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# Wide-angle redshift-space distortions at quasi-linear scales: cross-correlation functions from Zel'dovich approximation 

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#### Abstract

Redshift-space distortions (RSD) in galaxy redshift surveys generally break both the isotropy and homogeneity of galaxy distribution. While the former aspect is particularly highlighted as a probe of growth of structure induced by gravity, the latter aspect, often quoted as wide-angle RSD but ignored in most of the cases, will become important and critical to account for as increasing the statistical precision in next-generation surveys. However, the impact of wideangle RSD has been mostly studied using linear perturbation theory. In this paper, employing the Zel'dovich approximation, i.e. first-order Lagrangian perturbation theory for gravitational evolution of matter fluctuations, we present a quasi-linear treatment of wide-angle RSD, and compute the cross-correlation function. The present formalism consistently reproduces linear theory results, and can be easily extended to incorporate relativistic corrections (e.g. gravitational redshift).


Key words: methods: analytical-galaxies: distances and redshifts - cosmology: theory -large-scale structure of Universe.

## 1 INTRODUCTION

The large-scale structure of the Universe, as partly seen by galaxy distributions, has evolved dominantly under the influence of gravity and cosmic expansion. While the spatial inhomogeneity of matter and galaxy distribution is in nature random and stochastic, it is supposed to be statistically homogeneous and isotropic. However, the observation can break homogeneity and isotropy. In particular, the galaxy distribution observed via spectroscopic survey appears distorted along the observer's line of sight (LOS) due to the contribution of peculiar velocities to the measured redshift of a galaxy, referred to as the redshift-space distortions (RSD).

RSD generally complicates the data analysis and cosmological interpretation of the observed galaxy clustering, but one advantage may be that RSD provides an additional information on the velocity field at large scales. Indeed, taking the distant-observer or planeparallel limit, the statistical homogeneity is approximately restored, and the apparent anisotropies induced by RSD are characterized

[^0]well by the multipole expansion with respect to the LOS direction of the distant observer. On large scales, such anisotropies are described by linear theory only with few low multipoles, which tell us that the strength of anisotropies is directly related to the growth of cosmic structure induced by gravity (Kaiser 1987; Hamilton 1992). In this respect, the measurement of clustering anisotropies caused by RSD offers an exciting opportunity to probe gravity on cosmological scales. This explains why there have been so far numerous works in both theory and observation to model, predict, and measure the anisotropies of galaxy clustering, leading to fruitful cosmological constraints (e.g. Linder 2008; Percival \& White 2009; Song \& Percival 2009; Taruya, Nishimichi \& Saito 2010; Vlah et al. 2012; Beutler et al. 2014; Carlson, Reid \& White 2013; Alam et al. 2017a).
With the wealth of large data set from future galaxy surveys, the statistical precision will be substantially improved, and it will help to further tighten the cosmological constraints (see Weinberg et al. 2013, for a review). However, one must be careful in characterizing the galaxy clustering. Since the statistical homogeneity is not fully ensured in the presence of RSD, and the techniques developed so far in both measurement and theoretical predictions heavily rely on
statistical homogeneity, the impact of its violation, often quoted as wide-angle effect, can introduce systematics in constraining cosmology with RSD measurement, potentially leading to a biased cosmological result.

Indeed, the impact of wide-angle effect on RSD have been long studied in both analytical and numerical approaches, and there is thus a large number of literature on this topic, including early works (Fisher, Scharf \& Lahav 1994; Heavens \& Taylor 1995; Hamilton \& Culhane 1996; Zaroubi \& Hoffman 1996; Szalay, Matsubara \& Landy 1998; Matsubara 2000). For cosmological data analyses including the wide-angle effect, see e.g. Tadros et al. (1999), Matsubara, Szalay \& Landy (2000), Pope et al. (2004), and Okumura et al. (2008).

One important consequence of the wide-angle effect is that when naively applying the multipole expansion in a certain LOS definition, it produces new contributions not only at even multipoles but also at odd multipoles. Indeed, such contributions have been recently detected and measured at a statistically significant level from SDSS BOSS DR12 (Beutler, Castorina \& Zhang 2019) (see Gaztanaga, Bonvin \& Hui 2017, for the analysis using DR10). This immediately implies that as increasing the statistical precision, the wide-angle effect can definitely give an impact on cosmological interpretation from future surveys, and theoretical prediction and measurement technique beyond the distant-observer limit have to be developed from a modern viewpoint (Yoo \& Seljak 2015; Castorina \& White 2018a,b; Beutler et al. 2019).

There is also another motivation why we need to care about wide-angle effect. In general, the observed galaxy distributions are further distorted due to the relativistic corrections that arise from the light propagation in an inhomogeneous universe. For instance, a measurement of redshift receives corrections not only from galaxy's peculiar motion by Doppler effect, but also from the gravity induced by galaxy and foreground large-scale structure, i.e. gravitational redshift and integrated Sachs-Wolfe effects (e.g. Yoo, Fitzpatrick \& Zaldarriaga 2009; Yoo 2010; Bonvin \& Durrer 2011; Challinor \& Lewis 2011; Yoo et al. 2012). Those relativistic contributions are known to produce anisotropies in the observed galaxy distributions (e.g. Bertacca et al. 2012; Raccanelli et al. 2018), and some of the effects can generate odd multipoles in the cross-correlation function and cross power spectrum between different biased objects (McDonald 2009; Bonvin, Hui \& Gaztañaga 2014). Recent numerical studies taking consistently the relativistic effects into account suggest that relativistic contributions become manifest at large scales (Breton et al. 2019), and could be detected in future surveys (see Alam et al. 2017b, for a recent measurement). Thus, a precision measurement of odd multipoles can offer an interesting cosmological test of general relativity, alternative to the standard RSD measurement. Nevertheless, relativistic contributions are basically tiny, and one must be careful to discriminate from the wide-angle contributions, which also produce non-vanishing odd multipoles.

In these respects, a precision theoretical modelling of RSD taking account of wide-angle effect is a rather critical issue. Beyond linear theory, however, except the numerical study using $N$-body simulations (e.g. Raccanelli et al. 2010), little analytical work has been done (but see Shaw \& Lewis 2008). Recently, Castorina \& White (2018b) have presented the first quasi-linear treatment of the wide-angle effects based on the Zel'dovich approximation (Zel'dovich 1970; Shandarin \& Zeldovich 1989; Novikov 2010), particularly focusing on the autocorrelation function. In this paper, adopting the same Zel'dovich approximation, we generalize it to the calculation of the cross-correlation function of galaxies/haloes. Along the lines of generalization, we clarify similarities and differences between our formalism and that of Castorina \& White
(2018b), who actually considered part of the wide-angle terms with the Zel'dovich approximation. Our formalism takes into account all possible wide-angle terms relevant at the Newtonian level, assuming the uniform radial selection function. With this treatment, it is shown to be consistent with linear theory of wide-angle RSD discussed in the literature. We then study the impact of wide-angle effects in the cross-correlation functions. The cross-correlation between different biased objects is known to break the symmetry of the pair counting, and in the presence of wide-angle effects, this can produce an additional contribution to the anisotropies in the two-point statistics. Comparing the Zel'dovich approximation with linear theory predictions as well as $N$-body simulations, we quantitatively investigate the possible impact of its non-linear effect, particularly focusing on the weakly non-linear scales. In a separate paper, on the basis of the formalism in this paper, we will further incorporate the relativistic corrections into the prediction of cross-correlation functions, and make a detailed comparison between analytical predictions and simulations with relativistic corrections.

This paper is organized as follows. In Section 2, after briefly mentioning the RSD, we present an analytical framework to compute the cross-correlation functions at quasi-linear regime, employing the Zel'dovich approximation. Several remarks on the statistical calculation are addressed together with the comments on the treatment by Castorina \& White (2018b). Then, in Section 3, we present the results based on our quasi-linear formalism, and quantify the non-linear impacts of the wide-angle effects on the cross-correlation functions, which are compared with linear theory predictions and N -body simulations. Our important findings and an implications are summarized in Section 4. Derivation of the analytical expressions in Zel'dovich approximation as well as the linear theory formulas for cross-correlation functions are presented in detail in Appendix A and D, respectively, together with supplemental formulas and proof in Appendices B and C.

## 2 WIDE-ANGLE CROSS-CORRELATION FUNCTION IN REDSHIFT SPACE

In this paper, we are interested in computing and predicting the correlation function in redshift space without taking the distantobserver or plane-parallel limit. Here, we only consider the Doppler effect as a major source to cause RSD. An extension to include relativistic correction will be studied in a separate paper. In the presence of Doppler effect only, the comoving position at a given redshift $z$ in redshift space, $s$, is related to the real-space counterpart $x$ through
$s=\boldsymbol{x}+\frac{1}{a H}(\boldsymbol{v} \cdot \hat{\boldsymbol{x}}) \hat{\boldsymbol{x}}$,
where $\boldsymbol{v}$ is the velocity field at real-space position $\boldsymbol{x}$, and $\hat{\boldsymbol{x}}$ is the unit vector defined by $\hat{\boldsymbol{x}} \equiv \boldsymbol{x} /|\boldsymbol{x}|$. The quantities $a$ and $H$ are, respectively, the scale factor of the Universe and Hubble parameter at a given redshift $z$. Note that in the distant-observer limit, observer's LOS vector, $\hat{\boldsymbol{x}}$, is replaced with a specific direction vector $\hat{z}$.

With the definition of redshift space given above, consider the density fluctuations. Denoting the number density field of the objects $X$ by $n_{X}^{(S)}(s)$, we define
$\delta_{X}^{(\mathrm{S})}(\boldsymbol{s})=\frac{n_{X}^{(\mathrm{S})}(\boldsymbol{s})}{\left\langle n_{X}^{(\mathrm{S})}(\boldsymbol{s})\right\rangle}-1$.


Figure 1. Geometric configuration of redshift-space cross-correlation function. Along the line-of-sight direction $\boldsymbol{d}$, a pair of objects $X$ and $Y$ is found at the positions $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$, where the density fields, denoted by $\delta_{X}^{(\mathrm{S})}$ and $\delta_{Y}^{(S)}$, is measured. The separation between these two objects is defined by $\boldsymbol{s} \equiv \boldsymbol{s}_{2}-s_{1}$. Misalignment between $\boldsymbol{s}$ and $\boldsymbol{d}$ is characterized by the angle $\varphi$ or the directional cosine given by $\mu \equiv \cos \varphi$. Note that at this point, the meaning of line-of-sight direction is not well defined, and will be later specified (see Section 3).

The bracket $\langle\cdots\rangle$ stands for the ensemble average. Then, the crosscorrelation function between different species $X$ and $Y$ is given by
$\xi_{X Y}^{(S)}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) \equiv\left\langle\delta_{X}^{(S)}\left(\boldsymbol{s}_{1}\right) \delta_{Y}^{(S)}\left(\boldsymbol{s}_{2}\right)\right\rangle$.
Note that the cross-correlation function defined above is, as opposed to the one in real space, not simply described by the function of the separation between two objects. In the presence of observer's LOS vector $\hat{\boldsymbol{x}}$ in equation (1), both the statistical homogeneity and isotropy of the galaxy distributions no longer hold, and we generally need three variables to characterize the correlation function in redshift space. That is, $\xi_{X Y}^{(S)}$ is given as a function of the distances to the objects $\left|\boldsymbol{s}_{1}\right|$ and $\left|\boldsymbol{s}_{2}\right|$, and separation $s \equiv\left|s_{2}-s_{1}\right|$ (see Fig. 1). In other words, the correlation function is described with the triangle characterized by the vectors, $\boldsymbol{s}_{1}, \boldsymbol{s}_{2}$, and $\boldsymbol{s} \equiv \boldsymbol{s}_{2}-\boldsymbol{s}_{1}$, and it is invariant under the transformation such that the shape of this triangle remains unchanged.

### 2.1 Zel'dovich approximation

Our primary interest is to develop the quasi-linear theory of wide-angle redshift-space correlation function. For this purpose, we follow Castorina \& White (2018b) and use the Zel'dovich approximation, which allows us to predict the position and motion of mass element, given an initial condition of density field (Zel'dovich 1970; Shandarin \& Zeldovich 1989; Novikov 2010). An important building block in the Zel'dovich approximation is the displacement field of each mass element, which is given as a function of Lagrangian coordinate (initial position of each mass element), $\boldsymbol{q}$. In what follows, we assume that the objects of our interest to measure the correlation function simply follow the velocity flow of mass distributions (i.e. no velocity bias). Denoting the displacement field
by $\boldsymbol{\Psi}(\boldsymbol{q})$, the Eulerian position $\boldsymbol{x}$ and velocity of mass element at $\boldsymbol{x}$ are then expressed as
$\boldsymbol{x}=\boldsymbol{q}+\boldsymbol{\Psi}(\boldsymbol{q}), \quad \boldsymbol{v}(\boldsymbol{x})=a \frac{\mathrm{~d} \boldsymbol{\Psi}(\boldsymbol{q})}{\mathrm{d} t}$.
The Zel'dovich approximation gives a simple analytical expression for the displacement field in terms of the (Lagrangian) linear density field $\delta_{\mathrm{L}}$ as

$$
\begin{equation*}
\nabla \cdot \boldsymbol{\Psi}_{\mathrm{ZA}}(\boldsymbol{q})=-\delta_{\mathrm{L}}(\boldsymbol{q}) \tag{5}
\end{equation*}
$$

Recalling that the linear density field is related to initial density field $\delta_{0}$ through $\delta_{\mathrm{L}}=D_{+}(t) \delta_{0}$ with $D_{+}$being linear growth factor, we have
$\boldsymbol{v}=a H f(t) \Psi_{\mathrm{ZA}}(\boldsymbol{q})$.
Here, the function $f$ is linear growth rate defined by
$f(t) \equiv \frac{\mathrm{d} \ln D_{+}(t)}{\mathrm{d} \ln a(t)}$.
Substituting these relations into equation (1), we obtain (hereafter we omit the subscript ${ }_{\mathrm{ZA}}$, and simply write $\boldsymbol{\Psi}$ ),

$$
\begin{align*}
s_{i} & =q_{i}+\left\{\delta_{i j}+f \hat{x}_{i} \hat{x}_{j}\right\} \Psi_{j}(\boldsymbol{q}) \\
& \simeq q_{i}+\left\{\delta_{i j}+f \hat{q}_{i} \hat{q}_{j}\right\} \Psi_{j}(\boldsymbol{q}) . \tag{8}
\end{align*}
$$

Note that the second line is valid at first-order Lagrangian perturbation theory (i.e. Zel'dovich approximation). Here, we used the Einstein summation convention. The subscripts $i$ and $j$ take values 1, 2 , or 3 . Equation (8) gives a mapping relation between redshift space and Lagrangian space, and is a basis to compute statistical quantities in redshift space given the statistical properties in Lagrangian space.

### 2.2 Analytical expression

Once established the relation between Eulerian- and Lagrangianspace positions, we now express the observed number density field of the population $X$, defined in redshift space, $n_{X}^{(S)}$, in terms of the Lagrangian-space quantities. In what follows, we assume the linear bias relation for all objects to cross-correlate. Note that the extension to incorporate the non-linear Lagrangian bias into statistical calculation has been made in the case of distant-observer or plane-parallel limit by Carlson et al. (2013), Wang, Reid \& White (2014), and White (2014) (see also Matsubara 2008b, 2014, for slightly different formalism).

