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Improving representation of riparian vegetation shading in a regional stream temperature model using LiDAR data

3 Pierre Loicq^{a,*}, Florentina Moatar^a, Yann Jullian^b, Stephen J. Dugdale^c, David M. Hannah^c

^a EA 6293 GéHCO Géo-Hydrosystèmes Continentaux, Université François-Rabelais de Tours, Parc de Grandmont 37200 Tours, France

^b CaSciModOT, UFR Sciences et Techniques, Université François Rabelais, Parc de Grandmont 37200 Tours, France

^c School of Geography, Earth and Environmental Sciences, University of Birmingham, Edgbaston, Birmingham B15 2TT, United Kingdom
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- 8 *Corresponding author. E-mail address: pierre.loicq@univ-tours.fr
- 9 Keywords: river temperature modelling, regional scale, riparian shading, LiDAR, Loir River.

10 Highlights:

- Riparian shading was characterised on a 270 km stream using LiDAR data.
- Shading data were injected in a regional stream temperature model.
- Vegetation's cooling effect ranges from -3.0 °C (upstream) to -1.3 °C (downstream).
 - Model accuracy is improved compared to simpler shade characterisation methods.
 - Riparian vegetation data's quality is a key factor for stream temperature modelling.

16 Graphical abstract:



17

18 Abstract

19 Modelling river temperature at the catchment scale is needed to understand how aquatic communities may 20 adapt to current and projected climate change. In small and medium rivers, riparian vegetation can greatly 21 reduce maximum water temperature by providing shade. It is thus important that river temperature models are 22 able to correctly characterise the impact of this riparian shading. In this study, we describe the use of a spatiallyexplicit method using LiDAR-derived data for computing the riparian shading on direct and diffuse solar 23 24 radiation. The resulting data are used in the T-NET one-dimensional stream temperature model to simulate 25 water temperature from August 2007 to July 2014 for 270 km of the Loir River, an indirect tributary of the Loire River (France). Validation is achieved with 4 temperature monitoring stations spread along the Loir River. The 26 vegetation characterised with the LiDAR approach provides a cooling effect on maximum daily temperature 27 (T_{max}) ranging from 3.0°C (upstream) to 1.3°C (downstream) in late August 2009. Compared to two other riparian 28 29 shading routines that are less computationally-intensive, the use of our LiDAR-based methodology improves the

bias of T_{max} simulated by the T-NET model by 0.62°C on average between April and September. However, difference between the shading routines reaches up to 2°C (monthly average) at the upstream-most station. Standard deviation of errors on T_{max} is not improved. Computing the impact of riparian vegetation at the hourly timescale using reach-averaged parameters provides results close to the LiDAR-based approach, as long as it is supplied with accurate vegetation cover data. Improving the quality of riparian vegetation data should therefore be a priority to increase the accuracy of stream temperature modelling at the regional scale.

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37 **1. Introduction**

Temperature is a major water quality parameter because it controls not only oxygen solubility (Moatar et al., 38 39 2001) but also chemical and metabolic reactions (Haag and Westrich, 2002). Hence, it affects fish behaviour and 40 survival (Magnuson et al., 1979). River water temperature modelling is thus important for understanding the 41 distribution of aquatic species at regional scales, under present or future climatic conditions (Buisson et al., 42 2008; Tisseuil et al., 2012; Boisneau et al., 2008; Brown et al., 2005). River temperature is already increasing 43 across French water courses, a trend which is expected to continue further under projected climate change 44 (Moatar and Gailhard, 2006; Bustillo et al., 2014; Hannah and Garner, 2015). Such a warming could have severe 45 consequences for a range of aquatic species, and adaptation measures are currently being sought with a view to 46 ensuring the continued survival of temperature sensitive fluvial organisms. In this context, riparian shade and 47 groundwater exchanges have been given increasing research attention, because of their ability to regulate river 48 temperature (Lalot et al., 2015; Leach and Moore, 2010). Indeed, many studies have shown that shade can 49 moderate water temperature of relatively small rivers (Moore et al., 2005; Garner et al., 2014). Conversely, in 50 larger rivers, Teti (2006) showed (using shade measurements acquired along an increasing-width stream) that 51 riparian vegetation has a limited impact on rivers larger than 30 m. DeWalle (2008) quantified the maximal 52 wetted width for which riparian vegetation can effectively reduce received solar radiation. However, no study 53 has yet quantified the impact of shading on temperature on rivers of intermediate width (>15 m and <30 m) or 54 at the regional scale.

55 Process-based river temperature models function by simulating the energy exchange processes heating or cooling a river, in particular through the input of solar radiation. This solar radiation is composed of direct 56 57 (solar rays) and diffuse radiation (scattered by atmosphere), both of which are influenced in different ways by 58 the presence of riparian vegetation. The impact of riparian vegetation on the direct radiation can be quantified 59 by computing a shadow factor (SF), which is the proportion of a river being shaded at a given time. Several 60 methods have been proposed to compute it at an hourly time step. Chen et al. (1998) detailed a method to 61 compute riparian shade from GIS polygons of riparian vegetation. Their method used stream azimuth and tree 62 height (alongside solar position) to determine whether a section of stream channel was in shade. However, this 63 technique only accounted for the effect of vegetation located perpendicular to the stream centreline, and 64 furthermore, did not denote the fraction of the channel cross-section that was shaded. As a result, Li et al. 65 (2012) developed an enhanced version of the Chen et al. (1998) methodology, allowing for the determination of 66 the amount of channel cross-section covered by shade. This new method also enables the simulation of

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overhanging vegetation, but like its predecessor, only considers the effect of vegetation located perpendicular to the river reach. Approaches capable of simulating the effects of vegetation non-perpendicular to the reach include that of Cox and Bolte (2007), who devised a methodology capable of simulating shadow cast by vegetation located in 8 directions (steps of 45°) around each centreline node, and the Solar Analyst extension for ArcGIS (Fu and Rich, 1999), which can compute shadow factor at much finer spatial and temporal scales. Indeed, Johnson and Wilby (2015) applied this method to a small catchment in order to quantify the potential of planting trees, without using a physically-based river temperature model.

