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Patrick Gérard, Sandrine Grellier. On a damped Szego equation (with an appendix in collaboration with Christian Klein). SIAM Journal on Mathematical Analysis, 2020, 52 (5), pp.4391-4420. 10.1137/19M1299189. hal-02358383

HAL Id: hal-02358383 https://hal.science/hal-02358383v1

Submitted on 21 Dec 2019

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ON A DAMPED SZEGŐ EQUATION (WITH AN APPENDIX IN COLLABORATION WITH CHRISTIAN KLEIN)

PATRICK GÉRARD AND SANDRINE GRELLIER

ABSTRACT. We investigate how damping the lowest Fourier mode modifies the dynamics of the cubic Szegő equation. We show that there is a nonempty open subset of initial data generating trajectories with high Sobolev norms tending to infinity. In addition, we give a complete picture of this phenomenon on a reduced phase space of dimension 6. An appendix is devoted to numerical simulations supporting the generalisation of this picture to more general initial data.

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1. Introduction

In the last decade, a number of papers have tried to display growth of Sobolev norms of high regularity for solutions of globally wellposed nonlinear Hamiltonian partial differential equations. This question, raised by Bourgain in [1], [2] for the defocusing nonlinear Schrödinger

Introduction

Date: November 10, 2019.

 $^{1991\} Mathematics\ Subject\ Classification.\ 35B15,\ 47B35,\ 37K15.$

Key words and phrases. Cubic Szegő equation, integrable system, damped equations, Hankel operator, spectral analysis.

The authors are grateful to T. Alazard for drawing their attention to the introduction of damping in integrable PDEs.

equation on the torus, led to several contributions constructing solutions with a small initial Sobolev norm of high regularity and a big Sobolev norm at some later time, see [4], [5], [8], [13], [16], [19], [15], [14], [12]. The actual existence of unbounded trajectories was proved in [21], [17], [18], [7], [23], [24], [3], [22], [9]. In this paper, we intend to study a case where a weak damping can promote unbounded trajectories in Sobolev spaces with high regularity. This unexpected phenomenon will be displayed in the particular case of a weak damping applied to the cubic Szegő equation. It would be interesting to investigate how weak damping can perturb other Hamiltonian dynamics in the same way.

The cubic Szegő equation was introduced in [5] as a toy model of degenerate nondispersive Hamiltonian dynamics. A natural phase space is the intersection of the Sobolev space $H^{\frac{1}{2}}(\mathbb{T})$ with the Hardy space $L^2_+(\mathbb{T})$ made of square integrable functions on the circle with only nonnegative Fourier modes. This phase space will be denoted by $H^{\frac{1}{2}}_+(\mathbb{T})$. The equation reads

$$(1.1) i\partial_t u = \Pi(|u|^2 u) ,$$

where Π is the orthogonal projector from $L^2(\mathbb{T})$ onto $L^2_+(\mathbb{T})$. An important property of equation (1.1) is the existence of a Lax pair structure, leading to action—angle variables [6]. On the other hand, the conservation laws do not control high Sobolev regularity of the solutions, allowing for long term infinitely many transitions between low and high frequencies, as proved in [7] — see also the lecture notes [9]. However, such solutions are very unstable. The goal of this paper is to investigate how these properties are changed when adding a damping term, which breaks both the Hamiltonian and the integrable structures. Such a problem for integrable systems seems very difficult. In order to make it more amenable, we choose a specific damping term which keeps part of the above structure. This leads to the following equation.

(1.2)
$$i\partial_t u + i\alpha(u|1) = \Pi(|u|^2 u) ,$$

where $\alpha > 0$ is a given parameter, which could be made equal to 1 after a scaling transformation, and (u|1) is the Fourier coefficient $\hat{u}(0)$ of u. Note that the momentum

$$M(u) := (Du|u) = \sum_{k>1} k|\hat{u}(k)|^2$$

is preserved by the flow. An easy modification of the arguments in [5] shows that (1.2) is globally wellposed on $H_+^s := L_+^2 \cap H^s$ for every $s \geq \frac{1}{2}$. Our goal is to study the behaviour of solutions of (1.2) as $t \to +\infty$, in particular the growth of Sobolev norms H^s for $s > \frac{1}{2}$. Recall from [7] that, for a dense G_δ subset of initial data in $L_+^2 \cap C_-^\infty$,

the solutions of (1.1) satisfy, for every $s > \frac{1}{2}$,

$$\limsup_{t \to +\infty} \|u(t)\|_{H^s} = +\infty , \liminf_{t \to +\infty} \|u(t)\|_{H^s} < +\infty .$$

Furthermore, this subset has an empty interior, since it does not contain any trigonometric polynomial. It turns out that the introduction of the damping term drastically modifies this asymptotic behaviour. Indeed, our main result is the following.

Theorem 1. There exists an open subset Ω of $H_+^{\frac{1}{2}}$ such that, for every $s > \frac{1}{2}$, $\Omega \cap H_+^s$ is not empty and every solution u of (1.2) with $u(0) \in \Omega \cap H_+^s$ satisfies

$$||u(t)||_{H^s} \xrightarrow[t\to+\infty]{} +\infty$$
.

In fact, we obtain an explicit sufficient condition on initial data which drives to an exploding orbit in H_+^s (see Theorem 4 below).

Theorem 1 calls for a number of natural questions.

- (1) Is the open set $\Omega \cap H_+^s$ dense in H_+^s ?
- (2) What is the rate of the growth of $||u(t)||_{H^s}$?

At this stage, we do not have a complete answer to these questions. Nevertheless, the evolution of (1.2) admits an invariant finite dimensional submanifold on which a complete description of the dynamics is available, providing a precise answer to questions (1), (2) in this particular setting. We denote by \mathcal{W} the subset of functions u on \mathbb{T} of the form

$$u(x) = b + \frac{c e^{ix}}{1 - pe^{ix}},$$

where $b, c, p \in \mathbb{C}$, $c \neq 0$, |p| < 1. Note that \mathcal{W} is a closed submanifold of dimension 6 in $H^{\frac{1}{2}}_+$. One can prove that, if u is a solution of (1.2) with $u(0) \in \mathcal{W}$, then $u(t) \in \mathcal{W}$ for every $t \in \mathbb{R}$ (see section 2 below). Given M > 0, we define the following hypersurface of \mathcal{W}

$$\mathcal{E}_M = \{ u \in \mathcal{W}; \ M(u) = M \}.$$

We also denote by \mathcal{C}_M the circle made of functions of the form

$$u(z) = cz$$
, $|c|^2 = M$,

which is a closed orbit for (1.2).

Theorem 2. For every M > 0 and every $\alpha > 0$, there exists a codimension 2 submanifold $\Sigma_{M,\alpha}$ of \mathcal{E}_M , disjoint from \mathcal{C}_M , invariant by the evolution of (1.2), such that

• If u solves (1.2) with $u(0) \in \mathcal{E}_M \setminus (\mathcal{C}_M \cup \Sigma_{M,\alpha})$, then, for every $s > \frac{1}{2}$, as $t \to +\infty$,

$$||u(t)||_{H^s} \sim c(s, \alpha, M) t^{s-\frac{1}{2}}$$

with $c(s, \alpha, M) > 0$.

• If $u(0) \in \Sigma_{M,\alpha}$, then u(t) tends to C_M at $t \to +\infty$, and $\operatorname{dist}(u(t), C_M) \simeq e^{-\lambda(\alpha, M)t}$,

with
$$\lambda(\alpha, M) > 0$$
.

Let us say a few words about the ingredients of the proofs of Theorems 1 and 2. The first important feature of the damped Szegő equation (1.2) is that the L^2 norm is a Lyapunov functional,

$$\frac{d}{dt}||u(t)||_{L^2}^2 + 2\alpha|(u(t)|1)|^2 = 0.$$

Using LaSalle's invariance principle associated to this identity, one infers that limit points of u(t) as $t \to +\infty$ in the weak $H^{\frac{1}{2}}$ topology are initial data of solutions v of (1.1) satisfying (v(t)|1) = 0 for every $t \in \mathbb{R}$.

The second important argument relies on the Lax pair structure for the Szegő equation (1.1), which is given by

$$\frac{dH_u}{dt} = [B_u, H_u] , \frac{dK_u}{dt} = [C_u, K_u] ,$$

where H_u , K_u are Hankel operators associated to u, and B_u , C_u are antiselfadjoint operators. It turns out that, though the identity for H_u does not hold anymore for solutions of the damped Szegő equation (1.2), identity for K_u remains valid for (1.2). As a consequence, the spectrum of the positive trace class operator K_u^2 is conserved by the dynamics of (1.2).

The connection between the two above arguments is made thanks to a characterization of initial data of solutions v of (1.1) satisfying (v(t)|1) = 0 for every $t \in \mathbb{R}$, in terms of the spectral theory of H_v and K_v . If u is a solution whose H^s norm does not tend to $+\infty$, this allows to calculate the limit of the L^2 norm of u(t) in terms of the spectrum of K_u^2 , leading to Theorem 1.

As for Theorem 2, the Lax pair identity for K_u implies that the dynamics of (1.2) preserves functions u such that operator K_u has a given finite rank. Manifold \mathcal{W} precisely corresponds to operators K_u of rank 1. A careful study of the ODE system defined by (1.2) on \mathcal{W} then leads to Theorem 2.

This paper is organised as follows. Section 2 is devoted to recalling important facts about the Szegő equation and Hankel operators, and to establishing general properties of solutions of the damped Szegő equation. Theorem 1 is proved in Section 3, and Theorem 2 is proved in Section 4.

Let us mention that some introductory material to the Szegő equation can be found in [9], and in [10], where the results of this paper were announced.

2. Generalities on the damped and undamped Szegő equations

In the following, we denote by $t \mapsto S(t)u_0$ (respectively by $t \mapsto S_{\alpha}(t)u_0$) the solution of the Szegő equation (1.1) (respectively of the damped Szegő equation (1.2)) with initial datum u_0 .

2.1. **The Lyapunov functional.** As emphasized in the introduction, an important tool in the study of the damped Szegő equation (1.2) is the existence of a Lyapunov functional. Precisely, the following lemma holds.

Lemma 1. Let $u_0 \in H^{1/2}_+(\mathbb{T})$. Then, for any $t \in \mathbb{R}$,

(2.1)
$$\frac{d}{dt} ||S_{\alpha}(t)u_0||_{L^2}^2 + 2\alpha |(S_{\alpha}u_0(t)|1)|^2 = 0.$$

As a consequence, $t \mapsto ||S_{\alpha}(t)u_0||_{L^2}$ is decreasing, and $|(S_{\alpha}(t)u_0|1)|$ is square integrable on $[0, +\infty)$, tending to zero as t goes to $+\infty$.

