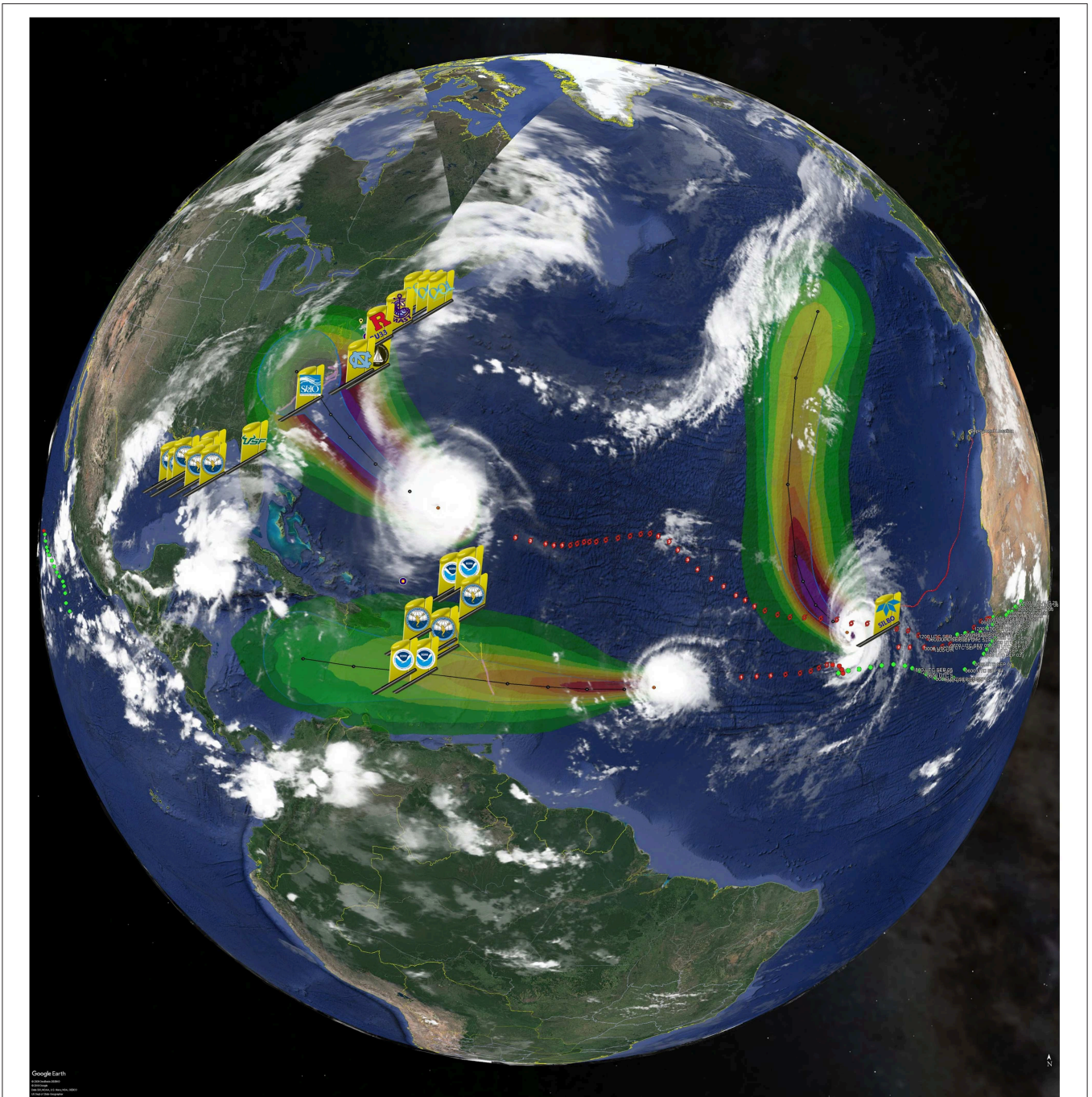


the rapid de-intensification of Hurricane *Irene* (Seroka et al., 2016). In stark contrast, gliders deployed ahead of Superstorm *Sandy* revealed a different Cold Pool response and impact on intensity. The onshore track, large wind field, and slow approach forced the Cold Pool more than 70 km offshore. This removed the bottom Cold Pool water and resulted in limited surface cooling and little storm weakening ahead of *Sandy*'s historic storm surge in the region (Miles et al., 2017). The warm surface layer and the bottom Cold Pool, and their rapid evolution during hurricanes, must be well-resolved to reduce the uncertainty of hurricane intensity predictions. This can only be accomplished with underwater gliders reporting whatever the sea conditions are, and real-time subsurface profiles over the GTS, since operational ocean models cut off satellite altimeter data assimilation for water depths <150 m, leaving satellite Sea Surface Temperature (SST) as the only operational data contribution on continental shelves.

Picket lines of subsurface gliders sustained for the hurricane season in areas of rapid intensity change where identified as the most critical addition to the integrated ocean observations required to improve the ocean component of coupled ocean-atmosphere forecast models. A U.S. collaborative effort between NOAA, Navy, NSF, Industry and Academia implemented the hurricane glider picket line concept for the first time during

the 2018 hurricane season. Data flow from individual glider operators to the GTS was coordinated through the U.S. IOOS Glider Data Assembly Center (DAC). The system was tested in September when 3 hurricanes were simultaneously present in the North Atlantic, each with gliders deployed in their path. This included Hurricane *Florence*, a category 4 storm at its peak that impacted the eastern seaboard of the US (Figure 8). The glider data transmitted over the GTS were used as input to the operational Ocean Heat Content maps that were used to help with NHC forecast intensity decisions.

