



HAL
open science

Recent results on non-convex functionals penalizing oblique oscillations

Michael Goldman, Benoît Merlet

► **To cite this version:**

Michael Goldman, Benoît Merlet. Recent results on non-convex functionals penalizing oblique oscillations. *Rendiconti del Seminario Matematico*, 2019, 77 (2). hal-02382214

HAL Id: hal-02382214

<https://hal.science/hal-02382214>

Submitted on 27 Nov 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Recent results on non-convex functionals penalizing oblique oscillations

M. Goldman* B. Merlet†

November 25, 2019

Abstract

The aim of this note is to review some recent results on a family of functionals penalizing oblique oscillations. These functionals naturally appeared in some variational problem related to pattern formation and are somewhat reminiscent of those introduced by Bourgain, Brezis and Mironescu to characterize Sobolev functions. We obtain both qualitative and quantitative results for functions of finite energy. It turns out that this problem naturally leads to the study of various differential inclusions and has connections with branched transportation models.

We review in this paper some recent results obtained in [GM19a, GM19b, GM19c] on non-convex functionals penalizing oblique oscillations. We are mainly interested in both qualitative and quantitative rigidity results for functions with finite energy. We also obtain concentration and rectifiability properties of the corresponding ‘defect’ measures. We will focus here on the most important results and sacrifice generality for clarity. In particular, we will restrict ourselves to a periodic setting to avoid boundary effects.

1 The energy

For $n_1, n_2 \geq 1$ and $n = n_1 + n_2$, we decompose $\mathbf{R}^n = X_1 \oplus X_2$ with $X_1 \perp X_2$ and $n_l = \dim X_l$ and consider the n dimensional torus $\mathbf{T}^n := (\mathbf{R}/\mathbf{Z})^n = \mathbf{T}^{n_1} \oplus \mathbf{T}^{n_2}$. For $x \in \mathbf{R}^n$ we write $x = x_1 + x_2$ its decomposition in $X_1 \oplus X_2$. For $(x, z) \in \mathbf{T}^n \times \mathbf{R}^n$, we introduce the notation

$$Du(x, z) := u(x + z) - u(x)$$

for the discrete derivative. We also fix a radial non-negative kernel¹

$$\rho \in L^1(\mathbf{R}^n, \mathbf{R}_+) \quad \text{with} \quad \int_{\mathbf{R}^n} \rho dx = 1, \quad \text{and} \quad \text{supp } \rho \subset B_1.$$

*Université de Paris, CNRS, Sorbonne-Université, Laboratoire Jacques-Louis Lions (LJLL), F-75005 Paris, France, email: goldman@math.univ-paris-diderot.fr

†Université de Lille, CNRS, UMR 8524, Inria - Laboratoire Paul Painlevé, F-59000 Lille, email: benoit.merlet@univ-lille.fr

¹we denote by B_1 the unit ball of \mathbf{R}^n .

As usual, for $\varepsilon > 0$ we introduce the rescaled kernel $\rho_\varepsilon := \varepsilon^{-n} \rho(\varepsilon^{-1} \cdot)$ so that $\{\rho_\varepsilon\}_{\varepsilon > 0}$ forms a family of radial mollifiers. We introduce three real parameters $p, \theta_1, \theta_2 > 0$ and define for any measurable function $u : \mathbf{T}^n \rightarrow \mathbf{R}$ and any $\varepsilon > 0$, the quantity

$$\mathcal{E}_{\varepsilon,p}^{\theta_1,\theta_2}(u) := \int_{\mathbf{R}^n} \rho_\varepsilon(z) \int_{\mathbf{T}^n} \frac{|Du(x, z_1)|^{\theta_1} |Du(x, z_2)|^{\theta_2}}{|z|^p} dx dz. \quad (1.1)$$

Eventually, we send ε to 0 and define the functional

$$\mathcal{E}_p^{\theta_1,\theta_2}(u) := \varliminf_{\varepsilon \downarrow 0} \mathcal{E}_{\varepsilon,p}^{\theta_1,\theta_2}(u).$$

Most of the time, we omit the dependency on the parameters θ_1, θ_2 and note

$$\mathcal{E}_{\varepsilon,p}(u) := \mathcal{E}_{\varepsilon,p}^{\theta_1,\theta_2}(u), \quad \mathcal{E}_p(u) := \mathcal{E}_p^{\theta_1,\theta_2}(u).$$