Proof. Denote by $u(t) := S_{\alpha}(t)u_0$ the solution of (1.2) with $u(0) = u_0$. Observe first that $t \mapsto ||u(t)||_{L^2}$ decreases:

$$\frac{d}{dt} ||u(t)||_{L^{2}}^{2} = 2\operatorname{Re}(\partial_{t}u|u) = 2\operatorname{Im}(i\partial_{t}u|u)
= 2\operatorname{Im}(\Pi(|u|^{2}u)|u) - 2\alpha\operatorname{Im}(i((u|1)|u))
= -2\alpha|(u(t)|1)|^{2}$$

Hence, $t \mapsto ||u(t)||_{L^2}^2$ admits a limit at infinity and since

$$||u(t)||_{L^2}^2 = ||u_0||_{L^2}^2 - 2\alpha \int_0^t |(u(s)|1)|^2 ds$$

we deduce the finiteness of

$$\int_{0}^{\infty} |(u(s)|1)|^2 ds.$$

On the other hand, we claim that

$$\frac{d}{dt}|(u(t)|1)|^2$$

is bounded. Indeed

$$\frac{d}{dt}|(u(t)|1)|^2 = 2\operatorname{Re}((\partial_t u|1)(1|u))
= 2\operatorname{Im}(-i\alpha(u|1)(1|u)) + 2\operatorname{Im}((\Pi(|u|^2u|1)(1|u)))
= -2\alpha|(u|1)|^2 + 2\operatorname{Im}((u^2|u)(1|u)).$$

but

$$|(u(t)|1)| \le ||u||_{L^2}$$

and

$$|(u^{2}(t)|u(t))| \leq ||u||_{L^{2}} \times ||u||_{L^{4}}^{2} \leq ||u||_{L^{2}} \times ||u||_{H^{1/2}}^{2} \leq ||u_{0}||_{L^{2}} (M + ||u_{0}||_{L^{2}}^{2}).$$

From both observations, we conclude that |(u(t)|1)| tends to zero as t goes to infinity. \Box

From Lemma 1 and the conservation of the momentum, the $H^{1/2}$ norm of $S_{\alpha}(t)u_0$ remains bounded as $t \to +\infty$, hence one can consider limit points u_{∞} of $S_{\alpha}(t)u_0$ for the weak topology of $H^{1/2}$ as $t \to +\infty$. Another general lemma describes more precisely these limit points, according to LaSalle's invariance principle.

Proposition 1. Let $u_0 \in H^{1/2}(\mathbb{T})$. Any $H^{1/2}$ - weak limit point u_{∞} of $(S_{\alpha}(t)u_0)$ as $t \to +\infty$ satisfies $(S_{\alpha}(t)u_{\infty}|1) = 0$ for all t. In particular, $S_{\alpha}(t)u_{\infty}$ solves the cubic Szegő equation – in other words $S_{\alpha}(t)u_{\infty} = S(t)u_{\infty}$.

Proof. Denote by Q the limit of the decreasing non-negative function $t \mapsto \|S_{\alpha}(t)u_0\|_{L^2}^2$. By the weak continuity of the flow in $H^{1/2}_+(\mathbb{T})$,

$$u(t+t_n) = S_{\alpha}(t)u(t_n) \to S_{\alpha}(t)u_{\infty}$$

weakly in $H^{1/2}$ as $n \to \infty$. Hence, thanks to the Rellich theorem,

$$||u(t+t_n)||_{L^2}^2 \to ||S_{\alpha}(t)u_{\infty}||_{L^2}^2$$

as n tends to infinity. On the other hand, by Lemma 1,

$$||u(t+t_n)||_{L^2}^2 \to Q$$

so eventually, for every $t \in \mathbb{R}$,

$$||S_{\alpha}(t)u_{\infty}||_{L^{2}}^{2} = ||u_{\infty}||_{L^{2}}^{2},$$

or

$$\frac{d}{dt} \|S_{\alpha}(t)u_{\infty}\|_{L^2}^2 = 0.$$

Recall that, from (2.1),

$$\frac{d}{dt} \|S_{\alpha}(t)u_{\infty}\|_{L^{2}}^{2} = -2\alpha |(S_{\alpha}(t)u_{\infty}|1)|^{2}.$$

It forces $(S_{\alpha}(t)u_{\infty}|1) = 0$ for all t. Hence $S_{\alpha}(t)u_{\infty} = S(t)u_{\infty}$ is a solution to the Szegő equation without damping.

In order to characterize u_{∞} , we need to recall some results about the cubic Szegő equation.

2.2. Hankel operators and the Lax pair structure. In this paragraph, we recall some basic facts about Hankel operators and the special structure of the cubic Szegő equation (1.1). We keep the notation of [7] and we refer to it for details. For $u \in H^{\frac{1}{2}}_+$, we denote by H_u the Hankel operator of symbol u namely

$$H_u: \left\{ \begin{array}{ccc} L_+^2(\mathbb{T}) & \to & L_+^2(\mathbb{T}) \\ f & \mapsto & \Pi(u\overline{f}) \end{array} \right.$$

It is well known that, for u in $H_{+}^{\frac{1}{2}}$, H_{u} is Hilbert-Schmidt with

$$Tr(H_u^2) = \sum_{k>0} (k+1)|\hat{u}(k)|^2 = ||u||_{L^2}^2 + M(u).$$

One can also consider the shifted Hankel operator K_u corresponding to H_{S^*u} where S^* denotes the adjoint of the shift operator $Sf(x) := e^{ix} f(x)$. This shifted Hankel operator is Hilbert-Schmidt as well, with

$$\operatorname{Tr}(K_u^2) = \sum_{k>0} k |\hat{u}(k)|^2 = M(u)$$

Observe in particular that $||u||_{L^2}^2 = \text{Tr}(H_u^2) - \text{Tr}(K_u^2)$.

A crucial property of the cubic Szegő equation is its Lax pair structure. Namely, if u is a smooth enough solution to (1.1), then there exists two antiselfadjoint operators B_u , C_u such that

(2.2)
$$\frac{d}{dt}H_u = [B_u, H_u], \quad \frac{d}{dt}K_u = [C_u, K_u].$$

Classically, these equalities imply that $H_{u(t)}$ and $K_{u(t)}$ are isometrically equivalent to $H_{u(0)}$ and $K_{u(0)}$ (see [7] for instance). In particular, both spectra of H_u and K_u are preserved by the cubic Szegő flow. It motivated the study of the spectral properties of both Hankel operators that we recall here.

For $u \in H^{\frac{1}{2}}_+$, let $(s_j^2)_{j\geq 1}$ be the strictly decreasing sequence of positive eigenvalues of H^2_u and K^2_u . Following the terminology of [7], σ^2 is an H-dominant eigenvalue (respectively K-dominant eigenvalue) if σ^2 is an eigenvalue of H^2_u (respectively of K^2_u) with $u \not\perp \ker(H^2_u - \sigma^2 I)$ (respectively with $u \not\perp \ker(K^2_u - \sigma^2 I)$). From the min-max formula and the fact that $K^2_u = H^2_u - (\cdot|u)u$, it is possible to prove that the s^2_{2j-1} correspond to H-dominant eigenvalues of H^2_u while the s^2_{2j} correspond to K-dominant eigenvalues of K^2_u . Furthermore, the eigenvalues of H^2_u and of K^2_u interlace and, as a consequence, if $m_j := \dim \ker(H^2_u - s^2_j I)$ and $\tilde{m}_j := \dim \ker(K^2_u - s^2_j I)$, then

$$m_{2j-1} = \tilde{m}_{2j-1} + 1$$
 as $\tilde{m}_{2j} = m_{2j} + 1$.

To complete the spectral analysis of these Hankel operators, we need

to recall the notion of Blaschke product. A function b is a Blaschke product of degree m if

$$b(x) = e^{i\varphi} \prod_{j=1}^{m} \frac{e^{ix} - p_j}{1 - \overline{p_j}e^{ix}}$$

for some $p_j \in \mathbb{C}$ with $|p_j| < 1$, j = 1 to m. As proved in [7] — see also [11] for a generalisation to non compact Hankel operators—, for any H-dominant eigenvalue s_{2j-1}^2 , there exists a Blaschke product Ψ_{2j-1} of degree $m_{2j-1} - 1$ such that, if u_j denotes the orthogonal projection of u on the eigenspace $\ker(H_u^2 - s_{2j-1}^2 I)$, then

$$\Psi_{2j-1}H_u(u_j) = s_{2j-1}u_j.$$

Analogously, for any K-dominant eigenvalue s_{2k}^2 , there exists a Blaschke product Ψ_{2k} of degree \tilde{m}_{2k} such that, if \tilde{u}_k denotes the orthogonal projection of u on $\ker(K_u^2 - s_{2k}^2 I)$ then

$$K_u(\tilde{u}_k) = \Psi_{2k} s_{2k} \tilde{u}_k.$$

We proved in [7] that the sequence $((s_j^2), (\Psi_j))$ characterizes u, and that it provides a system of action-angle variables for the Hamiltonian evolution (1.1). Namely, if u(0) has spectral coordinates $((s_j^2), (\Psi_j))$ then u(t) has spectral coordinates

$$((s_j^2), (e^{i(-1)^j s_j^2 t} \Psi_j)).$$

We are now in position to characterize the asymptotics of the damped Szegő equation. We first remark that the equation inherits one Lax pair, the one related to the shifted Hankel operator K_u . It comes easily from the fact the shifted Hankel operator associated to a constant symbol is identically 0 and so, if $u(t) := S_{\alpha}(t)u_0$, then

(2.3)
$$\frac{d}{dt}K_u = K_{-i\Pi(|u|^2u)} + \alpha K_{(u|1)} = [C_u, K_u]$$

where C_u is the antiselfadjoint operator given by (2.2). As a usual consequence, $K_{S_{\alpha}(t)u_0}$ is unitarily equivalent to K_{u_0} and for instance, the class of symbol u with K_u of fixed finite rank is preserved by the damped Szegő flow. In particular

(2.4)
$$\mathcal{W} := \left\{ u(x) = b + \frac{c e^{ix}}{1 - p e^{ix}}, \ b, c, p \in \mathbb{C}, c \neq 0, \ |p| < 1 \right\}$$

is invariant by the flow since it corresponds to the set of symbol whose shifted Hankel operators are of rank 1.

Another consequence is the following result.

