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Where to place a spherical obstacle so as to maximize the first Steklov eigenvalue.

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Abstract

We prove that among all doubly connected domains of \mathbb{R}^n of the form $B_1 \setminus \overline{B_2}$, where B_1 and B_2 are open balls of fixed radii such that $\overline{B_2} \subset B_1$, the first non-trivial Steklov eigenvalue achieves its maximal value uniquely when the balls are concentric. Furthermore, we show that the ideas of our proof also apply to a mixed boundary conditions eigenvalue problem found in literature.

Contents

1	Introduction	1
1.1	Optimization of the Steklov eigenvalue	1
1.2	Perforated domains: state of the art	3
1.3	Results of the paper	3
2	Proof of Theorem 1	4
2.1	Proof of the first assertion of Proposition 1	5
2.2	Spherical coordinates and preliminary computations	5
2.3	Proof of the second assertion of Proposition 1	6
2.4	Proof of the third assertion of Proposition 1	10
3	The Dirichlet-Steklov problem	11
3.1	A key proposition	12
3.2	Proof of Theorem 2	13
4	Appendix	13
4.1	Computation of the eigenvalues via classical separation of variables technique	14
4.2	A monotonicity result	15
4.3	Proof of Theorem 3	18

1. Introduction

1.1. Optimization of the Steklov eigenvalue

Let $\Omega \subset \mathbb{R}^n$, be a bounded, open set with Lipschitz boundary. In this paper we consider the following Steklov eigenvalue problem for the Laplace operator:

$$\begin{cases} \Delta u = 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial n} = \sigma u & \text{on } \partial\Omega, \end{cases} \quad (1)$$

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where $\partial u/\partial n$ is the outer normal derivative of u on $\partial\Omega$. It is well-known that the Steklov spectrum is discrete as long as the trace operator $H^1(\Omega) \rightarrow L^2(\partial\Omega)$ is compact, which is the case when the domain has Lipschitz boundary; in other words, in our framework the values of σ for which the problem (1) admits non-trivial solutions form an increasing sequence of eigenvalues $0 = \sigma_0(\Omega) < \sigma_1(\Omega) \leq \sigma_2(\Omega) \leq \dots \nearrow +\infty$, known as the Steklov spectrum of Ω .

We are interested in the first non-trivial Steklov eigenvalue, which can be given by a Rayleigh quotient:

$$\sigma_1(\Omega) = \inf \left\{ \frac{\int_{\Omega} |\nabla u|^2 dx}{\int_{\partial\Omega} u^2 d\sigma} \mid u \in H^1(\Omega) \setminus \{0\} \text{ such that } \int_{\partial\Omega} u d\sigma = 0 \right\},$$

where the infimum is attained for the corresponding eigenfunctions.

Among classical questions in spectral geometry, there are the problems of minimizing (or maximizing) the Laplace eigenvalues with various boundary conditions and different geometrical and topological constraints. The constraint of volume has been extensively studied in the last years. For example there is the celebrated Faber-Krahn inequality [20, 34], which states that the ball minimizes the first eigenvalue of the Laplacian with Dirichlet boundary condition among domains of fixed volume. There is a similar result for the maximization of the first non-trivial eigenvalue of the Laplacian with Neumann boundary known as the Szego-Weinberger inequality [40, 42]. For the Steklov problem, Brock proved in [10] that the first non-trivial eigenvalue of a Lipschitz domain is less than the eigenvalue of the ball with the same volume.

The perimeter constraint is very interesting to study, especially in the case of Steklov eigenvalues. One early result is due to Weinstock [43], who used conformal mapping techniques to prove the following inequality for simply connected planar sets:

$$P(\Omega)\sigma_1(\Omega) \leq P(B)\sigma_1(B),$$

where $P(\Omega)$ stands for the perimeter of Ω and B a unit ball.

Recently, A. Fraser and R. Schoen proved in [23] that the ball does not maximize the first nonzero Steklov eigenvalue among all contractible domains of fixed boundary measure in \mathbb{R}^n for $n \geq 3$. The proof was inspired from the following formula for the annulus:

$$P(B \setminus \varepsilon B)^{\frac{1}{n-1}} \sigma_1(B \setminus \varepsilon B) = P(B)^{\frac{1}{n-1}} \sigma_1(B) + \frac{1}{n-1} \varepsilon^{n-1} + o(\varepsilon^{n-1}) > P(B)^{\frac{1}{n-1}} \sigma_1(B),$$

where $\varepsilon B = \{\varepsilon x \mid x \in B\}$.

Note that by studying the variations of the function $\varepsilon \in [0, 1] \mapsto P(B \setminus \varepsilon B)^{\frac{1}{n-1}} \sigma_1(B \setminus \varepsilon B)$ one can prove that there exists a unique $\varepsilon_n \in (0, 1)$ such that:

$$\forall \varepsilon \in [0, 1), \quad P(B \setminus \varepsilon B)^{\frac{1}{n-1}} \sigma_1(B \setminus \varepsilon B) \leq P(B \setminus \varepsilon_n B)^{\frac{1}{n-1}} \sigma_1(B \setminus \varepsilon_n B)$$

This motivates to look at the problem of maximizing σ_1 among domains with holes and wondering if the spherical shell $B \setminus \varepsilon_n B$ maximizes σ_1 under perimeter constraint among some class of perforated domains, for example the doubly connected ones. Not long ago, L. R. Quinones used shape derivatives to prove that the annulus $B \setminus \varepsilon_2 B$ is a critical shape of the first non-trivial Steklov eigenvalue among planar doubly connected domains with fixed perimeter (see [38]).

At last, we mention that in contrast with the result in [23], it was recently proven in [11] that the Weinstock inequality is true in higher dimensions in the case of convex sets. Namely, the authors show that for every bounded convex set $\Omega \subset \mathbb{R}^n$ one has:

$$P(\Omega)^{\frac{1}{n-1}} \sigma_1(\Omega) \leq P(B)^{\frac{1}{n-1}} \sigma_1(B).$$

A natural question arises: can we remove the topological constraints (convexity or simple connectedness in the plane) as for the Laplacian eigenvalues with other boundary conditions? Does there exist a

domain which maximizes σ_1 under perimeter constraint? If not can we determine the supremum of σ_1 on Lipschitz open sets? In fact, all these questions are still open and the techniques used to deal with other eigenvalues problems don't apply for Steklov framework, this pushes to seek new methods and makes the problem very challenging.

1.2. Perforated domains: state of the art

The optimization of the placement of obstacles has interested many authors in the last decades. We briefly point out some classical and recent works in the topic.

Some early results, due to Payne and Weinberger [37] on the one hand and Hersch [31] on the other, are that for some extremum eigenvalue problems with mixed boundary conditions a certain annulus is the optimal set among multi-connected planar domains, i.e. whose boundary admits more than one component (see also [8]). The main ideas consist in constructing judicious test functions by using the notion of web-functions (see [14] for more details on web functions). These ideas were very recently used and adapted for other similar problems (see [5, 36]). A classical family of obstacle problems that attracted a lot of attention was to find the best emplacement of a spherical hole inside a ball that optimizes the value of a given spectral functional (see [6], section (9)). An early result in this direction is that the first Dirichlet eigenvalue is maximal when the spherical obstacle is in the center of the larger ball. The proof is based on shape derivatives (see Theorem 2.5.1 [29]) and on a reflection and domain monotonicity arguments, followed by the use of the boundary maximum principle. These arguments have been applied in greater generality by many authors: in [39] Ramm and Shivakumar proved this result in dimension 2, in [32] Kesavan gave a generalization to higher dimensions and showed a similar result for the Dirichlet energy, then Harrell, Kröger, and Kurata managed in [28] to replace the exterior ball by a convex set which is symmetric with respect to a given hyperplane. In the same spirit, El Soufi and Kiwan proved in [18] that the second Dirichlet eigenvalue is also maximal when the balls are concentric. Furthermore, many authors considered mixed boundary conditions problems, for instance in [1], while studying the internal stabilizability for a reaction–diffusion problem modeling a predator–prey system, the authors are led to consider an obstacle shape optimization problem for the first laplacian eigenvalue with mixed Dirichlet-Neumann boundary conditions. Another interesting work in the same direction is due to Bonder, Groisman and Rossi, who studied the so called Sobolev trace inequality (see [9, 19]), thus they were interested in the optimization of the first nontrivial eigenvalue of an elliptic operator with mixed Steklov-Dirichlet boundary conditions among perforated domains: the existence and regularity of an optimal hole are proved in [21, 22], and by using shape derivatives it is shown that annulus is a critical but not an optimum shape (see [21]). At last, we point out the recent paper [41], where the author considers the first eigenvalue of the Laplace operator with mixed Steklov-Dirichlet boundary conditions.