Let $S(\mathbf{T}^n)$ be the non-convex set of functions $u : \mathbf{T}^n \mapsto \mathbf{R}$ which depend only on the first n_1 coordinates or only on the last n_2 coordinates. That is

$$S(\mathbf{T}^n) := \{u : u(x) = u_l(x_l) \text{ in } \mathbf{T}^n \text{ with } l = 1 \text{ or } l = 2\}.$$

The functional \mathcal{E}_p vanishes on $S(\mathbf{T}^n)$ and our main question is to understand when the converse implication

$$\mathcal{E}_p(u) = 0 \implies u \in S(\mathbf{T}^n) \quad (1.2)$$

is also true. It turns out that the critical exponent p depends on θ_1 and θ_2 but also on the regularity of u . Once this question is settled, it is natural to investigate the properties of functions with finite energy in the critical case. This leads in particular to quantitative versions of (1.2). Throughout the paper we will use the notation

$$\theta := \theta_1 + \theta_2.$$

2 Motivations and examples

The main motivation for studying the functionals \mathcal{E}_p comes from the study of pattern formation in some variational models involving competition between a perimeter term and a non-local repulsive one. We refer the reader to [GR19, DR19] where energies related to \mathcal{E}_p are used to show that some sets are union of stripes. These functionals may also be seen as variants of those introduced by Bourgain, Brezis and Mironescu in [BBM01] to characterize Sobolev spaces. We recall for instance that it is proven in [Bre02, DMMS08] that for $p > \theta \geq 1$, if

$$\mathcal{F}_p(u) := \varliminf_{\varepsilon \downarrow 0} \int_{\mathbf{R}^n} \rho_\varepsilon(z) \int_{\mathbf{T}^n} \frac{|Du(x, z)|^\theta}{|z|^p} dx dz < \infty$$

then u is constant. Let us however point out that the functional \mathcal{F}_p is convex, which makes its analysis much easier compared to the one of \mathcal{E}_p .

Let us observe that if $\mathcal{E}_p(u) < \infty$ and $p > \theta$, then at almost every point of differentiability of u we have²

$$|\nabla_1 u(x)| |\nabla_2 u(x)| = 0 \quad (2.1)$$

²we denote by ∇_l the gradient with respect to x_l .

and one can wonder whether this differential inclusion (this may be rewritten as $\nabla u \in K$ where $K := X_1 \cup X_2$) is already rigid enough to imply $u \in S(\mathbf{T}^n)$. While this is the case for C^1 functions, since the convex hull of K is \mathbf{R}^n , it is already not rigid in the class of Lipschitz functions (see [Dac08, Theorem 10.18]). This may serve as another motivation for studying functions of finite energy $\mathcal{E}_p(u)$ rather than (2.1) in order to characterize functions in $S(\mathbf{T}^n)$.

If the threshold for rigidity is given by $p = \theta$ in the case of C^1 functions, it is larger for more general functions. Indeed, the main two examples of functions with finite energy but which are not in $S(\mathbf{T}^n)$ are the ‘roof’ and ‘corner’ functions. We present the constructions in \mathbf{R}^2 since they can be both easily extended to higher dimension and to the periodic setting. The ‘roof’ function is the Lipschitz function defined by $u(x) := \min(x_1, x_2)$. After localization, it satisfies $0 < \mathcal{E}_{1+\theta}(u) < \infty$ for every $\theta > 0$. The ‘corner’ function is defined as $u = \mathbf{1}_{(0,\infty)^2}$ and it is not hard to check that $0 < \mathcal{E}_2(u) < \infty$.

3 Qualitative and quantitative rigidity estimates

The results from this section were obtained in [GM19a].

The previous examples of the ‘roof’ and ‘corner’ functions show that in full generality, implication (1.2) can only hold for $p \geq \max(1 + \theta, 2)$. Our first main result is that this estimate is essentially sharp. Define

$$P(\theta_1, \theta_2) := \begin{cases} 2 & \text{if } \theta \leq 1 \\ 1 + \theta & \text{if } \theta \geq 1 \text{ and } \min(\theta_1, \theta_2) \leq 1 \\ \min(\theta_1, \theta_2) + \theta & \text{otherwise.} \end{cases} \quad (3.1)$$

From now on we use the notation

$$\mathcal{E}(u) := \mathcal{E}_{P(\theta_1, \theta_2)}(u).$$

Theorem 3.1. *For every measurable function u , if $\mathcal{E}(u) = 0$ then $u \in S(\mathbf{T}^n)$.*

Sketch of proof. Let us give a sketch of proof in the simplest case $n = 2$, $\theta = 1$ (and thus $P(\theta_1, \theta_2) = 2$). Substituting u by $\arctan u$, we may assume that $\|u\|_\infty \leq 1$.