Theorem 3. The solutions $u = u(t, \cdot)$ of the cubic Szegő equation satifying (u(t)|1) = 0 for all t are characterized by the property $(\Psi_{2j-1}|1) = 0$, for all the Blaschke products Ψ_{2j-1} 's corresponding to the H-dominant eigenvalues s_{2j-1}^2 of H_u^2 . In particular, the H-dominant eigenvalues are

at least of multiplicity 2 and hence, are eigenvalues of K_u^2 . Furthermore, if $\{\sigma_k^2\}_k$ denotes the strictly decreasing sequence of the eigenvalues of K_u^2 , one has

$$||u(t)||_{L^2}^2 = \sum_k (-1)^{k-1} \sigma_k^2.$$

Proof. Let us write $u = \sum u_j$ where u_j is the orthogonal projection of u onto the eigenspace $E_u(s_{2j-1}) := \ker(H_u^2 - s_{2j-1}^2 I)$ associated to the H-dominant eigenvalue s_{2j-1}^2 . By the spectral analysis of the Hankel operator recalled above, there exists a Blaschke product Ψ_{2j-1} of degree m-1 where m is the dimension of $E_u(s_{2j-1})$ with $s_{2j-1}u_j = \Psi_{2j-1}H_u(u_j)$. The evolution of the Blaschke product is given by

$$\Psi_{2j-1}(t) = e^{-is_{2j-1}^2 t} \Psi_{2j-1}(0).$$

Computing (u(t)|1), we get, for all $t \in \mathbb{R}$,

$$0 = (u(t)|1) = \sum_{j} (u_j(t)|1) = \sum_{j} \frac{e^{-is_{2j-1}^2 t}}{s_{2j-1}} (\Psi_{2j-1}(0)|1) ||u_j||_{L^2}^2.$$

It implies that $(\Psi_{2j-1}(0)|1) = 0$ so that the degree of Ψ_{2j-1} is at least 1 and hence, the multiplicity of s_{2j-1}^2 is at least 2. From the interlacement property, this eigenvalue is also an eigenvalue for K_u^2 . Let $\{\sigma_k^2\}_k$ denote the strictly decreasing sequence of the eigenvalues of K_u^2 . We denote by m_k the multiplicity of σ_k^2 as an eigenvalue of H_u^2 and by \tilde{m}_k its multiplicity as a eigenvalue of K_u^2 . From the interlacement property, if k is odd, $m_k = \tilde{m}_k + 1$ and if k is even, $m_k = \tilde{m}_k - 1$. We now compute the L^2 norm of u(t):

$$||u(t)||_{L^2}^2 = \text{Tr}H_u^2 - \text{Tr}K_u^2 = \sum m_k \sigma_k^2 - \sum \tilde{m}_k \sigma_k^2 = \sum_k (-1)^{k-1} \sigma_k^2.$$

3. Exploding trajectories

In this section, we consider trajectories of (1.2) in H^s , $s > \frac{1}{2}$, along which the H^s norm of u(t) tends to infinity as $t \to +\infty$. Let us define the functional

$$F(u) = \sum_{k} (-1)^{k-1} \sigma_k^2$$

where $(\sigma_k^2)_k$ is the strictly decreasing sequence of positive eigenvalues of K_u^2 . We prove the following result.

Theorem 4. Let $s > \frac{1}{2}$. If $u_0 \in H^s_+$ satisfies

- either $||u_0||_{L^2}^2 < F(u_0)$,
- or $||u_0||_{L^2}^2 = F(u_0)$ and $(u_0|1) \neq 0$,

then the H^s -norm of the solution of the damped Szegő equation

$$||u(t)||_{H^s} = ||S_{\alpha}(t)u_0||_{H^s}$$

tends to $+\infty$ as t tends to $+\infty$.

Proof. Let us proceed by contradiction and assume that there exists a sequence $t_n \to +\infty$ such that $u(t_n) := S_{\alpha}(t_n)u_0$ is bounded in H^s . We may assume that $u(t_n)$ is weakly convergent to some u_{∞} in H^s_+ . By the Rellich theorem, the convergence is strong in $H^{\frac{1}{2}}_+$, and

(3.1)
$$M(u_{\infty}) = M(u_0) = \sum_{\sigma^2 \in \Sigma(u_0)} m(\sigma)\sigma^2 ,$$

where $\Sigma(u_0)$ denotes the set of eigenvalues of $K_{u_0}^2$ and $m(\sigma)$ the multiplicity of $\sigma^2 \in \Sigma(u_0)$. By the Lax pair structure, the eigenvalues of $K_{u(t_n)}^2$ are the same as the eigenvalues of $K_{u_0}^2$, with the same multiplicities, hence every eigenvalue σ^2 of $K_{u_\infty}^2$ must belong to $\Sigma(u_0)$, with a multiplicity not bigger than $m(\sigma)$. In view of identity (3.1), we infer that

$$\Sigma(u_{\infty}) = \Sigma(u_0) ,$$

with the same multiplicities. On the other hand, from Proposition 1, we know that u_{∞} generates a solution of the cubic Szegő equation which is orthogonal to 1 at every time. Consequently, Theorem 3 gives

$$||u_{\infty}||_{L^2}^2 = F(u_0)$$
.

Since the L^2 -norm of the solution is decreasing by Lemma 1, $||u_0||_{L^2}^2 \ge ||u_\infty||_{L^2}^2$. Hence, $||u_0||_{L^2}^2 \ge F(u_0)$. If $||u_0||_{L^2}^2 = F(u_0)$ then $||S_\alpha(t)u_0||_{L^2}$ remains constant and necessarily, by the Lyapunov functional identity (2.1), $(S_\alpha(t)u_0|1) = 0$ so that in particular, $(u_0|1) = 0$. Hence, the case $||u_0||_{L^2}^2 = F(u_0)$ and $(u_0|1) \ne 0$ drives to an exploding orbit in H^s as well as the case $||u_0||_{L^2}^2 < F(u_0)$. It ends the proof of Theorem 4.

3.1. The case of Blaschke products. As a particular case of initial datum satisfying $||u_0||_{L^2}^2 = F(u_0)$ and $(u_0|1) \neq 0$, we consider initial datum given by a Blaschke product.

Corollary 1. Let Ψ be a Blaschke product with $(\Psi|1) \neq 0$ then $||S_{\alpha}(t)\Psi||_{H^s}$ tends to $+\infty$ with t for any $s > \frac{1}{2}$.

Proof. Observe that, as Ψ is inner, $H^2_{\Psi}(\Psi) = H_{\Psi}(1) = \Psi$ so that 1 is an eigenvalue of H^2_{Ψ} with eigenvector Ψ . From the spectral analysis done in [7], and in particular from Lemma 3.5.2, one obtains the explicit description of the eigenspace corresponding to 1. If Ψ is of degree N, this eigenspace is of dimension N+1 hence 1 is H-dominant, of multiplicity N+1 and the representation of Ψ through the non-linear Fourier transform is Ψ itself. In particular, the rank of H_{Ψ} is N+1. On the other hand, from the interlacing property, 1 is a singular value of K_{Ψ} of multiplicity N and the rank of K_{Ψ} is N. Hence K_{Ψ} has only

1 as possible non zero singular value and $F(\Psi) = 1$. As $\|\Psi\|_{L^2} = 1$ we get the norm explosion as a corollary of Theorem 4.

3.2. **An open condition.** As a second corollary of Theorem 4, we get the following result, which implies Theorem 1.

Corollary 2. Denote by Ω the interior in $H^{\frac{1}{2}}_+$ of the set of $u_0 \in H^{\frac{1}{2}}_+$ such that $||u_0||^2_{L^2} < F(u_0)$. For every $s > \frac{1}{2}$, $\Omega \cap H^s_+$ of $H^s_+(\mathbb{T})$ is not empty, and every solution u of with $u(0) \in \Omega \cap H^s_+$ satisfies

$$||u(t)||_{H^s} \to \infty$$

as t tends to $+\infty$.

Proof. By elementary perturbation theory, it is easy to prove that function F is continuous at those u of $H^{1/2}_+(\mathbb{T})$ such that K^2_u has simple non zero spectrum. Furthermore, in the particular case

$$u(x) = \frac{e^{ix}}{1 - pe^{ix}}, \ p \in \mathbb{D}, \ p \neq 0,$$

it is easy to check that K_u^2 has rank one with $\frac{1}{(1-|p|^2)^2}$ as simple eigenvalue. As $\|u\|_{L^2}^2 = \frac{1}{1-|p|^2}$, this function belongs to Ω , and moreover it belongs to every H^s . In view of Theorem 4, this completes the proof.

We end this section by giving a simple example of functions in Ω :

Example 1. The set of functions u_0 whose nonzero eigenvalues of $H^2_{u_0}$ and $K^2_{u_0}$ are all simple, and form the decreasing square summable list

$$\rho_1 > \sigma_1 > \rho_2 > \sigma_2 > \dots$$

with

$$\sum_{j} \rho_j^2 < 2 \sum_{k \text{ odd}} \sigma_k^2$$

is a subset of Ω .

4. A SPECIAL CASE

In this section, we restrict ourselves to the set

$$W := \left\{ u(x) = b + \frac{c e^{ix}}{1 - pe^{ix}}, \ b, c, p \in \mathbb{C}, c \neq 0, \ |p| < 1 \right\}$$

introduced in (2.4). As recalled in section 2.2, W corresponds to rational functions u with shifted Hankel operator K_u of rank 1 and hence it is preserved by the damped Szegő flow. It is straightforward to check that the system on variables b, c, p reads

(4.1)
$$\begin{cases} i(\dot{b} + \alpha b) &= (|b|^2 + 2M(1 - |p|^2))b + Mc\overline{p} \\ i\dot{c} &= (2|b|^2 + M)c + 2M(1 - |p|^2)bp \\ i\dot{p} &= M(1 - |p|^2)p + c\overline{b} \end{cases}$$

In this section, we provide a panorama of the dynamics of the damped Szegő equation on \mathcal{W} .

In particular, we prove that the set of functions u_0 such that, for some t, condition

$$||S_{\alpha}(t)u_0||_{L^2}^2 < F(u_0).$$

is satisfied, is a dense open subset of \mathcal{W} on which the growth of the H^s norm of $S_{\alpha}(t)u_0$ as t tends to $+\infty$ is of order $t^{s-\frac{1}{2}}$. Moreover we indicate the structure of the complement of this set. Let us observe that when $u_0 \in \mathcal{W}$, $F(u_0) = M(u_0)$ so that condition (4.2) reads $||S_{\alpha}(t)u_0||_{L^2}^2 < M(u_0)$.

Let us recall the statement given in the introduction in a more precise form.

Given M>0, we define the following five dimensional hypersurface of \mathcal{W}

$$\mathcal{E}_M = \{ u \in \mathcal{W}; \ M(u) = M \}.$$

We also denote by \mathcal{C}_M the circle made of functions of the form

$$u(x) = c e^{ix}, |c|^2 = M$$

which are invariant by the damped Szegő flow (1.2) as a periodic orbit. In the next statement, we normalise the H^s norm as follows.

(4.3)
$$||u||_{H^s}^2 = \sum_{k=0}^{\infty} (1+k^2)^s |\hat{u}(k)|^2 .$$

Theorem 5. For every M > 0 and every $\alpha > 0$, there exists a codimension 2 submanifold $\Sigma_{M,\alpha}$ of \mathcal{E}_M , disjoint from \mathcal{C}_M , invariant by the action of $S_{\alpha}(t)$, such that $\Sigma_{M,\alpha} \cup \mathcal{C}_M$ is closed and

• If $u_0 \in \mathcal{E}_M \setminus (\mathcal{C}_M \cup \Sigma_{M,\alpha})$, then, for every $s > \frac{1}{2}$, as $t \to +\infty$, $||S_{\alpha}(t)u_0||_{H^s}^2 \sim c^2(s,\alpha,M) t^{2s-1}$

with

$$c^{2}(s,\alpha,M) := \Gamma(2s+1)M^{4s-1} \left(\frac{\alpha^{2}+M^{2}}{2\alpha}\right)^{1-2s} > 0.$$

• If $u_0 \in \Sigma_{M,\alpha}$, then $S_{\alpha}(t)u_0$ tends to \mathcal{C}_M as $t \to +\infty$, and $\operatorname{dist}(S_{\alpha}(t)u_0, \mathcal{C}_M) \simeq e^{-\lambda(\alpha, M)t} ,$ with $\lambda(\alpha, M) > 0$.

