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Neuroplasticity of prehensile neural networks after quadriplegia

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Targeting cortical neuroplasticity through rehabilitation-based practice is believed to enhance functional recovery after spinal cord injury (SCI). While prehensile performance is severely disturbed after C6-C7 SCI, subjects with tetraplegia can learn a compensatory passive prehension using the *tenodesis* effect. During tenodesis, the active wrist extension triggers a passive flexion of the fingers allowing grasping. We investigated whether motor imagery training could promote activity-dependent neuroplasticity and improve prehensile tenodesis performance. SCI participants (*n* = 6) and healthy participants $(n = 6)$ took part in a repeated measurement design. After an extended baseline period of three weeks including repeated magnetoencephalography (MEG) measurements, MI training was embedded within the classical course of physiotherapy for five additional weeks (3 sessions per week). An immediate MEG post-test and a follow up at two months were performed. Before MI training, compensatory activations and recruitment of deafferented cortical regions characterized the cortical activity during actual and imagined prehension in SCI participants. After MI training, MEG data yielded reduced compensatory activations. Cortical recruitment became similar to that in healthy participants. Behavioral analysis evidenced decreased movement variability suggesting motor learning of tenodesis. The data suggest that MI training participated to reverse compensatory neuroplasticity in SCI participants, and promoted the integration of new upper limb prehensile coordination in the neural networks functionally dedicated to the control of healthy prehension before injury.

Keywords: Magnetoencephalography, rehabilitation, spinal cord injury

1. Introduction

Spinal Cord Injury (SCI) is the traumatic disruption of the neural pathways between the brain and the peripheral effectors. Extensive cortical reorganizations due to neuroplasticity occur after SCI [\(for a review, see Kokotilo et al., 2009\)](#page-24-0). Transcranial magnetic stimulation studies evidenced higher levels of corticospinal excitability in muscles innervated above the level of injury [\(Levy et al., 1990,](#page-24-1) [Topka et al., 1991,](#page-27-0) [Streletz et al., 1995\)](#page-27-1). Brain imaging studies provided evidence that disconnected brain regions became progressively re-assigned to the control of spared movements represented in adjacent sites of the cortical homonculus [\(Bruehlmeier et al., 1998,](#page-21-0) [Lotze et al., 1999a,](#page-25-0) [Curt et al.,](#page-22-0) [2002,](#page-22-0) [Mikulis et al., 2002\)](#page-26-0). Overall, cortical neuroplasticity after SCI appeared to *"maximize output"* to the unaffected muscles [\(for a review, see Nardone et al., 2013\)](#page-26-1). [Jurkiewicz et al. \(2007\)](#page-24-2) reported that concentration of activations within the primary motor cortex and decreased activity within secondary brain motor regions during wrist extensions correlated with functional recovery during the first year post-injury [\(see also Green et al., 1999\)](#page-23-0). Targeting cortical neuroplasticity through rehabilitation-based practice may thus lead to better understand the recovery processes after complete SCI.

Activity-dependent neuroplasticity inspired the development of rehabilitation strategies after SCI (for review, see [Dunlop, 2008,](#page-22-1) [Harvey et al., 2009\)](#page-23-1). These foremost involve PP-based training (*e.g.*, physiotherapy, robot-assisted motor training). Interestingly, Motor Imagery (MI, the mental representation of an action without engaging in its actual execution) represents an *"emerging avenue"* to CNS stimulation after SCI [\(Dunlop, 2008\)](#page-22-1). A large body of neuroscience research provided evidence that MI and PP were functionally equivalent neural processes, *i.e.,* both tasks engage overlapping structures within the brain motor network underlying actual motor preparation and execution [\(Decety et al., 1994,](#page-22-2) [Jeannerod, 1994,](#page-24-3) [Porro et al., 1996,](#page-26-2) [Lotze et al., 1999b,](#page-25-1) [Ehrsson et al.,](#page-22-3) [2003,](#page-22-3) [Lotze and Halsband, 2006,](#page-25-2) [Szameitat et al., 2007b,](#page-27-2) [a,](#page-27-3) [Guillot et al., 2012a,](#page-23-2) [Szameitat](#page-27-4) et al., [2012,](#page-27-4) [Burianova et al., 2013,](#page-21-1) [Hétu et al., 2013\)](#page-23-3). Reduced activations intensities by 30 to 50 % are usually recorded during MI compared to PP [\(Porro et al., 1996,](#page-26-2) [Lotze and Halsband, 2006,](#page-25-2) [Munzert et](#page-26-3) [al., 2009\)](#page-26-3). Nonetheless, MI elicits sufficient CNS activation to stimulate cerebral neuroplasticity,