Making the changes of variables $(\tilde{x}, \tilde{z}) = (x + z_1, -z_1 + z_2)$, $(\tilde{x}, \tilde{z}) = (x + z_2, z_1 - z_2)$ and $(\tilde{x}, \tilde{z}) = (x + z_1 + z_2, -z_1 - z_2)$ in the definition of $\mathcal{E}(u)$, we see that if $\mathcal{E}(u) = 0$ then also

$$\lim_{\varepsilon \downarrow 0} \int_{\mathbf{R}^2} \rho_\varepsilon(z) \int_{\mathbf{T}^2} \frac{(|Du(x + z_2, z_1)| + |Du(x, z_1)|)^{\theta_1} (|Du(x + z_1, z_2)| + |Du(x, z_2)|)^{\theta_2}}{|z|^2} dx dz = 0.$$

Since by triangle inequality, we have

$$\begin{aligned} |Du(x + z_2, z_1)| + |Du(x, z_1)| &\geq |u(x + z_1 + z_2) - u(x + z_2) - u(x + z_1) + u(x)| \\ &= |D[Du(\cdot, z_2)](x, z_1)| \end{aligned}$$

and the same lower bound for $|Du(x + z_2, z_1)| + |Du(x, z_1)|$, we obtain (recall that $\theta = 1$)

$$\lim_{\varepsilon \downarrow 0} \int_{\mathbf{R}^2} \rho_\varepsilon(z) \int_{\mathbf{T}^2} \frac{|D[Du(\cdot, z_2)](x, z_1)|}{|z|^2} dx dz = 0.$$

This implies that we can find a sequence $z^k \rightarrow 0$ with $|z_1^k| \sim |z_2^k|$ for which

$$\lim_{k \rightarrow \infty} \int_{\mathbf{T}^2} \frac{|D[Du(\cdot, z_2^k)](x, z_1^k)|}{|z^k|^2} dx = 0. \quad (3.2)$$

From this we may deduce that in the sense of distributions,

$$\partial_1 \partial_2 u = 0. \quad (3.3)$$

We can thus write $u(x) = u_1(x_1) + u_2(x_2)$. Plugging this back into the definition of $\mathcal{E}(u)$, we conclude that either $u_1 = 0$ or $u_2 = 0$. \square

If this result is sharp in the first two cases of (3.1) as seen from the ‘roof’ and ‘corner’ functions, we believe that it is not in the last case.

Conjecture 3.2. For every $\theta \geq 1$, Theorem 3.1 holds with $P(\theta_1, \theta_2) = 1 + \theta$.

The main insight in the proof of Theorem 3.1 is that the energy $\mathcal{E}(u)$ does not only control first derivatives as seen from (2.1) but also the mixed second order derivatives (see (3.3))

$$\mu[u] := \nabla_1 \nabla_2 u.$$

With a more careful proof, it is possible to show that the energy gives a quantitative control on the defect measure $\mu[u]$.

Proposition 3.3. *If $\|u\|_\infty \leq 1$ and $\theta \leq 1$, then for every³ $\varphi \in C^\infty(\mathbf{T}^n, \mathbf{R}^{n_1 \times n_2})$,*

$$\langle \mu[u], \varphi \rangle \lesssim \mathcal{E}(u) \|\varphi\|_\infty. \quad (3.4)$$

In particular this means that in the case $\theta \leq 1$, if $\mathcal{E}(u) < \infty$ then $\mu[u]$ is a Radon measure. If $\theta > 1$ we can also obtain control on $\mu[u]$ by $\mathcal{E}(u)$ in some Sobolev spaces with negative regularity index. However, for every $\theta > 1$ we can construct Lipschitz functions with finite energy for which $\mu[u]$ is not a Radon measure. Since all the subsequent results build on (3.4), we only consider from now on the case $\theta \leq 1$.

In light of (3.4), one can wonder if a quantitative version of Theorem 3.1 holds: is it true that $\mathcal{E}(u)$ controls the distance of u to $S(\mathbf{T}^n)$ in some norm? The strongest result we obtained is for $n = 2$.