Before giving the proof of this result, let us make some basic observations. We write

$$u(t) := S_{\alpha}(t)u_0 = b(t) + \frac{c(t) e^{ix}}{1 - p(t) e^{ix}},$$

 $b, c, p \in \mathbb{C}$. Since the momentum is a conservation law,

$$M(u) = \frac{|c|^2}{(1 - |p|^2)^2}$$

remains a constant, denoted by M. Denoting by Q the limit as t goes to infinity of $||u(t)||_{L^2}^2 = |b|^2 + \frac{|c|^2}{(1-|p|^2)} = |b|^2 + M(1-|p|^2)$, we get that $M(1-|p|^2)$ tends to Q (from Lemma 1, $|b| \to 0$). In particular, $|p(t)|^2$ admits a limit in [0,1] as t tends to infinity.

We claim that the following alternative holds:

• either $\lim_{t\to+\infty} |p(t)|^2 = 1$, Q = 0 and

$$||u(t)||_{H^s}^2 \sim \Gamma(2s+1) \frac{|c|^2}{(1-|p|^2)^{2s+1}} = \frac{\Gamma(2s+1) M}{(1-|p|^2)^{2s-1}} \to \infty$$

for any s > 1/2.

• or $\lim_{t\to+\infty} |p(t)|^2 < 1$ and we claim that

$$\lim_{t \to \infty} |p(t)|^2 = 0.$$

Indeed, let us consider the latter case. As $\lim_{t\to +\infty} |p(t)|^2 < 1$, the set $\{u(t), t \geq 0\}$ is relatively compact in any $H^s(\mathbb{T})$. Denote by u_∞ any $H^{1/2}$ limit of $(S_\alpha(t)u_0)$. As \mathcal{W} is closed in $H^{1/2}_+$, u_∞ belongs to \mathcal{W} . From Proposition 1, $S_\alpha(t)u_\infty$ solves the cubic Szegő equation and so equals $S(t)u_\infty$. As $S(t)u_\infty \in \mathcal{W}$ and $(S(t)u_\infty|1) = 0$ for all t, $S(t)u_\infty$ is necessarily of the form $x \mapsto \frac{c_\infty(t)e^{ix}}{1-p_\infty(t)e^{ix}}$. From the equation satisfied by b in system (4.1),

$$i(\dot{b} + \alpha b) = (|b|^2 + 2M(1 - |p|^2))b + Mc\overline{p},$$

since $b_{\infty}(t) = 0$, we obtain $p_{\infty}(t) = 0$.

Hence, $\lim_{t\to+\infty} |p(t)|^2 = 0$, and

$$\lim_{t \to +\infty} ||u(t)||_{L^2}^2 = Q = M(1 - \lim_{t \to +\infty} |p(t)|^2) = M,$$

in particular $||u_0||_{L^2}^2 \ge M$.

Eventually, we get the following alternative.

Proposition 2. If u is a solution of (1.2) on W, either u(t) is bounded in any H^s , s > 1/2, as $t \to +\infty$, and $||u_0||_{L^2}^2 \ge M$, or the trajectory is exploding in the sense that $||u(t)||_{H^s}$ tends to infinity for any $s > \frac{1}{2}$.

So we can rephrase the statement of Theorem 5 in view of these observations. Theorem 5 claims that those data of momentum M for which $p(t) \to 0$ as $t \to +\infty$ form the disjoint union of the circle \mathcal{C}_M and of a three dimensional submanifold $\Sigma_{M,\alpha}$, which is a union of trajectories converging exponentially to \mathcal{C}_M as $t \to +\infty$. Furthermore, outside of this set, $1 - |p(t)|^2 \to 0$ as $t \to +\infty$, with a universal rate

$$(1 - |p(t)|^2) \sim \frac{\rho(\alpha, M)}{t},$$

where $\rho(\alpha, M) = \frac{\alpha^2 + M^2}{2\alpha M^2} > 0$.

We split the proof of Theorem 5 into two parts. The first one is a careful analysis of the case $|p(t)| \to 1$ through the differential equations corresponding to (1.2) on some reduced variables. The second part consists in reducing the system to a scattering problem.

4.1. The growth of Sobolev norms. In this section, we consider a solution of (1.2)

$$u(t,x) = b(t) + \frac{c(t) e^{ix}}{1 - p(t) e^{ix}}$$

such that $|p(t)|^2 \to 1$ as $t \to +\infty$, of momentum

$$M = \frac{|c(t)|^2}{(1 - |p(t)|^2)^2} .$$

In order to avoid the gauge and translation invariances, we appeal to the following reduced variables,

$$\beta := |b|^2$$
, $\gamma := M(1 - |p|^2)$, $\zeta := Mc\overline{b}\overline{p}$,

which, from system (4.1), satisfy the following reduced system,

(4.4)
$$\begin{cases} \dot{\beta} + 2\alpha\beta &= 2\mathrm{Im}\zeta \\ \dot{\gamma} &= -2\mathrm{Im}\zeta \\ \dot{\zeta} + (\alpha + iM)\zeta &= (3i\gamma - i\beta)\zeta - 2i\beta\gamma M \\ + i\gamma^2(M - \gamma + 3\beta) \end{cases}$$

Notice that

$$|\zeta|^2 = (M - \gamma)\gamma^2\beta$$
, $\beta \ge 0$, $M \ge \gamma > 0$.

From Lemma 1, we already know that $\beta(t) \to 0$ as $t \to +\infty$ and that

$$\int_{0}^{\infty} \beta(t) dt < +\infty .$$

Our task is to prove, under the additional assumption $\gamma(t) \to 0$ as $t \to +\infty$, that

$$\gamma(t) \sim \frac{\kappa}{t}$$

with $\kappa = \kappa(\alpha, M) > 0$.

As a first step, let us establish that

$$\int_{0}^{\infty} \gamma(t)^2 dt < +\infty .$$

We write the equation on ζ in system (4.4) as

(4.5)
$$\frac{\dot{\zeta}}{\alpha + iM} + \zeta = f + r \;,$$

where

$$f := i \frac{\gamma^2}{\alpha + iM} \left(M - \gamma + 3 \frac{\zeta}{\gamma} \right) ,$$

$$r := -i \frac{\beta}{\alpha + iM} \left(\zeta + 2\gamma M - 3\gamma^2 \right) .$$

Notice that $r \in L^1(\mathbb{R}_+)$ and that, as $t \to +\infty$,

$$\operatorname{Im} f(t) \sim \frac{\alpha M}{\alpha^2 + M^2} \gamma(t)^2 > 0$$
.

Integrating from 0 to T the imaginary part of both sides of (4.5), we obtain, using $\dot{\gamma} = -2\text{Im}\zeta$,

$$\int_{0}^{T} \operatorname{Im} f(t) \, dt = O(1)$$

as $T \to +\infty$. This provides

$$\int_{0}^{\infty} \gamma(t)^2 dt < +\infty .$$

The second step consists in coming back to (4.5) and integrating the imaginary part of both sides from t to $+\infty$. Using $|\zeta| = O(\gamma\sqrt{\beta})$ and $r = O(\beta\gamma)$, we infer

$$\gamma(t)(1+o(1)) = \frac{2\alpha M}{\alpha^2 + M^2} \left(\int_t^\infty \gamma(s)^2 ds \right) (1+o(1)) + O\left(\int_t^\infty \beta(s)\gamma(s) ds \right) .$$

Using again that $\beta \in L^1(\mathbb{R}_+)$, this yields

(4.6)
$$\gamma(t) = \frac{1}{\kappa} \left(\int_{t}^{\infty} \gamma(s)^{2} ds \right) (1 + o(1)) + o\left(\sup_{s \ge t} \gamma(s) \right) ,$$

with

(4.7)
$$\kappa := \frac{\alpha^2 + M^2}{2\alpha M} .$$

Using the monotonicity of

(4.8)
$$\Gamma(t) := \int_{1}^{\infty} \gamma(s)^{2} ds ,$$

equation (4.6) leads to

$$\sup_{s \ge t} \gamma(s) = \frac{1}{\kappa} \left(\int_{t}^{\infty} \gamma(s)^{2} ds \right) (1 + o(1)) ,$$

and, coming back to (4.6), we finally obtain

(4.9)
$$\gamma(t) = \frac{1}{\kappa} \left(\int_{t}^{\infty} \gamma(s)^{2} ds \right) (1 + o(1)).$$

This equation can be written as an ODE in function Γ introduced above in (4.8),

$$\dot{\Gamma} + \frac{1}{\kappa^2} \Gamma^2 (1 + o(1)) = 0$$
,

which can be solved as

$$\Gamma(t) = \frac{\kappa^2}{t} (1 + o(1))$$

and, coming back to (4.9),

$$\gamma(t) = \frac{\kappa}{t}(1 + o(1)).$$

Eventually, one gets

$$||u(t)||_{H^s}^2 \sim \frac{\Gamma(2s+1) M}{(1-|p(t)|^2)^{2s-1}} = \Gamma(2s+1) M^{2s} \gamma(t)^{1-2s}$$
$$\sim \Gamma(2s+1) M^{2s} \kappa^{1-2s} t^{2s-1}$$

which, in view of the expression (4.7) of κ , is the expected result.

4.2. The stable manifold of the periodic orbit. We come to the second part of the theorem, characterising the trajectories of (1.2) in W which converge to C_M as $t \to +\infty$. Since C_M is a trajectory itself, we may focus on trajectories $\{u(t)\}$ of momentum M which are disjoint of C_M , and which satisfy

$$\forall t \ge 0 \ , \ \|u(t)\|_{L^2}^2 \ge M.$$

At this stage we are not sure that such trajectories exist. However we are going to establish a necessary condition on the asymptotic behaviour of (b(t), c(t), p(t)) as $t \to +\infty$.

As a first step, we will use a linearisation procedure that we now illustrate on a "baby example".

Proposition 3. Let $u_0^{\varepsilon}(x) = e^{ix} + \varepsilon$ with $\varepsilon \in \mathbb{R}$. For $|\varepsilon|$ small enough and $\varepsilon \neq 0$, the trajectory $S_{\alpha}(t)u_0^{\varepsilon}$ is exploding.

Proof. First observe that $\|u_0^{\varepsilon}\|_{L^2}^2 = 1 + \varepsilon^2$ and $F(u_0^{\varepsilon}) = M(u_0^{\varepsilon}) = 1$. We are going to prove that, for some T > 0, for ε small enough, $\|S_{\alpha}(T)u_0^{\varepsilon}\|_{L^2}^2 \leq 1 - \varepsilon^2$, so that Proposition 3 will follow from Theorem 4.