Using the number conservation in each space, we have

$$
\begin{equation*}
n_{X}^{(\mathrm{S})}(\boldsymbol{s}) \mathrm{d}^{3} \boldsymbol{s}=n_{X}(\boldsymbol{x}) \mathrm{d}^{3} \boldsymbol{x}=\bar{n}_{X}\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\} \mathrm{d}^{3} \boldsymbol{q}, \tag{9}
\end{equation*}
$$

where $\bar{n}_{X}$ is the mean number density at a given redshift, and we assume it to be constant over the survey region. The quantity $b_{X}^{\mathrm{L}}$ is the Lagrangian linear bias parameter for the population $X$, which is related to the Eulerian linear bias $b_{X}$ through $b_{X}=1+b_{X}^{\mathrm{L}}$. Note that $\bar{n}_{X}$ does not in general coincide with the mean density in redshift space, $\left\langle n_{X}^{(S)}(s)\right\rangle$, unless we take distant-observer or plane-parallel limit. Equation (9) is then rewritten with

$$
\begin{align*}
n_{X}^{(\mathrm{S})}(\boldsymbol{s}) & =\bar{n}_{X}\left|\frac{\partial \boldsymbol{s}}{\partial \boldsymbol{q}}\right|^{-1}\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\} \\
& =\bar{n}_{X} \int \mathrm{~d}^{3} \boldsymbol{q} \delta_{\mathrm{D}}\left[\boldsymbol{s}-\boldsymbol{q}-\boldsymbol{\Psi}^{(\mathrm{S})}(\boldsymbol{q})\right]\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\} \\
& =\bar{n}_{X} \int \frac{\mathrm{~d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot\left\{\boldsymbol{s}-\boldsymbol{q}-\boldsymbol{\Psi}^{(\mathrm{S})}(\boldsymbol{q})\right\}}\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\}, \tag{10}
\end{align*}
$$

where the quantity $\delta_{\mathrm{D}}$ is the Dirac delta function, which is reexpressed in the third line, introducing the auxiliary variable (wave vector), $\boldsymbol{k}$. Here, we define the redshift-space displacement field, $\boldsymbol{\Psi}^{(\mathrm{S})}$ (see equation 8):

$$
\begin{align*}
\Psi_{i}^{(\mathrm{S})}(\boldsymbol{q}) & =\left(\delta_{i j}+f \hat{q}_{i} \hat{q}_{j}\right) \Psi_{j}(\boldsymbol{q}) \\
& \equiv R_{i j}(\hat{\boldsymbol{q}}) \Psi_{j}(\boldsymbol{q}) \tag{11}
\end{align*}
$$

Substituting equation () into the redshift-space density fluctuation given at equation (2), the cross-correlation function $\xi_{X Y}^{(S)}$ at equation (3) is expressed as

$$
\begin{align*}
1+\xi_{X Y}^{(S)}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) & =\left\langle\left\{1+\delta_{X}^{(S)}\left(\boldsymbol{s}_{1}\right)\right\}\left\{1+\delta_{Y}^{(S)}\left(\boldsymbol{s}_{2}\right)\right\}\right\rangle \\
& =\frac{D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)}{R_{X}\left(\boldsymbol{s}_{1}\right) R_{Y}\left(\boldsymbol{s}_{2}\right)} \tag{12}
\end{align*}
$$

with the functions given at the denominator and numerator, $R_{X, Y}$ and $D_{X} D_{Y}$, respectively, defined by

$$
\begin{align*}
R_{X, Y}(\boldsymbol{s}) \equiv & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot\{\boldsymbol{s}-\boldsymbol{q}\}} \\
& \times\left\langle\mathrm{e}^{-i \boldsymbol{k} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}(\boldsymbol{q})}\left\{1+b_{X, Y}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\}\right\rangle  \tag{13}\\
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) \equiv & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \\
& \times \mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left\{\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}+i \boldsymbol{k}_{2} \cdot\left\{\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right\}} \\
& \times\left\langle\mathrm{e}^{-i \boldsymbol{k}_{1} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}\left(\boldsymbol{q}_{1}\right)-i \boldsymbol{k}_{2} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}\left(\boldsymbol{q}_{2}\right)}\right. \\
& \left.\times\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}\left(\boldsymbol{q}_{1}\right)\right\}\left\{1+b_{Y}^{\mathrm{L}} \delta_{\mathrm{L}}\left(\boldsymbol{q}_{2}\right)\right\}\right\rangle . \tag{14}
\end{align*}
$$

Note that the ensemble average in these expressions is evaluated with respect to the randomness of linear density field $\delta_{\mathrm{L}}$, which is, in Lagrangian space, statistically homogeneous and isotropic. Thus, one may expect that taking the average, quantities with brackets are expressed, after all, as function of separation only, i.e. $\left|\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right|$. If this is the case, the expressions given above can be drastically simplified under the Gaussian initial condition. Performing analytically the integrals over wavenumbers, $R_{X, Y}$ is found to be 1 , and $D_{X} D_{Y}$ is finally reduced to the form involving threedimensional Gaussian integral, which can be evaluated numerically with a better convergence (Bond \& Couchman 1988; Schneider \& Bartelmann 1995; Fisher \& Nusser 1996; Taylor \& Hamilton 1996, e.g.). However, this simplification can be applied only in the distant-observer or plane-parallel limit. Due to the positiondependent matrix $R_{i j}$ in the displacement field $\Psi^{(\mathrm{S})}$, the brackets have non-trivial dependence of the Lagrangian positions even after taking the averages. This is solely due to the wide-angle RSD that observer's LOS direction varies over the sky, and cannot be taken to be a specific direction.

Thus, taking a proper account of the wide-angle effect, the calculation of equations (13) and (14) ceases to be trivial. Nevertheless, it is still possible to reduce the expressions of $R_{X, Y}$ and $D_{X} D_{Y}$ given above to those involving three- and six-dimensional Gaussian integrals, respectively. In Appendix A, we derive the final forms. The expression of $R_{X, Y}$ is summarized as follows:

$$
\begin{equation*}
R_{X}(\boldsymbol{s})=R_{Y}(\boldsymbol{s})=\int \frac{\mathrm{d}^{3} \boldsymbol{q}}{(2 \pi)^{3 / 2}|\operatorname{det} A|} \mathrm{e}^{-(1 / 2) A_{i j}^{-1}(s-q)_{i}(s-q)_{j}}, \tag{15}
\end{equation*}
$$

where the matrix $A_{i j}$ is defined by
$A_{i j}(\boldsymbol{q}) \equiv\left\langle\Psi_{i}^{(\mathbf{S})}(\boldsymbol{q}) \Psi_{j}^{(\mathbf{S})}(\boldsymbol{q})\right\rangle$.

Note that starting with the expression given at equation (A1), one can also derive an approximate expression in the following analytical form (see Appendix A1):
$R_{X}(s) \simeq 1+\left(2 f+f^{2}\right)\left(\frac{\sigma_{\mathrm{d}}^{2}}{s^{2}}+\frac{\sigma_{\mathrm{d}}^{4}}{s^{4}}+3 \frac{\sigma_{\mathrm{d}}^{6}}{s^{6}}+\cdots\right)$,
which is accurate for the large-distance case with $\sigma_{\mathrm{d}} / s \ll 1$. Here, $\sigma_{\mathrm{d}}$ is the rms of the Lagrangian displacement field, and its explicit expression is given at equation (A29).

On the other hand, for $D_{X} D_{Y}$, we introduce the six-dimensional vectors for Lagrangian and redshift-space positions, $\boldsymbol{Q}$ and $\boldsymbol{S}$, and write these as $\boldsymbol{Q}=\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)$ and $\boldsymbol{S}=\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)$. Then, the correlation term $D_{X} D_{Y}$ is expressed as follows:

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{6} \boldsymbol{Q}}{(2 \pi)^{3}|\operatorname{det} \mathcal{A}|^{1 / 2}} \mathrm{e}^{-(1 / 2) \mathcal{A}_{a b}^{-1}(S-Q)_{a}(S-Q)_{b}} \\
& \times\left[1+b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}\left(\left|\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right|\right)-\mathcal{A}_{c d}^{-1} \mathcal{U}_{c}(S-Q)_{d}\right. \\
& \left.-\left\{\mathcal{A}_{c d}^{-1}-\mathcal{A}_{c e}^{-1} \mathcal{A}_{d f}^{-1}(S-Q)_{e}(S-Q)_{f}\right\} \mathcal{W}_{c d}\right] \tag{18}
\end{align*}
$$

The subscripts $a, b, \ldots$ run over $1-6$. The explicit expressions for the quantities given above, $\mathcal{U}_{a}, \mathcal{A}_{a b}$, and $\mathcal{W}_{a b}$, as well as the $3 \times 3$ matrix $A_{i j}$, are all presented in Appendix A2. Note that the function $D_{X} D_{Y}$ depends on the bias parameters not only explicitly in the coefficient of $\xi_{\mathrm{L}}$ but also implicitly through the definitions of $\mathcal{U}_{a}$ and $\mathcal{W}_{a b}$ (see equations A15 and A16).

In what follows, we use equations (15) and (18) to give quantitative predictions of wide-angle cross-correlation function $\xi_{X Y}^{(\mathrm{S})}$. Numerical integrals involved in these expressions are performed specifically with cuhre routine in the CUBA library (Hahn 2005). ${ }^{1}$

### 2.3 Relation to Castorina \& White (2018b)

Before closing this section, we compare our formalism in Section 2 with the one given in Castorina \& White (2018b), who have first presented the analytical calculation of wide-angle effects beyond linear theory prediction based on the same Zel'dovich approximation as we adopted. To be precise, Castorina \& White (2018b) considered part of the wide-angle effects. Here, we clarify the differences between our and their treatments.

Let us first check that the present formalism correctly reproduces the well-known linear theory result with wide-angle corrections under the uniform radial selection function. We derive the linearorder expression for the redshift-space density fluctuation, $\delta_{X}^{(S)}$, given at equation (2). Substituting the expression for the number density field at equation (10) into equation (2), we Taylorexpand the exponents. At the leading order, the denominator $\left\langle n_{X}^{(S)}\right\rangle$ does not play any role, and the expansion of the numerator leads to

$$
\begin{align*}
\delta_{X, \operatorname{lin}}^{(\mathrm{S})}(\boldsymbol{s})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot(\boldsymbol{s}-\boldsymbol{q})} \\
& \times\left[b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})-i \boldsymbol{k} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}(\boldsymbol{q})\right] . \tag{19}
\end{align*}
$$

Recalling that $\Psi^{(S)}$ is the displacement field defined in redshift space, and it is related to the real-space displacement field through

[^1]\[

$$
\begin{align*}
\Psi_{i}^{(\mathrm{S})}=\left(\delta_{i j}\right. & \left.+f \hat{q}_{i} \hat{q}_{j}\right) \Psi_{j}(\text { see equation 11), we have } \\
\delta_{X, \operatorname{lin}}^{(\mathrm{S})}(\boldsymbol{s})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot(\boldsymbol{s}-\boldsymbol{q})} \\
& \times\left[b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})-i \boldsymbol{k} \cdot \boldsymbol{\Psi}(\boldsymbol{q})-i f(\boldsymbol{k} \cdot \hat{\boldsymbol{q}})\{\hat{\boldsymbol{q}} \cdot \boldsymbol{\Psi}(\boldsymbol{q})\}\right] \tag{20}
\end{align*}
$$
\]

which can be recast as
$\delta_{X, \operatorname{lin}}^{(S)}(\boldsymbol{s})=b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{s})-\nabla_{s} \cdot \boldsymbol{\Psi}(\boldsymbol{s})-f \nabla_{s} \cdot[\{\hat{\boldsymbol{s}} \cdot \boldsymbol{\Psi}(\boldsymbol{s})\} \hat{\boldsymbol{s}}]$.
Here, $\hat{\boldsymbol{s}}$ is unit vector given by $\hat{\boldsymbol{s}} \equiv \boldsymbol{s} /|\boldsymbol{s}|$, and the operator $\nabla_{s}$ stands for the divergence in the redshift-space coordinates. Note that the second and third terms at right-hand side have been derived from equation (20) by rewriting the factor $i \boldsymbol{k} \mathrm{e}^{i \boldsymbol{k} \cdot(\boldsymbol{S}-\boldsymbol{q})}$ in the integrand with $-\nabla_{q} \mathrm{e}^{i \boldsymbol{k} \cdot(\boldsymbol{s}-\boldsymbol{q})}$, and performing the integral over $\boldsymbol{k}$. Using the formulas $\partial \hat{s}_{i} / \partial s_{j}=\left(\delta_{i j}-\hat{s}_{i} \hat{s}_{j}\right) /|\boldsymbol{s}|$ and $\left(\hat{\boldsymbol{s}} \cdot \nabla_{s}\right) \hat{\boldsymbol{s}}=0$, the last term of the above expression is rewritten with
$\nabla_{s} \cdot[\{\hat{\boldsymbol{s}} \cdot \boldsymbol{\Psi}(\boldsymbol{s})\} \hat{\boldsymbol{s}}]=\left\{\frac{2}{s}+\left(\hat{\boldsymbol{s}} \cdot \nabla_{s}\right)\right\}\{\boldsymbol{\Psi}(\boldsymbol{s}) \cdot \hat{\boldsymbol{s}}\}$.
Further, in Zel'dovich approximation, the real-space displacement field and its spatial derivative are related to the velocity and density field through $\boldsymbol{v}=a H f \boldsymbol{\Psi}$ and $\nabla_{s} \cdot \Psi=-\delta_{\mathrm{L}}$ (see equations 5 and 6). Then, equation (21) is finally reduced to the following form:
$\delta_{X, \operatorname{lin}}^{(S)}(\boldsymbol{s})=b_{X} \delta_{\mathrm{L}}(\boldsymbol{s})-\frac{1}{a H}\left\{\frac{2}{s}+\left(\hat{\boldsymbol{s}} \cdot \nabla_{s}\right)\right\}(\boldsymbol{v} \cdot \hat{\boldsymbol{s}})$,
where the factor $1+b_{X}^{\mathrm{L}}$ has been replaced with the Eulerian linear bias parameter $b_{X}$. Equation (23) coincides with the wellknown result for redshift-space linear density field taking account of the wide-angle effects, assuming a uniform radial selection function (e.g. Kaiser 1987; Szalay et al. 1998; Yoo \& Seljak 2015). ${ }^{2}$ Note that the term proportional to $(2 / s)(\boldsymbol{v} \cdot \hat{\boldsymbol{s}})$ is often called the selection function terms, and in general cases with nonuniform radial selection function, the factor 2 is replaced with $\alpha(r)=2+\mathrm{d} \ln \phi(r) / \mathrm{d} \ln r$, with $\phi(r)$ being the radial selection function slowly varying function of the radial distance, $r$ (e.g. Kaiser 1987; Szalay et al. 1998; Yoo \& Seljak 2015; Castorina \& White 2018a).