74 The impact of riparian vegetation on diffuse radiation can be quantified by computing a sky view factor 75 (SVF). It is the ratio between the diffuse radiation actually reaching the water and the diffuse radiation that 76 would reach this surface with no vegetation around. In a lowland area where topographic shade can be 77 neglected, the tree view factor (TVF) can be defined as 1-SVF. Unlike SF, these view factors (VF) are constant in 78 time since they do not depend on the sun's position. For short reaches, a precise calculation can be achieved 79 through hemispheric photography. For larger areas, remote sensing products or vegetation polygons are 80 needed. Most previous studies (Chen et al., 1998, Cox and Bolte, 2007, Loinaz et al., 2013, Sun et al., 2015) 81 simply use the angle between the horizon and the tree in the directions perpendicular to the river, from one 82 fixed point of view (usually the centre of the river). Moore et al. (2014) introduced the computation of width-83 averaged sky view factors, with equations considering infinitely long rivers, with or without overhanging trees.

With an approach similar to the one used to compute direct radiation, the Solar Analyst extension for ArcGIS handles the computation of diffuse radiation by overlaying a viewshed and a discretised sky map. Two different methods can be used to quantify the amount of radiation coming from each cell of the open sky (uniform radiation or depending on the zenith angle). This method was modified and used by Sridhar et al. (2004) to include the shading effects of near stream vegetation.

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90 In order to quantify the impact of riparian shading, existing regional-scale stream temperature models 91 usually rely on theoretical values regarding vegetation characteristics (Sun et al., 2015; Loinaz et al., 2013), on 92 simplified assumptions regarding shading process (Haag and Luce, 2008; Cheng and Wiley, 2016), or incorporate 93 shading data from low-resolution DEMs (Cox and Bolte, 2007). Nowadays however, LiDAR can provide accurate 94 data at a large scale. In order to develop a tool for riparian shade inventories using LiDAR data, Guzy et al. 95 (2015) adapted the insolation module of the Heat Source model (Boyd and Kasper, 2003). They created 96 polygons of homogenous potential canopy height and extracted the 75th percentile of the computed frequency distribution of canopy height provided by LiDAR. Greenberg et al. (2012) used LiDAR data and the r.sun module 97 98 of GRASS GIS to compute clear-sky solar radiation for three summer days in order to understand the impact of a 99 potential trees removal around a delta, without the use of a network based temperature model. Finally, 100 Wawrzyniak et al. (2017) used LiDAR data to compute the impact of riparian forest in a deterministic water 101 temperature model of a 21 km-long reach, during 5 days in summer 2010 and 2011. There is thus a range of 102 data sources and methods available to compute both SF and VF. However, there remains a lack of information 103 comparing the various methodologies, especially with regards to shading routines in regional-scale models. 104 Moreover, the use of LiDAR as a method for the computation of riparian shading is still in its infancy and has 105 never been used to compute the impact of riparian vegetation in a large-scale stream temperature model, 106 during a whole annual cycle.

107 The goal of this paper is therefore to test the influence of shadow and sky view factor computed from LiDAR data on the simulation of maximum daily water temperature (T_{max}) with the T-NET model, a dynamic 108 physically based model for simulating stream temperature at the regional scale using the equilibrium 109 110 temperature concept. We compute SF and VF based on a LiDAR-derived raster and incorporate these data into 111 the radiative balance of a T-NET model of the Loir River (France) (see Beaufort et al., 2016). We then compare the T_{max} simulated with LiDAR data to two other methods used in the T-NET model for computing riparian 112 shading at the regional scales. Model validation is achieved using data from 4 temperature monitoring stations 113 114 that are spread over the Loir River.

115 **2. Methods**

116 **2.1.Principles of T-NET model**

117 T-NET is a 1D physically-based model designed to compute water temperature along the longitudinal dimension 118 of a hydrographic network (a GIS polyline). Reaches of this network are limited by two confluences, or by a source and a confluence (for first order reaches). T-NET was designed and applied at the regional scale (110 000 119 km²) by Beaufort et al. (2016). T-NET runs at an hourly time step and is based on the equilibrium temperature 120 121 concept, which is defined as the water temperature at which the net rate of heat exchange at the interface of a water body is null (Bustillo et al., 2014). The model considers six fluxes [W·m⁻²]: net solar radiation, atmospheric 122 123 longwave radiation, longwave radiation emitted from the water surface, evaporative heat flux, convective heat flux, and groundwater heat inflow. To compute these terms, the model uses the following parameters as 124 gridded input data: air temperature [°C], specific humidity [kg·kg⁻¹], wind velocity [m·s⁻¹], atmospheric longwave 125 radiation [W·m⁻²] and direct and diffuse solar radiation [W·m⁻²]. Parameters are allocated to each river reach as 126 a function of the ratio between the length of the reach within a grid cell and the total reach length. All 127 128 meteorological parameters except solar radiation are derived from the SAFRAN atmospheric reanalysis dataset 129 (Vidal et al., 2010). These data are produced by Météo-France from both observations and modelling at an hourly time step and a spatial resolution of 8 km. Direct and diffuse solar radiation are derived from the 130 131 Helioclim3-v5 dataset (Marchand et al., 2017), generated with the help of Meteosat satellite imagery at an hourly time step and a resolution of $\sim 3 \times 5$ km. Inputs pertaining to river discharge and groundwater 132 133 contributions to river flow are also required by the model. These are computed at a daily time step with the 134 semi-distributed hydrological model EROS (Thiéry and Moutzopoulos, 1992). Both parameters are modelled at the outlets of sub-basins for which river discharge observations are available for calibration. They are then 135 136 scaled to the reaches inside each sub-basin using the partial area concept. T-NET simulates longitudinal variability in water temperature between the upstream and downstream nodes of each reach, with a spatial 137 138 resolution depending on the travel time (Figure 1). Water velocity is given by the ratio between discharge and 139 channel cross-section, which is computed using the ESTIMKART empirical model developed by Lamouroux et al. 140 (2010). At the confluence of two reaches, the output temperature is defined as the sum of the product of the

141 two confluences' temperature and discharge divided by the sum of the discharge of the two confluences. T-NET

142 was thus designed to be applied on well mixed streams and not on standing waters or large estuaries, where 2D

143 (Cole and Wells, 2006; Becker et al., 2010; Ouellet et al., 2014) or 3D models (Maderich et al., 2008) are more

144 suitable.



