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Mesoscale modeling of Venus' bow-shape waves

- Maxence Lefèvre¹, Aymeric Spiga^{1,2}, and Sébastien Lebonnois¹
- ¹Laboratoire de Météorologie Dynamique (LMD/IPSL), Sorbonne Université,
- Centre National de la Recherche Scientifique, École Polytechnique, École
- Normale Supérieure, Paris, France
 - ²Institut Universitaire de France, Paris, France
- submitted to Icarus

Abstract

The Akatsuki instrument LIR measured an unprecedented wave feature at the top of Venusian cloud layer. Stationary bow-shape waves of thousands of kilometers large lasting several Earth days have been observed over the main equatorial mountains. Here we use for the first time a 11 mesoscale model of the Venus's atmosphere with high-resolution topography and fully coupled 12 interactive radiative transfer computations. Mountain waves resolved by the model form large-13 scale bow shape waves with an amplitude of about 1.5 K and a size up to several decades of latitude similar to the ones measured by the Akatsuki spacecraft. The maximum amplitude of 15 the waves appears in the afternoon due to an increase of the near-surface stability. Propagating 16 vertically the waves encounter two regions of low static stability, the mixed layer between 17 approximately 18 and 30 km and the convective layer between 50 and 55 km. Some part of the 18 wave energy can pass through these regions via wave tunneling. These two layers act as wave 19 filter, especially the deep atmosphere layer. The encounter with these layers generates trapped 20 lee waves propagating horizontally. No stationary waves is resolved at cloud top over the polar 21 regions because of strong circumpolar transient waves, and a thicker deep atmosphere mixed 22 layer that filters most of the mountain waves. 23

1 Intro

The influence of the topography on the Venusian atmosphere, especially on the dynamics of the 25 cloud layer, is still not fully understood. The VeGa balloons campaign was the first measure-26 ment of the impact of the surface on the atmospheric dynamics and demonstrated an increase 27 of the vertical wind above Aphrodite Terra, speculated to be linked to the propagation of oro-28 graphic gravity waves (Blamont et al., 1986). Numerical modeling was then used to assess the 29 possibility for such kind of wave to emerge Young et al. (1987, 1994). These modeling efforts 30 showed that gravity waves generated by the topography can propagate up to the cloud layer, 31 even in the observed conditions of strong vertical variations of zonal wind and stability. Addi-32 tional observations of the interactions between the surface and the atmosphere have been made with the Venus Express mission (Bertaux et al., 2016). Correlations between the zonal wind at 34 the top of the cloud and the underlying topography has been evidenced by UV measurements with the Venus Monitoring Camera, and interpreted as the result of stationary gravity waves.

A water minimum has also been measured with *Venus Express* instrument SPICAV at cloud top above Aphrodite Terra (Fedorova et al., 2016) possibly linked to an interaction between

the surface and the cloud layer.

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Using the LIR instrument on board the Akatsuki mission, Fukuhara et al. (2017) discov-40 ered large-scale stationary bow-shaped oscillations at the top of the cloud above Aphrodite 41 Terra. This bow-shape signature, extending over 60° of latitude (about 10 000 km across), 42 was observed during 5 days. Similar signatures were also reported above the main equato-43 rial topographic features (Kouyama et al., 2017, e.g., Atla and Beta Regio). Those signatures were interpreted as stationary orographic gravity waves. The bow-shape wave above Aphrodite 45 Terra has been observed in the afternoon, with a maximum amplitude close to the evening terminator. The cloud-top signatures above the other Venusian mountains are visible during 47 the afternoon, with a maximum close to the evening terminator. Cloud-top signatures associ-48 ated with the underlying topography were also observed above Beta Regio with the instrument 49 Akatsuki/IR2 (2.02 μ m wavelength, Satoh et al., 2017) as well as with Akatsuki UV imager above Aphrodite Terra, Atla and Beta Regio (Kitahara et al., 2019). Stationary features have 51 also been measured by the Venus Express instrument VIRTIS above the main topographical 52 obstacles in the southern hemisphere in the nightside with no apparent dependence with the 53 local time (Peralta et al., 2017).

To investigate the atmospheric dynamics of those observed phenomena, two modeling ap-55 proaches were adopted: one by Fukuhara et al. (2017) using a very idealized (i.e. no represen-56 tation of physical processes and topography) high-resolution Global Circulation Model (GCM), 57 with an arbitrary perturbation as the source of the waves and one by Navarro et al. (2018) us-58 ing a subgrid-scale paramaterization for gravity waves in a low-resolution GCM with complete 59 physics (the IPSL Venus GCM described in Garate-Lopez and Lebonnois, 2018). In the study 60 by Navarro et al. (2018), the parametric representation of the orographic gravity waves in a 61 GCM demonstrated the link between the topography and the bow-shaped waves. In addition, 62 the impact of the large-scale mountain waves detected by Akatsuki on the global-scale dynamics 63 was shown to induce, along with the thermal tide and baroclinic waves, a significant change in 64 the rotation rate of the solid body, with variability of the order of minutes.

Despite those recent modeling studies, open questions remain on the source, propagation 66 and impact of the large-scale gravity waves evidenced by Akatsuki (Fukuhara et al., 2017; 67 Kouyama et al., 2017). Notably, Navarro et al. (2018) used a parameterization for orographic 68 gravity waves on Venus and did not resolve the complete emission and propagation of gravity 69 waves from the surface to Venus' cloud top, which is not possible with current GCMs for Venus. 70 Following the methodology described in Lefèvre et al. (2018) to study the turbulence and gravity 71 waves in the cloud layers, we propose a method combining high-resolution atmospheric dynamics 72 with detailed physics of the Venusian atmosphere to resolve the emission and propagation of 73 mountain waves in a realistic atmosphere. In other words, in order to address the Venusian bowshaped mountain waves, we developed the first Venusian mesoscale model. With high-resolution 75 topography from Magellan data, we can model the atmospheric dynamics of a limited area of Venus using the dynamical core of the Weather Research and Forecast (WRF, Skamarock and Klemp, 2008). Following a method used on Mars by Spiga and Forget (2009), the WRF 78 dynamical core is interfaced with the physics of the IPSL Venus GCM (Lebonnois et al., 2010; 79 Garate-Lopez and Lebonnois, 2018) to be able to compute radiative transfer and subgrid-scale turbulent mixing coupled in real-time with the dynamical integrations. 81

In this paper, using our new mesoscale model for Venus, we carry out simulations in areas 82 surrounding the main mountains of the Venusian equatorial belt at various local times, in 83 order to understand the generation and vertical propagation of the waves and to interpret the signal detected by Akatsuki at the top of the cloud. Our new mesoscale model for Venus can 85 potentially be used for many applications other than studying the bow-shaped mountain waves, 86 e.g. near-surface slope winds (Lebonnois et al., 2018), polar meteorology Garate-Lopez et al. 87 (2015), mesoscale structures in the vicinity of the super-rotating jet (Horinouchi et al., 2017). 88 This paper is organized as follows. Our mesoscale model for Venus is described in Section 2. 89 In Section 3, the emission of resolved gravity waves is presented. The resulting top-of-the-cloud 90 signal above Aphrodite Terra is developed in Section 4, and above Atla Regio and Beta Region 91 in Section 5. In Section 6, mountain waves in the polar regions are discussed. Our conclusions are summarized in Section 7.