thereby promoting motor learning and increased muscle performance in healthy participants [\(Pascual-](#page-26-4)[Leone et al., 1995,](#page-26-4) [Ranganathan et al., 2004\)](#page-26-5). Functional equivalence between PP and MI is preserved for spared actions after complete SCI [\(Lacourse et al., 1999,](#page-24-4) [Di Rienzo et al., 2013,](#page-22-4) [Di Rienzo et al.,](#page-22-5) [2014\)](#page-22-5), and [Cramer et al. \(2007\)](#page-22-6) provided evidence that SCI participants benefited from MI training to learn actions executed with muscles retaining a voluntary control.

Human prehension involves reaching and grasping objects within the haptic space [\(van de](#page-27-5) [Kamp and Zaal, 2007\)](#page-27-5). This function is severely disturbed after cervical SCI [\(Harvey, 1996,](#page-23-4) [Snoek et](#page-27-6) [al., 2004,](#page-27-6) [Snoek et al., 2008\)](#page-27-7). According to the surgical classification of Giens [\(McDowell et al.,](#page-26-6) [1986\)](#page-26-6), finger and forearm muscles are paralyzed from the C6/C7 level. Accordingly, how can C6/C7 quadriplegic SCI participants achieve manual prehension in spite of finger and forearm muscles paralysis? SCI participants must learn a different pattern of prehension through extensive rehabilitation. Voluntary control of shoulder muscles is preserved, while active elbow and wrist extension remain possible due to residual control of the *triceps brachii* and *extensors carpi radialis*. Arm and hand positions during reaching can be controlled by proximal shoulder muscles while grasping is achieved with the tenodesis effect, *i.e.,* an active extension of the wrist triggers a passive flexion of the fingers [\(Harvey et al., 2001,](#page-23-5) [Mateo et al., 2012\)](#page-25-3). Tenodesis prehension (TP) is thus a compensatory prehension that require new motor programs (*e.g.*[, Mateo et al., 2012\)](#page-25-3). Recent findings provided evidence that MI training improved the kinematic parameters of TP after cervical SCI, particularly movement speed and accuracy [\(Grangeon et al., 2010,](#page-22-7) [Grangeon et al., 2012\)](#page-22-8). MI was assumed to stimulate activity-dependent neuroplasticity. [Grangeon et al. \(2012\)](#page-22-8) nonetheless underlined that their results were to be replicated on larger sample of SCI participants.

Prehension is controlled by a widespread cortical network involving frontal, parietal and occipital associative cortices interacting with primary somatosensory and motor structures [\(Jeannerod](#page-24-5) [et al., 1995,](#page-24-5) [Rizzolatti et al., 1996,](#page-26-7) [Binkofski et al., 1998,](#page-21-2) [Kuhtz-Buschbeck et al., 2001,](#page-24-6) [Grafton,](#page-22-9) [2010\)](#page-22-9). Whether similar neural networks underpin TP in C6/C7 quadriplegic participants is a first interest. A second issue relates the effect of MI training on TP, and the associated effects on the neural networks controlling PP and MI of prehension. Also, previous studies reporting the preservation of functional equivalence between MI and PP after SCI foremost involved *simple* motor sequences which could be easily executed physically [\(Lacourse et al.,](#page-24-4) 1999, [Sabbah et al., 2002,](#page-27-8) [Di Rienzo et al., 2013\)](#page-22-4). However, [Olsson \(2012\)](#page-26-8) showed reduced recruitment of the motor system during MI of *complex* motor sequences that were impossible to perform physically after SCI. [Olsson \(2012\)](#page-26-8) argued that the lack of PP due to chronic deafferentation and deefferentation led to the degradation of complex motor representations. Whether C6/C7 quadriplegic participants are able to achieve MI of TP with a high degree of functional equivalence in spite the complexity of this skill is a final issue of interest. Using magnetoencephalography (MEG), we examined the effect of 5-week of MI training on TP performance in C6/C7 SCI participants. MI was integrated to the course of physiotherapy. MEG afforded investigation of cortical activity underlying actual and imagined TP.