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148 **2.2.Net solar radiation calculation**

149 In order to improve T-NET's ability to model the impact of riparian vegetation on solar radiation, modifications 150 were made to the original model detailed by Beaufort et al. (2016). Similar to the approach of LeBlanc et al. 151 (1997), net solar radiation (H_{ns}) is now computed as:

152
$$H_{ns} = R_{dir} (1 - \alpha_{dir}) ((1 - SF) + SF \tau) + R_{diff} (1 - \alpha_{diff}) ((1 - TVF) + TVF \tau)$$
(Eq. 1)

153 Where R_{dir} and R_{diff} are the direct and diffuse solar radiation [W·m⁻²] derived from the Helioclim3-v5 product, α_{dir} 154 and α_{diff} are the water surface albedo associated with direct and diffuse radiation respectively, τ is the 155 transmissivity of riparian vegetation (i.e. the fraction of solar radiation that passes through the canopy), *SF* is the 156 shadow factor and *TVF* is the tree view factor. α_{diff} was held at a constant of 0.09, following the recommendation 157 of Sellers (1965) and α_{dir} was computed using the formulation of Anderson (1954):

158
$$\begin{array}{c} \alpha_{dir} = 1 & if \ \Psi < 1.24^{\circ} \\ \alpha_{dir} = 1.18^{*} \Psi^{-0.77} & otherwise \end{array}$$
(Eq. 2)

159 Where Ψ is the angle between the horizon and the sun in degrees.

160 τ was fixed at 50% in winter and 15% in summer. These values are the averages of global solar radiation 161 transmissivities given by Cantón et al. (1994), Sattin et al. (1997) and Konarska et al. (2014) for deciduous tree 162 species. Transitions between winter and summer values are described with an ascending and descending logistic 163 regression whose equation is:

164
$$\tau = \frac{\kappa}{1 + \exp(\pm \gamma . DoY - \beta)} + \mu$$
 (Eq. 3)

165 Where *DoY* is the day of year and κ , β , γ and μ are the parameters fitted by least squares adjustment to an 166 averaged annual cycle of ground-based NDVI measured from oak trees during 2008-2012 (Soudani et al., 2012). 167 These trees are located in the forest of Fontainebleau (60 km to the south of Paris and ~150 km away from the 168 centre of the Loir catchment). Data from Lebourgeois et al. (2008) indicate that, for oak trees, there is little 169 phenologic difference between Fontainebleau and the Loir catchment. However, remote sensing observations from Muller (1995) show that, in 1987 and in the region of Toulouse (South of France), leaf emergence of riparian trees occurs about 15 days earlier than for oaks. In order to take into account this difference between oak and riparian species, we hence considered an enlarged growing season compared to oak's phenology (β -15 days in spring, β +15 days in autumn). After fitting the four parameters on NDVI values, κ and μ , representing the upper and lower values, are adjusted to fit the winter and summer values of transmissivity (50 and 15%, respectively).

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177 **2.3.Shadow factor and view factor calculations**

In order to test the influence of different riparian shading algorithms on water temperatures simulated with T NET, we used three approaches to compute both the shadow factor (SF) and the tree view factor (TVF).

180 In the first approach (hereafter referred to as the *constant* method), SF and TVF are held as coefficients 181 that are constant in time but vary as a function of Strahler order based on the equation:

$$182 \quad SF = TVF = vc \times k \tag{Eq. 4}$$

where vc is vegetation cover (%) computed at the reach scale in a buffer of 10 m around the river, and k is a coefficient aiming to account for the influence of the reach width on shadow (where 1 (maximum impact) denotes a Strahler order of 1 and 0 (no impact) is associated with a Strahler order of 8). This approach is used in Beaufort et al. (2015, 2016).

187 In the second approach (hereafter referred to as the *variable* method), SF and TVF are derived from 188 geometric calculations made at the reach scale, taking into account river width, tree height, vegetation cover, 189 and position of the sun (for the shadow factor).

To compute SF at an hourly time step, the model of Li et al. (2012) was implemented in its simplest version, i.e.considering rectangular trees, located at the edge of the bank, without overhang:

192
$$SF = \frac{H \times \cot \Psi \times \sin \delta}{W} \times vc$$
 (Eq. 5)

where *H* is tree height, *W* is river width, Ψ is the solar elevation angle, δ is the angle between solar azimuth and the mean azimuth [0° - 180°] of each T-NET reach (computed by considering the first and last vertices of each reach).

To compute VF, we used the second model described in Moore et al. (2014). It provides SVF for channels of infinite length, without taking into account overhanging trees. For a channel with vertical banks and fixed tree height, the width- and reach-averaged tree view factor is computed as:

199
$$TVF = \left[1 - \frac{0.5}{W} \left(\sqrt{H^2 + W^2} + \sqrt{H^2 + W^2} - 2H\right)\right] \times vc$$
 (Eq. 6)

200

The third approach (subsequently referred to as the *lidar* method) is a spatially-explicit method that computes SF and TVF from a LiDAR-derived digital surface model (DSM). It requires a) a high-resolution digital surface model (~1 m) describing the elevation of riparian vegetation , b) information about the exact location of the river in order to define water and non-water pixels and c) polygons of river area, allowing the DSM pixels to be linked to a given T-NET reach. 206 To compute SF, we modified the r.sun module (Hofierka and Suri, 2002) of GRASS GIS (GRASS Development Team, 2015) to map per-pixel shade cast by the DSM. Using this algorithm, a water pixel is defined as being in 207 208 shade if the elevation of the highest DSM pixel located along a 50 m track in the direction of the sun is greater 209 than the solar elevation. Dividing the number of shaded pixels by the number of water pixels belonging to each 210 river polygon thus provides a shadow factor for each T-NET reach. Because shading at a given hour vary slowly 211 throughout the year, the computation was done every hour when the sun is above the horizon, every 15 days of 212 a standard non-leap year, for every water pixel. A piecewise cubic interpolation is then applied to the SF of each 213 hour separately in order to get a value for each day of the year.