*OceanGliders* supports the development of sustained glider observations to address hurricane issues worldwide as well as additional ones related to extra-tropical storms. Extra-tropical storms, also referred to as mid-latitude cyclones, are large scale (>1,000 km) low pressure weather systems that occur in middle and high latitudes and are associated with frontal systems. The wind speeds of these storms can be as high as those associated with tropical storms but their impacts last longer because of their greater spatial extent. Due to the large-scale features, extra-tropical storms are well-represented in atmospheric models. Hence, ocean gliders have mainly contributed to understanding the impacts of the storms on the ocean and coastal environments, particularly in terms of changes to the heat content (e.g., rapid



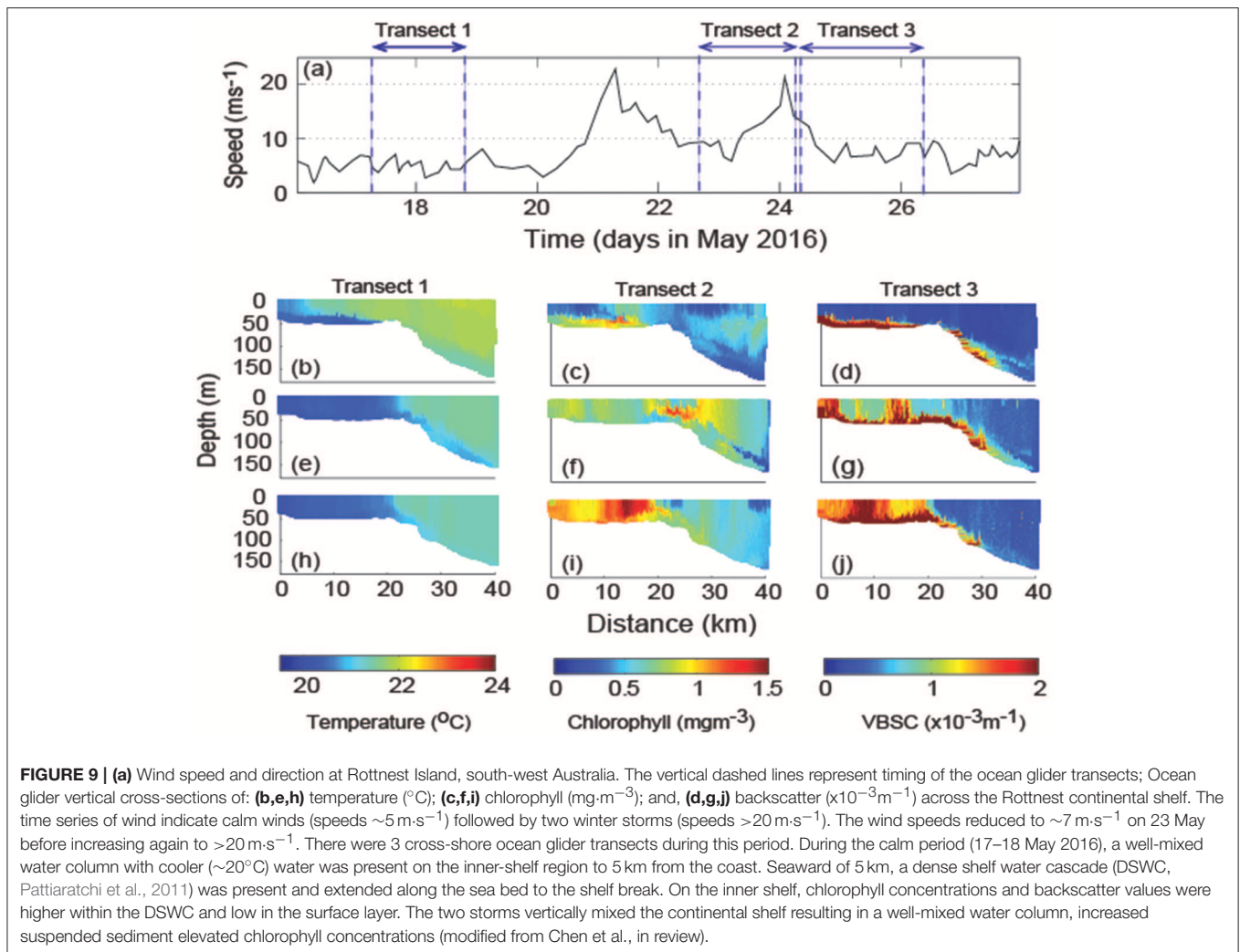
**FIGURE 8** | Hurricane Florence, Isaac and Helene cloudtops (left to right) on September 11, 2018, with NHC best tracks behind each hurricane, NHC probability of tropical storm force winds ahead of each hurricane, and the tails of the diverse fleet of ocean glider in the picket lines transmitting upper ocean data in near-real time to forecasters.

cooling), its feedback on storm intensity, sediment resuspension and transport processes, and ecosystem response.

Ocean gliders are complementary to other storm sampling systems in their ability to relatively rapidly profile the upper ocean and transmit data to land even during the most severe storm conditions (Domingues et al., 2019). They provide

unique datasets for studies of rapid upper ocean evolution and high-value profile data for assimilation in both operational forecast and research models before, during and after storms. Ocean glider measurements have revealed rapid changes in the distribution of water properties (temperature, salinity), and suspended sediment and chlorophyll (proxy for phytoplankton





biomass) concentrations. Gliders with turbulence packages are being used to quantify the strength of storm driven mixing and its relevance in supporting prolonged phytoplankton production (Swart et al., 2015; Nicholson et al., 2016) as also highlighted by data collected on the inner continental shelf along the Rottnest continental shelf in south-west Australia (Figure 9).

## Water Transformation

Physical, chemical, and biological properties are imported, redistributed, mixed and exported in substantial amounts by the oceanic circulation and processes. Any attempt to understand, model, and predict the evolution of the global and regional climates and marine ecosystems must include observations of their variability and their local and remote sensitivities to external changes. Indeed, fluctuation in any aspect is to lead to changes in the others, with the potential for feedback loops between them. While average conditions of the oceanic circulation and processes have been studied and assessed, little is known about the shifts in the system because of difficulties in observing water transformation phenomena directly and determining their (physical, chemical, biological) impacts.

Water transformation processes occur at relatively small scales and high frequencies not presently addressed by the GOOS. They are critical phenomena, however, that need to be assessed to better understand and model the evolution of the global/regional oceans, and in particular, their deep reservoirs of heat, salt, nutrients, etc. We do not know how these ocean processes influence change in these water properties. To fill this gap, the *OceanGliders* program proposes the long term and sustained observation of these phenomena with gliders whose unique capabilities (including under ice operations) and versatility allow the monitoring of such processes, in combination with other observing techniques, with sufficient accuracy. *OceanGliders* aims to address the two following global needs in ocean observations, by considering several key regions where water transformation processes that are important for the global (physical, chemical and biological) ocean occur.