2. Experimental procedures

2.1. Participants

SCI participants ($n = 6$) (5 right handed, 2 females) were recruited from the Henri Gabrielle hospital (St Genis Laval, France) over a 1 year period of inclusion. Inclusion criteria were: *i)* age range 18-55 years, *ii)* SCI at the C6/C7 level eliciting complete motor deficit according to the American Spinal Injury Association (ASIA) impairment scale [\(Maynard et al., 1997\)](#page-25-4), *iii)* post-traumatic period superior to 6 months *(i.e.*, corresponding to the spontaneous motor recovery plateau; Waters et al., [1993,](#page-27-9) [Yakura, 1996\)](#page-28-0). Exclusion criteria were: *i)* non-stabilized hypertension or pathological dysfunction of the autonomic nervous system, *ii)* cerebral damage and / or cognitive deficit, *iii)* elbow or shoulder joint amplitude restriction, upper limb para osteo-arthropathy, *iv)* simultaneous inclusion to another study, and *v)°*presence of metallic objects within the body (*e.g.* pacemaker, auditory device or brace) incompatible with MEG or fMRI recordings. HPs matched to SCI participants according to gender, age $(\pm 1 \text{ year})$ and handedness were recruited as controls.

All participants provided informed written consent according to the statements of the Declaration of Helsinki. This study was performed under approval of the Lyon Civil Hospices ethic

 committee (CPP 2009-051-B), and was part of the Hospital Program for Clinical Research n° 2010- 541/142 registered under the trial number ACTRN12612001030864.

2.2. Experimental design

SCI participants were hospitalized across the duration of experiments, and underwent daily standard medical care including physiotherapy (*e.g.*, passive limb mobilization, muscle strengthening above the lesion level, etc.) and occupational therapy.

We conducted repeated pre-test assessments over a five weeks period to define the baseline level (Figure 1). Pre-tests were separated from each other by a minimum period of one week. Then, individual MI sessions were embedded to the classical course of physiotherapy (3 sessions of 45 min per week). MI sessions were delivered in a quiet room at the hospital. Spinal cord injury (SCI) participants were seated on their wheelchair, in front of a table and performed imagined prehensile actions with tenodesis in an ecological environment. All tasks were goal-directed. During the first week, the experimenter showed the movement before the participant physically or mentally performed it. Experimenter was assisted by physiotherapists who helped the SCI participant to achieve execution of complex motor tasks. Training sessions were of increased complexity along the course of training, based on SCI participants' abilities (*i.e.*, from simple pointing actions during familiarization to complex sequences involving more rapid reaching/grasping of smaller, larger, or heavier objects placed in the haptic space). Visual and kinesthetic imagery were both used during training, promoting analysis of the kinematics and correcting inadequate executions. PP *vs.* MI training ratio was 1 to 5 and increased each week up to 1 to 9.

The intervention period was followed by an immediate post-test and a follow-up at 2 months (Figure 1). HPs underwent an identical procedure but performed a control task (*i.e.,* visualization of geometric forms) during the 5 weeks allocated to MI training in the SCI group. The HPs group thus only controlled for the general effect of MI training. The prehension used by HPs differed from TP, and thus potential transfer of MI training to healthy prehension would be limited for a similar training content.

2.3. Experimental sessions

Experimental sessions included MI assessments and MEG recordings (Figure 1).

2.3.1.Motor imagery ability assessment

During the first session, the participants completed the Kinesthetic and Visual Imagery Questionnaire [\(KVIQ; Malouin et al., 2007\)](#page-25-5) (Figure 1). The KVIQ was aimed at testing whether HPs and SCI participants share comparable capacities to achieve vivid MI. It is made of 20 items involving axial movements with head and trunk, as well as upper and lower limb movements. Each participant reported immediately after completion of actual movement the level of MI vividness on a 5-point Likert scale using first person visual or kinesthetic MI. If the participant was not able to physically perform the movement, he was requested to observe its execution by the experimenter before each trial. Only KVIQ data related to MI of the dominant upper limb were processed.

The capacity to achieve temporal equivalence between PP and MI durations was used as behavioral index of MI accuracy [\(Guillot and Collet, 2005,](#page-23-6) [Collet et al., 2011,](#page-21-3) [Guillot et al., 2012b\)](#page-23-7). The participants were requested to point to four cardinal points drawn on a 10 cm circle target in the clockwise direction with their dominant upper limb. They completed two PP and MI trials at each phase of the experimental procedure (Figure 1).