⁹⁴ 2 The LMD Venus mesoscale model

$_{\scriptscriptstyle 95}$ 2.1 Dynamical core

The dynamical core of our LMD Venus mesoscale model is based on the Advanced Research 96 Weather-Weather Research and Forecast (hereafter referred to as WRF) terrestrial model (Ska-97 marock and Klemp, 2008). This methodology is similar to the one adopted for the LMD Mars 98 mesoscale model (see Spiga and Forget (2009) for a reference publication of this model and 99 Spiga and Smith (2018) for the most up-to-date description). The WRF dynamical core in-100 tegrates the fully compressible non-hydrostatic Navier-Stokes equations on a defined area of 101 the planet. The conservation of the mass, momentum, and entropy is ensured by an explic-102 itly conservative flux-form formulation of the fundamental equations (Skamarock and Klemp, 103 2008), based on mass-coupled meteorological variables (winds and potential temperature). To 104 ensure the stability of the model, and given the typical horizontal scales aimed at in our studies, 105 the fundamental equations are integrated under the hydrostatic approximation, available as a 106 runtime option in WRF. 107

2.2 Coupling with complete physical packages for Venus

The radiative heating rates, solar and IR, are calculated using the IPSL Venus GCM radiative transfer scheme (Lebonnois et al., 2015). This setting is similar to the "online" mode described in Lefèvre et al. (2018). The time step ratio between the dynamical and physical integrations is set to 250, as a trade-off between computational efficiency and the requirement that the physical timestep is significantly less than the typical radiative timescale for Venus.

The version of the Venus radiative transfer model used in our mesoscale model is the same as in the version of the IPSL Venus GCM described in Garate-Lopez and Lebonnois (2018). The infrared (IR) transfer uses Eymet et al. (2009) net-exchange rate (NER) formalism: the exchanges of energy between the layers are computed before the dynamical simulations are carried out by separating temperature-independent coefficients from the temperature-dependent Planck functions of the different layers. These temperature-independent coefficients are then used in the mesoscale simulations to compute the infrared cooling rates of each layer. The solar rates are based on Haus et al. (2015) computations: look-up tables of vertical profiles of the

solar heating rate as a function of solar zenith angle are read, before being interpolated on the vertical grid adopted for mesoscale integrations.

The cloud model used in this study is based on the Haus et al. (2014) and Haus et al. 124 (2015) models derived from retrievals carried out with Venus Express instruments. The cloud 125 structure is latitude-dependent, the cloud top varies from 71 km to 62 km between the Equator 126 and the poles Haus et al. (2014). This latitudinal variation of the cloud takes the form of five 127 distinct latitude intervals: 0° to 50°, 50° to 60°, 60° to 70°, 70° to 80° and 80° to 90°. For each 128 latitudinal intervals different NER-coefficient matrices are computed on the vertical levels of 129 the model, ranging from the surface to roughly 100 km altitude. The cloud structure used for 130 the calculations is fixed prior to the simulation and does not evolve with time. 131

Since the horizontal grid spacing for the mesoscale simulations is set to several tens of 132 kilometer, the convective turbulence in the planetary boundary layer and the cloud layer is not 133 resolved. Therefore, similarly to what is done in GCMs, our mesoscale model uses subgrid-134 scale parameterizations for turbulent mixing. As in the IPSL Venus GCM, for mixing by 135 smaller-scale turbulent eddies, the formalism of Mellor and Yamada (1982) is adopted, which 136 calculates with a prognostic equation the turbulent kinetic energy and mixing length. For 137 mixing by larger-scale turbulent plumes (such as those resolved by Large-Eddy Simulations, 138 see Lefèvre et al., 2017, 2018), a simple dry convective adjustment is used to compute mixed 139 layers in situations of convectively-unstable temperature profiles. In the physics (same as in the 140 GCM), the dependency of the heat capacity with temperature $c_p(T)$ is taken into account, but 141 in the dynamical core, we use a constant heat capacity as in Lefèvre et al. (2018), with a mean 142 value of $c_p = 1000 \text{ J kg}^{-1} \text{ K}^{-1}$ suitable for the vertical extent of our model from the surface 143 to 100 km altitude. The initial state and the boundary conditions of the mesoscale domain, 144 detailed in the next section, are calculated using a variable c_p to ensure a realistic forcing of 145 the mesoscale model by the large-scale dynamics. Therefore the impact of the constant value 146 of c_p is minimum in our configuration because the equations of the WRF dynamical core are 147 formulated in potential temperature and the conversion from the dynamics to the physics (and 148 vice versa) between potential temperature and temperature is done with a variable $c_p(T)$.

¹⁵⁰ 2.3 Simulation settings

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The topography used in our mesoscale model is presented in Figure 1, it is based on Magellan 151 data (Ford and Pettengill, 1992) for the majority of the surface, with *Pioneer Venus* data used 152 to fill the blank spots wherever needed (Pettengill et al., 1980). The dataset has a resolution of 153 8192 points along the longitude and 4096 points along the latitude. Given the detection of bow-154 shaped features by the Akatsuki spacecraft (Kouyama et al., 2017), we choose three domains 155 of interest: Aphrodite Terra, Atla Regio and Beta Regio. These three mesoscale domains 156 has been computed with a horizontal resolution of 40 km for Aphrodite Terra, 30 km for Beta 157 Region and 15 km for Atla Regio. Given the horizontal resolutions involved, the dynamical 158 timestep for mesoscale integrations is set between 8 and 10 s (typical for those horizontal 159 resolutions, see Spiga and Forget, 2009). The horizontal domains and resolutions have been 160 chosen to enclose the whole latitudinal extent of the bow-shaped waves, while keeping a feasible 161 computing time. The vertical grid is composed of 150 levels from the ground to 100 km, with 162 a similar distribution as the LMD Venus LES model (Lefèvre et al., 2018).

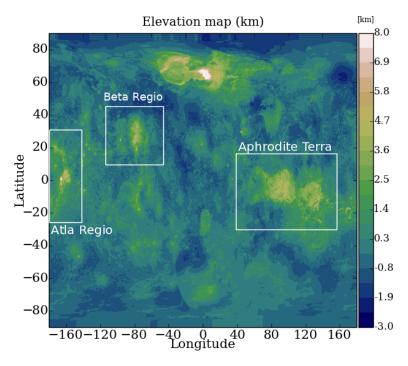


Figure 1: Topographic map of Venus used for the mesoscale simulations, from *Magellan* (Ford and Pettengill, 1992) and *Pioneer Venus* (Pettengill et al., 1980) datasets. The different domains used in the mesoscale simulations are indicated: Aphrodite Terra, Beta Regio and Atla Terra.