## Open Sea and Shelf Water Formation

Much of what is known about the oceanic circulation derives from the fundamental concept of water mass. The global/regional ocean is composed of a limited number of water masses that

are formed (or transformed) in particular regions because of favorable local conditions (atmospheric regimes, stratification, topography, general circulation and major currents interactions) that can trigger buoyancy changes and the vertical mixing of the resident water masses in the surface and/or bottom boundary layers. Due to preconditioning effects (bottom topography, atmospheric forcing, stratification) the water formation processes lead to large mixed patches (100s km) presenting quasi-homogeneous (physical, chemical and biological) properties, and intermediate (100s of m, shelf/slope bottom) or sometimes deep (1–2 km, bottom) mixed layer depths, or thick (100s of m) bottom boundary layers.

The buoyancy decrease can be due to strong air-sea interactions (Swart et al., 2015; Houpert et al., 2016), sea ice and polynya formation in winter (Queste et al., 2015; Schofield et al., 2015), rough bottom topography (Beaird et al., 2013; Ruan et al., 2017), and major current instabilities (Schaeffer and Roughan, 2015). The water formation processes are common in winter in the subpolar gyres and high latitudes leading to the formation of the open ocean and shelf waters (Pattiaratchi et al., 2011; Durrieu de Madron et al., 2013; Bourrin et al., 2015; Peterson et al., 2017—**Figure 9**). It is so-called deep convection in few areas in the world where the mixing can reach great depths and ventilate the deep layers of the ocean due to peculiar and regional conditions (Testor et al., 2018). Later, in spring, these regions restratify, while the new water masses spread (or cascade on the ocean bottom) and mix with their surroundings. During this phase, intense blooms occur as the vertical mixing brought a large amount of nutrients in the euphotic layer and this can be sustained for a while by restratification processes (Queste et al., 2015; Schofield et al., 2015; Mayot et al., 2017), while the impacts on the benthic ecosystems can be important because of resuspended sediments. Mixing due to rough topography can also occur in overflow regions (Antarctic, Mediterranean, Denmark Strait) leading to the formation of new water masses and sediment resuspension (Durrieu de Madron et al., 2013, 2017; Venables et al., 2017) and through upwelling dynamics. The ice edge, presently in retreat toward the shelf, is a region of particular interest for water mass transformation, and gliders are ideal tools for exploring the marginal ice zone, as demonstrated in studies close to Greenland (Lee and Thomson, 2017; Våge et al., 2018).

These processes lead to the formation of water masses that move (together with their properties) through the oceanic basins interacting at the large scale with other water masses. This mixing can “buffer” or “memorize” climatic (physical, biogeochemical and biological) signals for long periods of time, until these water masses are mixed again vertically in the following years/decades/centuries, possibly far away (1,000s of km) from their formation areas. This water mass transformations can lead to rapid changes in the ocean, both locally and in remote places (Schroeder et al., 2017; Bosse et al., 2018).

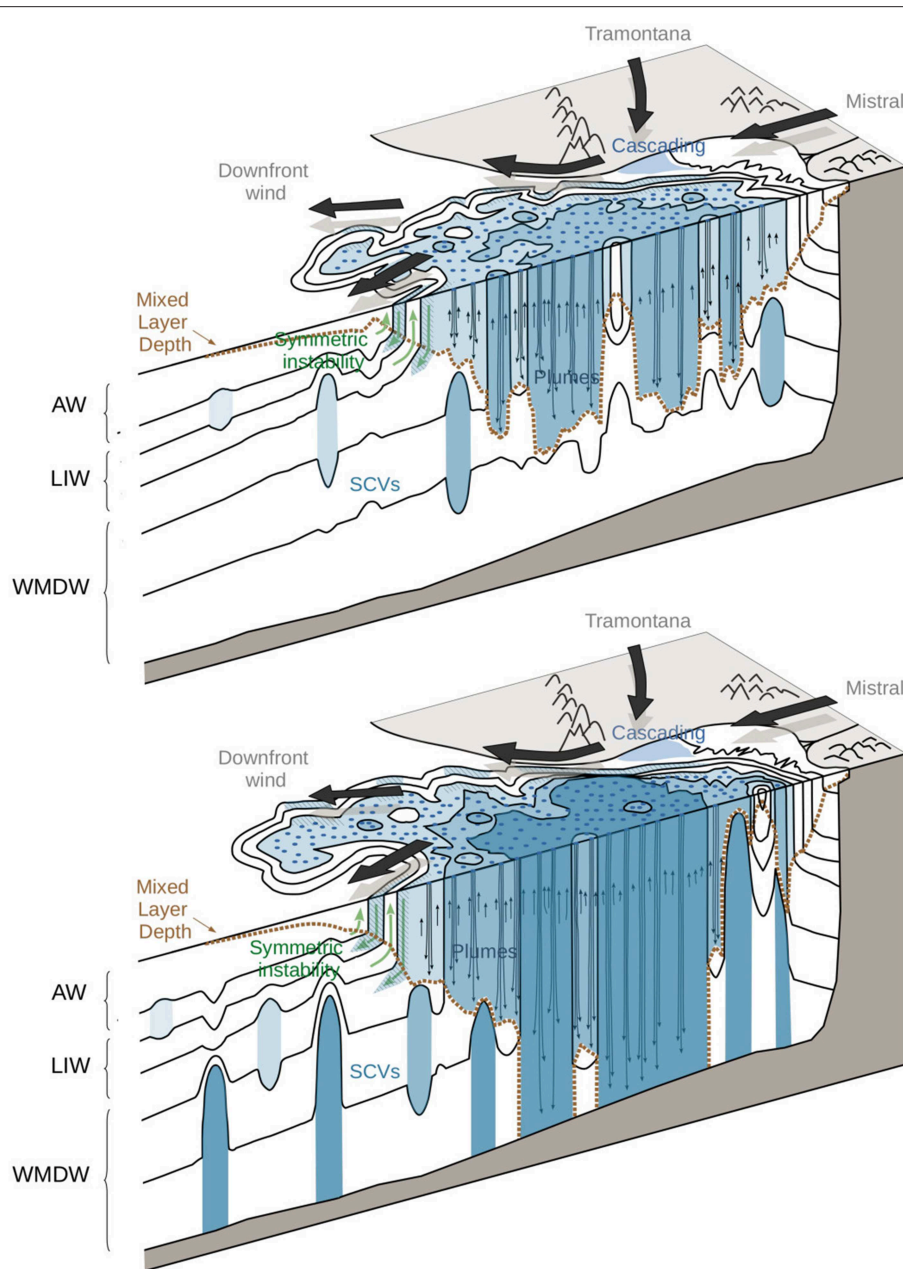
Presently the large-scale formation of mode waters in winter is relatively well-covered by the present GOOS, but not by other open sea and shelf water mass formations that are more constrained by the regional scale. These processes are critical to the ventilation of the ocean and the evolution of the marine