2.3.2.Magnetoencephalography recordings

The MEG was a CTF-MEG system (CERMEP, F-69677), with 275 radial gradiometers over the scalp and 33 reference channels for ambient field correction. MEG signals were digitalized at sampling rate of 600 Hz and low-pass filtered (0 - 150 Hz). Head position was controlled in real-time using three head coils placed on the nasion and pre-auricular points prior to scanning. Each participant was installed on the MEG seat by two physiotherapists under the supervision of a medical doctor. A wooden table was placed above their knees standardizing the position of the dominant hand and making the non-dominant arm lying in a comfortable position (Figure 2A). A fake apple was the target placed in the sagital plane within 60 % of the haptic space. Participants were requested to reach and grasp the apple, to put it into contact with their mouth and then to place it back on the initial position (Figure 2A). This motor sequence was selected for its complexity and its functionality.

**** Insert Figure 2 about here ****

Participants were instructed to complete 10 successive trials of the prehensile sequence (PP condition). Movement time (MT, from movement initiation until the participant has put the apple again to its initial position) was recorded using optical fiber switch system (Figure 2BC). Each participant also performed 10 MI trials of the same sequence using first-person and kinesthetic MI concurrently (MI condition). Finally, they were instructed to remain motionless during 10 trials (CONTROL condition). An auditory soundtrack provided instructions regarding each experimental condition and triggered each trial every 15s. Experimental conditions were randomly presented three times each within a block-design for a total of 30 trials in each condition. The number of trials was expected to preserve SCI participants from deleterious effects of physical and mental fatigue.

Anatomical MRI was recorded during the week preceding the first pretest for co-registration with MEG data. A 1.5T Siemens Magnetom scanner (CERMEP, France - Siemens AG, Erlangen, Germany) computed 3-dimentional anatomical T1 weighted pictures covering the whole brain with 1 $mm³$ cubic voxels (TR: 9.7 ms, TE: 4 ms).

2.3.3.Magnetoencephalography data processing

We used Synthetic Aperture Magnetometry (SAM) as beamformer to map the distribution of event-related synchronization (ERS) and desynchronization (ERD) of brain oscillations. We investigated MEG beta signals (15-30 Hz), as this frequency domain was shown particularly relevant for the study of MI and motor execution networks in both HPs and SCI subjects [\(Burianova et al.,](#page-21-1) [2013,](#page-21-1) [Di Rienzo et al., 2013\)](#page-22-4). Brain rhythms encompassing few frequencies (*e.g.,* the mu-sensorimotor rhythm) were not investigated. Considering the number of trials, beamforming imaging was expected to be more powerful/reliable carried on MEG signals encompassing larger frequency domains [\(Brookes et al., 2008\)](#page-21-4). SAM displays the spatial distribution of event-related changes of power in defined brain rhythms using t-paired Jackknife statistics between an active and a control state. In the present experiment, the active state duration corresponded to the median duration of the prehensile sequence (PP condition). Depending on participants' ability to achieve temporal equivalence between MI and PP, active state duration would remain unchanged between MI and PP conditions, otherwise increased or shortened. Control state was placed before stimulus onset for each condition, and its duration corresponded to the median PP duration throughout sessions and participants, thus ensuring an identical reference period for computation of MEG contrasts.

In the present design, the sample size was due to the highly specific inclusion criteria and restricted inclusion period. We used a unique approach to delineate the neural underpinnings of actual and imagined prehensile actions in HPs and SCI groups. SAM computes and displays t-contrast values between active and control states at each point of a 3-dimensional cubic grid (5 mm) overlaid to the anatomical MRI brain volume of each individual. We applied a statistical mask to each SAM map for each experimental condition: SAM sites displaying t-contrast values between active and control states inferior or equal to *t* = 2 were coded 0. SAM sites which displayed t-contrast values strictly superior to $t = 2$ were coded 1. For each participant, masked SAM maps corresponding to each pretest were summed for each experimental condition. Only SAM sites displaying maximal values (corresponding to brain sites which elicited t-contrast ratios higher than $t = 2$ during each of the three pre-tests) were considered part of the task-specific neural network (*i.e.*, each site thus corresponded to a $p = 1.10^{-4}$ level of statistical significance as SAM t-contrast values were computed on the basis of paired t-tests with 30 trials per condition). For group analysis, we combined and normalized pre-tests masked SAM maps for each experimental condition within the Talairach and Tournoux space [\(Talairach and](#page-27-10) [Tournoux, 1988\)](#page-27-10) using AFNI® functions [\(http://afni.nimh.nih.gov/\)](http://afni.nimh.nih.gov/). Again, only SAM sites displaying the maximal values were considered part of the task-related network of the group ($p = 1.10$ ⁻ 23).