In Appendix C, for the sake of the completeness, we also show that our formalism, starting from the expression given at equation (12), consistently reproduces the linear cross-correlation function with wide-angle effects. Note that in this case, not only the numerator in equation (12) but also the denominator, i.e. product of mean density, $R_{X} R_{Y}$, play a role, and have to be taken into consideration properly.
Let us next look at the linear density field based on the treatment by Castorina \& White (2018b). A crucial assumption or proposition is to rewrite the redshift-space displacement field $\boldsymbol{\Psi}^{(\mathrm{S})}$, given at equation (11), with
${ }^{\mathrm{CW}} \Psi_{i}^{(\mathrm{S})}(\boldsymbol{q})=\left(\delta_{i j}+f \hat{s}_{i} \hat{\bar{s}}_{j}\right) \Psi_{j}(\boldsymbol{q})$,
where the redshift-position $s$ is linked to the Lagrangian counterpart $\boldsymbol{q}$ through equation (8). Seemingly, equation (24) is relevant, and looks equivalent to equation (11) at linear order. However, substituting it into (19) and repeating the same calculation as given

[^2]above, we obtain the following expression: ${ }^{3}$
${ }^{\mathrm{CW}} \delta_{X, \text { lin }}^{(\mathrm{S})}(\boldsymbol{s})=b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})-\nabla_{s} \cdot \boldsymbol{\Psi}(\boldsymbol{s})-f\left[\hat{\boldsymbol{s}} \cdot\left\{\left(\hat{\boldsymbol{s}} \cdot \nabla_{s}\right) \boldsymbol{\Psi}(\boldsymbol{s})\right\}\right]$,
which is finally reduced to
$\mathrm{Cw}_{\delta_{X, \operatorname{lin}}^{(S)}}(\boldsymbol{s})=b_{X} \delta_{\mathrm{L}}(\boldsymbol{q})-\frac{1}{a H}\left(\hat{\boldsymbol{s}} \cdot \nabla_{s}\right)(\boldsymbol{v} \cdot \hat{\boldsymbol{s}})$.
Compared to equation (23), the above expression misses the selection function terms, proportional to $(2 / s)(\boldsymbol{v} \cdot \hat{\boldsymbol{s}})$. The second term at right-hand side of equation (26) is known to produce the wide-angle effect, and is shown to play an important role (e.g. Bonvin et al. 2014). On the other hand, due to the suppression factor, the contribution of the selection function terms seemingly becomes unimportant for the clustering signal at high $-z$. We will come back to this point, and discuss its actual impact in comparison with $N$-body simulations in Section 3.3.2.

Another notable difference between this paper and Castorina \& White (2018b) appears in the expression of redshift-space correlation function. In this paper, starting from the mapping formula given at equations (1) and (8), the redshift-space correlation function has been derived from scratch, the resultant expression of which involves six-dimensional integrals. On the other hand, Castorina \& White (2018b) have obtained the expression based on the real-space correlation function, replacing simply the displacement field in real space with redshift-space counterpart, $\boldsymbol{\Psi}^{(S)}$, adopting equation (24). Since their derivation makes use of the statistical isotropy and homogeneity that hold in real-space correlation function, the final expression involves only the three-dimensional integral. While this treatment greatly reduces the computational cost, translational invariance is, taking account of the wide-angle effect, violated in the actual redshift space, and thus their final expression is only valid if we take the plane-parallel limit. Despite of this, the predicted behaviours of the wide-angle corrections are found to be similar to those obtained from our treatment, especially for even multipole moments of correlation functions. We will see quantitatively the similarities and differences between their treatment and the present formalism.

## 3 RESULTS

In this section, based on the expression given at equation (12) with (15) and (18), we present the predictions of redshift-space crosscorrelation functions, which are compared with linear theory and $N$-body simulations. In doing so, we made a slight extension of the linear theory formalism to predict the cross-correlation function including wide-angle corrections. In Appendix D, we present the analytical expressions for linear cross-correlation function, and the results are summarized as the trigonometric polynomial expansion, using the technique developed by Szapudi (2004) and Pápai \& Szapudi (2008). ${ }^{4}$

As we discussed, the cross-correlation function $\xi_{X Y}^{(\mathrm{S})}$ is given as function of the three variables, associated with the triangle formed

[^3]with the positions of pair of objects ( $s_{1}$ and $s_{2}$ ) and their separation $s \equiv s_{2}-s_{1}$. To characterize it, as shown in Fig. 1, we may introduce the LOS distance $\boldsymbol{d}$, the vector pointing to a pair of objects from the observer, and the misalignment angle $\varphi$ between the LOS direction and separation for a pair of objects. Then, the correlation function can be expressed as the function of $s=|\boldsymbol{s}|, d=|\boldsymbol{d}|$, and $\mu \equiv \cos \varphi=\hat{\boldsymbol{d}} \cdot \hat{\boldsymbol{s}}$, i.e. $\xi_{X Y}^{(\mathrm{S})}(s, d, \mu)$. It is convenient to express it as multipole expansion:
$\xi_{X Y}^{(\mathrm{S})}\left(s_{1}, s_{2}\right)=\sum_{\ell} \xi_{\ell}^{(\mathrm{S})}(s, d) \mathcal{P}_{\ell}(\mu)$.
Note that the multipole moment $\xi_{\ell}^{(\mathrm{S})}$ depends not only on separation $s$ but also on the LOS distance $d$. One thus has to further expand $\xi_{\ell}^{(S)}$ in powers of $(s / d)$ :
$\xi_{\ell}^{(\mathrm{S})}(s, d)=\sum_{n}\left(\frac{s}{d}\right)^{n} \xi_{\ell, n}^{(\mathrm{S})}(s)$.
The leading-order contributions with $n=0$, i.e. $\xi_{\ell, 0}^{(\mathrm{S})}$ represent the conventional multipole correlation functions in the plane-parallel limit, where even multipoles are only relevant non-vanishing quantities. On the other hand, higher order terms of $n \geq 1$ basically describe the wide-angle corrections, for which both even and odd multipoles become generally non-zero.

One important remark of the multipole expansion in equations (27) and (28) is that the wide-angle contributions crucially depends on how we choose the LOS direction, and the impact of wide-angle effects is largely changed. This point has been recently investigated in both analytical and numerical calculations (Reimberg et al. 2016; Castorina \& White 2018b; Beutler et al. 2019). In what follows, keeping these aspects in mind, we will present a quantitative estimate of the impact of wide-angle effects, focusing particularly on quasi-linear scales. Analytical and numerical results presented below are obtained assuming a flat lambda cold dark matter ( $\Lambda \mathrm{CDM}$ ) model, with the initial power spectrum created by Camb (Lewis, Challinor \& Lasenby 2000). The fiducial model parameters are chosen based on the 7-yr WMAP results (Komatsu et al. 2011): $\Omega_{\mathrm{m}}=0.25733$ for matter density, $\Omega_{\mathrm{b}}=0.04356$ for baryon density, $\Omega_{\Lambda}=0.74259$ for dark energy with equation-ofstate parameter $w=-1, \Omega_{\mathrm{r}}=8.076 \times 10^{-5}$ for radiation density, $h=0.72$ for Hubble parameter, $n_{\mathrm{s}}=0.963$ for scalar spectral index, and finally, $\sigma_{8}=0.801$ for the normalization amplitude of the matter fluctuations at $8 h^{-1} \mathrm{Mpc}$.

### 3.1 Deviation from plane-parallel limit

Let us evaluate quantitatively the impact of wide-angle corrections, varying the distance to the objects, $d$. For a sufficiently long distance larger than the separation, i.e. $d \gg s$, the variation of $d$ is equivalent to that of redshift, $z$. Here, we consider the mid-point LOS as one of the simplest definitions:
Mid-point : $\quad \boldsymbol{d} \equiv \frac{1}{2}\left(\boldsymbol{s}_{1}+\boldsymbol{s}_{2}\right)$.
Then, we compute the multipole moments of the cross-correlation function $\xi_{\ell}^{(\mathrm{S})}$, assuming $b_{X}=2.07$ and $b_{Y}=1.08$ as a fiducial set of Eulerian bias parameters.

First look at the even multipole moments. In Fig. 2, the results for $\ell=0$ (left), 2 (middle), and 4 (right), are shown at $z=0.1$ (black), 0.33 (green), and 0.57 (blue), corresponding to the distance $d=0.29$, 0.92 , and $1.50 h^{-1} \mathrm{Gpc}$, respectively. Note that the latter two cases are close to the mean redshifts of SDSS BOSS LRG/LOWZ and CMASS samples. The plotted quantity here is the fractional
difference of the correlation function relative to the one in the planeparallel limit, $\left|\xi_{\ell}^{(\mathrm{S})} / \xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}-1\right|$ with $\xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}$ being the multipole crosscorrelation function in the plane-parallel limit, equivalently $\xi_{\ell, 0}^{(S)}$ in equation (28). Solid lines are the results obtained from Zel'dovich approximation, which are compared with linear theory predictions, depicted as dashed lines.

Overall, both the linear and Zel'dovich predictions give the same trend, that is, the impact of wide-angle corrections, characterized by the departure from plane-parallel limit, becomes prominent at large separation, and it is more significant at lower redshifts (small d). Note that a sharp feature near $s=140 h^{-1} \mathrm{Mpc}$ in the monopole and $s=20 h^{-1} \mathrm{Mpc}$ in the hexadecapole just comes from the zerocrossing of the correlation function. Quasi-linear prediction with Zel'dovich slightly changes the impact of wide-angle corrections in the monopole and quadrupole, and the structure of the baryon acoustic peak is smeared to some extent. The is a well-known non-linear feature in both real and redshift space (e.g. Crocce \& Scoccimarro 2008; Matsubara 2008a; Taruya et al. 2009). On the other hand, the hexadecapole exhibits a notable enhancement of the deviation from plane-parallel limit, and compared to the linear theory, it amounts to several tens of percent even at small separation. Remarkably, these behaviours are qualitatively similar to those obtained in Castorina \& White (2018b), although they considered the autocorrelation function, ignoring the contributions arising from the selection function (see figs 3 and 4 of their paper ${ }^{5}$ ). We have also examined the cases with different values of bias parameters. Increasing $b_{X}$ while keeping $b_{Y}$, the resultant fractional difference is found to decrease for monopole, but to increase for hexadecapole. For quadrupole, no notable change is found. As shown in Appendix D2, the wide-angle corrections are of the order of $\mathcal{O}\left((s / d)^{2}\right)$, and they include the terms linearly proportional to the bias in all multipoles. Recalling the fact that in the planeparallel limit, the monopole and quadrupole include, respectively, the terms proportional to $b_{X} b_{Y}$ and $\left(b_{X}+b_{Y}\right)$ (see equations D21 and D22), the fractional difference $\left|\xi_{\ell}^{(\mathrm{S})} / \xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}-1\right|$ tends to decrease for monopole, and to have a small bias dependence for quadrupole. On the other hand, the hexadecapole in the plane-parallel limit has no bias dependence see equation D23). Thus, the fractional difference gets large as increasing the bias parameters. Although this argument is based on the linear theory formulas in D2, we expect that it generally holds even beyond linear regime.

Next look at the odd multipoles, which become vanishing in the plane-parallel limit. Any deviation from linear theory will therefore directly show up in the total signal, without taking ratio. Fig. 3 shows the dipole (left) and octupole (right) moments of cross-correlation function, multiplied by the square of separation. We see clearly the baryon acoustic feature in linear theory prediction, but it is smeared in Zel'dovich approximation, as expected from the behaviour in even multipole. The amplitude of the odd multipoles is basically proportional to the difference of the bias parameter, $b_{X}-b_{Y}$, and hence it becomes zero in the autocorrelation case. Typically, it is smaller than that of the even multipoles by one order of magnitude. Nevertheless, it can still be detectable even with current surveys, depending on the LOS definition (Gaztanaga et al. 2017). Since the observed relativistic effects such as gravitational redshift effect also produce non-zero odd multipoles, a quantitative prediction of odd multipoles arising from the standard Doppler effect is crucial. In this

[^4]

Figure 2. Fractional difference of the monopole (left), quadrupole (middle), and hexadecapole (right) moments of correlation function between predictions with and without wide-angle effects, $\left|\xi_{\ell}^{(\mathrm{S})} / \xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}-1\right|$, where $\xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}$ represents the multipole correlation function in the plane-parallel limit. The results at $z=0.1$, 0.33 , and 0.57 are shown in different colours. Solid and dashed lines are, respectively, the predictions based on Zel'dovich approximation and linear theory, assuming the Eulerian linear bias of $b_{X}=2.07$ and $b_{Y}=1.08$.


Figure 3. Dipole (left) and octupole (right) moments of cross-correlation function at $z=0.1$ (black), 0.33 (green), and 0.57 (blue). The plotted results are the multipole correlation function multiplied by $s^{2}$. Solid and dashed lines are the predictions based on Zel'dovich approximation and linear theory, respectively. Same as in Fig. 2, we assume the Eulerian linear bias of $b_{X}=2.07$ and $b_{Y}=1.08$.
respect, the present formalism based on Zel'dovich approximation would help to disentangle several effects from the measured odd multipoles, and could be used to probe relativistic effects at quasilinear scales.

### 3.2 Dependence of line-of-sight definitions

As we mentioned, the impact of wide-angle effects can change with the definition of the LOS direction. Here, we compute the crosscorrelation function with several definitions of the LOS direction, and see how the results are quantitatively changed. In addition to the mid-point LOS, one may consider the end-point LOS, for which we take one of the position vectors $s_{1}$ and $s_{2}$ to be the LOS vector. Here, we adopt

End-point : $\quad d=s_{1}$.
This definition is frequently used in measuring the multipole power spectra. One advantage of adopting equation (30) is that one can construct a fast power spectrum estimator, making full use of the fast Fourier transform (Bianchi et al. 2015; Scoccimarro 2015). Another natural definition is the angular bisector line between position vectors $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$ :

Bisector : $\boldsymbol{d}=\frac{s_{1} s_{2}}{s_{1}+s_{2}}\left(\hat{\boldsymbol{s}}_{1}+\hat{\boldsymbol{s}}_{2}\right)$.