Many examples stated in the last paragraph deal with linear operators eigenvalues in the special case of doubly connected domains with spherical outer and inner boundaries. The question we are treating in this paper belongs to this family of problems. Yet, it is also natural to seek for generalizations and the literature is quite rich of works treating more general cases: for results on linear operators with more general shapes of the domain and the obstacle in the euclidean case we refer to [16, 17, 24, 30, 33], on the other hand, many results for manifolds were obtained by Anisa and Aithal [3] in the setting of space-forms (complete simply connected Riemannian manifolds of constant sectional curvature), by Anisa and Vemuri [13] in the setting of rank 1 symmetric spaces of non-compact type and by Aithal and Raut [2] in the case of punctured regular polygons in two dimensional space forms. As for the case of non-linear operators we refer to the interesting progress made for the p -Laplace operator (see [4, 12]).

1.3. Results of the paper

In this paper, we are interested in finding the optimal placement of a spherical obstacle in a given ball so that the first non-trivial Steklov eigenvalue is maximal.

Our main result is stated as follows:

Theorem 1. *Among all doubly connected domains of \mathbb{R}^n ($n \geq 2$) of the form $B_1 \setminus \overline{B_2}$, where B_1 and B_2 are open balls of fixed radii such that $\overline{B_2} \subset B_1$, the first non-trivial Steklov eigenvalue achieves its maximal value uniquely when the balls are concentric.*

In [41], the authors consider a mixed Steklov-Dirichlet eigenvalue problem. They prove that the first non-trivial eigenvalue is maximal when the balls are concentric in dimensions larger or equal than 3 (cf. Theorem 1 [41]) and remark that the planar case remains open (cf. Remark 2). We show that the ideas developed in this paper allow us to give an alternative and simpler proof of Theorem 1 [41]. Then we extend this result to the planar case.

Theorem 2. *Among all doubly connected domains of \mathbb{R}^n ($n \geq 2$) of the form $B_1 \setminus \overline{B_2}$, where B_1 and B_2 are open balls of fixed radii such that $\overline{B_2} \subset B_1$, the first non-trivial eigenvalue of the problem*

$$\begin{cases} \Delta u = 0 & \text{in } B_1 \setminus \overline{B_2}, \\ u = 0 & \text{on } \partial B_2, \\ \frac{\partial u}{\partial n} = \tau u & \text{on } \partial B_1, \end{cases}$$

achieves its maximal value uniquely when the balls are concentric.

This paper is organized in 3 parts. First, we give the proof of Theorem 1. Then we use the ideas developed in section 2 to give a new proof of Theorem 1 [41] and tackle the planar case which was up to our knowledge still open. Finally, the Appendix is devoted to the computation of the Steklov eigenvalues and eigenfunctions of the spherical shell and the determination of the first non-trivial Steklov eigenvalue (Theorem 3) via a monotonicity result (Lemma 3).

2. Proof of Theorem 1

By invariance with respect to rotations and translations and scaling properties of σ_1 , we can reformulate the problem as follows:

We assume that the obstacle B_2 is the open ball of radius $a \in (0, 1)$ centred at the origin 0 and $B_1 = y_d + B$, where B is the unit ball centred in 0, $y_d := (0, \dots, 0, d) \in \mathbb{R}^n$ and $d \in [0, 1 - a)$. What is the value of d such that $\sigma_1(B_1 \setminus \overline{B_2})$ is maximal ?

For every $d \in [0, 1 - a)$, we denote $\Omega_d := (y_d + B) \setminus aB$ (see Figure 1).

It is sufficient to prove that:

$$\forall d \in (0, 1 - a), \quad \sigma_1(\Omega_0) > \sigma_1(\Omega_d).$$

The proof is based on the following Proposition:

Proposition 1. *There exists a function $f_n \in H^1(\mathbb{R}^n \setminus \overline{B_2})$ satisfying:*

1. f_n is an eigenfunction associated to $\sigma_1(\Omega_0)$ and can be used as a test function in the variational definition of $\sigma_1(\Omega_d)$.
2. $\int_{\Omega_d} |\nabla f_n|^2 dx \leq \int_{\Omega_0} |\nabla f_n|^2 dx$, with equality if and only if $d = 0$.
3. $\int_{\partial \Omega_d} f_n^2 d\sigma \geq \int_{\partial \Omega_0} f_n^2 d\sigma$, with equality if and only if $d = 0$.

Using Proposition 1, we conclude as follows:

$$\forall d \in (0, 1 - a), \quad \sigma_1(\Omega_d) \leq \frac{\int_{\Omega_d} |\nabla f_n|^2 dx}{\int_{\partial \Omega_d} f_n^2 d\sigma} < \frac{\int_{\Omega_0} |\nabla f_n|^2 dx}{\int_{\partial \Omega_0} f_n^2 d\sigma} = \sigma_1(\Omega_0).$$

This proves Theorem 1.

2.1. Proof of the first assertion of Proposition 1

The first eigenvalue of the spherical shell Ω_0 is computed in Theorem 3. It is also proven that its multiplicity is equal to n and the corresponding eigenfunctions are:

$$\begin{aligned} u_n^i &: \mathbb{R}^n &\longrightarrow & \mathbb{R} \\ x = (x_1, \dots, x_n) &\longmapsto & x_i \left(1 + \frac{\mu_{\sigma,n}}{|x|^n} \right) \end{aligned}$$

Where $i \in \llbracket 1, n \rrbracket$ and $\mu_{\sigma,n} = \frac{1 - \sigma_1(\Omega_0)}{n + \sigma_1(\Omega_0) - 1}$.

Take $i \in \llbracket 1, n-1 \rrbracket$. Since Ω_d is symmetrical to the hyperplane $\{x_i = 0\}$, we have:

$$\begin{aligned} \int_{\partial\Omega_d} u_n^i d\sigma &= \int_{\partial\Omega_d \cap \{x_i \geq 0\}} u_n^i d\sigma + \int_{\partial\Omega_d \cap \{x_i \leq 0\}} u_n^i d\sigma, \\ &= \int_{\partial\Omega_d \cap \{x_i \geq 0\}} u_n^i d\sigma - \int_{\partial\Omega_d \cap \{x_i \geq 0\}} u_n^i d\sigma \quad (\text{because } u_n^i(x_1, \dots, -x_i, \dots, x_n) = -u_n^i(x_1, \dots, x_i, \dots, x_n)) \\ &= 0. \end{aligned}$$

Thus, every eigenfunction u_n^i (where $i \in \llbracket 1, n-1 \rrbracket$) can be taken as a test function in the variational definition of $\sigma_1(\Omega_d)$ (note that this is not the case for u_n^n). This proves the first assertion of Proposition 1.

2.2. Spherical coordinates and preliminary computations

Since the shapes considered are described by spheres, it is more convenient to work with the spherical coordinates instead of the Cartesian ones.

We set:

$$\begin{cases} x_1 = r \sin \theta_1 \sin \theta_1 \dots \sin \theta_{n-2} \sin \theta_{n-1} \\ x_2 = r \sin \theta_1 \sin \theta_1 \dots \sin \theta_{n-2} \cos \theta_{n-1} \\ \vdots \\ x_{n-1} = r \sin \theta_1 \cos \theta_2 \\ x_n = r \cos \theta_1 \end{cases}$$

where $(r, \theta_1, \dots, \theta_{n-1}) \in \mathbb{R}^+ \times [0, \pi] \times \dots \times [0, \pi] \times [0, 2\pi]$.

Since, every eigenfunction u_n^i (where $i \in \llbracket 1, n-1 \rrbracket$) can be used as a test function in the variational definition of $\sigma_1(\Omega_d)$, we chose to take $f_n = u_n^{n-1}$ (see Remark 1).