2.4. Statistical procedure

We performed the statistical analyses with R [\(R Core Team, 2014\)](#page-26-9). Data normality was checked through visual inspection of Q-Q plots, and the type 1 error rate settled at $\alpha = .05$.

2.4.1.Motor imagery evaluations

Student's t-tests were used to compare KVIQ scores between groups. We tested the temporal equivalence between PP and MI durations. We calculated Pearson's product-moment correlation between PP and MI durations, and compared median PP and MI durations using a paired Student's ttest.

2.4.1.Motor performance

MT and movement variability (MV, the variance of MT) were bootstrapped at the individual level for each experimental session. We used R [\(R Core Team, 2014\)](#page-26-9) and *lme4* [\(Bates et al., 2014\)](#page-21-5) to perform a linear mixed effects analysis [\(Winter, 2013\)](#page-28-1). A rank transformation of MT and MV was applied to increase the statistical power [\(Baguley, 2012\)](#page-21-6). As fixed effect, we entered the interaction between group and experimental session. As random effect, we had intercepts by subjects. Visual inspection of the residual plots did not reveal any deviations from homoscedasticity or normality. The *p*-values were obtained using likelihood ratio tests of the full model against the model without the effect in question. For post-hoc investigations, mixed linear models were applied on datasets from which classes of the factors considered were removed to allow dual comparisons. Holm's sequential corrections were applied to control the false discovery rate [\(Holm, 1979\)](#page-24-7).

2.4.1.MEG

Due to the stringent procedure used to disclose MEG activation sources underlying actual and imagined prehensile actions in HPs and SCI groups (see above), we opted for descriptive between- and intra-group comparisons.

3. Results

3.1. Motor imagery evaluations

Mean $(\pm SD)$ KVIQ visual (HPs = 4.33 \pm 0.47; SCI = 3.55 \pm 0.95) and kinesthetic sub scores $(HPs = 3.66 \pm 0.44$; SCI = 3.83 \pm 0.91), as well as KVIQ total scores (HPs = 3.91 \pm 0.41; SCI = 3.66 \pm 0.91), were comparable in both the HCs and the SCI group $(t = -1.78, p = 0.12; t = 0.54, p = 0.60; t = -1.78)$ 0.67, $p = 0.52$; respectively). Data from the mental chronometry task showed significant correlation between MI and PP durations at the whole-group level ($r = 0.94$, $p < .001$). No significant difference emerged between MI and PP durations ($t = 0.46$, $p = 0.66$). Accordingly, we used similar SAM time windows for MEG data analysis during PP and MI conditions.

3.2. Motor performance data

Mixed linear models revealed the significant interaction between group and experimental session on MV ($\chi^2(4) = 25.60, p < .01$), but not on MT ($\chi^2(4) = 7.56, p = .11$). The statistical power of the test for MV was .83. Post-hoc investigations revealed a higher MV during the pre-test 3 as compared to the pre-test 2 in HPs ($p < .05$) whereas, in the SCI group, MV during the post-test 1 was lower than during each of the pre-tests by 70-76 % (all $p < .01$), see Figure 3.

**** Insert Figure 3 about here ****

Linear models also yielded significant group effects on MT (χ^2 (4) = 19.15, p < .001) and MV $(\chi^2(4) = 19.74, p < .001)$, with a statistical power of .98 and .99, respectively. As shown in Figure 3, comparisons between groups showed lower MT and MV in HPs compared to SCI subjects, for each experimental session (all $p < .01$). MT values ranged between 3.62 to 4.30 s in HPs and 7.00 to 8.00 s in SCI groups. Based on MT data, SAM control state duration was settled at 5.75 s (see methods).