Theorem 3.4. *Assume that $n_1 = n_2 = 1$ and $\theta \leq 1$. Then for every function u with $\|u\|_\infty \leq 1$, there exists $\bar{u} \in S(\mathbf{T}^2)$ such that $u - \bar{u} \in BV(\mathbf{T}^2) \cap L^\infty(\mathbf{T}^2)$ with*

$$\|u - \bar{u}\|_\infty + |\nabla[u - \bar{u}]|(\mathbf{T}^2) \lesssim \mathcal{E}(u) + \mathcal{E}(u)^{\frac{1}{2}}. \quad (3.5)$$

³By convention $a \lesssim b$ means that there exists a non-negative constant C which may only depend on θ_1, θ_2, n or on the kernel ρ such that $a \leq Cb$.

The idea of the proof is to first decompose u as $u(x) = u_1(x_1) + u_2(x_2) + w(x)$ where w satisfies $\partial_1 \partial_2 w = \mu[u] = \partial_1 \partial_2 u$ and $\|w\|_\infty + |\nabla w|(\mathbf{T}^2) \lesssim \mathcal{E}(u)$. Using this (and in particular the L^∞ bound on w), we can quantify how much the integration with respect to x_1 and x_2 in the definition of $\mathcal{E}(u)$ decouples. In higher dimension, the failure of the Sobolev embedding $BV(\mathbf{T}^{n_i}) \subset L^\infty(\mathbf{T}^{n_i})$ makes the situation more complex (and in particular the energy does not control the corresponding w in L^∞) and we were not able to obtain a BV estimate. Nevertheless, we have,

Theorem 3.5. *Assume that $\hat{n} := \max(n_1, n_2) \geq 2$ and that $\theta \leq 1$. Then for every function u with $\|u\|_\infty \leq 1$, there exists $\bar{u} \in S(\mathbf{T}^n)$ such that $u - \bar{u} \in L^{\frac{\hat{n}}{\hat{n}-1}}(\mathbf{T}^n)$ with*

$$\|u - \bar{u}\|_{L^{\frac{\hat{n}}{\hat{n}-1}}(\mathbf{T}^n)} \lesssim \mathcal{E}(u) + \mathcal{E}(u)^{\frac{1}{2}}.$$

4 Structure of the defect measure

The results from this section can be found in [GM19b] with the exception of Theorem 4.7 which is part of [GM19c].

A natural question to investigate is the structure of the defect measure $\mu[u]$. Since the ‘corner’ function, whose defect measure is a Dirac mass, is optimal for $\theta \leq 1$ while the ‘roof’ function, whose defect measure is concentrated on the line $x_1 = x_2$, is optimal only for $\theta = 1$, we can expect that this structure will depend on the value of θ .

4.1 The case $\theta < 1$

We start with the case $n_1 = n_2 = 1$.

Theorem 4.1. *For $n = 2$ and $\theta < 1$, if u is such that $\|u\|_\infty \leq 1$ and $\mathcal{E}(u) < \infty$, then there exist $\sigma^k \in \mathbf{R}$ and $x^k \in \mathbf{T}^2$ such that*

$$\mu[u] = \sum_k \sigma^k \delta_{x^k}.$$

Moreover,

$$\sum_k |\sigma^k|^\theta \lesssim \mathcal{E}(u). \quad (4.1)$$

Sketch of proof. The proof of this result is much easier if u is assumed to be a characteristic function. Indeed, in this case the differential inclusion⁴

$$\partial_1 \partial_2 u \in \mathcal{M}(\mathbf{T}^2) \quad \text{and} \quad u \in \{0, 1\} \quad (4.2)$$

is quite rigid. If Q is a rectangle with vertices $\{a, b, c, d\}$ (with a the top left vertex and using then clockwise enumeration), and if u satisfies (4.2) then

$$\mu[u](Q) = u(b) + u(d) - u(a) - u(c) \in \pm\{0, 1, 2\},$$

⁴here $\mathcal{M}(\mathbf{T}^n)$ denotes the set of Radon measures on \mathbf{T}^n .

which forces $\mu[u]$ to be atomic.