To compute SVF from the DSM, we represented the sky as a hemisphere of radius R centred on a water pixel (as in Essery et al. (2008), Johnson and Watson (1984) and Tung et al. (2006); Figure 2). We used the r.horizon module of GRASS GIS to calculate the angle θ between the horizon and the highest DSM pixel as seen from each water pixel at horizontal azimuth steps ϕ of 10°. The whole hemisphere is thus made of n=36 segments. The diffuse radiation emission is considered to be isotropic and the river surface to be horizontal. The SVF for each segment is computed from the sphere area formula:

220
$$\frac{R^2 \int_{\theta}^{\frac{\pi}{2}} \int_{0}^{\theta} \cos \theta \sin \theta \, d\phi \, d\theta}{R^2 \int_{0}^{\frac{\pi}{2}} \int_{0}^{\phi} \cos \theta \sin \theta \, d\phi \, d\theta} = \frac{1 + \cos 2\theta}{2}$$
(Eq. 7)

221 It therefore follows that the SVF for the whole hemisphere is given by:

222
$$SVF = \frac{1}{2} + \frac{1}{n} \sum_{i=1}^{n} \cos 2\theta_i$$
 (Eq. 8)

223 An averaged TVF value (TVF=1-SVF) is subsequently attributed to each T-NET reach as the mean TVF value for all

224 DSM pixels located within the reach.



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Figure 2: Calculation of a sky view factor from measures of θ , the angle between the horizon and the highest vegetation seen from a water pixel and with an angular step ϕ of 10°. R is the radius of the hemisphere

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229 **2.4.Study site and water temperature observations**

The Loir River basin is an 8283 km² sub-catchment of the Maine River watershed located in central France (Figure 3). The river network of the Loir basin is 4420 km long, of which the Loir River itself is 316 km. The basin is generally low-lying, with altitudes ranging from 20 to 140 meters above sea level. As highlighted by the river network's variable drainage density (Figure 3), a calcareous aquifer with high permeability is present in the 234 north-east of the catchment. It feeds the river network with groundwater exchanges in its upstream sections (Baratelli et al., 2016). Channel slope (computed from a 25 m resolution digital terrain model of the watershed) 235 236 ranges from 0.01% to 5%, with a median value of 0.5%. The main tributaries of the Loir are the Conie, the Yerre and the Aigre, with catchments areas of 530, 300 and 280 km² respectively. The mean discharge of the Loir at its 237 downstream-most gauging station (1961-2015) is 31.8 $m^3 \cdot s^{-1}$ (specific discharge = 4.0 $l \cdot s^{-1} \cdot km^{-2}$). The flows of the 238 Aigre (specific discharge = 5.4 $I \cdot s^{-1} \cdot km^{-2}$) and the Conie (specific discharge = 3.4 $I \cdot s^{-1} \cdot km^{-2}$) show little variation 239 during the year, compared to the Loir. However, interannual fluctuations are much greater, driven by 240 241 piezometric fluctuations of the Beauce aquifer.

Eighteen temperature loggers allowing for the model validation are located in the catchment. They acquired 242 data at an hourly time step with varying periods of availability (extending from summer 2008 to summer 2014). 243 244 The loggers were generally placed at a depth greater than 1 meter (according to the mean interannual water 245 level), and steps were taken to ensure than they were installed within well-mixed sections of the channel to avoid potential stratification biases. Four of these stations are located within the main stem of the Loir (S1 to 246 247 S4), where LiDAR data are available. The period of measurement is different for each station and is given in Figure 4. The annual cycle of mean daily temperature of the Loir River ranges from 2 to 24 °C at station 1 248 (between 08/2010 and 07/2011), while the annual amplitude of the Aigre and the Yerre are smaller because of 249 the groundwater fluxes (5-21 °C and 4-16 °C on the same period, respectively). Temperature regime of the Conie 250 251 River is strongly dependent on the groundwater level. Its variability can be similar to the Loir River (2009, 2010) 252 or very limited (annual range of 8-14 °C in 2014).



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Figure 3: Map of the Loir catchment, with stream temperature monitoring stations, gauging stations, watersheds used for discharge modelling, LiDAR area, geologic formations, Helioclim grid.



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Figure 4: Period of availability of stream temperature observation at the four logger stations located on the Loir River

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2.5.T-NET model implementation and criteria of model performance

The Loir River basin was implemented in the T-NET model. It consists of 2206 reaches, of which the Loir River itself is covered by 161 reaches. Simulated discharge and groundwater inputs used to drive T-NET (derived from the EROS hydrological model) were found to agree reasonably well with observed data. Nash-Sutcliffe (Nash and Sutcliffe, 1970) model efficiency coefficient (NSE) calculated against hydrometric observations ranged from 0.59 to 0.95 (1974-2012 period) for 21 of the 23 sub-basins of the Loir catchment. The remaining two subbasins (<0.10 m³·s⁻¹; located in the upper portions of the watershed) yielded negative NSE values.

In order to compare the three shading methods detailed in section 2.3, we ran the T-NET model three times on
seven hydrologic years (from August 2007 to July 2014).

For the *constant* method, vegetation cover (*vc*) was derived from a dataset available at the national scale (Valette et al., 2012), which is based on river and vegetation polygons from the BD TOPO[®] database, provided by Institut national de l'information géographique et forestière (IGN).

For the *variable* method, *vc* was also derived from this dataset. Tree height *H* was fixed at 15m and river width *W* was estimated using the ESTIMKART empirical model (Lamouroux et al., 2010).