ecosystem, and this limits our understanding of the present state and evolution of the ocean and marine ecosystem. They occur sometimes in local patches on the shelf and in open sea, and on an intermittent basis, and are consequently not well resolved (temporally and spatially) at present. In addition, they generally result from different oceanic and atmospheric factors that encompass at least a year, owing to preconditioning effects (Durrieu de Madron et al., 2011; Bosse et al., 2018). This implies that sustained *in-situ* observing efforts must often be carried out in relatively large areas throughout the year to fully grasp the phenomena, with efforts occurring at a high frequency, and with high horizontal resolution to resolve the features that are involved. Moreover, in case of strong air-sea interactions in winter/spring, it is challenging to carry out traditional *in situ* measurements due to severe conditions at sea, for example winter convection in the Labrador Sea (deYoung et al., 2018). The observation of such phenomena remained a challenge until the use of autonomous underwater gliders, in combination with more classical ocean observing techniques. Much progress has been made during the last decade thanks to these relatively new platforms as demonstrated by many new publications on that subject (see introduction) and has led to a paradigm shift for deep convection (**Figure 10**). *OceanGliders* supports initiatives to fill these observational gaps in regions of water mass transformation in the coastal and open ocean.

### Mesoscale and Submesoscale Phenomena

Mesoscale eddies (10–100 km horiz.) occur throughout the ocean and are not well-resolved by the present GOOS, particularly their vertical structure. They are responsible for large fluxes of energy and matter in the ocean. Depending on whether they rotate cyclonically or anticyclonically, they can be rich or poor in nutrients and can provide favorable or unfavorable conditions for phytoplankton and other organisms. They can be surface constrained, centered at intermediate depths or even extend down to the bottom (even the abyssal plain) and resuspend sea-floor sediments (Durrieu de Madron et al., 2017). Between their cores and their surroundings, temperature can vary by several degrees and practical salinity by 1 g/kg or more, while biogeochemical properties such as oxygen saturation can vary from 0 to 100% and pH by more than 1 (Bosse et al., 2017; Karstensen et al., 2017—**Figure 11**).

Mesoscale eddies can have a sub-surface expression, typical of the water mass composing their cores, and some are undetectable by satellite which makes their observation a challenge. They can be very coherent and dissipate mainly through very small-scale processes (diffusion, microturbulence) making their lifetimes extend to months or even years (Yu et al., 2017). They are able to transport the physical, biogeochemical, and biological properties of the waters composing their cores over great distances (1,000s km) after their formation before they finally dissipate (Fan et al., 2013; Pelland et al., 2013; Bosse et al., 2015, 2016, 2017; Meunier et al., 2018a). They can dissipate due to dramatic events like vertical mixing driven by atmospheric forcing reaching into their cores or by interactions with other eddies, currents or topography. Their properties, particularly their biological ones, can also change drastically throughout their lifetime due to such