Let us now outline the proof in the case of a generic function u . For $(x, z) \in \mathbf{T}^2 \times \mathbf{R}^2$, we define $Q_{x,z} := x + [0, z_1) \times [0, z_2)$ and observe that

$$\mu[u](Q_{x,z}) = D[Du(\cdot, z_2)](x, z_1).$$

Arguing as for (3.2), we may find a sequence $z^k \rightarrow 0$ with $|z_1^k| \sim |z_2^k|$ and such that

$$\overline{\lim}_{k \rightarrow \infty} \int_{\mathbf{T}^2} \frac{|\mu[u](Q_{x,z^k})|^\theta}{|z^k|^2} dx \lesssim \mathcal{E}(u).$$

We then prove that every measure μ for which the left-hand side is finite must be atomic. \square

Using this result, one can improve Theorem 3.4. First, if u is a characteristic function and $\mathcal{E}(u)$ is small enough, then (4.1) implies that $\mu[u] = 0$ (since in this case $\sigma^k \in \pm\{1, 2\}$) from which we obtain that $u \in S(\mathbf{T}^n)$. Second, for generic functions u , we can prove that the function $v = u - \bar{u}$, which appears in (3.5) has essentially the structure of the ‘corner’ function: its distributional derivative is purely concentrated on a jump part. That is $\nabla v = \sigma \mathcal{H}^1 \llcorner J_v$ with J_v a 1–rectifiable set and moreover

$$\int_{J_v} |\sigma|^\theta d\mathcal{H}^1 \lesssim \mathcal{E}(u) + \mathcal{E}^{\frac{1}{2}}(u).$$

In higher dimension, we can prove the following rectifiability result.

Theorem 4.2. *Let $\theta < 1$ and $n \geq 2$. If u is such that $\|u\|_\infty \leq 1$ and $\mathcal{E}(u) < \infty$, then μ is $(n - 2)$ –rectifiable i.e.*

$$\mu[u] = \sigma \nu_1 \otimes \nu_2 \mathcal{H}^{n-2} \llcorner \Sigma,$$

where $\Sigma \subset \mathbf{T}^n$ is $(n - 2)$ –rectifiable, $\sigma : \Sigma \mapsto \mathbf{R}$ is a multiplicity and (ν_1, ν_2) are normals to Σ with $\nu_l \in X_l$. Moreover, if we let $h(\sigma) := |\sigma| + |\sigma|^\theta$,

$$\mathbb{M}_h(\mu[u]) := \int_\Sigma h(\sigma) d\mathcal{H}^{n-2} \lesssim \mathcal{E}(u). \quad (4.3)$$

Sketch of proof. To prove this result we first identify the measure $\mu[u]$ with an $(n - 2)$ –current (see [Fed69]). If we slice the corresponding current by 2–dimensional planes of the form $V = \text{span}(\xi_1, \xi_2)$ with $\xi_l \in X_l$, we obtain 0–rectifiable currents applying Theorem 4.1 to the trace of u on the slice. We then conclude using White’s rectifiability criterion [Whi99]. Estimate (4.3) is a consequence of (4.1) and the co-area formula [Fed69, Theorem 3.2.22]. \square

Let us point out that the quantity \mathbb{M}_h appearing in (4.3) is often called the h -mass. The fact that it is finite implies that μ has to be quite concentrated since $\theta < 1$. This type of energies appears naturally in branched transportation models and has been the subject of intense recent work (see for instance [BCM09, CFM18, CRM19, BW18]).

Let us also observe that since $\mu[u] = \nabla_1 \nabla_2 u$, we have $\nabla_1 \times \mu[u] = 0$ and $\nabla_2 \times \mu[u] = 0$. From [ARDPHR19] we could have thus directly obtained that $\mu[u]$ is concentrated on a

set with Hausdorff dimension at least $n - 2$ and that its $(n - 2)$ -part is rectifiable. Here we obtain a stronger result since we rule out more diffuse parts of the measure.

In the case when $n_1 = 1$ or $n_2 = 1$, we can say more and prove that Σ is tensorized. For definiteness let us state the result in the case $n_2 = 1$.

Proposition 4.3. *Assume that $n_1 > 1$, $n_2 = 1$ and $\theta < 1$. If u is such that $\|u\|_\infty \leq 1$ and $\mathcal{E}(u) < \infty$, then we may write $\mu[u] = \sum_k \mu^k$ where for every k ,*

$$\mu^k = \sigma^k \nu^k \mathcal{H}^{n_1-1} \llcorner (\Sigma^k \times \{x_2^k\})$$

with $\Sigma^k \subset \mathbf{T}^{n_1}$ an $(n_1 - 1)$ -rectifiable set with normal ν^k and such that

$$\mathbb{M}_h(\mu[u]) = \sum_k \mathbb{M}_h(\mu^k).$$

The main ingredient in the proof of Proposition 4.3 is the extension to rectifiable currents with finite h -mass of the classical decomposition in indecomposable components of integral currents (see [Fed69, 4.2.25]).