274 For the *lidar* method, the digital surface model (DSM) required for the shading computation was derived from a LiDAR survey conducted by IGN on approximately 270 km of the Loir River (85% of the total river length) 275 on 26 May 2012. That day, average discharge was 25.5 m³·s⁻¹ at the downstream-most gauging station 276 (interannual average is 31.8 m³·s⁻¹). The DSM was generated by gridding the LiDAR first returns at a resolution of 277 278 1 m². LiDAR accuracy was assessed as ~60 cm in the horizontal and ~20 cm in the vertical components. Because 279 water does not reflect the LiDAR pulses, no data was available for the water pixels (unless emergent aquatic 280 vegetation was present), and we used this property to discriminate water vs. non-water pixels inside the river 281 polygons of the BD TOPO database. Elevations for these water pixels as well as for other sporadic data gaps 282 were computed by attributing values from a digital elevation model (DEM) to the no data pixels. This 1-m 283 resolution DEM, built from LiDAR final returns, provides values above water by interpolation of altitudes 284 between the river banks. Finally, polygons from BD TOPO were also used to attribute DSM pixels to each reach 285 of the T-NET network. Because LiDAR data were not available on the tributaries and the headwaters of the Loir, the constant method was applied on these reaches. With this configuration, the lidar method takes less than 5 286 287 hours to run on a computer with 16 CPUs and 64 Gb of RAM. Finally, in order to compare the *lidar* method with 288 a situation without riparian vegetation, a supplementary simulation was done with SF and TVF fixed at zero 289 everywhere.

In order to characterise differences in vegetation cover between the DSM and that derived from the BD
 TOPO database (Valette et al., 2012), a DEM was also used to create a raster of vegetation height by subtracting

the DEM (ground) elevations from the DSM. A vegetation cover map was then extracted from the vegetation height raster, where vegetation cover was defined as all pixels with vegetation higher than 1 m. A LiDAR-derived river width was also extracted for analysis purposes by dividing the area of water pixel inside each polygon by the length of the T-NET reaches.

Three model performance metrics were used to quantify the accuracy of the different methods regarding the maximum daily temperature. The root-mean-square error (RMSE) was used as a global performance metric:

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$$RMSE = \sqrt{\frac{\sum (T_{sim} - T_{obs})^2}{N}}$$
 (Eq. 9)

299 where N is the number of observations, T_{sim} is the simulated river temperature and T_{obs} is the observed river 300 temperature. Bias (defined as the mean difference between simulated and measured temperatures) was used 301 to quantify the mean over/underestimation of the model. Finally, the standard deviation of errors (SDE) 302 quantifies the variability of daily biases in a given period. Because the temperature time series used for model 303 validation were not concomitant (Figure 4), model performance was analysed using two methods. First, we 304 compared model performance against all available validation data. This allows for comparison between the 305 three shading methods detailed in section 2.3. Second, in order to compare spatial variability in the model's 306 performance between the 4 temperature logger stations, we used temperature data from the period during which concurrent measures were available at all 4 stations (13th to the 31st August 2009). 307

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309 **3. Results**

310 **3.1.Characterisation of riparian vegetation cover**

311 Analysis of vegetation cover extracted from the LiDAR data inside a single buffer of 10 m around the 270 km of 312 river shows that 58% of the riparian zone is vegetated. The median vegetation height in this area is 10.0 m and the third quartile of the height (considered by Guzy et al., 2015) is 14.9 m, while the standard deviation is 6.5 m. 313 Longitudinal profiles of vegetation cover, median and 3rd quartile of height are given in Figure 5. There is a slight 314 315 but significant decreasing downstream trend for these three variables (p-value = 0.014). In comparison with the 316 LiDAR-derived vegetation cover, vegetation cover derived from the BD TOPO database is overestimated 317 everywhere with the exception of some small reaches (Figure 5). The median overestimation is 35% upstream of 318 river km 160 and 22% downstream. This overestimation rises to more than 39% for 20% of the reaches.



Figure 5: Characterisation of riparian vegetation for each T-NET reach (a) comparison of vegetation cover derived from the BD TOPO database (Valette et al., 2012) and LiDAR datasets (buffer of 10 m on both sides of the river polygons) (b) median and 3rd quartile vegetation heights from LiDAR data

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324 **3.2.** Variation in riparian shading computed with the three methods

In the Loir catchment, direct and diffuse radiation comprise ~70% and ~30% respectively of the incoming solar radiation received at the river surface between 8 and 16h (period 2007-2014). This means that shadow factor has a greater impact on water temperature than view factor.

Figure 6 shows the longitudinal profile of SF on the Loir River for the three methods at midday on the summer solstice, when solar radiation is strongest. For the *constant* method, the reaches covered by LiDAR data have a uniform Strahler order of 5, so that the weighting coefficient *k* in this area is always equal to 0.4 (see section 2.3). The variation of SF is thus only dependent on the vegetation cover. The *variable* method varies strongly as a function of reach azimuth, even though the sun is at its highest elevation, while the *lidar* method shows smaller variations. The *lidar* method is thus less sensitive to reach azimuth, compared to the *variable* method.



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At noon, the Loir's SF computed with the *lidar* method lies between 0 and 0.3 in June (median=0.1; Figure 7a solid lines) and between 0.1 and 1 in December (median=0.5). There is thus more variability in winter than in summer, because reach azimuth has a much greater impact when the sun is low in the sky. Seasonal variability 341 in SF exhibits strong annual cyclicity, with SF minima centred on the summer solstice for every reach. Highest SF values are found on a reach located 85 km from the source, flowing East-West and bordered by persistent 342 343 riparian forest cover (>20 m tall). Lowest SF values are found on a North-South oriented reach located 271 km 344 from the source, explaining the weak annual cycle at noon (Figure 7a, pink solid line). Figure 7b shows the daily cycles at the summer solstice. The hour of minimum SF in a day is not always centred on noon because it 345 depends on the reach orientation. SF obtained from the *variable* method is usually higher than that provided by 346 347 the *lidar* method, except in winter and at noon for North-South oriented reaches (Figure 7a, dashed pink line). At the summer solstice, between 6 and 18h, the variable method yields higher SF than the lidar method 74% of 348 349 the time, especially in the upstream parts of the watershed. Indeed, the variable method yields 184 occurrences of SF values equal to 1, while it only occurs 3 times with the *lidar* method. 350



Figure 7: Percentiles of the SF distribution obtained with the three methods on the 135 T-NET reaches

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(a) Annual cycles at noon (b) daily cycles at the summer solstice.