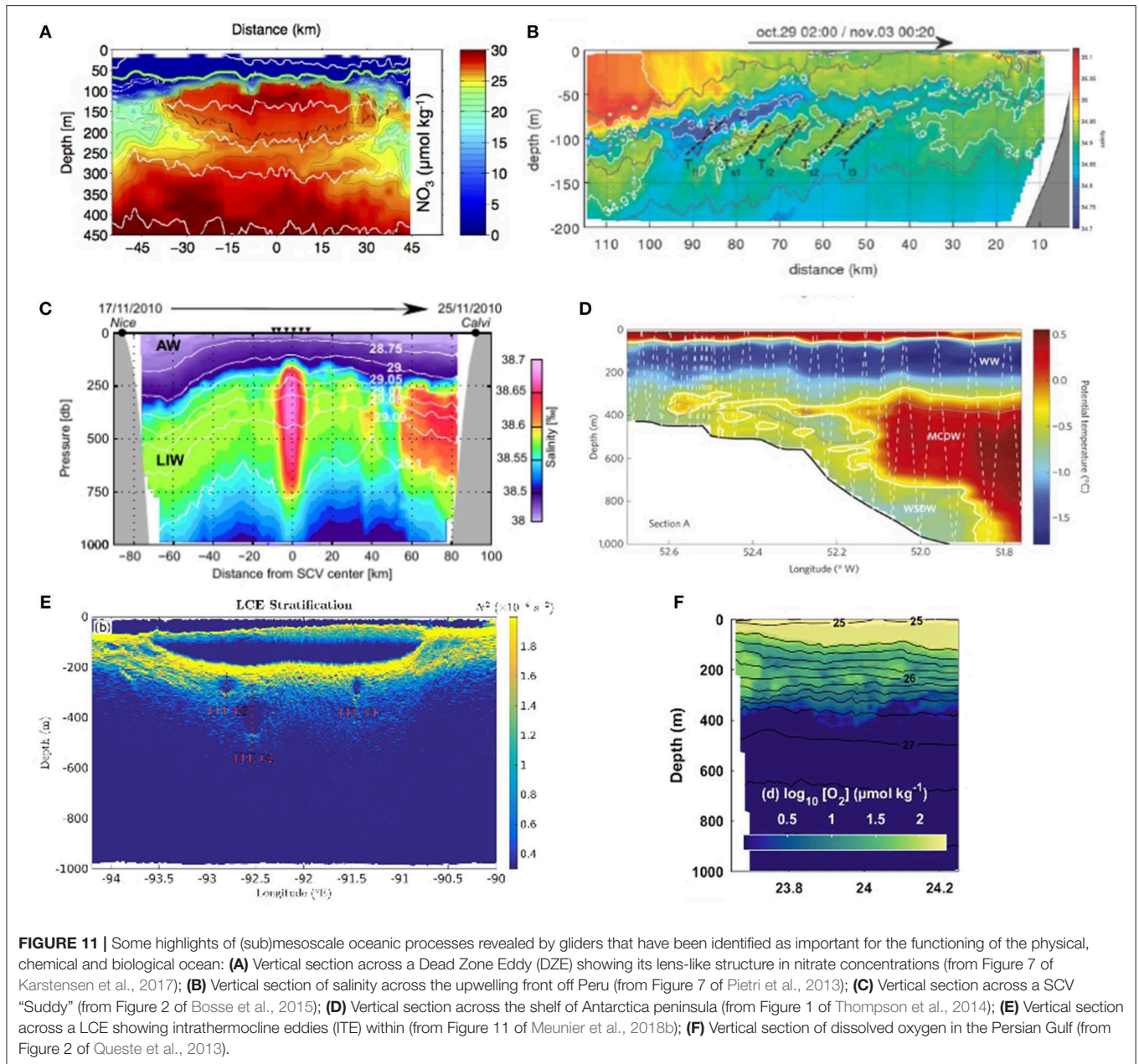


**FIGURE 10 |** Schematic diagram of the evolution of the convection area during the violent mixing phase in a period of 1–2 weeks. Underlying stratification/outcrop is shown by selected isopycnals (continuous black lines). The volume of fluid just mixed by convection is shaded and color coded according to potential density classes. (Figure 13 from Testor et al., 2018). Numerous glider deployments have allowed to objectively map the (physical and biogeochemical) evolution of the deep convection area on a 10-days basis for quantitative estimates while high resolution measurements allowed to investigate the small scale processes at stake.

external factors (McClatchie et al., 2012; Ainley et al., 2015; Villar et al., 2015; Durrieu de Madron et al., 2017). The impact of such factors on the properties of the eddy cores clearly depends on their vertical structure which in turn, depends on the oceanic (and atmospheric) conditions at their formation.

Mesoscale eddies can be formed through vertical mixing (due to air-sea-ice interactions or induced by rough topography, major current barotropic/baroclinic instabilities and/or detachments

from the boundary circulation due to the continental slope curvature (Caldeira et al., 2014) and/or other effects like upwelling (Bosse et al., 2015). Mesoscale eddies can be classified according to their formation mechanism because they present similar characteristics and core properties. It has been shown that a number of different types of eddies (Loop Current Eddies, Agulhas rings, Dead Zone Eddies, Gulf Stream rings, Meddies, Suddies, Weddies, Algerian/Sardinian Eddies, deep



convection SCVs, ITEs...) can have a great impact on the ocean circulation/ecosystem state and evolution through their particular structures and transport mechanisms. Other fine scale processes are clearly involved in the ocean mixing, like microturbulence (Fer et al., 2014; Palmer et al., 2015; Schultze et al., 2017) or frontogenesis, filamentation due to stirring or symmetric instability (Figure 11 and Ruiz et al., 2012; Thompson et al., 2014, 2016; Thomsen et al., 2016; Pietri et al., 2013; Brannigan et al., 2017; Buffett et al., 2017; Du Plessis et al., 2017; Pascual et al., 2017; Kolodziejczyk et al., 2018) that can lead to significant vertical velocities and fluxes. However, the extent and variability of their impact over long periods of time still needs to be assessed. The “mesoscale” dynamics and associated “submesoscale” features are important contributors to the ocean

state and are of crucial importance for biogeochemical and biological processes in the ocean. Gliders offer a new high-resolution lens for observing the full seasonal cycle, a dominant mode of the earth system, in their ability to observe the physical-biological coupling at sub-seasonal and sub-mesoscale (Martin et al., 2009; Swart et al., 2012, 2015; Monteiro et al., 2015; Thomalla et al., 2015; Du Plessis et al., 2017).

It is difficult for an *in situ* ocean observing system to capture all these important but relatively small circulation features, but a regular (annual) statistical assessment of the numbers and properties (and impact) of the main families of eddies and smaller processes can be achieved through subsurface, continuous and sustained glider observations of sufficient horizontal resolution. The time and space resolution

of the glider sampling, for a variety of different sensors, make gliders essential observing platforms for studies and continuous assessments of the role of (sub)mesoscale processes in the ocean circulation and ecosystem. Over the last decade, a remarkable number of articles on (sub)mesoscale dynamics and smaller scale mixing processes based on underwater glider data and their impact on biogeochemistry and biology has been published (see introduction). The importance of Submesoscale Coherent Vortices (SCV), filaments along fronts and around mesoscale eddies, and induced vertical movement, has been demonstrated from ground truth and their impact can now be monitored on the long term in key regions with gliders (Hristova et al., 2014; Bosse et al., 2016; Yu et al., 2017).

Underwater gliders do sample the vertical structure of the ocean in an unprecedented way, with high resolution along the horizontal over long periods of time. Gliders also transmit the observational data in near real-time. This remote access to observational data that resolves the (sub)mesoscale can improve forecasting the ocean dynamics, biogeochemistry and ecosystem. The glider data is a perfect match for assimilation in regional/coastal numerical models, providing ocean state estimates at small scales with increased accuracy benefiting societal applications. Gliders can map the subsurface ocean at high resolution and provide powerful tools for monitoring previously inaccessible ecological processes. *OceanGliders* promotes and supports all physical, biogeochemical and biological studies focusing on these small-scale processes and encourages long-term continuation of these studies. The anomalies caused by these (sub)mesoscale variabilities exceed by one order of magnitude those attributed to changes in large scale circulation and marine ecosystem variability brought about by a warming planet, as assessed by the IPCC (Bates et al., 2018) and must be considered to further our understanding and monitoring of the physical, biogeochemical and biological ocean.