Let us prove the claim. We linearize the flow $S_{\alpha}(t)$ around the solution $e^{i(x-t)}$ for $\varepsilon = 0$ by writing

$$S_{\alpha}(t)u_0^{\varepsilon} = e^{-it}(e^{ix} + \varepsilon v + \varepsilon^2 w^{\varepsilon})$$

where v satisfies

$$i(\partial_t v + \alpha(v|1)) = v + \Pi(e^{2ix}\overline{v}), \quad v(0, e^{ix}) = 1$$

and, for every T > 0, for every s, there exists $C_{s,T}$ such that

$$\forall t \in [0, T], \ \|w^{\varepsilon}(t)\|_{H^s} \le C_{s, T}.$$

From the Lyapunov functional (2.1), for any $t \in [0, T]$,

$$||S_{\alpha}(t)u_{0}^{\varepsilon}||_{L^{2}}^{2} = ||u_{0}^{\varepsilon}||_{L^{2}}^{2} - 2\alpha \int_{0}^{t} |(S_{\alpha}(s)u_{0}^{\varepsilon}|1)|^{2} ds$$
$$= 1 + \varepsilon^{2} - 2\alpha \varepsilon^{2} \int_{0}^{t} (|(v(s)|1)|^{2} + \mathcal{O}_{T}(\varepsilon)) ds.$$

Let us write

$$v(t,x) = q_0(t) + q_2(t)e^{i2x}$$

with

$$i(\dot{q}_0 + \alpha q_0) = q_0 + \overline{q}_2 ,$$

 $i\dot{q}_2 = q_2 + \overline{q}_0 ,$
 $q_0(0) = 1 , q_2(0) = 0 .$

Let us focus on $q_0 = (v|1)$. Deriving the first equation, we are left with the following second order ODE,

$$q_0'' + \alpha \dot{q}_0 - i\alpha q_0 = 0 ,$$

with the initial data

$$q_0(0) = 1$$
, $\dot{q}_0(0) = -(\alpha + i)$.

The solutions of the characteristic equation

$$\lambda^2 + \alpha\lambda - i\alpha = 0$$

are given by

$$\lambda_{\pm} = \frac{-\alpha \pm \left(a + i\sqrt{a^2 - \alpha^2}\right)}{2} \ .$$

where

$$a := \left(\frac{\alpha\sqrt{\alpha^2 + 16} + \alpha^2}{2}\right)^{\frac{1}{2}} > \alpha.$$

Notice that $\operatorname{Re}(\lambda_+) > 0$ while $\operatorname{Re}(\lambda_-) < 0$. This leads to

$$q_0(t) = A_+ e^{\lambda_+ t} + A_- e^{\lambda_- t}$$
,

with

$$A_{+} = \frac{\dot{q}_{0}(0) - \lambda_{-}q_{0}(0)}{\lambda_{+} - \lambda_{-}} = -\frac{(\alpha + i + \lambda_{-})}{(a + i\sqrt{a^{2} - \alpha^{2}})},$$

$$A_{-} = \frac{\lambda_{+}q_{0}(0) - \dot{q}_{0}(0)}{\lambda_{+} - \lambda_{-}} = \frac{(\alpha + i + \lambda_{+})}{(a + i\sqrt{a^{2} - \alpha^{2}})}$$

In particular,

$$\int_{0}^{t} |q_0(s)|^2 ds$$

tends to $+\infty$ with t. Let us come back to the expression of the L^2 norm of our solution,

$$||S_{\alpha}(t)u_0^{\varepsilon}||_{L^2}^2 = 1 + \varepsilon^2 - 2\alpha\varepsilon^2 \int_0^t (|q_0(s)|^2 + \mathcal{O}_T(\varepsilon))ds.$$

Fix T > 0 such that

$$2\alpha \int_{0}^{T} |q_0(s)|^2 ds \ge 3.$$

Fix $\varepsilon > 0$ small enough so that $2\alpha T\mathcal{O}_T(\varepsilon) \leq 1$, we obtain

$$||S_{\alpha}(T)u_0^{\varepsilon}||_{L^2}^2 \leq 1 - \varepsilon^2$$
,

which is the claim.

Let us complete the proof of the second part of Theorem 5. First we extend to this general context the notation introduced in the proof of Proposition 3,

(4.10)
$$a := \left(\frac{\sqrt{\alpha^4 + 16M^2\alpha^2 + \alpha^2}}{2}\right)^{\frac{1}{2}} > \alpha.$$

Notice that

$$(4.11) a\sqrt{a^2 - \alpha^2} = 2M\alpha .$$

Lemma 2. If $\{u(t)\}$ is a trajectory of (1.2) in W, of momentum M, disjoint of C_M and such that

$$\forall t \ge 0 \ , \ \|u(t)\|_{L^2}^2 \ge M,$$

then $b(t) \neq 0$ for every t, and there exists $\theta \in \mathbb{T}$ such that, as $t \to +\infty$,

$$e^{-itM}\sqrt{M}\frac{\overline{p(t)}}{b(t)} \rightarrow e^{-i\theta}\left(\frac{\sqrt{a^2-\alpha^2}+i(\alpha-a)}{2M}-1\right),$$

 $e^{itM}c(t) \rightarrow \sqrt{M}e^{i\theta}.$

Proof. Since

$$||u(t)||_{L^2}^2 = |b(t)|^2 + M(1 - |p(t)|^2),$$

the condition on u reads

$$(4.12) \forall t, |b(t)|^2 \ge M|p(t)|^2.$$

Since the trajectory is disjoint from \mathcal{C}_M , b and p cannot cancel at the same time, and therefore $b(t) \neq 0$ for every t. From the ODE on c in (4.1), we have

$$(4.13) \quad i\frac{d}{dt} \left(e^{itM} c(t) \right) = e^{itM} \left(2|b(t)|^2 c(t) + 2M(1 - |p(t)|^2)b(t)p(t) \right).$$

Recall that $|b|^2 \in L^1(\mathbb{R}_+)$. Therefore (4.12) implies that $|p|^2 \in L^1(\mathbb{R}_+)$, hence

$$\frac{d}{dt}\left(e^{itM}c(t)\right) \in L^1(\mathbb{R}_+) ,$$

and consequently

$$e^{itM}c(t) \to c_{\infty}$$
.

Notice that, since $p(t) \to 0$, $|c_{\infty}|^2 = M$, hence there exists $\theta \in \mathbb{T}$ such that

$$c_{\infty} = \sqrt{M} e^{i\theta}$$
.

In order to establish the other condition, we fix $T \gg 1$ and we set

$$\varepsilon = \varepsilon(T) := |b(T)|$$
.

Integrating from T to $+\infty$ the identity

$$\frac{d}{dt}(|b(t)|^2 + M(1 - |p(t)|^2)) = -2\alpha|b(t)|^2,$$

we obtain

(4.14)
$$|b(T)|^2 - M|p(T)|^2 = 2\alpha \int_T^\infty |b(t)|^2 dt.$$

Consequently,

$$|b(T)| = \varepsilon, \ |p(T)| \le \frac{|b(T)|}{\sqrt{M}} = O(\varepsilon), \ |c(T) - c_{\infty} e^{-iTM}| = O\left(\int_{T}^{\infty} |b(t)|^{2} dt\right) = O(\varepsilon^{2}),$$

where the last estimate comes from integrating (4.13). In other words, in any H^s space,

$$\begin{aligned} & \text{dist} \left(u(T), c_{\infty} \mathrm{e}^{-iTM} \mathrm{e}^{ix} \right) = O(\varepsilon) \ , \\ & \text{dist} \left(u(T), b(T) + c_{\infty} \mathrm{e}^{-iTM} \mathrm{e}^{ix} + c_{\infty} \mathrm{e}^{-iTM} p(T) \mathrm{e}^{2ix} \right) = O(\varepsilon^2) \ . \end{aligned}$$

At this stage, we are going to describe $u(t+T) = S_{\alpha}(t)u(T)$ for $t \geq 0$ by means of the linearised equation, exactly as in the proof of Proposition 3. We obtain

$$S_{\alpha}(t)u(T)(x) = e^{-itM} \left(c_{\infty} e^{-iTM} e^{ix} + \varepsilon v(t,x) + \varepsilon^2 w(t,x) \right) ,$$

where v is the solution of the linearised problem

$$i(\partial_t v + \alpha(v|1)) + Mv = 2Mv + \Pi \left(c_{\infty}^2 e^{-2iTM} e^{2ix} \overline{v} \right) ,$$

$$v(0,x) = \frac{b(T)}{\varepsilon} + c_{\infty} e^{-iTM} \frac{p(T)}{\varepsilon} e^{2ix} ,$$

and, for every R > 0, there exists $C_{s,R}$ independent of T such that

$$\forall t \in [0, R], ||w(t)||_{H^s} \leq C_{s,R}$$
.

This leads to

$$||S_{\alpha}(t)u(T)||_{L^{2}}^{2} - M = ||u(T)||_{L^{2}}^{2} - M - 2\alpha \int_{0}^{t} |(S(s)u(T)|1)|^{2} ds$$
$$= |b(T)|^{2} - M|p(T)|^{2} - 2\alpha\varepsilon^{2} \int_{0}^{t} (|(v(s)|1)|^{2} + O_{R}(\varepsilon)) ds$$

for every $t \in [0, R]$. In other words, the condition $||u(t+T)||^2 \ge M$ reads as follows: for every R > 0, there exists $c_R > 0$ such that, for every $t \in [0, R]$, for every T > 0,

$$(4.15) |b(T)|^2 - M|p(T)|^2 - 2\alpha\varepsilon^2 \int_0^t |(v(s)|1)|^2 ds \ge -c_R \varepsilon^3.$$

Let us compute v(t). From the linearized problem, we find

$$v(t,x) = q_0(t) + q_2(t)e^{2ix}$$
,

with

$$i(\dot{q}_0 + \alpha q_0) = Mq_0 + c_{\infty}^2 e^{-2iTM} \overline{q}_2 ,$$

 $i\dot{q}_2 = Mq_2 + c_{\infty}^2 e^{-2iTM} \overline{q}_0 ,$
 $q_0(0) = \frac{b(T)}{\varepsilon} , \quad q_2(0) = c_{\infty} e^{-iTM} \frac{p(T)}{\varepsilon} .$

Let us focus on q_0 . Deriving the first equation, we have

$$i(q_0'' + \alpha \dot{q}_0) = M \dot{q}_0 + c_\infty^2 e^{-2iTM} \overline{\dot{q}_2} ,$$

$$= M \dot{q}_0 + c_\infty^2 e^{-2iTM} \left(iM \overline{q}_2 + i \overline{c}_\infty^2 e^{2iTM} q_0 \right)$$

$$= -M(\alpha + iM) q_0 + iM^2 q_0$$

$$= -\alpha M q_0 .$$

We are left with the following second order ODE,

$$q_0'' + \alpha \dot{q}_0 - i\alpha M q_0 = 0 ,$$

with the initial data

$$q_0(0) = \frac{b(T)}{\varepsilon}$$
, $\dot{q}_0(0) = -(\alpha + iM)\frac{b(T)}{\varepsilon} - iMc_{\infty}e^{-iTM}\frac{\overline{p(T)}}{\varepsilon}$.