The horizontal boundary conditions have been chosen as 'specified', i.e. meteorological fields are extracted from IPSL Venus GCM simulations (detailed in Garate-Lopez and Lebonnois,

2018) and interpolated both on the vertical grid, accounting for the refined topography of the 166 mesoscale, and on the temporal dimension, accounting for the evolution of those fields over the 167 low dynamical timestep in mesoscale integrations. This ensures that the planetary-scale super-168 rotation of the Venusian atmosphere is well represented. The mesoscale simulations presented 169 in this study are performed using an update frequency of a 1/100 Venus day, which enables a 170 correct representation of the large-scale variability simulated by the GCM at the boundaries 171 of the mesoscale domain. Between the mesoscale domain and the specified boundary fields, a relaxation zone is implemented in order to allow for the development of the mesoscale circu-173 lations inside the domain, while keeping prescribed GCM fields at the boundaries (Skamarock 174 and Klemp, 2008). In this study, the number of relaxation grid points is set to 5. An expo-175 nential function is used to reach a smooth transition between the domain and the specified boundary fields; the coefficient is set to 1, a value used for terrestrial and Martian applications 177 that appeared suitable for the Venusian case as well. At the top of the mesoscale model, a diffu-178 sive Rayleigh damping layer is applied to avoid any spurious reflection of vertically-propagating 179 gravity waves. The damping coefficient is set to 0.01 and the depth of the damping layer to 180 5 km. 181

The initialization of the meteorological fields for the mesoscale domain are, similarly to boundary conditions, extracted from the Garate-Lopez and Lebonnois (2018) GCM. First the fields are interpolated horizontally to the mesoscale refined-resolution grid, then interpolated vertically on the mesoscale vertical grid – accounting for high-resolution topography. To extrapolate the high-resolution features, the same methodology is used as in the LMD Mars Mesoscale Model (Spiga and Forget, 2009).

Venus's rotation is retrograde, but the WRF dynamical core has been built for Earth applications, and therefore assuming implicitly prograde rotation. In order to solve this issue, as is the case for the IPSL GCM runs (Lebonnois et al., 2010), the GCM fields are turned upside down and the meridional wind is multiplied by minus 1. At the post-processing stage, the fields are turned upside down again and the meridional wind is again multiplied by minus 1, to obtain the diagnostics enclosed in this paper.

¹⁹⁴ 3 Generation and propagation of orographic gravity waves

To discuss the orographic wave generation, we focus first on Atla Regio which facilitates the visualization of the phenomena given its very sharp mountains. Figure 2 shows the domain chosen for Atla Regio.

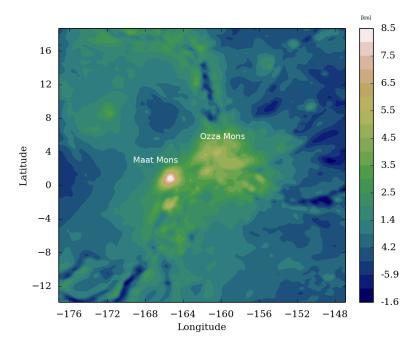


Figure 2: Elevation map (km) of the selected domain for Atla Regio with a resolution of 15 km.

Figure 3 shows a vertical cross-section of the vertical wind (m s⁻¹) at 1° of latitude, be-198 tween the surface and approximately 55 km in the beginning of afternoon. Contours represent 199 potential temperature. For this figure 3, and all the similar cross-sections shown in this paper, 200 the zonal wind comes for the right side of the plot, i.e. wind is blowing westward. The Pioneer 201 Venus probe measured horizontal wind (u and v) from the ground to 3 km between 0.1 and 1.5 202 m s⁻¹ (Schubert et al., 1980). In the GCM, the horizontal wind on the same vertical extent is 203 between 0.1 and about 3.0 m s^{-1} . The horizontal wind is of the same order of magnitude as 204 in-situ measurements although slightly overestimated. 205

Strong vertical winds are visible above the two main mountains, Maat Mons at -165° of longitude and Ozza Mons at -156° of longitude. The interaction between the incoming zonal flow and those sharp topographical obstacles leads to the generation of gravity waves. Near the surface, the value of the dimensionless mountain height $H_d = H N_B/u$ can reach value close to 1, where H is the maximum mountain height, N_B is Brunt-Väisälä frequency and u the zonal wind, meaning that the flow is in a non-linear regime (Durran, 2003). The waves propagate

vertically and encounter two regions of low static stability, the mixed layer between 18 and 35 km and the convective layer between 48 and 52 km. Above, the waves propagate into the stratified layers. The vertical wavelength of the waves is around 30 km.

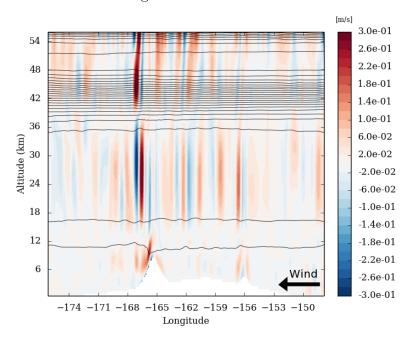


Figure 3: Vertical cross-section of the vertical wind (m s⁻¹) at 1° of latitude, between the surface and approximately 55 km in the beginning of afternoon. Contours represent the potential temperature. Direction of the zonal is indicated with the black arrow.

The impact of these two near-neutral low-stability regions on the vertical propagation of the wave can be understood via the Scorer parameter (km⁻¹) (Scorer, 1949) : $l^2 = \frac{N_B^2}{u^2} - \frac{1}{u} \frac{d^2 u}{dz^2}$.

This parameter represents the minimum vertical wavelength of propagation. Figure 4 shows the vertical cross-section of the Scorer parameter, and its domain-averaged vertical profile, at the same location as Figure. 3.

Beyond 12 km altitude, the Scorer parameter decreases strongly up to 18 km and has very 220 small values, sometimes negative, from 18 to 35 km. Then it increases up to 42 km, and de-221 creases until reaching the convective layer at 48 km. Inside this convective layer, the Scorer 222 parameter is again very small. Above the convective layer, the Scorer parameter increases through the stable atmosphere. These two regions of low Scorer parameter indicate the pre-224 dominance of trapped lee waves that propagate horizontally. The horizontally-propagating trapped waves are visible in Figure 3 within layers exhibiting low Scorer parameter, between 226 18 and 35 km and between 48 and around 54 km. An additional vertical propagation of those 227 trapped waves is visible at some longitudes. This phenomenon is similar to the leakage of 228 trapped lee waves into the stratosphere on Earth (Brown, 1983). On Venus, the horizontal 229

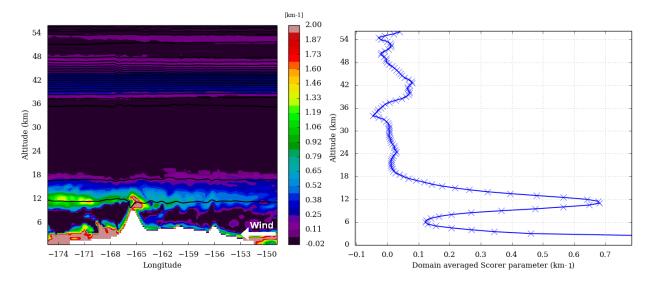


Figure 4: Left: Instantaneous vertical cross-section of the Scorer parameter (km⁻¹) at 1° of latitude, between the surface and approximately 55 km in the beginning of afternoon. Contours represent the potential temperature. Right: domain-averaged vertical profile of the Scorer parameter at the same local time. Direction of the zonal is indicated with the white arrow.

wavelength is approximately 150 km, one order of magnitude larger to typical Earth's trapped lee waves (Ralph et al., 1997). Large horizontal wavelengths are known to increase the vertical leakage of trapped lee waves (Durran et al., 2015). The horizontal wavelength of the trapped lee waves generated above Atla Regio is consistent with VEx/VIRTIS nightside measurements in the low cloud region (Peralta et al., 2008), whereas the trapped lee waves generated above Aphrodite Terra and Beta Regio are larger by at least a factor of 2.