Using spherical coordinates, we write:

$$\begin{aligned} f_2 &: \mathbb{R}_+ \times [0, 2\pi] &\longrightarrow & \mathbb{R} \\ (r, \theta_1) &\longmapsto & \sin \theta_1 \left(r + \frac{\mu_{\sigma,n}}{r} \right), \end{aligned}$$

and for $n \geq 3$:

$$\begin{aligned} f_n &: \mathbb{R}_+ \times [0, \pi] \times \dots \times [0, \pi] \times [0, 2\pi] &\longrightarrow & \mathbb{R} \\ (r, \theta_1, \dots, \theta_{n-1}) &\longmapsto & \sin \theta_1 \cos \theta_2 \left(r + \frac{\mu_{\sigma,n}}{r^{n-1}} \right) \end{aligned}$$

Remark 1. The choice of the test function $f_n = u_n^{n-1}$ between all u_n^i ($i \in \llbracket 1, n-1 \rrbracket$) is motivated by the will to have less variables to deal with while computing the gradient (see section 2.3). Nevertheless, one should note that all these functions satisfy the three assertions of Proposition 1.

The following figure shows the perforated domains Ω_0 and Ω_d , the angle θ_1 and the radius $R_d(\theta_1)$ which plays an important role in the upcoming computations.

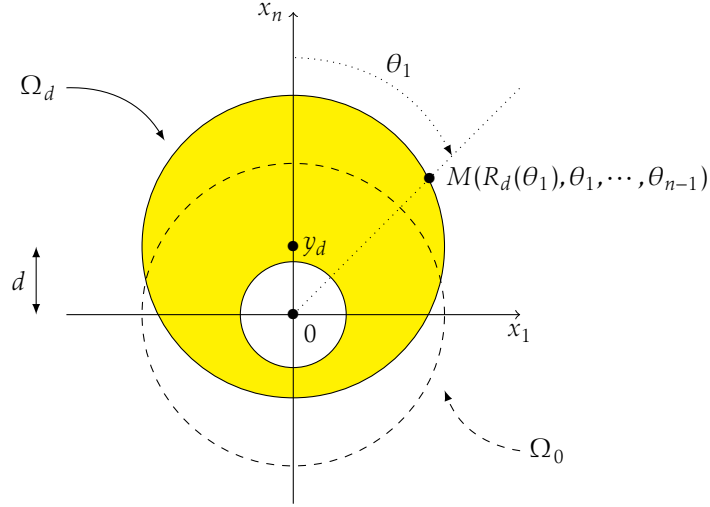


Figure 1: The domains Ω_d and Ω_0

Let $M \in \partial(y_d + B)$, by using Al-Kashi's formula on the triangle $0y_dM$, we have:

$$1^2 = d^2 + R_d^2(\theta_1) - 2dR_d(\theta_1)\cos\theta_1$$

By solving the equation of second degree satisfied by $R_d(\theta_1)$ we get two roots $d\cos\theta_1 \pm \sqrt{1 - d^2\sin^2\theta_1}$. The lower one being negative due to the fact that $d \in [0, 1)$, we deduce that:

$$R_d(\theta_1) = d\cos\theta_1 + \sqrt{1 - d^2\sin^2\theta_1}.$$

We compute the first derivative of R_d , which appears in the area element when integrating on $\partial\Omega_d$ (more precisely on $\partial(y_d + B)$).

$$R'_d(\theta_1) = -d\sin\theta_1 - \frac{d^2\sin\theta_1\cos\theta_1}{\sqrt{1 - d^2\sin^2\theta_1}} = -\frac{d\sin\theta_1}{\sqrt{1 - d^2\sin^2\theta_1}} \times (d\cos\theta_1 + \sqrt{1 - d^2\sin^2\theta_1}).$$

With straightforward computations, we get the important equalities:

$$\sqrt{R_d^2(\theta_1) + R'_d{}^2(\theta_1)} = 1 + \frac{d\cos\theta_1}{\sqrt{1 - d^2\sin^2\theta_1}} = \frac{R_d(\theta_1)}{\sqrt{1 - d^2\sin^2\theta_1}}. \quad (2)$$

2.3. Proof of the second assertion of Proposition 1

We compute the gradient of f_n in the spherical coordinates and calculate the L^2 -norm of its gradient on Ω_d .

For $n = 2$, we have:

$$\nabla f_2(r, \theta_1) = \begin{bmatrix} \frac{\partial f}{\partial r} \\ \frac{1}{r} \frac{\partial f}{\partial \theta_1} \end{bmatrix} = \begin{bmatrix} \sin\theta_1 \left(1 - \frac{\mu_{\sigma,n}}{r^2} \right) \\ \cos\theta_1 \left(1 + \frac{\mu_{\sigma,n}}{r^2} \right) \end{bmatrix}$$

then:

$$\begin{aligned}
\int_{\Omega_d} |\nabla f_2|^2 dx &= \int_{\theta_1=0}^{2\pi} \int_{r=a}^{R_d(\theta_1)} \left[\sin^2 \theta_1 \left(1 - \frac{\mu_{\sigma,2}}{r^2}\right)^2 + \sin^2 \theta_1 \left(1 - \frac{\mu_{\sigma,2}}{r^2}\right)^2 \right] r dr d\theta_1, \\
&= \int_{\theta_1=0}^{2\pi} \int_{r=a}^{R_d(\theta_1)} \left[r + 2\mu_{\sigma,2} (\cos^2 \theta_1 - \sin^2 \theta_1) \frac{1}{r} + \frac{\mu_{\sigma,2}^2}{r^3} \right] dr d\theta_1, \\
&= \int_{\theta_1=0}^{2\pi} \left(\frac{R_d^2(\theta_1) - a^2}{2} - 2\mu_{\sigma,2} (\cos^2 \theta_1 - \sin^2 \theta_1) \ln R_d(\theta_1) - \frac{\mu_{\sigma,2}^2}{2} \times \left(\frac{1}{R_d^2(\theta_1)} - \frac{1}{a^2} \right) \right) d\theta_1
\end{aligned}$$

In the same spirit, for $n \geq 3$, we have:

$$\nabla f_n(r, \theta_1, \dots, \theta_{n-1}) = \begin{bmatrix} \frac{\partial f}{\partial r} \\ \frac{1}{r} \frac{\partial f}{\partial \theta_1} \\ \frac{1}{r \sin \theta_1} \frac{\partial f}{\partial \theta_2} \\ \frac{1}{r \sin \theta_1 \sin \theta_2} \frac{\partial f}{\partial \theta_3} \\ \vdots \\ \frac{1}{r \sin \theta_1 \dots \sin \theta_{n-2}} \frac{\partial f}{\partial \theta_{n-1}} \end{bmatrix} = \begin{bmatrix} \sin \theta_1 \cos \theta_2 \left(1 - \frac{(n-1)\mu_{\sigma,n}}{r^n}\right) \\ \cos \theta_1 \cos \theta_2 \left(1 + \frac{\mu_{\sigma,n}}{r^n}\right) \\ -\sin \theta_2 \left(1 + \frac{\mu_{\sigma,n}}{r^n}\right) \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

For $p \in \mathbb{N}$, we introduce $I_p := \int_0^\pi \sin^p t dt$, which is the double of the classical Wallis integral. These integrals satisfy the essential recursive property:

$$\forall p \in \mathbb{N}, \quad I_{p+2} = \frac{p+1}{p+2} I_p. \quad (3)$$

Remark 2. Since $I_0 = \pi$ and $I_1 = 2$, one can use the recursive property (3) to compute the values of all other I_k (for $k \in \mathbb{N}$).