Again, the solutions of the characteristic equation

$$\lambda^2 + \alpha \lambda - iM\alpha = 0$$

are given by

$$\lambda_{\pm} = \frac{-\alpha \pm \left(a + i\sqrt{a^2 - \alpha^2}\right)}{2} \ .$$

Again, $Re(\lambda_+) > 0 > Re(\lambda_-)$ and this leads to

$$q_0(t) = A_+ e^{\lambda_+ t} + A_- e^{\lambda_- t}$$
,

with

$$A_{+} = \frac{\dot{q}_{0}(0) - \lambda_{-}q_{0}(0)}{\lambda_{+} - \lambda_{-}} = -\frac{(\alpha + iM + \lambda_{-})b(T) + iMc_{\infty}e^{-iTM}\overline{p(T)}}{\varepsilon(T)(a + i\sqrt{a^{2} - \alpha^{2}})},$$

$$A_{-} = \frac{\lambda_{+}q_{0}(0) - \dot{q}_{0}(0)}{\lambda_{+} - \lambda_{-}} = \frac{(\alpha + iM + \lambda_{+})b(T) + iMc_{\infty}e^{-iTM}\overline{p(T)}}{\varepsilon(T)(a + i\sqrt{a^{2} - \alpha^{2}})}$$

Rephrasing (4.15), we must have, for every R > 0, for every $t \in [0, R]$, for every T > 0,

(4.16)
$$1 - M \frac{|p(T)|^2}{\varepsilon(T)^2} - 2\alpha \int_0^t |q_0(t)|^2 dt \ge -c_R \varepsilon(T) .$$

Computing the integral of $|q_0|^2$, we infer, for some uniform constant B > 0,

$$\frac{2\alpha}{a-\alpha}|A_+(T)|^2 e^{(a-\alpha)R} \le c_R \,\varepsilon(T) + B \ .$$

Taking the upper limit of both sides as $T \to \infty$, we infer

$$\frac{2\alpha}{a-\alpha} \limsup_{T \to \infty} |A_{+}(T)|^2 e^{(a-\alpha)R} \le B ,$$

and finally, making $R \to +\infty$,

$$\limsup_{T \to \infty} |A_+(T)|^2 = 0 .$$

Coming back to the expression of $A_{+}(T)$ and of c_{∞} above, this yields

$$e^{-iTM}\sqrt{M}\frac{\overline{p(T)}}{b(T)} \to i\frac{\alpha + iM + \lambda_-}{M}e^{-i\theta} = e^{-i\theta}\left(\frac{\sqrt{a^2 - \alpha^2} + i(\alpha - a)}{2M} - 1\right).$$

This completes the proof of Lemma 2.

Remark 1. For further reference, it is useful to observe that the result of Lemma 2 can be made uniform. Indeed, assume that we have a sequence of solutions $\{u_n\}$ of fixed momentum M satisfying $\|u_n(t)\|_{L^2}^2 \geq M$ for every t, n and such that $(u_n(T)|1) \underset{T \to +\infty}{\longrightarrow} 0$ uniformly with respect to n. Then we claim that the two convergences established by Lemma 2 are also uniform with respect to n. Indeed, this is straightforward for $c_n(t)$, since, as we already noticed,

$$|c_n(t) - c_{n,\infty} e^{-itM}| \le C \int_{t}^{\infty} |b_n(s)|^2 ds \le C' |b_n(t)|^2$$
.

As for the second quantity, we just need to reproduce the above linearisation proof by observing that the linearisation is made near a compact sequence of solutions $\{c_{n,\infty}e^{-itM}\}$ with a family $\{\varepsilon_n(T)\}$ of uniformly small parameters, so that, for every R > 0, the bound

$$\sup_{t \in [0,R]} \|w_n(t)\|_{H^s} \le C_{s,R}$$

is uniform with respect to n. The result then follows from the estimate

$$\frac{2\alpha}{a-\alpha} \limsup_{T \to \infty} \sup_{n} |A_{n,+}(T)|^2 e^{(a-\alpha)R} \le B.$$

As a next step, we show that the corresponding solutions of the reduced system on $\beta := |b|^2, \delta := M|p|^2 = M - \gamma, \zeta := M\overline{cpb}$, satisfy a nonlinear scattering problem.

Lemma 3. Let $\{u(t)\}$ be a trajectory of (1.2) in W, of momentum M, disjoint of \mathcal{C}_M , such that

$$\forall t \geq 0 , \|u(t)\|_{L^2}^2 \geq M.$$

Write

$$u(t,x) = b(t) + \frac{c(t)e^{ix}}{1 - p(t)e^{ix}} ,$$

$$\beta(t) := |b(t)|^2 , \ \delta(t) := M|p(t)|^2 , \ \zeta(t) := Mc(t)\overline{b(t)p(t)} .$$

Then there exists $\beta_{\infty} > 0$ such that, as $t \to +\infty$,

$$\beta(t) = \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\delta(t) = \frac{a-\alpha}{a+\alpha} \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\zeta(t) = \left(\frac{\sqrt{a^2 - \alpha^2} + i(\alpha - a)}{2} - M \right) \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) .$$

Conversely, for every $\beta_{\infty} > 0$, there exists a unique solution (β, δ, ζ) of the reduced system

$$\begin{cases} \dot{\beta} + 2\alpha\beta &= 2\mathrm{Im}\zeta \\ \dot{\delta} &= 2\mathrm{Im}\zeta \\ \dot{\zeta} + (\alpha - 2iM)\zeta &= -i(3\delta + \beta)\zeta + i(M - \delta)^2(\delta + \beta) - 2i\beta\delta(M - \delta) \end{cases}$$

with the above asymptotic expansion as $t \to +\infty$.

Furthermore, in this context, for every C > 0, there exists C' > 0such that

- If $\beta(0) \ge C^{-1}$, then $\beta_{\infty} \ge (C')^{-1}$. If $\beta(0) \le C$, then $\beta_{\infty} \le C'$.

Proof. Setting $\delta := M - \gamma$ in the reduced system (4.4) in β, γ, ζ , we indeed obtain

$$\begin{cases} \dot{\beta} + 2\alpha\beta &= 2\mathrm{Im}\zeta, \\ \dot{\delta} &= 2\mathrm{Im}\zeta, \\ \dot{\zeta} + (\alpha - 2iM)\zeta &= -i(3\delta + \beta)\zeta + i(M - \delta)^2(\delta + \beta) - 2i\beta\delta(M - \delta) \end{cases}$$

Furthermore, we already know that $(\beta(t), \delta(t), \zeta(t)) \to (0, 0, 0)$ as $t \to +\infty$, and that

$$\int_{0}^{\infty} \beta(t) dt < \infty .$$

From the first two equations, we infer

$$\beta(t) - \delta(t) = 2\alpha \int_{t}^{\infty} \beta(s) ds$$
.

On the other hand, from Lemma 2, we have

$$\frac{\delta(t)}{\beta(t)} \underset{t \to +\infty}{\longrightarrow} \left| \frac{\sqrt{a^2 - \alpha^2} + i(\alpha - a)}{2M} - 1 \right|^2 = \frac{a - \alpha}{a + \alpha} ,$$

as an elementary calculation using (4.11) shows. Combining the above two informations, we obtain

$$\frac{\beta(t)}{\int_{t}^{\infty} \beta(s) \, ds} \xrightarrow[t \to +\infty]{} a + \alpha ,$$

and consequently

$$\log \left(\int_{t}^{\infty} \beta(s) \, ds \right) = -(a + \alpha)t(1 + o(1)) .$$

In particular, for every $\varepsilon > 0$, there exists C_{ε} such that

$$\beta(t) \le C_{\varepsilon} e^{-(a+\alpha-\varepsilon)t}, \ t \ge 0.$$

The same estimate holds for $\delta(t)$, and, in view of $|\zeta| = (M - \delta)\sqrt{\beta\delta}$, for $|\zeta(t)|$. Writing

$$X(t) := \begin{pmatrix} \beta(t) \\ \delta(t) \\ \zeta_R(t) := \operatorname{Re}\zeta(t) \\ \zeta_I(t) := \operatorname{Im}\zeta(t) \end{pmatrix} \in \mathbb{R}^4 ,$$

we observe that

$$\dot{X} + AX = Q(X) ,$$

where

$$A := \begin{pmatrix} 2\alpha & 0 & 0 & -2\\ 0 & 0 & 0 & -2\\ 0 & 0 & \alpha & 2M\\ -M^2 & -M^2 & -2M & \alpha \end{pmatrix},$$

$$Q(X) := \begin{pmatrix} 0\\ 0\\ (\beta + 3\delta)\zeta_I\\ -(\beta + 3\delta)\zeta_R - 2M\delta^2 - 4M\beta\delta + \delta^3 + 3\beta\delta^2 \end{pmatrix}$$

An elementary calculation — involving for instance $A - \alpha I$ — shows that the four eigenvalues of A are

$$\alpha \pm a$$
, $\alpha \pm i\sqrt{a^2 - \alpha^2}$.

Now recall that we have proved

$$|X(t)| \le C_{\varepsilon} e^{-(a+\alpha-\varepsilon)t}, \ t \ge 0,$$

hence, in view of the spectrum of A, since Q(X) is a quadratic–cubic expression of X, we infer

$$|e^{tA}[Q(X(t))]| \le D_{\varepsilon} e^{-(a+\alpha-2\varepsilon)t}, t \ge 0.$$

From (4.17), we have

$$\frac{d}{dt}[e^{tA}X(t)] = e^{tA}Q[X(t)].$$

Consequently there exists $X_{\infty} \in \mathbb{R}^4$ such that $e^{tA}X(t) \to X_{\infty}$ as $t \to +\infty$. Integrating from t to $+\infty$, we infer

(4.18)
$$X(t) = e^{-tA} X_{\infty} - \int_{t}^{\infty} e^{(s-t)A} [Q(X(s))] ds.$$

In view of the spectrum of A, we have, for $s \geq t$,

$$|e^{(s-t)A}[Q(X(s))]| < E_{\varepsilon}e^{(a+\alpha)(s-t)-2(a+\alpha-\varepsilon)s}$$
,

so that

$$\left| \int_{t}^{\infty} e^{(s-t)A} [Q(X(s))] ds \right| \leq F_{\varepsilon} e^{-2(a+\alpha-\varepsilon)t} .$$

This implies in particular

$$e^{-tA}X_{\infty} = O\left(e^{-(a+\alpha)t}\right)$$

for every $\varepsilon > 0$, which, in view of the spectrum of A, imposes that X_{∞} is an eigenvector of A for the eigenvalue $\lambda = \alpha + a$, hence there exists $\beta_{\infty} \in \mathbb{R}$ such that

$$X_{\infty} = \beta_{\infty} \begin{pmatrix} 1 \\ \frac{a - \alpha}{a + \alpha} \\ M \frac{\alpha - a}{a} \\ \frac{\alpha - a}{2} \end{pmatrix} .$$

Since $\beta(t) > 0$, this imposes in particular $\beta_{\infty} > 0$, so that, improving the remainder estimates by coming back to equation (4.18), we conclude, using again (4.11),

$$\beta(t) = \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\delta(t) = \frac{a-\alpha}{a+\alpha} \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\zeta(t) = \left(\frac{\sqrt{a^2 - \alpha^2} + i(\alpha - a)}{2} - M \right) \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) .$$

Conversely, given any $\beta_{\infty} > 0$, one can easily solve equation (4.18) by a fixed point argument on some interval $[T, \infty[$ for T > 0 large enough, with the norm

$$||X||_T := \sup_{t>T} e^{(a+\alpha)t} |X(t)|$$
.