One of the main questions about the vertical propagation of bow-shaped waves on Venus 236 (and the reason why they can be detected at high altitudes by Akatsuki) is how the waves can 237 propagate through two (near-neutral) mixed layers. A similar configuration can be found in 238 the Earth's oceans where the seasonal and main thermoclines can be separated by a relatively 239 weakly stratified region (Eckart, 1961). An analogous case in the Earth atmosphere is the 240 propagation of gravity waves from the troposphere to the upper mesosphere and lower ther-241 mosphere, tunneling through an evanescent region (Walterscheid et al., 2001). Gravity waves are evanescent in neutral-stability layers, in which the energy of the waves decrease exponen-243 tially with altitude. However, if the vertical extension of the neutral region is not too large, it is possible for a significant fraction of the incident wave energy to pass through the neutral 245 stability region. By analogy with quantum mechanics, some transfer of energy is possible via wave tunneling (Sutherland and Yewchuk, 2004) through a neutral barrier. To quantify the 247

energy transmitted from a region with a Brunt-Väisälä frequency N through a barrier of zero Brunt-Väisälä frequency, the transmission T is defined as

$$T = \left[1 + \left(\frac{\sinh(k_x H)}{\sin 2\theta}\right)^2\right]^{-1} \tag{1}$$

according to Sutherland and Yewchuk (2004), with k_x the horizontal wavenumber, H the height of the barrier and θ equals to $\cos(\omega/N)$ with ω the frequency of the wave.

For the first barrier, between 18 and 35 km, the horizontal wavelength is of the order of 200 km, H is equal to 17 km, ω to 3.4 10^{-4} s⁻¹ and N to 2.3 10^{-3} s⁻¹. For the second barrier, the convective layer between 48 and 52 km, the horizontal wavelength is of the order of 200 km, H is equal to 4 km, ω to 1.3 10^{-3} s⁻¹ and N to 9.0 10^{-3} s⁻¹. With these values, the transmission T for the first layer is equal to 21 % and to 84 % for the second barrier. The cloud convective layer depth is closer to 10 km (Tellmann et al., 2009), with that value the transmission drops to about 45 %.

We conclude that, despite the presence of the two neutral-stability layers in the atmosphere of Venus, there is a significant energy transmission through these two barriers. In other words, this tunneling effect enables the orographic gravity waves to propagate towards the top Venusian clouds, where those waves are detected by Akatsuki (Fukuhara et al., 2017; Kouyama et al., 2017).

The mixed layer in the deep atmosphere between altitudes 18 and 35 km (Schubert et al., 264 1980) is the thickest of the two barriers, and is the one that affects the most the vertically-265 propagating wave, since a fifth of the wave energy makes it through this mixed layer. Our 266 simulations thereby provide insights into the mechanisms responsible for the propagation of the bow-shape perturbation from the surface to 35 km, left unexplained by the approach based on 268 gravity-wave parameterization used in Navarro et al. (2018). Conversely, the cloud convective layer between altitudes 48 and 52 km, thinner than the deep atmosphere mixed layer but with 270 strong vertical plumes (Lefèvre et al., 2018), plays a minor role and does not affect substantially the wave vertical propagation (more than 80% of the incoming wave energy is propagating 272 through this mixed layer). These two neutral barriers would also be an obstacle to the vertical propagation of sound waves (Martire et al., 2018) induced by putative Venusian seismic activity, 274 possibly detectable via infrasound sensors on balloons (Krishnamoorthy et al., 2018) or through

airglow radiation perturbation (Didion et al., 2018).

Saturation of a wave occurs either through critical levels (when the speed of the background horizontal flow is equal to the wave phase speed) or wave breaking through convective instability.

To quantify this probability, the saturation index S of Hauchecorne et al. (1987) is used

$$S = \sqrt{\frac{F_0 N}{\rho k_x |\overline{u} - c|^3}} \tag{2}$$

where F_0 is the vertical momentum flux, N is the Brunt-Väisälä frequency, ρ the density of the atmosphere, k_x the horizontal wave number c the phase speed of the wave, and $\bar{\cdot}$ the average 281 over our chosen mesoscale domain (thought to represent the large-scale component). When Sreaches values close to 1 the wave may be likely to break through critical level or saturation. For 283 the case of Venus, the main wave is orographic and stationary with respect to the surface, with a phase speed c equals to zero. The zonal wind speed is constantly increasing up to roughly 285 80 km of altitude, thus $|\overline{u}-c|\gg 0$ and superior to F_0N/k_x , which causes S to be much smaller 286 than 1, even for the largest values of stability N. The saturation index only reaches values up 287 to 1 10⁻¹, and most often values of 1 10⁻², thus the probability of saturation of the mountain 288 waves is low. 289

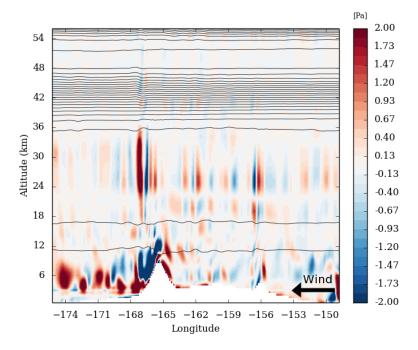


Figure 5: Instantaneous vertical cross-section of the quantity $-\rho u'w'$ (Pa) at 1° of latitude, between the surface and approximately 55 km in the beginning of afternoon. Contours represent the potential temperature. Direction of the zonal is indicated with the black arrow.

The propagation of the waves into the two mixed layers engender a dissipation of the waves: 290 the part of the energy that is not transferred upward through tunneling effect is deposited in 291 those mixed layers. This deposition of momentum can be quantified by calculating the vertical 292 component of the Eliassen-Palm momentum flux (Andrews, 1987) that is equal to $-\rho \overline{u'w'}$ where 293 ρ is the density and u' and w' the perturbations of the zonal wind u and vertical wind w (with 294 respect to the mean defined as $\bar{\cdot}$). A postive value of u' represents an eastward velocity pertur-295 bation and a positive value of w' represents an upward velocity perturbation and therefore a 296 positive value of $-\rho \overline{u'w'}$ represents an upward transport of westward momentum. The quantity 297 displayed at Figure 5 is an instantaneous snapshot of the quantity $-\rho u'w'$. This flux is around 298 10 times larger than the strongest measured on Earth in Antarctica (Jewtoukoff et al., 2015). 299 This is partly due to the fact that the density of the Venusian atmosphere is 65 times larger than the Earth atmosphere. Momentum is transported by the waves near the surface (where density 301 is the highest), but also in the mixed layer around 30 km of altitude (where wave perturbations 302 are strong). The trapped lee waves also transport momentum horizontally, while the vertical 303 transport of momentum due to leakage is negligible. The momentum flux $-\overline{\rho u'w'}$ is the drag 304 coefficient (Smith, 1979) calculated in sub-grid-scale parameterizations, such as the one used in 305 the GCM runs by Navarro et al. (2018), who employed the orographic-wave parameterization 306 of Lott and Miller (1997). In this parameterization, Navarro et al. (2018) had to adopt values 307 of 2 Pa for the threshold of the gravity wave mountain stress, and 35 km for the initial altitude 308 of deposition of this mountain stress, to reproduce the bow-shape waves observed by Akatsuki. 309 Our mesoscale modeling of the Venusian mountain waves, in which the propagation of gravity 310 waves is resolved from the surface to 100 km, therefore validates the assumption of the Navarro 311 et al. (2018) study, both for the amplitude of the stress and the altitude of the stress deposition 312 (a maximum of momentum is deposited by the waves at this altitude), and shows that they are 313 physically based. 314

What we describe here for Alta Regio extends to the other regions considered in this study.