## END-USER BENEFITS

In section Addressing global observing needs, we have detailed the unique “oceanographic” monitoring space that gliders occupy. Here we describe how this translates to benefit for the end users of a fully integrated observing system, i.e., what key roles (primary and supporting) a global sustained glider network can play in delivering services for both science and society.

Gliders can make sustained observations at high resolution, bringing temporal and spatial scales, hourly to sub seasonal and from 10 m to 1,000 km’s, relevant for a number of key ocean processes within economic reach. They are navigable and can be directed to sample ocean phenomena in real-time and with a fleet of gliders monitoring can be continuous, if required, and operational. Glider sensor payloads are expanding and their unique role in acoustic monitoring is already being exploited. They can sample in extreme conditions and to increasing depths, from surface to 6,000 m depth.

Gliders require pilots; however navigation is increasingly automated as a result of advances in platform reliability, community experience and piloting support tools. Glider observations require careful data processing protocols, an area

that is being actively resolved, with tools and services emerging, and standard products from several deployments (e.g., gridded sections, geostrophic currents, etc.) that could be more accessible to non-expert users, many of which are from the *OceanGliders* community. Although gliders are relatively “slow” samplers, this is not an impediment to providing sampling capability at key space and time scales for the global observing system.

Gliders are uniquely poised to deliver sustained and responsive observations to the GOOS in the following areas:

- Connecting coast to open ocean: key for monitoring the regional effects of climate variability, and of processes (circulation, currents, upwelling) that have an impact on regional ecosystems.
- Boundary current monitoring: key to the transport of heat, salt, biogeochemical variables (nutrients) and plankton, they influence ecosystems and therefore variability in ocean productivity, and impact flood levels, erosion and commercial activity.
- The observation of ocean state variables at a high density in time and space in order to gain insight into the variability/statistical distribution of these variables locally given the turbulent nature of ocean flows.
- Surface to deep profiles in extreme conditions: observing ocean structure that affects the strength of violent storms (e.g., hurricanes) and of violent ocean mixing.
- Sustained observations in the polar regions where ship persistence is challenging due to ice and harsh conditions.
- Fast deployment and real-time navigation enabling delivery of vital information for environmental disaster management.

Looking at these key sampling capabilities under the GOOS theme areas of climate, operational services and ocean health, it is clear that sustained glider monitoring, as part of a fully integrated global ocean observing system, delivers a range of benefits.

### Climate

- Monitoring boundary currents delivers knowledge on sub-seasonal variability and long-term trends that affect climate, leading to improved climate prediction. This information is used for adaptation to climatic change.
- Sustained 3D observations of deep and shelf water formation, a key component of our climate and ocean circulation system, provide knowledge to assess deep storage of heat, salt, nutrients and carbon sequestration. They uniquely can aid our understanding of variability in water formation and the impact of this on the global ocean budgets.
- Monitoring the subsurface development of climate oscillations (e.g., el Niño) aid prediction, support advanced warning capability and improved parameterization of climate patterns that affect seasonal forecasts.

### Operational Services

- Monitoring lines across key coast-to-open ocean transects (often boundary current regions) increase the accuracy of regional ocean forecasts, which have economic impact (e.g., offshore wind, powerful eddies that affect oil platform drilling, flood hazard warnings, abundance and location of commercial

- species) supporting reanalysis and prediction models, good for getting real time data back to inform the next modeling cycle.
- Glider deployments in the path of hurricanes and violent storms (tropical and extratropical) provide *in situ* water profiles of ocean structure and heat/salt content assimilated real-time into models, significantly increasing the accuracy of the storm intensity prediction, which is vital to regional government and emergency services.
  - Speedy deployments of gliders at pollution events, provide simultaneous data on ocean circulation and pollutants, either to track the pollutants or to improve ocean forecasts by providing data for assimilation. This supports decision making by better disaster management services and thus can reduce environmental impact.
  - Speedy and flexible deployments of gliders can enable co-located measurements with other air/ocean observing systems, which are key for advancing scientific understanding of marine biogeochemical-physical interactions and/or air-sea flux interactions across the oceanic surface. These can also help provide precious data points for future coupled data assimilation methods under active consideration for balanced initialization of coupled earth system models.
  - Sustained ocean sound monitoring delivers real time information on key marine mammal species, for ship avoidance decisions. Increasingly, this is a must for conservation of populations as new shipping routes increasingly intersect with marine mammal habitats.
  - Monitoring boundary currents or water transformation in key areas delivers knowledge on ocean changes, both sub-seasonal variability and long-term trends, that affect climate. Real-time information on these key components of the global circulation better constrain models and are used, for example, to increase the accuracy of forecasts for coastal regions.

### Ocean Health

- Sustained transects from coastal to open ocean, including boundary currents and water transformation areas, are key for monitoring the regional effects of ocean variability on regional ecosystems. Physical, chemical and biological information from these sections improves understanding of ecosystem response to environmental stressors (e.g., low dissolved oxygen, ocean acidification), aids regional ecosystem management and can provide ocean health monitoring indicators.
- Sustained acoustic (fish tags, passive acoustics for mammals, active acoustics for zooplankton) and video monitoring from coast to open ocean, deliver information assessing distributions and stocks as well as behaviors of marine organisms and response to environmental conditions that enables improved physical/ecosystem modeling, prediction, and resource management.

## THE WAY FORWARD

At present, global glider operations are still at the pilot stage and are not fully developed. There are some regional operations, e.g., the repeated glider transects off the west coast of the

United States, that are well-established and fully operational but full coordination of glider missions at the regional, basin or global scale, as discussed, remain in the planning stages. There has been enough activity to prove that we have the capability to conduct such operations but the development of clear scientific and operational goals for the proposed network remains under discussion. Indeed, this white paper is a contribution to that discussion and is meant to further stimulate consideration of the potential opportunities to fill gaps in the present networks of global ocean sampling.