In Fig. 4, fixing the redshift to $z=0.33$ (corresponding to the comoving distance $d=0.92 h^{-1} \mathrm{Gpc}$ ), we plot the fractional difference, as similarly shown in Fig. 2, for the even multipoles. Further, in Fig. 5, the odd multipoles are shown, multiplying by the square of separation. Again, the cross-correlation is computed assuming the linear Eulerian biases of $b_{X}=2.07$ and $b_{Y}=1.08$. In both figures, the results for mid-point, end-point, and bisector LOS are, respectively, depicted as blue, magenta, and green lines.
For even multipoles, as we see from Fig. 4, the dependence of the LOS definitions is not so large except for the hexadecapole $(\ell=4)$. The main reason basically comes from the fact that in linear theory, the lowest order wide-angle corrections in equation (28) appears at $n \geq 2$ in all the three cases. In Appendix D2, we present the leadingorder expressions for the wide-angle corrections to the crosscorrelation in linear theory. The expressions indicate that the impact of the LOS dependence also changes with the bias parameters, but it is linear dependence on $b_{X}$ and $b_{Y}$. For hexadecapole, the endpoint LOS definition gets a larger wide-angle correction, and for the prediction with Zel'dovich approximation, the deviation from the plane-parallel limit exceeds 10 per cent even at the scales smaller than the baryon acoustic peak, $s \gtrsim 80 h^{-1} \mathrm{Mpc}$.
For odd multipoles, a more significant difference can be seen in Fig. 5. While no clear difference of the results is found for the midpoint and bisector LOS definitions, the end-point LOS gives a rather


Figure 4. Dependence of monopole (left), quadrupole (middle), and hexadecapole (right) cross-correlation functions on the LOS definition at $z=0.33$. Same as in Fig. 2, we assume the Eulerian linear bias of $b_{X}=2.07$ and $b_{Y}=1.08$, and the fractional differences between the cross-correlation function with and without wide-angle corrections, $\left|\xi_{\ell}^{(\mathrm{S})}(s) / \xi_{\ell, \mathrm{pp}}^{(\mathrm{S})}(s)-1\right|$, are plotted in each panel. The results for the mid-point, end-point, and bisector LOS are, respectively, shown in magenta, blue, and green colours. Solid and dashed lines are the predictions based on Zel'dovich approximation and linear theory, respectively.



Figure 5. Dependence of LOS definition on dipole (left) and octupole (right) moments of cross-correlation functions at $z=0.33$. The plotted results are the multipole correlation function multiplied by $s^{2}$, assuming the Eulerian linear bias of $b_{X}=2.07$ and $b_{Y}=1.08$. Meanings of line types and colours are the same as in Fig. 4. Note that the results for mid-point LOS are overlapped with those for bisector LOS.
large differences in both dipole and octupole moments. In particular, the dipole correlation function changes its sign. Indeed, these behaviours are qualitatively explained by the analytic expression in linear theory, as shown in Appendix D2. At the lowest order of expansion in equation (28), we have
$\operatorname{bisect}_{1,1}^{(S)}(s)={ }^{\text {mid }} \xi_{1,1}^{(S)}(s)$,
$\operatorname{bisect}_{3,1}^{(\mathrm{S})}(s)={ }^{\text {mid }} \xi_{3,1}^{(\mathrm{S})}(s)$,
for the bisector LOS, and

$$
\begin{align*}
{ }^{\operatorname{end}} \xi_{1,1}^{(\mathrm{S})}(s)= & { }^{\operatorname{mid}} \xi_{1,1}^{(\mathrm{S})}(s)-\frac{2}{5} f\left(b_{X}+b_{Y}+\frac{6}{7} f\right) \Xi_{2}^{0}(s),  \tag{34}\\
{ }^{\operatorname{end}} \xi_{3,1}^{(\mathrm{S})}(s)= & { }^{\operatorname{mid}} \xi_{3,1}^{(\mathrm{S})}(s)+\frac{2}{5} f\left(b_{X}+b_{Y}+\frac{6}{7} f\right) \Xi_{2}^{0}(s) \\
& +\frac{16}{63} f^{2} \Xi_{4}^{0}(s), \tag{35}
\end{align*}
$$

for the end-point LOS definition. Here, the function $\Xi_{m}^{n}$ is defined by (see equation D28)
$\Xi_{m}^{n}(s)=\int \frac{\mathrm{d} k k^{2}}{2 \pi^{2}} \frac{j_{m}(k s)}{(k s)^{n}} P_{\mathrm{L}}(k)$.
Since the functions $\Xi_{2}^{0}$ and $\Xi_{4}^{0}$ give the positive contributions at the scales of our interest, the above expressions imply that the dipole moment for the end-point LOS is shown to be always smaller than that for the mid-point or bisector LOS, whereas the end-point
octupole always gets a positive correction on top of the prediction for mid-point LOS. Another notable feature may be that the differences of the predictions between Zel'dovich approximation and linear theory look larger for the end-point LOS. This is particularly true at large scales beyond baryon acoustic peak. This implies that the effect of non-linear gravitational growth would become significant for the end-point LOS, and thus an accurate non-linear modelling would be important.

### 3.3 Comparison with simulations

Finally, the predictions based on Zel'dovich approximation are compared with $N$-body simulations. For this purpose, we measure the cross-correlation functions from the full-sky halo catalogue presented in Breton et al. (2019). This catalogue has been created based on the full-sky light-cone outputs of the $\Lambda$ CDM RayGalGroupSims cosmological $N$-body simulation with $4096^{3}$ particles in a volume of $\left(2.625 h^{-1} \mathrm{Gpc}\right)^{3}$. Using ray-tracing techniques, all the relevant relativistic contributions to the observed large-scale structure have been self-consistently incorporated under the weakfield approximation, including also the wide-angle effects on RSD. In this respect, the catalogue provides an ideal suite for modelling, characterizing and testing relativistic signature detectable with future surveys. But, here, we consider the standard Doppler effect only, and rather focus on the wide-angle effects, ignoring all other contributions. A detailed comparison of the analytical model
with the data including relativistic effects will be presented in a companion paper (Saga et al. in preparation). Note that the volume-averaged redshift of this catalogue is $z=0.341$, and the cosmological parameters are the same as we adopted in this paper.

### 3.3.1 Non-linear impacts on odd multipoles

Fig. 6 shows the measured results of the dipole (left) and octupole (right) cross-correlations for the mid-point LOS observer, obtained from the halo sub-samples of data $\__{-} \mathrm{H}_{100}$ and data_ $\mathrm{H}_{1600}$ (upper), and data_ $\mathrm{H}_{100}$ and data_ $\mathrm{H}_{800}$ (lower). ${ }^{6}$ The bias of these samples is estimated from the ratio of autocorrelation function to give 1.08, 1.69, and 2.07 for data $\mathrm{H}_{100}$, data $\mathrm{H}_{800}$, and data $\mathrm{H}_{1600}$, respectively (see table 2 of Breton et al. 2019). The errorbars of the measured results indicate the statistical error estimated from the jackknife method with 32 re-samplings. Though the size of errors is large, we see clearly the non-zero signals both from dipole and octupoles, which are purely originated from the wide-angle effects. We have also measured the monopole and quadrupole moments of cross-correlation functions, which yield a much larger and clearer signal. However, they are basically dominated by the contributions from the plane-parallel limit, as shown in Figs 2 and 4, and hence it is difficult to isolate tiny wide-angle corrections from others.
In Fig. 6, analytical predictions with Zel'dovich approximation are plotted in magenta solid lines, adopting the measured linear bias parameters in Breton et al. (2019) (see table 2 of their paper). Note that in computing the cross-correlation function, we take haloes with larger (smaller) bias to be the object $X(Y)$, so that the separation vector, given by $s=s_{2}-s_{1}$, always points to the haloes with smaller bias (see Fig. 1). The redshift in the analytic calculations was actually chosen to be the mean redshift of the most massive haloes (i.e. data $H_{1600}$ ), $z=0.334$. To be precise, this is slightly different from the volume-averaged one $(z=0.341)$, but a qualitative aspect of the comparison remains totally unchanged. In fact, the predictions agree well with measured results, and capture the overall trends, although the linear theory predictions, depicted as dashed lines, also give a good job. Since the measured odd multipoles are still noisy, one cannot clearly see that the Zel'dovich approximation outperforms the linear theory prediction. Rather, one might say that the linear theory still works well to model and predict their impacts (see Beutler et al. 2019, for practical application).
Nevertheless, as shown in Breton et al. (2019), the deviation from linear theory appears manifest when we consider the relativistic contributions. In particular, the relativistic contributions tend to have a large impact on non-linear correction (see Di Dio \& Seljak 2019, for a quantitative study with perturbation theory), and a large deviation is indeed found for the dipole purely arising from relativistic effects below $40-50 h^{-1} \mathrm{Mpc}$. In this respect, quasi-linear treatment of wide-angle effects still deserves further investigation. Extending the present formalism to include relativistic effect, we will study in detail modelling and predicting the cross-correlation functions in a separate paper (Saga et al. in preparation).

### 3.3.2 Impacts of selection function contributions

As a final remark, we discuss the impacts of the selection function contributions, arising from the terms proportional to $(2 / s)(\boldsymbol{v} \cdot \hat{\boldsymbol{s}})$
in linear density field (second term in equation 23). In Fig. 6, the predictions ignoring these contributions are plotted in blue dot-dashed and black dotted lines, which respectively indicate the results from Zel'dovich approximation and linear theory. Here, the former is obtained by tracing the same calculation as done by Castorina \& White (2018b), with a slight extension to the crosscorrelation function. The latter is computed from equation (D19), taking account of a part of the coefficients $a_{m n}$ and $b_{m n}$, i.e. $a_{00}, a_{02}$, $a_{20}, a_{22}$, and $b_{22}$.
Compared to the predictions shown in magenta solid and black dashed lines, the results in the octupole moment remain almost the same, and are hardly distinguishable from those including the selection function contributions. The fractional differences are merely $\sim 2.5$ per cent even at $s=200 h^{-1} \mathrm{Mpc}$, and we checked that this is also the case for even multipoles of $\ell=0,2$, and 4. Remarkably, however, the dipole cross-correlations exhibit a rather notable difference, with qualitatively the same trend between Zel'dovich and linear theory predictions.

These results can be deduced analytically from the linear theory based on the expansion at equation (28) as follows. The dipole crosscorrelation function for the mid-point LOS observer is expressed, at leading order, as $\xi_{1}^{(\mathrm{S})}(s, d) \simeq(s / d)^{\text {mid }} \xi_{1,1}^{(\mathrm{S})}(s)$ with the coefficient $\operatorname{mid}_{1,1}^{(\mathrm{S})}$ given by equation (D29). As it has been pointed out by Bonvin et al. (2014), Tansella et al. (2018), and Breton et al. (2019), this coefficient can be decomposed into two parts, and the resultant dipole correlation is expressed as ${ }^{7}$

$$
\begin{align*}
\xi_{1, \text { lin }}^{(\mathrm{S})}(s, d) & \simeq\left(\frac{s}{d}\right)\left\{\xi_{\mathrm{div}}(s)+\xi_{\mathrm{wa}}(s)\right\} \\
\xi_{\mathrm{div}}(s) & =\frac{2}{3} f\left(b_{X}-b_{Y}\right)\left\{\Xi_{0}^{0}(s)+\Xi_{2}^{0}(s)\right\}, \\
\xi_{\mathrm{wa}}(s) & =-\frac{2}{5} f\left(b_{X}-b_{Y}\right) \Xi_{2}^{0}(s) \tag{37}
\end{align*}
$$

In the above, $\xi_{\text {div }}$ includes the contribution of the (uniform) selection function terms. On the other hand, the term $\xi_{\text {wa }}$, which gives a negative amplitude, represents the rest of the wide-angle contributions, arising from the projection of peculiar velocities on to the radial LOS directions (third term in equation 23). That is, ignoring the selection function contributions, the predicted dipole becomes negative if $b_{X}>b_{Y}$. This is consistent with the results shown in Fig. 6. Note that for octupole, only the term corresponding to $\xi_{\text {wa }}$ appears at the leading order $\mathcal{O}(s / d)$ (equation D30), and thus the predictions with and without the selection functions do not show any difference.
The results suggest that a consistent framework to include all the wide-angle contributions is important in predicting the dipole, and a proper account of the selection function contribution is especially crucial. For future practical application, a further extension of the present formalism to incorporate non-uniform selection function would be important. Since a part of the relativistic effects is also known to produce similar contributions (e.g. Bertacca et al. 2012; Raccanelli et al. 2018), a more careful treatment may be necessary to identify and isolate the relativistic effects from others. Although the present formalism can only deal with uniform selection function, recalling the fact that the halo samples in our light-cone catalogue is not perfectly uniform along the LOS, a good agreement with

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Figure 6. Comparison of the dipole (left) and octupole (right) moments of cross-correlation function between analytical predictions and measured results in $N$-body simulations, adopting the mid-point LOS given at equation (29). Upper and lower panels shows the results for the haloes with different linear bias: $\left(b_{X}, b_{Y}\right)=(2.07,1.08)$ (upper), (1.69, 1.08) (lower). The plotted results are the cross-correlation functions multiplied by $s^{2}$ at $z=0.33$. In each panel, predictions based on linear theory and Zel'dovich approximation are shown in magenta solid and black dashed lines, respectively. Also, predictions ignoring the selection function contributions are also shown in blue dot-dashed and black dotted lines, which are computed from Zel'dovich approximation and linear theory, respectively. Note that for the octupole, predictions with and without selection function contributions mostly coincide with each other.
simulations suggests some hints to approximately treat non-uniform selection function on top of the present formalism. We leave these investigations to future work.

## 4 CONCLUSION

The observations of large-scale structure, made through a specific observer, often break symmetries inherent in the large-scale structure. But, the symmetry breaking induced by observer can bring additional cosmological information, and offer an interesting test of cosmology. This is the RSD arising from the peculiar velocity of galaxies along the LOS direction. Increasing the statistical precision in next-generation galaxy surveys, one will be able to not only tighten the cosmological constraints from standard RSD measurements, but also detect yet another distortion induced by the relativistic effects. In doing so, a quantitative understanding of the physical effects as well as the observational systematics is crucial issue, and a possible impacts on the cosmological interpretation needs to be investigated.

One such effect is the wide-angle effect, which appears manifest for the statistics of a widely separated galaxies. Unlike the standard RSD in which the plane-parallel limit of the observed
galaxy distribution is assumed with a fixed LOS direction, the translational invariance is broken for the statistical correlation of a widely separated galaxy pair, and this produces several non-trivial properties for two-point correlation function. So far, analytical study on the impact of wide-angle effects has been mostly restricted to the linear theory framework. In this paper, employing the first-order Lagrangian perturbation theory for gravitational clustering, i.e. Zel'dovich approximation, we presented a quasi-linear formalism of wide-angle effects to compute the cross-correlation function between different biased objects.

Our quasi-linear treatment of cross-correlation function is similar to what have been presented in Castorina \& White (2018b). We have clarified the similarity and differences between the two treatments, and have checked in two ways that our treatment correctly reproduces the linear theory of wide-angle RSD under the uniform radial selection function. Our quasi-linear formalism with Zel'dovich approximation is thus regarded as a consistent nonlinear extension taking a proper account of wide-angle effects.