Figure 6 shows the vertical cross-section of the vertical wind, Scorer parameter and momentum

flux for Aphrodite Terra (left) and Beta Regio (right). As for Atla Regio, the major terrain

elevations generate gravity waves and the flow is in a non-linear regime. The two layers of

low static stability are also present in those regions, which entails the generation of trapped

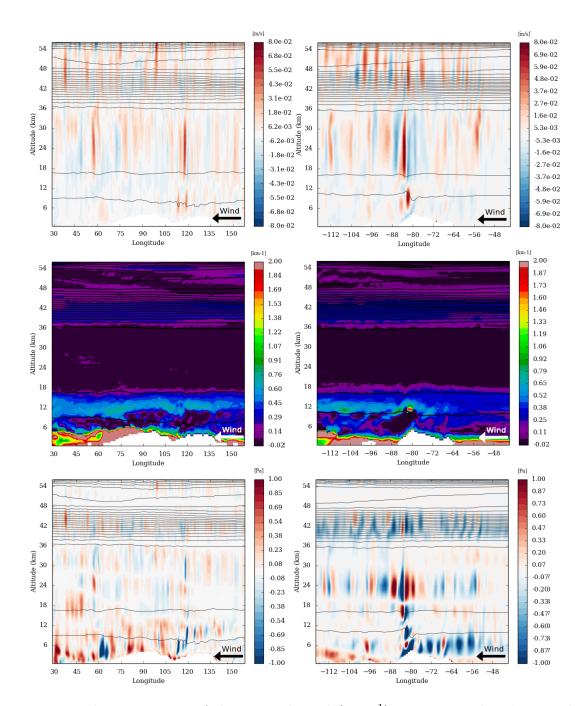


Figure 6: Vertical cross-section of the vertical wind (m s⁻¹) on top panel and vertical cross-section of the Scorer parameter (km⁻¹) on middle panel and vertical cross-section of vertical momentum flux (Pa) on bottom panel for Aphrodite Terra on left column and Beta Regio on right column. Contour is potential temperature. Direction of the zonal is indicated with arrows.

lee waves. The amplitude of the vertical wind is smaller than in the Atla case due to lower slopes. Thus, the amplitude of the momentum flux is of the same order of magnitude, albeit slightly smaller. The vertical extent of the two mixed layers is very similar to Atla Region, in both the Aphrodite Terra and Beta Regio cases, but the horizontal wavelengths are slightly larger and resulting in a small decrease of the tunneling transmission T but in the same order of magnitude, about 20 % for the first barrier (18-35 km altitudes) and 80 % for the second

$_{\scriptscriptstyle 127}$ 4 Aphrodite Terra

Figure 7 shows the selected domain for Aphrodite Terra with a resolution of 40 km, Ovda Terra is visible between 60 and 100° of longitude where the main bow-shape gravity waves have been observed by *Akatsuki*.

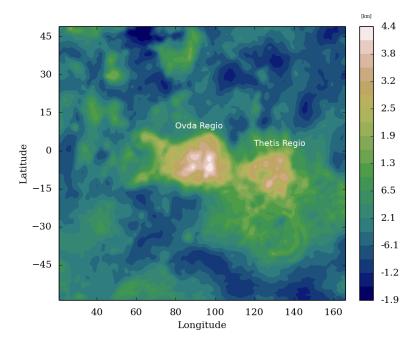


Figure 7: Elevation map (km) of the selected domain for Aphrodite Terra with a resolution of 40 km.

Akatsuki LIR measurements consist of a mean of the brightness temperature between 8 331 and 12 μ m to which is applied a high-pass filter (Fukuhara et al., 2017; Kouyama et al., 2017; 332 Taguchi et al., 2007). To be able to compare the outputs of the model with the observations, 333 we have to analyze in the model the deformation of the cloud top by the gravity waves. We 334 consider that the characteristic timescale of the wave propagation is smaller than the radiative 335 timescale, so that the deformation is adiabatic; it follows that potential temperature can be 336 used as a tracer for the deformation of the cloud top by waves. By choosing one value for 337 potential temperature to set a relevant material surface, a corresponding temperature map 338 can be reconstructed, as well as a map of the corresponding altitude. To compare the waves 339 resolved by the model to the ones observed by the Akatsuki spacecraft, anomaly temperature 340 is calculated for potential temperature surface between 55 and 80 km, corresponding to a range 341

of potential temperature from 800 to 1300 K, with a gaussian weighting function mimicking the LIR's weight function. Then the temperature perturbations are vertically averaged. A 343 high-pass gaussian filter is applied to filter out the global dynamics component (similarly to what is done in the maps derived from Akatsuki observations Fukuhara et al., 2017; Kouyama 345 et al., 2017), and a low-pass gaussian filter is also applied to remove the small-scale features smaller than a few tens of kilometer (i.e. approaching the effective horizontal resolution of our 347 mesoscale simulations for Venus). Figure 9 presents the associated residuals of the temperature anomaly after filtering. In the end, temperature maps such as Figure 8 obtained from our 349 mesoscale modeling by this method can be directly compared to the Akatsuki observations in 350 Fukuhara et al. (2017) and Kouyama et al. (2017). 351

$_{2}$ 4.1 Resulting bow-shape wave

Figure 8 shows the temperature anomaly modeled by our LMD Venus mesoscale model at 353 the top of the cloud above Aphrodite Terra, close to the evening terminator. Cyan contours 354 show the topography. The topography-induced perturbation at the top of the cloud expands 355 from -40 to 40° of latitude with a bow-shaped morphology, resembling the measured signal by 356 Akatsuki. Above Ovda Terra, the positive and negative anomaly measured by LIR (Fukuhara 357 et al., 2017) is reproduced with a similar amplitude, ± 2 K. Outside of the bow-shape wave 358 small-scale waves features are visible, similar structures are visible in the UV images (Kitahara 359 et al., 2019). This orographic gravity wave induces a deformation of about 600 m of the cloud 360 top altitude. Temperature anomalies induced by mountain waves are visible in the middle 361 and upper cloud layers whereas no temperature anomaly is discernible in the lower cloud layer 362 due to the presence of the convective layer. This could explain the fact that VEx/VIRTIS 363 measured on the nightside stationary waves in the upper cloud layer but not in the lower cloud 364 layer (Peralta et al., 2017). 365 The divergence of the momentum flux indicates the acceleration (or equivalently the force 366 per unit mass) caused by gravity waves on the mean flow when they break or encounter a 367

$$\frac{\partial \overline{u}}{\partial t} = \frac{1}{\rho} \frac{\partial}{\partial z} \rho \overline{u'w'} \tag{3}$$

critical level (Frits and Alexander, 2003). This acceleration can be calculated by the equation

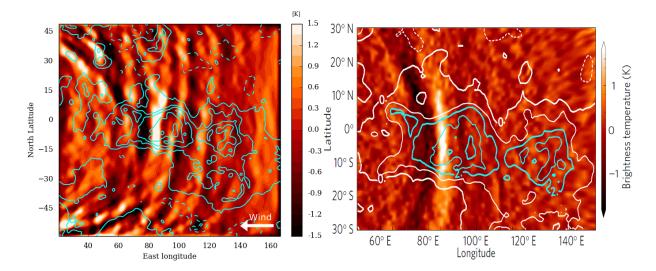


Figure 8: Left: Temperature anomaly (K) at the top of the cloud in late afternoon. Cyan contours show the topography every 1 km (Fig. 7). Direction of the zonal is indicated with the white arrow. Right: Temperature anomaly (K) at the top of the cloud observed by Akatsuki/LIR adapted from Fukuhara et al. (2017). White and cyan lines are topography.