Further developments should be framed with clear measurement goals and analysis of the appropriate technological solutions to address the observational challenges. There are now many different options to address the three themes of the GOOS: Climate, Operational Services and Ocean Health, including autonomous surface and underwater craft, drifters, subsurface moorings, ships of opportunity and research ships and satellite systems. All of the options should be considered to determine which solution, or mix of platforms, best meets the observational goals. We have some of the tools needed for this analysis but also need to work together as a community to optimize the design of the global observing system.

Ocean gliders, and other autonomous marine vehicles, are evolving and improving at a remarkable pace. Their endurance, related to battery capacity and sensor performance, continues to improve, as does their range of operations in both the coastal and open sea environments. It is now possible to sample the deep ocean with gliders, with developments that will enable us to routinely reach depths of 6,000 m, while missions of many months or longer are now routine. There is also a growing range of private companies building these systems providing a wider range of options. This diversity shows the wide interest in these platforms and builds our confidence in their further development and availability, which is a key aspect of sustainability. Performance in extreme conditions, such as winter conditions, and navigation under sea-ice, is improving, and there are very few places on the planet where they cannot operate. Autonomy continues to develop, while full operational independence is still quite a few years away. As with many new platforms, in the first few years enormous effort is required to setup and deploy them. After two decades of operation, the learning curve for new users is not as steep as it was because of technological improvements and because the global community supports new users. Internationally, the *OceanGliders* program will help the glider community focus on the GOOS requirements. It builds on several long-term glider observational programs that exist in Europe, Australia, Canada, the United States, Mexico, Peru, Chile, South Africa, New Zealand, etc. Further development and coordination among these initiatives, and new ones that form, will provide support for coordinated global operations.

Global observing systems have shifted from a primarily physical focus to expanded measurements, spanning biological and biogeochemical variables. Essential Ocean Variables (EOV) within the GOOS now span a wide range, including biogeochemistry, biology and ecosystems. There has been

a lot of progress in developing such sensors for gliders, for example, fluorometers for measuring phytoplankton have been in development for a long-time. So too have active/passive multi-frequency acoustic sensors been deployed on gliders to measure oceanic currents, surface wind intensity, zooplankton, and to detect acoustic small/large fish tags, marine mammals, sharks etc. Other sensors include imagery, as well as nitrate, oxygen and pH, carbon dioxide sensors, and various optical sensors to detect light, backscatter, attenuation, particles, harmful algal blooms and ocean acidification. However, the battery capacity of the gliders still limits the total range of sensors that can be deployed on a single vehicle. It is clear that further battery and sensor developments will enable a wider range of possibilities and demonstrate that the platform has potential for making an even wider range of observations than at the moment.

Data from ocean gliders are presently being used in operational ocean models and operational weather forecast models. The data are typically streamed in real-time through the GTS and are then available to all operational users. They have been used in research or pre-operational systems and improved weather forecast modeling and operational global and regional ocean forecasts such as Mercator Ocean, FOAM (Met Office), MFS (Mediterranean Forecasting System), BLUELink (Bureau of Meteorology, Australia), CONCEPTS (Fisheries and Oceans, Environment and Climate Change Canada and Department of National Defence, Canada), HYCOM/NCODA (USA), NAVOCEANO (US Naval Oceanographic Office), REMO (Brazil), TOPAZ/NERSC (Norway). Observation impact studies show the value of sub-surface hydrographic observations, such as those from gliders, in improving prediction. Moreover, data products can be created, such as data aggregations and mean fields, that are easily usable for model validation and assessment. In this paper we have presented plans to deploy gliders in the waters near hurricanes, in ocean boundary currents and in key areas of water transformation. Data from such deployments could provide critical information to improve the performance of ocean forecast models as ocean dynamics in such regions remains a modeling challenge for the next decade. Improved prediction at sub-seasonal to seasonal (S2S) scales requires use of ensembles (or super-ensembles) including those from ocean models. These ensembles can also provide a good representation of quantified uncertainty in time and space which could be targeted by future flexible positioning of underwater gliders in real-time or near real-time. Having a large network of gliders, potentially with different sensor packages and/or different measurement goals, will lead to piloting challenges on a day-to-day basis for individuals. Eventually the sampling patterns might be autonomously determined through use of data-assimilating models, remote sensing products, and other *in situ* measurements.

The increasing operational interest in gliders and glider teams' capability suggests that the applications mentioned in section End-user benefits could all become operationally routine within a decade. Looking further ahead there is much capacity for the use of gliders to expand, particularly in relation to ocean health and human pressures.

We envision that:

- Increase in sensor capability of gliders will increase their use for early warning of environmental stress or pollution (Verfuss et al., 2019), for example to manage compliance areas of ecosystem sensitivity.
- The weather/modeling community may invest in gliders in key ocean areas to support improved prediction, perhaps with artificial intelligence, smart models autopiloting the gliders in real-time in the regions of greatest uncertainty.
- Deep gliders will deliver the same insight on deep variability of currents, water mass, heat, salt, biogeochemical and biological variables, fundamentally changing our ability to model deep flow and thus climate scale predictions and seasonal forecasts. They will also be our cost-effective eyes and ears on the deep, policing infringement of deep mining and reporting on deep ecosystem health.
- Increasing battery life, introducing novel energy sources, and improving solutions to bio-fouling, will lower costs and extend glider operation time. This will allow for the monitoring of open ocean areas at low cost (there will still be a need to deploy them from small boats).
- International consortia will share sites for recovery/deployment, facilities for refurbishment, and even pilots to optimize operations worldwide and reduce the costs of operation and the loss probability.
- The cost of the gliders will decline as their numbers increase and the number of users worldwide increase.
- The glider's payload space will increase enabling them to carry a wider range of sensors and/or a different battery configuration.

In considering the application of gliders to problems such as boundary currents, water transformations or storms, a careful analysis of the measurement challenge should include consideration of other approaches to ocean observation. Gliders have strengths and limitations, as do all platforms and sensors, and both should be taken into account when designing an observing solution to address critical gaps in our global ocean observing strategy. Formal design exercises must be carried out with the other components of the GOOS considering its 3 themes: Climate, Operational Services and Ocean Health. Such design studies must consider all the societal benefits and needs of GOOS applications, including human impact, ecosystem, biodiversity and pollution assessments as well as sustainable management and marine hazard response (cf. GOOS strategic mapping<sup>13</sup>).

