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Jennifer Montaña, Giovanni Coco, Jose a A Antolinez, Tom Beuzen, Karin Bryan, et al.. SHORECASTS: A BLIND-TEST OF SHORELINE MODELS. Coastal Sediments'19, May 2019, Tampa, United States. <10.1142/9789811204487_0055>. <hal-02394970>

HAL Id: hal-02394970

<https://hal.science/hal-02394970v1>

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SHORECASTS: A BLIND-TEST OF SHORELINE MODELS

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Abstract: Predictions of shoreline change are of great societal importance, but models tend to be tested and tuned for the specific site of interest. To overcome this issue and test the ability of numerical models to simulate shoreline change over the medium scale (order of years) we have organized a non-competitive competition where participants were given data to train their model (1999–2014) and data to predict seasonal to inter-annual future changes (2014–2017). Participants were shown the observed shoreline changes only after submission of their modelling results. Overall, 19 numerical models were tested, the vast majority falling in the broad categories of “hybrid models” or “machine learning”. Models were able to reproduce the mean characteristics of shoreline change but often failed to reproduce the observed rapid changes induced by storms.

Introduction

Understanding processes regulating beach erosion and recovery remains a fundamental challenge in coastal research due to the inherent uncertainty in predicting the future “drivers” (e.g., wave characteristics) and to our limited understanding of interactions between drivers and response (e.g., sediment transport). Still, given the ongoing climatic changes and that most of the world’s population lives near the coast, it is imperative to improve predictive capability of shoreline change. In fact, driven by the pressure from decision-makers, managers, politicians and the public, research efforts to understand and predict shoreline evolution have recently increased.

From a modelling perspective, several approaches have been proposed (Fig. 1), but two approaches seem particularly suited to predict shoreline change over the medium scale (seasonal to inter-annual): (a) Hybrid models (usually based on the equilibrium concept) and (b) machine learning. So far, a number of numerical models have been implemented for the prediction of shoreline evolution but there are very few studies that have attempted a detailed comparison of their predictive skill. The objective of our study is to test the ability of such models in predicting shoreline evolution seasonal to inter-annual scales. Here, we report on a novel approach to prediction and model testing based on a non-competitive competition (*Shorecast*) and subsequent workshop (*Shoreshop 2018*) specifically carried to bridge this gap. Overall, contributors from 15 institutions participated to the Shorecast competition and contributed to the discussion on advances in shoreline evolution models.

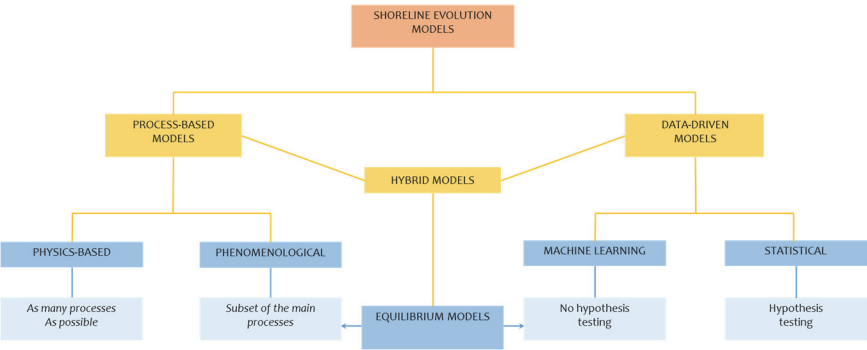


Fig. 1. Classification of numerical models for shoreline change.

Data

In order to develop the Shorecast competition, data from a variety of sources had to be obtained and compiled. The cornerstone of the dataset is the eighteen years

(1999–2017) of daily video shoreline position of Tairua Beach (NZ). Tairua Beach (Fig. 2) is an embayed beach of ~1200 m length located on the Coromandel Peninsula of New Zealand’s North Island. Tairua beach faces northeast and is usually exposed to waves characterized by 1–3 m significant height and 10 s period, and approaching predominantly from NE. The tidal range is around 2 m. The beach is generally steep with sand of mean diameter of about 0.35 mm. The beach is highly dynamic and displays rhythmic longshore bar patterns frequently being modified by the formation of rips channels. The wave (significant wave height, peak wave period and direction) and tide characteristics were obtained from numerical modelling. We used SLR predictions until 2100 for the specific area.