Observations indicate that around cloud top, for altitudes above 67 km, there is a deceleration of the zonal wind.

Bertaux et al. (2016) calculated that an deceleration of 13 m s⁻¹ per Venus day was nec-371 essary to explain longitudinal shift of zonal wind patterns. The Akatsuki spacecraft measured 372 a longitudinal variability of the zonal wind around cloud top between 4 and 12 m s⁻¹ at the 373 Equator (Horinouchi et al., 2018) with no correlation with topography. The deceleration in-374 duced by the bow-shape waves resolved by our LMD Venus mesoscale model, integrated over a 375 Venus day, reaches values around 3 m s⁻¹ consistent with the lower range of estimates based on Akatsuki measurements. This value is smaller than the computations in Bertaux et al. (2016) 377 (and the higher range of Akatsuki estimates), which tends to indicate that the deceleration of 378 zonal wind at cloud top cannot be explained solely by the impact of bow-shaped gravity waves. 379

4.2 Variability with local time

380

The temperature anomaly of 2 K at the top of the cloud shown in Figure 8 is the maximum signal obtained. This wave is visible in the model with an amplitude superior to 0.5 K for about 10 Earth days, against approximately 14 Earth days for the *Akatsuki* observation (between 14h et 17h in local time). Figure 10 shows Temperature anomaly (K) at the top of the cloud 3.5 Earth day after Figure 8, the bow-shape wave above Ovda Regio is still visible but with smaller amplitude meanwhile a bow-shape wave above Thetis Regio is discernible similarly to

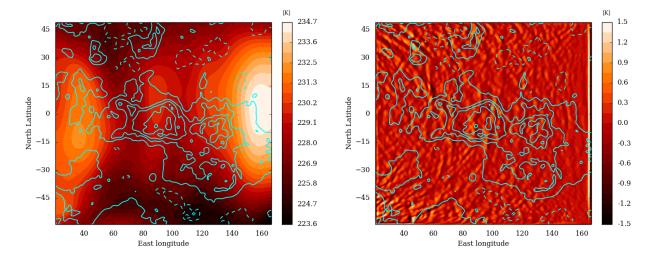


Figure 9: The scene displayed in this figure is similar to Figure 8. The low-pass filter signal (left panel) representing the global dynamics component has a maximum around 160° of longitude, where the local time is close to noon. The high-pass filter signal (right panel) shows small-scale wave features not visible on Akatsuki LIR images (Kouyama et al., 2017) but discernible on UV images (Kitahara et al., 2019). Cyan contours show the topography (Fig. 7).

LIR observations (Kouyama et al., 2017).

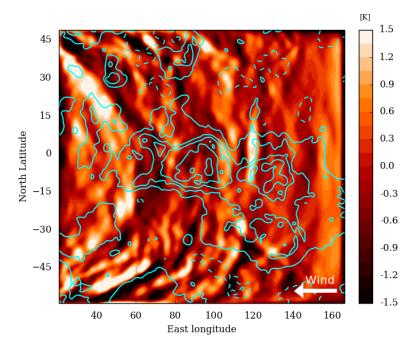


Figure 10: Temperature anomaly (K) at the top of the cloud 3.5 Earth day after Figure 8. Cyan contours show the topography every 1 km (Fig. 7). Direction of the zonal wind is indicated with the white arrow.

Additional simulations were performed at midnight and noon to study the variability of the waves at cloud top. At midnight, no significant wave (amplitude superior to 0.5 K) is observed. At noon, transient waves are visible with amplitude smaller than 1 K. The variation of the surface wind along the day, about 1 m s⁻¹ above Ovda Terra, is too small to explain this variability. This indicates that the near-surface conditions responsible for the emission of orographic gravity wave are not changing significantly along the day. The diurnal variability of conditions responsible for the propagation of orographic gravity waves towards high altitude is more likely to explain the observed variability with local time of the bow-shaped waves.

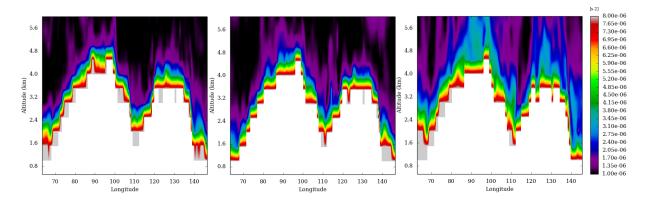


Figure 11: Square of the Brunt-Väisälä frequency (s⁻²) of the atmosphere from the surface to 6 km for midnight (left), noon (middle) and late afternoon (right) for Aphrodite Terra.

Figure 11 shows the square of the Brunt-Väisälä frequency (s⁻²) above Aphrodite Terra be-396 tween the surface and 6 km of altitude for the three local times: midnight (left), noon (center), 397 late afternoon (right). Close to the surface the atmosphere is very stable, but this stability is 398 decreasing with altitude by an order of magnitude. This decrease is different depending on the 399 local time. At midnight, the static stability shows a strong gradient with altitude. At noon this 400 gradient is smaller, and even smaller in late afternoon with constant value of 3×10^{-6} s⁻² over 401 more than one kilometer. This slow decrease has consequences over the Scorer parameter, it is 402 superior to 2 km in the first 8 km in late afternoon, against only in the first 3 km at other local 403 times. This strong value of the Scorer parameter over several kilometers favors the vertical 404 propagation of the gravity waves. This is correlated to the vertical momentum flux: at night 405 the amplitude is about 10^{-2} Pa, while it is about 10^{-1} Pa at noon. Meanwhile, the very-near 406 surface (first hundred meters) stability is consistent with Navarro et al. (2018) study: the at-407 mosphere is more stable at night, but with a smaller local-time variability. This behavior plays 408 a role in the generation of the waves, while the first 4 to 5 km affect the vertical propagation. 409

$_{ ext{\tiny 110}}$ 5 Atla and Beta Regios

411 5.1 Atla Regio

426

The left panel of Figure 12 shows the resulting temperature anomaly at cloud top for the Atla Terra (Fig. 2) simulation, using the same methodology as for Aphrodite Terra. Two waves are visible, one above the main mountain Maat Mons at -168° of longitude and an other over Ozza Mons at -163° of longitude. The amplitude of these waves is of about ± 1.5 K for the first one and about ± 1 K for the last one. The latitudinal expansion is about 20°.