3.3. Magnetoencephalography data

SAM maps yielded clear ERD patterns during PP and MI conditions in both groups. No brain region reached the required level of statistical significance during the CONTROL condition in both groups.

3.3.1.Pre-tests

During PP, both SCI and HP groups recruited a widespread cortical network that encompassed the contralateral pre-central gyrus, left inferior parietal lobe and precuneus (Figure 4 and Table 1). HPs recruited portions of the contralateral pre-central gyrus corresponding to the hand area, whereas portions of the pre-central gyrus corresponding to the representation of the legs were activated in SCI participants (*i.e.,* activation located more medially) (Figure 4). Finally recruitment of the contralateral post-central gyrus was observed in the HP but not in the SCI group, while contralateral precuneus activations extended anteriorly towards the paracentral lobe in SCI subjects only. Ipsilateral activations were also present. Both groups recruited the ipsilateral pre- and post-central gyrii, and inferior parietal lobe (Figure 4 and Table 1).

During MI, no ipsilateral activations were detected in SCI and HPs groups. Strong overlap with contralateral brain regions activated during PP was noted. Activations were detected in both groups in the pre- and post-central gyrii, superior parietal lobe and precuneus. Compared to HPs, no activation of the inferior parietal lobe was present in SCI subjects. Similarly as during PP, precuneus activations extended to the paracentral lobe in SCI participants but not in HPs. SCI participants recruited portions of the post-central gyrus corresponding to the representation of lower limbs within the sensory homunculus, whereas HPs recruited sites corresponding to hand representation (see Figure and Table 1). Surprisingly, however, SCI and HPs both recruited portions of the pre-central gyrus corresponding to the hand motor area (see Table 1).

**** Insert Figure 4 about here ****

3.3.2.Post-test

There was no MV difference between post-test 1 and 2 in SCI participants ($p > .05$), albeit mean MV slightly increased in post-test 2 (Figure 3). Accordingly, masked post-test 1 and 2 SAM activation maps were combined to increase the statistical power of post-test MEG analyses. We used the same procedure for pre-tests SAM activation maps. Only sites showing the maximal score were taken into account (*i.e.*, corresponding to a $p < 1.10^{-15}$ level of statistical significance).

During PP, both groups recruited the contralateral pre- and post-central gyrii, inferior parietal lobe and precuneus. Recruitment of the upper limb motor representation within the motor and somatosensory homunculi was present in both groups, whereas it was not the case in SCI subjects during the pre-tests (Figure 4 and Table 1). Furthermore, activation of the the contralateral superior parietal lobe was recorded in SCI subjects only. SCI subjects finally showed reduced ipsilateral involvement of the pre- and post-central gyrii as compared to HPs.

Only contralateral activity was present in HP and SCI groups, similarly as during the pre-tests. Brain activation during MI was congruent with that during PP. Pre- and post-central gyrii activations were observed at sites corresponding to the hand representation within the motor and somatosensory homunculi (Figure 4 and Table 1). We also observed the activation of the inferior parietal lobe while the superior part was activated in HPs but not in SCI participants (Table 1).

4. Discussion

This study addressed the neural networks controlling actual and imagined prehension in participants with SCI at C6-C7 level, before and after embedding MI training to the classical course of rehabilitation. In HCs, post-tests networks were similar to those activated during the pre-tests. As the HCs group did not receive any specific training intervention, this supports reliability of the MEG analysis procedure applied ensure power/reproducibility of the findings [\(Button et al., 2013\)](#page-21-7).