We then studied quantitatively the impact of wide-angle effects on the cross-correlation function at quasi-linear scales. In particular, we evaluated the size of the wide-angle corrections that appear in the conventional multipole expansion. We found that for even
multipoles, higher multipoles tend to receive a larger wide-angle correction to the cross-correlation function, and the quasi-linear treatment with Zel'dovich approximation predicts a more significant impact of the wide-angle effects on the hexadecapole moment even at small scales. These findings are qualitatively similar to what have been found by Castorina \& White (2018b) in the case of the autocorrelation function. Further, a noticeable result of the crosscorrelation function appears in the non-zero odd multipoles, which basically vanish in the plane-parallel limit. The amplitude of odd multipoles is roughly proportional to the difference between bias parameters, and the baryon acoustic feature is clearly seen, with the structure smeared in the quasi-linear predictions. Note cautiously that the shape of odd multipoles can be drastically changed, depending on which LOS definition we use. We showed that the prediction based on the end-point LOS is rather different from that for others. The linear theory formulas presented in Appendix D would provide a useful guideline to understand the LOS dependence of wide-angle effects, although a quantitative understanding needs the quasi-linear treatment with Zel'dovich approximation.
Finally, we have compared our quasi-linear prediction of odd multipoles with measured results in $N$-body simulations. The predictions agree well with simulations, but within the statistical error, no noticeable difference of the predictions between linear theory and Zel'dovich approximation was found. In other words, our results implies that the linear theory description of wide-angle effects still works well at lower redshifts. Nevertheless, we note that ignoring the selection function contributions, the predicted dipole significantly deviates from simulations in both linear theory and Zel'dovich approximation. In this respect, a proper account of all wide-angle effects is crucial. Further, as it has been shown in Breton et al. (2019), when including the relativistic contributions, the linear theory prediction fails to describe the odd-multipole cross-correlation at relatively large scales. A proper account of the non-linear clustering effects seems essential for a quantitative prediction, and in this respect, the present formalism is useful and can be a basis to model and predict the cross-correlation functions including relativistic corrections. We will discuss it in more detail in a forthcoming paper.

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## APPENDIX A: ANALYTIC EXPRESSION OF CROSS-CORRELATION FUNCTION

In this appendix, starting from the expressions given at equation (12) with (13) and (14), we derive analytical expressions for crosscorrelation function $\xi_{X Y}^{(\mathrm{S})}$ summarized at equations (15) and (18), which involves three- and six-dimensional integrals for $R_{X}$ and $D_{X} D_{Y}$, respectively.

## A1 $\boldsymbol{R}_{X}, \boldsymbol{R}_{Y}$-part

To derive equation (15), we first make use of the fact that the quantities $\boldsymbol{\Psi}^{(\mathrm{S})}$ and $\delta_{\mathrm{L}}$ are Gaussian fields. Then, the bracket in the integrand is rewritten with
$\left\langle\mathrm{e}^{-i \boldsymbol{k} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}(\boldsymbol{q})}\left\{1+b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}(\boldsymbol{q})\right\}\right\rangle=\exp \left[-\frac{1}{2} k_{i} k_{j}\left\langle\Psi_{i}^{(\mathrm{S})}(\boldsymbol{q}) \Psi_{j}^{(\mathrm{S})}(\boldsymbol{q})\right\rangle\right]$.
Here, we used the fact that $\left\langle\Psi_{i}^{(S)}(\boldsymbol{q}) \delta_{\mathrm{L}}(\boldsymbol{q})\right\rangle=0$. This implies that $R_{X}=R_{Y}$. Using the definition at equation (16), we can rewrite equation (13) with
$R_{X}(\boldsymbol{s})=\int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot(\boldsymbol{s}-\boldsymbol{q})} \exp \left[-\frac{1}{2} A_{i j}(\boldsymbol{q}) k_{i} k_{j}\right]$.
With the Gaussian integral formula at equation (B1), the integral over wavevector is analytically performed to give equation (15):
$R_{X}(\boldsymbol{s})=\int \frac{\mathrm{d}^{3} \boldsymbol{q}}{(2 \pi)^{3 / 2}|\operatorname{det} A|^{1 / 2}} \mathrm{e}^{-(1 / 2) A_{i j}^{-1}(s-q)_{i}(s-q)_{j}}$.
The explicit expression for the matrix $A_{i j}$ will be given in next subsection (see equation A23).

A further reduction of the above expression is not straightforward because of the non-trivial dependence of the matrix $A_{i j}$. But, one can exploit the approximation with which $R_{X, Y}$ leads to a simple analytical form. Taylor-expanding the exponential factor in equation (A1), we have

$$
\begin{aligned}
R_{X, Y}(\boldsymbol{s})= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \mathrm{e}^{i \boldsymbol{k} \cdot\{\boldsymbol{s}-\boldsymbol{q}\}} \sum_{n=0} \frac{1}{n!}\left\{-\frac{k_{i} k_{j}}{2} A_{i j}(\hat{\boldsymbol{q}})\right\}^{n} \\
= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q} \\
& \times \sum_{n=0} \frac{1}{n!}\left\{\frac{1}{2} A_{i j}(\hat{\boldsymbol{q}}) \frac{\partial^{2}}{\partial q_{i} \partial q_{j}}\right\}^{n} \mathrm{e}^{i \boldsymbol{k} \cdot\{\boldsymbol{s}-\boldsymbol{q}\}},
\end{aligned}
$$

which, repeating the integration by part, is reduced to (see also Section C for similar technique)
$R_{X, Y}(\boldsymbol{s})=\sum_{n=0} \frac{1}{n!}\left\{\frac{1}{2} \frac{\partial^{2}}{\partial s_{i} \partial s_{j}} A_{i j}(\hat{\boldsymbol{s}})\right\}^{n}$.
Substituting the explicit expression of the matrix $A_{i j}$ at equation (A23) into the above, the approximate form of $R_{X, Y}$ truncating at finite order in $A_{i j}$ is obtained to give equation (17), which is expressed as function of $s=|\boldsymbol{s}|$.

## A2 $D_{X} D_{Y}$-part

In order to derive the expression of $D_{X} D_{Y}$ relevant for numerical calculations, let us first define the following quantities:

$$
\begin{align*}
X_{1} & \equiv b_{X}^{\mathrm{L}} \delta_{\mathrm{L}}\left(\boldsymbol{q}_{1}\right), \quad X_{2} \equiv b_{Y}^{\mathrm{L}} \delta_{\mathrm{L}}\left(\boldsymbol{q}_{2}\right) \\
Y & \equiv-i\left\{\boldsymbol{k}_{1} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}\left(\boldsymbol{q}_{1}\right)+\boldsymbol{k}_{2} \cdot \boldsymbol{\Psi}^{(\mathrm{S})}\left(\boldsymbol{q}_{2}\right)\right\} \tag{A3}
\end{align*}
$$

Then, equation (14) is rewritten with

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \\
& \times \mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left(\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right)+i \boldsymbol{k}_{2} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right)}\left\langle\mathrm{e}^{Y}\left(1+X_{1}\right)\left(1+X_{2}\right)\right\rangle . \tag{A4}
\end{align*}
$$

At first order in Lagrangian perturbation theory (i.e. Zel'dovich approximation), the quantities $X_{1}, X_{2}$, and $Y$ all follows Gaussian statistics. Then, using the properties between moment and cumulant generating function, one can exploit the following expression (see e.g. Scoccimarro 2004; Matsubara 2008a; Taruya et al. 2010):

$$
\begin{aligned}
\left\langle e^{Y}\left(1+X_{1}\right)\left(1+X_{2}\right)\right\rangle= & \exp \left[\frac{1}{2}\left\langle Y^{2}\right\rangle_{c}\right]\left\{1+\left\langle X_{1} X_{2}\right\rangle_{c}+\left\langle X_{1} Y\right\rangle_{c}\right. \\
& \left.+\left\langle X_{2} Y\right\rangle_{c}+\left\langle X_{1} Y\right\rangle_{c}\left\langle X_{2} Y\right\rangle_{c}\right\} .
\end{aligned}
$$

Here, the quantities enclosed by the bracket $\langle\cdots\rangle_{c}$ imply the cumulants, for which the disconnected part of the ensemble average is subtracted. In our case with Gaussian random fields of $X_{i}$ and $Y$, there is actually no distinction between cumulant and moment, and we simply omit subscript $c$. Then, statistical quantities at right-hand side are explicitly given as follows:

$$
\begin{align*}
\left\langle Y^{2}\right\rangle= & -k_{1, i} k_{1, j} A_{i j}\left(\hat{\boldsymbol{q}}_{1}\right)-k_{2, i} k_{2, j} A_{i j}\left(\hat{\boldsymbol{q}}_{2}\right) \\
& -2 k_{1, i} k_{2, j} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right),  \tag{A5}\\
\left\langle X_{1} Y\right\rangle= & i b_{X}^{\mathrm{L}} k_{2, i} U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right),  \tag{A6}\\
\left\langle X_{2} Y\right\rangle= & i b_{Y}^{\mathrm{L}} k_{1, i} U_{i}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right),  \tag{A7}\\
\left\langle X_{1} X_{2}\right\rangle= & b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}\left(\left|\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right|\right), \tag{A8}
\end{align*}
$$

where the quantity $\xi_{\mathrm{L}}$ is the correlation function of Lagrangian matter density field, $\xi_{\mathrm{L}}\left(\left|\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right|\right) \equiv\left\langle\delta_{\mathrm{L}}\left(\boldsymbol{q}_{1}\right) \delta_{\mathrm{L}}\left(\boldsymbol{q}_{2}\right)\right\rangle$. Here, the quantities $A_{i j}$ and $B_{i j}$ are the $3 \times 3$ matrices, and $U_{i}$ are the threedimensional vectors, defined by

$$
\begin{align*}
A_{i j}(\hat{\boldsymbol{q}}) & =\left\langle\Psi_{i}^{(\mathrm{S})}(\boldsymbol{q}) \Psi_{j}^{(\mathrm{S})}(\boldsymbol{q})\right\rangle,  \tag{A9}\\
B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & =\left\langle\Psi_{i}^{(\mathrm{S})}\left(\boldsymbol{q}_{1}\right) \Psi_{j}^{(\mathrm{S})}\left(\boldsymbol{q}_{2}\right)\right\rangle,  \tag{A10}\\
U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & =-\left\langle\delta_{\mathrm{L}}\left(\boldsymbol{q}_{1}\right) \Psi_{i}^{(\mathrm{S})}\left(\boldsymbol{q}_{2}\right)\right\rangle . \tag{A11}
\end{align*}
$$

Note that equation (A9) is the same one as given at equation (16).

Substituting equations (A5)-(A7) into equation (A4), the crosscorrelation term becomes

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{\left.(2 \pi)^{6}\right)} \int \mathrm{d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \\
& \times \mathrm{e}^{i} \boldsymbol{k}_{1} \cdot\left(\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right)+i \boldsymbol{k}_{2} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right) \\
& \times \exp \left[-\frac{1}{2} k_{1, i} k_{1, j} A_{i j}\left(\hat{\boldsymbol{q}}_{1}\right)-\frac{1}{2} k_{2, i} k_{2, j} A_{i j}\left(\hat{\boldsymbol{q}}_{2}\right)\right. \\
& \left.-k_{1, i} k_{2, j} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)\right] \\
& \times\left[1+b_{X}^{L} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(q)+i b_{X}^{\mathrm{L}} k_{2, i} U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)\right. \\
& +i b_{Y}^{\mathrm{L}} k_{1, i} U_{i}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right) \\
& \left.-b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} k_{1, i} k_{2, j} U_{i}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right) U_{j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)\right] . \tag{A12}
\end{align*}
$$

The above expression is further simplified if we introduce the six-dimensional vectors composed of two three-dimensional vectors, i.e. $\boldsymbol{K} \equiv\left(\boldsymbol{k}_{1}, \boldsymbol{k}_{2}\right), \boldsymbol{Q} \equiv\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)$, and $\boldsymbol{S} \equiv\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)$. Then, equation (A12) is rewritten with

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{6} \boldsymbol{K}}{(2 \pi)^{6}} \int \mathrm{~d}^{6} \boldsymbol{Q} \mathrm{e}^{i K_{c}(S-Q)_{c}} \\
& \times \exp \left[-\frac{1}{2} \mathcal{A}_{a b}(\boldsymbol{Q}) K_{a} K_{b}\right]\left[1+b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(q)\right. \\
& \left.+i K_{c} \mathcal{U}_{c}(\boldsymbol{Q})-K_{a} K_{b} \mathcal{W}_{a b}(\boldsymbol{Q})\right] \tag{A13}
\end{align*}
$$

where the subscripts $a, b, c$ run over $1-6$. The quantities $\mathcal{A}_{a b}$ and $\mathcal{W}_{a b}$ are the $6 \times 6$ matrices, and $\mathcal{U}_{a}$ is the six-dimensional vector, given by

$$
\begin{align*}
\mathcal{A}_{a b} & =\left(\begin{array}{cc}
\boldsymbol{A}\left(\hat{\boldsymbol{q}}_{1}\right) & \boldsymbol{B}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) \\
{ }^{T} \boldsymbol{B}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & \boldsymbol{A}\left(\hat{\boldsymbol{q}}_{2}\right)
\end{array}\right),  \tag{A14}\\
\mathcal{U}_{a} & =\binom{b_{Y}^{\mathrm{L}} \boldsymbol{U}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right)}{b_{X}^{\mathrm{L}} \boldsymbol{U}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)},  \tag{A15}\\
\mathcal{W}_{a b} & =\frac{1}{2} b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}}\left(\begin{array}{cc}
0 & U_{i}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right) U_{j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) \\
U_{j}\left(\boldsymbol{q}_{2}, \boldsymbol{q}_{1}\right) U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & 0
\end{array}\right) . \tag{A16}
\end{align*}
$$

Now, making use of the formulas for multidimensional Gaussian integrals in Appendix B, the integral over the six-dimensional wavevector $\boldsymbol{K}$ is analytically performed, and we obtain

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{6} \boldsymbol{Q}}{(2 \pi)^{3}|\operatorname{det} \mathcal{A}|^{1 / 2}} \mathrm{e}^{-(1 / 2) \mathcal{A}_{a b}^{-1}(S-Q)_{a}(S-Q)_{b}} \\
& \times\left[1+b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(q)-\mathcal{A}_{c d}^{-1} \mathcal{U}_{c}(S-Q)_{d}\right. \\
& \left.-\left\{\mathcal{A}_{c d}^{-1}-\mathcal{A}_{c e}^{-1} \mathcal{A}_{d f}^{-1}(S-Q)_{e}(S-Q)_{f}\right\} \mathcal{W}_{c d}\right] \tag{A17}
\end{align*}
$$