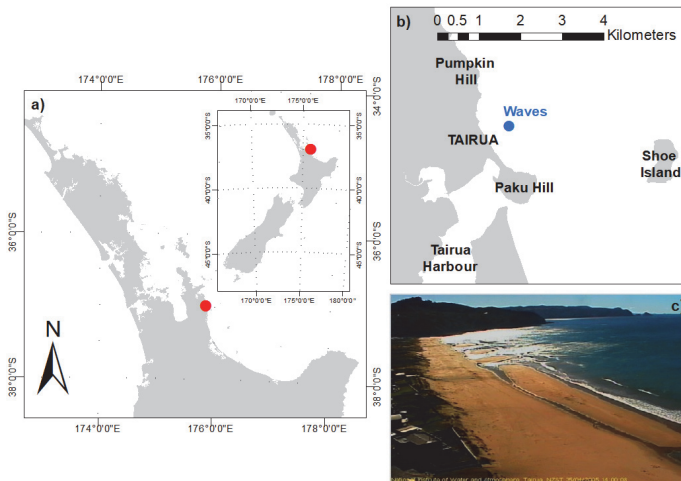


Fig. 2. a) and b) Tairua beach location c) Camera view of Tairua beach (courtesy of NIWA and Waikato Regional Council).

Methods

The Participants to the Shorecast were asked to predict shoreline evolution at Tairua beach for the period 2014–2017, by using data to train their models from (1999–2014). For the Shorecast, we only provided the wave characteristics for the period 2014–2017, but not the shoreline evolution. This ensured that participants would not be biased by knowing the “result” and so avoided that the competition was reduced to a parameter fitting/calibration exercise.

Results

Overall, 19 models among Equilibrium Model types (12) and Machine Learning techniques (7) were used to predict shoreline behavior. Interestingly, almost all models displayed agreement with the observations, but they also indicated shortcomings that future research will need to address. Fig. 3 shows two examples: a Hybrid model (cyan line) and a Machine Learning model (magenta line). As can be seen in Fig. 3, upper panel, both models are able to capture seasonal to interannual changes in shoreline position. However, the Hybrid model was also able to predict faster shoreline changes. In general, many of the models reproduced the overall mean trend and seasonality but often failed to reproduce these large variations at faster time-scales as those induced by storms. Additionally, models showed a better performance during the hindcast period. In general, predictions followed a smooth trend, showing less variability during the prediction period (Fig. 3, bottom panel). Differences during hindcast and shorecast models performance were more evident for machine learning models than for hybrid models (Fig. 3, bottom panel).

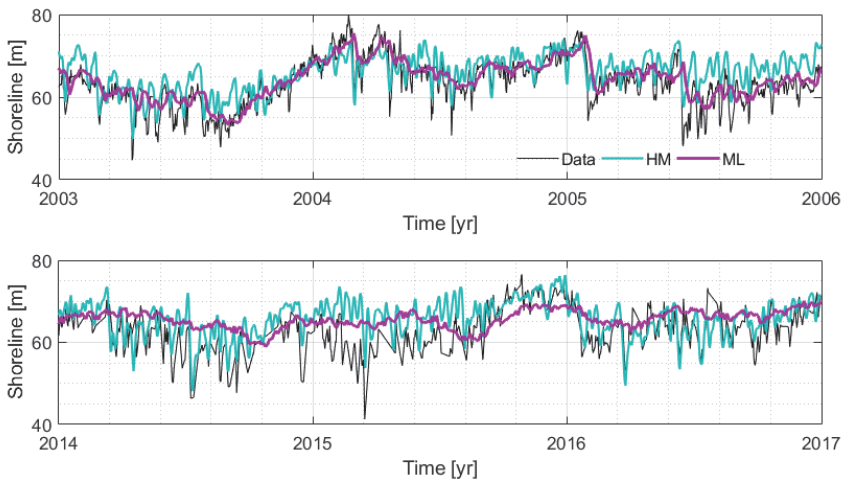


Fig. 3. Top panel: Hindcast prediction from 2003 – 2006. Bottom panel: Shorecast prediction. Example of a Hybrid model (cyan) and of Machine learning model (magenta). The black line indicates the observed shoreline position.

Conclusion

We used observations of shoreline change at Tairua beach (New Zealand) to perform a “blind” test of numerical models. Our objective was to test model performance avoiding the possibility of calibration. Results indicate that both

modelling methodologies can reproduce shoreline change over the medium term. All participants to the blind test appreciated the value of attempting uncalibrated predictions and it is hopeful that future studies will attempt similar tests.

Acknowledgements

We wish to thank all people and institutions that have made this research possible by making data available. In particular, we wish to thank the Waikato Regional Council, NIWA, George Payne and B. Blossier for their work in the codes for the video images, R. Bell (NIWA) for the tide and SLR data, and MetOcean for the wave hindcast. Funding from the Auckland Hazard Hub and a project awarded to GC (Climate change impacts on weather-related hazards) are gratefully acknowledged.