4.1. Pre-tests data

MT and MV remained stable in HPs and SCI participants across the three pre-tests. TP is an intrinsically distinct skill from the usual pattern of healthy prehension [\(Laffont et al., 2000,](#page-24-8) [Mateo et](#page-25-6) [al., 2013\)](#page-25-6). Nonetheless, MEG data yielded overlapping brain activations within bilateral pre-central gyrii, inferior parietal lobe and contralateral precuneus in both HCs and SCI groups. These regions are known to be part of the reaching and grasping networks [\(Jeannerod et al., 1995,](#page-24-5) [Binkofski et al., 1998,](#page-21-2) [Grafton, 2010,](#page-22-9) [Davare et al., 2011\)](#page-22-10). Particularly, the precuneus is involved in attention switches during target selection and visuo-motor processing during pointing to grasp sequences (for reviews, see [Kawashima et al., 1995,](#page-24-9) [Cavanna and Trimble, 2006\)](#page-21-8). Contralateral paracentral lobe, superior parietal lobe and pre-motor cortex activation was observed only in SCI subjects. This may reflect the recruitment of a compensatory network during TP. Interestingly, the same pattern of premotor/parietal compensation was reported during attempted movements that were impossible to perform physically in SCI participants [\(Hotz-Boendermaker et al., 2008\)](#page-24-10). Here, SCI participants also recruited cortical sites corresponding to the representation of limbs distal to the level of spinal injury within the primary motor cortex. This finding is congruent with data related to spontaneous neuroplasticity after SCI (*e.g.*, [Bruehlmeier et al., 1998,](#page-21-0) [Lotze et al., 1999a,](#page-25-0) [Mikulis et al., 2002,](#page-26-0) [Lotze](#page-25-7) [et al., 2006\)](#page-25-7). Overall, compensatory activations and recruitment of deafferented motor networks support the hypothesis of low central integration of TP motor programs. Lastly, no contralateral postcentral activation was evidenced during TP in SCI participants. Albeit SCI participants received

proprioceptive input from proximal upper limb body parts and forearm wrist extensors muscles during TP, these may have been insufficient to elicit primary somatosensory cortex activation.

SCI and HPs groups had comparable MI capacities based on psychometric and behavioral evaluations. During MI, pre-tests MEG data yielded contralateral activations only. This result contrasts with the bilateral cortical involvement observed during PP, but is in congruent with previous brain imaging reports of MI (*e.g.*, [Ehrsson et al., 2003,](#page-22-3) [Michelon et al., 2006\)](#page-26-10). Functional overlap between MI and PP was present in both groups within the contralateral hemisphere (Figure 4 and Table 1). The neural networks controlling imagined TP during the pre-tests were close to those observed during PP. This result supports intact functional equivalence in spite the complexity of the tenodesis sequence. Particularly, MI mirrored increased recruitment of the pre-motor network in SCI subjects compared to HPs. Recruitment of cortical sites controlling the lower limbs within the primary somatosensory cortex was also noted. Such pattern of activation may originate from kinesthetic information processing during MI within a reorganized somatosensory system [\(Guillot et al., 2009\)](#page-23-8). Surprisingly, SCI participants recruited the hand motor representation within the pre-central gyrus, similarly as HPs (Figure 4). The effector-specific recruitment of the primary motor cortex during imagined, but not during actual, TP was not expected. Hypothetically, the representation of prehension may be alimented and maintained by other sources of sensory input than proprioception (*e.g.*, action observation engaging motor stimulation) [\(Vogt et al., 2013\)](#page-27-11).

4.2. Post-tests data

MT and MV were higher in SCI subjects compared to HPs, which reflects the impaired performance in the case of SCI [\(Mateo et al., 2013\)](#page-25-6). MT remained unchanged after inclusion of MI training in the rehabilitation program. MI practice focused on the kinematic aspects of tenodesis (see Appendix 1), and did not involve instructions as regards movement speed. Accordingly, absence of MT change is not surprising [\(Louis et al., 2008\)](#page-25-8). During the post-test 1, MV was significantly lower in SCI participants as compared to pre-tests values, thus attesting improved performance (Figure 4). Embedding MI training within the rehabilitation program increased movement consistency. This effect

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was maintained two months after the intervention. MV no longer differed from pre-tests values [\(see](#page-22-8) [Grangeon et al., 2012 for an analogous patter of results\)](#page-22-8). Baseline and intervention periods were of equivalent duration in this design. TP improvements may thus be imputable to the adjunction of MI training in the classical hospitalization program (*i.e.*, including physiotherapy). However, the present study does not provide straightforward evidence of MI efficacy. Such hypothesis would require a randomized controlled trial. For ethical reasons, a group of SCI participants not receiving MI training program could not be included (*i.e.*, risk of unbalance between additional costs and potential benefits associated with participation in the design for SCI participants in the control group)¹.