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355 Figure 8 shows the longitudinal profile of TVF for the three methods. Mean values are 0.34, 0.38 and 0.26 for the constant, variable and lidar methods respectively. TVF computed with the lidar method comprises values 356 357 between 0.47 and 0.11. Like for the SF, there is a significant (p < 0.01) decreasing trend due to both the increasing width of the river and the decreasing vegetation cover. The variable method overestimates TVF, 358 359 especially for the upstream portion of the river. Indeed, the inter-method variability in computed TVF values 360 decreases as the influence of vegetation on TVF reduces with increasing river width.





Results of this paper focus on the 4 temperature monitoring stations located on the Loir River, where LiDAR data are available. For the 14 other temperature monitoring stations located on the tributaries, the constant method provides a median annual RMSE on mean daily temperature at 1.69 °C (min=1.35 °C, max=2.89 °C). Seasonality in the accuracy is observed since median bias on mean daily temperature is -0.4 °C when computed for the full year but rises to 0.2 °C in summer. 67% of daily biases are comprised between ±2 °C.

Biases, SDE and RMSE averaged on the four stations are shown in Table 1 for the April-September and the October-March periods. In the April-September period, the *lidar* method improves the mean bias by 0.62 °C in comparison with the *constant* method. The mean RMSE is improved by 0.22 °C although the mean SDE is increased by 0.10 °C. The three metrics show that the *constant* method provides better results than the *variable* method. During the October-March period, biases of the 3 methods are closer to zero. All criteria of the *constant* and the *lidar* methods are very similar because solar radiation is lower and vegetation transmissivity is high. However, the *variable* method is consistently colder than the other methods by ~0.3 °C.



Table 1: Model performance criteria for maximum daily temperature,

averaged for the 4 stations located on the Loir River from April to September and from October to March (°C)						
	April to September			October to March		
	Bias	SDE	RMSE	Bias	SDE	RMSE
Constant method	-1.44	1.61	2.17	-0.31	2.04	2.07
Variable method (h=15m)	-1.86	1.65	2.55	-0.60	2.09	2.18
Lidar method	-0.82	1.75	1.95	-0.33	2.05	2.08

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381 Figure 9 shows the monthly biases (T_{sim} - T_{obs}) of maximum daily temperature (T_{max}) computed on available 382 measured data (see Figure 4). At the four stations, the *lidar* method provides improved biases in comparison to both the variable and the constant method from April to September. Compared to the variable method, the 383 maximum improvement occurs during the spring and autumn months (2 °C at S1; 1.5 °C at S2; 0.5 °C at S3; 0.7 384 385 °C at S4). Despite this improvement, the *lidar* method still underestimates river temperature by more than 1 °C 386 during at least 2 months in summer at S1, S2 and S4. The constant method provides a consistently colder T_{max} 387 than the variable (and lidar) methods at stations 3 and 4 from May to August, presumably because this method 388 does not model the seasonal cycle of increasing and decreasing shadow length.



Figure 9: Monthly biases (T_{sim}-T_{obs}) and standard deviation of errors of maximum daily temperature provided by the 3 methods at the 4 stations (averaged annual cycles computed on available observed data)

Averaged annual cycles of SDE show little difference between methods and always stay above 1 °C (Figure 9). That means that simulated T_{max} is substantially more variable than observed data, whatever the method used.

396 **3.4.Impact of riparian shading method on summer maximum daily temperature long profile**

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397 We analysed longitudinal profiles in summer by considering average maximum temperature between the 13th and the 31^{st} August 2009. During this period, discharges were low (<7 m³·s⁻¹ at the downstream-most gauging 398 station) and the averaged maximum daily air temperature in the catchment was relatively high (25.9 °C). The 399 400 longitudinal profiles (Figure 10) exhibit discontinuities in the thermal signal that are driven by cool water inflows from the Conie and Aigre rivers, which drain the Beauce aquifer (Baratelli et al., 2016). Before entering the 401 402 LiDAR-covered area (shown with a dashed vertical line), the variable method is colder than the constant method 403 by more than 2.5 °C. This difference decreases slowly in a streamwise direction until it reverses and the variable method becomes warmer than the constant. Indeed, the three methods provide a persistent warming trend as a 404 405 function of distance from source, but this trend is higher for the variable method (1.87 °C/100 km compared to 1.23 °C/100 km and 1.25 °C/100 km for the constant and lidar methods respectively). This difference in 406 longitudinal trend persists across all summers in the 2007-2014 simulation period. On average between the 13th 407 and 31st August 2009, the *lidar* methods provide warmer T_{max} than the two other methods all along the Loir, 408 409 with biases close to zero at stations 3 and 4. However, T_{max} is still underestimated by 1.6 and 1.3 °C at stations 1 and 2. RMSE values are 1.99, 2.08, 1.43 and 1.79 °C on S1 to S4 respectively. Figure 10 also shows the simulation 410 considering the absence of riparian vegetation. The difference between this output and the lidar method 411

- 412 reaches up to 3.0 °C just upstream of the Conie confluence, where sensitivity analysis shows that the *lidar*
- 413 method simulation is no longer under the influence of the constant method applied upstream of the LiDAR area.
- 414 This difference reaches a minimal value of 1.3 °C at the downstream-most point.



Figure 10: Longitudinal profile of maximum daily temperature (averaged between the 13 and the 31 August 2009) provided by
 the 3 methods and by a vegetation-free simulation. The vertical dashed line depicts the start of LiDAR cover. Conie, Yerre and
 Aigre are the main tributaries.