We get:

$$\forall k \in \mathbb{N}, \quad \begin{cases} I_{2k} = \pi \frac{(2k)!}{(2^k k!)^2} = \frac{\pi}{2^{2k}} \binom{2k}{k} \\ I_{2k+1} = 2 \times \frac{(2^k k!)^2}{(2k+1)!} \end{cases} \quad (4)$$

We compute:

$$\begin{aligned}
A_1^n(d) &= \int_{\partial B_d} [\nabla f_n]_1^2 dx \\
&= 2 \int_{\theta_1=0}^\pi \dots \int_{\theta_{n-1}=0}^\pi \int_{r=a}^{R_d(\theta_1)} \sin^2 \theta_1 \cos^2 \theta_2 \left(1 - \frac{(n-1)\mu_{\sigma,n}}{r^n}\right)^2 r^{n-1} \times \prod_{i=1}^{n-2} \sin^{n-1-i} \theta_i dr d\theta_1 \dots d\theta_{n-1} \\
&= 2 \left(\prod_{k=0}^{n-4} I_k \right) \int_{\theta_2=0}^\pi \cos^2 \theta_2 \sin^{n-3} \theta_2 d\theta_2 \int_{\theta_1=0}^\pi \sin^n \theta_1 \int_{r=a}^{R_d(\theta_1)} \left(r^{n-1} - \frac{2(n-1)\mu_{\sigma,n}}{r} + \frac{(n-1)^2 \mu_{\sigma,n}^2}{r^{n+1}} \right) dr d\theta_1 \\
&= 2 \left(\prod_{k=0}^{n-4} I_k \right) (I_{n-3} - I_{n-1}) \times \int_{\theta_1=0}^\pi \sin^n \theta_1 \left(\frac{R_d^n(\theta_1) - a^n}{n} - 2(n-1)\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{(n-1)^2 \mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1 \\
&= \frac{2}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \times \int_{\theta_1=0}^\pi \sin^n \theta_1 \left(\frac{R_d^n(\theta_1) - a^n}{n} - 2(n-1)\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{(n-1)^2 \mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1,
\end{aligned}$$

where we used (3) for the last equality.

$$\begin{aligned}
A_2^n(d) &= \int_{\partial B_d} [\nabla f_n]_2^2 dx, \\
&= 2 \left(\prod_{k=0}^{n-4} I_k \right) (I_{n-3} - I_{n-1}) \times \int_{\theta_1=0}^{\pi} \cos^2 \theta_1 \sin^{n-2} \theta_1 \left(\frac{R_d^n(\theta_1) - a^n}{n} + 2\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{\mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1, \\
&= \frac{2}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \times \int_{\theta_1=0}^{\pi} (\sin^{n-2} \theta_1 - \sin^n \theta_1) \left(\frac{R_d^n(\theta_1) - a^n}{n} + 2\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{\mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1,
\end{aligned}$$

then:

$$\begin{aligned}
A_3^n(d) &= \int_{\partial B_d} [\nabla f_n]_3^2 dx \\
&= 2 \left(\prod_{k=0}^{n-4} I_k \right) I_{n-1} \times \int_{\theta_1=0}^{\pi} \sin^{n-2} \theta_1 \left(\frac{R_d^n(\theta_1) - a^n}{n} + 2\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{\mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1, \\
&= \frac{2(n-2)}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \times \int_{\theta_1=0}^{\pi} \sin^{n-2} \theta_1 \left(\frac{R_d^n(\theta_1) - a^n}{n} + 2\mu_{\sigma,n} \ln \left(\frac{R_d(\theta_1)}{a} \right) - \frac{\mu_{\sigma,n}^2}{n} \times \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) \right) d\theta_1.
\end{aligned}$$

We decompose the integral in three parts:

$$\int_{\Omega_d} |\nabla f|^2 dx = A_1^n(d) + A_2^n(d) + A_3^n(d) = \frac{2}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \left((n-1)W_1^n(d) + 2\mu_{\sigma,n}W_2^n(d) - \frac{\mu_{\sigma,n}^2}{n}W_3^n(d) \right), \quad (5)$$

where:

$$\begin{cases}
W_1^n(d) = \int_0^{\pi} \sin^{n-2} \theta_1 (R_d^n(\theta_1) - a^n) d\theta_1 \\
W_2^n(d) = \int_0^{\pi} \phi_n(\theta_1) \ln \left(\frac{R_d(\theta_1)}{a} \right) d\theta_1, \quad \text{with: } \phi_n(\theta_1) = -n \sin^n \theta_1 + (n-1) \sin^{n-2} \theta_1 \\
W_3^n(d) = \int_0^{\pi} \psi_n(\theta_1) \left(\frac{1}{R_d^n(\theta_1)} - \frac{1}{a^n} \right) d\theta_1, \quad \text{with: } \psi_n(\theta_1) = n(n-2) \sin^n \theta_1 + (n-1) \sin^{n-2} \theta_1 \geq 0
\end{cases}$$

Note that the equality (5) applies also for the planar case. From now on, we take $n \geq 2$.

In the following Lemma, we study $W_k^n(d)$ for each $k \in \{1, 2, 3\}$.

Lemma 1. For every $n \geq 2$ and every $d \in [0, 1-a]$:

1. $W_1^n(d) = W_1^n(0)$.
2. $W_2^n(d) = 0$.
3. $W_3^n(d) \geq W_3^n(0)$, with equality if and only if $d = 0$.

Proof. 1. The idea is to see that the quantities $W_1^n(0)$ and $W_1^n(d)$ can be interpreted (up to a multiplicative constant) as volumes of the unit balls B and $y_d + B$ in \mathbb{R}^n . Then, since the measure is invariant by translations, we get the equality.

We have:

$$\begin{aligned}
W_1^n(d) &= \int_0^\pi \sin^{n-2} \theta_1 (R_d^n(\theta_1) - a^n) d\theta_1 \\
&= \frac{n}{\prod_{k=0}^{n-3} I_k} \times 2 \int_{\theta_1=0}^\pi \dots \int_{\theta_{n-1}=0}^\pi \int_{r=a}^{R_d(\theta_1)} 1 \times r^{n-1} \prod_{i=1}^{n-2} \sin^{n-1-i} \theta_i dr d\theta_1 \dots d\theta_{n-1} \\
&= \frac{n}{\prod_{k=0}^{n-3} I_k} \times |\Omega_d| = \frac{n}{\prod_{k=0}^{n-3} I_k} \times (|y_d + B| - |aB|) = \frac{n}{\prod_{k=0}^{n-3} I_k} \times (|B| - |aB|) \\
&= \frac{n}{\prod_{k=0}^{n-3} I_k} \times 2 \int_{\theta_1=0}^\pi \dots \int_{\theta_{n-1}=0}^\pi \int_{r=a}^1 1 \times r^{n-1} \prod_{i=1}^{n-2} \sin^{n-1-i} \theta_i dr d\theta_1 \dots d\theta_{n-1} \\
&= W_1^n(0).
\end{aligned}$$

2. We remark that for every $\theta_1 \in (0, \pi)$ one has $\phi_n(\pi - \theta_1) = \phi_n(\theta_1)$, thus:

$$\begin{aligned}
W_2(d) &= \int_0^{\frac{\pi}{2}} \phi_n(\theta_1) \ln\left(\frac{R_d(\theta_1)}{a}\right) d\theta_1 + \int_{\frac{\pi}{2}}^\pi \phi_n(\theta_1) \ln\left(\frac{R_d(\theta_1)}{a}\right) d\theta_1 \\
&= \int_0^{\frac{\pi}{2}} \phi_n(\theta_1) \ln\left(\frac{d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1}}{a}\right) d\theta_1 + \int_0^{\frac{\pi}{2}} \phi_n(\theta_1) \ln\left(\frac{-d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1}}{a}\right) d\theta_1 \\
&= \int_0^{\frac{\pi}{2}} \phi_n(\theta_1) \ln\left(\frac{(d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1}) \times (-d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1})}{a^2}\right) d\theta_1 \\
&= \ln\left(\frac{1-d^2}{a^2}\right) \times \int_0^{\frac{\pi}{2}} \phi_n(\theta_1) d\theta_1 = \ln\left(\frac{1-d^2}{a^2}\right) \times \int_0^{\frac{\pi}{2}} (-n \sin^n \theta_1 + (n-1) \sin^{n-2} \theta_1) d\theta_1 \\
&= \frac{1}{2} \ln\left(\frac{1-d^2}{a^2}\right) \times (-nI_n + (n-1)I_{n-2}) = 0 \quad (\text{by (3)})
\end{aligned}$$

3. We have:

$$\begin{aligned}
W_3(d) &= \int_{\theta_1=0}^\pi \psi_n(\theta_1) \left(\frac{1}{(d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1})^n} - \frac{1}{a^n} \right) d\theta_1 \\
&\geq \int_{\theta_1=0}^\pi \psi_n(\theta_1) \left(\frac{1}{(d \cos \theta_1 + 1)^n} - \frac{1}{a^n} \right) d\theta_1 =: G(d) \geq G(0) = W_3(0)
\end{aligned}$$