Then the extension to the whole real line is ensured by, say, the identities

$$|\zeta|^2 = (M - \delta)^2 \beta \delta$$
, $\delta(t) + 2\alpha \int_t^\infty \beta(s) ds = \beta(t)$

which, combined with the first equation, lead to

$$|\dot{\beta}| = O(\beta)$$
.

Finally, let us prove the last statement. From the fixed point argument mentioned above, it is easy to check that there exists K > 0 such that, if $|X_{\infty}|$ is small enough, then

$$|X(0)| \le K|X_{\infty}|.$$

By contradiction, this proves that, if $\beta(0) \geq C^{-1}$, then $\beta_{\infty} \geq (C')^{-1}$. The proof of the other inequality is slightly more delicate. Assume $\beta(0) \leq C$. As a first step, we are going to prove that $\beta(t) \to 0$ as $t \to +\infty$ uniformly. Indeed, since

(4.19)
$$\beta(t) = \delta(t) + 2\alpha \int_{t}^{\infty} \beta(s) ds ,$$

we infer

$$\frac{d}{dt} \left(e^{2\alpha t} \int_{t}^{\infty} \beta(s) \, ds \right) = -\delta(t) e^{2\alpha t} \le 0.$$

Hence

$$\int_{t}^{\infty} \beta(s) \, ds \le \left(\int_{0}^{\infty} \beta(s) \, ds \right) e^{-2\alpha t} \le \frac{\beta(0)}{2\alpha} e^{-2\alpha t} .$$

On the other hand, since $\beta(t) + M - \delta(t)$ is a decreasing function of t, we have

$$\beta(t) + M - \delta(t) \le \beta(0) + M - \delta(0) ,$$

so that $\beta(t) \leq C + M$. Coming back to the equation, we infer that there exists $B = B(\alpha, M, C)$ such that

$$|\dot{\beta}(t)| \leq B$$
.

Consequently, for every $s \in \left[t, t + \frac{\beta(t)}{B}\right]$, we have

$$\beta(s) \ge \beta(t) - B(s-t)$$

and therefore

$$\int_{t}^{t+\frac{\beta(t)}{B}} \beta(s) \, ds \ge \frac{\beta(t)^{2}}{B} - B \int_{t}^{t+\frac{\beta(t)}{B}} (s-t) \, ds = \frac{\beta(t)^{2}}{2B} .$$

In view of the estimate on $\int_{t}^{\infty} \beta$, we conclude

$$\beta(t) < Ke^{-\alpha t}$$

with $K = K(\alpha, M, C)$, which implies the uniform convergence of $\beta(t)$ to 0.

Then, using Remark 1 on uniformity in Lemma 2, we infer that, for every $\varepsilon > 0$, there exists $T = T(\alpha, M, C, \varepsilon)$ such that

$$\forall t \ge T \ , \ \frac{a - \alpha - \varepsilon}{a + \alpha - \varepsilon} \le \frac{\delta(t)}{\beta(t)} \le \frac{a - \alpha + \varepsilon}{a + \alpha + \varepsilon} \ .$$

Coming back to identity (4.19), we infer, for every $t \geq T$,

$$\frac{d}{dt} \left(e^{(a+\alpha-\varepsilon)t} \int_{t}^{\infty} \beta(s) \, ds \right) \leq 0 ,$$

so that

$$\int_{t}^{\infty} \beta(s) ds \le \left(\int_{T}^{\infty} \beta(s) ds \right) e^{-(a+\alpha-\varepsilon)(t-T)} \le \frac{\beta(0)}{2\alpha} e^{-(a+\alpha-\varepsilon)(t-T)}.$$

Since

$$\beta(t) = \delta(t) + 2\alpha \int_{t}^{\infty} \beta \le \frac{a - \alpha + \varepsilon}{a + \alpha + \varepsilon} \beta(t) + 2\alpha \int_{t}^{\infty} \beta,$$

we finally obtain

$$\forall t \geq 0 , \ \beta(t) \leq K' e^{-(a+\alpha-\varepsilon)t}$$

with $K' = K'(\alpha, M, C, \varepsilon)$. We have the same estimate for |X(t)|, and, coming back to the identity

$$X_{\infty} = X(0) + \int_{0}^{\infty} e^{sA}[Q(X(s))] ds ,$$

we conclude, by choosing ε small enough, that

$$|X_{\infty}| \le C'(\alpha, M, C).$$

Notice that Lemma 3 combined with the estimate

$$|c(t) - c_{\infty}e^{-itM}| = O\left(\int_{t}^{\infty} \beta(s) ds\right)$$

leads to

$$\operatorname{dist}(u(t), \mathcal{C}_M) = O\left(e^{-\lambda t}\right), \ \lambda = \frac{a+\alpha}{2}.$$

Finally, in order to describe the geometric structure of $\Sigma_{M,\alpha}$, we give a complete description of the asymptotic properties of u(t) as $t \to +\infty$.

Lemma 4. Under the assumptions of Lemma 3, there exist $(\beta_{\infty}, \theta, \varphi) \in (0, \infty) \times \mathbb{T} \times \mathbb{T}$ such that, as $t \to +\infty$,

$$b(t) \sim \sqrt{\beta_{\infty}} e^{-\frac{a+\alpha}{2}t - itM\left(1 + \frac{\alpha}{a}\right) + i\varphi} ,$$

$$c(t) \sim \sqrt{M} e^{-itM + i\theta} ,$$

$$p(t) \sim \sqrt{\frac{\beta_{\infty}}{M}} \left(\frac{\sqrt{a^2 - \alpha^2} - i(\alpha - a)}{2M} - 1\right) e^{-\frac{a+\alpha}{2}t + itM\frac{\alpha}{a} + i(\theta - \varphi)} .$$

Conversely, for every $(\beta_{\infty}, \theta, \varphi) \in (0, \infty) \times \mathbb{T} \times \mathbb{T}$, there exists a unique trajectory

$$u(t,x) = b(t) + \frac{c(t)e^{ix}}{1 - p(t)e^{ix}}$$

satisfying the above asymptotic properties.

Proof. The asymptotic property has already been established for c(t). Let us prove it for b(t) and p(t). Recall from system (4.1) that

$$i(\dot{b} + \alpha b) = (|b|^2 + 2M(1 - |p|^2))b + Mc\overline{p} = \left(\beta + 2M - 2\delta + \frac{\zeta}{\beta}\right)b,$$

$$i\dot{p} = M(1 - |p|^2)p + c\overline{b} = \left(M - \delta + \frac{\zeta}{\delta}\right)p.$$

Furthermore, we know that β, δ, ζ satisfy the properties of Lemma 3. Therefore

$$i\frac{d}{dt}\left(\frac{b}{\sqrt{\beta}}\right) = \left(\beta + 2M - 2\delta + \frac{\operatorname{Re}\zeta}{\beta}\right)\frac{b}{\sqrt{\beta}}$$

$$= \left(M\frac{a+\alpha}{a} + O\left(e^{-(a+\alpha)t}\right)\right)\frac{b}{\sqrt{\beta}},$$

$$i\frac{d}{dt}\left(\frac{\sqrt{M}p}{\sqrt{\delta}}\right) = \left(M - \delta + \frac{\operatorname{Re}\zeta}{\delta}\right)\frac{\sqrt{M}p}{\sqrt{\delta}}$$

$$= \left(-\frac{M\alpha}{a} + O\left(e^{-(a+\alpha)t}\right)\right)\frac{\sqrt{M}p}{\sqrt{\delta}}.$$

This implies that there exist angles φ, ψ such that

$$b(t) \sim \sqrt{\beta_{\infty}} e^{-\frac{a+\alpha}{2}t - itM\left(1 + \frac{\alpha}{a}\right) + i\varphi}$$

$$p(t) \sim \sqrt{\frac{\beta_{\infty}}{M}} \left(\frac{a-\alpha}{a+\alpha}\right)^{\frac{1}{2}} e^{-\frac{a+\alpha}{2}t + itM\frac{\alpha}{a} + i\psi}$$

In view of Lemma 2,

$$e^{-itM}\sqrt{M}\frac{\overline{p(t)}}{b(t)} \to e^{-i\theta}\left(\frac{\sqrt{a^2-\alpha^2}+i(\alpha-a)}{2M}-1\right)$$

and of the elementary formula

$$\left(\frac{a-\alpha}{a+\alpha}\right)^{\frac{1}{2}} = \left|\frac{\sqrt{a^2-\alpha^2}-i(\alpha-a)}{2M}-1\right| ,$$

we infer that the asymptotic formula for p(t) reads in fact

$$p(t) \sim \sqrt{\frac{\beta_{\infty}}{M}} \left(\frac{\sqrt{a^2 - \alpha^2} - i(\alpha - a)}{2M} - 1 \right) e^{-\frac{a + \alpha}{2}t + itM\frac{\alpha}{a} + i(\theta - \varphi)}$$
.

Conversely, let us prove that, given any $(\beta_{\infty}, \theta, \varphi) \in (0, \infty) \times \mathbb{T} \times \mathbb{T}$, there exists a unique trajectory with these asymptotic properties. By Lemma 3, there exists a unique trajectory (β, δ, ζ) of the reduced system such that

$$\beta(t) = \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\delta(t) = \frac{a-\alpha}{a+\alpha} \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) ,$$

$$\zeta(t) = \left(\frac{\sqrt{a^2 - \alpha^2} + i(\alpha - a)}{2} - M \right) \beta_{\infty} e^{-(a+\alpha)t} \left(1 + O\left(e^{-(a+\alpha)t}\right) \right) .$$

Note that $e^{2\alpha t}[|\zeta|^2 - (M-\delta)^2\beta\delta]$ is a constant wich tends to 0 as $t\to +\infty$, hence it is identically 0. This implies $\beta>0, 0\leq \delta$. Fix

T > 0 big enough so that $M > \delta(T) > 0, \zeta(T) \neq 0$. Consider the solution (b_1, c_1, p_1) of the system in (b, c, p) with

$$b_1(T) = \sqrt{\beta(T)}$$
, $\sqrt{M} p_1(T) = \sqrt{\delta(T)}$, $M c_1(T) = \frac{\zeta(T)}{\overline{b_1(T)p_1(T)}}$.

Then, by uniqueness of the Cauchy problem for the reduced system, we have

$$\forall t \in \mathbb{R} , |b_1(t)|^2 = \beta(t) , M |p_1(t)|^2 = \delta(t) , M c_1(t) \overline{b_1(t)p_1(t)} = \zeta(t) .$$

Applying the first part of Lemma 4, there exists $(\theta_1, \varphi_1) \in \mathbb{T} \times \mathbb{T}$ such that as $t \to +\infty$,

$$b_1(t) \sim \sqrt{\beta_{\infty}} e^{-\frac{a+\alpha}{2}t - itM\left(1 + \frac{\alpha}{a}\right) + i\varphi_1} ,$$

$$c_1(t) \sim \sqrt{M} e^{-itM + i\theta_1} ,$$

$$p_1(t) \sim \sqrt{\frac{\beta_{\infty}}{M}} \left(\frac{\sqrt{a^2 - \alpha^2} - i(\alpha - a)}{2M} - 1\right) e^{-\frac{a+\alpha}{2}t + itM\frac{\alpha}{a} + i(\theta_1 - \varphi_1)} .$$

Then

$$b(t) := e^{i(\varphi - \varphi_1)} b_1(t) , c(t) := e^{i(\theta - \theta_1)} c_1(t) , p(t) := e^{i(\theta - \varphi - \theta_1 + \varphi_1)} p_1(t)$$

satisfies the system in b, c, p with the required asymptotic properties.