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420 **4. Discussion**

421 4.1.Discrepancies in computed SF and TVF

The global overestimation of SF and TVF provided by the variable method compared to the lidar method can be 422 explained by four key factors. First, the BD TOPO database that weights the results of the variable method 423 424 clearly overestimates vegetation cover in relation to the LiDAR-derived values (discussed in section 3.1). Second, comparison of the wetted widths used in the variable method with LiDAR-derived river widths shows that the 425 426 former are underestimated, especially upstream of ~150 km and downstream of ~250 km from the source. These width uncertainties drive an increase in SF (TVF) of 6% (4%) when averaged over the entire modelling 427 period and 14% (9%) between 13th and 31st August 2009. Third, discrepancies may also arise from the fact that 428 the variable method uses averaged stream azimuths while the lidar method intrinsically considers the position 429 430 of vegetation in regard to the water surface. Indeed, reach azimuth impacts the timing of minimum SF (Li et al. 2012), the hourly amount of direct solar radiation and hence the maximum daily temperature (Garner et al., 431 2017). In order to quantify these discrepancies, we cut the Loir river GIS line in 50 m parts and compared 432 azimuths of these small reaches with the original T-NET reaches azimuths. The mean absolute difference is 26° 433 434 and R² is 0.66. Finally, the characterisation of vegetation cover and height at high resolution with the LiDAR data 435 may not be reproducible in the variable method by taking an average of these data at the reach scale. Indeed, Greenberg et al. (2012) report that 28% of the change in insolation caused by removal of riparian vegetation 436 437 characterised with LiDAR data could not be explained by considering averages at the reach scale. In our case, a 438 multiple linear regression between LiDAR-derived TVF and LiDAR-derived tree height, vegetation cover and river width averaged at the reach scale provides R^2 =0.83. Hence, 17% of the TVF variance cannot be explained by 439 these three variables when averaged at the reach scale. 440

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442 **4.2.Influence of shading routine on simulated river temperatures**

443 In order to separate the influence of the variable method itself from the influence of the vegetation cover data used to drive it, we injected the vegetation cover computed from the LiDAR data (10 m buffers on each river 444 445 bank for each reach) into the variable method. As a first step, tree height was kept at 15 m. The resulting 446 longitudinal profile (13 to 31 August 2009 average) shows that, in this configuration, the variable method closely 447 approximates the lidar method (Figure 11). The mean bias (computed against observed temperatures) between April and September is -1.19 °C, compared to -0.94 °C for the lidar method and to -1.86 °C for the variable 448 449 method with the original vegetation cover. The median vegetation height computed from the LiDAR dataset was subsequently also injected into the variable method. In this case, mean bias is further reduced to -0.78 °C. Using 450 the same approach with the *constant* method provides a profile that is warmer than the *lidar* method profile 451 prior to river km 100 and colder after river km 200. Hence, a coefficient k=0.4 seems to be appropriate for a 452 453 river width of 25-30 m, during the month of August.



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Figure 11: Longitudinal profile of maximum daily temperature (averaged between the 13 and the 31 August 2009) provided by injecting the *variable* method with vegetation cover (*vc*) and median height from LiDAR data. The vertical dashed line depicts the start of LiDAR cover. Conie, Yerre and Aigre are the main tributaries.

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459 **4.3.Performance of T-NET model on the Loir River**

460 Although the T-NET model of the Loir River (driven with the *lidar* method) provides relatively unbiased temperature at station 3, it still underestimates temperature at stations 1 and 2 and to a lesser extent at station 461 4 (Figure 9). Sensitivity analyses show that uncertainty about the impact of vegetation on tributaries (because of 462 463 the application of the *constant* method in areas where LiDAR data do not exist) cannot fully explain the 464 underestimation of modelled temperatures on the Loir. Underestimation at station 1 is partly due to the underestimation of the Conie tributary. An impoundment located at the source of the river likely explains why 465 the Conie is warmer than expected (Pedersen and Sand-Jensen, 2007; Dripps and Granger, 2013). 466 Impoundments on several other tributaries may have the same effect and contribute to warming the Loir River 467 468 and hence explain the negative biases at station 2. Station 4 is located just upstream of a small weir. There are more than 120 small weirs (height <3m) on the Loir River that may partially explain the temperature 469 470 underestimation. Indeed, by increasing water depth, they increase travel time and thus sensitivity to air temperature. By decreasing water velocity, they can favour thermal stratification in summer (Torgersen et al., 471 2001) and since water is usually released by weir-overflow, warmer water may be selectively released. This 472 process is not taken into account in T-NET because it only considers the longitudinal dimension. Other more 473 474 complex hydrodynamic models (eg. Becker et al., 2010; Cole and Wells, 2006; Maderich et al., 2008; Deltares,

475 2014) would therefore be required to incorporate this process. The high temporal variability in modelled temperatures (compared to observed data) is likely due to modelled flow velocities that exceed real values. 476 477 Unfortunately however, we have no observed values of travel time to compare with. Finally, it must be kept in 478 mind that 1) computed model performances are dependent on the number of validation stations, which is 479 limited to 4 in the current study and 2) that the T-NET model is driven with re-analysis data which are 480 themselves subject to errors. In particular, the number of meteorological stations providing air temperature as 481 input of the SAFRAN reanalysis in the Loir catchment is limited: approximately 10 stations are located upstream 482 of S1 but only 2 stations located close to each other cover the rest of the basin (Quintana-Seguí et al., 2008). The 483 density of stations is still lower for wind velocity and relative humidity but is higher for precipitations.

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4.4.Implications, shading methods limitations and perspectives

486 Our results show that the *lidar* method has good potential for computation of SF and SVF at hourly 487 timesteps on medium to large rivers and at large temporal and spatial scales. For small rivers (width < 10 m), 488 whose precise location can be hard to determine using remote sensing due to obscuration by the tree canopy, 489 the variable method may be more suitable, as long as it is fed with accurate vegetation cover data. Indeed, our 490 results show that differences of modelled T_{max} can be large if the methods are used with inaccurate vegetation 491 cover data. The quality of these input data is therefore highly important for improving stream temperature 492 modelling. LiDAR covers of riparian zones are increasingly available, in particular because of their use for flood 493 risk assessments. Furthermore, vegetation heights can also be obtained at the catchment scale by 494 photogrammetric techniques (eg. Michez et al., 2017), while satellite and airborne high resolution imagery can 495 provide accurate location of riparian vegetation (Tormos et al., 2014). These new techniques could potentially 496 be valuable for improving future river temperature modelling efforts.