LIR observed one main wave above Ozza Mons with an amplitude of ± 2 K and an extension 417 of 30° as well as a second wave of a few degrees of latitude associated with Maat Mons (Kouyama et al., 2017). The main resolved wave is similar to the observations, with however sharp 419 morphology that may be due to the abrupt terrain elevation; the second wave is more extended 420 in latitude than in the observations. These waves are obtained for the beginning of the afternoon 421 when the amplitude is maximum, whereas LIR observed the maximum in the middle of the afternoon. The waves resolved by the model are symmetrical to the obstacle, meaning the 423 latitudinal expansion towards the north and towards the south is the same, while LIR observed 424 non-symmetrical waves attributed to the complex terrain. 425

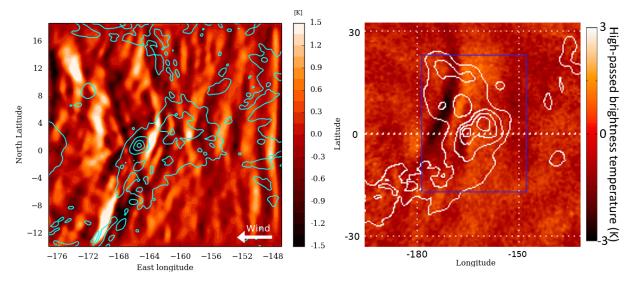


Figure 12: Left: Temperature anomaly (K) at the top of the cloud in the afternoon. Cyan contours show topography every 1.6 km (Fig. 2). Direction of the zonal is indicated with the white arrow. Right: Temperature anomaly (K) at the top of the cloud observed by Akatsuki/LIR adapted from Kouyama et al. (2017). White and cyan lines are the topography. Blue lines on the right panel show the mesoscale domain.

The generation and propagation of the waves are sensitive to the wind and stability condi-

tions close to the surface and therefore to physical representations within the model, for example
the radiative transfer. The Venus GCM may not represent fully accurate surface conditions,
especially for winds, as well as their evolution with time. These differences could explain that,
while the overall bow-shaped wave is reproduced in our Venus mesoscale simulation, some
discrepancies with the observations do exist.

$_{ ext{32}}$ 5.2 Beta Regio

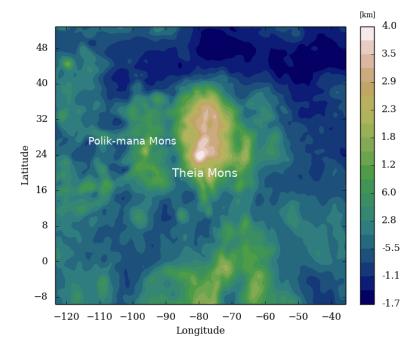


Figure 13: Elevation map (km) of the selected domain for Beta Regio with a resolution of 30 km.

Figure 13 shows the selected domain Beta Regio with a resolution of 30 km, where the 433 highest elevation point is Theia Mons at -80° of longitude and 30° of latitude. The temperature 434 anomaly at the top of the cloud is shown in left panel of Figure 14. Two distinct stationary waves are visible, a main one above Theia Mons and a smaller one above Polik-mana Mons 436 at 30° of latitude and -100°. These two waves are observed by Akatsuki/LIR with the same 437 relative size visible in the right panel of Figure 14. The bow shape is visible with an amplitude 438 of ± 1.5 K. A difference with previous anomaly is the asymmetry of the waves, which is more 439 developed towards the North. This non-symmetrical shape is not clearly observed above Beta 440 Regio in LIR images (Kouyama et al., 2017) but visible in UV images (Kitahara et al., 2019). The latitude of the region, 30°, may have an impact on the morphology of the wave. 442

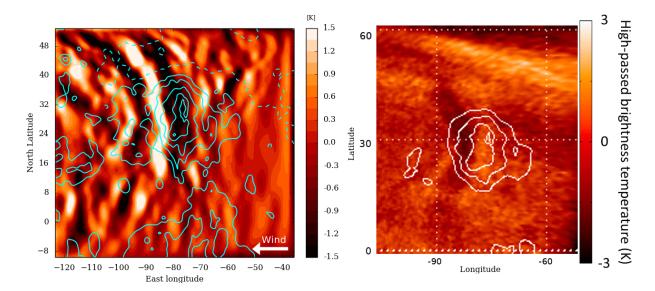


Figure 14: Left: Temperature anomaly (K) at the top of the cloud in late afternoon. Cyan contours show topography every 850 m (Fig. 13). Direction of the zonal is indicated with the white arrow. Right: Temperature anomaly (K) at the top of the cloud observed by Akatsuki/LIR adapted from Kouyama et al. (2017). White and cyan lines are the topography.

443 6 Polar regions

The highest topographical point is Maxwell Montes peaking at approximately 10 km at 65°N 444 latitude. This is a site of interest in orographic gravity waves on Venus. Unfortunately, the orbit of Akatsuki is equatorial and therefore the spacecraft cannot observe the atmospheric activity 446 in polar regions; Venus Express had an elliptical polar orbit suited to study the south pole, but not the north pole. To study the generation of orographic waves above Maxwell Montes, 448 and more generally in the polar regions, mesoscale simulations can be performed with polar stereographic projection over both poles for comparison. The chosen domains for North (right) 450 and South pole (left) are shown in Figure 15, with a resolution of 40 km for both domains. 451 Recent improvements of the IPSL Venus GCM used to provide initial and boundary for our 452 Venus mesoscale model, especially in the polar regions, ensure a correct large-scale forcing with the inclusion of the cold collar and mid-to-high-latitude jets (Garate-Lopez and Lebonnois, 454 2018). 455 Figure 16 shows the temperature anomaly at the top of the cloud. Transient waves rotating 456

Figure 16 shows the temperature anomaly at the top of the cloud. Transient waves rotating around the planet are visible in both polar regions down to \pm 60° with an amplitude larger than 5 K. The wave structure and amplitude are similar for both regions meaning that the underlying topography has hardly any impact on the temperature anomaly at cloud top. These waves resemble the planetary streak structure visible in the Akatsuki/IR2 images (Limaye et al.,

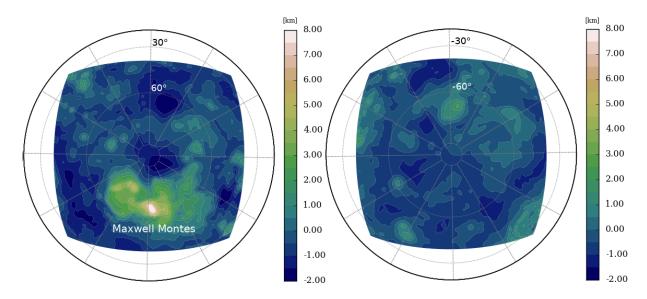


Figure 15: Elevation map (km) of the selected domains for the North pole (left) and the South pole (right) regions with a resolution of 40 km.

2018) and reproduced with GCM modelling (Kashimura et al., 2019).

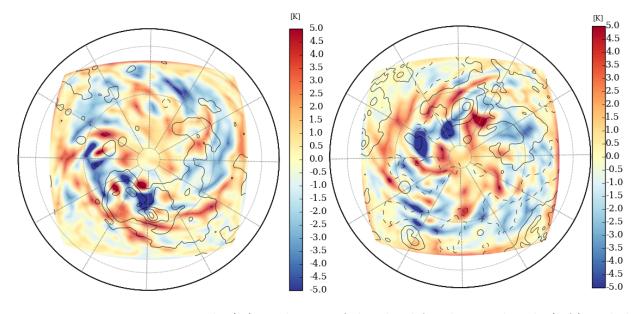


Figure 16: Temperature anomaly (K) at the top of the cloud for the North pole (left) and the South pole (right) regions. Black contours show topography every 1.6 km for the North pole and every 800 m for the South pole (Fig. 15).