Lemma 4.4. *Let T be an m -rectifiable current in \mathbf{R}^n with⁵ $\mathbb{M}_h(T) < \infty$ and $\partial T = 0$. Then, T may be decomposed into indecomposable components T^k in the sense that*

$$T = \sum_k T^k \quad \text{and} \quad \mathbb{M}_h(T) = \sum_k \mathbb{M}_h(T^k)$$

and the currents T^k cannot be further decomposed.

It is tempting to conjecture that a similar tensorized structure also holds for arbitrary dimension. It is however possible to construct an example in \mathbf{R}^4 where it is impossible to write $\mu[u]$ as $\mu[u] = \sum_k \mu_1^k \otimes \mu_2^k$ with

$$\mu_l^k = \sigma_l^k \nu_l^k \mathcal{H}^{n_l-1} \llcorner \Sigma_l^k$$

where $\Sigma_l^k \subset \mathbf{T}^{n_l}$ are $(n_l - 1)$ -rectifiable sets and such that

$$\mathbb{M}_h(\mu[u]) = \sum_k \mathbb{M}_h(\mu_1^k) \mathbb{M}_h(\mu_2^k).$$

However, we can combine Proposition 4.3 with slicing to improve the conclusion of Theorem 4.2. Indeed, if we see $\mu[u]$ as a $(n_2 - 1)$ -flat chain in \mathbf{T}^{n_2} with values in the group of $(n_1 - 1)$ -rectifiable currents in \mathbf{T}^{n_1} , Proposition 4.3 tells us that every slice with respect to $(n_1 + 1)$ -spaces of the form $V = \text{span}(X_1, \xi_2)$ where $\xi_2 \in X_2$, is rectifiable. Hence, another application of White's rectifiability criterion yields rectifiability of $\mu[u]$ (as a flat chain with values in the space of currents). Exchanging the roles played by n_1 and n_2 we obtain our final result which improves Theorem 4.2.

Theorem 4.5. *Let $\theta < 1$ and $n \geq 2$. If u is such that $\|u\|_\infty \leq 1$ and $\mathcal{E}(u) < \infty$, then μ is $(n - 2)$ -rectifiable with $(n_1 - 1) \times (n_2 - 1)$ tensor structure i.e.*

$$\mu[u] = \sigma \nu_1 \otimes \nu_2 \mathcal{H}^{n-2} \llcorner (\Sigma_1 \times \Sigma_2), \quad (4.4)$$

where $\Sigma_l \subset \mathbf{T}^{n_l}$ are $(n_l - 1)$ -rectifiable, $\sigma : \Sigma_1 \times \Sigma_2 \mapsto \mathbf{R}$ is a multiplicity and ν_l is normal to Σ_l .

Notice that in (4.4), the multiplicity σ is a priori *not* tensorized (and is actually equal to zero at many points of $\Sigma_1 \times \Sigma_2$).

⁵The definition of the h -mass for a rectifiable current is analogous to (4.3).

4.2 The case $\theta = 1$

In the case $\theta = 1$, both the ‘roof’ and the ‘corner’ functions have finite energy. Therefore, $\mu[u]$ can contain parts of different dimensions and the situation is more delicate to study. For this reason we were only able to obtain results in the case $n = 2$.

Our first result is that $\mu[u]$ is concentrated on a set of Hausdorff dimension at most one. The proof has a similar flavor to the proof of Theorem 4.1 but is much more involved.

Theorem 4.6. *Let $n = 2$ and $\theta = 1$. If u is such that $\mathcal{E}(u) < \infty$ then there exists a Borel set $\Sigma \subset \mathbf{T}^2$ such that $\mathcal{H}^1 \llcorner \Sigma$ is σ -finite and $|\mu[u]|(\mathbf{T}^2 \setminus \Sigma) = 0$.*

In order to study the case when $\mu[u]$ is expected to concentrate on one-dimensional objects, it is natural to consider the class of Lipschitz functions of finite energy. We can actually prove that for this problem the energy plays no role. Letting $v = \nabla u$, and recalling that $K = X_1 \cup X_2$, (2.1) and (3.4), we are thus interested in the differential inclusion

$$\|v\|_\infty \leq 1, \quad \partial_2 v_1 = \partial_1 v_2 \in \mathcal{M}(\mathbf{T}^2) \quad \text{and} \quad v \in K \text{ a.e.} . \quad (4.5)$$

Notice that (4.5) is reminiscent of the entropy solutions of the Eikonal equation studied by De Lellis and Otto in [DLO03] (where K is replaced by \mathbb{S}^1). As in [DLO03], we can prove that if v satisfies (4.5), then it has a BV type structure.