Inequality $G(d) \geq G(0)$ is a consequence of the monotonicity of the function G and equality occurs if and only if $d = 0$. Indeed for every $d \in (0, 1-a)$:

$$\begin{aligned}
G'(d) &= \int_0^\pi -n\psi_n(\theta_1) \frac{\cos \theta_1}{(d \cos \theta_1 + 1)^{n+1}} d\theta_1 \\
&= \int_0^{\frac{\pi}{2}} -n\psi_n(\theta_1) \frac{\cos \theta_1}{(d \cos \theta_1 + 1)^{n+1}} d\theta_1 + \int_{\theta_1=\frac{\pi}{2}}^\pi -n\psi_n(\theta_1) \frac{\cos \theta_1}{(d \cos \theta_1 + 1)^{n+1}} d\theta_1 \\
&= n \int_0^{\frac{\pi}{2}} \psi_n(\theta_1) \cos \theta_1 \left(\frac{1}{(1-d \cos \theta_1)^{n+1}} - \frac{1}{(1+d \cos \theta_1)^{n+1}} \right) d\theta_1 \\
&> 0 \quad (\text{because } \forall \theta_1 \in (0, \pi/2), \quad \psi_n(\theta_1) \cos \theta_1 > 0 \quad \text{and} \quad (1+d \cos \theta_1)^{n+1} > (1-d \cos \theta_1)^{n+1})
\end{aligned}$$

□

Using the results of Lemma 1, we get:

$$\begin{aligned} \int_{\Omega_d} |\nabla f|^2 dx &= \frac{2}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \left((n-1)W_1^n(d) + 2\mu_{\sigma,n}W_2^n(d) - \frac{\mu_{\sigma,n}^2}{n}W_3^n(d) \right) \\ &\leq \frac{2}{n-1} \left(\prod_{k=0}^{n-3} I_k \right) \left((n-1)W_1^n(0) + 2\mu_{\sigma,n}W_2^n(0) - \frac{\mu_{\sigma,n}^2}{n}W_3^n(0) \right) = \int_{\Omega_0} |\nabla f|^2 dx, \end{aligned}$$

with equality if and only if $d = 0$. This proves the second assertion of Proposition 1.

2.4. Proof of the third assertion of Proposition 1

Take $n \geq 2$, we have:

$$\begin{aligned} \int_{\partial(y_d+B)} f^2 d\sigma &= 2 \int_{\theta_1=0}^{\pi} \dots \int_{\theta_{n-2}=0}^{\pi} \int_{\theta_{n-1}=0}^{\pi} f_n^2(r, \theta_1, \dots, \theta_{n-1}) \times R_d^{n-2}(\theta_1) \prod_{i=1}^{n-2} \sin^{n-1-i} \theta_i \times \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \dots d\theta_{n-1} \\ &= \left(2 \prod_{k=2}^{n-1} I_k \right) \int_0^{\pi} \left(R_d(\theta_1) + \frac{\mu_{\sigma,n}}{R_d^{n-1}(\theta_1)} \right)^2 \times R_d^{n-2}(\theta_1) \sin^n \theta_1 \times \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \\ &= \left(2 \prod_{k=2}^{n-1} I_k \right) \int_0^{\pi} \left(R_d^n(\theta_1) + 2\mu_{\sigma,n} + \frac{\mu_{\sigma,n}^2}{R_d^n(\theta_1)} \right) \sin^n \theta_1 \times \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \\ &= \left(2 \prod_{k=2}^{n-1} I_k \right) \times \left(V_1^n(d) + 2\mu_{\sigma,n}(I_n + V_2^n(d)) + \mu_{\sigma,n}^2 V_3^n(d) \right) \end{aligned}$$

where:

$$\begin{cases} V_1^n(d) = \int_0^{\pi} \sin^n \theta_1 R_d^n(\theta_1) \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \\ V_2^n(d) = \int_0^{\pi} \sin^n \theta_1 \frac{d \cos \theta_1}{\sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 \quad (\text{by using (2)}) \\ V_3^n(d) = \int_0^{\pi} \frac{\sin^n \theta_1}{R_d^{n-1}(\theta_1) \sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 \quad (\text{by using (2)}) \end{cases}$$

Let us now prove the following Lemma:

Lemma 2. For every $n \geq 1$ and every $d \in [0, 1-a]$:

1. $V_1^n(d) = V_1^n(0)$.
2. $V_2^n(d) = 0$.
3. $V_3^n(d) \geq V_3^n(0)$, with equality if and only if $d = 0$.

Proof. 1. Take B the unit ball of \mathbb{R}^{n+2} centred in 0 and $y_d = (0, \dots, 0, d) \in \mathbb{R}^{n+2}$.

In the same spirit of the proof of the assertion 1 of Lemma 1, the idea is to see that the quantities $V_1^n(0)$ and $V_1^n(d)$ can be interpreted (up to a multiplicative constant) as perimeters of B and $y_d + B$. Then, since the perimeter is invariant by translations we get the equality.

We have:

$$\begin{aligned} V_1^n(d) &= \int_0^{\pi} \sin^n \theta_1 R_d^n(\theta_1) \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \\ &= \frac{1}{2 \prod_{k=0}^{n-1} I_k} \times 2 \int_{\theta_1=0}^{\pi} \dots \int_{\theta_{n+1}=0}^{\pi} 1 \times R_d^n(\theta_1) \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} \prod_{i=1}^n \sin^{n+1-i} \theta_i d\theta_1 \dots d\theta_{n+1} \\ &= \frac{1}{2 \prod_{k=0}^{n-1} I_k} \times P(y_d + B) = \frac{1}{2 \prod_{k=0}^{n-1} I_k} \times P(B) = V_1^n(0) \end{aligned}$$

2. We compute:

$$\begin{aligned}
V_2^n(d) &= \int_0^{\frac{\pi}{2}} \sin^n \theta_1 \frac{d \cos \theta_1}{\sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 + \int_{\frac{\pi}{2}}^{\pi} \sin^n \theta_1 \frac{d \cos \theta_1}{\sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 \\
&= \int_0^{\frac{\pi}{2}} \sin^n \theta_1 \frac{d \cos \theta_1}{\sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 - \int_0^{\frac{\pi}{2}} \sin^n t \frac{d \cos t}{\sqrt{1-d^2 \sin^2 t}} dt \\
&= 0
\end{aligned}$$

3. We have:

$$\begin{aligned}
V_3^n(d) &= \int_0^{\pi} \frac{\sin^n \theta_1}{\left(d \cos \theta_1 + \sqrt{1-d^2 \sin^2 \theta_1}\right)^{n-1} \sqrt{1-d^2 \sin^2 \theta_1}} d\theta_1 \\
&\geq \int_0^{\pi} \frac{\sin^n \theta_1}{\left(d \cos \theta_1 + 1\right)^{n-1}} d\theta_1 =: H(d) \geq H(0) = V_3^n(0).
\end{aligned}$$

Inequality $H(d) \geq H(0)$ follows from the monotonicity of H and is an equality if and only if $d = 0$. This can be proven with the same method used for G in the previous section. \square

Using the results of Lemma 2, we get:

$$\begin{aligned}
\int_{\partial\Omega_d} f^2 d\sigma &= \left(2 \prod_{k=2}^{n-1} I_k\right) \times \left(V_1^n(d) + 2\mu_{\sigma,n}(I_n + V_2^n(d)) + \mu_{\sigma,n}^2 V_3^n(d)\right) + \int_{\partial(aB)} f^2 d\sigma \\
&\geq \left(2 \prod_{k=2}^{n-1} I_k\right) \times \left(V_1^n(0) + 2\mu_{\sigma,n}(I_n + V_2^n(0)) + \mu_{\sigma,n}^2 V_3^n(0)\right) + \int_{\partial(aB)} f^2 d\sigma \\
&= \int_{\partial\Omega_0} f^2 d\sigma.
\end{aligned}$$

which proofs the third assertion of Proposition 1.

3. The Dirichlet-Steklov problem

In this section, we show that the ideas of our proof in section 2 also apply to the problem considered in [41]. Thus, we give an alternative proof of Theorem 1 [41] which deals with $n \geq 3$ and tackle the planar case which was to our knowledge still open (Remark 2 [41]).

Let $n \geq 2$ and B_1 be an open ball in \mathbb{R}^n and B_2 be an open ball contained in B_1 . We are interested in the eigenvalue problem

$$\begin{cases} \Delta u = 0 & \text{in } B_1 \setminus \overline{B_2}, \\ u = 0 & \text{on } \partial B_2, \\ \frac{\partial u}{\partial n} = \tau u & \text{on } \partial B_1, \end{cases}$$

The first eigenvalue of $B_1 \setminus \overline{B_2}$ is given by the following Rayleigh quotient:

$$\tau_1(B_1 \setminus \overline{B_2}) = \inf \left\{ \frac{\int_{B_1 \setminus \overline{B_2}} |\nabla u|^2 dx}{\int_{\partial B_1} u^2 d\sigma} \mid u \in H^1(\Omega) \setminus \{0\} \text{ such that } u = 0 \text{ on } \partial B_2 \right\}$$

As stated in Theorem 2, the eigenvalue τ_1 is maximal when the balls are concentric. As for the case of pure Steklov boundary condition, we can assume without loss of generality that the obstacle B_2 is the open ball

of radius $a \in (0, 1)$ centred at the origin 0 and $B_1 = y_d + B$, where B is the unit ball centred in 0. We use the notations introduced in section 2.