However, mountain waves are generated by Ishtar Terra. The vertical velocity above
Maxwell Montes is shown in Figure 17. These waves propagate vertically and encounter the two
low static stability regions but do not yield any stationary temperature anomaly at cloud-top.
The two barriers are thicker than that for the other cases, 22 against 17 km for the first one and
against 4 km for the convective layer. The increase of the cloud convective layer thickness is
expected from observations (Tellmann et al., 2009; Haus et al., 2014) and modelling (Imamura
et al., 2014; Lefèvre et al., 2018), yet few observations have been performed regarding the mixed

layer in the deep atmosphere, especially regarding the variation of depth with latitude and local time. Only the temperature profiles of the Pioneer Venus probes (Seiff et al., 1980) would be available for such an analysis.

As is discussed in section 3, the two mixed layers in the lower atmosphere of Venus act 472 as barriers for gravity waves. For the first barrier (altitudes 15-35 km) with ω equals to 473 $2.3 ext{ } 10^{-4} ext{ s}^{-1}$, N to $1.6 ext{ } 10^{-3} ext{ s}^{-1}$ and a horizontal wavelength of 200 km, the transmission is 474 only of 13 %. For the second barrier (altitudes 45-55 km) with ω equals to 1.1 10^{-3} s⁻¹, N to $7.5 ext{ } 10^{-3} ext{ s}^{-1}$ and the same horizontal wavelength, the transmission drops to 63 %. The 476 orographic wave is therefore strongly affected by propagating through the two mixed layers (especially the lowermost one). As a result, the cloud top temperature anomaly induced by 478 gravity waves in polar regions is smaller than the ones in the equatorial regions, and negligible against the cloud top transient waves. The large amplitude of the transient polar waves could 480 prevent the visibility of the comparatively-low stationary gravity-wave perturbation and explain 481 the non-observation of stationary waves in Venus Express/VIRTIS data at latitudes above 65°S 482 (Peralta et al., 2017). The saturation of the waves is here again unlikely, so contrary to mixed 483 layers acting as efficient barriers, it does not seem a plausible mechanism to explain the lack of 484 observed gravity-wave stationary wave in polar regions. 485

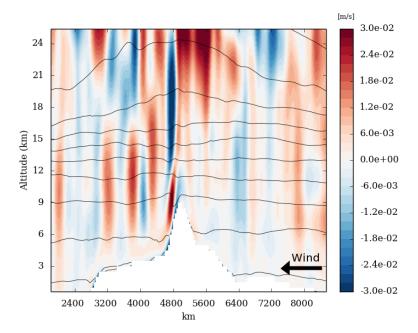


Figure 17: Vertical cross-section of the vertical wind (m s⁻¹) between the surface and approximately 55 km. Please note that the cross-section is not at a constant latitude. Contours represent the potential temperature.

⁴⁸⁶ 7 Conclusion

We present here the first mesocale model applied to Venus, in which the WRF dynamical core 487 is coupled the set of physical parameterizations developed for the IPSL Venus GCM, notably 488 the radiative transfer to compute the solar and IR rates during the simulations. Focusing 489 on three areas of interest, the model resolves bow shape stationary waves with an amplitude 490 around 1.5 K. The lifetime of the waves is about ten Earth days. The maximum amplitude 491 of the waves are in the afternoon, close to the terminator for Aphrodite Terra, earlier for the 492 two another cases. The characteristics and morphology of the waves observed by Akatsuki are 493 overall well reproduced by the model. 494

Theses gravity waves are generated by the large-scale flow forced to go over Venus' moun-495 tains. Propagating vertically, those orographic gravity waves encounter two layers of low static 496 stability, the mixed layer (20-32 km) and the convective layer (47-55 km) where some energy is 497 transmitted through the layers via tunneling phenomenon. The deep mixed layer is the most 498 critical barrier for the wave, and comprehensive studies about the variability of this layer with 499 latitude and local time would improve the understanding of the propagation of the mountain 500 waves. The presence of these two layers generate trapped lee waves that propagate horizontally 501 with some vertical leakage due to their large horizontal wavelength. 502

The variations of the wave characteristics with local time is imputed to the stability of the atmosphere close to the surface. In the afternoon, the first 4-5 km of the atmosphere are more stable that at night or at noon, which favors the vertical propagation of the waves.

The waves extract momentum from the surface with a flux around 2 Pa and deposit this momentum at around 30 km. Values of parameters used in the orographic parameterization of Navarro et al. (2018) are therefore be confirmed by our mesoscale model which resolves the emission and propagation of gravity waves from the surface to 100-km altitude. At the cloud top, the waves induce a deceleration of several meters per second over a Venus day, consistent with *Akatsuki* measurements.

Temperature anomalies above Venus' polar regions have also been explored with our mesoscale model. Transient waves rotating around the poles dominate the signal and the influence of the underlying topography is not noticeable. However, mountain waves are generated above Ishtar

Terra – similarly to the waves generated by the other main mountains at lower latitudes. The

increase of the deep atmosphere neutral barrier thickness strongly affects the amplitude of the orographic waves, which become negligible against the circumpolar transient waves.

Surface wind and the two mixed layers are key factors for the generation and propagation of mountain waves, a sensitivity study should be therefore considered in future work. Such study will imply complex changes in the IPSL Venus GCM dynamics and cloud model.

Additional simulations may be performed in the future for several other regions of interest,
like Pheobe Regio at the Equator with a complex bow-shape morphology witnessed by Akatsuki,
Gula Mons and Bell Regio, two sharp mountains at respectively 20°N and 30°N and Imdr
Regio composed of two sharp mountains at 45°S to investigate the influence of the impact of
the morphology of the mountain, of the conditions near the surface and of the latitude on the
temperature anomaly. Moreover the observations of stationary waves by VEx/VIRTIS in the
southern hemisphere in the nightside with no apparent dependence with the local time (Peralta
et al., 2017) are features to be investigated.

The LMD Mesoscale model for Venus based on WRF (Skamarock and Klemp, 2008) can be applied to the study of several other regional-scale phenomena, in particular slope winds, which were studied on Earth (Bromwich et al., 2001) and on Mars (Spiga et al., 2011), and play a key role in the vertical extension of the planetary boundary layer convection (Lebonnois et al., 2018) and local meteorology in general.

Implementation of the photochemistry and microphysics schemes developed at IPSL in the
Venus mesoscale model is planned to investigate the influence of mountains on the chemistry
and the cloud formation. Explosive volcanism could explain SO₂ anomaly at the top of the cloud
(Esposito et al., 1988): the study of the vertical transport and the impact of the waves on SO₂
(Glaze, 1999) and other volatile like water (Airey et al., 2015) could constrain this phenomenon,
especially above Atla Regio where hot spots have been observed with *Venus Express* suggesting
active volcanism (Shalygin et al., 2015). Atmospheric variability on its own, without the need
to invoke active volcanism, could also explain the observed SO₂ variability (Marcq et al., 2013).

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