Theorem 4.7. *If v satisfies (4.5) then there exists a 1-rectifiable set Σ such that letting ν be a normal to Σ and $B_r^\pm(x) := \{y \in B_r(x) : \pm y \cdot \nu > 0\}$, we have*

(i) *for \mathcal{H}^1 a.e. $x \in \Sigma$, v has traces $v^\pm(x) \in K$ on Σ in the sense that*

$$\lim_{r \downarrow 0} \frac{1}{r^2} \int_{B_r^\pm(x)} |v(y) - v^\pm(x)| dy = 0;$$

(ii) *for \mathcal{H}^1 a.e. $x \in \Sigma$ and $l = 1, 2$ we have the implication $v_l^\pm(x) = 0 \implies v_l^\mp(x) \neq 0$;*

(iii) *the defect measure $\mu := \partial_2 v_1 = \partial_1 v_2$ is concentrated on Σ and*

$$\mu = (v_1^+ - v_1^-) \nu_2 \mathcal{H}^1 \llcorner \Sigma = (v_2^+ - v_2^-) \nu_1 \mathcal{H}^1 \llcorner \Sigma;$$

(iv) *\mathcal{H}^1 a.e. $x \in \mathbf{T}^2 \setminus \Sigma$ is either a Lebesgue point of v_1 with $v_1(x) = 0$ or a Lebesgue point of v_2 with $v_2(x) = 0$.*

Notice that in comparison with [DLO03], we obtain a stronger result since we prove here that μ is exactly concentrated on a one-dimensional set while for the Eikonal equation it is still an open problem to exclude concentration of the energy on more diffused sets.

Sketch of proof. As in [DLO03], the main point is to prove the rectifiability of μ , that is (iii). While one could argue along the lines of [DLO03], our proof relies on the study of the level sets of the function u such that $v = \nabla u$.

For $t \in \mathbf{R}$, we define $E_t := \{u < t\}$ and $\Gamma_t := \{u = t\}$ so that for a.e. t , $\Gamma_t = \partial E_t$. Using

the co-area formula, we can decompose the measure μ on the level sets of u and prove that for every $\varphi \in C^\infty(\mathbf{T}^2)$ and every $\psi \in C^0(\mathbf{R})$,

$$\int_{\mathbf{T}^2} \varphi(x)\psi(u(x))d\mu(x) = - \int_{\mathbf{R}} \psi(t) \left[\int_{\Gamma_t} \partial_1\varphi\nu_2 d\mathcal{H}^1 \right] dt.$$

Therefore, for a.e. t , the distribution

$$\langle \kappa_t, \varphi \rangle := \int_{\Gamma_t} \partial_1\varphi\nu_2 d\mathcal{H}^1$$

is a Radon measure with

$$\int_{\mathbf{R}} |\kappa_t|(\mathbf{T}^2) dt = |\mu|(\mathbf{T}^2).$$

Notice that since $\nu_1\nu_2 = 0$ a.e., κ_t coincides with the mean curvature of ∂E_t in the sense of varifolds (see [Sim83]). By the divergence theorem,

$$\langle \kappa_t, \varphi \rangle = \langle \partial_1\partial_2\mathbf{1}_{E_t}, \varphi \rangle$$

and thus if κ_t is a Radon measure, then $\mathbf{1}_{E_t}$ satisfies (4.2). By a variant of Theorem 4.1, E_t is a finite union of polygons with sides parallel to the coordinate axes. The measure κ_t is then a sum of Dirac masses located at the corners of E_t .