Finally, let us prove the uniqueness of such a solution. If $\tilde{b}, \tilde{c}, \tilde{\zeta}$ is a solution of the same system with the same asymptotic properties, we first observe that, in view of the uniqueness in Lemma 3,

$$\forall t \in \mathbb{R} , \ |\tilde{b}(t)|^2 = \beta(t) , \ M \, |\tilde{p}(t)|^2 = \delta(t) , \ M \, \tilde{c}(t) \overline{\tilde{b}(t)} \overline{\tilde{p}(t)} = \zeta(t) .$$

Then we come back to the equations on $b/\sqrt{\beta}$ and $\sqrt{M}p/\sqrt{\delta}$ that we derived in the beginning of this proof. We obtain

$$i\frac{d}{dt}\left(\frac{b-\tilde{b}}{\sqrt{\beta}}\right) = \left(M\frac{a+\alpha}{a} + O\left(e^{-(a+\alpha)t}\right)\right)\frac{b-\tilde{b}}{\sqrt{\beta}},$$

$$i\frac{d}{dt}\left(\frac{\sqrt{M}(p-\tilde{p})}{\sqrt{\delta}}\right) = \left(-\frac{M\alpha}{a} + O\left(e^{-(a+\alpha)t}\right)\right)\frac{\sqrt{M}(p-\tilde{p})}{\sqrt{\delta}}.$$

This implies that $\xi_1 := (b - \tilde{b})/\sqrt{\beta}$ and $\xi_2 := \sqrt{M}(p - \tilde{p})/\sqrt{\delta}$ satisfy the inequality

$$|\xi(t)| \le \int_{t}^{\infty} O\left(e^{-(a+\alpha)s}\right) |\xi(s)| ds$$

and consequently that $\xi(t) \equiv 0$ for t large enough. Hence $b = \tilde{b}, p = \tilde{p}$, and finally $c = \tilde{c}$ from the definition of ζ .

In order to complete the proof of Theorem 5, we consider the mapping

$$J:(0,\infty)\times\mathbb{T}\times\mathbb{T}\longrightarrow\mathcal{E}_M$$

defined by

$$J(\beta_{\infty}, \theta, \varphi) = u(0) ,$$

where u is the unique solution of (1.2) provided by the second statement of Lemma 4. In view of Lemma 4, the range of J is precisely the set $\Sigma_{M,\alpha}$. In order to prove that this set is a submanifold of dimension 3 of \mathcal{E}_M , it is enough to establish that J is a one to one proper immersion.

The injectivity of J is trivial. Its smoothness with respect to β_{∞} is a consequence of the fixed point argument in Lemma 3; the dependence with respect to (θ, φ) is much more elementary, since it reflects the gauge and translation invariances, hence it is smooth as well.

To prove the immersion property, we just have to check that, for every $(\beta_{\infty}, \theta, \varphi)$, the three vectors

$$\partial_{\beta_{\infty}} J(\beta_{\infty}, \theta, \varphi), \partial_{\theta} J(\beta_{\infty}, \theta, \varphi), \partial_{\varphi} J(\beta_{\infty}, \theta, \varphi)$$

are independent. We claim that the subspace spanned by these three vectors is also spanned by $\partial_t u(0), -i\partial_x u(0), iu(0)$. Indeed, in view of Lemma 4 and of the invariances of equation (1.2), one easily checks the following identity,

$$e^{i\varphi}S_{\alpha}(t+T)\left[J(\beta_{\infty},\theta_{0},\varphi_{0})\right](x+\theta-\varphi)) = S_{\alpha}(t)\left[J\left(\beta_{\infty}e^{-(a+\alpha)T},\theta_{0}+\theta-MT,\varphi_{0}+\varphi-MT\left(1+\frac{\alpha}{a}\right)\right)\right](x) .$$

If these three vectors were dependent, this would mean that u is a traveling wave of equation (1.2). This would impose that $(u|1) \equiv 0$, hence $u \in \mathcal{C}_M$, which is impossible since $\Sigma_{M,\alpha}$ is disjoint from \mathcal{C}_M .

Finally, J is proper because of the last statement of Lemma 3.

The last statement to be proved is that $\Sigma_{M,\alpha} \cup \mathcal{C}_M$ is closed. Since \mathcal{C}_M is compact, it is enough to prove that the closure of $\Sigma_{M,\alpha}$ is contained into $\Sigma_{M,\alpha} \cup \mathcal{C}_M$. Let (u_n) be a sequence of points of $\Sigma_{M,\alpha}$ which tends to $u \in \mathcal{W}$. Set $(\beta_n, \theta_n, \varphi_n) := J^{-1}(u_n)$. Since J is a homeomorphism onto its range $\Sigma_{M,\alpha}$, the only cases to be studied are $\beta_n \to 0$ and $\beta_n \to +\infty$. Now we appeal to the last statement of Lemma 3. In the first case, we obtain that (u|1) = 0, and more generally that $(S_{\alpha}(t)(u)|1) = 0$, so that $u \in \mathcal{C}_M$. In the second case, we infer $|(u_n|1)| \to \infty$, which contradicts the fact that u_n is convergent.

The proof of Theorem 5 is complete.

Appendix A. Numerical simulations in collaboration with C. Klein (Université de Bourgogne)

As mentioned in the introduction, the complete study made in section 4 suggests that the open subset Ω of initial data which give rise to exploding orbits is a dense subset. Furthermore, it is natural to

ask about the rate of the Sobolev norms for such trajectories. For instance, is it true that the square of the H^1 norm grows linearly for generic initial data, as in the case of exploding trajectories in \mathcal{W} ? The numerical simulations below suggest that these two questions have a positive answer.

To numerically study the damped Szegö equation (1.2), we approximate u by a trigonometric polynomial,

(A.1)
$$u(x) \approx \sum_{k=-N/2+1}^{N/2} \hat{u}_k e^{ikx}, \quad N \in 2\mathbb{N},$$

i.e., we consider the discrete Fourier transform (DFT) of a vector u (in an abuse of notation, we use the same symbol for the function u and its discrete approximation) with components $u_n = u(x_n)$, where $x_n = -\pi + 2\pi n/N$, n = 1, 2, ..., N. The DFT can be computed efficiently with a Fast Fourier transform. Note that we work in the Hardy space, thus all coefficients \hat{u}_k corresponding to negative wave numbers vanish. But for computing the DFT, the negative wave numbers are nonetheless important. The action of the projector Π is simply to put the coefficients of the negative wave numbers equal to zero.

The approximation of the function u via a DFT implies that equation (1.2) is approximated via a finite dimensional system of ODEs. The latter is integrated with the standard explicit fourth order Runge-Kutta method. Derivatives with respect to x are computed in standard way by multiplying the coefficients \hat{u}_k by ik. We apply a Krasny filter, i.e., we put Fourier coefficients with a modulus smaller than 10^{-12} equal to 0 to address that we work with finite precision, and to take care of unavoidable rounding errors.

To test the code, we first study an element of \mathcal{W} , namely

$$u_0(x) = \frac{e^{ix}}{1 - pe^{ix}}$$

with p = 0.5 and $\alpha = 1$, for which we validate the result of Theorem 5, namely, as $t \to +\infty$,

(A.2)
$$||S_{\alpha}(t)u_0||_{H^1}^2 \sim \frac{4\alpha M^3}{\alpha^2 + M^2}t$$
.

Notice that

$$||u_0||_{L^2}^2 = \frac{1}{1-|p|^2} < \frac{1}{(1-|p|^2)^2} = M(u_0).$$

We use $N_t = 10^5$ time steps for $t \in [0, 20]$ and $N = 2^{12}$. During the computation we observe relative conservation of the momentum to the order of 10^{-15} , i.e., essentially machine precision, and the Fourier coefficients decrease to the order of the Krasny filter. This means the solution is well resolved both in space and in time. As can be seen in Fig. A.1, the agreement between theoretical prediction and numerics

is excellent, the asymptotic regime is reached for comparatively small values of t.

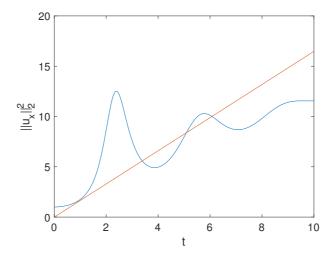


FIGURE A.1. In blue, the norm $||S_{\alpha}(t)u_0||_{H_1}^2$ for the solution to the equation (1.2) with $\alpha = 1$ for the initial data $u_0(x) = \frac{e^{ix}}{1-pe^{ix}}$ with p = 0.5 in dependence of time. In red, the asymptotic relation (A.2)

The second example studies the case of an initial datum with two poles,

$$u_0(x) = \frac{e^{ix}}{1 - p_1 e^{ix}} + \frac{e^{ix}}{1 - p_2 e^{ix}},$$

which corresponds to a more complicated phase space than W, but still finite dimensional, since the rank of K_{u_0} is 2. We put $p_1 = 0.7$, $p_2 = 0.8$ and use the same numerical parameters as before. The relative conservation of the momentum is of the order of 10^{-7} . The norm $||S_{\alpha}(t)u_0||_{H_1}^2$ in dependence of time for this example can be seen in Fig. A.2. The norm appears to grow linearly in time.

The third example illustrates the case of an arbitrary initial datum with a Gaussian profile, $u_0 = \Pi \exp(-10x^2)$. We use the same numerical parameters, this time for $t \in [0, 1000]$. The momentum is conserved to the order of 10^{-13} . The norm $||S_{\alpha}(t)u_0||_{H_1}^2$ can be seen for this case in Fig. A.3. Once more the square of the H^1 norm grows linearly in time.

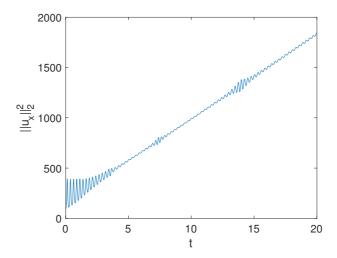


FIGURE A.2. The norm $||S_{\alpha}(t)u_0||_{H_1}^2$ for the solution to the equation (1.2) with $\alpha = 1$ for the initial data $u_0(x) = \frac{e^{ix}}{1 - 0.7e^{ix}} + \frac{e^{ix}}{1 - 0.8e^{ix}}$ in dependence of time.

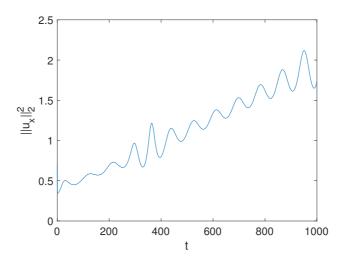


FIGURE A.3. The norm $||S_{\alpha}(t)u_0||_{H_1}^2$ for the solution to the equation (1.2) with $\alpha = 1$ for the initial data $u_0(x) = \Pi \exp(-10x^2)$ in dependence of time.

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