Using separation of variables S. Verma and G. Santhanam proved that the first eigenfunction g_n of the spherical shell Ω_0 is given by:

$$g_n(r, \theta_1, \dots, \theta_{n-1}) = \begin{cases} \ln r - \ln a & \text{if } n=2 \\ \left(\frac{1}{a^{n-2}} - \frac{1}{r^{n-2}}\right) & \text{if } n \geq 3 \end{cases}$$

3.1. A key proposition

Here also, Theorem 2 is an immediate consequence of the following proposition:

Proposition 2. *Let $n \geq 2$, we have:*

1. g_n can be used as a test function in the variational definition of $\tau_1(\Omega_d)$.
2. $\int_{\Omega_d} |\nabla g_n|^2 dx \leq \int_{\Omega_0} |\nabla g_n|^2 dx$.
3. $\int_{\partial(y_d+B)} g_n^2 d\sigma \geq \int_{\partial B} g_n^2 d\sigma$, with equality if and only if $d = 0$.

Proof. This proposition has been proved in [41] for the case $n \geq 3$.

The first assertion is obvious since $g_n(a, \theta_1, \dots, \theta_{n-1}) = 0$.

As for the second, it has been remarked in [41] page 13, the inequality $\int_{\Omega_d} |\nabla g_n|^2 dx \leq \int_{\Omega_0} |\nabla g_n|^2 dx$ is a straightforward consequence of the monotonicity of $r \mapsto \frac{\partial g_n}{\partial r}$. Unfortunately, this is not the case for the inequality on the boundary (assertion 3) for which the author needs more computations (see [41] section 2.2).

First, we show that Lemma 2 allows us to give an alternative and simpler proof of the last inequality in the case $n \geq 3$, then we prove it in the planar case $n = 2$.

If $n \geq 3$, we have:

$$\begin{aligned} \int_{\partial(y_d+B)} g_n^2 d\sigma &= \left(2 \prod_{j=2}^{n-3} I_j\right) \int_0^\pi \left(\frac{1}{a^{n-2}} - \frac{1}{R_d^{n-2}(\theta_1)}\right)^2 R_d^{n-2}(\theta_1) \sin^{n-2} \theta_1 \sqrt{R_d^2(\theta_1) + R_d'^2(\theta_1)} d\theta_1 \\ &= \left(2 \prod_{j=2}^{n-3} I_j\right) \left(\frac{1}{a^{2n-4}} V_1^{n-2}(d) - \frac{2}{a^{n-2}} (I_{n-2} + V_2^{n-2}(d)) + V_3^{n-2}(d)\right) \\ &\geq \left(2 \prod_{j=2}^{n-3} I_j\right) \left(\frac{1}{a^{2n-4}} V_1^{n-2}(0) - \frac{2}{a^{n-2}} (I_{n-2} + V_2^{n-2}(0)) + V_3^{n-2}(0)\right) = \int_{\partial B} g_n^2 d\sigma \end{aligned}$$

Now take $n = 2$. We use the following parameterization of the shifted sphere:

$$y_d + \partial B = \{M(t) = (\sin t, d + \cos t) \mid t \in [0, 2\pi)\}.$$

Note that: $|M(t)| = 1 + d^2 + 2d \cos t$. We have:

$$\begin{aligned} \int_{\partial(y_d+B)} g_2^2 d\sigma &= \int_0^{2\pi} (\ln(1 + d^2 + 2d \cos t) - \ln a)^2 dt \\ &= \int_0^{2\pi} \ln^2(1 + d^2 + 2d \cos t) dt - 2 \ln a \int_0^{2\pi} \ln(1 + d^2 + 2d \cos t) dt + 2\pi \ln^2 a \\ &\geq 2\pi \ln^2 a = \int_{\partial B} g_2^2 d\sigma, \end{aligned}$$

because:

$$\int_0^{2\pi} \ln^2(1 + d^2 + 2d \cos t) dt \geq 0 \quad \text{and} \quad \int_0^{2\pi} \ln(1 + d^2 + 2d \cos t) dt = 0.$$

Indeed, on the one hand the inequality is obvious and is an equality if and only if $d = 0$, on the other hand the second assertion is obtained by series expansion and the following classical identity (cf. (6) [35]):

$$\forall x \in \left(-\frac{1}{4}, \frac{1}{4}\right), \quad \sum_{n=1}^{+\infty} \frac{1}{n} \binom{2n}{n} x^n = 2 \ln \left(\frac{1 - \sqrt{1 - 4x}}{2x} \right) = 2 \ln \left(\frac{2}{1 + \sqrt{1 - 4x}} \right). \quad (6)$$

$$\begin{aligned} \int_0^{2\pi} \ln(1 + d^2 + 2d \cos t) dt &= \int_0^{2\pi} \ln(1 + d^2) dt + \int_0^{2\pi} \ln \left(1 + \frac{2d \cos t}{1 + d^2} \right) dt \\ &= 2\pi \ln(1 + d^2) + \int_0^{2\pi} \sum_{n=1}^{+\infty} \frac{(-1)^{n+1}}{n} \times \left(\frac{2d}{1 + d^2} \right)^n \cos^n t dt \\ &= 2\pi \ln(1 + d^2) + \sum_{n=1}^{+\infty} \frac{(-1)^{n+1}}{n} \times \left(\frac{2d}{1 + d^2} \right)^n \int_0^{2\pi} \cos^n t dt \\ &= 2\pi \ln(1 + d^2) - \pi \sum_{n=1}^{+\infty} \frac{1}{n} \binom{2n}{n} \times \left(\frac{d}{1 + d^2} \right)^{2n} \quad (\text{by (4), } \int_0^{2\pi} \cos^n t dt = 2I_{2n} = \frac{\pi}{2^{2n}} \binom{2n}{n}) \\ &= 0 \quad (\text{we took } x = \left(\frac{d}{1 + d^2} \right)^2 \text{ in (6)}). \end{aligned}$$

This ends the proof of the third assertion and the demonstration of Proposition 2. □

3.2. Proof of Theorem 2

Finally, we conclude as before:

$$\tau_1(\Omega_d) \leq \frac{\int_{\Omega_d} |\nabla g_n|^2 dx}{\int_{\partial(y_d+B)} g_n^2 d\sigma} \leq \frac{\int_{\Omega_0} |\nabla g_n|^2 dx}{\int_{\partial B} g_n^2 d\sigma} = \tau_1(\Omega_0),$$

with equality if and only if $d = 0$. This ends the proof of Theorem 2.

4. Appendix

In this appendix we compute the Steklov eigenvalues of the spherical shell $\Omega_0 = B \setminus aB \subset \mathbb{R}^n$, where $a \in (0, 1)$. We then prove a monotonicity result on these eigenvalues, which allows us to give the exact value of $\sigma_1(\Omega_0)$ and its corresponding eigenfunctions.

Theorem 3. *Let $n \geq 2$. The first non-trivial Steklov eigenvalue of the spherical shell $\Omega_0 = B \setminus aB \subset \mathbb{R}^n$ is:*

$$\sigma_1(\Omega_0) = \frac{(n+1)a^{n+1} + a^n + a + n - 1 - \sqrt{((n+1)a^{n+1} + a^n + a + n - 1)^2 - 4(n-1)a(1-a)^2}}{2a(1-a^n)}.$$

It is of multiplicity n and the corresponding eigenfunctions are:

$$u_n^i : \quad \mathbb{R}^n \quad \longrightarrow \quad \mathbb{R} \\ x = (x_1, \dots, x_n) \quad \longmapsto \quad x_i \left(1 + \frac{\mu_{\sigma,n}}{|x|^n} \right),$$

where $i \in \llbracket 1, n \rrbracket$ and $\mu_{\sigma,n} = \frac{1 - \sigma_1(\Omega_0)}{n + \sigma_1(\Omega_0) - 1}$.