Numerical simulation experiments, using sophisticated coupled ocean-atmosphere models to determine the best mix of platforms and the tradeoffs in ocean sampling that result from deploying different systems should be carried out. However, this must be done while keeping a critical eye on the model's performances and this must not be the only basis when producing a design. While gliders may fill a critical role for a particular system, for example a particular boundary current, it

<sup>13</sup>[http://www.goosoocean.org/index.php?option=com\\_content&view=article&id=120&Itemid=277](http://www.goosoocean.org/index.php?option=com_content&view=article&id=120&Itemid=277)

may still be the case that a mix of moorings, drifters and other platforms would provide the best observational solution because of logistical constraints. It could be that biological requirements balance the needs of operational services, in a particular region in terms of resources optimization or the contrary, and so on.

The *OceanGliders* program can contribute to societal development and sustainability, and there are many examples of this potential already being achieved. These can be exemplified by activities that contribute toward achieving the United Nations Sustainable Development Goals (SDGs)<sup>14</sup>, of which SDG2 (Zero Hunger), SDG13 (Climate Action) and SDG14 (Life Below Water) are arguably most germane. Examples of glider networks making such contributions include deployments in climatically sensitive regions that are also important breeding and nursery grounds for foodwebs, and the focus of a significant fishing industry. Sustained glider missions in these areas conducted as part of whole-ecosystem research programs provide the underpinning scientific knowledge for ecosystems-based fishery management. Glider networks provide enhanced data collection and improved transfer of knowledge to policymakers, so as to support such societally-relevant sustainability activities.

It is important to consider the targeted phenomena, their space/time scales and EOV since they will impose requirements in terms of sampling. The different *OceanGliders* TT will define what “operational” means for them. The Boundary Currents TT requirements of sampling the seasonal cycle implies that “operational” means having gliders in water year-round, while Storms requirements imply having gliders in the water only during the storm periods, and Water Transformation requirements could be year-round or focus only on the winter/summer period depending on the water transformation phenomenon that is considered. Other requirements will emerge as the program develops with TT on biogeochemistry or polar regions for instance.

The world ocean will change. We need to assess those changes appropriately and must not underestimate what could be done with gliders. Without doubt, there will be more end-user engagements, new technologies on board, more connectivity, more sensors, more gliders and more users to address that. The flexibility of gliders allows complementarity, and this is an asset for their integration in the GOOS. The challenge for the next decade will be to build a GOOS glider component that will help the GOOS reach the right balance between its different components to deliver products for societal benefits and applications, through the monitoring of the required oceanic phenomena and EOV.

## VISION

Our vision is for a mature sustained global glider observing network by 2030. It will not only support regional, sustained operational deployment of gliders serving the present societal needs around operational services, ocean health and climate, but also solely allow new ocean observing applications in this framework. The outstanding capacity of gliders to play a role

as an agent of integration, across scales, from the coast to the open ocean, and from physics to biology, needs to be used to enhance the GOOS, integrating with its other components (*in situ* and satellites). These global glider operations will likely have different schedules of operation, carry different sensors, and serve different needs but will have a shared support system through the *OceanGliders* program that will allow them to work together efficiently, to govern and support the system, coordinating global glider operations and ensuring that the needs of society for ocean data are best met.

*OceanGliders* will support global standards and best practices to ensure that the operations and the data delivered can be monitored at the global scale. Improved data interfaces and standardized data will ensure quality-controlled data are easily found and effectively used. By 2030 one should be able to effortlessly, perhaps unknowingly, find and acquire quality-controlled physical, biogeochemical and biological data from gliders alongside an already huge range of earth observations and use them to address scientific, commercial, or policy initiatives. Attaining our vision would ensure that the value of observations to society will never be lost, indeed, will increase over time as they are used and reused and in new ways not originally imagined.

Here, we have identified three key areas for the *OceanGliders* program to focus on: Boundary Currents, Storms and Water Transformation. These represent interests heard from the glider and user community, but we expect more to develop, as the *OceanGliders* program matures. Moving forward, *OceanGliders* will have, together with a wide range of stakeholders and participants, to conduct a value-chain assessment to explore further needs of users to ensure that the network continues to be fit-for-purpose, as discussed in the Framework on Ocean Observing. Through this paper, we have sought to demonstrate, through exploration of some key thematic examples, the opportunities and potential benefits of coordinated deployment of ocean gliders to fill some key gaps in the existing ocean observation system. The precise form of such activity requires a comprehensive and integrated analysis of the needs for observation, that is the most broadly defined societal needs, and an assessment of the different approaches to observation, just one of which is ocean gliders. Such an assessment will have to address needs related to the three key thematic areas of the GOOS: Ocean health, Operational services and Climate.

In his seminal paper, Stommel (1989), foresaw an operational fleet of 300–550 gliders at any time evolving in the world ocean to support the GOOS by 2025. Only a substantial increase in global resources would yield such an outcome by 2030. We propose a more modest implementation of the *OceanGliders* global program for the next decade. Sustained observations of boundary currents are perhaps the most established capability of gliders relevant to the GOOS. A sensible goal is to have continuously 100 gliders in a sustained Boundary Ocean Observing Network within the next 10 years, with some additional gliders addressing Storms and Water Transformation issues where and when this fleet would not already do so. We are confident that operation of such a fleet of 100 gliders is achievable. Further development will rely on capacity building and would be driven by a combination

<sup>14</sup><https://sustainabledevelopment.un.org/?menu=1300>



of need and demonstrated benefit of the glider program. We have presented results from 25 boundary current sections sustained for a minimum of 1 year, and for as long as 12 years. While not all these 25 sections are currently sustained, the proof that they are operable has been made. An increase in this sampling by a factor of 4 is a relatively reasonable worldwide goal. The operational cost to keep one glider in the water for 1 year is approximately \$200K, thus 100 gliders would cost \$20M per year, a relatively affordable cost for a global component of the GOOS.

## AUTHOR CONTRIBUTIONS

The editorial team for this paper (PT, BY, DR, SG, DHa, CL, CP, KHi, EH, and VT) has collected the contributions of the other co-authors and coordinated the writing of the paper.

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