Now, fix a point \bar{x} around which μ is concentrated. Generically, it is a corner of $\Gamma_{\bar{t}}$ for some $\bar{t} \in \mathbf{R}$, which is also a Lebesgue point of $t \mapsto |\kappa_t|(\Gamma_t)$ (which counts the number of vertices of Γ_t). For t close to \bar{t} most Γ_t have the same number of vertices as $\Gamma_{\bar{t}}$. In particular, for such t there is exactly one corner x_t of Γ_t which is close to \bar{x} and we can locally parameterize the set Σ by x_t . The proof is then concluded by proving that $t \mapsto x_t$ has a derivative in \bar{t} . In turn, this follows from the fact that the distance between Γ_t and $\Gamma_{\bar{t}}$ is essentially given by the difference of the areas of E_t and $E_{\bar{t}}$ which is itself closely related to ∇u . In particular, because of (4.5), the normal to Σ is determined by v^\pm through the condition

$$(v_1^+ - v_1^-)\nu_2 = (v_2^+ - v_2^-)\nu_1.$$

□

Acknowledgments

M. Goldman is partially supported by the ANR SHAPO. B. Merlet is partially supported by the INRIA team RAPSODI and the Labex CEMPI (ANR-11-LABX-0007-01).

References

- [ARDPHR19] A. Arroyo-Rabasa, G. De Philippis, J. Hirsch, and F. Rindler. Dimensional estimates and rectifiability for measures satisfying linear PDE constraints. *Geom. Funct. Anal.*, 29(3):639–658, 2019.
- [BBM01] J. Bourgain, H. Brezis, and P. Mironescu. Another look at Sobolev spaces. In *Optimal control and partial differential equations*, pages 439–455. IOS, Amsterdam, 2001.

- [BCM09] M. Bernot, V. Caselles, and J.-M. Morel. *Optimal transportation networks*, volume 1955 of *Lecture Notes in Mathematics*. Springer-Verlag, Berlin, 2009. Models and theory.
- [Bre02] H. Brezis. How to recognize constant functions. A connection with Sobolev spaces. *Uspekhi Mat. Nauk*, 57(4(346)):59–74, 2002.
- [BW18] A. Brancolini and B. Wirth. General transport problems with branched minimizers as functionals of 1-currents with prescribed boundary. *Calc. Var. Partial Differential Equations*, 57(3):Art. 82, 39, 2018.
- [CFM18] A. Chambolle, L. A. Ferrari, and B. Merlet. Strong approximation in h-mass of rectifiable currents under homological constraint. *ArXiv e-prints*, June 2018.
- [CRM19] M. Colombo, A. De Rosa, and A. Marchese. On the well-posedness of branched transportation, 2019.
- [Dac08] B. Dacorogna. *Direct methods in the calculus of variations*, volume 78 of *Applied Mathematical Sciences*. Springer, New York, second edition, 2008.
- [DLO03] C. De Lellis and F. Otto. Structure of entropy solutions to the eikonal equation. *Journal of the European Mathematical Society*, 5(2):107–145, 2003.
- [DMMS08] G. De Marco, C. Mariconda, and S. Solimini. An elementary proof of a characterization of constant functions. *Adv. Nonlinear Stud.*, 8(3):597–602, 2008.
- [DR19] S. Daneri and E. Runa. Exact periodic stripes for minimizers of a local/nonlocal interaction functional in general dimension. *Arch. Ration. Mech. Anal.*, 231(1):519–589, 2019.
- [Fed69] H. Federer. *Geometric measure theory*. Die Grundlehren der mathematischen Wissenschaften, Band 153. Springer-Verlag New York Inc., New York, 1969.
- [GM19a] M. Goldman and B. Merlet. Non-convex functionals penalizing simultaneous oscillations along independent directions: rigidity estimates. *arXiv e-prints*, page arXiv:1905.07905, May 2019.
- [GM19b] M. Goldman and B. Merlet. Non-convex functionals penalizing simultaneous oscillations along independent directions: structure of the defect measure. *In preparation*, 2019.
- [GM19c] M. Goldman and B. Merlet. Structure of Lipschitz continuous functions complying to an anisotropic differential inclusion. *In preparation*, 2019.
- [GR19] M. Goldman and E. Runa. On the optimality of stripes in a variational model with non-local interactions. *Calc. Var. Partial Differential Equations*, 58(3):Art. 103, 26, 2019.

- [Sim83] L. Simon. *Lectures on geometric measure theory*, volume 3 of *Proceedings of the Centre for Mathematical Analysis, Australian National University*. Australian National University, Centre for Mathematical Analysis, Canberra, 1983.
- [Whi99] B. White. Rectifiability of flat chains. *Ann. of Math. (2)*, 150(1):165–184, 1999.