Remark 3. Theorem 3 has already been proved for the planar case by B. Dittmar [15] (see also [27]). For higher dimensions, A. Fraser and R. Schoen [23] gave asymptotic formula for the lowest eigenvalues of spherical shells when the hole is vanishing. In this case, it is easy to identify the first eigenvalues (in particular the first one). Unfortunately, this is no longer the case when the hole is not vanishing as explained in sections 4.1 and 4.2.

4.1. Computation of the eigenvalues via classical separation of variables technique

Finding the eigenvalues and eigenfunctions of the Laplacian on special domains (balls, rectangles, annulus...) is a classical problem (see for example [26] Section 3). The standard method is to look for eigenfunctions via separation of variables and then prove that they form a complete basis of a convenient function space, this combined with orthogonality properties of the eigenfunctions shows that we didn't miss any.

Take $k \in \mathbb{N}$, let us search harmonic functions h_k of the form

$$h_k : \mathbb{R}_+ \times [0, \pi] \times \cdots \times [0, \pi] \times [0, 2\pi] \longrightarrow \mathbb{R} \\ (r, \theta_1, \dots, \theta_{n-1}) \longmapsto \alpha_k(r)\beta_k(\theta_1, \dots, \theta_{n-1})$$

where $\beta_k \in H_k^n$ is a spherical harmonic of order k and H_k^n is the set of restrictions of homogeneous harmonic polynomial of degree k with n variables on the unit sphere ∂B (for an introduction to harmonic polynomials we refer to [7] Chapter 5). It is well-known that the set H_k^n corresponds to the eigenspace of the Laplace-Beltrami operator $-\Delta_{\partial B}$ associated to the eigenvalue $k(k+n-1)$.

We have:

$$\Delta h_k = \left(\frac{\partial^2}{\partial r^2} + \frac{n-1}{r} \frac{\partial}{\partial r} + r^{-2} \Delta_{\partial B} \right) h_k = \left(\alpha_k''(r) + \frac{n-1}{r} \alpha_k'(r) - \frac{k(k+n-1)}{r^2} \alpha_k(r) \right) \beta_k(\theta_1, \dots, \theta_{n-1}).$$

The condition $\Delta h_k = 0$ implies that α_k must satisfy the differential equation:

$$\alpha_k''(r) + \frac{n-1}{r} \alpha_k'(r) - \frac{k(k+n-1)}{r^2} \alpha_k(r) = 0.$$

By standard methods of solving ODEs, the solutions of the last equation are given by:

$$\alpha_0(r) = \begin{cases} p_{0,2} + q_{0,2} \ln r & \text{if } n = 2 \\ p_{0,n} + \frac{q_{0,n}}{r^{n-2}} & \text{if } n \geq 3, \end{cases}$$

and for $k \geq 1$:

$$\alpha_k(r) = p_{k,n} r^k + \frac{q_{k,n}}{r^{k+n-2}},$$

where $p_{k,n}$ and $q_{k,n}$ are constants.

It remains to look for all possible values δ_k such that: $\frac{\partial h_k}{\partial n} = \delta_k h_k$ on $\partial \Omega_0$. This equality is equivalent to

$$\begin{cases} \alpha_k'(1) = \delta_k \alpha_k(1), \\ \alpha_k'(a) = \delta_k \alpha_k(a). \end{cases}$$

As explained in the proof of Proposition 3 of [23], those equalities imply that the possible eigenvalues δ_k are solutions of equations of second order.

When $k = 0$, we find two eigenvalues: 0 that corresponds to constant eigenfunctions and δ_0 that corresponds to a (non-constant) radial one.

$$\delta_0 = \begin{cases} \frac{1+a}{a \ln 1/a} & \text{if } n = 2 \\ \frac{(n-2)(1+a^{n-1})}{a(1-a^{n-2})} & \text{if } n \geq 3. \end{cases}$$

The corresponding (radial) eigenfunction is given by:

$$h_0(r, \theta_1, \dots, \theta_{n-1}) = \begin{cases} 1 + \delta_0 \ln r & \text{if } n = 2 \\ (2 - n - \delta_0) + \frac{\delta_0}{r^{n-2}} & \text{if } n \geq 3. \end{cases}$$

On the other hand, as mentioned in [23], when $k \geq 1$, one finds two eigenvalues $\delta_k^{(1)} < \delta_k^{(2)}$ corresponding to the solutions of the following equation:

$$A_k \delta^2 + B_k \delta + C_k = 0, \quad (7)$$

where:

$$\begin{cases} A_k = a - a^{2k+n-1}, \\ B_k = -\left((k+n-2)a^{2k+n-1} + ka^{2k+n-2} + ka + k + n - 2\right), \\ C_k = (k+n-2)k(1 - a^{2k+n-2}). \end{cases}$$

We compute the determinant Δ_k , and use the fact that $a \in (0, 1)$ to check that $\Delta_k > 0$:

$$\begin{aligned} \Delta_k &= B_k^2 - 4A_k \times C_k \\ &= \left[(k+n-2)a^{2k+n-1} + ka^{2k+n-2} + ka + k + n - 2 \right]^2 - (k+n-2)ka(1 - a^{2k+n-2})^2 \\ &\geq (k+n-2)^2 - (k+n-2)ka(1 - a^{2k+n-2})^2 \quad (\text{because } a \geq 0) \\ &\geq (k+n-2)\left[(k+n-2) - k\right] \quad (\text{because } 0 \leq a(1 - a^{2k+n-2})^2 \leq 1) \\ &= (k+n-2)(n-2) > 0. \end{aligned}$$

Then, the equation (7) admits two different positive solutions $\delta_k^{(1)} := \frac{-B_k - \sqrt{\Delta_k}}{2A_k} < \frac{-B_k + \sqrt{\Delta_k}}{2A_k} =: \delta_k^{(2)}$.

By straightforward computations, the corresponding eigenfunctions are given by:

$$h_k^{(i)}(r, \theta_1, \dots, \theta_{n-1}) = \left(r^k + \frac{k - \delta_k^{(i)}}{n + \delta_k^{(i)} + k - 2} \times \frac{1}{r^{k+n-2}} \right) Y_{k,j}(\theta_1, \dots, \theta_{n-1}), \quad (8)$$

where $Y_{k,j} \in H_k^n$ denotes the j -th ($j \in \llbracket 1, \dim H_k^n \rrbracket$) spherical harmonic of order k and $i \in \{1, 2\}$.

Thus, the multiplicity of $\delta_k^{(i)}$ is equal to

$$\dim H_k^n = \binom{n+k-1}{n-1} - \binom{n+k-3}{n-1}.$$

At last, by using expansions results for harmonic functions on annuli (see 9.17 [7] for $n = 2$ and 10.1 [7] for $n \geq 3$), we deduce that the eigenfunctions we found form a complete basis of the space of harmonic functions on the annulus Ω_0 .

It remains to determine the lowest eigenvalue between δ_0 and the $\delta_k^{(i)}$ for $k \in \mathbb{N}^*$ and $i \in \{1, 2\}$.

4.2. A monotonicity result

We state and prove the following key lemma, which combined with results of section 4.1 gives an immediate proof of Theorem 3.

Lemma 3. *We have:*

1. The sequence $(\delta_k^{(1)})_{k \geq 1}$ is strictly increasing.

2. $\sigma_1(\Omega_0) < \delta_0$.

Proof. The case $n = 2$ had been considered in [15, 27]. Let $n \geq 3$.

1. We have:

$$\delta_k^{(1)} = \frac{2C_k}{-B_k + \sqrt{B_k^2 - 4A_k \times C_k}} = \frac{2(k+n-2)k(1-a^{2k+n-2})}{-B_k + \sqrt{B_k^2 - 4(k+n-2)ka(1-a^{2k+n-2})^2}}.$$

The idea of proof is to write $\delta_k^{(1)} = P_k/Q_k$, where $(P_k)_k$ (resp. $(Q_k)_k$) is a positive increasing (resp. decreasing) sequence. Indeed, we can write:

$$\delta_k^{(1)} = \frac{2\sqrt{(k+n-2)k}(1-a^{2k+n-2})}{-\frac{B_k}{\sqrt{(k+n-2)k}} + \sqrt{\left(-\frac{B_k}{\sqrt{(k+n-2)k}}\right)^2 - 4a(1-a^{2k+n-2})^2}}$$

The sequences $(2\sqrt{(k+n-2)k}(1-a^{2k+n-2}))_k$ and $(a(1-a^{2k+n-2}))_k$ are strictly increasing. It remains to prove that the (positive) sequence $\left(-\frac{B_k}{\sqrt{(k+n-2)k}}\right)_{k \geq 1}$ is strictly decreasing.