The features of TP networks in SCI participants closely resembled those in HPs during the post- tests as compared to pre-tests. Compensatory activations were no longer present. A striking finding is that primary motor cortex recruitment switched back to the hand motor representation. Accordingly, MI may have contributed to strengthen the task-specific recruitment of upper limb motor networks. Activation of the contralateral superior parietal lobe was also noted in SCI but not in HPs. The superior parietal lobe plays a crucial role in the preparation and online control of prehension [\(Jeannerod et al.,](#page-24-5) 1995, [Grafton, 2010\)](#page-22-9). During MI, precuneus activation was no longer present in both HPs and SCI groups. This might reflect the habituation to the MI task in a repeated measures design. Indeed, [Guillot et al. \(2008\)](#page-23-9) highlighted the role of cuneus regions in the generation of motor images.

Overall, post-test MEG data provided evidence for reversed cortical neuroplasticity underlying reinforcement of TP programs. The networks were similar to those recorded in HPs performing healthy prehensions. This original result shows that TP, a *compensatory* prehension, became progressively integrated within neural networks functionally dedicated to the control of prehension.

¹ Counterbalanced interventions were also rejected due to risk of inequities during the early stages of training (*i.e.*, as a group of SCI subjects would be receiving MI practice while the other not), resulting in differential effects on motor recovery (higher gains are usually achieved during the early stages of training).

4.3. Limitations

In this MEG experiment, we primarily observed cortical activations. [Cramer et al. \(2007\)](#page-22-6) reported plastic changes at the subcortical level after MI training in SCI subjects. This study required memorization of sequences of foot and tongue movements. Here, TP was perceptually driven by the functional purpose of grasping and placing an apple to the mouth. It is therefore obvious that changes should primarily be observed within the cortical network underlying online control of TP, rather than within sub-cortical centers of motor memory. Further, MEG is primarily sensitive to post-synaptic current from apical dendrites of pyramidal neurons [\(Hari, 2005,](#page-23-10) [Lopes da Silva and van Rotterdam,](#page-25-9) [2005\)](#page-25-9). Detection of subcortical activity is usually achieved by a considerable number of trials, which we could not afford here due to fatigability of SCI participants and risk of excessive duration allocated to MEG recordings. The stringent procedure implemented for source localization, has made difficult the detection of isolated subcortical sources. We did not detect frontal cortex activity during pre- and post-tests in both groups, a structure with well-identified roles in the control of prehension (*e.g.*, [Jeannerod et al., 1995,](#page-24-5) Grol et [al., 2007\)](#page-23-11). This may be due to long SAM active state duration, which encompassed all aspects of prehension sequences with MEG. Frontal regions are primarily involved in visuo-motor processing during preparation of prehension [\(Botvinick et al., 2009,](#page-21-9) [Grafton, 2010\)](#page-22-9).

5. Conclusions

The present study investigated the neural underpinnings of TP before and after embedding MI training to the classical course of rehabilitation. Functional equivalence between MI and PP was preserved in SCI participants and reflected compensatory neuroplasticity during the pre-tests. MI training restored effector-specific patterns of activity within the primary motor and somatosensory cortices. These changes were associated with reduced movement variability suggesting increased motor efficiency.

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Conflict of interest

The authors declare no conflict of interest.

Contributors

CC, GR, CD and AG designed the experiment. All authors participated to the experimental recordings. CD, SD, SM and FDR performed the MEG analyses. FDR carried on the statistical analyses and drafted the manuscript. All authors corrected and approved the final version of the manuscript.

Figure captions

Figure 1. Experimental design including five experimental sessions (*i.e.*, 3 pre-tests and 2 post-tests).

Figure 2. Experimental settings. A: Installation of participants within the MEG seat. The onset of the 3 phases of prehension is provided. B: Optical fiber switch systems spotting hand and apple movements from their standardized start positions. C: CTF® software displaying the sudden drops in the optical fiber baseline for the hand and apple switch systems, thus spotting start and end of the prehension.

Figure 3. A: Median duration (*SD*) of prehension in SCI and HP across experimental sessions. B: Median movement variability (*SD*) in the two groups. During pre-tests 2 and post-test 1, movement variability was extremely low in HP. HP: Healthy participants, SCI: spinal cord injury.

Figure 4. Neural networks controlling actual and imagined prehension during the three preand the two post-tests, in healthy and spinal cord injury participants. The statistical threshold for detection of activations in post-test is higher than that in the pre-tests since only two masked activation maps were combined.

Table 1. Cerebral regions recruited during physical practice and motor imagery of the prehension task in pre- and post-tests, in healthy and spinal cord injury participants. Coordinates of the center of gravity is provided for each region. SCI: Spinal Cord Injury.

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