This is equation (18).
For a quantitative calculation of equation (A17) or (18), we further need explicit functional forms of $3 \times 3$ matrices $A_{i j}$ and $B_{i j}$ as well as three-dimensional vectors $U_{1, i}$ and $U_{2, i}$, which are the building blocks of $\mathcal{A}_{a b}, \mathcal{W}_{a b}$, and $\mathcal{U}_{a}$. Recall that the displacement field in Zel'dovich approximation is related to the linear density
field $\delta_{\mathrm{L}}$ through equation (5), we have

$$
\begin{align*}
\Psi_{i}^{(\mathrm{S})}\left(\boldsymbol{q}_{J}\right) & =R_{i k}\left(\boldsymbol{q}_{J}\right) \Psi_{\mathrm{ZA}, i}\left(\boldsymbol{q}_{J}\right) \\
& =R_{i k}\left(\boldsymbol{q}_{J}\right) \int \frac{\mathrm{d}^{3} \boldsymbol{p}}{(2 \pi)^{3}} \frac{i p_{k}}{|\boldsymbol{p}|^{2}} \widetilde{\delta}_{\mathrm{L}}(\boldsymbol{p}) \mathrm{e}^{i} \boldsymbol{p} \cdot \boldsymbol{q}_{J},(J=1,2) \tag{A18}
\end{align*}
$$

with $\widetilde{\delta}_{\mathrm{L}}$ being the Fourier counterpart of the initial density field. Substituting the above expression into the definitions given at equations (A9)-(A11), we obtain

$$
\begin{align*}
& A_{i j}\left(\hat{\boldsymbol{q}}_{J}\right)=R_{i k}\left(\hat{\boldsymbol{q}}_{J}\right) R_{j l}\left(\hat{\boldsymbol{q}}_{J}\right) \int \frac{\mathrm{d}^{3} \boldsymbol{p}}{(2 \pi)^{3}} \frac{p_{k} p_{l}}{p^{2}} P_{\mathrm{L}}(p),(J=1,2) \\
& B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)=R_{i k}\left(\hat{\boldsymbol{q}}_{1}\right) R_{j l}\left(\hat{\boldsymbol{q}}_{2}\right) \int \frac{\mathrm{d}^{3} \boldsymbol{p}}{(2 \pi)^{3}} \frac{p_{k} p_{l}}{p^{2}} \mathrm{e}^{i} \boldsymbol{p} \cdot\left(\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right)  \tag{A19}\\
& P_{\mathrm{L}}(p),
\end{align*}
$$

$$
\begin{equation*}
U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)=-R_{i k}\left(\hat{\boldsymbol{q}}_{2}\right) \int \frac{\mathrm{d}^{3} \boldsymbol{p}}{(2 \pi)^{3}} \frac{i p_{k}}{p^{2}} \mathrm{e}^{i} \boldsymbol{p} \cdot\left(\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right) P_{\mathrm{L}}(p) \tag{A21}
\end{equation*}
$$

where the quantity $P_{\mathrm{L}}$ is the linear power spectrum of the density field $\widetilde{\delta_{\mathrm{L}}}$, defined by

$$
\begin{equation*}
\left\langle\widetilde{\delta}_{\mathrm{L}}(\boldsymbol{p}) \widetilde{\delta}_{\mathrm{L}}\left(\boldsymbol{p}^{\prime}\right)\right\rangle=(2 \pi)^{3} \delta_{\mathrm{D}}\left(\boldsymbol{p}+\boldsymbol{p}^{\prime}\right) P_{\mathrm{L}}(\boldsymbol{p}) \tag{A22}
\end{equation*}
$$

Using the rotational invariance of the integrals, the above expressions are reduced to the simplified forms as

$$
\begin{align*}
A_{i j}\left(\hat{\boldsymbol{q}}_{J}\right) & =R_{i k}\left(\hat{\boldsymbol{q}}_{J}\right) R_{j k}\left(\hat{\boldsymbol{q}}_{J}\right) \sigma_{\mathrm{d}}^{2} ; \quad(J=1,2),  \tag{A23}\\
B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & =R_{i k}\left(\hat{\boldsymbol{q}}_{1}\right) R_{j l}\left(\hat{\boldsymbol{q}}_{2}\right)\left\{C(q) \delta_{k l}+D(q) \hat{q}_{k} \hat{q}_{l}\right\}  \tag{A24}\\
U_{i}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) & =R_{i k}\left(\hat{\boldsymbol{q}}_{2}\right) \hat{q}_{k} L(q), \tag{A25}
\end{align*}
$$

with $q \equiv\left|\boldsymbol{q}_{2}-\boldsymbol{q}_{1}\right|$ and $\hat{q}_{k} \equiv\left(q_{2, k}-q_{1, k}\right) / q$. The explicit expressions for the quantity $\sigma_{\mathrm{d}}^{2}$ and functions $C, D$, and $L$ become

$$
\begin{align*}
C(q) & =\int \frac{\mathrm{d} p}{2 \pi^{2}} \frac{j_{1}(p q)}{p q} P_{\mathrm{L}}(p)  \tag{A26}\\
D(q) & =-\int \frac{\mathrm{d} p}{2 \pi^{2}} j_{2}(p q) P_{\mathrm{L}}(p)  \tag{A27}\\
L(q) & =\int \frac{\mathrm{d} p}{2 \pi^{2}} p j_{1}(p q) P_{\mathrm{L}}(p)  \tag{A28}\\
\sigma_{\mathrm{d}}^{2} & =\int \frac{\mathrm{d} p}{6 \pi^{2}} P_{\mathrm{L}}(p)  \tag{A29}\\
\xi_{\mathrm{L}}(q) & =\int \frac{\mathrm{d} p}{2 \pi^{2}} p^{2} j_{0}(p q) P_{\mathrm{L}}(p) \tag{A30}
\end{align*}
$$

where $j_{\ell}(x)$ is the spherical Bessel function of the first kind.

## APPENDIX B: FORMULAS FOR MULTIDIMENSIONAL GAUSSIAN INTEGRALS

Here, we summarize the formulas for Gaussian integrals used to derive the analytical expressions in Appendix A. Let $K_{a}$ and $X_{a}$ be $n$-dimensional vectors, and $\mathcal{A}_{a b}$ be $n \times n$ symmetric matrix independent of $K_{a}$ and $X_{a}$. Then, we have

$$
\begin{align*}
& \int \frac{\mathrm{d}^{n} \boldsymbol{K}}{(2 \pi)^{n}} \mathrm{e}^{i K_{a} X_{a}} \exp \left[-\frac{1}{2} K_{a} K_{b} \mathcal{A}_{a b}\right] \\
& \quad=\frac{1}{(2 \pi)^{n / 2}|\operatorname{det} \mathcal{A}|^{1 / 2}} \exp \left[-\frac{1}{2} \mathcal{A}_{a b}^{-1} X_{a} X_{b}\right], \tag{B1}
\end{align*}
$$

$$
\begin{align*}
& \int \frac{\mathrm{d}^{n} \boldsymbol{K}}{(2 \pi)^{n}} \mathrm{e}^{i K_{a} X_{a}} K_{c} \exp \left[-\frac{1}{2} K_{a} K_{b} \mathcal{A}_{a b}\right] \\
& =\frac{i}{(2 \pi)^{n / 2}|\operatorname{det} \mathcal{A}|^{1 / 2}} \mathcal{A}_{c d}^{-1} X_{d} \exp \left[-\frac{1}{2} \mathcal{A}_{a b}^{-1} X_{a} X_{b}\right],  \tag{B2}\\
& \int \frac{\mathrm{d}^{n} \boldsymbol{K}}{(2 \pi)^{n}} \mathrm{e}^{i K_{a} X_{a}} K_{c} K_{d} \exp \left[-\frac{1}{2} K_{a} K_{b} \mathcal{A}_{a b}\right] \\
& =\frac{1}{(2 \pi)^{n / 2}|\operatorname{det} \mathcal{A}|^{1 / 2}}\left\{\mathcal{A}_{c d}^{-1}-\mathcal{A}_{c e}^{-1} \mathcal{A}_{d f}^{-1} X_{e} X_{f}\right\} \\
& \quad \times \exp \left[-\frac{1}{2} \mathcal{A}_{a b}^{-1} X_{a} X_{b}\right] . \tag{B3}
\end{align*}
$$

## APPENDIX C: RECOVERY OF WIDE-ANGLE LINEAR CROSS-CORRELATION FUNCTION

In this appendix, for the sake of completeness, we show that starting with the expressions involving the wide-angle effect, i.e. Equations (12), (13), and (14), their leading-order expansions correctly reproduce the linear theory including wide-angle effect. To do this, we keep and expand the terms up to $\mathcal{O}\left(P_{\mathrm{L}}\right)$, then $D_{X} D_{Y}$, $R_{X}$, and $R_{Y}$ are rewritten as

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) \simeq & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \\
& \times \mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left\{\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}+i \boldsymbol{k}_{2} \cdot\left\{\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right\}}\left[1+b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(q)\right. \\
& -\frac{1}{2} k_{1, i} k_{1, j} A_{i j}\left(\boldsymbol{q}_{1}\right)-\frac{1}{2} k_{2, i} k_{2, j} A_{i j}\left(\boldsymbol{q}_{2}\right) \\
& -k_{1, i} k_{2, j} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)+i b_{X}^{\mathrm{L}} k_{2, i} U_{1, i} \\
& \left.+i b_{Y}^{\mathrm{L}} k_{1, i} U_{2, i}+\cdots\right] . \tag{C1}
\end{align*}
$$

To simplify the expression, we notice that a factor of wavenumber $\boldsymbol{k}_{1,2}$ in the integrand is always multiplied by the exponential $\mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left(\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right)+i} \boldsymbol{k}_{2} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right)$. Thus, we replace it with a Lagrangian spatial derivative:
$k_{1, i} \longrightarrow i \frac{\partial}{\partial q_{1, i}}, \quad k_{2, i} \longrightarrow i \frac{\partial}{\partial q_{2, i}}$.
Then, the integration can be performed analytically in a systematic manner. An explicit demonstration is given below for the term involving $B_{i j}$ :

$$
\begin{aligned}
\int & \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \mathrm{e}^{i} \boldsymbol{k}_{1} \cdot\left\{\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}+i \boldsymbol{k}_{2} \cdot\left\{\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right\} \\
= & \times\left\{-k_{1, i} k_{2, j} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right)\right\} \\
& \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) \\
& \times \frac{\partial^{2}}{\partial q_{1, i} \partial q_{2, j}} \mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left\{\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}+i \boldsymbol{k}_{2} \cdot\left\{\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right\}}
\end{aligned}
$$

$$
\begin{align*}
= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1} \mathrm{~d}^{3} \boldsymbol{k}_{2}}{(2 \pi)^{6}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \mathrm{e}^{i \boldsymbol{k}_{1} \cdot\left\{\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}+i \boldsymbol{\boldsymbol { k } _ { 2 } \cdot \{ \boldsymbol { s } _ { 2 } - \boldsymbol { q } _ { 2 } \}}} \\
& \times \frac{\partial^{2}}{\partial q_{1, i} \partial q_{2, j}} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) \\
= & \int \mathrm{d}^{3} \boldsymbol{q}_{1} \mathrm{~d}^{3} \boldsymbol{q}_{2} \delta_{\mathrm{D}}\left(\boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right) \delta_{\mathrm{D}}\left(\boldsymbol{s}_{2}-\boldsymbol{q}_{2}\right) \\
& \times \frac{\partial^{2}}{\partial q_{1, i} \partial q_{2, j}} B_{i j}\left(\boldsymbol{q}_{1}, \boldsymbol{q}_{2}\right) \\
= & \frac{\partial^{2}}{\partial s_{1, i} \partial s_{2, j}} B_{i j}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) . \tag{C3}
\end{align*}
$$

Note that in the third line, integration by parts is performed, assuming the finite support of the function $B_{i j}$. Applying the above procedure to other terms in the integrand, equation (C1) is reduced to

$$
\begin{align*}
D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & 1+b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(s) \\
& +\frac{1}{2}\left\{\frac{\partial^{2}}{\partial s_{1, i} \partial s_{1, j}} A_{i j}\left(\hat{\boldsymbol{s}}_{1}\right)+\frac{\partial^{2}}{\partial s_{2, i} \partial s_{2, j}} A_{i j}\left(\hat{\boldsymbol{s}}_{2}\right)\right\}  \tag{C4}\\
& +\frac{\partial^{2}}{\partial s_{1, i} \partial s_{2, j}} B_{i j}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) \\
& +b_{X}^{\mathrm{L}} \frac{\partial}{\partial s_{2, i}} U_{1, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)+b_{Y}^{\mathrm{L}} \frac{\partial}{\partial s_{1, i}} U_{2, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) . \tag{C5}
\end{align*}
$$

Similarly, the function $R_{X}$ and $R_{Y}$ are expanded up to leading order in $\delta_{\mathrm{L}}$, and are computed systematically to give

$$
\begin{align*}
R_{X}\left(\boldsymbol{s}_{1}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}_{1}}{(2 \pi)^{3}} \int \mathrm{~d}^{3} \boldsymbol{q}_{1} \mathrm{e}^{\left.i \boldsymbol{k}_{1 \cdot\{ } \cdot \boldsymbol{s}_{1}-\boldsymbol{q}_{1}\right\}} \\
& \times\left\{1-\frac{1}{2} A_{1, i j}\left(\hat{\boldsymbol{q}}_{1}\right) k_{1, i} k_{1, j}+\cdots\right\} \\
= & 1+\frac{1}{2} \frac{\partial^{2}}{\partial s_{1, i} \partial s_{1, j}} A_{i j}\left(\hat{\boldsymbol{s}}_{1}\right) .  \tag{C6}\\
R_{Y}\left(\boldsymbol{s}_{2}\right)= & 1+\frac{1}{2} \frac{\partial^{2}}{\partial s_{2, i} \partial s_{2, j}} A_{i j}\left(\hat{\boldsymbol{s}}_{2}\right) . \tag{C7}
\end{align*}
$$

Combining the expressions given at equations (C5), (C6), and (C7), the leading order expression of the correlation function, $\xi_{X Y \text {, } \mathrm{lin}}^{(\mathrm{S})}$, becomes

$$
\begin{align*}
\xi_{X Y, \text { lin }}^{(\mathrm{S})}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \frac{D_{X} D_{Y}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)}{R_{X}\left(\boldsymbol{s}_{1}\right) R_{X}\left(\boldsymbol{s}_{2}\right)}-1 \\
\simeq & b_{X}^{\mathrm{L}} b_{Y}^{\mathrm{L}} \xi_{\mathrm{L}}(q)+\frac{\partial^{2}}{\partial s_{1, i} \partial s_{2, j}} B_{i j}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) \\
& +b_{X}^{\mathrm{L}} \frac{\partial}{\partial s_{2, i}} U_{1, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)+b_{Y}^{\mathrm{L}} \frac{\partial}{\partial s_{1, i}} U_{2, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right) . \tag{C8}
\end{align*}
$$

To further reduce the above expression, we evaluate the spatial derivative of the matrix $B_{i j}$ and vectors $U_{I, i}$. Based on the expressions given at equations (A20) and (A21), a straightforward calculation
leads to

$$
\begin{align*}
\frac{\partial^{2}}{\partial s_{1, i} \partial s_{2, j}} B_{i j}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{i \boldsymbol{k} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right)} P_{\mathrm{L}}(k) \\
& \times\left(1+f \mu_{1}^{2}+i 2 f \frac{\mu_{1}}{k s_{1}}\right) \\
& \times\left(1+f \mu_{2}^{2}-i 2 f \frac{\mu_{2}}{k s_{2}}\right),  \tag{C9}\\
\frac{\partial}{\partial s_{2, i}} U_{1, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{i \boldsymbol{k} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right)} P_{\mathrm{L}}(k) \\
& \times\left(1+f \mu_{2}^{2}-i 2 f \frac{\mu_{2}}{k s_{2}}\right),  \tag{C10}\\
\frac{\partial}{\partial s_{1, i}} U_{2, i}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{i \boldsymbol{k} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right)} P_{\mathrm{L}}(k) \\
& \times\left(1+f \mu_{1}^{2}+i 2 f \frac{\mu_{1}}{k s_{1}}\right), \tag{C11}
\end{align*}
$$

with $s_{1}=\left|\boldsymbol{s}_{1}\right|$ and $s_{2}=\left|\boldsymbol{s}_{2}\right|$. Here, the directional cosine $\mu_{i}$ is defined by $\mu_{i}=\hat{\boldsymbol{k}} \cdot \hat{\boldsymbol{s}}_{i}$. Summing up the contributions above, we finally obtain

$$
\begin{align*}
\xi_{\mathrm{XY}, \operatorname{lin}}^{(\mathrm{S})}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)= & \int \frac{\mathrm{d}^{3} \boldsymbol{k}}{(2 \pi)^{3}} \mathrm{e}^{i \boldsymbol{k} \cdot\left(\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right)} P_{L}(k) \\
& \times\left(b_{X}+f \mu_{1}^{2}+i 2 f \frac{\mu_{1}}{k s_{1}}\right) \\
& \times\left(b_{Y}+f \mu_{2}^{2}-i 2 f \frac{\mu_{2}}{k s_{2}}\right), \tag{C12}
\end{align*}
$$

with $b_{X, Y}$ being the Eulerian linear bias given by $b_{X, Y}=1+b_{X, Y}^{\mathrm{L}}$. Equation (C12) fully coincides with the linear theory expression that have been derived previously (e.g. Pápai \& Szapudi 2008; Yoo \& Seljak 2015; Reimberg et al. 2016).