We have:

$$\begin{aligned} -\frac{B_k}{\sqrt{(k+n-2)k}} &= \frac{(k+n-2)a^{2k+n-1} + ka^{2k+n-2} + ka + k + n - 2}{\sqrt{k}\sqrt{k+n-2}} \\ &= \frac{(k+n-2)(a^{2k+n-1} + 1) + ka(a^{2k+n-3} + 1)}{\sqrt{k}\sqrt{k+n-2}} \\ &= \sqrt{\frac{k+n-2}{k}}(a^{2k+n-1} + 1) + a\sqrt{\frac{k}{k+n-2}}(a^{2k+n-3} + 1). \end{aligned}$$

Let us introduce the function:

$$\begin{aligned} h_{a,n} : [1, +\infty[&\longrightarrow \mathbb{R} \\ t &\longmapsto \sqrt{\frac{t+n-2}{t}} \times (a^{2t+n-1} + 1) + a\sqrt{\frac{t}{t+n-2}} \times (a^{2t+n-3} + 1). \end{aligned}$$

we prove that $h_{a,n}$ is strictly decreasing. To do so, we compute the derivative $h'_{a,n}$ and prove that it is negative on $[1, +\infty[$.

We have for every $t \geq 1$:

$$\begin{aligned} h'_{a,n}(t) &= \frac{-\frac{n-2}{t^2}(a^{n+2t-1} + 1)}{2\sqrt{\frac{n+t-2}{t}}} + \frac{\frac{n-2}{(n+t-2)^2}a(a^{n+2t-3} + 1)}{2\sqrt{\frac{t}{n+t-2}}} \\ &\quad + 2\ln(a)\sqrt{\frac{t}{n+t-2}}a^{n+2t-2} + 2\ln(a)\sqrt{\frac{n+t-2}{t}}a^{n+2t-1} \\ &< \frac{-\frac{n-2}{t^2}(a^{n+2t-1} + 1)}{2\sqrt{\frac{n+t-2}{t}}} + \frac{\frac{n-2}{(n+t-2)^2}a(a^{n+2t-3} + 1)}{2\sqrt{\frac{t}{n+t-2}}} \quad (\text{because } \ln(a) < 0). \\ &= \frac{2(n-2)}{t(n+t-2)(a^{n+2t-1} + 1)}\sqrt{\frac{t}{n+t-2}} \times \left(a \times \frac{a^{n+2t-3} + 1}{a^{n+2t-1} + 1} - 1 - \frac{n-2}{t}\right) \\ &< \frac{2(n-2)}{t(n+t-2)(a^{n+2t-1} + 1)}\sqrt{\frac{t}{n+t-2}} \times \left(\frac{a^{n+2t-3} + 1}{a^{n+2t-1} + 1} - \frac{t+n-2}{t}\right) \quad (\text{because } a \in (0, 1)). \end{aligned}$$

We have:

$$\frac{a^{n+2t-3} + 1}{a^{n+2t-1} + 1} - \frac{t+n-2}{t} < 0 \Leftrightarrow \frac{t+n-2}{t} \times a^{n+2t-1} - a^{n+2t-3} + \frac{n-2}{t} > 0$$

Now, let $t \geq 1$ and $n \geq 3$. Consider the function:

$$g_{t,n} : (0, 1) \longrightarrow \mathbb{R} \\ a \longmapsto \frac{n+t-2}{t} \times a^{n+2t-1} - a^{n+2t-3} + \frac{n-2}{t}$$

We compute the derivative of $g_{t,n}$, for every $a \in (0, 1)$:

$$g'_{t,n}(a) = \frac{n+t-2}{t} \times (n+2t-1) \times a^{n+2t-4} \times \left(a^2 - \frac{t}{n+t-2} \times \frac{n+2t-3}{n+2t-1} \right).$$

We deduce that $g_{t,n}$ is decreasing on $(0, a_{t,n})$ and increasing on $(a_{t,n}, 1)$, which implies that it attains its minimum in $a_{t,n}$, where:

$$a_{t,n} = \sqrt{\frac{t}{n+t-2} \times \frac{n+2t-3}{n+2t-1}}.$$

We have:

$$\begin{aligned} g_{t,n}(a) &\geq g_{t,n}(a_{t,n}) \\ &= \frac{n+t-2}{t} \times \left(\frac{t}{n+t-2} \right)^{\frac{n+2t-1}{2}} \left(\frac{n+2t-3}{n+2t-1} \right)^{\frac{n+2t-1}{2}} - \left(\frac{t}{n+t-2} \right)^{\frac{n+2t-3}{2}} \left(\frac{n+2t-3}{n+2t-1} \right)^{\frac{n+2t-3}{2}} + \frac{n-2}{t} \\ &= - \left(\frac{t}{n+t-2} \right)^{\frac{n+2t-3}{2}} \left(\frac{n+2t-3}{n+2t-1} \right)^{\frac{n+2t-3}{2}} \times \frac{2}{n+2t-1} + \frac{n-2}{t} \\ &\geq - \frac{1}{t + \frac{n-1}{2}} + \frac{n-2}{t} > 0 \quad (\text{because: } n-2 \geq 1 \text{ and } t + \frac{n-1}{2} > t). \end{aligned}$$

We deduce that for all $t \geq 1$: $h'_{a,n}(t) < 0$, which implies that $h_{a,n}$ is strictly decreasing on $[1, +\infty[$. In particular, the sequence $\left(- \frac{B_k}{\sqrt{(k+n-2)k}} \right)_{k \geq 1}$ is strictly decreasing and so is

$$\left(- \frac{B_k}{\sqrt{(k+n-2)k}} + \sqrt{\left(- \frac{B_k}{\sqrt{(k+n-2)k}} \right)^2 - 4a(1-a^{2k+n-2})^2} \right)_{k \geq 1}.$$

2. Take $\gamma : x \in \mathbb{R}^n \mapsto x_1$ an eigenfunction corresponding to the first nontrivial Steklov eigenvalue of the unit ball B centred in 0. This function can be used as a test function in the variational definition of $\sigma_1(B \setminus aB)$.

We write:

$$\begin{aligned} \sigma_1(B \setminus aB) &= \inf \left\{ \frac{\int_{B \setminus aB} |\nabla u|^2 dx}{\int_{\partial(B \setminus aB)} u^2 d\sigma} \mid u \in H^1(\Omega) \setminus \{0\} \text{ such that } \int_{\partial\Omega} u d\sigma = 0 \right\} \\ &\leq \frac{\int_{B \setminus aB} |\nabla \gamma|^2 dx}{\int_{\partial B \cup \partial(aB)} \gamma^2 d\sigma} \leq \frac{\int_B |\nabla \gamma|^2 dx}{\int_{\partial B} \gamma^2 d\sigma} = \sigma_1(B) = 1 \quad (\text{see [25] Example 1.3.2 for the last equality}) \\ &< (n-2) \frac{1+a^{n-1}}{a(1-a^{n-2})} = \delta_0. \end{aligned}$$

□

4.3. Proof of Theorem 3

We have $\delta_1^{(1)} < \delta_1^{(2)}$ and by Lemma 3:

$$\begin{cases} \forall k \geq 2, & \delta_1^{(1)} < \delta_k^{(1)} < \delta_k^{(2)}, \\ & \sigma_1(\Omega_0) < \delta_0. \end{cases}$$

This implies that $\delta_1^{(1)}$ is the lowest non-trivial Steklov eigenvalue of Ω_0 , which writes $\sigma_1(\Omega_0) = \delta_1^{(1)}$. It is of multiplicity n and the corresponding eigenfunctions are given by (8) as follows:

$$u_n^i : \mathbb{R}^n \longrightarrow \mathbb{R} \\ x = (x_1, \dots, x_n) \longmapsto \left(|x| + \frac{\mu_{\sigma,n}}{|x|^{n-1}} \right) \frac{x_i}{|x|} = x_i \left(1 + \frac{\mu_{\sigma,n}}{|x|^n} \right)$$

where $i \in \llbracket 1, n \rrbracket$ and $\mu_{\sigma,n} = \frac{1 - \sigma_1(\Omega_0)}{n + \sigma_1(\Omega_0) - 1}$.

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