497 Our results show that in late August 2009, the Loir's vegetation decreases T_{max} up to 3 °C in the 498 upstream part of the river and by 1.3 °C at the downstream-most reaches. This difference is caused by the 499 increasing wetted width (from ~25 to ~50 m) but also by decreasing vegetation cover in the streamwise 500 direction. These quantifications of the thermal impact of riparian vegetation are likely minimum values for two 501 reasons. First, the impact of overhanging trees was neglected (as in all methods used in this paper) (Li et al., 502 2012; DeWalle, 2008). Secondly, the summer transmissivity value comes from publications studying single trees' 503 transmissivity. However, because riparian buffers are often composed of several rows of trees, real world 504 transmissivity values are likely to be lower, resulting in slightly cooler water temperatures (Duursma and 505 Mäkelä, 2007; Dugdale et al., 2018). Beside this, further research is needed to validate the accuracy of shadows 506 obtained with the lidar method against aerial imagery. As an example, Greenberg et al. (2012) reported an 507 overall accuracy of 92%. Since their LiDAR data and ours were both acquired when trees were in leaf, a similar 508 accuracy may be expected.

509 A wide range of values is reported in the literature regarding the cooling effect of vegetation (Moore et 510 al., 2005), mainly for streams narrower than 10 m, for which the response of T_{max} to clear-cutting can range from 511 2 to 8°C (Gomi et al., 2006). For streams wider than 10 m, a modelling approach is usually used to quantify the 512 impacts of vegetation on stream temperature. Our results are in agreement with Woltemade and Hawkins (2016), who modelled a cooling effect of vegetation of approximately 2 °C for a 14 m wide North-West/South-513 514 East oriented stream flowing in a mountainous catchment of California (low-flow conditions). A topographic 515 shade of 17% was considered in the deforested scenario; their result would thus be higher in an environment 516 without mountains, like the Loir catchment. Using LiDAR data, Wawrzyniak et al. (2017) modelled a cooling impact of 0.4 °C on T_{max} on a 22 km-long groundwater-fed river reach with a wetted width ranging from 50 to 517 518 120 m. The overall NNE-SSW orientation of this river is likely to decrease the impact of riparian vegetation, in 519 comparison with the Loir, which is globally east-west orientated. Other studies show that the impact of 520 vegetation decreases steadily as wetted width increases to about 30 m (Teti, 2006), 10 m (Davies-Colley and Quinn, 1998) and 17 to 43 m for East-West to North-South oriented streams (DeWalle, 2008). Our results 521 522 suggest that the cooling effect can remain above 1 °C even for widths larger than 40 m.

523 Potential improvements to our *lidar* method include the incorporation of wetted widths related to the 524 discharge. Although this is possible at small spatial and temporal scales by using a hydraulic model (Wawrzyniak 525 et al., 2017), modelling wetted widths at regional scales can be very complex, especially without field measures 526 of hydraulic geometry. Channel morphology from bathymetric LiDAR data may be one potential solution to this 527 issue (eg. Hilldale and Raff, 2008; Bailly et al., 2010). Another potential improvement to our methodology relates to the use of Beer's law to model the extinction of solar rays through the tree canopy, as demonstrated by 528 529 several investigations using coarse vegetation data (Sun et al., 2015; Tung et al., 2007; Sridhar et al., 2004; Lee et al., 2012). Transmission of light beneath the canopy of overhanging trees could also be modelled, but 530 requires information or hypotheses regarding the shape of trees. When aerial imagery is available, more 531 532 complex methods considering position of individual trees may be used in order to model the transmission of 533 light beneath the canopy (Essery et al., 2008).

534 Finally, this paper focuses on the impact of vegetation on solar radiation and hence on maximum daily 535 temperature (Johnson, 2004; Garner et al., 2017). Although the impact of vegetation on longwave radiation is 536 limited on sunny days (Leach and Moore, 2010; DeWalle, 2008), view factors computed in this paper could be used to quantify the impact of vegetation on longwave fluxes at both regional scales and during a complete 537 538 annual cycle. LiDAR data could also be used to model the impact of vegetation on water temperature resulting 539 from decreased air temperature and wind velocity engendered by the riparian canopy. Indeed, forest canopies 540 can reduce daytime air temperature by 3 °C to more than 6 °C and wind velocity by 10-20 % in comparison with 541 open areas (Moore et al., 2005).

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543 **5. Conclusion**

The main goal of this study was to understand the influence of using a LiDAR-derived digital surface model to quantify the impact of riparian vegetation on 270 km of the Loir River. We demonstrated that the use of LiDAR data improves the mean biases of simulated maximum daily temperatures (T_{max}) in summer, compared to two other simpler methods for computing the effects of riparian shading at large scales. However, it did not improve the standard deviation of errors on T_{max} , which is likely more influenced by the presence of weirs and impoundments.

550 The monthly-averaged difference in T_{max} computed by the various shading methods can reach up to 2 °C at the 551 upstream-most station and 1 °C at the downstream-most station. However, this difference is mainly due to the 552 overestimation of vegetation cover in the dataset used to compute shadow and view factors in the non-lidar methods. Indeed, injection of vegetation cover extracted from the LiDAR data into the shading method of 553 554 medium complexity (variable method) decreased the largest difference at the upstream-most station to 0.8 °C, 555 suggesting that this method is sufficient for the computation of SF and VF provided that it is supplied with accurate (high-resolution) data pertaining to vegetation cover. Improving the quality of riparian vegetation data 556 should therefore be a priority for improving stream temperature modelling at the regional scale. The simplest 557 558 method (constant method) may be appropriate to model mean daily temperature for a given period of the year, 559 as long as vegetation cover is weighted with a coefficient depending on the river width.

We hope that the application and comparison of methods demonstrated in this paper will improve understanding of the strengths and limitations of other existing stream temperature models. Enhancing the ability of models to simulate the impact of riparian vegetation is of key importance for the development of climate change adaptation measures and understanding the fundamental processes responsible for spatiotemporal variability of river temperature.

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