## APPENDIX D: LINEAR THEORY OF CROSS-CORRELATION FUNCTION WITH WIDE-ANGLE RSD

In this appendix, starting with equation (C12), we present the analytical formulas to compute the cross-correlation function at linear order, including the wide-angle effects.

## D1 Expansion form of linear cross-correlation function

In Szapudi (2004) and Pápai \& Szapudi (2008), the linear-order correlation function with wide-angle effects is expanded in terms of the tripolar spherical harmonics, and it is evaluated in three different coordinate systems in the case of autocorrelation function (similar expansion has been also introduced in Szalay et al. 1998). Here, following Szapudi (2004) and Pápai \& Szapudi (2008), we extend their treatment to the linear-order correlation function between different biased objects.
The tripolar spherical harmonics characterize the angular dependence of correlation function, defined by

$$
\begin{align*}
S_{\ell_{1}, \ell_{2}, \ell}\left(\hat{\boldsymbol{s}}_{1}, \hat{\boldsymbol{s}}_{2}, \hat{\boldsymbol{s}}\right)= & \sum_{m_{1}, m_{2}, m}\left(\begin{array}{ccc}
\ell_{1} & \ell_{2} & \ell \\
m_{1} & m_{2} & m
\end{array}\right) \\
& \times C_{\ell_{1} m_{1}}^{*}\left(\hat{\boldsymbol{s}}_{1}\right) C_{\ell_{2} m_{2}}^{*}\left(\hat{\boldsymbol{s}}_{2}\right) C_{\ell m}^{*}(\hat{\boldsymbol{s}}), \tag{D1}
\end{align*}
$$

with the function $C_{\ell m}(\hat{\boldsymbol{x}})$ being the normalized spherical harmonics, given by $C_{\ell m}(\hat{\boldsymbol{x}}) \equiv \sqrt{4 \pi /(2 \ell+1)} Y_{\ell m}(\hat{\boldsymbol{x}})$. Note that Wigner $3 j$ symbols appear at right-hand side. With the harmonics above, we can separate the dependence of the distance and separation from their angular dependence in the cross-correlation function at equation (C12). We have
$\xi_{\text {lin }}^{(\mathrm{S})}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)=\sum_{\ell_{1}, \ell_{2}, \ell} b_{\ell_{1}, \ell_{2}, \ell}\left(s_{1}, s_{2}, s\right) S_{\ell_{1}, \ell_{2}, \ell,\left(\hat{\boldsymbol{s}}_{1}, \hat{\boldsymbol{s}}_{2}, \hat{\boldsymbol{s}}\right) .}$
The coefficients $b_{\ell_{1}, \ell_{2}, \ell}$ are given as the function of $s_{1}=\left|s_{1}\right|$, $s_{2}=\left|\boldsymbol{s}_{2}\right|$, and $s=\left|\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right|$. The non-vanishing coefficients are summarized as follows:
$b_{000}=\left\{b_{X} b_{Y}+\frac{f}{3}\left(b_{X}+b_{Y}\right)+\frac{f^{2}}{9}\right\} \xi_{0}^{2}(s)$,
$b_{220}=\frac{4 f^{2}}{9 \sqrt{5}} \xi_{0}^{2}(s)$,
$b_{202}=-\frac{2 \sqrt{5}}{3}\left(b_{Y} f+\frac{f^{2}}{3}\right) \xi_{2}^{2}(s)$,
$b_{022}=-\frac{2 \sqrt{5}}{3}\left(b_{X} f+\frac{f^{2}}{3}\right) \xi_{2}^{2}(s)$,
$b_{222}=\frac{4}{9} \sqrt{\frac{10}{7}} f^{2} \xi_{2}^{2}(s)$,
$b_{224}=4 \sqrt{\frac{2}{35}} f^{2} \xi_{4}^{2}(s)$,
$b_{101}=2 \sqrt{3}\left(\frac{b_{Y} f}{s_{1}}+\frac{f^{2}}{3 s_{1}}\right) \xi_{1}^{1}(s)$,
$b_{011}=-2 \sqrt{3}\left(\frac{b_{X} f}{s_{2}}+\frac{f^{2}}{3 s_{2}}\right) \xi_{1}^{1}(s)$,
$b_{121}=-4 \sqrt{\frac{2}{15}} \frac{f^{2}}{s_{1}} \xi_{1}^{1}(s)$,
$b_{211}=4 \sqrt{\frac{2}{15}} \frac{f^{2}}{s_{2}} \xi_{1}^{1}(s)$,
$b_{123}=-4 \sqrt{\frac{7}{15}} \frac{f^{2}}{s_{1}} \xi_{3}^{1}(s)$,
$b_{213}=4 \sqrt{\frac{7}{15}} \frac{f^{2}}{s_{2}} \xi_{3}^{1}(s)$,
$b_{110}=-\frac{4 f^{2}}{\sqrt{3} s_{1} s_{2}} \xi_{0}^{0}(s)$,
$b_{112}=-4 \sqrt{\frac{10}{3}} \frac{f^{2}}{s_{1} s_{2}} \xi_{2}^{0}(s)$,
where the function $\xi_{\ell}^{m}$ is defined by
$\xi_{\ell}^{n}(s) \equiv \int \frac{\mathrm{d} k}{2 \pi^{2}} k^{n} j_{\ell}(k s) P_{\mathrm{L}}(k)$.
The coefficients given above exactly coincide with those listed in Pápai \& Szapudi (2008) if we set $b_{X}=1=b_{Y}$ and flip the sign for the terms involving either of factor $1 / s_{1}$ or $1 / s_{2}$ (see equations 6-8 in their paper). This is because the separation $s$, given by $s=\left|s_{2}-s_{1}\right|$, differs from the one defined in Pápai \& Szapudi (2008).

As it has been shown in Szapudi (2004) and Pápai \& Szapudi (2008), we can further exploit a simplified expansion, which is suited for numerically computing the correlation function. To do this, based on the expansion given in equation (D2), we choose a specific coordinate system, in which the triangle formed with the position vectors $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$ is confined on the $x-y$ plane, and the pair separation vector $\boldsymbol{s}=\boldsymbol{s}_{2}-\boldsymbol{s}_{1}$ is parallel to the $x$-axis [i.e. $\hat{s}=(1,0,0)]$. To be precise, we set
$\hat{\boldsymbol{s}}_{1}=\left\{\cos \phi_{1}, \sin \phi_{1}, 0\right\}, \quad \hat{\boldsymbol{s}}_{2}=\left\{\cos \phi_{2}, \sin \phi_{2}, 0\right\}$.

This implies
$S_{\ell_{1}, \ell_{2}, \ell}\left(\hat{\boldsymbol{s}}_{1}, \hat{\boldsymbol{s}}_{2}, \hat{\boldsymbol{s}}\right)=S_{\ell_{1}, \ell_{2}, \ell}\left(\left\{\theta_{1}=\pi / 2, \phi_{1}\right\}\right.$,

$$
\left.\left\{\theta_{2}=\pi / 2, \phi_{2}\right\},\{\theta=\pi / 2, \phi=0\}\right)
$$

With this choice of coordinate system, the full expressions for linear cross-correlation function can be described by a finite number of terms that depend on the two angles $\phi_{1}, \phi_{2}$, and distances $s_{1}, s_{2}$, and separation $s$ :
$\xi_{X Y}^{(S)}\left(\boldsymbol{s}_{1}, \boldsymbol{s}_{2}\right)=\sum_{m, n}\left\{a_{m n} \cos \left(m \phi_{1}\right) \cos \left(n \phi_{2}\right)+b_{m n} \sin \left(m \phi_{1}\right) \sin \left(n \phi_{2}\right)\right\}$.

The non-vanishing coefficients $a_{m n}$ and $b_{m n}$ for the linear crosscorrelation function are summarized as follows:

$$
\begin{aligned}
a_{00}= & \left\{b_{X} b_{Y}+\frac{f}{3}\left(b_{X}+b_{Y}\right)+\frac{2 f^{2}}{15}\right\} \xi_{0}^{2}(s) \\
& -\left\{\frac{f}{6}\left(b_{X}+b_{Y}\right)+\frac{2 f^{2}}{21}\right\} \xi_{2}^{2}(s)+\frac{3 f^{2}}{140} \xi_{4}^{2}(s), \\
a_{02}= & -\left(\frac{f}{2} b_{X}+\frac{3 f^{2}}{14}\right) \xi_{2}^{2}(s)+\frac{f^{2}}{28} \xi_{4}^{2}(s), \\
a_{20}= & -\left(\frac{f}{2} b_{Y}+\frac{3 f^{2}}{14}\right) \xi_{2}^{2}(s)+\frac{f^{2}}{28} \xi_{4}^{2}(s), \\
a_{22}= & f^{2}\left\{\frac{1}{15} \xi_{0}^{2}(s)-\frac{1}{21} \xi_{2}^{2}(s)+\frac{19}{140} \xi_{4}^{2}(s)\right\}, \\
b_{22}= & f^{2}\left\{\frac{1}{15} \xi_{0}^{2}(s)-\frac{1}{21} \xi_{2}^{2}(s)-\frac{4}{35} \xi_{4}^{2}(s)\right\}, \\
a_{10}= & -\left\{\frac{2 b_{Y} f}{s_{1}}+\frac{4 f^{2}}{5 s_{1}}\right\} \xi_{1}^{1}(s)+\frac{f^{2}}{5 s_{1}} \xi_{3}^{1}(s), \\
a_{01}= & \left\{\frac{2 b_{X} f}{s_{2}}+\frac{4 f^{2}}{5 s_{2}}\right\} \xi_{1}^{1}(s)-\frac{f^{2}}{5 s_{2}} \xi_{3}^{1}(s), \\
a_{11}= & \frac{4 f^{2}}{3 s_{1} s_{2}}\left\{\xi_{0}^{0}(s)-2 \xi_{2}^{0}(s)\right\}, \\
a_{21}= & \frac{2 f^{2}}{5 s_{2}} \xi_{1}^{1}(s)-\frac{3 f^{2}}{5 s_{2}} \xi_{3}^{1}(s),
\end{aligned}
$$

$a_{12}=-\frac{2 f^{2}}{5 s_{1}} \xi_{1}^{1}(s)+\frac{3 f^{2}}{5 s_{1}} \xi_{3}^{1}(s)$,
$b_{11}=\frac{4 f^{2}}{3 s_{1} s_{2}}\left\{\xi_{0}^{0}(s)+\xi_{2}^{0}(s)\right\}$,
$b_{21}=\frac{2 f^{2}}{5 s_{2}}\left\{\xi_{1}^{1}(s)+\xi_{3}^{1}(s)\right\}$,
$b_{12}=-\frac{2 f^{2}}{5 s_{1}}\left\{\xi_{1}^{1}(s)+\xi_{3}^{1}(s)\right\}$.
Note again that the coefficients $a_{m n}$ and $b_{m n}$ coincide exactly with those listed in Pápai \& Szapudi (2008) if we set $b_{X}=1=b_{Y}$, and flip the sign for the terms involving either of factor $1 / s_{1}$ or $1 / s_{2}$.

## D2 Line-of-sight dependent wide-angle corrections for cross-correlation function

As we discussed in Section 3, the cross-correlation function for a widely separated pair can be also expressed as a function of LOS distance, $d=|\boldsymbol{d}|$, separation for a pair of objects, $s=\left|\boldsymbol{s}_{2}-\boldsymbol{s}_{1}\right|$, and the directional cosine, $\mu=\hat{\boldsymbol{d}} \cdot \hat{\boldsymbol{s}}$, with unit vector $\hat{\boldsymbol{s}}$ defined by $\hat{\boldsymbol{s}} \equiv$ $\left(\boldsymbol{s}_{2}-\boldsymbol{s}_{2}\right) / s$. When applying the conventional multipole expansion, we have in general the following expression (see equations 27 and 28):
$\xi_{X Y}^{(\mathrm{S})}(s, d, \mu)=\sum_{\ell} \sum_{n}\left(\frac{s}{d}\right)^{n} \xi_{\ell, n}^{(\mathrm{S})}(s) \mathcal{P}_{\ell}(\mu)$.
In linear theory, the leading-order expressions for the coefficients in $n$, i.e. $\xi_{\ell, 0}$, are reduced to the well-known formulas in the planeparallel limit (e.g. Hamilton 1992):
$\xi_{0,0}^{(\mathrm{S})}(s)=\left\{b_{X} b_{Y}+\frac{f}{3}\left(b_{X}+b_{Y}\right)+\frac{f^{2}}{5}\right\} \xi_{0}^{2}(s)$,
$\xi_{2,0}^{(\mathrm{S})}(s)=-\left\{\frac{2 f}{3}\left(b_{X}+b_{Y}\right)+\frac{4 f^{2}}{7}\right\} \xi_{2}^{2}(s)$,
$\xi_{4,0}^{(S)}(s)=\frac{8 f^{2}}{35} \xi_{4}^{2}(s)$.
For higher order terms of $n \geq 1$, the expressions for $\xi_{\ell, n}^{(\mathrm{S})}$ depends on the definition of LOS direction. Below, based on the expansion form given at equation (D19), we derive the next-to-leading-order expressions for the wide-angle corrections, i.e. $\xi_{\ell, 1}^{(\mathrm{S})}$ for the odd multipoles and $\xi_{\ell, 2}^{(\mathrm{S})}$ for the even multipoles, in three different definitions of LOS direction.

## D2.1 Mid-point LOS

Consider first the mid-point LOS, defined at equation (29). With this specific definition, the position vectors for the pair of objects, $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$, are expressed in terms of the LOS vector $\boldsymbol{d}$ and separation vector $s$ as
$s_{1}=\boldsymbol{d}-\frac{1}{2} \boldsymbol{s}, \quad \boldsymbol{s}_{2}=\boldsymbol{d}+\frac{1}{2} \boldsymbol{s}$.
We also recall that the two angles $\phi_{1}$ and $\phi_{2}$, defined in the specific coordinate system in Section D1, are related to the position vectors $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$ through equation (D18). With a help of these expressions and relation, we substitute the explicit form of the LOS and separation vectors, $\boldsymbol{s}=(s, 0,0)$ and $\boldsymbol{d}=d\left(\mu, \sqrt{1-\mu^{2}}, 0\right)$, into the expansion at equation (D19). Then, the correlation function
$\xi_{X Y}^{(S)}$ is expressed explicitly in terms of the three variables, $s, d$, and $\mu$. With this expression, the correlation function is now systematically expanded in powers of $(s / d)$.
For even multipole, the next-to-leading-order non-vanishing contribution to equation (D20) appears at $n=2$. Up to $\ell=4$, we have

$$
\begin{align*}
\operatorname{mid} \xi_{0,2}^{(S)}(s)= & \left\{\frac{f}{9}\left(b_{X}+b_{Y}\right)-\frac{14 f^{2}}{15}\right\} \Xi_{0}^{0}(s) \\
& +\left\{\frac{7 f}{90}\left(b_{X}+b_{Y}\right)-\frac{69 f^{2}}{315}\right\} \Xi_{2}^{0}(s)+\frac{4 f^{2}}{3} \Xi_{0}^{2}(s), \tag{D25}
\end{align*}
$$

${ }^{\operatorname{mid}} \xi_{2,2}^{(S)}(s)=-\left\{\frac{4 f}{9}\left(b_{X}+b_{Y}\right)+\frac{4 f^{2}}{15}\right\} \Xi_{0}^{0}(s)$

$$
\begin{equation*}
-\left\{\frac{23 f}{126}\left(b_{X}+b_{Y}\right)+\frac{23 f^{2}}{147}\right\} \Xi_{2}^{0}(s)-\frac{8 f^{2}}{245} \Xi_{4}^{0}(s) \tag{D26}
\end{equation*}
$$

${ }^{\operatorname{mid}} \xi_{4,2}^{(S)}(s)=-\left\{\frac{8 f}{35}\left(b_{X}+b_{Y}\right)+\frac{48 f^{2}}{245}\right\} \Xi_{2}^{0}(s)+\frac{4 f^{2}}{2695} \Xi_{4}^{0}(s)$,
with the function $\Xi_{m}^{n}(s)$ defined by
$\Xi_{m}^{n}(s) \equiv \int \frac{\mathrm{d} k k^{2}}{2 \pi^{2}} \frac{j_{m}(k s)}{(k s)^{n}} P_{\mathrm{L}}(k)$.
Note that this is related to the function $\xi_{m}^{n}$ at equation (D17) through $\Xi_{m}^{n}=\xi_{m}^{2-n} / s^{n}$. Setting $b_{X}=b_{Y}$, the expressions given above coincide with those obtained by Reimberg et al. (2016) except for the hexadecapole, where we found a small typo in their paper (see equations 4.18-4.20 of their paper).
On the other hand, the odd multipoles appears non-vanishing at $n=1$. We obtain
${ }^{\operatorname{mid}} \xi_{1,1}^{(S)}(s)=\frac{2}{3} f\left(b_{X}-b_{Y}\right)\left\{\Xi_{0}^{0}(s)+\frac{2}{5} \Xi_{2}^{0}(s)\right\}$,
$\operatorname{mid}_{\xi_{3,1}(\mathrm{~S})}(s)=\frac{2}{5} f\left(b_{X}-b_{Y}\right) \Xi_{2}^{0}(s)$.
The odd multipoles become vanishing in general for autocorrelation function (i.e. $b_{X}=b_{Y}$ ).

## D2.2 End-point LOS

Let us next consider the end-point LOS defined by equation (30). In this case, the position vectors $s_{1}$ and 2 are expressed in terms of $\boldsymbol{d}$ and $\boldsymbol{s}$ as
$s_{1}=\boldsymbol{d}, \quad s_{2}=\boldsymbol{d}+\boldsymbol{s}$.
Similar to the mid-point LOS case, we use equations (D31) and (D18) to express the expansion at equation (D19) in terms of the variables $s, d$, and $\mu$.
Then, systematic expansion in power of $(s / d)$ leads to the following next-to-leading-order wide-angle corrections:

$$
\begin{align*}
\text { end } \xi_{0,2}^{(S)}(s)= & \left\{\frac{2 f}{9} b_{X}-\frac{14 f^{2}}{45}\right\} \Xi_{0}^{0}(s) \\
& +\left\{\frac{4 f}{45} b_{X}-\frac{68 f^{2}}{315}\right\} \Xi_{2}^{0}(s)+\frac{4 f^{2}}{3} \Xi_{0}^{2}(s), \tag{D32}
\end{align*}
$$

$$
\begin{align*}
{ }^{\operatorname{end}} \xi_{2,2}^{(S)}(s)= & -\left\{\frac{8 f}{9} b_{X}+\frac{4 f^{2}}{15}\right\} \Xi_{0}^{0}(s) \\
& +\left\{\frac{10 f}{63} b_{X}+\frac{10 f^{2}}{147}\right\} \Xi_{2}^{0}(s)+\frac{12 f^{2}}{245} \Xi_{4}^{0}(s),  \tag{D33}\\
\operatorname{end} \xi_{4,2}^{(S)}(s)= & -\left\{\frac{32 f}{9} b_{X}+\frac{96 f^{2}}{245}\right\} \Xi_{2}^{0}(s)-\frac{776 f^{2}}{2695} \Xi_{4}^{0}(s) \tag{D34}
\end{align*}
$$

for the even multipoles, and

$$
\begin{align*}
\text { end } \xi_{1,1}^{(S)}(s)= & \left\{\frac{2 f}{3} b_{X}-\frac{2 f}{3} b_{Y}\right\} \Xi_{0}^{0}(s) \\
& -\left\{\frac{2 f}{15} b_{X}+\frac{2 f}{3} b_{Y}+\frac{12 f^{2}}{35}\right\} \Xi_{2}^{0}(s),  \tag{D35}\\
\text { end } \xi_{3,1}^{(S)}(s)= & \left\{\frac{4 f}{5} b_{X}+\frac{12 f^{2}}{35}\right\} \Xi_{2}^{0}(s)+\frac{16 f^{2}}{63} \Xi_{4}^{0}(s) \tag{D36}
\end{align*}
$$

for the odd multipoles. Note that setting $b_{X}=b_{Y}$ and flipping the overall sign, equations (D35) and (D36) coincide with those obtained by Reimberg et al. (2016). ${ }^{8}$
Note that the above expressions are related to those in the midpoint LOS case as follows:

$$
\begin{align*}
\begin{aligned}
\operatorname{end} \xi_{0,2}^{(S)}(s)= & { }^{\operatorname{mid}} \xi_{0,2}^{(\mathrm{S})}(s)+\frac{f}{9}\left(b_{X}-b_{Y}\right) \Xi_{0}^{0}(s) \\
& +\frac{f}{90}\left\{b_{X}-7 f-\frac{18 f^{2}}{7}\right\} \Xi_{2}^{0}(s), \\
\text { end } \xi_{2,2}^{(\mathrm{S})}(s)={ }^{\operatorname{mid}} & \xi_{2,2}^{(\mathrm{S})}(s)-\frac{4 f}{9}\left(b_{X}-b_{Y}\right) \Xi_{0}^{0}(s) \\
& +\frac{43 f}{126}\left\{b_{X}+\frac{23}{43} b_{Y}+\frac{198 f}{301}\right\} \Xi_{2}^{0}(s) \\
& +\frac{4 f^{2}}{49} \Xi_{4}^{0}(s), \\
& \\
& \quad-\frac{156 f^{2}}{539} \Xi_{4}^{0}(s)
\end{aligned}
\end{align*}
$$

for even multipoles, and

$$
\begin{align*}
\operatorname{end} \xi_{1,1}^{(S)}(s) & ={ }^{\text {mid }} \xi_{1,1}^{(S)}(s)-\frac{2}{5} f\left(b_{X}+b_{Y}+\frac{6}{7} f\right) \Xi_{2}^{0}(s),  \tag{D40}\\
{ }^{\text {end }} \xi_{3,1}^{(S)}(s) & ={ }^{\text {mid }} \\
\xi_{3,1}^{(S)}(s) & +\frac{2}{5} f\left(b_{X}+b_{Y}+\frac{6}{7} f\right) \Xi_{2}^{0}(s)  \tag{D41}\\
& +\frac{16 f^{2}}{63} \Xi_{4}^{0}(s)
\end{align*}
$$

for odd multipoles. That is, the odd multipoles for the end-point LOS generally become non-vanishing even if we set $b_{X}=b_{Y}$.

## D2.3 Bisector LOS

Finally, we consider the bisector LOS, and derive the wide-angle corrections. From the definition given at equation (31) and the

[^7]geometrical relation, we can express the position vectors $\boldsymbol{s}_{1}$ and $\boldsymbol{s}_{2}$ in terms of LOS vector $\boldsymbol{d}$ and separation vector $\boldsymbol{s}$ as follows:
$\boldsymbol{s}_{1}=\boldsymbol{d}-(1-t) \boldsymbol{s}, \quad \boldsymbol{s}_{2}=\boldsymbol{d}+t \boldsymbol{s}$
with the quantity $t$ given by (Castorina \& White 2018a,b)
$t=\frac{d+s \mu-\sqrt{\mathrm{d}^{2}+(s \mu)^{2}}}{2 s \mu}$.
Repeating the same procedure as given in Section D2.1 and D2.2, equation (D19) is expressed in terms of the variables $s, d$, and $\mu$, and we can then expand it in powers of $(s / d)$.

The non-vanishing even multipoles at next-to-leading order become

$$
\begin{align*}
\operatorname{bisect}_{\xi_{0,2}^{(S)}}^{(s)}= & \left\{\frac{f}{9} b_{X}+\frac{f}{9} b_{Y}-\frac{14 f^{2}}{45}\right\} \Xi_{0}^{0}(s) \\
& +\left\{\frac{f}{90} b_{X}+\frac{f}{90} b_{Y}-\frac{11 f^{2}}{45}\right\} \Xi_{2}^{0}(s)+\frac{4 f^{2}}{3} \Xi_{0}^{2}(s), \tag{D44}
\end{align*}
$$

$$
\begin{align*}
\operatorname{bisect} \xi_{0,2}^{(S)}(s)= & -\left\{\frac{4 f}{9} b_{X}+\frac{4 f}{9} b_{Y}-\frac{4 f^{2}}{15}\right\} \Xi_{0}^{0}(s) \\
& -\left\{\frac{29 f}{126} b_{X}+\frac{29 f}{126} b_{Y}-\frac{29 f^{2}}{147}\right\} \Xi_{2}^{0}(s) \\
& +\frac{16 f^{2}}{735} \Xi_{0}^{2}(s), \tag{D4}
\end{align*}
$$

$$
\operatorname{bisect}_{\xi_{4,2}^{(S)}}^{(s)}=-\left\{\frac{4 f}{35} b_{X}+\frac{4 f}{35} b_{Y}+\frac{24 f^{2}}{245}\right\} \Xi_{2}^{0}(s)
$$

$$
\begin{equation*}
+\frac{4 f^{2}}{245} \Xi_{4}^{0}(s), \tag{D46}
\end{equation*}
$$

which are compared with those in the mid-point LOS as follows:

$$
\begin{align*}
& \operatorname{bisect}_{\xi_{0,2}(S)}^{(S)}={ }^{\text {mid }} \xi_{0,2}^{(\mathrm{S})}(s)-\frac{f}{15}\left\{b_{X}+b_{Y}+\frac{6 f}{7}\right\} \Xi_{2}^{0}(s),  \tag{D47}\\
& \operatorname{bisect} \xi_{2,2}^{(\mathrm{S})}(s)={ }^{\text {mid }} \xi_{2,2}^{(\mathrm{S})}(s)-\frac{f}{21}\left\{b_{X}+b_{Y}+\frac{6 f}{7}\right\} \Xi_{2}^{0}(s) \\
&+\frac{8 f^{2}}{147} \Xi_{4}^{0}(s),  \tag{D48}\\
& \operatorname{bisect}_{\xi_{4,2}^{(S)}(s)=}{ }^{\text {mid }} \xi_{4,2}^{(\mathrm{S})}(s)+\frac{4 f}{35}\left\{b_{X}+b_{Y}+\frac{6 f}{7}\right\} \Xi_{2}^{0}(s) \\
&+\frac{8 f^{2}}{539} \Xi_{4}^{0}(s) . \tag{D49}
\end{align*}
$$

Setting $b_{X}=b_{Y}$, equations (D44)-(D46) are basically the same expressions as presented in Reimberg et al. (2016), where there are minor typos in equations 4.25 and 4.26 .

On the other hand, the leading-order non-vanishing odd multipoles are shown to be exactly coincide with those in the mid-point LOS. That is, we have

$$
\begin{align*}
& \operatorname{bisect} \xi_{1,1}^{(\mathrm{S})}(s)=\operatorname{mid} \xi_{1,1}^{(\mathrm{S})}(s) \\
& \text { bisect } \xi_{3,1}^{(\mathrm{S})}(s)={ }^{\operatorname{mid}} \xi_{3,1}^{(\mathrm{S})}(s)
\end{align*}
$$

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[^0]:    * E-mail: ataruya@yukawa.kyoto-u.ac.jp

[^1]:    ${ }^{1}$ http://www.feynarts.de/cuba/

[^2]:    ${ }^{2}$ To be precise, we assume the constant mean number density, and the contribution from its evolution is ignored in equation (23).

[^3]:    ${ }^{3}$ When integrating equation (19) over $\boldsymbol{q}$, we treat the unit vector $\hat{\boldsymbol{s}}$ in equation (24) independent of the Lagrangian position $\boldsymbol{q}$, in a similar way to what we derived equation (21).
    ${ }^{4}$ To be strict, the analytical expressions for linear cross-correlation function has been presented in Bonvin et al. (2014), in a mixture of relativistic and standard RSD contributions. In Appendix D, we re-derived the full analytical expressions, leaving only the relevant standard RSD contributions, and present the results together with the formulas for multipole expansion based on three different representation of LOS direction.

[^4]:    ${ }^{5}$ To be strict, figs 3 and 4 of their paper adopts the bisector LOS, not the mid-point LOS. Nevertheless, as we will show in Section 3.2, the differences between bisector and mid-point LOS are sufficiently small.

[^5]:    ${ }^{7}$ The dipole contributions coming from $\xi_{\text {div }}$ and $\xi_{\text {wa }}$ in equation (37) exactly correspond to $\left\langle\xi^{\mathrm{div}}\right\rangle$ and $\left\langle\xi^{\mathrm{wa}}\right\rangle$ in Breton et al. (2019) (see equations 23 and 29 of their paper).

[^6]:    ${ }^{6}$ The label, data_ $\mathrm{H}_{N}$, indicates the halo sub-sample in which each halo contains dark matter particles of the numbers ranging from $N$ to $2 N$, with the mass of dark matter particle being $1.88 \times 10^{10} h^{-1} \mathrm{M}_{\odot}$.

[^7]:    ${ }^{8}$ In their paper, the position vector $\boldsymbol{s}_{2}$ is taken to be the end-point LOS.

